What is "<u>Embedded - Microcontrollers</u>"?

"<u>Embedded - Microcontrollers</u>" refer to small, integrated circuits designed to perform specific tasks within larger systems. These microcontrollers are essentially compact computers on a single chip, containing a processor core, memory, and programmable input/output peripherals. They are called "embedded" because they are embedded within electronic devices to control various functions, rather than serving as standalone computers. Microcontrollers are crucial in modern electronics, providing the intelligence and control needed for a wide range of applications.

Applications of "<u>Embedded - Microcontrollers</u>"

Details	
Product Status	Obsolete
Core Processor	80C51
Core Size	8-Bit
Speed	40/20MHz
Connectivity	UART/USART
Peripherals	POR, WDT
Number of I/O	32
Program Memory Size	16KB (16K x 8)
Program Memory Type	OTP
EEPROM Size	-
RAM Size	256 x 8
Voltage - Supply (Vcc/Vdd)	4.5V ~ 5.5V
Data Converters	-
Oscillator Type	Internal
Operating Temperature	-40°C ~ 85°C (TA)
Mounting Type	Surface Mount
Package / Case	44-QFP
Supplier Device Package	44-VQFP
Purchase URL	https://www.e-xfl.com/product-detail/microchip-technology/ts87c54x2-mie

Table 4-1. All SFRs with their address and their reset value

	Bit address-able	Non Bit addressable							
	0/8	1/9	2/A	3/B	4/C	5/D	6/E	7/F	
F8h									FFh
F0h	B 0000 0000								F7h
E8h									EFh
E0h	ACC 0000 0000								E7h
D8h									DFh
D0h	PSW 0000 0000								D7h
C8h	T2CON 0000 0000	T2MOD XXXX XX00	RCAP2L 0000 0000	RCAP2H 0000 0000	TL2 0000 0000	TH2 0000 0000			CFh
C0h									C7h
B8h	IP XX00 0000	SADEN 0000 0000							BFh
B0h	P3 1111 1111							IPH XX00 0000	B7h
A8h	IE 0X00 0000	SADDR 0000 0000							AFh
A0h	P2 1111 1111		AUXR1 XXXX 0XX0				WDTRST XXXX XXXX	WDTPRG XXXX X000	A7h
98h	SCON 0000 0000	SBUF XXXX XXXX							9Fh
90h	P1 1111 1111								97h
88h	TCON 0000 0000	TMOD 0000 0000	TL0 0000 0000	TL1 0000 0000	TH0 0000 0000	TH1 0000 0000	AUXR XXXX XXX0	CKCON XXXX XXX0	8Fh
80h	P0 1111 1111	SP 0000 0111	DPL 0000 0000	DPH 0000 0000				PCON 00X1 0000	87h
	0/8	1/9	2/A	3/B	4/C	5/D	6/E	7/F	

reserved

6. TS80C54/58X2 Enhanced Features

In comparison to the original 80C52, the TS80C54/58X2 implements some new features, which are:

- The X2 option.
- The Dual Data Pointer.
- The Watchdog.
- The 4 level interrupt priority system.
- The power-off flag.
- The ONCE mode.
- The ALE disabling.
- Some enhanced features are also located in the UART and the timer 2.

6.1   X2 Feature

The TS80C54/58X2 core needs only 6 clock periods per machine cycle. This feature called "X2" provides the following advantages:

- Divide frequency crystals by 2 (cheaper crystals) while keeping same CPU power.
- Save power consumption while keeping same CPU power (oscillator power saving).
- Save power consumption by dividing dynamically operating frequency by 2 in operating and idle modes.
- Increase CPU power by 2 while keeping same crystal frequency.

In order to keep the original C51 compatibility, a divider by 2 is inserted between the XTAL1 signal and the main clock input of the core (phase generator). This divider may be disabled by software.

6.1.1   Description

The clock for the whole circuit and peripheral is first divided by two before being used by the CPU core and peripherals. This allows any cyclic ratio to be accepted on XTAL1 input. In X2 mode, as this divider is bypassed, the signals on XTAL1 must have a cyclic ratio between 40 to 60%. Figure 6-2. shows the clock generation block diagram. X2 bit is validated on XTAL1÷2 rising edge to avoid glitches when switching from X2 to STD mode. Figure 6-2. shows the mode switching waveforms.
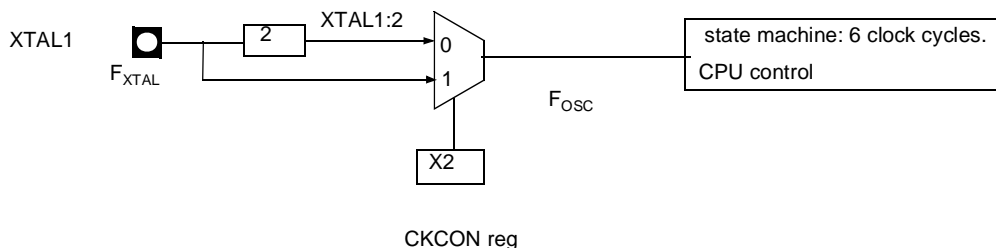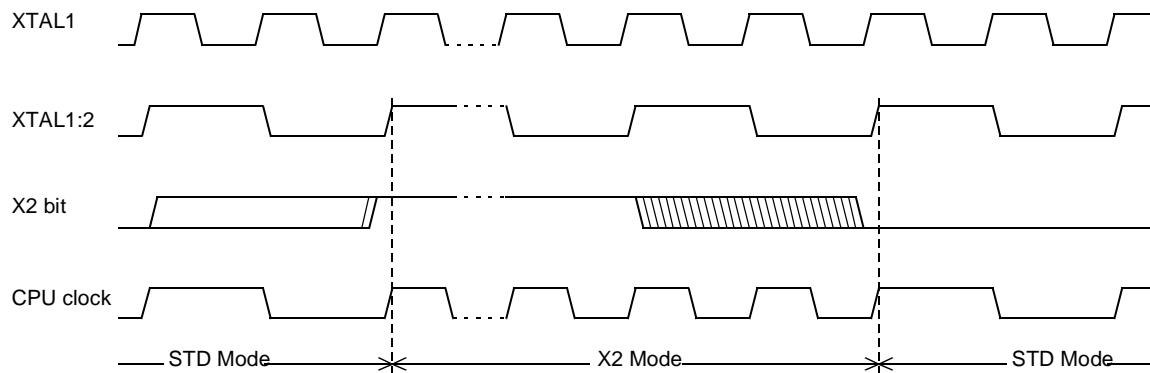
Figure 6-1.   Clock Generation Diagram

Figure 6-2. Mode Switching Waveforms

The X2 bit in the CKCON register (See Table 6-1.) allows to switch from 12 clock cycles per instruction to 6 clock cycles and vice versa. At reset, the standard speed is activated (STD mode). Setting this bit activates the X2 feature (X2 mode).

CAUTION

In order to prevent any incorrect operation while operating in X2 mode, user must be aware that all peripherals using clock frequency as time reference (UART, timers) will have their time reference divided by two. For example a free running timer generating an interrupt every 20 ms will then generate an interrupt every 10 ms. UART with 4800 baud rate will have 9600 baud rate.

8. Timer 2

The timer 2 in the TS80C54/58X2 is compatible with the timer 2 in the 80C52.

It is a 16-bit timer/counter: the count is maintained by two eight-bit timer registers, TH2 and TL2, connected in cascade. It is controlled by T2CON register (See Table 8-1) and T2MOD register (See Table 8-2). Timer 2 operation is similar to Timer 0 and Timer 1. C/$\overline{T2}$ selects F_{OSC}/12 (timer operation) or external pin T2 (counter operation) as the timer clock input. Setting TR2 allows TL2 to be incremented by the selected input.

Timer 2 has 3 operating modes: capture, autoreload and Baud Rate Generator. These modes are selected by the combination of RCLK, TCLK and CP/$\overline{RL2}$ (T2CON), as described in the Atmel Wireless & Microcontrollers 8-bit Microcontroller Hardware description.

Refer to the Atmel Wireless & Microcontrollers 8-bit Microcontroller Hardware description for the description of Capture and Baud Rate Generator Modes.

In TS80C54/58X2 Timer 2 includes the following enhancements:

- Auto-reload mode with up or down counter
- Programmable clock-output

8.1 Auto-Reload Mode

The auto-reload mode configures timer 2 as a 16-bit timer or event counter with automatic reload. If DCEN bit in T2MOD is cleared, timer 2 behaves as in 80C52 (refer to the Atmel Wireless & Microcontrollers 8-bit Microcontroller Hardware description). If DCEN bit is set, timer 2 acts as an Up/down timer/counter as shown in Figure 8-1. In this mode the T2EX pin controls the direction of count.

When T2EX is high, timer 2 counts up. Timer overflow occurs at FFFFh which sets the TF2 flag and generates an interrupt request. The overflow also causes the 16-bit value in RCAP2H and RCAP2L registers to be loaded into the timer registers TH2 and TL2.

When T2EX is low, timer 2 counts down. Timer underflow occurs when the count in the timer registers TH2 and TL2 equals the value stored in RCAP2H and RCAP2L registers. The underflow sets TF2 flag and reloads FFFFh into the timer registers.

The EXF2 bit toggles when timer 2 overflows or underflows according to the the direction of the count. EXF2 does not generate any interrupt. This bit can be used to provide 17-bit resolution

Figure 8-1. Auto-Reload Mode Up/Down Counter (DCEN = 1)

8.1.1 Programmable Clock-Output

In the clock-out mode, timer 2 operates as a 50%-duty-cycle, programmable clock generator (See Figure 8-2) . The input clock increments TL2 at frequency $F_{OSC}/2$. The timer repeatedly counts to overflow from a loaded value. At overflow, the contents of RCAP2H and RCAP2L registers are loaded into TH2 and TL2. In this mode, timer 2 overflows do not generate interrupts. The formula gives the clock-out frequency as a function of the system oscillator frequency and the value in the RCAP2H and RCAP2L registers :

$$Clock-OutFrequency = \frac{F_{osc}}{4 \times (65536 - RCAP2H/RCAP2L)}$$

For a 16 MHz system clock, timer 2 has a programmable frequency range of 61 Hz ($F_{OSC}/2^{16}$) to 4 MHz ($F_{OSC}/4$). The generated clock signal is brought out to T2 pin (P1.0).

Timer 2 is programmed for the clock-out mode as follows:

- Set T2OE bit in T2MOD register.
- Clear C/$\overline{T2}$ bit in T2CON register.
- Determine the 16-bit reload value from the formula and enter it in RCAP2H/RCAP2L registers.

Table 8-1.   T2CON Register
T2CON - Timer 2 Control Register (C8h)

7	6	5	4	3	2	1	0
TF2	EXF2	RCLK	TCLK	EXEN2	TR2	C/T2#	CP/RL2#

Bit Number	Bit Mnemonic	Description
7	TF2	**Timer 2 overflow Flag** Must be cleared by software. Set by hardware on timer 2 overflow, if RCLK = 0 and TCLK = 0.
6	EXF2	Timer 2 External Flag Set when a capture or a reload is caused by a negative transition on T2EX pin if EXEN2=1. When set, causes the CPU to vector to timer 2 interrupt routine when timer 2 interrupt is enabled. Must be cleared by software. EXF2 doesn't cause an interrupt in Up/down counter mode (DCEN = 1)
5	RCLK	Receive Clock bit Clear to use timer 1 overflow as receive clock for serial port in mode 1 or 3. Set to use timer 2 overflow as receive clock for serial port in mode 1 or 3.
4	TCLK	Transmit Clock bit Clear to use timer 1 overflow as transmit clock for serial port in mode 1 or 3. Set to use timer 2 overflow as transmit clock for serial port in mode 1 or 3.
3	EXEN2	Timer 2 External Enable bit Clear to ignore events on T2EX pin for timer 2 operation. Set to cause a capture or reload when a negative transition on T2EX pin is detected, if timer 2 is not used to clock the serial port.
2	TR2	Timer 2 Run control bit Clear to turn off timer 2. Set to turn on timer 2.
1	C/T2#	**Timer/Counter 2 select bit** Clear for timer operation (input from internal clock system: F_{OSC}). Set for counter operation (input from T2 input pin, falling edge trigger). Must be 0 for clock out mode.
0	CP/RL2#	Timer 2 Capture/Reload bit If RCLK=1 or TCLK=1, CP/RL2# is ignored and timer is forced to auto-reload on timer 2 overflow. Clear to auto-reload on timer 2 overflows or negative transitions on T2EX pin if EXEN2=1. Set to capture on negative transitions on T2EX pin if EXEN2=1.

Reset Value = 0000 0000b
Bit addressable

9. TS80C54/58X2 Serial I/O Port

The serial I/O port in the TS80C54/58X2 is compatible with the serial I/O port in the 80C52. It provides both synchronous and asynchronous communication modes. It operates as an Universal Asynchronous Receiver and Transmitter (UART) in three full-duplex modes (Modes 1, 2 and 3). Asynchronous transmission and reception can occur simultaneously and at different baud rates
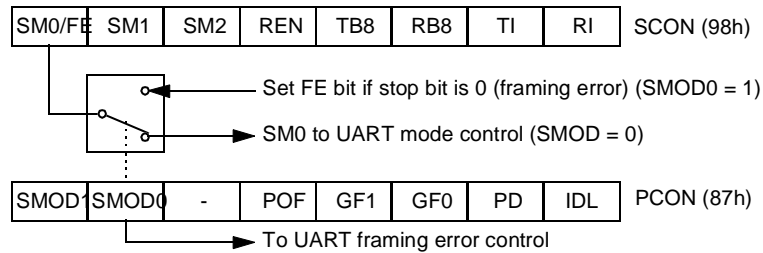
Serial I/O port includes the following enhancements:

- Framing error detection
- Automatic address recognition

9.1 Framing Error Detection

Framing bit error detection is provided for the three asynchronous modes (modes 1, 2 and 3). To enable the framing bit error detection feature, set SMOD0 bit in PCON register (See Figure 9-1).

Figure 9-1. Framing Error Block Diagram

| SM0/FE | SM1 | SM2 | REN | TB8 | RB8 | TI | RI | SCON (98h) |

Set FE bit if stop bit is 0 (framing error) (SMOD0 = 1)

SM0 to UART mode control (SMOD = 0)

| SMOD1 | SMOD0 | - | POF | GF1 | GF0 | PD | IDL | PCON (87h) |

To UART framing error control

When this feature is enabled, the receiver checks each incoming data frame for a valid stop bit. An invalid stop bit may result from noise on the serial lines or from simultaneous transmission by two CPUs. If a valid stop bit is not found, the Framing Error bit (FE) in SCON register (See Table 9-3.) bit is set.

Software may examine FE bit after each reception to check for data errors. Once set, only software or a reset can clear FE bit. Subsequently received frames with valid stop bits cannot clear FE bit. When FE feature is enabled, RI rises on stop bit instead of the last data bit (See Figure 9-2. and Figure 9-3.).

Figure 9-2. UART Timings in Mode 1
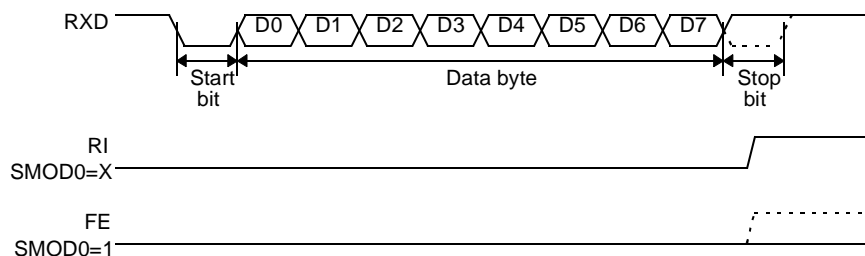
Table 9-3. SCON Register
SCON - Serial Control Register (98h)

7	6	5	4	3	2	1	0
FE/SM0	SM1	SM2	REN	TB8	RB8	TI	RI

Bit Number	Bit Mnemonic	Description
7	FE	**Framing Error bit (SMOD0=1**) Clear to reset the error state, not cleared by a valid stop bit. Set by hardware when an invalid stop bit is detected. SMOD0 must be set to enable access to the FE bit
	SM0	**Serial port Mode bit 0** Refer to SM1 for serial port mode selection. SMOD0 must be cleared to enable access to the SM0 bit
6	SM1	**Serial port Mode bit 1** SM0 SM1 Mode Description Baud Rate 0 0 0 Shift RegisterF_{XTAL}/12 (/6 in X2 mode) 0 1 1 8-bit UARTVariable 1 0 2 9-bit UARTF_{XTAL}/64 or F_{XTAL}/32 (/32, /16 in X2 mode) 1 1 3 9-bit UARTVariable
5	SM2	**Serial port Mode 2 bit / Multiprocessor Communication Enable bit** Clear to disable multiprocessor communication feature. Set to enable multiprocessor communication feature in mode 2 and 3, and eventually mode 1. This bit should be cleared in mode 0.
4	REN	**Reception Enable bit** Clear to disable serial reception. Set to enable serial reception.
3	TB8	Transmitter Bit 8 / Ninth bit to transmit in modes 2 and 3. Clear to transmit a logic 0 in the 9th bit. Set to transmit a logic 1 in the 9th bit.
2	RB8	**Receiver Bit 8 / Ninth bit received in modes 2 and 3** Cleared by hardware if 9th bit received is a logic 0. Set by hardware if 9th bit received is a logic 1. In mode 1, if SM2 = 0, RB8 is the received stop bit. In mode 0 RB8 is not used.
1	TI	**Transmit Interrupt flag** Clear to acknowledge interrupt. Set by hardware at the end of the 8th bit time in mode 0 or at the beginning of the stop bit in the other modes.
0	RI	**Receive Interrupt flag** Clear to acknowledge interrupt. Set by hardware at the end of the 8th bit time in mode 0, see Figure 9-2. and Figure 9-3. in the other modes.

Reset Value = 0000 0000b
Bit addressable

Table 9-4. PCON Register

Table 9-5. PCON - Power Control Register (87h)

7	6	5	4	3	2	1	0
SMOD1	SMOD0	-	POF	GF1	GF0	PD	IDL

Bit Number	Bit Mnemonic	Description
7	SMOD1	**Serial port Mode bit 1** Set to select double baud rate in mode 1, 2 or 3.
6	SMOD0	**Serial port Mode bit 0** Clear to select SM0 bit in SCON register. Set to to select FE bit in SCON register.
5	-	**Reserved** The value read from this bit is indeterminate. Do not set this bit.
4	POF	**Power-Off Flag** Clear to recognize next reset type. Set by hardware when VCC rises from 0 to its nominal voltage. Can also be set by software.
3	GF1	**General purpose Flag** Cleared by user for general purpose usage. Set by user for general purpose usage.
2	GF0	**General purpose Flag** Cleared by user for general purpose usage. Set by user for general purpose usage.
1	PD	**Power-Down mode bit** Cleared by hardware when reset occurs. Set to enter power-down mode.
0	IDL	**Idle mode bit** Clear by hardware when interrupt or reset occurs. Set to enter idle mode.

Reset Value = 00X1 0000b
Not bit addressable

Power-off flag reset value will be 1 only after a power on (cold reset). A warm reset doesn't affect the value of this bit.

Table 10-4. IPH Register

IPH - Interrupt Priority High Register (B7h)

7	6	5	4	3	2	1	0
-	-	PT2H	PSH	PT1H	PX1H	PT0H	PX0H

Bit Number	Bit Mnemonic	Description
7	-	**Reserved** The value read from this bit is indeterminate. Do not set this bit.
6	-	**Reserved** The value read from this bit is indeterminate. Do not set this bit.
5	PT2H	Timer 2 overflow interrupt Priority High bit PT2H PT2 Priority Level 0 0 Lowest 0 1 1 0 1 1 Highest
4	PSH	Serial port Priority High bit PSH PS Priority Level 0 0 Lowest 0 1 1 0 1 1 Highest
3	PT1H	Timer 1 overflow interrupt Priority High bit PT1H PT1 Priority Level 0 0 Lowest 0 1 1 0 1 1 Highest
2	PX1H	External interrupt 1 Priority High bit PX1H PX1 Priority Level 0 0 Lowest 0 1 1 0 1 1 Highest
1	PT0H	Timer 0 overflow interrupt Priority High bit PT0H PT0 Priority Level 0 0 Lowest 0 1 1 0 1 1 Highest
0	PX0H	External interrupt 0 Priority High bit PX0H PX0 Priority Level 0 0 Lowest 0 1 1 0 1 1 Highest

Reset Value = XX00 0000b

Not bit addressable

11. Idle mode

An instruction that sets PCON.0 causes that to be the last instruction executed before going into the Idle mode. In the Idle mode, the internal clock signal is gated off to the CPU, but not to the interrupt, Timer, and Serial Port functions. The CPU status is preserved in its entirely : the Stack Pointer, Program Counter, Program Status Word, Accumulator and all other registers maintain their data during Idle. The port pins hold the logical states they had at the time Idle was activated. ALE and PSEN hold at logic high levels.

There are two ways to terminate the Idle. Activation of any enabled interrupt will cause PCON.0 to be cleared by hardware, terminating the Idle mode. The interrupt will be serviced, and following RETI the next instruction to be executed will be the one following the instruction that put the device into idle.

The flag bits GF0 and GF1 can be used to give an indication if an interrupt occured during normal operation or during an Idle. For example, an instruction that activates Idle can also set one or both flag bits. When Idle is terminated by an interrupt, the interrupt service routine can examine the flag bits.

The other way of terminating the Idle mode is with a hardware reset. Since the clock oscillator is still running, the hardware reset needs to be held active for only two machine cycles (24 oscillator periods) to complete the reset.

11.1 Power-Down Mode

To save maximum power, a power-down mode can be invoked by software (Refer to Table 9-4., PCON register).

In power-down mode, the oscillator is stopped and the instruction that invoked power-down mode is the last instruction executed. The internal RAM and SFRs retain their value until the power-down mode is terminated. V_{CC} can be lowered to save further power. Either a hardware reset or an external interrupt can cause an exit from power-down. To properly terminate power-down, the reset or external interrupt should not be executed before V_{CC} is restored to its normal operating level and must be held active long enough for the oscillator to restart and stabilize.

Only external interrupts $\overline{INT0}$ and $\overline{INT1}$ are useful to exit from power-down. For that, interrupt must be enabled and configured as level or edge sensitive interrupt input.
Holding the pin low restarts the oscillator but bringing the pin high completes the exit as detailed in Figure 11-1. When both interrupts are enabled, the oscillator restarts as soon as one of the two inputs is held low and power down exit will be completed when the first input will be released. In this case the higher priority interrupt service routine is executed.
Once the interrupt is serviced, the next instruction to be executed after RETI will be the one following the instruction that put TS80C54/58X2 into power-down mode.

17.2.3 Signature bytes

The TS87C54/58X2 contains 4 factory programmed signatures bytes. To read these bytes, perform the process described in section 8.3.

17.3 EPROM Programming

17.3.1 Set-up modes

In order to program and verify the EPROM or to read the signature bytes, the TS87C54/58X2 is placed in specific set-up modes (See Figure 17-1.).

Control and program signals must be held at the levels indicated in Table 17-2.

17.3.2 Definition of terms

Address Lines:P1.0-P1.7, P2.0-P2.5, P3.4 respectively for A0-A14 (P2.5 (A13) for TS87C54X2, P3.4 (A14) for TS87C58X2).

Data Lines:P0.0-P0.7 for D0-D7

Control Signals:RST, $\overline{PSEN}$, P2.6, P2.7, P3.3, P3.6, P3.7.

Program Signals:ALE/$\overline{PROG}$, $\overline{EA}$/VPP.

Table 17-2. EPROM Set-Up Modes

Mode	RST	PSEN	ALE/PROG	EA/VPP	P2.6	P2.7	P3.3	P3.6	P3.7
Program Code data	1	0	⊓	12.75	0	1	1	1	1
Verify Code data	1	0	1	1	0	⊔	0	1	1
Program Encryption Array Address 0-3Fh	1	0	⊓	12.75	0	1	1	0	1
Read Signature Bytes	1	0	1	1	0	⊔	0	0	0
Program Lock bit 1	1	0	⊓	12.75	1	1	1	1	1
Program Lock bit 2	1	0	⊓	12.75	1	1	1	0	0
Program Lock bit 3	1	0	⊓	12.75	1	0	1	1	0

Figure 17-1. Set-Up Modes Configuration
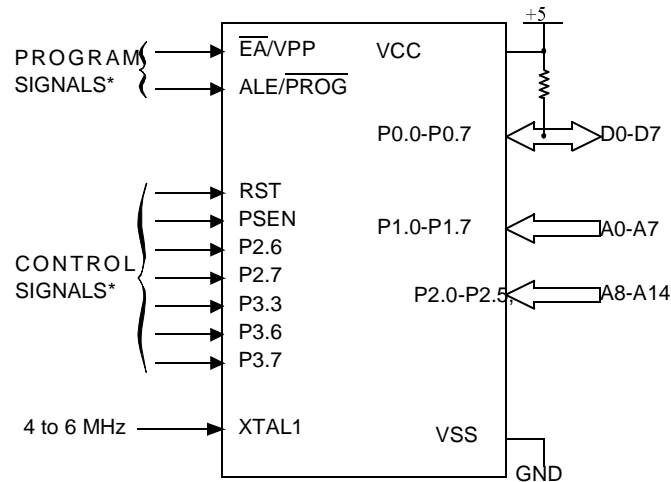
* See Table 31. for proper value on these inputs

17.3.3 Programming Algorithm

The Improved Quick Pulse algorithm is based on the Quick Pulse algorithm and decreases the number of pulses applied during byte programming from 25 to 1.

To program the TS80C54/58X2 the following sequence must be exercised:

- Step 1: Activate the combination of control signals.
- Step 2: Input the valid address on the address lines.
- Step 3: Input the appropriate data on the data lines.
- Step 4: Raise $\overline{EA}$/VPP from VCC to VPP (typical 12.75V).
- Step 5: Pulse ALE/$\overline{PROG}$ once.
- Step 6: Lower $\overline{EA}$/VPP from VPP to VCC

Repeat step 2 through 6 changing the address and data for the entire array or until the end of the object file is reached (See Figure 17-2.).

17.3.4 Verify algorithm

Code array verify must be done after each byte or block of bytes is programmed. In either case, a complete verify of the programmed array will ensure reliable programming of the TS87C54/58X2.

P 2.7 is used to enable data output.

To verify the TS87C54/58X2 code the following sequence must be exercised:

- Step 1: Activate the combination of program and control signals.
- Step 2: Input the valid address on the address lines.
- Step 3: Read data on the data lines.

Repeat step 2 through 3 changing the address for the entire array verification (See Figure 17-2.)

Symbol	Parameter	Min	Typ	Max	Unit	Test Conditions
V_{OL1}	Output Low Voltage, port 0 [6]			0.3 0.45 1.0	V V V	I_{OL} = 200 μA[4] I_{OL} = 3.2 mA[4] I_{OL} = 7.0 mA[4]
V_{OL2}	Output Low Voltage, ALE, $\overline{PSEN}$			0.3 0.45 1.0	V V V	I_{OL} = 100 μA[4] I_{OL} = 1.6 mA[4] I_{OL} = 3.5 mA[4]
V_{OH}	Output High Voltage, ports 1, 2, 3	V_{CC} - 0.3 V_{CC} - 0.7 V_{CC} - 1.5			V V V	I_{OH} = -10 μA I_{OH} = -30 μA I_{OH} = -60 μA V_{CC} = 5 V ± 10%
V_{OH1}	Output High Voltage, port 0	V_{CC} - 0.3 V_{CC} - 0.7 V_{CC} - 1.5			V V V	I_{OH} = -200 μA I_{OH} = -3.2 mA I_{OH} = -7.0 mA V_{CC} = 5 V ± 10%
V_{OH2}	Output High Voltage, ALE, $\overline{PSEN}$	V_{CC} - 0.3 V_{CC} - 0.7 V_{CC} - 1.5			V V V	I_{OH} = -100 μA I_{OH} = -1.6 mA I_{OH} = -3.5 mA V_{CC} = 5 V ± 10%
R_{RST}	RST Pulldown Resistor	50	90 [5]	200	kΩ	
I_{IL}	Logical 0 Input Current ports 1, 2 and 3			-50	μA	Vin = 0.45 V
I_{LI}	Input Leakage Current			±10	μA	0.45 V < Vin < V_{CC}
I_{TL}	Logical 1 to 0 Transition Current, ports 1, 2, 3			-650	μA	Vin = 2.0 V
C_{IO}	Capacitance of I/O Buffer			10	pF	Fc = 1 MHz T_A = 25°C
I_{PD}	Power Down Current		20 [5]	50	μA	2.0 V < V_{CC} < 5.5 V[3]
I_{CC} under RESET	Power Supply Current Maximum values, X1 mode: [7]			1 + 0.4 Freq (MHz) @12MHz 5.8 @16MHz 7.4	mA	V_{CC} = 5.5 V[1]
I_{CC} operating	Power Supply Current Maximum values, X1 mode: [7]			3 + 0.6 Freq (MHz) @12MHz 10.2 @16MHz 12.6	mA	V_{CC} = 5.5 V[8]
I_{CC} idle	Power Supply Current Maximum values, X1 mode: [7]			0.25+0.3 Freq (MHz) @12MHz 3.9 @16MHz 5.1	mA	V_{CC} = 5.5 V[2]

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19.4 DC Parameters for Low Voltage

$T_A = 0°C$ to $+70°C$; $V_{SS} = 0$ V; $V_{CC} = 2.7$ V to 5.5 V $\pm 10\%$; F = 0 to 30 MHz.
$T_A = -40°C$ to $+85°C$; $V_{SS} = 0$ V; $V_{CC} = 2.7$ V to 5.5 V $\pm 10\%$; F = 0 to 30 MHz.

Table 19-2. DC Parameters for Low Voltage

Symbol	Parameter	Min	Typ	Max	Unit	Test Conditions
V_{IL}	Input Low Voltage	-0.5		$0.2 V_{CC}$ - 0.1	V	
V_{IH}	Input High Voltage except XTAL1, RST	$0.2 V_{CC}$ + 0.9		V_{CC} + 0.5	V	
V_{IH1}	Input High Voltage, XTAL1, RST	$0.7 V_{CC}$		V_{CC} + 0.5	V	
V_{OL}	Output Low Voltage, ports 1, 2, 3 [6]			0.45	V	I_{OL} = 0.8 mA[4]
V_{OL1}	Output Low Voltage, port 0, ALE, $\overline{PSEN}$ [6]			0.45	V	I_{OL} = 1.6 mA[4]
V_{OH}	Output High Voltage, ports 1, 2, 3	$0.9 V_{CC}$			V	I_{OH} = -10 µA
V_{OH1}	Output High Voltage, port 0, ALE, $\overline{PSEN}$	$0.9 V_{CC}$			V	I_{OH} = -40 µA
I_{IL}	Logical 0 Input Current ports 1, 2 and 3			-50	µA	Vin = 0.45 V
I_{LI}	Input Leakage Current			±10	µA	0.45 V < Vin < V_{CC}
I_{TL}	Logical 1 to 0 Transition Current, ports 1, 2, 3			-650	µA	Vin = 2.0 V
R_{RST}	RST Pulldown Resistor	50	90 [5]	200	kΩ	
CIO	Capacitance of I/O Buffer			10	pF	Fc = 1 MHz T_A = 25°C
I_{PD}	Power Down Current	20 [5] 10 [5]		50 30	µA	V_{CC} = 2.0 V to 5.5 V[3] V_{CC} = 2.0 V to 3.3 V[3]
I_{CC} under RESET	Power Supply Current Maximum values, X1 mode: [7]			1 + 0.2 Freq (MHz) @12MHz 3.4 @16MHz 4.2	mA	V_{CC} = 3.3 V[1]
I_{CC} operating	Power Supply Current Maximum values, X1 mode: [7]			1 + 0.3 Freq (MHz) @12MHz 4.6 @16MHz 5.8	mA	V_{CC} = 3.3 V[8]
I_{CC} idle	Power Supply Current Maximum values, X1 mode: [7]			0.15 Freq (MHz) + 0.2 @12MHz 2 @16MHz 2.6	mA	V_{CC} = 3.3 V[2]

1. I_{CC} under reset is measured with all output pins disconnected; XTAL1 driven with T_{CLCH}, T_{CHCL} = 5 ns (see Figure 19-5.), $V_{IL} = V_{SS}$ + 0.5 V, $V_{IH} = V_{CC}$ - 0.5V; XTAL2 N.C.; $\overline{EA}$ = RST = Port 0 = V_{CC}. I_{CC} would be slightly higher if a crystal oscillator used..

2. Idle I_{CC} is measured with all output pins disconnected; XTAL1 driven with T_{CLCH}, T_{CHCL} = 5 ns, $V_{IL} = V_{SS}$ + 0.5 V, $V_{IH} = V_{CC}$ - 0.5 V; XTAL2 N.C; Port 0 = V_{CC}; $\overline{EA}$ = RST = V_{SS} (see Figure 19-3.).

3. Power Down I_{CC} is measured with all output pins disconnected; $\overline{EA} = V_{SS}$, PORT 0 = V_{CC}; XTAL2 NC.; RST = V_{SS} (see Figure 19-4.).

4. Capacitance loading on Ports 0 and 2 may cause spurious noise pulses to be superimposed on the V_{OL}s of ALE and Ports 1 and 3. The noise is due to external bus capacitance discharging into the Port 0 and Port 2 pins when these pins make 1 to 0 transitions during bus operation. In the worst cases (capacitive loading 100pF), the noise pulse on the ALE line may exceed 0.45V with maxi V_{OL} peak 0.6V. A Schmitt Trigger use is not necessary.

5. Typicals are based on a limited number of samples and are not guaranteed. The values listed are at room temperature and 5V.

6. Under steady state (non-transient) conditions, I_{OL} must be externally limited as follows:
   Maximum I_{OL} per port pin: 10 mA
   Maximum I_{OL} per 8-bit port:
   Port 0: 26 mA
   Ports 1, 2 and 3: 15 mA
   Maximum total I_{OL} for all output pins: 71 mA
   If I_{OL} exceeds the test condition, V_{OL} may exceed the related specification. Pins are not guaranteed to sink current greater than the listed test conditions.

7. For other values, please contact your sales office.

8. Operating I_{CC} is measured with all output pins disconnected; XTAL1 driven with T_{CLCH}, T_{CHCL} = 5 ns (see Figure 19-5.), $V_{IL} = V_{SS} + 0.5$ V,
   $V_{IH} = V_{CC} - 0.5V$; XTAL2 N.C.; $\overline{EA}$ = Port 0 = V_{CC}; RST = V_{SS}. The internal ROM runs the code 80 FE (label: SJMP label). I_{CC} would be slightly higher if a crystal oscillator is used. Measurements are made with OTP products when possible, which is the worst case.
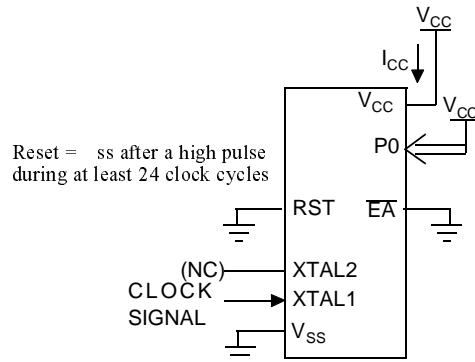
Figure 19-1. I_{CC} Test Condition, under reset
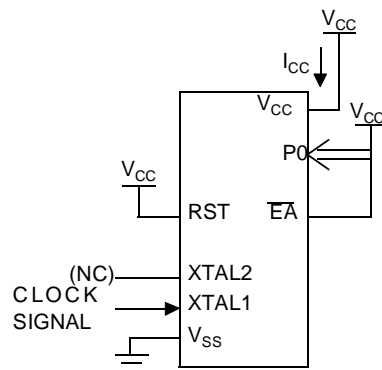
All other pins are disconnected.
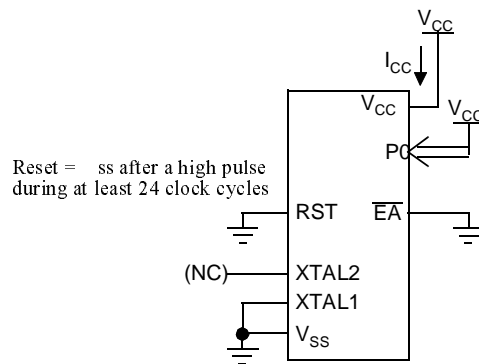
Figure 19-2. Operating I_{CC} Test Condition
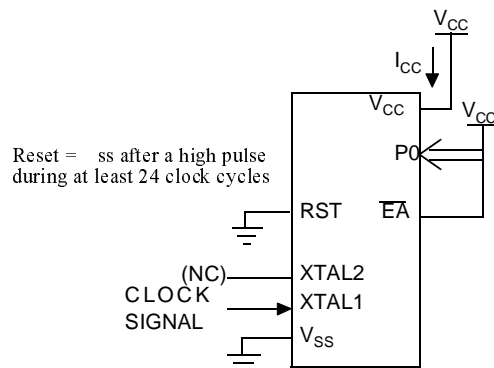
All other pins are disconnected.

Figure 19-3. I_{CC} Test Condition, Idle Mode

Reset = ss after a high pulse
during at least 24 clock cycles

V_{CC}

I_{CC}

V_{CC} V_{CC}

P0

RST $\overline{EA}$

(NC)   XTAL2
CLOCK   XTAL1
SIGNAL V_{SS}

All other pins are disconnected.

Figure 19-4. I_{CC} Test Condition, Power-Down Mode

Reset = ss after a high pulse
during at least 24 clock cycles

V_{CC}

I_{CC}

V_{CC} V_{CC}

P0

RST $\overline{EA}$

(NC)   XTAL2
XTAL1
V_{SS}

All other pins are disconnected.

Figure 19-5. Clock Signal Waveform for I_{CC} Tests in Active and Idle Modes

V_{CC}-0.5V $0.7V_{CC}$
0.45V $0.2V_{CC}$-0.1
T_{CHCL} T_{CLCH}
$T_{CLCH} = T_{CHCL} = 5ns.$
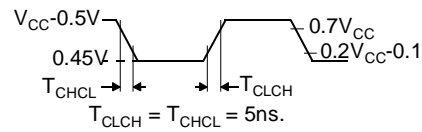
19.5.4 External Data Memory Characteristics

Table 19-8. Symbol Description

Symbol	Parameter
T_{RLRH}	$\overline{RD}$ Pulse Width
T_{WLWH}	$\overline{WR}$ Pulse Width
T_{RLDV}	$\overline{RD}$ to Valid Data In
T_{RHDX}	Data Hold After $\overline{RD}$
T_{RHDZ}	Data Float After $\overline{RD}$
T_{LLDV}	ALE to Valid Data In
T_{AVDV}	Address to Valid Data In
T_{LLWL}	ALE to $\overline{WR}$ or $\overline{RD}$
T_{AVWL}	Address to $\overline{WR}$ or $\overline{RD}$
T_{QVWX}	Data Valid to $\overline{WR}$ Transition
T_{QVWH}	Data set-up to $\overline{WR}$ High
T_{WHQX}	Data Hold After $\overline{WR}$
T_{RLAZ}	$\overline{RD}$ Low to Address Float
T_{WHLH}	$\overline{RD}$ or $\overline{WR}$ High to ALE high

Table 19-9. AC Parameters for a Fix Clock

Speed	-M 40 MHz		-V X2 mode 30 MHz 60 MHz equiv.		-V standard mode 40 MHz		-L X2 mode 20 MHz 40 MHz equiv.		-L standard mode 30 MHz		Units
Symbol	Min	Max	Min	Max	Min	Max	Min	Max	Min	Max	
T_{RLRH}	130		85		135		125		175		ns
T_{WLWH}	130		85		135		125		175		ns
T_{RLDV}		100		60		102		95		137	ns
T_{RHDX}	0		0		0		0		0		ns
T_{RHDZ}		30		18		35		25		42	ns
T_{LLDV}		160		98		165		155		222	ns
T_{AVDV}		165		100		175		160		235	ns
T_{LLWL}	50	100	30	70	55	95	45	105	70	130	ns
T_{AVWL}	75		47		80		70		103		ns
T_{QVWX}	10		7		15		5		13		ns
T_{QVWH}	160		107		165		155		213		ns
T_{WHQX}	15		9		17		10		18		ns
T_{RLAZ}		0		0		0		0		0	ns
T_{WHLH}	10	40	7	27	15	35	5	45	13	53	ns

Part Number	Supply Voltage	Temperature Range	Package	Packing
TS80C58X2xxx-MCA	-5 to +/-10%	Commercial	PDIL40	Stick
TS80C58X2xxx-MCB	-5 to +/-10%	Commercial	PLCC44	Stick
TS80C58X2xxx-MCC	-5 to +/-10%	Commercial	PQFP44	Tray
TS80C58X2xxx-MCE	-5 to +/-10%	Commercial	VQFP44	Tray
TS80C58X2xxx-VCA	-5 to +/-10%	Commercial	PDIL40	Stick
TS80C58X2xxx-VCB	-5 to +/-10%	Commercial	PLCC44	Stick
TS80C58X2xxx-VCC	-5 to +/-10%	Commercial	PQFP44	Tray
TS80C58X2xxx-VCE	-5 to +/-10%	Commercial	VQFP44	Tray
TS80C58X2xxx-LCA	-5 to +/-10%	Commercial	PDIL40	Stick
TS80C58X2xxx-LCB	-5 to +/-10%	Commercial	PLCC44	Stick
TS80C58X2xxx-LCC	-5 to +/-10%	Commercial	PQFP44	Tray
TS80C58X2xxx-LCE	-5 to +/-10%	Commercial	VQFP44	Tray
TS80C58X2xxx-MIA	-5 to +/-10%	Industrial	PDIL40	Stick
TS80C58X2xxx-MIB	-5 to +/-10%	Industrial	PLCC44	Stick
TS80C58X2xxx-MIC	-5 to +/-10%	Industrial	PQFP44	Tray
TS80C58X2xxx-MIE	-5 to +/-10%	Industrial	VQFP44	Tray
TS80C58X2xxx-VIA	-5 to +/-10%	Industrial	PDIL40	Stick
TS80C58X2xxx-VIB	-5 to +/-10%	Industrial	PLCC44	Stick
TS80C58X2xxx-VIC	-5 to +/-10%	Industrial	PQFP44	Tray
TS80C58X2xxx-VIE	-5 to +/-10%	Industrial	VQFP44	Tray
TS80C58X2xxx-LIA	-5 to +/-10%	Industrial	PDIL40	Stick
TS80C58X2xxx-LIB	-5 to +/-10%	Industrial	PLCC44	Stick
TS80C58X2xxx-LIC	-5 to +/-10%	Industrial	PQFP44	Tray
TS80C58X2xxx-LIE	-5 to +/-10%	Industrial	VQFP44	Tray
AT80C58X2zzz-3CSUM	-5 to +/-10%	Industrial & Green	PDIL40	Stick
AT80C58X2zzz-SLSUM	-5 to +/-10%	Industrial & Green	PLCC44	Stick
AT80C58X2zzz-RLTUM	-5 to +/-10%	Industrial & Green	VQFP44	Tray
AT80C58X2zzz-3CSUL	-5 to +/-10%	Industrial & Green	PDIL40	Stick
AT80C58X2zzz-SLSUL	-5 to +/-10%	Industrial & Green	PLCC44	Stick
AT80C58X2zzz-RLTUL	-5 to +/-10%	Industrial & Green	VQFP44	Tray
AT80C58X2zzz-3CSUV	-5 to +/-10%	Industrial & Green	PDIL40	Stick
AT80C58X2zzz-SLSUV	-5 to +/-10%	Industrial & Green	PLCC44	Stick
AT80C58X2zzz-RLTUV	-5 to +/-10%	Industrial & Green	VQFP44	Tray
TS87C58X2-MCA	5V ±10%	Commercial	PDIL40	Stick
TS87C58X2-MCB	5V ±10%	Commercial	PLCC44	Stick
TS87C58X2-MCC	5V ±10%	Commercial	PQFP44	Tray

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