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Understanding [Embedded - FPGAs \(Field Programmable Gate Array\)](#)

Embedded - FPGAs, or Field Programmable Gate Arrays, are advanced integrated circuits that offer unparalleled flexibility and performance for digital systems. Unlike traditional fixed-function logic devices, FPGAs can be programmed and reprogrammed to execute a wide array of logical operations, enabling customized functionality tailored to specific applications. This reprogrammability allows developers to iterate designs quickly and implement complex functions without the need for custom hardware.

Applications of Embedded - FPGAs

The versatility of Embedded - FPGAs makes them indispensable in numerous fields. In telecommunications.

Details

Product Status	Active
Number of LABs/CLBs	-
Number of Logic Elements/Cells	6060
Total RAM Bits	719872
Number of I/O	84
Number of Gates	-
Voltage - Supply	1.14V ~ 2.625V
Mounting Type	Surface Mount
Operating Temperature	0°C ~ 85°C (TJ)
Package / Case	144-LQFP
Supplier Device Package	144-TQFP (20x20)
Purchase URL	https://www.e-xfl.com/product-detail/microchip-technology/m2gl005s-tqg144

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2 IGLOO2 FPGA and SmartFusion2 SoC FPGA

Microsemi's mainstream SmartFusion[®]2 SoC and IGLOO[®]2 FPGA families integrate an industry standard 4-input lookup table-based (LUT) FPGA fabric with integrated math blocks, multiple embedded memory blocks, and high-performance SerDes communication interfaces on a single chip. Both families benefit from low-power flash technology and are the most secure and reliable FPGAs in the industry. These next generation devices offer up to 150K Logic Elements, up to 5 MBs of embedded RAM, up to 16 SerDes lanes, and up to four PCI Express Gen 2 endpoints, as well as integrated hard DDR3 memory controllers with error correction.

SmartFusion2 devices integrate an entire low-power, real-time microcontroller subsystem (MSS) with a rich set of industry-standard peripherals including Ethernet, USB, and CAN, while IGLOO2 devices integrate a high-performance memory subsystem with on-chip flash, 32 Kbyte embedded SRAM, and multiple DMA controllers.

2.1 Device Status

The following table shows the design security densities and development status of the IGLOO2 FPGA and SmartFusion2 SoC FPGA devices.

Table 1 • IGLOO2 and SmartFusion2 Design Security Densities

Design Security Device Densities	Status
005	Production
010, 010T	Production
025, 025T	Production
050, 050T	Production
060, 060T	Production
090, 090T	Production
150, 150T	Production

The following table shows the data security densities and development status of the IGLOO2 FPGA and SmartFusion2 SoC FPGA devices.

Table 2 • IGLOO2 and SmartFusion2 Data Security Densities

Data Security Device Densities	Status
005S	Production
010TS	Production
025TS	Production
050TS	Production
060TS	Production
090TS	Production
150TS	Production

Table 9 • Package Thermal Resistance of SmartFusion2 and IGLOO2 Devices (continued)

	Still Air	1.0 m/s	2.5 m/s			
Device	θ_{JA}			θ_{JB}	θ_{JC}	Unit
150						
FC1152	9.08	6.81	5.87	2.56	0.38	°C/W
FCS536	15.01	12.06	10.76	3.69	1.55	°C/W
FCV484	16.21	13.11	11.84	6.73	0.10	°C/W

2.3.1.2.1 Theta-JA

Junction-to-ambient thermal resistance (θ_{JA}) is determined under standard conditions specified by JEDEC (JESD-51), but it has little relevance in the actual performance of the product. It must be used with caution, but it is useful for comparing the thermal performance of one package with another.

The maximum power dissipation allowed is calculated using EQ4.

$$\text{Maximum power allowed} = \frac{T_{J(\text{MAX})} - T_{A(\text{MAX})}}{\theta_{JA}}$$

EQ 4

The absolute maximum junction temperature is 100 °C. EQ5 shows a sample calculation of the absolute maximum power dissipation allowed for the M2GL050T-FG896 package at commercial temperature and in still air, where:

$$\theta_{JA} = 14.7 \text{ °C/W (taken from Table 9, page 10).}$$

$$T_A = 85 \text{ °C}$$

$$\text{Maximum power allowed} = \frac{100 \text{ °C} - 85 \text{ °C}}{14.7 \text{ °C/W}} = 1.088 \text{ W}$$

EQ 5

The power consumption of a device can be calculated using the Microsemi SoC Products Group power calculator. The device's power consumption must be lower than the calculated maximum power dissipation by the package.

If the power consumption is higher than the device's maximum allowable power dissipation, a heat sink may be attached to the top of the case, or the airflow inside the system must be increased.

2.3.1.2.2 Theta-JB

Junction-to-board thermal resistance (θ_{JB}) measures the ability of the package to dissipate heat from the surface of the chip to the PCB. As defined by the JEDEC (JESD-51) standard, the thermal resistance from the junction to the board uses an isothermal ring cold plate zone concept. The ring cold plate is simply a means to generate an isothermal boundary condition at the perimeter. The cold plate is mounted on a JEDEC standard board with a minimum distance of 5.0 mm away from the package edge.

2.3.1.2.3 Theta-JC

Junction-to-case thermal resistance (θ_{JC}) measures the ability of a device to dissipate heat from the surface of the chip to the top or bottom surface of the package. It is applicable to packages used with external heat sinks. Constant temperature is applied to the surface, which acts as a boundary condition.

This only applies to situations where all or nearly all of the heat is dissipated through the surface in consideration.

2.3.1.3 ESD Performance

See RT0001: Microsemi Corporation - SoC Products Reliability Report for information about ESD.

Table 15 • Inrush Currents at Power up, $-40\text{ }^{\circ}\text{C} \leq T_J \leq 100\text{ }^{\circ}\text{C}$ – Typical Process

Power Supplies	Voltage (V)	005	010	025	050	060	090	150	Unit
V_{DD}	1.26	25	32	38	48	45	77	109	mA
V_{PP}	3.46	33	49	36	180	13	36	51	mA
V_{DDI}	2.62	134	141	161	187	93	272	388	mA
Number of banks		7	8	8	10	10	9	19	

2.3.3 Average Fabric Temperature and Voltage Derating Factors

The following table lists the average temperature and voltage derating factors for fabric timing delays normalized to $T_J = 85\text{ }^{\circ}\text{C}$, in worst-case $V_{DD} = 1.14\text{ V}$.

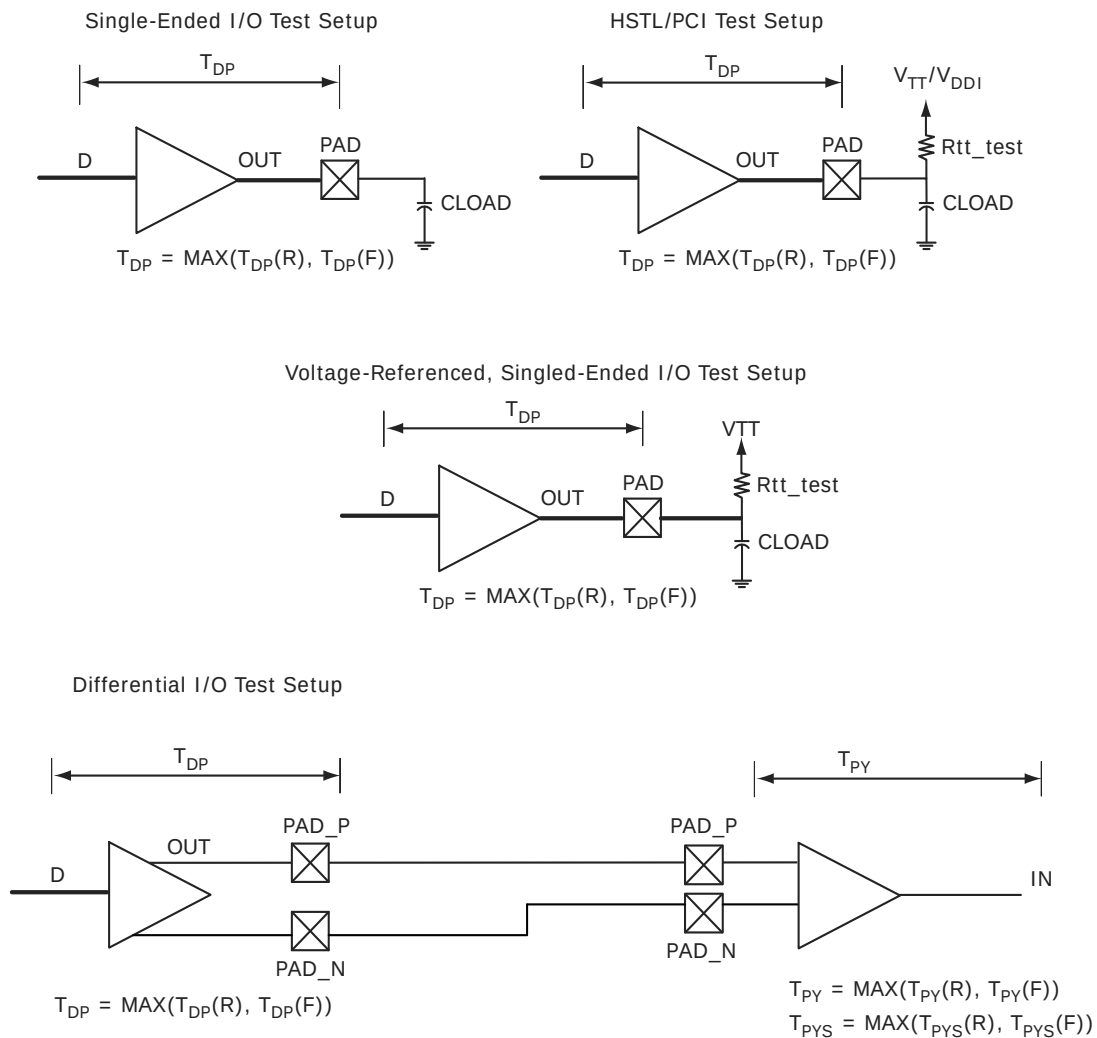
Table 16 • Average Junction Temperature and Voltage Derating Factors for Fabric Timing Delays

Array Voltage V_{DD} (V)	$-40\text{ }^{\circ}\text{C}$	$0\text{ }^{\circ}\text{C}$	$25\text{ }^{\circ}\text{C}$	$70\text{ }^{\circ}\text{C}$	$85\text{ }^{\circ}\text{C}$	$100\text{ }^{\circ}\text{C}$
1.14	0.83	0.89	0.92	0.98	1.00	1.02
1.2	0.75	0.80	0.83	0.89	0.91	0.93
1.26	0.69	0.73	0.76	0.81	0.83	0.85

2.3.5.2 Output Buffer and AC Loading

The following figure shows the output buffer and AC loading.

Figure 4 • Output Buffer AC Loading



2.3.5.5 Detailed I/O Characteristics

Table 24 • Input Capacitance, Leakage Current, and Ramp Time

Symbol	Description	Maximum	Unit	Conditions
C_{IN}	Input capacitance	10	pF	
I_{IL} (dc)	Input current low (Applicable to HSTL/SSTL inputs only)	400	μA	$V_{DDI} = 2.5 V$
		500	μA	$V_{DDI} = 1.8 V$
		600	μA	$V_{DDI} = 1.5 V^1$
	Input current low (Applicable to all other digital inputs)	10	μA	
I_{IH} (dc)	Input current high (Applicable to HSTL/SSTL inputs only)	400	μA	$V_{DDI} = 2.5 V$
		500	μA	$V_{DDI} = 1.8 V$
		600	μA	$V_{DDI} = 1.5 V^1$
	Input current high (Applicable to all other digital inputs)	10	μA	
T_{RAMPIN}^2	Input ramp time (Applicable to all digital inputs)	50	ns	

1. Applicable when I/O pair is programmed with an HSTL/SSTL I/O type on IOP and an un-terminated I/O type (LVCMOS, for example) on ION pad.
2. Voltage ramp must be monotonic.

The following table lists the minimum and maximum I/O weak pull-up/pull-down resistance values of DDRIO I/O bank at V_{OH}/V_{OL} Level.

Table 25 • I/O Weak Pull-up/Pull-down Resistances for DDRIO I/O Bank

V_{DDI} Domain	R(WEAK PULL-UP) at V_{OH} (Ω)		R(WEAK PULL-DOWN) at V_{OL} (Ω)	
	Min	Max	Min	Max
2.5 V ^{1, 2}	10K	17.8K	9.98K	18K
1.8 V ^{1, 2}	10.3K	19.1K	10.3K	19.5K
1.5 V ^{1, 2}	10.6K	20.2K	10.6K	21.1K
1.2 V ^{1, 2}	11.1K	22.7K	11.2K	24.6K

1. $R(\text{WEAK PULL-DOWN}) = (V_{OLspec})/I(\text{WEAK PULL-DOWN MAX})$.
2. $R(\text{WEAK PULL-UP}) = (V_{DDImax} - V_{OHspec})/I(\text{WEAK PULL-UP MIN})$.

Table 43 • LVCMOS 2.5 V AC Test Parameter Specifications

Parameter	Symbol	Typ	Unit
Measuring/trip point for data path	V_{TRIP}	1.2	V
Resistance for enable path (T_{ZH} , T_{ZL} , T_{HZ} , T_{LZ})	R_{ENT}	2K	$\Omega\sigma$
Capacitive loading for enable path (T_{ZH} , T_{ZL} , T_{HZ} , T_{LZ})	C_{ENT}	5	pF
Capacitive loading for data path (T_{DP})	C_{LOAD}	5	pF

Table 44 • LVCMOS 2.5 V Transmitter Drive Strength Specifications

Output Drive Selection			VOH (V)	VOL (V)	IOH (at VOH) mA	IOL (at VOL) mA
MSIO I/O Bank	MSIOD I/O Bank	DDRIO I/O Bank (With Software Default Fixed Code)	Min	Max		
2 mA	2 mA	2 mA	$V_{DDI} - 0.4$	0.4	2	2
4 mA	4 mA	4 mA	$V_{DDI} - 0.4$	0.4	4	4
6 mA	6 mA	6 mA	$V_{DDI} - 0.4$	0.4	6	6
8 mA	8 mA	8 mA	$V_{DDI} - 0.4$	0.4	8	8
12 mA	12 mA	12 mA	$V_{DDI} - 0.4$	0.4	12	12
16 mA		16 mA	$V_{DDI} - 0.4$	0.4	16	16

Note: For board design considerations, output slew rates extraction, detailed output buffer resistances, and I/V Curve, use the corresponding IBIS models located at:
www.microsemi.com/soc/download/ibis/default.aspx.

AC Switching Characteristics

Worst commercial-case conditions: $T_J = 85^\circ\text{C}$, $V_{DD} = 1.14\text{ V}$, $V_{DDI} = 2.375\text{ V}$

Table 45 • LVCMOS 2.5 V Receiver Characteristics (Input Buffers)

	On-Die Termination (ODT)	T_{PY}		T_{PYS}		Unit
		-1	-Std	-1	-Std	
LVCMOS 2.5 V (for DDRIO I/O bank)	None	1.823	2.145	1.932	2.274	ns
LVCMOS 2.5 V (for MSIO I/O bank)	None	2.486	2.925	2.495	2.935	ns
LVCMOS 2.5 V (for MSIOD I/O bank)	None	2.29	2.694	2.305	2.712	ns

Table 46 • LVCMOS 2.5 V Transmitter Characteristics for DDRIO Bank (Output and Tristate Buffers)

Output Drive Selection	Slew Control	T_{DP}		T_{ZL}		T_{ZH}		T_{HZ}^1		T_{LZ}^1		Unit
		-1	-Std	-1	-Std	-1	-Std	-1	-Std	-1	-Std	
2 mA	Slow	3.657	4.302	3.393	3.991	3.675	4.323	3.894	4.582	3.552	4.18	ns
	Medium	3.374	3.97	3.139	3.693	3.396	3.995	3.635	4.277	3.253	3.828	ns
	Medium fast	3.239	3.811	3.036	3.572	3.261	3.836	3.519	4.141	3.128	3.681	ns
	Fast	3.224	3.793	3.029	3.563	3.246	3.818	3.512	4.132	3.119	3.67	ns

Table 70 • LVCMOS 1.5 V Transmitter Characteristics for DDRIO I/O Bank (Output and Tristate Buffers)
(continued)

Output Drive Selection	Slew Control	T _{DP}		T _{ZL}		T _{ZH}		T _{HZ} ¹		T _{LZ} ¹		Unit
		-1	-Std	-1	-Std	-1	-Std	-1	-Std	-1	-Std	
6 mA	Slow	4.244	4.993	3.465	4.076	4.233	4.979	6.39	7.518	5.736	6.748	ns
	Medium	3.774	4.44	3.05	3.587	3.762	4.426	6.114	7.193	5.397	6.35	ns
	Medium fast	3.544	4.17	2.839	3.339	3.529	4.152	5.978	7.033	5.27	6.2	ns
	Fast	3.519	4.14	2.82	3.317	3.504	4.122	5.965	7.017	5.259	6.187	ns
8 mA	Slow	4.099	4.823	3.311	3.894	4.087	4.807	6.584	7.746	5.854	6.888	ns
	Medium	3.656	4.301	2.927	3.443	3.642	4.284	6.311	7.425	5.553	6.533	ns
	Medium fast	3.437	4.044	2.731	3.213	3.42	4.023	6.182	7.273	5.435	6.394	ns
	Fast	3.41	4.012	2.715	3.193	3.393	3.991	6.178	7.269	5.425	6.383	ns
10 mA	Slow	4.029	4.74	3.238	3.809	4.015	4.723	6.732	7.921	5.965	7.018	ns
	Medium	3.601	4.237	2.867	3.372	3.586	4.218	6.473	7.615	5.669	6.669	ns
	Medium fast	3.384	3.981	2.672	3.143	3.365	3.958	6.351	7.471	5.55	6.529	ns
	Fast	3.357	3.949	2.655	3.123	3.338	3.927	6.345	7.464	5.54	6.518	ns
12 mA	Slow	3.974	4.675	3.196	3.759	3.958	4.656	6.842	8.049	6.068	7.139	ns
	Medium	3.55	4.176	2.827	3.326	3.534	4.157	6.584	7.746	5.751	6.766	ns
	Medium fast	3.345	3.935	2.638	3.103	3.325	3.911	6.488	7.633	5.641	6.637	ns
	Fast	3.316	3.902	2.621	3.083	3.297	3.878	6.486	7.63	5.626	6.619	ns

1. Delay increases with drive strength are inherent to built-in slew control circuitry for simultaneous switching output (SSO) management.

Table 71 • LVCMOS 1.5 V Transmitter Characteristics for MSIO I/O Bank (Output and Tristate Buffers)

Output Drive Selection	Slew Control	T _{DP}		T _{ZL}		T _{ZH}		T _{HZ} ¹		T _{LZ} ¹		Unit
		-1	-Std	-1	-Std	-1	-Std	-1	-Std	-1	-Std	
2 mA	Slow	4.423	5.203	5.397	6.35	5.686	6.69	5.609	6.599	5.561	6.542	ns
4 mA	Slow	4.05	4.765	4.503	5.298	4.92	5.788	7.358	8.657	6.525	7.677	ns
6 mA	Slow	4.081	4.801	4.259	5.012	4.699	5.528	7.659	9.011	6.709	7.893	ns
8 mA	Slow	4.234	4.98	4.068	4.786	4.521	5.319	8.218	9.668	7.05	8.294	ns

1. Delay increases with drive strength are inherent to built-in slew control circuitry for simultaneous switching output (SSO) management.

Table 82 • LVCMOS 1.2 V Receiver Characteristics for MSIOD I/O Bank (Input Buffers)

On-Die Termination (ODT)	T_{PY}		T_{PYS}		Unit
	-1	-Std	-1	-Std	
None	4.154	4.887	4.114	4.84	ns
50	6.918	8.139	6.806	8.008	ns
75	5.613	6.603	5.533	6.509	ns
150	4.716	5.549	4.657	5.479	ns

Table 83 • LVCMOS 1.2 V Transmitter Characteristics for DDRIO I/O Bank (Output and Tristate Buffers)

Output Drive Selection	Slew Control	T_{DP}		T_{ZL}		T_{ZH}		T_{HZ}^1		T_{LZ}^1		Unit
		-1	-Std	-1	-Std	-1	-Std	-1	-Std	-1	-Std	
2 mA	Slow	6.713	7.897	5.362	6.308	6.723	7.909	7.233	8.51	6.375	7.499	ns
	Medium	5.912	6.955	4.616	5.43	5.915	6.959	6.887	8.102	6.009	7.069	ns
	Medium fast	5.5	6.469	4.231	4.978	5.5	6.471	6.672	7.849	5.835	6.865	ns
	Fast	5.462	6.426	4.194	4.935	5.463	6.427	6.646	7.819	5.828	6.857	ns
4 mA	Slow	6.109	7.186	4.708	5.539	6.098	7.174	8.005	9.418	7.033	8.274	ns
	Medium	5.355	6.299	4.034	4.746	5.338	6.28	7.637	8.985	6.672	7.849	ns
	Medium fast	4.953	5.826	3.685	4.336	4.932	5.802	7.44	8.752	6.499	7.646	ns
	Fast	4.911	5.777	3.658	4.303	4.89	5.754	7.427	8.737	6.488	7.632	ns
6 mA	Slow	5.89	6.929	4.506	5.301	5.874	6.911	8.337	9.808	7.315	8.605	ns
	Medium	5.176	6.089	3.862	4.543	5.155	6.065	7.986	9.394	6.943	8.168	ns
	Medium fast	4.792	5.637	3.523	4.145	4.765	5.606	7.808	9.186	6.775	7.97	ns
	Fast	4.754	5.593	3.486	4.101	4.728	5.563	7.777	9.149	6.769	7.963	ns

1. Delay increases with drive strength are inherent to built-in slew control circuitry for simultaneous switching output (SSO) management.

Table 84 • LVCMOS 1.2 V Transmitter Characteristics for MSIO I/O Bank (Output and Tristate Buffers)

Output Drive Selection	Slew Control	T_{DP}		T_{ZL}		T_{ZH}		T_{HZ}^1		T_{LZ}^1		Unit
		-1	-Std	-1	-Std	-1	-Std	-1	-Std	-1	-Std	
2 mA	Slow	6.746	7.937	7.458	8.774	8.172	9.614	9.867	11.608	8.393	9.874	ns
4 mA	Slow	7.068	8.315	6.678	7.857	7.474	8.793	10.986	12.924	9.043	10.638	ns

1. Delay increases with drive strength are inherent to built-in slew control circuitry for simultaneous switching output (SSO) management.

Table 122 • SSTL18 DC Differential Voltage Specification

Parameter	Symbol	Min	Unit
DC input differential voltage	V_{ID} (DC)	0.3	V

Table 123 • SSTL18 AC Differential Voltage Specifications (Applicable to DDRIO Bank Only)

Parameter	Symbol	Min	Max	Unit
AC input differential voltage	V_{DIFF} (AC)	0.5		V
AC differential cross point voltage	V_x (AC)	$0.5 \times V_{DDI} - 0.175$	$0.5 \times V_{DDI} + 0.175$	V

Table 124 • SSTL18 Minimum and Maximum AC Switching Speed (Applicable to DDRIO Bank Only)

Parameter	Symbol	Max	Unit	Conditions
Maximum data rate (for DDRIO I/O bank)	D_{MAX}	667	Mbps	AC loading: per JEDEC specification

Table 125 • SSTL18 AC Impedance Specifications (Applicable to DDRIO Bank Only)

Parameter	Symbol	Typ	Unit	Conditions
Supported output driver calibrated impedance (for DDRIO I/O bank)	R_{REF}	20, 42	Ω	Reference resistor = 150 Ω
Effective impedance value (ODT)	R_{TT}	50, 75, 150	Ω	Reference resistor = 150 Ω

Table 126 • SSTL18 AC Test Parameter Specifications (Applicable to DDRIO Bank Only)

Parameter	Symbol	Typ	Unit
Measuring/trip point for data path	V_{TRIP}	0.9	V
Resistance for enable path (T_{ZH} , T_{ZL} , T_{HZ} , T_{LZ})	R_{ENT}	2K	Ω
Capacitive loading for enable path (T_{ZH} , T_{ZL} , T_{HZ} , T_{LZ})	C_{ENT}	5	pF
Reference resistance for data test path for SSTL18 Class I (T_{DP})	RTT_TEST	50	Ω
Reference resistance for data test path for SSTL18 Class II (T_{DP})	RTT_TEST	25	Ω
Capacitive loading for data path (T_{DP})	C_{LOAD}	5	pF

AC Switching Characteristics

Worst commercial-case conditions: $T_J = 85^\circ\text{C}$, $V_{DD} = 1.14\text{ V}$, $V_{DDI} = 1.71\text{ V}$

Table 127 • DDR2/SSTL18 Receiver Characteristics for DDRIO I/O Bank with Fixed Code

		T_{PY}		Unit
		-1	-Std	
Pseudo differential	None	1.567	1.844	ns
True differential	None	1.588	1.869	ns

Table 150 • LPDDR Full Drive for DDRIO I/O Bank (Output and Tristate Buffers)

	T_{DP}		T_{ENZL}		T_{ENZH}		T_{ENHZ}		T_{ENLZ}		Unit
	-1	-Std	-1	-Std	-1	-Std	-1	-Std	-1	-Std	
Single-ended	2.281	2.683	2.196	2.584	2.195	2.583	2.171	2.555	2.17	2.554	ns
Differential	2.298	2.703	2.288	2.692	2.288	2.692	2.593	3.051	2.593	3.051	ns

Minimum and Maximum DC/AC Input and Output Levels Specification using LPDDR-LVCMOS 1.8 V Mode

Table 151 • LPDDR-LVCMOS 1.8 V Mode Recommended DC Operating Conditions

Parameter	Symbol	Min	Typ	Max	Unit
Supply voltage	V_{DDI}	1.710	1.8	1.89	V

Table 152 • LPDDR-LVCMOS 1.8 V Mode DC Input Voltage Specification

Parameter	Symbol	Min	Max	Unit
DC input logic high (for MSIOD and DDRIO I/O banks)	V_{IH} (DC)	$0.65 \times V_{DDI}$	1.89	V
DC input logic high (for MSIO I/O bank)	V_{IH} (DC)	$0.65 \times V_{DDI}$	3.45	V
DC input logic low	V_{IL} (DC)	-0.3	$0.35 \times V_{DDI}$	V
Input current high ¹	I_{IH} (DC)			
Input current low ¹	I_{IL} (DC)			

1. See Table 24, page 22.

Table 153 • LPDDR-LVCMOS 1.8 V Mode DC Output Voltage Specification

Parameter	Symbol	Min	Max	Unit
DC output logic high	V_{OH}	$V_{DDI} - 0.45$		V
DC output logic low	V_{OL}		0.45	V

Table 154 • LPDDR-LVCMOS 1.8 V Minimum and Maximum AC Switching Speeds

Parameter	Symbol	Max	Unit	Conditions
Maximum data rate (for DDRIO I/O bank)	D_{MAX}	400	Mbps	AC loading: 17pf load, 8 ma drive and above/all slew

Table 155 • LPDDR-LVCMOS 1.8 V Calibrated Impedance Option

Parameter	Symbol	Typ	Unit
Supported output driver calibrated impedance (for DDRIO I/O bank)	RODT_CAL	75, 60, 50, 33, 25, 20	Ω

Table 156 • LPDDR-LVCMOS 1.8 V AC Test Parameter Specifications

Parameter	Symbol	Typ	Unit
Measuring/trip point for data path	V_{TRIP}	0.9	V
Resistance for enable path (T_{ZH} , T_{ZL} , T_{HZ} , T_{LZ})	R_{ENT}	2K	Ω
Capacitive loading for enable path (T_{ZH} , T_{ZL} , T_{HZ} , T_{LZ})	C_{ENT}	5	pF
Capacitive loading for data path (T_{DP})	C_{LOAD}	5	pF

Table 157 • LPDDR-LVCMOS 1.8 V Mode Transmitter Drive Strength Specification for DDRIO Bank

Output Drive Selection	V_{OH} (V) Min	V_{OL} (V) Max	I_{OH} (at V_{OH}) mA	I_{OL} (at V_{OL}) mA
2 mA	$V_{DDI} - 0.45$	0.45	2	2
4 mA	$V_{DDI} - 0.45$	0.45	4	4
6 mA	$V_{DDI} - 0.45$	0.45	6	6
8 mA	$V_{DDI} - 0.45$	0.45	8	8
10 mA	$V_{DDI} - 0.45$	0.45	10	10
12 mA	$V_{DDI} - 0.45$	0.45	12	12
16 mA ¹	$V_{DDI} - 0.45$	0.45	16	16

1. 16 mA Drive Strengths, All Slews, meet LPDDR JEDEC electrical compliance.

Table 158 • LPDDR-LVCMOS 1.8V AC Switching Characteristics for Receiver (for DDRIO I/O Bank with Fixed Code - Input Buffers)

ODT (On Die Termination)	-1	-Std	-1	-Std	Unit
None	1.968	2.315	2.099	2.47	ns

Table 159 • LPDDR-LVCMOS 1.8 V AC Switching Characteristics for Transmitter for DDRIO I/O Bank (Output and Tristate Buffers)

Output Drive Selection	Slew Control	T_{DP}		T_{ZL}		T_{ZH}		T_{HZ}^1		T_{LZ}^1		Unit
		-1	-Std	-1	-Std	-1	-Std	-1	-Std	-1	-Std	
2 mA	slow	4.234	4.981	3.646	4.29	4.245	4.995	4.908	5.774	4.434	5.216	ns
	medium	3.824	4.498	3.282	3.861	3.834	4.511	4.625	5.441	4.116	4.843	ns
	medium_fast	3.627	4.267	3.111	3.66	3.637	4.279	4.481	5.272	3.984	4.687	ns
	fast	3.605	4.241	3.097	3.644	3.615	4.253	4.472	5.262	3.973	4.674	ns
4 mA	slow	3.923	4.615	3.314	3.9	3.918	4.61	5.403	6.356	4.894	5.757	ns
	medium	3.518	4.138	2.961	3.484	3.515	4.135	5.121	6.025	4.561	5.366	ns
	medium_fast	3.321	3.907	2.783	3.275	3.317	3.903	4.966	5.843	4.426	5.206	ns
	fast	3.301	3.883	2.77	3.259	3.296	3.878	4.957	5.831	4.417	5.196	ns
6 mA	slow	3.71	4.364	3.104	3.652	3.702	4.355	5.62	6.612	5.08	5.977	ns
	medium	3.333	3.921	2.779	3.27	3.325	3.913	5.346	6.289	4.777	5.62	ns
	medium_fast	3.155	3.712	2.62	3.083	3.146	3.702	5.21	6.13	4.657	5.479	ns
	fast	3.134	3.688	2.608	3.068	3.125	3.677	5.202	6.12	4.648	5.468	ns
8 mA	slow	3.619	4.258	3.007	3.538	3.607	4.244	5.815	6.841	5.249	6.175	ns

Table 159 • LPDDR-LVCMOS 1.8 V AC Switching Characteristics for Transmitter for DDRIO I/O Bank (Output and Tristate Buffers) (continued)

10 mA	medium	3.246	3.819	2.686	3.16	3.236	3.807	5.542	6.52	4.936	5.807	ns
	medium_fast	3.066	3.607	2.525	2.971	3.054	3.593	5.405	6.359	4.811	5.66	ns
	fast	3.046	3.584	2.513	2.957	3.034	3.57	5.401	6.353	4.803	5.651	ns
	slow	3.498	4.115	2.878	3.386	3.481	4.096	6.046	7.113	5.444	6.404	ns
12 mA	medium	3.138	3.692	2.569	3.023	3.126	3.678	5.782	6.803	5.129	6.034	ns
	medium_fast	2.966	3.489	2.414	2.841	2.951	3.472	5.666	6.665	5.013	5.897	ns
	fast	2.945	3.464	2.401	2.826	2.93	3.448	5.659	6.658	5.003	5.886	ns
	slow	3.417	4.02	2.807	3.303	3.401	4.002	6.083	7.156	5.464	6.428	ns
16 mA	medium	3.076	3.618	2.519	2.964	3.063	3.604	5.828	6.856	5.176	6.089	ns
	medium_fast	2.913	3.427	2.376	2.795	2.898	3.41	5.725	6.736	5.072	5.966	ns
	fast	2.894	3.405	2.362	2.78	2.879	3.388	5.715	6.724	5.064	5.957	ns
	slow	3.366	3.96	2.751	3.237	3.348	3.939	6.226	7.324	5.576	6.56	ns
	medium	3.03	3.565	2.47	2.906	3.017	3.55	5.981	7.036	5.282	6.214	ns
	medium_fast	2.87	3.377	2.328	2.739	2.854	3.358	5.895	6.935	5.18	6.094	ns
	fast	2.853	3.357	2.314	2.723	2.837	3.338	5.889	6.929	5.177	6.09	ns

1. Delay increases with drive strength are inherent to built-in slew control circuitry for simultaneous switching output (SSO) management).

2.3.7 Differential I/O Standards

Configuration of the I/O modules as a differential pair is handled by Microsemi SoC Products Group Libero software when the user instantiates a differential I/O macro in the design. Differential I/Os can also be used in conjunction with the embedded Input register (InReg), Output register (OutReg), Enable register (EnReg), and Double Data Rate registers (DDR).

2.3.7.1 LVDS

Low-Voltage Differential Signaling (ANSI/TIA/EIA-644) is a high-speed, differential I/O standard.

Minimum and Maximum Input and Output Levels

Table 160 • LVDS Recommended DC Operating Conditions

Parameter	Symbol	Min	Typ	Max	Unit	Conditions
Supply voltage	V_{DDI}	2.375	2.5	2.625	V	2.5 V range
Supply voltage	V_{DDI}	3.15	3.3	3.45	V	3.3 V range

Table 161 • LVDS DC Input Voltage Specification

Parameter	Symbol	Min	Max	Unit	Conditions
DC Input voltage	V_I	0	2.925	V	2.5 V range
DC input voltage	V_I	0	3.45	V	3.3 V range
Input current high ¹	I_{IH} (DC)				
Input current low ¹	I_{IL} (DC)				

1. See Table 24, page 22.

Table 191 • M-LVDS AC Switching Characteristics for Receiver (for MSIOD I/O Bank - Input Buffers)

On-Die Termination (ODT)	T _{py}		Unit
	-1	-Std	
None	2.495	2.934	ns
100	2.495	2.935	ns

Table 192 • M-LVDS AC Switching Characteristics for Transmitter (for MSIO I/O Bank - Output and Tristate Buffers)

T _{DP}		T _{ZL}		T _{ZH}		T _{HZ}		T _{LZ}		Unit
-1	-Std	-1	-Std	-1	-Std	-1	-Std	-1	-Std	
2.258	2.656	2.348	2.762	2.334	2.746	2.123	2.497	2.125	2.5	ns

2.3.7.4 Mini-LVDS

Mini-LVDS is an unidirectional interface from the timing controller to the column drivers and is designed to the Texas Instruments Standard SLDA007A.

Mini-LVDS Minimum and Maximum Input and Output Levels

Table 193 • Mini-LVDS Recommended DC Operating Conditions

Parameter	Symbol	Min	Typ	Max	Unit
Supply voltage	V _{DDI}	2.375	2.5	2.625	V

Table 194 • Mini-LVDS DC Input Voltage Specification

Parameter	Symbol	Min	Max	Unit
DC Input voltage	V _I	0	2.925	V

Table 195 • Mini-LVDS DC Output Voltage Specification

Parameter	Symbol	Min	Typ	Max	Unit
DC output logic high	V _{OH}	1.25	1.425	1.6	V
DC output logic low	V _{OL}	0.9	1.075	1.25	V

Table 196 • Mini-LVDS DC Differential Voltage Specification

Parameter	Symbol	Min	Max	Unit
Differential output voltage swing	V _{OD}	300	600	mV
Output common mode voltage	V _{OCM}	1	1.4	V
Input common mode voltage	V _{ICM}	0.3	1.2	V
Input differential voltage	V _{ID}	100	600	mV

Table 197 • Mini-LVDS Minimum and Maximum AC Switching Speed

Parameter	Symbol	Max	Unit	Conditions
Maximum data rate (for MSIO I/O bank)	D _{MAX}	520	Mbps	AC loading: 2 pF / 100 Ω differential load
Maximum data rate (for MSIOD I/O bank)	D _{MAX}	700	Mbps	AC loading: 2 pF / 100 Ω differential load

2.3.10.2 Timing Characteristics

The following table lists the combinatorial cell propagation delays in worst commercial-case conditions when $T_J = 85^\circ\text{C}$, $V_{DD} = 1.14\text{ V}$.

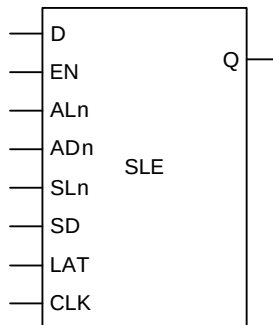
Table 223 • Combinatorial Cell Propagation Delays

Combinatorial Cell	Equation	Symbol	–1	–Std	Unit
INV	$Y = !A$	T_{PD}	0.1	0.118	ns
AND2	$Y = A \cdot B$	T_{PD}	0.164	0.193	ns
NAND2	$Y = !(A \cdot B)$	T_{PD}	0.147	0.173	ns
OR2	$Y = A + B$	T_{PD}	0.164	0.193	ns
NOR2	$Y = !(A + B)$	T_{PD}	0.147	0.173	ns
XOR2	$Y = A \oplus B$	T_{PD}	0.164	0.193	ns
XOR3	$Y = A \oplus B \oplus C$	T_{PD}	0.225	0.265	ns
AND3	$Y = A \cdot B \cdot C$	T_{PD}	0.209	0.246	ns
AND4	$Y = A \cdot B \cdot C \cdot D$	T_{PD}	0.287	0.338	ns

2.3.10.3 Sequential Module

IGLOO2 and SmartFusion2 SoC FPGAs offer a separate flip-flop which can be used independently from the LUT. The flip-flop can be configured as a register or a latch and has a data input and optional enable, synchronous load (clear or preset), and asynchronous load (clear or preset).

Figure 15 • Sequential Module



2.3.12.2 FPGA Fabric Micro SRAM (μ SRAM)

The following table lists the μ SRAM in 64×18 mode in worst commercial-case conditions when $T_J = 85^\circ\text{C}$, $V_{DD} = 1.14\text{ V}$.

Table 237 • μ SRAM (RAM64x18) in 64×18 Mode

Parameter	Symbol	–1		–Std		Unit
		Min	Max	Min	Max	
Read clock period	T_{CY}	4		4		ns
Read clock minimum pulse width high	$T_{CLKMPWH}$	1.8		1.8		ns
Read clock minimum pulse width low	$T_{CLKMPWL}$	1.8		1.8		ns
Read pipeline clock period	T_{PLCY}	4		4		ns
Read pipeline clock minimum pulse width high	$T_{PLCLKMPWH}$	1.8		1.8		ns
Read pipeline clock minimum pulse width low	$T_{PLCLKMPWL}$	1.8		1.8		ns
Read access time with pipeline register	T_{CLK2Q}	0.266		0.313		ns
Read access time without pipeline register		1.677		1.973		ns
Read address setup time in synchronous mode	T_{ADDRSU}	0.301		0.354		ns
Read address setup time in asynchronous mode		1.856		2.184		ns
Read address hold time in synchronous mode	T_{ADDRHD}	0.091		0.107		ns
Read address hold time in asynchronous mode		–0.778		–0.915		ns
Read enable setup time	T_{RDENSU}	0.278		0.327		ns
Read enable hold time	T_{RDENHD}	0.057		0.067		ns
Read block select setup time	T_{BLKSU}	1.839		2.163		ns
Read block select hold time	T_{BLKHD}	–0.65		–0.765		ns
Read block select to out disable time (when pipelined register is disabled)	T_{BLK2Q}	2.036		2.396		ns
Read asynchronous reset removal time (pipelined clock)	T_{RSTREM}	–0.023		–0.027		ns
Read asynchronous reset removal time (non-pipelined clock)		0.046		0.054		ns
Read asynchronous reset recovery time (pipelined clock)	T_{RSTREC}	0.507		0.597		ns
Read asynchronous reset recovery time (non-pipelined clock)		0.236		0.278		ns
Read asynchronous reset to output propagation delay (with pipelined register enabled)	T_{R2Q}	0.839		0.987		ns
Read synchronous reset setup time	T_{SRSTSU}	0.271		0.319		ns
Read synchronous reset hold time	T_{SRSTHD}	0.061		0.071		ns
Write clock period	T_{CCY}	4		4		ns
Write clock minimum pulse width high	$T_{CCLKMPWH}$	1.8		1.8		ns
Write clock minimum pulse width low	$T_{CCLKMPWL}$	1.8		1.8		ns
Write block setup time	T_{BLKCSU}	0.404		0.476		ns
Write block hold time	T_{BLKCHD}	0.007		0.008		ns
Write input data setup time	T_{DINCSU}	0.115		0.135		ns
Write input data hold time	T_{DINCHD}	0.15		0.177		ns

Table 243 • μ SRAM (RAM1024x1) in 1024 × 1 Mode (continued)

Parameter	Symbol	–1		–Std		Unit
		Min	Max	Min	Max	
Read asynchronous reset recovery time (pipelined clock)	T_{RSTREC}	0.507		0.597		ns
Read asynchronous reset recovery time (non-pipelined clock)		0.236		0.278		ns
Read asynchronous reset to output propagation delay (with pipelined register enabled)	T_{R2Q}		0.83		0.98	ns
Read synchronous reset setup time	T_{SRSTSU}	0.271		0.319		ns
Read synchronous reset hold time	T_{SRSTHD}	0.061		0.071		ns
Write clock period	T_{CCY}	4		4		ns
Write clock minimum pulse width high	$T_{CCLKMPWH}$	1.8		1.8		ns
Write clock minimum pulse width low	$T_{CCLKMPWL}$	1.8		1.8		ns
Write block setup time	T_{BLKCSU}	0.404		0.476		ns
Write block hold time	T_{BLKCHD}	0.007		0.008		ns
Write input data setup time	T_{DINCSU}	0.003		0.004		ns
Write input data hold time	T_{DINCHD}	0.137		0.161		ns
Write address setup time	$T_{ADDRCSU}$	0.088		0.104		ns
Write address hold time	$T_{ADDRCHD}$	0.247		0.29		ns
Write enable setup time	T_{WECSU}	0.397		0.467		ns
Write enable hold time	T_{WECHD}	–0.03		–0.03		ns
Maximum frequency	F_{MAX}		250		250	MHz

2.3.13 Programming Times

The following tables list the programming times in typical conditions when $T_J = 25\text{ }^{\circ}\text{C}$, $V_{DD} = 1.2\text{ V}$. External SPI flash part# AT25DF641-s3H is used during this measurement.

Table 244 • JTAG Programming (Fabric Only)

M2S/M2GL				
Device	Image size Bytes	Program	Verify	Unit
005	302672	22	10	Sec
010	568784	28	18	Sec
025	1223504	51	26	Sec
050	2424832	66	54	Sec
060	2418896	77	54	Sec
090	3645968	113	126	Sec
150	6139184	155	193	Sec

2.3.14 Math Block Timing Characteristics

The fundamental building block in any digital signal processing algorithm is the multiply-accumulate function. Each IGLOO2 and SmartFusion2 SoC math block supports 18×18 signed multiplication, dot product, and built-in addition, subtraction, and accumulation units to combine multiplication results efficiently. The following table lists the math blocks with all registers used in worst commercial-case conditions when $T_J = 85^\circ\text{C}$, $V_{DD} = 1.14\text{ V}$.

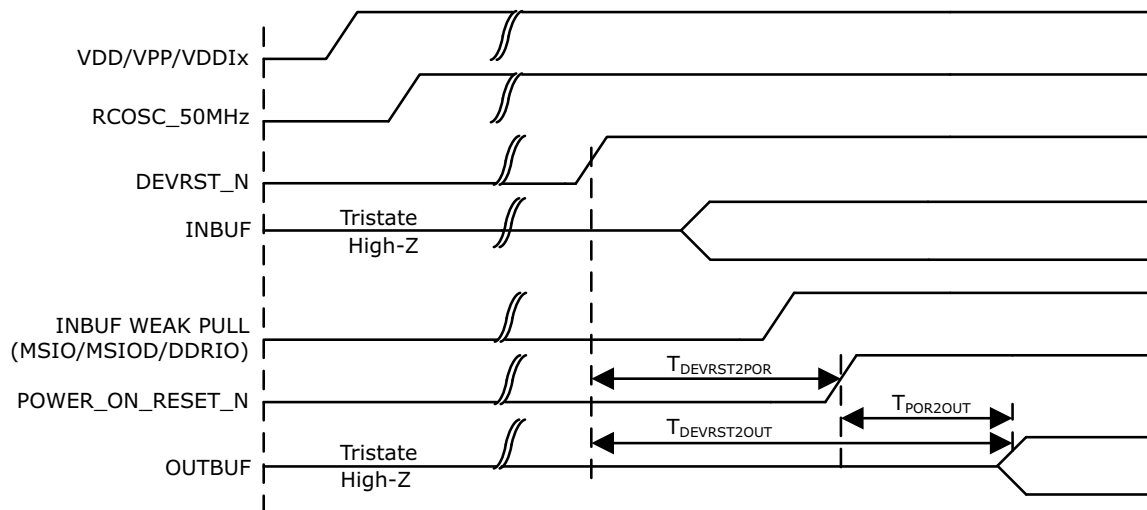
Table 268 • Math Blocks with all Registers Used

Parameter	Symbol	–1		–Std		Unit
		Min	Max	Min	Max	
Input, control register setup time	T_{MISU}	0.149		0.176		ns
Input, control register hold time	T_{MIHD}	1.68		1.976		ns
CDIN input setup time	$T_{MOCDINSU}$	0.185		0.218		ns
CDIN input hold time	$T_{MOCDINHHD}$	0.08		0.094		ns
Synchronous reset/enable setup time	$T_{MSRSTENSU}$	–0.419		–0.493		ns
Synchronous reset/enable hold time	$T_{MSRSTENHD}$	0.011		0.013		ns
Asynchronous reset removal time	$T_{MARSTREM}$	0		0		ns
Asynchronous reset recovery time	$T_{MARSTREC}$	0.088		0.104		ns
Output register clock to out delay	T_{MOCQ}		0.232		0.273	ns
CLK minimum period	T_{MCLKMP}	2.245		2.641		ns

The following table lists the math blocks with input bypassed and output registers used in worst commercial-case conditions when $T_J = 85^\circ\text{C}$, $V_{DD} = 1.14\text{ V}$.

Table 269 • Math Block with Input Bypassed and Output Registers Used

Parameter	Symbol	–1		–Std		Unit
		Min	Max	Min	Max	
Output register setup time	T_{MOSU}	2.294		2.699		ns
Output register hold time	T_{MOHD}	1.68		1.976		ns
CDIN input setup time	$T_{MOCDINSU}$	0.115		0.136		ns
CDIN input hold time	$T_{MOCDINHHD}$	–0.444		–0.522		ns
Synchronous reset/enable setup time	$T_{MSRSTENSU}$	–0.419		–0.493		ns
Synchronous reset/enable hold time	$T_{MSRSTENHD}$	0.011		0.013		ns
Asynchronous reset removal time	$T_{MARSTREM}$	0		0		ns
Asynchronous reset recovery time	$T_{MARSTREC}$	0.014		0.017		ns
Output register clock to out delay	T_{MOCQ}		0.232		0.273	ns
CLK minimum period	T_{MCLKMP}	2.179		2.563		ns

Figure 20 • DEVRST_N to Functional Timing Diagram for IGLOO2

2.3.27 Flash*Freeze Timing Characteristics

The following table lists the Flash*Freeze entry and exit times in worst-case industrial conditions when $T_J = 100^\circ\text{C}$, $V_{DD} = 1.14\text{ V}$.

Table 293 • Flash*Freeze Entry and Exit Times

Parameter	Symbol	Entry/Exit Timing FCLK = 100MHz		Entry/Exit Timing FCLK = 3 MHz		Unit	Conditions
		005, 010, 025, 060, 090, and 150	050	All Devices			
Entry time	TFF_ENTRY	160	150	320		μs	eNVM and MSS/HPMS PLL = ON
		215	200	430		μs	eNVM and MSS/HPMS PLL= OFF
Exit time with respect to the MSS PLL Lock	TFF_EXIT	100	100	140		μs	eNVM and MSS/HPMS PLL = ON during F*F
		136	120	190		μs	eNVM = ON and MSS/HPMS PLL = OFF during F*F and MSS/HPMS PLL turned back on at exit
		200	200	285		μs	eNVM and MSS/HPMS PLL = OFF during F*F and both are turned back on at exit
		200	200	285		μs	eNVM = OFF and MSS/HPMS PLL = ON during F*F and eNVM turned back on at exit

2.3.31.2 SmartFusion2 Inter-Integrated Circuit (I²C) Characteristics

This section describes the DC and switching of the I²C interface. Unless otherwise noted, all output characteristics given are for a 100 pF load on the pins. For timing parameter definitions, see Figure 21, page 125.

The following table lists the I²C characteristics in worst-case industrial conditions when $T_J = 100\text{ }^{\circ}\text{C}$, $V_{DD} = 1.14\text{ V}$

Table 303 • I²C Characteristics

Parameter	Symbol	Min	Typ	Max	Unit	Conditions
Input low voltage	V_{IL}	-0.3		0.8	V	See Single-Ended I/O Standards, page 24 for more information. I/O standard used for illustration: MSIO bank-LVTTL 8 mA low drive.
Input high voltage	V_{IH}	2		3.45	V	See Single-Ended I/O Standards, page 24 for more information. I/O standard used for illustration: MSIO bank-LVTTL 8 mA low drive.
Hysteresis of schmitt triggered inputs for $V_{DDI} > 2\text{ V}$	V_{HYS}	$0.05 \times V_{DDI}$			V	See Table 28, page 23 for more information.
Input current high	I_{IL}			10	μA	See Single-Ended I/O Standards, page 24 for more information.
Input current low	I_{IH}			10	μA	See Single-Ended I/O Standards, page 24 for more information.
Input rise time	T_{ir}			1000	ns	Standard mode
				300	ns	Fast mode
Input fall time	T_{if}			300	ns	Standard mode
				300	ns	Fast mode
Maximum output voltage low (open drain) at 3 mA sink current for $V_{DDI} > 2\text{ V}$	V_{OL}			0.4	V	See Single-Ended I/O Standards, page 24 for more information. I/O standard used for illustration: MSIO bank-LVTTL 8 mA low drive.
Pin capacitance	C_{in}			10	pF	$V_{IN} = 0$, $f = 1.0\text{ MHz}$
Output fall time from V_{IHMin} to V_{ILMax}^1	t_{OF}^1		21.04		ns	V_{IHmin} to V_{ILMax} , $C_{LOAD} = 400\text{ pF}$
			5.556		ns	V_{IHmin} to V_{ILMax} , $C_{LOAD} = 100\text{ pF}$
Output rise time from V_{ILMax} to V_{IHMin}^1	t_{OR}^1		19.887		ns	V_{ILMax} to V_{IHmin} , $C_{LOAD} = 400\text{ pF}$
			5.218		ns	V_{ILMax} to V_{IHmin} , $C_{LOAD} = 100\text{ pF}$
Output buffer maximum pull-down resistance ^{2, 3}	$R_{pull-up}^{2,3}$			50	Ω	
Output buffer maximum pull-up resistance ^{2, 4}	$R_{pull-down}^{2,4}$			131.25	Ω	