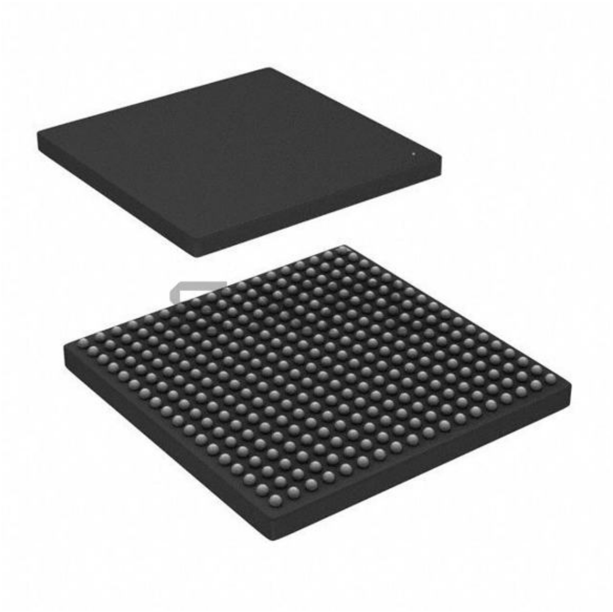
Microchip Technology - M2GL025-FCSG325 Datasheet



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Understanding Embedded - FPGAs (Field Programmable Gate Array)

Embedded - FPGAs, or Field Programmable Gate Arrays, are advanced integrated circuits that offer unparalleled flexibility and performance for digital systems. Unlike traditional fixed-function logic devices, FPGAs can be programmed and reprogrammed to execute a wide array of logical operations, enabling customized functionality tailored to specific applications. This reprogrammability allows developers to iterate designs quickly and implement complex functions without the need for custom hardware.

Applications of Embedded - FPGAs

The versatility of Embedded - FPGAs makes them indispensable in numerous fields. In telecommunications,

Details	
Product Status	Active
Number of LABs/CLBs	-
Number of Logic Elements/Cells	27696
Total RAM Bits	1130496
Number of I/O	180
Number of Gates	-
Voltage - Supply	1.14V ~ 2.625V
Mounting Type	Surface Mount
Operating Temperature	0°C ~ 85°C (TJ)
Package / Case	325-TFBGA, FCBGA
Supplier Device Package	325-FCBGA (11x11)
Purchase URL	https://www.e-xfl.com/product-detail/microchip-technology/m2gl025-fcsg325

Table 9 • **Package Thermal Resistance of SmartFusion2 and IGLOO2 Devices *(continued)***

	Still Air	**1.0 m/s**	**2.5 m/s**			
Device		θ_{JA}		θ_{JB}	θ_{JC}	**Unit**
150						
FC1152	9.08	6.81	5.87	2.56	0.38	°C/W
FCS536	15.01	12.06	10.76	3.69	1.55	°C/W
FCV484	16.21	13.11	11.84	6.73	0.10	°C/W

2.3.1.2.1 Theta-JA

Junction-to-ambient thermal resistance (θ_{JA}) is determined under standard conditions specified by JEDEC (JESD-51), but it has little relevance in the actual performance of the product. It must be used with caution, but it is useful for comparing the thermal performance of one package with another.

The maximum power dissipation allowed is calculated using EQ4.

$$\text{Maximum power allowed} = \frac{T_{J(MAX)} - T_{A(MAX)}}{\theta_{JA}}$$

EQ 4

The absolute maximum junction temperature is 100 °C. EQ5 shows a sample calculation of the absolute maximum power dissipation allowed for the M2GL050T-FG896 package at commercial temperature and in still air, where:

θ_{JA} = 14.7 °C/W (taken from Table 9, page 10).

T_A = 85 °C

$$\text{Maximum power allowed} = \frac{100\ °\text{C} - 85\ °\text{C}}{14.7\ °\text{C/W}} = 1.088\ \text{W}$$

EQ 5

The power consumption of a device can be calculated using the Microsemi SoC Products Group power calculator. The device's power consumption must be lower than the calculated maximum power dissipation by the package.

If the power consumption is higher than the device's maximum allowable power dissipation, a heat sink may be attached to the top of the case, or the airflow inside the system must be increased.

2.3.1.2.2 Theta-JB

Junction-to-board thermal resistance (θ_{JB}) measures the ability of the package to dissipate heat from the surface of the chip to the PCB. As defined by the JEDEC (JESD-51) standard, the thermal resistance from the junction to the board uses an isothermal ring cold plate zone concept. The ring cold plate is simply a means to generate an isothermal boundary condition at the perimeter. The cold plate is mounted on a JEDEC standard board with a minimum distance of 5.0 mm away from the package edge.

2.3.1.2.3 Theta-JC

Junction-to-case thermal resistance (θ_{JC}) measures the ability of a device to dissipate heat from the surface of the chip to the top or bottom surface of the package. It is applicable to packages used with external heat sinks. Constant temperature is applied to the surface, which acts as a boundary condition.

This only applies to situations where all or nearly all of the heat is dissipated through the surface in consideration.

2.3.1.3 ESD Performance

See *RT0001: Microsemi Corporation - SoC Products Reliability Report* for information about ESD.

Table 58 • **LVCMOS 1.8 V Transmitter Characteristics for MSIO I/O Bank**

Output Drive Selection	Slew Control	T_{DP}		T_{ZL}		T_{ZH}		T_{HZ}[1]		T_{LZ}[1]		Unit
		–1	–Std	–1	–Std	–1	–Std	–1	–Std	–1	–Std	
2 mA	Slow	3.441	4.047	4.165	4.9	4.413	5.192	4.891	5.755	5.138	6.044	ns
4 mA	Slow	3.218	3.786	3.642	4.284	3.941	4.636	5.665	6.665	5.568	6.551	ns
6 mA	Slow	3.141	3.694	3.501	4.118	3.823	4.498	6.587	7.75	6.032	7.096	ns
8 mA	Slow	3.165	3.723	3.319	3.904	3.654	4.298	6.898	8.115	6.216	7.313	ns
10 mA	Slow	3.202	3.767	3.278	3.857	3.616	4.254	7.25	8.529	6.435	7.571	ns
12 mA	Slow	3.277	3.855	3.175	3.736	3.519	4.139	7.392	8.697	6.538	7.692	ns

1. Delay increases with drive strength are inherent to built-in slew control circuitry for simultaneous switching output (SSO) management.

Table 59 • **LVCMOS 1.8 V Transmitter Characteristics for MSIOD I/O Bank**

Output Drive Selection	Slew Control	T_{DP}		T_{ZL}		T_{ZH}		T_{HZ}[1]		T_{LZ}[1]		Unit
		–1	–Std	–1	–Std	–1	–Std	–1	–Std	–1	–Std	
2 mA	Slow	2.725	3.206	3.316	3.901	3.484	4.099	5.204	6.123	4.997	5.88	ns
4 mA	Slow	2.242	2.638	2.777	3.267	2.947	3.466	5.729	6.74	5.448	6.41	ns
6 mA	Slow	1.995	2.347	2.466	2.901	2.63	3.094	6.372	7.496	5.987	7.043	ns
8 mA	Slow	2.001	2.354	2.44	2.87	2.6	3.058	6.633	7.804	6.193	7.286	ns
10 mA	Slow	2.025	2.382	2.312	2.719	2.47	2.906	6.94	8.165	6.412	7.544	ns

1. Delay increases with drive strength are inherent to built-in slew control circuitry for simultaneous switching output (SSO) management.

2.3.5.9 1.5 V LVCMOS

LVCMOS 1.5 is a general standard for 1.5 V applications and is supported in IGLOO2 FPGAs and SmartFusion2 SoC FPGAs in compliance to the JEDEC specification JESD8-11A.

Minimum and Maximum DC/AC Input and Output Levels Specification

Table 60 • **LVCMOS 1.5 V DC Recommended Operating Conditions**

Parameter	Symbol	Min	Typ	Max	Unit
Supply voltage	V_{DDI}	1.425	1.5	1.575	V

Table 61 • **LVCMOS 1.5 V DC Input Voltage Specification**

Parameter	Symbol	Min	Max	Unit
DC input logic high for (MSIOD and DDRIO I/O banks)	V_{IH} (DC)	0.65 × V_{DDI}	1.575	V
DC input logic high (for MSIO I/O bank)	V_{IH} (DC)	0.65 × V_{DDI}	3.45	V
DC input logic low	V_{IL} (DC)	–0.3	0.35 × V_{DDI}	V
Input current high[1]	I_{IH} (DC)			–
Input current low[1]	I_{IL} (DC			–

1. See Table 24, page 22.

Table 72 • **LVCMOS 1.5 V Transmitter Characteristics for MSIOD I/O Bank (Output and Tristate Buffers)**

Output Drive Selection	Slew Control	T_{DP}		T_{ZL}		T_{ZH}		T_{HZ}[1]		T_{LZ}[1]		Unit
		–1	–Std	–1	–Std	–1	–Std	–1	–Std	–1	–Std	
2 mA	Slow	2.735	3.218	3.371	3.966	3.618	4.257	6.03	7.095	5.705	6.712	ns
4 mA	Slow	2.426	2.854	2.992	3.521	3.221	3.79	6.738	7.927	6.298	7.41	ns
6 mA	Slow	2.433	2.862	2.81	3.306	3.031	3.566	7.123	8.38	6.596	7.76	ns

1. Delay increases with drive strength are inherent to built-in slew control circuitry for simultaneous switching output (SSO) management.

2.3.5.10 1.2 V LVCMOS

LVCMOS 1.2 is a general standard for 1.2 V applications and is supported in IGLOO2 FPGAs and SmartFusion2 SoC FPGAs in compliance to the JEDEC specification JESD8-12A.

Minimum and Maximum DC/AC Input and Output Levels Specification

Table 73 • **LVCMOS 1.2 V DC Recommended DC Operating Conditions**

Parameter	Symbol	Min	Typ	Max	Unit
Supply voltage	V_{DDI}	1.140	1.2	1.26	V

Table 74 • **LVCMOS 1.2 V DC Input Voltage Specification**

Parameter	Symbol	Min	Max	Unit
DC input logic high (for MSIOD and DDRIO I/O banks)	V_{IH} (DC)	0.65 × V_{DDI}	1.26	V
DC input logic high (for MSIO I/O bank)	V_{IH} (DC)	0.65 × V_{DDI}	3.45	V
DC input logic low	V_{IL} (DC)	–0.3	0.35 × V_{DDI}	V
Input current high[1]	I_{IH} (DC)			
Input current low[1]	I_{IL} (DC)			

1. See Table 24, page 22.

Table 75 • **LVCMOS 1.2 V DC Output Voltage Specification**

Parameter	Symbol	Min	Max	Unit
DC output logic high	V_{OH}	V_{DDI} × 0.75		V
DC output logic low	V_{OL}		V_{DDI} × 0.25	V

Table 76 • **LVCMOS 1.2 V Minimum and Maximum AC Switching Speed**

Parameter	Symbol	Max	Unit	Conditions
Maximum data rate (for DDRIO I/O bank)	D_{MAX}	200	Mbps	AC loading: 17 pF load, maximum drive/slew
Maximum data rate (for MSIO I/O bank)	D_{MAX}	120	Mbps	AC loading: 17 pF load, maximum drive/slew
Maximum data rate (for MSIOD I/O bank)	D_{MAX}	160	Mbps	AC loading: 17 pF load, maximum drive/slew

Table 85 • **LVCMOS 1.2 V Transmitter Characteristics for MSIOD I/O Bank (Output and Tristate Buffers)**

Output Drive Selection	Slew Control	T_{DP}		T_{ZL}		T_{ZH}		T_{HZ}[1]		T_{LZ}[1]		Unit
		–1	–Std	–1	–Std	–1	–Std	–1	–Std	–1	–Std	
2 mA	Slow	3.883	4.568	4.868	5.726	5.329	6.269	7.994	9.404	7.527	8.855	ns
4 mA	Slow	3.774	4.44	4.188	4.926	4.613	5.426	8.972	10.555	8.315	9.782	ns

1. Delay increases with drive strength are inherent to built-in slew control circuitry for simultaneous switching output (SSO) management.

2.3.5.11 3.3 V PCI/PCIX

Peripheral Component Interface (PCI) for 3.3 V standards specify support for 33 MHz and 66 MHz PCI bus applications.

Minimum and Maximum DC/AC Input and Output Levels Specification (Applicable to MSIO Bank Only)

Table 86 • **PCI/PCI-X DC Recommended Operating Conditions**

Parameter	Symbol	Min	Typ	Max	Unit
Supply voltage	V_{DDI}	3.15	3.3	3.45	V

Table 87 • **PCI/PCI-X DC Input Voltage Specification**

Parameter	Symbol	Min	Max	Unit
DC input voltage	V_I	0	3.45	V
Input current high[1]	I_{IH}(DC)			
Input current low[1]	I_{IL}(DC)			

1. See Table 24, page 22.

Table 88 • **PCI/PCI-X DC Output Voltage Specification**

Parameter	Symbol	Min	Typ	Max	Unit
DC output logic high	V_{OH}	Per PCI specification			V
DC output logic low	V_{OL}	Per PCI specification			V

Table 89 • **PCI/PCI-X Minimum and Maximum AC Switching Speed**

Parameter	Symbol	Max	Unit	Conditions
Maximum data rate (MSIO I/O bank)	D_{MAX}	630	Mbps	AC Loading: per JEDEC specifications

Table 90 • **PCI/PCI-X AC Test Parameter Specifications**

Parameter	Symbol	Typ	Unit
Measuring/trip point for data path (falling edge)	V_{TRIP}	0.615 × V_{DDI}	V
Measuring/trip point for data path (rising edge)	V_{TRIP}	0.285 × V_{DDI}	V
Resistance for data test path	RTT_TEST	25	Ω
Resistance for enable path (T_{ZH}, T_{ZL}, T_{HZ}, T_{LZ})	R_{ENT}	2K	Ω
Capacitive loading for enable path (T_{ZH}, T_{ZL}, T_{HZ}, T_{LZ})	C_{ENT}	5	pF
Capacitive loading for data path (T_{DP})	C_{LOAD}	10	pF

AC Switching Characteristics

Worst commercial-case conditions: T_J = 85 °C, V_{DD} = 1.14 V, V_{DDI} = 3.0 V

Table 91 • **PCI/PCIX AC Switching Characteristics for Receiver for MSIO I/O Bank (Input Buffers)**

	T_{PY}		T_{PYS}		
On-Die Termination (ODT)	**–1**	**–Std**	**–1**	**–Std**	**Unit**
None	2.229	2.623	2.238	2.633	ns

Table 92 • **PCI/PCIX AC switching Characteristics for Transmitter for MSIO I/O Bank (Output and Tristate Buffers)**

T_{DP}		T_{ZL}		T_{ZH}		T_{HZ}		T_{LZ}		
–1	**–Std**	**–1**	**–Std**	**–1**	**–Std**	**–1**	**–Std**	**–1**	**–Std**	**Unit**
2.146	2.525	2.043	2.404	2.084	2.452	6.095	7.171	5.558	6.539	ns

2.3.6 Memory Interface and Voltage Referenced I/O Standards

This section describes High-Speed Transceiver Logic (HSTL) memory interface and voltage reference I/O standards.

2.3.6.1 High-Speed Transceiver Logic (HSTL)

The HSTL standard is a general purpose high-speed bus standard sponsored by IBM (EIA/JESD8-6). IGLOO2 FPGA and SmartFusion2 SoC FPGA devices support two classes of the 1.5 V HSTL. These differential versions of the standard require a differential amplifier input buffer and a push-pull output buffer.

Minimum and Maximum DC/AC Input and Output Levels Specification (Applicable to DDRIO Bank Only)

Table 93 • **HSTL Recommended DC Operating Conditions**

Parameter	Symbol	Min	Typ	Max	Unit
Supply voltage	V_{DDI}	1.425	1.5	1.575	V
Termination voltage	V_{TT}	0.698	0.750	0.803	V
Input reference voltage	V_{REF}	0.698	0.750	0.803	V

Table 94 • **HSTL DC Input Voltage Specification**

Parameter	Symbol	Min	Max	Unit
DC input logic high	V_{IH} (DC)	V_{REF} + 0.1	1.575	V
DC input logic low	V_{IL} (DC)	–0.3	V_{REF} – 0.1	V
Input current high[1]	I_{IH} (DC)			
Input current low[1]	I_{IL} (DC)			

1. See Table 24, page 22.

Table 95 • **HSTL DC Output Voltage Specification Applicable to DDRIO I/O Bank Only**

Parameter	Symbol	Min	Max	Unit
	HSTL Class I			
DC output logic high	V_{OH}	V_{DDI} – 0.4		V
DC output logic low	V_{OL}		0.4	V
Output minimum source DC current (MSIO and DDRIO I/O banks)	I_{OH} at V_{OH}	–8.0		mA
Output minimum sink current (MSIO and DDRIO I/O banks)	I_{OL} at V_{OL}	8.0		mA
	HSTL Class II			
DC output logic high	V_{OH}	V_{DDI} – 0.4		V
DC output logic low	V_{OL}		0.4	V
Output minimum source DC current	I_{OH} at V_{OH}	–16.0		mA
Output minimum sink current	I_{OL} at V_{OL}	16.0		mA

Table 96 • **HSTL DC Differential Voltage Specification**

Parameter	Symbol	Min	Unit
DC input differential voltage	V_{ID} (DC)	0.2	V

Table 97 • **HSTL AC Differential Voltage Specifications**

Parameter	Symbol	Min	Max	Unit
AC input differential voltage	V_{DIFF}	0.4		V
AC differential cross point voltage	V_x	0.68	0.9	V

Table 98 • **HSTL Minimum and Maximum AC Switching Speed**

Parameter	Symbol	Max	Unit	Conditions
Maximum data rate	D_{MAX}	400	Mbps	AC loading: per JEDEC specifications

Table 99 • **HSTL Impedance Specification**

Parameter	Symbol	Typ	Unit	Conditions
Supported output driver calibrated impedance (for DDRIO I/O bank)	R_{REF}	25.5, 47.8	Ω	Reference resistance = 191 Ω
Effective impedance value (ODT for DDRIO I/O bank only)	R_{TT}	47.8	Ω	Reference resistance = 191 Ω

***Table 144* • LPDDR AC Differential Voltage Specifications (for DDRIO I/O Bank Only)**

Parameter	Symbol	Min	Max	Unit
AC input differential voltage	V_{DIFF}	0.6 × V_{DDI}		V
AC differential cross point voltage	V_x	0.4 × V_{DDI}	0.6 × V_{DDI}	V

***Table 145* • LPDDR AC Specifications (for DDRIO I/O Bank Only)**

Parameter	Symbol	Max	Unit	Conditions
Maximum data rate	D_{MAX}	400	Mbps	AC loading: per JEDEC specifications

***Table 146* • LPDDR AC Calibrated Impedance Option (for DDRIO I/O Bank Only)**

Parameter	Symbol	Typ	Unit	Conditions
Supported output driver calibrated impedance	R_{REF}	20, 42	Ω	Reference resistor = 150 Ω
Effective impedance value (ODT)	R_{TT}	50, 70, 150	Ω	Reference resistor = 150 Ω

***Table 147* • LPDDR AC Test Parameter Specifications (for DDRIO I/O Bank Only)**

Parameter	Symbol	Typ	Unit
Measuring/trip point for data path	V_{TRIP}	0.9	V
Resistance for enable path (T_{ZH}, T_{ZL}, T_{HZ}, T_{LZ})	R_{ENT}	2K	Ω
Capacitive loading for enable path (T_{ZH}, T_{ZL}, T_{HZ}, T_{LZ})	C_{ENT}	5	pF
Reference resistance for data test path for LPDDR (T_{DP})	RTT_TEST	50	Ω
Capacitive loading for data path (T_{DP})	C_{LOAD}	5	Ω

AC Switching Characteristics

Worst-case commercial conditions: T_J = 85 °C, V_{DD} = 1.14 V, worst-case V_{DDI}.

***Table 148* • LPDDR Receiver Characteristics for DDRIO I/O Bank with Fixed Codes**

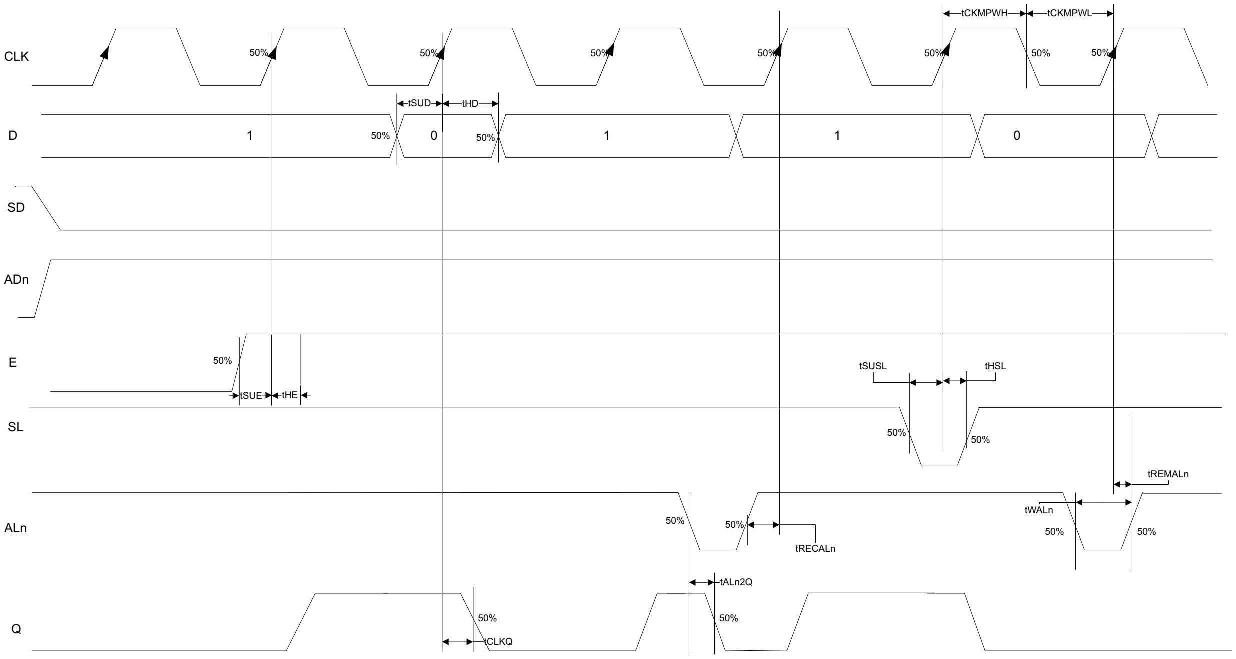
		T_{PY}		
	On-Die Termination (ODT)	**–1**	**–Std**	**Unit**
Pseudo differential	None	1.568	1.845	ns
True differential	None	1.588	1.869	ns

***Table 149* • LPDDR Reduced Drive for DDRIO I/O Bank (Output and Tristate Buffers)**

	T_{DP}		T_{ENZL}		T_{ENZH}		T_{ENHZ}		T_{ENLZ}		
	–1	**–Std**	**–1**	**–Std**	**–1**	**–Std**	**–1**	**–Std**	**–1**	**–Std**	**Unit**
Single-ended	2.383	2.804	2.23	2.623	2.229	2.622	2.202	2.591	2.201	2.59	ns
Differential	2.396	2.819	2.764	3.252	2.764	3.252	2.255	2.653	2.255	2.653	ns

The following figure shows a configuration with SD = 0 (synchronous clear) and ADn = 1 (asynchronous clear) for a flip-flop (LAT = 0).

Figure 16 • **Sequential Module Timing Diagram**



2.3.10.3.1 Timing Characteristics

The following table lists the register delays in worst commercial-case conditions when T_J = 85 °C, V_{DD} = 1.14 V.

Table 224 • **Register Delays**

Parameter	Symbol	–1	–Std	Unit
Clock-to-Q of the core register	T_{CLKQ}	0.108	0.127	ns
Data setup time for the core register	T_{SUD}	0.254	0.298	ns
Data hold time for the core register	T_{HD}	0	0	ns
Enable setup time for the core register	T_{SUE}	0.335	0.394	ns
Enable hold time for the core register	T_{HE}	0	0	ns
Synchronous load setup time for the core register	T_{SUSL}	0.335	0.394	ns
Synchronous load hold time for the core register	T_{HSL}	0	0	ns
Asynchronous Clear-to-Q of the core register (ADn = 1)	T_{ALN2Q}	0.473	0.556	ns
Asynchronous preset-to-Q of the core register (ADn = 0)		0.451	0.531	ns
Asynchronous load removal time for the core register	T_{REMALN}	0	0	ns
Asynchronous load recovery time for the core register	T_{RECALN}	0.353	0.415	ns
Asynchronous load minimum pulse width for the core register	T_{WALN}	0.266	0.313	ns
Clock minimum pulse width high for the core register	T_{CKMPWH}	0.065	0.077	ns
Clock minimum pulse width low for the core register	T_{CKMPWL}	0.139	0.164	ns

Table 232 • **RAM1K18 – Dual-Port Mode for Depth × Width Configuration 2K × 9** ***(continued)***

		–1		–Std		
Parameter	**Symbol**	**Min**	**Max**	**Min**	**Max**	**Unit**
Address setup time	T_{ADDRSU}	0.475		0.559		ns
Address hold time	T_{ADDRHD}	0.274		0.322		ns
Data setup time	T_{DSU}	0.336		0.395		ns
Data hold time	T_{DHD}	0.082		0.096		ns
Block select setup time	T_{BLKSU}	0.207		0.244		ns
Block select hold time	T_{BLKHD}	0.216		0.254		ns
Block select to out disable time (when pipelined register is disabled)	T_{BLK2Q}		1.529		1.799	ns
Block select minimum pulse width	T_{BLKMPW}	0.186		0.219		ns
Read enable setup time	T_{RDESU}	0.485		0.57		ns
Read enable hold time	T_{RDEHD}	0.071		0.083		ns
Pipelined read enable setup time (A_DOUT_EN, B_DOUT_EN)	$T_{RDPLESU}$	0.248		0.291		ns
Pipelined read enable hold time (A_DOUT_EN, B_DOUT_EN)	$T_{RDPLEHD}$	0.102		0.12		ns
Asynchronous reset to output propagation delay	T_{R2Q}		1.514		1.781	ns
Asynchronous reset removal time	T_{RSTREM}	0.506		0.595		ns
Asynchronous reset recovery time	T_{RSTREC}	0.004		0.005		ns
Asynchronous reset minimum pulse width	T_{RSTMPW}	0.301		0.354		ns
Pipelined register asynchronous reset removal time	$T_{PLRSTREM}$	–0.279		–0.328		ns
Pipelined register asynchronous reset recovery time	$T_{PLRSTREC}$	0.327		0.385		ns
Pipelined register asynchronous reset minimum pulse width	$T_{PLRSTMPW}$	0.282		0.332		ns
Synchronous reset setup time	T_{SRSTSU}	0.226		0.265		ns
Synchronous reset hold time	T_{SRSTHD}	0.036		0.043		ns
Write enable setup time	T_{WESU}	0.415		0.488		ns
Write enable hold time	T_{WEHD}	0.048		0.057		ns
Maximum frequency	F_{MAX}		400		340	MHz

The following table lists the RAM1K18 – dual-port mode for depth × width configuration 4K × 4 in worst commercial-case conditions when T_J = 85 °C, V_{DD} = 1.14 V.

Table 233 • **RAM1K18 – Dual-Port Mode for Depth × Width Configuration 4K × 4**

		–1		–Std		
Parameter	**Symbol**	**Min**	**Max**	**Min**	**Max**	**Unit**
Clock period	T_{CY}	2.5		2.941		ns
Clock minimum pulse width high	$T_{CLKMPWH}$	1.125		1.323		ns
Clock minimum pulse width low	$T_{CLKMPWL}$	1.125		1.323		ns
Pipelined clock period	T_{PLCY}	2.5		2.941		ns
Pipelined clock minimum pulse width high	$T_{PLCLKMPWH}$	1.125		1.323		ns

The following table lists the RAM1K18 – two-port mode for depth × width configuration 512 × 36 in worst commercial-case conditions when T_J = 85 °C, V_{DD} = 1.14 V.

Table 236 • **RAM1K18 – Two-Port Mode for Depth × Width Configuration 512 × 36**

		–1		–Std		
Parameter	**Symbol**	**Min**	**Max**	**Min**	**Max**	**Unit**
Clock period	T_{CY}	2.5		2.941		ns
Clock minimum pulse width high	$T_{CLKMPWH}$	1.125		1.323		ns
Clock minimum pulse width low	$T_{CLKMPWL}$	1.125		1.323		ns
Pipelined clock period	T_{PLCY}	2.5		2.941		ns
Pipelined clock minimum pulse width high	$T_{PLCLKMPWH}$	1.125		1.323		ns
Pipelined clock minimum pulse width low	$T_{PLCLKMPWL}$	1.125		1.323		ns
Read access time with pipeline register	T_{CLK2Q}		0.334		0.393	ns
Read access time without pipeline register			2.25		2.647	ns
Address setup time	T_{ADDRSU}	0.313		0.368		ns
Address hold time	T_{ADDRHD}	0.274		0.322		ns
Data setup time	T_{DSU}	0.337		0.396		ns
Data hold time	T_{DHD}	0.111		0.13		ns
Block select setup time	T_{BLKSU}	0.207		0.244		ns
Block select hold time	T_{BLKHD}	0.201		0.237		ns
Block select to out disable time (when pipelined register is disabled)	T_{BLK2Q}		2.25		2.647	ns
Block select minimum pulse width	T_{BLKMPW}	0.186		0.219		ns
Read enable setup time	T_{RDESU}	0.449		0.528		ns
Read enable hold time	T_{RDEHD}	0.167		0.197		ns
Pipelined read enable setup time (A_DOUT_EN, B_DOUT_EN)	$T_{RDPLESU}$	0.248		0.291		ns
Pipelined read enable hold time (A_DOUT_EN, B_DOUT_EN)	$T_{RDPLEHD}$	0.102		0.12		ns
Asynchronous reset to output propagation delay	T_{R2Q}		1.506		1.772	ns
Asynchronous reset removal time	T_{RSTREM}	0.506		0.595		ns
Asynchronous reset recovery time	T_{RSTREC}	0.004		0.005		ns
Asynchronous reset minimum pulse width	T_{RSTMPW}	0.301		0.354		ns
Pipelined register asynchronous reset removal time	$T_{PLRSTREM}$	–0.279		–0.328		ns
Pipelined register asynchronous reset recovery time	$T_{PLRSTREC}$	0.327		0.385		ns
Pipelined register asynchronous reset minimum pulse width	$T_{PLRSTMPW}$	0.282		0.332		ns
Synchronous reset setup time	T_{SRSTSU}	0.226		0.265		ns
Synchronous reset hold time	T_{SRSTHD}	0.036		0.043		ns
Write enable setup time	T_{WESU}	0.39		0.458		ns
Write enable hold time	T_{WEHD}	0.242		0.285		ns
Maximum frequency	F_{MAX}		400		340	MHz

Table 237 • **µSRAM (RAM64x18) in 64 × 18 Mode *(continued)***

		–1		–Std		
Parameter	**Symbol**	**Min**	**Max**	**Min**	**Max**	**Unit**
Write address setup time	$T_{ADDRCSU}$	0.088		0.104		ns
Write address hold time	$T_{ADDRCHD}$	0.128		0.15		ns
Write enable setup time	T_{WECSU}	0.397		0.467		ns
Write enable hold time	T_{WECHD}	–0.026		–0.03		ns
Maximum frequency	F_{MAX}		250		250	MHz

The following table lists the µSRAM in 64 × 16 mode in worst commercial-case conditions when T_J = 85 °C, V_{DD} = 1.14 V.

Table 238 • **µSRAM (RAM64x16) in 64 × 16 Mode**

		–1		–Std		
Parameter	**Symbol**	**Min**	**Max**	**Min**	**Max**	**Unit**
Read clock period	T_{CY}	4		4		ns
Read clock minimum pulse width high	$T_{CLKMPWH}$	1.8		1.8		ns
Read clock minimum pulse width low	$T_{CLKMPWL}$	1.8		1.8		ns
Read pipeline clock period	T_{PLCY}	4		4		ns
Read pipeline clock minimum pulse width high	$T_{PLCLKMPWH}$	1.8		1.8		ns
Read pipeline clock minimum pulse width low	$T_{PLCLKMPWL}$	1.8		1.8		ns
Read access time with pipeline register	T_{CLK2Q}		0.266		0.313	ns
Read access time without pipeline register			1.677		1.973	ns
Read address setup time in synchronous mode	T_{ADDRSU}	0.301		0.354		ns
Read address setup time in asynchronous mode		1.856		2.184		ns
Read address hold time in synchronous mode	T_{ADDRHD}	0.091		0.107		ns
Read address hold time in asynchronous mode		–0.778		–0.915		ns
Read enable setup time	T_{RDENSU}	0.278		0.327		ns
Read enable hold time	T_{RDENHD}	0.057		0.067		ns
Read block select setup time	T_{BLKSU}	1.839		2.163		ns
Read block select hold time	T_{BLKHD}	–0.65		–0.765		ns
Read block select to out disable time (when pipelined register is disabled)	T_{BLK2Q}		2.036		2.396	ns
Read asynchronous reset removal time (pipelined clock)	T_{RSTREM}	–0.023		–0.027		ns
Read asynchronous reset removal time (non-pipelined clock)		0.046		0.054		ns
Read asynchronous reset recovery time (pipelined clock)	T_{RSTREC}	0.507		0.597		ns
Read asynchronous reset recovery time (non-pipelined clock)		0.236		0.278		ns
Read asynchronous reset to output propagation delay (with pipelined register enabled)	T_{R2Q}		0.835		0.983	ns
Read synchronous reset setup time	T_{SRSTSU}	0.271		0.319		ns

Table 242 • **µSRAM (RAM512x2) in 512 × 2 Mode *(continued)***

		–1		–Std		
Parameter	**Symbol**	**Min**	**Max**	**Min**	**Max**	**Unit**
Write clock period	T_{CCY}	4		4		ns
Write clock minimum pulse width high	$T_{CCLKMPWH}$	1.8		1.8		ns
Write clock minimum pulse width low	$T_{CCLKMPWL}$	1.8		1.8		ns
Write block setup time	T_{BLKCSU}	0.404		0.476		ns
Write block hold time	T_{BLKCHD}	0.007		0.008		ns
Write input data setup time	T_{DINCSU}	0.101		0.118		ns
Write input data hold time	T_{DINCHD}	0.137		0.161		ns
Write address setup time	$T_{ADDRCSU}$	0.088		0.104		ns
Write address hold time	$T_{ADDRCHD}$	0.247		0.29		ns
Write enable setup time	T_{WECSU}	0.397		0.467		ns
Write enable hold time	T_{WECHD}	–0.03		–0.03		ns
Maximum frequency	F_{MAX}		250		250	MHz

The following table lists the µSRAM in 1024 × 1 mode in worst commercial-case conditions when T_J = 85 °C, V_{DD} = 1.14 V.

Table 243 • **µSRAM (RAM1024x1) in 1024 × 1 Mode**

		–1		–Std		
Parameter	**Symbol**	**Min**	**Max**	**Min**	**Max**	**Unit**
Read clock period	T_{CY}	4		4		ns
Read clock minimum pulse width high	$T_{CLKMPWH}$	1.8		1.8		ns
Read clock minimum pulse width low	$T_{CLKMPWL}$	1.8		1.8		ns
Read pipeline clock period	T_{PLCY}	4		4		ns
Read pipeline clock minimum pulse width high	$T_{PLCLKMPWH}$	1.8		1.8		ns
Read pipeline clock minimum pulse width low	$T_{PLCLKMPWL}$	1.8		1.8		ns
Read access time with pipeline register	T_{CLK2Q}		0.27		0.31	ns
Read access time without pipeline register			1.78		2.1	ns
Read address setup time in synchronous mode	T_{ADDRSU}	0.301		0.354		ns
Read address setup time in asynchronous mode		1.978		2.327		ns
Read address hold time in synchronous mode	T_{ADDRHD}	0.137		0.161		ns
Read address hold time in asynchronous mode		–0.6		–0.71		ns
Read enable setup time	T_{RDENSU}	0.278		0.327		ns
Read enable hold time	T_{RDENHD}	0.057		0.067		ns
Read block select setup time	T_{BLKSU}	1.839		2.163		ns
Read block select hold time	T_{BLKHD}	–0.65		–0.77		ns
Read block select to out disable time (when pipelined register is disabled)	T_{BLK2Q}		2.16		2.54	ns
Read asynchronous reset removal time (pipelined clock)	T_{RSTREM}	–0.02		–0.03		ns
Read asynchronous reset removal time (non-pipelined clock)		0.046		0.054		ns

Table 251 • **SmartFusion2 Cortex-M3 ISP Programming (eNVM Only) *(continued)***

M2S/M2GL Device	Image size Bytes	Authenticate	Program	Verify	Unit
150	544496	10	158	15	Sec

Table 252 • **SmartFusion2 Cortex-M3 ISP Programming (Fabric and eNVM)**

M2S/M2GL Device	Image size Bytes	Authenticate	Program	Verify	Unit
005	439296	9	61	11	Sec
010	842688	15	107	21	Sec
025	1497408	26	121	35	Sec
050	2695168	43	141	55	Sec
060	2686464	48	143	60	Sec
090	4190208	75	244	91	Sec
150	6682768	117	296	141	Sec

Table 253 • **Programming Times with 100 kHz, 25 MHz, and 12.5 MHz SPI Clock Rates (Fabric Only)**

M2S/M2GL Device	Auto Programming	Auto Update	Programming Recovery	
	100 kHz	25 MHz	12.5 MHz	Unit
005	47	27	28	Sec
010	77	35	35	Sec
025	150	42	41	Sec
050	33[1]	Not Supported	Not Supported	Sec
060	291	83	82	Sec
090	427	109	108	Sec
150	708	157	160	Sec

1. Auto Programming in 050 device is done through SC_SPI, and SPI CLK is set to 6.25 MHz.

Table 254 • **Programming Times with 100 kHz, 25 MHz, and 12.5 MHz SPI Clock Rates (eNVM Only)**

M2S/M2GL Device	Auto Programming	Auto Update	Programming Recovery	
	100 kHz	25 MHz	12.5 MHz	Unit
005	41	48	49	Sec
010	86	87	87	Sec
025	87	85	86	Sec
050	85	Not Supported	Not Supported	Sec
060	78	86	86	Sec
090	154	162	162	Sec

The following table lists the math blocks with input register used and output in bypass mode in worst commercial-case conditions when T_J = 85 °C, V_{DD} = 1.14 V.

Table 270 • **Math Block with Input Register Used and Output in Bypass Mode**

		–1		–Std		
Parameter	**Symbol**	**Min**	**Max**	**Min**	**Max**	**Unit**
Input register setup time	T_{MISU}	0.149		0.176		ns
Input register hold time	T_{MIHD}	0.185		0.218		ns
Synchronous reset/enable setup time	$T_{MSRSTENSU}$	0.08		0.094		ns
Synchronous reset/enable hold time	$T_{MSRSTENHD}$	–0.012		–0.014		ns
Asynchronous reset removal time	$T_{MARSTREM}$	–0.005		–0.005		ns
Asynchronous reset recovery time	$T_{MARSTREC}$	0.088		0.104		ns
Input register clock to output delay	T_{MICQ}		2.52		2.964	ns
CDIN to output delay	$T_{MCDIN2Q}$		1.951		2.295	ns

The following table lists the math blocks with input and output in bypass mode in worst commercial-case conditions when T_J = 85 °C, V_{DD} = 1.14 V.

Table 271 • **Math Block with Input and Output in Bypass Mode**

		–1	–Std	
Parameter	**Symbol**	**Max**	**Max**	**Unit**
Input to output delay	T_{MIQ}	2.568	3.022	ns
CDIN to output delay	$T_{MCDIN2Q}$	1.951	2.295	ns

2.3.15 Embedded NVM (eNVM) Characteristics

The following table lists the eNVM read performance in worst-case conditions when V_{DD} = 1.14 V, V_{PPNVM} = V_{PP} = 2.375 V.

Table 272 • **eNVM Read Performance**

		Operating Temperature Range						
Symbol	**Description**	**–1**	**–Std**	**–1**	**–Std**	**–1**	**–Std**	**Unit**
T_J	Junction temperature range	–55 °C to 125 °C		–40 °C to 100 °C		0 °C to 85 °C		°C
$F_{MAXREAD}$	eNVM maximum read frequency	25	25	25	25	25	25	MHz

The following table lists the eNVM page programming in worst-case conditions when V_{DD} = 1.14 V, V_{PPNVM} = V_{PP} = 2.375 V.

Table 273 • **eNVM Page Programming**

		Operating Temperature Range						
Symbol	**Description**	**–1**	**–Std**	**–1**	**–Std**	**–1**	**–Std**	**Unit**
T_J	Junction temperature range	–55 °C to 125 °C		–40 °C to 100 °C		0 °C to 85 °C		°C
$T_{PAGEPGM}$	eNVM page programming time	40	40	40	40	40	40	ms

2.3.16 SRAM PUF

For more details on static random-access memory (SRAM) physical unclonable functions (PUF) services, see *AC434: Using SRAM PUF System Service in SmartFusion2 Application Note*.

The following table lists the SRAM PUF in worst-case industrial conditions when T_J = 100 °C, V_{DD} = 1.14 V.

Table 274 • **SRAM PUF**

	PUF Off		**PUF On**		
Service	**Typ**	**Max**	**Typ**	**Max**	**Unit**
Create activation code	709.1	746.4	754.4	762.5	ms
Delete activation code	1329.3	1399.3	1414.1	1429.3	ms
Create intrinsic keycode	656.6	691.1	698.5	706.0	ms
Create extrinsic keycode	656.6	691.1	698.5	706.0	ms
Get number of keys	1.3	1.4	1.4	1.4	ms
Export (Kc0, Kc1)	998.0	1050.5	1061.7	1073.1	ms
Export 2 keycodes	2020.2	2126.5	2149.2	2172.3	ms
Export 4 keycodes	3065.7	3227.0	3261.3	3296.4	ms
Export 8 keycodes	5101.0	5369.5	5426.6	5485.0	ms
Export 16 keycodes	9212.1	9697.0	9800.1	9905.5	ms
Import (Kc0, Kc1)	39.7	41.8	42.2	42.7	ms
Import 2 keycodes	50.1	52.7	53.3	53.9	ms
Import 4 keycodes	60.6	63.8	64.5	65.2	ms
Import 8 keycodes	80.9	85.1	86.1	87.0	ms
Import 16 keycodes	123.8	130.4	131.7	133.2	ms
Delete keycode	552.5	581.6	587.8	594.1	ms
Fetch key	31.4	33.0	33.4	33.7	ms
Fetch ecc key	20.0	21.1	21.3	21.5	ms
Get seed	2.0	2.1	2.2	2.2	ms

1. The minimum output clock frequency is limited by the PLL. For more information, see *UG0449: SmartFusion2 and IGLOO2 Clocking Resources User Guide*.
2. The PLL is used in conjunction with the Clock Conditioning Circuitry. Performance is limited by the CCC output frequency.

The following table lists the CCC/PLL jitter specifications in worst-case industrial conditions when T_J = 100 °C, V_{DD} = 1.14 V.

Table 283 • **IGLOO2 and SmartFusion2 SoC FPGAs CCC/PLL Jitter Specifications**

CCC Output Maximum Peak-to-Peak Period Jitter F_{OUT_CCC}						
Parameter	**Conditions/Package Combinations**					**Unit**
10 FG484, 050 FG896/FG484/FCS325 Packages[1]	SSO = 0	0 < SSO <= 2	SSO <= 4	SSO <= 8	SSO <= 16	
20 MHz to 100 MHz	Max(110, ± 1% x (1/F_{OUT_CCC}))	Max(150, ± 1% x (1/F_{OUT_CCC}))				ps
100 MHz to 400 MHz	Max(120, ± 1% x (1/F_{OUT_CCC}))	Max(150, ± 1% x (1/F_{OUT_CCC}))			Max(170, ± 1% x (1/F_{OUT_CCC}))	ps
025 FG484/FCS325 Package[1]	0 < SSO <=16					
20 MHz to 74 MHz	± 1% x (1/F_{OUT_CCC}))					ps
74 MHz to 400 MHz	210					ps
005 FG484 Package[1]	0 < SSO <=16					
20 MHz to 53 MHz	± 1% x (1/F_{OUT_CCC}))					ps
53 MHz to 400 MHz	270					ps
090 FG676 and FC325 Package[1]	0 < SSO <=16					
20 MHz to 100 MHz	± 1% x (1/F_{OUT_CCC}))					ps
100 MHz to 400 MHz	150					ps
060 FG676 Package[1]	0 < SSO <=16					
20 MHz to 100 MHz	± 1% x (1/F_{OUT_CCC})					ps
100 MHz to 400 MHz	150					
150 FC1152 Package[1]	0 < SSO <=16					
20 MHz to 100 MHz	± 1% x (1/F_{OUT_CCC}))					ps
100 MHz to 400 MHz	120					ps

1. SSO data is based on LVCMOS 2.5 V MSIO and/or MSIOD bank I/Os.

Table 291 • **DEVRST_N to Functional Times for SmartFusion2 *(continued)***

				Maximum Power-up to Functional Time for SmartFusion2 (uS)						
Symbol	**From**	**To**	**Description**	**005**	**010**	**025**	**050**	**060**	**090**	**150**
$T_{DEVRST2POR}$	DEVRST_N	POWER_ON_RESET_N	V_{DD} at its minimum threshold level to fabric	233	289	216	213	237	234	219
$T_{DEVRST2MSSRST}$	DEVRST_N	MSS_RESET_N_M2F	V_{DD} at its minimum threshold level to MSS	702	765	712	688	636	630	866
$T_{DEVRST2WPU}$	DEVRST_N	DDRIO Inbuf weak pull	DEVRST_N to Inbuf weak pull	208	202	197	193	216	215	215
	DEVRST_N	MSIO Inbuf weak pull	DEVRST_N to Inbuf weak pull	208	202	197	193	216	215	215
	DEVRST_N	MSIOD Inbuf weak pull	DEVRST_N to Inbuf weak pull	208	202	197	193	216	215	215

Figure 19 • **DEVRST_N to Functional Timing Diagram for SmartFusion2**

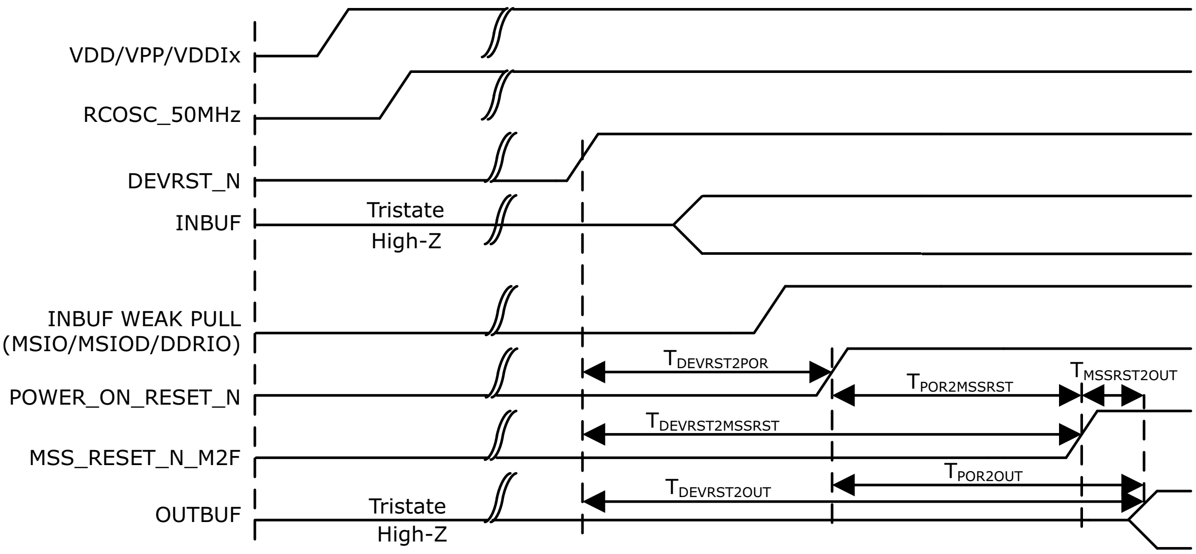


Table 303* • I2C Characteristics *(continued)

Parameter	Symbol	Min	Typ	Max	Unit	Conditions
Maximum data rate	D_{MAX}			400	Kbps	Fast mode
				100	Kbps	Standard mode
Pulse width of spikes which must be suppressed by the input filter	T_{FILT}		50		ns	Fast mode

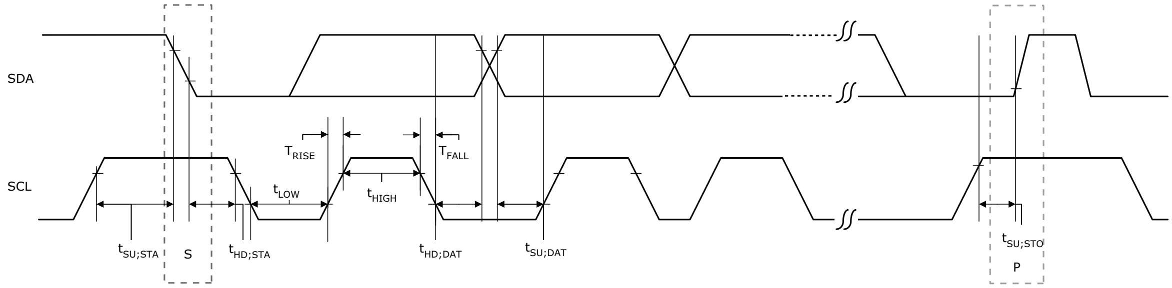
1. These values are provided for MSIO Bank–LVTTL 8 mA Low Drive at 25 °C, typical conditions. For board design considerations and detailed output buffer resistances, use the corresponding IBIS models located on the SoC Products Group website: http://www.microsemi.com/soc/download/ibis/default.aspx.
2. These maximum values are provided for information only. Minimum output buffer resistance values depend on V_{DDIx}, drive strength selection, temperature, and process. For board design considerations and detailed output buffer resistances, use the corresponding IBIS models located on the SoC Products Group website: http://www.microsemi.com/soc/download/ibis/default.aspx.
3. R(PULL-DOWN-MAX) = (VOLspec)/IOLspec.
4. R(PULL-UP-MAX) = (VDDImax–VOHspec)/IOHspec.

The following table lists the I^2C switching characteristics in worst-case industrial conditions when T_J = 100 °C, V_{DD} = 1.14 V

***Table 304* • I2C Switching Characteristics**

		–1	Std	
Parameter	**Symbol**	**Min**	**Min**	**Unit**
Low period of I2C_x_SCL	T_{LOW}	1	1	PCLK cycles
High period of I2C_x_SCL	T_{HIGH}	1	1	PCLK cycles
START hold time	$T_{HD;STA}$	1	1	PCLK cycles
START setup time	$T_{SU;STA}$	1	1	PCLK cycles
DATA hold time	$T_{HD;DAT}$	1	1	PCLK cycles
DATA setup time	$T_{SU;DAT}$	1	1	PCLK cycles
STOP setup time	$T_{SU;STO}$	1	1	PCLK cycles

***Figure 21* • I^2C Timing Parameter Definition**



2.3.31.3 Serial Peripheral Interface (SPI) Characteristics

This section describes the DC and switching of the SPI interface. Unless otherwise noted, all output characteristics given are for a 35 pF load on the pins and all sequential timing characteristics are related to SPI_x_CLK. For timing parameter definitions, see Figure 22, page 128.

The following table lists the SPI characteristics in worst-case industrial conditions when T_J = 100 °C, V_{DD} = 1.14 V

Table 305 • **SPI Characteristics for All Devices**

Symbol	Description	Min	Typ	Max	Unit	Conditions
SPIFMAX	Maximum operating frequency of SPI interface			20	MHz	
sp1	SPI_[0|1]_CLK minimum period					
	SPI_[0|1]_CLK = PCLK/2	12			ns	
	SPI_[0|1]_CLK = PCLK/4	24.1			ns	
	SPI_[0|1]_CLK = PCLK/8	48.2			ns	
	SPI_[0|1]_CLK = PCLK/16	0.1			µs	
	SPI_[0|1]_CLK = PCLK/32	0.19			µs	
	SPI_[0|1]_CLK = PCLK/64	0.39			µs	
	SPI_[0|1]_CLK = PCLK/128	0.77			µs	
sp2	SPI_[0|1]_CLK minimum pulse width high					
	SPI_[0|1]_CLK = PCLK/2	6			ns	
	SPI_[0|1]_CLK = PCLK/4	12.05			ns	
	SPI_[0|1]_CLK = PCLK/8	24.1			ns	
	SPI_[0|1]_CLK = PCLK/16	0.05			µs	
	SPI_[0|1]_CLK = PCLK/32	0.095			µs	
	SPI_[0|1]_CLK = PCLK/64	0.195			µs	
	SPI_[0|1]_CLK = PCLK/128	0.385			µs	
sp3	SPI_[0|1]_CLK minimum pulse width low					
	SPI_[0|1]_CLK = PCLK/2	6			ns	
	SPI_[0|1]_CLK = PCLK/4	12.05			ns	
	SPI_[0|1]_CLK = PCLK/8	24.1			ns	
	SPI_[0|1]_CLK = PCLK/16	0.05			µs	
	SPI_[0|1]_CLK = PCLK/32	0.095			µs	
	SPI_[0|1]_CLK = PCLK/64	0.195			µs	
	SPI_[0|1]_CLK = PCLK/128	0.385			µs	
sp4	SPI_[0|1]_CLK, SPI_[0|1]_DO, SPI_[0|1]_SS rise time (10%–90%)[1]		2.77		ns	I/O Configuration: LVCMOS 2.5 V– 8 mA AC loading: 35 pF Test conditions: Typical voltage, 25 °C

Table 310 • **SPI Characteristics for All Devices *(continued)***

Symbol	Description	Min	Typ	Max	Unit	Conditions
SPI master configuration (applicable for 060, 090, and 150 devices)						
sp6m	SPI_[0|1]_DO setup time[2]	(SPI_x_CLK_period/2) – 7.0			ns	
sp7m	SPI_[0|1]_DO hold time[2]	(SPI_x_CLK_period/2) – 9.5			ns	
sp8m	SPI_[0|1]_DI setup time[2]	15			ns	
sp9m	SPI_[0|1]_DI hold time[2]	–2.5			ns	
SPI slave configuration (applicable for 060, 090, and 150 devices)						
sp6s	SPI_[0|1]_DO setup time[2]	(SPI_x_CLK_period/2) – 16.0			ns	
sp7s	SPI_[0|1]_DO hold time[2]	(SPI_x_CLK_period/2) - 3.5			ns	
sp8s	SPI_[0|1]_DI setup time[2]	3			ns	
sp9s	SPI_[0|1]_DI hold time[2]	2.5			ns	

1. For specific Rise/Fall Times board design considerations and detailed output buffer resistances, use the corresponding IBIS models located on the Microsemi SoC Products Group website: http://www.microsemi.com/soc/download/ibis/default.aspx.
2. For allowable pclk configurations, see the Serial Peripheral Interface Controller section in the *UG0331: SmartFusion2 Microcontroller Subsystem User Guide*.

Figure 23 • **SPI Timing for a Single Frame Transfer in Motorola Mode (SPH = 1)**