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Understanding Embedded - FPGAs (Field Programmable Gate Array)

Embedded - FPGAs, or Field Programmable Gate Arrays, are advanced integrated circuits that offer unparalleled flexibility and performance for digital systems. Unlike traditional fixed-function logic devices, FPGAs can be programmed and reprogrammed to execute a wide array of logical operations, enabling customized functionality tailored to specific applications. This reprogrammability allows developers to iterate designs quickly and implement complex functions without the need for custom hardware.

Applications of Embedded - FPGAs

The versatility of Embedded - FPGAs makes them indispensable in numerous fields. In telecommunications.

Details

Product Status	Obsolete
Number of LABs/CLBs	-
Number of Logic Elements/Cells	12084
Total RAM Bits	933888
Number of I/O	84
Number of Gates	-
Voltage - Supply	1.14V ~ 2.625V
Mounting Type	Surface Mount
Operating Temperature	0°C ~ 85°C (TJ)
Package / Case	144-LQFP
Supplier Device Package	144-TQFP (20x20)
Purchase URL	https://www.e-xfl.com/product-detail/microchip-technology/m2gl010-tq144



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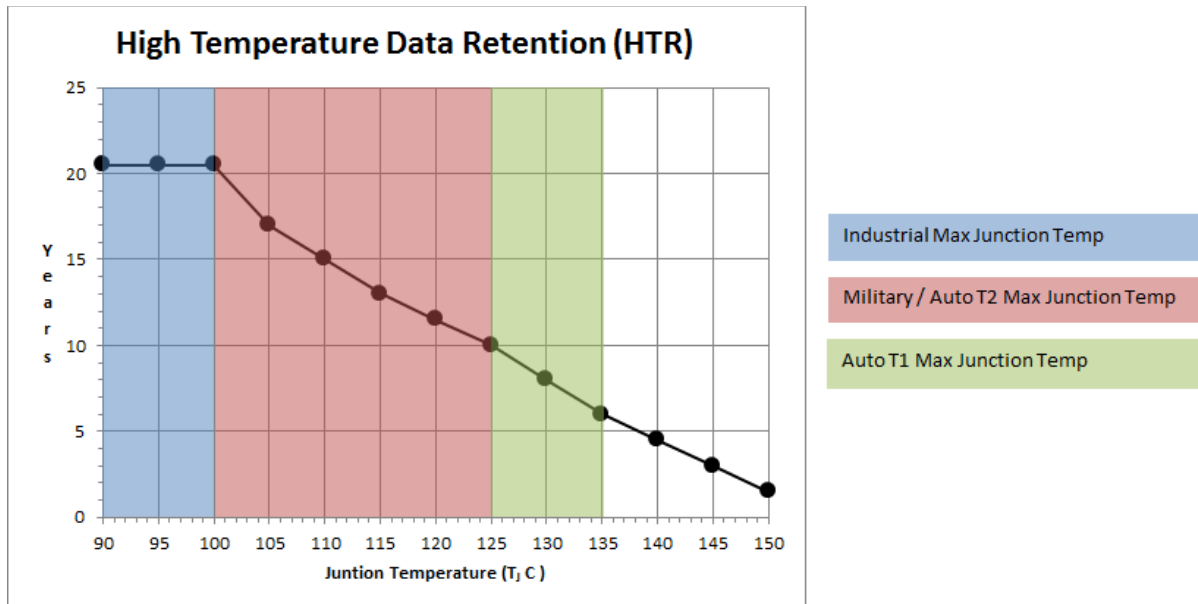
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Figure 1 • High Temperature Data Retention (HTR)

2.3.1.1 Overshoot/Undershoot Limits

For AC signals, the input signal may undershoot during transitions to -1.0 V for no longer than 10% of the period. The current during the transition must not exceed 100 mA.

For AC signals, the input signal may overshoot during transitions to $V_{CCI} + 1.0$ V for no longer than 10% of the period. The current during the transition must not exceed 100 mA.

Note: The above specifications do not apply to the PCI standard. The IGLOO2 and SmartFusion2 PCI I/Os are compliant with the PCI standard including the PCI overshoot/undershoot specifications.

2.3.1.2 Thermal Characteristics

The temperature variable in the Microsemi SoC Products Group Designer software refers to the junction temperature, not the ambient, case, or board temperatures. This is an important distinction because dynamic and static power consumption causes the chip's junction temperature to be higher than the ambient, case, or board temperatures.

EQ1 through EQ3 give the relationship between thermal resistance, temperature gradient, and power.

$$\theta_{JA} = \frac{T_J - T_A}{P} \quad \text{EQ 1}$$

$$\theta_{JB} = \frac{T_J - T_B}{P} \quad \text{EQ 2}$$

$$\theta_{JC} = \frac{T_J - T_C}{P} \quad \text{EQ 3}$$

Table 77 • LVCMOS 1.2 V AC Calibrated Impedance Option

Parameter	Symbol	Typ	Unit
Supported output driver calibrated impedance (for DDRIO I/O bank)	RODT_CAL	75, 60, 50, 40	Ω

Table 78 • LVCMOS 1.2 V AC Test Parameter Specifications

Parameter	Symbol	Typ	Unit
Measuring/trip point	V_{TRIP}	0.6	V
Resistance for enable path (T_{ZH} , T_{ZL} , T_{HZ} , T_{LZ})	R_{ENT}	2K	Ω
Capacitive loading for enable path (T_{ZH} , T_{ZL} , T_{HZ} , T_{LZ})	C_{ENT}	5	pF
Capacitive loading for data path (T_{DP})	C_{LOAD}	5	pF

Table 79 • LVCMOS 1.2 V Transmitter Drive Strength Specifications

Output Drive Selection			V_{OH} (V)	V_{OL} (V)	IOH (at V_{OH}) mA	IOL (at V_{OL}) mA
MSIO I/O Bank	MSIOD I/O Bank	DDRIO I/O Bank	Min	Max		
2 mA	2 mA	2 mA	$V_{DDI} \times 0.75$	$V_{DDI} \times 0.25$	2	2
4 mA	4 mA	4 mA	$V_{DDI} \times 0.75$	$V_{DDI} \times 0.25$	4	4
		6 mA	$V_{DDI} \times 0.75$	$V_{DDI} \times 0.25$	6	6

Note: For a detailed I/V curve, use the corresponding IBIS models:

www.microsemi.com/soc/download/ibis/default.aspx.

AC Switching Characteristics

Worst commercial-case conditions: $T_J = 85^\circ\text{C}$, $V_{DD} = 1.14\text{ V}$, $V_{DDI} = 1.14\text{ V}$

Table 80 • LVCMOS 1.2 V Receiver Characteristics for DDRIO I/O Bank with Fixed Code (Input Buffers)

On-Die Termination (ODT)	T_{PY}		T_{PYS}		Unit
	-1	-Std	-1	-Std	
None	2.448	2.88	2.466	2.901	ns

Table 81 • LVCMOS 1.2 V Receiver Characteristics for MSIO I/O Bank (Input Buffers)

On-Die Termination ODT)	T_{PY}		T_{PYS}		Unit
	-1	-Std	-1	-Std	
None	4.714	5.545	4.675	5.5	ns
50	6.668	7.845	6.579	7.74	ns
75	5.832	6.862	5.76	6.777	ns
150	5.162	6.073	5.111	6.014	ns

AC Switching Characteristics

Worst commercial-case conditions: $T_J = 85\text{ }^{\circ}\text{C}$, $V_{DD} = 1.14\text{ V}$, $V_{DDI} = 3.0\text{ V}$

Table 91 • PCI/PCIX AC Switching Characteristics for Receiver for MSIO I/O Bank (Input Buffers)

On-Die Termination (ODT)	T_{PY}		T_{PYS}		Unit
	-1	-Std	-1	-Std	
None	2.229	2.623	2.238	2.633	ns

Table 92 • PCI/PCIX AC switching Characteristics for Transmitter for MSIO I/O Bank (Output and Tristate Buffers)

T_{DP}		T_{ZL}		T_{ZH}		T_{HZ}		T_{LZ}		Unit
-1	-Std	-1	-Std	-1	-Std	-1	-Std	-1	-Std	
2.146	2.525	2.043	2.404	2.084	2.452	6.095	7.171	5.558	6.539	ns

2.3.6 Memory Interface and Voltage Referenced I/O Standards

This section describes High-Speed Transceiver Logic (HSTL) memory interface and voltage reference I/O standards.

2.3.6.1 High-Speed Transceiver Logic (HSTL)

The HSTL standard is a general purpose high-speed bus standard sponsored by IBM (EIA/JESD8-6). IGLOO2 FPGA and SmartFusion2 SoC FPGA devices support two classes of the 1.5 V HSTL. These differential versions of the standard require a differential amplifier input buffer and a push-pull output buffer.

Minimum and Maximum DC/AC Input and Output Levels Specification (Applicable to DDRIO Bank Only)

Table 93 • HSTL Recommended DC Operating Conditions

Parameter	Symbol	Min	Typ	Max	Unit
Supply voltage	V_{DDI}	1.425	1.5	1.575	V
Termination voltage	V_{TT}	0.698	0.750	0.803	V
Input reference voltage	V_{REF}	0.698	0.750	0.803	V

Table 94 • HSTL DC Input Voltage Specification

Parameter	Symbol	Min	Max	Unit
DC input logic high	$V_{IH}(\text{DC})$	$V_{REF} + 0.1$	1.575	V
DC input logic low	$V_{IL}(\text{DC})$	-0.3	$V_{REF} - 0.1$	V
Input current high ¹	$I_{IH}(\text{DC})$			
Input current low ¹	$I_{IL}(\text{DC})$			

1. See Table 24, page 22.

Table 95 • HSTL DC Output Voltage Specification Applicable to DDRIO I/O Bank Only

Parameter	Symbol	Min	Max	Unit
HSTL Class I				
DC output logic high	V_{OH}	$V_{DDI} - 0.4$		V
DC output logic low	V_{OL}		0.4	V
Output minimum source DC current (MSIO and DDRIO I/O banks)	I_{OH} at V_{OH}	-8.0		mA
Output minimum sink current (MSIO and DDRIO I/O banks)	I_{OL} at V_{OL}	8.0		mA
HSTL Class II				
DC output logic high	V_{OH}	$V_{DDI} - 0.4$		V
DC output logic low	V_{OL}		0.4	V
Output minimum source DC current	I_{OH} at V_{OH}	-16.0		mA
Output minimum sink current	I_{OL} at V_{OL}	16.0		mA

Table 96 • HSTL DC Differential Voltage Specification

Parameter	Symbol	Min	Unit
DC input differential voltage	V_{ID} (DC)	0.2	V

Table 97 • HSTL AC Differential Voltage Specifications

Parameter	Symbol	Min	Max	Unit
AC input differential voltage	V_{DIFF}	0.4		V
AC differential cross point voltage	V_x	0.68	0.9	V

Table 98 • HSTL Minimum and Maximum AC Switching Speed

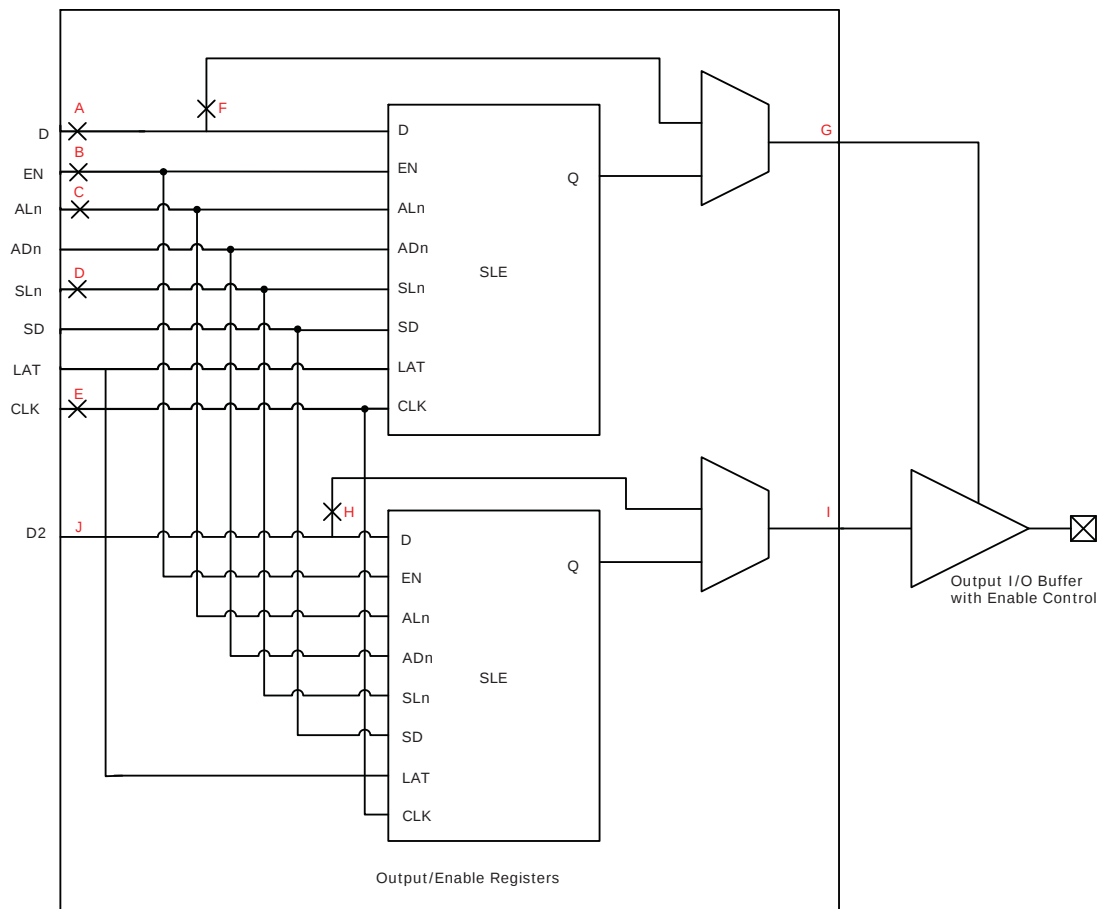
Parameter	Symbol	Max	Unit	Conditions
Maximum data rate	D_{MAX}	400	Mbps	AC loading: per JEDEC specifications

Table 99 • HSTL Impedance Specification

Parameter	Symbol	Typ	Unit	Conditions
Supported output driver calibrated impedance (for DDRIO I/O bank)	R_{REF}	25.5, 47.8	Ω	Reference resistance = 191 Ω
Effective impedance value (ODT for DDRIO I/O bank only)	R_{TT}	47.8	Ω	Reference resistance = 191 Ω

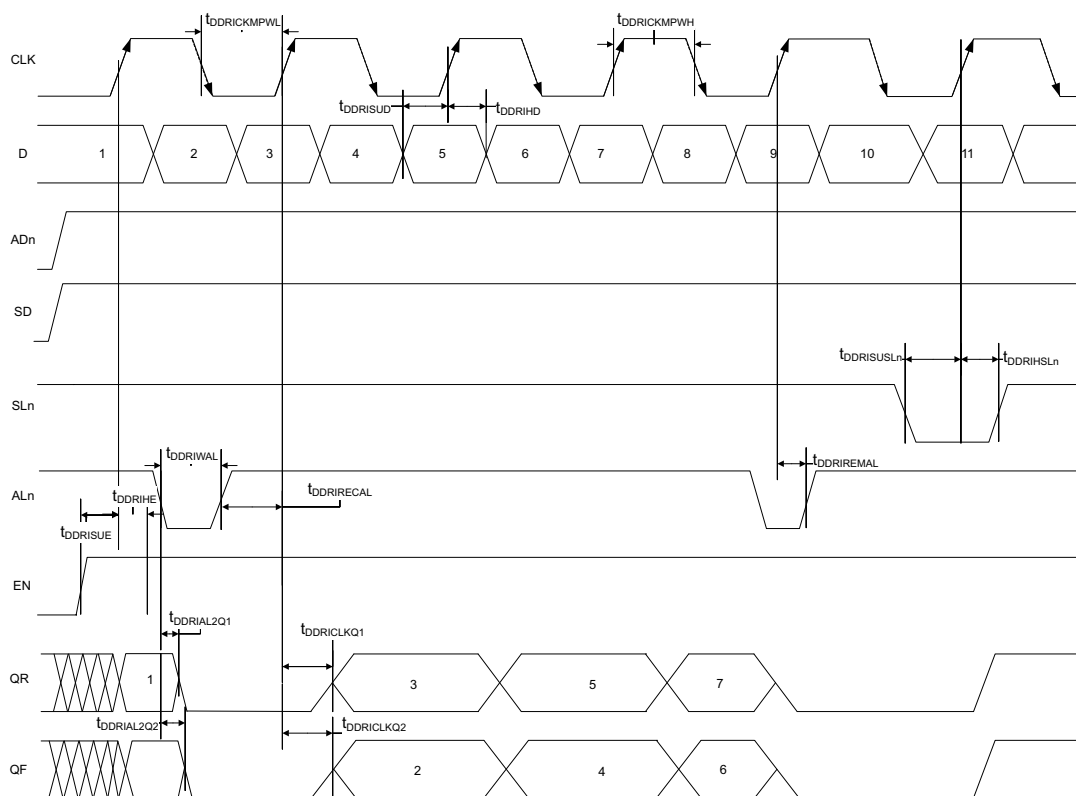
2.3.8.2 Output/Enable Register

Figure 8 • Timing Model for Output/Enable Register



2.3.9.2 Input DDR Timing Diagram

Figure 11 • Input DDR Timing Diagram

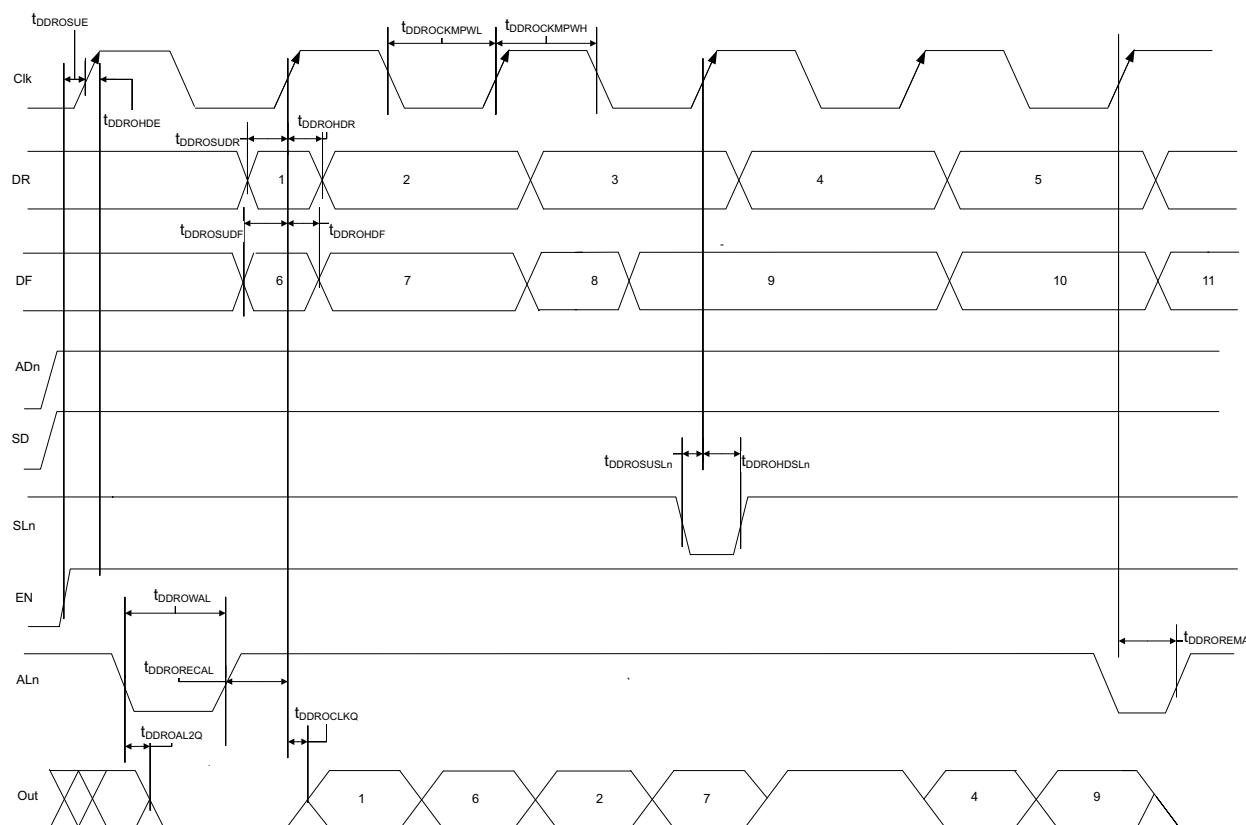


2.3.9.3 Timing Characteristics

The following table lists the input DDR propagation delays in worst commercial-case conditions when $T_J = 85^\circ\text{C}$, $V_{DD} = 1.14\text{ V}$.

Table 221 • Input DDR Propagation Delays

Symbol	Description	Measuring Nodes (from, to)	–1	–Std	Unit
$T_{DDRICKQ1}$	Clock-to-Out Out_QR for input DDR	B, C	0.16	0.188	ns
$T_{DDRICKQ2}$	Clock-to-Out Out_QF for input DDR	B, D	0.166	0.195	ns
$T_{DDRISUD}$	Data setup for input DDR	A, B	0.357	0.421	ns
T_{DDRIHD}	Data hold for input DDR	A, B	0	0	ns
$T_{DDRISUE}$	Enable setup for input DDR	E, B	0.46	0.542	ns
T_{DDRIHE}	Enable hold for input DDR	E, B	0	0	ns
$T_{DDRISUSLn}$	Synchronous load setup for input DDR	G, B	0.46	0.542	ns
$T_{DDRIHSLn}$	Synchronous load hold for input DDR	G, B	0	0	ns
$T_{DDRIAL2Q1}$	Asynchronous load-to-out QR for input DDR	F, C	0.587	0.69	ns
$T_{DDRIAL2Q2}$	Asynchronous load-to-out QF for input DDR	F, D	0.541	0.636	ns
$T_{DDRIREMAL}$	Asynchronous load removal time for input DDR	F, B	0	0	ns
$T_{DDRIRECAL}$	Asynchronous load recovery time for input DDR	F, B	0.074	0.087	ns

Figure 13 • Output DDR Timing Diagram**2.3.9.5 Timing Characteristics**

The following table lists the output DDR propagation delays in worst commercial-case conditions when $T_J = 85^\circ\text{C}$, $V_{DD} = 1.14\text{ V}$.

Table 222 • Output DDR Propagation Delays

Symbol	Description	Measuring Nodes (from, to)	-1	-Std	Unit
$T_{DDROCLKQ}$	Clock-to-out of DDR for output DDR	E, G	0.263	0.309	ns
$T_{DDROSUDF}$	Data_F data setup for output DDR	F, E	0.143	0.168	ns
$T_{DDROSUDR}$	Data_R data setup for output DDR	A, E	0.19	0.223	ns
$T_{DDROHDF}$	Data_F data hold for output DDR	F, E	0	0	ns
$T_{DDROHDR}$	Data_R data hold for output DDR	A, E	0	0	ns
$T_{DDROSUE}$	Enable setup for input DDR	B, E	0.419	0.493	ns
T_{DDROHE}	Enable hold for input DDR	B, E	0	0	ns
$T_{DDROSUSLn}$	Synchronous load setup for input DDR	D, E	0.196	0.231	ns
$T_{DDROHSLn}$	Synchronous load hold for input DDR	D, E	0	0	ns
$T_{DDROAL2Q}$	Asynchronous load-to-out for output DDR	C, G	0.528	0.621	ns
$T_{DDRORECAL}$	Asynchronous load removal time for output DDR	C, E	0	0	ns
$T_{DDRORECAL}$	Asynchronous load recovery time for output DDR	C, E	0.034	0.04	ns

The following table lists the RAM1K18 – dual-port mode for depth × width configuration 8K × 2 in worst commercial-case conditions when $T_J = 85^\circ\text{C}$, $V_{DD} = 1.14\text{ V}$.

Table 234 • RAM1K18 – Dual-Port Mode for Depth × Width Configuration 8K × 2

Parameter	Symbol	–1		–Std		Unit
		Min	Max	Min	Max	
Clock period	T_{CY}	2.5		2.941		ns
Clock minimum pulse width high	$T_{CLKMPWH}$	1.125		1.323		ns
Clock minimum pulse width low	$T_{CLKMPWL}$	1.125		1.323		ns
Pipelined clock period	T_{PLCY}	2.5		2.941		ns
Pipelined clock minimum pulse width high	$T_{PLCLKMPWH}$	1.125		1.323		ns
Pipelined clock minimum pulse width low	$T_{PLCLKMPWL}$	1.125		1.323		ns
Read access time with pipeline register			0.32		0.377	ns
Read access time without pipeline register	T_{CLK2Q}		2.272		2.673	ns
Access time with feed-through write timing			1.511		1.778	ns
Address setup time	T_{ADDRSU}	0.612		0.72		ns
Address hold time	T_{ADDRHD}	0.274		0.322		ns
Data setup time	T_{DSU}	0.33		0.388		ns
Data hold time	T_{DHD}	0.082		0.096		ns
Block select setup time	T_{BLKSU}	0.207		0.244		ns
Block select hold time	T_{BLKHD}	0.216		0.254		ns
Block select to out disable time (when pipelined register is disabled)	T_{BLK2Q}		1.511		1.778	ns
Block select minimum pulse width	T_{BLKMPW}	0.186		0.219		ns
Read enable setup time	T_{RDESU}	0.529		0.622		ns
Read enable hold time	T_{RDEHD}	0.071		0.083		ns
Pipelined read enable setup time (A_DOUT_EN, B_DOUT_EN)	$T_{RDPLESU}$	0.248		0.291		ns
Pipelined read enable hold time (A_DOUT_EN, B_DOUT_EN)	$T_{RDPLEHD}$	0.102		0.12		ns
Asynchronous reset to output propagation delay	T_{R2Q}		1.528		1.797	ns
Asynchronous reset removal time	T_{RSTREM}	0.506		0.595		ns
Asynchronous reset recovery time	T_{RSTREC}	0.004		0.005		ns
Asynchronous reset minimum pulse width	T_{RSTMPW}	0.301		0.354		ns
Pipelined register asynchronous reset removal time	$T_{PLRSTREM}$	–0.279		–0.328		ns
Pipelined register asynchronous reset recovery time	$T_{PLRSTREC}$	0.327		0.385		ns
Pipelined register asynchronous reset minimum pulse width	$T_{PLRSTMPW}$	0.282		0.332		ns
Synchronous reset setup time	T_{SRSTSU}	0.226		0.265		ns
Synchronous reset hold time	T_{SRSTHD}	0.036		0.043		ns
Write enable setup time	T_{WESU}	0.488		0.574		ns
Write enable hold time	T_{WEHD}	0.048		0.057		ns
Maximum frequency	F_{MAX}		400		340	MHz

The following table lists the RAM1K18 – dual-port mode for depth × width configuration 16K × 1 in worst commercial-case conditions when $T_J = 85\text{ }^{\circ}\text{C}$, $V_{DD} = 1.14\text{ V}$.

Table 235 • RAM1K18 – Dual-Port Mode for Depth × Width Configuration 16K × 1

Parameter	Symbol	–1		–Std		Unit
		Min	Max	Min	Max	
Clock period	T_{CY}	2.5		2.941		ns
Clock minimum pulse width high	$T_{CLKMPWH}$	1.125		1.323		ns
Clock minimum pulse width low	$T_{CLKMPWL}$	1.125		1.323		ns
Pipelined clock period	T_{PLCY}	2.5		2.941		ns
Pipelined clock minimum pulse width high	$T_{PLCLKMPWH}$	1.125		1.323		ns
Pipelined clock minimum pulse width low	$T_{PLCLKMPWL}$	1.125		1.323		ns
Read access time with pipeline register			0.32		0.377	ns
Read access time without pipeline register	T_{CLK2Q}		2.269		2.669	ns
Access time with feed-through write timing			1.51		1.777	ns
Address setup time	T_{ADDRSU}	0.626		0.737		ns
Address hold time	T_{ADDRHD}	0.274		0.322		ns
Data setup time	T_{DSU}	0.322		0.378		ns
Data hold time	T_{DHD}	0.082		0.096		ns
Block select setup time	T_{BLKSU}	0.207		0.244		ns
Block select hold time	T_{BLKHD}	0.216		0.254		ns
Block select to out disable time (when pipelined register is disabled)	T_{BLK2Q}		1.51		1.777	ns
Block select minimum pulse width	T_{BLKMPW}	0.186		0.219		ns
Read enable setup time	T_{RDESU}	0.53		0.624		ns
Read enable hold time	T_{RDEHD}	0.071		0.083		ns
Pipelined read enable setup time (A_DOUT_EN, B_DOUT_EN)	$T_{RDPLESU}$	0.248		0.291		ns
Pipelined read enable hold time (A_DOUT_EN, B_DOUT_EN)	$T_{RDPLEHD}$	0.102		0.12		ns
Asynchronous reset to output propagation delay	T_{R2Q}		1.547		1.82	ns
Asynchronous reset removal time	T_{RSTREM}	0.506		0.595		ns
Asynchronous reset recovery time	T_{RSTREC}	0.004		0.005		ns
Asynchronous reset minimum pulse width	T_{RSTMPW}	0.301		0.354		ns
Pipelined register asynchronous reset removal time	$T_{PLRSTREM}$	–0.279		–0.328		ns
Pipelined register asynchronous reset recovery time	$T_{PLRSTREC}$	0.327		0.385		ns
Pipelined register asynchronous reset minimum pulse width	$T_{PLRSTMPW}$	0.282		0.332		ns
Synchronous reset setup time	T_{SRSTSU}	0.226		0.265		ns
Synchronous reset hold time	T_{SRSTHD}	0.036		0.043		ns
Write enable setup time	T_{WESU}	0.454		0.534		ns
Write enable hold time	T_{WEHD}	0.048		0.057		ns
Maximum frequency	F_{MAX}		400		340	MHz

Table 238 • μ SRAM (RAM64x16) in 64 × 16 Mode (continued)

Parameter	Symbol	–1		–Std		Unit
		Min	Max	Min	Max	
Read synchronous reset hold time	T_{SRSTHD}	0.061		0.071		ns
Write clock period	T_{CCY}	4		4		ns
Write clock minimum pulse width high	$T_{CCLKMPWH}$	1.8		1.8		ns
Write clock minimum pulse width low	$T_{CCLKMPWL}$	1.8		1.8		ns
Write block setup time	T_{BLKCSU}	0.404		0.476		ns
Write block hold time	T_{BLKCHD}	0.007		0.008		ns
Write input data setup time	T_{DINCSU}	0.115		0.135		ns
Write input data hold time	T_{DINCHD}	0.15		0.177		ns
Write address setup time	$T_{ADDRCSU}$	0.088		0.104		ns
Write address hold time	$T_{ADDRCHD}$	0.128		0.15		ns
Write enable setup time	T_{WECSU}	0.397		0.467		ns
Write enable hold time	T_{WECHD}	–0.026		–0.03		ns
Maximum frequency	F_{MAX}		250		250	MHz

The following table lists the μ SRAM in 128 × 9 mode in worst commercial-case conditions when $T_J = 85^\circ\text{C}$, $V_{DD} = 1.14\text{ V}$.

Table 239 • μ SRAM (RAM128x9) in 128 × 9 Mode

Parameter	Symbol	–1		–Std		Unit
		Min	Max	Min	Max	
Read clock period	T_{CY}	4		4		ns
Read clock minimum pulse width high	$T_{CLKMPWH}$	1.8		1.8		ns
Read clock minimum pulse width low	$T_{CLKMPWL}$	1.8		1.8		ns
Read pipeline clock period	T_{PLCY}	4		4		ns
Read pipeline clock minimum pulse width high	$T_{PLCLKMPWH}$	1.8		1.8		ns
Read pipeline clock minimum pulse width low	$T_{PLCLKMPWL}$	1.8		1.8		ns
Read access time with pipeline register	T_{CLK2Q}		0.266		0.313	ns
Read access time without pipeline register			1.677		1.973	ns
Read address setup time in synchronous mode	T_{ADDRSU}	0.301		0.354		ns
Read address setup time in asynchronous mode		1.856		2.184		ns
Read address hold time in synchronous mode	T_{ADDRHD}	0.091		0.107		ns
Read address hold time in asynchronous mode		–0.778		–0.915		ns
Read enable setup time	T_{RDENSU}	0.278		0.327		ns
Read enable hold time	T_{RDENHD}	0.057		0.067		ns
Read block select setup time	T_{BLKSU}	1.839		2.163		ns
Read block select hold time	T_{BLKHD}	–0.65		–0.765		ns
Read block select to out disable time (when pipelined register is disabled)	T_{BLK2Q}		2.036		2.396	ns

Table 277 • Electrical Characteristics of the Crystal Oscillator – High Gain Mode (20 MHz) (continued)

Parameter	Symbol	Min	Typ	Max	Unit	Condition
Startup time (with regard to stable oscillator output)	SUXTAL			0.8	ms	005, 010, 025, and 050 devices
				1.0	ms	090 and 150 devices

Table 278 • Electrical Characteristics of the Crystal Oscillator – Medium Gain Mode (2 MHz)

Parameter	Symbol	Min	Typ	Max	Unit	Condition
Operating frequency	FXTAL		2		MHz	
Accuracy	ACCXTAL			0.00105	%	050 devices
				0.003	%	005, 010, 025, 090, and 150 devices
				0.004	%	060 devices
Output duty cycle	CYCXTAL		49–51	47–53	%	
Output period jitter (peak to peak)	JITPERXTAL		1	5	ns	
Output cycle to cycle jitter (peak to peak)	JITCYCXTAL		1	5	ns	
Operating current	IDYNXTAL		0.3		mA	
Input logic level high	VIHXTAL	0.9 V _{PP}			V	
Input logic level low	VILXTAL			0.1 V _{PP}	V	
Startup time (with regard to stable oscillator output)	SUXTAL			4.5	ms	010 and 050 devices
				5	ms	005 and 025 devices
				7	ms	090 and 150 devices

Table 279 • Electrical Characteristics of the Crystal Oscillator – Low Gain Mode (32 kHz)

Parameter	Symbol	Min	Typ	Max	Unit	Condition
Operating frequency	FXTAL		32		kHz	
Accuracy	ACCXTAL			0.004	%	005, 010, 025, 050, 060, and 090 devices
				0.005	%	150 devices
Output duty cycle	CYCXTAL		49–51	47–53	%	
Output period jitter (peak to peak)	JITPERXTAL		150	300	ns	
Output cycle to cycle jitter (peak to peak)	JITCYCXTAL		150	300	ns	
Operating current	IDYNXTAL		0.044		mA	010 and 050 devices
			0.060		mA	005, 025, 060, 090, and 150 devices
Input logic level high	VIHXTAL	0.9 V _{PP}			V	
Input logic level low	VILXTAL			0.1 V _{PP}	V	
Startup time (with regard to stable oscillator output)	SUXTAL			115	ms	005, 025, 050, 090, and 150 devices
				126	ms	010 devices

The following table lists the system controller characteristics in worst-case industrial conditions when $T_J = 100\text{ }^{\circ}\text{C}$, $V_{DD} = 1.14\text{ V}$.

Table 286 • System Controller SPI Characteristics for All Devices

Symbol	Description	Conditions	Min	Typ	Unit
sp1	SC_SPI_SCK minimum period		20		ns
sp2	SC_SPI_SCK minimum pulse width high		10		ns
sp3	SC_SPI_SCK minimum pulse width low		10		ns
sp4 ¹	SC_SPI_SCK, SC_SPI_SDO, SC_SPI_SS rise time (10%–90%) 1	I/O configuration: LVTTTL 3.3 V–20 mA AC loading: 35 pF Test conditions: Typical voltage, 25 °C		1.239	ns
sp5 ¹	SC_SPI_SCK, SC_SPI_SDO, SC_SPI_SS fall time (10%–90%) 1	I/O configuration: LVTTTL 3.3 V–20 mA AC loading: 35 pF Test conditions: Typical voltage, 25 °C		1.245	ns
sp6	Data from master (SC_SPI_SDO) setup time		160		ns
sp7	Data from master (SC_SPI_SDO) hold time		160		ns
sp8	SC_SPI_SDI setup time		20		ns
sp9	SC_SPI_SDI hold time		20		ns

1. For specific Rise/Fall Times, board design considerations and detailed output buffer resistances, use the corresponding IBIS models located on the Microsemi SoC Products Group website: <http://www.microsemi.com/soc/download/ibis/default.aspx>. Use the supported I/O Configurations for the System Controller SPI in the following table.

Table 287 • Supported I/O Configurations for System Controller SPI (for MSIO Bank Only)

Voltage Supply	I/O Drive Configuration	Unit
3.3 V	20	mA
2.5 V	16	mA
1.8 V	12	mA
1.5 V	8	mA
1.2 V	4	mA

Table 303 • I2C Characteristics (continued)

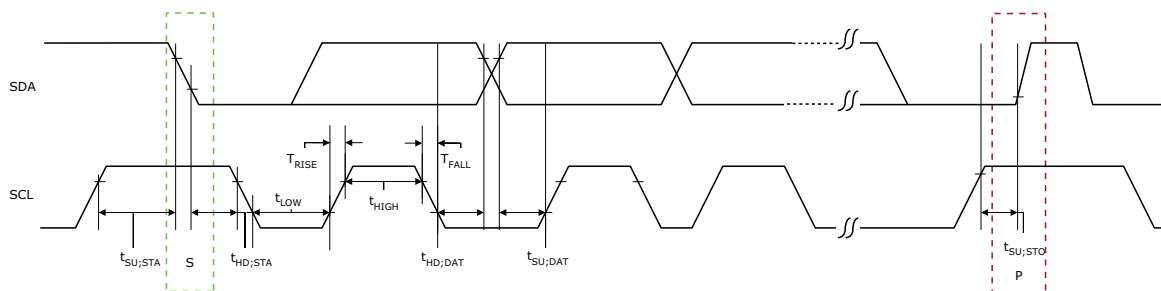
Parameter	Symbol	Min	Typ	Max	Unit	Conditions
Maximum data rate	D_{MAX}			400	Kbps	Fast mode
				100	Kbps	Standard mode
Pulse width of spikes which must be suppressed by the input filter	T_{FILT}		50		ns	Fast mode

- These values are provided for MSIO Bank–LVTTL 8 mA Low Drive at 25 °C, typical conditions. For board design considerations and detailed output buffer resistances, use the corresponding IBIS models located on the SoC Products Group website: <http://www.microsemi.com/soc/download/ibis/default.aspx>.
- These maximum values are provided for information only. Minimum output buffer resistance values depend on V_{DDIX} , drive strength selection, temperature, and process. For board design considerations and detailed output buffer resistances, use the corresponding IBIS models located on the SoC Products Group website: <http://www.microsemi.com/soc/download/ibis/default.aspx>.
- $R(PULL-DOWN-MAX) = (VOL_{spec})/IOL_{spec}$.
- $R(PULL-UP-MAX) = (VDDImax - VOH_{spec})/IOH_{spec}$.

The following table lists the I²C switching characteristics in worst-case industrial conditions when $T_J = 100\text{ °C}$, $V_{DD} = 1.14\text{ V}$

Table 304 • I2C Switching Characteristics

Parameter	Symbol	–1	Std	Unit
		Min	Min	
Low period of I2C_x_SCL	T_{LOW}	1	1	PCLK cycles
High period of I2C_x_SCL	T_{HIGH}	1	1	PCLK cycles
START hold time	$T_{HD;STA}$	1	1	PCLK cycles
START setup time	$T_{SU;STA}$	1	1	PCLK cycles
DATA hold time	$T_{HD;DAT}$	1	1	PCLK cycles
DATA setup time	$T_{SU;DAT}$	1	1	PCLK cycles
STOP setup time	$T_{SU;STO}$	1	1	PCLK cycles

Figure 21 • I²C Timing Parameter Definition

2.3.31.3 Serial Peripheral Interface (SPI) Characteristics

This section describes the DC and switching of the SPI interface. Unless otherwise noted, all output characteristics given are for a 35 pF load on the pins and all sequential timing characteristics are related to SPI_x_CLK. For timing parameter definitions, see [Figure 22](#), page 128.

The following table lists the SPI characteristics in worst-case industrial conditions when $T_J = 100\text{ }^{\circ}\text{C}$, $V_{DD} = 1.14\text{ V}$

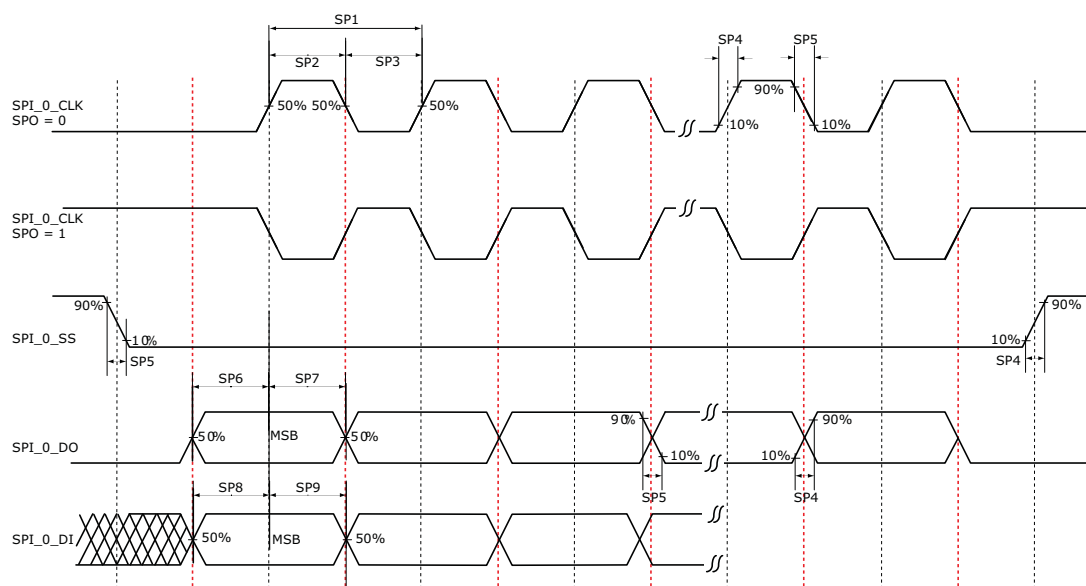
Table 305 • SPI Characteristics for All Devices

Symbol	Description	Min	Typ	Max	Unit	Conditions
SPIFMAX	Maximum operating frequency of SPI interface			20	MHz	
sp1	SPI_[0 1]_CLK minimum period					
	SPI_[0 1]_CLK = PCLK/2	12			ns	
	SPI_[0 1]_CLK = PCLK/4	24.1			ns	
	SPI_[0 1]_CLK = PCLK/8	48.2			ns	
	SPI_[0 1]_CLK = PCLK/16	0.1			μs	
	SPI_[0 1]_CLK = PCLK/32	0.19			μs	
	SPI_[0 1]_CLK = PCLK/64	0.39			μs	
	SPI_[0 1]_CLK = PCLK/128	0.77			μs	
sp2	SPI_[0 1]_CLK minimum pulse width high					
	SPI_[0 1]_CLK = PCLK/2	6			ns	
	SPI_[0 1]_CLK = PCLK/4	12.05			ns	
	SPI_[0 1]_CLK = PCLK/8	24.1			ns	
	SPI_[0 1]_CLK = PCLK/16	0.05			μs	
	SPI_[0 1]_CLK = PCLK/32	0.095			μs	
	SPI_[0 1]_CLK = PCLK/64	0.195			μs	
	SPI_[0 1]_CLK = PCLK/128	0.385			μs	
sp3	SPI_[0 1]_CLK minimum pulse width low					
	SPI_[0 1]_CLK = PCLK/2	6			ns	
	SPI_[0 1]_CLK = PCLK/4	12.05			ns	
	SPI_[0 1]_CLK = PCLK/8	24.1			ns	
	SPI_[0 1]_CLK = PCLK/16	0.05			μs	
	SPI_[0 1]_CLK = PCLK/32	0.095			μs	
	SPI_[0 1]_CLK = PCLK/64	0.195			μs	
	SPI_[0 1]_CLK = PCLK/128	0.385			μs	
sp4	SPI_[0 1]_CLK, SPI_[0 1]_DO, SPI_[0 1]_SS rise time (10%–90%) ¹		2.77		ns	I/O Configuration: LVCMOS 2.5 V– 8 mA AC loading: 35 pF Test conditions: Typical voltage, 25 °C

Table 305 • SPI Characteristics for All Devices (continued)

Symbol	Description	Min	Typ	Max	Unit	Conditions
sp5	SPI_[0 1]_CLK, SPI_[0 1]_DO, SPI_[0 1]_SS fall time (10%– 90%) ¹		2.906		ns	IO Configuration: LVCMOS 2.5 V-8 mA AC Loading: 35 pF Test Conditions: Typical Voltage, 25 °C
SPI master configuration (applicable for 005, 010, 025, and 050 devices)						
sp6m	SPI_[0 1]_DO setup time ²	$(\text{SPI_x_CLK_period}/2) - 8.0$			ns	
sp7m	SPI_[0 1]_DO hold time ²	$(\text{SPI_x_CLK_period}/2) - 2.5$			ns	
sp8m	SPI_[0 1]_DI setup time ²	12			ns	
sp9m	SPI_[0 1]_DI hold time ²	2.5			ns	
SPI slave configuration (applicable for 005, 010, 025, and 050 devices)						
sp6s	SPI_[0 1]_DO setup time ²	$(\text{SPI_x_CLK_period}/2) - 17.0$			ns	
sp7s	SPI_[0 1]_DO hold time ²	$(\text{SPI_x_CLK_period}/2) + 3.0$			ns	
sp8s	SPI_[0 1]_DI setup time ²	2			ns	
sp9s	SPI_[0 1]_DI hold time ²	7			ns	
SPI master configuration (applicable for 060, 090, and 150 devices)						
sp6m	SPI_[0 1]_DO setup time ²	$(\text{SPI_x_CLK_period}/2) - 7.0$			ns	
sp7m	SPI_[0 1]_DO hold time ²	$(\text{SPI_x_CLK_period}/2) - 9.5$			ns	
sp8m	SPI_[0 1]_DI setup time ²	15			ns	
sp9m	SPI_[0 1]_DI hold time ²	-2.5			ns	
SPI slave configuration (applicable for 060, 090, and 150 devices)						
sp6s	SPI_[0 1]_DO setup time ²	$(\text{SPI_x_CLK_period}/2) - 16.0$			ns	
sp7s	SPI_[0 1]_DO hold time ²	$(\text{SPI_x_CLK_period}/2) - 3.5$			ns	
sp8s	SPI_[0 1]_DI setup time ²	3			ns	
sp9s	SPI_[0 1]_DI hold time ²	2.5			ns	

1. For specific Rise/Fall Times board design considerations and detailed output buffer resistances, use the corresponding IBIS models located on the Microsemi SoC Products Group website: <http://www.microsemi.com/soc/download/ibis/default.aspx>.
2. For allowable pclk configurations, see Serial Peripheral Interface Controller section in the *UG0331: SmartFusion2 Microcontroller Subsystem User Guide*.

Figure 22 • SPI Timing for a Single Frame Transfer in Motorola Mode (SPH = 1)

2.3.32 CAN Controller Characteristics

The following table lists the CAN controller characteristics in worst-case industrial conditions when $T_J = 100^\circ\text{C}$, $V_{DD} = 1.14\text{ V}$.

Table 306 • CAN Controller Characteristics

Parameter	Description	–1	–Std	Unit
FCANREFCLK ¹	Internally sourced CAN reference clock frequency	160	136	MHz
BAUDCANMAX	Maximum CAN performance baud rate	1	1	Mbps
BAUDCANMIN	Minimum CAN performance baud rate	0.05	0.05	Mbps

1. PCLK to CAN controller must be a multiple of 8 MHz.

2.3.33 USB Characteristics

The following table lists the USB characteristics in worst-case industrial conditions when $T_J = 100^\circ\text{C}$, $V_{DD} = 1.14\text{ V}$.

Table 307 • USB Characteristics

Parameter	Description	–1	–Std	Unit
FUSBREFCLK	Internally sourced USB reference clock frequency	166	142	MHz
TUSBCLK	USB clock period	16.66	16.66	ns
TUSBPD	Clock to USB data propagation delay	9.0	9.0	ns
TUSBSU	Setup time for USB data	6.0	6.0	ns
TUSBHD	Hold time for USB data	0	0	ns

Table 310 • SPI Characteristics for All Devices (continued)

Symbol	Description	Min	Typ	Max	Unit	Conditions
SPI master configuration (applicable for 060, 090, and 150 devices)						
sp6m	SPI_[0 1]_DO setup time ²	$(\text{SPI_x_CLK_period}/2) - 7.0$			ns	
sp7m	SPI_[0 1]_DO hold time ²	$(\text{SPI_x_CLK_period}/2) - 9.5$			ns	
sp8m	SPI_[0 1]_DI setup time ²	15			ns	
sp9m	SPI_[0 1]_DI hold time ²	-2.5			ns	
SPI slave configuration (applicable for 060, 090, and 150 devices)						
sp6s	SPI_[0 1]_DO setup time ²	$(\text{SPI_x_CLK_period}/2) - 16.0$			ns	
sp7s	SPI_[0 1]_DO hold time ²	$(\text{SPI_x_CLK_period}/2) - 3.5$			ns	
sp8s	SPI_[0 1]_DI setup time ²	3			ns	
sp9s	SPI_[0 1]_DI hold time ²	2.5			ns	

- For specific Rise/Fall Times board design considerations and detailed output buffer resistances, use the corresponding IBIS models located on the Microsemi SoC Products Group website: <http://www.microsemi.com/soc/download/ibis/default.aspx>.
- For allowable pclk configurations, see the Serial Peripheral Interface Controller section in the *UG0331: SmartFusion2 Microcontroller Subsystem User Guide*.

Figure 23 • SPI Timing for a Single Frame Transfer in Motorola Mode (SPH = 1)