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### Understanding [Embedded - FPGAs \(Field Programmable Gate Array\)](#)

Embedded - FPGAs, or Field Programmable Gate Arrays, are advanced integrated circuits that offer unparalleled flexibility and performance for digital systems. Unlike traditional fixed-function logic devices, FPGAs can be programmed and reprogrammed to execute a wide array of logical operations, enabling customized functionality tailored to specific applications. This reprogrammability allows developers to iterate designs quickly and implement complex functions without the need for custom hardware.

### Applications of Embedded - FPGAs

The versatility of Embedded - FPGAs makes them indispensable in numerous fields. In telecommunications.

#### Details

Product Status	Active
Number of LABs/CLBs	-
Number of Logic Elements/Cells	12084
Total RAM Bits	933888
Number of I/O	195
Number of Gates	-
Voltage - Supply	1.14V ~ 2.625V
Mounting Type	Surface Mount
Operating Temperature	-40°C ~ 100°C (TJ)
Package / Case	400-LFBGA
Supplier Device Package	400-VFBGA (17x17)
Purchase URL	<a href="https://www.e-xfl.com/product-detail/microchip-technology/m2gl010-vfg400i">https://www.e-xfl.com/product-detail/microchip-technology/m2gl010-vfg400i</a>

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**Table 43 • LVCMOS 2.5 V AC Test Parameter Specifications**

Parameter	Symbol	Typ	Unit
Measuring/trip point for data path	$V_{TRIP}$	1.2	V
Resistance for enable path ( $T_{ZH}$ , $T_{ZL}$ , $T_{HZ}$ , $T_{LZ}$ )	$R_{ENT}$	2K	$\Omega\sigma$
Capacitive loading for enable path ( $T_{ZH}$ , $T_{ZL}$ , $T_{HZ}$ , $T_{LZ}$ )	$C_{ENT}$	5	pF
Capacitive loading for data path ( $T_{DP}$ )	$C_{LOAD}$	5	pF

**Table 44 • LVCMOS 2.5 V Transmitter Drive Strength Specifications**

Output Drive Selection			VOH (V)	VOL (V)	IOH (at VOH) mA	IOL (at VOL) mA
MSIO I/O Bank	MSIOD I/O Bank	DDRIO I/O Bank (With Software Default Fixed Code)	Min	Max		
2 mA	2 mA	2 mA	$V_{DDI} - 0.4$	0.4	2	2
4 mA	4 mA	4 mA	$V_{DDI} - 0.4$	0.4	4	4
6 mA	6 mA	6 mA	$V_{DDI} - 0.4$	0.4	6	6
8 mA	8 mA	8 mA	$V_{DDI} - 0.4$	0.4	8	8
12 mA	12 mA	12 mA	$V_{DDI} - 0.4$	0.4	12	12
16 mA		16 mA	$V_{DDI} - 0.4$	0.4	16	16

**Note:** For board design considerations, output slew rates extraction, detailed output buffer resistances, and I/V Curve, use the corresponding IBIS models located at:  
[www.microsemi.com/soc/download/ibis/default.aspx](http://www.microsemi.com/soc/download/ibis/default.aspx).

**AC Switching Characteristics**

Worst commercial-case conditions:  $T_J = 85\text{ }^\circ\text{C}$ ,  $V_{DD} = 1.14\text{ V}$ ,  $V_{DDI} = 2.375\text{ V}$

**Table 45 • LVCMOS 2.5 V Receiver Characteristics (Input Buffers)**

	On-Die Termination (ODT)	$T_{PY}$		$T_{PYS}$		Unit
		-1	-Std	-1	-Std	
LVCMOS 2.5 V (for DDRIO I/O bank)	None	1.823	2.145	1.932	2.274	ns
LVCMOS 2.5 V (for MSIO I/O bank)	None	2.486	2.925	2.495	2.935	ns
LVCMOS 2.5 V (for MSIOD I/O bank)	None	2.29	2.694	2.305	2.712	ns

**Table 46 • LVCMOS 2.5 V Transmitter Characteristics for DDRIO Bank (Output and Tristate Buffers)**

Output Drive Selection	Slew Control	$T_{DP}$		$T_{ZL}$		$T_{ZH}$		$T_{HZ}^1$		$T_{LZ}^1$		Unit
		-1	-Std	-1	-Std	-1	-Std	-1	-Std	-1	-Std	
2 mA	Slow	3.657	4.302	3.393	3.991	3.675	4.323	3.894	4.582	3.552	4.18	ns
	Medium	3.374	3.97	3.139	3.693	3.396	3.995	3.635	4.277	3.253	3.828	ns
	Medium fast	3.239	3.811	3.036	3.572	3.261	3.836	3.519	4.141	3.128	3.681	ns
	Fast	3.224	3.793	3.029	3.563	3.246	3.818	3.512	4.132	3.119	3.67	ns

**AC Switching Characteristics**

Worst commercial-case conditions:  $T_J = 85\text{ }^\circ\text{C}$ ,  $V_{DD} = 1.14\text{ V}$ ,  $V_{DDI} = 1.425\text{ V}$

**Table 67 • LVCMOS 1.5 V Receiver Characteristics for DDRIO I/O Bank with Fixed Codes (Input Buffers)**

On-Die Termination (ODT)	$T_{PY}$		$T_{PYS}$		Unit
	-1	-Std	-1	-Std	
None	2.051	2.413	2.086	2.455	ns

**Table 68 • LVCMOS 1.5 V Receiver Characteristics for MSIO I/O Bank (Input Buffers)**

On-Die Termination (ODT)	$T_{PY}$		$T_{PYS}$		Unit
	-1	-Std	-1	-Std	
None	3.311	3.896	3.285	3.865	ns
50	3.654	4.299	3.623	4.263	ns
75	3.533	4.156	3.501	4.119	ns
150	3.415	4.018	3.388	3.986	ns

**Table 69 • LVCMOS 1.5 V Receiver Characteristics for MSIOD I/O Bank (Input Buffers)**

On-Die Termination (ODT)	$T_{PY}$		$T_{PYS}$		Unit
	-1	-Std	-1	-Std	
None	2.959	3.481	2.93	3.447	ns
50	3.298	3.88	3.268	3.845	ns
75	3.162	3.719	3.128	3.68	ns
150	3.053	3.592	3.021	3.554	ns

**Table 70 • LVCMOS 1.5 V Transmitter Characteristics for DDRIO I/O Bank (Output and Tristate Buffers)**

Output Drive Selection	Slew Control	$T_{DP}$		$T_{ZL}$		$T_{ZH}$		$T_{HZ}^1$		$T_{LZ}^1$		Unit
		-1	-Std	-1	-Std	-1	-Std	-1	-Std	-1	-Std	
2 mA	Slow	5.122	6.026	4.31	5.07	5.145	6.052	5.258	6.186	4.672	5.496	ns
	Medium	4.58	5.389	3.86	4.54	4.6	5.411	4.977	5.855	4.357	5.126	ns
	Medium fast	4.323	5.086	3.629	4.269	4.341	5.107	4.804	5.652	4.228	4.974	ns
	Fast	4.296	5.054	3.609	4.245	4.314	5.075	4.791	5.636	4.219	4.963	ns
4 mA	Slow	4.449	5.235	3.707	4.361	4.443	5.227	6.058	7.127	5.458	6.421	ns
	Medium	3.961	4.66	3.264	3.839	3.954	4.651	5.778	6.797	5.116	6.018	ns
	Medium fast	3.729	4.387	3.043	3.579	3.72	4.376	5.63	6.624	4.981	5.86	ns
	Fast	3.704	4.358	3.027	3.56	3.695	4.347	5.624	6.617	4.973	5.851	ns

### 2.3.6.3 Stub-Series Terminated Logic 2.5 V (SSTL2)

SSTL2 Class I and Class II are supported in IGLOO2 and SmartFusion2 SoC FPGAs and also comply with reduced and full drive of double data rate (DDR) standards. IGLOO2 and SmartFusion2 SoC FPGA I/Os supports both standards for single-ended signaling and differential signaling for SSTL2. This standard requires a differential amplifier input buffer and a push-pull output buffer.

#### Minimum and Maximum DC/AC Input and Output Levels Specification

**Table 103 • DDR1/SSTL2 DC Recommended Operating Conditions**

Parameter	Symbol	Min	Typ	Max	Unit
Supply voltage	$V_{DDI}$	2.375	2.5	2.625	V
Termination voltage	$V_{TT}$	1.164	1.250	1.339	V
Input reference voltage	$V_{REF}$	1.164	1.250	1.339	V

**Table 104 • DDR1/SSTL2 DC Input Voltage Specification**

Parameter	Symbol	Min	Max	Unit
DC input logic high	$V_{IH}$ (DC)	$V_{REF} + 0.15$	2.625	V
DC input logic low	$V_{IL}$ (DC)	-0.3	$V_{REF} - 0.15$	V
Input current high <sup>1</sup>	$I_{IH}$ (DC)			
Input current low <sup>1</sup>	$I_{IL}$ (DC)			

1. See Table 24, page 22.

**Table 105 • DDR1/SSTL2 DC Output Voltage Specification**

Parameter	Symbol	Min	Max	Unit
<b>SSTL2 Class I (DDR Reduced Drive)</b>				
DC output logic high	$V_{OH}$	$V_{TT} + 0.608$		V
DC output logic low	$V_{OL}$		$V_{TT} - 0.608$	V
Output minimum source DC current	$I_{OH}$ at $V_{OH}$	8.1		mA
Output minimum sink current	$I_{OL}$ at $V_{OL}$	-8.1		mA
<b>SSTL2 Class II (DDR Full Drive) – Applicable to MSIO and DDRIO I/O Bank Only</b>				
DC output logic high	$V_{OH}$	$V_{TT} + 0.81$		V
DC output logic low	$V_{OL}$		$V_{TT} - 0.81$	V
Output minimum source DC current	$I_{OH}$ at $V_{OH}$	16.2		mA
Output minimum sink current	$I_{OL}$ at $V_{OL}$	-16.2		mA

**Table 106 • DDR1/SSTL2 DC Differential Voltage Specification**

Parameter	Symbol	Min	Unit
DC input differential voltage	$V_{ID}$ (DC)	0.3	V

**Table 122 • SSTL18 DC Differential Voltage Specification**

Parameter	Symbol	Min	Unit
DC input differential voltage	$V_{ID}$ (DC)	0.3	V

**Table 123 • SSTL18 AC Differential Voltage Specifications (Applicable to DDRIO Bank Only)**

Parameter	Symbol	Min	Max	Unit
AC input differential voltage	$V_{DIFF}$ (AC)	0.5		V
AC differential cross point voltage	$V_x$ (AC)	$0.5 \times V_{DDI} - 0.175$	$0.5 \times V_{DDI} + 0.175$	V

**Table 124 • SSTL18 Minimum and Maximum AC Switching Speed (Applicable to DDRIO Bank Only)**

Parameter	Symbol	Max	Unit	Conditions
Maximum data rate (for DDRIO I/O bank)	$D_{MAX}$	667	Mbps	AC loading: per JEDEC specification

**Table 125 • SSTL18 AC Impedance Specifications (Applicable to DDRIO Bank Only)**

Parameter	Symbol	Typ	Unit	Conditions
Supported output driver calibrated impedance (for DDRIO I/O bank)	$R_{REF}$	20, 42	$\Omega$	Reference resistor = 150 $\Omega$
Effective impedance value (ODT)	$R_{TT}$	50, 75, 150	$\Omega$	Reference resistor = 150 $\Omega$

**Table 126 • SSTL18 AC Test Parameter Specifications (Applicable to DDRIO Bank Only)**

Parameter	Symbol	Typ	Unit
Measuring/trip point for data path	$V_{TRIP}$	0.9	V
Resistance for enable path ( $T_{ZH}$ , $T_{ZL}$ , $T_{HZ}$ , $T_{LZ}$ )	$R_{ENT}$	2K	$\Omega$
Capacitive loading for enable path ( $T_{ZH}$ , $T_{ZL}$ , $T_{HZ}$ , $T_{LZ}$ )	$C_{ENT}$	5	pF
Reference resistance for data test path for SSTL18 Class I ( $T_{DP}$ )	$R_{TT\_TEST}$	50	$\Omega$
Reference resistance for data test path for SSTL18 Class II ( $T_{DP}$ )	$R_{TT\_TEST}$	25	$\Omega$
Capacitive loading for data path ( $T_{DP}$ )	$C_{LOAD}$	5	pF

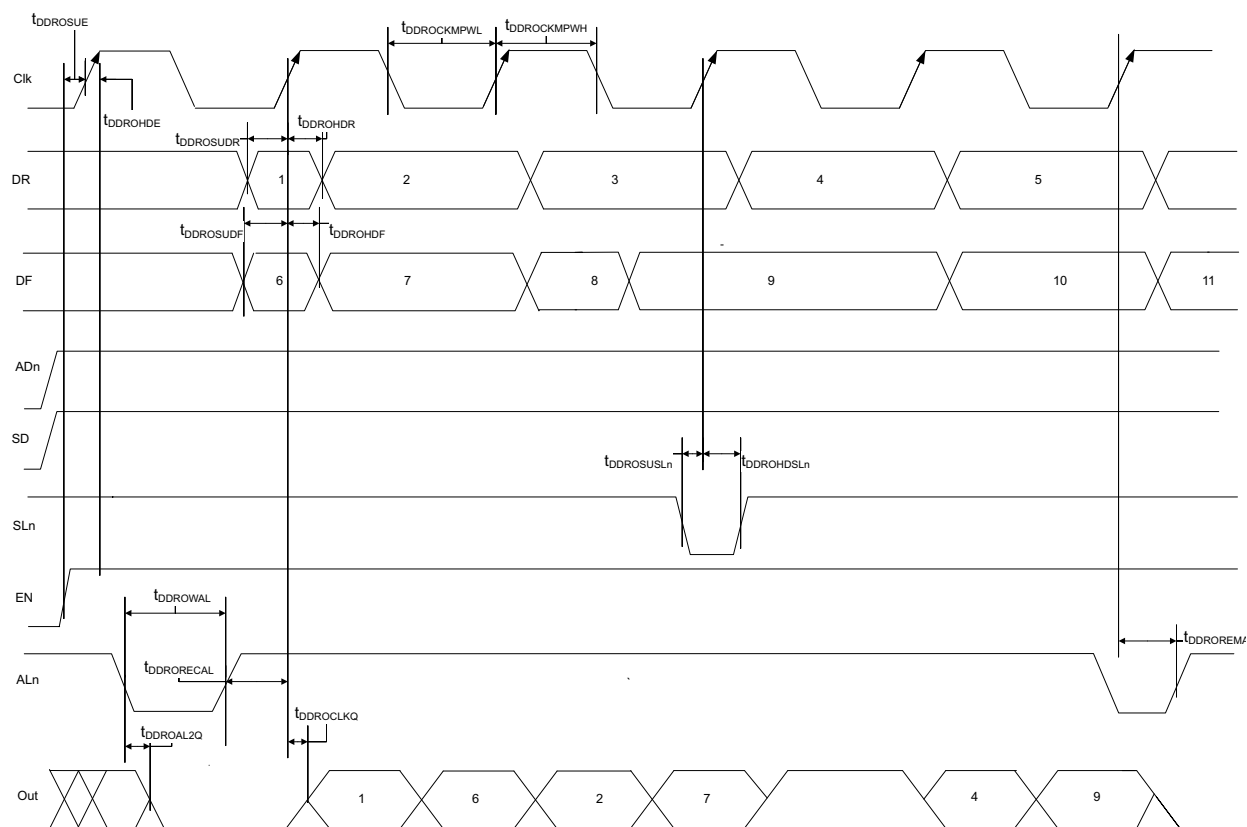
**AC Switching Characteristics**

Worst commercial-case conditions:  $T_J = 85^\circ\text{C}$ ,  $V_{DD} = 1.14\text{ V}$ ,  $V_{DDI} = 1.71\text{ V}$

**Table 127 • DDR2/SSTL18 Receiver Characteristics for DDRIO I/O Bank with Fixed Code**

	On-Die Termination (ODT)	$T_{PY}$		Unit
		-1	-Std	
Pseudo differential	None	1.567	1.844	ns
True differential	None	1.588	1.869	ns

**Figure 13 • Output DDR Timing Diagram**



### 2.3.9.5 Timing Characteristics

The following table lists the output DDR propagation delays in worst commercial-case conditions when  $T_J = 85^\circ\text{C}$ ,  $V_{DD} = 1.14\text{ V}$ .

**Table 222 • Output DDR Propagation Delays**

Symbol	Description	Measuring Nodes (from, to)	-1	-Std	Unit
$T_{DDROCLKQ}$	Clock-to-out of DDR for output DDR	E, G	0.263	0.309	ns
$T_{DDROSUDF}$	Data_F data setup for output DDR	F, E	0.143	0.168	ns
$T_{DDROSUDR}$	Data_R data setup for output DDR	A, E	0.19	0.223	ns
$T_{DDROHDF}$	Data_F data hold for output DDR	F, E	0	0	ns
$T_{DDROHDR}$	Data_R data hold for output DDR	A, E	0	0	ns
$T_{DDROSUE}$	Enable setup for input DDR	B, E	0.419	0.493	ns
$T_{DDROHE}$	Enable hold for input DDR	B, E	0	0	ns
$T_{DDROSUSLn}$	Synchronous load setup for input DDR	D, E	0.196	0.231	ns
$T_{DDROHSLn}$	Synchronous load hold for input DDR	D, E	0	0	ns
$T_{DDROAL2Q}$	Asynchronous load-to-out for output DDR	C, G	0.528	0.621	ns
$T_{DDROREMA}$	Asynchronous load removal time for output DDR	C, E	0	0	ns
$T_{DDRORECAL}$	Asynchronous load recovery time for output DDR	C, E	0.034	0.04	ns



## 2.3.11 Global Resource Characteristics

The IGLOO2 and SmartFusion2 SoC FPGA devices offer a powerful, low skew global routing network which provides an effective clock distribution throughout the FPGA fabric. See *UG0445: IGLOO2 FPGA and SmartFusion2 SoC FPGA Fabric User Guide* for the positions of various global routing resources.

The following table lists the 150 device global resources in worst commercial-case conditions when  $T_J = 85\text{ }^\circ\text{C}$ ,  $V_{DD} = 1.14\text{ V}$ .

**Table 225 • 150 Device Global Resource**

Parameter	Symbol	-1		-Std		Unit
		Min	Max	Min	Max	
Input low delay for global clock	$T_{RCKL}$	0.83	0.911	0.831	0.913	ns
Input high delay for global clock	$T_{RCKH}$	1.457	1.588	1.715	1.869	ns
Maximum skew for global clock	$T_{RCKSW}$		0.131		0.154	ns

The following table lists the 090 device global resources in worst commercial-case conditions when  $T_J = 85\text{ }^\circ\text{C}$ ,  $V_{DD} = 1.14\text{ V}$ .

**Table 226 • 090 Device Global Resource**

Parameter	Symbol	-1		-Std		Unit
		Min	Max	Min	Max	
Input low delay for global clock	$T_{RCKL}$	0.835	0.888	0.833	0.886	ns
Input high delay for global clock	$T_{RCKH}$	1.405	1.489	1.654	1.752	ns
Maximum skew for global clock	$T_{RCKSW}$		0.084		0.098	ns

The following table lists the 050 device global resources in worst commercial-case conditions when  $T_J = 85\text{ }^\circ\text{C}$ ,  $V_{DD} = 1.14\text{ V}$ .

**Table 227 • 050 Device Global Resource**

Parameter	Symbol	-1		-Std		Unit
		Min	Max	Min	Max	
Input low delay for global clock	$T_{RCKL}$	0.827	0.897	0.826	0.896	ns
Input high delay for global clock	$T_{RCKH}$	1.419	1.53	1.671	1.8	ns
Maximum skew for global clock	$T_{RCKSW}$		0.111		0.129	ns

The following table lists the 025 device global resources in worst commercial-case conditions when  $T_J = 85\text{ }^\circ\text{C}$ ,  $V_{DD} = 1.14\text{ V}$ .

**Table 228 • 025 Device Global Resource**

Parameter	Symbol	-1		-Std		Unit
		Min	Max	Min	Max	
Input low delay for global clock	$T_{RCKL}$	0.747	0.799	0.745	0.797	ns
Input high delay for global clock	$T_{RCKH}$	1.294	1.378	1.522	1.621	ns
Maximum skew for global clock	$T_{RCKSW}$		0.084		0.099	ns

The following table lists the  $\mu$ SRAM in  $256 \times 4$  mode in worst commercial-case conditions when  $T_J = 85^\circ\text{C}$ ,  $V_{DD} = 1.14\text{ V}$ .

**Table 241 •  $\mu$ SRAM (RAM256x4) in  $256 \times 4$  Mode**

Parameter	Symbol	-1		-Std		Unit
		Min	Max	Min	Max	
Read clock period	$T_{CY}$	4		4		ns
Read clock minimum pulse width high	$T_{CLKMPWH}$	1.8		1.8		ns
Read clock minimum pulse width low	$T_{CLKMPWL}$	1.8		1.8		ns
Read pipeline clock period	$T_{PLCY}$	4		4		ns
Read pipeline clock minimum pulse width high	$T_{PLCLKMPWH}$	1.8		1.8		ns
Read pipeline clock minimum pulse width low	$T_{PLCLKMPWL}$	1.8		1.8		ns
Read access time with pipeline register	$T_{CLK2Q}$		0.27		0.31	ns
Read access time without pipeline register				1.75		2.06
Read address setup time in synchronous mode	$T_{ADDRSU}$	0.301		0.354		ns
Read address setup time in asynchronous mode		1.931		2.272		ns
Read address hold time in synchronous mode	$T_{ADDRHD}$	0.121		0.142		ns
Read address hold time in asynchronous mode		-0.65		-0.76		ns
Read enable setup time	$T_{RDENSU}$	0.278		0.327		ns
Read enable hold time	$T_{RDENHD}$	0.057		0.067		ns
Read block select setup time	$T_{BLKSU}$	1.839		2.163		ns
Read block select hold time	$T_{BLKHD}$	-0.65		-0.77		ns
Read block select to out disable time (when pipelined register is disabled)	$T_{BLK2Q}$		2.09		2.46	ns
Read asynchronous reset removal time (pipelined clock)	$T_{RSTREM}$	-0.02		-0.03		ns
Read asynchronous reset removal time (non-pipelined clock)		0.046		0.054		ns
Read asynchronous reset recovery time (pipelined clock)	$T_{RSTREC}$	0.507		0.597		ns
Read asynchronous reset recovery time (non-pipelined clock)		0.236		0.278		ns
Read asynchronous reset to output propagation delay (with pipelined register enabled)	$T_{R2Q}$		0.83		0.98	ns
Read synchronous reset setup time	$T_{SRSTSU}$	0.271		0.319		ns
Read synchronous reset hold time	$T_{SRSTHD}$	0.061		0.071		ns
Write clock period	$T_{CCY}$	4		4		ns
Write clock minimum pulse width high	$T_{CCLKMPWH}$	1.8		1.8		ns
Write clock minimum pulse width low	$T_{CCLKMPWL}$	1.8		1.8		ns
Write block setup time	$T_{BLKCSU}$	0.404		0.476		ns
Write block hold time	$T_{BLKCHD}$	0.007		0.008		ns
Write input data setup time	$T_{DINCSU}$	0.101		0.118		ns
Write input data hold time	$T_{DINCHD}$	0.137		0.161		ns
Write address setup time	$T_{ADDRCSU}$	0.088		0.104		ns

**Table 241 •  $\mu$ SRAM (RAM256x4) in 256 x 4 Mode (continued)**

Parameter	Symbol	-1		-Std		Unit
		Min	Max	Min	Max	
Write address hold time	$T_{ADDRCHD}$	0.245		0.288		ns
Write enable setup time	$T_{WECSU}$	0.397		0.467		ns
Write enable hold time	$T_{WECHD}$	-0.03		-0.03		ns
Maximum frequency	$F_{MAX}$		250		250	MHz

The following table lists the  $\mu$ SRAM in 512 x 2 mode in worst commercial-case conditions when  $T_J = 85\text{ }^\circ\text{C}$ ,  $V_{DD} = 1.14\text{ V}$ .

**Table 242 •  $\mu$ SRAM (RAM512x2) in 512 x 2 Mode**

Parameter	Symbol	-1		-Std		Unit
		Min	Max	Min	Max	
Read clock period	$T_{CY}$	4		4		ns
Read clock minimum pulse width high	$T_{CLKMPWH}$	1.8		1.8		ns
Read clock minimum pulse width low	$T_{CLKMPWL}$	1.8		1.8		ns
Read pipeline clock period	$T_{PLCY}$	4		4		ns
Read pipeline clock minimum pulse width high	$T_{PLCLKMPWH}$	1.8		1.8		ns
Read pipeline clock minimum pulse width low	$T_{PLCLKMPWL}$	1.8		1.8		ns
Read access time with pipeline register	$T_{CLK2Q}$		0.27		0.31	ns
Read access time without pipeline register				1.76		2.08
Read address setup time in synchronous mode	$T_{ADDRSU}$	0.301		0.354		ns
Read address setup time in asynchronous mode			1.96		2.306	
Read address hold time in synchronous mode	$T_{ADDRHD}$	0.137		0.161		ns
Read address hold time in asynchronous mode			-0.58		-0.68	
Read enable setup time	$T_{RDENSU}$	0.278		0.327		ns
Read enable hold time	$T_{RDENHD}$	0.057		0.067		ns
Read block select setup time	$T_{BLKSU}$	1.839		2.163		ns
Read block select hold time	$T_{BLKHD}$	-0.65		-0.77		ns
Read block select to out disable time (when pipelined register is disabled)	$T_{BLK2Q}$		2.14		2.52	ns
Read asynchronous reset removal time (pipelined clock)	$T_{RSTREM}$	-0.02		-0.03		ns
Read asynchronous reset removal time (non-pipelined clock)			0.046		0.054	
Read asynchronous reset recovery time (pipelined clock)	$T_{RSTREC}$	0.507		0.597		ns
Read asynchronous reset recovery time (non-pipelined clock)			0.236		0.278	
Read asynchronous reset to output propagation delay (with pipelined register enabled)	$T_{R2Q}$		0.83		0.98	ns
Read synchronous reset setup time	$T_{SRSTSU}$	0.271		0.319		ns
Read synchronous reset hold time	$T_{SRSTHD}$	0.061		0.071		ns

**Table 242 •  $\mu$ SRAM (RAM512x2) in 512 x 2 Mode (continued)**

Parameter	Symbol	-1		-Std		Unit
		Min	Max	Min	Max	
Write clock period	$T_{CCY}$	4		4		ns
Write clock minimum pulse width high	$T_{CCLKMPWH}$	1.8		1.8		ns
Write clock minimum pulse width low	$T_{CCLKMPWL}$	1.8		1.8		ns
Write block setup time	$T_{BLKCSU}$	0.404		0.476		ns
Write block hold time	$T_{BLKCHD}$	0.007		0.008		ns
Write input data setup time	$T_{DINCSU}$	0.101		0.118		ns
Write input data hold time	$T_{DINCHD}$	0.137		0.161		ns
Write address setup time	$T_{ADDRCSU}$	0.088		0.104		ns
Write address hold time	$T_{ADDRCHD}$	0.247		0.29		ns
Write enable setup time	$T_{WECSU}$	0.397		0.467		ns
Write enable hold time	$T_{WECHD}$	-0.03		-0.03		ns
Maximum frequency	$F_{MAX}$		250		250	MHz

The following table lists the  $\mu$ SRAM in 1024 x 1 mode in worst commercial-case conditions when  $T_J = 85^\circ\text{C}$ ,  $V_{DD} = 1.14\text{ V}$ .

**Table 243 •  $\mu$ SRAM (RAM1024x1) in 1024 x 1 Mode**

Parameter	Symbol	-1		-Std		Unit
		Min	Max	Min	Max	
Read clock period	$T_{CY}$	4		4		ns
Read clock minimum pulse width high	$T_{CLKMPWH}$	1.8		1.8		ns
Read clock minimum pulse width low	$T_{CLKMPWL}$	1.8		1.8		ns
Read pipeline clock period	$T_{PLCY}$	4		4		ns
Read pipeline clock minimum pulse width high	$T_{PLCLKMPWH}$	1.8		1.8		ns
Read pipeline clock minimum pulse width low	$T_{PLCLKMPWL}$	1.8		1.8		ns
Read access time with pipeline register	$T_{CLK2Q}$		0.27		0.31	ns
Read access time without pipeline register				1.78		2.1
Read address setup time in synchronous mode	$T_{ADDRSU}$	0.301		0.354		ns
Read address setup time in asynchronous mode			1.978		2.327	
Read address hold time in synchronous mode	$T_{ADDRHD}$	0.137		0.161		ns
Read address hold time in asynchronous mode			-0.6		-0.71	
Read enable setup time	$T_{RDENSU}$	0.278		0.327		ns
Read enable hold time	$T_{RDENHD}$	0.057		0.067		ns
Read block select setup time	$T_{BLKSU}$	1.839		2.163		ns
Read block select hold time	$T_{BLKHHD}$	-0.65		-0.77		ns
Read block select to out disable time (when pipelined register is disabled)	$T_{BLK2Q}$		2.16		2.54	ns
Read asynchronous reset removal time (pipelined clock)	$T_{RSTREM}$	-0.02		-0.03		ns
Read asynchronous reset removal time (non-pipelined clock)			0.046		0.054	

**Table 243 •  $\mu$ SRAM (RAM1024x1) in 1024 x 1 Mode (continued)**

Parameter	Symbol	-1		-Std		Unit
		Min	Max	Min	Max	
Read asynchronous reset recovery time (pipelined clock)	$T_{RSTREC}$	0.507		0.597		ns
Read asynchronous reset recovery time (non-pipelined clock)		0.236		0.278		ns
Read asynchronous reset to output propagation delay (with pipelined register enabled)	$T_{R2Q}$		0.83		0.98	ns
Read synchronous reset setup time	$T_{SRSTSU}$	0.271		0.319		ns
Read synchronous reset hold time	$T_{SRSTHD}$	0.061		0.071		ns
Write clock period	$T_{CCY}$	4		4		ns
Write clock minimum pulse width high	$T_{CCLKMPWH}$	1.8		1.8		ns
Write clock minimum pulse width low	$T_{CCLKMPWL}$	1.8		1.8		ns
Write block setup time	$T_{BLKCSU}$	0.404		0.476		ns
Write block hold time	$T_{BLKCHD}$	0.007		0.008		ns
Write input data setup time	$T_{DINCSU}$	0.003		0.004		ns
Write input data hold time	$T_{DINCHD}$	0.137		0.161		ns
Write address setup time	$T_{ADDRCSU}$	0.088		0.104		ns
Write address hold time	$T_{ADDRCHD}$	0.247		0.29		ns
Write enable setup time	$T_{WECSU}$	0.397		0.467		ns
Write enable hold time	$T_{WECHD}$	-0.03		-0.03		ns
Maximum frequency	$F_{MAX}$		250		250	MHz

### 2.3.13 Programming Times

The following tables list the programming times in typical conditions when  $T_J = 25\text{ }^\circ\text{C}$ ,  $V_{DD} = 1.2\text{ V}$ . External SPI flash part# AT25DF641-s3H is used during this measurement.

**Table 244 • JTAG Programming (Fabric Only)**

M2S/M2GL				
Device	Image size Bytes	Program	Verify	Unit
005	302672	22	10	Sec
010	568784	28	18	Sec
025	1223504	51	26	Sec
050	2424832	66	54	Sec
060	2418896	77	54	Sec
090	3645968	113	126	Sec
150	6139184	155	193	Sec

**Table 262 • SmartFusion2 Cortex-M3 ISP Programming (Fabric Only)**

<b>M2S/M2GL Device</b>	<b>Image size Bytes</b>	<b>Authenticate</b>	<b>Program</b>	<b>Verify</b>	<b>Unit</b>
005	302672	6	41	8	Sec
010	568784	10	48	14	Sec
025	1223504	21	61	29	Sec
050	2424832	39	82	50	Sec
060	2418896	44	87	54	Sec
090	3645968	66	112	79	Sec
150	6139184	108	162	128	Sec

**Table 263 • SmartFusion2 Cortex-M3 ISP Programming (eNVM Only)**

<b>M2S/M2GL Device</b>	<b>Image size Bytes</b>	<b>Authenticate</b>	<b>Program</b>	<b>Verify</b>	<b>Unit</b>
005	137536	3	64	4	Sec
010	274816	4	104	7	Sec
025	274816	4	104	8	Sec
050	2,78,528	4	102	8	Sec
060	268480	6	102	8	Sec
090	544496	10	179	15	Sec
150	544496	10	180	15	Sec

**Table 264 • SmartFusion2 Cortex-M3 ISP Programming (Fabric and eNVM)**

<b>M2S/M2GL Device</b>	<b>Image size Bytes</b>	<b>Authenticate</b>	<b>Program</b>	<b>Verify</b>	<b>Unit</b>
005	439296	9	83	11	Sec
010	842688	15	129	21	Sec
025	1497408	26	143	35	Sec
050	2695168	43	163	55	Sec
060	2686464	48	165	60	Sec
090	4190208	75	266	91	Sec
150	6682768	117	318	141	Sec

## 2.3.20 On-Chip Oscillator

The following tables describe the electrical characteristics of the available on-chip oscillators in the IGLOO2 FPGAs and SmartFusion2 SoC FPGAs.

**Table 280 • Electrical Characteristics of the 50 MHz RC Oscillator**

Parameter	Symbol	Typ	Max	Unit	Condition
Operating frequency	F50RC	50		MHz	
Accuracy	ACC50RC	1	4	%	050 devices
		1	5	%	005, 025, and 060 devices
		1	6.3	%	090 devices
		1	7.1	%	010 and 150 devices
Output duty cycle	CYC50RC	49–51	46.5–53.5	%	
Output jitter (peak to peak)	JIT50RC	Period Jitter			
		200	300	ps	005, 010, 050, and 060 devices
		200	400	ps	150 devices
		300	500	ps	025 and 090 devices
		Cycle-to-Cycle Jitter			
		200	300	ps	005 and 050 devices
		320	420	ps	010, 060, and 150 devices
		320	850	ps	025 and 090 devices
Operating current	IDYN50RC	6.5		mA	

**Table 281 • Electrical Characteristics of the 1 MHz RC Oscillator**

Parameter	Symbol	Typ	Max	Unit	Condition
Operating frequency	F1RC	1		MHz	
Accuracy	ACC1RC	1	3	%	005, 010, 025, and 050 devices
		1	4.5	%	060, and 150 devices
		1	5.6	%	090 devices
Output duty cycle	CYC1RC	49–51	46.5–53.5	%	005, 010, 025, 050, 090 and 150 devices
		49-51	46.0-54.0	%	060 devices
Output jitter (peak to peak)	JIT1RC	Period Jitter			
		10	20	ns	005, 010, 025, and 050 devices
		10	28	ns	060, 090 and 150 devices
		Cycle-to-Cycle Jitter			
		10	20	ns	005, 010, and 050 devices
		10	35	ns	025, 060, and 150 devices
		10	45	ns	090 devices
Operating current	IDYN1RC	0.1		mA	
Startup time	SU1RC	17		μs	050, 090, and 150 devices
		18		μs	005, 010, and 025 devices

## 2.3.22 JTAG

**Table 284 • JTAG 1532 for 005, 010, 025, and 050 Devices**

Parameter	Symbol	005		010		025		050		Unit
		-1	-Std	-1	-Std	-1	-Std	-1	-Std	
Clock to Q (data out)	$T_{TCK2Q}$	7.47	8.79	7.73	9.09	7.75	9.12	7.89	9.28	ns
Reset to Q (data out)	$T_{RSTB2Q}$	7.65	9	6.43	7.56	6.13	7.21	7.40	8.70	ns
Test data input setup time	$T_{DISU}$	-1.05	-0.89	-0.69	-0.59	-0.67	-0.57	-0.30	-0.25	ns
Test data input hold time	$T_{DIHD}$	2.38	2.8	2.38	2.8	2.42	2.85	2.09	2.45	ns
Test mode select setup time	$T_{TMSSU}$	-0.73	-0.62	-1.03	-1.21	-1.1	-0.94	0.28	0.33	ns
Test mode select hold time	$T_{TMDHD}$	1.36	1.6	1.43	1.68	1.93	2.27	0.16	0.19	ns
ResetB removal time	$T_{TRSTREM}$	-0.77	-0.65	-1.08	-0.92	-1.33	-1.13	-0.45	-0.38	ns
ResetB recovery time	$T_{TRSTREC}$	-0.76	-0.65	-1.07	-0.91	-1.34	-1.14	-0.45	-0.38	ns
TCK maximum frequency	$F_{TCKMAX}$	25	21.25	25	21.25	25	21.25	25.00	21.25	MHz

**Table 285 • JTAG 1532 for 060, 090, and 150 Devices**

Parameter	Symbol	060		090		150		Unit
		-1	-Std	-1	-Std	-1	-Std	
Clock to Q (data out)	$T_{TCK2Q}$	8.38	9.86	8.96	10.54	8.66	10.19	ns
Reset to Q (data out)	$T_{RSTB2Q}$	8.54	10.04	7.75	9.12	8.79	10.34	ns
Test data input setup time	$T_{DISU}$	-1.18	-1	-1.31	-1.11	-0.96	-0.82	ns
Test data input hold time	$T_{DIHD}$	2.52	2.97	2.68	3.15	2.57	3.02	ns
Test mode select setup time	$T_{TMSSU}$	-0.97	-0.83	-1.02	-0.87	-0.53	-0.45	ns
Test mode select hold time	$T_{TMDHD}$	1.7	2	1.67	1.96	1.02	1.2	ns
ResetB removal time	$T_{TRSTREM}$	-1.21	-1.03	-0.76	-0.65	-1.03	-0.88	ns
ResetB recovery time	$T_{TRSTREC}$	-1.21	-1.03	-0.77	-0.65	-1.03	-0.88	ns
TCK maximum frequency	$F_{TCKMAX}$	25	21.25	25	21.25	25	21.25	MHz

## 2.3.23 System Controller SPI Characteristics



The following table lists the system controller characteristics in worst-case industrial conditions when  $T_J = 100\text{ }^\circ\text{C}$ ,  $V_{DD} = 1.14\text{ V}$ .

**Table 286 • System Controller SPI Characteristics for All Devices**

Symbol	Description	Conditions	Min	Typ	Unit
sp1	SC_SPI_SCK minimum period		20		ns
sp2	SC_SPI_SCK minimum pulse width high		10		ns
sp3	SC_SPI_SCK minimum pulse width low		10		ns
sp4 <sup>1</sup>	SC_SPI_SCK, SC_SPI_SDO, SC_SPI_SS rise time (10%–90%) 1	I/O configuration: LVTTTL 3.3 V–20 mA AC loading: 35 pF Test conditions: Typical voltage, 25 °C		1.239	ns
sp5 <sup>1</sup>	SC_SPI_SCK, SC_SPI_SDO, SC_SPI_SS fall time (10%–90%) 1	I/O configuration: LVTTTL 3.3 V–20 mA AC loading: 35 pF Test conditions: Typical voltage, 25 °C		1.245	ns
sp6	Data from master (SC_SPI_SDO) setup time		160		ns
sp7	Data from master (SC_SPI_SDO) hold time		160		ns
sp8	SC_SPI_SDI setup time		20		ns
sp9	SC_SPI_SDI hold time		20		ns

- For specific Rise/Fall Times, board design considerations and detailed output buffer resistances, use the corresponding IBIS models located on the Microsemi SoC Products Group website: <http://www.microsemi.com/soc/download/ibis/default.aspx>. Use the supported I/O Configurations for the System Controller SPI in the following table.

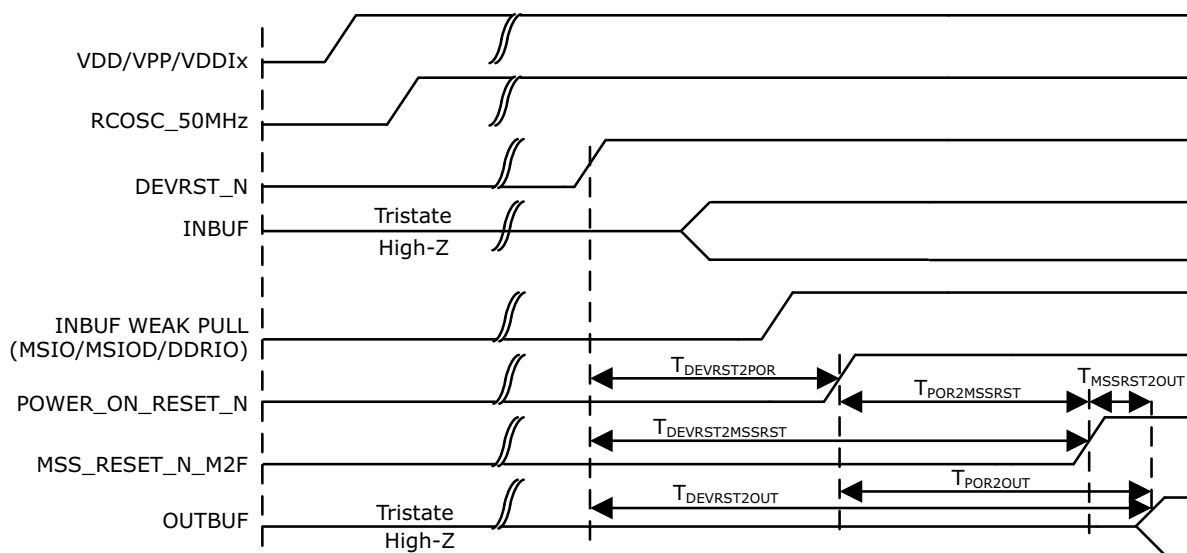
**Table 287 • Supported I/O Configurations for System Controller SPI (for MSIO Bank Only)**

Voltage Supply	I/O Drive Configuration	Unit
3.3 V	20	mA
2.5 V	16	mA
1.8 V	12	mA
1.5 V	8	mA
1.2 V	4	mA

**Table 291 • DEVRST\_N to Functional Times for SmartFusion2 (continued)**

Symbol	From	To	Description	Maximum Power-up to Functional Time for SmartFusion2 (uS)						
				005	010	025	050	060	090	150
$T_{DEVRST2POR}$	DEVRST_N	POWER_ON_RESET_N	$V_{DD}$ at its minimum threshold level to fabric	233	289	216	213	237	234	219
$T_{DEVRST2MSSRST}$	DEVRST_N	MSS_RESET_N_M2F	$V_{DD}$ at its minimum threshold level to MSS	702	765	712	688	636	630	866
$T_{DEVRST2WPU}$	DEVRST_N	DDRIO Inbuf weak pull	DEVRST_N to Inbuf weak pull	208	202	197	193	216	215	215
	DEVRST_N	MSIO Inbuf weak pull	DEVRST_N to Inbuf weak pull	208	202	197	193	216	215	215
	DEVRST_N	MSIOD Inbuf weak pull	DEVRST_N to Inbuf weak pull	208	202	197	193	216	215	215

**Figure 19 • DEVRST\_N to Functional Timing Diagram for SmartFusion2**



**Table 293 • Flash\*Freeze Entry and Exit Times (continued)**

Parameter	Symbol	Entry/Exit Timing			Unit	Conditions
		FCLK = 100MHz		FCLK = 3 MHz		
		005, 010, 025, 060, 090, and 150	050	All Devices		
Exit time with respect to the fabric PLL lock <sup>1</sup>	TFF_EXIT	1.5	1.5	1.5	ms	eNVM and MSS/HPMS PLL = ON during F*F
		1.5	1.5	1.5	ms	eNVM and MSS/HPMS PLL = OFF during F*F and both are turned back on at exit
Exit time with respect to the fabric buffer output	TFF_EXIT	21	15	21	µs	eNVM and MSS/HPMS PLL = ON during F*F
		65	55	65	µs	eNVM and MSS/HPMS PLL = OFF during F*F and both are turned back on at exit

1. PLL Lock Delay set to 1024 cycles (default).

### 2.3.28 DDR Memory Interface Characteristics

The following table lists the DDR memory interface characteristics in worst-case industrial conditions when  $T_J = 100\text{ }^\circ\text{C}$ ,  $V_{DD} = 1.14\text{ V}$ .

**Table 294 • DDR Memory Interface Characteristics**

Standard	Supported Data Rate		Unit
	Min	Max	
DDR3	667	667	Mbps
DDR2	667	667	Mbps
LPDDR	50	400	Mbps

### 2.3.29 SFP Transceiver Characteristics

IGLOO2 and SmartFusion2 SerDes complies with small form-factor pluggable (SFP) requirements as specified in SFP INF-80741. The following table provides the electrical characteristics.

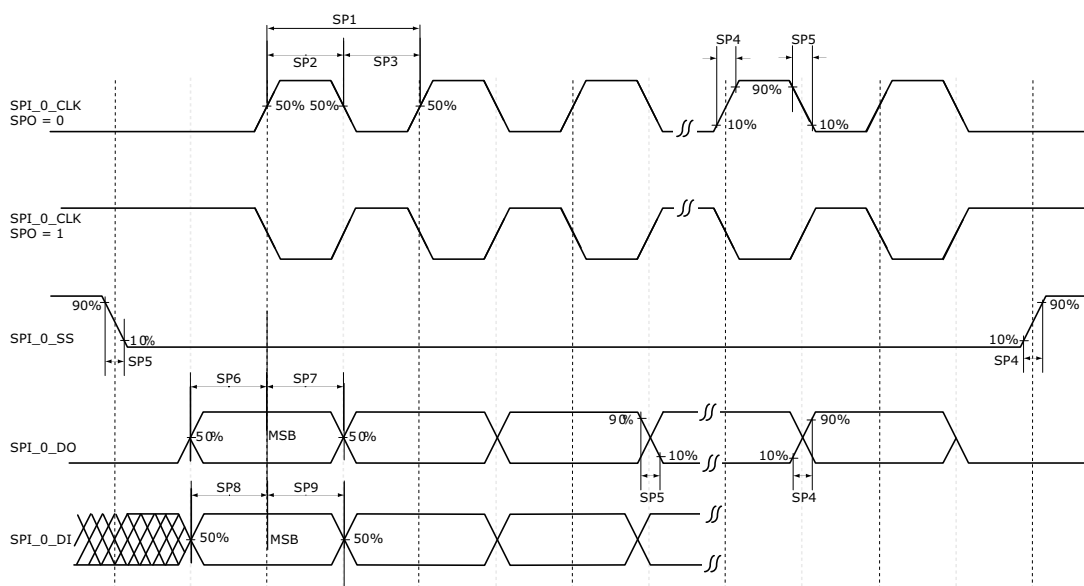
The following table lists the SFP transceiver electrical characteristics in worst-case industrial conditions when  $T_J = 100\text{ }^\circ\text{C}$ ,  $V_{DD} = 1.14\text{ V}$ .

**Table 295 • SFP Transceiver Electrical Characteristics**

Pin	Direction	Differential Peak-Peak Voltage		Unit
		Min	Max	
RD+/- <sup>1</sup>	Output	1600	2400	mV
TD+/- <sup>2</sup>	Input	350	2400	mV

1. Based on default SerDes transmitter settings for PCIe Gen1. Lower amplitudes are available through programming changes to TX\_AMP setting.
2. Based on Input Voltage Common-Mode (VICM) = 0 V. Requires AC Coupling.

Figure 22 • SPI Timing for a Single Frame Transfer in Motorola Mode (SPH = 1)



### 2.3.32 CAN Controller Characteristics

The following table lists the CAN controller characteristics in worst-case industrial conditions when  $T_J = 100\text{ }^\circ\text{C}$ ,  $V_{DD} = 1.14\text{ V}$ .

Table 306 • CAN Controller Characteristics

Parameter	Description	-1	-Std	Unit
FCANREFCLK <sup>1</sup>	Internally sourced CAN reference clock frequency	160	136	MHz
BAUDCANMAX	Maximum CAN performance baud rate	1	1	Mbps
BAUDCANMIN	Minimum CAN performance baud rate	0.05	0.05	Mbps

1. PCLK to CAN controller must be a multiple of 8 MHz.

### 2.3.33 USB Characteristics

The following table lists the USB characteristics in worst-case industrial conditions when  $T_J = 100\text{ }^\circ\text{C}$ ,  $V_{DD} = 1.14\text{ V}$ .

Table 307 • USB Characteristics

Parameter	Description	-1	-Std	Unit
FUSBREFCLK	Internally sourced USB reference clock frequency	166	142	MHz
TUSBCLK	USB clock period	16.66	16.66	ns
TUSBPD	Clock to USB data propagation delay	9.0	9.0	ns
TUSBSU	Setup time for USB data	6.0	6.0	ns
TUSBHD	Hold time for USB data	0	0	ns

**Table 310 • SPI Characteristics for All Devices (continued)**

Symbol	Description	Min	Typ	Max	Unit	Conditions
SPI master configuration (applicable for 060, 090, and 150 devices)						
sp6m	SPI_[0 1]_DO setup time <sup>2</sup>	(SPI_x_CLK_period/2) – 7.0			ns	
sp7m	SPI_[0 1]_DO hold time <sup>2</sup>	(SPI_x_CLK_period/2) – 9.5			ns	
sp8m	SPI_[0 1]_DI setup time <sup>2</sup>	15			ns	
sp9m	SPI_[0 1]_DI hold time <sup>2</sup>	–2.5			ns	
SPI slave configuration (applicable for 060, 090, and 150 devices)						
sp6s	SPI_[0 1]_DO setup time <sup>2</sup>	(SPI_x_CLK_period/2) – 16.0			ns	
sp7s	SPI_[0 1]_DO hold time <sup>2</sup>	(SPI_x_CLK_period/2) – 3.5			ns	
sp8s	SPI_[0 1]_DI setup time <sup>2</sup>	3			ns	
sp9s	SPI_[0 1]_DI hold time <sup>2</sup>	2.5			ns	

1. For specific Rise/Fall Times board design considerations and detailed output buffer resistances, use the corresponding IBIS models located on the Microsemi SoC Products Group website: <http://www.microsemi.com/soc/download/ibis/default.aspx>.
2. For allowable pclk configurations, see the Serial Peripheral Interface Controller section in the *UG0331: SmartFusion2 Microcontroller Subsystem User Guide*.

**Figure 23 • SPI Timing for a Single Frame Transfer in Motorola Mode (SPH = 1)**

