Microchip Technology - PIC32MZ1064DAA169-I/HF Datasheet

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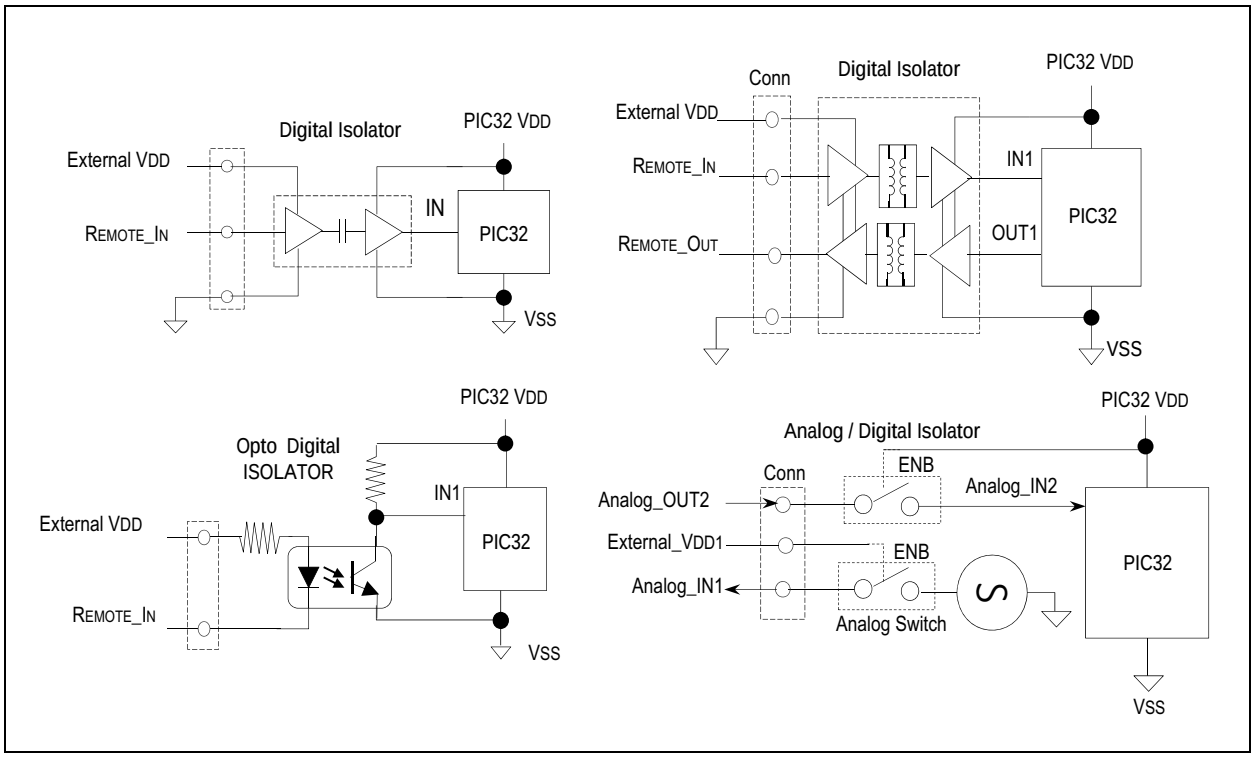
Applications of "Embedded - Microcontrollers"

Details	
Product Status	Active
Core Processor	MIPS32® microAptiv™
Core Size	32-Bit Single-Core
Speed	200MHz
Connectivity	CANbus, EBI/EMI, Ethernet, I²C, IrDA, LINbus, PMP, SPI, SQI, UART/USART, USB OTG
Peripherals	Brown-out Detect/Reset, DMA, HLVD, I²S, POR, PWM, WDT
Number of I/O	120
Program Memory Size	1MB (1M x 8)
Program Memory Type	FLASH
EEPROM Size	-
RAM Size	640K x 8
Voltage - Supply (Vcc/Vdd)	1.7V ~ 3.6V
Data Converters	A/D 45x12b
Oscillator Type	Internal
Operating Temperature	-40°C ~ 85°C (TA)
Mounting Type	Surface Mount
Package / Case	169-LFBGA
Supplier Device Package	169-LFBGA (11x11)
Purchase URL	https://www.e-xfl.com/product-detail/microchip-technology/pic32mz1064daa169-i-hf

TABLE 2-1: EXAMPLES OF DIGITAL/ ANALOG ISOLATORS WITH OPTIONAL LEVEL TRANSLATION

Example Digital/Analog Signal Isolation Circuits	Inductive Coupling	Capacitive Coupling	Opto Coupling	Analog/Digital Switch
ADuM7241 / 40 ARZ (1 Mbps)	X	—	—	—
ADuM7241 / 40 CRZ (25 Mbps)	X	—	—	—
ISO721	—	X	—	—
LTV-829S (2 Channel)	—	—	X	—
LTV-849S (4 Channel)	—	—	X	—
FSA266 / NC7WB66	—	—	—	X

FIGURE 2-6: EXAMPLE DIGITAL/ANALOG SIGNAL ISOLATION CIRCUITS



7.2 Interrupts

The PIC32MZ DA family uses variable offsets for vector spacing. This allows the interrupt vector spacing to be configured according to application needs. A unique interrupt vector offset can be set for each vector using its associated OFFx register.

For details on the Variable Offset feature, refer to **8.5.2 "Variable Offset"** in **Section 8. "Interrupt Controller"** (DS60001108) of the *"PIC32 Family Reference Manual"*.

Table 7-2 provides the Interrupt IRQ, vector and bit location information.

TABLE 7-2: INTERRUPT IRQ, VECTOR AND BIT LOCATION

Interrupt Source(1)	XC32 Vector Name	IRQ #	Vector #	Interrupt Bit Location				Persistent Interrupt
				Flag	Enable	Priority	Sub-priority	
Highest Natural Order Priority								
Core Timer Interrupt	_CORE_TIMER_VECTOR	0	OFF000<17:1>	IFS0<0>	IEC0<0>	IPC0<4:2>	IPC0<1:0>	No
Core Software Interrupt 0	_CORE_SOFTWARE_0_VECTOR	1	OFF001<17:1>	IFS0<1>	IEC0<1>	IPC0<12:10>	IPC0<9:8>	No
Core Software Interrupt 1	_CORE_SOFTWARE_1_VECTOR	2	OFF002<17:1>	IFS0<2>	IEC0<2>	IPC0<20:18>	IPC0<17:16>	No
External Interrupt 0	_EXTERNAL_0_VECTOR	3	OFF003<17:1>	IFS0<3>	IEC0<3>	IPC0<28:26>	IPC0<25:24>	No
Timer1	_TIMER_1_VECTOR	4	OFF004<17:1>	IFS0<4>	IEC0<4>	IPC1<4:2>	IPC1<1:0>	No
Input Capture 1 Error	_INPUT_CAPTURE_1_ERROR_VECTOR	5	OFF005<17:1>	IFS0<5>	IEC0<5>	IPC1<12:10>	IPC1<9:8>	Yes
Input Capture 1	_INPUT_CAPTURE_1_VECTOR	6	OFF006<17:1>	IFS0<6>	IEC0<6>	IPC1<20:18>	IPC1<17:16>	Yes
Output Compare 1	_OUTPUT_COMPARE_1_VECTOR	7	OFF007<17:1>	IFS0<7>	IEC0<7>	IPC1<28:26>	IPC1<25:24>	No
External Interrupt 1	_EXTERNAL_1_VECTOR	8	OFF008<17:1>	IFS0<8>	IEC0<8>	IPC2<4:2>	IPC2<1:0>	No
Timer2	_TIMER_2_VECTOR	9	OFF009<17:1>	IFS0<9>	IEC0<9>	IPC2<12:10>	IPC2<9:8>	No
Input Capture 2 Error	_INPUT_CAPTURE_2_ERROR_VECTOR	10	OFF010<17:1>	IFS0<10>	IEC0<10>	IPC2<20:18>	IPC2<17:16>	Yes
Input Capture 2	_INPUT_CAPTURE_2_VECTOR	11	OFF011<17:1>	IFS0<11>	IEC0<11>	IPC2<28:26>	IPC2<25:24>	Yes
Output Compare 2	_OUTPUT_COMPARE_2_VECTOR	12	OFF012<17:1>	IFS0<12>	IEC0<12>	IPC3<4:2>	IPC3<1:0>	No
External Interrupt 2	_EXTERNAL_2_VECTOR	13	OFF013<17:1>	IFS0<13>	IEC0<13>	IPC3<12:10>	IPC3<9:8>	No
Timer3	_TIMER_3_VECTOR	14	OFF014<17:1>	IFS0<14>	IEC0<14>	IPC3<20:18>	IPC3<17:16>	No
Input Capture 3 Error	_INPUT_CAPTURE_3_ERROR_VECTOR	15	OFF015<17:1>	IFS0<15>	IEC0<15>	IPC3<28:26>	IPC3<25:24>	Yes
Input Capture 3	_INPUT_CAPTURE_3_VECTOR	16	OFF016<17:1>	IFS0<16>	IEC0<16>	IPC4<4:2>	IPC4<1:0>	Yes
Output Compare 3	_OUTPUT_COMPARE_3_VECTOR	17	OFF017<17:1>	IFS0<17>	IEC0<17>	IPC4<12:10>	IPC4<9:8>	No
External Interrupt 3	_EXTERNAL_3_VECTOR	18	OFF018<17:1>	IFS0<18>	IEC0<18>	IPC4<20:18>	IPC4<17:16>	No
Timer4	_TIMER_4_VECTOR	19	OFF019<17:1>	IFS0<19>	IEC0<19>	IPC4<28:26>	IPC4<25:24>	No
Input Capture 4 Error	_INPUT_CAPTURE_4_ERROR_VECTOR	20	OFF020<17:1>	IFS0<20>	IEC0<20>	IPC5<4:2>	IPC5<1:0>	Yes
Input Capture 4	_INPUT_CAPTURE_4_VECTOR	21	OFF021<17:1>	IFS0<21>	IEC0<21>	IPC5<12:10>	IPC5<9:8>	Yes
Output Compare 4	_OUTPUT_COMPARE_4_VECTOR	22	OFF022<17:1>	IFS0<22>	IEC0<22>	IPC5<20:18>	IPC5<17:16>	No

Note 1: Not all interrupt sources are available on all devices. See the Family Features tables (Table 1 through Table 2) for the list of available peripherals.

2: Upon Reset, the GLCD interrupt (both HSYNC and VSYNC) are persistent. However, through the IRQCON bit (GLCDINT<31>), the type of interrupt can be changed to non-persistent.

9.0 PREFETCH MODULE

Note: This data sheet summarizes the features of the PIC32MZ Graphics (DA) Family of devices. It is not intended to be a comprehensive reference source. To complement the information in this data sheet, refer to **Section 41. "Prefetch Module for Devices with L1 CPU Cache"** (DS60001183), which is available from the *Documentation > Reference Manual* section of the Microchip PIC32 web site (www.microchip.com/pic32).

The Prefetch module is a performance enhancing module that is included in PIC32MZ DA family devices. When running at high-clock rates, Wait states must be inserted into Program Flash Memory (PFM) read transactions to meet the access time of the PFM. Wait states can be hidden to the core by prefetching and storing instructions in a temporary holding area that the CPU can access quickly. Although the data path to the CPU is 32 bits wide, the data path to the PFM is 128 bits wide. This wide data path provides the same bandwidth to the CPU as a 32-bit path running at four times the frequency.

The Prefetch module holds a subset of PFM in temporary holding spaces known as lines. Each line contains a tag and data field. Normally, the lines hold a copy of what is currently in memory to make instructions or data available to the CPU without Flash Wait states.

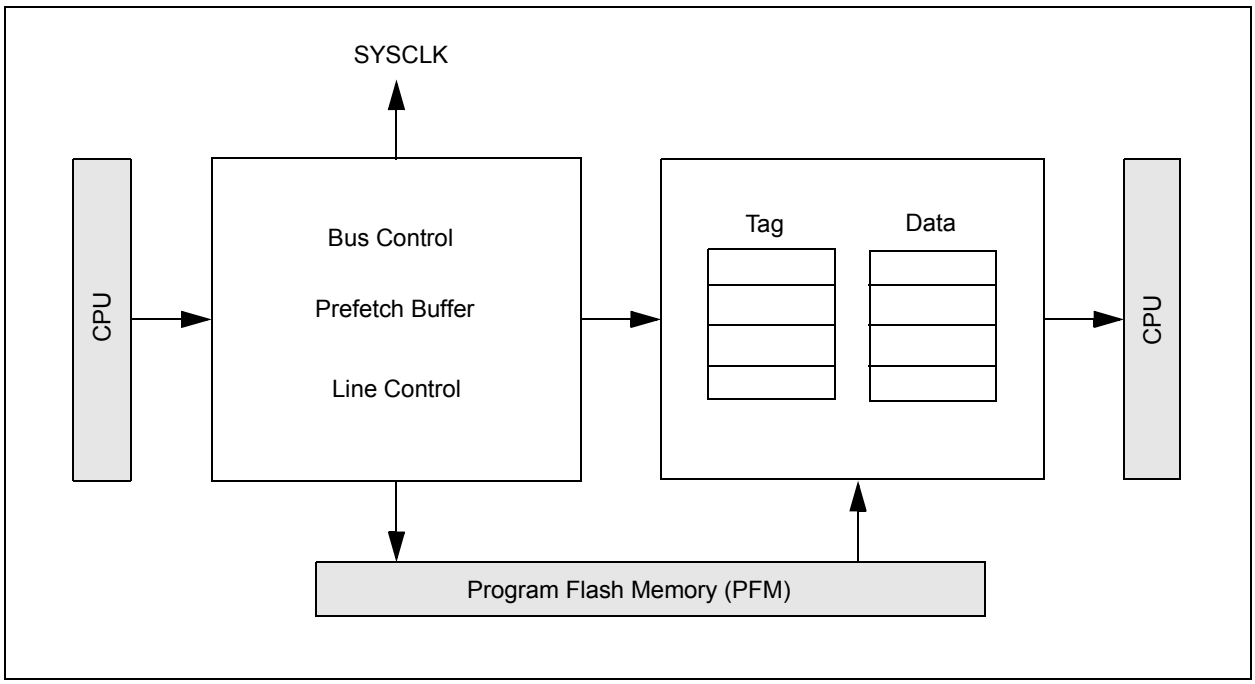
9.1 Features

The Prefetch module includes the following key features:

- 4x16 byte fully-associative lines
- One line for CPU instructions
- One line for CPU data
- Two lines for peripheral data
- 16-byte parallel memory fetch
- Configurable predictive prefetch
- Error detection and correction

A simplified block diagram of the Prefetch module is shown in Figure 9-1.

FIGURE 9-1: PREFETCH MODULE BLOCK DIAGRAM



REGISTER 10-5: DCRCDATA: DMA CRC DATA REGISTER

Bit Range	Bit 31/23/15/7	Bit 30/22/14/6	Bit 29/21/13/5	Bit 28/20/12/4	Bit 27/19/11/3	Bit 26/18/10/2	Bit 25/17/9/1	Bit 24/16/8/0
31:24	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0
	DCRCDATA<31:24>							
23:16	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0
	DCRCDATA<23:16>							
15:8	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0
	DCRCDATA<15:8>							
7:0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0
	DCRCDATA<7:0>							

Legend:			
R = Readable bit	W = Writable bit	U = Unimplemented bit, read as '0'	
-n = Value at POR	'1' = Bit is set	'0' = Bit is cleared	x = Bit is unknown

bit 31-0 **DCRCDATA<31:0>:** CRC Data Register bits

Writing to this register will seed the CRC generator. Reading from this register will return the current value of the CRC. Bits greater than PLEN will return '0' on any read.

When CRCTYP (DCRCCON<5>) = 1 (CRC module is in IP Header mode):
Only the lower 16 bits contain IP header checksum information. The upper 16 bits are always '0'. Data written to this register is converted and read back in 1's complement form (i.e., current IP header checksum value).

When CRCTYP (DCRCCON<5>) = 0 (CRC module is in LFSR mode):
Bits greater than PLEN will return '0' on any read.

REGISTER 10-6: DCRCXOR: DMA CRCXOR ENABLE REGISTER

Bit Range	Bit 31/23/15/7	Bit 30/22/14/6	Bit 29/21/13/5	Bit 28/20/12/4	Bit 27/19/11/3	Bit 26/18/10/2	Bit 25/17/9/1	Bit 24/16/8/0
31:24	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0
	DCRCXOR<31:24>							
23:16	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0
	DCRCXOR<23:16>							
15:8	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0
	DCRCXOR<15:8>							
7:0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0
	DCRCXOR<7:0>							

Legend:			
R = Readable bit	W = Writable bit	U = Unimplemented bit, read as '0'	
-n = Value at POR	'1' = Bit is set	'0' = Bit is cleared	x = Bit is unknown

bit 31-0 **DCRCXOR<31:0>:** CRC XOR Register bits

When CRCTYP (DCRCCON<5>) = 1 (CRC module is in IP Header mode):
This register is unused.

When CRCTYP (DCRCCON<5>) = 0 (CRC module is in LFSR mode):
1 = Enable the XOR input to the Shift register
0 = Disable the XOR input to the Shift register; data is shifted in directly from the previous stage in the register

TABLE 11-1: USB REGISTER MAP 1 (CONTINUED)

Virtual Address	Register Name	Bit Range	Bits															All Resets
			31/15	30/14	29/13	28/12	27/11	26/10	25/9	24/8	23/7	22/6	21/5	20/4	19/3	18/2	17/1	16/0	
3248	USB DMA5A	31:16	DMAADDR<31:16>																0000
		15:0	DMAADDR<15:0>																0000
324C	USB DMA5N	31:16	DMACOUNT<31:16>																0000
		15:0	DMACOUNT<15:0>																0000
3254	USB DMA6C	31:16	—	—	—	—	—	—	—	—	—	—	—	—	—	—	—	—	0000
		15:0	—	—	—	—	—	DMABRSTM<1:0>		DMAERR	DMAEP<3:0>				DMAIE	DMAMODE	DMADIR	DMAEN	0000
3258	USB DMA6A	31:16	DMAADDR<31:16>																0000
		15:0	DMAADDR<15:0>																0000
325C	USB DMA6N	31:16	DMACOUNT<31:16>																0000
		15:0	DMACOUNT<15:0>																0000
3264	USB DMA7C	31:16	—	—	—	—	—	—	—	—	—	—	—	—	—	—	—	—	0000
		15:0	—	—	—	—	—	DMABRSTM<1:0>		DMAERR	DMAEP<3:0>				DMAIE	DMAMODE	DMADIR	DMAEN	0000
3268	USB DMA7A	31:16	DMAADDR<31:16>																0000
		15:0	DMAADDR<15:0>																0000
326C	USB DMA7N	31:16	DMACOUNT<31:16>																0000
		15:0	DMACOUNT<15:0>																0000
3274	USB DMA8C	31:16	—	—	—	—	—	—	—	—	—	—	—	—	—	—	—	—	0000
		15:0	—	—	—	—	—	DMABRSTM<1:0>		DMAERR	DMAEP<3:0>				DMAIE	DMAMODE	DMADIR	DMAEN	0000
3278	USB DMA8A	31:16	DMAADDR<31:16>																0000
		15:0	DMAADDR<15:0>																0000
327C	USB DMA8N	31:16	DMACOUNT<31:16>																0000
		15:0	DMACOUNT<15:0>																0000
3304	USB E1RPC	31:16	—	—	—	—	—	—	—	—	—	—	—	—	—	—	—	—	0000
		15:0	RQPKTCNT<15:0>																0000
3308	USB E2RPC	31:16	—	—	—	—	—	—	—	—	—	—	—	—	—	—	—	—	0000
		15:0	RQPKTCNT<15:0>																0000
330C	USB E3RPC	31:16	—	—	—	—	—	—	—	—	—	—	—	—	—	—	—	—	0000
		15:0	RQPKTCNT<15:0>																0000
3310	USB E4RPC	31:16	—	—	—	—	—	—	—	—	—	—	—	—	—	—	—	—	0000
		15:0	RQPKTCNT<15:0>																0000
3314	USB E5RPC	31:16	—	—	—	—	—	—	—	—	—	—	—	—	—	—	—	—	0000
		15:0	RQPKTCNT<15:0>																0000
3318	USB E6RPC	31:16	—	—	—	—	—	—	—	—	—	—	—	—	—	—	—	—	0000
		15:0	RQPKTCNT<15:0>																0000
331C	USB E7RPC	31:16	—	—	—	—	—	—	—	—	—	—	—	—	—	—	—	—	0000
		15:0	RQPKTCNT<15:0>																0000

Legend: x = unknown value on Reset; — = unimplemented, read as '0'. Reset values are shown in hexadecimal.

Note 1: Device mode.
2: Host mode.
3: Definition for Endpoint 0 (ENDPOINT<3:0> (USBCSR<19:16>) = 0).
4: Definition for Endpoints 1-7 (ENDPOINT<3:0> (USBCSR<19:16>) = 1 through 7).

TABLE 16-2: OUTPUT COMPARE 1 THROUGH OUTPUT COMPARE 9 REGISTER MAP (CONTINUED)

Virtual Address (BF84_#)	Register Name(1)	Bit Range	Bits																All Resets
			31/15	30/14	29/13	28/12	27/11	26/10	25/9	24/8	23/7	22/6	21/5	20/4	19/3	18/2	17/1	16/0	
4A00	OC6CON	31:16	—	—	—	—	—	—	—	—	—	—	—	—	—	—	—	—	0000
		15:0	ON	—	SIDL	—	—	—	—	—	—	—	OC32	OCFLT	OCTSEL	OCM<2:0>			0000
4A10	OC6R	31:16	OC6R<31:0>																xxxx
		15:0																	xxxx
4A20	OC6RS	31:16	OC6RS<31:0>																xxxx
		15:0																	xxxx
4C00	OC7CON	31:16	—	—	—	—	—	—	—	—	—	—	—	—	—	—	—	—	0000
		15:0	ON	—	SIDL	—	—	—	—	—	—	—	OC32	OCFLT	OCTSEL	OCM<2:0>			0000
4C10	OC7R	31:16	OC7R<31:0>																xxxx
		15:0																	xxxx
4C20	OC7RS	31:16	OC7RS<31:0>																xxxx
		15:0																	xxxx
4E00	OC8CON	31:16	—	—	—	—	—	—	—	—	—	—	—	—	—	—	—	—	0000
		15:0	ON	—	SIDL	—	—	—	—	—	—	—	OC32	OCFLT	OCTSEL	OCM<2:0>			0000
4E10	OC8R	31:16	OC8R<31:0>																xxxx
		15:0																	xxxx
4E20	OC8RS	31:16	OC8RS<31:0>																xxxx
		15:0																	xxxx
5000	OC9CON	31:16	—	—	—	—	—	—	—	—	—	—	—	—	—	—	—	—	0000
		15:0	ON	—	SIDL	—	—	—	—	—	—	—	OC32	OCFLT	OCTSEL	OCM<2:0>			0000
5010	OC9R	31:16	OC9R<31:0>																xxxx
		15:0																	xxxx
5020	OC9RS	31:16 15:0	OC9RS<31:0>																xxxx

Legend: x = unknown value on Reset; — = unimplemented, read as '0'. Reset values are shown in hexadecimal.

Note 1: All registers in this table have corresponding CLR, SET and INV registers at their virtual addresses, plus offsets of 0x4, 0x8 and 0xC, respectively. See **Section 12.2 "CLR, SET, and INV Registers"** for more information.

REGISTER 23-2: I2CxSTAT: I²C STATUS REGISTER

Bit Range	Bit 31/23/15/7	Bit 30/22/14/6	Bit 29/21/13/5	Bit 28/20/12/4	Bit 27/19/11/3	Bit 26/18/10/2	Bit 25/17/9/1	Bit 24/16/8/0
31:24	U-0	U-0	U-0	U-0	U-0	U-0	U-0	U-0
	—	—	—	—	—	—	—	—
23:16	U-0	U-0	U-0	U-0	U-0	U-0	U-0	U-0
	—	—	—	—	—	—	—	—
15:8	R-0, HS, HC	R-0, HS, HC	R/C-0, HS, HC	U-0	U-0	R/C-0, HS	R-0, HS, HC	R-0, HS, HC
	ACKSTAT	TRSTAT	ACKTIM	—	—	BCL	GCSTAT	ADD10
7:0	R/C-0, HS, SC	R/C-0, HS, SC	R-0, HS, HC	R/C-0, HS, HC	R/C-0, HS, HC	R-0, HS, HC	R-0, HS, HC	R-0, HS, HC
	IWCOL	I2COV	D_A	P	S	R_W	RBF	TBF

Legend:	HS = Hardware Set	HC = Hardware Cleared	SC = Software Cleared
R = Readable bit	W = Writable bit	U = Unimplemented bit, read as '0'	
-n = Value at POR	'1' = Bit is set	'0' = Bit is cleared	C = Clearable bit

bit 31-16 **Unimplemented:** Read as '0'

bit 15 **ACKSTAT:** Acknowledge Status bit
(when operating as I²C master, applicable to master transmit operation)
1 = NACK received from slave
0 = ACK received from slave
Hardware set or clear at end of slave Acknowledge.

bit 14 **TRSTAT:** Transmit Status bit (when operating as I²C master, applicable to master transmit operation)
1 = Master transmit is in progress (8 bits + ACK)
0 = Master transmit is not in progress
Hardware set at beginning of master transmission. Hardware clear at end of slave Acknowledge.

bit 13 **ACKTIM:** Acknowledge Time Status bit (Valid in I²C Slave mode only)
1 = I²C bus is in an Acknowledge sequence, set on 8th falling edge of SCL clock
0 = Not an Acknowledge sequence, cleared on 9th rising edge of SCL clock

bit 12-11 **Unimplemented:** Read as '0'

bit 10 **BCL:** Master Bus Collision Detect bit
1 = A bus collision has been detected during a master operation
0 = No collision
Hardware set at detection of bus collision.

bit 9 **GCSTAT:** General Call Status bit
1 = General call address was received
0 = General call address was not received
Hardware set when address matches general call address. Hardware clear at Stop detection.

bit 8 **ADD10:** 10-bit Address Status bit
1 = 10-bit address was matched
0 = 10-bit address was not matched
Hardware set at match of 2nd byte of matched 10-bit address. Hardware clear at Stop detection.

bit 7 **IWCOL:** Write Collision Detect bit
1 = An attempt to write the I2CxTRN register failed because the I²C module is busy
0 = No collision
Hardware set at occurrence of write to I2CxTRN while busy (cleared by software).

bit 6 **I2COV:** Receive Overflow Flag bit
1 = A byte was received while the I2CxRCV register is still holding the previous byte
0 = No overflow
Hardware set at attempt to transfer I2CxRSR to I2CxRCV (cleared by software).

FIGURE 27-9: FORMAT OF BD_MSG_LEN

Bit Range	Bit 31/23/15/7	Bit 30/22/14/6	Bit 29/21/13/5	Bit 28/20/12/4	Bit 27/19/11/3	Bit 26/18/10/2	Bit 25/17/9/1	Bit 24/16/8/0
31-24	MSG_LENGTH<31:24>							
23-16	MSG_LENGTH<23:16>							
15-8	MSG_LENGTH<15:8>							
7-0	MSG_LENGTH<7:0>							

bit 31-0 **MSG_LENGTH:** Total Message Length

Total message length for the hash and HMAC algorithms in bytes. Total number of crypto bytes in case of GCM algorithm (LEN-C).

FIGURE 27-10: FORMAT OF BD_ENC_OFF

Bit Range	Bit 31/23/15/7	Bit 30/22/14/6	Bit 29/21/13/5	Bit 28/20/12/4	Bit 27/19/11/3	Bit 26/18/10/2	Bit 25/17/9/1	Bit 24/16/8/0
31-24	ENCR_OFFSET<31:24>							
23-16	ENCR_OFFSET<23:16>							
15-8	ENCR_OFFSET<15:8>							
7-0	ENCR_OFFSET<7:0>							

bit 31-0 **ENCR_OFFSET:** Encryption Offset

Encryption offset for the multi-task test cases (both encryption and authentication). The number of AAD bytes in the case of GCM algorithm (LEN-A).

29.0 12-BIT HIGH-SPEED SUCCESSIVE APPROXIMATION REGISTER (SAR) ANALOG-TO-DIGITAL CONVERTER (ADC)

Note: This data sheet summarizes the features of the PIC32MZ DA family of devices. It is not intended to be a comprehensive reference source. To complement the information in this data sheet, refer to **Section 22. "12-bit High-Speed Successive Approximation Register (SAR) Analog-to-Digital Converter (ADC)"** (DS60001344) in the *"PIC32 Family Reference Manual"*, which is available from the Microchip web site (www.microchip.com/PIC32).

The 12-bit High-Speed Successive Approximation Register (SAR) Analog-to-Digital Converter (ADC) includes the following features:

- 12-bit resolution
- Six ADC modules with dedicated Sample and Hold (S&H) circuits
- Two dedicated ADC modules can be combined in Turbo mode to provide double conversion rate (clock sources for combined ADCs must be synchronous)
- Up to 45 analog input sources, in addition to the internal CTMU, VBAT, internal voltage reference and internal temperature sensor
- Single-ended and/or differential inputs
- Can operate during Sleep mode
- Supports touch sense applications
- Six digital comparators
- Six digital filters supporting two modes:
  - Oversampling mode
  - Averaging mode
- 16-word FIFO on ADC0 through ADC4 for increased throughput
- Early interrupt generation resulting in faster processing of converted data
- Designed for motor control, power conversion, and general purpose applications
- Operation during Sleep and Idle modes

A simplified block diagram of the ADC module is illustrated in Figure 29-1.

The 12-bit HS SAR ADC has up to five dedicated ADC modules (ADC0-ADC4) and one shared ADC module (ADC7). The dedicated ADC modules use a single input (or its alternate) and are intended for high-speed and precise sampling of time-sensitive or transient inputs. The the shared ADC module incorporates a multiplexer on the input to facilitate a larger group of inputs, with slower sampling, and provides flexible automated scanning option through the input scan logic.

For each ADC module, the analog inputs are connected to the S&H capacitor. The clock, sampling time, and output data resolution for each ADC module can be set independently. The ADC module performs the conversion of the input analog signal based on the configurations set in the registers. When conversion is complete, the final result is stored in the result buffer for the specific analog input and is passed to the digital filter and digital comparator if configured to use data from this particular sample. Input to ADCx mapping is illustrated in Figure 29-2.

29.1 Activation Sequence

Step 1: Initialize the ADC calibration values by copying them from the factory programmed DEVADCx Flash locations starting at 0xBFC45000 into the ADCxCFG registers starting at 0xBF887D00. Then, configure the AICPMPEN bit (ADCCON1<12> and the IOANCPEN bit (CFGCON<7>) = 1 if and only if VDD is less than 2.5V. The default is '0', which assumes VDD is greater than or equal to 2.5V.

Step 2: The user writes all the essential ADC configuration SFRs including the ADC control clock and all ADC core clocks setup:

- ADCCON1, keeping the ON bit = 0
- ADCCON2, especially paying attention to ADCDIV<6:0> and SAMC<9:0>
- ADCANCON, keeping all analog enables ANENx bit = 0, WKUPCLKCNT bit = 0xA
- ADCCON3, keeping all DIGEN5x = 0, especially paying attention to ADCSEL<1:0>, CONCLKDIV <5:0>, and VREFSEL<2:0>
- ADCxTIME, ADCDIVx<6:0>, and SAMCx<9:0>
- ADCTRGMODE, ADCIMCONx, ADCTRGSNS, ADCCSSx, ADCGIRQENx, ADCTRGx, ADCBASE
- Comparators, filters, and so on

Step 3: The user sets the ANENx bit to '1' for the ADC SAR Cores needed (which internally in the ADC module enables the control clock to generate by division the core clocks for the desired ADC SAR Cores, which in turn enables the bias circuitry for these ADC SAR Cores).

REGISTER 29-4: ADCTRGMODE: ADC TRIGGERING MODE FOR DEDICATED ADC REGISTER

Bit Range	Bit 31/23/15/7	Bit 30/22/14/6	Bit 29/21/13/5	Bit 28/20/12/4	Bit 27/19/11/3	Bit 26/18/10/2	Bit 25/17/9/1	Bit 24/16/8/0
31:24	U-0	U-0	U-0	U-0	U-0	U-0	R/W-0	R/W-0
	—	—	—	—	—	—	SH4ALT<1:0>	
23:16	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0
	SH3ALT<1:0>		SH2ALT<1:0>		SH1ALT<1:0>		SH0ALT<1:0>	
15:8	U-0	U-0	U-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0
	—	—	—	STRGEN4	STRGEN3	STRGEN2	STRGEN1	STRGEN0
7:0	U-0	U-0	U-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0
	—	—	—	SSAMPEN4	SSAMPEN3	SSAMPEN2	SSAMPEN1	SSAMPEN0

Legend:			
R = Readable bit	W = Writable bit	U = Unimplemented bit, read as '0'	
-n = Value at POR	'1' = Bit is set	'0' = Bit is cleared	x = Bit is unknown

bit 31-26 **Unimplemented:** Read as ' '

bit 25-24 **SH4ALT<1:0>:** ADC4 Analog Input Select bit
- 11 = Reserved
- 10 = Reserved
- 01 = AN49
- 00 = AN4

bit 23-22 **SH3ALT<1:0>:** ADC3 Analog Input Select bit
- 11 = Reserved
- 10 = Reserved
- 01 = AN48
- 00 = AN3

bit 21-20 **SH2ALT<1:0>:** ADC2 Analog Input Select bit
- 11 = Reserved
- 10 = Reserved
- 01 = AN47
- 00 = AN2

bit 19-18 **SH1ALT<1:0>:** ADC1 Analog Input Select bit
- 11 = Reserved
- 10 = Reserved
- 01 = AN46
- 00 = AN1

bit 17-16 **SH0ALT<1:0>:** ADC0 Analog Input Select bit
- 11 = Reserved
- 10 = Reserved
- 01 = AN45
- 00 = AN0

bit 15-13 **Unimplemented:** Read as ' '

bit 12 **STRGEN4:** ADC4 Presynchronized Triggers bit
- 1 = ADC4 uses presynchronized triggers
- 0 = ADC4 does not use presynchronized triggers

bit 11 **STRGEN3:** ADC3 Presynchronized Triggers bit
- 1 = ADC3 uses presynchronized triggers
- 0 = ADC3 does not use presynchronized triggers

bit 10 **STRGEN2:** ADC2 Presynchronized Triggers bit
- 1 = ADC2 uses presynchronized triggers
- 0 = ADC2 does not use presynchronized triggers

REGISTER 30-11: CiFLTCON1: CAN FILTER CONTROL REGISTER 1

Bit Range	Bit 31/23/15/7	Bit 30/22/14/6	Bit 29/21/13/5	Bit 28/20/12/4	Bit 27/19/11/3	Bit 26/18/10/2	Bit 25/17/9/1	Bit 24/16/8/0
31:24	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0
	FLTEN7	MSEL7<1:0>		FSEL7<4:0>				
23:16	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0
	FLTEN6	MSEL6<1:0>		FSEL6<4:0>				
15:8	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0
	FLTEN5	MSEL5<1:0>		FSEL5<4:0>				
7:0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0
	FLTEN4	MSEL4<1:0>		FSEL4<4:0>				

Legend:			
R = Readable bit	W = Writable bit	U = Unimplemented bit, read as '0'	
-n = Value at POR	'1' = Bit is set	'0' = Bit is cleared	x = Bit is unknown

bit 31 **FLTEN7:** Filter 7 Enable bit
1 = Filter is enabled
0 = Filter is disabled

bit 30-29 **MSEL7<1:0>:** Filter 7 Mask Select bits
11 = Acceptance Mask 3 selected
10 = Acceptance Mask 2 selected
01 = Acceptance Mask 1 selected
00 = Acceptance Mask 0 selected

bit 28-24 **FSEL7<4:0>:** FIFO Selection bits
11111 = Message matching filter is stored in FIFO buffer 31
11110 = Message matching filter is stored in FIFO buffer 30
•
•
•
00001 = Message matching filter is stored in FIFO buffer 1
00000 = Message matching filter is stored in FIFO buffer 0

bit 23 **FLTEN6:** Filter 6 Enable bit
1 = Filter is enabled
0 = Filter is disabled

bit 22-21 **MSEL6<1:0>:** Filter 6 Mask Select bits
11 = Acceptance Mask 3 selected
10 = Acceptance Mask 2 selected
01 = Acceptance Mask 1 selected
00 = Acceptance Mask 0 selected

bit 20-16 **FSEL6<4:0>:** FIFO Selection bits
11111 = Message matching filter is stored in FIFO buffer 31
11110 = Message matching filter is stored in FIFO buffer 30
•
•
•
00001 = Message matching filter is stored in FIFO buffer 1
00000 = Message matching filter is stored in FIFO buffer 0

Note: The bits in this register can only be modified if the corresponding filter enable (FLTENn) bit is '0'.

REGISTER 31-16: ETHRXOVFLOW: ETHERNET CONTROLLER RECEIVE OVERFLOW STATISTICS REGISTER

Bit Range	Bit 31/23/15/7	Bit 30/22/14/6	Bit 29/21/13/5	Bit 28/20/12/4	Bit 27/19/11/3	Bit 26/18/10/2	Bit 25/17/9/1	Bit 24/16/8/0
31:24	U-0	U-0	U-0	U-0	U-0	U-0	U-0	U-0
	—	—	—	—	—	—	—	—
23:16	U-0	U-0	U-0	U-0	U-0	U-0	U-0	U-0
	—	—	—	—	—	—	—	—
15:8	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0
	RXOVFLWCNT<15:8>							
7:0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0
	RXOVFLWCNT<7:0>							

Legend:			
R = Readable bit	W = Writable bit	U = Unimplemented bit, read as '0'	
-n = Value at POR	'1' = Bit is set	'0' = Bit is cleared	x = Bit is unknown

bit 31-16 **Unimplemented:** Read as '0'

bit 15-0 **RXOVFLWCNT<15:0>:** Dropped Receive Frames Count bits

Increment counter for frames accepted by the RX filter and subsequently dropped due to internal receive error (RXFIFO overrun). This event also sets the RXOVFLW bit (ETHIRQ<0>) interrupt flag.

Note 1: This register is only used for RX operations.

2: This register is automatically cleared by hardware after a read operation, unless the byte enables for bytes 0/1 are '0'.

3: It is recommended to use the SET, CLR, or INV registers to set or clear any bit in this register. Setting or clearing any bits in this register should only be done for debug/test purposes.

35.0 CHARGE TIME MEASUREMENT UNIT (CTMU)

Note: This data sheet summarizes the features of the PIC32MZ Graphics (DA) Family family of devices. It is not intended to be a comprehensive reference source. To complement the information in this data sheet, refer to **Section 37. "Charge Time Measurement Unit (CTMU)"** (DS60001167), which is available from the *Documentation > Reference Manual* section of the Microchip PIC32 web site (www.microchip.com/pic32).

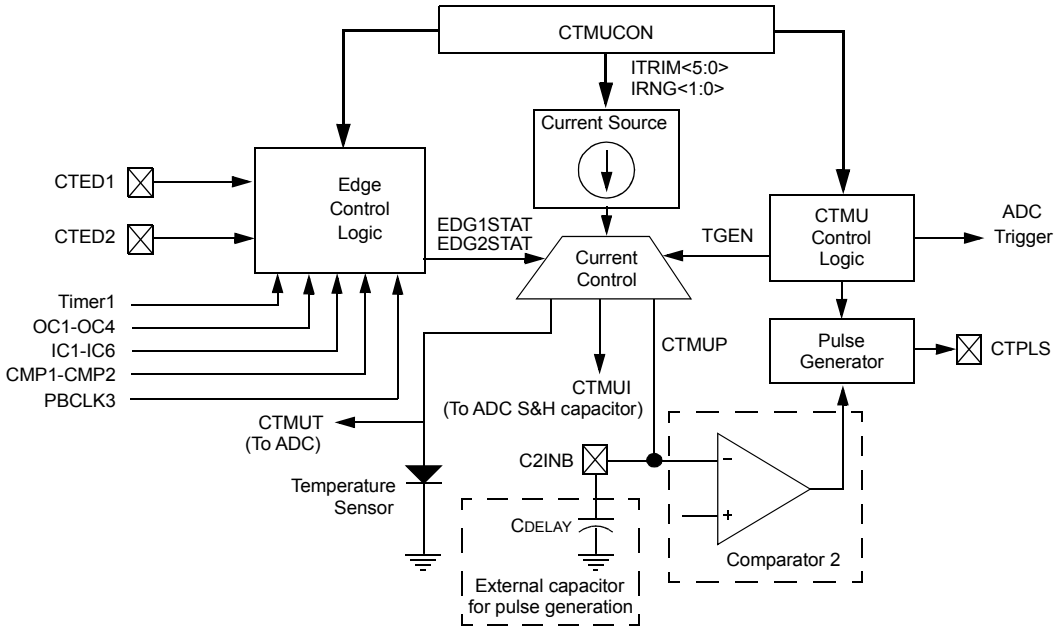
The Charge Time Measurement Unit (CTMU) is a flexible analog module that has a configurable current source with a digital configuration circuit built around it. The CTMU can be used for differential time measurement between pulse sources and can be used for generating an asynchronous pulse. By working with other on-chip analog modules, the CTMU can be used for high resolution time measurement, measure capacitance, measure relative changes in capacitance or generate output pulses with a specific time delay. The CTMU is ideal for interfacing with capacitive-based sensors.

The CTMU module includes the following key features:

- Up to 35 channels available for capacitive or time measurement input
- On-chip precision current source
- 16-edge input trigger sources
- Selection of edge or level-sensitive inputs
- Polarity control for each edge source
- Control of edge sequence
- Control of response to edges
- High precision time measurement
- Time delay of external or internal signal asynchronous to system clock
- Integrated temperature sensing diode
- Control of current source during auto-sampling
- Four current source ranges
- Time measurement resolution of one nanosecond

A block diagram of the CTMU is shown in Figure 35-1.

FIGURE 35-1: CTMU BLOCK DIAGRAM



Current Control Selection	TGEN	EDG1STAT, EDG2STAT
CTMUT	0	EDG1STAT = EDG2STAT
CTMUI	0	EDG1STAT ≠ EDG2STAT
CTMUP	1	EDG1STAT ≠ EDG2STAT
No Connect	1	EDG1STAT = EDG2STAT

REGISTER 36-3: GLCDBGCOLOR: GRAPHICS LCD CONTROLLER BACKGROUND COLOR REGISTER

Bit Range	Bit 31/23/15/7	Bit 30/22/14/6	Bit 29/21/13/5	Bit 28/20/12/4	Bit 27/19/11/3	Bit 26/18/10/2	Bit 25/17/9/1	Bit 24/16/8/0
31:24	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0
	RED<7:0>							
23:16	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0
	GREEN<7:0>							
15:8	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0
	BLUE<7:0>							
7:0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0
	ALPHA<7:0>							

Legend:			
R = Readable bit	W = Writable bit	U = Unimplemented bit, read as '0'	
-n = Value at POR	'1' = Bit is set	'0' = Bit is cleared	x = Bit is unknown

bit 31-24 **RED<7:0>:** Color Red as Background bits
These bits specify that the color red is to be used as the background color.

bit 23-16 **GREEN<7:0>:** Color Green as Background bits
These bits specify that the color green is to be used as the background color.

bit 15-8 **BLUE<7:0>:** Color Blue as Background bits
These bits specify that the color blue is to be used as the background color.

bit 7-0 **ALPHA<7:0>:** Color Alpha as Background bits
These bits specify that the color alpha is to be used as the background color.

Note: If all of the bits in this register are set (RED, GREEN, BLUE and ALPHA), RGBA color is used as the background.

REGISTER 36-4: GLCDRES: GRAPHICS LCD CONTROLLER RESOLUTION REGISTER

Bit Range	Bit 31/23/15/7	Bit 30/22/14/6	Bit 29/21/13/5	Bit 28/20/12/4	Bit 27/19/11/3	Bit 26/18/10/2	Bit 25/17/9/1	Bit 24/16/8/0
31:24	U-0	U-0	U-0	U-0	U-0	R/W-0	R/W-0	R/W-0
	—	—	—	—	—	RESX<10:8>		
23:16	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0
	RESX<7:0>							
15:8	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0
	—	—	—	—	—	RESY<10:8>		
7:0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0
	RESY<7:0>							

Legend:			
R = Readable bit	W = Writable bit	U = Unimplemented bit, read as '0'	
-n = Value at POR	'1' = Bit is set	'0' = Bit is cleared	x = Bit is unknown

bit 31-27 **Unimplemented:** Read as '0'

bit 26-16 **RESX<10:0>:** X Dimension Pixel Resolution bits
These bits specify the pixel resolution for the X dimension.

bit 15-11 **Unimplemented:** Read as '0'

bit 10-0 **RESY<10:0>:** Y Dimension Pixel Resolution bits
These bits specify the pixel resolution for the Y dimension.

REGISTER 36-17: GLCDCLUTx: GRAPHICS LCD CONTROLLER GLOBAL COLOR LOOKUP TABLE REGISTER x ('x'=0-255)

Bit Range	Bit 31/23/15/7	Bit 30/22/14/6	Bit 29/21/13/5	Bit 28/20/12/4	Bit 27/19/11/3	Bit 26/18/10/2	Bit 25/17/9/1	Bit 24/16/8/0
31:24	U-0	U-0	U-0	U-0	U-0	U-0	U-0	U-0
	—	—	—	—	—	—	—	—
23:16	U-0	U-0	U-0	U-0	U-0	U-0	U-0	U-0
	RED<7:0>							
15:8	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0
	GREEN<7:0>							
7:0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0
	BLUE<7:0>							

Legend:			
R = Readable bit	W = Writable bit	U = Unimplemented bit, read as '0'	
-n = Value at POR	'1' = Bit is set	'0' = Bit is cleared	x = Bit is unknown

bit 31-24 **Unimplemented:** Read as '0'

bit 23-16 **RED<7:0>:** Global Color Lookup Table Red Component bits

bit 15-8 **GREEN<7:0>:** Global Color Lookup Table Green Component bits

bit 7-0 **BLUE<7:0>:** Global Color Lookup Table Blue Component bits

TABLE 38-1: DDR SDRAM CONTROLLER REGISTER SUMMARY (CONTINUED)

Virtual Address (BF8E_#)	Register Name	Bit Range	Bits																All Resets
			31/15	30/14	29/13	28/12	27/11	26/10	25/9	24/8	23/7	22/6	21/5	20/4	19/3	18/2	17/1	16/0	
80E8	DDR CMD210	31:16	—	—	—	—	—	—	—	—	—	—	—	—	WAIT<8:5>				0000
		15:0	WAIT<4:0>					BNKADDRCMD<2:0>			MDADDRHCMD<7:0>								0000
80EC	DDR CMD211	31:16	—	—	—	—	—	—	—	—	—	—	—	—	WAIT<8:5>				0000
		15:0	WAIT<4:0>					BNKADDRCMD<2:0>			MDADDRHCMD<7:0>								0000
80F0	DDR CMD212	31:16	—	—	—	—	—	—	—	—	—	—	—	—	WAIT<8:5>				0000
		15:0	WAIT<4:0>					BNKADDRCMD<2:0>			MDADDRHCMD<7:0>								0000
80F4	DDR CMD213	31:16	—	—	—	—	—	—	—	—	—	—	—	—	WAIT<8:5>				0000
		15:0	WAIT<4:0>					BNKADDRCMD<2:0>			MDADDRHCMD<7:0>								0000
80F8	DDR CMD214	31:16	—	—	—	—	—	—	—	—	—	—	—	—	WAIT<8:5>				0000
		15:0	WAIT<4:0>					BNKADDRCMD<2:0>			MDADDRHCMD<7:0>								0000
80FC	DDR CMD215	31:16	—	—	—	—	—	—	—	—	—	—	—	—	WAIT<8:5>				0000
		15:0	WAIT<4:0>					BNKADDRCMD<2:0>			MDADDRHCMD<7:0>								0000
9100	DDR SCLSTART	31:16	—	—	SCL PHCAL	SCL START	—	SCLEN	—	—	—	—	—	—	—	—	—	—	0000
		15:0	—	—	—	—	—	—	—	—	—	—	—	—	—	—	SCL UBPASS	SCL LBPASS	0000
910C	DDR SCLLAT	31:16	—	—	—	—	—	—	—	—	—	—	—	—	—				0000
		15:0	—	—	—	—	—	—	—	—	DDRCLKDLY<3:0>				CAPCLKDLY<3:0>				0000
9118	DDR SCLCFG0	31:16	—	—	—	—	—	—	—	ODTCSW	—	—	—	—	—	—	—	—	0000
		15:0	—	—	—	—	—	—	—	—	RCASLAT<3:0>				—	—	DDR2	BURST8	0000
911C	DDR SCLCFG1	31:16	—	—	—	—	—	—	—	—	—	—	—	—	—	—	—	—	0000
		15:0	—	—	—	DBL REFDLY	WCASLAT<3:0>				—	—	—	—	—	—	—	SCLSEN	0000
9120	DDR PHYPADCON	31:16	—	PREAMBDLY<1:0>		RCVREN	—	—	—	—	DRVSTRPFET<3:0>				DRVSTRNFET<3:0>				0000
		15:0	—	HALF RATE	WR CMDDLY	—	—	—	NOEXT DLL	EOEN CLKCYC	ODTPUCAL<1:0>		ODTPDCAL<1:0>		ADDC DRVSEL	DAT DRVSEL	ODTEN	ODTSEL	0000
9124	DDR PHYDLLR	31:16	DLYSTVAL<3:0>				—	DIS RECALIB	RECALIBCNT<17:8>										0000
		15:0	RECALIBCNT<7:0>								—	—	—	—	—	—	—	—	0000
9128	DDR PHYDLLCTRL	31:16	—	—	—	—	—	—	—	—	—	—	—	—	—	—	—	—	0000
		15:0	—	—	—	—	—	—	—	—	DDRDLLTRIM<7:0>								0000
9140	DDR PHYCLKDLY	31:16	—	—	—	—	—	—	—	—	—	—	—	—	—	—	—	—	0000
		15:0	—	—	—	—	—	—	—	—	—	—	SCL UBPASS	SCL LBPASS	—	CLKDLYDELTA<2:0>			0000
915C	DDR ADLLBYP	31:16	—	—	—	—	—	—	—	ANL DLLBYP	—	—	—	—	—	—	—	—	0000
		15:0	—	—	—	—	—	—	—	—	—	—	—	—	—	—	—	—	0000
916C	DDR SCLCFG2	31:16	—	—	—	—	—	—	—	—	—	—	—	—	—	—	—	—	0000
		15:0	—	—	—	—	—	—	—	—	—	—	—	—	—	—	SCLLANSEL<1:0>		0000
9188	DDR PHYSCLADR	31:16	SCLBANKADR<3:0>				SCLCOLADR<12:0>												0000
		15:0	SCLROWADR<15:0>																0000

REGISTER 39-4: SDHCRESPx: SDHC RESPONSE REGISTER 'x' ('x' = 0-3)

Bit Range	Bit 31/23/15/7	Bit 30/22/14/6	Bit 29/21/13/5	Bit 28/20/12/4	Bit 27/19/11/3	Bit 26/18/10/2	Bit 25/17/9/1	Bit 24/16/8/0
31:24	R-0	R-0	R-0	R-0	R-0	R-0	R-0	R-0
	RESP<31:24>							
23:16	R-0	R-0	R-0	R-0	R-0	R-0	R-0	R-0
	RESP<23:16>							
15:8	R-0	R-0	R-0	R-0	R-0	R-0	R-0	R-0
	RESP<15:8>							
7:0	R-0	R-0	R-0	R-0	R-0	R-0	R-0	R-0
	RESP<7:0>							

Legend:			
R = Readable bit	W = Writable bit	U = Unimplemented bit, read as '0'	
-n = Value at POR	'1' = Bit is set	'0' = Bit is cleared	x = Bit is unknown

bit 31-0 **RESP<31:0>:** Response bits

These bits indicate the bit positions of Responses [31:0] defined in the *"SD Host Controller Simplified Specification* (version 2.00). Refer to Table 39-2 for full bit definitions.

TABLE 39-2: RESPONSE BIT DEFINITION FOR EACH RESPONSE TYPE

Response Type (see Note 1)	Response Meaning	Response Register
R1, R1b (normal response)	Card status	SDHCRESP0<31:0>
R1b (Auto CMD12 response)	Card status for Auto CMD12	SDHCRESP3<31:0>
R2 (CID, CSD register)	CID or CSD register	SDHCRESP0<31:0> SDHCRESP1<31:0> SDHCRESP2<31:0> SDHCRESP3<31:0>
R3 (OCR register)	OCR register for memory	SDHCRESP0<31:0>
R4 (OCR register)	OCR register for I/O, etc.	SDHCRESP0<31:0>
R5, R5b	SDIO response	SDHCRESP0<31:0>
R6 (published RCA response)	New published RCA<31:16>, etc.	SDHCRESP0<31:0>

Note 1: For additional information, refer to the "*SD Host Controller Simplified Specification"* (version 2.00), the "*Physical Layer Simplified Specification"* (version 2.00), and the *"SDIO Simplified Specification"* (version 2.00). These documents are available for download by visiting the SD Association web site at: http://www.sdcard.org/downloads/pls/simplified_specs/archive/index.html

TABLE 40-1: POWER-SAVING MODES REGISTER SUMMARY

Virtual Address (BF8C_#)	Register Name(2)	Bit Range	Bits															All Resets(1)
			31/15	30/14	29/13	28/12	27/11	26/10	25/9	24/8	23/7	22/6	21/5	20/4	19/3	18/2	17/1	16/0	
02A8	DSGPR27	31:16	Deep Sleep Persistent General Purpose bits <31:16>																0000
		15:0	Deep Sleep Persistent General Purpose bits <15:0>																0000
02AC	DSGPR28	31:16	Deep Sleep Persistent General Purpose bits <31:16>																0000
		15:0	Deep Sleep Persistent General Purpose bits <15:0>																0000
02B0	DSGPR29	31:16	Deep Sleep Persistent General Purpose bits <31:16>																0000
		15:0	Deep Sleep Persistent General Purpose bits <15:0>																0000
02B4	DSGPR30	31:16	Deep Sleep Persistent General Purpose bits <31:16>																0000
		15:0	Deep Sleep Persistent General Purpose bits <15:0>																0000
02B8	DSGPR31	31:16	Deep Sleep Persistent General Purpose bits <31:16>																0000
		15:0	Deep Sleep Persistent General Purpose bits <15:0>																0000
02BC	DSGPR32	31:16	Deep Sleep Persistent General Purpose bits <31:16>																0000
		15:0	Deep Sleep Persistent General Purpose bits <15:0>																0000

Legend: — = unimplemented, read as '0'.

Note 1: The DSGPR0 register is persistent in all device modes of operation.

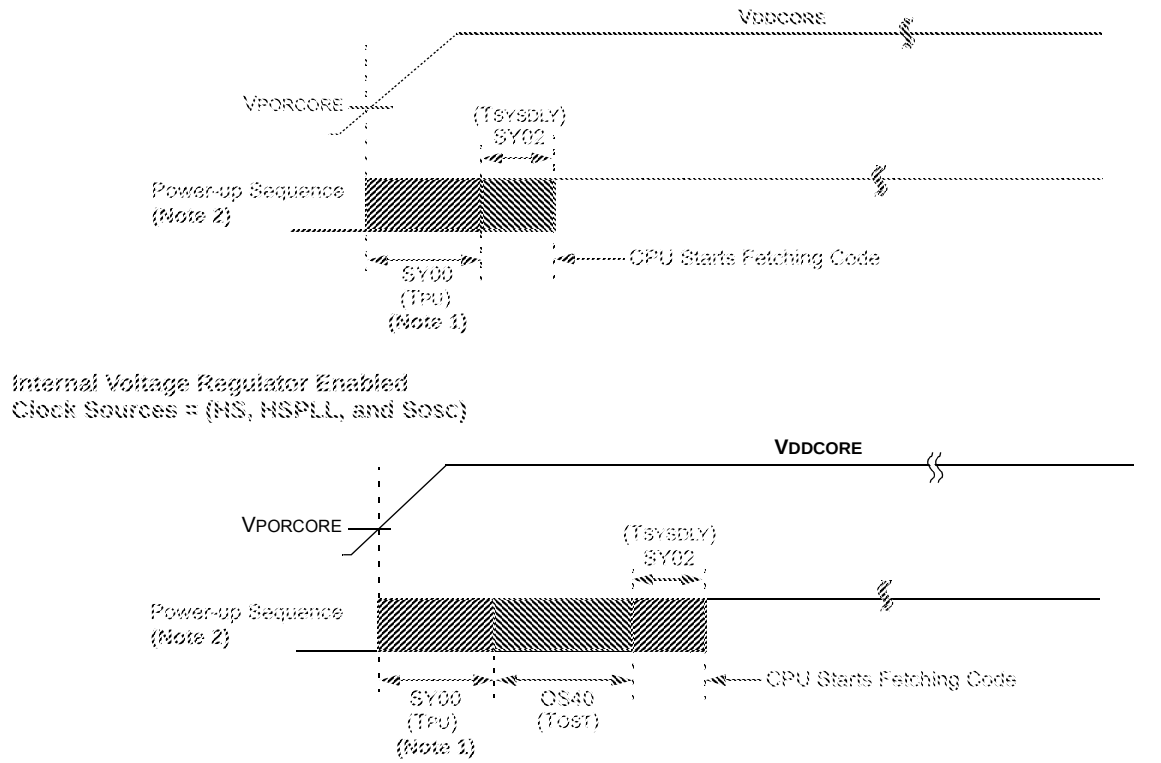
2: The Deep Sleep Control registers can only be accessed after the system unlock sequence has been performed. In addition, these registers must be written twice.

TABLE 44-26: MPLL CLOCK TIMING REQUIREMENTS

AC CHARACTERISTICS			Standard Operating Conditions: V_{DDIO} = 2.2V to 3.6V, V_{DDCORE} = 1.7V to 1.9V (unless otherwise stated) Operating temperature -40°C ≤ TA ≤ +85°C for Industrial				
Param. No.	**Symbol**	**Characteristic(1)**	**Min.**	**Typ.**	**Max.**	**Units**	**Conditions**
MP10	MF_{IN}	MPLL Input Frequency	8	—	64	MHz	—
MP11	MFV_{CO}	MPLL Vco Frequency Range	400	—	1600	MHz	—
MP12	MF_{MPLL}	MPLL Output Frequency	8	—	400	MHz	—
MP13	M_{LOCK}	MPLL Start-up Time (Lock Time)	—	—	1500 x 1/MF_{IN}	µs	—
MP14	M_{PJ}	MPLL Period Jitter	—		0.015	%	—
MP15	M_{CJ}	MPLL Cycle Jitter	—	—	0.02	%	—
MP16	M_{LTJ}	MPLL Long-term Jitter	—	—	0.5	%	—

Note 1: These parameters are characterized, but not test in manufacturing.

FIGURE 44-4: POWER-ON RESET TIMING CHARACTERISTICS



Note 1: The power-up period will be extended if the power-up sequence completes before the device exits from BOR ($V_{DDIO} < V_{DDIOMIN}$).

2: Includes interval voltage regulator stabilization delay.