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Understanding [Embedded - FPGAs \(Field Programmable Gate Array\)](#)

Embedded - FPGAs, or Field Programmable Gate Arrays, are advanced integrated circuits that offer unparalleled flexibility and performance for digital systems. Unlike traditional fixed-function logic devices, FPGAs can be programmed and reprogrammed to execute a wide array of logical operations, enabling customized functionality tailored to specific applications. This reprogrammability allows developers to iterate designs quickly and implement complex functions without the need for custom hardware.

Applications of Embedded - FPGAs

The versatility of Embedded - FPGAs makes them indispensable in numerous fields. In telecommunications.

Details

Product Status	Active
Number of LABs/CLBs	-
Number of Logic Elements/Cells	6060
Total RAM Bits	719872
Number of I/O	161
Number of Gates	-
Voltage - Supply	1.14V ~ 2.625V
Mounting Type	Surface Mount
Operating Temperature	-40°C ~ 100°C (TJ)
Package / Case	256-LFBGA
Supplier Device Package	256-FPBGA (14x14)
Purchase URL	https://www.e-xfl.com/product-detail/microchip-technology/m2gl005-1vf256i

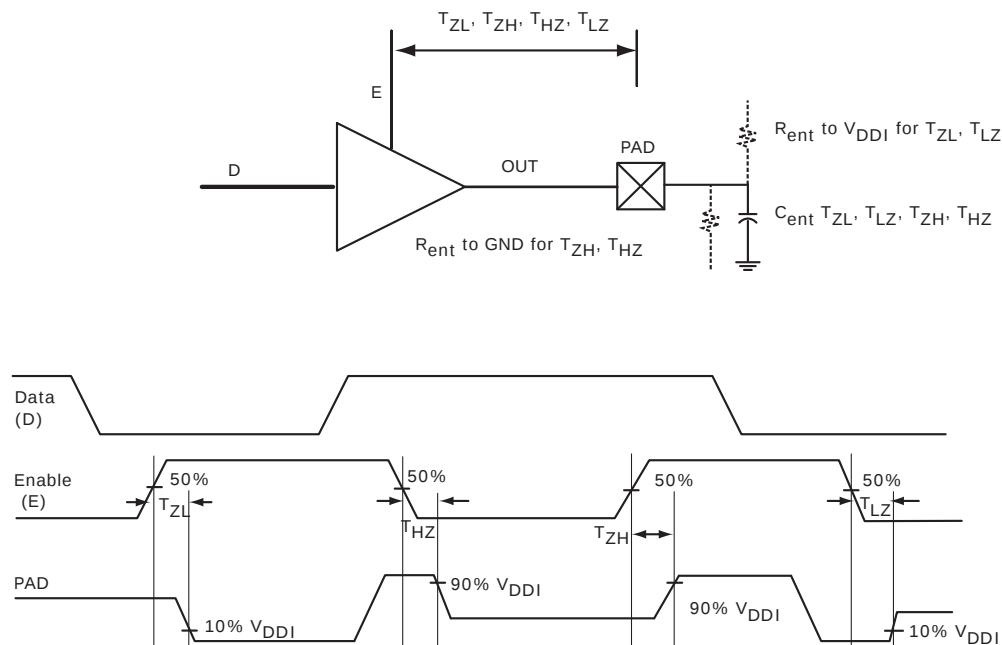
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2.3.5.3 Tristate Buffer and AC Loading

The tristate path for enable path loadings is described in the respective specifications. The following figure shows the methodology of characterization illustrated by the enable path test point.

Figure 5 • Tristate Buffer for Enable Path Test Point



2.3.5.4 I/O Speeds

This section describes the maximum data rate summary of I/O in worst-case industrial conditions. See the individual I/O standards for operating conditions.

Table 18 • Maximum Data Rate Summary Table for Single-Ended I/O in Worst-Case Industrial Conditions

I/O	MSIO	MSIOD	DDRIO	Unit
PCI 3.3 V	630			Mbps
LVTTL 3.3 V	600			Mbps
LVC MOS 3.3 V	600			Mbps
LVC MOS 2.5 V	410	420	400	Mbps
LVC MOS 1.8 V	295	400	400	Mbps
LVC MOS 1.5 V	160	220	235	Mbps
LVC MOS 1.2 V	120	160	200	Mbps
LPDDR-LVC MOS 1.8 V mode			400	Mbps

Table 53 • LVCMOS 1.8 V AC Calibrated Impedance Option

Parameter	Symbol	Typ	Unit
Supported output driver calibrated impedance (for DDRIO I/O bank)	R _{odt_cal}	75, 60, 50, 33, 25, 20	Ω

Table 54 • LVCMOS 1.8 V AC Test Parameter Specifications

Parameter	Symbol	Typ	Unit
Measuring/trip point for data path	V _{TRIP}	0.9	V
Resistance for enable path (T _{ZH} , T _{ZL} , T _{HZ} , T _{LZ})	R _{ENT}	2k	Ω
Capacitive loading for enable path (T _{ZH} , T _{ZL} , T _{HZ} , T _{LZ})	C _{ENT}	5	pF
Capacitive loading for data path (T _{DP})	C _{LOAD}	5	pF

Table 55 • LVCMOS 1.8 V Transmitter Drive Strength Specifications

Output Drive Selection			V _{OH} (V)	V _{OL} (V)	IOH (at V _{OH})	IOL (at V _{OL})
MSIO I/O Bank	MSIOD I/O Bank	DDRIO I/O Bank	Min	Max	mA	mA
2 mA	2 mA	2 mA	V _{DDI} – 0.45	0.45	2	2
4 mA	4 mA	4 mA	V _{DDI} – 0.45	0.45	4	4
6 mA	6 mA	6 mA	V _{DDI} – 0.45	0.45	6	6
8 mA	8 mA	8 mA	V _{DDI} – 0.45	0.45	8	8
10 mA	10 mA	10 mA	V _{DDI} – 0.45	0.45	10	10
12 mA		12 mA	V _{DDI} – 0.45	0.45	12	12
		16 mA ¹	V _{DDI} – 0.45	0.45	16	16

1. 16 mA drive strengths, all slews, meets LPDDR JEDEC electrical compliance.

AC Switching Characteristics

Worst commercial-case conditions: T_J = 85 °C, V_{DD} = 1.14 V, V_{DDI} = 1.71 V

Table 56 • LVCMOS 1.8 V Receiver Characteristics (Input Buffers)

	On-Die Termination (ODT)	T _{Py}		T _{PYS}		Unit
		–1	–Std	–1	–Std	
LVCMOS 1.8 V (for DDRIO I/O bank with Fixed Codes)	None	1.968	2.315	2.099	2.47	ns
	None	2.898	3.411	2.883	3.393	ns
LVCMOS 1.8 V (for MSIO I/O bank)	50	3.05	3.59	3.044	3.583	ns
	75	2.999	3.53	2.987	3.516	ns
	150	2.947	3.469	2.933	3.452	ns
	None	2.611	3.071	2.598	3.057	ns
LVCMOS 1.8 V (for MSIOD I/O bank)	50	2.775	3.264	2.775	3.265	ns
	75	2.72	3.2	2.712	3.19	ns
	150	2.666	3.137	2.655	3.123	ns
	None	2.611	3.071	2.598	3.057	ns

Table 72 • LVCMOS 1.5 V Transmitter Characteristics for MSIOD I/O Bank (Output and Tristate Buffers)

Output Drive Selection	Slew Control	T_{DP}		T_{ZL}		T_{ZH}		T_{HZ}^1		T_{LZ}^1		Unit
		-1	-Std	-1	-Std	-1	-Std	-1	-Std	-1	-Std	
2 mA	Slow	2.735	3.218	3.371	3.966	3.618	4.257	6.03	7.095	5.705	6.712	ns
4 mA	Slow	2.426	2.854	2.992	3.521	3.221	3.79	6.738	7.927	6.298	7.41	ns
6 mA	Slow	2.433	2.862	2.81	3.306	3.031	3.566	7.123	8.38	6.596	7.76	ns

1. Delay increases with drive strength are inherent to built-in slew control circuitry for simultaneous switching output (SSO) management.

2.3.5.10 1.2 V LVCMOS

LVCMOS 1.2 is a general standard for 1.2 V applications and is supported in IGLOO2 FPGAs and SmartFusion2 SoC FPGAs in compliance to the JEDEC specification JESD8-12A.

Minimum and Maximum DC/AC Input and Output Levels Specification

Table 73 • LVCMOS 1.2 V DC Recommended DC Operating Conditions

Parameter	Symbol	Min	Typ	Max	Unit
Supply voltage	V_{DDI}	1.140	1.2	1.26	V

Table 74 • LVCMOS 1.2 V DC Input Voltage Specification

Parameter	Symbol	Min	Max	Unit
DC input logic high (for MSIOD and DDRIO I/O banks)	$V_{IH} (DC)$	$0.65 \times V_{DDI}$	1.26	V
DC input logic high (for MSIO I/O bank)	$V_{IH} (DC)$	$0.65 \times V_{DDI}$	3.45	V
DC input logic low	$V_{IL} (DC)$	-0.3	$0.35 \times V_{DDI}$	V
Input current high ¹	$I_{IH} (DC)$			
Input current low ¹	$I_{IL} (DC)$			

1. See Table 24, page 22.

Table 75 • LVCMOS 1.2 V DC Output Voltage Specification

Parameter	Symbol	Min	Max	Unit
DC output logic high	V_{OH}	$V_{DDI} \times 0.75$		V
DC output logic low	V_{OL}		$V_{DDI} \times 0.25$	V

Table 76 • LVCMOS 1.2 V Minimum and Maximum AC Switching Speed

Parameter	Symbol	Max	Unit	Conditions
Maximum data rate (for DDRIO I/O bank)	D_{MAX}	200	Mbps	AC loading: 17 pF load, maximum drive/slew
Maximum data rate (for MSIO I/O bank)	D_{MAX}	120	Mbps	AC loading: 17 pF load, maximum drive/slew
Maximum data rate (for MSIOD I/O bank)	D_{MAX}	160	Mbps	AC loading: 17 pF load, maximum drive/slew

Table 85 • LVCMOS 1.2 V Transmitter Characteristics for MSIOD I/O Bank (Output and Tristate Buffers)

Output Drive Selection	Slew Control	T _{DP}		T _{ZL}		T _{ZH}		T _{HZ} ¹		T _{LZ} ¹		Unit
		-1	-Std	-1	-Std	-1	-Std	-1	-Std	-1	-Std	
2 mA	Slow	3.883	4.568	4.868	5.726	5.329	6.269	7.994	9.404	7.527	8.855	ns
4 mA	Slow	3.774	4.44	4.188	4.926	4.613	5.426	8.972	10.555	8.315	9.782	ns

1. Delay increases with drive strength are inherent to built-in slew control circuitry for simultaneous switching output (SSO) management.

2.3.5.11 3.3 V PCI/PCIX

Peripheral Component Interface (PCI) for 3.3 V standards specify support for 33 MHz and 66 MHz PCI bus applications.

Minimum and Maximum DC/AC Input and Output Levels Specification (Applicable to MSIO Bank Only)

Table 86 • PCI/PCI-X DC Recommended Operating Conditions

Parameter	Symbol	Min	Typ	Max	Unit
Supply voltage	V _{DDI}	3.15	3.3	3.45	V

Table 87 • PCI/PCI-X DC Input Voltage Specification

Parameter	Symbol	Min	Max	Unit
DC input voltage	V _I	0	3.45	V
Input current high ¹	I _{IH} (DC)			
Input current low ¹	I _{IL} (DC)			

1. See Table 24, page 22.

Table 88 • PCI/PCI-X DC Output Voltage Specification

Parameter	Symbol	Min	Typ	Max	Unit
DC output logic high	V _{OH}		Per PCI specification		V
DC output logic low	V _{OL}		Per PCI specification		V

Table 89 • PCI/PCI-X Minimum and Maximum AC Switching Speed

Parameter	Symbol	Max	Unit	Conditions
Maximum data rate (MSIO I/O bank)	D _{MAX}	630	Mbps	AC Loading: per JEDEC specifications

Table 90 • PCI/PCI-X AC Test Parameter Specifications

Parameter	Symbol	Typ	Unit
Measuring/trip point for data path (falling edge)	V _{TRIP}	0.615 × V _{DDI}	V
Measuring/trip point for data path (rising edge)	V _{TRIP}	0.285 × V _{DDI}	V
Resistance for data test path	RTT_TEST	25	Ω
Resistance for enable path (T _{ZH} , T _{ZL} , T _{HZ} , T _{LZ})	R _{ENT}	2K	Ω
Capacitive loading for enable path (T _{ZH} , T _{ZL} , T _{HZ} , T _{LZ})	C _{ENT}	5	pF
Capacitive loading for data path (T _{DP})	C _{LOAD}	10	pF

Table 122 • SSTL18 DC Differential Voltage Specification

Parameter	Symbol	Min	Unit
DC input differential voltage	V_{ID} (DC)	0.3	V

Table 123 • SSTL18 AC Differential Voltage Specifications (Applicable to DDRIO Bank Only)

Parameter	Symbol	Min	Max	Unit
AC input differential voltage	V_{DIFF} (AC)	0.5		V
AC differential cross point voltage	V_x (AC)	$0.5 \times V_{DDI} - 0.175$	$0.5 \times V_{DDI} + 0.175$	V

Table 124 • SSTL18 Minimum and Maximum AC Switching Speed (Applicable to DDRIO Bank Only)

Parameter	Symbol	Max	Unit	Conditions
Maximum data rate (for DDRIO I/O bank)	D_{MAX}	667	Mbps	AC loading: per JEDEC specification

Table 125 • SSTL18 AC Impedance Specifications (Applicable to DDRIO Bank Only)

Parameter	Symbol	Typ	Unit	Conditions
Supported output driver calibrated impedance (for DDRIO I/O bank)	R_{REF}	20, 42	Ω	Reference resistor = 150 Ω
Effective impedance value (ODT)	R_{TT}	50, 75, 150	Ω	Reference resistor = 150 Ω

Table 126 • SSTL18 AC Test Parameter Specifications (Applicable to DDRIO Bank Only)

Parameter	Symbol	Typ	Unit
Measuring/trip point for data path	V_{TRIP}	0.9	V
Resistance for enable path (T_{ZH} , T_{ZL} , T_{HZ} , T_{LZ})	R_{ENT}	2K	Ω
Capacitive loading for enable path (T_{ZH} , T_{ZL} , T_{HZ} , T_{LZ})	C_{ENT}	5	pF
Reference resistance for data test path for SSTL18 Class I (T_{DP})	RTT_TEST	50	Ω
Reference resistance for data test path for SSTL18 Class II (T_{DP})	RTT_TEST	25	Ω
Capacitive loading for data path (T_{DP})	C_{LOAD}	5	pF

AC Switching Characteristics

Worst commercial-case conditions: $T_J = 85^\circ\text{C}$, $V_{DD} = 1.14\text{ V}$, $V_{DDI} = 1.71\text{ V}$

Table 127 • DDR2/SSTL18 Receiver Characteristics for DDRIO I/O Bank with Fixed Code

		T_{PY}		Unit
		-1	-Std	
Pseudo differential	None	1.567	1.844	ns
True differential	None	1.588	1.869	ns

Table 168 • LVDS25 Receiver Characteristics for MSIOD I/O Bank (Input Buffers)

On-Die Termination (ODT)	T_{PY}		Unit
	-1	-Std	
None	2.554	3.004	ns
100	2.549	2.999	ns

Table 169 • LVDS25 Transmitter Characteristics for MSIO I/O Bank (Output and Tristate Buffers)

T_{DP}		T_{ZL}		T_{ZH}		T_{HZ}		T_{LZ}		Unit
-1	-Std	-1	-Std	-1	-Std	-1	-Std	-1	-Std	
2.136	2.513	2.416	2.842	2.402	2.825	2.423	2.85	2.409	2.833	ns

Table 170 • LVDS25 Transmitter Characteristics for MSIOD I/O Bank (Output and Tristate Buffers)

	T_{DP}		T_{ZL}		T_{ZH}		T_{HZ}		T_{LZ}		Unit
	-1	-Std	-1	-Std	-1	-Std	-1	-Std	-1	-Std	
No pre-emphasis	1.61	1.893	1.749	2.058	1.735	2.041	1.897	2.231	1.866	2.195	ns
Min pre-emphasis	1.527	1.796	1.757	2.067	1.744	2.052	1.905	2.241	1.876	2.207	ns
Med pre-emphasis	1.496	1.76	1.765	2.077	1.751	2.06	1.914	2.252	1.884	2.216	ns

LVDS33 AC Switching Characteristics**Table 171 • LVDS33 Receiver Characteristics for MSIO I/O Bank (Input Buffers)**

On Die Termination (ODT)	T_{PY}		Unit
	-1	-Std	
None	2.572	3.025	ns
100	2.569	3.023	ns

Table 172 • LVDS33 Transmitter Characteristics for MSIO I/O Bank (Output and Tristate Buffers)

T_{DP}		T_{ZL}		T_{ZH}		T_{HZ}		T_{LZ}		Unit
-1	-Std	-1	-Std	-1	-Std	-1	-Std	-1	-Std	
1.942	2.284	1.98	2.33	1.97	2.318	1.953	2.298	1.96	2.307	ns

Table 215 • LVPECL DC Input Voltage Specification

Parameter	Symbol	Min	Max	Unit
DC input voltage	V_I	0	3.45	V

Table 216 • LVPECL DC Differential Voltage Specification

Parameter	Symbol	Min	Typ	Max	Unit
Input common mode voltage	V_{ICM}	0.3		2.8	V
Input differential voltage	V_{IDIFF}	100	300	1,000	mV

Table 217 • LVPECL Minimum and Maximum AC Switching Speeds

Parameter	Symbol	Max	Unit
Maximum data rate	D _{MAX}	900	Mbps

AC Switching Characteristics

Worst commercial-case conditions: $T_J = 85^\circ\text{C}$, $V_{DD} = 1.14\text{ V}$, $V_{DDI} = 2.375\text{ V}$.

Table 218 • LVPECL Receiver Characteristics for MSIO I/O Bank

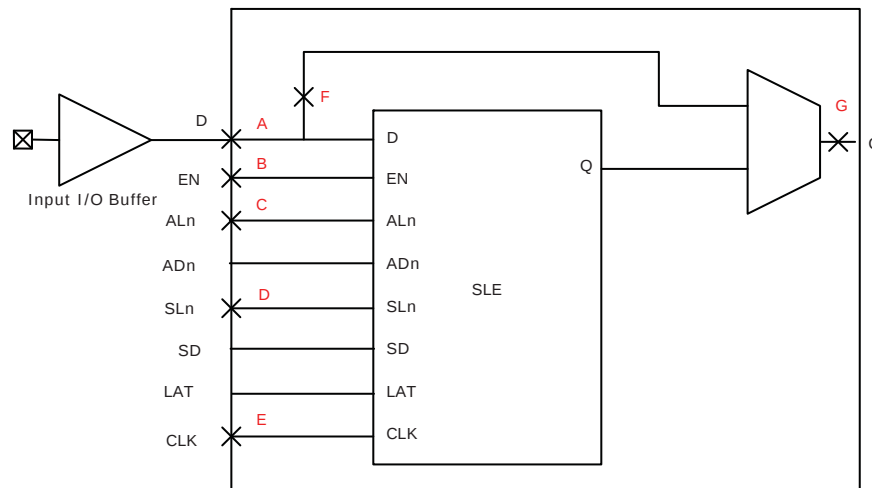
On-Die Termination (ODT)	T _{Py}		Unit
	-1	-Std	
None	2.572	3.025	ns
100	2.569	3.023	ns

2.3.8 I/O Register Specifications

This section describes input and output register specifications.

2.3.8.1 Input Register

Figure 6 • Timing Model for Input Register



2.3.9.4 Output DDR Module

Figure 12 • Output DDR Module

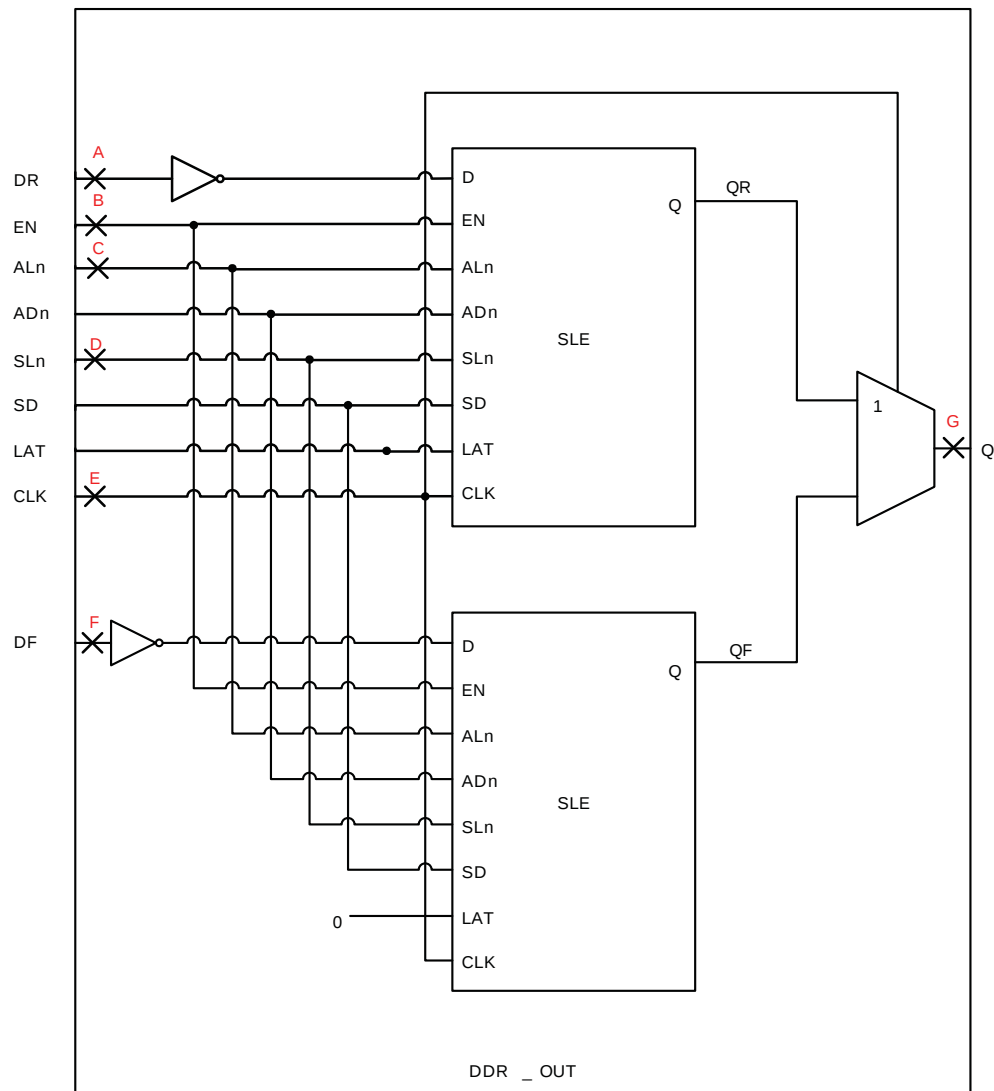


Table 232 • RAM1K18 – Dual-Port Mode for Depth × Width Configuration 2K × 9 (continued)

Parameter	Symbol	–1		–Std		Unit
		Min	Max	Min	Max	
Address setup time	T_{ADDRSU}	0.475		0.559		ns
Address hold time	T_{ADDRHD}	0.274		0.322		ns
Data setup time	T_{DSU}	0.336		0.395		ns
Data hold time	T_{DHD}	0.082		0.096		ns
Block select setup time	T_{BLKSU}	0.207		0.244		ns
Block select hold time	T_{BLKHD}	0.216		0.254		ns
Block select to out disable time (when pipelined register is disabled)	T_{BLK2Q}		1.529		1.799	ns
Block select minimum pulse width	T_{BLKMPW}	0.186		0.219		ns
Read enable setup time	T_{RDESU}	0.485		0.57		ns
Read enable hold time	T_{RDEHD}	0.071		0.083		ns
Pipelined read enable setup time (A_DOUT_EN, B_DOUT_EN)	T_{RDPLESU}	0.248		0.291		ns
Pipelined read enable hold time (A_DOUT_EN, B_DOUT_EN)	T_{RDPLEHD}	0.102		0.12		ns
Asynchronous reset to output propagation delay	T_{R2Q}		1.514		1.781	ns
Asynchronous reset removal time	T_{RSTREM}	0.506		0.595		ns
Asynchronous reset recovery time	T_{RSTREC}	0.004		0.005		ns
Asynchronous reset minimum pulse width	T_{RSTMPW}	0.301		0.354		ns
Pipelined register asynchronous reset removal time	T_{PLRSTREM}	–0.279		–0.328		ns
Pipelined register asynchronous reset recovery time	T_{PLRSTREC}	0.327		0.385		ns
Pipelined register asynchronous reset minimum pulse width	T_{PLRSTMPW}	0.282		0.332		ns
Synchronous reset setup time	T_{SRSTSU}	0.226		0.265		ns
Synchronous reset hold time	T_{SRSTHD}	0.036		0.043		ns
Write enable setup time	T_{WESU}	0.415		0.488		ns
Write enable hold time	T_{WEHD}	0.048		0.057		ns
Maximum frequency	F_{MAX}		400		340	MHz

The following table lists the RAM1K18 – dual-port mode for depth × width configuration 4K × 4 in worst commercial-case conditions when $T_J = 85^\circ\text{C}$, $V_{DD} = 1.14\text{ V}$.

Table 233 • RAM1K18 – Dual-Port Mode for Depth × Width Configuration 4K × 4

Parameter	Symbol	–1		–Std		Unit
		Min	Max	Min	Max	
Clock period	T_{CY}	2.5		2.941		ns
Clock minimum pulse width high	T_{CLKMPWH}	1.125		1.323		ns
Clock minimum pulse width low	T_{CLKMPWL}	1.125		1.323		ns
Pipelined clock period	T_{PLCY}	2.5		2.941		ns
Pipelined clock minimum pulse width high	$T_{\text{PLCLKMPWH}}$	1.125		1.323		ns

Table 237 • μ SRAM (RAM64x18) in 64×18 Mode (continued)

Parameter	Symbol	-1		-Std		Unit
		Min	Max	Min	Max	
Write address setup time	$T_{ADDRCSU}$	0.088		0.104		ns
Write address hold time	$T_{ADDRCHD}$	0.128		0.15		ns
Write enable setup time	T_{WECSU}	0.397		0.467		ns
Write enable hold time	T_{WECHD}	-0.026		-0.03		ns
Maximum frequency	F_{MAX}		250		250	MHz

The following table lists the μ SRAM in 64×16 mode in worst commercial-case conditions when $T_J = 85^\circ\text{C}$, $V_{DD} = 1.14\text{ V}$.

Table 238 • μ SRAM (RAM64x16) in 64×16 Mode

Parameter	Symbol	-1		-Std		Unit
		Min	Max	Min	Max	
Read clock period	T_{CY}	4		4		ns
Read clock minimum pulse width high	$T_{CLKMPWH}$	1.8		1.8		ns
Read clock minimum pulse width low	$T_{CLKMPWL}$	1.8		1.8		ns
Read pipeline clock period	T_{PLCY}	4		4		ns
Read pipeline clock minimum pulse width high	$T_{PLCLKMPWH}$	1.8		1.8		ns
Read pipeline clock minimum pulse width low	$T_{PLCLKMPWL}$	1.8		1.8		ns
Read access time with pipeline register	T_{CLK2Q}		0.266		0.313	ns
Read access time without pipeline register			1.677		1.973	ns
Read address setup time in synchronous mode	T_{ADDRSU}	0.301		0.354		ns
Read address setup time in asynchronous mode		1.856		2.184		ns
Read address hold time in synchronous mode	T_{ADDRHD}	0.091		0.107		ns
Read address hold time in asynchronous mode		-0.778		-0.915		ns
Read enable setup time	T_{RDENSU}	0.278		0.327		ns
Read enable hold time	T_{RDENHD}	0.057		0.067		ns
Read block select setup time	T_{BLKSU}	1.839		2.163		ns
Read block select hold time	T_{BLKHD}	-0.65		-0.765		ns
Read block select to out disable time (when pipelined register is disabled)	T_{BLK2Q}		2.036		2.396	ns
Read asynchronous reset removal time (pipelined clock)	T_{RSTREM}	-0.023		-0.027		ns
Read asynchronous reset removal time (non-pipelined clock)		0.046		0.054		ns
Read asynchronous reset recovery time (pipelined clock)	T_{RSTREC}	0.507		0.597		ns
Read asynchronous reset recovery time (non-pipelined clock)		0.236		0.278		ns
Read asynchronous reset to output propagation delay (with pipelined register enabled)	T_{R2Q}		0.835		0.983	ns
Read synchronous reset setup time	T_{SRSTSU}	0.271		0.319		ns

Table 248 • 2 Step IAP Programming (eNVM Only)

M2S/M2GL Device	Image size Bytes	Authenticate	Program	Verify	Unit
005	137536	2	37	5	Sec
010	274816	4	76	11	Sec
025	274816	4	78	10	Sec
050	278528	3	85	9	Sec
060	268480	5	76	22	Sec
090	544496	10	152	43	Sec
150	544496	10	153	44	Sec

Table 249 • 2 Step IAP Programming (Fabric and eNVM)

M2S/M2GL Device	Image size Bytes	Authenticate	Program	Verify	Unit
005	439296	6	56	11	Sec
010	842688	11	100	21	Sec
025	1497408	19	113	32	Sec
050	2695168	32	136	48	Sec
060	2686464	43	137	70	Sec
090	4190208	68	236	115	Sec
150	6682768	109	286	162	Sec

Table 250 • SmartFusion2 Cortex-M3 ISP Programming (Fabric Only)

M2S/M2GL Device	Image size Bytes	Authenticate	Program	Verify	Unit
005	302672	6	19	8	Sec
010	568784	10	26	14	Sec
025	1223504	21	39	29	Sec
050	2424832	39	60	50	Sec
060	2418896	44	65	54	Sec
090	3645968	66	90	79	Sec
150	6139184	108	140	128	Sec

Table 251 • SmartFusion2 Cortex-M3 ISP Programming (eNVM Only)

M2S/M2GL Device	Image size Bytes	Authenticate	Program	Verify	Unit
005	137536	3	42	4	Sec
010	274816	4	82	7	Sec
025	274816	4	82	8	Sec
050	278528	4	80	8	Sec
060	268480	6	80	8	Sec
090	544496	10	157	15	Sec

Table 254 • Programming Times with 100 kHz, 25 MHz, and 12.5 MHz SPI Clock Rates (eNVM Only) (continued)

M2S/M2GL Device	Auto Programming	Auto Update	Programming Recovery	Unit
	100 kHz	25 MHz	12.5 MHz	
150	161	161	161	Sec

Table 255 • Programming Times with 100 kHz, 25 MHz, and 12.5 MHz SPI Clock Rates (Fabric and eNVM)

M2S/M2GL Device	Auto Programming	Auto Update	Programming Recovery	Unit
	100 kHz	25 MHz	12.5 MHz	
005	47	27	28	Sec
010	77	35	35	Sec
025	150	42	41	Sec
050	33 ¹	Not Supported	Not Supported	Sec
060	291	83	82	Sec
090	427	109	108	Sec
150	708	157	160	Sec
005	41	48	49	Sec
010	86	87	87	Sec
025	87	85	86	Sec
050	85	Not Supported	Not Supported	Sec
060	78	86	86	Sec
090	154	162	162	Sec
150	161	161	161	Sec
005	87	67	66	Sec
010	161	113	113	Sec
025	229	120	121	Sec
050	112	Not Supported	Not Supported	Sec
060	368	161	158	Sec
090	582	261	260	Sec
150	867	309	310	Sec

1. Auto Programming in 050 device is done through SC_SPI, and SPI CLK is set to 6.25 MHz.

The following table lists the programming times in worst-case conditions when $T_J = 100\text{ }^{\circ}\text{C}$, $V_{DD} = 1.14\text{ V}$. External SPI flash part# AT25DF641-s3H is used during this measurement.

Table 256 • JTAG Programming (Fabric Only)

M2S/M2GL Device	Image size		Program	Verify	Unit
	Bytes				
005	302672	44	10		Sec
010	568784	50	18		Sec
025	1223504	73	26		Sec
050	2424832	88	54		Sec
060	2418896	99	54		Sec
090	3645968	135	126		Sec
150	6139184	177	193		Sec

Table 257 • JTAG Programming (eNVM Only)

M2S/M2GL Device	Image size		Program	Verify	Unit
	Bytes				
005	137536	61	4		Sec
010	274816	100	9		Sec
025	274816	100	9		Sec
050	2,78,528	106	8		Sec
060	268480	98	8		Sec
090	544496	176	15		Sec
150	544496	177	15		Sec

Table 258 • JTAG Programming (Fabric and eNVM)

M2S/M2GL Device	Image size		Program	Verify	Unit
	Bytes				
005	439296	71	11		Sec
010	842688	129	20		Sec
025	1497408	142	35		Sec
050	2695168	184	59		Sec
060	2686464	180	70		Sec
090	4190208	288	147		Sec
150	6682768	338	231		Sec

Table 262 • SmartFusion2 Cortex-M3 ISP Programming (Fabric Only)

M2S/M2GL Device	Image size Bytes	Authenticate	Program	Verify	Unit
005	302672	6	41	8	Sec
010	568784	10	48	14	Sec
025	1223504	21	61	29	Sec
050	2424832	39	82	50	Sec
060	2418896	44	87	54	Sec
090	3645968	66	112	79	Sec
150	6139184	108	162	128	Sec

Table 263 • SmartFusion2 Cortex-M3 ISP Programming (eNVM Only)

M2S/M2GL Device	Image size Bytes	Authenticate	Program	Verify	Unit
005	137536	3	64	4	Sec
010	274816	4	104	7	Sec
025	274816	4	104	8	Sec
050	2,78,528	4	102	8	Sec
060	268480	6	102	8	Sec
090	544496	10	179	15	Sec
150	544496	10	180	15	Sec

Table 264 • SmartFusion2 Cortex-M3 ISP Programming (Fabric and eNVM)

M2S/M2GL Device	Image size Bytes	Authenticate	Program	Verify	Unit
005	439296	9	83	11	Sec
010	842688	15	129	21	Sec
025	1497408	26	143	35	Sec
050	2695168	43	163	55	Sec
060	2686464	48	165	60	Sec
090	4190208	75	266	91	Sec
150	6682768	117	318	141	Sec

2.3.14 Math Block Timing Characteristics

The fundamental building block in any digital signal processing algorithm is the multiply-accumulate function. Each IGLOO2 and SmartFusion2 SoC math block supports 18×18 signed multiplication, dot product, and built-in addition, subtraction, and accumulation units to combine multiplication results efficiently. The following table lists the math blocks with all registers used in worst commercial-case conditions when $T_J = 85^\circ\text{C}$, $V_{DD} = 1.14\text{ V}$.

Table 268 • Math Blocks with all Registers Used

Parameter	Symbol	–1		–Std		Unit
		Min	Max	Min	Max	
Input, control register setup time	T_{MISU}	0.149		0.176		ns
Input, control register hold time	T_{MIHD}	1.68		1.976		ns
CDIN input setup time	$T_{MOCDINSU}$	0.185		0.218		ns
CDIN input hold time	$T_{MOCDINHHD}$	0.08		0.094		ns
Synchronous reset/enable setup time	$T_{MSRSTENSU}$	–0.419		–0.493		ns
Synchronous reset/enable hold time	$T_{MSRSTENHD}$	0.011		0.013		ns
Asynchronous reset removal time	$T_{MARSTREM}$	0		0		ns
Asynchronous reset recovery time	$T_{MARSTREC}$	0.088		0.104		ns
Output register clock to out delay	T_{MOCQ}		0.232		0.273	ns
CLK minimum period	T_{MCLKMP}	2.245		2.641		ns

The following table lists the math blocks with input bypassed and output registers used in worst commercial-case conditions when $T_J = 85^\circ\text{C}$, $V_{DD} = 1.14\text{ V}$.

Table 269 • Math Block with Input Bypassed and Output Registers Used

Parameter	Symbol	–1		–Std		Unit
		Min	Max	Min	Max	
Output register setup time	T_{MOSU}	2.294		2.699		ns
Output register hold time	T_{MOHD}	1.68		1.976		ns
CDIN input setup time	$T_{MOCDINSU}$	0.115		0.136		ns
CDIN input hold time	$T_{MOCDINHHD}$	–0.444		–0.522		ns
Synchronous reset/enable setup time	$T_{MSRSTENSU}$	–0.419		–0.493		ns
Synchronous reset/enable hold time	$T_{MSRSTENHD}$	0.011		0.013		ns
Asynchronous reset removal time	$T_{MARSTREM}$	0		0		ns
Asynchronous reset recovery time	$T_{MARSTREC}$	0.014		0.017		ns
Output register clock to out delay	T_{MOCQ}		0.232		0.273	ns
CLK minimum period	T_{MCLKMP}	2.179		2.563		ns

2.3.20 On-Chip Oscillator

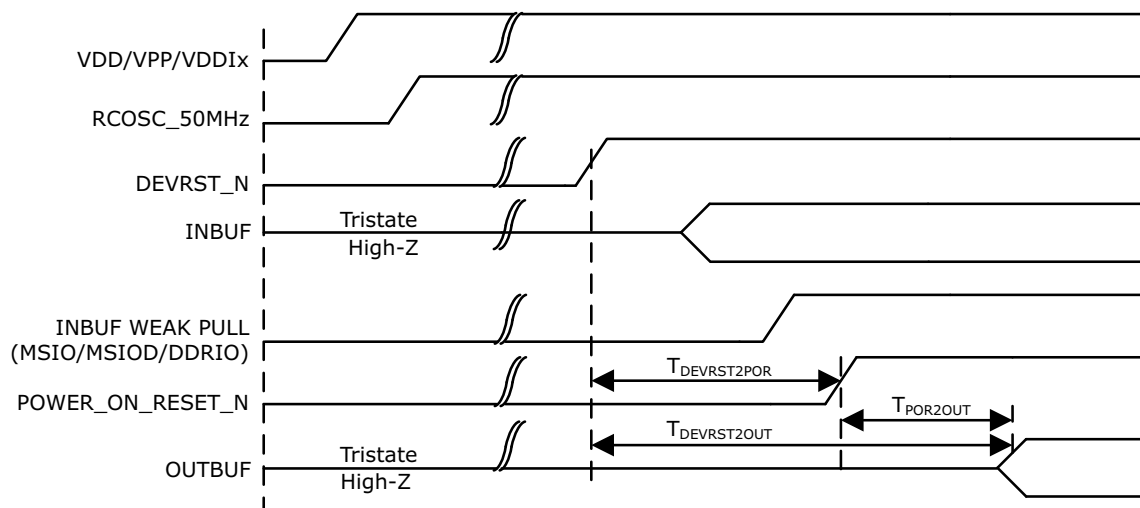
The following tables describe the electrical characteristics of the available on-chip oscillators in the IGLOO2 FPGAs and SmartFusion2 SoC FPGAs.

Table 280 • Electrical Characteristics of the 50 MHz RC Oscillator

Parameter	Symbol	Typ	Max	Unit	Condition
Operating frequency	F50RC	50		MHz	
Accuracy	ACC50RC	1	4	%	050 devices
		1	5	%	005, 025, and 060 devices
		1	6.3	%	090 devices
		1	7.1	%	010 and 150 devices
Output duty cycle	CYC50RC	49–51	46.5–53.5	%	
Output jitter (peak to peak)	JIT50RC				Period Jitter
		200	300	ps	005, 010, 050, and 060 devices
		200	400	ps	150 devices
		300	500	ps	025 and 090 devices
					Cycle-to-Cycle Jitter
		200	300	ps	005 and 050 devices
		320	420	ps	010, 060, and 150 devices
		320	850	ps	025 and 090 devices
Operating current	IDYN50RC	6.5		mA	

Table 281 • Electrical Characteristics of the 1 MHz RC Oscillator

Parameter	Symbol	Typ	Max	Unit	Condition
Operating frequency	F1RC	1		MHz	
Accuracy	ACC1RC	1	3	%	005, 010, 025, and 050 devices
		1	4.5	%	060, and 150 devices
		1	5.6	%	090 devices
Output duty cycle	CYC1RC	49–51	46.5–53.5	%	005, 010, 025, 050, 090 and 150 devices
		49–51	46.0–54.0	%	060 devices
Output jitter (peak to peak)	JIT1RC				Period Jitter
		10	20	ns	005, 010, 025, and 050 devices
		10	28	ns	060, 090 and 150 devices
					Cycle-to-Cycle Jitter
		10	20	ns	005, 010, and 050 devices
		10	35	ns	025, 060, and 150 devices
		10	45	ns	090 devices
Operating current	IDYN1RC	0.1		mA	
Startup time	SU1RC		17	μs	050, 090, and 150 devices
			18	μs	005, 010, and 025 devices

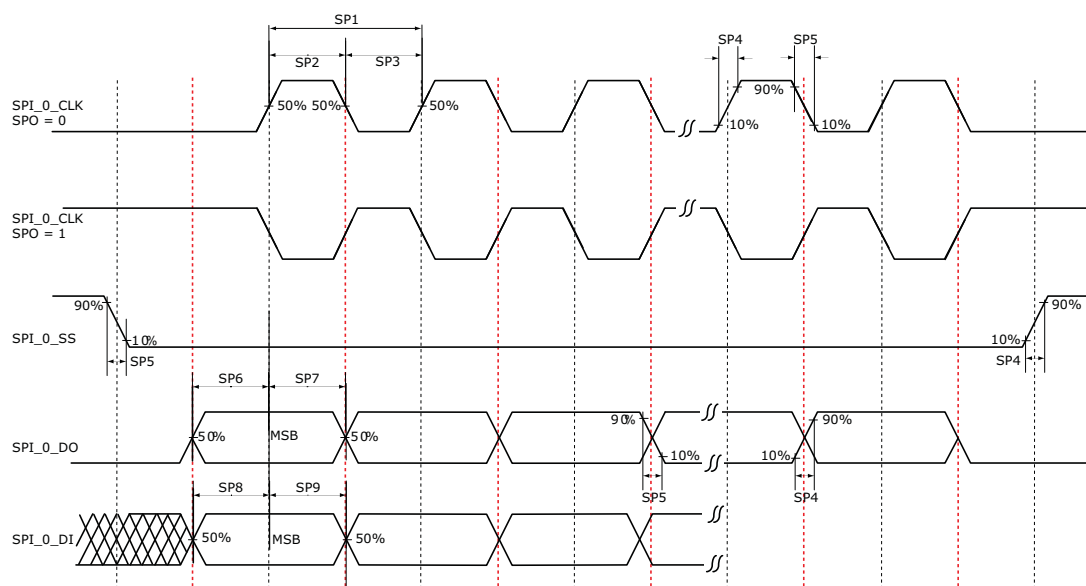
Figure 20 • DEVRST_N to Functional Timing Diagram for IGLOO2

2.3.27 Flash*Freeze Timing Characteristics

The following table lists the Flash*Freeze entry and exit times in worst-case industrial conditions when $T_J = 100^\circ\text{C}$, $V_{DD} = 1.14\text{ V}$.

Table 293 • Flash*Freeze Entry and Exit Times

Parameter	Symbol	Entry/Exit Timing FCLK = 100MHz		Entry/Exit Timing FCLK = 3 MHz		Unit	Conditions
		005, 010, 025, 060, 090, and 150	050	All Devices			
Entry time	TFF_ENTRY	160	150	320		μs	eNVM and MSS/HPMS PLL = ON
		215	200	430		μs	eNVM and MSS/HPMS PLL= OFF
Exit time with respect to the MSS PLL Lock	TFF_EXIT	100	100	140		μs	eNVM and MSS/HPMS PLL = ON during F*F
		136	120	190		μs	eNVM = ON and MSS/HPMS PLL = OFF during F*F and MSS/HPMS PLL turned back on at exit
		200	200	285		μs	eNVM and MSS/HPMS PLL = OFF during F*F and both are turned back on at exit
		200	200	285		μs	eNVM = OFF and MSS/HPMS PLL = ON during F*F and eNVM turned back on at exit

Figure 22 • SPI Timing for a Single Frame Transfer in Motorola Mode (SPH = 1)

2.3.32 CAN Controller Characteristics

The following table lists the CAN controller characteristics in worst-case industrial conditions when $T_J = 100^\circ\text{C}$, $V_{DD} = 1.14\text{ V}$.

Table 306 • CAN Controller Characteristics

Parameter	Description	–1	–Std	Unit
FCANREFCLK ¹	Internally sourced CAN reference clock frequency	160	136	MHz
BAUDCANMAX	Maximum CAN performance baud rate	1	1	Mbps
BAUDCANMIN	Minimum CAN performance baud rate	0.05	0.05	Mbps

1. PCLK to CAN controller must be a multiple of 8 MHz.

2.3.33 USB Characteristics

The following table lists the USB characteristics in worst-case industrial conditions when $T_J = 100^\circ\text{C}$, $V_{DD} = 1.14\text{ V}$.

Table 307 • USB Characteristics

Parameter	Description	–1	–Std	Unit
FUSBREFCLK	Internally sourced USB reference clock frequency	166	142	MHz
TUSBCLK	USB clock period	16.66	16.66	ns
TUSBPD	Clock to USB data propagation delay	9.0	9.0	ns
TUSBSU	Setup time for USB data	6.0	6.0	ns
TUSBHD	Hold time for USB data	0	0	ns

Table 310 • SPI Characteristics for All Devices (continued)

Symbol	Description	Min	Typ	Max	Unit	Conditions
SPI master configuration (applicable for 060, 090, and 150 devices)						
sp6m	SPI_[0 1]_DO setup time ²	$(\text{SPI_x_CLK_period}/2) - 7.0$			ns	
sp7m	SPI_[0 1]_DO hold time ²	$(\text{SPI_x_CLK_period}/2) - 9.5$			ns	
sp8m	SPI_[0 1]_DI setup time ²	15			ns	
sp9m	SPI_[0 1]_DI hold time ²	-2.5			ns	
SPI slave configuration (applicable for 060, 090, and 150 devices)						
sp6s	SPI_[0 1]_DO setup time ²	$(\text{SPI_x_CLK_period}/2) - 16.0$			ns	
sp7s	SPI_[0 1]_DO hold time ²	$(\text{SPI_x_CLK_period}/2) - 3.5$			ns	
sp8s	SPI_[0 1]_DI setup time ²	3			ns	
sp9s	SPI_[0 1]_DI hold time ²	2.5			ns	

- For specific Rise/Fall Times board design considerations and detailed output buffer resistances, use the corresponding IBIS models located on the Microsemi SoC Products Group website: <http://www.microsemi.com/soc/download/ibis/default.aspx>.
- For allowable pclk configurations, see the Serial Peripheral Interface Controller section in the *UG0331: SmartFusion2 Microcontroller Subsystem User Guide*.

Figure 23 • SPI Timing for a Single Frame Transfer in Motorola Mode (SPH = 1)