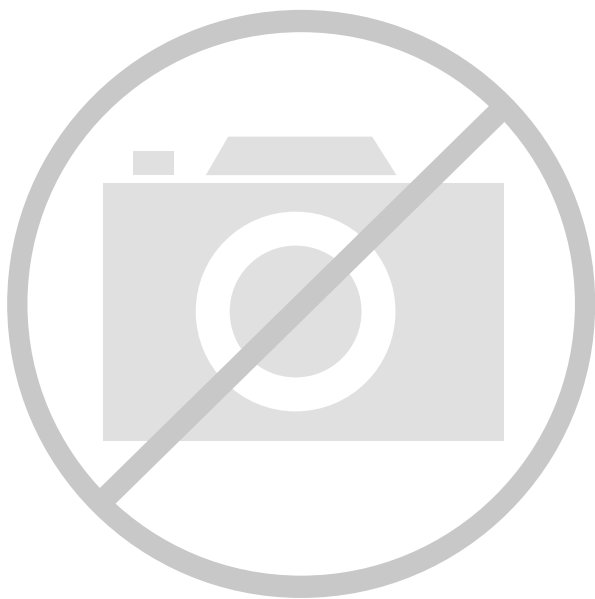




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Understanding [Embedded - FPGAs \(Field Programmable Gate Array\)](#)

Embedded - FPGAs, or Field Programmable Gate Arrays, are advanced integrated circuits that offer unparalleled flexibility and performance for digital systems. Unlike traditional fixed-function logic devices, FPGAs can be programmed and reprogrammed to execute a wide array of logical operations, enabling customized functionality tailored to specific applications. This reprogrammability allows developers to iterate designs quickly and implement complex functions without the need for custom hardware.

Applications of Embedded - FPGAs

The versatility of Embedded - FPGAs makes them indispensable in numerous fields. In telecommunications.

Details

Product Status	Active
Number of LABs/CLBs	-
Number of Logic Elements/Cells	56340
Total RAM Bits	1869824
Number of I/O	267
Number of Gates	-
Voltage - Supply	1.14V ~ 2.625V
Mounting Type	Surface Mount
Operating Temperature	0°C ~ 85°C (TJ)
Package / Case	484-BGA
Supplier Device Package	484-FPBGA (23x23)
Purchase URL	https://www.e-xfl.com/product-detail/microchip-technology/m2gl050ts-1fgg484



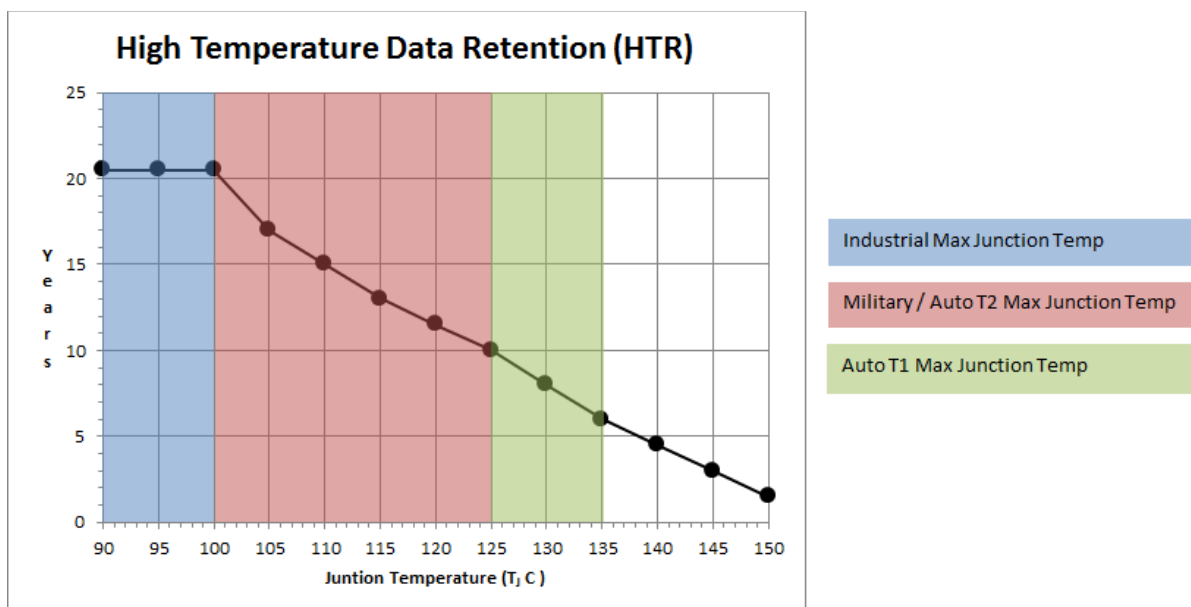
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Figure 1 • High Temperature Data Retention (HTR)

2.3.1.1 Overshoot/Undershoot Limits

For AC signals, the input signal may undershoot during transitions to -1.0 V for no longer than 10% of the period. The current during the transition must not exceed 100 mA.

For AC signals, the input signal may overshoot during transitions to $V_{CCI} + 1.0$ V for no longer than 10% of the period. The current during the transition must not exceed 100 mA.

Note: The above specifications do not apply to the PCI standard. The IGLOO2 and SmartFusion2 PCI I/Os are compliant with the PCI standard including the PCI overshoot/undershoot specifications.

2.3.1.2 Thermal Characteristics

The temperature variable in the Microsemi SoC Products Group Designer software refers to the junction temperature, not the ambient, case, or board temperatures. This is an important distinction because dynamic and static power consumption causes the chip's junction temperature to be higher than the ambient, case, or board temperatures.

EQ1 through EQ3 give the relationship between thermal resistance, temperature gradient, and power.

$$\theta_{JA} = \frac{T_J - T_A}{P} \quad \text{EQ 1}$$

$$\theta_{JB} = \frac{T_J - T_B}{P} \quad \text{EQ 2}$$

$$\theta_{JC} = \frac{T_J - T_C}{P} \quad \text{EQ 3}$$

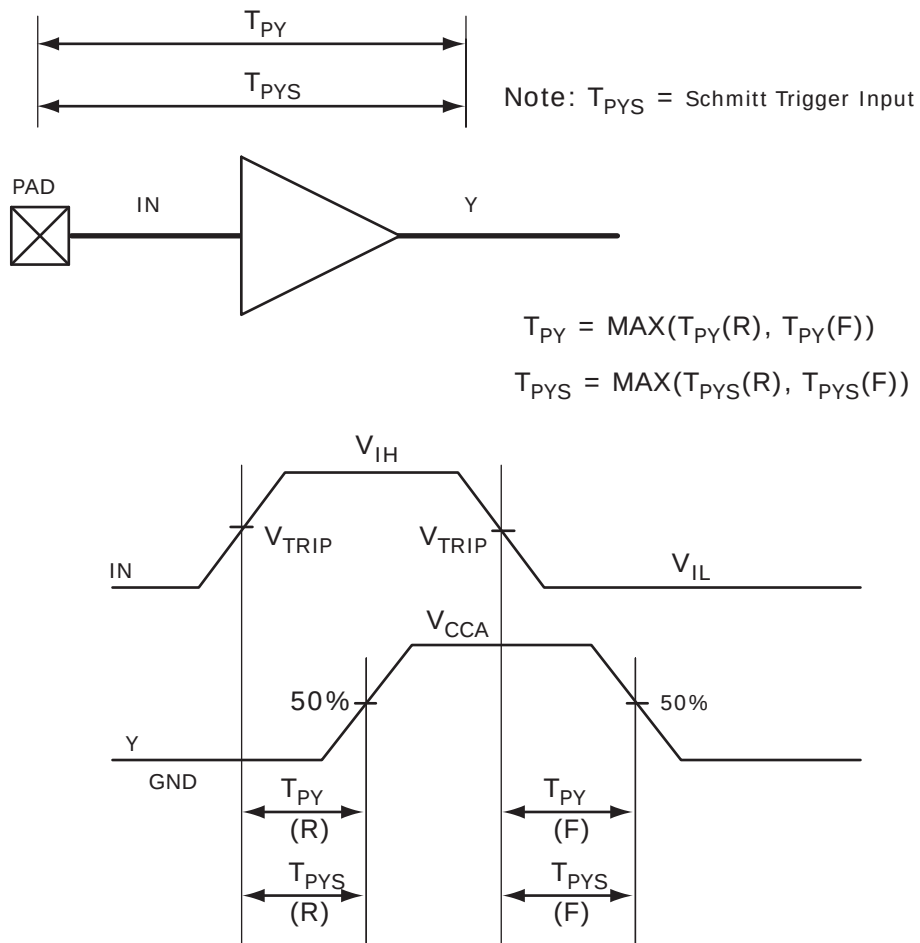
2.3.5 User I/O Characteristics

There are three types of I/Os supported in the IGLOO2 FPGA and SmartFusion2 SoC FPGA families: MSIO, MSIOD, and DDRIO I/O banks. The I/O standards supported by the different I/O banks is described in the I/Os section of the *UG0445: IGLOO2 FPGA and SmartFusion2 SoC FPGA Fabric User Guide*.

2.3.5.1 Input Buffer and AC Loading

The following figure shows the input buffer and AC loading.

Figure 3 • Input Buffer AC Loading



2.3.5.2 Output Buffer and AC Loading

The following figure shows the output buffer and AC loading.

Figure 4 • Output Buffer AC Loading

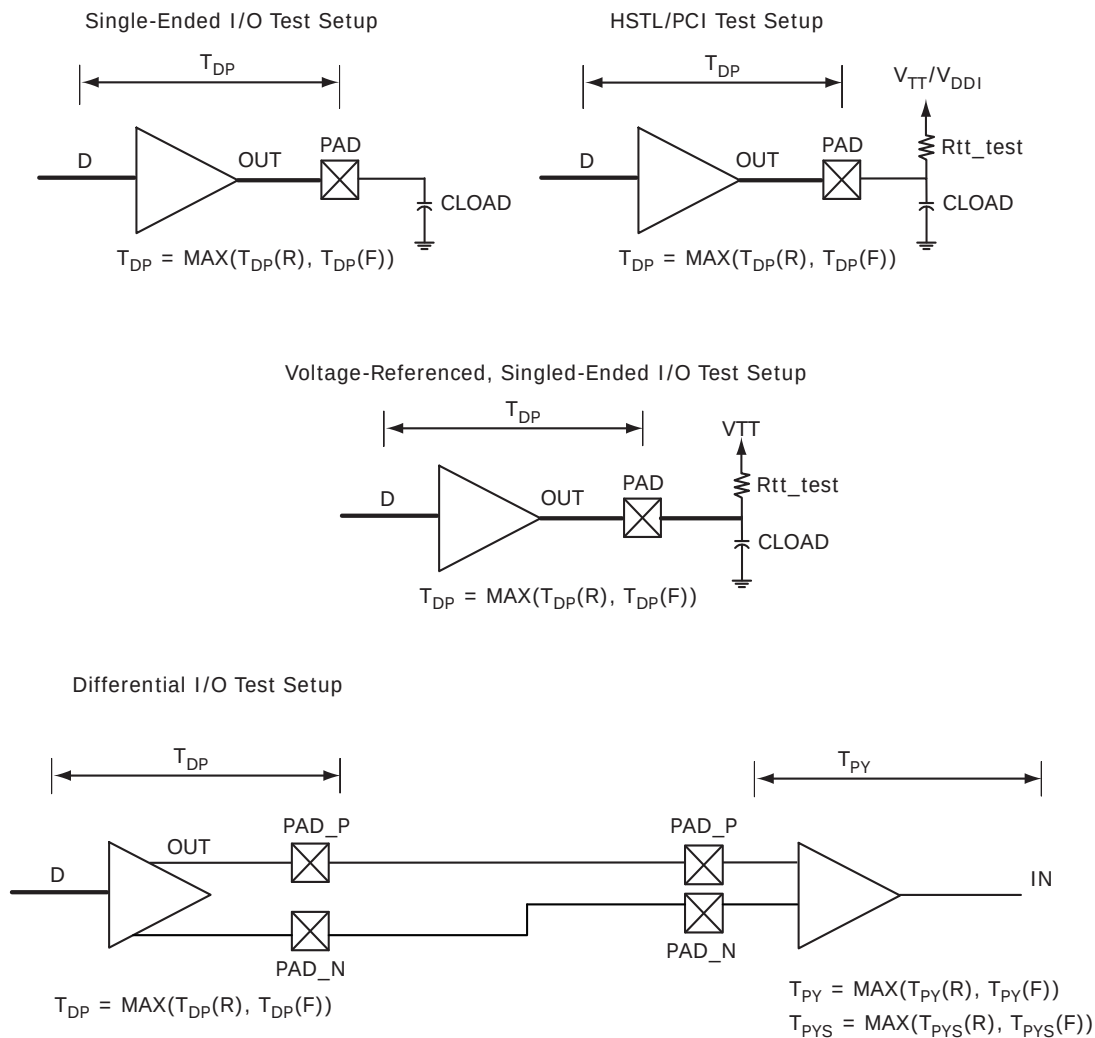


Table 22 • Maximum Frequency Summary Table for Voltage-Referenced I/O in Worst-Case Industrial Conditions

I/O	MSIO	MSIOD	DDRIO	Unit
LPDDR			200	MHz
HSTL1.5 V			200	MHz
SSTL 2.5 V	255	350	200	MHz
SSTL 1.8 V			334	MHz
SSTL 1.5 V			334	MHz

Table 23 • Maximum Frequency Summary Table for Differential I/O in Worst-Case Industrial Conditions

I/O	MSIO	MSIOD	Unit
LVPECL (input only)	450		MHz
LVDS 3.3 V	267.5		MHz
LVDS 2.5 V	267.5	350	MHz
RSDS	260	350	MHz
BLVDS	250		MHz
MLVDS	250		MHz
Mini-LVDS	260	350	MHz

The following table lists the minimum and maximum I/O weak pull-up/pull-down resistance values of MSIO I/O bank at V_{OH}/V_{OL} Level.

Table 26 • I/O Weak Pull-Up/Pull-Down Resistances for MSIO I/O Bank

V_{DDI} Domain	R(WEAK PULL-UP) at V_{OH} (Ω)		R(WEAK PULL-DOWN) at V_{OL} (Ω)	
	Min	Max	Min	Max
3.3 V	9.9K	17.1K	9.98K	17.5K
2.5 V ^{1, 2}	10K	17.6K	10.1K	18.4K
1.8 V ^{1, 2}	10.4K	19.1K	10.4K	20.4K
1.5 V ^{1, 2}	10.7K	20.4K	10.8K	22.2K
1.2 V ^{1, 2}	11.3K	23.2K	11.5K	26.7K

1. $R(\text{WEAK PULL-DOWN}) = (V_{OLspec})/I(\text{WEAK PULL-DOWN MAX})$.
2. $R(\text{WEAK PULL-UP}) = (V_{DDImax} - V_{OHspec})/I(\text{WEAK PULL-UP MIN})$.

The following table lists the minimum and maximum I/O weak pull-up/pull-down resistance values of MSIOD I/O bank at V_{OH}/V_{OL} Level.

Table 27 • I/O Weak Pull-up/Pull-down Resistances for MSIOD I/O Bank

V_{DDI} Domain	R(WEAK PULL-UP) at V_{OH} (Ω)		R(WEAK PULL-DOWN) at V_{OL} (Ω)	
	Min	Max	Min	Max
2.5 V ^{1, 2}	9.6K	16.6K	9.5K	16.4K
1.8 V ^{1, 2}	9.7K	17.3K	9.7K	17.1K
1.5 V ^{1, 2}	9.9K	18K	9.8K	17.6K
1.2 V ^{1, 2}	10.3K	19.6K	10K	19.1K

1. $R(\text{WEAK PULL-DOWN}) = (V_{OLspec})/I(\text{WEAK PULL-DOWN MAX})$.
2. $R(\text{WEAK PULL-UP}) = (V_{DDImax} - V_{OHspec})/I(\text{WEAK PULL-UP MIN})$.

The following table lists the hysteresis voltage value for schmitt trigger mode input buffers.

Table 28 • Schmitt Trigger Input Hysteresis

Input Buffer Configuration	Hysteresis Value (Typical, unless otherwise noted)
3.3 V LVTTTL/LVCMOS/ PCI/PCI-X	$0.05 \times V_{DDI}$ (worst-case)
2.5 V LVCMOS	$0.05 \times V_{DDI}$ (worst-case)
1.8 V LVCMOS	$0.1 \times V_{DDI}$ (worst-case)
1.5 V LVCMOS	60 mV
1.2 V LVCMOS	20 mV

2.3.5.7 2.5 V LVCMOS

LVCMOS 2.5 V is a general standard for 2.5 V applications and is supported in IGLOO2 FPGA and SmartFusion2 SoC FPGAs that are in compliance with the JEDEC specification JESD8-5A.

Minimum and Maximum DC/AC Input and Output Levels Specification

Table 38 • LVCMOS 2.5 V DC Recommended DC Operating Conditions

Parameter	Symbol	Min	Typ	Max	Unit
Supply voltage	V _{DDI}	2.375	2.5	2.625	V

Table 39 • LVCMOS 2.5 V DC Input Voltage Specification

Parameter	Symbol	Min	Max	Unit
DC input logic high (for MSIOD and DDRIO I/O banks)	V _{IH} (DC)	1.7	2.625	V
DC input logic high (for MSIO I/O bank)	V _{IH} (DC)	1.7	3.45	V
DC input logic low	V _{IL} (DC)	−0.3	0.7	V
Input current high ¹	I _{IH} (DC)			
Input current low ¹	I _{IL} (DC)			

1. See Table 24, page 22.

Table 40 • LVCMOS 2.5 V DC Output Voltage Specification

Parameter	Symbol	Min	Max	Unit
DC output logic high	V _{OH} ¹	V _{DDI} − 0.4	–	V
DC output logic low	V _{OL} ²		0.4	V

1. The VOH/VOL test points selected ensure compliance with LVCMOS 2.5 V JEDEC8-5A requirements.

Table 41 • LVCMOS 2.5 V AC Minimum and Maximum Switching Speed

Parameter	Symbol	Max	Unit	Conditions
Maximum data rate (for DDRIO I/O bank)	D _{MAX}	400	Mbps	AC loading: 17 pF load, maximum drive/slew
Maximum data rate (for MSIO I/O bank)	D _{MAX}	410	Mbps	AC loading: 17 pF load, maximum drive/slew
Maximum data rate (for MSIOD I/O bank)	D _{MAX}	420	Mbps	AC loading: 17 pF load, maximum drive/slew

Table 42 • LVCMOS 2.5 V AC Calibrated Impedance Option

Parameter	Symbol	Typ	Unit
Supported output driver calibrated impedance (for DDRIO I/O bank)	Rodt_cal	75, 60, 50, 33, 25, 20	Ω

Table 112 • SSTL2 Receiver Characteristics for MSIO I/O Bank (Input Buffers)

		T_{PY}		Unit
	On-Die Termination (ODT)	-1	-Std	
Pseudo differential	None	2.798	3.293	ns
True differential	None	2.733	3.215	ns

Table 113 • DDR1/SSTL2 Receiver Characteristics for MSIOD I/O Bank (Input Buffers)

		T_{PY}		Unit
	On-Die Termination (ODT)	-1	-Std	
Pseudo differential	None	2.476	2.913	ns
True differential	None	2.475	2.911	ns

Table 114 • SSTL2 Class I Transmitter Characteristics for DDRIO I/O Bank (Output and Tristate Buffers)

	T_{DP}		T_{ZL}		T_{ZH}		T_{HZ}		T_{LZ}		Unit
	-1	-Std	-1	-Std	-1	-Std	-1	-Std	-1	-Std	
Single-ended	2.26	2.66	1.99	2.341	1.985	2.335	2.135	2.512	2.13	2.505	ns
Differential	2.26	2.658	2.202	2.591	2.201	2.589	2.393	2.815	2.392	2.814	ns

Table 115 • DDR1/SSTL2 Class I Transmitter Characteristics for MSIO I/O Bank (Output and Tristate Buffers)

	T_{DP}		T_{ZL}		T_{ZH}		T_{HZ}		T_{LZ}		Unit
	-1	-Std	-1	-Std	-1	-Std	-1	-Std	-1	-Std	
Single-ended	2.055	2.417	2.037	2.396	2.03	2.388	2.068	2.433	2.061	2.425	ns
Differential	2.192	2.58	2.434	2.864	2.425	2.852	2.164	2.545	2.156	2.536	ns

Table 116 • DDR1/SSTL2 Class I Transmitter Characteristics for MSIOD I/O Bank (Output and Tristate Buffers)

	T_{DP}		T_{ZL}		T_{ZH}		T_{HZ}		T_{LZ}		Unit
	-1	-Std	-1	-Std	-1	-Std	-1	-Std	-1	-Std	
Single-ended	1.512	1.779	1.462	1.72	1.462	1.72	1.676	1.972	1.676	1.971	ns
Differential	1.676	1.971	1.774	2.087	1.766	2.077	1.854	2.181	1.845	2.171	ns

Table 117 • DDR1/SSTL2 Class II Transmitter Characteristics for DDRIO I/O Bank (Output and Tristate Buffers)

	T_{DP}		T_{ZL}		T_{ZH}		T_{HZ}		T_{LZ}		Unit
	-1	-Std	-1	-Std	-1	-Std	-1	-Std	-1	-Std	
Single-ended	2.122	2.497	1.906	2.243	1.902	2.237	2.061	2.424	2.056	2.418	ns
Differential	2.127	2.501	2.042	2.402	2.043	2.403	2.363	2.78	2.365	2.781	ns

2.3.6.6 Low Power Double Data Rate (LPDDR)

LPDDR reduced and full drive low power double data rate standards are supported in IGLOO2 FPGA and SmartFusion2 SoC FPGA I/Os. This standard requires a differential amplifier input buffer and a push-pull output buffer.

Minimum and Maximum DC/AC Input and Output Levels Specification

Table 139 • LPDDR DC Recommended DC Operating Conditions

Parameter	Symbol	Min	Typ	Max
Supply voltage	V_{DDI}	1.71	1.8	1.89
Termination voltage	V_{TT}	0.838	0.900	0.964
Input reference voltage	V_{REF}	0.838	0.900	0.964

Table 140 • LPDDR DC Input Voltage Specification

Parameter	Symbol	Min	Max
DC input logic high	V_{IH} (DC)	$0.7 \times V_{DDI}$	1.89
DC input logic low	V_{IL} (DC)	-0.3	$0.3 \times V_{DDI}$
Input current high ¹	I_{IH} (DC)		
Input current low ¹	I_{IL} (DC)		

1. See Table 24, page 22.

Table 141 • LPDDR DC Output Voltage Specification Reduced Drive

Parameter	Symbol	Min	Max
DC output logic high	V_{OH}	$0.9 \times V_{DDI}$	
DC output logic low	V_{OL}		$0.1 \times V_{DDI}$
Output minimum source DC current	I_{OH} at V_{OH}	0.1	
Output minimum sink current	I_{OL} at V_{OL}	-0.1	

Table 142 • LPDDR DC Output Voltage Specification Full Drive¹

Parameter	Symbol	Min	Max
DC output logic high	V_{OH}	$0.9 \times V_{DDI}$	
DC output logic low	V_{OL}		$0.1 \times V_{DDI}$
Output minimum source DC current	I_{OH} at V_{OH}	0.1	
Output minimum sink current	I_{OL} at V_{OL}	-0.1	

1. To meet JEDEC Electrical Compliance, use LPDDR Full Drive Transmitter.

Table 143 • LPDDR DC Differential Voltage Specification

Parameter	Symbol	Min
DC input differential voltage	V_{ID} (DC)	$0.4 \times V_{DDI}$

2.3.7.2 B-LVDS

Bus LVDS (B-LVDS) specifications extend the existing LVDS standard to high-performance multipoint bus applications. Multidrop and multipoint bus configurations may contain any combination of drivers, receivers, and transceivers.

Minimum and Maximum DC/AC Input and Output Levels Specification

Table 173 • B-LVDS Recommended DC Operating Conditions

Parameter	Symbol	Min	Typ	Max	Unit
Supply voltage	V_{DDI}	2.375	2.5	2.625	V

Table 174 • B-LVDS DC Input Voltage Specification

Parameter	Symbol	Min	Max	Unit
DC input voltage	V_I	0	2.925	V
Input current high ¹	I_{IH} (DC)			
Input current low ¹	I_{IL} (DC)			

1. See Table 24, page 22.

Table 175 • B-LVDS DC Output Voltage Specification (for MSIO I/O Bank Only)

Parameter	Symbol	Min	Typ	Max	Unit
DC output logic high	V_{OH}	1.25	1.425	1.6	V
DC output logic low	V_{OL}	0.9	1.075	1.25	V

Table 176 • B-LVDS DC Differential Voltage Specification

Parameter	Symbol	Min	Max	Unit
Differential output voltage swing (for MSIO I/O bank only)	V_{OD}	65	460	mV
Output common mode voltage (for MSIO I/O bank only)	V_{OCM}	1.1	1.5	V
Input common mode voltage	V_{ICM}	0.05	2.4	V
Input differential voltage	V_{ID}	0.1	V_{DDI}	V

Table 177 • B-LVDS Minimum and Maximum AC Switching Speed

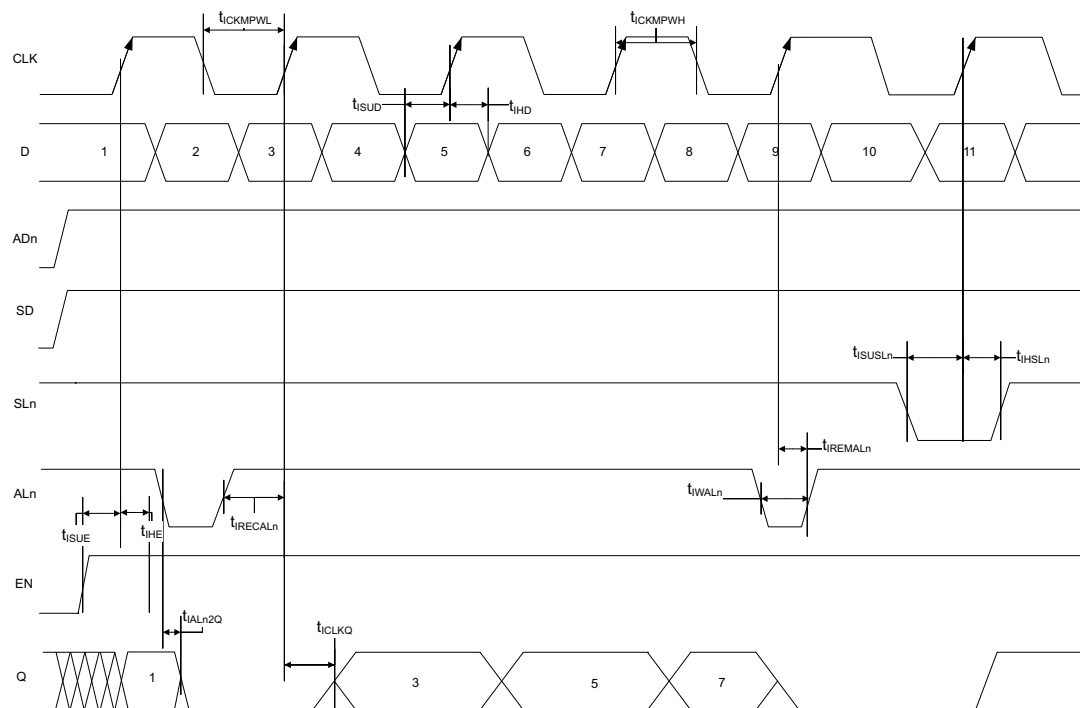
Parameter	Symbol	Max	Unit	Conditions
Maximum data rate (for MSIO I/O bank)	D_{MAX}	500	Mbps	AC loading: 2 pF / 100 Ω differential load

Table 178 • B-LVDS AC Impedance Specifications

Parameter	Symbol	Typ	Unit
Termination resistance	R_T	27	Ω

Table 179 • B-LVDS AC Test Parameter Specifications

Parameter	Symbol	Typ	Unit
Measuring/trip point for data path	V_{TRIP}	Cross point	V
Resistance for enable path (T_{ZH} , T_{ZL} , T_{HZ} , T_{LZ})	R_{ENT}	2K	Ω
Capacitive loading for enable path (T_{ZH} , T_{ZL} , T_{HZ} , T_{LZ})	C_{ENT}	5	pF

Figure 7 • I/O Register Input Timing Diagram

2.3.11 Global Resource Characteristics

The IGLOO2 and SmartFusion2 SoC FPGA devices offer a powerful, low skew global routing network which provides an effective clock distribution throughout the FPGA fabric. See [UG0445: IGLOO2 FPGA and SmartFusion2 SoC FPGA Fabric User Guide](#) for the positions of various global routing resources.

The following table lists the 150 device global resources in worst commercial-case conditions when $T_J = 85^\circ\text{C}$, $V_{DD} = 1.14\text{ V}$.

Table 225 • 150 Device Global Resource

Parameter	Symbol	-1		-Std		Unit
		Min	Max	Min	Max	
Input low delay for global clock	T_{RCKL}	0.83	0.911	0.831	0.913	ns
Input high delay for global clock	T_{RCKH}	1.457	1.588	1.715	1.869	ns
Maximum skew for global clock	T_{RCKSW}		0.131		0.154	ns

The following table lists the 090 device global resources in worst commercial-case conditions when $T_J = 85^\circ\text{C}$, $V_{DD} = 1.14\text{ V}$.

Table 226 • 090 Device Global Resource

Parameter	Symbol	-1		-Std		Unit
		Min	Max	Min	Max	
Input low delay for global clock	T_{RCKL}	0.835	0.888	0.833	0.886	ns
Input high delay for global clock	T_{RCKH}	1.405	1.489	1.654	1.752	ns
Maximum skew for global clock	T_{RCKSW}		0.084		0.098	ns

The following table lists the 050 device global resources in worst commercial-case conditions when $T_J = 85^\circ\text{C}$, $V_{DD} = 1.14\text{ V}$.

Table 227 • 050 Device Global Resource

Parameter	Symbol	-1		-Std		Unit
		Min	Max	Min	Max	
Input low delay for global clock	T_{RCKL}	0.827	0.897	0.826	0.896	ns
Input high delay for global clock	T_{RCKH}	1.419	1.53	1.671	1.8	ns
Maximum skew for global clock	T_{RCKSW}		0.111		0.129	ns

The following table lists the 025 device global resources in worst commercial-case conditions when $T_J = 85^\circ\text{C}$, $V_{DD} = 1.14\text{ V}$.

Table 228 • 025 Device Global Resource

Parameter	Symbol	-1		-Std		Unit
		Min	Max	Min	Max	
Input low delay for global clock	T_{RCKL}	0.747	0.799	0.745	0.797	ns
Input high delay for global clock	T_{RCKH}	1.294	1.378	1.522	1.621	ns
Maximum skew for global clock	T_{RCKSW}		0.084		0.099	ns

The following table lists the RAM1K18 – two-port mode for depth × width configuration 512 × 36 in worst commercial-case conditions when $T_J = 85\text{ }^{\circ}\text{C}$, $V_{DD} = 1.14\text{ V}$.

Table 236 • RAM1K18 – Two-Port Mode for Depth × Width Configuration 512 × 36

Parameter	Symbol	–1		–Std		Unit
		Min	Max	Min	Max	
Clock period	T_{CY}	2.5		2.941		ns
Clock minimum pulse width high	$T_{CLKMPWH}$	1.125		1.323		ns
Clock minimum pulse width low	$T_{CLKMPWL}$	1.125		1.323		ns
Pipelined clock period	T_{PLCY}	2.5		2.941		ns
Pipelined clock minimum pulse width high	$T_{PLCLKMPWH}$	1.125		1.323		ns
Pipelined clock minimum pulse width low	$T_{PLCLKMPWL}$	1.125		1.323		ns
Read access time with pipeline register	T_{CLK2Q}		0.334		0.393	ns
Read access time without pipeline register			2.25		2.647	ns
Address setup time	T_{ADDRSU}	0.313		0.368		ns
Address hold time	T_{ADDRHD}	0.274		0.322		ns
Data setup time	T_{DSU}	0.337		0.396		ns
Data hold time	T_{DHD}	0.111		0.13		ns
Block select setup time	T_{BLKSU}	0.207		0.244		ns
Block select hold time	T_{BLKHD}	0.201		0.237		ns
Block select to out disable time (when pipelined register is disabled)	T_{BLK2Q}		2.25		2.647	ns
Block select minimum pulse width	T_{BLKMPW}	0.186		0.219		ns
Read enable setup time	T_{RDESU}	0.449		0.528		ns
Read enable hold time	T_{RDEHD}	0.167		0.197		ns
Pipelined read enable setup time (A_DOUT_EN, B_DOUT_EN)	$T_{RDPLESU}$	0.248		0.291		ns
Pipelined read enable hold time (A_DOUT_EN, B_DOUT_EN)	$T_{RDPLEHD}$	0.102		0.12		ns
Asynchronous reset to output propagation delay	T_{R2Q}		1.506		1.772	ns
Asynchronous reset removal time	T_{RSTREM}	0.506		0.595		ns
Asynchronous reset recovery time	T_{RSTREC}	0.004		0.005		ns
Asynchronous reset minimum pulse width	T_{RSTMPW}	0.301		0.354		ns
Pipelined register asynchronous reset removal time	$T_{PLRSTREM}$	–0.279		–0.328		ns
Pipelined register asynchronous reset recovery time	$T_{PLRSTREC}$	0.327		0.385		ns
Pipelined register asynchronous reset minimum pulse width	$T_{PLRSTMPW}$	0.282		0.332		ns
Synchronous reset setup time	T_{SRSTSU}	0.226		0.265		ns
Synchronous reset hold time	T_{SRSTHD}	0.036		0.043		ns
Write enable setup time	T_{WESU}	0.39		0.458		ns
Write enable hold time	T_{WEHD}	0.242		0.285		ns
Maximum frequency	F_{MAX}		400		340	MHz

Table 238 • μ SRAM (RAM64x16) in 64 × 16 Mode (continued)

Parameter	Symbol	–1		–Std		Unit
		Min	Max	Min	Max	
Read synchronous reset hold time	T_{SRSTHD}	0.061		0.071		ns
Write clock period	T_{CCY}	4		4		ns
Write clock minimum pulse width high	$T_{CCLKMPWH}$	1.8		1.8		ns
Write clock minimum pulse width low	$T_{CCLKMPWL}$	1.8		1.8		ns
Write block setup time	T_{BLKCSU}	0.404		0.476		ns
Write block hold time	T_{BLKCHD}	0.007		0.008		ns
Write input data setup time	T_{DINCSU}	0.115		0.135		ns
Write input data hold time	T_{DINCHD}	0.15		0.177		ns
Write address setup time	$T_{ADDRCSU}$	0.088		0.104		ns
Write address hold time	$T_{ADDRCHD}$	0.128		0.15		ns
Write enable setup time	T_{WECSU}	0.397		0.467		ns
Write enable hold time	T_{WECHD}	–0.026		–0.03		ns
Maximum frequency	F_{MAX}		250		250	MHz

The following table lists the μ SRAM in 128 × 9 mode in worst commercial-case conditions when $T_J = 85^\circ\text{C}$, $V_{DD} = 1.14\text{ V}$.

Table 239 • μ SRAM (RAM128x9) in 128 × 9 Mode

Parameter	Symbol	–1		–Std		Unit
		Min	Max	Min	Max	
Read clock period	T_{CY}	4		4		ns
Read clock minimum pulse width high	$T_{CLKMPWH}$	1.8		1.8		ns
Read clock minimum pulse width low	$T_{CLKMPWL}$	1.8		1.8		ns
Read pipeline clock period	T_{PLCY}	4		4		ns
Read pipeline clock minimum pulse width high	$T_{PLCLKMPWH}$	1.8		1.8		ns
Read pipeline clock minimum pulse width low	$T_{PLCLKMPWL}$	1.8		1.8		ns
Read access time with pipeline register	T_{CLK2Q}		0.266		0.313	ns
Read access time without pipeline register			1.677		1.973	ns
Read address setup time in synchronous mode	T_{ADDRSU}	0.301		0.354		ns
Read address setup time in asynchronous mode		1.856		2.184		ns
Read address hold time in synchronous mode	T_{ADDRHD}	0.091		0.107		ns
Read address hold time in asynchronous mode		–0.778		–0.915		ns
Read enable setup time	T_{RDENSU}	0.278		0.327		ns
Read enable hold time	T_{RDENHD}	0.057		0.067		ns
Read block select setup time	T_{BLKSU}	1.839		2.163		ns
Read block select hold time	T_{BLKHD}	–0.65		–0.765		ns
Read block select to out disable time (when pipelined register is disabled)	T_{BLK2Q}		2.036		2.396	ns

Table 241 • μ SRAM (RAM256x4) in 256 × 4 Mode (continued)

Parameter	Symbol	-1		-Std		Unit
		Min	Max	Min	Max	
Write address hold time	$T_{ADDRCHD}$	0.245		0.288		ns
Write enable setup time	T_{WECSU}	0.397		0.467		ns
Write enable hold time	T_{WECHD}	-0.03		-0.03		ns
Maximum frequency	F_{MAX}		250		250	MHz

The following table lists the μ SRAM in 512 × 2 mode in worst commercial-case conditions when $T_J = 85^\circ\text{C}$, $V_{DD} = 1.14\text{ V}$.

Table 242 • μ SRAM (RAM512x2) in 512 × 2 Mode

Parameter	Symbol	-1		-Std		Unit
		Min	Max	Min	Max	
Read clock period	T_{CY}	4		4		ns
Read clock minimum pulse width high	$T_{CLKMPWH}$	1.8		1.8		ns
Read clock minimum pulse width low	$T_{CLKMPWL}$	1.8		1.8		ns
Read pipeline clock period	T_{PLCY}	4		4		ns
Read pipeline clock minimum pulse width high	$T_{PLCLKMPWH}$	1.8		1.8		ns
Read pipeline clock minimum pulse width low	$T_{PLCLKMPWL}$	1.8		1.8		ns
Read access time with pipeline register	T_{CLK2Q}		0.27		0.31	ns
Read access time without pipeline register			1.76		2.08	ns
Read address setup time in synchronous mode	T_{ADDRSU}	0.301		0.354		ns
Read address setup time in asynchronous mode		1.96		2.306		ns
Read address hold time in synchronous mode	T_{ADDRHD}	0.137		0.161		ns
Read address hold time in asynchronous mode		-0.58		-0.68		ns
Read enable setup time	T_{RDENSU}	0.278		0.327		ns
Read enable hold time	T_{RDENHD}	0.057		0.067		ns
Read block select setup time	T_{BLKSU}	1.839		2.163		ns
Read block select hold time	T_{BLKHD}	-0.65		-0.77		ns
Read block select to out disable time (when pipelined register is disabled)	T_{BLK2Q}		2.14		2.52	ns
Read asynchronous reset removal time (pipelined clock)	T_{RSTREM}	-0.02		-0.03		ns
Read asynchronous reset removal time (non-pipelined clock)		0.046		0.054		ns
Read asynchronous reset recovery time (pipelined clock)	T_{RSTREC}	0.507		0.597		ns
Read asynchronous reset recovery time (non-pipelined clock)		0.236		0.278		ns
Read asynchronous reset to output propagation delay (with pipelined register enabled)	T_{R2Q}		0.83		0.98	ns
Read synchronous reset setup time	T_{SRSTSU}	0.271		0.319		ns
Read synchronous reset hold time	T_{SRSTHD}	0.061		0.071		ns

Table 243 • μ SRAM (RAM1024x1) in 1024 × 1 Mode (continued)

Parameter	Symbol	–1		–Std		Unit
		Min	Max	Min	Max	
Read asynchronous reset recovery time (pipelined clock)	T_{RSTREC}	0.507		0.597		ns
Read asynchronous reset recovery time (non-pipelined clock)		0.236		0.278		ns
Read asynchronous reset to output propagation delay (with pipelined register enabled)	T_{R2Q}		0.83		0.98	ns
Read synchronous reset setup time	T_{SRSTSU}	0.271		0.319		ns
Read synchronous reset hold time	T_{SRSTHD}	0.061		0.071		ns
Write clock period	T_{CCY}	4		4		ns
Write clock minimum pulse width high	$T_{CCLKMPWH}$	1.8		1.8		ns
Write clock minimum pulse width low	$T_{CCLKMPWL}$	1.8		1.8		ns
Write block setup time	T_{BLKCSU}	0.404		0.476		ns
Write block hold time	T_{BLKCHD}	0.007		0.008		ns
Write input data setup time	T_{DINCSU}	0.003		0.004		ns
Write input data hold time	T_{DINCHD}	0.137		0.161		ns
Write address setup time	$T_{ADDRCSU}$	0.088		0.104		ns
Write address hold time	$T_{ADDRCHD}$	0.247		0.29		ns
Write enable setup time	T_{WECSU}	0.397		0.467		ns
Write enable hold time	T_{WECHD}	–0.03		–0.03		ns
Maximum frequency	F_{MAX}		250		250	MHz

2.3.13 Programming Times

The following tables list the programming times in typical conditions when $T_J = 25\text{ }^{\circ}\text{C}$, $V_{DD} = 1.2\text{ V}$. External SPI flash part# AT25DF641-s3H is used during this measurement.

Table 244 • JTAG Programming (Fabric Only)

M2S/M2GL				
Device	Image size Bytes	Program	Verify	Unit
005	302672	22	10	Sec
010	568784	28	18	Sec
025	1223504	51	26	Sec
050	2424832	66	54	Sec
060	2418896	77	54	Sec
090	3645968	113	126	Sec
150	6139184	155	193	Sec

2.3.14 Math Block Timing Characteristics

The fundamental building block in any digital signal processing algorithm is the multiply-accumulate function. Each IGLOO2 and SmartFusion2 SoC math block supports 18×18 signed multiplication, dot product, and built-in addition, subtraction, and accumulation units to combine multiplication results efficiently. The following table lists the math blocks with all registers used in worst commercial-case conditions when $T_J = 85^\circ\text{C}$, $V_{DD} = 1.14\text{ V}$.

Table 268 • Math Blocks with all Registers Used

Parameter	Symbol	–1		–Std		Unit
		Min	Max	Min	Max	
Input, control register setup time	T_{MISU}	0.149		0.176		ns
Input, control register hold time	T_{MIHD}	1.68		1.976		ns
CDIN input setup time	$T_{MOCDINSU}$	0.185		0.218		ns
CDIN input hold time	$T_{MOCDINHHD}$	0.08		0.094		ns
Synchronous reset/enable setup time	$T_{MSRSTENSU}$	–0.419		–0.493		ns
Synchronous reset/enable hold time	$T_{MSRSTENHD}$	0.011		0.013		ns
Asynchronous reset removal time	$T_{MARSTREM}$	0		0		ns
Asynchronous reset recovery time	$T_{MARSTREC}$	0.088		0.104		ns
Output register clock to out delay	T_{MOCQ}		0.232		0.273	ns
CLK minimum period	T_{MCLKMP}	2.245		2.641		ns

The following table lists the math blocks with input bypassed and output registers used in worst commercial-case conditions when $T_J = 85^\circ\text{C}$, $V_{DD} = 1.14\text{ V}$.

Table 269 • Math Block with Input Bypassed and Output Registers Used

Parameter	Symbol	–1		–Std		Unit
		Min	Max	Min	Max	
Output register setup time	T_{MOSU}	2.294		2.699		ns
Output register hold time	T_{MOHD}	1.68		1.976		ns
CDIN input setup time	$T_{MOCDINSU}$	0.115		0.136		ns
CDIN input hold time	$T_{MOCDINHHD}$	–0.444		–0.522		ns
Synchronous reset/enable setup time	$T_{MSRSTENSU}$	–0.419		–0.493		ns
Synchronous reset/enable hold time	$T_{MSRSTENHD}$	0.011		0.013		ns
Asynchronous reset removal time	$T_{MARSTREM}$	0		0		ns
Asynchronous reset recovery time	$T_{MARSTREC}$	0.014		0.017		ns
Output register clock to out delay	T_{MOCQ}		0.232		0.273	ns
CLK minimum period	T_{MCLKMP}	2.179		2.563		ns

2.3.24 Power-up to Functional Times

The following table lists the SmartFusion2 power-up to functional times in worst-case industrial conditions when $T_J = 100\text{ }^{\circ}\text{C}$, $V_{DD} = 1.14\text{ V}$.

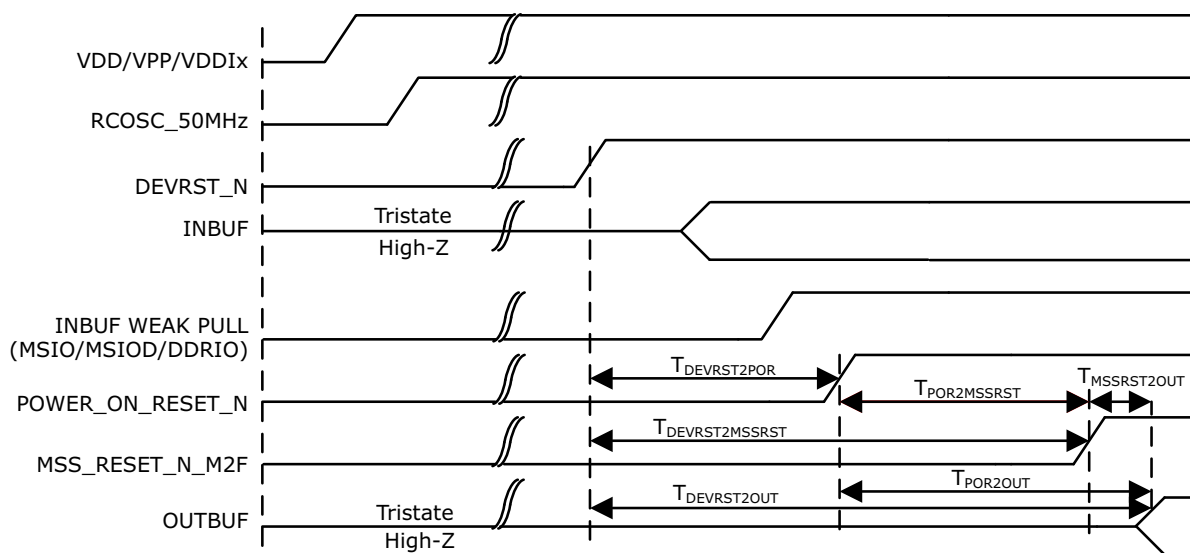
Table 288 • Power-up to Functional Times for SmartFusion2

Symbol	From	To	Description	Maximum Power-up to Functional Time for SmartFusion2 (uS)						
				005	010	025	050	060	090	150
$T_{POR2OUT}$	POWER_ON_RESET_N	Output available at I/O	Fabric to output	647	500	531	483	474	524	647
$T_{POR2MSSRST}$	POWER_ON_RESET_N	MSS_RESE T_N_M2F	Fabric to MSS	644	497	528	480	468	518	641
$T_{MSSRST2OUT}$	MSS_RESET_N_M2F	Output available at I/O	MSS to output	3.6	3.6	3.6	3.4	4.9	4.8	4.8
$T_{VDD2OUT}$	V_{DD}	Output available at I/O	V_{DD} at its minimum threshold level to output	3096	2975	3012	2959	2869	2992	3225
$T_{VDD2POR}$	V_{DD}	POWER_ON_RESET_N	V_{DD} at its minimum threshold level to fabric	2476	2487	2496	2486	2406	2563	2602
$T_{VDD2MSSRST}$	V_{DD}	MSS_RESE T_N_M2F	V_{DD} at its minimum threshold level to MSS	3093	2972	3008	2956	2864	2987	3220
$T_{VDD2WPU}$	DEV_RST_N	DDRIO Inbuf weak pull	DEV_RST_N to Inbuf weak pull	2500	2487	2509	2475	2507	2519	2617
	DEV_RST_N	MSIO Inbuf weak pull	DEV_RST_N to Inbuf weak pull	2504	2491	2510	2478	2517	2525	2620
	DEV_RST_N	MSIOD Inbuf weak pull	DEV_RST_N to Inbuf weak pull	2479	2468	2493	2458	2486	2499	2595

Note: For more information about power-up times, see [UG0331: SmartFusion2 Microcontroller Subsystem User Guide](#).

Table 291 • DEVRST_N to Functional Times for SmartFusion2 (continued)

Symbol	From	To	Description	Maximum Power-up to Functional Time for SmartFusion2 (uS)						
				005	010	025	050	060	090	150
$T_{\text{DEVRST2POR}}$	DEVRST_N	POWER_ON_RESET_N	V_{DD} at its minimum threshold level to fabric	233	289	216	213	237	234	219
$T_{\text{DEVRST2MSSRST}}$	DEVRST_N	MSS_RESET_N_M2F	V_{DD} at its minimum threshold level to MSS	702	765	712	688	636	630	866
$T_{\text{DEVRST2WPU}}$	DEVRST_N	DDRIO Inbuf weak pull	DEVRST_N to Inbuf weak pull	208	202	197	193	216	215	215
	DEVRST_N	MSIO Inbuf weak pull	DEVRST_N to Inbuf weak pull	208	202	197	193	216	215	215
	DEVRST_N	MSIOD Inbuf weak pull	DEVRST_N to Inbuf weak pull	208	202	197	193	216	215	215

Figure 19 • DEVRST_N to Functional Timing Diagram for SmartFusion2

2.3.31.3 Serial Peripheral Interface (SPI) Characteristics

This section describes the DC and switching of the SPI interface. Unless otherwise noted, all output characteristics given are for a 35 pF load on the pins and all sequential timing characteristics are related to SPI_x_CLK. For timing parameter definitions, see [Figure 22](#), page 128.

The following table lists the SPI characteristics in worst-case industrial conditions when $T_J = 100\text{ }^{\circ}\text{C}$, $V_{DD} = 1.14\text{ V}$

Table 305 • SPI Characteristics for All Devices

Symbol	Description	Min	Typ	Max	Unit	Conditions
SPIFMAX	Maximum operating frequency of SPI interface			20	MHz	
sp1	SPI_[0 1]_CLK minimum period					
	SPI_[0 1]_CLK = PCLK/2	12			ns	
	SPI_[0 1]_CLK = PCLK/4	24.1			ns	
	SPI_[0 1]_CLK = PCLK/8	48.2			ns	
	SPI_[0 1]_CLK = PCLK/16	0.1			μs	
	SPI_[0 1]_CLK = PCLK/32	0.19			μs	
	SPI_[0 1]_CLK = PCLK/64	0.39			μs	
	SPI_[0 1]_CLK = PCLK/128	0.77			μs	
sp2	SPI_[0 1]_CLK minimum pulse width high					
	SPI_[0 1]_CLK = PCLK/2	6			ns	
	SPI_[0 1]_CLK = PCLK/4	12.05			ns	
	SPI_[0 1]_CLK = PCLK/8	24.1			ns	
	SPI_[0 1]_CLK = PCLK/16	0.05			μs	
	SPI_[0 1]_CLK = PCLK/32	0.095			μs	
	SPI_[0 1]_CLK = PCLK/64	0.195			μs	
	SPI_[0 1]_CLK = PCLK/128	0.385			μs	
sp3	SPI_[0 1]_CLK minimum pulse width low					
	SPI_[0 1]_CLK = PCLK/2	6			ns	
	SPI_[0 1]_CLK = PCLK/4	12.05			ns	
	SPI_[0 1]_CLK = PCLK/8	24.1			ns	
	SPI_[0 1]_CLK = PCLK/16	0.05			μs	
	SPI_[0 1]_CLK = PCLK/32	0.095			μs	
	SPI_[0 1]_CLK = PCLK/64	0.195			μs	
	SPI_[0 1]_CLK = PCLK/128	0.385			μs	
sp4	SPI_[0 1]_CLK, SPI_[0 1]_DO, SPI_[0 1]_SS rise time (10%–90%) ¹		2.77		ns	I/O Configuration: LVCMOS 2.5 V– 8 mA AC loading: 35 pF Test conditions: Typical voltage, 25 °C