Microchip Technology - M2GL090T-FGG484 Datasheet

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Understanding Embedded - FPGAs (Field Programmable Gate Array)

Embedded - FPGAs, or Field Programmable Gate Arrays, are advanced integrated circuits that offer unparalleled flexibility and performance for digital systems. Unlike traditional fixed-function logic devices, FPGAs can be programmed and reprogrammed to execute a wide array of logical operations, enabling customized functionality tailored to specific applications. This reprogrammability allows developers to iterate designs quickly and implement complex functions without the need for custom hardware.

Applications of Embedded - FPGAs

The versatility of Embedded - FPGAs makes them indispensable in numerous fields. In telecommunications,

Details	
Product Status	Active
Number of LABs/CLBs	-
Number of Logic Elements/Cells	86316
Total RAM Bits	2648064
Number of I/O	267
Number of Gates	-
Voltage - Supply	1.14V ~ 2.625V
Mounting Type	Surface Mount
Operating Temperature	0°C ~ 85°C (TJ)
Package / Case	484-BGA
Supplier Device Package	484-FPBGA (23x23)
Purchase URL	https://www.e-xfl.com/product-detail/microchip-technology/m2gl090t-fgg484

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1 Revision History

The revision history describes the changes that were implemented in the document. The changes are listed by revision, starting with the most current publication.

1.1 Revision 11.0

The following is a summary of the changes in revision 11.0 of this document.

- Updated Table 24, page 22 with minimum and maximum values for input current low and high (SAR 73114 and 80314).
- Added Non-Deterministic Random Bit Generator (NRBG) Characteristics, page 106 (SAR 73114 and 79517).
- Added 060 device in Table 282, page 110 (SAR 79860).
- Added DEVRST_N to Functional Times, page 116 (SAR 73114).
- Added Cryptographic Block Characteristics, page 106 (SAR 73114 and 79516).
- Update Table 296, page 121 with VTX-AMP details (SAR 81756).
- Update note in Table 297, page 122 (SAR 74570 and 80677).
- Update Table 298, page 122 with generic EPCS details (SAR 75307).
- Added Table 308, page 129 (SAR 50424).

1.2 Revision 10.0

The following is a summary of the changes in revision 10.0 of this document.

- The Surge Current on VDD during DEVRST_B Assertion and Surge Current on VDD during Digest Check using System Services tables were deleted and added reference to *AC393: Board Design Guidelines for SmartFusion2 SoC and IGLOO2 FPGAs Application Note*. (SAR 76865 and 76623).
- Added 060 device in Table 4, page 6 (SAR 76383).
- Updated Table 24, page 22 for ramp time input (SAR 72103).
- Added 060 device details in Table 284, page 112 (SAR 74927).
- Updated Table 290, page 116 for name change (SAR 74925).
- Updated Table 283, page 111 for 060 FG676 Package details (SAR 78849).
- Updated Table 305, page 126 for SmartFusion2 and Table 310, page 129 for IGLOO2 for SPI timing and Fmax (SAR 56645, 75331).
- Updated Table 293, page 119 for Flash*Freeze entry and exit times (SAR 75329, 75330).
- Updated Table 297, page 122 for RX-CID information (SAR 78271).
- Added Table 8, page 8 and Figure 1, page 9 (SAR 78932).
- Updated Table 223, page 76 for timing characteristics and Table 224, page 77(SAR 75998).
- Added SRAM PUF, page 105 (SAR 64406).
- Added a footnote on digest cycle in Table 5, page 7 (SAR 79812).

1.3 Revision 9.0

The following is a summary of the changes in revision 9.0 of this document.

- Added a note in Table 5, page 7 (SAR 71506).
- Added a note in Table 6, page 8 (SAR 74616).
- Added a note in Figure 3, page 17 (SAR 71506).
- Updated Quiescent Supply Current for 060 in Table 11, page 12 and Table 12, page 13 (SAR 74483).
- Updated programming currents for 060 in Table 13, page 13, Table 14, page 13, and Table 15, page 14.
- Added DEVRST_B assertion tables (SAR 74708).
- Updated I/O speeds for LVDS 3.3 V in Table 18, page 19 and Table 21, page 20 (SAR 69829).
- Updated Table 24, page 22 (SAR 69418).
- Updated Table 25, page 22, Table 26, page 23, Table 27, page 23 (SAR 74570).
- Updated all AC/DC table to link to the Input Capacitance, Leakage Current, and Ramp Time, page 22 for reference (SAR 69418).

Table 15 • **Inrush Currents at Power up, –40 °C <= T_J <= 100 °C – Typical Process**

Power Supplies	Voltage (V)	005	010	025	050	060	090	150	Unit
V_{DD}	1.26	25	32	38	48	45	77	109	mA
V_{PP}	3.46	33	49	36	180	13	36	51	mA
V_{DDI}	2.62	134	141	161	187	93	272	388	mA
Number of banks		7	8	8	10	10	9	19	

2.3.3 Average Fabric Temperature and Voltage Derating Factors

The following table lists the average temperature and voltage derating factors for fabric timing delays normalized to T_J = 85 °C, in worst-case V_{DD} = 1.14 V.

Table 16 • **Average Junction Temperature and Voltage Derating Factors for Fabric Timing Delays**

Array Voltage V_{DD} (V)	–40 °C	0 °C	25 °C	70 °C	85 °C	100 °C
1.14	0.83	0.89	0.92	0.98	**1.00**	1.02
1.2	0.75	0.80	0.83	0.89	0.91	0.93
1.26	0.69	0.73	0.76	0.81	0.83	0.85

Table 46 • **LVCMOS 2.5 V Transmitter Characteristics for DDRIO Bank (Output and Tristate Buffers) *(continued)***

Output Drive Selection	**Slew Control**	T_{DP}		T_{ZL}		T_{ZH}		T_{HZ}[1]		T_{LZ}[1]		**Unit**
		–1	**–Std**	**–1**	**–Std**	**–1**	**–Std**	**–1**	**–Std**	**–1**	**–Std**	
4 mA	Slow	3.095	3.641	2.705	3.182	3.088	3.633	4.738	5.575	4.348	5.116	ns
	Medium	2.825	3.324	2.488	2.927	2.823	3.321	4.492	5.285	4.063	4.781	ns
	Medium fast	2.701	3.178	2.384	2.804	2.698	3.173	4.364	5.135	3.945	4.642	ns
	Fast	2.69	3.165	2.377	2.796	2.687	3.161	4.359	5.129	3.94	4.636	ns
6 mA	Slow	2.919	3.434	2.491	2.93	2.902	3.414	5.085	5.983	4.674	5.5	ns
	Medium	2.65	3.118	2.279	2.681	2.642	3.108	4.845	5.701	4.375	5.148	ns
	Medium fast	2.529	2.975	2.176	2.56	2.521	2.965	4.724	5.558	4.259	5.011	ns
	Fast	2.516	2.96	2.168	2.551	2.508	2.95	4.717	5.55	4.251	5.002	ns
8 mA	Slow	2.863	3.368	2.427	2.855	2.844	3.346	5.196	6.114	4.769	5.612	ns
	Medium	2.599	3.058	2.217	2.608	2.59	3.047	4.952	5.827	4.471	5.261	ns
	Medium fast	2.483	2.921	2.114	2.487	2.473	2.91	4.832	5.685	4.364	5.134	ns
	Fast	2.467	2.902	2.106	2.478	2.457	2.89	4.826	5.678	4.348	5.116	ns
12 mA	Slow	2.747	3.232	2.296	2.701	2.724	3.204	5.39	6.342	4.938	5.81	ns
	Medium	2.493	2.934	2.102	2.473	2.483	2.921	5.166	6.078	4.65	5.471	ns
	Medium fast	2.382	2.803	2.006	2.36	2.371	2.789	5.067	5.962	4.546	5.349	ns
	Fast	2.369	2.787	1.999	2.352	2.357	2.773	5.063	5.958	4.538	5.339	ns
16 mA	Slow	2.677	3.149	2.213	2.604	2.649	3.116	5.575	6.56	5.08	5.977	ns
	Medium	2.432	2.862	2.028	2.386	2.421	2.848	5.372	6.32	4.801	5.649	ns
	Medium fast	2.324	2.734	1.937	2.278	2.311	2.718	5.297	6.233	4.7	5.531	ns
	Fast	2.313	2.721	1.929	2.269	2.3	2.706	5.296	6.231	4.699	5.529	ns

1. Delay increases with drive strength are inherent to built-in slew control circuitry for simultaneous switching output (SSO) management.

Table 47 • **LVCMOS 2.5 V Transmitter Characteristics for MSIO Bank (Output and Tristate Buffers)**

Output Drive Selection	**Slew Control**	T_{DP}		T_{ZL}		T_{ZH}		T_{HZ}[1]		T_{LZ}[1]		**Unit**
		–1	**–Std**	**–1**	**–Std**	**–1**	**–Std**	**–1**	**–Std**	**–1**	**–Std**	
2 mA	Slow	3.48	4.095	3.855	4.534	3.785	4.453	2.12	2.494	3.45	4.059	ns
4 mA	Slow	2.583	3.039	3.042	3.579	3.138	3.691	4.143	4.874	4.687	5.513	ns
6 mA	Slow	2.392	2.815	2.669	3.139	2.82	3.317	4.909	5.775	5.083	5.98	ns
8 mA	Slow	2.309	2.717	2.565	3.017	2.74	3.223	5.812	6.837	5.523	6.497	ns
12 mA	Slow	2.333	2.745	2.437	2.867	2.626	3.089	6.131	7.213	5.712	6.72	ns
16 mA	Slow	2.412	2.838	2.335	2.747	2.533	2.979	6.54	7.694	6.007	7.067	ns

1. Delay increases with drive strength are inherent to built-in slew control circuitry for simultaneous switching output (SSO) management.

Table 70 • LVCMOS 1.5 V Transmitter Characteristics for DDRIO I/O Bank (Output and Tristate Buffers) _(continued)_

Output Drive Selection	Slew Control	T_{DP}		T_{ZL}		T_{ZH}		T_{HZ}[1]		T_{LZ}[1]		Unit
		–1	–Std	–1	–Std	–1	–Std	–1	–Std	–1	–Std	
6 mA	Slow	4.244	4.993	3.465	4.076	4.233	4.979	6.39	7.518	5.736	6.748	ns
	Medium	3.774	4.44	3.05	3.587	3.762	4.426	6.114	7.193	5.397	6.35	ns
	Medium fast	3.544	4.17	2.839	3.339	3.529	4.152	5.978	7.033	5.27	6.2	ns
	Fast	3.519	4.14	2.82	3.317	3.504	4.122	5.965	7.017	5.259	6.187	ns
8 mA	Slow	4.099	4.823	3.311	3.894	4.087	4.807	6.584	7.746	5.854	6.888	ns
	Medium	3.656	4.301	2.927	3.443	3.642	4.284	6.311	7.425	5.553	6.533	ns
	Medium fast	3.437	4.044	2.731	3.213	3.42	4.023	6.182	7.273	5.435	6.394	ns
	Fast	3.41	4.012	2.715	3.193	3.393	3.991	6.178	7.269	5.425	6.383	ns
10 mA	Slow	4.029	4.74	3.238	3.809	4.015	4.723	6.732	7.921	5.965	7.018	ns
	Medium	3.601	4.237	2.867	3.372	3.586	4.218	6.473	7.615	5.669	6.669	ns
	Medium fast	3.384	3.981	2.672	3.143	3.365	3.958	6.351	7.471	5.55	6.529	ns
	Fast	3.357	3.949	2.655	3.123	3.338	3.927	6.345	7.464	5.54	6.518	ns
12 mA	Slow	3.974	4.675	3.196	3.759	3.958	4.656	6.842	8.049	6.068	7.139	ns
	Medium	3.55	4.176	2.827	3.326	3.534	4.157	6.584	7.746	5.751	6.766	ns
	Medium fast	3.345	3.935	2.638	3.103	3.325	3.911	6.488	7.633	5.641	6.637	ns
	Fast	3.316	3.902	2.621	3.083	3.297	3.878	6.486	7.63	5.626	6.619	ns

1. Delay increases with drive strength are inherent to built-in slew control circuitry for simultaneous switching output (SSO) management.

Table 71 • LVCMOS 1.5 V Transmitter Characteristics for MSIO I/O Bank (Output and Tristate Buffers)

Output Drive Selection	Slew Control	T_{DP}		T_{ZL}		T_{ZH}		T_{HZ}[1]		T_{LZ}[1]		Unit
		–1	–Std	–1	–Std	–1	–Std	–1	–Std	–1	–Std	
2 mA	Slow	4.423	5.203	5.397	6.35	5.686	6.69	5.609	6.599	5.561	6.542	ns
4 mA	Slow	4.05	4.765	4.503	5.298	4.92	5.788	7.358	8.657	6.525	7.677	ns
6 mA	Slow	4.081	4.801	4.259	5.012	4.699	5.528	7.659	9.011	6.709	7.893	ns
8 mA	Slow	4.234	4.98	4.068	4.786	4.521	5.319	8.218	9.668	7.05	8.294	ns

1. Delay increases with drive strength are inherent to built-in slew control circuitry for simultaneous switching output (SSO) management.

Table 144 • **LPDDR AC Differential Voltage Specifications (for DDRIO I/O Bank Only)**

Parameter	Symbol	Min	Max	Unit
AC input differential voltage	V_{DIFF}	0.6 × V_{DDI}		V
AC differential cross point voltage	V_x	0.4 × V_{DDI}	0.6 × V_{DDI}	V

Table 145 • **LPDDR AC Specifications (for DDRIO I/O Bank Only)**

Parameter	Symbol	Max	Unit	Conditions
Maximum data rate	D_{MAX}	400	Mbps	AC loading: per JEDEC specifications

Table 146 • **LPDDR AC Calibrated Impedance Option (for DDRIO I/O Bank Only)**

Parameter	Symbol	Typ	Unit	Conditions
Supported output driver calibrated impedance	R_{REF}	20, 42	Ω	Reference resistor = 150 Ω
Effective impedance value (ODT)	R_{TT}	50, 70, 150	Ω	Reference resistor = 150 Ω

Table 147 • **LPDDR AC Test Parameter Specifications (for DDRIO I/O Bank Only)**

Parameter	Symbol	Typ	Unit
Measuring/trip point for data path	V_{TRIP}	0.9	V
Resistance for enable path (T_{ZH}, T_{ZL}, T_{HZ}, T_{LZ})	R_{ENT}	2K	Ω
Capacitive loading for enable path (T_{ZH}, T_{ZL}, T_{HZ}, T_{LZ})	C_{ENT}	5	pF
Reference resistance for data test path for LPDDR (T_{DP})	RTT_TEST	50	Ω
Capacitive loading for data path (T_{DP})	C_{LOAD}	5	Ω

AC Switching Characteristics

Worst-case commercial conditions: T_J = 85 °C, V_{DD} = 1.14 V, worst-case V_{DDI}.

Table 148 • **LPDDR Receiver Characteristics for DDRIO I/O Bank with Fixed Codes**

		T_{PY}		
	On-Die Termination (ODT)	**–1**	**–Std**	**Unit**
Pseudo differential	None	1.568	1.845	ns
True differential	None	1.588	1.869	ns

Table 149 • **LPDDR Reduced Drive for DDRIO I/O Bank (Output and Tristate Buffers)**

	T_{DP}		T_{ENZL}		T_{ENZH}		T_{ENHZ}		T_{ENLZ}		
	–1	**–Std**	**–1**	**–Std**	**–1**	**–Std**	**–1**	**–Std**	**–1**	**–Std**	**Unit**
Single-ended	2.383	2.804	2.23	2.623	2.229	2.622	2.202	2.591	2.201	2.59	ns
Differential	2.396	2.819	2.764	3.252	2.764	3.252	2.255	2.653	2.255	2.653	ns

AC Switching Characteristics

Worst commercial-case conditions: T_J = 85 °C, V_{DD} = 1.14 V, V_{DDI} = 2.375 V.

Table 180 • **B-LVDS AC Switching Characteristics for Receiver for MSIO I/O Bank (Input Buffers)**

	T_{PY}		
On-Die Termination (ODT)	**–1**	**–Std**	**Unit**
None	2.738	3.221	ns
100	2.735	3.218	ns

Table 181 • **B-LVDS AC Switching Characteristics for Receiver for MSIOD I/O Bank (Input Buffers)**

	T_{PY}		
On-Die Termination (ODT)	**–1**	**–Std**	**Unit**
None	2.495	2.934	ns
100	2.495	2.935	ns

Table 182 • **B-LVDS AC Switching Characteristics for Transmitter (for MSIO I/O Bank - Output and Tristate Buffers)**

T_{DP}		T_{ZL}		T_{ZH}		T_{HZ}		T_{LZ}		
–1	**–Std**	**–1**	**–Std**	**–1**	**–Std**	**–1**	**–Std**	**–1**	**–Std**	**Unit**
2.258	2.656	2.343	2.756	2.329	2.74	2.12	2.494	2.123	2.497	ns

2.3.7.3 M-LVDS

M-LVDS specifications extend the existing LVDS standard to high-performance multipoint bus applications. Multidrop and multipoint bus configurations may contain any combination of drivers, receivers, and transceivers.

Minimum and Maximum Input and Output Levels

Table 183 • **M-LVDS Recommended DC Operating Conditions**

Parameter	Symbol	Min	Typ	Max	Unit
Supply voltage[1]	V_{DDI}	2.375	2.5	2.625	V

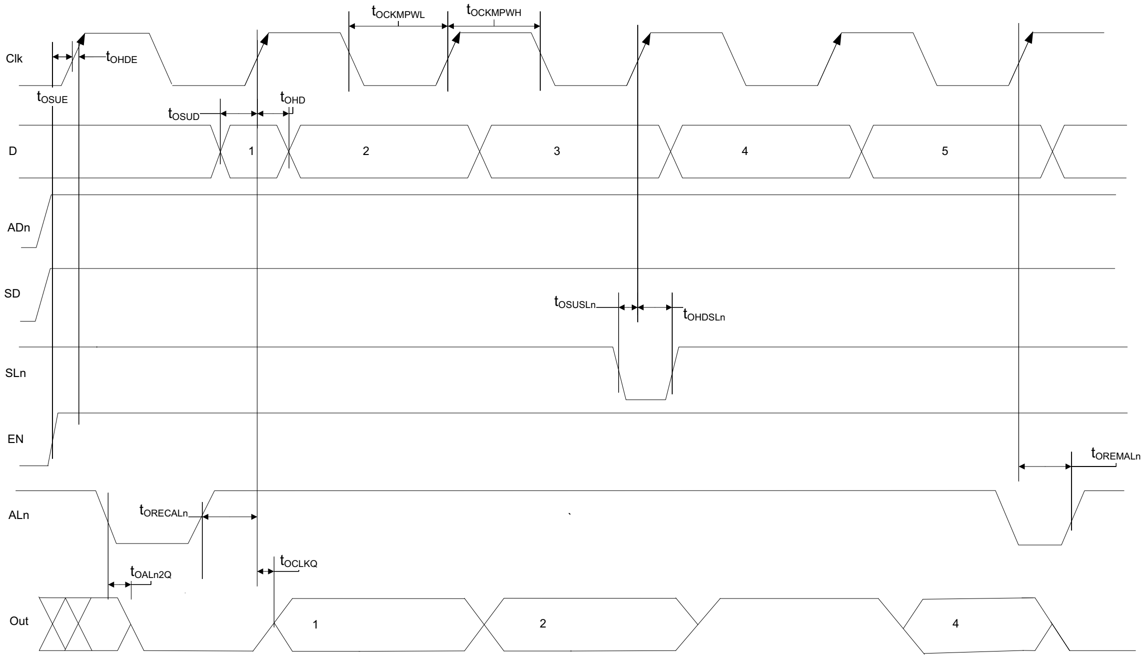
1. Only M-LVDS TYPE I is supported.

Table 184 • **M-LVDS DC Input Voltage Specification**

Parameter	Symbol	Min	Max	Unit
DC input voltage	V_I	0	2.925	V
Input current high[1]	I_{IH} (DC)			
Input current low[2]	I_{IL} (DC)			

1. See Table 24, page 22.

Figure 9 • **I/O Register Output Timing Diagram**



The following table lists the output/enable propagation delays in worst commercial-case conditions when T_J = 85 °C, V_{DD} = 1.14 V.

Table 220 • **Output/Enable Data Register Propagation Delays**

Parameter	Symbol	Measuring Nodes (from, to)[1]	–1	–Std	Unit
Bypass delay of the output/enable register	T_{OBYP}	F, G or H, I	0.353	0.415	ns
Clock-to-Q of the output/enable register	T_{OCLKQ}	E, G or E, I	0.263	0.309	ns
Data setup time for the output/enable register	T_{OSUD}	A, E or J, E	0.19	0.223	ns
Data hold time for the output/enable register	T_{OHD}	A, E or J, E	0	0	ns
Enable setup time for the output/enable register	T_{OSUE}	B, E	0.419	0.493	ns
Enable hold time for the output/enable register	T_{OHE}	B, E	0	0	ns
Synchronous load setup time for the output/enable register	T_{OSUSL}	D, E	0.196	0.231	ns
Synchronous load hold time for the output/enable register	T_{OHSL}	D, E	0	0	ns
Asynchronous clear-to-q of the output/enable register (ADn = 1)	T_{OALN2Q}	C, G or C, I	0.505	0.594	ns
Asynchronous preset-to-q of the output/enable register (ADn = 0)		C, G or C, I	0.528	0.621	ns
Asynchronous load removal time for the output/enable register	$T_{OREMALN}$	C, E	0	0	ns
Asynchronous load recovery time for the output/enable register	$T_{ORECALN}$	C, E	0.034	0.04	ns
Asynchronous load minimum pulse width for the output/enable register	T_{OWALN}	C, C	0.304	0.357	ns
Clock minimum pulse width high for the output/enable register	$T_{OCKMPWH}$	E, E	0.075	0.088	ns
Clock minimum pulse width low for the output/enable register	$T_{OCKMPWL}$	E, E	0.159	0.187	ns

1. For the derating values at specific junction temperature and voltage supply levels, see Table 16, page 14 for derating values.

The following table lists the RAM1K18 – dual-port mode for depth × width configuration 8K × 2 in worst commercial-case conditions when T_J = 85 °C, V_{DD} = 1.14 V.

Table 234 • **RAM1K18 – Dual-Port Mode for Depth × Width Configuration 8K × 2**

		–1		–Std		
Parameter	**Symbol**	**Min**	**Max**	**Min**	**Max**	**Unit**
Clock period	T_{CY}	2.5		2.941		ns
Clock minimum pulse width high	$T_{CLKMPWH}$	1.125		1.323		ns
Clock minimum pulse width low	$T_{CLKMPWL}$	1.125		1.323		ns
Pipelined clock period	T_{PLCY}	2.5		2.941		ns
Pipelined clock minimum pulse width high	$T_{PLCLKMPWH}$	1.125		1.323		ns
Pipelined clock minimum pulse width low	$T_{PLCLKMPWL}$	1.125		1.323		ns
Read access time with pipeline register	T_{CLK2Q}		0.32		0.377	ns
Read access time without pipeline register			2.272		2.673	ns
Access time with feed-through write timing			1.511		1.778	ns
Address setup time	T_{ADDRSU}	0.612		0.72		ns
Address hold time	T_{ADDRHD}	0.274		0.322		ns
Data setup time	T_{DSU}	0.33		0.388		ns
Data hold time	T_{DHD}	0.082		0.096		ns
Block select setup time	T_{BLKSU}	0.207		0.244		ns
Block select hold time	T_{BLKHD}	0.216		0.254		ns
Block select to out disable time (when pipelined register is disabled)	T_{BLK2Q}		1.511		1.778	ns
Block select minimum pulse width	T_{BLKMPW}	0.186		0.219		ns
Read enable setup time	T_{RDESU}	0.529		0.622		ns
Read enable hold time	T_{RDEHD}	0.071		0.083		ns
Pipelined read enable setup time (A_DOUT_EN, B_DOUT_EN)	$T_{RDPLESU}$	0.248		0.291		ns
Pipelined read enable hold time (A_DOUT_EN, B_DOUT_EN)	$T_{RDPLEHD}$	0.102		0.12		ns
Asynchronous reset to output propagation delay	T_{R2Q}		1.528		1.797	ns
Asynchronous reset removal time	T_{RSTREM}	0.506		0.595		ns
Asynchronous reset recovery time	T_{RSTREC}	0.004		0.005		ns
Asynchronous reset minimum pulse width	T_{RSTMPW}	0.301		0.354		ns
Pipelined register asynchronous reset removal time	$T_{PLRSTREM}$	–0.279		–0.328		ns
Pipelined register asynchronous reset recovery time	$T_{PLRSTREC}$	0.327		0.385		ns
Pipelined register asynchronous reset minimum pulse width	$T_{PLRSTMPW}$	0.282		0.332		ns
Synchronous reset setup time	T_{SRSTSU}	0.226		0.265		ns
Synchronous reset hold time	T_{SRSTHD}	0.036		0.043		ns
Write enable setup time	T_{WESU}	0.488		0.574		ns
Write enable hold time	T_{WEHD}	0.048		0.057		ns
Maximum frequency	F_{MAX}		400		340	MHz

The following table lists the µSRAM in 256 × 4 mode in worst commercial-case conditions when T_J = 85 °C, V_{DD} = 1.14 V.

Table 241 • **µSRAM (RAM256x4) in 256 × 4 Mode**

		–1		–Std		
Parameter	**Symbol**	**Min**	**Max**	**Min**	**Max**	**Unit**
Read clock period	T_{CY}	4		4		ns
Read clock minimum pulse width high	$T_{CLKMPWH}$	1.8		1.8		ns
Read clock minimum pulse width low	$T_{CLKMPWL}$	1.8		1.8		ns
Read pipeline clock period	T_{PLCY}	4		4		ns
Read pipeline clock minimum pulse width high	$T_{PLCLKMPWH}$	1.8		1.8		ns
Read pipeline clock minimum pulse width low	$T_{PLCLKMPWL}$	1.8		1.8		ns
Read access time with pipeline register	T_{CLK2Q}		0.27		0.31	ns
Read access time without pipeline register			1.75		2.06	ns
Read address setup time in synchronous mode	T_{ADDRSU}	0.301		0.354		ns
Read address setup time in asynchronous mode		1.931		2.272		ns
Read address hold time in synchronous mode	T_{ADDRHD}	0.121		0.142		ns
Read address hold time in asynchronous mode		–0.65		–0.76		ns
Read enable setup time	T_{RDENSU}	0.278		0.327		ns
Read enable hold time	T_{RDENHD}	0.057		0.067		ns
Read block select setup time	T_{BLKSU}	1.839		2.163		ns
Read block select hold time	T_{BLKHD}	–0.65		–0.77		ns
Read block select to out disable time (when pipelined register is disabled)	T_{BLK2Q}		2.09		2.46	ns
Read asynchronous reset removal time (pipelined clock)	T_{RSTREM}	–0.02		–0.03		ns
Read asynchronous reset removal time (non-pipelined clock)		0.046		0.054		ns
Read asynchronous reset recovery time (pipelined clock)	T_{RSTREC}	0.507		0.597		ns
Read asynchronous reset recovery time (non-pipelined clock)		0.236		0.278		ns
Read asynchronous reset to output propagation delay (with pipelined register enabled)	T_{R2Q}		0.83		0.98	ns
Read synchronous reset setup time	T_{SRSTSU}	0.271		0.319		ns
Read synchronous reset hold time	T_{SRSTHD}	0.061		0.071		ns
Write clock period	T_{CCY}	4		4		ns
Write clock minimum pulse width high	$T_{CCLKMPWH}$	1.8		1.8		ns
Write clock minimum pulse width low	$T_{CCLKMPWL}$	1.8		1.8		ns
Write block setup time	T_{BLKCSU}	0.404		0.476		ns
Write block hold time	T_{BLKCHD}	0.007		0.008		ns
Write input data setup time	T_{DINCSU}	0.101		0.118		ns
Write input data hold time	T_{DINCHD}	0.137		0.161		ns
Write address setup time	$T_{ADDRCSU}$	0.088		0.104		ns

Table 242 • **µSRAM (RAM512x2) in 512 × 2 Mode *(continued)***

		–1		–Std		
Parameter	**Symbol**	**Min**	**Max**	**Min**	**Max**	**Unit**
Write clock period	T_{CCY}	4		4		ns
Write clock minimum pulse width high	$T_{CCLKMPWH}$	1.8		1.8		ns
Write clock minimum pulse width low	$T_{CCLKMPWL}$	1.8		1.8		ns
Write block setup time	T_{BLKCSU}	0.404		0.476		ns
Write block hold time	T_{BLKCHD}	0.007		0.008		ns
Write input data setup time	T_{DINCSU}	0.101		0.118		ns
Write input data hold time	T_{DINCHD}	0.137		0.161		ns
Write address setup time	$T_{ADDRCSU}$	0.088		0.104		ns
Write address hold time	$T_{ADDRCHD}$	0.247		0.29		ns
Write enable setup time	T_{WECSU}	0.397		0.467		ns
Write enable hold time	T_{WECHD}	–0.03		–0.03		ns
Maximum frequency	F_{MAX}		250		250	MHz

The following table lists the µSRAM in 1024 × 1 mode in worst commercial-case conditions when T_J = 85 °C, V_{DD} = 1.14 V.

Table 243 • **µSRAM (RAM1024x1) in 1024 × 1 Mode**

		–1		–Std		
Parameter	**Symbol**	**Min**	**Max**	**Min**	**Max**	**Unit**
Read clock period	T_{CY}	4		4		ns
Read clock minimum pulse width high	$T_{CLKMPWH}$	1.8		1.8		ns
Read clock minimum pulse width low	$T_{CLKMPWL}$	1.8		1.8		ns
Read pipeline clock period	T_{PLCY}	4		4		ns
Read pipeline clock minimum pulse width high	$T_{PLCLKMPWH}$	1.8		1.8		ns
Read pipeline clock minimum pulse width low	$T_{PLCLKMPWL}$	1.8		1.8		ns
Read access time with pipeline register	T_{CLK2Q}		0.27		0.31	ns
Read access time without pipeline register			1.78		2.1	ns
Read address setup time in synchronous mode	T_{ADDRSU}	0.301		0.354		ns
Read address setup time in asynchronous mode		1.978		2.327		ns
Read address hold time in synchronous mode	T_{ADDRHD}	0.137		0.161		ns
Read address hold time in asynchronous mode		–0.6		–0.71		ns
Read enable setup time	T_{RDENSU}	0.278		0.327		ns
Read enable hold time	T_{RDENHD}	0.057		0.067		ns
Read block select setup time	T_{BLKSU}	1.839		2.163		ns
Read block select hold time	T_{BLKHD}	–0.65		–0.77		ns
Read block select to out disable time (when pipelined register is disabled)	T_{BLK2Q}		2.16		2.54	ns
Read asynchronous reset removal time (pipelined clock)	T_{RSTREM}	–0.02		–0.03		ns
Read asynchronous reset removal time (non-pipelined clock)		0.046		0.054		ns

Table 251 • **SmartFusion2 Cortex-M3 ISP Programming (eNVM Only)** ***(continued)***

M2S/M2GL Device	Image size Bytes	Authenticate	Program	Verify	Unit
150	544496	10	158	15	Sec

Table 252 • **SmartFusion2 Cortex-M3 ISP Programming (Fabric and eNVM)**

M2S/M2GL Device	Image size Bytes	Authenticate	Program	Verify	Unit
005	439296	9	61	11	Sec
010	842688	15	107	21	Sec
025	1497408	26	121	35	Sec
050	2695168	43	141	55	Sec
060	2686464	48	143	60	Sec
090	4190208	75	244	91	Sec
150	6682768	117	296	141	Sec

Table 253 • **Programming Times with 100 kHz, 25 MHz, and 12.5 MHz SPI Clock Rates (Fabric Only)**

M2S/M2GL Device	Auto Programming	Auto Update	Programming Recovery	
	100 kHz	25 MHz	12.5 MHz	Unit
005	47	27	28	Sec
010	77	35	35	Sec
025	150	42	41	Sec
050	33[1]	Not Supported	Not Supported	Sec
060	291	83	82	Sec
090	427	109	108	Sec
150	708	157	160	Sec

1. Auto Programming in 050 device is done through SC_SPI, and SPI CLK is set to 6.25 MHz.

Table 254 • **Programming Times with 100 kHz, 25 MHz, and 12.5 MHz SPI Clock Rates (eNVM Only)**

M2S/M2GL Device	Auto Programming	Auto Update	Programming Recovery	
	100 kHz	25 MHz	12.5 MHz	Unit
005	41	48	49	Sec
010	86	87	87	Sec
025	87	85	86	Sec
050	85	Not Supported	Not Supported	Sec
060	78	86	86	Sec
090	154	162	162	Sec

Table 265 • **Programming Times with 100 kHz, 25 MHz. and 12.5 MHz SPI Clock Rates (Fabric Only)**

	Auto Programming	Auto Update	Programming Recovery	
M2S/M2GL Device	**100 kHz**	**25 MHz**	**12.5 MHz**	**Unit**
005	69	49	50	Sec
010	99	57	57	Sec
025	150	64	63	Sec
050	55[1]	Not Supported	Not Supported	Sec
060	313	105	104	Sec
090	449	131	130	Sec
150	730	179	183	Sec

1. Auto programming in 050 device is done through SC_SPI, and SPI CLK is set to 6.25 MHz.

Table 266 • **Programming Times with 100 kHz, 25 MHz. and 12.5 MHz SPI Clock Rates (eNVM Only)**

	Auto Programming	Auto Update	Programming Recovery	
M2S/M2GL Device	**100 kHz**	**25 MHz**	**12.5 MHz**	**Unit**
005	63	70	71	Sec
010	108	109	109	Sec
025	109	107	108	Sec
050	107	Not Supported	Not Supported	Sec
060	100	108	108	Sec
090	176	184	184	Sec
150	183	183	183	Sec

Table 267 • **Programming Times with 100 kHz, 25 MHz. and 12.5 MHz SPI Clock Rates (Fabric and eNVM)**

	Auto Programming	Auto Update	Programming Recovery	
M2S/M2GL Device	**100 kHz**	**25 MHz**	**12.5 MHz**	**Unit**
005	109	89	88	Sec
010	183	135	135	Sec
025	251	142	143	Sec
050	134	Not Supported	Not Supported	Sec
060	390	183	180	Sec
090	604	283	282	Sec
150	889	331	332	Sec

The following table lists the math blocks with input register used and output in bypass mode in worst commercial-case conditions when T_J = 85 °C, V_{DD} = 1.14 V.

Table 270 • **Math Block with Input Register Used and Output in Bypass Mode**

		–1		–Std		
Parameter	**Symbol**	**Min**	**Max**	**Min**	**Max**	**Unit**
Input register setup time	T_{MISU}	0.149		0.176		ns
Input register hold time	T_{MIHD}	0.185		0.218		ns
Synchronous reset/enable setup time	$T_{MSRSTENSU}$	0.08		0.094		ns
Synchronous reset/enable hold time	$T_{MSRSTENHD}$	–0.012		–0.014		ns
Asynchronous reset removal time	$T_{MARSTREM}$	–0.005		–0.005		ns
Asynchronous reset recovery time	$T_{MARSTREC}$	0.088		0.104		ns
Input register clock to output delay	T_{MICQ}		2.52		2.964	ns
CDIN to output delay	$T_{MCDIN2Q}$		1.951		2.295	ns

The following table lists the math blocks with input and output in bypass mode in worst commercial-case conditions when T_J = 85 °C, V_{DD} = 1.14 V.

Table 271 • **Math Block with Input and Output in Bypass Mode**

		–1	–Std	
Parameter	**Symbol**	**Max**	**Max**	**Unit**
Input to output delay	T_{MIQ}	2.568	3.022	ns
CDIN to output delay	$T_{MCDIN2Q}$	1.951	2.295	ns

2.3.15 Embedded NVM (eNVM) Characteristics

The following table lists the eNVM read performance in worst-case conditions when V_{DD} = 1.14 V, V_{PPNVM} = V_{PP} = 2.375 V.

Table 272 • **eNVM Read Performance**

		Operating Temperature Range						
Symbol	**Description**	**–1**	**–Std**	**–1**	**–Std**	**–1**	**–Std**	**Unit**
T_J	Junction temperature range	–55 °C to 125 °C		–40 °C to 100 °C		0 °C to 85 °C		°C
$F_{MAXREAD}$	eNVM maximum read frequency	25	25	25	25	25	25	MHz

The following table lists the eNVM page programming in worst-case conditions when V_{DD} = 1.14 V, V_{PPNVM} = V_{PP} = 2.375 V.

Table 273 • **eNVM Page Programming**

		Operating Temperature Range						
Symbol	**Description**	**–1**	**–Std**	**–1**	**–Std**	**–1**	**–Std**	**Unit**
T_J	Junction temperature range	–55 °C to 125 °C		–40 °C to 100 °C		0 °C to 85 °C		°C
$T_{PAGEPGM}$	eNVM page programming time	40	40	40	40	40	40	ms

2.3.21 Clock Conditioning Circuits (CCC)

The following table lists the CCC/PLL specifications in worst-case industrial conditions when T_J = 100 °C, V_{DD} = 1.14 V.

Table 282 • **IGLOO2 and SmartFusion2 SoC FPGAs CCC/PLL Specification**

Parameter	Min	Typ	Max	Unit	Conditions
Clock conditioning circuitry input frequency F_{IN_CCC}	1		200	MHz	All CCC
	0.032		200	MHz	32 kHz capable CCC
Clock conditioning circuitry output frequency F_{OUT_CCC}[1]	0.078		400	MHz	
PLL VCO frequency[2]	500		1000	MHz	
Delay increments in programmable delay blocks		75	100	ps	
Number of programmable values in each programmable delay block			64		
Acquisition time		70	100	µs	F_{IN} >= 1 MHz
		1	16	ms	F_{IN} = 32 kHz
Input duty cycle (reference clock)					Internal Feedback
	10		90	%	1 MHz ≤ F_{IN_CCC} ≤ 25 MHz
	25		75	%	25 MHz ≤ F_{IN_CCC}≤ 100 MHz
	35		65	%	100 MHz ≤ F_{IN_CCC} ≤ 150 MHz
	45		55	%	150 MHz ≤ F_{IN_CCC} ≤ 200 MHz
					External Feedback (CCC, FPGA, Off-chip)
	25		75	%	1 MHz ≤ F_{IN_CCC} ≤ 25 MHz
	35		65	%	25 MHz ≤ F_{IN_CCC} ≤ 35 MHz
	45		55	%	35 MHz ≤ F_{IN_CCC} ≤ 50 MHz
Output duty cycle	48		52	%	050 devices F_{OUT} ≤ 400 MHz
	48		52	%	005, 010, and 025 devices F_{OUT} < 350 MHz
	46		54	%	005, 010, and 025 devices 350 MHz ≤ F_{out} ≤ 400 MHz
	48		52	%	060 and 090 devices F_{OUT} ≤ 100 MHz
	44		52	%	060 and 090 devices 100 MHz ≤ F_{OUT} ≤ 400 MHz
	48		52	%	150 devices F_{OUT} ≤ 120 MHz
	45		52	%	150 devices 120 MHz ≤ F_{OUT} ≤ 400 MHz
Spread Spectrum Characteristics					
Modulation frequency range	25	35	50	k	
Modulation depth range	0		1.5	%	
Modulation depth control		0.5		%	

2.3.24 Power-up to Functional Times

The following table lists the SmartFusion2 power-up to functional times in worst-case industrial conditions when T_J = 100 °C, V_{DD} = 1.14 V.

Table 288 • **Power-up to Functional Times for SmartFusion2**

				Maximum Power-up to Functional Time for SmartFusion2 (uS)						
Symbol	**From**	**To**	**Description**	**005**	**010**	**025**	**050**	**060**	**090**	**150**
$T_{POR2OUT}$	POWER_ON_RESET_N	Output available at I/O	Fabric to output	647	500	531	483	474	524	647
$T_{POR2MSSRST}$	POWER_ON_RESET_N	MSS_RESET_N_M2F	Fabric to MSS	644	497	528	480	468	518	641
$T_{MSSRST2OUT}$	MSS_RESET_N_M2F	Output available at I/O	MSS to output	3.6	3.6	3.6	3.4	4.9	4.8	4.8
$T_{VDD2OUT}$	V_{DD}	Output available at I/O	V_{DD} at its minimum threshold level to output	3096	2975	3012	2959	2869	2992	3225
$T_{VDD2POR}$	V_{DD}	POWER_ON_RESET_N	V_{DD} at its minimum threshold level to fabric	2476	2487	2496	2486	2406	2563	2602
$T_{VDD2MSSRST}$	V_{DD}	MSS_RESET_N_M2F	V_{DD} at its minimum threshold level to MSS	3093	2972	3008	2956	2864	2987	3220
$T_{VDD2WPU}$	DEVRST_N	DDRIO Inbuf weak pull	DEVRST_N to Inbuf weak pull	2500	2487	2509	2475	2507	2519	2617
	DEVRST_N	MSIO Inbuf weak pull	DEVRST_N to Inbuf weak pull	2504	2491	2510	2478	2517	2525	2620
	DEVRST_N	MSIOD Inbuf weak pull	DEVRST_N to Inbuf weak pull	2479	2468	2493	2458	2486	2499	2595

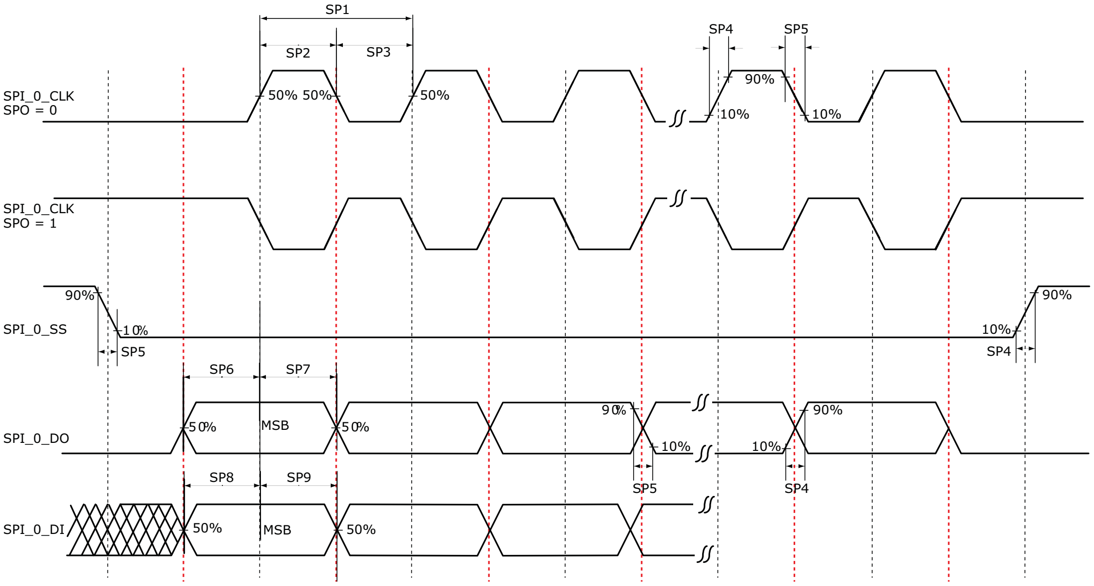
Note: For more information about power-up times, see *UG0331: SmartFusion2 Microcontroller Subsystem User Guide*.

Table 305 • **SPI Characteristics for All Devices *(continued)***

Symbol	Description	Min	Typ	Max	Unit	Conditions
sp5	SPI_[0|1]_CLK, SPI_[0|1]_DO, SPI_[0|1]_SS fall time (10%–90%)[1]		2.906		ns	IO Configuration: LVCMOS 2.5 V-8 mA AC Loading: 35 pF Test Conditions: Typical Voltage, 25 °C
SPI master configuration (applicable for 005, 010, 025, and 050 devices)						
sp6m	SPI_[0|1]_DO setup time[2]	(SPI_x_CLK_period/2) – 8.0			ns	
sp7m	SPI_[0|1]_DO hold time[2]	(SPI_x_CLK_period/2) – 2.5			ns	
sp8m	SPI_[0|1]_DI setup time[2]	12			ns	
sp9m	SPI_[0|1]_DI hold time[2]	2.5			ns	
SPI slave configuration (applicable for 005, 010, 025, and 050 devices)						
sp6s	SPI_[0|1]_DO setup time[2]	(SPI_x_CLK_period/2) – 17.0			ns	
sp7s	SPI_[0|1]_DO hold time[2]	(SPI_x_CLK_period/2) + 3.0			ns	
sp8s	SPI_[0|1]_DI setup time[2]	2			ns	
sp9s	SPI_[0|1]_DI hold time[2]	7			ns	
SPI master configuration (applicable for 060, 090, and 150 devices)						
sp6m	SPI_[0|1]_DO setup time[2]	(SPI_x_CLK_period/2) – 7.0			ns	
sp7m	SPI_[0|1]_DO hold time[2]	(SPI_x_CLK_period/2) – 9.5			ns	
sp8m	SPI_[0|1]_DI setup time[2]	15			ns	
sp9m	SPI_[0|1]_DI hold time[2]	—2.5			ns	
SPI slave configuration (applicable for 060, 090, and 150 devices)						
sp6s	SPI_[0|1]_DO setup time[2]	(SPI_x_CLK_period/2) – 16.0			ns	
sp7s	SPI_[0|1]_DO hold time[2]	(SPI_x_CLK_period/2) - 3.5			ns	
sp8s	SPI_[0|1]_DI setup time[2]	3			ns	
sp9s	SPI_[0|1]_DI hold time[2]	2.5			ns	

1. For specific Rise/Fall Times board design considerations and detailed output buffer resistances, use the corresponding IBIS models located on the Microsemi SoC Products Group website: http://www.microsemi.com/soc/download/ibis/default.aspx.
2. For allowable pclk configurations, see Serial Peripheral Interface Controller section in the *UG0331: SmartFusion2 Microcontroller Subsystem User Guide*.

Figure 22 • SPI Timing for a Single Frame Transfer in Motorola Mode (SPH = 1)



2.3.32 CAN Controller Characteristics

The following table lists the CAN controller characteristics in worst-case industrial conditions when T_J = 100 °C, V_{DD} = 1.14 V.

Table 306 • CAN Controller Characteristics

Parameter	Description	–1	–Std	Unit
FCANREFCLK[1]	Internally sourced CAN reference clock frequency	160	136	MHz
BAUDCANMAX	Maximum CAN performance baud rate	1	1	Mbps
BAUDCANMIN	Minimum CAN performance baud rate	0.05	0.05	Mbps

1. PCLK to CAN controller must be a multiple of 8 MHz.

2.3.33 USB Characteristics

The following table lists the USB characteristics in worst-case industrial conditions when T_J = 100 °C, V_{DD} = 1.14 V.

Table 307 • USB Characteristics

Parameter	Description	–1	–Std	Unit
FUSBREFCLK	Internally sourced USB reference clock frequency	166	142	MHz
TUSBCLK	USB clock period	16.66	16.66	ns
TUSBPD	Clock to USB data propagation delay	9.0	9.0	ns
TUSBSU	Setup time for USB data	6.0	6.0	ns
TUSBHD	Hold time for USB data	0	0	ns

Table 310 • **SPI Characteristics for All Devices *(continued)***

Symbol	Description	Min	Typ	Max	Unit	Conditions
SPI master configuration (applicable for 060, 090, and 150 devices)						
sp6m	SPI_[0|1]_DO setup time[2]	(SPI_x_CLK_period/2) – 7.0			ns	
sp7m	SPI_[0|1]_DO hold time[2]	(SPI_x_CLK_period/2) – 9.5			ns	
sp8m	SPI_[0|1]_DI setup time[2]	15			ns	
sp9m	SPI_[0|1]_DI hold time[2]	—2.5			ns	
SPI slave configuration (applicable for 060, 090, and 150 devices)						
sp6s	SPI_[0|1]_DO setup time[2]	(SPI_x_CLK_period/2) – 16.0			ns	
sp7s	SPI_[0|1]_DO hold time[2]	(SPI_x_CLK_period/2) - 3.5			ns	
sp8s	SPI_[0|1]_DI setup time[2]	3			ns	
sp9s	SPI_[0|1]_DI hold time[2]	2.5			ns	

1. For specific Rise/Fall Times board design considerations and detailed output buffer resistances, use the corresponding IBIS models located on the Microsemi SoC Products Group website: http://www.microsemi.com/soc/download/ibis/default.aspx.
2. For allowable pclk configurations, see the Serial Peripheral Interface Controller section in the *UG0331: SmartFusion2 Microcontroller Subsystem User Guide*.

Figure 23 • **SPI Timing for a Single Frame Transfer in Motorola Mode (SPH = 1)**