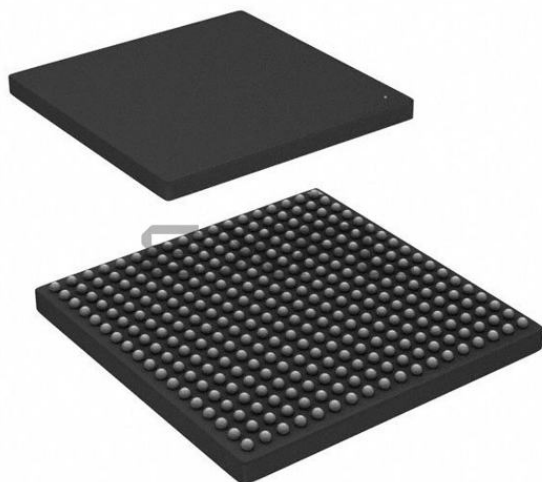




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Understanding [Embedded - FPGAs \(Field Programmable Gate Array\)](#)

Embedded - FPGAs, or Field Programmable Gate Arrays, are advanced integrated circuits that offer unparalleled flexibility and performance for digital systems. Unlike traditional fixed-function logic devices, FPGAs can be programmed and reprogrammed to execute a wide array of logical operations, enabling customized functionality tailored to specific applications. This reprogrammability allows developers to iterate designs quickly and implement complex functions without the need for custom hardware.

Applications of Embedded - FPGAs

The versatility of Embedded - FPGAs makes them indispensable in numerous fields. In telecommunications.

Details

Product Status	Active
Number of LABs/CLBs	-
Number of Logic Elements/Cells	56340
Total RAM Bits	1869824
Number of I/O	200
Number of Gates	-
Voltage - Supply	1.14V ~ 2.625V
Mounting Type	Surface Mount
Operating Temperature	0°C ~ 85°C (TJ)
Package / Case	325-TFBGA, FCBGA
Supplier Device Package	325-FCBGA (11x11)
Purchase URL	https://www.e-xfl.com/product-detail/microchip-technology/m2gl050ts-fcsg325

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Table 11 • SmartFusion2 and IGLOO2 Quiescent Supply Current ($V_{DD} = 1.2 \text{ V}$) – Typical Process

Symbol	Modes	005	010	025	050	060	090	150	Unit	Conditions
IDC2	Flash*Freeze	1.4	2.6	3.7	5.1	5.0	5.1	8.9	mA	Typical ($T_J = 25^\circ\text{C}$)
		12.0	20.0	26.6	35.3	35.4	35.7	57.8	mA	Commercial ($T_J = 85^\circ\text{C}$)
		18.5	30.8	41.0	54.5	54.5	55.0	89.0	mA	Industrial ($T_J = 100^\circ\text{C}$)

Table 12 • SmartFusion2 and IGLOO2 Quiescent Supply Current ($V_{DD} = 1.26 \text{ V}$) – Worst-Case Process

Symbol	Modes	005	010	025	050	060	090	150	Unit	Conditions
IDC1	Non-Flash*Freeze	43.8	57.0	84.6	132.3	161.4	163.0	242.5	mA	Commercial ($T_J = 85^\circ\text{C}$)
		65.3	85.7	127.8	200.9	245.4	247.8	369.0	mA	Industrial ($T_J = 100^\circ\text{C}$)
IDC2	Flash*Freeze	29.1	45.6	51.7	62.7	69.3	70.0	84.8	mA	Commercial ($T_J = 85^\circ\text{C}$)
		44.9	70.3	79.7	96.5	106.8	107.8	130.6	mA	Industrial ($T_J = 100^\circ\text{C}$)

2.3.2.2 Programming Currents

The following tables represent programming, verify and Inrush currents for SmartFusion2 SoC and IGLOO2 FPGA devices.

Table 13 • Currents During Program Cycle, $0^\circ\text{C} \leq T_J \leq 85^\circ\text{C}$ – Typical Process

Power Supplies	Voltage (V)	005	010	025	050	060	090	150 ¹	Unit
V_{DD}	1.26	46	53	55	58	30	42	52	mA
V_{PP}	3.46	8	11	6	10	9	12	12	mA
V_{PPNVM}	3.46	1	2	2	3	3	3		mA
V_{DDI}	2.62	31	16	17	1	12	12	81	mA
	3.46	62	31	36	1	12	17	84	mA
Number of banks		7	8	8	10	10	9	19	

1. V_{PP} and V_{PPNVM} are internally shorted.

Table 14 • Currents During Verify Cycle, $0^\circ\text{C} \leq T_J \leq 85^\circ\text{C}$ – Typical Process

Power Supplies	Voltage (V)	005	010	025	050	060	090	150 ¹	Unit
V_{DD}	1.26	44	53	55	58	33	41	51	mA
V_{PP}	3.46	6	5	3	15	8	11	12	mA
V_{PPNVM}	3.46	1	0	0	1	1	1		mA
V_{DDI}	2.62	31	16	17	1	12	11	81	mA
	3.46	61	32	36	1	12	17	84	mA
Number of banks		7	8	8	10	10	9	19	

1. V_{PP} and V_{PPNVM} are internally shorted.

2.3.6.3 Stub-Series Terminated Logic 2.5 V (SSTL2)

SSTL2 Class I and Class II are supported in IGLOO2 and SmartFusion2 SoC FPGAs and also comply with reduced and full drive of double data rate (DDR) standards. IGLOO2 and SmartFusion2 SoC FPGA I/Os supports both standards for single-ended signaling and differential signaling for SSTL2. This standard requires a differential amplifier input buffer and a push-pull output buffer.

Minimum and Maximum DC/AC Input and Output Levels Specification

Table 103 • DDR1/SSTL2 DC Recommended Operating Conditions

Parameter	Symbol	Min	Typ	Max	Unit
Supply voltage	V_{DDI}	2.375	2.5	2.625	V
Termination voltage	V_{TT}	1.164	1.250	1.339	V
Input reference voltage	V_{REF}	1.164	1.250	1.339	V

Table 104 • DDR1/SSTL2 DC Input Voltage Specification

Parameter	Symbol	Min	Max	Unit
DC input logic high	$V_{IH} (DC)$	$V_{REF} + 0.15$	2.625	V
DC input logic low	$V_{IL} (DC)$	-0.3	$V_{REF} - 0.15$	V
Input current high ¹	$I_{IH} (DC)$			
Input current low ¹	$I_{IL} (DC)$			

1. See Table 24, page 22.

Table 105 • DDR1/SSTL2 DC Output Voltage Specification

Parameter	Symbol	Min	Max	Unit
SSTL2 Class I (DDR Reduced Drive)				
DC output logic high	V_{OH}	$V_{TT} + 0.608$		V
DC output logic low	V_{OL}		$V_{TT} - 0.608$	V
Output minimum source DC current	I_{OH} at V_{OH}	8.1		mA
Output minimum sink current	I_{OL} at V_{OL}	-8.1		mA
SSTL2 Class II (DDR Full Drive) – Applicable to MSIO and DDRIO I/O Bank Only				
DC output logic high	V_{OH}	$V_{TT} + 0.81$		V
DC output logic low	V_{OL}		$V_{TT} - 0.81$	V
Output minimum source DC current	I_{OH} at V_{OH}	16.2		mA
Output minimum sink current	I_{OL} at V_{OL}	-16.2		mA

Table 106 • DDR1/SSTL2 DC Differential Voltage Specification

Parameter	Symbol	Min	Unit
DC input differential voltage	$V_{ID} (DC)$	0.3	V

Table 191 • M-LVDS AC Switching Characteristics for Receiver (for MSIOD I/O Bank - Input Buffers)

On-Die Termination (ODT)	T _{py}		Unit
	-1	-Std	
None	2.495	2.934	ns
100	2.495	2.935	ns

Table 192 • M-LVDS AC Switching Characteristics for Transmitter (for MSIO I/O Bank - Output and Tristate Buffers)

T _{DP}		T _{ZL}		T _{ZH}		T _{HZ}		T _{LZ}		Unit
-1	-Std	-1	-Std	-1	-Std	-1	-Std	-1	-Std	
2.258	2.656	2.348	2.762	2.334	2.746	2.123	2.497	2.125	2.5	ns

2.3.7.4 Mini-LVDS

Mini-LVDS is an unidirectional interface from the timing controller to the column drivers and is designed to the Texas Instruments Standard SLDA007A.

Mini-LVDS Minimum and Maximum Input and Output Levels

Table 193 • Mini-LVDS Recommended DC Operating Conditions

Parameter	Symbol	Min	Typ	Max	Unit
Supply voltage	V _{DDI}	2.375	2.5	2.625	V

Table 194 • Mini-LVDS DC Input Voltage Specification

Parameter	Symbol	Min	Max	Unit
DC Input voltage	V _I	0	2.925	V

Table 195 • Mini-LVDS DC Output Voltage Specification

Parameter	Symbol	Min	Typ	Max	Unit
DC output logic high	V _{OH}	1.25	1.425	1.6	V
DC output logic low	V _{OL}	0.9	1.075	1.25	V

Table 196 • Mini-LVDS DC Differential Voltage Specification

Parameter	Symbol	Min	Max	Unit
Differential output voltage swing	V _{OD}	300	600	mV
Output common mode voltage	V _{OCM}	1	1.4	V
Input common mode voltage	V _{ICM}	0.3	1.2	V
Input differential voltage	V _{ID}	100	600	mV

Table 197 • Mini-LVDS Minimum and Maximum AC Switching Speed

Parameter	Symbol	Max	Unit	Conditions
Maximum data rate (for MSIO I/O bank)	D _{MAX}	520	Mbps	AC loading: 2 pF / 100 Ω differential load
Maximum data rate (for MSIOD I/O bank)	D _{MAX}	700	Mbps	AC loading: 2 pF / 100 Ω differential load

Table 215 • LVPECL DC Input Voltage Specification

Parameter	Symbol	Min	Max	Unit
DC input voltage	V_I	0	3.45	V

Table 216 • LVPECL DC Differential Voltage Specification

Parameter	Symbol	Min	Typ	Max	Unit
Input common mode voltage	V_{ICM}	0.3		2.8	V
Input differential voltage	V_{IDIFF}	100	300	1,000	mV

Table 217 • LVPECL Minimum and Maximum AC Switching Speeds

Parameter	Symbol	Max	Unit
Maximum data rate	D_{MAX}	900	Mbps

AC Switching Characteristics

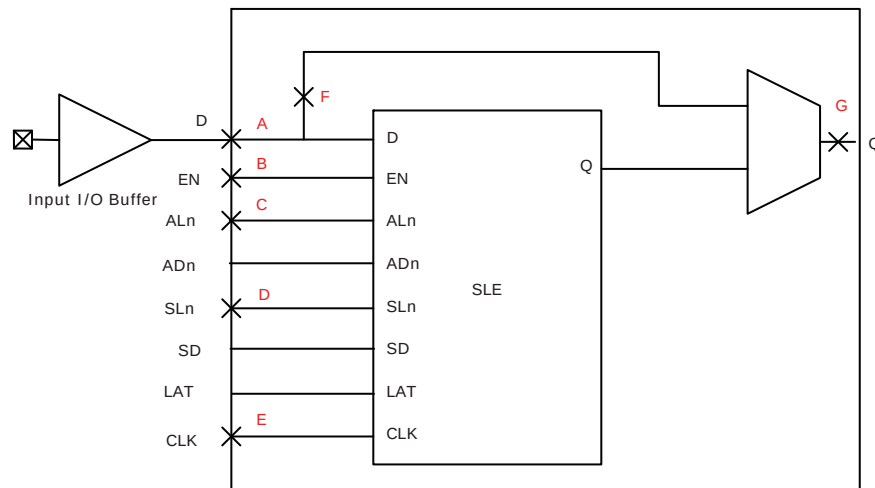
Worst commercial-case conditions: $T_J = 85^\circ\text{C}$, $V_{DD} = 1.14\text{ V}$, $V_{DDI} = 2.375\text{ V}$.

Table 218 • LVPECL Receiver Characteristics for MSIO I/O Bank

On-Die Termination (ODT)	T_{PY}		Unit
	-1	-Std	
None	2.572	3.025	ns
100	2.569	3.023	ns

2.3.8 I/O Register Specifications

This section describes input and output register specifications.

2.3.8.1 Input Register**Figure 6 • Timing Model for Input Register**

The following table lists the input data register propagation delays in worst commercial-case conditions when $T_J = 85^\circ\text{C}$, $V_{DD} = 1.14\text{ V}$.

Table 219 • Input Data Register Propagation Delays

Parameter	Symbol	Measuring Nodes (from, to) ¹	-1	-Std	Unit
Bypass delay of the input register	T_{IBYP}	F, G	0.353	0.415	ns
Clock-to-Q of the input register	T_{ICLKQ}	E, G	0.16	0.188	ns
Data setup time for the input register	T_{ISUD}	A, E	0.357	0.421	ns
Data hold time for the input register	T_{IHD}	A, E	0	0	ns
Enable setup time for the input register	T_{ISUE}	B, E	0.46	0.542	ns
Enable hold time for the input register	T_{IHE}	B, E	0	0	ns
Synchronous load setup time for the input register	T_{ISUSL}	D, E	0.46	0.542	ns
Synchronous load hold time for the input register	T_{IHSL}	D, E	0	0	ns
Asynchronous clear-to-Q of the input register (ADn=1)	T_{IALN2Q}	C, G	0.625	0.735	ns
Asynchronous preset-to-Q of the input register (ADn=0)		C, G	0.587	0.69	ns
Asynchronous load removal time for the input register	$T_{IREMALN}$	C, E	0	0	ns
Asynchronous load recovery time for the input register	$T_{IRECALN}$	C, E	0.074	0.087	ns
Asynchronous load minimum pulse width for the input register	T_{IWALN}	C, C	0.304	0.357	ns
Clock minimum pulse width high for the input register	$T_{ICKMPWH}$	E, E	0.075	0.088	ns
Clock minimum pulse width low for the input register	$T_{ICKMPWL}$	E, E	0.159	0.187	ns

1. For the derating values at specific junction temperature and voltage supply levels, see [Table 16](#), page 14 for derating values.

2.3.9 DDR Module Specification

This section describes input and output DDR module and timing specifications.

2.3.9.1 Input DDR Module

Figure 10 • Input DDR Module

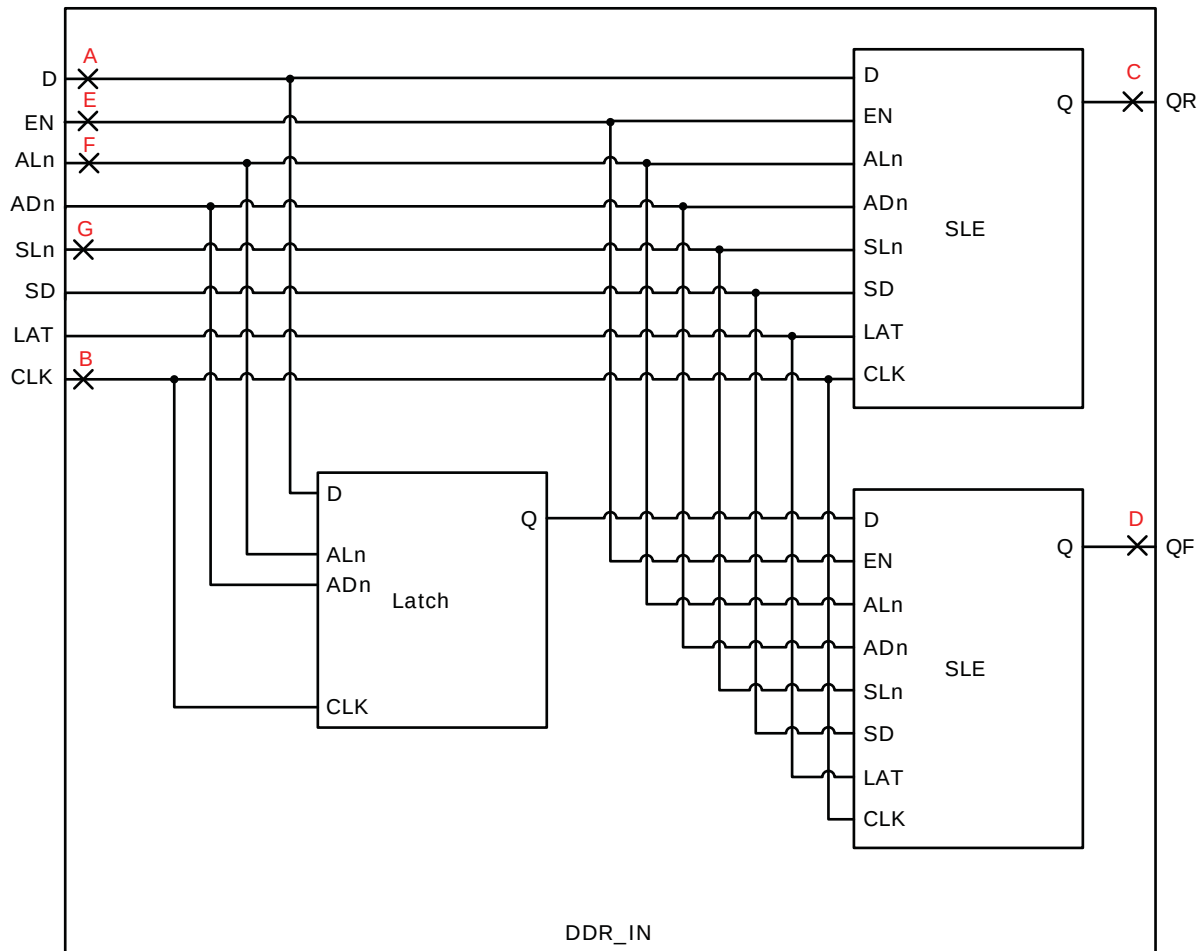


Table 231 • RAM1K18 – Dual-Port Mode for Depth × Width Configuration 1K × 18 (continued)

Parameter	Symbol	–1		–Std		Unit
		Min	Max	Min	Max	
Block select hold time	T _{BLKHD}	0.216		0.254		ns
Block select to out disable time (when pipelined register is disabled)	T _{BLK2Q}		1.529		1.799	ns
Block select minimum pulse width	T _{BLKMPW}	0.186		0.219		ns
Read enable setup time	T _{RDESU}	0.449		0.528		ns
Read enable hold time	T _{RDEHD}	0.167		0.197		ns
Pipelined read enable setup time (A_DOUT_EN, B_DOUT_EN)	T _{RDPLESU}	0.248		0.291		ns
Pipelined read enable hold time (A_DOUT_EN, B_DOUT_EN)	T _{RDPLEHD}	0.102		0.12		ns
Asynchronous reset to output propagation delay	T _{R2Q}	–	1.506	–	1.772	ns
Asynchronous reset removal time	T _{RSTREM}	0.506		0.595		ns
Asynchronous reset recovery time	T _{RSTREC}	0.004		0.005		ns
Asynchronous reset minimum pulse width	T _{RSTMPW}	0.301		0.354		ns
Pipelined register asynchronous reset removal time	T _{PLRSTREM}	–0.279		–0.328		ns
Pipelined register asynchronous reset recovery time	T _{PLRSTREC}	0.327		0.385		ns
Pipelined register asynchronous reset minimum pulse width	T _{PLRSTMPW}	0.282		0.332		ns
Synchronous reset setup time	T _{SRSTSU}	0.226		0.265		ns
Synchronous reset hold time	T _{SRSTHD}	0.036		0.043		ns
Write enable setup time	T _{WESU}	0.39		0.458		ns
Write enable hold time	T _{WEHD}	0.242		0.285		ns
Maximum frequency	F _{MAX}		400		340	MHz

The following table lists the RAM1K18 – dual-port mode for depth × width configuration 2K × 9 in worst commercial-case conditions when T_J = 85 °C, V_{DD} = 1.14 V.

Table 232 • RAM1K18 – Dual-Port Mode for Depth × Width Configuration 2K × 9

Parameter	Symbol	–1		–Std		Unit
		Min	Max	Min	Max	
Clock period	T _{CY}	2.5		2.941		ns
Clock minimum pulse width high	T _{CLKMPWH}	1.125		1.323		ns
Clock minimum pulse width low	T _{CLKMPWL}	1.125		1.323		ns
Pipelined clock period	T _{PLCY}	2.5		2.941		ns
Pipelined clock minimum pulse width high	T _{PLCLKMPWH}	1.125		1.323		ns
Pipelined clock minimum pulse width low	T _{PLCLKMPWL}	1.125		1.323		ns
Read access time with pipeline register			0.334		0.393	ns
Read access time without pipeline register	T _{CLK2Q}		2.273		2.674	ns
Access time with feed-through write timing			1.529		1.799	ns

Table 232 • RAM1K18 – Dual-Port Mode for Depth × Width Configuration 2K × 9 (continued)

Parameter	Symbol	–1		–Std		Unit
		Min	Max	Min	Max	
Address setup time	T_{ADDRSU}	0.475		0.559		ns
Address hold time	T_{ADDRHD}	0.274		0.322		ns
Data setup time	T_{DSU}	0.336		0.395		ns
Data hold time	T_{DHD}	0.082		0.096		ns
Block select setup time	T_{BLKSU}	0.207		0.244		ns
Block select hold time	T_{BLKHD}	0.216		0.254		ns
Block select to out disable time (when pipelined register is disabled)	T_{BLK2Q}		1.529		1.799	ns
Block select minimum pulse width	T_{BLKMPW}	0.186		0.219		ns
Read enable setup time	T_{RDESU}	0.485		0.57		ns
Read enable hold time	T_{RDEHD}	0.071		0.083		ns
Pipelined read enable setup time (A_DOUT_EN, B_DOUT_EN)	T_{RDPLESU}	0.248		0.291		ns
Pipelined read enable hold time (A_DOUT_EN, B_DOUT_EN)	T_{RDPLEHD}	0.102		0.12		ns
Asynchronous reset to output propagation delay	T_{R2Q}		1.514		1.781	ns
Asynchronous reset removal time	T_{RSTREM}	0.506		0.595		ns
Asynchronous reset recovery time	T_{RSTREC}	0.004		0.005		ns
Asynchronous reset minimum pulse width	T_{RSTMPW}	0.301		0.354		ns
Pipelined register asynchronous reset removal time	T_{PLRSTREM}	–0.279		–0.328		ns
Pipelined register asynchronous reset recovery time	T_{PLRSTREC}	0.327		0.385		ns
Pipelined register asynchronous reset minimum pulse width	T_{PLRSTMPW}	0.282		0.332		ns
Synchronous reset setup time	T_{SRSTSU}	0.226		0.265		ns
Synchronous reset hold time	T_{SRSTHD}	0.036		0.043		ns
Write enable setup time	T_{WESU}	0.415		0.488		ns
Write enable hold time	T_{WEHD}	0.048		0.057		ns
Maximum frequency	F_{MAX}		400		340	MHz

The following table lists the RAM1K18 – dual-port mode for depth × width configuration 4K × 4 in worst commercial-case conditions when $T_J = 85^\circ\text{C}$, $V_{DD} = 1.14\text{ V}$.

Table 233 • RAM1K18 – Dual-Port Mode for Depth × Width Configuration 4K × 4

Parameter	Symbol	–1		–Std		Unit
		Min	Max	Min	Max	
Clock period	T_{CY}	2.5		2.941		ns
Clock minimum pulse width high	T_{CLKMPWH}	1.125		1.323		ns
Clock minimum pulse width low	T_{CLKMPWL}	1.125		1.323		ns
Pipelined clock period	T_{PLCY}	2.5		2.941		ns
Pipelined clock minimum pulse width high	$T_{\text{PLCLKMPWH}}$	1.125		1.323		ns

Table 233 • RAM1K18 – Dual-Port Mode for Depth × Width Configuration 4K × 4 (continued)

Parameter	Symbol	–1		–Std		Unit
		Min	Max	Min	Max	
Pipelined clock minimum pulse width low	T _{PLCLKMPWL}	1.125		1.323		ns
Read access time with pipeline register	T _{CLK2Q}		0.323		0.38	ns
Read access time without pipeline register			2.273		2.673	ns
Access time with feed-through write timing			1.511		1.778	ns
Address setup time	T _{ADDRSU}	0.543		0.638		ns
Address hold time	T _{ADDRHD}	0.274		0.322		ns
Data setup time	T _{DSU}	0.334		0.393		ns
Data hold time	T _{DHD}	0.082		0.096		ns
Block select setup time	T _{BLKSU}	0.207		0.244		ns
Block select hold time	T _{BLKHD}	0.216		0.254		ns
Block select to out disable time (when pipelined register is disabled)	T _{BLK2Q}		1.511		1.778	ns
Block select minimum pulse width	T _{BLKMPW}	0.186		0.219		ns
Read enable setup time	T _{RDESU}	0.516		0.607		ns
Read enable hold time	T _{RDEHD}	0.071		0.083		ns
Pipelined read enable setup time (A_DOUT_EN, B_DOUT_EN)	T _{RDPLESU}	0.248		0.291		ns
Pipelined read enable hold time (A_DOUT_EN, B_DOUT_EN)	T _{RDPLEHD}	0.102		0.12		ns
Asynchronous reset to output propagation delay	T _{R2Q}		1.507		1.773	ns
Asynchronous reset removal time	T _{RSTREM}	0.506		0.595		ns
Asynchronous reset recovery time	T _{RSTREC}	0.004		0.005		ns
Asynchronous reset minimum pulse width	T _{RSTMPW}	0.301		0.354		ns
Pipelined register asynchronous reset removal time	T _{PLRSTREM}	–0.279		–0.328		ns
Pipelined register asynchronous reset recovery time	T _{PLRSTREC}	0.327		0.385		ns
Pipelined register asynchronous reset minimum pulse width	T _{PLRSTMPW}	0.282		0.332		ns
Synchronous reset setup time	T _{SRSTSU}	0.226		0.265		ns
Synchronous reset hold time	T _{SRSTHD}	0.036		0.043		ns
Write enable setup time	T _{WESU}	0.458		0.539		ns
Write enable hold time	T _{WEHD}	0.048		0.057		ns
Maximum frequency	F _{MAX}		400		340	MHz

The following table lists the RAM1K18 – dual-port mode for depth × width configuration 8K × 2 in worst commercial-case conditions when $T_J = 85^\circ\text{C}$, $V_{DD} = 1.14\text{ V}$.

Table 234 • RAM1K18 – Dual-Port Mode for Depth × Width Configuration 8K × 2

Parameter	Symbol	–1		–Std		Unit
		Min	Max	Min	Max	
Clock period	T_{CY}	2.5		2.941		ns
Clock minimum pulse width high	$T_{CLKMPWH}$	1.125		1.323		ns
Clock minimum pulse width low	$T_{CLKMPWL}$	1.125		1.323		ns
Pipelined clock period	T_{PLCY}	2.5		2.941		ns
Pipelined clock minimum pulse width high	$T_{PLCLKMPWH}$	1.125		1.323		ns
Pipelined clock minimum pulse width low	$T_{PLCLKMPWL}$	1.125		1.323		ns
Read access time with pipeline register			0.32		0.377	ns
Read access time without pipeline register	T_{CLK2Q}		2.272		2.673	ns
Access time with feed-through write timing			1.511		1.778	ns
Address setup time	T_{ADDRSU}	0.612		0.72		ns
Address hold time	T_{ADDRHD}	0.274		0.322		ns
Data setup time	T_{DSU}	0.33		0.388		ns
Data hold time	T_{DHD}	0.082		0.096		ns
Block select setup time	T_{BLKSU}	0.207		0.244		ns
Block select hold time	T_{BLKHD}	0.216		0.254		ns
Block select to out disable time (when pipelined register is disabled)	T_{BLK2Q}		1.511		1.778	ns
Block select minimum pulse width	T_{BLKMPW}	0.186		0.219		ns
Read enable setup time	T_{RDESU}	0.529		0.622		ns
Read enable hold time	T_{RDEHD}	0.071		0.083		ns
Pipelined read enable setup time (A_DOUT_EN, B_DOUT_EN)	$T_{RDPLESU}$	0.248		0.291		ns
Pipelined read enable hold time (A_DOUT_EN, B_DOUT_EN)	$T_{RDPLEHD}$	0.102		0.12		ns
Asynchronous reset to output propagation delay	T_{R2Q}		1.528		1.797	ns
Asynchronous reset removal time	T_{RSTREM}	0.506		0.595		ns
Asynchronous reset recovery time	T_{RSTREC}	0.004		0.005		ns
Asynchronous reset minimum pulse width	T_{RSTMPW}	0.301		0.354		ns
Pipelined register asynchronous reset removal time	$T_{PLRSTREM}$	–0.279		–0.328		ns
Pipelined register asynchronous reset recovery time	$T_{PLRSTREC}$	0.327		0.385		ns
Pipelined register asynchronous reset minimum pulse width	$T_{PLRSTMPW}$	0.282		0.332		ns
Synchronous reset setup time	T_{SRSTSU}	0.226		0.265		ns
Synchronous reset hold time	T_{SRSTHD}	0.036		0.043		ns
Write enable setup time	T_{WESU}	0.488		0.574		ns
Write enable hold time	T_{WEHD}	0.048		0.057		ns
Maximum frequency	F_{MAX}		400		340	MHz

Table 254 • Programming Times with 100 kHz, 25 MHz, and 12.5 MHz SPI Clock Rates (eNVM Only) (continued)

M2S/M2GL Device	Auto Programming	Auto Update	Programming Recovery	Unit
	100 kHz	25 MHz	12.5 MHz	
150	161	161	161	Sec

Table 255 • Programming Times with 100 kHz, 25 MHz, and 12.5 MHz SPI Clock Rates (Fabric and eNVM)

M2S/M2GL Device	Auto Programming	Auto Update	Programming Recovery	Unit
	100 kHz	25 MHz	12.5 MHz	
005	47	27	28	Sec
010	77	35	35	Sec
025	150	42	41	Sec
050	33 ¹	Not Supported	Not Supported	Sec
060	291	83	82	Sec
090	427	109	108	Sec
150	708	157	160	Sec
005	41	48	49	Sec
010	86	87	87	Sec
025	87	85	86	Sec
050	85	Not Supported	Not Supported	Sec
060	78	86	86	Sec
090	154	162	162	Sec
150	161	161	161	Sec
005	87	67	66	Sec
010	161	113	113	Sec
025	229	120	121	Sec
050	112	Not Supported	Not Supported	Sec
060	368	161	158	Sec
090	582	261	260	Sec
150	867	309	310	Sec

1. Auto Programming in 050 device is done through SC_SPI, and SPI CLK is set to 6.25 MHz.

Table 262 • SmartFusion2 Cortex-M3 ISP Programming (Fabric Only)

M2S/M2GL Device	Image size Bytes	Authenticate	Program	Verify	Unit
005	302672	6	41	8	Sec
010	568784	10	48	14	Sec
025	1223504	21	61	29	Sec
050	2424832	39	82	50	Sec
060	2418896	44	87	54	Sec
090	3645968	66	112	79	Sec
150	6139184	108	162	128	Sec

Table 263 • SmartFusion2 Cortex-M3 ISP Programming (eNVM Only)

M2S/M2GL Device	Image size Bytes	Authenticate	Program	Verify	Unit
005	137536	3	64	4	Sec
010	274816	4	104	7	Sec
025	274816	4	104	8	Sec
050	2,78,528	4	102	8	Sec
060	268480	6	102	8	Sec
090	544496	10	179	15	Sec
150	544496	10	180	15	Sec

Table 264 • SmartFusion2 Cortex-M3 ISP Programming (Fabric and eNVM)

M2S/M2GL Device	Image size Bytes	Authenticate	Program	Verify	Unit
005	439296	9	83	11	Sec
010	842688	15	129	21	Sec
025	1497408	26	143	35	Sec
050	2695168	43	163	55	Sec
060	2686464	48	165	60	Sec
090	4190208	75	266	91	Sec
150	6682768	117	318	141	Sec

2.3.17 Non-Deterministic Random Bit Generator (NRBG) Characteristics

For more information about NRBG, see [AC407: Using NRBG Services in SmartFusion2 and IGLOO2 Devices Application Note](#). The following table lists the NRBG in worst-case industrial conditions when $T_J = 100\text{ }^{\circ}\text{C}$, $V_{DD} = 1.14\text{ V}$.

Table 275 • Non-Deterministic Random Bit Generator (NRBG)

Service	Timing	Unit	Conditions	
			Prediction Resistance	Additional Input
Instantiate	85	ms	OFF	X
Generate (after Instantiate) ¹	4.5 ms + (6.25 us/byte x No. of Bytes)		OFF	0
	6.0 ms + (6.25 us/byte x No. of Bytes)		OFF	64
	7.0 ms + (6.25 us/byte x No. of Bytes)		OFF	128
Generate (after Instantiate)	47	ms	ON	X
Generate (subsequent) ¹	0.5 ms + (6.25 us/byte x No. of Bytes)		OFF	0
	2.0 ms + (6.25 us/byte x No. of Bytes)		OFF	64
	3.0 ms + (6.25 us/byte x No. of Bytes)		OFF	128
Generate (subsequent)	43	ms	ON	X
Reseed	40	ms		
Uninstantiate	0.16	ms		
Reset	0.10	ms		
Self test	20	ms	First time after power-up	
	6	ms	Subsequent	

1. If PUF_OFF, generate will incur additional PUF delay time for consecutive service calls.

2.3.18 Cryptographic Block Characteristics

For more information about cryptographic block and associated services, see [AC410: Using AES System Services in SmartFusion2 and IGLOO2 Devices Application Note](#) and [AC432: Using SHA-256 System Services in SmartFusion2 and IGLOO2 Devices Application Note](#).

The following table lists the cryptographic block characteristics in worst-case industrial conditions when $T_J = 100\text{ }^{\circ}\text{C}$, $V_{DD} = 1.14\text{ V}$.

Table 276 • Cryptographic Block Characteristics

Service	Conditions	Timing	Unit
Any service	First certificate check penalty at boot	11.5	ms
AES128/256 (encoding-/decoding) ¹	100 blocks up to 64k blocks	700	kbps

2.3.21 Clock Conditioning Circuits (CCC)

The following table lists the CCC/PLL specifications in worst-case industrial conditions when $T_J = 100^\circ\text{C}$, $V_{DD} = 1.14\text{ V}$.

Table 282 • IGLOO2 and SmartFusion2 SoC FPGAs CCC/PLL Specification

Parameter	Min	Typ	Max	Unit	Conditions
Clock conditioning circuitry input frequency F_{IN_CCC}	1		200	MHz	All CCC
	0.032		200	MHz	32 kHz capable CCC
Clock conditioning circuitry output frequency $F_{OUT_CCC}^1$	0.078		400	MHz	
PLL VCO frequency ²	500		1000	MHz	
Delay increments in programmable delay blocks		75	100	ps	
Number of programmable values in each programmable delay block			64		
Acquisition time		70	100	μs	$F_{IN} \geq 1\text{ MHz}$
		1	16	ms	$F_{IN} = 32\text{ kHz}$
Input duty cycle (reference clock)					Internal Feedback
	10		90	%	$1\text{ MHz} \leq F_{IN_CCC} \leq 25\text{ MHz}$
	25		75	%	$25\text{ MHz} \leq F_{IN_CCC} \leq 100\text{ MHz}$
	35		65	%	$100\text{ MHz} \leq F_{IN_CCC} \leq 150\text{ MHz}$
	45		55	%	$150\text{ MHz} \leq F_{IN_CCC} \leq 200\text{ MHz}$
					External Feedback (CCC, FPGA, Off-chip)
	25		75	%	$1\text{ MHz} \leq F_{IN_CCC} \leq 25\text{ MHz}$
	35		65	%	$25\text{ MHz} \leq F_{IN_CCC} \leq 35\text{ MHz}$
	45		55	%	$35\text{ MHz} \leq F_{IN_CCC} \leq 50\text{ MHz}$
	48		52	%	050 devices $F_{OUT} \leq 400\text{ MHz}$
	48		52	%	005, 010, and 025 devices $F_{OUT} < 350\text{ MHz}$
	46		54	%	005, 010, and 025 devices $350\text{ MHz} \leq F_{out} \leq 400\text{ MHz}$
Output duty cycle	48		52	%	060 and 090 devices $F_{OUT} \leq 100\text{ MHz}$
	44		52	%	060 and 090 devices $100\text{ MHz} \leq F_{OUT} \leq 400\text{ MHz}$
	48		52	%	150 devices $F_{OUT} \leq 120\text{ MHz}$
	45		52	%	150 devices $120\text{ MHz} \leq F_{OUT} \leq 400\text{ MHz}$
Spread Spectrum Characteristics					
Modulation frequency range	25	35	50	k	
Modulation depth range	0		1.5	%	
Modulation depth control		0.5		%	

1. The minimum output clock frequency is limited by the PLL. For more information, see [UG0449: SmartFusion2 and IGLOO2 Clocking Resources User Guide](#).
2. The PLL is used in conjunction with the Clock Conditioning Circuitry. Performance is limited by the CCC output frequency.

The following table lists the CCC/PLL jitter specifications in worst-case industrial conditions when $T_J = 100\text{ }^{\circ}\text{C}$, $V_{DD} = 1.14\text{ V}$.

Table 283 • IGLOO2 and SmartFusion2 SoC FPGAs CCC/PLL Jitter Specifications

CCC Output Maximum Peak-to-Peak Period Jitter F _{OUT_CCC}						
Parameter	Conditions/Package Combinations					Unit
10 FG484, 050 FG896/FG484/FCS325 Packages¹	SSO = 0	0 < SSO <= 2	SSO <= 4	SSO <= 8	SSO <= 16	
20 MHz to 100 MHz	Max(110, ± 1% x (1/F _{OUT_CCC}))	Max(150, ± 1% x (1/F _{OUT_CCC}))				ps
100 MHz to 400 MHz	Max(120, ± 1% x (1/F _{OUT_CCC}))	Max(150, ± 1% x (1/F _{OUT_CCC}))			Max(170, ± 1% x (1/F _{OUT_CCC}))	ps
025 FG484/FCS325 Package¹	0 < SSO <=16					
20 MHz to 74 MHz	± 1% x (1/F _{OUT_CCC}))					ps
74 MHz to 400 MHz	210					ps
005 FG484 Package¹	0 < SSO <=16					
20 MHz to 53 MHz	± 1% x (1/F _{OUT_CCC}))					ps
53 MHz to 400 MHz	270					ps
090 FG676 and FC325 Package¹	0 < SSO <=16					
20 MHz to 100 MHz	± 1% x (1/F _{OUT_CCC}))					ps
100 MHz to 400 MHz	150					ps
060 FG676 Package¹	0 < SSO <=16					
20 MHz to 100 MHz	± 1% x (1/F _{OUT_CCC})					ps
100 MHz to 400 MHz	150					
150 FC1152 Package¹	0 < SSO <=16					
20 MHz to 100 MHz	± 1% x (1/F _{OUT_CCC}))					ps
100 MHz to 400 MHz	120					ps

1. SSO data is based on LVCMOS 2.5 V MSIO and/or MSIOD bank I/Os.

2.3.31.2 SmartFusion2 Inter-Integrated Circuit (I²C) Characteristics

This section describes the DC and switching of the I²C interface. Unless otherwise noted, all output characteristics given are for a 100 pF load on the pins. For timing parameter definitions, see [Figure 21](#), page 125.

The following table lists the I²C characteristics in worst-case industrial conditions when $T_J = 100\text{ }^{\circ}\text{C}$, $V_{DD} = 1.14\text{ V}$

Table 303 • I²C Characteristics

Parameter	Symbol	Min	Typ	Max	Unit	Conditions
Input low voltage	V_{IL}	-0.3		0.8	V	See Single-Ended I/O Standards , page 24 for more information. I/O standard used for illustration: MSIO bank-LVTTL 8 mA low drive.
Input high voltage	V_{IH}	2		3.45	V	See Single-Ended I/O Standards , page 24 for more information. I/O standard used for illustration: MSIO bank-LVTTL 8 mA low drive.
Hysteresis of schmitt triggered inputs for $V_{DDI} > 2\text{ V}$	V_{HYS}	$0.05 \times V_{DDI}$			V	See Table 28 , page 23 for more information.
Input current high	I_{IL}			10	μA	See Single-Ended I/O Standards , page 24 for more information.
Input current low	I_{IH}			10	μA	See Single-Ended I/O Standards , page 24 for more information.
Input rise time	T_{ir}			1000	ns	Standard mode
				300	ns	Fast mode
Input fall time	T_{if}			300	ns	Standard mode
				300	ns	Fast mode
Maximum output voltage low (open drain) at 3 mA sink current for $V_{DDI} > 2\text{ V}$	V_{OL}			0.4	V	See Single-Ended I/O Standards , page 24 for more information. I/O standard used for illustration: MSIO bank-LVTTL 8 mA low drive.
Pin capacitance	C_{in}			10	pF	$V_{IN} = 0$, $f = 1.0\text{ MHz}$
Output fall time from V_{IHMin} to V_{ILMax}^1	t_{OF}^1		21.04		ns	V_{IHmin} to V_{ILMax} , $C_{LOAD} = 400\text{ pF}$
			5.556		ns	V_{IHmin} to V_{ILMax} , $C_{LOAD} = 100\text{ pF}$
Output rise time from V_{ILMax} to V_{IHMin}^1	t_{OR}^1		19.887		ns	V_{ILMax} to V_{IHmin} , $C_{LOAD} = 400\text{ pF}$
			5.218		ns	V_{ILMax} to V_{IHmin} , $C_{LOAD} = 100\text{ pF}$
Output buffer maximum pull-down resistance ^{2, 3}	$R_{pull-up}^{2,3}$			50	Ω	
Output buffer maximum pull-up resistance ^{2, 4}	$R_{pull-down}^{2,4}$			131.25	Ω	

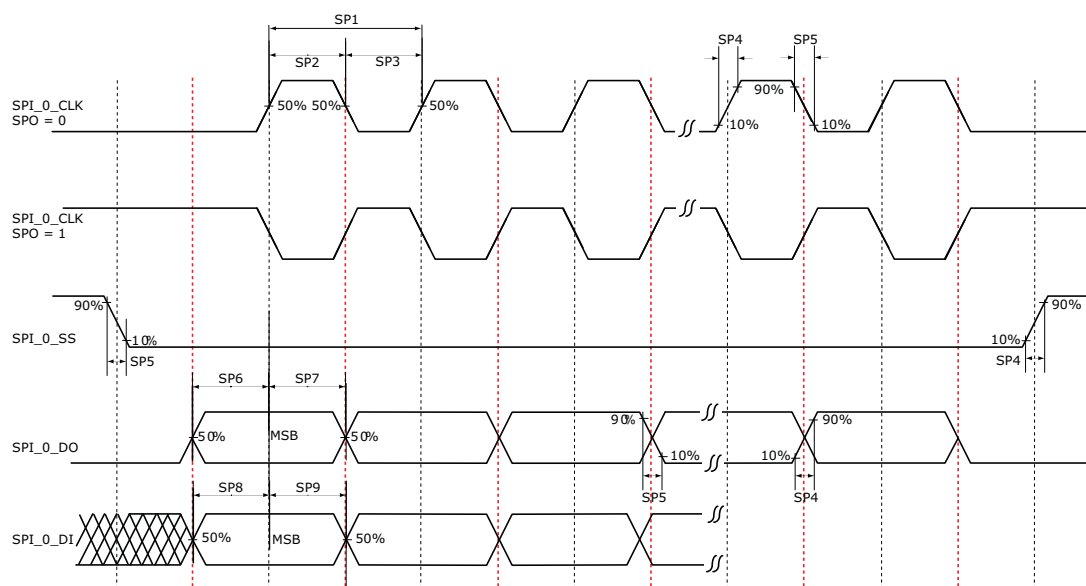
2.3.31.3 Serial Peripheral Interface (SPI) Characteristics

This section describes the DC and switching of the SPI interface. Unless otherwise noted, all output characteristics given are for a 35 pF load on the pins and all sequential timing characteristics are related to SPI_x_CLK. For timing parameter definitions, see [Figure 22](#), page 128.

The following table lists the SPI characteristics in worst-case industrial conditions when $T_J = 100\text{ }^{\circ}\text{C}$, $V_{DD} = 1.14\text{ V}$

Table 305 • SPI Characteristics for All Devices

Symbol	Description	Min	Typ	Max	Unit	Conditions
SPIFMAX	Maximum operating frequency of SPI interface			20	MHz	
sp1	SPI_[0 1]_CLK minimum period					
	SPI_[0 1]_CLK = PCLK/2	12			ns	
	SPI_[0 1]_CLK = PCLK/4	24.1			ns	
	SPI_[0 1]_CLK = PCLK/8	48.2			ns	
	SPI_[0 1]_CLK = PCLK/16	0.1			μs	
	SPI_[0 1]_CLK = PCLK/32	0.19			μs	
	SPI_[0 1]_CLK = PCLK/64	0.39			μs	
	SPI_[0 1]_CLK = PCLK/128	0.77			μs	
sp2	SPI_[0 1]_CLK minimum pulse width high					
	SPI_[0 1]_CLK = PCLK/2	6			ns	
	SPI_[0 1]_CLK = PCLK/4	12.05			ns	
	SPI_[0 1]_CLK = PCLK/8	24.1			ns	
	SPI_[0 1]_CLK = PCLK/16	0.05			μs	
	SPI_[0 1]_CLK = PCLK/32	0.095			μs	
	SPI_[0 1]_CLK = PCLK/64	0.195			μs	
	SPI_[0 1]_CLK = PCLK/128	0.385			μs	
sp3	SPI_[0 1]_CLK minimum pulse width low					
	SPI_[0 1]_CLK = PCLK/2	6			ns	
	SPI_[0 1]_CLK = PCLK/4	12.05			ns	
	SPI_[0 1]_CLK = PCLK/8	24.1			ns	
	SPI_[0 1]_CLK = PCLK/16	0.05			μs	
	SPI_[0 1]_CLK = PCLK/32	0.095			μs	
	SPI_[0 1]_CLK = PCLK/64	0.195			μs	
	SPI_[0 1]_CLK = PCLK/128	0.385			μs	
sp4	SPI_[0 1]_CLK, SPI_[0 1]_DO, SPI_[0 1]_SS rise time (10%–90%) ¹		2.77		ns	I/O Configuration: LVCMOS 2.5 V– 8 mA AC loading: 35 pF Test conditions: Typical voltage, 25 °C

Figure 22 • SPI Timing for a Single Frame Transfer in Motorola Mode (SPH = 1)

2.3.32 CAN Controller Characteristics

The following table lists the CAN controller characteristics in worst-case industrial conditions when $T_J = 100^\circ\text{C}$, $V_{DD} = 1.14\text{ V}$.

Table 306 • CAN Controller Characteristics

Parameter	Description	–1	–Std	Unit
FCANREFCLK ¹	Internally sourced CAN reference clock frequency	160	136	MHz
BAUDCANMAX	Maximum CAN performance baud rate	1	1	Mbps
BAUDCANMIN	Minimum CAN performance baud rate	0.05	0.05	Mbps

1. PCLK to CAN controller must be a multiple of 8 MHz.

2.3.33 USB Characteristics

The following table lists the USB characteristics in worst-case industrial conditions when $T_J = 100^\circ\text{C}$, $V_{DD} = 1.14\text{ V}$.

Table 307 • USB Characteristics

Parameter	Description	–1	–Std	Unit
FUSBREFCLK	Internally sourced USB reference clock frequency	166	142	MHz
TUSBCLK	USB clock period	16.66	16.66	ns
TUSBPD	Clock to USB data propagation delay	9.0	9.0	ns
TUSBSU	Setup time for USB data	6.0	6.0	ns
TUSBHD	Hold time for USB data	0	0	ns

Table 310 • SPI Characteristics for All Devices (continued)

Symbol	Description	Min	Typ	Max	Unit	Conditions
SPI master configuration (applicable for 060, 090, and 150 devices)						
sp6m	SPI_[0 1]_DO setup time ²	$(\text{SPI_x_CLK_period}/2) - 7.0$			ns	
sp7m	SPI_[0 1]_DO hold time ²	$(\text{SPI_x_CLK_period}/2) - 9.5$			ns	
sp8m	SPI_[0 1]_DI setup time ²	15			ns	
sp9m	SPI_[0 1]_DI hold time ²	-2.5			ns	
SPI slave configuration (applicable for 060, 090, and 150 devices)						
sp6s	SPI_[0 1]_DO setup time ²	$(\text{SPI_x_CLK_period}/2) - 16.0$			ns	
sp7s	SPI_[0 1]_DO hold time ²	$(\text{SPI_x_CLK_period}/2) - 3.5$			ns	
sp8s	SPI_[0 1]_DI setup time ²	3			ns	
sp9s	SPI_[0 1]_DI hold time ²	2.5			ns	

- For specific Rise/Fall Times board design considerations and detailed output buffer resistances, use the corresponding IBIS models located on the Microsemi SoC Products Group website: <http://www.microsemi.com/soc/download/ibis/default.aspx>.
- For allowable pclk configurations, see the Serial Peripheral Interface Controller section in the *UG0331: SmartFusion2 Microcontroller Subsystem User Guide*.

Figure 23 • SPI Timing for a Single Frame Transfer in Motorola Mode (SPH = 1)