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Embedded - System On Chip (SoC): The Heart of Modern Embedded Systems

Embedded - System On Chip (SoC) refers to an integrated circuit that consolidates all the essential components of a computer system into a single chip. This includes a microprocessor, memory, and other peripherals, all packed into one compact and efficient package. SoCs are designed to provide a complete computing solution, optimizing both space and power consumption, making them ideal for a wide range of embedded applications.

What are Embedded - System On Chip (SoC)?

System On Chip (SoC) integrates multiple functions of a computer or electronic system onto a single chip. Unlike traditional multi-chip solutions, SoCs combine a central

Details

Product Status	Active
Architecture	MCU, FPGA
Core Processor	ARM® Cortex®-M3
Flash Size	128KB
RAM Size	64KB
Peripherals	-
Connectivity	CANbus, Ethernet, I ² C, SPI, UART/USART, USB
Speed	166MHz
Primary Attributes	FPGA - 5K Logic Modules
Operating Temperature	0°C ~ 85°C (TJ)
Package / Case	144-LQFP
Supplier Device Package	144-TQFP (20x20)
Purchase URL	https://www.e-xfl.com/product-detail/microchip-technology/m2s005s-1tqg144

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2.2 References

The following documents are recommended references:

- *PB0121: IGLOO2 Product Brief*
- *DS0124: IGLOO2 Pin Descriptions*
- *PB0115: SmartFusion2 SoC FPGA Product Brief*
- *DS0115: SmartFusion2 Pin Descriptions*

All product documentation for IGLOO2 and SmartFusion2 is available at:

<http://www.microsemi.com/products/fpga-soc/fpga/igloo2-fpga>

<http://www.microsemi.com/products/fpga-soc/soc-fpga/smartfusion2#overview>

2.3 Electrical Specifications

2.3.1 Operating Conditions

The following table lists the stress limits. Stress applied above the specified limit may cause permanent damage to the device. Exposure to absolute maximum rating conditions for extended periods may affect device reliability.

Absolute maximum ratings are stress ratings only; functional operation of the device at these or any other conditions beyond those listed under the recommended operating conditions specified in the following table are not implied.

Table 3 • Absolute Maximum Ratings

Parameter	Symbol	Min	Max	Unit
DC core supply voltage. Must always power this pin.	V_{DD}	-0.3	1.32	V
Power supply for charge pumps (for normal operation and programming). Must always power this pin.	V_{PP}	-0.3	3.63	V
Analog power pad for MDDR PLL	MSS_MDDR_PLL_VDDA	-0.3	3.63	V
Analog power pad for MDDR PLL	HPMS_MDDR_PLL_VDDA	-0.3	3.63	V
Analog power pad for FDDR PLL	FDDR_PLL_VDDA	-0.3	3.63	V
Analog power pad for MDDR PLL	PLL0_PLL1_MSS_MDDR_VDDA	-0.3	3.63	V
Analog power pad for MDDR PLL	PLL0_PLL1_HPMS_MDDR_VDDA	-0.3	3.63	V
Analog power pad for PLL0-5	CCC_XX[01]_PLL_VDDA	-0.3	3.63	V
High supply voltage for PLL SerDes[01]	SERDES_[01]_PLL_VDDA	-0.3	3.63	V
Analog power for SerDes[01] PLL lane0 to lane3. This is a 2.5 V SerDes internal PLL supply.	SERDES_[01]_L[0123]_VDDAPLL	-0.3	2.75	V
TX/RX analog I/O voltage. Low voltage power for the lanes of SerDesIF0. This is a 1.2 V SerDes PMA supply.	SERDES_[01]_L[0123]_VDDAIO	-0.3	1.32	V
PCIe/PCS power supply	SERDES_[01]_VDD	-0.3	1.32	V
DC FPGA I/O buffer supply voltage for MSIO I/O bank	V_{DDIx}	-0.3	3.63	V
DC FPGA I/O buffer supply voltage for MSIOD/DDRIO I/O banks	V_{DDIx}	-0.3	2.75	V
I/O Input voltage for MSIO I/O bank	V_I	-0.3	3.63	V
I/O Input voltage for MSIOD/DDRIO I/O bank	V_I	-0.3	2.75	V
Analog sense circuit supply of embedded nonvolatile memory (eNVM). Must be shorted to V_{PP} .	V_{PPNVM}	-0.3	3.63	V
Storage temperature ¹	T_{STG}	-65	150	°C
Junction temperature	T_J	-55	135	°C

The following table lists the embedded operating flash limits.

Table 6 • Embedded Operating Flash Limits

Product Grade	Element	Programming Temperature	Maximum Operating Temperature	Programming Cycles	Retention (Biased/Unbiased)
Commercial	Embedded flash	Min $T_J = 0\text{ }^\circ\text{C}$ Max $T_J = 85\text{ }^\circ\text{C}$	Min $T_J = 0\text{ }^\circ\text{C}$ Max $T_J = 85\text{ }^\circ\text{C}$	< 1000 cycles per page, up to two million cycles per eNVM array	20 years
				Min $T_J = 0\text{ }^\circ\text{C}$ Max $T_J = 85\text{ }^\circ\text{C}$	< 10000 cycles per page, up to 20 million cycles per eNVM array
Industrial	Embedded flash	Min $T_J = -40\text{ }^\circ\text{C}$ Max $T_J = 100\text{ }^\circ\text{C}$	Min $T_J = -40\text{ }^\circ\text{C}$ Max $T_J = 100\text{ }^\circ\text{C}$	< 1000 cycles per page, up to two million cycles per eNVM array	20 years
				Min $T_J = -40\text{ }^\circ\text{C}$ Max $T_J = 100\text{ }^\circ\text{C}$	< 10000 cycles per page, up to 20 million cycles per eNVM array

Note: If your product qualification requires accelerated programming cycles, see [Microsemi SoC Products Quality and Reliability Report](#) about recommended methodologies.

Table 7 • Device Storage Temperature and Retention

Product Grade	Storage Temperature (Tstg)	Retention
Commercial	Min $T_J = 0\text{ }^\circ\text{C}$ Max $T_J = 85\text{ }^\circ\text{C}$	20 years
Industrial	Min $T_J = -40\text{ }^\circ\text{C}$ Max $T_J = 100\text{ }^\circ\text{C}$	20 years

Table 8 • High Temperature Data Retention (HTR) Lifetime

T_J (C)	HTR Lifetime ¹ (yrs)
90	20.5
95	20.5
100	20.5
105	17.0
110	15.0
115	13.0
120	11.5
125	10.0
130	8.0
135	6.0
140	4.5
145	3.0
150	1.5

1. HTR Lifetime is the period during which a verify failure is not expected due to flash leakage.

Table 9 • Package Thermal Resistance of SmartFusion2 and IGLOO2 Devices (continued)

Device	Still Air	1.0 m/s	2.5 m/s	θ_{JB}	θ_{JC}	Unit
	θ_{JA}					
150						
FC1152	9.08	6.81	5.87	2.56	0.38	°C/W
FCS536	15.01	12.06	10.76	3.69	1.55	°C/W
FCV484	16.21	13.11	11.84	6.73	0.10	°C/W

2.3.1.2.1 Theta-JA

Junction-to-ambient thermal resistance (θ_{JA}) is determined under standard conditions specified by JEDEC (JESD-51), but it has little relevance in the actual performance of the product. It must be used with caution, but it is useful for comparing the thermal performance of one package with another.

The maximum power dissipation allowed is calculated using EQ4.

$$\text{Maximum power allowed} = \frac{T_{J(\text{MAX})} - T_{A(\text{MAX})}}{\theta_{JA}}$$

EQ 4

The absolute maximum junction temperature is 100 °C. EQ5 shows a sample calculation of the absolute maximum power dissipation allowed for the M2GL050T-FG896 package at commercial temperature and in still air, where:

$$\theta_{JA} = 14.7 \text{ °C/W (taken from Table 9, page 10).}$$

$$T_A = 85 \text{ °C}$$

$$\text{Maximum power allowed} = \frac{100 \text{ °C} - 85 \text{ °C}}{14.7 \text{ °C/W}} = 1.088 \text{ W}$$

EQ 5

The power consumption of a device can be calculated using the Microsemi SoC Products Group power calculator. The device's power consumption must be lower than the calculated maximum power dissipation by the package.

If the power consumption is higher than the device's maximum allowable power dissipation, a heat sink may be attached to the top of the case, or the airflow inside the system must be increased.

2.3.1.2.2 Theta-JB

Junction-to-board thermal resistance (θ_{JB}) measures the ability of the package to dissipate heat from the surface of the chip to the PCB. As defined by the JEDEC (JESD-51) standard, the thermal resistance from the junction to the board uses an isothermal ring cold plate zone concept. The ring cold plate is simply a means to generate an isothermal boundary condition at the perimeter. The cold plate is mounted on a JEDEC standard board with a minimum distance of 5.0 mm away from the package edge.

2.3.1.2.3 Theta-JC

Junction-to-case thermal resistance (θ_{JC}) measures the ability of a device to dissipate heat from the surface of the chip to the top or bottom surface of the package. It is applicable to packages used with external heat sinks. Constant temperature is applied to the surface, which acts as a boundary condition.

This only applies to situations where all or nearly all of the heat is dissipated through the surface in consideration.

2.3.1.3 ESD Performance

See *RT0001: Microsemi Corporation - SoC Products Reliability Report* for information about ESD.

2.3.5 User I/O Characteristics

There are three types of I/Os supported in the IGLOO2 FPGA and SmartFusion2 SoC FPGA families: MSIO, MSIOD, and DDRIO I/O banks. The I/O standards supported by the different I/O banks is described in the I/Os section of the *UG0445: IGLOO2 FPGA and SmartFusion2 SoC FPGA Fabric User Guide*.

2.3.5.1 Input Buffer and AC Loading

The following figure shows the input buffer and AC loading.

Figure 3 • Input Buffer AC Loading

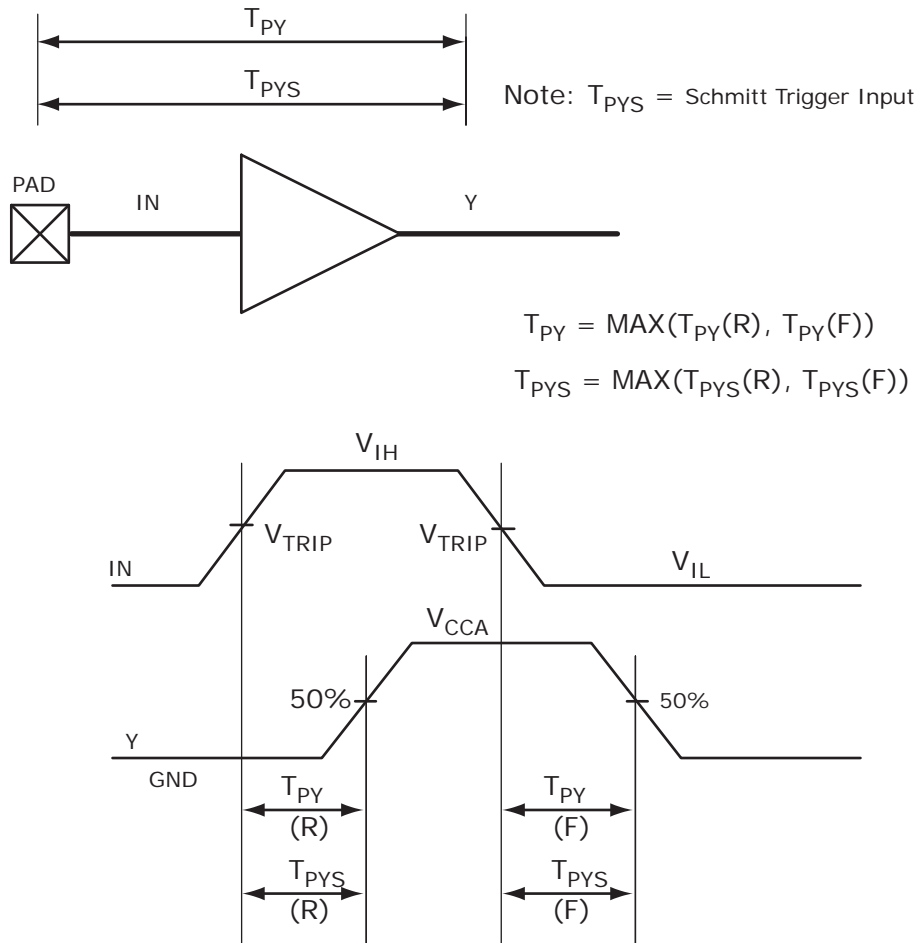


Table 34 • LVTTTL/LVCMOS 3.3 V AC Test Parameter Specifications (Applicable to MSIO I/O Bank Only)

Parameter	Symbol	Typ	Unit
Measuring/trip point for data path	V_{TRIP}	1.4	V
Resistance for enable path (T_{ZH} , T_{ZL} , T_{HZ} , T_{LZ})	R_{ENT}	2K	Ω
Capacitive loading for enable path (T_{ZH} , T_{ZL} , T_{HZ} , T_{LZ})	C_{ENT}	5	pF
Capacitive loading for data path (T_{DP})	C_{LOAD}	5	pF

Table 35 • LVTTTL/LVCMOS 3.3 V Transmitter Drive Strength Specifications for MSIO I/O Bank

Output Drive Selection	V_{OH} (V)	V_{OL} (V)	IOH (at V_{OH}) mA	IOL (at V_{OL}) mA
2 mA	$V_{DDI} - 0.4$	0.4	2	2
4 mA	$V_{DDI} - 0.4$	0.4	4	4
8 mA	$V_{DDI} - 0.4$	0.4	8	8
12 mA	$V_{DDI} - 0.4$	0.4	12	12
16 mA	$V_{DDI} - 0.4$	0.4	16	16
20 mA	$V_{DDI} - 0.4$	0.4	20	20

Note: For a detailed I/V curve, use the corresponding IBIS models:
www.microsemi.com/soc/download/ibis/default.aspx.

AC Switching Characteristics

Worst commercial-case conditions: $T_J = 85\text{ }^\circ\text{C}$, $V_{DD} = 1.14\text{ V}$, $V_{DDI} = 3.0\text{ V}$

Table 36 • LVTTTL/LVCMOS 3.3 V Receiver Characteristics for MSIO I/O Bank (Input Buffers)

On-Die Termination (ODT)	T_{PY}		T_{PYS}		Unit
	-1	-Std	-1	-Std	
None	2.262	2.663	2.289	2.695	ns

Table 37 • LVTTTL/LVCMOS 3.3 V Transmitter Characteristics for MSIO I/O Bank (Output and Tristate Buffers)

Output Drive Selection	Slew Control	T_{DP}		T_{ZL}		T_{ZH}		T_{HZ}^1		T_{LZ}^1		Unit
		-1	-Std	-1	-Std	-1	-Std	-1	-Std	-1	-Std	
2 mA	Slow	3.192	3.755	3.47	4.083	2.969	3.494	1.856	2.183	3.337	3.926	ns
4 mA	Slow	2.331	2.742	2.673	3.145	2.526	2.973	3.034	3.569	4.451	5.236	ns
8 mA	Slow	2.135	2.511	2.33	2.741	2.297	2.703	4.532	5.331	4.825	5.676	ns
12 mA	Slow	2.052	2.414	2.107	2.479	2.162	2.544	5.75	6.764	5.445	6.406	ns
16 mA	Slow	2.062	2.425	2.072	2.438	2.145	2.525	5.993	7.05	5.625	6.618	ns
20 mA	Slow	2.148	2.527	1.999	2.353	2.088	2.458	6.262	7.367	5.876	6.913	ns

1. Delay increases with drive strength are inherent to built-in slew control circuitry for simultaneous switching output (SSO) management.

AC Switching Characteristics

Worst commercial-case conditions: $T_J = 85\text{ }^\circ\text{C}$, $V_{DD} = 1.14\text{ V}$, $V_{DDI} = 1.425\text{ V}$

Table 67 • LVCMOS 1.5 V Receiver Characteristics for DDRIO I/O Bank with Fixed Codes (Input Buffers)

On-Die Termination (ODT)	T_{PY}		T_{PYS}		Unit
	-1	-Std	-1	-Std	
None	2.051	2.413	2.086	2.455	ns

Table 68 • LVCMOS 1.5 V Receiver Characteristics for MSIO I/O Bank (Input Buffers)

On-Die Termination (ODT)	T_{PY}		T_{PYS}		Unit
	-1	-Std	-1	-Std	
None	3.311	3.896	3.285	3.865	ns
50	3.654	4.299	3.623	4.263	ns
75	3.533	4.156	3.501	4.119	ns
150	3.415	4.018	3.388	3.986	ns

Table 69 • LVCMOS 1.5 V Receiver Characteristics for MSIOD I/O Bank (Input Buffers)

On-Die Termination (ODT)	T_{PY}		T_{PYS}		Unit
	-1	-Std	-1	-Std	
None	2.959	3.481	2.93	3.447	ns
50	3.298	3.88	3.268	3.845	ns
75	3.162	3.719	3.128	3.68	ns
150	3.053	3.592	3.021	3.554	ns

Table 70 • LVCMOS 1.5 V Transmitter Characteristics for DDRIO I/O Bank (Output and Tristate Buffers)

Output Drive Selection	Slew Control	T_{DP}		T_{ZL}		T_{ZH}		T_{HZ}^1		T_{LZ}^1		Unit
		-1	-Std	-1	-Std	-1	-Std	-1	-Std	-1	-Std	
2 mA	Slow	5.122	6.026	4.31	5.07	5.145	6.052	5.258	6.186	4.672	5.496	ns
	Medium	4.58	5.389	3.86	4.54	4.6	5.411	4.977	5.855	4.357	5.126	ns
	Medium fast	4.323	5.086	3.629	4.269	4.341	5.107	4.804	5.652	4.228	4.974	ns
	Fast	4.296	5.054	3.609	4.245	4.314	5.075	4.791	5.636	4.219	4.963	ns
4 mA	Slow	4.449	5.235	3.707	4.361	4.443	5.227	6.058	7.127	5.458	6.421	ns
	Medium	3.961	4.66	3.264	3.839	3.954	4.651	5.778	6.797	5.116	6.018	ns
	Medium fast	3.729	4.387	3.043	3.579	3.72	4.376	5.63	6.624	4.981	5.86	ns
	Fast	3.704	4.358	3.027	3.56	3.695	4.347	5.624	6.617	4.973	5.851	ns

Table 95 • HSTL DC Output Voltage Specification Applicable to DDRIO I/O Bank Only

Parameter	Symbol	Min	Max	Unit
HSTL Class I				
DC output logic high	V_{OH}	$V_{DDI} - 0.4$		V
DC output logic low	V_{OL}		0.4	V
Output minimum source DC current (MSIO and DDRIO I/O banks)	I_{OH} at V_{OH}	-8.0		mA
Output minimum sink current (MSIO and DDRIO I/O banks)	I_{OL} at V_{OL}	8.0		mA
HSTL Class II				
DC output logic high	V_{OH}	$V_{DDI} - 0.4$		V
DC output logic low	V_{OL}		0.4	V
Output minimum source DC current	I_{OH} at V_{OH}	-16.0		mA
Output minimum sink current	I_{OL} at V_{OL}	16.0		mA

Table 96 • HSTL DC Differential Voltage Specification

Parameter	Symbol	Min	Unit
DC input differential voltage	V_{ID} (DC)	0.2	V

Table 97 • HSTL AC Differential Voltage Specifications

Parameter	Symbol	Min	Max	Unit
AC input differential voltage	V_{DIFF}	0.4		V
AC differential cross point voltage	V_x	0.68	0.9	V

Table 98 • HSTL Minimum and Maximum AC Switching Speed

Parameter	Symbol	Max	Unit	Conditions
Maximum data rate	D_{MAX}	400	Mbps	AC loading: per JEDEC specifications

Table 99 • HSTL Impedance Specification

Parameter	Symbol	Typ	Unit	Conditions
Supported output driver calibrated impedance (for DDRIO I/O bank)	R_{REF}	25.5, 47.8	Ω	Reference resistance = 191 Ω
Effective impedance value (ODT for DDRIO I/O bank only)	R_{TT}	47.8	Ω	Reference resistance = 191 Ω

Figure 7 • I/O Register Input Timing Diagram

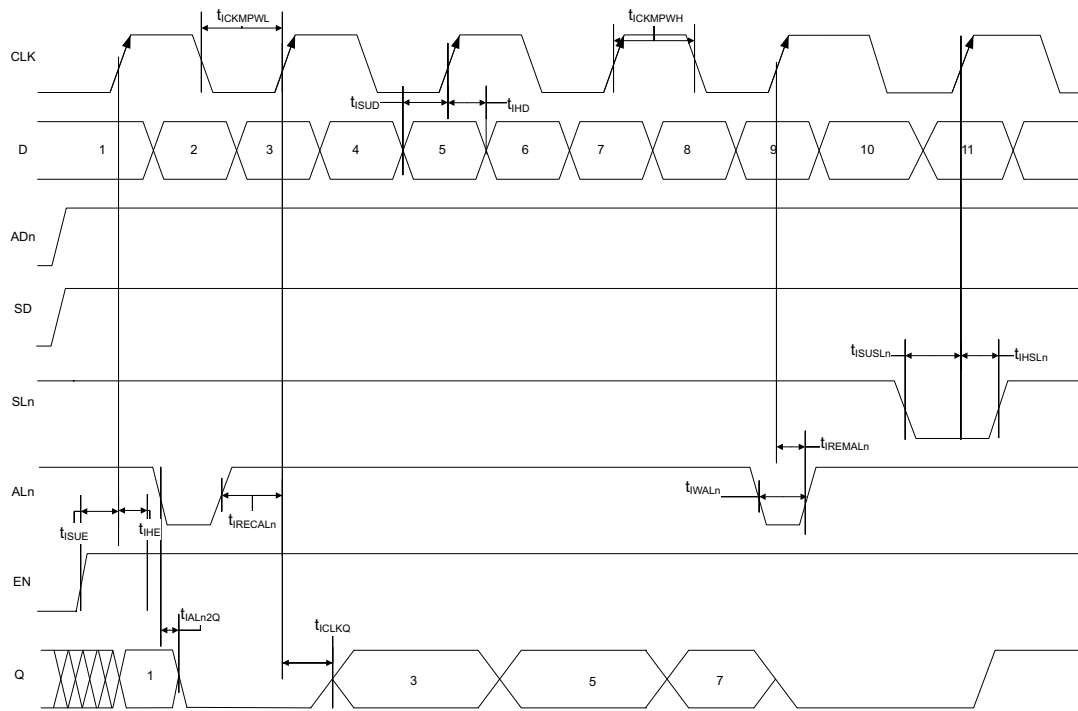
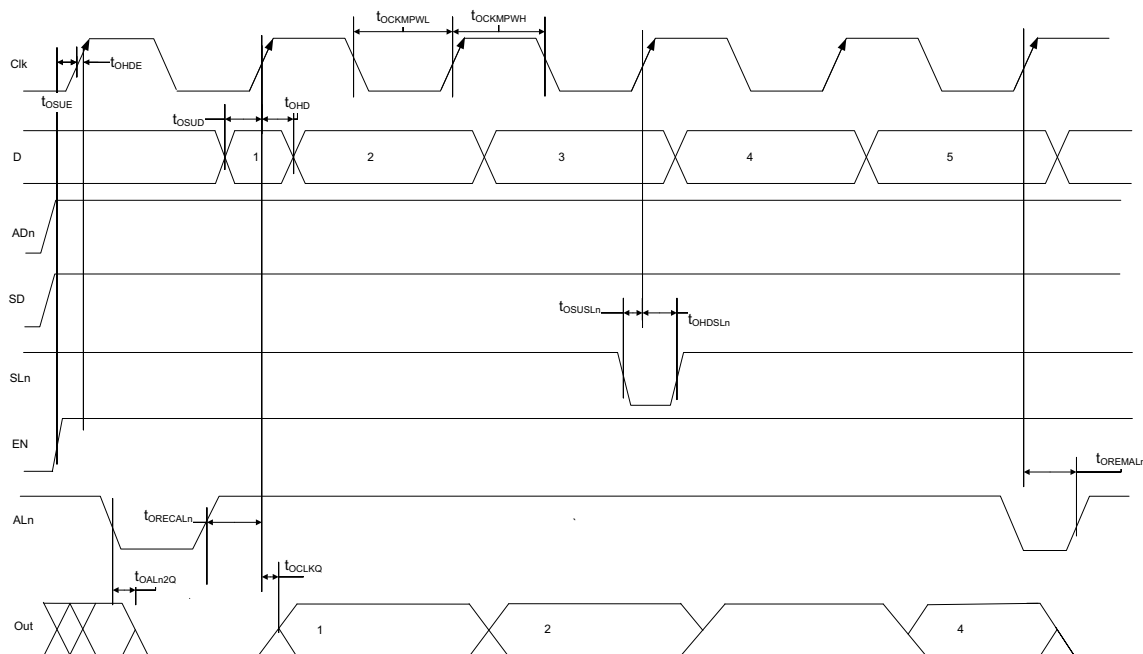


Figure 9 • I/O Register Output Timing Diagram



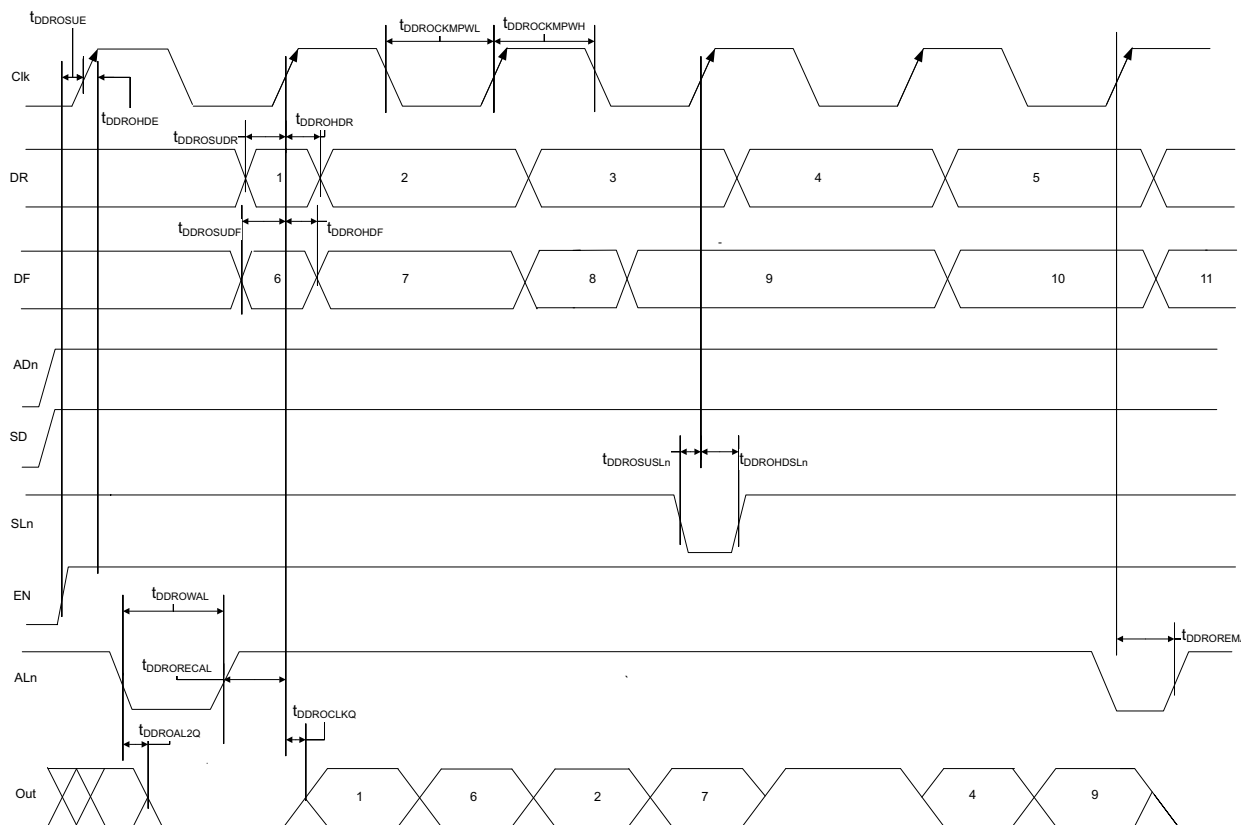
The following table lists the output/enable propagation delays in worst commercial-case conditions when $T_J = 85\text{ }^\circ\text{C}$, $V_{DD} = 1.14\text{ V}$.

Table 220 • Output/Enable Data Register Propagation Delays

Parameter	Symbol	Measuring Nodes (from, to) ¹	-1	-Std	Unit
Bypass delay of the output/enable register	T_{OBYP}	F, G or H, I	0.353	0.415	ns
Clock-to-Q of the output/enable register	T_{OCLKQ}	E, G or E, I	0.263	0.309	ns
Data setup time for the output/enable register	T_{OSUD}	A, E or J, E	0.19	0.223	ns
Data hold time for the output/enable register	T_{OHD}	A, E or J, E	0	0	ns
Enable setup time for the output/enable register	T_{OSUE}	B, E	0.419	0.493	ns
Enable hold time for the output/enable register	T_{OHE}	B, E	0	0	ns
Synchronous load setup time for the output/enable register	T_{OSUSL}	D, E	0.196	0.231	ns
Synchronous load hold time for the output/enable register	T_{OHSL}	D, E	0	0	ns
Asynchronous clear-to-q of the output/enable register (ADn = 1)	T_{OALN2Q}	C, G or C, I	0.505	0.594	ns
Asynchronous preset-to-q of the output/enable register (ADn = 0)		C, G or C, I	0.528	0.621	ns
Asynchronous load removal time for the output/enable register	$T_{OREMALN}$	C, E	0	0	ns
Asynchronous load recovery time for the output/enable register	$T_{ORECALN}$	C, E	0.034	0.04	ns
Asynchronous load minimum pulse width for the output/enable register	T_{OWALN}	C, C	0.304	0.357	ns
Clock minimum pulse width high for the output/enable register	$T_{OACKMPWH}$	E, E	0.075	0.088	ns
Clock minimum pulse width low for the output/enable register	$T_{OACKMPWL}$	E, E	0.159	0.187	ns

1. For the derating values at specific junction temperature and voltage supply levels, see Table 16, page 14 for derating values.

Figure 13 • Output DDR Timing Diagram



2.3.9.5 Timing Characteristics

The following table lists the output DDR propagation delays in worst commercial-case conditions when $T_J = 85^\circ\text{C}$, $V_{DD} = 1.14\text{ V}$.

Table 222 • Output DDR Propagation Delays

Symbol	Description	Measuring Nodes (from, to)	-1	-Std	Unit
$T_{DDROCLKQ}$	Clock-to-out of DDR for output DDR	E, G	0.263	0.309	ns
$T_{DDROSUDF}$	Data_F data setup for output DDR	F, E	0.143	0.168	ns
$T_{DDROSUDR}$	Data_R data setup for output DDR	A, E	0.19	0.223	ns
$T_{DDROHDF}$	Data_F data hold for output DDR	F, E	0	0	ns
$T_{DDROHDR}$	Data_R data hold for output DDR	A, E	0	0	ns
$T_{DDROSUE}$	Enable setup for input DDR	B, E	0.419	0.493	ns
T_{DDROHE}	Enable hold for input DDR	B, E	0	0	ns
$T_{DDROSUSLn}$	Synchronous load setup for input DDR	D, E	0.196	0.231	ns
$T_{DDROHSLn}$	Synchronous load hold for input DDR	D, E	0	0	ns
$T_{DDROAL2Q}$	Asynchronous load-to-out for output DDR	C, G	0.528	0.621	ns
$T_{DDROREMA}$	Asynchronous load removal time for output DDR	C, E	0	0	ns
$T_{DDRORECAL}$	Asynchronous load recovery time for output DDR	C, E	0.034	0.04	ns

The following table lists the μ SRAM in 256×4 mode in worst commercial-case conditions when $T_J = 85^\circ\text{C}$, $V_{DD} = 1.14\text{ V}$.

Table 241 • μ SRAM (RAM256x4) in 256×4 Mode

Parameter	Symbol	-1		-Std		Unit
		Min	Max	Min	Max	
Read clock period	T_{CY}	4		4		ns
Read clock minimum pulse width high	$T_{CLKMPWH}$	1.8		1.8		ns
Read clock minimum pulse width low	$T_{CLKMPWL}$	1.8		1.8		ns
Read pipeline clock period	T_{PLCY}	4		4		ns
Read pipeline clock minimum pulse width high	$T_{PLCLKMPWH}$	1.8		1.8		ns
Read pipeline clock minimum pulse width low	$T_{PLCLKMPWL}$	1.8		1.8		ns
Read access time with pipeline register	T_{CLK2Q}		0.27		0.31	ns
Read access time without pipeline register				1.75		2.06
Read address setup time in synchronous mode	T_{ADDRSU}	0.301		0.354		ns
Read address setup time in asynchronous mode			1.931		2.272	
Read address hold time in synchronous mode	T_{ADDRHD}	0.121		0.142		ns
Read address hold time in asynchronous mode			-0.65		-0.76	
Read enable setup time	T_{RDENSU}	0.278		0.327		ns
Read enable hold time	T_{RDENHD}	0.057		0.067		ns
Read block select setup time	T_{BLKSU}	1.839		2.163		ns
Read block select hold time	T_{BLKHD}	-0.65		-0.77		ns
Read block select to out disable time (when pipelined register is disabled)	T_{BLK2Q}		2.09		2.46	ns
Read asynchronous reset removal time (pipelined clock)	T_{RSTREM}	-0.02		-0.03		ns
Read asynchronous reset removal time (non-pipelined clock)			0.046		0.054	
Read asynchronous reset recovery time (pipelined clock)	T_{RSTREC}	0.507		0.597		ns
Read asynchronous reset recovery time (non-pipelined clock)			0.236		0.278	
Read asynchronous reset to output propagation delay (with pipelined register enabled)	T_{R2Q}		0.83		0.98	ns
Read synchronous reset setup time	T_{SRSTSU}	0.271		0.319		ns
Read synchronous reset hold time	T_{SRSTHD}	0.061		0.071		ns
Write clock period	T_{CCY}	4		4		ns
Write clock minimum pulse width high	$T_{CCCLKMPWH}$	1.8		1.8		ns
Write clock minimum pulse width low	$T_{CCCLKMPWL}$	1.8		1.8		ns
Write block setup time	T_{BLKCSU}	0.404		0.476		ns
Write block hold time	T_{BLKCHD}	0.007		0.008		ns
Write input data setup time	T_{DINCSU}	0.101		0.118		ns
Write input data hold time	T_{DINCHD}	0.137		0.161		ns
Write address setup time	$T_{ADDRCSU}$	0.088		0.104		ns

Table 245 • JTAG Programming (eNVM Only)

M2S/M2GL				
Device	Image size Bytes	Program	Verify	Unit
005	137536	39	4	Sec
010	274816	78	9	Sec
025	274816	78	9	Sec
050	278528	84	8	Sec
060	268480	76	8	Sec
090	544496	154	15	Sec
150	544496	155	15	Sec

Table 246 • JTAG Programming (Fabric and eNVM)

M2S/M2GL				
Device	Image size Bytes	Program	Verify	Unit
005	439296	59	11	Sec
010	842688	107	20	Sec
025	1497408	120	35	Sec
050	2695168	162	59	Sec
060	2686464	158	70	Sec
090	4190208	266	147	Sec
150	6682768	316	231	Sec

Table 247 • 2 Step IAP Programming (Fabric Only)

M2S/M2GL					
Device	Image size Bytes	Authenticate	Program	Verify	Unit
005	302672	4	17	6	Sec
010	568784	7	23	12	Sec
025	1223504	14	33	23	Sec
050	2424832	29	52	40	Sec
060	2418896	39	61	50	Sec
090	3645968	60	84	73	Sec
150	6139184	100	132	120	Sec

The following table lists the programming times in worst-case conditions when $T_J = 100\text{ }^\circ\text{C}$, $V_{DD} = 1.14\text{ V}$. External SPI flash part# AT25DF641-s3H is used during this measurement.

Table 256 • JTAG Programming (Fabric Only)

M2S/M2GL Device	Image size		Verify	Unit
	Bytes	Program		
005	302672	44	10	Sec
010	568784	50	18	Sec
025	1223504	73	26	Sec
050	2424832	88	54	Sec
060	2418896	99	54	Sec
090	3645968	135	126	Sec
150	6139184	177	193	Sec

Table 257 • JTAG Programming (eNVM Only)

M2S/M2GL Device	Image size		Verify	Unit
	Bytes	Program		
005	137536	61	4	Sec
010	274816	100	9	Sec
025	274816	100	9	Sec
050	2,78,528	106	8	Sec
060	268480	98	8	Sec
090	544496	176	15	Sec
150	544496	177	15	Sec

Table 258 • JTAG Programming (Fabric and eNVM)

M2S/M2GL Device	Image size		Verify	Unit
	Bytes	Program		
005	439296	71	11	Sec
010	842688	129	20	Sec
025	1497408	142	35	Sec
050	2695168	184	59	Sec
060	2686464	180	70	Sec
090	4190208	288	147	Sec
150	6682768	338	231	Sec

2.3.16 SRAM PUF

For more details on static random-access memory (SRAM) physical unclonable functions (PUF) services, see [AC434: Using SRAM PUF System Service in SmartFusion2 Application Note](#).

The following table lists the SRAM PUF in worst-case industrial conditions when $T_J = 100\text{ }^\circ\text{C}$, $V_{DD} = 1.14\text{ V}$.

Table 274 • SRAM PUF

Service	PUF Off		PUF On		Unit
	Typ	Max	Typ	Max	
Create activation code	709.1	746.4	754.4	762.5	ms
Delete activation code	1329.3	1399.3	1414.1	1429.3	ms
Create intrinsic keycode	656.6	691.1	698.5	706.0	ms
Create extrinsic keycode	656.6	691.1	698.5	706.0	ms
Get number of keys	1.3	1.4	1.4	1.4	ms
Export (Kc0, Kc1)	998.0	1050.5	1061.7	1073.1	ms
Export 2 keycodes	2020.2	2126.5	2149.2	2172.3	ms
Export 4 keycodes	3065.7	3227.0	3261.3	3296.4	ms
Export 8 keycodes	5101.0	5369.5	5426.6	5485.0	ms
Export 16 keycodes	9212.1	9697.0	9800.1	9905.5	ms
Import (Kc0, Kc1)	39.7	41.8	42.2	42.7	ms
Import 2 keycodes	50.1	52.7	53.3	53.9	ms
Import 4 keycodes	60.6	63.8	64.5	65.2	ms
Import 8 keycodes	80.9	85.1	86.1	87.0	ms
Import 16 keycodes	123.8	130.4	131.7	133.2	ms
Delete keycode	552.5	581.6	587.8	594.1	ms
Fetch key	31.4	33.0	33.4	33.7	ms
Fetch ecc key	20.0	21.1	21.3	21.5	ms
Get seed	2.0	2.1	2.2	2.2	ms

Table 276 • Cryptographic Block Characteristics (continued)

Service	Conditions	Timing	Unit
SHA256	512 bits	540	kbps
	1024 bits	780	kbps
	2048 bits	950	kbps
	24 kbits	1140	kbps
HMAC	512 bytes	820	kbps
	1024 bytes	890	kbps
	2048 bytes	930	kbps
	24 kbytes	980	kbps
KeyTree		1.8	ms
Challenge-response	PUF = OFF	25	ms
	PUF = ON	7	ms
ECC point multiplication		590	ms
ECC point addition		8	ms

1. Using cypher block chaining (CBC) mode.

2.3.19 Crystal Oscillator

The following table describes the electrical characteristics of the crystal oscillator in the IGLOO2 FPGA and SmartFusion2 SoC FPGAs.

Table 277 • Electrical Characteristics of the Crystal Oscillator – High Gain Mode (20 MHz)

Parameter	Symbol	Min	Typ	Max	Unit	Condition
Operating frequency	FXTAL		20		MHz	
Accuracy	ACCXTAL			0.0047	%	005, 010, 025, 050, 060, and 090 devices
				0.0058	%	150 devices
Output duty cycle	CYCXTAL		49–51	47–53	%	
Output period jitter (peak to peak)	JITPERXTAL		200	300	ps	
Output cycle to cycle jitter (peak to peak)	JITCYCXTAL		200	300	ps	010, 025, 050, and 060 devices
			250	410	ps	150 devices
			250	550	ps	005 and 090 devices
Operating current	IDYNXTAL		1.5		mA	010, 050, and 060 devices
			1.65		mA	005, 025, 090, and 150 devices
Input logic level high	VIHXTAL	0.9 V _{PP}			V	
Input logic level low	VILXTAL			0.1 V _{PP}	V	

2.3.22 JTAG

Table 284 • JTAG 1532 for 005, 010, 025, and 050 Devices

Parameter	Symbol	005		010		025		050		Unit
		-1	-Std	-1	-Std	-1	-Std	-1	-Std	
Clock to Q (data out)	T_{TCK2Q}	7.47	8.79	7.73	9.09	7.75	9.12	7.89	9.28	ns
Reset to Q (data out)	T_{RSTB2Q}	7.65	9	6.43	7.56	6.13	7.21	7.40	8.70	ns
Test data input setup time	T_{DISU}	-1.05	-0.89	-0.69	-0.59	-0.67	-0.57	-0.30	-0.25	ns
Test data input hold time	T_{DIHD}	2.38	2.8	2.38	2.8	2.42	2.85	2.09	2.45	ns
Test mode select setup time	T_{TMSSU}	-0.73	-0.62	-1.03	-1.21	-1.1	-0.94	0.28	0.33	ns
Test mode select hold time	T_{TMDHD}	1.36	1.6	1.43	1.68	1.93	2.27	0.16	0.19	ns
ResetB removal time	$T_{TRSTREM}$	-0.77	-0.65	-1.08	-0.92	-1.33	-1.13	-0.45	-0.38	ns
ResetB recovery time	$T_{TRSTREC}$	-0.76	-0.65	-1.07	-0.91	-1.34	-1.14	-0.45	-0.38	ns
TCK maximum frequency	F_{TCKMAX}	25	21.25	25	21.25	25	21.25	25.00	21.25	MHz

Table 285 • JTAG 1532 for 060, 090, and 150 Devices

Parameter	Symbol	060		090		150		Unit
		-1	-Std	-1	-Std	-1	-Std	
Clock to Q (data out)	T_{TCK2Q}	8.38	9.86	8.96	10.54	8.66	10.19	ns
Reset to Q (data out)	T_{RSTB2Q}	8.54	10.04	7.75	9.12	8.79	10.34	ns
Test data input setup time	T_{DISU}	-1.18	-1	-1.31	-1.11	-0.96	-0.82	ns
Test data input hold time	T_{DIHD}	2.52	2.97	2.68	3.15	2.57	3.02	ns
Test mode select setup time	T_{TMSSU}	-0.97	-0.83	-1.02	-0.87	-0.53	-0.45	ns
Test mode select hold time	T_{TMDHD}	1.7	2	1.67	1.96	1.02	1.2	ns
ResetB removal time	$T_{TRSTREM}$	-1.21	-1.03	-0.76	-0.65	-1.03	-0.88	ns
ResetB recovery time	$T_{TRSTREC}$	-1.21	-1.03	-0.77	-0.65	-1.03	-0.88	ns
TCK maximum frequency	F_{TCKMAX}	25	21.25	25	21.25	25	21.25	MHz

2.3.23 System Controller SPI Characteristics

2.3.31.3 Serial Peripheral Interface (SPI) Characteristics

This section describes the DC and switching of the SPI interface. Unless otherwise noted, all output characteristics given are for a 35 pF load on the pins and all sequential timing characteristics are related to SPI_x_CLK. For timing parameter definitions, see [Figure 22](#), page 128.

The following table lists the SPI characteristics in worst-case industrial conditions when $T_J = 100\text{ }^\circ\text{C}$, $V_{DD} = 1.14\text{ V}$

Table 305 • SPI Characteristics for All Devices

Symbol	Description	Min	Typ	Max	Unit	Conditions
SPIFMAX	Maximum operating frequency of SPI interface			20	MHz	
sp1	SPI_[0 1]_CLK minimum period					
	SPI_[0 1]_CLK = PCLK/2	12			ns	
	SPI_[0 1]_CLK = PCLK/4	24.1			ns	
	SPI_[0 1]_CLK = PCLK/8	48.2			ns	
	SPI_[0 1]_CLK = PCLK/16	0.1			μs	
	SPI_[0 1]_CLK = PCLK/32	0.19			μs	
	SPI_[0 1]_CLK = PCLK/64	0.39			μs	
	SPI_[0 1]_CLK = PCLK/128	0.77			μs	
sp2	SPI_[0 1]_CLK minimum pulse width high					
	SPI_[0 1]_CLK = PCLK/2	6			ns	
	SPI_[0 1]_CLK = PCLK/4	12.05			ns	
	SPI_[0 1]_CLK = PCLK/8	24.1			ns	
	SPI_[0 1]_CLK = PCLK/16	0.05			μs	
	SPI_[0 1]_CLK = PCLK/32	0.095			μs	
	SPI_[0 1]_CLK = PCLK/64	0.195			μs	
	SPI_[0 1]_CLK = PCLK/128	0.385			μs	
sp3	SPI_[0 1]_CLK minimum pulse width low					
	SPI_[0 1]_CLK = PCLK/2	6			ns	
	SPI_[0 1]_CLK = PCLK/4	12.05			ns	
	SPI_[0 1]_CLK = PCLK/8	24.1			ns	
	SPI_[0 1]_CLK = PCLK/16	0.05			μs	
	SPI_[0 1]_CLK = PCLK/32	0.095			μs	
	SPI_[0 1]_CLK = PCLK/64	0.195			μs	
	SPI_[0 1]_CLK = PCLK/128	0.385			μs	
sp4	SPI_[0 1]_CLK, SPI_[0 1]_DO, SPI_[0 1]_SS rise time (10%–90%) ¹		2.77		ns	I/O Configuration: LVCMOS 2.5 V– 8 mA AC loading: 35 pF Test conditions: Typical voltage, 25 °C

Table 310 • SPI Characteristics for All Devices (continued)

Symbol	Description	Min	Typ	Max	Unit	Conditions
SPI master configuration (applicable for 060, 090, and 150 devices)						
sp6m	SPI_[0 1]_DO setup time ²	(SPI_x_CLK_period/2) – 7.0			ns	
sp7m	SPI_[0 1]_DO hold time ²	(SPI_x_CLK_period/2) – 9.5			ns	
sp8m	SPI_[0 1]_DI setup time ²	15			ns	
sp9m	SPI_[0 1]_DI hold time ²	–2.5			ns	
SPI slave configuration (applicable for 060, 090, and 150 devices)						
sp6s	SPI_[0 1]_DO setup time ²	(SPI_x_CLK_period/2) – 16.0			ns	
sp7s	SPI_[0 1]_DO hold time ²	(SPI_x_CLK_period/2) – 3.5			ns	
sp8s	SPI_[0 1]_DI setup time ²	3			ns	
sp9s	SPI_[0 1]_DI hold time ²	2.5			ns	

1. For specific Rise/Fall Times board design considerations and detailed output buffer resistances, use the corresponding IBIS models located on the Microsemi SoC Products Group website: <http://www.microsemi.com/soc/download/ibis/default.aspx>.
2. For allowable pclk configurations, see the Serial Peripheral Interface Controller section in the *UG0331: SmartFusion2 Microcontroller Subsystem User Guide*.

Figure 23 • SPI Timing for a Single Frame Transfer in Motorola Mode (SPH = 1)

