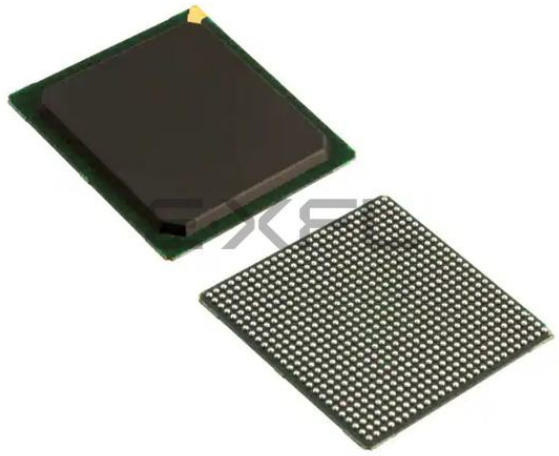

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Understanding Embedded - FPGAs (Field Programmable Gate Array)

Embedded - FPGAs, or Field Programmable Gate Arrays, are advanced integrated circuits that offer unparalleled flexibility and performance for digital systems. Unlike traditional fixed-function logic devices, FPGAs can be programmed and reprogrammed to execute a wide array of logical operations, enabling customized functionality tailored to specific applications. This reprogrammability allows developers to iterate designs quickly and implement complex functions without the need for custom hardware.

Applications of Embedded - FPGAs

The versatility of Embedded - FPGAs makes them indispensable in numerous fields. In telecommunications.

Details	
Product Status	Active
Number of LABs/CLBs	-
Number of Logic Elements/Cells	86316
Total RAM Bits	2648064
Number of I/O	425
Number of Gates	-
Voltage - Supply	1.14V ~ 2.625V
Mounting Type	Surface Mount
Operating Temperature	-40°C ~ 100°C (TJ)
Package / Case	676-BGA
Supplier Device Package	676-FBGA (27x27)
Purchase URL	https://www.e-xfl.com/product-detail/microchip-technology/m2gl090-1fg676i

Contents

1 Revision History

The revision history describes the changes that were implemented in the document. The changes are listed by revision, starting with the most current publication.

1.1 Revision 11.0

The following is a summary of the changes in revision 11.0 of this document.

- Updated Table 24, page 22 with minimum and maximum values for input current low and high (SAR 73114 and 80314).
- Added Non-Deterministic Random Bit Generator (NRBG) Characteristics, page 106 (SAR 73114 and 79517).
- Added 060 device in Table 282, page 110 (SAR 79860).
- Added DEVRST_N to Functional Times, page 116 (SAR 73114).
- Added Cryptographic Block Characteristics, page 106 (SAR 73114 and 79516).
- Update Table 296, page 121 with VTX-AMP details (SAR 81756).
- Update note in Table 297, page 122 (SAR 74570 and 80677).
- Update Table 298, page 122 with generic EPCS details (SAR 75307).
- Added Table 308, page 129 (SAR 50424).

1.2 Revision 10.0

The following is a summary of the changes in revision 10.0 of this document.

- The Surge Current on VDD during DEVRST_B Assertion and Surge Current on VDD during Digest Check using System Services tables were deleted and added reference to *AC393: Board Design Guidelines for SmartFusion2 SoC and IGLOO2 FPGAs Application Note*. (SAR 76865 and 76623).
- Added 060 device in Table 4, page 6 (SAR 76383).
- Updated Table 24, page 22 for ramp time input (SAR 72103).
- Added 060 device details in Table 284, page 112 (SAR 74927).
- Updated Table 290, page 116 for name change (SAR 74925).
- Updated Table 283, page 111 for 060 FG676 Package details (SAR 78849).
- Updated Table 305, page 126 for SmartFusion2 and Table 310, page 129 for IGLOO2 for SPI timing and Fmax (SAR 56645, 75331).
- Updated Table 293, page 119 for Flash*Freeze entry and exit times (SAR 75329, 75330).
- Updated Table 297, page 122 for RX-CID information (SAR 78271).
- Added Table 8, page 8 and Figure 1, page 9 (SAR 78932).
- Updated Table 223, page 76 for timing characteristics and Table 224, page 77(SAR 75998).
- Added SRAM PUF, page 105 (SAR 64406).
- Added a footnote on digest cycle in Table 5, page 7 (SAR 79812).

1.3 Revision 9.0

The following is a summary of the changes in revision 9.0 of this document.

- Added a note in Table 5, page 7 (SAR 71506).
- Added a note in Table 6, page 8 (SAR 74616).
- Added a note in Figure 3, page 17 (SAR 71506).
- Updated Quiescent Supply Current for 060 in Table 11, page 12 and Table 12, page 13 (SAR 74483).
- Updated programming currents for 060 in Table 13, page 13, Table 14, page 13, and Table 15, page 14.
- Added DEVRST_B assertion tables (SAR 74708).
- Updated I/O speeds for LVDS 3.3 V in Table 18, page 19 and Table 21, page 20 (SAR 69829).
- Updated Table 24, page 22 (SAR 69418).
- Updated Table 25, page 22, Table 26, page 23, Table 27, page 23 (SAR 74570).
- Updated all AC/DC table to link to the Input Capacitance, Leakage Current, and Ramp Time, page 22 for reference (SAR 69418).

1.9 Revision 3.0

In revision 3.0 of this document, the Theta B/C columns and FCS325 package was updated. For more information, see Table 9, page 10 (SAR 62002).

1.10 Revision 2.0

The following is a summary of the changes in revision 2.0 of this document.

- Table 1, page 4 was updated (SAR 59056).
- Table 7, page 8 temperature and data retention information was updated SAR (61363).
- Storage Operating Table was updated and split into three tables – Table 5, page 7, Table 7, page 8 (SAR 58725).
- Updated Theta B/C columns and FCS325 package in Table 9, page 10 (SAR 62002).
- Added 090-FCS325 thermal resistance to Table 9, page 10 (SAR 59384).
- TQ144 package was added to Table 9, page 10 (SAR 57708).
- Added PLL jitter data for the VF400 package (SAR 53162).
- Added Additional Worst Case IDD to Table 11, page 12 and Table 12, page 13 (SAR 59077).
- Table 13, page 13, Table 14, page 13, and Table 15, page 14 were added to verify Inrush currents (SAR 56348).
- Table 18, page 19 and Table 21, page 20 – I/O speeds were replaced.
- Max speed was changed in Table 41, page 26 (SAR 57221) and in Table 52, page 29 (SAR 57113).
- Minimum and Maximum DC/AC Input and Output Levels Specification, page 29 and Table 49, page 29–Table 57, page 31 were added.
- Added Cload to Table 89, page 39 (SAR 56238).
- Removed "Rs" information in DDR Timing Measurement Table 123, page 47, Table 133, page 49, and Table 144, page 52.
- Updated drive programming for M/B-LVDS outputs (SAR 58154).
- Added an inverter bubble to DDR_IN latch in Figure 10, page 70 (SAR 61418).
- QF waveform in Figure 11, page 71 was updated (SAR 59816).
- uSRAM Write Clock minimum values were updated in Table 237, page 86–Table 243, page 93 (SAR 55236).
- Fixed typo in the 32 kHz Crystal (XTAL) oscillator accuracy data section (SAR 59669).
- The "On-Chip Oscillator" section was split, and the Embedded NVM (eNVM) Characteristics, page 104 was added. Table 277, page 107–Table 281, page 109 were revised.(SARs 57898 and 59669).
- PLL VCP Frequency and conditions were added to Table 282, page 110 (SAR 57416).
- Fixed typo for PLL jitter data in the 100-400 MHz range (SAR 60727).
- Updated FCCC information in Table 282, page 110 and Table 283, page 111 (SAR 60799).
- Device 025 specifications were added to Table 283, page 111 (SAR 51625).
- JTAG Table 284, page 112 was replaced (SAR 51188).
- Flash*Freeze Table 293, page 119 was replaced (SAR 57828).
- Added support for HCSL I/O Standard for SERDES reference clocks in Table 300, page 123 and Table 301, page 123 (SAR 50748).
- Tir and Tif parameters were added to Table 303, page 124 (SAR 52203).
- Speed grade consistency was fixed in tables throughout the datasheet (SAR 50722).
- Added jitter attenuation information (SAR 59405).

1.11 Revision 1.0

The following is a summary of the changes in revision 1.0 of this document.

- The IGLOO2 v2 and the SmartFusion2 v5 datasheets are combined into this single product family datasheet.

Table 4 • **Recommended Operating Conditions *(continued)***

Parameter	Symbol	Min	Typ	Max	Unit	Conditions
3.3 V DC supply voltage	V_{DDIx}	3.15	3.3	3.45	V	
LVDS differential I/O	V_{DDIx}	2.375	2.5	3.45	V	
B-LVDS, M-LVDS, Mini-LVDS, RSDS differential I/O	V_{DDIx}	2.375	2.5	2.625	V	
LVPECL differential I/O	V_{DDIx}	3.15	3.3	3.45	V	
Reference voltage supply for FDDR (Bank0) and MDDR (Bank5)	V_{REFx}	0.49 × V_{DDIx}	0.5 × V_{DDIx}	0.51 × V_{DDIx}	V	
Analog sense circuit supply of embedded nonvolatile memory (eNVM). Must be shorted to V_{PP}.	V_{PPNVM}	2.375	2.5	2.625	V	2.5 V range
		3.15	3.3	3.45	V	3.3 V range

1. Programming at Industrial temperature range is available only with V_{PP} = 3.3 V.

Note: Power supply ramps must all be strictly monotonic, without plateaus.

Table 5 • **FPGA Operating Limits**

Product Grade	Element	Programming Temperature	Operating Temperature	Programming Cycles	Digest Temperature	Digest Cycles	Retention (Biased/ Unbiased)
Commercial	FPGA	Min T_J = 0 °C Max T_J = 85 °C	Min T_J = 0 °C Max T_J = 85 °C	500	Min T_J = 0 °C Max T_J = 85 °C	2000	20 years
Industrial[1]	FPGA	Min T_J = –40 °C Max T_J = 100 °C	Min T_J = –40 °C Max T_J = 100 °C	500	Min T_J = –40 °C Max T_J = 100 °C	2000	20 years

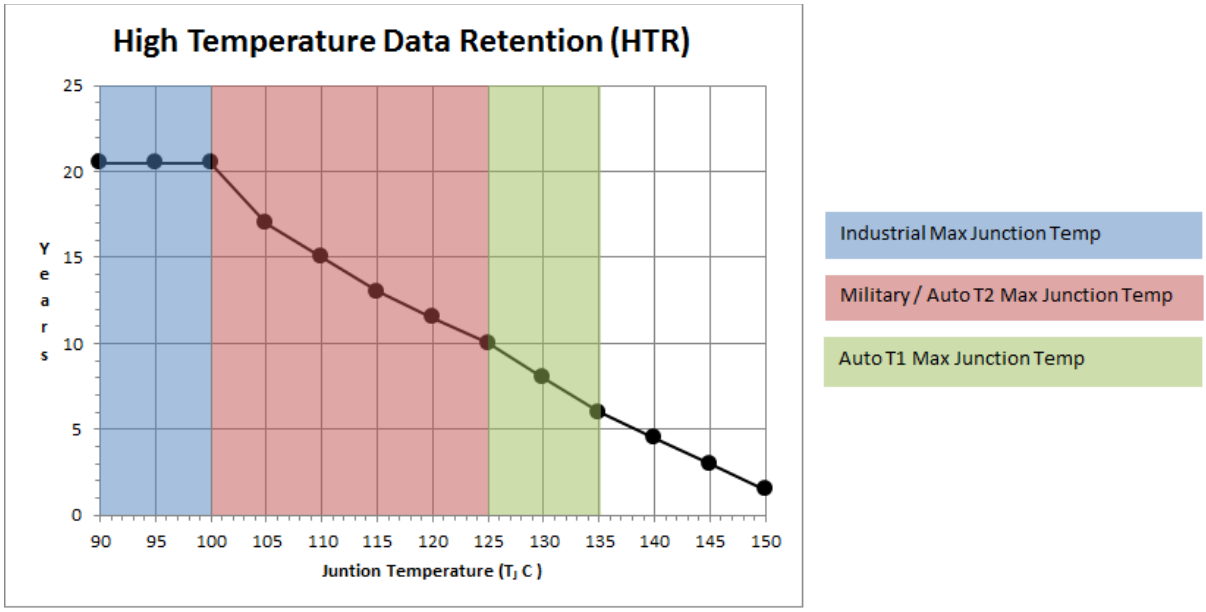
1. Programming at Industrial temperature range is available only with VPP = 3.3 V.

Note: The retention specification is defined as the total number of programing and digest cycles. For example, 20 years of retention after 500 programming cycles.

Note: The digest cycle specification is 2000 digest cycles for every program cycle with a maximum of 500 programming cycles.

Note: If your product qualification requires accelerated programming cycles, see *Microsemi SoC Products Quality and Reliability Report* about recommended methodologies.

Figure 1 • **High Temperature Data Retention (HTR)**



2.3.1.1 Overshoot/Undershoot Limits

For AC signals, the input signal may undershoot during transitions to –1.0 V for no longer than 10% of the period. The current during the transition must not exceed 100 mA.

For AC signals, the input signal may overshoot during transitions to V_{CCI} + 1.0 V for no longer than 10% of the period. The current during the transition must not exceed 100 mA.

Note: The above specifications do not apply to the PCI standard. The IGLOO2 and SmartFusion2 PCI I/Os are compliant with the PCI standard including the PCI overshoot/undershoot specifications.

2.3.1.2 Thermal Characteristics

The temperature variable in the Microsemi SoC Products Group Designer software refers to the junction temperature, not the ambient, case, or board temperatures. This is an important distinction because dynamic and static power consumption causes the chip's junction temperature to be higher than the ambient, case, or board temperatures.

EQ1 through EQ3 give the relationship between thermal resistance, temperature gradient, and power.

$$\theta_{JA} = \frac{T_J - T_A}{P}$$

EQ 1

$$\theta_{JB} = \frac{T_J - T_B}{P}$$

EQ 2

$$\theta_{JC} = \frac{T_J - T_C}{P}$$

EQ 3

Table 9 • **Package Thermal Resistance of SmartFusion2 and IGLOO2 Devices *(continued)***

Device	Still Air θ_{JA}	1.0 m/s θ_{JA}	2.5 m/s θ_{JA}	θ_{JB}	θ_{JC}	Unit
150						
FC1152	9.08	6.81	5.87	2.56	0.38	°C/W
FCS536	15.01	12.06	10.76	3.69	1.55	°C/W
FCV484	16.21	13.11	11.84	6.73	0.10	°C/W

2.3.1.2.1 Theta-JA

Junction-to-ambient thermal resistance (θ_{JA}) is determined under standard conditions specified by JEDEC (JESD-51), but it has little relevance in the actual performance of the product. It must be used with caution, but it is useful for comparing the thermal performance of one package with another.

The maximum power dissipation allowed is calculated using EQ4.

$$\text{Maximum power allowed} = \frac{T_{J(MAX)} - T_{A(MAX)}}{\theta_{JA}}$$

EQ 4

The absolute maximum junction temperature is 100 °C. EQ5 shows a sample calculation of the absolute maximum power dissipation allowed for the M2GL050T-FG896 package at commercial temperature and in still air, where:

θ_{JA} = 14.7 °C/W (taken from Table 9, page 10).

T_A = 85 °C

$$\text{Maximum power allowed} = \frac{100\ °C - 85\ °C}{14.7\ °C/W} = 1.088\ W$$

EQ 5

The power consumption of a device can be calculated using the Microsemi SoC Products Group power calculator. The device's power consumption must be lower than the calculated maximum power dissipation by the package.

If the power consumption is higher than the device's maximum allowable power dissipation, a heat sink may be attached to the top of the case, or the airflow inside the system must be increased.

2.3.1.2.2 Theta-JB

Junction-to-board thermal resistance (θ_{JB}) measures the ability of the package to dissipate heat from the surface of the chip to the PCB. As defined by the JEDEC (JESD-51) standard, the thermal resistance from the junction to the board uses an isothermal ring cold plate zone concept. The ring cold plate is simply a means to generate an isothermal boundary condition at the perimeter. The cold plate is mounted on a JEDEC standard board with a minimum distance of 5.0 mm away from the package edge.

2.3.1.2.3 Theta-JC

Junction-to-case thermal resistance (θ_{JC}) measures the ability of a device to dissipate heat from the surface of the chip to the top or bottom surface of the package. It is applicable to packages used with external heat sinks. Constant temperature is applied to the surface, which acts as a boundary condition.

This only applies to situations where all or nearly all of the heat is dissipated through the surface in consideration.

2.3.1.3 ESD Performance

See *RT0001: Microsemi Corporation - SoC Products Reliability Report* for information about ESD.

2.3.5.5 Detailed I/O Characteristics

Table 24 • **Input Capacitance, Leakage Current, and Ramp Time**

Symbol	Description	Maximum	Unit	Conditions
C_{IN}	Input capacitance	10	pF	
I_{IL} (dc)	Input current low (Applicable to HSTL/SSTL inputs only)	400	µA	V_{DDI} = 2.5 V
		500	µA	V_{DDI} = 1.8 V
		600	µA	V_{DDI} = 1.5 V[1]
	Input current low (Applicable to all other digital inputs)	10	µA	
I_{IH} (dc)	Input current high (Applicable to HSTL/SSTL inputs only)	400	µA	V_{DDI} = 2.5 V
		500	µA	V_{DDI} = 1.8 V
		600	µA	V_{DDI} = 1.5 V[1]
	Input current high (Applicable to all other digital inputs)	10	µA	
T_{RAMPIN}[2]	Input ramp time (Applicable to all digital inputs)	50	ns	

1. Applicable when I/O pair is programmed with an HSTL/SSTL I/O type on IOP and an un-terminated I/O type (LVCMOS, for example) on ION pad.
2. Voltage ramp must be monotonic.

The following table lists the minimum and maximum I/O weak pull-up/pull-down resistance values of DDRIO I/O bank at V_{OH}/V_{OL} Level.

Table 25 • **I/O Weak Pull-up/Pull-down Resistances for DDRIO I/O Bank**

	R(WEAK PULL-UP) at V_{OH} (Ω)		R(WEAK PULL-DOWN) at V_{OL} (Ω)	
V_{DDI} Domain	Min	Max	Min	Max
2.5 V[1, 2]	10K	17.8K	9.98K	18K
1.8 V[1, 2]	10.3K	19.1K	10.3K	19.5K
1.5 V[1, 2]	10.6K	20.2K	10.6K	21.1K
1.2 V[1, 2]	11.1K	22.7K	11.2K	24.6K

1. R(WEAK PULL-DOWN) = (VOLspec)/I(WEAK PULL-DOWN MAX).
2. R(WEAK PULL-UP) = (VDDImax – VOHspec)/I(WEAK PULL-UP MIN).

2.3.5.7 2.5 V LVCMOS

LVCMOS 2.5 V is a general standard for 2.5 V applications and is supported in IGLOO2 FPGA and SmartFusion2 SoC FPGAs that are in compliance with the JEDEC specification JESD8-5A.

Minimum and Maximum DC/AC Input and Output Levels Specification

Table 38 • **LVCMOS 2.5 V DC Recommended DC Operating Conditions**

Parameter	Symbol	Min	Typ	Max	Unit
Supply voltage	V_{DDI}	2.375	2.5	2.625	V

Table 39 • **LVCMOS 2.5 V DC Input Voltage Specification**

Parameter	Symbol	Min	Max	Unit
DC input logic high (for MSIOD and DDRIO I/O banks)	V_{IH} (DC)	1.7	2.625	V
DC input logic high (for MSIO I/O bank)	V_{IH} (DC)	1.7	3.45	V
DC input logic low	V_{IL} (DC)	–0.3	0.7	V
Input current high[1]	I_{IH} (DC)			
Input current low[1]	I_{IL} (DC)			

1. See Table 24, page 22.

Table 40 • **LVCMOS 2.5 V DC Output Voltage Specification**

Parameter	Symbol	Min	Max	Unit
DC output logic high	V_{OH}[1]	V_{DDI} – 0.4	–	V
DC output logic low	V_{OL}[2]		0.4	V

1. The VOH/VOL test points selected ensure compliance with LVCMOS 2.5 V JEDEC8-5A requirements.

Table 41 • **LVCMOS 2.5 V AC Minimum and Maximum Switching Speed**

Parameter	Symbol	Max	Unit	Conditions
Maximum data rate (for DDRIO I/O bank)	D_{MAX}	400	Mbps	AC loading: 17 pF load, maximum drive/slew
Maximum data rate (for MSIO I/O bank)	D_{MAX}	410	Mbps	AC loading: 17 pF load, maximum drive/slew
Maximum data rate (for MSIOD I/O bank)	D_{MAX}	420	Mbps	AC loading: 17 pF load, maximum drive/slew

Table 42 • **LVCMOS 2.5 V AC Calibrated Impedance Option**

Parameter	Symbol	Typ	Unit
Supported output driver calibrated impedance (for DDRIO I/O bank)	Rodt_cal	75, 60, 50, 33, 25, 20	Ω

Table 46 • **LVCMOS 2.5 V Transmitter Characteristics for DDRIO Bank (Output and Tristate Buffers) *(continued)***

Output Drive Selection	Slew Control	T_{DP}		T_{ZL}		T_{ZH}		T_{HZ}[1]		T_{LZ}[1]		
		–1	–Std	–1	–Std	–1	–Std	–1	–Std	–1	–Std	Unit
4 mA	Slow	3.095	3.641	2.705	3.182	3.088	3.633	4.738	5.575	4.348	5.116	ns
	Medium	2.825	3.324	2.488	2.927	2.823	3.321	4.492	5.285	4.063	4.781	ns
	Medium fast	2.701	3.178	2.384	2.804	2.698	3.173	4.364	5.135	3.945	4.642	ns
	Fast	2.69	3.165	2.377	2.796	2.687	3.161	4.359	5.129	3.94	4.636	ns
6 mA	Slow	2.919	3.434	2.491	2.93	2.902	3.414	5.085	5.983	4.674	5.5	ns
	Medium	2.65	3.118	2.279	2.681	2.642	3.108	4.845	5.701	4.375	5.148	ns
	Medium fast	2.529	2.975	2.176	2.56	2.521	2.965	4.724	5.558	4.259	5.011	ns
	Fast	2.516	2.96	2.168	2.551	2.508	2.95	4.717	5.55	4.251	5.002	ns
8 mA	Slow	2.863	3.368	2.427	2.855	2.844	3.346	5.196	6.114	4.769	5.612	ns
	Medium	2.599	3.058	2.217	2.608	2.59	3.047	4.952	5.827	4.471	5.261	ns
	Medium fast	2.483	2.921	2.114	2.487	2.473	2.91	4.832	5.685	4.364	5.134	ns
	Fast	2.467	2.902	2.106	2.478	2.457	2.89	4.826	5.678	4.348	5.116	ns
12 mA	Slow	2.747	3.232	2.296	2.701	2.724	3.204	5.39	6.342	4.938	5.81	ns
	Medium	2.493	2.934	2.102	2.473	2.483	2.921	5.166	6.078	4.65	5.471	ns
	Medium fast	2.382	2.803	2.006	2.36	2.371	2.789	5.067	5.962	4.546	5.349	ns
	Fast	2.369	2.787	1.999	2.352	2.357	2.773	5.063	5.958	4.538	5.339	ns
16 mA	Slow	2.677	3.149	2.213	2.604	2.649	3.116	5.575	6.56	5.08	5.977	ns
	Medium	2.432	2.862	2.028	2.386	2.421	2.848	5.372	6.32	4.801	5.649	ns
	Medium fast	2.324	2.734	1.937	2.278	2.311	2.718	5.297	6.233	4.7	5.531	ns
	Fast	2.313	2.721	1.929	2.269	2.3	2.706	5.296	6.231	4.699	5.529	ns

1. Delay increases with drive strength are inherent to built-in slew control circuitry for simultaneous switching output (SSO) management.

Table 47 • **LVCMOS 2.5 V Transmitter Characteristics for MSIO Bank (Output and Tristate Buffers)**

Output Drive Selection	Slew Control	T_{DP}		T_{ZL}		T_{ZH}		T_{HZ}[1]		T_{LZ}[1]		
		–1	–Std	–1	–Std	–1	–Std	–1	–Std	–1	–Std	Unit
2 mA	Slow	3.48	4.095	3.855	4.534	3.785	4.453	2.12	2.494	3.45	4.059	ns
4 mA	Slow	2.583	3.039	3.042	3.579	3.138	3.691	4.143	4.874	4.687	5.513	ns
6 mA	Slow	2.392	2.815	2.669	3.139	2.82	3.317	4.909	5.775	5.083	5.98	ns
8 mA	Slow	2.309	2.717	2.565	3.017	2.74	3.223	5.812	6.837	5.523	6.497	ns
12 mA	Slow	2.333	2.745	2.437	2.867	2.626	3.089	6.131	7.213	5.712	6.72	ns
16 mA	Slow	2.412	2.838	2.335	2.747	2.533	2.979	6.54	7.694	6.007	7.067	ns

1. Delay increases with drive strength are inherent to built-in slew control circuitry for simultaneous switching output (SSO) management.

Table 62 • LVCMOS 1.5 V DC Output Voltage Specification

Parameter	Symbol	Min	Max	Unit
DC output logic high	VOH	V_{DDI} × 0.75		V
DC output logic low	VOL		V_{DDI} × 0.25	V

Table 63 • LVCMOS 1.5 V AC Minimum and Maximum Switching Speed

Parameter	Symbol	Max	Unit	Conditions
Maximum data rate (for DDRIO I/O bank)	D_{MAX}	235	Mbps	AC loading: 17 pF load, maximum drive/slew
Maximum data rate (for MSIO I/O bank)	D_{MAX}	160	Mbps	AC loading: 17 pF load, maximum drive/slew
Maximum data rate (for MSIOD I/O bank)	D_{MAX}	220	Mbps	AC loading: 17 pF load, maximum drive/slew

Table 64 • LVCMOS 1.5 V AC Calibrated Impedance Option

Parameter	Symbol	Typ	Unit
Supported output driver calibrated impedance (for DDRIO I/O bank)	RODT_CAL	75, 60, 50, 40	Ω

Table 65 • LVCMOS 1.5 V AC Test Parameter Specifications

Parameter	Symbol	Typ	Unit
Measuring/trip point	V_{TRIP}	0.75	V
Resistance for enable path (T_{ZH}, T_{ZL}, T_{HZ}, T_{LZ})	R_{ENT}	2K	Ω
Capacitive loading for enable path (T_{ZH}, T_{ZL}, T_{HZ}, T_{LZ})	C_{ENT}	5	pF
Capacitive loading for data path (T_{DP})	C_{LOAD}	5	pF

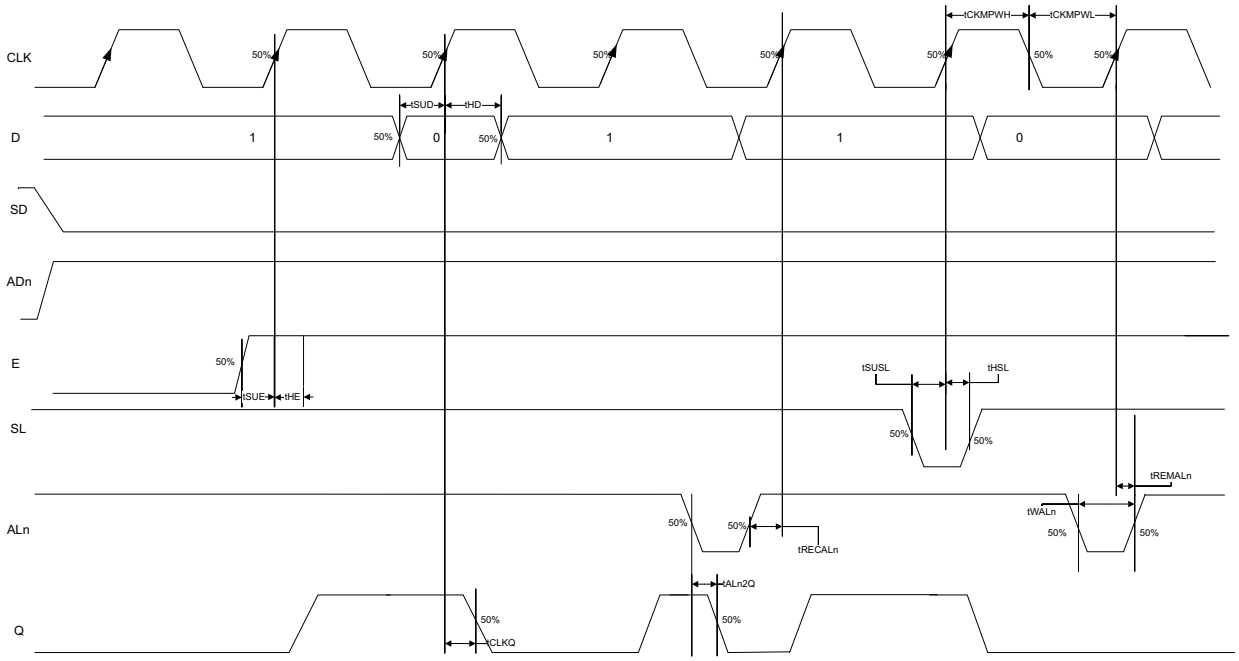
Table 66 • LVCMOS 1.5 V Transmitter Drive Strength Specifications

Output Drive Selection			V_{OH} (V)	V_{OL} (V)	IOH (at V_{OH})	IOL (at V_{OL})
MSIO I/O Bank	MSIOD I/O Bank	DDRIO I/O Bank	Min	Max	mA	mA
2 mA	2 mA	2 mA	V_{DDI} × 0.75	V_{DDI} × 0.25	2	2
4 mA	4 mA	4 mA	V_{DDI} × 0.75	V_{DDI} × 0.25	4	4
6 mA	6 mA	6 mA	V_{DDI} × 0.75	V_{DDI} × 0.25	6	6
8 mA		8 mA	V_{DDI} × 0.75	V_{DDI} × 0.25	8	8
		10 mA	V_{DDI} × 0.75	V_{DDI} × 0.25	10	10
		12 mA	V_{DDI} × 0.75	V_{DDI} × 0.25	12	12

Note: For a detailed I/V curve, use the corresponding IBIS models: www.microsemi.com/soc/download/ibis/default.aspx.

The following figure shows a configuration with SD = 0 (synchronous clear) and ADn = 1 (asynchronous clear) for a flip-flop (LAT = 0).

Figure 16 • **Sequential Module Timing Diagram**



2.3.10.3.1 Timing Characteristics

The following table lists the register delays in worst commercial-case conditions when T_J = 85 °C, V_{DD} = 1.14 V.

Table 224 • **Register Delays**

Parameter	Symbol	–1	–Std	Unit
Clock-to-Q of the core register	T_{CLKQ}	0.108	0.127	ns
Data setup time for the core register	T_{SUD}	0.254	0.298	ns
Data hold time for the core register	T_{HD}	0	0	ns
Enable setup time for the core register	T_{SUE}	0.335	0.394	ns
Enable hold time for the core register	T_{HE}	0	0	ns
Synchronous load setup time for the core register	T_{SUSL}	0.335	0.394	ns
Synchronous load hold time for the core register	T_{HSL}	0	0	ns
Asynchronous Clear-to-Q of the core register (ADn = 1)	T_{ALN2Q}	0.473	0.556	ns
Asynchronous preset-to-Q of the core register (ADn = 0)		0.451	0.531	ns
Asynchronous load removal time for the core register	T_{REMALN}	0	0	ns
Asynchronous load recovery time for the core register	T_{RECALN}	0.353	0.415	ns
Asynchronous load minimum pulse width for the core register	T_{WALN}	0.266	0.313	ns
Clock minimum pulse width high for the core register	T_{CKMPWH}	0.065	0.077	ns
Clock minimum pulse width low for the core register	T_{CKMPWL}	0.139	0.164	ns

Table 232 • **RAM1K18 – Dual-Port Mode for Depth × Width Configuration 2K × 9 *(continued)***

		–1		–Std		
Parameter	**Symbol**	**Min**	**Max**	**Min**	**Max**	**Unit**
Address setup time	T_{ADDRSU}	0.475		0.559		ns
Address hold time	T_{ADDRHD}	0.274		0.322		ns
Data setup time	T_{DSU}	0.336		0.395		ns
Data hold time	T_{DHD}	0.082		0.096		ns
Block select setup time	T_{BLKSU}	0.207		0.244		ns
Block select hold time	T_{BLKHD}	0.216		0.254		ns
Block select to out disable time (when pipelined register is disabled)	T_{BLK2Q}		1.529		1.799	ns
Block select minimum pulse width	T_{BLKMPW}	0.186		0.219		ns
Read enable setup time	T_{RDESU}	0.485		0.57		ns
Read enable hold time	T_{RDEHD}	0.071		0.083		ns
Pipelined read enable setup time (A_DOUT_EN, B_DOUT_EN)	$T_{RDPLESU}$	0.248		0.291		ns
Pipelined read enable hold time (A_DOUT_EN, B_DOUT_EN)	$T_{RDPLEHD}$	0.102		0.12		ns
Asynchronous reset to output propagation delay	T_{R2Q}		1.514		1.781	ns
Asynchronous reset removal time	T_{RSTREM}	0.506		0.595		ns
Asynchronous reset recovery time	T_{RSTREC}	0.004		0.005		ns
Asynchronous reset minimum pulse width	T_{RSTMPW}	0.301		0.354		ns
Pipelined register asynchronous reset removal time	$T_{PLRSTREM}$	–0.279		–0.328		ns
Pipelined register asynchronous reset recovery time	$T_{PLRSTREC}$	0.327		0.385		ns
Pipelined register asynchronous reset minimum pulse width	$T_{PLRSTMPW}$	0.282		0.332		ns
Synchronous reset setup time	T_{SRSTSU}	0.226		0.265		ns
Synchronous reset hold time	T_{SRSTHD}	0.036		0.043		ns
Write enable setup time	T_{WESU}	0.415		0.488		ns
Write enable hold time	T_{WEHD}	0.048		0.057		ns
Maximum frequency	F_{MAX}		400		340	MHz

The following table lists the RAM1K18 – dual-port mode for depth × width configuration 4K × 4 in worst commercial-case conditions when T_J = 85 °C, V_{DD} = 1.14 V.

Table 233 • **RAM1K18 – Dual-Port Mode for Depth × Width Configuration 4K × 4**

		–1		–Std		
Parameter	**Symbol**	**Min**	**Max**	**Min**	**Max**	**Unit**
Clock period	T_{CY}	2.5		2.941		ns
Clock minimum pulse width high	$T_{CLKMPWH}$	1.125		1.323		ns
Clock minimum pulse width low	$T_{CLKMPWL}$	1.125		1.323		ns
Pipelined clock period	T_{PLCY}	2.5		2.941		ns
Pipelined clock minimum pulse width high	$T_{PLCLKMPWH}$	1.125		1.323		ns

Table 237 • **µSRAM (RAM64x18) in 64 × 18 Mode *(continued)***

		–1		–Std		
Parameter	**Symbol**	**Min**	**Max**	**Min**	**Max**	**Unit**
Write address setup time	$T_{ADDRCSU}$	0.088		0.104		ns
Write address hold time	$T_{ADDRCHD}$	0.128		0.15		ns
Write enable setup time	T_{WECSU}	0.397		0.467		ns
Write enable hold time	T_{WECHD}	–0.026		–0.03		ns
Maximum frequency	F_{MAX}		250		250	MHz

The following table lists the µSRAM in 64 × 16 mode in worst commercial-case conditions when T_J = 85 °C, V_{DD} = 1.14 V.

Table 238 • **µSRAM (RAM64x16) in 64 × 16 Mode**

		–1		–Std		
Parameter	**Symbol**	**Min**	**Max**	**Min**	**Max**	**Unit**
Read clock period	T_{CY}	4		4		ns
Read clock minimum pulse width high	$T_{CLKMPWH}$	1.8		1.8		ns
Read clock minimum pulse width low	$T_{CLKMPWL}$	1.8		1.8		ns
Read pipeline clock period	T_{PLCY}	4		4		ns
Read pipeline clock minimum pulse width high	$T_{PLCLKMPWH}$	1.8		1.8		ns
Read pipeline clock minimum pulse width low	$T_{PLCLKMPWL}$	1.8		1.8		ns
Read access time with pipeline register	T_{CLK2Q}		0.266		0.313	ns
Read access time without pipeline register			1.677		1.973	ns
Read address setup time in synchronous mode	T_{ADDRSU}	0.301		0.354		ns
Read address setup time in asynchronous mode		1.856		2.184		ns
Read address hold time in synchronous mode	T_{ADDRHD}	0.091		0.107		ns
Read address hold time in asynchronous mode		–0.778		–0.915		ns
Read enable setup time	T_{RDENSU}	0.278		0.327		ns
Read enable hold time	T_{RDENHD}	0.057		0.067		ns
Read block select setup time	T_{BLKSU}	1.839		2.163		ns
Read block select hold time	T_{BLKHD}	–0.65		–0.765		ns
Read block select to out disable time (when pipelined register is disabled)	T_{BLK2Q}		2.036		2.396	ns
Read asynchronous reset removal time (pipelined clock)	T_{RSTREM}	–0.023		–0.027		ns
Read asynchronous reset removal time (non-pipelined clock)		0.046		0.054		ns
Read asynchronous reset recovery time (pipelined clock)	T_{RSTREC}	0.507		0.597		ns
Read asynchronous reset recovery time (non-pipelined clock)		0.236		0.278		ns
Read asynchronous reset to output propagation delay (with pipelined register enabled)	T_{R2Q}		0.835		0.983	ns
Read synchronous reset setup time	T_{SRSTSU}	0.271		0.319		ns

Table 254 • Programming Times with 100 kHz, 25 MHz, and 12.5 MHz SPI Clock Rates (eNVM Only) *(continued)*

M2S/M2GL Device	Auto Programming 100 kHz	Auto Update 25 MHz	Programming Recovery 12.5 MHz	Unit
150	161	161	161	Sec

Table 255 • Programming Times with 100 kHz, 25 MHz, and 12.5 MHz SPI Clock Rates (Fabric and eNVM)

M2S/M2GL Device	Auto Programming 100 kHz	Auto Update 25 MHz	Programming Recovery 12.5 MHz	Unit
005	47	27	28	Sec
010	77	35	35	Sec
025	150	42	41	Sec
050	33[1]	Not Supported	Not Supported	Sec
060	291	83	82	Sec
090	427	109	108	Sec
150	708	157	160	Sec
005	41	48	49	Sec
010	86	87	87	Sec
025	87	85	86	Sec
050	85	Not Supported	Not Supported	Sec
060	78	86	86	Sec
090	154	162	162	Sec
150	161	161	161	Sec
005	87	67	66	Sec
010	161	113	113	Sec
025	229	120	121	Sec
050	112	Not Supported	Not Supported	Sec
060	368	161	158	Sec
090	582	261	260	Sec
150	867	309	310	Sec

1. Auto Programming in 050 device is done through SC_SPI, and SPI CLK is set to 6.25 MHz.

The following table lists the programming times in worst-case conditions when T_J = 100 °C, V_{DD} = 1.14 V. External SPI flash part# AT25DF641-s3H is used during this measurement.

Table 256 • **JTAG Programming (Fabric Only)**

M2S/M2GL Device	Image size Bytes	Program	Verify	Unit
005	302672	44	10	Sec
010	568784	50	18	Sec
025	1223504	73	26	Sec
050	2424832	88	54	Sec
060	2418896	99	54	Sec
090	3645968	135	126	Sec
150	6139184	177	193	Sec

Table 257 • **JTAG Programming (eNVM Only)**

M2S/M2GL Device	Image size Bytes	Program	Verify	Unit
005	137536	61	4	Sec
010	274816	100	9	Sec
025	274816	100	9	Sec
050	2,78,528	106	8	Sec
060	268480	98	8	Sec
090	544496	176	15	Sec
150	544496	177	15	Sec

Table 258 • **JTAG Programming (Fabric and eNVM)**

M2S/M2GL Device	Image size Bytes	Program	Verify	Unit
005	439296	71	11	Sec
010	842688	129	20	Sec
025	1497408	142	35	Sec
050	2695168	184	59	Sec
060	2686464	180	70	Sec
090	4190208	288	147	Sec
150	6682768	338	231	Sec

Table 259 • **2 Step IAP Programming (Fabric Only)**

M2S/M2GL Device	Image size Bytes	Authenticate	Program	Verify	Unit
005	302672	4	39	6	Sec
010	568784	7	45	12	Sec
025	1223504	14	55	23	Sec
050	2424832	29	74	40	Sec
060	2418896	39	83	50	Sec
090	3645968	60	106	73	Sec
150	6139184	100	154	120	Sec

Table 260 • **2 Step IAP Programming (eNVM Only)**

M2S/M2GL Device	Image size Bytes	Authenticate	Program	Verify	Unit
005	137536	2	59	5	Sec
010	274816	4	98	11	Sec
025	274816	4	100	10	Sec
050	2,78,528	3	107	9	Sec
060	268480	5	98	22	Sec
090	544496	10	174	43	Sec
150	544496	10	175	44	Sec

Table 261 • **2 Step IAP Programming (Fabric and eNVM)**

M2S/M2GL Device	Image size Bytes	Authenticate	Program	Verify	Unit
005	439296	6	78	11	Sec
010	842688	11	122	21	Sec
025	1497408	19	135	32	Sec
050	2695168	32	158	48	Sec
060	2686464	43	159	70	Sec
090	4190208	68	258	115	Sec
150	6682768	109	308	162	Sec

2.3.22 JTAG

Table 284 • **JTAG 1532 for 005, 010, 025, and 050 Devices**

		005		010		025		050		Unit
Parameter	**Symbol**	**–1**	**–Std**	**–1**	**–Std**	**–1**	**–Std**	**–1**	**–Std**	
Clock to Q (data out)	T_{TCK2Q}	7.47	8.79	7.73	9.09	7.75	9.12	7.89	9.28	ns
Reset to Q (data out)	T_{RSTB2Q}	7.65	9	6.43	7.56	6.13	7.21	7.40	8.70	ns
Test data input setup time	T_{DISU}	–1.05	–0.89	–0.69	–0.59	–0.67	–0.57	–0.30	–0.25	ns
Test data input hold time	T_{DIHD}	2.38	2.8	2.38	2.8	2.42	2.85	2.09	2.45	ns
Test mode select setup time	T_{TMSSU}	–0.73	–0.62	–1.03	–1.21	–1.1	–0.94	0.28	0.33	ns
Test mode select hold time	T_{TMDHD}	1.36	1.6	1.43	1.68	1.93	2.27	0.16	0.19	ns
ResetB removal time	$T_{TRSTREM}$	–0.77	–0.65	–1.08	–0.92	–1.33	–1.13	–0.45	–0.38	ns
ResetB recovery time	$T_{TRSTREC}$	–0.76	–0.65	–1.07	–0.91	–1.34	–1.14	–0.45	–0.38	ns
TCK maximum frequency	F_{TCKMAX}	25	21.25	25	21.25	25	21.25	25.00	21.25	MHz

Table 285 • **JTAG 1532 for 060, 090, and 150 Devices**

		060		090		150		
Parameter	**Symbol**	**–1**	**–Std**	**–1**	**–Std**	**–1**	**–Std**	**Unit**
Clock to Q (data out)	T_{TCK2Q}	8.38	9.86	8.96	10.54	8.66	10.19	ns
Reset to Q (data out)	T_{RSTB2Q}	8.54	10.04	7.75	9.12	8.79	10.34	ns
Test data input setup time	T_{DISU}	–1.18	–1	–1.31	–1.11	–0.96	–0.82	ns
Test data input hold time	T_{DIHD}	2.52	2.97	2.68	3.15	2.57	3.02	ns
Test mode select setup time	T_{TMSSU}	–0.97	–0.83	–1.02	–0.87	–0.53	–0.45	ns
Test mode select hold time	T_{TMDHD}	1.7	2	1.67	1.96	1.02	1.2	ns
ResetB removal time	$T_{TRSTREM}$	–1.21	–1.03	–0.76	–0.65	–1.03	–0.88	ns
ResetB recovery time	$T_{TRSTREC}$	–1.21	–1.03	–0.77	–0.65	–1.03	–0.88	ns
TCK maximum frequency	F_{TCKMAX}	25	21.25	25	21.25	25	21.25	MHz

2.3.23 System Controller SPI Characteristics

2.3.24 Power-up to Functional Times

The following table lists the SmartFusion2 power-up to functional times in worst-case industrial conditions when T_J = 100 °C, V_{DD} = 1.14 V.

Table 288 • **Power-up to Functional Times for SmartFusion2**

				Maximum Power-up to Functional Time for SmartFusion2 (uS)						
Symbol	**From**	**To**	**Description**	**005**	**010**	**025**	**050**	**060**	**090**	**150**
$T_{POR2OUT}$	POWER_ON_RESET_N	Output available at I/O	Fabric to output	647	500	531	483	474	524	647
$T_{POR2MSSRST}$	POWER_ON_RESET_N	MSS_RESET_N_M2F	Fabric to MSS	644	497	528	480	468	518	641
$T_{MSSRST2OUT}$	MSS_RESET_N_M2F	Output available at I/O	MSS to output	3.6	3.6	3.6	3.4	4.9	4.8	4.8
$T_{VDD2OUT}$	V_{DD}	Output available at I/O	V_{DD} at its minimum threshold level to output	3096	2975	3012	2959	2869	2992	3225
$T_{VDD2POR}$	V_{DD}	POWER_ON_RESET_N	V_{DD} at its minimum threshold level to fabric	2476	2487	2496	2486	2406	2563	2602
$T_{VDD2MSSRST}$	V_{DD}	MSS_RESET_N_M2F	V_{DD} at its minimum threshold level to MSS	3093	2972	3008	2956	2864	2987	3220
$T_{VDD2WPU}$	DEVRST_N	DDRIO Inbuf weak pull	DEVRST_N to Inbuf weak pull	2500	2487	2509	2475	2507	2519	2617
	DEVRST_N	MSIO Inbuf weak pull	DEVRST_N to Inbuf weak pull	2504	2491	2510	2478	2517	2525	2620
	DEVRST_N	MSIOD Inbuf weak pull	DEVRST_N to Inbuf weak pull	2479	2468	2493	2458	2486	2499	2595

Note: For more information about power-up times, see *UG0331: SmartFusion2 Microcontroller Subsystem User Guide*.

Table 310 • **SPI Characteristics for All Devices *(continued)***

Symbol	Description	Min	Typ	Max	Unit	Conditions
SPI master configuration (applicable for 060, 090, and 150 devices)						
sp6m	SPI_[0|1]_DO setup time[2]	(SPI_x_CLK_period/2) – 7.0			ns	
sp7m	SPI_[0|1]_DO hold time[2]	(SPI_x_CLK_period/2) – 9.5			ns	
sp8m	SPI_[0|1]_DI setup time[2]	15			ns	
sp9m	SPI_[0|1]_DI hold time[2]	–2.5			ns	
SPI slave configuration (applicable for 060, 090, and 150 devices)						
sp6s	SPI_[0|1]_DO setup time[2]	(SPI_x_CLK_period/2) – 16.0			ns	
sp7s	SPI_[0|1]_DO hold time[2]	(SPI_x_CLK_period/2) - 3.5			ns	
sp8s	SPI_[0|1]_DI setup time[2]	3			ns	
sp9s	SPI_[0|1]_DI hold time[2]	2.5			ns	

1. For specific Rise/Fall Times board design considerations and detailed output buffer resistances, use the corresponding IBIS models located on the Microsemi SoC Products Group website: http://www.microsemi.com/soc/download/ibis/default.aspx.
2. For allowable pclk configurations, see the Serial Peripheral Interface Controller section in the *UG0331: SmartFusion2 Microcontroller Subsystem User Guide*.

Figure 23 • **SPI Timing for a Single Frame Transfer in Motorola Mode (SPH = 1)**