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Applications of "Embedded - Microcontrollers"

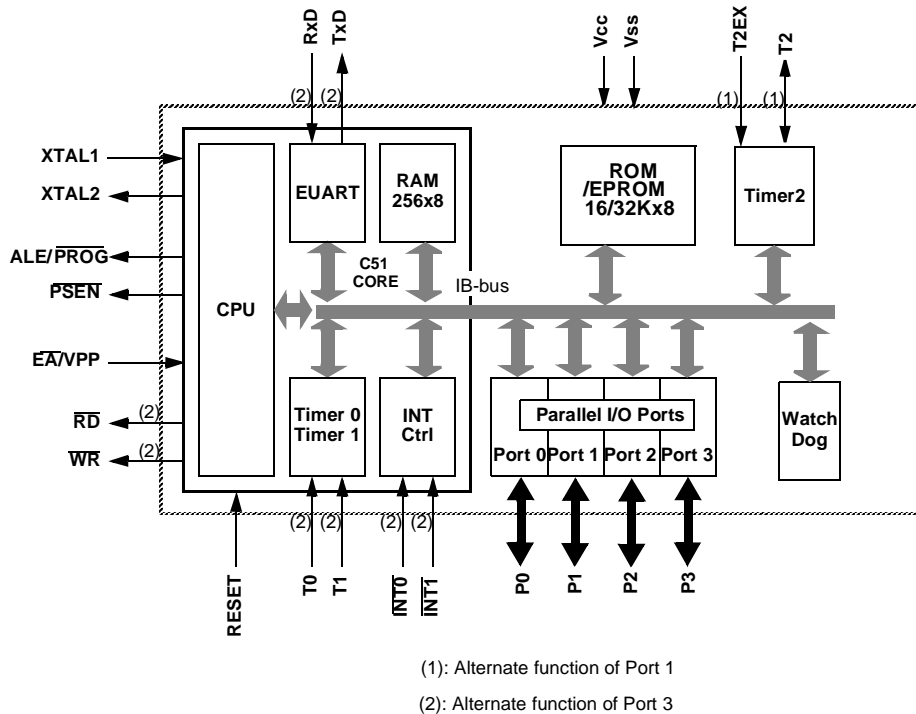## Details

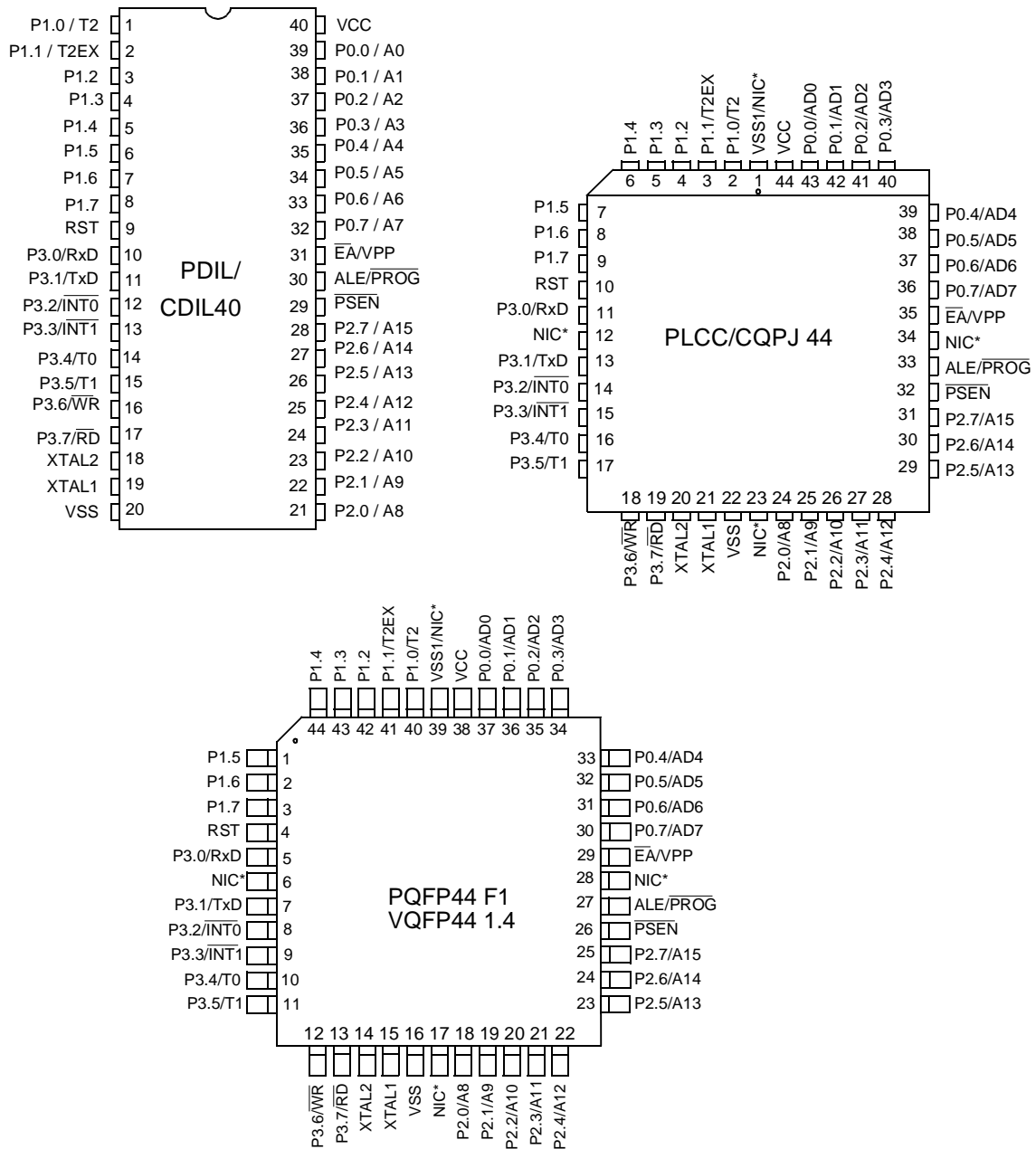|	
Product Status	Obsolete
Core Processor	80C51
Core Size	8-Bit
Speed	40/20MHz
Connectivity	UART/USART
Peripherals	POR, WDT
Number of I/O	32
Program Memory Size	32KB (32K x 8)
Program Memory Type	OTP
EEPROM Size	-
RAM Size	256 x 8
Voltage - Supply (Vcc/Vdd)	4.5V ~ 5.5V
Data Converters	-
Oscillator Type	Internal
Operating Temperature	0°C ~ 70°C (TA)
Mounting Type	Surface Mount
Package / Case	44-QFP
Supplier Device Package	44-PQFP
Purchase URL	https://www.e-xfl.com/product-detail/microchip-technology/ts87c58x2-mcc

The TS80C54/58X2 has 2 software-selectable modes of reduced activity for further reduction in power consumption. In the idle mode the CPU is frozen while the timers, the serial port and the interrupt system are still operating. In the power-down mode the RAM is saved and all other functions are inoperative.

PDIL40 PLCC44 PQFP44 F1 VQFP44 1.4	ROM (bytes)	EPROM (bytes)
TS80C54X2	16k	0
TS80C58X2	32k	0
TS87C54X2	0	16k
TS87C58X2	0	32k

2. Block Diagram

(1): Alternate function of Port 1

(2): Alternate function of Port 3

5. Pin Configuration

PDIL/CDIL40

P1.0 / T2	1	40	VCC
P1.1 / T2EX	2	39	P0.0 / A0
P1.2	3	38	P0.1 / A1
P1.3	4	37	P0.2 / A2
P1.4	5	36	P0.3 / A3
P1.5	6	35	P0.4 / A4
P1.6	7	34	P0.5 / A5
P1.7	8	33	P0.6 / A6
RST	9	32	P0.7 / A7
P3.0/RxD	10	31	$\overline{EA}$/VPP
P3.1/TxD	11	30	ALE/$\overline{PROG}$
P3.2/$\overline{INT0}$	12	29	$\overline{PSEN}$
P3.3/$\overline{INT1}$	13	28	P2.7 / A15
P3.4/T0	14	27	P2.6 / A14
P3.5/T1	15	26	P2.5 / A13
P3.6/$\overline{WR}$	16	25	P2.4 / A12
P3.7/$\overline{RD}$	17	24	P2.3 / A11
XTAL2	18	23	P2.2 / A10
XTAL1	19	22	P2.1 / A9
VSS	20	21	P2.0 / A8

PLCC/CQPJ 44

Top pins (6,5,4,3,2,1,44,43,42,41,40): P1.4, P1.3, P1.2, P1.1/T2EX, P1.0/T2, VSS1/NIC*, VCC, P0.0/AD0, P0.1/AD1, P0.2/AD2, P0.3/AD3

Left side:
P1.5	7
P1.6	8
P1.7	9
RST	10
P3.0/RxD	11
NIC*	12
P3.1/TxD	13
P3.2/$\overline{INT0}$	14
P3.3/$\overline{INT1}$	15
P3.4/T0	16
P3.5/T1	17

Right side:
39	P0.4/AD4
38	P0.5/AD5
37	P0.6/AD6
36	P0.7/AD7
35	$\overline{EA}$/VPP
34	NIC*
33	ALE/$\overline{PROG}$
32	$\overline{PSEN}$
31	P2.7/A15
30	P2.6/A14
29	P2.5/A13

Bottom pins (18,19,20,21,22,23,24,25,26,27,28): P3.6/$\overline{WR}$, P3.7/$\overline{RD}$, XTAL2, XTAL1, VSS, NIC*, P2.0/A8, P2.1/A9, P2.2/A10, P2.3/A11, P2.4/A12

PQFP44 F1 / VQFP44 1.4

Top pins (44,43,42,41,40,39,38,37,36,35,34): P1.4, P1.3, P1.2, P1.1/T2EX, P1.0/T2, VSS1/NIC*, VCC, P0.0/AD0, P0.1/AD1, P0.2/AD2, P0.3/AD3

Left side:
P1.5	1
P1.6	2
P1.7	3
RST	4
P3.0/RxD	5
NIC*	6
P3.1/TxD	7
P3.2/$\overline{INT0}$	8
P3.3/$\overline{INT1}$	9
P3.4/T0	10
P3.5/T1	11

Right side:
33	P0.4/AD4
32	P0.5/AD5
31	P0.6/AD6
30	P0.7/AD7
29	$\overline{EA}$/VPP
28	NIC*
27	ALE/$\overline{PROG}$
26	$\overline{PSEN}$
25	P2.7/A15
24	P2.6/A14
23	P2.5/A13

Bottom pins (12,13,14,15,16,17,18,19,20,21,22): P3.6/$\overline{WR}$, P3.7/$\overline{RD}$, XTAL2, XTAL1, VSS, NIC*, P2.0/A8, P2.1/A9, P2.2/A10, P2.3/A11, P2.4/A12

*NIC: No Internal Connection

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Table 5-1. Pin Description for 40/44 pin packages

MNEMONIC	PIN NUMBER			TYPE	Name And Function
	DIL	LCC	VQFP 1.4		
V_{SS}	20	22	16	I	**Ground:** 0V reference
Vss1		1	39	I	Optional Ground: **Contact the Sales Office for ground connection.**
V_{CC}	40	44	38	I	**Power Supply:** This is the power supply voltage for normal, idle and power-down operation
P0.0-P0.7	39-32	43-36	37-30	I/O	**Port 0**: Port 0 is an open-drain, bidirectional I/O port. Port 0 pins that have 1s written to them float and can be used as high impedance inputs. Port 0 pins must be polarized to Vcc or Vss in order to prevent any parasitic current consumption. Port 0 is also the multiplexed low-order address and data bus during access to external program and data memory. In this application, it uses strong internal pull-up when emitting 1s. Port 0 also inputs the code bytes during EPROM programming. External pull-ups are required during program verification during which P0 outputs the code bytes.
P1.0-P1.7	1-8	2-9	40-44 1-3	I/O	Port 1: Port 1 is an 8-bit bidirectional I/O port with internal pull-ups. Port 1 pins that have 1s written to them are pulled high by the internal pull-ups and can be used as inputs. As inputs, Port 1 pins that are externally pulled low will source current because of the internal pull-ups. Port 1 also receives the low-order address byte during memory programming and verification. Alternate functions for Port 1 include:
	1	2	40	I/O	**T2 (P1.0):** Timer/Counter 2 external count input/Clockout
	2	3	41	I	**T2EX (P1.1):** Timer/Counter 2 Reload/Capture/Direction Control
P2.0-P2.7	21-28	24-31	18-25	I/O	**Port 2**: Port 2 is an 8-bit bidirectional I/O port with internal pull-ups. Port 2 pins that have 1s written to them are pulled high by the internal pull-ups and can be used as inputs. As inputs, Port 2 pins that are externally pulled low will source current because of the internal pull-ups. Port 2 emits the high-order address byte during fetches from external program memory and during accesses to external data memory that use 16-bit addresses (MOVX @DPTR).In this application, it uses strong internal pull-ups emitting 1s. During accesses to external data memory that use 8-bit addresses (MOVX @Ri), port 2 emits the contents of the P2 SFR. Some Port 2 pins receive the high order address bits during EPROM programming and verification: P2.0 to P2.5 for A8 to A13
P3.0-P3.7	10-17	11, 13-19	5, 7-13	I/O	**Port 3**: Port 3 is an 8-bit bidirectional I/O port with internal pull-ups. Port 3 pins that have 1s written to them are pulled high by the internal pull-ups and can be used as inputs. As inputs, Port 3 pins that are externally pulled low will source current because of the internal pull-ups. Some Port 3 pin P3.4 receive the high order address bits during EPROM programming and verification for TS8xC58X2 devices. Port 3 also serves the special features of the 80C51 family, as listed below.
	10	11	5	I	**RXD (P3.0):** Serial input port
	11	13	7	O	**TXD (P3.1):** Serial output port
	12	14	8	I	**INT0 (P3.2):** External interrupt 0
	13	15	9	I	**INT1 (P3.3):** External interrupt 1
	14	16	10	I	**T0 (P3.4):** Timer 0 external input
	15	17	11	I	**T1 (P3.5):** Timer 1 external input
	16	18	12	O	**WR (P3.6):** External data memory write strobe
	17	19	13	O	**RD (P3.7):** External data memory read strobe P3.4 also receives A14 during TS87C58X2 EPROM Programming.
Reset	9	10	4	I	**Reset:** A high on this pin for two machine cycles while the oscillator is running, resets the device. An internal diffused resistor to V_{SS} permits a power-on reset using only an external capacitor to V_{CC}.

Table 5-1. Pin Description for 40/44 pin packages

MNEMONIC	PIN NUMBER			TYPE	Name And Function
	DIL	LCC	VQFP 1.4		
MNEMONIC	PIN NUMBER			TYPE	NAME AND FUNCTION
ALE/$\overline{PROG}$	30	33	27	O (I)	**Address Latch Enable/Program Pulse:** Output pulse for latching the low byte of the address during an access to external memory. In normal operation, ALE is emitted at a constant rate of 1/6 (1/3 in X2 mode) the oscillator frequency, and can be used for external timing or clocking. Note that one ALE pulse is skipped during each access to external data memory. This pin is also the program pulse input ($\overline{PROG}$) during EPROM programming. ALE can be disabled by setting SFR's AUXR.0 bit. With this bit set, ALE will be inactive during internal fetches.
$\overline{PSEN}$	29	32	26	O	**Program Store ENable:** The read strobe to external program memory. When executing code from the external program memory, $\overline{PSEN}$ is activated twice each machine cycle, except that two $\overline{PSEN}$ activations are skipped during each access to external data memory. $\overline{PSEN}$ is not activated during fetches from internal program memory.
$\overline{EA}$/V_{PP}	31	35	29	I	**External Access Enable/Programming Supply Voltage:** $\overline{EA}$ must be externally held low to enable the device to fetch code from external program memory locations 0000H and 3FFFH (54X2) or 7FFFH (58X2). If EA is held high, the device executes from internal program memory unless the program counter contains an address greater than 3FFFH (54X2) or 7FFFH (58X2). This pin also receives the 12.75V programming supply voltage (V_{PP}) during EPROM programming. If security level 1 is programmed, $\overline{EA}$ will be internally latched on Reset.
XTAL1	19	21	15	I	**Crystal 1:** Input to the inverting oscillator amplifier and input to the internal clock generator circuits.
XTAL2	18	20	14	O	**Crystal 2:** Output from the inverting oscillator amplifier

Table 6-1. CKCON Register
CKCON - Clock Control Register (8Fh)

7	6	5	4	3	2	1	0
-	-	-	-	-	-	-	X2

Bit Number	Bit Mnemonic	Description
7	-	**Reserved** The value read from this bit is indeterminate. Do not set this bit.
6	-	**Reserved** The value read from this bit is indeterminate. Do not set this bit.
5	-	**Reserved** The value read from this bit is indeterminate. Do not set this bit.
4	-	**Reserved** The value read from this bit is indeterminate. Do not set this bit.
3	-	**Reserved** The value read from this bit is indeterminate. Do not set this bit.
2	-	**Reserved** The value read from this bit is indeterminate. Do not set this bit.
1	-	**Reserved** The value read from this bit is indeterminate. Do not set this bit.
0	X2	**CPU and peripheral clock bit** Clear to select 12 clock periods per machine cycle (STD mode, $F_{OSC}=F_{XTAL}/2$). Set to select 6 clock periods per machine cycle (X2 mode, $F_{OSC}=F_{XTAL}$).

Reset Value = XXXX XXX0b

Not bit addressable

For further details on the X2 feature, please refer to ANM072 available on the web (http://www.atmel.com)

7.1 Application

Software can take advantage of the additional data pointers to both increase speed and reduce code size, for example, block operations (copy, compare, search ...) are well served by using one data pointer as a 'source' pointer and the other one as a "destination" pointer.

ASSEMBLY LANGUAGE

```
; Block move using dual data pointers
; Destroys DPTR0, DPTR1, A and PSW
; note: DPS exits opposite of entry state
; unless an extra INC AUXR1 is added
;
00A2                AUXR1 EQU 0A2H
;
0000 909000         MOV   DPTR,#SOURCE    ; address of SOURCE
0003 05A2           INC   AUXR1           ; switch data pointers
0005 90A000         MOV   DPTR,#DEST      ; address of DEST
0008                LOOP:
0008 05A2           INC   AUXR1           ; switch data pointers
000A E0             MOVX A, @DPTR         ; get a byte from SOURCE
000B A3             INC   DPTR            ; increment SOURCE address
000C 05A2           INC   AUXR1           ; switch data pointers
000E F0             MOVX  @DPTR,A         ; write the byte to DEST
000F A3             INC   DPTR            ; increment DEST address
0010 70F6           JNZ   LOOP            ; check for 0 terminator
0012 05A2           INC   AUXR1           ; (optional) restore DPS
```

INC is a short (2 bytes) and fast (12 clocks) way to manipulate the DPS bit in the AUXR1 SFR. However, note that the INC instruction does not directly force the DPS bit to a particular state, but simply toggles it. In simple routines, such as the block move example, only the fact that DPS is toggled in the proper sequence matters, not its actual value. In other words, the block move routine works the same whether DPS is '0' or '1' on entry. Observe that without the last instruction (INC AUXR1), the routine will exit with DPS in the opposite state.

Table 8-2. T2MOD Register
T2MOD - Timer 2 Mode Control Register (C9h)

7	6	5	4	3	2	1	0
-	-	-	-	-	-	T2OE	DCEN

Bit Number	Bit Mnemonic	Description
7	-	**Reserved** The value read from this bit is indeterminate. Do not set this bit.
6	-	**Reserved** The value read from this bit is indeterminate. Do not set this bit.
5	-	**Reserved** The value read from this bit is indeterminate. Do not set this bit.
4	-	**Reserved** The value read from this bit is indeterminate. Do not set this bit.
3	-	**Reserved** The value read from this bit is indeterminate. Do not set this bit.
2	-	**Reserved** The value read from this bit is indeterminate. Do not set this bit.
1	T2OE	**Timer 2 Output Enable bit** Clear to program P1.0/T2 as clock input or I/O port. Set to program P1.0/T2 as clock output.
0	DCEN	**Down Counter Enable bit** Clear to disable timer 2 as up/down counter. Set to enable timer 2 as up/down counter.

Reset Value = XXXX XX00b

Not bit addressable

11. Idle mode

An instruction that sets PCON.0 causes that to be the last instruction executed before going into the Idle mode. In the Idle mode, the internal clock signal is gated off to the CPU, but not to the interrupt, Timer, and Serial Port functions. The CPU status is preserved in its entirely : the Stack Pointer, Program Counter, Program Status Word, Accumulator and all other registers maintain their data during Idle. The port pins hold the logical states they had at the time Idle was activated. ALE and PSEN hold at logic high levels.

There are two ways to terminate the Idle. Activation of any enabled interrupt will cause PCON.0 to be cleared by hardware, terminating the Idle mode. The interrupt will be serviced, and following RETI the next instruction to be executed will be the one following the instruction that put the device into idle.

The flag bits GF0 and GF1 can be used to give an indication if an interrupt occured during normal operation or during an Idle. For example, an instruction that activates Idle can also set one or both flag bits. When Idle is terminated by an interrupt, the interrupt service routine can examine the flag bits.

The other way of terminating the Idle mode is with a hardware reset. Since the clock oscillator is still running, the hardware reset needs to be held active for only two machine cycles (24 oscillator periods) to complete the reset.

11.1 Power-Down Mode

To save maximum power, a power-down mode can be invoked by software (Refer to Table 9-4., PCON register).

In power-down mode, the oscillator is stopped and the instruction that invoked power-down mode is the last instruction executed. The internal RAM and SFRs retain their value until the power-down mode is terminated. V_{CC} can be lowered to save further power. Either a hardware reset or an external interrupt can cause an exit from power-down. To properly terminate power-down, the reset or external interrupt should not be executed before V_{CC} is restored to its normal operating level and must be held active long enough for the oscillator to restart and stabilize.

Only external interrupts $\overline{INT0}$ and $\overline{INT1}$ are useful to exit from power-down. For that, interrupt must be enabled and configured as level or edge sensitive interrupt input.
Holding the pin low restarts the oscillator but bringing the pin high completes the exit as detailed in Figure 11-1. When both interrupts are enabled, the oscillator restarts as soon as one of the two inputs is held low and power down exit will be completed when the first input will be released. In this case the higher priority interrupt service routine is executed.
Once the interrupt is serviced, the next instruction to be executed after RETI will be the one following the instruction that put TS80C54/58X2 into power-down mode.

12. Hardware Watchdog Timer

The WDT is intended as a recovery method in situations where the CPU may be subjected to software upset. The WDT consists of a 14-bit counter and the WatchDog Timer ReSeT (WDTRST) SFR. The WDT is by default disabled from exiting reset. To enable the WDT, user must write 01EH and 0E1H in sequence to the WDTRST, SFR location 0A6H. When WDT is enabled, it will increment every machine cycle while the oscillator is running and there is no way to disable the WDT except through reset (either hardware reset or WDT overflow reset). When WDT overflows, it will drive an output RESET HIGH pulse at the RST-pin.

12.1 Using the WDT

To enable the WDT, user must write 01EH and 0E1H in sequence to the WDTRST, SFR location 0A6H. When WDT is enabled, the user needs to service it by writing to 01EH and 0E1H to WDTRST to avoid WDT overflow. The 14-bit counter overflows when it reaches 16383 (3FFFH) and this will reset the device. When WDT is enabled, it will increment every machine cycle while the oscillator is running. This means the user must reset the WDT at least every 16383 machine cycle. To reset the WDT the user must write 01EH and 0E1H to WDTRST. WDTRST is a write only register. The WDT counter cannot be read or written. When WDT overflows, it will generate an output RESET pulse at the RST-pin. The RESET pulse duration is 96 x T_{OSC} , where T_{OSC} = $1/F_{OSC}$. To make the best use of the WDT, it should be serviced in those sections of code that will periodically be executed within the time required to prevent a WDT reset.

To have a more powerful WDT, a 2^7 counter has been added to extend the Time-out capability, ranking from 16ms to 2s @ F_{OSC} = 12MHz. To manage this feature, refer to WDTPRG register description, Table 12-2. (SFR0A7h).

Table 12-1. WDTRST Register
WDTRST Address (0A6h)

	7	6	5	4	3	2	1
Reset value	X	X	X	X	X	X	X

Write only, this SFR is used to reset/enable the WDT by writing 01EH then 0E1H in sequence.

15. Reduced EMI Mode

The ALE signal is used to demultiplex address and data buses on port 0 when used with external program or data memory. Nevertheless, during internal code execution, ALE signal is still generated. In order to reduce EMI, ALE signal can be disabled by setting AO bit.

The AO bit is located in AUXR register at bit location 0. As soon as AO is set, ALE is no longer output but remains active during MOVX and MOVC instructions and external fetches. During ALE disabling, ALE pin is weakly pulled high.

Table 15-1. AUXR Register
AUXR - Auxiliary Register (8Eh)

7	6	5	4	3	2	1	0
-	-	-	-	-	-	RESERVED	AO

Bit Number	Bit Mnemonic	Description
7	-	**Reserved** The value read from this bit is indeterminate. Do not set this bit.
6	-	**Reserved** The value read from this bit is indeterminate. Do not set this bit.
5	-	**Reserved** The value read from this bit is indeterminate. Do not set this bit.
4	-	**Reserved** The value read from this bit is indeterminate. Do not set this bit.
3	-	**Reserved** The value read from this bit is indeterminate. Do not set this bit.
2	-	**Reserved** The value read from this bit is indeterminate. Do not set this bit.
1	-	**Reserved** The value read from this bit is indeterminate. Do not set this bit.
0	AO	**ALE Output bit** Clear to restore ALE operation during internal fetches. Set to disable ALE operation during internal fetches.

Reset Value = XXXX XXX0b
Not bit addressable

Figure 17-1. Set-Up Modes Configuration
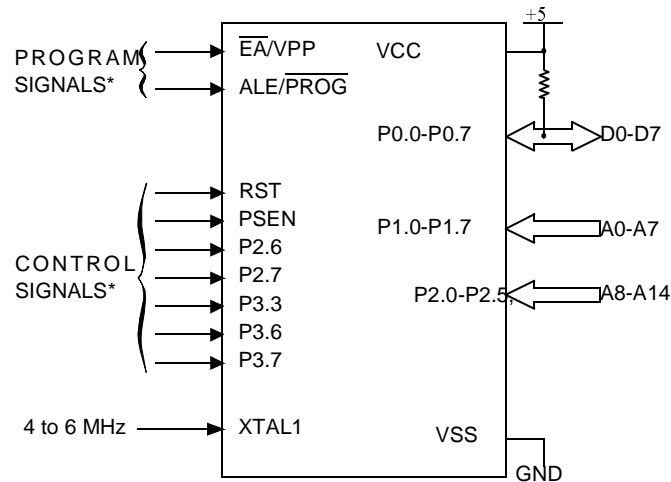
* See Table 31. for proper value on these inputs

17.3.3 Programming Algorithm

The Improved Quick Pulse algorithm is based on the Quick Pulse algorithm and decreases the number of pulses applied during byte programming from 25 to 1.

To program the TS80C54/58X2 the following sequence must be exercised:

- Step 1: Activate the combination of control signals.
- Step 2: Input the valid address on the address lines.
- Step 3: Input the appropriate data on the data lines.
- Step 4: Raise $\overline{EA}$/VPP from VCC to VPP (typical 12.75V).
- Step 5: Pulse ALE/$\overline{PROG}$ once.
- Step 6: Lower $\overline{EA}$/VPP from VPP to VCC

Repeat step 2 through 6 changing the address and data for the entire array or until the end of the object file is reached (See Figure 17-2.).

17.3.4 Verify algorithm

Code array verify must be done after each byte or block of bytes is programmed. In either case, a complete verify of the programmed array will ensure reliable programming of the TS87C54/58X2.

P 2.7 is used to enable data output.

To verify the TS87C54/58X2 code the following sequence must be exercised:

- Step 1: Activate the combination of program and control signals.
- Step 2: Input the valid address on the address lines.
- Step 3: Read data on the data lines.

Repeat step 2 through 3 changing the address for the entire array verification (See Figure 17-2.)

The encryption array cannot be directly verified. Verification of the encryption array is done by observing that the code array is well encrypted.

Figure 17-2. Programming and Verification Signal's Waveform
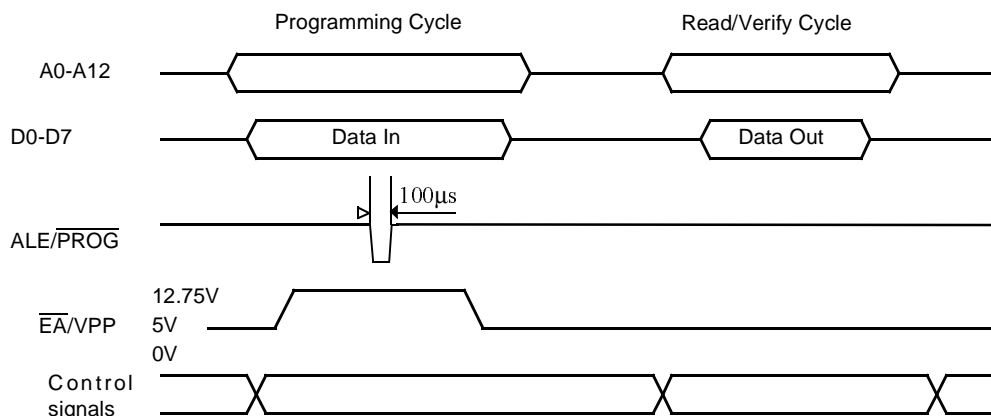
17.4 EPROM Erasure (Windowed Packages Only)

Erasing the EPROM erases the code array, the encryption array and the lock bits returning the parts to full functionality.

Erasure leaves all the EPROM cells in a 1's state (FF).

17.4.1 Erasure Characteristics

The recommended erasure procedure is exposure to ultraviolet light (at 2537 Å) to an integrated dose at least 15 W-sec/cm^2. Exposing the EPROM to an ultraviolet lamp of 12,000 μW/cm^2 rating for 30 minutes, at a distance of about 25 mm, should be sufficient. An exposure of 1 hour is recommended with most of standard erasers.

Erasure of the EPROM begins to occur when the chip is exposed to light with wavelength shorter than approximately 4,000 Å. Since sunlight and fluorescent lighting have wavelengths in this range, exposure to these light sources over an extended time (about 1 week in sunlight, or 3 years in room-level fluorescent lighting) could cause inadvertent erasure. If an application subjects the device to this type of exposure, it is suggested that an opaque label be placed over the window.

18. Signature Bytes

The TS87C54/58X2 has four signature bytes in location 30h, 31h, 60h and 61h. To read these bytes follow the procedure for EPROM verify but activate the control lines provided in Table 31. for Read Signature Bytes. Table 18-1. shows the content of the signature byte for the TS80C54/58X2.

19.4 DC Parameters for Low Voltage

$T_A = 0°C$ to $+70°C$; $V_{SS} = 0$ V; $V_{CC} = 2.7$ V to 5.5 V $\pm$ 10%; F = 0 to 30 MHz.
$T_A = -40°C$ to $+85°C$; $V_{SS} = 0$ V; $V_{CC} = 2.7$ V to 5.5 V $\pm$ 10%; F = 0 to 30 MHz.

Table 19-2. DC Parameters for Low Voltage

Symbol	Parameter	Min	Typ	Max	Unit	Test Conditions
V_{IL}	Input Low Voltage	-0.5		$0.2 V_{CC}$ - 0.1	V	
V_{IH}	Input High Voltage except XTAL1, RST	$0.2 V_{CC}$ + 0.9		V_{CC} + 0.5	V	
V_{IH1}	Input High Voltage, XTAL1, RST	$0.7 V_{CC}$		V_{CC} + 0.5	V	
V_{OL}	Output Low Voltage, ports 1, 2, 3 [6]			0.45	V	I_{OL} = 0.8 mA[4]
V_{OL1}	Output Low Voltage, port 0, ALE, $\overline{PSEN}$ [6]			0.45	V	I_{OL} = 1.6 mA[4]
V_{OH}	Output High Voltage, ports 1, 2, 3	$0.9 V_{CC}$			V	I_{OH} = -10 µA
V_{OH1}	Output High Voltage, port 0, ALE, $\overline{PSEN}$	$0.9 V_{CC}$			V	I_{OH} = -40 µA
I_{IL}	Logical 0 Input Current ports 1, 2 and 3			-50	µA	Vin = 0.45 V
I_{LI}	Input Leakage Current			$\pm$10	µA	0.45 V < Vin < V_{CC}
I_{TL}	Logical 1 to 0 Transition Current, ports 1, 2, 3			-650	µA	Vin = 2.0 V
R_{RST}	RST Pulldown Resistor	50	90 [5]	200	kΩ	
CIO	Capacitance of I/O Buffer			10	pF	Fc = 1 MHz T_A = 25°C
I_{PD}	Power Down Current		20 [5] 10 [5]	50 30	µA	V_{CC} = 2.0 V to 5.5 V[3] V_{CC} = 2.0 V to 3.3 V[3]
I_{CC} under RESET	Power Supply Current Maximum values, X1 mode: [7]			1 + 0.2 Freq (MHz) @12MHz 3.4 @16MHz 4.2	mA	V_{CC} = 3.3 V[1]
I_{CC} operating	Power Supply Current Maximum values, X1 mode: [7]			1 + 0.3 Freq (MHz) @12MHz 4.6 @16MHz 5.8	mA	V_{CC} = 3.3 V[8]
I_{CC} idle	Power Supply Current Maximum values, X1 mode: [7]			0.15 Freq (MHz) + 0.2 @12MHz 2 @16MHz 2.6	mA	V_{CC} = 3.3 V[2]

1. I_{CC} under reset is measured with all output pins disconnected; XTAL1 driven with T_{CLCH}, T_{CHCL} = 5 ns (see Figure 19-5.), $V_{IL} = V_{SS}$ + 0.5 V,
    $V_{IH} = V_{CC}$ - 0.5V; XTAL2 N.C.; $\overline{EA}$ = RST = Port 0 = V_{CC}. I_{CC} would be slightly higher if a crystal oscillator used..

2. Idle I_{CC} is measured with all output pins disconnected; XTAL1 driven with T_{CLCH}, T_{CHCL} = 5 ns, $V_{IL} = V_{SS}$ + 0.5 V,
    $V_{IH} = V_{CC}$ - 0.5 V; XTAL2 N.C; Port 0 = V_{CC}; $\overline{EA}$ = RST = V_{SS} (see Figure 19-3.).

3. Power Down I_{CC} is measured with all output pins disconnected; $\overline{EA} = V_{SS}$, PORT 0 = V_{CC}; XTAL2 NC.; RST = V_{SS}
    (see Figure 19-4.).

4. Capacitance loading on Ports 0 and 2 may cause spurious noise pulses to be superimposed on the V_{OL}s of ALE and Ports 1 and 3. The noise is due to external bus capacitance discharging into the Port 0 and Port 2 pins when these pins make 1 to 0 transitions during bus operation. In the worst cases (capacitive loading 100pF), the noise pulse on the ALE line may exceed 0.45V with maxi V_{OL} peak 0.6V. A Schmitt Trigger use is not necessary.

19.5 AC Parameters

19.5.1 Explanation of the AC Symbols

Each timing symbol has 5 characters. The first character is always a "T" (stands for time). The other characters, depending on their positions, stand for the name of a signal or the logical status of that signal. The following is a list of all the characters and what they stand for.

Example: T_{AVLL} = Time for Address Valid to ALE Low.

T_{LLPL} = Time for ALE Low to $\overline{PSEN}$ Low.

T_A = 0 to +70°C (commercial temperature range); V_{SS} = 0 V; V_{CC} = 5 V $\pm$ 10%; -M and -V ranges.
T_A = -40°C to +85°C (industrial temperature range); V_{SS} = 0 V; V_{CC} = 5 V $\pm$ 10%; -M and -V ranges.
T_A = 0 to +70°C (commercial temperature range); V_{SS} = 0 V; 2.7 V < V_{CC} < 5.5 V; -L range.
T_A = -40°C to +85°C (industrial temperature range); V_{SS} = 0 V; 2.7 V < V_{CC} < 5.5 V; -L range.

Table 19-3. gives the maximum applicable load capacitance for Port 0, Port 1, 2 and 3, and ALE and $\overline{PSEN}$ signals. Timings will be guaranteed if these capacitances are respected. Higher capacitance values can be used, but timings will then be degraded.

Table 19-3. Load Capacitance versus speed range, in pF

	-M	**-V**	**-L**
Port 0	100	50	100
Port 1, 2, 3	80	50	80
ALE / $\overline{PSEN}$	100	30	100

Table 19-5., Table 19-8. and Table 19-11. give the description of each AC symbols.

Table 19-6., Table 19-9. and Table 19-12. give for each range the AC parameter.

Table 19-7., Table 19-10. and Table 19-13. give the frequency derating formula of the AC parameter. To calculate each AC symbols, take the x value corresponding to the speed grade you need (-M, -V or -L) and replace this value in the formula. Values of the frequency must be limited to the corresponding speed grade:

Table 19-4. Max frequency for derating formula regarding the speed grade

	-M X1 mode	**-M X2 mode**	**-V X1 mode**	**-V X2 mode**	**-L X1 mode**	**-L X2 mode**
Freq (MHz)	40	20	40	30	30	20
T (ns)	25	50	25	33.3	33.3	50

Example:

T_{LLIV} in X2 mode for a -V part at 20 MHz (T = $1/20^{E6}$ = 50 ns):

x= 22 (Table 19-7.)

T= 50ns

T_{LLIV}= 2T - x = 2 x 50 - 22 = 78ns

19.5.4 External Data Memory Characteristics

Table 19-8. Symbol Description

Symbol	Parameter
T$_{RLRH}$	$\overline{RD}$ Pulse Width
T$_{WLWH}$	$\overline{WR}$ Pulse Width
T$_{RLDV}$	$\overline{RD}$ to Valid Data In
T$_{RHDX}$	Data Hold After $\overline{RD}$
T$_{RHDZ}$	Data Float After $\overline{RD}$
T$_{LLDV}$	ALE to Valid Data In
T$_{AVDV}$	Address to Valid Data In
T$_{LLWL}$	ALE to $\overline{WR}$ or $\overline{RD}$
T$_{AVWL}$	Address to $\overline{WR}$ or $\overline{RD}$
T$_{QVWX}$	Data Valid to $\overline{WR}$ Transition
T$_{QVWH}$	Data set-up to $\overline{WR}$ High
T$_{WHQX}$	Data Hold After $\overline{WR}$
T$_{RLAZ}$	$\overline{RD}$ Low to Address Float
T$_{WHLH}$	$\overline{RD}$ or $\overline{WR}$ High to ALE high

Table 19-9. AC Parameters for a Fix Clock

Speed	-M 40 MHz		-V X2 mode 30 MHz 60 MHz equiv.		-V standard mode 40 MHz		-L X2 mode 20 MHz 40 MHz equiv.		-L standard mode 30 MHz		Units
Symbol	Min	Max	Min	Max	Min	Max	Min	Max	Min	Max	
T$_{RLRH}$	130		85		135		125		175		ns
T$_{WLWH}$	130		85		135		125		175		ns
T$_{RLDV}$		100		60		102		95		137	ns
T$_{RHDX}$	0		0		0		0		0		ns
T$_{RHDZ}$		30		18		35		25		42	ns
T$_{LLDV}$		160		98		165		155		222	ns
T$_{AVDV}$		165		100		175		160		235	ns
T$_{LLWL}$	50	100	30	70	55	95	45	105	70	130	ns
T$_{AVWL}$	75		47		80		70		103		ns
T$_{QVWX}$	10		7		15		5		13		ns
T$_{QVWH}$	160		107		165		155		213		ns
T$_{WHQX}$	15		9		17		10		18		ns
T$_{RLAZ}$		0		0		0		0		0	ns
T$_{WHLH}$	10	40	7	27	15	35	5	45	13	53	ns

19.5.6 External Data Memory Read Cycle

Figure 19-8. External Data Memory Read Cycle
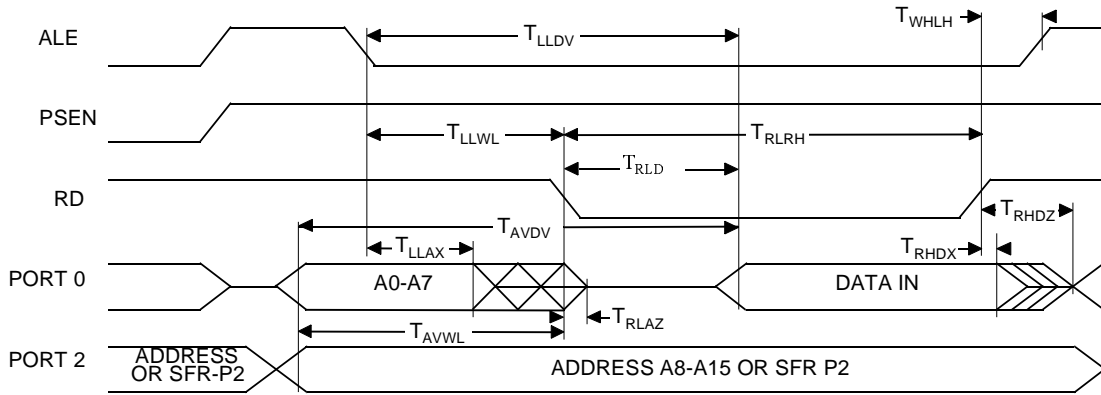
19.5.7 Serial Port Timing - Shift Register Mode

Table 19-11. Symbol Description

Symbol	Parameter
T_{XLXL}	Serial port clock cycle time
T_{QVHX}	Output data set-up to clock rising edge
T_{XHQX}	Output data hold after clock rising edge
T_{XHDX}	Input data hold after clock rising edge
T_{XHDV}	Clock rising edge to input data valid

Table 19-12. AC Parameters for a Fix Clock

Speed	-M 40 MHz		-V X2 mode 30 MHz 60 MHz equiv.		-V standard mode 40 MHz		-L X2 mode 20 MHz 40 MHz equiv.		-L standard mode 30 MHz		Units
Symbol	Min	Max	Min	Max	Min	Max	Min	Max	Min	Max	
T_{XLXL}	300		200		300		300		400		ns
T_{QVHX}	200		117		200		200		283		ns
T_{XHQX}	30		13		30		30		47		ns
T_{XHDX}	0		0		0		0		0		ns
T_{XHDV}		117		34		117		117		200	ns

19.5.9 EPROM Programming and Verification Characteristics

$T_A = 21°C$ to $27°C$; $V_{SS} = 0V$; $V_{CC} = 5V \pm 10\%$ while programming. V_{CC} = operating range while verifying.

Table 19-14. EPROM Programming Parameters

Symbol	Parameter	Min	Max	Units
V_{PP}	Programming Supply Voltage	12.5	13	V
I_{PP}	Programming Supply Current		75	mA
$1/T_{CLCL}$	Oscillator Frquency	4	6	MHz
T_{AVGL}	Address Setup to $\overline{PROG}$ Low	48 T_{CLCL}		
T_{GHAX}	Adress Hold after $\overline{PROG}$	48 T_{CLCL}		
T_{DVGL}	Data Setup to $\overline{PROG}$ Low	48 T_{CLCL}		
T_{GHDX}	Data Hold after $\overline{PROG}$	48 T_{CLCL}		
T_{EHSH}	(Enable) High to V_{PP}	48 T_{CLCL}		
T_{SHGL}	V_{PP} Setup to $\overline{PROG}$ Low	10		µs
T_{GHSL}	V_{PP} Hold after $\overline{PROG}$	10		µs
T_{GLGH}	$\overline{PROG}$ Width	90	110	µs
T_{AVQV}	Address to Valid Data		48 T_{CLCL}	
T_{ELQV}	ENABLE Low to Data Valid		48 T_{CLCL}	
T_{EHQZ}	Data Float after ENABLE	0	48 T_{CLCL}	

19.5.10 EPROM Programming and Verification Waveforms

Figure 19-10. EPROM Programming and Verification Waveforms
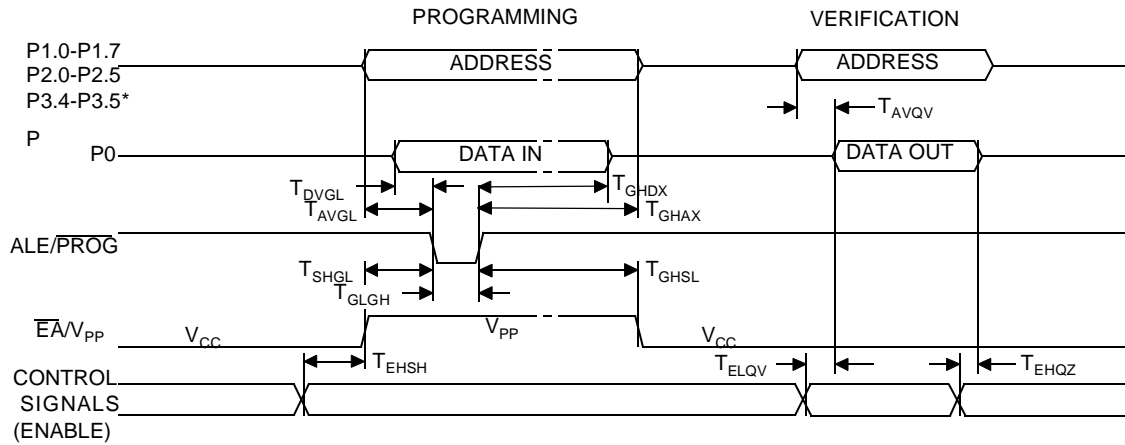
* 8KB: up to P2.4, 16KB: up to P2.5, 32KB: up to P3.4, 64KB: up to P3.5

19.5.11   External Clock Drive Characteristics (XTAL1)

Table 19-15. AC Parameters

Symbol	Parameter	Min	Max	Units
T_{CLCL}	Oscillator Period	25		ns
T_{CHCX}	High Time	5		ns
T_{CLCX}	Low Time	5		ns
T_{CLCH}	Rise Time		5	ns
T_{CHCL}	Fall Time		5	ns
T_{CHCX}/T_{CLCX}	Cyclic ratio in X2 mode	40	60	%

19.5.12   External Clock Drive Waveforms

Figure 19-11. External Clock Drive Waveforms
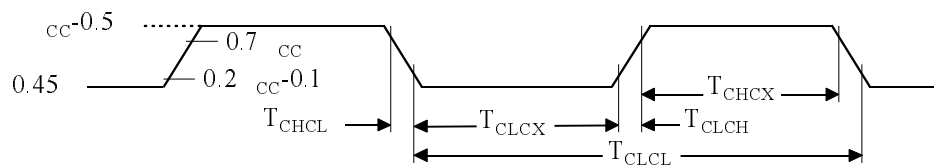
Part Number	Supply Voltage	Temperature Range	Package	Packing
TS87C54X2-MCC	5V ±10%	Commercial	PQFP44	Tray
TS87C54X2-MCE	5V ±10%	Commercial	VQFP44	Tray
TS87C54X2-VCA	5V ±10%	Commercial	PDIL40	Stick
TS87C54X2-VCB	5V ±10%	Commercial	PLCC44	Stick
TS87C54X2-VCC	5V ±10%	Commercial	PQFP44	Tray
TS87C54X2-VCE	5V ±10%	Commercial	VQFP44	Tray
TS87C54X2-LCA	2.7 to 5.5V	Commercial	PDIL40	Stick
TS87C54X2-LCB	2.7 to 5.5V	Commercial	PLCC44	Stick
TS87C54X2-LCC	2.7 to 5.5V	Commercial	PQFP44	Tray
TS87C54X2-LCE	2.7 to 5.5V	Commercial	VQFP44	Tray
TS87C54X2-MIA	5V ±10%	Industrial	PDIL40	Stick
TS87C54X2-MIB	5V ±10%	Industrial	PLCC44	Stick
TS87C54X2-MIC	5V ±10%	Industrial	PQFP44	Tray
TS87C54X2-MIE	5V ±10%	Industrial	VQFP44	Tray
TS87C54X2-VIA	5V ±10%	Industrial	PDIL40	Stick
TS87C54X2-VIB	5V ±10%	Industrial	PLCC44	Stick
TS87C54X2-VIC	5V ±10%	Industrial	PQFP44	Tray
TS87C54X2-VIE	5V ±10%	Industrial	VQFP44	Tray
TS87C54X2-LIA	2.7 to 5.5V	Industrial	PDIL40	Stick
TS87C54X2-LIB	2.7 to 5.5V	Industrial	PLCC44	Stick
TS87C54X2-LIC	2.7 to 5.5V	Industrial	PQFP44	Tray
TS87C54X2-LIE	2.7 to 5.5V	Industrial	VQFP44	Tray
AT87C54X2-3CSUM	5V ±10%	Industrial & Green	PDIL40	Stick
AT87C54X2-SLSUM	5V ±10%	Industrial & Green	PLCC44	Stick
AT87C54X2-RLTUM	5V ±10%	Industrial & Green	VQFP44	Tray
AT87C54X2-3CSUL	2.7 to 5.5V	Industrial & Green	PDIL40	Stick
AT87C54X2-SLSUL	2.7 to 5.5V	Industrial & Green	PLCC44	Stick
AT87C54X2-RLTUL	2.7 to 5.5V	Industrial & Green	VQFP44	Tray
AT87C54X2-3CSUV	5V ±10%	Industrial & Green	PDIL40	Stick
AT87C54X2-SLSUV	5V ±10%	Industrial & Green	PLCC44	Stick
AT87C54X2-RLTUV	5V ±10%	Industrial & Green	VQFP44	Tray

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