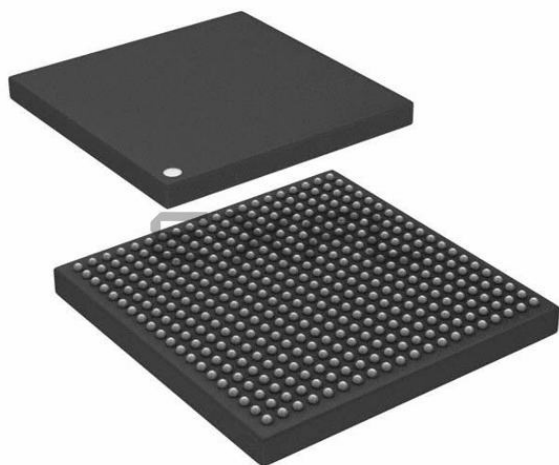




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Embedded - FPGAs, or Field Programmable Gate Arrays, are advanced integrated circuits that offer unparalleled flexibility and performance for digital systems. Unlike traditional fixed-function logic devices, FPGAs can be programmed and reprogrammed to execute a wide array of logical operations, enabling customized functionality tailored to specific applications. This reprogrammability allows developers to iterate designs quickly and implement complex functions without the need for custom hardware.

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Details

Product Status	Active
Number of LABs/CLBs	-
Number of Logic Elements/Cells	6060
Total RAM Bits	719872
Number of I/O	169
Number of Gates	-
Voltage - Supply	1.14V ~ 2.625V
Mounting Type	Surface Mount
Operating Temperature	0°C ~ 85°C (TJ)
Package / Case	400-LFBGA
Supplier Device Package	400-VFBGA (17x17)
Purchase URL	https://www.e-xfl.com/product-detail/microchip-technology/m2gl005s-vfg400

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1 Revision History

The revision history describes the changes that were implemented in the document. The changes are listed by revision, starting with the most current publication.

1.1 Revision 11.0

The following is a summary of the changes in revision 11.0 of this document.

- Updated Table 24, page 22 with minimum and maximum values for input current low and high (SAR 73114 and 80314).
- Added Non-Deterministic Random Bit Generator (NRBG) Characteristics, page 106 (SAR 73114 and 79517).
- Added 060 device in Table 282, page 110 (SAR 79860).
- Added DEVRST_N to Functional Times, page 116 (SAR 73114).
- Added Cryptographic Block Characteristics, page 106 (SAR 73114 and 79516).
- Update Table 296, page 121 with VTX-AMP details (SAR 81756).
- Update note in Table 297, page 122 (SAR 74570 and 80677).
- Update Table 298, page 122 with generic EPCS details (SAR 75307).
- Added Table 308, page 129 (SAR 50424).

1.2 Revision 10.0

The following is a summary of the changes in revision 10.0 of this document.

- The Surge Current on VDD during DEVRST_B Assertion and Surge Current on VDD during Digest Check using System Services tables were deleted and added reference to *AC393: Board Design Guidelines for SmartFusion2 SoC and IGLOO2 FPGAs Application Note*. (SAR 76865 and 76623).
- Added 060 device in Table 4, page 6 (SAR 76383).
- Updated Table 24, page 22 for ramp time input (SAR 72103).
- Added 060 device details in Table 284, page 112 (SAR 74927).
- Updated Table 290, page 116 for name change (SAR 74925).
- Updated Table 283, page 111 for 060 FG676 Package details (SAR 78849).
- Updated Table 305, page 126 for SmartFusion2 and Table 310, page 129 for IGLOO2 for SPI timing and Fmax (SAR 56645, 75331).
- Updated Table 293, page 119 for Flash*Freeze entry and exit times (SAR 75329, 75330).
- Updated Table 297, page 122 for RX-CID information (SAR 78271).
- Added Table 8, page 8 and Figure 1, page 9 (SAR 78932).
- Updated Table 223, page 76 for timing characteristics and Table 224, page 77 (SAR 75998).
- Added SRAM PUF, page 105 (SAR 64406).
- Added a footnote on digest cycle in Table 5, page 7 (SAR 79812).

1.3 Revision 9.0

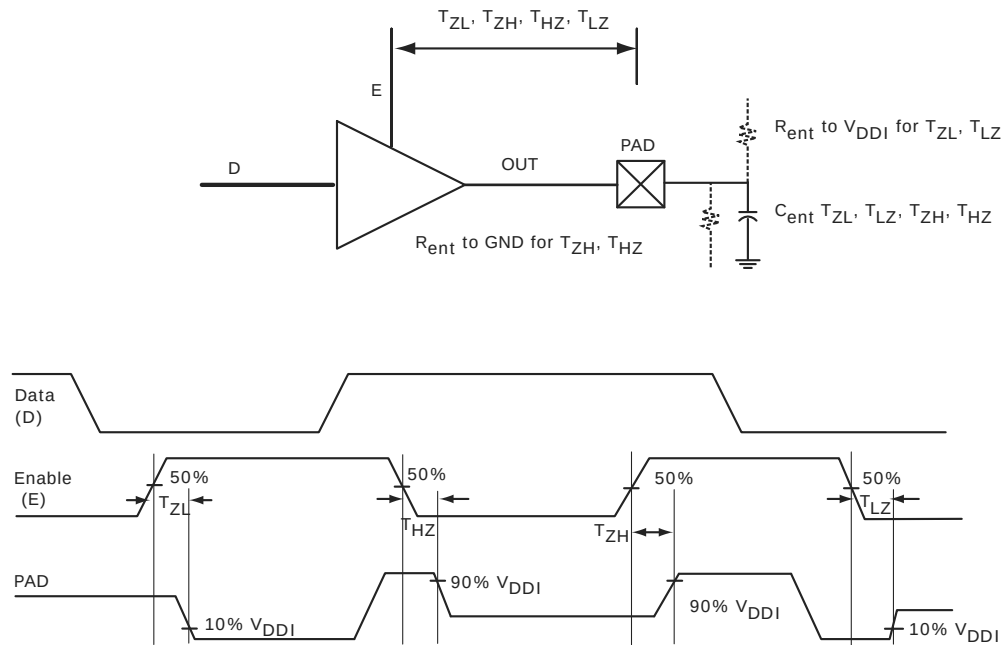
The following is a summary of the changes in revision 9.0 of this document.

- Added a note in Table 5, page 7 (SAR 71506).
- Added a note in Table 6, page 8 (SAR 74616).
- Added a note in Figure 3, page 17 (SAR 71506).
- Updated Quiescent Supply Current for 060 in Table 11, page 12 and Table 12, page 13 (SAR 74483).
- Updated programming currents for 060 in Table 13, page 13, Table 14, page 13, and Table 15, page 14.
- Added DEVRST_B assertion tables (SAR 74708).
- Updated I/O speeds for LVDS 3.3 V in Table 18, page 19 and Table 21, page 20 (SAR 69829).
- Updated Table 24, page 22 (SAR 69418).
- Updated Table 25, page 22, Table 26, page 23, Table 27, page 23 (SAR 74570).
- Updated all AC/DC table to link to the Input Capacitance, Leakage Current, and Ramp Time, page 22 for reference (SAR 69418).

2.3.5.3 Tristate Buffer and AC Loading

The tristate path for enable path loadings is described in the respective specifications. The following figure shows the methodology of characterization illustrated by the enable path test point.

Figure 5 • Tristate Buffer for Enable Path Test Point



2.3.5.4 I/O Speeds

This section describes the maximum data rate summary of I/O in worst-case industrial conditions. See the individual I/O standards for operating conditions.

Table 18 • Maximum Data Rate Summary Table for Single-Ended I/O in Worst-Case Industrial Conditions

I/O	MSIO	MSIOD	DDRIO	Unit
PCI 3.3 V	630			Mbps
LVTTL 3.3 V	600			Mbps
LVC MOS 3.3 V	600			Mbps
LVC MOS 2.5 V	410	420	400	Mbps
LVC MOS 1.8 V	295	400	400	Mbps
LVC MOS 1.5 V	160	220	235	Mbps
LVC MOS 1.2 V	120	160	200	Mbps
LPDDR-LVC MOS 1.8 V mode			400	Mbps

Table 22 • Maximum Frequency Summary Table for Voltage-Referenced I/O in Worst-Case Industrial Conditions

I/O	MSIO	MSIOD	DDRIO	Unit
LPDDR			200	MHz
HSTL1.5 V			200	MHz
SSTL 2.5 V	255	350	200	MHz
SSTL 1.8 V			334	MHz
SSTL 1.5 V			334	MHz

Table 23 • Maximum Frequency Summary Table for Differential I/O in Worst-Case Industrial Conditions

I/O	MSIO	MSIOD	Unit
LVPECL (input only)	450		MHz
LVDS 3.3 V	267.5		MHz
LVDS 2.5 V	267.5	350	MHz
RSDS	260	350	MHz
BLVDS	250		MHz
MLVDS	250		MHz
Mini-LVDS	260	350	MHz

Table 82 • LVCMOS 1.2 V Receiver Characteristics for MSIOD I/O Bank (Input Buffers)

On-Die Termination (ODT)	T_{PY}		T_{PYS}		Unit
	-1	-Std	-1	-Std	
None	4.154	4.887	4.114	4.84	ns
50	6.918	8.139	6.806	8.008	ns
75	5.613	6.603	5.533	6.509	ns
150	4.716	5.549	4.657	5.479	ns

Table 83 • LVCMOS 1.2 V Transmitter Characteristics for DDRIO I/O Bank (Output and Tristate Buffers)

Output Drive Selection	Slew Control	T_{DP}		T_{ZL}		T_{ZH}		T_{HZ}^1		T_{LZ}^1		Unit
		-1	-Std	-1	-Std	-1	-Std	-1	-Std	-1	-Std	
2 mA	Slow	6.713	7.897	5.362	6.308	6.723	7.909	7.233	8.51	6.375	7.499	ns
	Medium	5.912	6.955	4.616	5.43	5.915	6.959	6.887	8.102	6.009	7.069	ns
	Medium fast	5.5	6.469	4.231	4.978	5.5	6.471	6.672	7.849	5.835	6.865	ns
	Fast	5.462	6.426	4.194	4.935	5.463	6.427	6.646	7.819	5.828	6.857	ns
4 mA	Slow	6.109	7.186	4.708	5.539	6.098	7.174	8.005	9.418	7.033	8.274	ns
	Medium	5.355	6.299	4.034	4.746	5.338	6.28	7.637	8.985	6.672	7.849	ns
	Medium fast	4.953	5.826	3.685	4.336	4.932	5.802	7.44	8.752	6.499	7.646	ns
	Fast	4.911	5.777	3.658	4.303	4.89	5.754	7.427	8.737	6.488	7.632	ns
6 mA	Slow	5.89	6.929	4.506	5.301	5.874	6.911	8.337	9.808	7.315	8.605	ns
	Medium	5.176	6.089	3.862	4.543	5.155	6.065	7.986	9.394	6.943	8.168	ns
	Medium fast	4.792	5.637	3.523	4.145	4.765	5.606	7.808	9.186	6.775	7.97	ns
	Fast	4.754	5.593	3.486	4.101	4.728	5.563	7.777	9.149	6.769	7.963	ns

1. Delay increases with drive strength are inherent to built-in slew control circuitry for simultaneous switching output (SSO) management.

Table 84 • LVCMOS 1.2 V Transmitter Characteristics for MSIO I/O Bank (Output and Tristate Buffers)

Output Drive Selection	Slew Control	T_{DP}		T_{ZL}		T_{ZH}		T_{HZ}^1		T_{LZ}^1		Unit
		-1	-Std	-1	-Std	-1	-Std	-1	-Std	-1	-Std	
2 mA	Slow	6.746	7.937	7.458	8.774	8.172	9.614	9.867	11.608	8.393	9.874	ns
4 mA	Slow	7.068	8.315	6.678	7.857	7.474	8.793	10.986	12.924	9.043	10.638	ns

1. Delay increases with drive strength are inherent to built-in slew control circuitry for simultaneous switching output (SSO) management.

2.3.6.3 Stub-Series Terminated Logic 2.5 V (SSTL2)

SSTL2 Class I and Class II are supported in IGLOO2 and SmartFusion2 SoC FPGAs and also comply with reduced and full drive of double data rate (DDR) standards. IGLOO2 and SmartFusion2 SoC FPGA I/Os supports both standards for single-ended signaling and differential signaling for SSTL2. This standard requires a differential amplifier input buffer and a push-pull output buffer.

Minimum and Maximum DC/AC Input and Output Levels Specification

Table 103 • DDR1/SSTL2 DC Recommended Operating Conditions

Parameter	Symbol	Min	Typ	Max	Unit
Supply voltage	V_{DDI}	2.375	2.5	2.625	V
Termination voltage	V_{TT}	1.164	1.250	1.339	V
Input reference voltage	V_{REF}	1.164	1.250	1.339	V

Table 104 • DDR1/SSTL2 DC Input Voltage Specification

Parameter	Symbol	Min	Max	Unit
DC input logic high	V_{IH} (DC)	$V_{REF} + 0.15$	2.625	V
DC input logic low	V_{IL} (DC)	-0.3	$V_{REF} - 0.15$	V
Input current high ¹	I_{IH} (DC)			
Input current low ¹	I_{IL} (DC)			

1. See Table 24, page 22.

Table 105 • DDR1/SSTL2 DC Output Voltage Specification

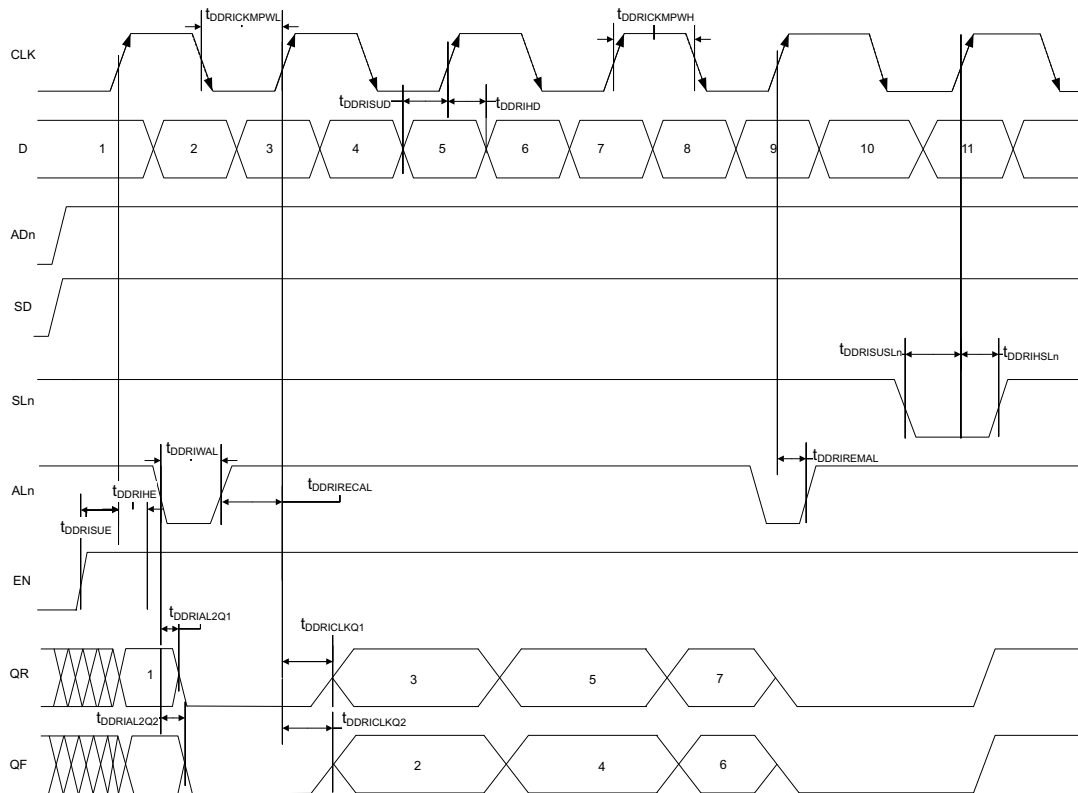
Parameter	Symbol	Min	Max	Unit
SSTL2 Class I (DDR Reduced Drive)				
DC output logic high	V_{OH}	$V_{TT} + 0.608$		V
DC output logic low	V_{OL}		$V_{TT} - 0.608$	V
Output minimum source DC current	I_{OH} at V_{OH}	8.1		mA
Output minimum sink current	I_{OL} at V_{OL}	-8.1		mA
SSTL2 Class II (DDR Full Drive) – Applicable to MSIO and DDRIO I/O Bank Only				
DC output logic high	V_{OH}	$V_{TT} + 0.81$		V
DC output logic low	V_{OL}		$V_{TT} - 0.81$	V
Output minimum source DC current	I_{OH} at V_{OH}	16.2		mA
Output minimum sink current	I_{OL} at V_{OL}	-16.2		mA

Table 106 • DDR1/SSTL2 DC Differential Voltage Specification

Parameter	Symbol	Min	Unit
DC input differential voltage	V_{ID} (DC)	0.3	V

2.3.9.2 Input DDR Timing Diagram

Figure 11 • Input DDR Timing Diagram



2.3.9.3 Timing Characteristics

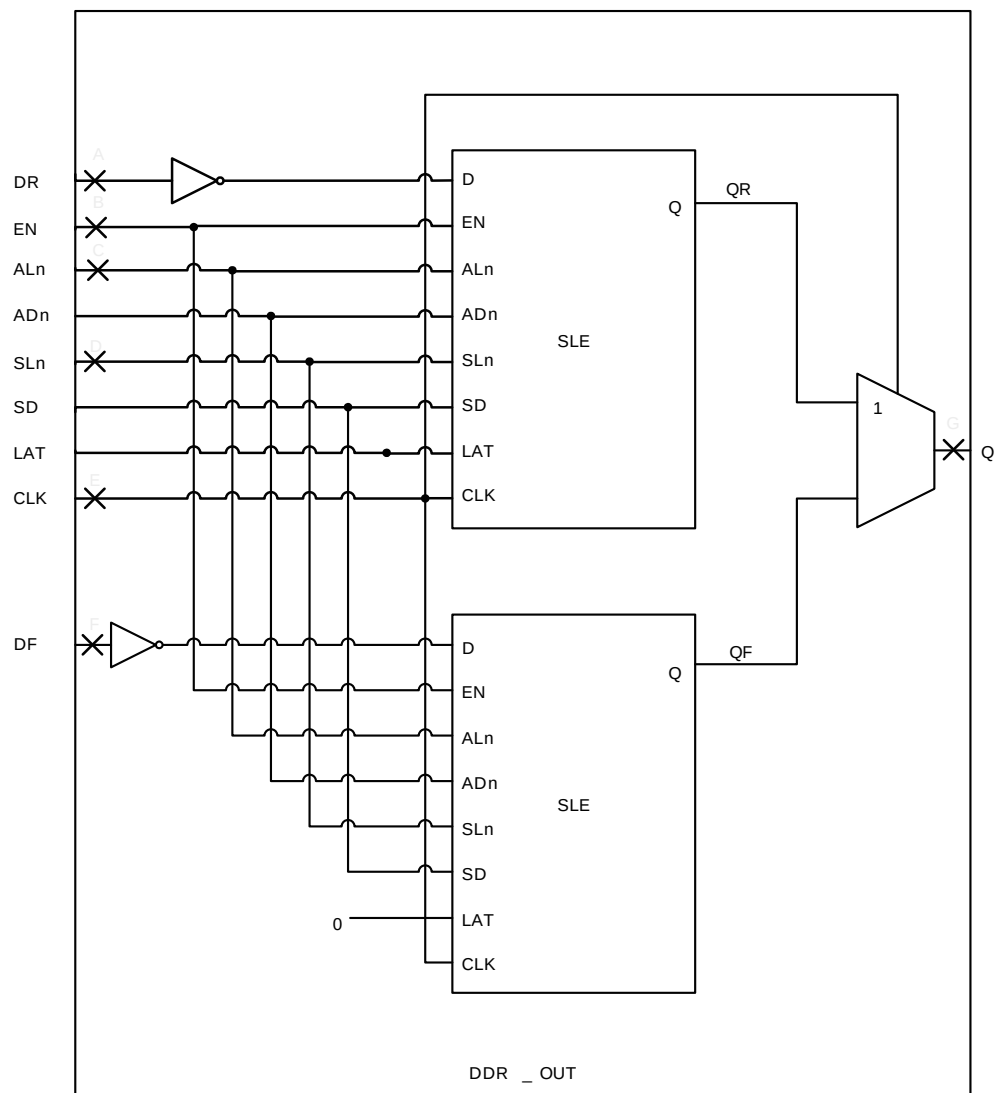
The following table lists the input DDR propagation delays in worst commercial-case conditions when $T_J = 85^\circ\text{C}$, $V_{DD} = 1.14\text{ V}$.

Table 221 • Input DDR Propagation Delays

Symbol	Description	Measuring Nodes (from, to)	-1	-Std	Unit
$T_{DDRICKQ1}$	Clock-to-Out Out_QR for input DDR	B, C	0.16	0.188	ns
$T_{DDRICKQ2}$	Clock-to-Out Out_QF for input DDR	B, D	0.166	0.195	ns
$T_{DDRISUD}$	Data setup for input DDR	A, B	0.357	0.421	ns
T_{DDRIHD}	Data hold for input DDR	A, B	0	0	ns
$T_{DDRISUE}$	Enable setup for input DDR	E, B	0.46	0.542	ns
T_{DDRIHE}	Enable hold for input DDR	E, B	0	0	ns
$T_{DDRISUSLn}$	Synchronous load setup for input DDR	G, B	0.46	0.542	ns
$T_{DDRIHSLn}$	Synchronous load hold for input DDR	G, B	0	0	ns
$T_{DDRIAL2Q1}$	Asynchronous load-to-out QR for input DDR	F, C	0.587	0.69	ns
$T_{DDRIAL2Q2}$	Asynchronous load-to-out QF for input DDR	F, D	0.541	0.636	ns
$T_{DDRIREMAL}$	Asynchronous load removal time for input DDR	F, B	0	0	ns
$T_{DDRIRECAL}$	Asynchronous load recovery time for input DDR	F, B	0.074	0.087	ns

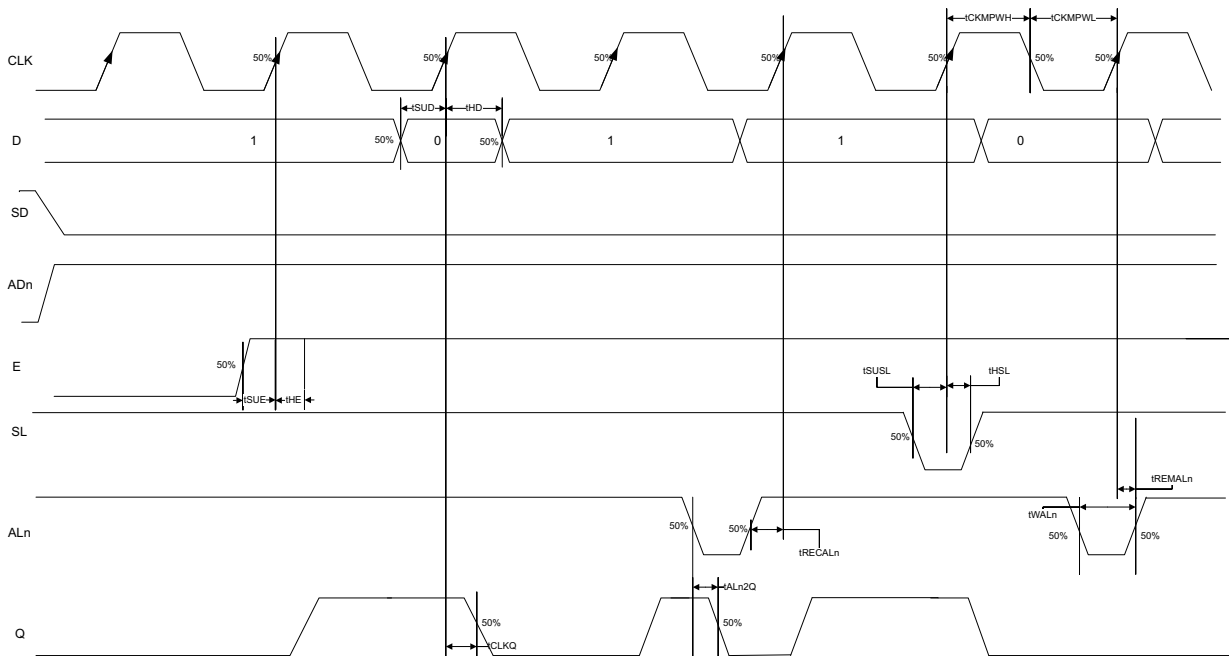
2.3.9.4 Output DDR Module

Figure 12 • Output DDR Module



The following figure shows a configuration with SD = 0 (synchronous clear) and ADn = 1 (asynchronous clear) for a flip-flop (LAT = 0).

Figure 16 • Sequential Module Timing Diagram



2.3.10.3.1 Timing Characteristics

The following table lists the register delays in worst commercial-case conditions when $T_J = 85^\circ\text{C}$, $V_{DD} = 1.14\text{ V}$.

Table 224 • Register Delays

Parameter	Symbol	-1	-Std	Unit
Clock-to-Q of the core register	T_{CLKQ}	0.108	0.127	ns
Data setup time for the core register	T_{SUD}	0.254	0.298	ns
Data hold time for the core register	T_{HD}	0	0	ns
Enable setup time for the core register	T_{SUE}	0.335	0.394	ns
Enable hold time for the core register	T_{HE}	0	0	ns
Synchronous load setup time for the core register	T_{SUSL}	0.335	0.394	ns
Synchronous load hold time for the core register	T_{HSL}	0	0	ns
Asynchronous Clear-to-Q of the core register (ADn = 1)	T_{ALn2Q}	0.473	0.556	ns
Asynchronous preset-to-Q of the core register (ADn = 0)		0.451	0.531	ns
Asynchronous load removal time for the core register	T_{REMAIn}	0	0	ns
Asynchronous load recovery time for the core register	T_{RECALn}	0.353	0.415	ns
Asynchronous load minimum pulse width for the core register	T_{WALn}	0.266	0.313	ns
Clock minimum pulse width high for the core register	T_{CKMPWH}	0.065	0.077	ns
Clock minimum pulse width low for the core register	T_{CKMPWL}	0.139	0.164	ns

2.3.11 Global Resource Characteristics

The IGLOO2 and SmartFusion2 SoC FPGA devices offer a powerful, low skew global routing network which provides an effective clock distribution throughout the FPGA fabric. See *UG0445: IGLOO2 FPGA and SmartFusion2 SoC FPGA Fabric User Guide* for the positions of various global routing resources.

The following table lists the 150 device global resources in worst commercial-case conditions when $T_J = 85^\circ\text{C}$, $V_{DD} = 1.14\text{ V}$.

Table 225 • 150 Device Global Resource

Parameter	Symbol	–1		–Std		Unit
		Min	Max	Min	Max	
Input low delay for global clock	T_{RCKL}	0.83	0.911	0.831	0.913	ns
Input high delay for global clock	T_{RCKH}	1.457	1.588	1.715	1.869	ns
Maximum skew for global clock	T_{RCKSW}		0.131		0.154	ns

The following table lists the 090 device global resources in worst commercial-case conditions when $T_J = 85^\circ\text{C}$, $V_{DD} = 1.14\text{ V}$.

Table 226 • 090 Device Global Resource

Parameter	Symbol	–1		–Std		Unit
		Min	Max	Min	Max	
Input low delay for global clock	T_{RCKL}	0.835	0.888	0.833	0.886	ns
Input high delay for global clock	T_{RCKH}	1.405	1.489	1.654	1.752	ns
Maximum skew for global clock	T_{RCKSW}		0.084		0.098	ns

The following table lists the 050 device global resources in worst commercial-case conditions when $T_J = 85^\circ\text{C}$, $V_{DD} = 1.14\text{ V}$.

Table 227 • 050 Device Global Resource

Parameter	Symbol	–1		–Std		Unit
		Min	Max	Min	Max	
Input low delay for global clock	T_{RCKL}	0.827	0.897	0.826	0.896	ns
Input high delay for global clock	T_{RCKH}	1.419	1.53	1.671	1.8	ns
Maximum skew for global clock	T_{RCKSW}		0.111		0.129	ns

The following table lists the 025 device global resources in worst commercial-case conditions when $T_J = 85^\circ\text{C}$, $V_{DD} = 1.14\text{ V}$.

Table 228 • 025 Device Global Resource

Parameter	Symbol	–1		–Std		Unit
		Min	Max	Min	Max	
Input low delay for global clock	T_{RCKL}	0.747	0.799	0.745	0.797	ns
Input high delay for global clock	T_{RCKH}	1.294	1.378	1.522	1.621	ns
Maximum skew for global clock	T_{RCKSW}		0.084		0.099	ns

Table 240 • μ SRAM (RAM128x8) in 128 × 8 Mode (continued)

Parameter	Symbol	–1		–Std		Unit
		Min	Max	Min	Max	
Read address hold time in synchronous mode	T_{ADDRHD}	0.091		0.107		ns
Read address hold time in asynchronous mode		–0.778		–0.915		ns
Read enable setup time	T_{RDENSU}	0.278		0.327		ns
Read enable hold time	T_{RDENHD}	0.057		0.067		ns
Read block select setup time	T_{BLKSU}	1.839		2.163		ns
Read block select hold time	T_{BLKHD}	–0.65		–0.765		ns
Read block select to out disable time (when pipelined register is disabled)	T_{BLK2Q}		2.036		2.396	ns
Read asynchronous reset removal time (pipelined clock)	T_{RSTREM}	–0.023		–0.027		ns
Read asynchronous reset removal time (non-pipelined clock)		0.046		0.054		ns
Read asynchronous reset recovery time (pipelined clock)	T_{RSTREC}	0.507		0.597		ns
Read asynchronous reset recovery time (non-pipelined clock)		0.236		0.278		ns
Read asynchronous reset to output propagation delay (with pipelined register enabled)	T_{R2Q}		0.835		0.982	ns
Read synchronous reset setup time	T_{SRSTSU}	0.271		0.319		ns
Read synchronous reset hold time	T_{SRSTHD}	0.061		0.071		ns
Write clock period	T_{CCY}	4		4		ns
Write clock minimum pulse width high	$T_{CCLKMPWH}$	1.8		1.8		ns
Write clock minimum pulse width low	$T_{CCLKMPWL}$	1.8		1.8		ns
Write block setup time	T_{BLKCSU}	0.404		0.476		ns
Write block hold time	T_{BLKCHD}	0.007		0.008		ns
Write input data setup time	T_{DINCSU}	0.115		0.135		ns
Write input data hold time	T_{DINCHD}	0.15		0.177		ns
Write address setup time	$T_{ADDRCSU}$	0.088		0.104		ns
Write address hold time	$T_{ADDRCHD}$	0.128		0.15		ns
Write enable setup time	T_{WECSU}	0.397		0.467		ns
Write enable hold time	T_{WECHD}	–0.026		–0.03		ns
Maximum frequency	F_{MAX}		250		250	MHz

The following table lists the μ SRAM in 256×4 mode in worst commercial-case conditions when $T_J = 85^\circ\text{C}$, $V_{DD} = 1.14\text{ V}$.

Table 241 • μ SRAM (RAM256x4) in 256×4 Mode

Parameter	Symbol	-1		-Std		Unit
		Min	Max	Min	Max	
Read clock period	T_{CY}	4		4		ns
Read clock minimum pulse width high	$T_{CLKMPWH}$	1.8		1.8		ns
Read clock minimum pulse width low	$T_{CLKMPWL}$	1.8		1.8		ns
Read pipeline clock period	T_{PLCY}	4		4		ns
Read pipeline clock minimum pulse width high	$T_{PLCLKMPWH}$	1.8		1.8		ns
Read pipeline clock minimum pulse width low	$T_{PLCLKMPWL}$	1.8		1.8		ns
Read access time with pipeline register	T_{CLK2Q}		0.27		0.31	ns
Read access time without pipeline register			1.75		2.06	ns
Read address setup time in synchronous mode	T_{ADDRSU}	0.301		0.354		ns
Read address setup time in asynchronous mode		1.931		2.272		ns
Read address hold time in synchronous mode	T_{ADDRHD}	0.121		0.142		ns
Read address hold time in asynchronous mode		-0.65		-0.76		ns
Read enable setup time	T_{RDENSU}	0.278		0.327		ns
Read enable hold time	T_{RDENHD}	0.057		0.067		ns
Read block select setup time	T_{BLKSU}	1.839		2.163		ns
Read block select hold time	T_{BLKHD}	-0.65		-0.77		ns
Read block select to out disable time (when pipelined register is disabled)	T_{BLK2Q}		2.09		2.46	ns
Read asynchronous reset removal time (pipelined clock)	T_{RSTREM}	-0.02		-0.03		ns
Read asynchronous reset removal time (non-pipelined clock)		0.046		0.054		ns
Read asynchronous reset recovery time (pipelined clock)	T_{RSTREC}	0.507		0.597		ns
Read asynchronous reset recovery time (non-pipelined clock)		0.236		0.278		ns
Read asynchronous reset to output propagation delay (with pipelined register enabled)	T_{R2Q}		0.83		0.98	ns
Read synchronous reset setup time	T_{SRSTSU}	0.271		0.319		ns
Read synchronous reset hold time	T_{SRSTHD}	0.061		0.071		ns
Write clock period	T_{CCY}	4		4		ns
Write clock minimum pulse width high	$T_{CCLKMPWH}$	1.8		1.8		ns
Write clock minimum pulse width low	$T_{CCLKMPWL}$	1.8		1.8		ns
Write block setup time	T_{BLKCSU}	0.404		0.476		ns
Write block hold time	T_{BLKCHD}	0.007		0.008		ns
Write input data setup time	T_{DINCSU}	0.101		0.118		ns
Write input data hold time	T_{DINCHD}	0.137		0.161		ns
Write address setup time	$T_{ADDRCSU}$	0.088		0.104		ns

Table 248 • 2 Step IAP Programming (eNVM Only)

M2S/M2GL Device	Image size Bytes	Authenticate	Program	Verify	Unit
005	137536	2	37	5	Sec
010	274816	4	76	11	Sec
025	274816	4	78	10	Sec
050	278528	3	85	9	Sec
060	268480	5	76	22	Sec
090	544496	10	152	43	Sec
150	544496	10	153	44	Sec

Table 249 • 2 Step IAP Programming (Fabric and eNVM)

M2S/M2GL Device	Image size Bytes	Authenticate	Program	Verify	Unit
005	439296	6	56	11	Sec
010	842688	11	100	21	Sec
025	1497408	19	113	32	Sec
050	2695168	32	136	48	Sec
060	2686464	43	137	70	Sec
090	4190208	68	236	115	Sec
150	6682768	109	286	162	Sec

Table 250 • SmartFusion2 Cortex-M3 ISP Programming (Fabric Only)

M2S/M2GL Device	Image size Bytes	Authenticate	Program	Verify	Unit
005	302672	6	19	8	Sec
010	568784	10	26	14	Sec
025	1223504	21	39	29	Sec
050	2424832	39	60	50	Sec
060	2418896	44	65	54	Sec
090	3645968	66	90	79	Sec
150	6139184	108	140	128	Sec

Table 251 • SmartFusion2 Cortex-M3 ISP Programming (eNVM Only)

M2S/M2GL Device	Image size Bytes	Authenticate	Program	Verify	Unit
005	137536	3	42	4	Sec
010	274816	4	82	7	Sec
025	274816	4	82	8	Sec
050	278528	4	80	8	Sec
060	268480	6	80	8	Sec
090	544496	10	157	15	Sec

Table 251 • SmartFusion2 Cortex-M3 ISP Programming (eNVM Only) (continued)

M2S/M2GL Device	Image size Bytes	Authenticate	Program	Verify	Unit
150	544496	10	158	15	Sec

Table 252 • SmartFusion2 Cortex-M3 ISP Programming (Fabric and eNVM)

M2S/M2GL Device	Image size Bytes	Authenticate	Program	Verify	Unit
005	439296	9	61	11	Sec
010	842688	15	107	21	Sec
025	1497408	26	121	35	Sec
050	2695168	43	141	55	Sec
060	2686464	48	143	60	Sec
090	4190208	75	244	91	Sec
150	6682768	117	296	141	Sec

Table 253 • Programming Times with 100 kHz, 25 MHz, and 12.5 MHz SPI Clock Rates (Fabric Only)

M2S/M2GL Device	Auto Programming	Auto Update	Programming Recovery	Unit
	100 kHz	25 MHz	12.5 MHz	
005	47	27	28	Sec
010	77	35	35	Sec
025	150	42	41	Sec
050	33 ¹	Not Supported	Not Supported	Sec
060	291	83	82	Sec
090	427	109	108	Sec
150	708	157	160	Sec

1. Auto Programming in 050 device is done through SC_SPI, and SPI CLK is set to 6.25 MHz.

Table 254 • Programming Times with 100 kHz, 25 MHz, and 12.5 MHz SPI Clock Rates (eNVM Only)

M2S/M2GL Device	Auto Programming	Auto Update	Programming Recovery	Unit
	100 kHz	25 MHz	12.5 MHz	
005	41	48	49	Sec
010	86	87	87	Sec
025	87	85	86	Sec
050	85	Not Supported	Not Supported	Sec
060	78	86	86	Sec
090	154	162	162	Sec

The following table lists the programming times in worst-case conditions when $T_J = 100\text{ }^{\circ}\text{C}$, $V_{DD} = 1.14\text{ V}$. External SPI flash part# AT25DF641-s3H is used during this measurement.

Table 256 • JTAG Programming (Fabric Only)

M2S/M2GL Device	Image size		Program	Verify	Unit
	Bytes				
005	302672	44	10		Sec
010	568784	50	18		Sec
025	1223504	73	26		Sec
050	2424832	88	54		Sec
060	2418896	99	54		Sec
090	3645968	135	126		Sec
150	6139184	177	193		Sec

Table 257 • JTAG Programming (eNVM Only)

M2S/M2GL Device	Image size		Program	Verify	Unit
	Bytes				
005	137536	61	4		Sec
010	274816	100	9		Sec
025	274816	100	9		Sec
050	2,78,528	106	8		Sec
060	268480	98	8		Sec
090	544496	176	15		Sec
150	544496	177	15		Sec

Table 258 • JTAG Programming (Fabric and eNVM)

M2S/M2GL Device	Image size		Program	Verify	Unit
	Bytes				
005	439296	71	11		Sec
010	842688	129	20		Sec
025	1497408	142	35		Sec
050	2695168	184	59		Sec
060	2686464	180	70		Sec
090	4190208	288	147		Sec
150	6682768	338	231		Sec

2.3.14 Math Block Timing Characteristics

The fundamental building block in any digital signal processing algorithm is the multiply-accumulate function. Each IGLOO2 and SmartFusion2 SoC math block supports 18×18 signed multiplication, dot product, and built-in addition, subtraction, and accumulation units to combine multiplication results efficiently. The following table lists the math blocks with all registers used in worst commercial-case conditions when $T_J = 85^\circ\text{C}$, $V_{DD} = 1.14\text{ V}$.

Table 268 • Math Blocks with all Registers Used

Parameter	Symbol	–1		–Std		Unit
		Min	Max	Min	Max	
Input, control register setup time	T_{MISU}	0.149		0.176		ns
Input, control register hold time	T_{MIHD}	1.68		1.976		ns
CDIN input setup time	$T_{MOCDINSU}$	0.185		0.218		ns
CDIN input hold time	$T_{MOCDINHHD}$	0.08		0.094		ns
Synchronous reset/enable setup time	$T_{MSRSTENSU}$	–0.419		–0.493		ns
Synchronous reset/enable hold time	$T_{MSRSTENHD}$	0.011		0.013		ns
Asynchronous reset removal time	$T_{MARSTREM}$	0		0		ns
Asynchronous reset recovery time	$T_{MARSTREC}$	0.088		0.104		ns
Output register clock to out delay	T_{MOCQ}		0.232		0.273	ns
CLK minimum period	T_{MCLKMP}	2.245		2.641		ns

The following table lists the math blocks with input bypassed and output registers used in worst commercial-case conditions when $T_J = 85^\circ\text{C}$, $V_{DD} = 1.14\text{ V}$.

Table 269 • Math Block with Input Bypassed and Output Registers Used

Parameter	Symbol	–1		–Std		Unit
		Min	Max	Min	Max	
Output register setup time	T_{MOSU}	2.294		2.699		ns
Output register hold time	T_{MOHD}	1.68		1.976		ns
CDIN input setup time	$T_{MOCDINSU}$	0.115		0.136		ns
CDIN input hold time	$T_{MOCDINHHD}$	–0.444		–0.522		ns
Synchronous reset/enable setup time	$T_{MSRSTENSU}$	–0.419		–0.493		ns
Synchronous reset/enable hold time	$T_{MSRSTENHD}$	0.011		0.013		ns
Asynchronous reset removal time	$T_{MARSTREM}$	0		0		ns
Asynchronous reset recovery time	$T_{MARSTREC}$	0.014		0.017		ns
Output register clock to out delay	T_{MOCQ}		0.232		0.273	ns
CLK minimum period	T_{MCLKMP}	2.179		2.563		ns

Table 277 • Electrical Characteristics of the Crystal Oscillator – High Gain Mode (20 MHz) (continued)

Parameter	Symbol	Min	Typ	Max	Unit	Condition
Startup time (with regard to stable oscillator output)	SUXTAL			0.8	ms	005, 010, 025, and 050 devices
				1.0	ms	090 and 150 devices

Table 278 • Electrical Characteristics of the Crystal Oscillator – Medium Gain Mode (2 MHz)

Parameter	Symbol	Min	Typ	Max	Unit	Condition
Operating frequency	FXTAL		2		MHz	
Accuracy	ACCXTAL			0.00105	%	050 devices
				0.003	%	005, 010, 025, 090, and 150 devices
				0.004	%	060 devices
Output duty cycle	CYCXTAL		49–51	47–53	%	
Output period jitter (peak to peak)	JITPERXTAL		1	5	ns	
Output cycle to cycle jitter (peak to peak)	JITCYCXTAL		1	5	ns	
Operating current	IDYNXTAL		0.3		mA	
Input logic level high	VIHXTAL	0.9 V _{PP}			V	
Input logic level low	VILXTAL			0.1 V _{PP}	V	
Startup time (with regard to stable oscillator output)	SUXTAL			4.5	ms	010 and 050 devices
				5	ms	005 and 025 devices
				7	ms	090 and 150 devices

Table 279 • Electrical Characteristics of the Crystal Oscillator – Low Gain Mode (32 kHz)

Parameter	Symbol	Min	Typ	Max	Unit	Condition
Operating frequency	FXTAL		32		kHz	
Accuracy	ACCXTAL			0.004	%	005, 010, 025, 050, 060, and 090 devices
				0.005	%	150 devices
Output duty cycle	CYCXTAL		49–51	47–53	%	
Output period jitter (peak to peak)	JITPERXTAL		150	300	ns	
Output cycle to cycle jitter (peak to peak)	JITCYCXTAL		150	300	ns	
Operating current	IDYNXTAL		0.044		mA	010 and 050 devices
			0.060		mA	005, 025, 060, 090, and 150 devices
Input logic level high	VIHXTAL	0.9 V _{PP}			V	
Input logic level low	VILXTAL			0.1 V _{PP}	V	
Startup time (with regard to stable oscillator output)	SUXTAL			115	ms	005, 025, 050, 090, and 150 devices
				126	ms	010 devices

Table 291 • DEVRST_N to Functional Times for SmartFusion2 (continued)

Symbol	From	To	Description	Maximum Power-up to Functional Time for SmartFusion2 (uS)						
				005	010	025	050	060	090	150
$T_{\text{DEVRST2POR}}$	DEVRST_N	POWER_ON_RESET_N	V_{DD} at its minimum threshold level to fabric	233	289	216	213	237	234	219
$T_{\text{DEVRST2MSSRST}}$	DEVRST_N	MSS_RESET_N_M2F	V_{DD} at its minimum threshold level to MSS	702	765	712	688	636	630	866
$T_{\text{DEVRST2WPU}}$	DEVRST_N	DDRIO Inbuf weak pull	DEVRST_N to Inbuf weak pull	208	202	197	193	216	215	215
	DEVRST_N	MSIO Inbuf weak pull	DEVRST_N to Inbuf weak pull	208	202	197	193	216	215	215
	DEVRST_N	MSIOD Inbuf weak pull	DEVRST_N to Inbuf weak pull	208	202	197	193	216	215	215

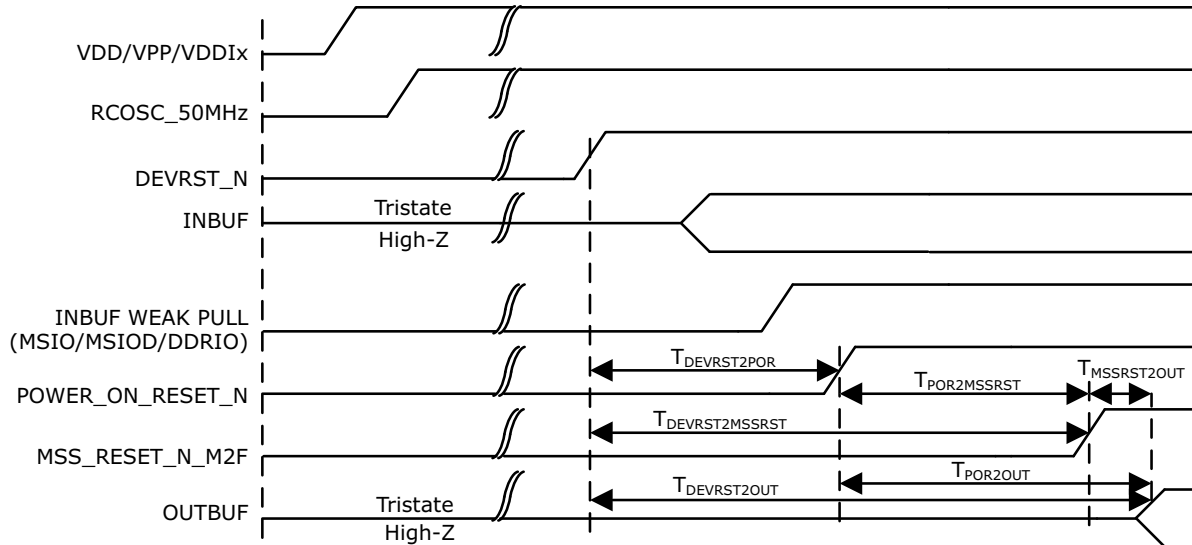
Figure 19 • DEVRST_N to Functional Timing Diagram for SmartFusion2

Table 310 • SPI Characteristics for All Devices (continued)

Symbol	Description	Min	Typ	Max	Unit	Conditions
SPI master configuration (applicable for 060, 090, and 150 devices)						
sp6m	SPI_[0 1]_DO setup time ²	$(\text{SPI_x_CLK_period}/2) - 7.0$			ns	
sp7m	SPI_[0 1]_DO hold time ²	$(\text{SPI_x_CLK_period}/2) - 9.5$			ns	
sp8m	SPI_[0 1]_DI setup time ²	15			ns	
sp9m	SPI_[0 1]_DI hold time ²	-2.5			ns	
SPI slave configuration (applicable for 060, 090, and 150 devices)						
sp6s	SPI_[0 1]_DO setup time ²	$(\text{SPI_x_CLK_period}/2) - 16.0$			ns	
sp7s	SPI_[0 1]_DO hold time ²	$(\text{SPI_x_CLK_period}/2) - 3.5$			ns	
sp8s	SPI_[0 1]_DI setup time ²	3			ns	
sp9s	SPI_[0 1]_DI hold time ²	2.5			ns	

- For specific Rise/Fall Times board design considerations and detailed output buffer resistances, use the corresponding IBIS models located on the Microsemi SoC Products Group website: <http://www.microsemi.com/soc/download/ibis/default.aspx>.
- For allowable pclk configurations, see the Serial Peripheral Interface Controller section in the *UG0331: SmartFusion2 Microcontroller Subsystem User Guide*.

Figure 23 • SPI Timing for a Single Frame Transfer in Motorola Mode (SPH = 1)