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Understanding [Embedded - FPGAs \(Field Programmable Gate Array\)](#)

Embedded - FPGAs, or Field Programmable Gate Arrays, are advanced integrated circuits that offer unparalleled flexibility and performance for digital systems. Unlike traditional fixed-function logic devices, FPGAs can be programmed and reprogrammed to execute a wide array of logical operations, enabling customized functionality tailored to specific applications. This reprogrammability allows developers to iterate designs quickly and implement complex functions without the need for custom hardware.

Applications of Embedded - FPGAs

The versatility of Embedded - FPGAs makes them indispensable in numerous fields. In telecommunications.

Details

Product Status	Active
Number of LABs/CLBs	-
Number of Logic Elements/Cells	146124
Total RAM Bits	5120000
Number of I/O	293
Number of Gates	-
Voltage - Supply	1.14V ~ 2.625V
Mounting Type	Surface Mount
Operating Temperature	0°C ~ 85°C (TJ)
Package / Case	536-LFBGA, CSPBGA
Supplier Device Package	536-CSPBGA (16x16)
Purchase URL	https://www.e-xfl.com/product-detail/microchip-technology/m2gl150ts-1fcsg536



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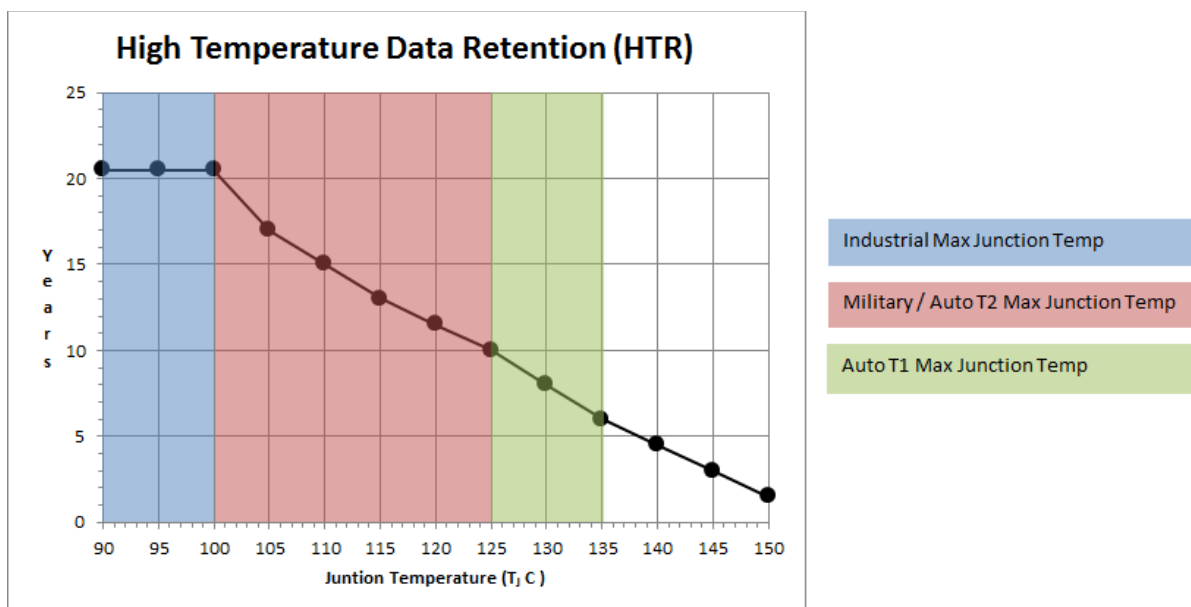
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Figure 1 • High Temperature Data Retention (HTR)

2.3.1.1 Overshoot/Undershoot Limits

For AC signals, the input signal may undershoot during transitions to -1.0 V for no longer than 10% of the period. The current during the transition must not exceed 100 mA.

For AC signals, the input signal may overshoot during transitions to $V_{CCI} + 1.0$ V for no longer than 10% of the period. The current during the transition must not exceed 100 mA.

Note: The above specifications do not apply to the PCI standard. The IGLOO2 and SmartFusion2 PCI I/Os are compliant with the PCI standard including the PCI overshoot/undershoot specifications.

2.3.1.2 Thermal Characteristics

The temperature variable in the Microsemi SoC Products Group Designer software refers to the junction temperature, not the ambient, case, or board temperatures. This is an important distinction because dynamic and static power consumption causes the chip's junction temperature to be higher than the ambient, case, or board temperatures.

EQ1 through EQ3 give the relationship between thermal resistance, temperature gradient, and power.

$$\theta_{JA} = \frac{T_J - T_A}{P} \quad \text{EQ 1}$$

$$\theta_{JB} = \frac{T_J - T_B}{P} \quad \text{EQ 2}$$

$$\theta_{JC} = \frac{T_J - T_C}{P} \quad \text{EQ 3}$$

where

- θ_{JA} = Junction-to-air thermal resistance
 θ_{JB} = Junction-to-board thermal resistance
 θ_{JC} = Junction-to-case thermal resistance
 T_J = Junction temperature
 T_A = Ambient temperature
 T_B = Board temperature (measured 1.0 mm away from the package edge)
 T_C = Case temperature
 P = Total power dissipated by the device

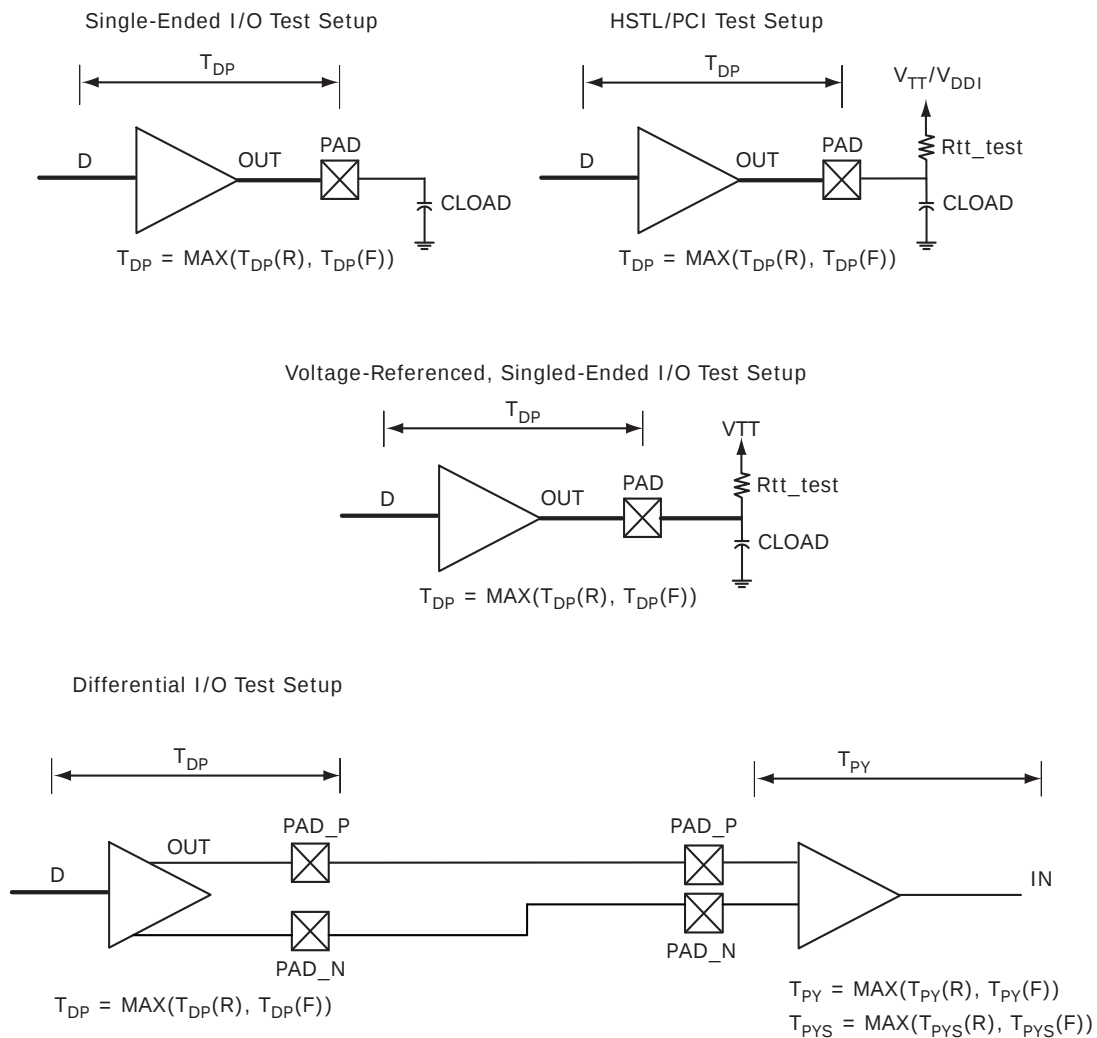
Table 9 • Package Thermal Resistance of SmartFusion2 and IGLOO2 Devices

	Still Air	1.0 m/s	2.5 m/s			
Device	θ_{JA}			θ_{JB}	θ_{JC}	Unit
005						
FG484	19.36	15.81	14.63	9.74	5.27	°C/W
VF256	41.30	38.16	35.30	28.41	3.94	°C/W
VF400	20.19	16.94	15.41	8.86	4.95	°C/W
TQ144	42.80	36.80	34.50	37.20	10.80	°C/W
010						
FG484	18.22	14.83	13.62	8.83	4.92	°C/W
VF256	37.36	34.26	31.45	24.84	7.89	°C/W
VF400	19.40	15.75	14.22	8.11	4.22	°C/W
TQ144	38.60	32.60	30.30	31.80	8.60	°C/W
025						
FG484	17.03	13.66	12.45	7.66	4.18	°C/W
VF256	33.85	30.59	27.85	21.63	6.13	°C/W
VF400	18.36	14.89	13.36	7.12	3.41	°C/W
FCS325	29.17	24.87	23.12	14.44	2.31	°C/W
050						
FG484	15.29	12.19	10.99	6.27	3.24	°C/W
FG896	14.70	12.50	10.90	7.20	4.90	°C/W
VF400	17.53	14.17	12.63	6.32	2.81	°C/W
FCS325	27.38	23.18	21.41	12.47	1.59	°C/W
060						
FG484	15.40	12.06	10.85	6.14	3.15	°C/W
FG676	15.49	12.21	11.06	7.07	3.87	°C/W
VF400	17.45	14.01	12.47	6.22	2.69	°C/W
FCS325	27.03	22.91	21.25	12.33	1.54	°C/W
090						
FG484	14.64	11.37	10.16	5.43	2.77	°C/W
FG676	14.52	11.19	10.37	6.17	3.24	°C/W
FCS325	26.63	22.26	20.13	14.24	2.50	°C/W

2.3.5.2 Output Buffer and AC Loading

The following figure shows the output buffer and AC loading.

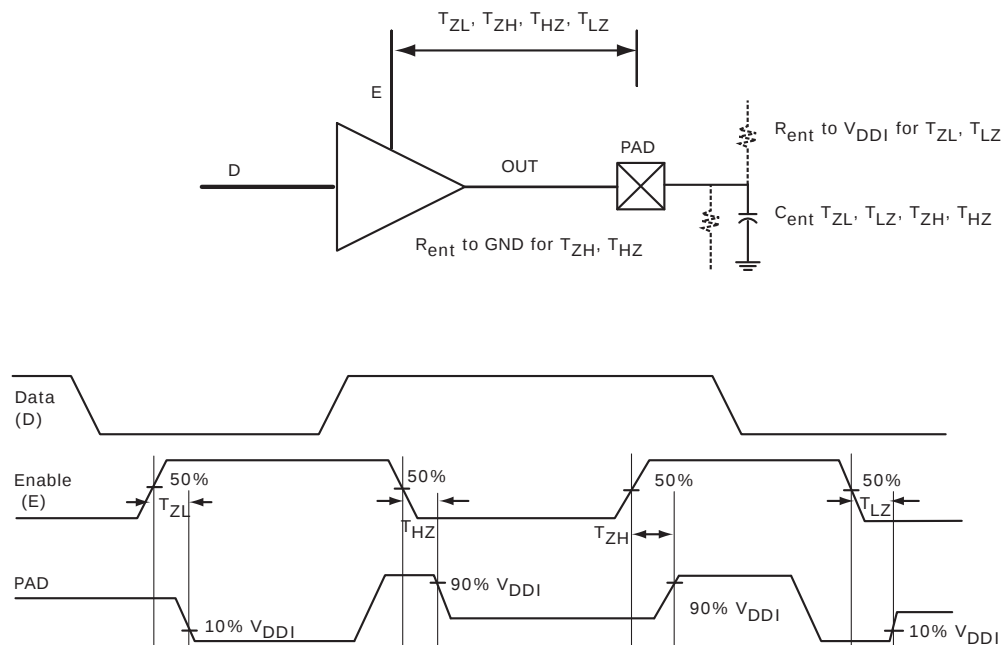
Figure 4 • Output Buffer AC Loading



2.3.5.3 Tristate Buffer and AC Loading

The tristate path for enable path loadings is described in the respective specifications. The following figure shows the methodology of characterization illustrated by the enable path test point.

Figure 5 • Tristate Buffer for Enable Path Test Point



2.3.5.4 I/O Speeds

This section describes the maximum data rate summary of I/O in worst-case industrial conditions. See the individual I/O standards for operating conditions.

Table 18 • Maximum Data Rate Summary Table for Single-Ended I/O in Worst-Case Industrial Conditions

I/O	MSIO	MSIOD	DDRIO	Unit
PCI 3.3 V	630			Mbps
LVTTL 3.3 V	600			Mbps
LVC MOS 3.3 V	600			Mbps
LVC MOS 2.5 V	410	420	400	Mbps
LVC MOS 1.8 V	295	400	400	Mbps
LVC MOS 1.5 V	160	220	235	Mbps
LVC MOS 1.2 V	120	160	200	Mbps
LPDDR-LVC MOS 1.8 V mode			400	Mbps

AC Switching Characteristics
 Worst commercial-case conditions: $T_J = 85^\circ\text{C}$, $V_{DD} = 1.14\text{ V}$, $V_{DDI} = 1.425\text{ V}$
Table 67 • LVCMOS 1.5 V Receiver Characteristics for DDRIO I/O Bank with Fixed Codes (Input Buffers)

On-Die Termination (ODT)	T_{PY}		T_{PYS}		Unit
	-1	-Std	-1	-Std	
None	2.051	2.413	2.086	2.455	ns

Table 68 • LVCMOS 1.5 V Receiver Characteristics for MSIO I/O Bank (Input Buffers)

On-Die Termination (ODT)	T_{PY}		T_{PYS}		Unit
	-1	-Std	-1	-Std	
None	3.311	3.896	3.285	3.865	ns
50	3.654	4.299	3.623	4.263	ns
75	3.533	4.156	3.501	4.119	ns
150	3.415	4.018	3.388	3.986	ns

Table 69 • LVCMOS 1.5 V Receiver Characteristics for MSIOD I/O Bank (Input Buffers)

On-Die Termination (ODT)	T_{PY}		T_{PYS}		Unit
	-1	-Std	-1	-Std	
None	2.959	3.481	2.93	3.447	ns
50	3.298	3.88	3.268	3.845	ns
75	3.162	3.719	3.128	3.68	ns
150	3.053	3.592	3.021	3.554	ns

Table 70 • LVCMOS 1.5 V Transmitter Characteristics for DDRIO I/O Bank (Output and Tristate Buffers)

Output Drive Selection	Slew Control	T_{DP}		T_{ZL}		T_{ZH}		T_{HZ}^1		T_{LZ}^1		Unit
		-1	-Std	-1	-Std	-1	-Std	-1	-Std	-1	-Std	
2 mA	Slow	5.122	6.026	4.31	5.07	5.145	6.052	5.258	6.186	4.672	5.496	ns
	Medium	4.58	5.389	3.86	4.54	4.6	5.411	4.977	5.855	4.357	5.126	ns
	Medium fast	4.323	5.086	3.629	4.269	4.341	5.107	4.804	5.652	4.228	4.974	ns
	Fast	4.296	5.054	3.609	4.245	4.314	5.075	4.791	5.636	4.219	4.963	ns
4 mA	Slow	4.449	5.235	3.707	4.361	4.443	5.227	6.058	7.127	5.458	6.421	ns
	Medium	3.961	4.66	3.264	3.839	3.954	4.651	5.778	6.797	5.116	6.018	ns
	Medium fast	3.729	4.387	3.043	3.579	3.72	4.376	5.63	6.624	4.981	5.86	ns
	Fast	3.704	4.358	3.027	3.56	3.695	4.347	5.624	6.617	4.973	5.851	ns

Table 72 • LVCMOS 1.5 V Transmitter Characteristics for MSIOD I/O Bank (Output and Tristate Buffers)

Output Drive Selection	Slew Control	T _{DP}		T _{ZL}		T _{ZH}		T _{HZ} ¹		T _{LZ} ¹		Unit
		-1	-Std	-1	-Std	-1	-Std	-1	-Std	-1	-Std	
2 mA	Slow	2.735	3.218	3.371	3.966	3.618	4.257	6.03	7.095	5.705	6.712	ns
4 mA	Slow	2.426	2.854	2.992	3.521	3.221	3.79	6.738	7.927	6.298	7.41	ns
6 mA	Slow	2.433	2.862	2.81	3.306	3.031	3.566	7.123	8.38	6.596	7.76	ns

1. Delay increases with drive strength are inherent to built-in slew control circuitry for simultaneous switching output (SSO) management.

2.3.5.10 1.2 V LVCMOS

LVCMOS 1.2 is a general standard for 1.2 V applications and is supported in IGLOO2 FPGAs and SmartFusion2 SoC FPGAs in compliance to the JEDEC specification JESD8-12A.

Minimum and Maximum DC/AC Input and Output Levels Specification

Table 73 • LVCMOS 1.2 V DC Recommended DC Operating Conditions

Parameter	Symbol	Min	Typ	Max	Unit
Supply voltage	V _{DDI}	1.140	1.2	1.26	V

Table 74 • LVCMOS 1.2 V DC Input Voltage Specification

Parameter	Symbol	Min	Max	Unit
DC input logic high (for MSIOD and DDRIO I/O banks)	V _{IH} (DC)	0.65 × V _{DDI}	1.26	V
DC input logic high (for MSIO I/O bank)	V _{IH} (DC)	0.65 × V _{DDI}	3.45	V
DC input logic low	V _{IL} (DC)	-0.3	0.35 × V _{DDI}	V
Input current high ¹	I _{IH} (DC)			
Input current low ¹	I _{IL} (DC)			

1. See Table 24, page 22.

Table 75 • LVCMOS 1.2 V DC Output Voltage Specification

Parameter	Symbol	Min	Max	Unit
DC output logic high	V _{OH}	V _{DDI} × 0.75		V
DC output logic low	V _{OL}		V _{DDI} × 0.25	V

Table 76 • LVCMOS 1.2 V Minimum and Maximum AC Switching Speed

Parameter	Symbol	Max	Unit	Conditions
Maximum data rate (for DDRIO I/O bank)	D _{MAX}	200	Mbps	AC loading: 17 pF load, maximum drive/slew
Maximum data rate (for MSIO I/O bank)	D _{MAX}	120	Mbps	AC loading: 17 pF load, maximum drive/slew
Maximum data rate (for MSIOD I/O bank)	D _{MAX}	160	Mbps	AC loading: 17 pF load, maximum drive/slew

Table 77 • LVCMOS 1.2 V AC Calibrated Impedance Option

Parameter	Symbol	Typ	Unit
Supported output driver calibrated impedance (for DDRIO I/O bank)	RODT_CAL	75, 60, 50, 40	Ω

Table 78 • LVCMOS 1.2 V AC Test Parameter Specifications

Parameter	Symbol	Typ	Unit
Measuring/trip point	V_{TRIP}	0.6	V
Resistance for enable path (T_{ZH} , T_{ZL} , T_{HZ} , T_{LZ})	R_{ENT}	2K	Ω
Capacitive loading for enable path (T_{ZH} , T_{ZL} , T_{HZ} , T_{LZ})	C_{ENT}	5	pF
Capacitive loading for data path (T_{DP})	C_{LOAD}	5	pF

Table 79 • LVCMOS 1.2 V Transmitter Drive Strength Specifications

Output Drive Selection			V_{OH} (V)	V_{OL} (V)	IOH (at V_{OH}) mA	IOL (at V_{OL}) mA
MSIO I/O Bank	MSIOD I/O Bank	DDRIO I/O Bank	Min	Max		
2 mA	2 mA	2 mA	$V_{DDI} \times 0.75$	$V_{DDI} \times 0.25$	2	2
4 mA	4 mA	4 mA	$V_{DDI} \times 0.75$	$V_{DDI} \times 0.25$	4	4
		6 mA	$V_{DDI} \times 0.75$	$V_{DDI} \times 0.25$	6	6

Note: For a detailed I/V curve, use the corresponding IBIS models:

www.microsemi.com/soc/download/ibis/default.aspx.

AC Switching Characteristics

Worst commercial-case conditions: $T_J = 85^\circ\text{C}$, $V_{DD} = 1.14\text{ V}$, $V_{DDI} = 1.14\text{ V}$

Table 80 • LVCMOS 1.2 V Receiver Characteristics for DDRIO I/O Bank with Fixed Code (Input Buffers)

On-Die Termination (ODT)	T_{PY}		T_{PYS}		Unit
	-1	-Std	-1	-Std	
None	2.448	2.88	2.466	2.901	ns

Table 81 • LVCMOS 1.2 V Receiver Characteristics for MSIO I/O Bank (Input Buffers)

On-Die Termination ODT	T_{PY}		T_{PYS}		Unit
	-1	-Std	-1	-Std	
None	4.714	5.545	4.675	5.5	ns
50	6.668	7.845	6.579	7.74	ns
75	5.832	6.862	5.76	6.777	ns
150	5.162	6.073	5.111	6.014	ns

Table 168 • LVDS25 Receiver Characteristics for MSIOD I/O Bank (Input Buffers)

On-Die Termination (ODT)	T_{PY}		Unit
	-1	-Std	
None	2.554	3.004	ns
100	2.549	2.999	ns

Table 169 • LVDS25 Transmitter Characteristics for MSIO I/O Bank (Output and Tristate Buffers)

T_{DP}		T_{ZL}		T_{ZH}		T_{HZ}		T_{LZ}		Unit
-1	-Std	-1	-Std	-1	-Std	-1	-Std	-1	-Std	
2.136	2.513	2.416	2.842	2.402	2.825	2.423	2.85	2.409	2.833	ns

Table 170 • LVDS25 Transmitter Characteristics for MSIOD I/O Bank (Output and Tristate Buffers)

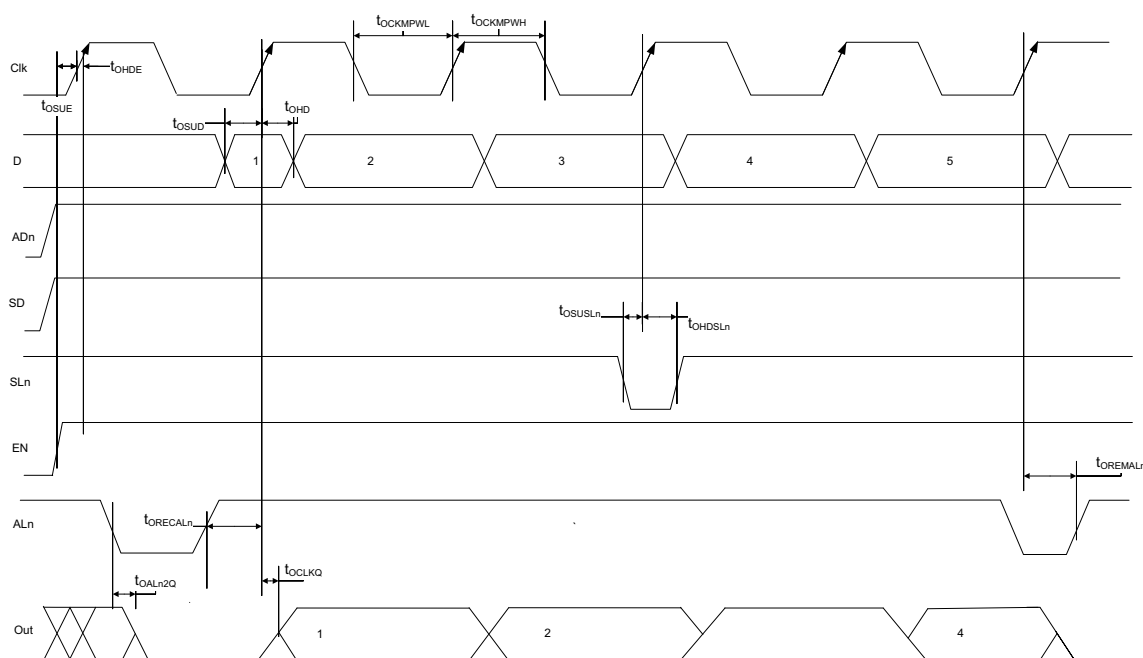
	T_{DP}		T_{ZL}		T_{ZH}		T_{HZ}		T_{LZ}		Unit
	-1	-Std	-1	-Std	-1	-Std	-1	-Std	-1	-Std	
No pre-emphasis	1.61	1.893	1.749	2.058	1.735	2.041	1.897	2.231	1.866	2.195	ns
Min pre-emphasis	1.527	1.796	1.757	2.067	1.744	2.052	1.905	2.241	1.876	2.207	ns
Med pre-emphasis	1.496	1.76	1.765	2.077	1.751	2.06	1.914	2.252	1.884	2.216	ns

LVDS33 AC Switching Characteristics**Table 171 • LVDS33 Receiver Characteristics for MSIO I/O Bank (Input Buffers)**

On Die Termination (ODT)	T_{PY}		Unit
	-1	-Std	
None	2.572	3.025	ns
100	2.569	3.023	ns

Table 172 • LVDS33 Transmitter Characteristics for MSIO I/O Bank (Output and Tristate Buffers)

T_{DP}		T_{ZL}		T_{ZH}		T_{HZ}		T_{LZ}		Unit
-1	-Std	-1	-Std	-1	-Std	-1	-Std	-1	-Std	
1.942	2.284	1.98	2.33	1.97	2.318	1.953	2.298	1.96	2.307	ns

Figure 9 • I/O Register Output Timing Diagram

The following table lists the output/enable propagation delays in worst commercial-case conditions when $T_J = 85^\circ\text{C}$, $V_{DD} = 1.14\text{ V}$.

Table 220 • Output/Enable Data Register Propagation Delays

Parameter	Symbol	Measuring Nodes (from, to) ¹	-1	-Std	Unit
Bypass delay of the output/enable register	T_{OBYP}	F, G or H, I	0.353	0.415	ns
Clock-to-Q of the output/enable register	T_{OCLKQ}	E, G or E, I	0.263	0.309	ns
Data setup time for the output/enable register	T_{OSUD}	A, E or J, E	0.19	0.223	ns
Data hold time for the output/enable register	T_{OHD}	A, E or J, E	0	0	ns
Enable setup time for the output/enable register	T_{OSUE}	B, E	0.419	0.493	ns
Enable hold time for the output/enable register	T_{OHE}	B, E	0	0	ns
Synchronous load setup time for the output/enable register	T_{OSUSL}	D, E	0.196	0.231	ns
Synchronous load hold time for the output/enable register	T_{OHSL}	D, E	0	0	ns
Asynchronous clear-to-q of the output/enable register ($ADn = 1$)	T_{OALN2Q}	C, G or C, I	0.505	0.594	ns
Asynchronous preset-to-q of the output/enable register ($ADn = 0$)		C, G or C, I	0.528	0.621	ns
Asynchronous load removal time for the output/enable register	$T_{OREMALN}$	C, E	0	0	ns
Asynchronous load recovery time for the output/enable register	$T_{ORECALN}$	C, E	0.034	0.04	ns
Asynchronous load minimum pulse width for the output/enable register	T_{OWALN}	C, C	0.304	0.357	ns
Clock minimum pulse width high for the output/enable register	$T_{OCLMPWH}$	E, E	0.075	0.088	ns
Clock minimum pulse width low for the output/enable register	$T_{OCLMPWL}$	E, E	0.159	0.187	ns

1. For the derating values at specific junction temperature and voltage supply levels, see [Table 16](#), page 14 for derating values.

Table 231 • RAM1K18 – Dual-Port Mode for Depth × Width Configuration 1K × 18 (continued)

Parameter	Symbol	–1		–Std		Unit
		Min	Max	Min	Max	
Block select hold time	T _{BLKHD}	0.216		0.254		ns
Block select to out disable time (when pipelined register is disabled)	T _{BLK2Q}		1.529		1.799	ns
Block select minimum pulse width	T _{BLKMPW}	0.186		0.219		ns
Read enable setup time	T _{RDESU}	0.449		0.528		ns
Read enable hold time	T _{RDEHD}	0.167		0.197		ns
Pipelined read enable setup time (A_DOUT_EN, B_DOUT_EN)	T _{RDPLESU}	0.248		0.291		ns
Pipelined read enable hold time (A_DOUT_EN, B_DOUT_EN)	T _{RDPLEHD}	0.102		0.12		ns
Asynchronous reset to output propagation delay	T _{R2Q}	–	1.506	–	1.772	ns
Asynchronous reset removal time	T _{RSTREM}	0.506		0.595		ns
Asynchronous reset recovery time	T _{RSTREC}	0.004		0.005		ns
Asynchronous reset minimum pulse width	T _{RSTMPW}	0.301		0.354		ns
Pipelined register asynchronous reset removal time	T _{PLRSTREM}	–0.279		–0.328		ns
Pipelined register asynchronous reset recovery time	T _{PLRSTREC}	0.327		0.385		ns
Pipelined register asynchronous reset minimum pulse width	T _{PLRSTMPW}	0.282		0.332		ns
Synchronous reset setup time	T _{SRSTSU}	0.226		0.265		ns
Synchronous reset hold time	T _{SRSTHD}	0.036		0.043		ns
Write enable setup time	T _{WESU}	0.39		0.458		ns
Write enable hold time	T _{WEHD}	0.242		0.285		ns
Maximum frequency	F _{MAX}		400		340	MHz

The following table lists the RAM1K18 – dual-port mode for depth × width configuration 2K × 9 in worst commercial-case conditions when T_J = 85 °C, V_{DD} = 1.14 V.

Table 232 • RAM1K18 – Dual-Port Mode for Depth × Width Configuration 2K × 9

Parameter	Symbol	–1		–Std		Unit
		Min	Max	Min	Max	
Clock period	T _{CY}	2.5		2.941		ns
Clock minimum pulse width high	T _{CLKMPWH}	1.125		1.323		ns
Clock minimum pulse width low	T _{CLKMPWL}	1.125		1.323		ns
Pipelined clock period	T _{PLCY}	2.5		2.941		ns
Pipelined clock minimum pulse width high	T _{PLCLKMPWH}	1.125		1.323		ns
Pipelined clock minimum pulse width low	T _{PLCLKMPWL}	1.125		1.323		ns
Read access time with pipeline register			0.334		0.393	ns
Read access time without pipeline register	T _{CLK2Q}		2.273		2.674	ns
Access time with feed-through write timing			1.529		1.799	ns

The following table lists the RAM1K18 – two-port mode for depth × width configuration 512 × 36 in worst commercial-case conditions when $T_J = 85\text{ }^{\circ}\text{C}$, $V_{DD} = 1.14\text{ V}$.

Table 236 • RAM1K18 – Two-Port Mode for Depth × Width Configuration 512 × 36

Parameter	Symbol	–1		–Std		Unit
		Min	Max	Min	Max	
Clock period	T_{CY}	2.5		2.941		ns
Clock minimum pulse width high	$T_{CLKMPWH}$	1.125		1.323		ns
Clock minimum pulse width low	$T_{CLKMPWL}$	1.125		1.323		ns
Pipelined clock period	T_{PLCY}	2.5		2.941		ns
Pipelined clock minimum pulse width high	$T_{PLCLKMPWH}$	1.125		1.323		ns
Pipelined clock minimum pulse width low	$T_{PLCLKMPWL}$	1.125		1.323		ns
Read access time with pipeline register	T_{CLK2Q}		0.334		0.393	ns
Read access time without pipeline register			2.25		2.647	ns
Address setup time	T_{ADDRSU}	0.313		0.368		ns
Address hold time	T_{ADDRHD}	0.274		0.322		ns
Data setup time	T_{DSU}	0.337		0.396		ns
Data hold time	T_{DHD}	0.111		0.13		ns
Block select setup time	T_{BLKSU}	0.207		0.244		ns
Block select hold time	T_{BLKHD}	0.201		0.237		ns
Block select to out disable time (when pipelined register is disabled)	T_{BLK2Q}		2.25		2.647	ns
Block select minimum pulse width	T_{BLKMPW}	0.186		0.219		ns
Read enable setup time	T_{RDESU}	0.449		0.528		ns
Read enable hold time	T_{RDEHD}	0.167		0.197		ns
Pipelined read enable setup time (A_DOUT_EN, B_DOUT_EN)	$T_{RDPLESU}$	0.248		0.291		ns
Pipelined read enable hold time (A_DOUT_EN, B_DOUT_EN)	$T_{RDPLEHD}$	0.102		0.12		ns
Asynchronous reset to output propagation delay	T_{R2Q}		1.506		1.772	ns
Asynchronous reset removal time	T_{RSTREM}	0.506		0.595		ns
Asynchronous reset recovery time	T_{RSTREC}	0.004		0.005		ns
Asynchronous reset minimum pulse width	T_{RSTMPW}	0.301		0.354		ns
Pipelined register asynchronous reset removal time	$T_{PLRSTREM}$	–0.279		–0.328		ns
Pipelined register asynchronous reset recovery time	$T_{PLRSTREC}$	0.327		0.385		ns
Pipelined register asynchronous reset minimum pulse width	$T_{PLRSTMPW}$	0.282		0.332		ns
Synchronous reset setup time	T_{SRSTSU}	0.226		0.265		ns
Synchronous reset hold time	T_{SRSTHD}	0.036		0.043		ns
Write enable setup time	T_{WESU}	0.39		0.458		ns
Write enable hold time	T_{WEHD}	0.242		0.285		ns
Maximum frequency	F_{MAX}		400		340	MHz

Table 238 • μ SRAM (RAM64x16) in 64 × 16 Mode (continued)

Parameter	Symbol	–1		–Std		Unit
		Min	Max	Min	Max	
Read synchronous reset hold time	T_{SRSTHD}	0.061		0.071		ns
Write clock period	T_{CCY}	4		4		ns
Write clock minimum pulse width high	$T_{CCLKMPWH}$	1.8		1.8		ns
Write clock minimum pulse width low	$T_{CCLKMPWL}$	1.8		1.8		ns
Write block setup time	T_{BLKCSU}	0.404		0.476		ns
Write block hold time	T_{BLKCHD}	0.007		0.008		ns
Write input data setup time	T_{DINCSU}	0.115		0.135		ns
Write input data hold time	T_{DINCHD}	0.15		0.177		ns
Write address setup time	$T_{ADDRCSU}$	0.088		0.104		ns
Write address hold time	$T_{ADDRCHD}$	0.128		0.15		ns
Write enable setup time	T_{WECSU}	0.397		0.467		ns
Write enable hold time	T_{WECHD}	–0.026		–0.03		ns
Maximum frequency	F_{MAX}		250		250	MHz

The following table lists the μ SRAM in 128 × 9 mode in worst commercial-case conditions when $T_J = 85^\circ\text{C}$, $V_{DD} = 1.14\text{ V}$.

Table 239 • μ SRAM (RAM128x9) in 128 × 9 Mode

Parameter	Symbol	–1		–Std		Unit
		Min	Max	Min	Max	
Read clock period	T_{CY}	4		4		ns
Read clock minimum pulse width high	$T_{CLKMPWH}$	1.8		1.8		ns
Read clock minimum pulse width low	$T_{CLKMPWL}$	1.8		1.8		ns
Read pipeline clock period	T_{PLCY}	4		4		ns
Read pipeline clock minimum pulse width high	$T_{PLCLKMPWH}$	1.8		1.8		ns
Read pipeline clock minimum pulse width low	$T_{PLCLKMPWL}$	1.8		1.8		ns
Read access time with pipeline register	T_{CLK2Q}		0.266		0.313	ns
Read access time without pipeline register			1.677		1.973	ns
Read address setup time in synchronous mode	T_{ADDRSU}	0.301		0.354		ns
Read address setup time in asynchronous mode		1.856		2.184		ns
Read address hold time in synchronous mode	T_{ADDRHD}	0.091		0.107		ns
Read address hold time in asynchronous mode		–0.778		–0.915		ns
Read enable setup time	T_{RDENSU}	0.278		0.327		ns
Read enable hold time	T_{RDENHD}	0.057		0.067		ns
Read block select setup time	T_{BLKSU}	1.839		2.163		ns
Read block select hold time	T_{BLKHD}	–0.65		–0.765		ns
Read block select to out disable time (when pipelined register is disabled)	T_{BLK2Q}		2.036		2.396	ns

Table 241 • μ SRAM (RAM256x4) in 256 × 4 Mode (continued)

Parameter	Symbol	-1		-Std		Unit
		Min	Max	Min	Max	
Write address hold time	$T_{ADDRCHD}$	0.245		0.288		ns
Write enable setup time	T_{WECSU}	0.397		0.467		ns
Write enable hold time	T_{WECHD}	-0.03		-0.03		ns
Maximum frequency	F_{MAX}		250		250	MHz

The following table lists the μ SRAM in 512 × 2 mode in worst commercial-case conditions when $T_J = 85^\circ\text{C}$, $V_{DD} = 1.14\text{ V}$.

Table 242 • μ SRAM (RAM512x2) in 512 × 2 Mode

Parameter	Symbol	-1		-Std		Unit
		Min	Max	Min	Max	
Read clock period	T_{CY}	4		4		ns
Read clock minimum pulse width high	$T_{CLKMPWH}$	1.8		1.8		ns
Read clock minimum pulse width low	$T_{CLKMPWL}$	1.8		1.8		ns
Read pipeline clock period	T_{PLCY}	4		4		ns
Read pipeline clock minimum pulse width high	$T_{PLCLKMPWH}$	1.8		1.8		ns
Read pipeline clock minimum pulse width low	$T_{PLCLKMPWL}$	1.8		1.8		ns
Read access time with pipeline register	T_{CLK2Q}		0.27		0.31	ns
Read access time without pipeline register			1.76		2.08	ns
Read address setup time in synchronous mode	T_{ADDRSU}	0.301		0.354		ns
Read address setup time in asynchronous mode		1.96		2.306		ns
Read address hold time in synchronous mode	T_{ADDRHD}	0.137		0.161		ns
Read address hold time in asynchronous mode		-0.58		-0.68		ns
Read enable setup time	T_{RDENSU}	0.278		0.327		ns
Read enable hold time	T_{RDENHD}	0.057		0.067		ns
Read block select setup time	T_{BLKSU}	1.839		2.163		ns
Read block select hold time	T_{BLKHD}	-0.65		-0.77		ns
Read block select to out disable time (when pipelined register is disabled)	T_{BLK2Q}		2.14		2.52	ns
Read asynchronous reset removal time (pipelined clock)	T_{RSTREM}	-0.02		-0.03		ns
Read asynchronous reset removal time (non-pipelined clock)		0.046		0.054		ns
Read asynchronous reset recovery time (pipelined clock)	T_{RSTREC}	0.507		0.597		ns
Read asynchronous reset recovery time (non-pipelined clock)		0.236		0.278		ns
Read asynchronous reset to output propagation delay (with pipelined register enabled)	T_{R2Q}		0.83		0.98	ns
Read synchronous reset setup time	T_{SRSTSU}	0.271		0.319		ns
Read synchronous reset hold time	T_{SRSTHD}	0.061		0.071		ns

The following table lists the math blocks with input register used and output in bypass mode in worst commercial-case conditions when $T_J = 85\text{ }^{\circ}\text{C}$, $V_{DD} = 1.14\text{ V}$.

Table 270 • Math Block with Input Register Used and Output in Bypass Mode

Parameter	Symbol	–1		–Std		Unit
		Min	Max	Min	Max	
Input register setup time	T_{MISU}	0.149		0.176		ns
Input register hold time	T_{MIHD}	0.185		0.218		ns
Synchronous reset/enable setup time	$T_{MSRSTENSU}$	0.08		0.094		ns
Synchronous reset/enable hold time	$T_{MSRSTENHD}$	–0.012		–0.014		ns
Asynchronous reset removal time	$T_{MARSTREM}$	–0.005		–0.005		ns
Asynchronous reset recovery time	$T_{MARSTREC}$	0.088		0.104		ns
Input register clock to output delay	T_{MICQ}		2.52		2.964	ns
CDIN to output delay	$T_{MCDIN2Q}$		1.951		2.295	ns

The following table lists the math blocks with input and output in bypass mode in worst commercial-case conditions when $T_J = 85\text{ }^{\circ}\text{C}$, $V_{DD} = 1.14\text{ V}$.

Table 271 • Math Block with Input and Output in Bypass Mode

Parameter	Symbol	–1	–Std	Unit
		Max	Max	
Input to output delay	T_{MIQ}	2.568	3.022	ns
CDIN to output delay	$T_{MCDIN2Q}$	1.951	2.295	ns

2.3.15 Embedded NVM (eNVM) Characteristics

The following table lists the eNVM read performance in worst-case conditions when $V_{DD} = 1.14\text{ V}$, $V_{PPNVM} = V_{PP} = 2.375\text{ V}$.

Table 272 • eNVM Read Performance

Symbol	Description	Operating Temperature Range						Unit
		–1	–Std	–1	–Std	–1	–Std	
T_J	Junction temperature range	–55 °C to 125 °C		–40 °C to 100 °C		0 °C to 85 °C		°C
$F_{MAXREAD}$	eNVM maximum read frequency	25	25	25	25	25	25	MHz

The following table lists the eNVM page programming in worst-case conditions when $V_{DD} = 1.14\text{ V}$, $V_{PPNVM} = V_{PP} = 2.375\text{ V}$.

Table 273 • eNVM Page Programming

Symbol	Description	Operating Temperature Range						Unit
		–1	–Std	–1	–Std	–1	–Std	
T_J	Junction temperature range	–55 °C to 125 °C		–40 °C to 100 °C		0 °C to 85 °C		°C
$T_{PAGEPGM}$	eNVM page programming time	40	40	40	40	40	40	ms

2.3.22 JTAG

Table 284 • JTAG 1532 for 005, 010, 025, and 050 Devices

Parameter	Symbol	005		010		025		050		Unit
		-1	-Std	-1	-Std	-1	-Std	-1	-Std	
Clock to Q (data out)	T_{TCK2Q}	7.47	8.79	7.73	9.09	7.75	9.12	7.89	9.28	ns
Reset to Q (data out)	T_{RSTB2Q}	7.65	9	6.43	7.56	6.13	7.21	7.40	8.70	ns
Test data input setup time	T_{DISU}	-1.05	-0.89	-0.69	-0.59	-0.67	-0.57	-0.30	-0.25	ns
Test data input hold time	T_{DIHD}	2.38	2.8	2.38	2.8	2.42	2.85	2.09	2.45	ns
Test mode select setup time	T_{TMSSU}	-0.73	-0.62	-1.03	-1.21	-1.1	-0.94	0.28	0.33	ns
Test mode select hold time	T_{TMDHD}	1.36	1.6	1.43	1.68	1.93	2.27	0.16	0.19	ns
ResetB removal time	$T_{TRSTREM}$	-0.77	-0.65	-1.08	-0.92	-1.33	-1.13	-0.45	-0.38	ns
ResetB recovery time	$T_{TRSTREC}$	-0.76	-0.65	-1.07	-0.91	-1.34	-1.14	-0.45	-0.38	ns
TCK maximum frequency	F_{TCKMAX}	25	21.25	25	21.25	25	21.25	25.00	21.25	MHz

Table 285 • JTAG 1532 for 060, 090, and 150 Devices

Parameter	Symbol	060		090		150		Unit
		-1	-Std	-1	-Std	-1	-Std	
Clock to Q (data out)	T_{TCK2Q}	8.38	9.86	8.96	10.54	8.66	10.19	ns
Reset to Q (data out)	T_{RSTB2Q}	8.54	10.04	7.75	9.12	8.79	10.34	ns
Test data input setup time	T_{DISU}	-1.18	-1	-1.31	-1.11	-0.96	-0.82	ns
Test data input hold time	T_{DIHD}	2.52	2.97	2.68	3.15	2.57	3.02	ns
Test mode select setup time	T_{TMSSU}	-0.97	-0.83	-1.02	-0.87	-0.53	-0.45	ns
Test mode select hold time	T_{TMDHD}	1.7	2	1.67	1.96	1.02	1.2	ns
ResetB removal time	$T_{TRSTREM}$	-1.21	-1.03	-0.76	-0.65	-1.03	-0.88	ns
ResetB recovery time	$T_{TRSTREC}$	-1.21	-1.03	-0.77	-0.65	-1.03	-0.88	ns
TCK maximum frequency	F_{TCKMAX}	25	21.25	25	21.25	25	21.25	MHz

2.3.23 System Controller SPI Characteristics

2.3.31.3 Serial Peripheral Interface (SPI) Characteristics

This section describes the DC and switching of the SPI interface. Unless otherwise noted, all output characteristics given are for a 35 pF load on the pins and all sequential timing characteristics are related to SPI_x_CLK. For timing parameter definitions, see [Figure 22](#), page 128.

The following table lists the SPI characteristics in worst-case industrial conditions when $T_J = 100\text{ }^{\circ}\text{C}$, $V_{DD} = 1.14\text{ V}$

Table 305 • SPI Characteristics for All Devices

Symbol	Description	Min	Typ	Max	Unit	Conditions
SPIFMAX	Maximum operating frequency of SPI interface			20	MHz	
sp1	SPI_[0 1]_CLK minimum period					
	SPI_[0 1]_CLK = PCLK/2	12			ns	
	SPI_[0 1]_CLK = PCLK/4	24.1			ns	
	SPI_[0 1]_CLK = PCLK/8	48.2			ns	
	SPI_[0 1]_CLK = PCLK/16	0.1			μs	
	SPI_[0 1]_CLK = PCLK/32	0.19			μs	
	SPI_[0 1]_CLK = PCLK/64	0.39			μs	
	SPI_[0 1]_CLK = PCLK/128	0.77			μs	
sp2	SPI_[0 1]_CLK minimum pulse width high					
	SPI_[0 1]_CLK = PCLK/2	6			ns	
	SPI_[0 1]_CLK = PCLK/4	12.05			ns	
	SPI_[0 1]_CLK = PCLK/8	24.1			ns	
	SPI_[0 1]_CLK = PCLK/16	0.05			μs	
	SPI_[0 1]_CLK = PCLK/32	0.095			μs	
	SPI_[0 1]_CLK = PCLK/64	0.195			μs	
	SPI_[0 1]_CLK = PCLK/128	0.385			μs	
sp3	SPI_[0 1]_CLK minimum pulse width low					
	SPI_[0 1]_CLK = PCLK/2	6			ns	
	SPI_[0 1]_CLK = PCLK/4	12.05			ns	
	SPI_[0 1]_CLK = PCLK/8	24.1			ns	
	SPI_[0 1]_CLK = PCLK/16	0.05			μs	
	SPI_[0 1]_CLK = PCLK/32	0.095			μs	
	SPI_[0 1]_CLK = PCLK/64	0.195			μs	
	SPI_[0 1]_CLK = PCLK/128	0.385			μs	
sp4	SPI_[0 1]_CLK, SPI_[0 1]_DO, SPI_[0 1]_SS rise time (10%–90%) ¹		2.77		ns	I/O Configuration: LVCMOS 2.5 V– 8 mA AC loading: 35 pF Test conditions: Typical voltage, 25 °C

Table 305 • SPI Characteristics for All Devices (continued)

Symbol	Description	Min	Typ	Max	Unit	Conditions
sp5	SPI_[0 1]_CLK, SPI_[0 1]_DO, SPI_[0 1]_SS fall time (10%– 90%) ¹		2.906		ns	IO Configuration: LVCMOS 2.5 V-8 mA AC Loading: 35 pF Test Conditions: Typical Voltage, 25 °C
SPI master configuration (applicable for 005, 010, 025, and 050 devices)						
sp6m	SPI_[0 1]_DO setup time ²	$(\text{SPI_x_CLK_period}/2) - 8.0$			ns	
sp7m	SPI_[0 1]_DO hold time ²	$(\text{SPI_x_CLK_period}/2) - 2.5$			ns	
sp8m	SPI_[0 1]_DI setup time ²	12			ns	
sp9m	SPI_[0 1]_DI hold time ²	2.5			ns	
SPI slave configuration (applicable for 005, 010, 025, and 050 devices)						
sp6s	SPI_[0 1]_DO setup time ²	$(\text{SPI_x_CLK_period}/2) - 17.0$			ns	
sp7s	SPI_[0 1]_DO hold time ²	$(\text{SPI_x_CLK_period}/2) + 3.0$			ns	
sp8s	SPI_[0 1]_DI setup time ²	2			ns	
sp9s	SPI_[0 1]_DI hold time ²	7			ns	
SPI master configuration (applicable for 060, 090, and 150 devices)						
sp6m	SPI_[0 1]_DO setup time ²	$(\text{SPI_x_CLK_period}/2) - 7.0$			ns	
sp7m	SPI_[0 1]_DO hold time ²	$(\text{SPI_x_CLK_period}/2) - 9.5$			ns	
sp8m	SPI_[0 1]_DI setup time ²	15			ns	
sp9m	SPI_[0 1]_DI hold time ²	-2.5			ns	
SPI slave configuration (applicable for 060, 090, and 150 devices)						
sp6s	SPI_[0 1]_DO setup time ²	$(\text{SPI_x_CLK_period}/2) - 16.0$			ns	
sp7s	SPI_[0 1]_DO hold time ²	$(\text{SPI_x_CLK_period}/2) - 3.5$			ns	
sp8s	SPI_[0 1]_DI setup time ²	3			ns	
sp9s	SPI_[0 1]_DI hold time ²	2.5			ns	

1. For specific Rise/Fall Times board design considerations and detailed output buffer resistances, use the corresponding IBIS models located on the Microsemi SoC Products Group website: <http://www.microsemi.com/soc/download/ibis/default.aspx>.
2. For allowable pclk configurations, see Serial Peripheral Interface Controller section in the *UG0331: SmartFusion2 Microcontroller Subsystem User Guide*.

Table 310 • SPI Characteristics for All Devices (continued)

Symbol	Description	Min	Typ	Max	Unit	Conditions
sp2	SPI_[0 1]_CLK minimum pulse width high					
	SPI_[0 1]_CLK = PCLK/2	6			ns	
	SPI_[0 1]_CLK = PCLK/4	12.05			ns	
	SPI_[0 1]_CLK = PCLK/8	24.1			ns	
	SPI_[0 1]_CLK = PCLK/16	0.05			µs	
	SPI_[0 1]_CLK = PCLK/32	0.095			µs	
	SPI_[0 1]_CLK = PCLK/64	0.195			µs	
	SPI_[0 1]_CLK = PCLK/128	0.385			µs	
sp3	SPI_[0 1]_CLK minimum pulse width low					
	SPI_[0 1]_CLK = PCLK/2	6			ns	
	SPI_[0 1]_CLK = PCLK/4	12.05			ns	
	SPI_[0 1]_CLK = PCLK/8	24.1			ns	
	SPI_[0 1]_CLK = PCLK/16	0.05			µs	
	SPI_[0 1]_CLK = PCLK/32	0.095			µs	
	SPI_[0 1]_CLK = PCLK/64	0.195			µs	
	SPI_[0 1]_CLK = PCLK/128	0.385			µs	
sp4	SPI_[0 1]_CLK, SPI_[0 1]_DO, SPI_[0 1]_SS rise time (10%–90%) ¹		2.77		ns	I/O Configuration: LVCMOS 2.5 V - 8 mA AC loading: 35 pF test conditions: Typical voltage, 25 °C
sp5	SPI_[0 1]_CLK, SPI_[0 1]_DO, SPI_[0 1]_SS fall time (10%–90%) ¹		2.906		ns	I/O Configuration: LVCMOS 2.5 V - 8 mA AC loading: 35 pF test conditions: Typical voltage, 25 °C
SPI master configuration (applicable for 005, 010, 025, and 050 devices)						
sp6m	SPI_[0 1]_DO setup time ²	(SPI_x_CLK_period/2) – 8.0			ns	
sp7m	SPI_[0 1]_DO hold time ²	(SPI_x_CLK_period/2) – 2.5			ns	
sp8m	SPI_[0 1]_DI setup time ²	12			ns	
sp9m	SPI_[0 1]_DI hold time ²	2.5			ns	
SPI slave configuration (applicable for 005, 010, 025, and 050 devices)						
sp6s	SPI_[0 1]_DO setup time ²	(SPI_x_CLK_period/2) – 17.0			ns	
sp7s	SPI_[0 1]_DO hold time ²	(SPI_x_CLK_period/2) + 3.0			ns	
sp8s	SPI_[0 1]_DI setup time ²	2			ns	
sp9s	SPI_[0 1]_DI hold time ²	7			ns	