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"[Embedded - Microcontrollers](#)" refer to small, integrated circuits designed to perform specific tasks within larger systems. These microcontrollers are essentially compact computers on a single chip, containing a processor core, memory, and programmable input/output peripherals. They are called "embedded" because they are embedded within electronic devices to control various functions, rather than serving as standalone computers. Microcontrollers are crucial in modern electronics, providing the intelligence and control needed for a wide range of applications.

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Details

Product Status	Obsolete
Core Processor	80C51
Core Size	8-Bit
Speed	40/20MHz
Connectivity	UART/USART
Peripherals	POR, WDT
Number of I/O	32
Program Memory Size	32KB (32K x 8)
Program Memory Type	OTP
EEPROM Size	-
RAM Size	256 x 8
Voltage - Supply (Vcc/Vdd)	4.5V ~ 5.5V
Data Converters	-
Oscillator Type	Internal
Operating Temperature	-40°C ~ 85°C (TA)
Mounting Type	Surface Mount
Package / Case	44-LCC (J-Lead)
Supplier Device Package	44-PLCC (16.6x16.6)
Purchase URL	https://www.e-xfl.com/product-detail/microchip-technology/at87c58x2-slrum

The TS80C54/58X2 has 2 software-selectable modes of reduced activity for further reduction in power consumption. In the idle mode the CPU is frozen while the timers, the serial port and the interrupt system are still operating. In the power-down mode the RAM is saved and all other functions are inoperative.

PDIL40 PLCC44 PQFP44 F1 VQFP44 1.4	ROM (bytes)	EPROM (bytes)
TS80C54X2	16k	0
TS80C58X2	32k	0
TS87C54X2	0	16k
TS87C58X2	0	32k

2. Block Diagram

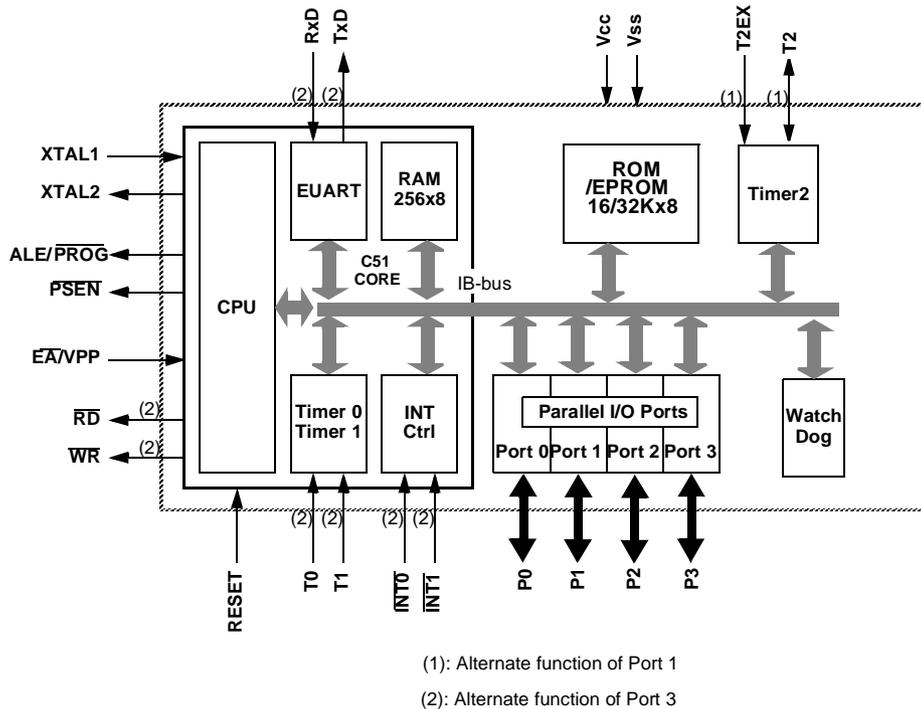
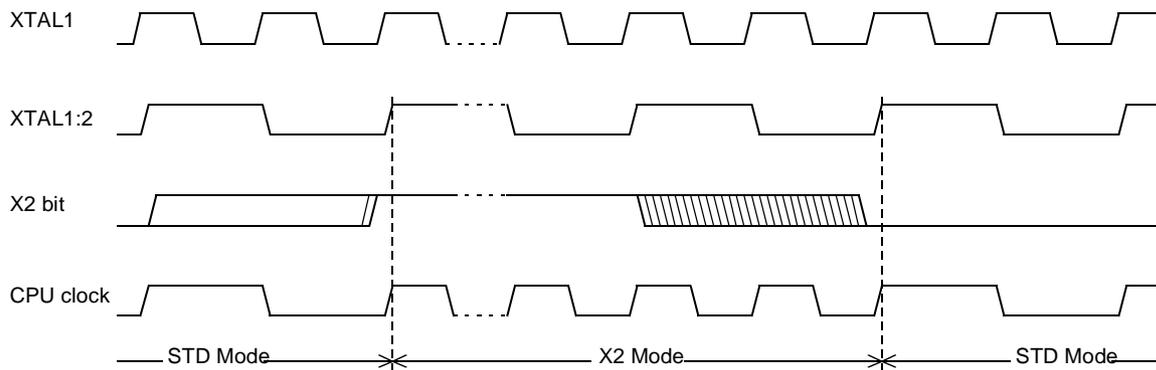




Table 5-1. Pin Description for 40/44 pin packages

MNEMONIC	PIN NUMBER			TYPE	Name And Function
	DIL	LCC	VQFP 1.4		
V _{SS}	20	22	16	I	Ground: 0V reference
V _{SS1}		1	39	I	Optional Ground: Contact the Sales Office for ground connection.
V _{CC}	40	44	38	I	Power Supply: This is the power supply voltage for normal, idle and power-down operation
P0.0-P0.7	39-32	43-36	37-30	I/O	Port 0: Port 0 is an open-drain, bidirectional I/O port. Port 0 pins that have 1s written to them float and can be used as high impedance inputs. Port 0 pins must be polarized to V _{CC} or V _{SS} in order to prevent any parasitic current consumption. Port 0 is also the multiplexed low-order address and data bus during access to external program and data memory. In this application, it uses strong internal pull-up when emitting 1s. Port 0 also inputs the code bytes during EPROM programming. External pull-ups are required during program verification during which P0 outputs the code bytes.
P1.0-P1.7	1-8	2-9	40-44 1-3	I/O	Port 1: Port 1 is an 8-bit bidirectional I/O port with internal pull-ups. Port 1 pins that have 1s written to them are pulled high by the internal pull-ups and can be used as inputs. As inputs, Port 1 pins that are externally pulled low will source current because of the internal pull-ups. Port 1 also receives the low-order address byte during memory programming and verification. Alternate functions for Port 1 include:
	1	2	40	I/O	T2 (P1.0): Timer/Counter 2 external count input/Clockout
	2	3	41	I	T2EX (P1.1): Timer/Counter 2 Reload/Capture/Direction Control
P2.0-P2.7	21-28	24-31	18-25	I/O	Port 2: Port 2 is an 8-bit bidirectional I/O port with internal pull-ups. Port 2 pins that have 1s written to them are pulled high by the internal pull-ups and can be used as inputs. As inputs, Port 2 pins that are externally pulled low will source current because of the internal pull-ups. Port 2 emits the high-order address byte during fetches from external program memory and during accesses to external data memory that use 16-bit addresses (MOVX @DPTR). In this application, it uses strong internal pull-ups emitting 1s. During accesses to external data memory that use 8-bit addresses (MOVX @Ri), port 2 emits the contents of the P2 SFR. Some Port 2 pins receive the high order address bits during EPROM programming and verification: P2.0 to P2.5 for A8 to A13
P3.0-P3.7	10-17	11, 13-19	5, 7-13	I/O	Port 3: Port 3 is an 8-bit bidirectional I/O port with internal pull-ups. Port 3 pins that have 1s written to them are pulled high by the internal pull-ups and can be used as inputs. As inputs, Port 3 pins that are externally pulled low will source current because of the internal pull-ups. Some Port 3 pin P3.4 receive the high order address bits during EPROM programming and verification for TS8xC58X2 devices. Port 3 also serves the special features of the 80C51 family, as listed below.
	10	11	5	I	RXD (P3.0): Serial input port
	11	13	7	O	TXD (P3.1): Serial output port
	12	14	8	I	INT0 (P3.2): External interrupt 0
	13	15	9	I	INT1 (P3.3): External interrupt 1
	14	16	10	I	T0 (P3.4): Timer 0 external input
	15	17	11	I	T1 (P3.5): Timer 1 external input
	16	18	12	O	WR (P3.6): External data memory write strobe
	17	19	13	O	RD (P3.7): External data memory read strobe P3.4 also receives A14 during TS87C58X2 EPROM Programming.
Reset	9	10	4	I	Reset: A high on this pin for two machine cycles while the oscillator is running, resets the device. An internal diffused resistor to V _{SS} permits a power-on reset using only an external capacitor to V _{CC} .

Figure 6-2. Mode Switching Waveforms



The X2 bit in the CKCON register (See Table 6-1.) allows to switch from 12 clock cycles per instruction to 6 clock cycles and vice versa. At reset, the standard speed is activated (STD mode). Setting this bit activates the X2 feature (X2 mode).

CAUTION

In order to prevent any incorrect operation while operating in X2 mode, user must be aware that all peripherals using clock frequency as time reference (UART, timers) will have their time reference divided by two. For example a free running timer generating an interrupt every 20 ms will then generate an interrupt every 10 ms. UART with 4800 baud rate will have 9600 baud rate.

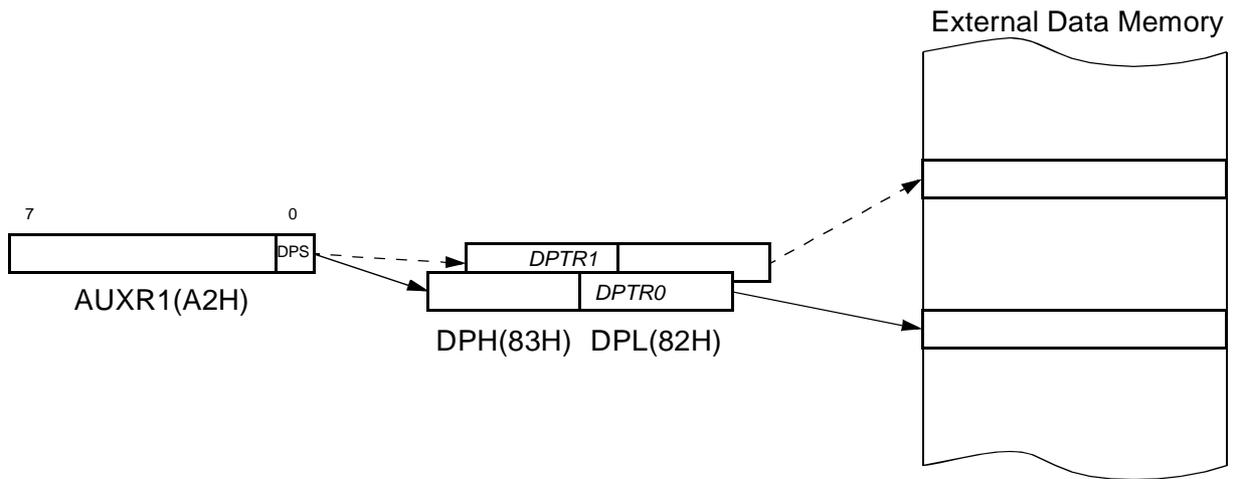
7. Dual Data Pointer Register Ddptr

The additional data pointer can be used to speed up code execution and reduce code size in a number of ways.

The dual DPTR structure is a way by which the chip will specify the address of an external data memory location. There are two 16-bit DPTR registers that address the external memory, and a single bit called

DPS = AUXR1/bit0 (See Table 7-1.) that allows the program code to switch between them (Refer to Figure 7-1).

Figure 7-1. Use of Dual Pointer



7.1 Application

Software can take advantage of the additional data pointers to both increase speed and reduce code size, for example, block operations (copy, compare, search ...) are well served by using one data pointer as a 'source' pointer and the other one as a "destination" pointer.

ASSEMBLY LANGUAGE

```

; Block move using dual data pointers
; Destroys DPTR0, DPTR1, A and PSW
; note: DPS exits opposite of entry state
; unless an extra INC AUXR1 is added
;
00A2          AUXR1 EQU 0A2H
;
0000 909000   MOV  DPTR,#SOURCE      ; address of SOURCE
0003 05A2     INC  AUXR1           ; switch data pointers
0005 90A000   MOV  DPTR,#DEST      ; address of DEST
0008          LOOP:
0008 05A2     INC  AUXR1           ; switch data pointers
000A E0       MOVX A,@DPTR        ; get a byte from SOURCE
000B A3       INC  DPTR           ; increment SOURCE address
000C 05A2     INC  AUXR1           ; switch data pointers
000E F0       MOVX @DPTR,A        ; write the byte to DEST
000F A3       INC  DPTR           ; increment DEST address
0010 70F6     JNZ  LOOP           ; check for 0 terminator
0012 05A2     INC  AUXR1           ; (optional) restore DPS

```

INC is a short (2 bytes) and fast (12 clocks) way to manipulate the DPS bit in the AUXR1 SFR. However, note that the INC instruction does not directly force the DPS bit to a particular state, but simply toggles it. In simple routines, such as the block move example, only the fact that DPS is toggled in the proper sequence matters, not its actual value. In other words, the block move routine works the same whether DPS is '0' or '1' on entry. Observe that without the last instruction (INC AUXR1), the routine will exit with DPS in the opposite state.



- Enter a 16-bit initial value in timer registers TH2/TL2. It can be the same as the reload value or a different one depending on the application.
- To start the timer, set TR2 run control bit in T2CON register.

It is possible to use timer 2 as a baud rate generator and a clock generator simultaneously. For this configuration, the baud rates and clock frequencies are not independent since both functions use the values in the RCAP2H and RCAP2L registers.

Figure 8-2. Clock-Out Mode $C/\overline{T2} = 0$

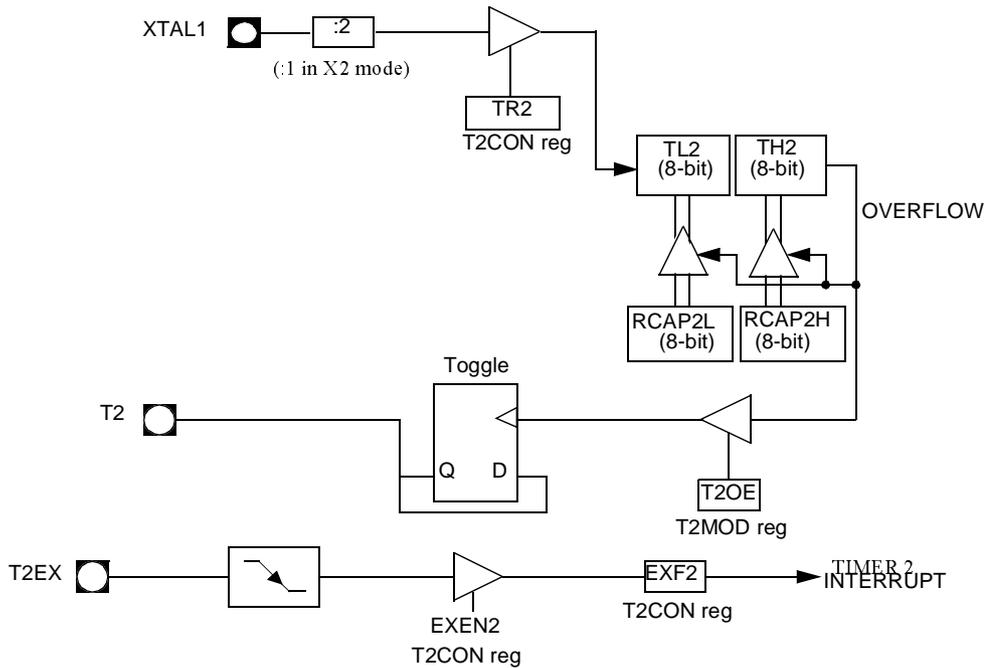
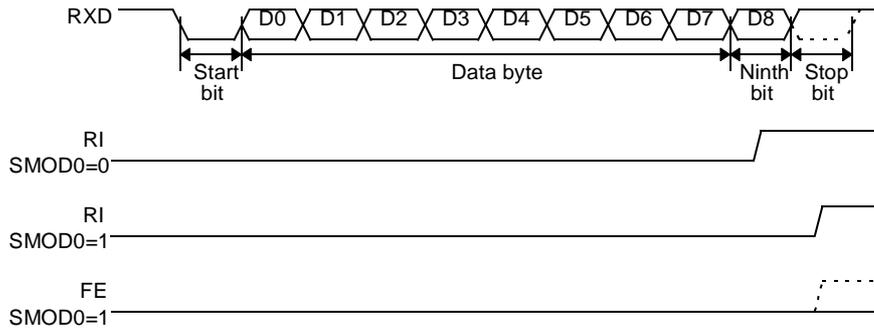


Figure 9-3. UART Timings in Modes 2 and 3



9.1.1 Automatic Address Recognition

The automatic address recognition feature is enabled when the multiprocessor communication feature is enabled (SM2 bit in SCON register is set).

Implemented in hardware, automatic address recognition enhances the multiprocessor communication feature by allowing the serial port to examine the address of each incoming command frame. Only when the serial port recognizes its own address, the receiver sets RI bit in SCON register to generate an interrupt. This ensures that the CPU is not interrupted by command frames addressed to other devices.

If desired, you may enable the automatic address recognition feature in mode 1. In this configuration, the stop bit takes the place of the ninth data bit. Bit RI is set only when the received command frame address matches the device's address and is terminated by a valid stop bit.

To support automatic address recognition, a device is identified by a given address and a broadcast address.

NOTE: The multiprocessor communication and automatic address recognition features cannot be enabled in mode 0 (i.e. setting SM2 bit in SCON register in mode 0 has no effect).

9.1.2 Given Address

Each device has an individual address that is specified in SADDR register; the SADEN register is a mask byte that contains don't-care bits (defined by zeros) to form the device's given address. The don't-care bits provide the flexibility to address one or more slaves at a time. The following example illustrates how a given address is formed.

To address a device by its individual address, the SADEN mask byte must be 1111 1111b.

For example:

SADDR	0101 0110b
SADEN	1111 1100b
Given	0101 01XXb

If two interrupt requests of different priority levels are received simultaneously, the request of higher priority level is serviced. If interrupt requests of the same priority level are received simultaneously, an internal polling sequence determines which request is serviced. Thus within each priority level there is a second priority structure determined by the polling sequence.

Table 10-2. IE Register
IE - Interrupt Enable Register (A8h)

7	6	5	4	3	2	1	0
EA	-	ET2	ES	ET1	EX1	ET0	EX0

Bit Number	Bit Mnemonic	Description
7	EA	Enable All interrupt bit Clear to disable all interrupts. Set to enable all interrupts. If EA=1, each interrupt source is individually enabled or disabled by setting or clearing its own interrupt enable bit.
6	-	Reserved The value read from this bit is indeterminate. Do not set this bit.
5	ET2	Timer 2 overflow interrupt Enable bit Clear to disable timer 2 overflow interrupt. Set to enable timer 2 overflow interrupt.
4	ES	Serial port Enable bit Clear to disable serial port interrupt. Set to enable serial port interrupt.
3	ET1	Timer 1 overflow interrupt Enable bit Clear to disable timer 1 overflow interrupt. Set to enable timer 1 overflow interrupt.
2	EX1	External interrupt 1 Enable bit Clear to disable external interrupt 1. Set to enable external interrupt 1.
1	ET0	Timer 0 overflow interrupt Enable bit Clear to disable timer 0 overflow interrupt. Set to enable timer 0 overflow interrupt.
0	EX0	External interrupt 0 Enable bit Clear to disable external interrupt 0. Set to enable external interrupt 0.

Reset Value = 0X00 0000b

Bit addressable

Table 10-3. IP Register
IP - Interrupt Priority Register (B8h)

7	6	5	4	3	2	1	0
-	-	PT2	PS	PT1	PX1	PT0	PX0

Bit Number	Bit Mnemonic	Description
7	-	Reserved The value read from this bit is indeterminate. Do not set this bit.
6	-	Reserved The value read from this bit is indeterminate. Do not set this bit.
5	PT2	Timer 2 overflow interrupt Priority bit Refer to PT2H for priority level.
4	PS	Serial port Priority bit Refer to PSH for priority level.
3	PT1	Timer 1 overflow interrupt Priority bit Refer to PT1H for priority level.
2	PX1	External interrupt 1 Priority bit Refer to PX1H for priority level.
1	PT0	Timer 0 overflow interrupt Priority bit Refer to PT0H for priority level.
0	PX0	External interrupt 0 Priority bit Refer to PX0H for priority level.

Reset Value = XX00 0000b

Bit addressable



14. Power-Off Flag

The power-off flag allows the user to distinguish between a “cold start” reset and a “warm start” reset.

A cold start reset is the one induced by V_{CC} switch-on. A warm start reset occurs while V_{CC} is still applied to the device and could be generated for example by an exit from power-down.

The power-off flag (POF) is located in PCON register (See Table 14-1.). POF is set by hardware when V_{CC} rises from 0 to its nominal voltage. The POF can be set or cleared by software allowing the user to determine the type of reset.

The POF value is only relevant with a V_{CC} range from 4.5V to 5.5V. For lower V_{CC} value, reading POF bit will return indeterminate value.

Table 14-1. PCON Register
PCON - Power Control Register (87h)

7	6	5	4	3	2	1	0
SMOD1	SMOD0	-	POF	GF1	GF0	PD	IDL

Bit Number	Bit Mnemonic	Description
7	SMOD1	Serial port Mode bit 1 Set to select double baud rate in mode 1, 2 or 3.
6	SMOD0	Serial port Mode bit 0 Clear to select SM0 bit in SCON register. Set to to select FE bit in SCON register.
5	-	Reserved The value read from this bit is indeterminate. Do not set this bit.
4	POF	Power-Off Flag Clear to recognize next reset type. Set by hardware when V_{CC} rises from 0 to its nominal voltage. Can also be set by software.
3	GF1	General purpose Flag Cleared by user for general purpose usage. Set by user for general purpose usage.
2	GF0	General purpose Flag Cleared by user for general purpose usage. Set by user for general purpose usage.
1	PD	Power-Down mode bit Cleared by hardware when reset occurs. Set to enter power-down mode.
0	IDL	Idle mode bit Clear by hardware when interrupt or reset occurs. Set to enter idle mode.

Reset Value = 00X1 0000b

Not bit addressable

15. Reduced EMI Mode

The ALE signal is used to demultiplex address and data buses on port 0 when used with external program or data memory. Nevertheless, during internal code execution, ALE signal is still generated. In order to reduce EMI, ALE signal can be disabled by setting AO bit.

The AO bit is located in AUXR register at bit location 0. As soon as AO is set, ALE is no longer output but remains active during MOVX and MOVC instructions and external fetches. During ALE disabling, ALE pin is weakly pulled high.

Table 15-1. AUXR Register
AUXR - Auxiliary Register (8Eh)

7	6	5	4	3	2	1	0
-	-	-	-	-	-	RESERVED	AO

Bit Number	Bit Mnemonic	Description
7	-	Reserved The value read from this bit is indeterminate. Do not set this bit.
6	-	Reserved The value read from this bit is indeterminate. Do not set this bit.
5	-	Reserved The value read from this bit is indeterminate. Do not set this bit.
4	-	Reserved The value read from this bit is indeterminate. Do not set this bit.
3	-	Reserved The value read from this bit is indeterminate. Do not set this bit.
2	-	Reserved The value read from this bit is indeterminate. Do not set this bit.
1	-	Reserved The value read from this bit is indeterminate. Do not set this bit.
0	AO	ALE Output bit Clear to restore ALE operation during internal fetches. Set to disable ALE operation during internal fetches.

Reset Value = XXXX XXX0b

Not bit addressable

17. TS87C54/58X2 EPROM

17.1 EPROM Structure

The TS87C54/58X2 EPROM is divided in two different arrays:

- the code array:16/32 Kbytes.
- the encryption array:64 bytes.
- In addition a third non programmable array is implemented:
- the signature array: 4 bytes.

17.2 EPROM Lock System

The program Lock system, when programmed, protects the on-chip program against software piracy.

17.2.1 Encryption Array

Within the EPROM array are 64 bytes of encryption array that are initially unprogrammed (all FF's). Every time a byte is addressed during program verify, 6 address lines are used to select a byte of the encryption array. This byte is then exclusive-NOR'ed (XNOR) with the code byte, creating an encrypted verify byte. The algorithm, with the encryption array in the unprogrammed state, will return the code in its original, unmodified form.

When using the encryption array, one important factor needs to be considered. If a byte has the value FFh, verifying the byte will produce the encryption byte value. If a large block (>64 bytes) of code is left unprogrammed, a verification routine will display the content of the encryption array. For this reason all the unused code bytes should be programmed with random values. This will ensure program protection.

17.2.2 Program Lock Bits

The three lock bits, when programmed according to Table 17-1., will provide different level of protection for the on-chip code and data.

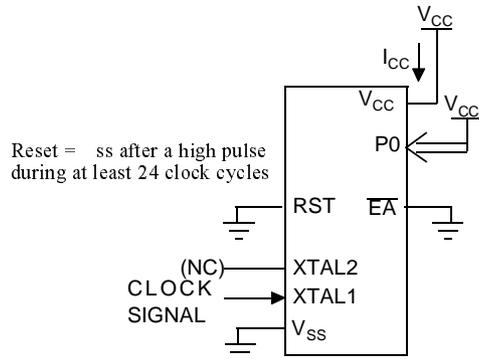
Table 17-1. Program Lock bits

Program Lock Bits				Protection Description
Security level	LB1	LB2	LB3	
1	U	U	U	No program lock features enabled. Code verify will still be encrypted by the encryption array if programmed. MOVC instruction executed from external program memory returns non encrypted data.
2	P	U	U	MOVC instruction executed from external program memory are disabled from fetching code bytes from internal memory, EA is sampled and latched on reset, and further programming of the EPROM is disabled.
3	U	P	U	Same as 2, also verify is disabled.
4	U	U	P	Same as 3, also external execution is disabled.

U: unprogrammed,
P: programmed

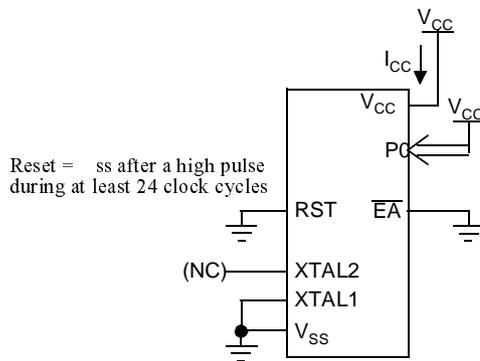
WARNING: Security level 2 and 3 should only be programmed after EPROM and Core verification.

Figure 19-3. I_{CC} Test Condition, Idle Mode



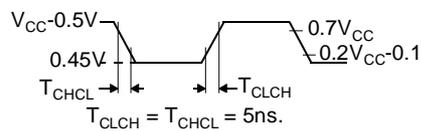
All other pins are disconnected.

Figure 19-4. I_{CC} Test Condition, Power-Down Mode



All other pins are disconnected.

Figure 19-5. Clock Signal Waveform for I_{CC} Tests in Active and Idle Modes



19.5 AC Parameters

19.5.1 Explanation of the AC Symbols

Each timing symbol has 5 characters. The first character is always a “T” (stands for time). The other characters, depending on their positions, stand for the name of a signal or the logical status of that signal. The following is a list of all the characters and what they stand for.

Example: T_{AVLL} = Time for Address Valid to ALE Low.

T_{LLPL} = Time for ALE Low to PSEN Low.

$T_A = 0$ to $+70^\circ\text{C}$ (commercial temperature range); $V_{SS} = 0\text{ V}$; $V_{CC} = 5\text{ V} \pm 10\%$; -M and -V ranges.
 $T_A = -40^\circ\text{C}$ to $+85^\circ\text{C}$ (industrial temperature range); $V_{SS} = 0\text{ V}$; $V_{CC} = 5\text{ V} \pm 10\%$; -M and -V ranges.

$T_A = 0$ to $+70^\circ\text{C}$ (commercial temperature range); $V_{SS} = 0\text{ V}$; $2.7\text{ V} < V_{CC} < 5.5\text{ V}$; -L range.

$T_A = -40^\circ\text{C}$ to $+85^\circ\text{C}$ (industrial temperature range); $V_{SS} = 0\text{ V}$; $2.7\text{ V} < V_{CC} < 5.5\text{ V}$; -L range.

Table 19-3. gives the maximum applicable load capacitance for Port 0, Port 1, 2 and 3, and ALE and PSEN signals. Timings will be guaranteed if these capacitances are respected. Higher capacitance values can be used, but timings will then be degraded.

Table 19-3. Load Capacitance versus speed range, in pF

	-M	-V	-L
Port 0	100	50	100
Port 1, 2, 3	80	50	80
ALE / $\overline{\text{PSEN}}$	100	30	100

Table 19-5., Table 19-8. and Table 19-11. give the description of each AC symbols.

Table 19-6., Table 19-9. and Table 19-12. give for each range the AC parameter.

Table 19-7., Table 19-10. and Table 19-13. give the frequency derating formula of the AC parameter. To calculate each AC symbols, take the x value corresponding to the speed grade you need (-M, -V or -L) and replace this value in the formula. Values of the frequency must be limited to the corresponding speed grade:

Table 19-4. Max frequency for derating formula regarding the speed grade

	-M X1 mode	-M X2 mode	-V X1 mode	-V X2 mode	-L X1 mode	-L X2 mode
Freq (MHz)	40	20	40	30	30	20
T (ns)	25	50	25	33.3	33.3	50

Example:

T_{LLIV} in X2 mode for a -V part at 20 MHz ($T = 1/20^{E6} = 50\text{ ns}$):

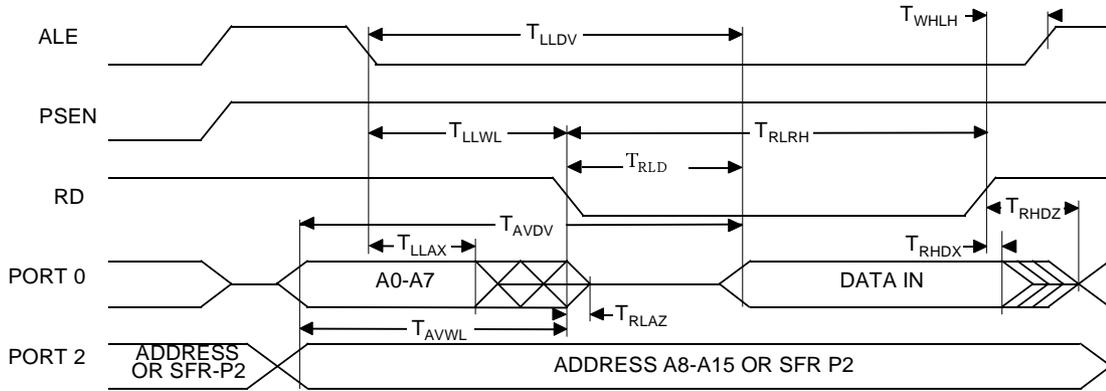
$$x = 22 \text{ (Table 19-7.)}$$

$$T = 50\text{ ns}$$

$$T_{LLIV} = 2T - x = 2 \times 50 - 22 = 78\text{ ns}$$

19.5.6 External Data Memory Read Cycle

Figure 19-8. External Data Memory Read Cycle



19.5.7 Serial Port Timing - Shift Register Mode

Table 19-11. Symbol Description

Symbol	Parameter
T_{XLXL}	Serial port clock cycle time
T_{QVHX}	Output data set-up to clock rising edge
T_{XHGX}	Output data hold after clock rising edge
T_{XHDX}	Input data hold after clock rising edge
T_{XHDV}	Clock rising edge to input data valid

Table 19-12. AC Parameters for a Fix Clock

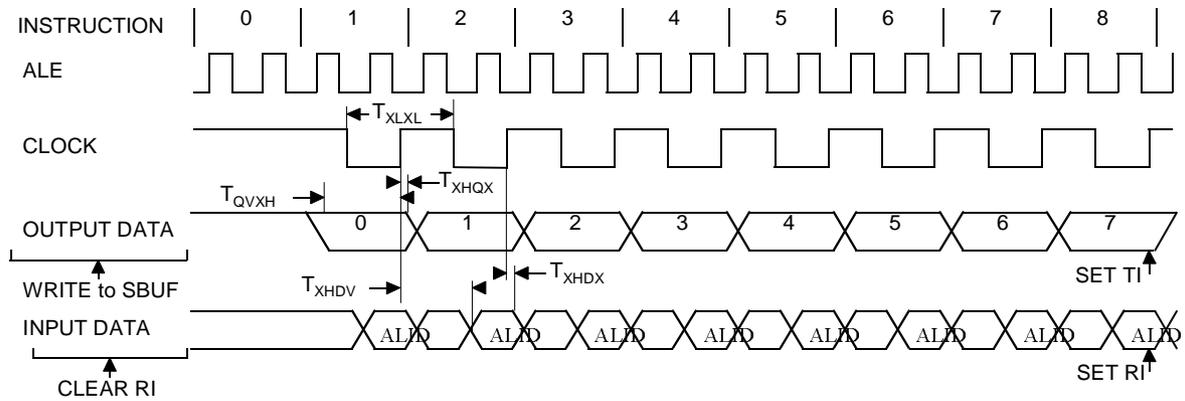
Speed	-M 40 MHz		-V X2 mode 30 MHz 60 MHz equiv.		-V standard mode 40 MHz		-L X2 mode 20 MHz 40 MHz equiv.		-L standard mode 30 MHz		Units
	Min	Max	Min	Max	Min	Max	Min	Max	Min	Max	
T_{XLXL}	300		200		300		300		400		ns
T_{QVHX}	200		117		200		200		283		ns
T_{XHGX}	30		13		30		30		47		ns
T_{XHDX}	0		0		0		0		0		ns
T_{XHDV}		117		34		117		117		200	ns

Table 19-13. AC Parameters for a Variable Clock: derating formula

Symbol	Type	Standard Clock	X2 Clock	-M	-V	-L	Units
T_{XLXL}	Min	12 T	6 T				ns
T_{QVXH}	Min	10 T - x	5 T - x	50	50	50	ns
T_{XHGX}	Min	2 T - x	T - x	20	20	20	ns
T_{XHDX}	Min	x	x	0	0	0	ns
T_{XHDV}	Max	10 T - x	5 T - x	133	133	133	ns

19.5.8 Shift Register Timing Waveforms

Figure 19-9. Shift Register Timing Waveforms





20. Ordering Information

Table 20-1. Possible Ordering Entries

Part Number	Supply Voltage	Temperature Range	Package	Packing
TS80C54X2xxx-MCA	-5 to +/-10%	Commercial	PDIL40	Stick
TS80C54X2xxx-MCB	-5 to +/-10%	Commercial	PLCC44	Stick
TS80C54X2xxx-MCC	-5 to +/-10%	Commercial	PQFP44	Tray
TS80C54X2xxx-MCE	-5 to +/-10%	Commercial	VQFP44	Tray
TS80C54X2xxx-VCA	-5 to +/-10%	Commercial	PDIL40	Stick
TS80C54X2xxx-VCB	-5 to +/-10%	Commercial	PLCC44	Stick
TS80C54X2xxx-VCC	-5 to +/-10%	Commercial	PQFP44	Tray
TS80C54X2xxx-VCE	-5 to +/-10%	Commercial	VQFP44	Tray
TS80C54X2xxx-LCA	-5 to +/-10%	Commercial	PDIL40	Stick
TS80C54X2xxx-LCB	-5 to +/-10%	Commercial	PLCC44	Stick
TS80C54X2xxx-LCC	-5 to +/-10%	Commercial	PQFP44	Tray
TS80C54X2xxx-LCE	-5 to +/-10%	Commercial	VQFP44	Tray
TS80C54X2xxx-MIA	-5 to +/-10%	Industrial	PDIL40	Stick
TS80C54X2xxx-MIB	-5 to +/-10%	Industrial	PLCC44	Stick
TS80C54X2xxx-MIC	-5 to +/-10%	Industrial	PQFP44	Tray
TS80C54X2xxx-MIE	-5 to +/-10%	Industrial	VQFP44	Tray
TS80C54X2xxx-VIA	-5 to +/-10%	Industrial	PDIL40	Stick
TS80C54X2xxx-VIB	-5 to +/-10%	Industrial	PLCC44	Stick
TS80C54X2xxx-VIC	-5 to +/-10%	Industrial	PQFP44	Tray
TS80C54X2xxx-VIE	-5 to +/-10%	Industrial	VQFP44	Tray
TS80C54X2xxx-LIA	-5 to +/-10%	Industrial	PDIL40	Stick
TS80C54X2xxx-LIB	-5 to +/-10%	Industrial	PLCC44	Stick
TS80C54X2xxx-LIC	-5 to +/-10%	Industrial	PQFP44	Tray
TS80C54X2xxx-LIE	-5 to +/-10%	Industrial	VQFP44	Tray
AT80C54X2zzz-3CSUM	-5 to +/-10%	Industrial & Green	PDIL40	Stick
AT80C54X2zzz-SLSUM	-5 to +/-10%	Industrial & Green	PLCC44	Stick
AT80C54X2zzz-RLTUM	-5 to +/-10%	Industrial & Green	VQFP44	Tray
AT80C54X2zzz-3CSUL	-5 to +/-10%	Industrial & Green	PDIL40	Stick
AT80C54X2zzz-SLSUL	-5 to +/-10%	Industrial & Green	PLCC44	Stick
AT80C54X2zzz-RLTUL	-5 to +/-10%	Industrial & Green	VQFP44	Tray
AT80C54X2zzz-3CSUV	-5 to +/-10%	Industrial & Green	PDIL40	Stick
AT80C54X2zzz-SLSUV	-5 to +/-10%	Industrial & Green	PLCC44	Stick
AT80C54X2zzz-RLTUV	-5 to +/-10%	Industrial & Green	VQFP44	Tray
TS87C54X2-MCA	5V ±10%	Commercial	PDIL40	Stick
TS87C54X2-MCB	5V ±10%	Commercial	PLCC44	Stick

Part Number	Supply Voltage	Temperature Range	Package	Packing
TS80C58X2xxx-MCA	-5 to +/-10%	Commercial	PDIL40	Stick
TS80C58X2xxx-MCB	-5 to +/-10%	Commercial	PLCC44	Stick
TS80C58X2xxx-MCC	-5 to +/-10%	Commercial	PQFP44	Tray
TS80C58X2xxx-MCE	-5 to +/-10%	Commercial	VQFP44	Tray
TS80C58X2xxx-VCA	-5 to +/-10%	Commercial	PDIL40	Stick
TS80C58X2xxx-VCB	-5 to +/-10%	Commercial	PLCC44	Stick
TS80C58X2xxx-VCC	-5 to +/-10%	Commercial	PQFP44	Tray
TS80C58X2xxx-VCE	-5 to +/-10%	Commercial	VQFP44	Tray
TS80C58X2xxx-LCA	-5 to +/-10%	Commercial	PDIL40	Stick
TS80C58X2xxx-LCB	-5 to +/-10%	Commercial	PLCC44	Stick
TS80C58X2xxx-LCC	-5 to +/-10%	Commercial	PQFP44	Tray
TS80C58X2xxx-LCE	-5 to +/-10%	Commercial	VQFP44	Tray
TS80C58X2xxx-MIA	-5 to +/-10%	Industrial	PDIL40	Stick
TS80C58X2xxx-MIB	-5 to +/-10%	Industrial	PLCC44	Stick
TS80C58X2xxx-MIC	-5 to +/-10%	Industrial	PQFP44	Tray
TS80C58X2xxx-MIE	-5 to +/-10%	Industrial	VQFP44	Tray
TS80C58X2xxx-VIA	-5 to +/-10%	Industrial	PDIL40	Stick
TS80C58X2xxx-VIB	-5 to +/-10%	Industrial	PLCC44	Stick
TS80C58X2xxx-VIC	-5 to +/-10%	Industrial	PQFP44	Tray
TS80C58X2xxx-VIE	-5 to +/-10%	Industrial	VQFP44	Tray
TS80C58X2xxx-LIA	-5 to +/-10%	Industrial	PDIL40	Stick
TS80C58X2xxx-LIB	-5 to +/-10%	Industrial	PLCC44	Stick
TS80C58X2xxx-LIC	-5 to +/-10%	Industrial	PQFP44	Tray
TS80C58X2xxx-LIE	-5 to +/-10%	Industrial	VQFP44	Tray
AT80C58X2zzz-3CSUM	-5 to +/-10%	Industrial & Green	PDIL40	Stick
AT80C58X2zzz-SLSUM	-5 to +/-10%	Industrial & Green	PLCC44	Stick
AT80C58X2zzz-RLTUM	-5 to +/-10%	Industrial & Green	VQFP44	Tray
AT80C58X2zzz-3CSUL	-5 to +/-10%	Industrial & Green	PDIL40	Stick
AT80C58X2zzz-SLSUL	-5 to +/-10%	Industrial & Green	PLCC44	Stick
AT80C58X2zzz-RLTUL	-5 to +/-10%	Industrial & Green	VQFP44	Tray
AT80C58X2zzz-3CSUV	-5 to +/-10%	Industrial & Green	PDIL40	Stick
AT80C58X2zzz-SLSUV	-5 to +/-10%	Industrial & Green	PLCC44	Stick
AT80C58X2zzz-RLTUV	-5 to +/-10%	Industrial & Green	VQFP44	Tray
TS87C58X2-MCA	5V ±10%	Commercial	PDIL40	Stick
TS87C58X2-MCB	5V ±10%	Commercial	PLCC44	Stick
TS87C58X2-MCC	5V ±10%	Commercial	PQFP44	Tray

Part Number	Supply Voltage	Temperature Range	Package	Packing
TS87C58X2-MCE	5V ±10%	Commercial	VQFP44	Tray
TS87C58X2-VCA	5V ±10%	Commercial	PDIL40	Stick
TS87C58X2-VCB	5V ±10%	Commercial	PLCC44	Stick
TS87C58X2-VCC	5V ±10%	Commercial	PQFP44	Tray
TS87C58X2-VCE	5V ±10%	Commercial	VQFP44	Tray
TS87C58X2-LCA	2.7 to 5.5V	Commercial	PDIL40	Stick
TS87C58X2-LCB	2.7 to 5.5V	Commercial	PLCC44	Stick
TS87C58X2-LCC	2.7 to 5.5V	Commercial	PQFP44	Tray
TS87C58X2-LCE	2.7 to 5.5V	Commercial	VQFP44	Tray
TS87C58X2-MIA	5V ±10%	Industrial	PDIL40	Stick
TS87C58X2-MIB	5V ±10%	Industrial	PLCC44	Stick
TS87C58X2-MIC	5V ±10%	Industrial	PQFP44	Tray
TS87C58X2-MIE	5V ±10%	Industrial	VQFP44	Tray
TS87C58X2-VIA	5V ±10%	Industrial	PDIL40	Stick
TS87C58X2-VIB	5V ±10%	Industrial	PLCC44	Stick
TS87C58X2-VIC	5V ±10%	Industrial	PQFP44	Tray
TS87C58X2-VIE	5V ±10%	Industrial	VQFP44	Tray
TS87C58X2-LIA	2.7 to 5.5V	Industrial	PDIL40	Stick
TS87C58X2-LIB	2.7 to 5.5V	Industrial	PLCC44	Stick
TS87C58X2-LIC	2.7 to 5.5V	Industrial	PQFP44	Tray
TS87C58X2-LIE	2.7 to 5.5V	Industrial	VQFP44	Tray
AT87C58X2-3CSUM	5V ±10%	Industrial & Green	PDIL40	Stick
AT87C58X2-SLSUM	5V ±10%	Industrial & Green	PLCC44	Stick
AT87C58X2-RLTUM	5V ±10%	Industrial & Green	VQFP44	Tray
AT87C58X2-3CSUL	2.7 to 5.5V	Industrial & Green	PDIL40	Stick
AT87C58X2-SLSUL	2.7 to 5.5V	Industrial & Green	PLCC44	Stick
AT87C58X2-RLTUL	2.7 to 5.5V	Industrial & Green	VQFP44	Tray
AT87C58X2-3CSUV	5V ±10%	Industrial & Green	PDIL40	Stick
AT87C58X2-SLSUV	5V ±10%	Industrial & Green	PLCC44	Stick
AT87C58X2-RLTUV	5V ±10%	Industrial & Green	VQFP44	Tray

21. Datasheet Revision History

21.1 Changes from Rev. C 01/01 to Rev. D 11/05

1. Added green product Ordering Information.

21.2 Changes from Rev. D 11/05 to Rev. E 04/06

1. Changed value of AUXR register.



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