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Understanding [Embedded - FPGAs \(Field Programmable Gate Array\)](#)

Embedded - FPGAs, or Field Programmable Gate Arrays, are advanced integrated circuits that offer unparalleled flexibility and performance for digital systems. Unlike traditional fixed-function logic devices, FPGAs can be programmed and reprogrammed to execute a wide array of logical operations, enabling customized functionality tailored to specific applications. This reprogrammability allows developers to iterate designs quickly and implement complex functions without the need for custom hardware.

Applications of Embedded - FPGAs

The versatility of Embedded - FPGAs makes them indispensable in numerous fields. In telecommunications.

Details

Product Status	Active
Number of LABs/CLBs	-
Number of Logic Elements/Cells	56340
Total RAM Bits	1869824
Number of I/O	200
Number of Gates	-
Voltage - Supply	1.14V ~ 2.625V
Mounting Type	Surface Mount
Operating Temperature	0°C ~ 85°C (TJ)
Package / Case	325-TFBGA, FCBGA
Supplier Device Package	325-FCBGA (11x11)
Purchase URL	https://www.e-xfl.com/product-detail/microchip-technology/m2gl050-fcs325

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Table 11 • SmartFusion2 and IGLOO2 Quiescent Supply Current ($V_{DD} = 1.2 \text{ V}$) – Typical Process

Symbol	Modes	005	010	025	050	060	090	150	Unit	Conditions
IDC2	Flash*Freeze	1.4	2.6	3.7	5.1	5.0	5.1	8.9	mA	Typical ($T_J = 25^\circ\text{C}$)
		12.0	20.0	26.6	35.3	35.4	35.7	57.8	mA	Commercial ($T_J = 85^\circ\text{C}$)
		18.5	30.8	41.0	54.5	54.5	55.0	89.0	mA	Industrial ($T_J = 100^\circ\text{C}$)

Table 12 • SmartFusion2 and IGLOO2 Quiescent Supply Current ($V_{DD} = 1.26 \text{ V}$) – Worst-Case Process

Symbol	Modes	005	010	025	050	060	090	150	Unit	Conditions
IDC1	Non-Flash*Freeze	43.8	57.0	84.6	132.3	161.4	163.0	242.5	mA	Commercial ($T_J = 85^\circ\text{C}$)
		65.3	85.7	127.8	200.9	245.4	247.8	369.0	mA	Industrial ($T_J = 100^\circ\text{C}$)
IDC2	Flash*Freeze	29.1	45.6	51.7	62.7	69.3	70.0	84.8	mA	Commercial ($T_J = 85^\circ\text{C}$)
		44.9	70.3	79.7	96.5	106.8	107.8	130.6	mA	Industrial ($T_J = 100^\circ\text{C}$)

2.3.2.2 Programming Currents

The following tables represent programming, verify and Inrush currents for SmartFusion2 SoC and IGLOO2 FPGA devices.

Table 13 • Currents During Program Cycle, $0^\circ\text{C} \leq T_J \leq 85^\circ\text{C}$ – Typical Process

Power Supplies	Voltage (V)	005	010	025	050	060	090	150 ¹	Unit
V_{DD}	1.26	46	53	55	58	30	42	52	mA
V_{PP}	3.46	8	11	6	10	9	12	12	mA
V_{PPNVM}	3.46	1	2	2	3	3	3		mA
V_{DDI}	2.62	31	16	17	1	12	12	81	mA
	3.46	62	31	36	1	12	17	84	mA
Number of banks		7	8	8	10	10	9	19	

1. V_{PP} and V_{PPNVM} are internally shorted.

Table 14 • Currents During Verify Cycle, $0^\circ\text{C} \leq T_J \leq 85^\circ\text{C}$ – Typical Process

Power Supplies	Voltage (V)	005	010	025	050	060	090	150 ¹	Unit
V_{DD}	1.26	44	53	55	58	33	41	51	mA
V_{PP}	3.46	6	5	3	15	8	11	12	mA
V_{PPNVM}	3.46	1	0	0	1	1	1		mA
V_{DDI}	2.62	31	16	17	1	12	11	81	mA
	3.46	61	32	36	1	12	17	84	mA
Number of banks		7	8	8	10	10	9	19	

1. V_{PP} and V_{PPNVM} are internally shorted.

Table 19 • Maximum Data Rate Summary Table for Voltage-Referenced I/O in Worst-Case Industrial Conditions

I/O	MSIO	MSIOD	DDRIO	Unit
LPDDR			400	Mbps
HSTL1.5 V			400	Mbps
SSTL 2.5 V	510	700	400	Mbps
SSTL 1.8 V			667	Mbps
SSTL 1.5 V			667	Mbps

Table 20 • Maximum Data Rate Summary Table for Differential I/O in Worst-Case Industrial Conditions

I/O	MSIO	MSIOD	Unit
LVPECL (input only)	900		Mbps
LVDS 3.3 V	535		Mbps
LVDS 2.5 V	535	700	Mbps
RSDS	520	700	Mbps
BLVDS	500		Mbps
MLVDS	500		Mbps
Mini-LVDS	520	700	Mbps

Table 21 • Maximum Frequency Summary Table for Single-Ended I/O in Worst-Case Industrial Conditions

I/O	MSIO	MSIOD	DDRIO	Unit
PCI 3.3 V	315			MHz
LVTTL 3.3 V	300			MHz
LVC MOS 3.3 V	300			MHz
LVC MOS 2.5 V	205	210	200	MHz
LVC MOS 1.8 V	147.5	200	200	MHz
LVC MOS 1.5 V	80	110	118	MHz
LVC MOS 1.2 V	60	80	100	MHz
LPDDR– LVC MOS 1.8 V mode			200	MHz

Table 128 • DDR2/SSTL18 Transmitter Characteristics (Output and Tristate Buffers)

	T _{DP}		T _{ZL}		T _{ZH}		T _{HZ}		T _{LZ}		Unit
	−1	−Std	−1	−Std	−1	−Std	−1	−Std	−1	−Std	
SSTL18 Class I (for DDRIO I/O Bank)											
Single-ended	2.383	2.804	2.23	2.623	2.229	2.622	2.202	2.591	2.201	2.59	ns
Differential	2.413	2.84	2.797	3.29	2.797	3.29	2.282	2.685	2.282	2.685	ns
SSTL18 Class II (for DDRIO I/O Bank)											
Single-ended	2.281	2.683	2.196	2.584	2.195	2.583	2.171	2.555	2.17	2.554	ns
Differential	2.315	2.724	2.698	3.173	2.698	3.173	2.242	2.639	2.242	2.639	ns

2.3.6.5 Stub-Series Terminated Logic 1.5 V (SSTL15)

SSTL15 Class I and Class II are supported in IGLOO2 FPGAs and SmartFusion2 SoC FPGAs, and also comply with the reduced and full drive double data rate (DDR3) standard. IGLOO2 FPGA and SmartFusion2 SoC FPGA I/Os supports both standards for single-ended signaling and differential signaling for SSTL18. This standard requires a differential amplifier input buffer and a push-pull output buffer.

Minimum and Maximum DC/AC Input and Output Levels Specification

The following table lists the SSTL15 DC voltage specifications for DDRIO bank.

Table 129 • SSTL15 DC Recommended DC Operating Conditions (for DDRIO I/O Bank Only)

Parameter	Symbol	Min	Typ	Max	Unit
Supply voltage	V_{DDI}	1.425	1.5	1.575	V
Termination voltage	V_{TT}	0.698	0.750	0.803	V
Input reference voltage	V_{REF}	0.698	0.750	0.803	V

Table 130 • SSTL15 DC Input Voltage Specification (for DDRIO I/O Bank Only)

Parameter	Symbol	Min	Max	Unit
DC input logic high	$V_{IH}(DC)$	$V_{REF} + 0.1$	1.575	V
DC input logic low	$V_{IL}(DC)$	-0.3	$V_{REF} - 0.1$	V
Input current high ¹	$I_{IH}(DC)$			
Input current low ¹	$I_{IL}(DC)$			

1. See Table 24, page 22.

Table 150 • LPDDR Full Drive for DDRIO I/O Bank (Output and Tristate Buffers)

	T_{DP}		T_{ENZL}		T_{ENZH}		T_{ENHZ}		T_{ENLZ}		Unit
	-1	-Std	-1	-Std	-1	-Std	-1	-Std	-1	-Std	
Single-ended	2.281	2.683	2.196	2.584	2.195	2.583	2.171	2.555	2.17	2.554	ns
Differential	2.298	2.703	2.288	2.692	2.288	2.692	2.593	3.051	2.593	3.051	ns

Minimum and Maximum DC/AC Input and Output Levels Specification using LPDDR-LVCMOS 1.8 V Mode

Table 151 • LPDDR-LVCMOS 1.8 V Mode Recommended DC Operating Conditions

Parameter	Symbol	Min	Typ	Max	Unit
Supply voltage	V_{DDI}	1.710	1.8	1.89	V

Table 152 • LPDDR-LVCMOS 1.8 V Mode DC Input Voltage Specification

Parameter	Symbol	Min	Max	Unit
DC input logic high (for MSIOD and DDRIO I/O banks)	V_{IH} (DC)	$0.65 \times V_{DDI}$	1.89	V
DC input logic high (for MSIO I/O bank)	V_{IH} (DC)	$0.65 \times V_{DDI}$	3.45	V
DC input logic low	V_{IL} (DC)	-0.3	$0.35 \times V_{DDI}$	V
Input current high ¹	I_{IH} (DC)			
Input current low ¹	I_{IL} (DC)			

1. See Table 24, page 22.

Table 153 • LPDDR-LVCMOS 1.8 V Mode DC Output Voltage Specification

Parameter	Symbol	Min	Max	Unit
DC output logic high	V_{OH}	$V_{DDI} - 0.45$		V
DC output logic low	V_{OL}		0.45	V

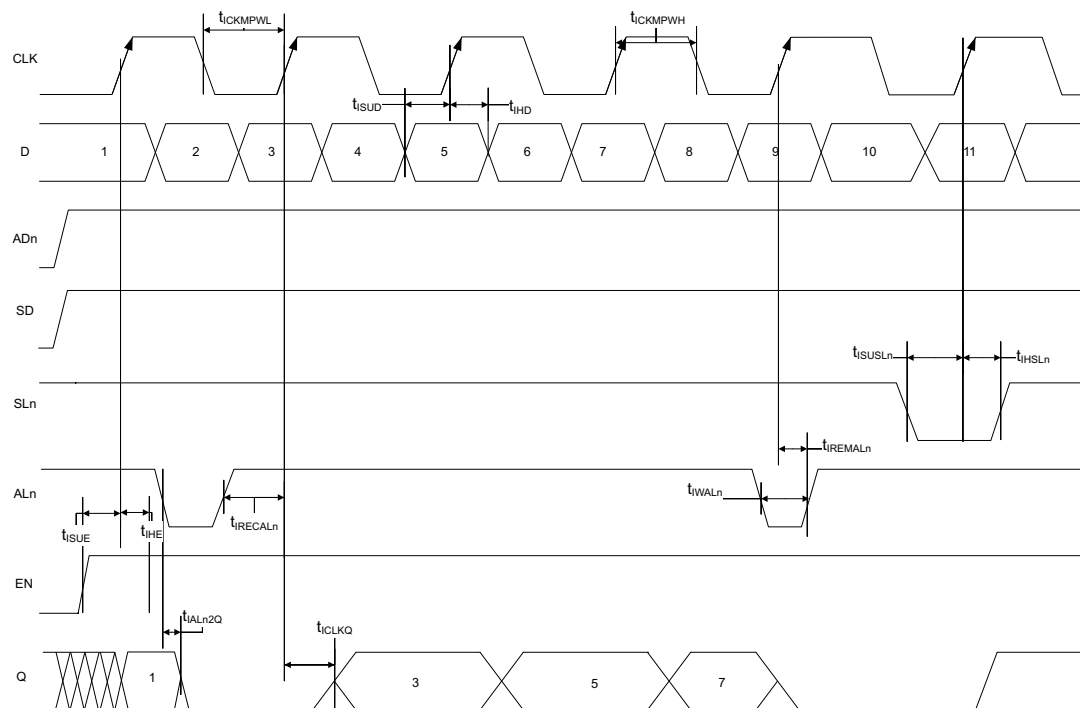
Table 154 • LPDDR-LVCMOS 1.8 V Minimum and Maximum AC Switching Speeds

Parameter	Symbol	Max	Unit	Conditions
Maximum data rate (for DDRIO I/O bank)	D_{MAX}	400	Mbps	AC loading: 17pf load, 8 ma drive and above/all slew

Table 155 • LPDDR-LVCMOS 1.8 V Calibrated Impedance Option

Parameter	Symbol	Typ	Unit
Supported output driver calibrated impedance (for DDRIO I/O bank)	RODT_CAL	75, 60, 50, 33, 25, 20	Ω

Figure 7 • I/O Register Input Timing Diagram



2.3.10.2 Timing Characteristics

The following table lists the combinatorial cell propagation delays in worst commercial-case conditions when $T_J = 85^\circ\text{C}$, $V_{DD} = 1.14\text{ V}$.

Table 223 • Combinatorial Cell Propagation Delays

Combinatorial Cell	Equation	Symbol	–1	–Std	Unit
INV	$Y = !A$	T_{PD}	0.1	0.118	ns
AND2	$Y = A \cdot B$	T_{PD}	0.164	0.193	ns
NAND2	$Y = !(A \cdot B)$	T_{PD}	0.147	0.173	ns
OR2	$Y = A + B$	T_{PD}	0.164	0.193	ns
NOR2	$Y = !(A + B)$	T_{PD}	0.147	0.173	ns
XOR2	$Y = A \oplus B$	T_{PD}	0.164	0.193	ns
XOR3	$Y = A \oplus B \oplus C$	T_{PD}	0.225	0.265	ns
AND3	$Y = A \cdot B \cdot C$	T_{PD}	0.209	0.246	ns
AND4	$Y = A \cdot B \cdot C \cdot D$	T_{PD}	0.287	0.338	ns

2.3.10.3 Sequential Module

IGLOO2 and SmartFusion2 SoC FPGAs offer a separate flip-flop which can be used independently from the LUT. The flip-flop can be configured as a register or a latch and has a data input and optional enable, synchronous load (clear or preset), and asynchronous load (clear or preset).

Figure 15 • Sequential Module

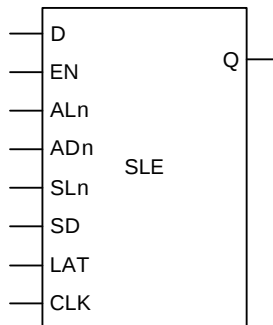


Table 233 • RAM1K18 – Dual-Port Mode for Depth × Width Configuration 4K × 4 (continued)

Parameter	Symbol	–1		–Std		Unit
		Min	Max	Min	Max	
Pipelined clock minimum pulse width low	$T_{PLCLKMPWL}$	1.125		1.323		ns
Read access time with pipeline register	T_{CLK2Q}		0.323		0.38	ns
Read access time without pipeline register			2.273		2.673	ns
Access time with feed-through write timing			1.511		1.778	ns
Address setup time	T_{ADDRSU}	0.543		0.638		ns
Address hold time	T_{ADDRHD}	0.274		0.322		ns
Data setup time	T_{DSU}	0.334		0.393		ns
Data hold time	T_{DHD}	0.082		0.096		ns
Block select setup time	T_{BLKSU}	0.207		0.244		ns
Block select hold time	T_{BLKHD}	0.216		0.254		ns
Block select to out disable time (when pipelined register is disabled)	T_{BLK2Q}		1.511		1.778	ns
Block select minimum pulse width	T_{BLKMPW}	0.186		0.219		ns
Read enable setup time	T_{RDESU}	0.516		0.607		ns
Read enable hold time	T_{RDEHD}	0.071		0.083		ns
Pipelined read enable setup time (A_DOUT_EN, B_DOUT_EN)	$T_{RDPLESU}$	0.248		0.291		ns
Pipelined read enable hold time (A_DOUT_EN, B_DOUT_EN)	$T_{RDPLEHD}$	0.102		0.12		ns
Asynchronous reset to output propagation delay	T_{R2Q}		1.507		1.773	ns
Asynchronous reset removal time	T_{RSTREM}	0.506		0.595		ns
Asynchronous reset recovery time	T_{RSTREC}	0.004		0.005		ns
Asynchronous reset minimum pulse width	T_{RSTMPW}	0.301		0.354		ns
Pipelined register asynchronous reset removal time	$T_{PLRSTREM}$	–0.279		–0.328		ns
Pipelined register asynchronous reset recovery time	$T_{PLRSTREC}$	0.327		0.385		ns
Pipelined register asynchronous reset minimum pulse width	$T_{PLRSTMPW}$	0.282		0.332		ns
Synchronous reset setup time	T_{SRSTSU}	0.226		0.265		ns
Synchronous reset hold time	T_{SRSTHD}	0.036		0.043		ns
Write enable setup time	T_{WESU}	0.458		0.539		ns
Write enable hold time	T_{WEHD}	0.048		0.057		ns
Maximum frequency	F_{MAX}		400		340	MHz

The following table lists the RAM1K18 – two-port mode for depth × width configuration 512 × 36 in worst commercial-case conditions when $T_J = 85\text{ }^{\circ}\text{C}$, $V_{DD} = 1.14\text{ V}$.

Table 236 • RAM1K18 – Two-Port Mode for Depth × Width Configuration 512 × 36

Parameter	Symbol	–1		–Std		Unit
		Min	Max	Min	Max	
Clock period	T_{CY}	2.5		2.941		ns
Clock minimum pulse width high	$T_{CLKMPWH}$	1.125		1.323		ns
Clock minimum pulse width low	$T_{CLKMPWL}$	1.125		1.323		ns
Pipelined clock period	T_{PLCY}	2.5		2.941		ns
Pipelined clock minimum pulse width high	$T_{PLCLKMPWH}$	1.125		1.323		ns
Pipelined clock minimum pulse width low	$T_{PLCLKMPWL}$	1.125		1.323		ns
Read access time with pipeline register	T_{CLK2Q}		0.334		0.393	ns
Read access time without pipeline register			2.25		2.647	ns
Address setup time	T_{ADDRSU}	0.313		0.368		ns
Address hold time	T_{ADDRHD}	0.274		0.322		ns
Data setup time	T_{DSU}	0.337		0.396		ns
Data hold time	T_{DHD}	0.111		0.13		ns
Block select setup time	T_{BLKSU}	0.207		0.244		ns
Block select hold time	T_{BLKHD}	0.201		0.237		ns
Block select to out disable time (when pipelined register is disabled)	T_{BLK2Q}		2.25		2.647	ns
Block select minimum pulse width	T_{BLKMPW}	0.186		0.219		ns
Read enable setup time	T_{RDESU}	0.449		0.528		ns
Read enable hold time	T_{RDEHD}	0.167		0.197		ns
Pipelined read enable setup time (A_DOUT_EN, B_DOUT_EN)	$T_{RDPLESU}$	0.248		0.291		ns
Pipelined read enable hold time (A_DOUT_EN, B_DOUT_EN)	$T_{RDPLEHD}$	0.102		0.12		ns
Asynchronous reset to output propagation delay	T_{R2Q}		1.506		1.772	ns
Asynchronous reset removal time	T_{RSTREM}	0.506		0.595		ns
Asynchronous reset recovery time	T_{RSTREC}	0.004		0.005		ns
Asynchronous reset minimum pulse width	T_{RSTMPW}	0.301		0.354		ns
Pipelined register asynchronous reset removal time	$T_{PLRSTREM}$	–0.279		–0.328		ns
Pipelined register asynchronous reset recovery time	$T_{PLRSTREC}$	0.327		0.385		ns
Pipelined register asynchronous reset minimum pulse width	$T_{PLRSTMPW}$	0.282		0.332		ns
Synchronous reset setup time	T_{SRSTSU}	0.226		0.265		ns
Synchronous reset hold time	T_{SRSTHD}	0.036		0.043		ns
Write enable setup time	T_{WESU}	0.39		0.458		ns
Write enable hold time	T_{WEHD}	0.242		0.285		ns
Maximum frequency	F_{MAX}		400		340	MHz

2.3.12.2 FPGA Fabric Micro SRAM (μ SRAM)

The following table lists the μ SRAM in 64×18 mode in worst commercial-case conditions when $T_J = 85^\circ\text{C}$, $V_{DD} = 1.14\text{ V}$.

Table 237 • μ SRAM (RAM64x18) in 64×18 Mode

Parameter	Symbol	–1		–Std		Unit
		Min	Max	Min	Max	
Read clock period	T_{CY}	4		4		ns
Read clock minimum pulse width high	$T_{CLKMPWH}$	1.8		1.8		ns
Read clock minimum pulse width low	$T_{CLKMPWL}$	1.8		1.8		ns
Read pipeline clock period	T_{PLCY}	4		4		ns
Read pipeline clock minimum pulse width high	$T_{PLCLKMPWH}$	1.8		1.8		ns
Read pipeline clock minimum pulse width low	$T_{PLCLKMPWL}$	1.8		1.8		ns
Read access time with pipeline register	T_{CLK2Q}	0.266		0.313		ns
Read access time without pipeline register		1.677		1.973		ns
Read address setup time in synchronous mode	T_{ADDRSU}	0.301		0.354		ns
Read address setup time in asynchronous mode		1.856		2.184		ns
Read address hold time in synchronous mode	T_{ADDRHD}	0.091		0.107		ns
Read address hold time in asynchronous mode		–0.778		–0.915		ns
Read enable setup time	T_{RDENSU}	0.278		0.327		ns
Read enable hold time	T_{RDENHD}	0.057		0.067		ns
Read block select setup time	T_{BLKSU}	1.839		2.163		ns
Read block select hold time	T_{BLKHD}	–0.65		–0.765		ns
Read block select to out disable time (when pipelined register is disabled)	T_{BLK2Q}	2.036		2.396		ns
Read asynchronous reset removal time (pipelined clock)	T_{RSTREM}	–0.023		–0.027		ns
Read asynchronous reset removal time (non-pipelined clock)		0.046		0.054		ns
Read asynchronous reset recovery time (pipelined clock)	T_{RSTREC}	0.507		0.597		ns
Read asynchronous reset recovery time (non-pipelined clock)		0.236		0.278		ns
Read asynchronous reset to output propagation delay (with pipelined register enabled)	T_{R2Q}	0.839		0.987		ns
Read synchronous reset setup time	T_{SRSTSU}	0.271		0.319		ns
Read synchronous reset hold time	T_{SRSTHD}	0.061		0.071		ns
Write clock period	T_{CCY}	4		4		ns
Write clock minimum pulse width high	$T_{CCLKMPWH}$	1.8		1.8		ns
Write clock minimum pulse width low	$T_{CCLKMPWL}$	1.8		1.8		ns
Write block setup time	T_{BLKCSU}	0.404		0.476		ns
Write block hold time	T_{BLKCHD}	0.007		0.008		ns
Write input data setup time	T_{DINCSU}	0.115		0.135		ns
Write input data hold time	T_{DINCHD}	0.15		0.177		ns

Table 251 • SmartFusion2 Cortex-M3 ISP Programming (eNVM Only) (continued)

M2S/M2GL Device	Image size Bytes	Authenticate	Program	Verify	Unit
150	544496	10	158	15	Sec

Table 252 • SmartFusion2 Cortex-M3 ISP Programming (Fabric and eNVM)

M2S/M2GL Device	Image size Bytes	Authenticate	Program	Verify	Unit
005	439296	9	61	11	Sec
010	842688	15	107	21	Sec
025	1497408	26	121	35	Sec
050	2695168	43	141	55	Sec
060	2686464	48	143	60	Sec
090	4190208	75	244	91	Sec
150	6682768	117	296	141	Sec

Table 253 • Programming Times with 100 kHz, 25 MHz, and 12.5 MHz SPI Clock Rates (Fabric Only)

M2S/M2GL Device	Auto Programming	Auto Update	Programming Recovery	Unit
	100 kHz	25 MHz	12.5 MHz	
005	47	27	28	Sec
010	77	35	35	Sec
025	150	42	41	Sec
050	33 ¹	Not Supported	Not Supported	Sec
060	291	83	82	Sec
090	427	109	108	Sec
150	708	157	160	Sec

1. Auto Programming in 050 device is done through SC_SPI, and SPI CLK is set to 6.25 MHz.

Table 254 • Programming Times with 100 kHz, 25 MHz, and 12.5 MHz SPI Clock Rates (eNVM Only)

M2S/M2GL Device	Auto Programming	Auto Update	Programming Recovery	Unit
	100 kHz	25 MHz	12.5 MHz	
005	41	48	49	Sec
010	86	87	87	Sec
025	87	85	86	Sec
050	85	Not Supported	Not Supported	Sec
060	78	86	86	Sec
090	154	162	162	Sec

Table 254 • Programming Times with 100 kHz, 25 MHz, and 12.5 MHz SPI Clock Rates (eNVM Only) (continued)

M2S/M2GL Device	Auto Programming	Auto Update	Programming Recovery	Unit
	100 kHz	25 MHz	12.5 MHz	
150	161	161	161	Sec

Table 255 • Programming Times with 100 kHz, 25 MHz, and 12.5 MHz SPI Clock Rates (Fabric and eNVM)

M2S/M2GL Device	Auto Programming	Auto Update	Programming Recovery	Unit
	100 kHz	25 MHz	12.5 MHz	
005	47	27	28	Sec
010	77	35	35	Sec
025	150	42	41	Sec
050	33 ¹	Not Supported	Not Supported	Sec
060	291	83	82	Sec
090	427	109	108	Sec
150	708	157	160	Sec
005	41	48	49	Sec
010	86	87	87	Sec
025	87	85	86	Sec
050	85	Not Supported	Not Supported	Sec
060	78	86	86	Sec
090	154	162	162	Sec
150	161	161	161	Sec
005	87	67	66	Sec
010	161	113	113	Sec
025	229	120	121	Sec
050	112	Not Supported	Not Supported	Sec
060	368	161	158	Sec
090	582	261	260	Sec
150	867	309	310	Sec

1. Auto Programming in 050 device is done through SC_SPI, and SPI CLK is set to 6.25 MHz.

Table 265 • Programming Times with 100 kHz, 25 MHz. and 12.5 MHz SPI Clock Rates (Fabric Only)

M2S/M2GL Device	Auto Programming	Auto Update	Programming Recovery	Unit
	100 kHz	25 MHz	12.5 MHz	
005	69	49	50	Sec
010	99	57	57	Sec
025	150	64	63	Sec
050	55 ¹	Not Supported	Not Supported	Sec
060	313	105	104	Sec
090	449	131	130	Sec
150	730	179	183	Sec

1. Auto programming in 050 device is done through SC_SPI, and SPI CLK is set to 6.25 MHz.

Table 266 • Programming Times with 100 kHz, 25 MHz. and 12.5 MHz SPI Clock Rates (eNVM Only)

M2S/M2GL Device	Auto Programming	Auto Update	Programming Recovery	Unit
	100 kHz	25 MHz	12.5 MHz	
005	63	70	71	Sec
010	108	109	109	Sec
025	109	107	108	Sec
050	107	Not Supported	Not Supported	Sec
060	100	108	108	Sec
090	176	184	184	Sec
150	183	183	183	Sec

Table 267 • Programming Times with 100 kHz, 25 MHz. and 12.5 MHz SPI Clock Rates (Fabric and eNVM)

M2S/M2GL Device	Auto Programming	Auto Update	Programming Recovery	Unit
	100 kHz	25 MHz	12.5 MHz	
005	109	89	88	Sec
010	183	135	135	Sec
025	251	142	143	Sec
050	134	Not Supported	Not Supported	Sec
060	390	183	180	Sec
090	604	283	282	Sec
150	889	331	332	Sec

2.3.17 Non-Deterministic Random Bit Generator (NRBG) Characteristics

For more information about NRBG, see *AC407: Using NRBG Services in SmartFusion2 and IGLOO2 Devices Application Note*. The following table lists the NRBG in worst-case industrial conditions when $T_J = 100\text{ }^{\circ}\text{C}$, $V_{DD} = 1.14\text{ V}$.

Table 275 • Non-Deterministic Random Bit Generator (NRBG)

Service	Timing	Unit	Conditions	
			Prediction Resistance	Additional Input
Instantiate	85	ms	OFF	X
Generate (after Instantiate) ¹	4.5 ms + (6.25 us/byte x No. of Bytes)		OFF	0
	6.0 ms + (6.25 us/byte x No. of Bytes)		OFF	64
	7.0 ms + (6.25 us/byte x No. of Bytes)		OFF	128
Generate (after Instantiate)	47	ms	ON	X
Generate (subsequent) ¹	0.5 ms + (6.25 us/byte x No. of Bytes)		OFF	0
	2.0 ms + (6.25 us/byte x No. of Bytes)		OFF	64
	3.0 ms + (6.25 us/byte x No. of Bytes)		OFF	128
Generate (subsequent)	43	ms	ON	X
Reseed	40	ms		
Uninstantiate	0.16	ms		
Reset	0.10	ms		
Self test	20	ms	First time after power-up	
	6	ms	Subsequent	

1. If PUF_OFF, generate will incur additional PUF delay time for consecutive service calls.

2.3.18 Cryptographic Block Characteristics

For more information about cryptographic block and associated services, see *AC410: Using AES System Services in SmartFusion2 and IGLOO2 Devices Application Note* and *AC432: Using SHA-256 System Services in SmartFusion2 and IGLOO2 Devices Application Note*.

The following table lists the cryptographic block characteristics in worst-case industrial conditions when $T_J = 100\text{ }^{\circ}\text{C}$, $V_{DD} = 1.14\text{ V}$.

Table 276 • Cryptographic Block Characteristics

Service	Conditions	Timing	Unit
Any service	First certificate check penalty at boot	11.5	ms
AES128/256 (encoding / decoding) ¹	100 blocks up to 64k blocks	700	kbps

Table 277 • Electrical Characteristics of the Crystal Oscillator – High Gain Mode (20 MHz) (continued)

Parameter	Symbol	Min	Typ	Max	Unit	Condition
Startup time (with regard to stable oscillator output)	SUXTAL			0.8	ms	005, 010, 025, and 050 devices
				1.0	ms	090 and 150 devices

Table 278 • Electrical Characteristics of the Crystal Oscillator – Medium Gain Mode (2 MHz)

Parameter	Symbol	Min	Typ	Max	Unit	Condition
Operating frequency	FXTAL		2		MHz	
Accuracy	ACCXTAL			0.00105	%	050 devices
				0.003	%	005, 010, 025, 090, and 150 devices
				0.004	%	060 devices
Output duty cycle	CYCXTAL		49–51	47–53	%	
Output period jitter (peak to peak)	JITPERXTAL		1	5	ns	
Output cycle to cycle jitter (peak to peak)	JITCYCXTAL		1	5	ns	
Operating current	IDYNXTAL		0.3		mA	
Input logic level high	VIHXTAL	0.9 V _{PP}			V	
Input logic level low	VILXTAL			0.1 V _{PP}	V	
Startup time (with regard to stable oscillator output)	SUXTAL			4.5	ms	010 and 050 devices
				5	ms	005 and 025 devices
				7	ms	090 and 150 devices

Table 279 • Electrical Characteristics of the Crystal Oscillator – Low Gain Mode (32 kHz)

Parameter	Symbol	Min	Typ	Max	Unit	Condition
Operating frequency	FXTAL		32		kHz	
Accuracy	ACCXTAL			0.004	%	005, 010, 025, 050, 060, and 090 devices
				0.005	%	150 devices
Output duty cycle	CYCXTAL		49–51	47–53	%	
Output period jitter (peak to peak)	JITPERXTAL		150	300	ns	
Output cycle to cycle jitter (peak to peak)	JITCYCXTAL		150	300	ns	
Operating current	IDYNXTAL		0.044		mA	010 and 050 devices
			0.060		mA	005, 025, 060, 090, and 150 devices
Input logic level high	VIHXTAL	0.9 V _{PP}			V	
Input logic level low	VILXTAL			0.1 V _{PP}	V	
Startup time (with regard to stable oscillator output)	SUXTAL			115	ms	005, 025, 050, 090, and 150 devices
				126	ms	010 devices

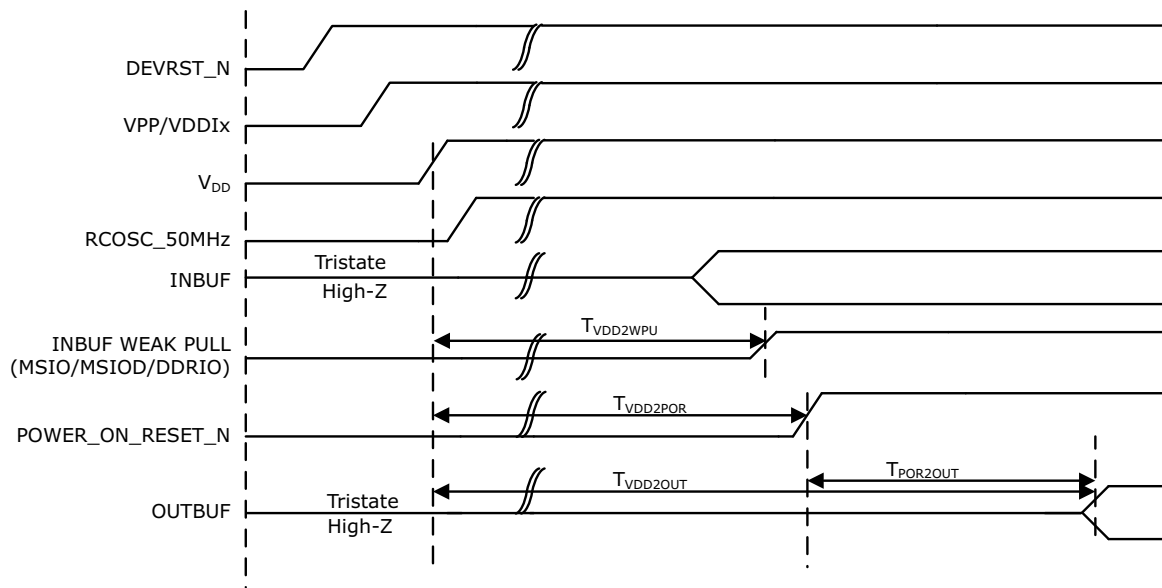
2.3.24 Power-up to Functional Times

The following table lists the SmartFusion2 power-up to functional times in worst-case industrial conditions when $T_J = 100\text{ }^{\circ}\text{C}$, $V_{DD} = 1.14\text{ V}$.

Table 288 • Power-up to Functional Times for SmartFusion2

Symbol	From	To	Description	Maximum Power-up to Functional Time for SmartFusion2 (uS)						
				005	010	025	050	060	090	150
$T_{POR2OUT}$	POWER_ON_RESET_N	Output available at I/O	Fabric to output	647	500	531	483	474	524	647
$T_{POR2MSSRST}$	POWER_ON_RESET_N	MSS_RESE T_N_M2F	Fabric to MSS	644	497	528	480	468	518	641
$T_{MSSRST2OUT}$	MSS_RESET_N_M2F	Output available at I/O	MSS to output	3.6	3.6	3.6	3.4	4.9	4.8	4.8
$T_{VDD2OUT}$	V_{DD}	Output available at I/O	V_{DD} at its minimum threshold level to output	3096	2975	3012	2959	2869	2992	3225
$T_{VDD2POR}$	V_{DD}	POWER_ON_RESET_N	V_{DD} at its minimum threshold level to fabric	2476	2487	2496	2486	2406	2563	2602
$T_{VDD2MSSRST}$	V_{DD}	MSS_RESE T_N_M2F	V_{DD} at its minimum threshold level to MSS	3093	2972	3008	2956	2864	2987	3220
$T_{VDD2WPU}$	DEV_RST_N	DDRIO Inbuf weak pull	DEV_RST_N to Inbuf weak pull	2500	2487	2509	2475	2507	2519	2617
	DEV_RST_N	MSIO Inbuf weak pull	DEV_RST_N to Inbuf weak pull	2504	2491	2510	2478	2517	2525	2620
	DEV_RST_N	MSIOD Inbuf weak pull	DEV_RST_N to Inbuf weak pull	2479	2468	2493	2458	2486	2499	2595

Note: For more information about power-up times, see *UG0331: SmartFusion2 Microcontroller Subsystem User Guide*.

Figure 18 • Power-up to Functional Timing Diagram for IGLOO2

2.3.25 DEVRST_N Characteristics

Table 290 • DEVRST_N Characteristics for All Devices

Parameter	Symbol	Max	Unit
DEVRST_N ramp rate	$T_{RAMPDEVRSTN}$	1	us
DEVRST_N cycling rate	$F_{MAXPDEVRSTN}$	100	kHz

2.3.26 DEVRST_N to Functional Times

The following table lists the SmartFusion2 DEVRST_N to functional times in worst-case industrial conditions when $T_J = 100^\circ\text{C}$, $V_{DD} = 1.14\text{ V}$.

Table 291 • DEVRST_N to Functional Times for SmartFusion2

				Maximum Power-up to Functional Time for SmartFusion2 (uS)						
Symbol	From	To	Description	005	010	025	050	060	090	150
T _{POR2OUT}	POWER_ON_RESET_N	Output available at I/O	Fabric to output	518	501	527	521	422	419	694
T _{POR2MSSRST}	POWER_ON_RESET_N	MSS_RESE T_N_M2F	Fabric to MSS	515	497	524	518	417	414	689
T _{MSSRST2OUT}	MSS_RESET_N_M2F	Output available at I/O	MSS to output	3.5	3.5	3.5	3.3	4.8	4.8	4.8
T _{DEVRST2OUT}	DEVRST_N	Output available at I/O	V _{DD} at its minimum threshold level to output	706	768	715	691	641	635	871

The following table lists the receiver pa in worst-case industrial conditions when $T_J = 100\text{ }^{\circ}\text{C}$, $V_{DD} = 1.14\text{ V}$.

Table 297 • Receiver Parameters

Symbol	Description	Min	Typ	Max	Unit
VRX-IN-PP-CC	Differential input peak-to-peak sensitivity (2.5 Gbps)	0.238		1.2	V
	Differential input peak-to-peak sensitivity (2.5 Gbps, de-emphasized)	0.219		1.2	V
	Differential input peak-to-peak sensitivity (5.0 Gbps)	0.300		1.2	V
	Differential input peak-to-peak sensitivity (5.0 Gbps, de-emphasized)	0.300		1.2	V
VRX-CM-AC-P	Input common mode range (AC coupled)			150	mV
ZRX-DIFF-DC	Differential input termination	80	100	120	Ω
REXT	External calibration resistor	1,188	1,200	1,212	Ω
CDR-LOCK-RST	CDR relock time from reset			15	μs
RLRX-DIFF	Return loss differential mode (2.5 Gbps)	-10			dB
	Return loss differential mode (5.0 Gbps)				
	0.05 GHz to 1.25 GHz	-10			dB
	1.25 GHz to 2.5 GHz	-8			dB
RLRX-CM	Return loss common mode (2.5 Gbps, 5.0 Gbps)	-6			dB
RX-CID ¹	CID limit PCIe Gen1/2			200	UI
VRX-IDLE-DET-DIFF-PP	Signal detect limit	65		175	mV

1. AC-coupled, BER = e^{-12} , using synchronous clock.

Table 298 • SerDes Protocol Compliance

Protocol	Maximum Data Rate (Gbps)	-1	-Std
PCIe Gen 1	2.5	Yes	Yes
PCIe Gen 2	5.0	Yes	
XAUI	3.125	Yes	
Generic EPCS	3.2	Yes	
Generic EPCS	2.5	Yes	Yes

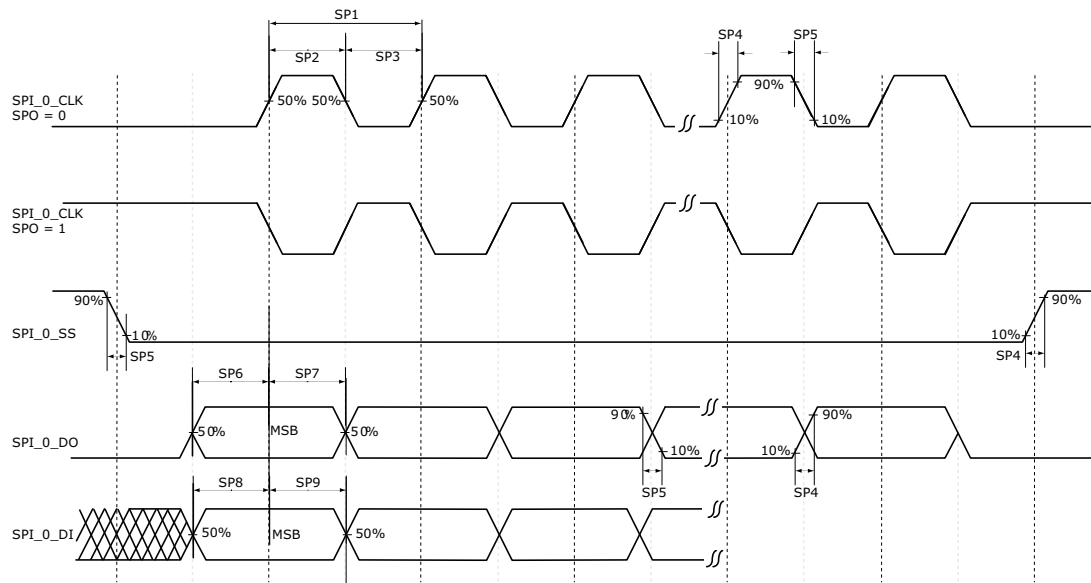
2.3.31.3 Serial Peripheral Interface (SPI) Characteristics

This section describes the DC and switching of the SPI interface. Unless otherwise noted, all output characteristics given are for a 35 pF load on the pins and all sequential timing characteristics are related to SPI_x_CLK. For timing parameter definitions, see Figure 22, page 128.

The following table lists the SPI characteristics in worst-case industrial conditions when $T_J = 100\text{ }^{\circ}\text{C}$, $V_{DD} = 1.14\text{ V}$

Table 305 • SPI Characteristics for All Devices

Symbol	Description	Min	Typ	Max	Unit	Conditions
SPIFMAX	Maximum operating frequency of SPI interface			20	MHz	
sp1	SPI_[0 1]_CLK minimum period					
	SPI_[0 1]_CLK = PCLK/2	12			ns	
	SPI_[0 1]_CLK = PCLK/4	24.1			ns	
	SPI_[0 1]_CLK = PCLK/8	48.2			ns	
	SPI_[0 1]_CLK = PCLK/16	0.1			μs	
	SPI_[0 1]_CLK = PCLK/32	0.19			μs	
	SPI_[0 1]_CLK = PCLK/64	0.39			μs	
	SPI_[0 1]_CLK = PCLK/128	0.77			μs	
sp2	SPI_[0 1]_CLK minimum pulse width high					
	SPI_[0 1]_CLK = PCLK/2	6			ns	
	SPI_[0 1]_CLK = PCLK/4	12.05			ns	
	SPI_[0 1]_CLK = PCLK/8	24.1			ns	
	SPI_[0 1]_CLK = PCLK/16	0.05			μs	
	SPI_[0 1]_CLK = PCLK/32	0.095			μs	
	SPI_[0 1]_CLK = PCLK/64	0.195			μs	
	SPI_[0 1]_CLK = PCLK/128	0.385			μs	
sp3	SPI_[0 1]_CLK minimum pulse width low					
	SPI_[0 1]_CLK = PCLK/2	6			ns	
	SPI_[0 1]_CLK = PCLK/4	12.05			ns	
	SPI_[0 1]_CLK = PCLK/8	24.1			ns	
	SPI_[0 1]_CLK = PCLK/16	0.05			μs	
	SPI_[0 1]_CLK = PCLK/32	0.095			μs	
	SPI_[0 1]_CLK = PCLK/64	0.195			μs	
	SPI_[0 1]_CLK = PCLK/128	0.385			μs	
sp4	SPI_[0 1]_CLK, SPI_[0 1]_DO, SPI_[0 1]_SS rise time (10%–90%) ¹		2.77		ns	I/O Configuration: LVCMOS 2.5 V– 8 mA AC loading: 35 pF Test conditions: Typical voltage, 25 °C

Figure 22 • SPI Timing for a Single Frame Transfer in Motorola Mode (SPH = 1)

2.3.32 CAN Controller Characteristics

The following table lists the CAN controller characteristics in worst-case industrial conditions when $T_J = 100^\circ\text{C}$, $V_{DD} = 1.14\text{ V}$.

Table 306 • CAN Controller Characteristics

Parameter	Description	–1	–Std	Unit
FCANREFCLK ¹	Internally sourced CAN reference clock frequency	160	136	MHz
BAUDCANMAX	Maximum CAN performance baud rate	1	1	Mbps
BAUDCANMIN	Minimum CAN performance baud rate	0.05	0.05	Mbps

1. PCLK to CAN controller must be a multiple of 8 MHz.

2.3.33 USB Characteristics

The following table lists the USB characteristics in worst-case industrial conditions when $T_J = 100^\circ\text{C}$, $V_{DD} = 1.14\text{ V}$.

Table 307 • USB Characteristics

Parameter	Description	–1	–Std	Unit
FUSBREFCLK	Internally sourced USB reference clock frequency	166	142	MHz
TUSBCLK	USB clock period	16.66	16.66	ns
TUSBPD	Clock to USB data propagation delay	9.0	9.0	ns
TUSBSU	Setup time for USB data	6.0	6.0	ns
TUSBHD	Hold time for USB data	0	0	ns