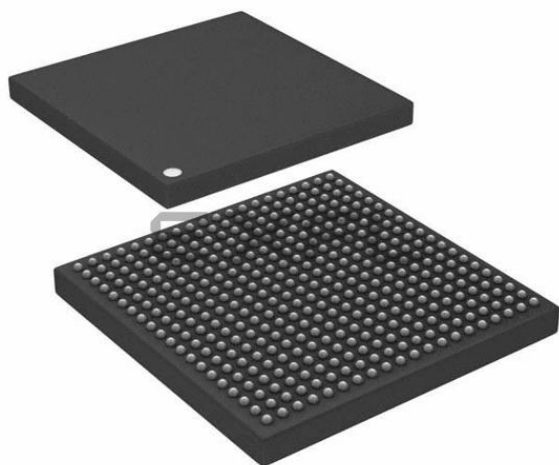




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Embedded - FPGAs, or Field Programmable Gate Arrays, are advanced integrated circuits that offer unparalleled flexibility and performance for digital systems. Unlike traditional fixed-function logic devices, FPGAs can be programmed and reprogrammed to execute a wide array of logical operations, enabling customized functionality tailored to specific applications. This reprogrammability allows developers to iterate designs quickly and implement complex functions without the need for custom hardware.

Applications of Embedded - FPGAs

The versatility of Embedded - FPGAs makes them indispensable in numerous fields. In telecommunications.

Details

Product Status	Active
Number of LABs/CLBs	-
Number of Logic Elements/Cells	56520
Total RAM Bits	1869824
Number of I/O	207
Number of Gates	-
Voltage - Supply	1.14V ~ 2.625V
Mounting Type	Surface Mount
Operating Temperature	-40°C ~ 100°C (TJ)
Package / Case	400-LFBGA
Supplier Device Package	400-VFBGA (17x17)
Purchase URL	https://www.e-xfl.com/product-detail/microchip-technology/m2gl060-vf400i

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Figure 1 • High Temperature Data Retention (HTR)**2.3.1.1 Overshoot/Undershoot Limits**

For AC signals, the input signal may undershoot during transitions to -1.0 V for no longer than 10% of the period. The current during the transition must not exceed 100 mA.

For AC signals, the input signal may overshoot during transitions to $V_{CCI} + 1.0$ V for no longer than 10% of the period. The current during the transition must not exceed 100 mA.

Note: The above specifications do not apply to the PCI standard. The IGLOO2 and SmartFusion2 PCI I/Os are compliant with the PCI standard including the PCI overshoot/undershoot specifications.

2.3.1.2 Thermal Characteristics

The temperature variable in the Microsemi SoC Products Group Designer software refers to the junction temperature, not the ambient, case, or board temperatures. This is an important distinction because dynamic and static power consumption causes the chip's junction temperature to be higher than the ambient, case, or board temperatures.

EQ1 through EQ3 give the relationship between thermal resistance, temperature gradient, and power.

$$\theta_{JA} = \frac{T_J - T_A}{P}$$

EQ 1

$$\theta_{JB} = \frac{T_J - T_B}{P}$$

EQ 2

$$\theta_{JC} = \frac{T_J - T_C}{P}$$

EQ 3

Table 9 • Package Thermal Resistance of SmartFusion2 and IGLOO2 Devices (continued)

	Still Air	1.0 m/s	2.5 m/s			
Device	θ_{JA}			θ_{JB}	θ_{JC}	Unit
150						
FC1152	9.08	6.81	5.87	2.56	0.38	°C/W
FCS536	15.01	12.06	10.76	3.69	1.55	°C/W
FCV484	16.21	13.11	11.84	6.73	0.10	°C/W

2.3.1.2.1 Theta-JA

Junction-to-ambient thermal resistance (θ_{JA}) is determined under standard conditions specified by JEDEC (JESD-51), but it has little relevance in the actual performance of the product. It must be used with caution, but it is useful for comparing the thermal performance of one package with another.

The maximum power dissipation allowed is calculated using EQ4.

$$\text{Maximum power allowed} = \frac{T_{J(\text{MAX})} - T_{A(\text{MAX})}}{\theta_{JA}}$$

EQ 4

The absolute maximum junction temperature is 100 °C. EQ5 shows a sample calculation of the absolute maximum power dissipation allowed for the M2GL050T-FG896 package at commercial temperature and in still air, where:

$$\theta_{JA} = 14.7 \text{ °C/W (taken from Table 9, page 10).}$$

$$T_A = 85 \text{ °C}$$

$$\text{Maximum power allowed} = \frac{100 \text{ °C} - 85 \text{ °C}}{14.7 \text{ °C/W}} = 1.088 \text{ W}$$

EQ 5

The power consumption of a device can be calculated using the Microsemi SoC Products Group power calculator. The device's power consumption must be lower than the calculated maximum power dissipation by the package.

If the power consumption is higher than the device's maximum allowable power dissipation, a heat sink may be attached to the top of the case, or the airflow inside the system must be increased.

2.3.1.2.2 Theta-JB

Junction-to-board thermal resistance (θ_{JB}) measures the ability of the package to dissipate heat from the surface of the chip to the PCB. As defined by the JEDEC (JESD-51) standard, the thermal resistance from the junction to the board uses an isothermal ring cold plate zone concept. The ring cold plate is simply a means to generate an isothermal boundary condition at the perimeter. The cold plate is mounted on a JEDEC standard board with a minimum distance of 5.0 mm away from the package edge.

2.3.1.2.3 Theta-JC

Junction-to-case thermal resistance (θ_{JC}) measures the ability of a device to dissipate heat from the surface of the chip to the top or bottom surface of the package. It is applicable to packages used with external heat sinks. Constant temperature is applied to the surface, which acts as a boundary condition.

This only applies to situations where all or nearly all of the heat is dissipated through the surface in consideration.

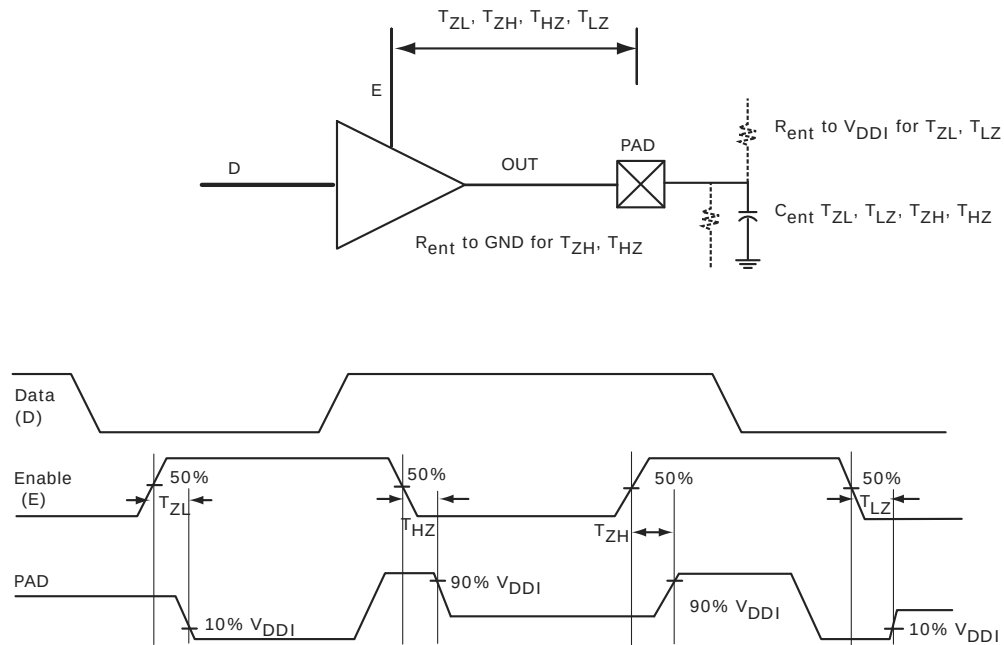
2.3.1.3 ESD Performance

See RT0001: Microsemi Corporation - SoC Products Reliability Report for information about ESD.

2.3.5.3 Tristate Buffer and AC Loading

The tristate path for enable path loadings is described in the respective specifications. The following figure shows the methodology of characterization illustrated by the enable path test point.

Figure 5 • Tristate Buffer for Enable Path Test Point



2.3.5.4 I/O Speeds

This section describes the maximum data rate summary of I/O in worst-case industrial conditions. See the individual I/O standards for operating conditions.

Table 18 • Maximum Data Rate Summary Table for Single-Ended I/O in Worst-Case Industrial Conditions

I/O	MSIO	MSIOD	DDRIO	Unit
PCI 3.3 V	630			Mbps
LVTTL 3.3 V	600			Mbps
LVC MOS 3.3 V	600			Mbps
LVC MOS 2.5 V	410	420	400	Mbps
LVC MOS 1.8 V	295	400	400	Mbps
LVC MOS 1.5 V	160	220	235	Mbps
LVC MOS 1.2 V	120	160	200	Mbps
LPDDR-LVC MOS 1.8 V mode			400	Mbps

Table 19 • Maximum Data Rate Summary Table for Voltage-Referenced I/O in Worst-Case Industrial Conditions

I/O	MSIO	MSIOD	DDRIO	Unit
LPDDR			400	Mbps
HSTL1.5 V			400	Mbps
SSTL 2.5 V	510	700	400	Mbps
SSTL 1.8 V			667	Mbps
SSTL 1.5 V			667	Mbps

Table 20 • Maximum Data Rate Summary Table for Differential I/O in Worst-Case Industrial Conditions

I/O	MSIO	MSIOD	Unit
LVPECL (input only)	900		Mbps
LVDS 3.3 V	535		Mbps
LVDS 2.5 V	535	700	Mbps
RSDS	520	700	Mbps
BLVDS	500		Mbps
MLVDS	500		Mbps
Mini-LVDS	520	700	Mbps

Table 21 • Maximum Frequency Summary Table for Single-Ended I/O in Worst-Case Industrial Conditions

I/O	MSIO	MSIOD	DDRIO	Unit
PCI 3.3 V	315			MHz
LVTTL 3.3 V	300			MHz
LVC MOS 3.3 V	300			MHz
LVC MOS 2.5 V	205	210	200	MHz
LVC MOS 1.8 V	147.5	200	200	MHz
LVC MOS 1.5 V	80	110	118	MHz
LVC MOS 1.2 V	60	80	100	MHz
LPDDR– LVC MOS 1.8 V mode			200	MHz

Table 46 • LVCMOS 2.5 V Transmitter Characteristics for DDRIO Bank (Output and Tristate Buffers)
(continued)

Output Drive Selection	Slew Control	T _{DP}		T _{ZL}		T _{ZH}		T _{HZ} ¹		T _{LZ} ¹		Unit
		–1	–Std	–1	–Std	–1	–Std	–1	–Std	–1	–Std	
4 mA	Slow	3.095	3.641	2.705	3.182	3.088	3.633	4.738	5.575	4.348	5.116	ns
	Medium	2.825	3.324	2.488	2.927	2.823	3.321	4.492	5.285	4.063	4.781	ns
	Medium fast	2.701	3.178	2.384	2.804	2.698	3.173	4.364	5.135	3.945	4.642	ns
	Fast	2.69	3.165	2.377	2.796	2.687	3.161	4.359	5.129	3.94	4.636	ns
6 mA	Slow	2.919	3.434	2.491	2.93	2.902	3.414	5.085	5.983	4.674	5.5	ns
	Medium	2.65	3.118	2.279	2.681	2.642	3.108	4.845	5.701	4.375	5.148	ns
	Medium fast	2.529	2.975	2.176	2.56	2.521	2.965	4.724	5.558	4.259	5.011	ns
	Fast	2.516	2.96	2.168	2.551	2.508	2.95	4.717	5.55	4.251	5.002	ns
8 mA	Slow	2.863	3.368	2.427	2.855	2.844	3.346	5.196	6.114	4.769	5.612	ns
	Medium	2.599	3.058	2.217	2.608	2.59	3.047	4.952	5.827	4.471	5.261	ns
	Medium fast	2.483	2.921	2.114	2.487	2.473	2.91	4.832	5.685	4.364	5.134	ns
	Fast	2.467	2.902	2.106	2.478	2.457	2.89	4.826	5.678	4.348	5.116	ns
12 mA	Slow	2.747	3.232	2.296	2.701	2.724	3.204	5.39	6.342	4.938	5.81	ns
	Medium	2.493	2.934	2.102	2.473	2.483	2.921	5.166	6.078	4.65	5.471	ns
	Medium fast	2.382	2.803	2.006	2.36	2.371	2.789	5.067	5.962	4.546	5.349	ns
	Fast	2.369	2.787	1.999	2.352	2.357	2.773	5.063	5.958	4.538	5.339	ns
16 mA	Slow	2.677	3.149	2.213	2.604	2.649	3.116	5.575	6.56	5.08	5.977	ns
	Medium	2.432	2.862	2.028	2.386	2.421	2.848	5.372	6.32	4.801	5.649	ns
	Medium fast	2.324	2.734	1.937	2.278	2.311	2.718	5.297	6.233	4.7	5.531	ns
	Fast	2.313	2.721	1.929	2.269	2.3	2.706	5.296	6.231	4.699	5.529	ns

1. Delay increases with drive strength are inherent to built-in slew control circuitry for simultaneous switching output (SSO) management.

Table 47 • LVCMOS 2.5 V Transmitter Characteristics for MSIO Bank (Output and Tristate Buffers)

Output Drive Selection	Slew Control	T _{DP}		T _{ZL}		T _{ZH}		T _{HZ} ¹		T _{LZ} ¹		Unit
		–1	–Std	–1	–Std	–1	–Std	–1	–Std	–1	–Std	
2 mA	Slow	3.48	4.095	3.855	4.534	3.785	4.453	2.12	2.494	3.45	4.059	ns
4 mA	Slow	2.583	3.039	3.042	3.579	3.138	3.691	4.143	4.874	4.687	5.513	ns
6 mA	Slow	2.392	2.815	2.669	3.139	2.82	3.317	4.909	5.775	5.083	5.98	ns
8 mA	Slow	2.309	2.717	2.565	3.017	2.74	3.223	5.812	6.837	5.523	6.497	ns
12 mA	Slow	2.333	2.745	2.437	2.867	2.626	3.089	6.131	7.213	5.712	6.72	ns
16 mA	Slow	2.412	2.838	2.335	2.747	2.533	2.979	6.54	7.694	6.007	7.067	ns

1. Delay increases with drive strength are inherent to built-in slew control circuitry for simultaneous switching output (SSO) management.

Table 58 • LVCMOS 1.8 V Transmitter Characteristics for MSIO I/O Bank

Output Drive Selection	Slew Control	T _{DP}		T _{ZL}		T _{ZH}		T _{HZ} ¹		T _{LZ} ¹		Unit
		-1	-Std	-1	-Std	-1	-Std	-1	-Std	-1	-Std	
2 mA	Slow	3.441	4.047	4.165	4.9	4.413	5.192	4.891	5.755	5.138	6.044	ns
4 mA	Slow	3.218	3.786	3.642	4.284	3.941	4.636	5.665	6.665	5.568	6.551	ns
6 mA	Slow	3.141	3.694	3.501	4.118	3.823	4.498	6.587	7.75	6.032	7.096	ns
8 mA	Slow	3.165	3.723	3.319	3.904	3.654	4.298	6.898	8.115	6.216	7.313	ns
10 mA	Slow	3.202	3.767	3.278	3.857	3.616	4.254	7.25	8.529	6.435	7.571	ns
12 mA	Slow	3.277	3.855	3.175	3.736	3.519	4.139	7.392	8.697	6.538	7.692	ns

1. Delay increases with drive strength are inherent to built-in slew control circuitry for simultaneous switching output (SSO) management.

Table 59 • LVCMOS 1.8 V Transmitter Characteristics for MSIOD I/O Bank

Output Drive Selection	Slew Control	T _{DP}		T _{ZL}		T _{ZH}		T _{HZ} ¹		T _{LZ} ¹		Unit
		-1	-Std	-1	-Std	-1	-Std	-1	-Std	-1	-Std	
2 mA	Slow	2.725	3.206	3.316	3.901	3.484	4.099	5.204	6.123	4.997	5.88	ns
4 mA	Slow	2.242	2.638	2.777	3.267	2.947	3.466	5.729	6.74	5.448	6.41	ns
6 mA	Slow	1.995	2.347	2.466	2.901	2.63	3.094	6.372	7.496	5.987	7.043	ns
8 mA	Slow	2.001	2.354	2.44	2.87	2.6	3.058	6.633	7.804	6.193	7.286	ns
10 mA	Slow	2.025	2.382	2.312	2.719	2.47	2.906	6.94	8.165	6.412	7.544	ns

1. Delay increases with drive strength are inherent to built-in slew control circuitry for simultaneous switching output (SSO) management.

2.3.5.9 1.5 V LVCMOS

LVCMOS 1.5 is a general standard for 1.5 V applications and is supported in IGLOO2 FPGAs and SmartFusion2 SoC FPGAs in compliance to the JEDEC specification JESD8-11A.

Minimum and Maximum DC/AC Input and Output Levels Specification

Table 60 • LVCMOS 1.5 V DC Recommended Operating Conditions

Parameter	Symbol	Min	Typ	Max	Unit
Supply voltage	V _{DDI}	1.425	1.5	1.575	V

Table 61 • LVCMOS 1.5 V DC Input Voltage Specification

Parameter	Symbol	Min	Max	Unit
DC input logic high for (MSIOD and DDRIO I/O banks)	V _{IH} (DC)	0.65 × V _{DDI}	1.575	V
DC input logic high (for MSIO I/O bank)	V _{IH} (DC)	0.65 × V _{DDI}	3.45	V
DC input logic low	V _{IL} (DC)	-0.3	0.35 × V _{DDI}	V
Input current high ¹	I _{IH} (DC)			–
Input current low ¹	I _{IL} (DC)			–

1. See Table 24, page 22.

Table 82 • LVCMOS 1.2 V Receiver Characteristics for MSIOD I/O Bank (Input Buffers)

On-Die Termination (ODT)	T_{PY}		T_{PYS}		Unit
	-1	-Std	-1	-Std	
None	4.154	4.887	4.114	4.84	ns
50	6.918	8.139	6.806	8.008	ns
75	5.613	6.603	5.533	6.509	ns
150	4.716	5.549	4.657	5.479	ns

Table 83 • LVCMOS 1.2 V Transmitter Characteristics for DDRIO I/O Bank (Output and Tristate Buffers)

Output Drive Selection	Slew Control	T_{DP}		T_{ZL}		T_{ZH}		T_{HZ}^1		T_{LZ}^1		Unit
		-1	-Std	-1	-Std	-1	-Std	-1	-Std	-1	-Std	
2 mA	Slow	6.713	7.897	5.362	6.308	6.723	7.909	7.233	8.51	6.375	7.499	ns
	Medium	5.912	6.955	4.616	5.43	5.915	6.959	6.887	8.102	6.009	7.069	ns
	Medium fast	5.5	6.469	4.231	4.978	5.5	6.471	6.672	7.849	5.835	6.865	ns
	Fast	5.462	6.426	4.194	4.935	5.463	6.427	6.646	7.819	5.828	6.857	ns
4 mA	Slow	6.109	7.186	4.708	5.539	6.098	7.174	8.005	9.418	7.033	8.274	ns
	Medium	5.355	6.299	4.034	4.746	5.338	6.28	7.637	8.985	6.672	7.849	ns
	Medium fast	4.953	5.826	3.685	4.336	4.932	5.802	7.44	8.752	6.499	7.646	ns
	Fast	4.911	5.777	3.658	4.303	4.89	5.754	7.427	8.737	6.488	7.632	ns
6 mA	Slow	5.89	6.929	4.506	5.301	5.874	6.911	8.337	9.808	7.315	8.605	ns
	Medium	5.176	6.089	3.862	4.543	5.155	6.065	7.986	9.394	6.943	8.168	ns
	Medium fast	4.792	5.637	3.523	4.145	4.765	5.606	7.808	9.186	6.775	7.97	ns
	Fast	4.754	5.593	3.486	4.101	4.728	5.563	7.777	9.149	6.769	7.963	ns

1. Delay increases with drive strength are inherent to built-in slew control circuitry for simultaneous switching output (SSO) management.

Table 84 • LVCMOS 1.2 V Transmitter Characteristics for MSIO I/O Bank (Output and Tristate Buffers)

Output Drive Selection	Slew Control	T_{DP}		T_{ZL}		T_{ZH}		T_{HZ}^1		T_{LZ}^1		Unit
		-1	-Std	-1	-Std	-1	-Std	-1	-Std	-1	-Std	
2 mA	Slow	6.746	7.937	7.458	8.774	8.172	9.614	9.867	11.608	8.393	9.874	ns
4 mA	Slow	7.068	8.315	6.678	7.857	7.474	8.793	10.986	12.924	9.043	10.638	ns

1. Delay increases with drive strength are inherent to built-in slew control circuitry for simultaneous switching output (SSO) management.

Table 198 • Mini-LVDS AC Impedance Specifications

Parameter	Symbol	Typ	Unit
Termination resistance	R_T	100	Ω

Table 199 • Mini-LVDS AC Test Parameter Specifications

Parameter	Symbol	Typ	Unit
Measuring/trip point for data path	V_{TRIP}	Cross point	V
Resistance for enable path (T_{ZH} , T_{ZL} , T_{HZ} , T_{LZ})	R_{ENT}	2K	Ω
Capacitive loading for enable path (T_{ZH} , T_{ZL} , T_{HZ} , T_{LZ})	C_{ENT}	5	pF

AC Switching Characteristics

Worst commercial-case conditions: $T_J = 85^\circ\text{C}$, $V_{DD} = 1.14\text{ V}$, $V_{DDI} = 2.375\text{ V}$.

Table 200 • Mini-LVDS AC Switching Characteristics for Receiver (for MSIO I/O Bank - Input Buffers)

On-Die Termination (ODT)	T_{PY}		Unit
	-1	-Std	
None	2.855	3.359	ns
100	2.85	3.353	ns
None	2.602	3.061	ns
100	2.597	3.055	ns

Table 201 • Mini-LVDS AC Switching Characteristics for Transmitter for MSIO I/O Bank (Output and Tristate Buffers)

T_{DP}		T_{ZL}		T_{ZH}		T_{HZ}		T_{LZ}		Unit
-1	-Std	-1	-Std	-1	-Std	-1	-Std	-1	-Std	
2.097	2.467	2.308	2.715	2.296	2.701	1.964	2.31	1.949	2.293	ns

Table 202 • Mini-LVDS AC Switching Characteristics for Transmitter (for MSIOD I/O Bank - Output and Tristate Buffers)

	T_{DP}		T_{ZL}		T_{ZH}		T_{HZ}		T_{LZ}		Unit
	-1	-Std	-1	-Std	-1	-Std	-1	-Std	-1	-Std	
No pre-emphasis	1.614	1.899	1.562	1.837	1.553	1.826	1.593	1.874	1.578	1.856	ns
Min pre-emphasis	1.604	1.887	1.745	2.053	1.731	2.036	1.892	2.225	1.861	2.189	ns
Med pre-emphasis	1.521	1.79	1.753	2.062	1.737	2.043	1.9	2.235	1.868	2.197	ns
Max pre-emphasis	1.492	1.754	1.762	2.073	1.745	2.052	1.91	2.247	1.876	2.206	ns

Table 215 • LVPECL DC Input Voltage Specification

Parameter	Symbol	Min	Max	Unit
DC input voltage	V_I	0	3.45	V

Table 216 • LVPECL DC Differential Voltage Specification

Parameter	Symbol	Min	Typ	Max	Unit
Input common mode voltage	V_{ICM}	0.3		2.8	V
Input differential voltage	V_{IDIFF}	100	300	1,000	mV

Table 217 • LVPECL Minimum and Maximum AC Switching Speeds

Parameter	Symbol	Max	Unit
Maximum data rate	D_{MAX}	900	Mbps

AC Switching Characteristics

Worst commercial-case conditions: $T_J = 85\text{ }^{\circ}\text{C}$, $V_{DD} = 1.14\text{ V}$, $V_{DDI} = 2.375\text{ V}$.

Table 218 • LVPECL Receiver Characteristics for MSIO I/O Bank

On-Die Termination (ODT)	T_{PY}		Unit
	-1	-Std	
None	2.572	3.025	ns
100	2.569	3.023	ns

2.3.8 I/O Register Specifications

This section describes input and output register specifications.

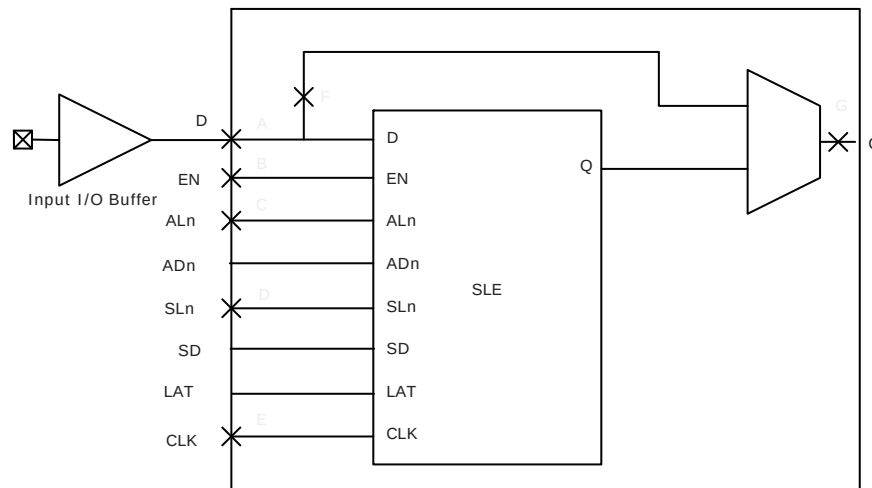
2.3.8.1 Input Register**Figure 6 • Timing Model for Input Register**

Table 231 • RAM1K18 – Dual-Port Mode for Depth × Width Configuration 1K × 18 (continued)

Parameter	Symbol	–1		–Std		Unit
		Min	Max	Min	Max	
Block select hold time	T_{BLKHD}	0.216		0.254		ns
Block select to out disable time (when pipelined register is disabled)	T_{BLK2Q}		1.529		1.799	ns
Block select minimum pulse width	T_{BLKMPW}	0.186		0.219		ns
Read enable setup time	T_{RDESU}	0.449		0.528		ns
Read enable hold time	T_{RDEHD}	0.167		0.197		ns
Pipelined read enable setup time (A_DOUT_EN, B_DOUT_EN)	$T_{RDPLESU}$	0.248		0.291		ns
Pipelined read enable hold time (A_DOUT_EN, B_DOUT_EN)	$T_{RDPLEHD}$	0.102		0.12		ns
Asynchronous reset to output propagation delay	T_{R2Q}	–	1.506	–	1.772	ns
Asynchronous reset removal time	T_{RSTREM}	0.506		0.595		ns
Asynchronous reset recovery time	T_{RSTREC}	0.004		0.005		ns
Asynchronous reset minimum pulse width	T_{RSTMPW}	0.301		0.354		ns
Pipelined register asynchronous reset removal time	$T_{PLRSTREM}$	–0.279		–0.328		ns
Pipelined register asynchronous reset recovery time	$T_{PLRSTREC}$	0.327		0.385		ns
Pipelined register asynchronous reset minimum pulse width	$T_{PLRSTMPW}$	0.282		0.332		ns
Synchronous reset setup time	T_{SRSTSU}	0.226		0.265		ns
Synchronous reset hold time	T_{SRSTHD}	0.036		0.043		ns
Write enable setup time	T_{WESU}	0.39		0.458		ns
Write enable hold time	T_{WEHD}	0.242		0.285		ns
Maximum frequency	F_{MAX}		400		340	MHz

The following table lists the RAM1K18 – dual-port mode for depth × width configuration 2K × 9 in worst commercial-case conditions when $T_J = 85^\circ\text{C}$, $V_{DD} = 1.14\text{ V}$.

Table 232 • RAM1K18 – Dual-Port Mode for Depth × Width Configuration 2K × 9

Parameter	Symbol	–1		–Std		Unit
		Min	Max	Min	Max	
Clock period	T_{CY}	2.5		2.941		ns
Clock minimum pulse width high	$T_{CLKMPWH}$	1.125		1.323		ns
Clock minimum pulse width low	$T_{CLKMPWL}$	1.125		1.323		ns
Pipelined clock period	T_{PLCY}	2.5		2.941		ns
Pipelined clock minimum pulse width high	$T_{PLCLKMPWH}$	1.125		1.323		ns
Pipelined clock minimum pulse width low	$T_{PLCLKMPWL}$	1.125		1.323		ns
Read access time with pipeline register			0.334		0.393	ns
Read access time without pipeline register	T_{CLK2Q}		2.273		2.674	ns
Access time with feed-through write timing			1.529		1.799	ns

Table 242 • μ SRAM (RAM512x2) in 512 × 2 Mode (continued)

Parameter	Symbol	–1		–Std		Unit
		Min	Max	Min	Max	
Write clock period	T_{CCY}	4		4		ns
Write clock minimum pulse width high	$T_{CCLKMPWH}$	1.8		1.8		ns
Write clock minimum pulse width low	$T_{CCLKMPWL}$	1.8		1.8		ns
Write block setup time	T_{BLKCSU}	0.404		0.476		ns
Write block hold time	T_{BLKCHD}	0.007		0.008		ns
Write input data setup time	T_{DINCSU}	0.101		0.118		ns
Write input data hold time	T_{DINCHD}	0.137		0.161		ns
Write address setup time	$T_{ADDRCSU}$	0.088		0.104		ns
Write address hold time	$T_{ADDRCHD}$	0.247		0.29		ns
Write enable setup time	T_{WECSU}	0.397		0.467		ns
Write enable hold time	T_{WECHD}	–0.03		–0.03		ns
Maximum frequency	F_{MAX}		250		250	MHz

The following table lists the μ SRAM in 1024 × 1 mode in worst commercial-case conditions when $T_J = 85^\circ\text{C}$, $V_{DD} = 1.14\text{ V}$.

Table 243 • μ SRAM (RAM1024x1) in 1024 × 1 Mode

Parameter	Symbol	–1		–Std		Unit
		Min	Max	Min	Max	
Read clock period	T_{CY}	4		4		ns
Read clock minimum pulse width high	$T_{CLKMPWH}$	1.8		1.8		ns
Read clock minimum pulse width low	$T_{CLKMPWL}$	1.8		1.8		ns
Read pipeline clock period	T_{PLCY}	4		4		ns
Read pipeline clock minimum pulse width high	$T_{PLCLKMPWH}$	1.8		1.8		ns
Read pipeline clock minimum pulse width low	$T_{PLCLKMPWL}$	1.8		1.8		ns
Read access time with pipeline register	T_{CLK2Q}		0.27		0.31	ns
Read access time without pipeline register			1.78		2.1	ns
Read address setup time in synchronous mode	T_{ADDRSU}	0.301		0.354		ns
Read address setup time in asynchronous mode		1.978		2.327		ns
Read address hold time in synchronous mode	T_{ADDRHD}	0.137		0.161		ns
Read address hold time in asynchronous mode		–0.6		–0.71		ns
Read enable setup time	T_{RDENSU}	0.278		0.327		ns
Read enable hold time	T_{RDENHD}	0.057		0.067		ns
Read block select setup time	T_{BLKSU}	1.839		2.163		ns
Read block select hold time	T_{BLKHD}	–0.65		–0.77		ns
Read block select to out disable time (when pipelined register is disabled)	T_{BLK2Q}		2.16		2.54	ns
Read asynchronous reset removal time (pipelined clock)	T_{RSTREM}	–0.02		–0.03		ns
Read asynchronous reset removal time (non-pipelined clock)		0.046		0.054		ns

Table 254 • Programming Times with 100 kHz, 25 MHz, and 12.5 MHz SPI Clock Rates (eNVM Only) (continued)

M2S/M2GL Device	Auto Programming	Auto Update	Programming Recovery	Unit
	100 kHz	25 MHz	12.5 MHz	
150	161	161	161	Sec

Table 255 • Programming Times with 100 kHz, 25 MHz, and 12.5 MHz SPI Clock Rates (Fabric and eNVM)

M2S/M2GL Device	Auto Programming	Auto Update	Programming Recovery	Unit
	100 kHz	25 MHz	12.5 MHz	
005	47	27	28	Sec
010	77	35	35	Sec
025	150	42	41	Sec
050	33 ¹	Not Supported	Not Supported	Sec
060	291	83	82	Sec
090	427	109	108	Sec
150	708	157	160	Sec
005	41	48	49	Sec
010	86	87	87	Sec
025	87	85	86	Sec
050	85	Not Supported	Not Supported	Sec
060	78	86	86	Sec
090	154	162	162	Sec
150	161	161	161	Sec
005	87	67	66	Sec
010	161	113	113	Sec
025	229	120	121	Sec
050	112	Not Supported	Not Supported	Sec
060	368	161	158	Sec
090	582	261	260	Sec
150	867	309	310	Sec

1. Auto Programming in 050 device is done through SC_SPI, and SPI CLK is set to 6.25 MHz.

2.3.14 Math Block Timing Characteristics

The fundamental building block in any digital signal processing algorithm is the multiply-accumulate function. Each IGLOO2 and SmartFusion2 SoC math block supports 18×18 signed multiplication, dot product, and built-in addition, subtraction, and accumulation units to combine multiplication results efficiently. The following table lists the math blocks with all registers used in worst commercial-case conditions when $T_J = 85^\circ\text{C}$, $V_{DD} = 1.14\text{ V}$.

Table 268 • Math Blocks with all Registers Used

Parameter	Symbol	–1		–Std		Unit
		Min	Max	Min	Max	
Input, control register setup time	T_{MISU}	0.149		0.176		ns
Input, control register hold time	T_{MIHD}	1.68		1.976		ns
CDIN input setup time	$T_{MOCDINSU}$	0.185		0.218		ns
CDIN input hold time	$T_{MOCDINHHD}$	0.08		0.094		ns
Synchronous reset/enable setup time	$T_{MSRSTENSU}$	–0.419		–0.493		ns
Synchronous reset/enable hold time	$T_{MSRSTENHD}$	0.011		0.013		ns
Asynchronous reset removal time	$T_{MARSTREM}$	0		0		ns
Asynchronous reset recovery time	$T_{MARSTREC}$	0.088		0.104		ns
Output register clock to out delay	T_{MOCQ}		0.232		0.273	ns
CLK minimum period	T_{MCLKMP}	2.245		2.641		ns

The following table lists the math blocks with input bypassed and output registers used in worst commercial-case conditions when $T_J = 85^\circ\text{C}$, $V_{DD} = 1.14\text{ V}$.

Table 269 • Math Block with Input Bypassed and Output Registers Used

Parameter	Symbol	–1		–Std		Unit
		Min	Max	Min	Max	
Output register setup time	T_{MOSU}	2.294		2.699		ns
Output register hold time	T_{MOHD}	1.68		1.976		ns
CDIN input setup time	$T_{MOCDINSU}$	0.115		0.136		ns
CDIN input hold time	$T_{MOCDINHHD}$	–0.444		–0.522		ns
Synchronous reset/enable setup time	$T_{MSRSTENSU}$	–0.419		–0.493		ns
Synchronous reset/enable hold time	$T_{MSRSTENHD}$	0.011		0.013		ns
Asynchronous reset removal time	$T_{MARSTREM}$	0		0		ns
Asynchronous reset recovery time	$T_{MARSTREC}$	0.014		0.017		ns
Output register clock to out delay	T_{MOCQ}		0.232		0.273	ns
CLK minimum period	T_{MCLKMP}	2.179		2.563		ns

Table 276 • Cryptographic Block Characteristics (continued)

Service	Conditions	Timing	Unit
SHA256	512 bits	540	kbps
	1024 bits	780	kbps
	2048 bits	950	kbps
	24 kbits	1140	kbps
HMAC	512 bytes	820	kbps
	1024 bytes	890	kbps
	2048 bytes	930	kbps
	24 kbytes	980	kbps
KeyTree		1.8	ms
Challenge-response	PUF = OFF	25	ms
	PUF = ON	7	ms
ECC point multiplication		590	ms
ECC point addition		8	ms

1. Using cypher block chaining (CBC) mode.

2.3.19 Crystal Oscillator

The following table describes the electrical characteristics of the crystal oscillator in the IGLOO2 FPGA and SmartFusion2 SoC FPGAs.

Table 277 • Electrical Characteristics of the Crystal Oscillator – High Gain Mode (20 MHz)

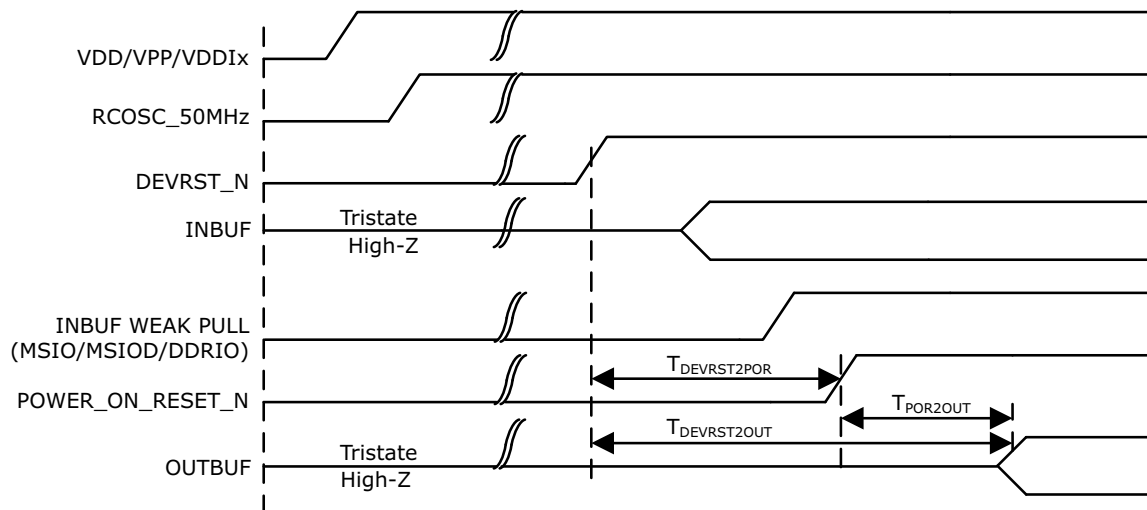
Parameter	Symbol	Min	Typ	Max	Unit	Condition
Operating frequency	FXTAL		20		MHz	
Accuracy	ACCXTAL			0.0047	%	005, 010, 025, 050, 060, and 090 devices
				0.0058	%	150 devices
Output duty cycle	CYCXTAL		49–51	47–53	%	
Output period jitter (peak to peak)	JITPERXTAL		200	300	ps	
Output cycle to cycle jitter (peak to peak)	JITCYCXTAL		200	300	ps	010, 025, 050, and 060 devices
			250	410	ps	150 devices
			250	550	ps	005 and 090 devices
Operating current	IDYNXTAL		1.5		mA	010, 050, and 060 devices
			1.65		mA	005, 025, 090, and 150 devices
Input logic level high	VIHXTAL	0.9 V _{PP}			V	
Input logic level low	VILXTAL			0.1 V _{PP}	V	

2.3.21 Clock Conditioning Circuits (CCC)

The following table lists the CCC/PLL specifications in worst-case industrial conditions when $T_J = 100^\circ\text{C}$, $V_{DD} = 1.14\text{ V}$.

Table 282 • IGLOO2 and SmartFusion2 SoC FPGAs CCC/PLL Specification

Parameter	Min	Typ	Max	Unit	Conditions
Clock conditioning circuitry input frequency F_{IN_CCC}	1		200	MHz	All CCC
	0.032		200	MHz	32 kHz capable CCC
Clock conditioning circuitry output frequency $F_{OUT_CCC}^1$	0.078		400	MHz	
PLL VCO frequency ²	500		1000	MHz	
Delay increments in programmable delay blocks		75	100	ps	
Number of programmable values in each programmable delay block			64		
Acquisition time		70	100	μs	$F_{IN} \geq 1\text{ MHz}$
		1	16	ms	$F_{IN} = 32\text{ kHz}$
Input duty cycle (reference clock)					Internal Feedback
	10		90	%	$1\text{ MHz} \leq F_{IN_CCC} \leq 25\text{ MHz}$
	25		75	%	$25\text{ MHz} \leq F_{IN_CCC} \leq 100\text{ MHz}$
	35		65	%	$100\text{ MHz} \leq F_{IN_CCC} \leq 150\text{ MHz}$
	45		55	%	$150\text{ MHz} \leq F_{IN_CCC} \leq 200\text{ MHz}$
					External Feedback (CCC, FPGA, Off-chip)
	25		75	%	$1\text{ MHz} \leq F_{IN_CCC} \leq 25\text{ MHz}$
	35		65	%	$25\text{ MHz} \leq F_{IN_CCC} \leq 35\text{ MHz}$
	45		55	%	$35\text{ MHz} \leq F_{IN_CCC} \leq 50\text{ MHz}$
	48		52	%	050 devices $F_{OUT} \leq 400\text{ MHz}$
	48		52	%	005, 010, and 025 devices $F_{OUT} < 350\text{ MHz}$
	46		54	%	005, 010, and 025 devices $350\text{ MHz} \leq F_{out} \leq 400\text{ MHz}$
Output duty cycle	48		52	%	060 and 090 devices $F_{OUT} \leq 100\text{ MHz}$
	44		52	%	060 and 090 devices $100\text{ MHz} \leq F_{OUT} \leq 400\text{ MHz}$
	48		52	%	150 devices $F_{OUT} \leq 120\text{ MHz}$
	45		52	%	150 devices $120\text{ MHz} \leq F_{OUT} \leq 400\text{ MHz}$
Spread Spectrum Characteristics					
Modulation frequency range	25	35	50	k	
Modulation depth range	0		1.5	%	
Modulation depth control		0.5		%	

Figure 20 • DEVRST_N to Functional Timing Diagram for IGLOO2

2.3.27 Flash*Freeze Timing Characteristics

The following table lists the Flash*Freeze entry and exit times in worst-case industrial conditions when $T_J = 100\text{ }^{\circ}\text{C}$, $V_{DD} = 1.14\text{ V}$.

Table 293 • Flash*Freeze Entry and Exit Times

Parameter	Symbol	Entry/Exit Timing FCLK = 100MHz		Entry/Exit Timing FCLK = 3 MHz		Unit	Conditions
		005, 010, 025, 060, 090, and 150	050	All Devices			
Entry time	TFF_ENTRY	160	150	320		μs	eNVM and MSS/HPMS PLL = ON
		215	200	430		μs	eNVM and MSS/HPMS PLL= OFF
Exit time with respect to the MSS PLL Lock	TFF_EXIT	100	100	140		μs	eNVM and MSS/HPMS PLL = ON during F*F
		136	120	190		μs	eNVM = ON and MSS/HPMS PLL = OFF during F*F and MSS/HPMS PLL turned back on at exit
		200	200	285		μs	eNVM and MSS/HPMS PLL = OFF during F*F and both are turned back on at exit
		200	200	285		μs	eNVM = OFF and MSS/HPMS PLL = ON during F*F and eNVM turned back on at exit

The following table lists the receiver pa in worst-case industrial conditions when $T_J = 100\text{ }^{\circ}\text{C}$, $V_{DD} = 1.14\text{ V}$.

Table 297 • Receiver Parameters

Symbol	Description	Min	Typ	Max	Unit
VRX-IN-PP-CC	Differential input peak-to-peak sensitivity (2.5 Gbps)	0.238		1.2	V
	Differential input peak-to-peak sensitivity (2.5 Gbps, de-emphasized)	0.219		1.2	V
	Differential input peak-to-peak sensitivity (5.0 Gbps)	0.300		1.2	V
	Differential input peak-to-peak sensitivity (5.0 Gbps, de-emphasized)	0.300		1.2	V
VRX-CM-AC-P	Input common mode range (AC coupled)			150	mV
ZRX-DIFF-DC	Differential input termination	80	100	120	Ω
REXT	External calibration resistor	1,188	1,200	1,212	Ω
CDR-LOCK-RST	CDR relock time from reset			15	μs
RLRX-DIFF	Return loss differential mode (2.5 Gbps)	-10			dB
	Return loss differential mode (5.0 Gbps)				
	0.05 GHz to 1.25 GHz	-10			dB
	1.25 GHz to 2.5 GHz	-8			dB
RLRX-CM	Return loss common mode (2.5 Gbps, 5.0 Gbps)	-6			dB
RX-CID ¹	CID limit PCIe Gen1/2			200	UI
VRX-IDLE-DET-DIFF-PP	Signal detect limit	65		175	mV

1. AC-coupled, BER = e^{-12} , using synchronous clock.

Table 298 • SerDes Protocol Compliance

Protocol	Maximum Data Rate (Gbps)	-1	-Std
PCIe Gen 1	2.5	Yes	Yes
PCIe Gen 2	5.0	Yes	
XAUI	3.125	Yes	
Generic EPCS	3.2	Yes	
Generic EPCS	2.5	Yes	Yes

2.3.31.2 SmartFusion2 Inter-Integrated Circuit (I²C) Characteristics

This section describes the DC and switching of the I²C interface. Unless otherwise noted, all output characteristics given are for a 100 pF load on the pins. For timing parameter definitions, see Figure 21, page 125.

The following table lists the I²C characteristics in worst-case industrial conditions when $T_J = 100\text{ }^{\circ}\text{C}$, $V_{DD} = 1.14\text{ V}$

Table 303 • I²C Characteristics

Parameter	Symbol	Min	Typ	Max	Unit	Conditions
Input low voltage	V_{IL}	-0.3		0.8	V	See Single-Ended I/O Standards, page 24 for more information. I/O standard used for illustration: MSIO bank-LVTTL 8 mA low drive.
Input high voltage	V_{IH}	2		3.45	V	See Single-Ended I/O Standards, page 24 for more information. I/O standard used for illustration: MSIO bank-LVTTL 8 mA low drive.
Hysteresis of schmitt triggered inputs for $V_{DDI} > 2\text{ V}$	V_{HYS}	$0.05 \times V_{DDI}$			V	See Table 28, page 23 for more information.
Input current high	I_{IL}			10	μA	See Single-Ended I/O Standards, page 24 for more information.
Input current low	I_{IH}			10	μA	See Single-Ended I/O Standards, page 24 for more information.
Input rise time	T_{ir}			1000	ns	Standard mode
				300	ns	Fast mode
Input fall time	T_{if}			300	ns	Standard mode
				300	ns	Fast mode
Maximum output voltage low (open drain) at 3 mA sink current for $V_{DDI} > 2\text{ V}$	V_{OL}			0.4	V	See Single-Ended I/O Standards, page 24 for more information. I/O standard used for illustration: MSIO bank-LVTTL 8 mA low drive.
Pin capacitance	C_{in}			10	pF	$V_{IN} = 0$, $f = 1.0\text{ MHz}$
Output fall time from V_{IHMin} to V_{ILMax}^1	t_{OF}^1		21.04		ns	V_{IHmin} to V_{ILMax} , $C_{LOAD} = 400\text{ pF}$
			5.556		ns	V_{IHmin} to V_{ILMax} , $C_{LOAD} = 100\text{ pF}$
Output rise time from V_{ILMax} to V_{IHMin}^1	t_{OR}^1		19.887		ns	V_{ILMax} to V_{IHmin} , $C_{LOAD} = 400\text{ pF}$
			5.218		ns	V_{ILMax} to V_{IHmin} , $C_{LOAD} = 100\text{ pF}$
Output buffer maximum pull-down resistance ^{2, 3}	$R_{pull-up}^{2,3}$			50	Ω	
Output buffer maximum pull-up resistance ^{2, 4}	$R_{pull-down}^{2,4}$			131.25	Ω	

Table 310 • SPI Characteristics for All Devices (continued)

Symbol	Description	Min	Typ	Max	Unit	Conditions
SPI master configuration (applicable for 060, 090, and 150 devices)						
sp6m	SPI_[0 1]_DO setup time ²	$(\text{SPI_x_CLK_period}/2) - 7.0$			ns	
sp7m	SPI_[0 1]_DO hold time ²	$(\text{SPI_x_CLK_period}/2) - 9.5$			ns	
sp8m	SPI_[0 1]_DI setup time ²	15			ns	
sp9m	SPI_[0 1]_DI hold time ²	-2.5			ns	
SPI slave configuration (applicable for 060, 090, and 150 devices)						
sp6s	SPI_[0 1]_DO setup time ²	$(\text{SPI_x_CLK_period}/2) - 16.0$			ns	
sp7s	SPI_[0 1]_DO hold time ²	$(\text{SPI_x_CLK_period}/2) - 3.5$			ns	
sp8s	SPI_[0 1]_DI setup time ²	3			ns	
sp9s	SPI_[0 1]_DI hold time ²	2.5			ns	

1. For specific Rise/Fall Times board design considerations and detailed output buffer resistances, use the corresponding IBIS models located on the Microsemi SoC Products Group website: <http://www.microsemi.com/soc/download/ibis/default.aspx>.
2. For allowable pclk configurations, see the Serial Peripheral Interface Controller section in the *UG0331: SmartFusion2 Microcontroller Subsystem User Guide*.

Figure 23 • SPI Timing for a Single Frame Transfer in Motorola Mode (SPH = 1)