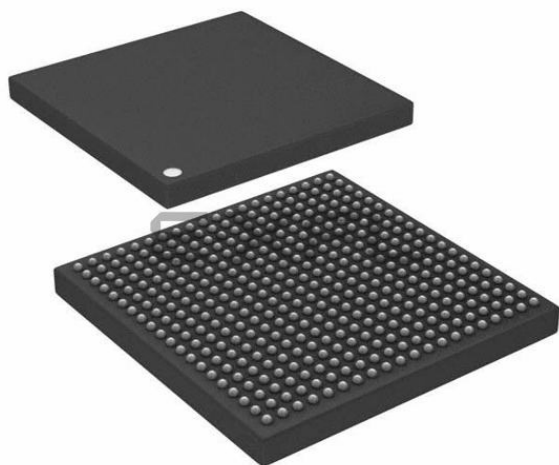




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Understanding [Embedded - FPGAs \(Field Programmable Gate Array\)](#)

Embedded - FPGAs, or Field Programmable Gate Arrays, are advanced integrated circuits that offer unparalleled flexibility and performance for digital systems. Unlike traditional fixed-function logic devices, FPGAs can be programmed and reprogrammed to execute a wide array of logical operations, enabling customized functionality tailored to specific applications. This reprogrammability allows developers to iterate designs quickly and implement complex functions without the need for custom hardware.

Applications of Embedded - FPGAs

The versatility of Embedded - FPGAs makes them indispensable in numerous fields. In telecommunications.

Details

Product Status	Active
Number of LABs/CLBs	-
Number of Logic Elements/Cells	6060
Total RAM Bits	719872
Number of I/O	169
Number of Gates	-
Voltage - Supply	1.14V ~ 2.625V
Mounting Type	Surface Mount
Operating Temperature	-40°C ~ 100°C (TJ)
Package / Case	400-LFBGA
Supplier Device Package	400-VFBGA (17x17)
Purchase URL	https://www.e-xfl.com/product-detail/microchip-technology/m2gl005-vfg400i

Figure 1 • High Temperature Data Retention (HTR)**2.3.1.1 Overshoot/Undershoot Limits**

For AC signals, the input signal may undershoot during transitions to -1.0 V for no longer than 10% of the period. The current during the transition must not exceed 100 mA.

For AC signals, the input signal may overshoot during transitions to $V_{CCI} + 1.0$ V for no longer than 10% of the period. The current during the transition must not exceed 100 mA.

Note: The above specifications do not apply to the PCI standard. The IGLOO2 and SmartFusion2 PCI I/Os are compliant with the PCI standard including the PCI overshoot/undershoot specifications.

2.3.1.2 Thermal Characteristics

The temperature variable in the Microsemi SoC Products Group Designer software refers to the junction temperature, not the ambient, case, or board temperatures. This is an important distinction because dynamic and static power consumption causes the chip's junction temperature to be higher than the ambient, case, or board temperatures.

EQ1 through EQ3 give the relationship between thermal resistance, temperature gradient, and power.

$$\theta_{JA} = \frac{T_J - T_A}{P}$$

EQ 1

$$\theta_{JB} = \frac{T_J - T_B}{P}$$

EQ 2

$$\theta_{JC} = \frac{T_J - T_C}{P}$$

EQ 3

where

- θ_{JA} = Junction-to-air thermal resistance
 θ_{JB} = Junction-to-board thermal resistance
 θ_{JC} = Junction-to-case thermal resistance
 T_J = Junction temperature
 T_A = Ambient temperature
 T_B = Board temperature (measured 1.0 mm away from the package edge)
 T_C = Case temperature
 P = Total power dissipated by the device

Table 9 • Package Thermal Resistance of SmartFusion2 and IGLOO2 Devices

	Still Air	1.0 m/s	2.5 m/s			
Device	θ_{JA}			θ_{JB}	θ_{JC}	Unit
005						
FG484	19.36	15.81	14.63	9.74	5.27	°C/W
VF256	41.30	38.16	35.30	28.41	3.94	°C/W
VF400	20.19	16.94	15.41	8.86	4.95	°C/W
TQ144	42.80	36.80	34.50	37.20	10.80	°C/W
010						
FG484	18.22	14.83	13.62	8.83	4.92	°C/W
VF256	37.36	34.26	31.45	24.84	7.89	°C/W
VF400	19.40	15.75	14.22	8.11	4.22	°C/W
TQ144	38.60	32.60	30.30	31.80	8.60	°C/W
025						
FG484	17.03	13.66	12.45	7.66	4.18	°C/W
VF256	33.85	30.59	27.85	21.63	6.13	°C/W
VF400	18.36	14.89	13.36	7.12	3.41	°C/W
FCS325	29.17	24.87	23.12	14.44	2.31	°C/W
050						
FG484	15.29	12.19	10.99	6.27	3.24	°C/W
FG896	14.70	12.50	10.90	7.20	4.90	°C/W
VF400	17.53	14.17	12.63	6.32	2.81	°C/W
FCS325	27.38	23.18	21.41	12.47	1.59	°C/W
060						
FG484	15.40	12.06	10.85	6.14	3.15	°C/W
FG676	15.49	12.21	11.06	7.07	3.87	°C/W
VF400	17.45	14.01	12.47	6.22	2.69	°C/W
FCS325	27.03	22.91	21.25	12.33	1.54	°C/W
090						
FG484	14.64	11.37	10.16	5.43	2.77	°C/W
FG676	14.52	11.19	10.37	6.17	3.24	°C/W
FCS325	26.63	22.26	20.13	14.24	2.50	°C/W

Table 9 • Package Thermal Resistance of SmartFusion2 and IGLOO2 Devices (continued)

	Still Air	1.0 m/s	2.5 m/s			
Device	θ_{JA}			θ_{JB}	θ_{JC}	Unit
150						
FC1152	9.08	6.81	5.87	2.56	0.38	°C/W
FCS536	15.01	12.06	10.76	3.69	1.55	°C/W
FCV484	16.21	13.11	11.84	6.73	0.10	°C/W

2.3.1.2.1 Theta-JA

Junction-to-ambient thermal resistance (θ_{JA}) is determined under standard conditions specified by JEDEC (JESD-51), but it has little relevance in the actual performance of the product. It must be used with caution, but it is useful for comparing the thermal performance of one package with another.

The maximum power dissipation allowed is calculated using EQ4.

$$\text{Maximum power allowed} = \frac{T_{J(\text{MAX})} - T_{A(\text{MAX})}}{\theta_{JA}}$$

EQ 4

The absolute maximum junction temperature is 100 °C. EQ5 shows a sample calculation of the absolute maximum power dissipation allowed for the M2GL050T-FG896 package at commercial temperature and in still air, where:

$$\theta_{JA} = 14.7 \text{ °C/W (taken from Table 9, page 10).}$$

$$T_A = 85 \text{ °C}$$

$$\text{Maximum power allowed} = \frac{100 \text{ °C} - 85 \text{ °C}}{14.7 \text{ °C/W}} = 1.088 \text{ W}$$

EQ 5

The power consumption of a device can be calculated using the Microsemi SoC Products Group power calculator. The device's power consumption must be lower than the calculated maximum power dissipation by the package.

If the power consumption is higher than the device's maximum allowable power dissipation, a heat sink may be attached to the top of the case, or the airflow inside the system must be increased.

2.3.1.2.2 Theta-JB

Junction-to-board thermal resistance (θ_{JB}) measures the ability of the package to dissipate heat from the surface of the chip to the PCB. As defined by the JEDEC (JESD-51) standard, the thermal resistance from the junction to the board uses an isothermal ring cold plate zone concept. The ring cold plate is simply a means to generate an isothermal boundary condition at the perimeter. The cold plate is mounted on a JEDEC standard board with a minimum distance of 5.0 mm away from the package edge.

2.3.1.2.3 Theta-JC

Junction-to-case thermal resistance (θ_{JC}) measures the ability of a device to dissipate heat from the surface of the chip to the top or bottom surface of the package. It is applicable to packages used with external heat sinks. Constant temperature is applied to the surface, which acts as a boundary condition.

This only applies to situations where all or nearly all of the heat is dissipated through the surface in consideration.

2.3.1.3 ESD Performance

See RT0001: Microsemi Corporation - SoC Products Reliability Report for information about ESD.

Table 58 • LVCMOS 1.8 V Transmitter Characteristics for MSIO I/O Bank

Output Drive Selection	Slew Control	T _{DP}		T _{ZL}		T _{ZH}		T _{HZ} ¹		T _{LZ} ¹		Unit
		-1	-Std	-1	-Std	-1	-Std	-1	-Std	-1	-Std	
2 mA	Slow	3.441	4.047	4.165	4.9	4.413	5.192	4.891	5.755	5.138	6.044	ns
4 mA	Slow	3.218	3.786	3.642	4.284	3.941	4.636	5.665	6.665	5.568	6.551	ns
6 mA	Slow	3.141	3.694	3.501	4.118	3.823	4.498	6.587	7.75	6.032	7.096	ns
8 mA	Slow	3.165	3.723	3.319	3.904	3.654	4.298	6.898	8.115	6.216	7.313	ns
10 mA	Slow	3.202	3.767	3.278	3.857	3.616	4.254	7.25	8.529	6.435	7.571	ns
12 mA	Slow	3.277	3.855	3.175	3.736	3.519	4.139	7.392	8.697	6.538	7.692	ns

1. Delay increases with drive strength are inherent to built-in slew control circuitry for simultaneous switching output (SSO) management.

Table 59 • LVCMOS 1.8 V Transmitter Characteristics for MSIOD I/O Bank

Output Drive Selection	Slew Control	T _{DP}		T _{ZL}		T _{ZH}		T _{HZ} ¹		T _{LZ} ¹		Unit
		-1	-Std	-1	-Std	-1	-Std	-1	-Std	-1	-Std	
2 mA	Slow	2.725	3.206	3.316	3.901	3.484	4.099	5.204	6.123	4.997	5.88	ns
4 mA	Slow	2.242	2.638	2.777	3.267	2.947	3.466	5.729	6.74	5.448	6.41	ns
6 mA	Slow	1.995	2.347	2.466	2.901	2.63	3.094	6.372	7.496	5.987	7.043	ns
8 mA	Slow	2.001	2.354	2.44	2.87	2.6	3.058	6.633	7.804	6.193	7.286	ns
10 mA	Slow	2.025	2.382	2.312	2.719	2.47	2.906	6.94	8.165	6.412	7.544	ns

1. Delay increases with drive strength are inherent to built-in slew control circuitry for simultaneous switching output (SSO) management.

2.3.5.9 1.5 V LVCMOS

LVCMOS 1.5 is a general standard for 1.5 V applications and is supported in IGLOO2 FPGAs and SmartFusion2 SoC FPGAs in compliance to the JEDEC specification JESD8-11A.

Minimum and Maximum DC/AC Input and Output Levels Specification

Table 60 • LVCMOS 1.5 V DC Recommended Operating Conditions

Parameter	Symbol	Min	Typ	Max	Unit
Supply voltage	V _{DDI}	1.425	1.5	1.575	V

Table 61 • LVCMOS 1.5 V DC Input Voltage Specification

Parameter	Symbol	Min	Max	Unit
DC input logic high for (MSIOD and DDRIO I/O banks)	V _{IH} (DC)	0.65 × V _{DDI}	1.575	V
DC input logic high (for MSIO I/O bank)	V _{IH} (DC)	0.65 × V _{DDI}	3.45	V
DC input logic low	V _{IL} (DC)	-0.3	0.35 × V _{DDI}	V
Input current high ¹	I _{IH} (DC)			–
Input current low ¹	I _{IL} (DC)			–

1. See Table 24, page 22.

Table 95 • HSTL DC Output Voltage Specification Applicable to DDRIO I/O Bank Only

Parameter	Symbol	Min	Max	Unit
HSTL Class I				
DC output logic high	V_{OH}	$V_{DDI} - 0.4$		V
DC output logic low	V_{OL}		0.4	V
Output minimum source DC current (MSIO and DDRIO I/O banks)	I_{OH} at V_{OH}	-8.0		mA
Output minimum sink current (MSIO and DDRIO I/O banks)	I_{OL} at V_{OL}	8.0		mA
HSTL Class II				
DC output logic high	V_{OH}	$V_{DDI} - 0.4$		V
DC output logic low	V_{OL}		0.4	V
Output minimum source DC current	I_{OH} at V_{OH}	-16.0		mA
Output minimum sink current	I_{OL} at V_{OL}	16.0		mA

Table 96 • HSTL DC Differential Voltage Specification

Parameter	Symbol	Min	Unit
DC input differential voltage	V_{ID} (DC)	0.2	V

Table 97 • HSTL AC Differential Voltage Specifications

Parameter	Symbol	Min	Max	Unit
AC input differential voltage	V_{DIFF}	0.4		V
AC differential cross point voltage	V_x	0.68	0.9	V

Table 98 • HSTL Minimum and Maximum AC Switching Speed

Parameter	Symbol	Max	Unit	Conditions
Maximum data rate	D_{MAX}	400	Mbps	AC loading: per JEDEC specifications

Table 99 • HSTL Impedance Specification

Parameter	Symbol	Typ	Unit	Conditions
Supported output driver calibrated impedance (for DDRIO I/O bank)	R_{REF}	25.5, 47.8	Ω	Reference resistance = 191 Ω
Effective impedance value (ODT for DDRIO I/O bank only)	R_{TT}	47.8	Ω	Reference resistance = 191 Ω

Table 112 • SSTL2 Receiver Characteristics for MSIO I/O Bank (Input Buffers)

		T_{PY}		Unit
	On-Die Termination (ODT)	-1	-Std	
Pseudo differential	None	2.798	3.293	ns
True differential	None	2.733	3.215	ns

Table 113 • DDR1/SSTL2 Receiver Characteristics for MSIOD I/O Bank (Input Buffers)

		T_{PY}		Unit
	On-Die Termination (ODT)	-1	-Std	
Pseudo differential	None	2.476	2.913	ns
True differential	None	2.475	2.911	ns

Table 114 • SSTL2 Class I Transmitter Characteristics for DDRIO I/O Bank (Output and Tristate Buffers)

	T_{DP}		T_{ZL}		T_{ZH}		T_{HZ}		T_{LZ}		Unit
	-1	-Std	-1	-Std	-1	-Std	-1	-Std	-1	-Std	
Single-ended	2.26	2.66	1.99	2.341	1.985	2.335	2.135	2.512	2.13	2.505	ns
Differential	2.26	2.658	2.202	2.591	2.201	2.589	2.393	2.815	2.392	2.814	ns

Table 115 • DDR1/SSTL2 Class I Transmitter Characteristics for MSIO I/O Bank (Output and Tristate Buffers)

	T_{DP}		T_{ZL}		T_{ZH}		T_{HZ}		T_{LZ}		Unit
	-1	-Std	-1	-Std	-1	-Std	-1	-Std	-1	-Std	
Single-ended	2.055	2.417	2.037	2.396	2.03	2.388	2.068	2.433	2.061	2.425	ns
Differential	2.192	2.58	2.434	2.864	2.425	2.852	2.164	2.545	2.156	2.536	ns

Table 116 • DDR1/SSTL2 Class I Transmitter Characteristics for MSIOD I/O Bank (Output and Tristate Buffers)

	T_{DP}		T_{ZL}		T_{ZH}		T_{HZ}		T_{LZ}		Unit
	-1	-Std	-1	-Std	-1	-Std	-1	-Std	-1	-Std	
Single-ended	1.512	1.779	1.462	1.72	1.462	1.72	1.676	1.972	1.676	1.971	ns
Differential	1.676	1.971	1.774	2.087	1.766	2.077	1.854	2.181	1.845	2.171	ns

Table 117 • DDR1/SSTL2 Class II Transmitter Characteristics for DDRIO I/O Bank (Output and Tristate Buffers)

	T_{DP}		T_{ZL}		T_{ZH}		T_{HZ}		T_{LZ}		Unit
	-1	-Std	-1	-Std	-1	-Std	-1	-Std	-1	-Std	
Single-ended	2.122	2.497	1.906	2.243	1.902	2.237	2.061	2.424	2.056	2.418	ns
Differential	2.127	2.501	2.042	2.402	2.043	2.403	2.363	2.78	2.365	2.781	ns

Table 131 • SSTL15 DC Output Voltage Specification (for DDRIO I/O Bank Only)

Parameter	Symbol	Min	Max	Unit
DDR3/SSTL15 Class I (DDR3 Reduced Drive)				
DC output logic high	V_{OH}	$0.8 \times V_{DDI}$		V
DC output logic low	V_{OL}		$0.2 \times V_{DDI}$	V
Output minimum source DC current	I_{OH} at V_{OH}	6.5		mA
Output minimum sink current	I_{OL} at V_{OL}	-6.5		mA
DDR3/SSTL15 Class II (DDR3 Full Drive)				
DC output logic high	V_{OH}	$0.8 \times V_{DDI}$		V
DC output logic low	V_{OL}		$0.2 \times V_{DDI}$	V
Output minimum source DC current	I_{OH} at V_{OH}	7.6		mA
Output minimum sink current	I_{OL} at V_{OL}	-7.6		mA

Table 132 • SSTL15 DC Differential Voltage Specification (for DDRIO I/O Bank Only)

Parameter	Symbol	Min	Unit
DC input differential voltage	V_{ID}	0.2	V

Note: To meet JEDEC electrical compliance, use DDR3 full drive transmitter.

Table 133 • SSTL15 AC SSTL15 Minimum and Maximum AC Switching Speed (for DDRIO I/O Bank Only)

Parameter	Symbol	Min	Max	Unit
AC input differential voltage	V_{DIFF} (AC)	0.3		V
AC differential cross point voltage	V_x (AC)	$0.5 \times V_{DDI} - 0.150$	$0.5 \times V_{DDI} + 0.150$	V

Table 134 • SSTL15 Minimum and Maximum AC Switching Speed (for DDRIO I/O Bank Only)

Parameter	Symbol	Max	Unit	Conditions
Maximum data rate	D_{MAX}	667	Mbps	AC loading: per JEDEC specifications

Table 135 • SSTL15 AC Calibrated Impedance Option (for DDRIO I/O Bank Only)

Parameter	Symbol	Typ	Unit	Conditions
Supported output driver calibrated impedance	R_{REF}	34, 40	Ω	Reference resistor = 240 Ω
Effective impedance value (ODT)	R_{TT}	20, 30, 40, 60, 120	Ω	Reference resistor = 240 Ω

2.3.6.6 Low Power Double Data Rate (LPDDR)

LPDDR reduced and full drive low power double data rate standards are supported in IGLOO2 FPGA and SmartFusion2 SoC FPGA I/Os. This standard requires a differential amplifier input buffer and a push-pull output buffer.

Minimum and Maximum DC/AC Input and Output Levels Specification

Table 139 • LPDDR DC Recommended DC Operating Conditions

Parameter	Symbol	Min	Typ	Max
Supply voltage	V_{DDI}	1.71	1.8	1.89
Termination voltage	V_{TT}	0.838	0.900	0.964
Input reference voltage	V_{REF}	0.838	0.900	0.964

Table 140 • LPDDR DC Input Voltage Specification

Parameter	Symbol	Min	Max
DC input logic high	V_{IH} (DC)	$0.7 \times V_{DDI}$	1.89
DC input logic low	V_{IL} (DC)	-0.3	$0.3 \times V_{DDI}$
Input current high ¹	I_{IH} (DC)		
Input current low ¹	I_{IL} (DC)		

1. See Table 24, page 22.

Table 141 • LPDDR DC Output Voltage Specification Reduced Drive

Parameter	Symbol	Min	Max
DC output logic high	V_{OH}	$0.9 \times V_{DDI}$	
DC output logic low	V_{OL}		$0.1 \times V_{DDI}$
Output minimum source DC current	I_{OH} at V_{OH}	0.1	
Output minimum sink current	I_{OL} at V_{OL}	-0.1	

Table 142 • LPDDR DC Output Voltage Specification Full Drive¹

Parameter	Symbol	Min	Max
DC output logic high	V_{OH}	$0.9 \times V_{DDI}$	
DC output logic low	V_{OL}		$0.1 \times V_{DDI}$
Output minimum source DC current	I_{OH} at V_{OH}	0.1	
Output minimum sink current	I_{OL} at V_{OL}	-0.1	

1. To meet JEDEC Electrical Compliance, use LPDDR Full Drive Transmitter.

Table 143 • LPDDR DC Differential Voltage Specification

Parameter	Symbol	Min
DC input differential voltage	V_{ID} (DC)	$0.4 \times V_{DDI}$

Table 150 • LPDDR Full Drive for DDRIO I/O Bank (Output and Tristate Buffers)

	T_{DP}		T_{ENZL}		T_{ENZH}		T_{ENHZ}		T_{ENLZ}		Unit
	-1	-Std	-1	-Std	-1	-Std	-1	-Std	-1	-Std	
Single-ended	2.281	2.683	2.196	2.584	2.195	2.583	2.171	2.555	2.17	2.554	ns
Differential	2.298	2.703	2.288	2.692	2.288	2.692	2.593	3.051	2.593	3.051	ns

Minimum and Maximum DC/AC Input and Output Levels Specification using LPDDR-LVCMOS 1.8 V Mode

Table 151 • LPDDR-LVCMOS 1.8 V Mode Recommended DC Operating Conditions

Parameter	Symbol	Min	Typ	Max	Unit
Supply voltage	V_{DDI}	1.710	1.8	1.89	V

Table 152 • LPDDR-LVCMOS 1.8 V Mode DC Input Voltage Specification

Parameter	Symbol	Min	Max	Unit
DC input logic high (for MSIOD and DDRIO I/O banks)	V_{IH} (DC)	$0.65 \times V_{DDI}$	1.89	V
DC input logic high (for MSIO I/O bank)	V_{IH} (DC)	$0.65 \times V_{DDI}$	3.45	V
DC input logic low	V_{IL} (DC)	-0.3	$0.35 \times V_{DDI}$	V
Input current high ¹	I_{IH} (DC)			
Input current low ¹	I_{IL} (DC)			

1. See Table 24, page 22.

Table 153 • LPDDR-LVCMOS 1.8 V Mode DC Output Voltage Specification

Parameter	Symbol	Min	Max	Unit
DC output logic high	V_{OH}	$V_{DDI} - 0.45$		V
DC output logic low	V_{OL}		0.45	V

Table 154 • LPDDR-LVCMOS 1.8 V Minimum and Maximum AC Switching Speeds

Parameter	Symbol	Max	Unit	Conditions
Maximum data rate (for DDRIO I/O bank)	D_{MAX}	400	Mbps	AC loading: 17pf load, 8 ma drive and above/all slew

Table 155 • LPDDR-LVCMOS 1.8 V Calibrated Impedance Option

Parameter	Symbol	Typ	Unit
Supported output driver calibrated impedance (for DDRIO I/O bank)	RODT_CAL	75, 60, 50, 33, 25, 20	Ω

Table 162 • LVDS DC Output Voltage Specification

Parameter	Symbol	Min	Typ	Max	Unit
DC output logic high	V _{OH}	1.25	1.425	1.6	V
DC output logic low	V _{OL}	0.9	1.075	1.25	V

Table 163 • LVDS DC Differential Voltage Specification

Parameter	Symbol	Min	Typ	Max	Unit
Differential output voltage swing	V _{OD}	250	350	450	mV
Output common mode voltage	V _{OCM}	1.125	1.25	1.375	V
Input common mode voltage	V _{ICM}	0.05	1.25	2.35	V
Input differential voltage	V _{ID}	100	350	600	mV

Table 164 • LVDS Minimum and Maximum AC Switching Speed

Parameter	Symbol	Max	Unit	Conditions
Maximum data rate (for MSIO I/O bank)	D _{MAX}	535	Mbps	AC loading: 12 pF / 100 Ω differential load
Maximum data rate (for MSIOD I/O bank) no pre-emphasis	D _{MAX}	620	Mbps	AC loading: 10 pF / 100 Ω differential load
		700	Mbps	AC loading: 2 pF / 100 Ω differential load

Table 165 • LVDS AC Impedance Specifications

Parameter	Symbol	Typ	Max	Unit
Termination resistance	RT	100		Ω

Table 166 • LVDS AC Test Parameter Specifications

Parameter	Symbol	Typ	Unit
Measuring/trip point for data path	V _{TRIP}	Cross point	V
Resistance for enable path (T _{ZH} , T _{ZL} , T _{HZ} , T _{LZ})	R _{ENT}	2K	Ω
Capacitive loading for enable path (T _{ZH} , T _{ZL} , T _{HZ} , T _{LZ})	C _{ENT}	5	pF

LVDS25 AC Switching Characteristics

Worst commercial-case conditions: T_J = 85 °C, V_{DD} = 1.14 V, V_{DDI} = 2.375 V

Table 167 • LVDS25 Receiver Characteristics for MSIO I/O Bank (Input Buffers)

On-Die Termination (ODT)	T _{py}		Unit
	-1	-Std	
None	2.774	3.263	ns
100	2.775	3.264	ns

2.3.7.5 RSDS

Reduced Swing Differential Signaling (RSDS) is similar to an LVDS high-speed interface using differential signaling. RSDS has a similar implementation to LVDS devices and is only intended for point-to-point applications.

Minimum and Maximum Input and Output Levels

Table 203 • RSDS Recommended DC Operating Conditions

Parameter	Symbol	Min	Typ	Max	Unit
Supply voltage	V_{DDI}	2.375	2.5	2.625	V

Table 204 • RSDS DC Input Voltage Specification

Parameter	Symbol	Min	Max	Unit
DC input voltage	V_I	0	2.925	V

Table 205 • RSDS DC Output Voltage Specification

Parameter	Symbol	Min	Typ	Max	Unit
DC output logic high	V_{OH}	1.25	1.425	1.6	V
DC output logic low	V_{OL}	0.9	1.075	1.25	V

Table 206 • RSDS Differential Voltage Specification

Parameter	Symbol	Min	Max	Unit
Differential output voltage swing	V_{OD}	100	600	mV
Output common mode voltage	V_{OCM}	0.5	1.5	V
Input common mode voltage	V_{ICM}	0.3	1.5	V
Input differential voltage	V_{ID}	100	600	mV

Table 207 • RSDS Minimum and Maximum AC Switching Speed

Parameter	Symbol	Max	Unit	Conditions
Maximum data rate (for MSIO I/O bank)	D_{MAX}	520	Mbps	AC loading: 2 pF / 100 Ω differential load
Maximum data rate (for MSIOD I/O bank)	D_{MAX}	700	Mbps	AC loading: 2 pF / 100 Ω differential load

Table 208 • RSDS AC Impedance Specifications

Parameter	Symbol	Typ	Unit
Termination resistance	R_T	100	Ω

Table 209 • RSDS AC Test Parameter Specifications

Parameter	Symbol	Typ	Unit
Measuring/trip point for data path	V_{TRIP}	Cross point	V
Resistance for enable path (T_{ZH} , T_{ZL} , T_{HZ} , T_{LZ})	R_{ENT}	2K	Ω
Capacitive loading for enable path (T_{ZH} , T_{ZL} , T_{HZ} , T_{LZ})	C_{ENT}	5	pF

Table 221 • Input DDR Propagation Delays (continued)

Symbol	Description	Measuring Nodes (from, to)	-1	-Std	Unit
T _{DDRIWAL}	Asynchronous load minimum pulse width for input DDR	F, F	0.304	0.357	ns
T _{DDRICKMPWH}	Clock minimum pulse width high for input DDR	B, B	0.075	0.088	ns
T _{DDRICKMPWL}	Clock minimum pulse width low for input DDR	B, B	0.159	0.187	ns

Table 222 • Output DDR Propagation Delays (continued)

Symbol	Description	Measuring Nodes (from, to)	-1	-Std	Unit
$T_{DDROWAL}$	Asynchronous load minimum pulse width for output DDR	C, C	0.304	0.357	ns
$T_{DDROCKMPWH}$	Clock minimum pulse width high for the output DDR	E, E	0.075	0.088	ns
$T_{DDROCKMPWL}$	Clock minimum pulse width low for the output DDR	E, E	0.159	0.187	ns

2.3.10 Logic Element Specifications

2.3.10.1 4-input LUT (LUT-4)

The IGLOO2 and SmartFusion2 SoC FPGAs offer a fully permutable 4-input LUT. In this section, timing characteristics are presented for a sample of the library. For more details, see *SmartFusion2 and IGLOO2 Macro Library Guide*.

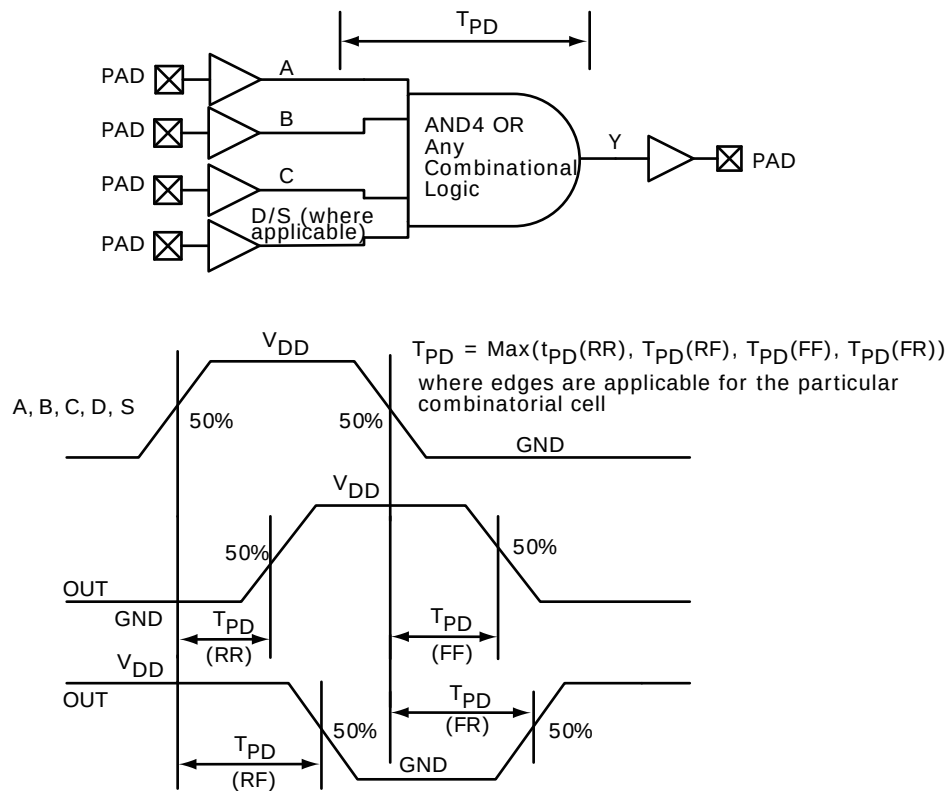
Figure 14 • LUT-4

Table 239 • μ SRAM (RAM128x9) in 128 × 9 Mode (continued)

Parameter	Symbol	–1		–Std		Unit
		Min	Max	Min	Max	
Read asynchronous reset removal time (pipelined clock)	T_{RSTREM}	–0.023		–0.027		ns
Read asynchronous reset removal time (non-pipelined clock)		0.046		0.054		ns
Read asynchronous reset recovery time (pipelined clock)	T_{RSTREC}	0.507		0.597		ns
Read asynchronous reset recovery time (non-pipelined clock)		0.236		0.278		ns
Read asynchronous reset to output propagation delay (with pipelined register enabled)	T_{R2Q}		0.835		0.982	ns
Read synchronous reset setup time	T_{SRSTSU}	0.271		0.319		ns
Read synchronous reset hold time	T_{SRSTHD}	0.061		0.071		ns
Write clock period	T_{CCY}	4		4		ns
Write clock minimum pulse width high	$T_{CCLKMPWH}$	1.8		1.8		ns
Write clock minimum pulse width low	$T_{CCLKMPWL}$	1.8		1.8		ns
Write block setup time	T_{BLKCSU}	0.404		0.476		ns
Write block hold time	T_{BLKCHD}	0.007		0.008		ns
Write input data setup time	T_{DINCSU}	0.115		0.135		ns
Write input data hold time	T_{DINCHD}	0.15		0.177		ns
Write address setup time	$T_{ADDRCSU}$	0.088		0.104		ns
Write address hold time	$T_{ADDRCHD}$	0.128		0.15		ns
Write enable setup time	T_{WECSU}	0.397		0.467		ns
Write enable hold time	T_{WECHD}	–0.026		–0.03		ns
Maximum frequency	F_{MAX}		250		250	MHz

The following table lists the μ SRAM in 128 × 8 mode in worst commercial-case conditions when $T_J = 85^\circ\text{C}$, $V_{DD} = 1.14\text{ V}$.

Table 240 • μ SRAM (RAM128x8) in 128 × 8 Mode

Parameter	Symbol	–1		–Std		Unit
		Min	Max	Min	Max	
Read clock period	T_{CY}	4		4		ns
Read clock minimum pulse width high	$T_{CLKMPWH}$	1.8		1.8		ns
Read clock minimum pulse width low	$T_{CLKMPWL}$	1.8		1.8		ns
Read pipeline clock period	T_{PLCY}	4		4		ns
Read pipeline clock minimum pulse width high	$T_{PLCLKMPWH}$	1.8		1.8		ns
Read pipeline clock minimum pulse width low	$T_{PLCLKMPWL}$	1.8		1.8		ns
Read access time with pipeline register	T_{CLK2Q}		0.266		0.313	ns
Read access time without pipeline register			1.677		1.973	ns
Read address setup time in synchronous mode	T_{ADDRSU}	0.301		0.354		ns
Read address setup time in asynchronous mode		1.856		2.184		ns

2.3.16 SRAM PUF

For more details on static random-access memory (SRAM) physical unclonable functions (PUF) services, see *AC434: Using SRAM PUF System Service in SmartFusion2 Application Note*.

The following table lists the SRAM PUF in worst-case industrial conditions when $T_J = 100\text{ }^{\circ}\text{C}$, $V_{DD} = 1.14\text{ V}$.

Table 274 • SRAM PUF

Service	PUF Off		PUF On		Unit
	Typ	Max	Typ	Max	
Create activation code	709.1	746.4	754.4	762.5	ms
Delete activation code	1329.3	1399.3	1414.1	1429.3	ms
Create intrinsic keycode	656.6	691.1	698.5	706.0	ms
Create extrinsic keycode	656.6	691.1	698.5	706.0	ms
Get number of keys	1.3	1.4	1.4	1.4	ms
Export (Kc0, Kc1)	998.0	1050.5	1061.7	1073.1	ms
Export 2 keycodes	2020.2	2126.5	2149.2	2172.3	ms
Export 4 keycodes	3065.7	3227.0	3261.3	3296.4	ms
Export 8 keycodes	5101.0	5369.5	5426.6	5485.0	ms
Export 16 keycodes	9212.1	9697.0	9800.1	9905.5	ms
Import (Kc0, Kc1)	39.7	41.8	42.2	42.7	ms
Import 2 keycodes	50.1	52.7	53.3	53.9	ms
Import 4 keycodes	60.6	63.8	64.5	65.2	ms
Import 8 keycodes	80.9	85.1	86.1	87.0	ms
Import 16 keycodes	123.8	130.4	131.7	133.2	ms
Delete keycode	552.5	581.6	587.8	594.1	ms
Fetch key	31.4	33.0	33.4	33.7	ms
Fetch ecc key	20.0	21.1	21.3	21.5	ms
Get seed	2.0	2.1	2.2	2.2	ms

Table 277 • Electrical Characteristics of the Crystal Oscillator – High Gain Mode (20 MHz) (continued)

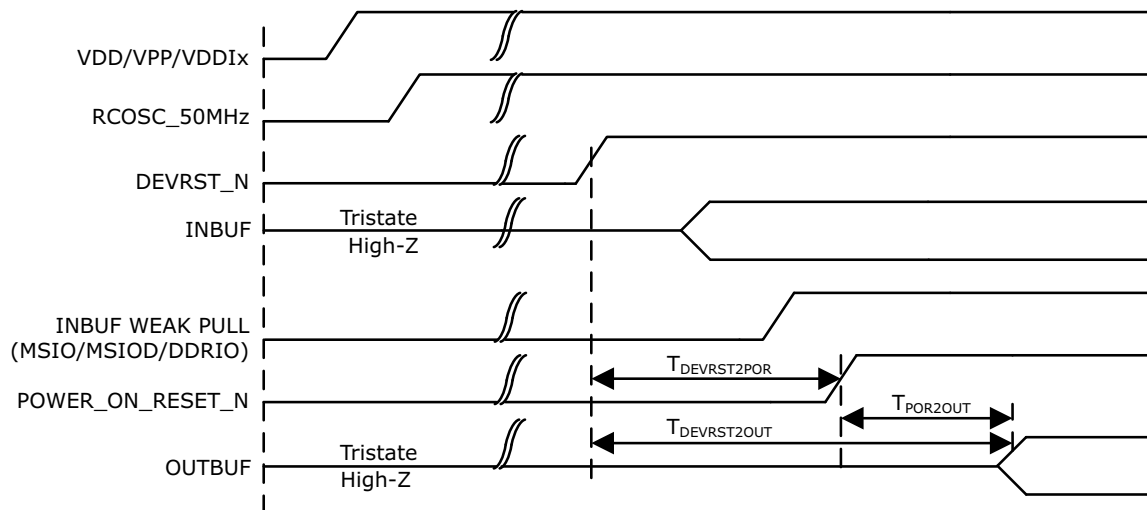
Parameter	Symbol	Min	Typ	Max	Unit	Condition
Startup time (with regard to stable oscillator output)	SUXTAL			0.8	ms	005, 010, 025, and 050 devices
				1.0	ms	090 and 150 devices

Table 278 • Electrical Characteristics of the Crystal Oscillator – Medium Gain Mode (2 MHz)

Parameter	Symbol	Min	Typ	Max	Unit	Condition
Operating frequency	FXTAL		2		MHz	
Accuracy	ACCXTAL			0.00105	%	050 devices
				0.003	%	005, 010, 025, 090, and 150 devices
				0.004	%	060 devices
Output duty cycle	CYCXTAL		49–51	47–53	%	
Output period jitter (peak to peak)	JITPERXTAL		1	5	ns	
Output cycle to cycle jitter (peak to peak)	JITCYCXTAL		1	5	ns	
Operating current	IDYNXTAL		0.3		mA	
Input logic level high	VIHXTAL	0.9 V _{PP}			V	
Input logic level low	VILXTAL			0.1 V _{PP}	V	
Startup time (with regard to stable oscillator output)	SUXTAL			4.5	ms	010 and 050 devices
				5	ms	005 and 025 devices
				7	ms	090 and 150 devices

Table 279 • Electrical Characteristics of the Crystal Oscillator – Low Gain Mode (32 kHz)

Parameter	Symbol	Min	Typ	Max	Unit	Condition
Operating frequency	FXTAL		32		kHz	
Accuracy	ACCXTAL			0.004	%	005, 010, 025, 050, 060, and 090 devices
				0.005	%	150 devices
Output duty cycle	CYCXTAL		49–51	47–53	%	
Output period jitter (peak to peak)	JITPERXTAL		150	300	ns	
Output cycle to cycle jitter (peak to peak)	JITCYCXTAL		150	300	ns	
Operating current	IDYNXTAL		0.044		mA	010 and 050 devices
			0.060		mA	005, 025, 060, 090, and 150 devices
Input logic level high	VIHXTAL	0.9 V _{PP}			V	
Input logic level low	VILXTAL			0.1 V _{PP}	V	
Startup time (with regard to stable oscillator output)	SUXTAL			115	ms	005, 025, 050, 090, and 150 devices
				126	ms	010 devices

Figure 20 • DEVRST_N to Functional Timing Diagram for IGLOO2

2.3.27 Flash*Freeze Timing Characteristics

The following table lists the Flash*Freeze entry and exit times in worst-case industrial conditions when $T_J = 100^\circ\text{C}$, $V_{DD} = 1.14\text{ V}$.

Table 293 • Flash*Freeze Entry and Exit Times

Parameter	Symbol	Entry/Exit Timing FCLK = 100MHz		Entry/Exit Timing FCLK = 3 MHz		Unit	Conditions
		005, 010, 025, 060, 090, and 150	050	All Devices			
Entry time	TFF_ENTRY	160	150	320		μs	eNVM and MSS/HPMS PLL = ON
		215	200	430		μs	eNVM and MSS/HPMS PLL= OFF
Exit time with respect to the MSS PLL Lock	TFF_EXIT	100	100	140		μs	eNVM and MSS/HPMS PLL = ON during F*F
		136	120	190		μs	eNVM = ON and MSS/HPMS PLL = OFF during F*F and MSS/HPMS PLL turned back on at exit
		200	200	285		μs	eNVM and MSS/HPMS PLL = OFF during F*F and both are turned back on at exit
		200	200	285		μs	eNVM = OFF and MSS/HPMS PLL = ON during F*F and eNVM turned back on at exit

Table 303 • I2C Characteristics (continued)

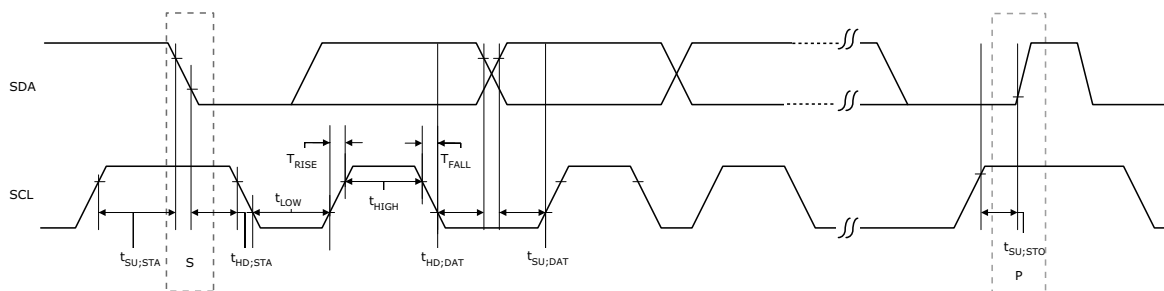
Parameter	Symbol	Min	Typ	Max	Unit	Conditions
Maximum data rate	D_{MAX}			400	Kbps	Fast mode
				100	Kbps	Standard mode
Pulse width of spikes which must be suppressed by the input filter	T_{FILT}		50		ns	Fast mode

1. These values are provided for MSIO Bank–LVTTL 8 mA Low Drive at 25 °C, typical conditions. For board design considerations and detailed output buffer resistances, use the corresponding IBIS models located on the SoC Products Group website: <http://www.microsemi.com/soc/download/ibis/default.aspx>.
2. These maximum values are provided for information only. Minimum output buffer resistance values depend on V_{DDIX} , drive strength selection, temperature, and process. For board design considerations and detailed output buffer resistances, use the corresponding IBIS models located on the SoC Products Group website: <http://www.microsemi.com/soc/download/ibis/default.aspx>.
3. $R(PULL-DOWN-MAX) = (VOL_{spec})/IOL_{spec}$.
4. $R(PULL-UP-MAX) = (VDDImax - VOH_{spec})/IOH_{spec}$.

The following table lists the I²C switching characteristics in worst-case industrial conditions when $T_J = 100\text{ °C}$, $V_{DD} = 1.14\text{ V}$

Table 304 • I2C Switching Characteristics

Parameter	Symbol	–1	Std	Unit
		Min	Min	
Low period of I2C_x_SCL	T_{LOW}	1	1	PCLK cycles
High period of I2C_x_SCL	T_{HIGH}	1	1	PCLK cycles
START hold time	$T_{HD;STA}$	1	1	PCLK cycles
START setup time	$T_{SU;STA}$	1	1	PCLK cycles
DATA hold time	$T_{HD;DAT}$	1	1	PCLK cycles
DATA setup time	$T_{SU;DAT}$	1	1	PCLK cycles
STOP setup time	$T_{SU;STO}$	1	1	PCLK cycles

Figure 21 • I²C Timing Parameter Definition

2.3.31.3 Serial Peripheral Interface (SPI) Characteristics

This section describes the DC and switching of the SPI interface. Unless otherwise noted, all output characteristics given are for a 35 pF load on the pins and all sequential timing characteristics are related to SPI_x_CLK. For timing parameter definitions, see Figure 22, page 128.

The following table lists the SPI characteristics in worst-case industrial conditions when $T_J = 100\text{ }^{\circ}\text{C}$, $V_{DD} = 1.14\text{ V}$

Table 305 • SPI Characteristics for All Devices

Symbol	Description	Min	Typ	Max	Unit	Conditions
SPIFMAX	Maximum operating frequency of SPI interface			20	MHz	
sp1	SPI_[0 1]_CLK minimum period					
	SPI_[0 1]_CLK = PCLK/2	12			ns	
	SPI_[0 1]_CLK = PCLK/4	24.1			ns	
	SPI_[0 1]_CLK = PCLK/8	48.2			ns	
	SPI_[0 1]_CLK = PCLK/16	0.1			μs	
	SPI_[0 1]_CLK = PCLK/32	0.19			μs	
	SPI_[0 1]_CLK = PCLK/64	0.39			μs	
	SPI_[0 1]_CLK = PCLK/128	0.77			μs	
sp2	SPI_[0 1]_CLK minimum pulse width high					
	SPI_[0 1]_CLK = PCLK/2	6			ns	
	SPI_[0 1]_CLK = PCLK/4	12.05			ns	
	SPI_[0 1]_CLK = PCLK/8	24.1			ns	
	SPI_[0 1]_CLK = PCLK/16	0.05			μs	
	SPI_[0 1]_CLK = PCLK/32	0.095			μs	
	SPI_[0 1]_CLK = PCLK/64	0.195			μs	
	SPI_[0 1]_CLK = PCLK/128	0.385			μs	
sp3	SPI_[0 1]_CLK minimum pulse width low					
	SPI_[0 1]_CLK = PCLK/2	6			ns	
	SPI_[0 1]_CLK = PCLK/4	12.05			ns	
	SPI_[0 1]_CLK = PCLK/8	24.1			ns	
	SPI_[0 1]_CLK = PCLK/16	0.05			μs	
	SPI_[0 1]_CLK = PCLK/32	0.095			μs	
	SPI_[0 1]_CLK = PCLK/64	0.195			μs	
	SPI_[0 1]_CLK = PCLK/128	0.385			μs	
sp4	SPI_[0 1]_CLK, SPI_[0 1]_DO, SPI_[0 1]_SS rise time (10%–90%) ¹		2.77		ns	I/O Configuration: LVCMOS 2.5 V– 8 mA AC loading: 35 pF Test conditions: Typical voltage, 25 °C

2.3.34 MMUART Characteristics

The following table lists the MMUART characteristics in worst-case industrial conditions when $T_J = 100\text{ }^{\circ}\text{C}$, $V_{DD} = 1.14\text{ V}$.

Table 308 • MMUART Characteristics

Parameter	Description	–1	–Std	Unit
FMMUART_REF_CLK	Internally sourced MMUART reference clock frequency.	166	142	MHz
BAUDMMUARTTx	Maximum transmit baud rate	10.375	8.875	Mbps
BAUDMMUARTRx	Maximum receive baud rate	10.375	8.875	Mbps

2.3.35 IGLOO2 Specifications

2.3.35.1 HPMS Clock Frequency

The following table lists the maximum frequency for HPMS main clock in worst-case industrial conditions when $T_J = 100\text{ }^{\circ}\text{C}$, $V_{DD} = 1.14\text{ V}$.

Table 309 • Maximum Frequency for HPMS Main Clock

Symbol	Description	–1	–Std	Unit
HPMS_CLK	Maximum frequency for the HPMS main clock	166	142	MHz

2.3.35.2 IGLOO2 Serial Peripheral Interface (SPI) Characteristics

This section describes the DC and switching of the SPI interface. Unless otherwise noted, all output characteristics given are for a 35 pF load on the pins and all sequential timing characteristics are related to SPI_0_CLK. For timing parameter definitions, see Figure 23, page 131.

The following table lists the SPI characteristics in worst-case industrial conditions when $T_J = 100\text{ }^{\circ}\text{C}$, $V_{DD} = 1.14\text{ V}$.

Table 310 • SPI Characteristics for All Devices

Symbol	Description	Min	Typ	Max	Unit	Conditions
SPIFMAX	Maximum operating frequency of SPI interface			20	MHz	
sp1	SPI_[0 1]_CLK minimum period					
	SPI_[0 1]_CLK = PCLK/2	12			ns	
	SPI_[0 1]_CLK = PCLK/4	24.1			ns	
	SPI_[0 1]_CLK = PCLK/8	48.2			ns	
	SPI_[0 1]_CLK = PCLK/16	0.1			μs	
	SPI_[0 1]_CLK = PCLK/32	0.19			μs	
	SPI_[0 1]_CLK = PCLK/64	0.39			μs	
	SPI_[0 1]_CLK = PCLK/128	0.77			μs	