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Understanding Embedded - FPGAs (Field Programmable Gate Array)

Embedded - FPGAs, or Field Programmable Gate Arrays, are advanced integrated circuits that offer unparalleled flexibility and performance for digital systems. Unlike traditional fixed-function logic devices, FPGAs can be programmed and reprogrammed to execute a wide array of logical operations, enabling customized functionality tailored to specific applications. This reprogrammability allows developers to iterate designs quickly and implement complex functions without the need for custom hardware.

Applications of Embedded - FPGAs

The versatility of Embedded - FPGAs makes them indispensable in numerous fields. In telecommunications.

Details

Product Status	Active
Number of LABs/CLBs	-
Number of Logic Elements/Cells	86316
Total RAM Bits	2648064
Number of I/O	425
Number of Gates	-
Voltage - Supply	1.14V ~ 2.625V
Mounting Type	Surface Mount
Operating Temperature	0°C ~ 85°C (TJ)
Package / Case	676-BGA
Supplier Device Package	676-FBGA (27x27)
Purchase URL	https://www.e-xfl.com/product-detail/microchip-technology/m2gl090-1fgg676

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Power Supplies	Voltage (V)	005	010	025	050	060	090	150	Unit
V_{DD}	1.26	25	32	38	48	45	77	109	mA
V_{PP}	3.46	33	49	36	180	13	36	51	mA
V_{DDI}	2.62	134	141	161	187	93	272	388	mA
Number of banks		7	8	8	10	10	9	19	

2.3.3 Average Fabric Temperature and Voltage Derating Factors

The following table lists the average temperature and voltage derating factors for fabric timing delays normalized to $T_J = 85\text{ }^{\circ}\text{C}$, in worst-case $V_{DD} = 1.14\text{ V}$.

Table 16 • Average Junction Temperature and Voltage Derating Factors for Fabric Timing Delays

Array Voltage V_{DD} (V)	$-40\text{ }^{\circ}\text{C}$	$0\text{ }^{\circ}\text{C}$	$25\text{ }^{\circ}\text{C}$	$70\text{ }^{\circ}\text{C}$	$85\text{ }^{\circ}\text{C}$	$100\text{ }^{\circ}\text{C}$
1.14	0.83	0.89	0.92	0.98	1.00	1.02
1.2	0.75	0.80	0.83	0.89	0.91	0.93
1.26	0.69	0.73	0.76	0.81	0.83	0.85

Table 17 • Timing Model Parameters (continued)

Index	Symbol	Description	-1	Unit	For More Information
F	T_{DP}	Propagation delay of an OR gate	0.179	ns	See Table 223, page 76
G	T_{DP}	Propagation delay of an LVDS transmitter	2.136	ns	See Table 169, page 57
H	T_{DP}	Propagation delay of a three-input XOR Gate	0.241	ns	See Table 223, page 76
I	T_{DP}	Propagation delay of LVCMOS 2.5 V transmitter, drive strength of 16 mA on the MSIO bank	2.412	ns	See Table 46, page 27
J	T_{DP}	Propagation delay of a two-input NAND gate	0.179	ns	See Table 223, page 76
K	T_{DP}	Propagation delay of LVCMOS 2.5 V transmitter, drive strength of 8 mA on the MSIO bank	2.309	ns	See Table 46, page 27
L	T_{CLKQ}	Clock-to-Q of the data register	0.108	ns	See Table 224, page 77
	T_{SUD}	Setup time of the data register	0.254	ns	See Table 224, page 77
M	T_{DP}	Propagation delay of a two-input AND gate	0.179	ns	See Table 223, page 76
N	T_{OCLKQ}	Clock-to-Q of the output data register	0.263	ns	See Table 220, page 69
	T_{OSUD}	Setup time of the output data register	0.19	ns	See Table 220, page 69
O	T_{DP}	Propagation delay of SSTL2, Class I transmitter on the MSIO bank	2.055	ns	See Table 114, page 45
P	T_{DP}	Propagation delay of LVCMOS 1.5 V transmitter, drive strength of 12 mA, fast slew on the DDRIO bank	3.316	ns	See Table 70, page 34

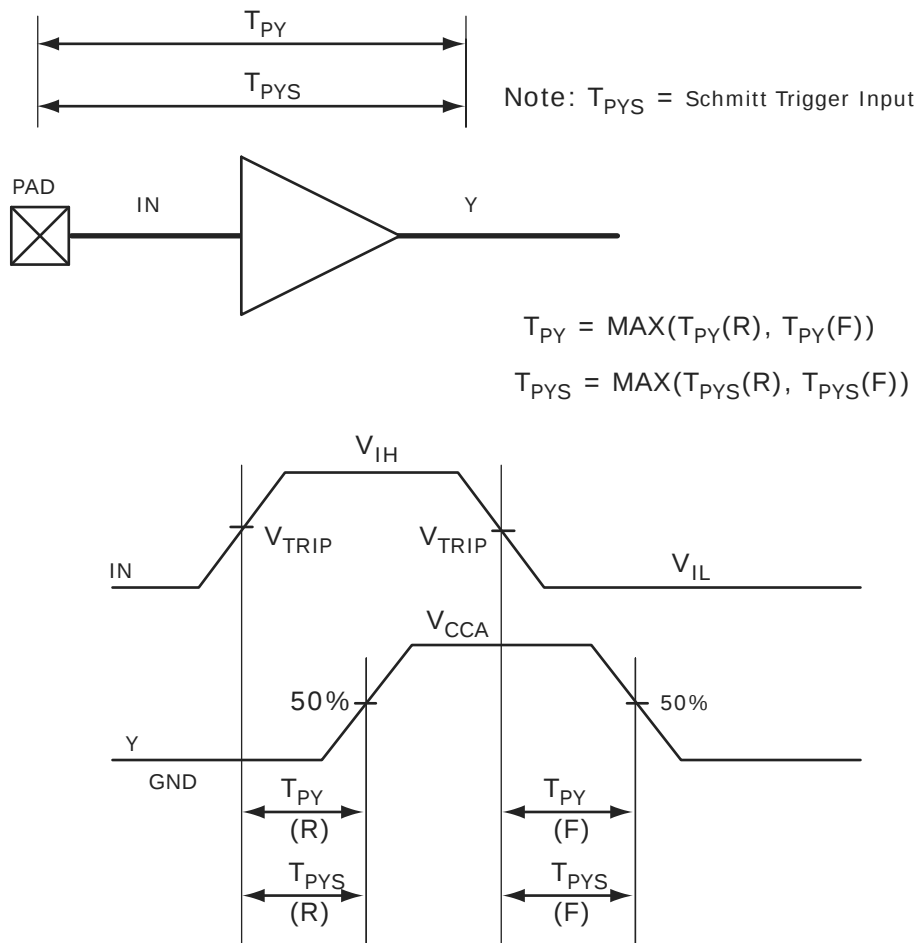
2.3.5 User I/O Characteristics

There are three types of I/Os supported in the IGLOO2 FPGA and SmartFusion2 SoC FPGA families: MSIO, MSIOD, and DDRIO I/O banks. The I/O standards supported by the different I/O banks is described in the I/Os section of the *UG0445: IGLOO2 FPGA and SmartFusion2 SoC FPGA Fabric User Guide*.

2.3.5.1 Input Buffer and AC Loading

The following figure shows the input buffer and AC loading.

Figure 3 • Input Buffer AC Loading



2.3.5.2 Output Buffer and AC Loading

The following figure shows the output buffer and AC loading.

Figure 4 • Output Buffer AC Loading

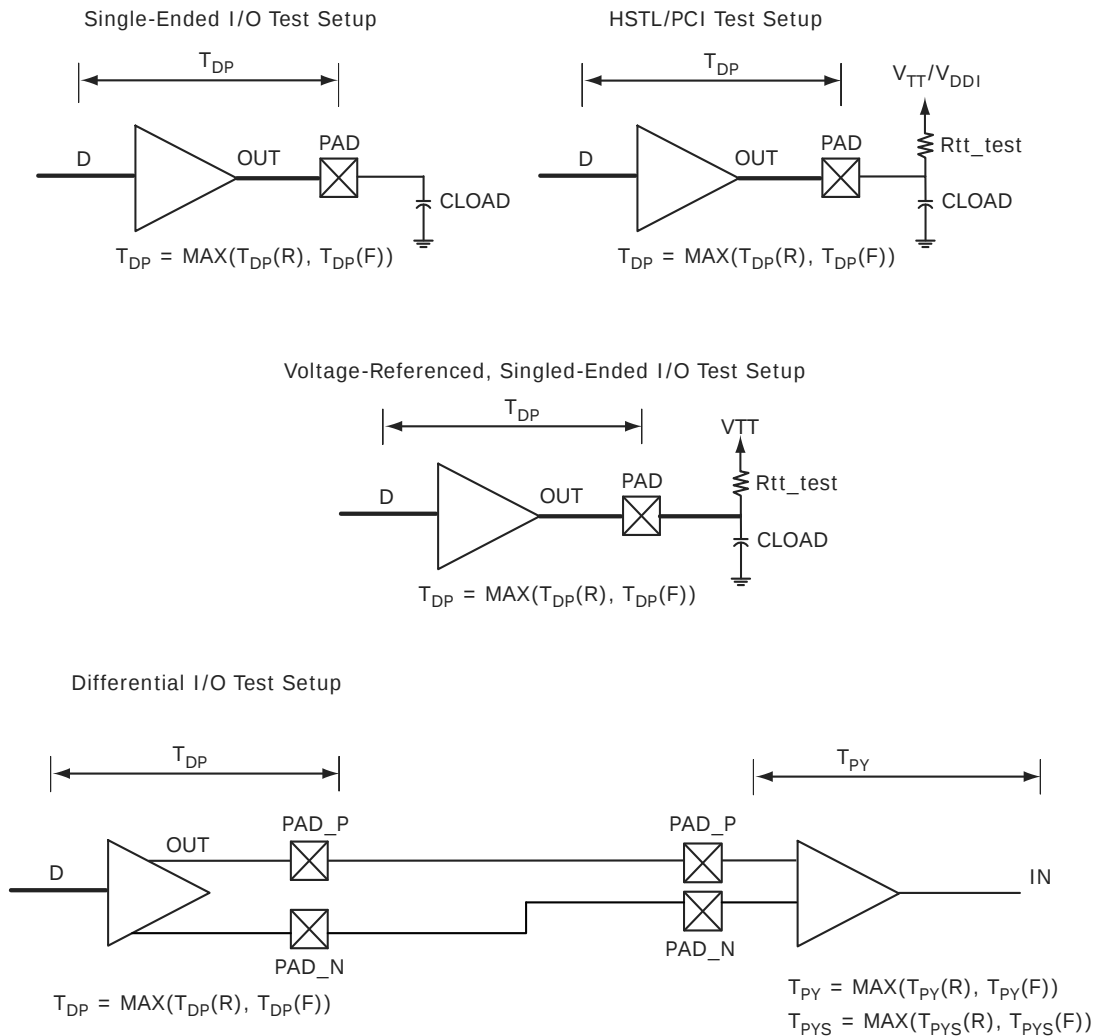


Table 53 • LVCMOS 1.8 V AC Calibrated Impedance Option

Parameter	Symbol	Typ	Unit
Supported output driver calibrated impedance (for DDRIO I/O bank)	R _{odt_cal}	75, 60, 50, 33, 25, 20	Ω

Table 54 • LVCMOS 1.8 V AC Test Parameter Specifications

Parameter	Symbol	Typ	Unit
Measuring/trip point for data path	V _{TRIP}	0.9	V
Resistance for enable path (T _{ZH} , T _{ZL} , T _{HZ} , T _{LZ})	R _{ENT}	2k	Ω
Capacitive loading for enable path (T _{ZH} , T _{ZL} , T _{HZ} , T _{LZ})	C _{ENT}	5	pF
Capacitive loading for data path (T _{DP})	C _{LOAD}	5	pF

Table 55 • LVCMOS 1.8 V Transmitter Drive Strength Specifications

Output Drive Selection			V _{OH} (V)	V _{OL} (V)	IOH (at V _{OH})	IOL (at V _{OL})
MSIO I/O Bank	MSIOD I/O Bank	DDRIO I/O Bank	Min	Max	mA	mA
2 mA	2 mA	2 mA	V _{DDI} – 0.45	0.45	2	2
4 mA	4 mA	4 mA	V _{DDI} – 0.45	0.45	4	4
6 mA	6 mA	6 mA	V _{DDI} – 0.45	0.45	6	6
8 mA	8 mA	8 mA	V _{DDI} – 0.45	0.45	8	8
10 mA	10 mA	10 mA	V _{DDI} – 0.45	0.45	10	10
12 mA		12 mA	V _{DDI} – 0.45	0.45	12	12
		16 mA ¹	V _{DDI} – 0.45	0.45	16	16

1. 16 mA drive strengths, all slews, meets LPDDR JEDEC electrical compliance.

AC Switching Characteristics

Worst commercial-case conditions: T_J = 85 °C, V_{DD} = 1.14 V, V_{DDI} = 1.71 V

Table 56 • LVCMOS 1.8 V Receiver Characteristics (Input Buffers)

	On-Die Termination (ODT)	T _{Py}		T _{PYS}		Unit
		–1	–Std	–1	–Std	
LVCMOS 1.8 V (for DDRIO I/O bank with Fixed Codes)	None	1.968	2.315	2.099	2.47	ns
	None	2.898	3.411	2.883	3.393	ns
	50	3.05	3.59	3.044	3.583	ns
	75	2.999	3.53	2.987	3.516	ns
LVCMOS 1.8 V (for MSIO I/O bank)	150	2.947	3.469	2.933	3.452	ns
	None	2.611	3.071	2.598	3.057	ns
	50	2.775	3.264	2.775	3.265	ns
	75	2.72	3.2	2.712	3.19	ns
LVCMOS 1.8 V (for MSIOD I/O bank)	150	2.666	3.137	2.655	3.123	ns

Table 82 • LVCMOS 1.2 V Receiver Characteristics for MSIOD I/O Bank (Input Buffers)

On-Die Termination (ODT)	T_{PY}		T_{PYS}		Unit
	-1	-Std	-1	-Std	
None	4.154	4.887	4.114	4.84	ns
50	6.918	8.139	6.806	8.008	ns
75	5.613	6.603	5.533	6.509	ns
150	4.716	5.549	4.657	5.479	ns

Table 83 • LVCMOS 1.2 V Transmitter Characteristics for DDRIO I/O Bank (Output and Tristate Buffers)

Output Drive Selection	Slew Control	T_{DP}		T_{ZL}		T_{ZH}		T_{HZ}^1		T_{LZ}^1		Unit
		-1	-Std	-1	-Std	-1	-Std	-1	-Std	-1	-Std	
2 mA	Slow	6.713	7.897	5.362	6.308	6.723	7.909	7.233	8.51	6.375	7.499	ns
	Medium	5.912	6.955	4.616	5.43	5.915	6.959	6.887	8.102	6.009	7.069	ns
	Medium fast	5.5	6.469	4.231	4.978	5.5	6.471	6.672	7.849	5.835	6.865	ns
	Fast	5.462	6.426	4.194	4.935	5.463	6.427	6.646	7.819	5.828	6.857	ns
4 mA	Slow	6.109	7.186	4.708	5.539	6.098	7.174	8.005	9.418	7.033	8.274	ns
	Medium	5.355	6.299	4.034	4.746	5.338	6.28	7.637	8.985	6.672	7.849	ns
	Medium fast	4.953	5.826	3.685	4.336	4.932	5.802	7.44	8.752	6.499	7.646	ns
	Fast	4.911	5.777	3.658	4.303	4.89	5.754	7.427	8.737	6.488	7.632	ns
6 mA	Slow	5.89	6.929	4.506	5.301	5.874	6.911	8.337	9.808	7.315	8.605	ns
	Medium	5.176	6.089	3.862	4.543	5.155	6.065	7.986	9.394	6.943	8.168	ns
	Medium fast	4.792	5.637	3.523	4.145	4.765	5.606	7.808	9.186	6.775	7.97	ns
	Fast	4.754	5.593	3.486	4.101	4.728	5.563	7.777	9.149	6.769	7.963	ns

1. Delay increases with drive strength are inherent to built-in slew control circuitry for simultaneous switching output (SSO) management.

Table 84 • LVCMOS 1.2 V Transmitter Characteristics for MSIO I/O Bank (Output and Tristate Buffers)

Output Drive Selection	Slew Control	T_{DP}		T_{ZL}		T_{ZH}		T_{HZ}^1		T_{LZ}^1		Unit
		-1	-Std	-1	-Std	-1	-Std	-1	-Std	-1	-Std	
2 mA	Slow	6.746	7.937	7.458	8.774	8.172	9.614	9.867	11.608	8.393	9.874	ns
4 mA	Slow	7.068	8.315	6.678	7.857	7.474	8.793	10.986	12.924	9.043	10.638	ns

1. Delay increases with drive strength are inherent to built-in slew control circuitry for simultaneous switching output (SSO) management.

AC Switching Characteristics

Worst commercial-case conditions: $T_J = 85\text{ }^{\circ}\text{C}$, $V_{DD} = 1.14\text{ V}$, $V_{DDI} = 3.0\text{ V}$

Table 91 • PCI/PCIX AC Switching Characteristics for Receiver for MSIO I/O Bank (Input Buffers)

On-Die Termination (ODT)	T_{PY}		T_{PYS}		Unit
	-1	-Std	-1	-Std	
None	2.229	2.623	2.238	2.633	ns

Table 92 • PCI/PCIX AC switching Characteristics for Transmitter for MSIO I/O Bank (Output and Tristate Buffers)

T_{DP}		T_{ZL}		T_{ZH}		T_{HZ}		T_{LZ}		Unit
-1	-Std	-1	-Std	-1	-Std	-1	-Std	-1	-Std	
2.146	2.525	2.043	2.404	2.084	2.452	6.095	7.171	5.558	6.539	ns

2.3.6 Memory Interface and Voltage Referenced I/O Standards

This section describes High-Speed Transceiver Logic (HSTL) memory interface and voltage reference I/O standards.

2.3.6.1 High-Speed Transceiver Logic (HSTL)

The HSTL standard is a general purpose high-speed bus standard sponsored by IBM (EIA/JESD8-6). IGLOO2 FPGA and SmartFusion2 SoC FPGA devices support two classes of the 1.5 V HSTL. These differential versions of the standard require a differential amplifier input buffer and a push-pull output buffer.

Minimum and Maximum DC/AC Input and Output Levels Specification (Applicable to DDRIO Bank Only)

Table 93 • HSTL Recommended DC Operating Conditions

Parameter	Symbol	Min	Typ	Max	Unit
Supply voltage	V_{DDI}	1.425	1.5	1.575	V
Termination voltage	V_{TT}	0.698	0.750	0.803	V
Input reference voltage	V_{REF}	0.698	0.750	0.803	V

Table 94 • HSTL DC Input Voltage Specification

Parameter	Symbol	Min	Max	Unit
DC input logic high	$V_{IH}(\text{DC})$	$V_{REF} + 0.1$	1.575	V
DC input logic low	$V_{IL}(\text{DC})$	-0.3	$V_{REF} - 0.1$	V
Input current high ¹	$I_{IH}(\text{DC})$			
Input current low ¹	$I_{IL}(\text{DC})$			

1. See Table 24, page 22.

Table 128 • DDR2/SSTL18 Transmitter Characteristics (Output and Tristate Buffers)

	T _{DP}		T _{ZL}		T _{ZH}		T _{HZ}		T _{LZ}		Unit
	−1	−Std	−1	−Std	−1	−Std	−1	−Std	−1	−Std	
SSTL18 Class I (for DDRIO I/O Bank)											
Single-ended	2.383	2.804	2.23	2.623	2.229	2.622	2.202	2.591	2.201	2.59	ns
Differential	2.413	2.84	2.797	3.29	2.797	3.29	2.282	2.685	2.282	2.685	ns
SSTL18 Class II (for DDRIO I/O Bank)											
Single-ended	2.281	2.683	2.196	2.584	2.195	2.583	2.171	2.555	2.17	2.554	ns
Differential	2.315	2.724	2.698	3.173	2.698	3.173	2.242	2.639	2.242	2.639	ns

2.3.6.5 Stub-Series Terminated Logic 1.5 V (SSTL15)

SSTL15 Class I and Class II are supported in IGLOO2 FPGAs and SmartFusion2 SoC FPGAs, and also comply with the reduced and full drive double data rate (DDR3) standard. IGLOO2 FPGA and SmartFusion2 SoC FPGA I/Os supports both standards for single-ended signaling and differential signaling for SSTL18. This standard requires a differential amplifier input buffer and a push-pull output buffer.

Minimum and Maximum DC/AC Input and Output Levels Specification

The following table lists the SSTL15 DC voltage specifications for DDRIO bank.

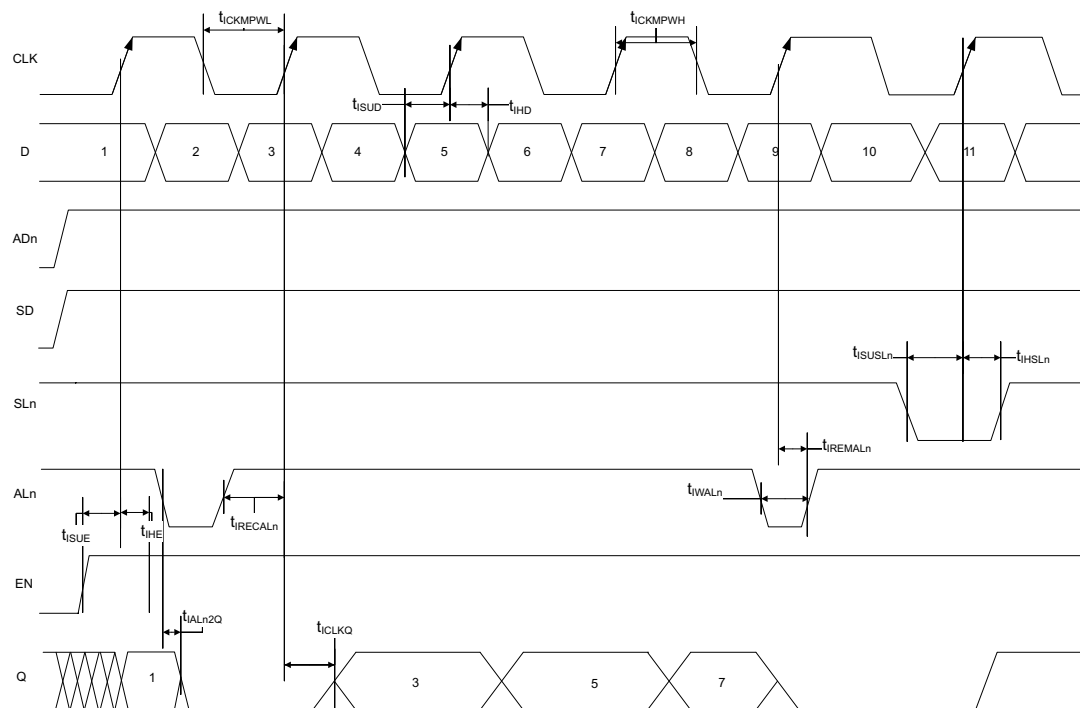
Table 129 • SSTL15 DC Recommended DC Operating Conditions (for DDRIO I/O Bank Only)

Parameter	Symbol	Min	Typ	Max	Unit
Supply voltage	V_{DDI}	1.425	1.5	1.575	V
Termination voltage	V_{TT}	0.698	0.750	0.803	V
Input reference voltage	V_{REF}	0.698	0.750	0.803	V

Table 130 • SSTL15 DC Input Voltage Specification (for DDRIO I/O Bank Only)

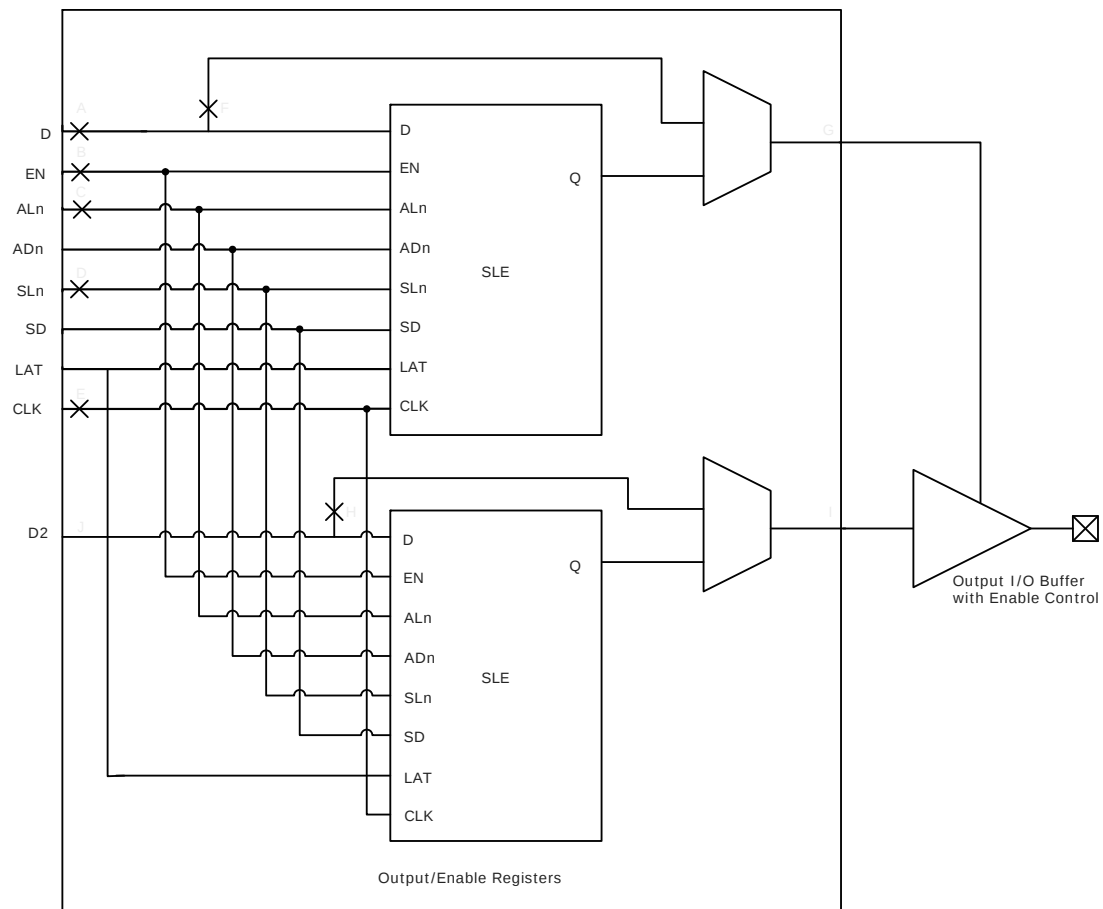
Parameter	Symbol	Min	Max	Unit
DC input logic high	$V_{IH}(DC)$	$V_{REF} + 0.1$	1.575	V
DC input logic low	$V_{IL}(DC)$	-0.3	$V_{REF} - 0.1$	V
Input current high ¹	$I_{IH}(DC)$			
Input current low ¹	$I_{IL}(DC)$			

1. See Table 24, page 22.

Figure 7 • I/O Register Input Timing Diagram

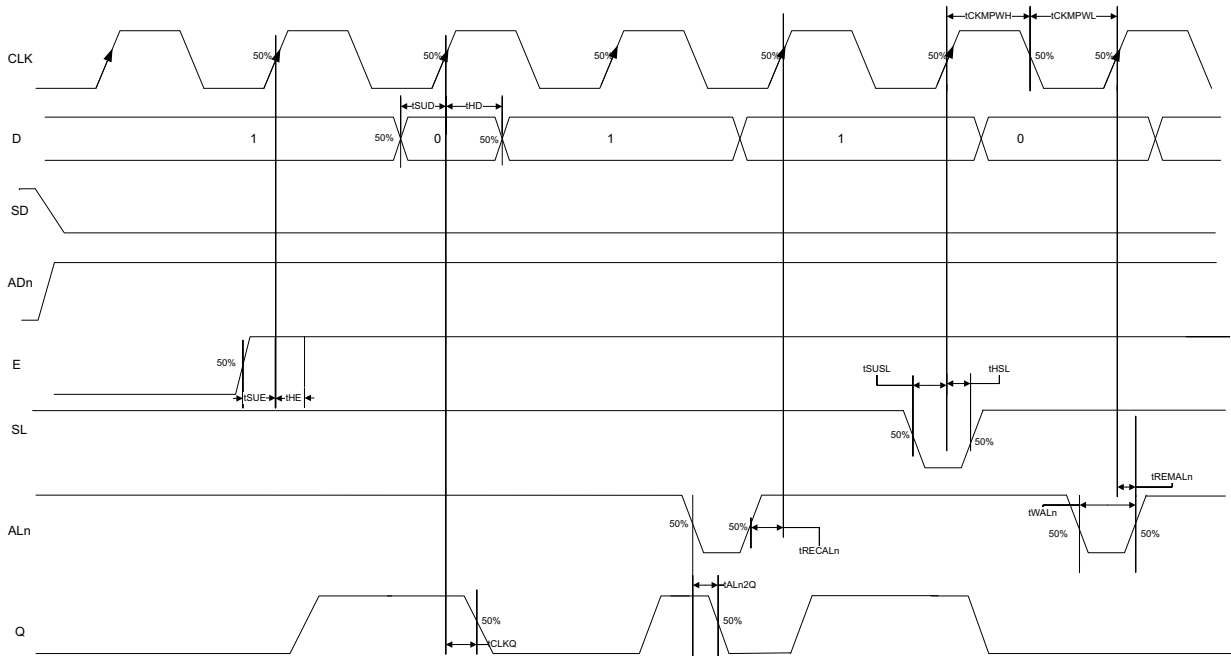
2.3.8.2 Output/Enable Register

Figure 8 • Timing Model for Output/Enable Register



The following figure shows a configuration with SD = 0 (synchronous clear) and ADn = 1 (asynchronous clear) for a flip-flop (LAT = 0).

Figure 16 • Sequential Module Timing Diagram



2.3.10.3.1 Timing Characteristics

The following table lists the register delays in worst commercial-case conditions when $T_J = 85^\circ\text{C}$, $V_{DD} = 1.14\text{ V}$.

Table 224 • Register Delays

Parameter	Symbol	-1	-Std	Unit
Clock-to-Q of the core register	T_{CLKQ}	0.108	0.127	ns
Data setup time for the core register	T_{SUD}	0.254	0.298	ns
Data hold time for the core register	T_{HD}	0	0	ns
Enable setup time for the core register	T_{SUE}	0.335	0.394	ns
Enable hold time for the core register	T_{HE}	0	0	ns
Synchronous load setup time for the core register	T_{SUSL}	0.335	0.394	ns
Synchronous load hold time for the core register	T_{HSL}	0	0	ns
Asynchronous Clear-to-Q of the core register (ADn = 1)	T_{ALN2Q}	0.473	0.556	ns
Asynchronous preset-to-Q of the core register (ADn = 0)		0.451	0.531	ns
Asynchronous load removal time for the core register	T_{RECALN}	0	0	ns
Asynchronous load recovery time for the core register	T_{RECALN}	0.353	0.415	ns
Asynchronous load minimum pulse width for the core register	T_{WALN}	0.266	0.313	ns
Clock minimum pulse width high for the core register	T_{CKMPWH}	0.065	0.077	ns
Clock minimum pulse width low for the core register	T_{CKMPWL}	0.139	0.164	ns

Table 248 • 2 Step IAP Programming (eNVM Only)

M2S/M2GL Device	Image size Bytes	Authenticate	Program	Verify	Unit
005	137536	2	37	5	Sec
010	274816	4	76	11	Sec
025	274816	4	78	10	Sec
050	278528	3	85	9	Sec
060	268480	5	76	22	Sec
090	544496	10	152	43	Sec
150	544496	10	153	44	Sec

Table 249 • 2 Step IAP Programming (Fabric and eNVM)

M2S/M2GL Device	Image size Bytes	Authenticate	Program	Verify	Unit
005	439296	6	56	11	Sec
010	842688	11	100	21	Sec
025	1497408	19	113	32	Sec
050	2695168	32	136	48	Sec
060	2686464	43	137	70	Sec
090	4190208	68	236	115	Sec
150	6682768	109	286	162	Sec

Table 250 • SmartFusion2 Cortex-M3 ISP Programming (Fabric Only)

M2S/M2GL Device	Image size Bytes	Authenticate	Program	Verify	Unit
005	302672	6	19	8	Sec
010	568784	10	26	14	Sec
025	1223504	21	39	29	Sec
050	2424832	39	60	50	Sec
060	2418896	44	65	54	Sec
090	3645968	66	90	79	Sec
150	6139184	108	140	128	Sec

Table 251 • SmartFusion2 Cortex-M3 ISP Programming (eNVM Only)

M2S/M2GL Device	Image size Bytes	Authenticate	Program	Verify	Unit
005	137536	3	42	4	Sec
010	274816	4	82	7	Sec
025	274816	4	82	8	Sec
050	278528	4	80	8	Sec
060	268480	6	80	8	Sec
090	544496	10	157	15	Sec

Table 251 • SmartFusion2 Cortex-M3 ISP Programming (eNVM Only) (continued)

M2S/M2GL Device	Image size Bytes	Authenticate	Program	Verify	Unit
150	544496	10	158	15	Sec

Table 252 • SmartFusion2 Cortex-M3 ISP Programming (Fabric and eNVM)

M2S/M2GL Device	Image size Bytes	Authenticate	Program	Verify	Unit
005	439296	9	61	11	Sec
010	842688	15	107	21	Sec
025	1497408	26	121	35	Sec
050	2695168	43	141	55	Sec
060	2686464	48	143	60	Sec
090	4190208	75	244	91	Sec
150	6682768	117	296	141	Sec

Table 253 • Programming Times with 100 kHz, 25 MHz, and 12.5 MHz SPI Clock Rates (Fabric Only)

M2S/M2GL Device	Auto Programming	Auto Update	Programming Recovery	Unit
	100 kHz	25 MHz	12.5 MHz	
005	47	27	28	Sec
010	77	35	35	Sec
025	150	42	41	Sec
050	33 ¹	Not Supported	Not Supported	Sec
060	291	83	82	Sec
090	427	109	108	Sec
150	708	157	160	Sec

1. Auto Programming in 050 device is done through SC_SPI, and SPI CLK is set to 6.25 MHz.

Table 254 • Programming Times with 100 kHz, 25 MHz, and 12.5 MHz SPI Clock Rates (eNVM Only)

M2S/M2GL Device	Auto Programming	Auto Update	Programming Recovery	Unit
	100 kHz	25 MHz	12.5 MHz	
005	41	48	49	Sec
010	86	87	87	Sec
025	87	85	86	Sec
050	85	Not Supported	Not Supported	Sec
060	78	86	86	Sec
090	154	162	162	Sec

2.3.14 Math Block Timing Characteristics

The fundamental building block in any digital signal processing algorithm is the multiply-accumulate function. Each IGLOO2 and SmartFusion2 SoC math block supports 18×18 signed multiplication, dot product, and built-in addition, subtraction, and accumulation units to combine multiplication results efficiently. The following table lists the math blocks with all registers used in worst commercial-case conditions when $T_J = 85^\circ\text{C}$, $V_{DD} = 1.14\text{ V}$.

Table 268 • Math Blocks with all Registers Used

Parameter	Symbol	–1		–Std		Unit
		Min	Max	Min	Max	
Input, control register setup time	T_{MISU}	0.149		0.176		ns
Input, control register hold time	T_{MIHD}	1.68		1.976		ns
CDIN input setup time	$T_{MOCDINSU}$	0.185		0.218		ns
CDIN input hold time	$T_{MOCDINHHD}$	0.08		0.094		ns
Synchronous reset/enable setup time	$T_{MSRSTENSU}$	–0.419		–0.493		ns
Synchronous reset/enable hold time	$T_{MSRSTENHD}$	0.011		0.013		ns
Asynchronous reset removal time	$T_{MARSTREM}$	0		0		ns
Asynchronous reset recovery time	$T_{MARSTREC}$	0.088		0.104		ns
Output register clock to out delay	T_{MOCQ}		0.232		0.273	ns
CLK minimum period	T_{MCLKMP}	2.245		2.641		ns

The following table lists the math blocks with input bypassed and output registers used in worst commercial-case conditions when $T_J = 85^\circ\text{C}$, $V_{DD} = 1.14\text{ V}$.

Table 269 • Math Block with Input Bypassed and Output Registers Used

Parameter	Symbol	–1		–Std		Unit
		Min	Max	Min	Max	
Output register setup time	T_{MOSU}	2.294		2.699		ns
Output register hold time	T_{MOHD}	1.68		1.976		ns
CDIN input setup time	$T_{MOCDINSU}$	0.115		0.136		ns
CDIN input hold time	$T_{MOCDINHHD}$	–0.444		–0.522		ns
Synchronous reset/enable setup time	$T_{MSRSTENSU}$	–0.419		–0.493		ns
Synchronous reset/enable hold time	$T_{MSRSTENHD}$	0.011		0.013		ns
Asynchronous reset removal time	$T_{MARSTREM}$	0		0		ns
Asynchronous reset recovery time	$T_{MARSTREC}$	0.014		0.017		ns
Output register clock to out delay	T_{MOCQ}		0.232		0.273	ns
CLK minimum period	T_{MCLKMP}	2.179		2.563		ns

The following table lists the math blocks with input register used and output in bypass mode in worst commercial-case conditions when $T_J = 85\text{ }^{\circ}\text{C}$, $V_{DD} = 1.14\text{ V}$.

Table 270 • Math Block with Input Register Used and Output in Bypass Mode

Parameter	Symbol	–1		–Std		Unit
		Min	Max	Min	Max	
Input register setup time	T_{MISU}	0.149		0.176		ns
Input register hold time	T_{MIHD}	0.185		0.218		ns
Synchronous reset/enable setup time	$T_{MSRSTENSU}$	0.08		0.094		ns
Synchronous reset/enable hold time	$T_{MSRSTENHD}$	–0.012		–0.014		ns
Asynchronous reset removal time	$T_{MARSTREM}$	–0.005		–0.005		ns
Asynchronous reset recovery time	$T_{MARSTREC}$	0.088		0.104		ns
Input register clock to output delay	T_{MICQ}		2.52		2.964	ns
CDIN to output delay	$T_{MCDIN2Q}$		1.951		2.295	ns

The following table lists the math blocks with input and output in bypass mode in worst commercial-case conditions when $T_J = 85\text{ }^{\circ}\text{C}$, $V_{DD} = 1.14\text{ V}$.

Table 271 • Math Block with Input and Output in Bypass Mode

Parameter	Symbol	–1	–Std	Unit
		Max	Max	
Input to output delay	T_{MIQ}	2.568	3.022	ns
CDIN to output delay	$T_{MCDIN2Q}$	1.951	2.295	ns

2.3.15 Embedded NVM (eNVM) Characteristics

The following table lists the eNVM read performance in worst-case conditions when $V_{DD} = 1.14\text{ V}$, $V_{PPNVM} = V_{PP} = 2.375\text{ V}$.

Table 272 • eNVM Read Performance

Symbol	Description	Operating Temperature Range						Unit
		–1	–Std	–1	–Std	–1	–Std	
T_J	Junction temperature range	–55 °C to 125 °C		–40 °C to 100 °C		0 °C to 85 °C		°C
$F_{MAXREAD}$	eNVM maximum read frequency	25	25	25	25	25	25	MHz

The following table lists the eNVM page programming in worst-case conditions when $V_{DD} = 1.14\text{ V}$, $V_{PPNVM} = V_{PP} = 2.375\text{ V}$.

Table 273 • eNVM Page Programming

Symbol	Description	Operating Temperature Range						Unit
		–1	–Std	–1	–Std	–1	–Std	
T_J	Junction temperature range	–55 °C to 125 °C		–40 °C to 100 °C		0 °C to 85 °C		°C
$T_{PAGEPGM}$	eNVM page programming time	40	40	40	40	40	40	ms

Table 277 • Electrical Characteristics of the Crystal Oscillator – High Gain Mode (20 MHz) (continued)

Parameter	Symbol	Min	Typ	Max	Unit	Condition
Startup time (with regard to stable oscillator output)	SUXTAL			0.8	ms	005, 010, 025, and 050 devices
				1.0	ms	090 and 150 devices

Table 278 • Electrical Characteristics of the Crystal Oscillator – Medium Gain Mode (2 MHz)

Parameter	Symbol	Min	Typ	Max	Unit	Condition
Operating frequency	FXTAL		2		MHz	
Accuracy	ACCXTAL			0.00105	%	050 devices
				0.003	%	005, 010, 025, 090, and 150 devices
				0.004	%	060 devices
Output duty cycle	CYCXTAL		49–51	47–53	%	
Output period jitter (peak to peak)	JITPERXTAL		1	5	ns	
Output cycle to cycle jitter (peak to peak)	JITCYCXTAL		1	5	ns	
Operating current	IDYNXTAL		0.3		mA	
Input logic level high	VIHXTAL	0.9 V _{PP}			V	
Input logic level low	VILXTAL			0.1 V _{PP}	V	
Startup time (with regard to stable oscillator output)	SUXTAL			4.5	ms	010 and 050 devices
				5	ms	005 and 025 devices
				7	ms	090 and 150 devices

Table 279 • Electrical Characteristics of the Crystal Oscillator – Low Gain Mode (32 kHz)

Parameter	Symbol	Min	Typ	Max	Unit	Condition
Operating frequency	FXTAL		32		kHz	
Accuracy	ACCXTAL			0.004	%	005, 010, 025, 050, 060, and 090 devices
				0.005	%	150 devices
Output duty cycle	CYCXTAL		49–51	47–53	%	
Output period jitter (peak to peak)	JITPERXTAL		150	300	ns	
Output cycle to cycle jitter (peak to peak)	JITCYCXTAL		150	300	ns	
Operating current	IDYNXTAL		0.044		mA	010 and 050 devices
			0.060		mA	005, 025, 060, 090, and 150 devices
Input logic level high	VIHXTAL	0.9 V _{PP}			V	
Input logic level low	VILXTAL			0.1 V _{PP}	V	
Startup time (with regard to stable oscillator output)	SUXTAL			115	ms	005, 025, 050, 090, and 150 devices
				126	ms	010 devices

2.3.22 JTAG

Table 284 • JTAG 1532 for 005, 010, 025, and 050 Devices

Parameter	Symbol	005		010		025		050		Unit
		–1	–Std	–1	–Std	–1	–Std	–1	–Std	
Clock to Q (data out)	T_{TCK2Q}	7.47	8.79	7.73	9.09	7.75	9.12	7.89	9.28	ns
Reset to Q (data out)	T_{RSTB2Q}	7.65	9	6.43	7.56	6.13	7.21	7.40	8.70	ns
Test data input setup time	T_{DISU}	–1.05	–0.89	–0.69	–0.59	–0.67	–0.57	–0.30	–0.25	ns
Test data input hold time	T_{DIHD}	2.38	2.8	2.38	2.8	2.42	2.85	2.09	2.45	ns
Test mode select setup time	T_{TMSSU}	–0.73	–0.62	–1.03	–1.21	–1.1	–0.94	0.28	0.33	ns
Test mode select hold time	T_{TMDHD}	1.36	1.6	1.43	1.68	1.93	2.27	0.16	0.19	ns
ResetB removal time	$T_{TRSTREM}$	–0.77	–0.65	–1.08	–0.92	–1.33	–1.13	–0.45	–0.38	ns
ResetB recovery time	$T_{TRSTREC}$	–0.76	–0.65	–1.07	–0.91	–1.34	–1.14	–0.45	–0.38	ns
TCK maximum frequency	F_{TCKMAX}	25	21.25	25	21.25	25	21.25	25.00	21.25	MHz

Table 285 • JTAG 1532 for 060, 090, and 150 Devices

Parameter	Symbol	060		090		150		Unit
		–1	–Std	–1	–Std	–1	–Std	
Clock to Q (data out)	T_{TCK2Q}	8.38	9.86	8.96	10.54	8.66	10.19	ns
Reset to Q (data out)	T_{RSTB2Q}	8.54	10.04	7.75	9.12	8.79	10.34	ns
Test data input setup time	T_{DISU}	–1.18	–1	–1.31	–1.11	–0.96	–0.82	ns
Test data input hold time	T_{DIHD}	2.52	2.97	2.68	3.15	2.57	3.02	ns
Test mode select setup time	T_{TMSSU}	–0.97	–0.83	–1.02	–0.87	–0.53	–0.45	ns
Test mode select hold time	T_{TMDHD}	1.7	2	1.67	1.96	1.02	1.2	ns
ResetB removal time	$T_{TRSTREM}$	–1.21	–1.03	–0.76	–0.65	–1.03	–0.88	ns
ResetB recovery time	$T_{TRSTREC}$	–1.21	–1.03	–0.77	–0.65	–1.03	–0.88	ns
TCK maximum frequency	F_{TCKMAX}	25	21.25	25	21.25	25	21.25	MHz

2.3.23 System Controller SPI Characteristics

2.3.24 Power-up to Functional Times

The following table lists the SmartFusion2 power-up to functional times in worst-case industrial conditions when $T_J = 100\text{ }^{\circ}\text{C}$, $V_{DD} = 1.14\text{ V}$.

Table 288 • Power-up to Functional Times for SmartFusion2

Symbol	From	To	Description	Maximum Power-up to Functional Time for SmartFusion2 (uS)						
				005	010	025	050	060	090	150
$T_{POR2OUT}$	POWER_ON_RESET_N	Output available at I/O	Fabric to output	647	500	531	483	474	524	647
$T_{POR2MSSRST}$	POWER_ON_RESET_N	MSS_RESE T_N_M2F	Fabric to MSS	644	497	528	480	468	518	641
$T_{MSSRST2OUT}$	MSS_RESET_N_M2F	Output available at I/O	MSS to output	3.6	3.6	3.6	3.4	4.9	4.8	4.8
$T_{VDD2OUT}$	V_{DD}	Output available at I/O	V_{DD} at its minimum threshold level to output	3096	2975	3012	2959	2869	2992	3225
$T_{VDD2POR}$	V_{DD}	POWER_ON_RESET_N	V_{DD} at its minimum threshold level to fabric	2476	2487	2496	2486	2406	2563	2602
$T_{VDD2MSSRST}$	V_{DD}	MSS_RESE T_N_M2F	V_{DD} at its minimum threshold level to MSS	3093	2972	3008	2956	2864	2987	3220
$T_{VDD2WPU}$	DEV_RST_N	DDRIO Inbuf weak pull	DEV_RST_N to Inbuf weak pull	2500	2487	2509	2475	2507	2519	2617
	DEV_RST_N	MSIO Inbuf weak pull	DEV_RST_N to Inbuf weak pull	2504	2491	2510	2478	2517	2525	2620
	DEV_RST_N	MSIOD Inbuf weak pull	DEV_RST_N to Inbuf weak pull	2479	2468	2493	2458	2486	2499	2595

Note: For more information about power-up times, see *UG0331: SmartFusion2 Microcontroller Subsystem User Guide*.

Table 305 • SPI Characteristics for All Devices (continued)

Symbol	Description	Min	Typ	Max	Unit	Conditions
sp5	SPI_[0 1]_CLK, SPI_[0 1]_DO, SPI_[0 1]_SS fall time (10%– 90%) ¹		2.906		ns	IO Configuration: LVCMOS 2.5 V-8 mA AC Loading: 35 pF Test Conditions: Typical Voltage, 25 °C
SPI master configuration (applicable for 005, 010, 025, and 050 devices)						
sp6m	SPI_[0 1]_DO setup time ²	(SPI_x_CLK_period/2) – 8.0			ns	
sp7m	SPI_[0 1]_DO hold time ²	(SPI_x_CLK_period/2) – 2.5			ns	
sp8m	SPI_[0 1]_DI setup time ²	12			ns	
sp9m	SPI_[0 1]_DI hold time ²	2.5			ns	
SPI slave configuration (applicable for 005, 010, 025, and 050 devices)						
sp6s	SPI_[0 1]_DO setup time ²	(SPI_x_CLK_period/2) – 17.0			ns	
sp7s	SPI_[0 1]_DO hold time ²	(SPI_x_CLK_period/2) + 3.0			ns	
sp8s	SPI_[0 1]_DI setup time ²	2			ns	
sp9s	SPI_[0 1]_DI hold time ²	7			ns	
SPI master configuration (applicable for 060, 090, and 150 devices)						
sp6m	SPI_[0 1]_DO setup time ²	(SPI_x_CLK_period/2) – 7.0			ns	
sp7m	SPI_[0 1]_DO hold time ²	(SPI_x_CLK_period/2) – 9.5			ns	
sp8m	SPI_[0 1]_DI setup time ²	15			ns	
sp9m	SPI_[0 1]_DI hold time ²	–2.5			ns	
SPI slave configuration (applicable for 060, 090, and 150 devices)						
sp6s	SPI_[0 1]_DO setup time ²	(SPI_x_CLK_period/2) – 16.0			ns	
sp7s	SPI_[0 1]_DO hold time ²	(SPI_x_CLK_period/2) – 3.5			ns	
sp8s	SPI_[0 1]_DI setup time ²	3			ns	
sp9s	SPI_[0 1]_DI hold time ²	2.5			ns	

1. For specific Rise/Fall Times board design considerations and detailed output buffer resistances, use the corresponding IBIS models located on the Microsemi SoC Products Group website: <http://www.microsemi.com/soc/download/ibis/default.aspx>.
2. For allowable pclk configurations, see Serial Peripheral Interface Controller section in the *UG0331: SmartFusion2 Microcontroller Subsystem User Guide*.