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Embedded - System On Chip (SoC): The Heart of Modern Embedded Systems

Embedded - System On Chip (SoC) refers to an integrated circuit that consolidates all the essential components of a computer system into a single chip. This includes a microprocessor, memory, and other peripherals, all packed into one compact and efficient package. SoCs are designed to provide a complete computing solution, optimizing both space and power consumption, making them ideal for a wide range of embedded applications.

What are Embedded - System On Chip (SoC)?

System On Chip (SoC) integrates multiple functions of a computer or electronic system onto a single chip. Unlike traditional multi-chip solutions, SoCs combine a central

Details

Product Status	Active
Architecture	MCU, FPGA
Core Processor	ARM® Cortex®-M3
Flash Size	128KB
RAM Size	64KB
Peripherals	-
Connectivity	CANbus, Ethernet, I ² C, SPI, UART/USART, USB
Speed	166MHz
Primary Attributes	FPGA - 5K Logic Modules
Operating Temperature	-40°C ~ 100°C (TJ)
Package / Case	256-LBGA
Supplier Device Package	256-FPBGA (17x17)
Purchase URL	https://www.e-xfl.com/product-detail/microchip-technology/m2s005s-vfg256i

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Table 4 • Recommended Operating Conditions (continued)

Parameter	Symbol	Min	Typ	Max	Unit	Conditions
3.3 V DC supply voltage	V_{DDIX}	3.15	3.3	3.45	V	
LVDS differential I/O	V_{DDIX}	2.375	2.5	3.45	V	
B-LVDS, M-LVDS, Mini-LVDS, RSDS differential I/O	V_{DDIX}	2.375	2.5	2.625	V	
LVPECL differential I/O	V_{DDIX}	3.15	3.3	3.45	V	
Reference voltage supply for FDDR (Bank0) and MDDR (Bank5)	V_{REFX}	$0.49 \times V_{DDIX}$	$0.5 \times V_{DDIX}$	$0.51 \times V_{DDIX}$	V	
Analog sense circuit supply of embedded nonvolatile memory (eNVM). Must be shorted to V_{PP} .	V_{PPNVM}	2.375	2.5	2.625	V	2.5 V range
		3.15	3.3	3.45	V	3.3 V range

1. Programming at Industrial temperature range is available only with $V_{PP} = 3.3$ V.

Note: Power supply ramps must all be strictly monotonic, without plateaus.

Table 5 • FPGA Operating Limits

Product Grade	Element	Programming Temperature	Operating Temperature	Programming Cycles	Digest Temperature	Digest Cycles	Retention (Biased/Unbiased)
Commercial	FPGA	Min $T_J = 0$ °C Max $T_J = 85$ °C	Min $T_J = 0$ °C Max $T_J = 85$ °C	500	Min $T_J = 0$ °C Max $T_J = 85$ °C	2000	20 years
Industrial ¹	FPGA	Min $T_J = -40$ °C Max $T_J = 100$ °C	Min $T_J = -40$ °C Max $T_J = 100$ °C	500	Min $T_J = -40$ °C Max $T_J = 100$ °C	2000	20 years

1. Programming at Industrial temperature range is available only with $V_{PP} = 3.3$ V.

Note: The retention specification is defined as the total number of programing and digest cycles. For example, 20 years of retention after 500 programming cycles.

Note: The digest cycle specification is 2000 digest cycles for every program cycle with a maximum of 500 programming cycles.

Note: If your product qualification requires accelerated programming cycles, see *Microsemi SoC Products Quality and Reliability Report* about recommended methodologies.

The following table lists the embedded operating flash limits.

Table 6 • Embedded Operating Flash Limits

Product Grade	Element	Programming Temperature	Maximum Operating Temperature	Programming Cycles	Retention (Biased/Unbiased)
Commercial	Embedded flash	Min T _J = 0 °C Max T _J = 85 °C	Min T _J = 0 °C Max T _J = 85 °C	< 1000 cycles per page, up to two million cycles per eNVM array	20 years
			Min T _J = 0 °C Max T _J = 85 °C	< 10000 cycles per page, up to 20 million cycles per eNVM array	10 years
Industrial	Embedded flash	Min T _J = -40 °C Max T _J = 100 °C	Min T _J = -40 °C Max T _J = 100 °C	< 1000 cycles per page, up to two million cycles per eNVM array	20 years
			Min T _J = -40 °C Max T _J = 100 °C	< 10000 cycles per page, up to 20 million cycles per eNVM array	10 years

Note: If your product qualification requires accelerated programming cycles, see *Microsemi SoC Products Quality and Reliability Report* about recommended methodologies.

Table 7 • Device Storage Temperature and Retention

Product Grade	Storage Temperature (T _{stg})	Retention
Commercial	Min T _J = 0 °C Max T _J = 85 °C	20 years
Industrial	Min T _J = -40 °C Max T _J = 100 °C	20 years

Table 8 • High Temperature Data Retention (HTR) Lifetime

T _J (°C)	HTR Lifetime ¹ (yrs)
90	20.5
95	20.5
100	20.5
105	17.0
110	15.0
115	13.0
120	11.5
125	10.0
130	8.0
135	6.0
140	4.5
145	3.0
150	1.5

1. HTR Lifetime is the period during which a verify failure is not expected due to flash leakage.

Table 15 • Inrush Currents at Power up, $-40\text{ }^{\circ}\text{C} \leq T_J \leq 100\text{ }^{\circ}\text{C}$ – Typical Process

Power Supplies	Voltage (V)	005	010	025	050	060	090	150	Unit
V_{DD}	1.26	25	32	38	48	45	77	109	mA
V_{PP}	3.46	33	49	36	180	13	36	51	mA
V_{DDI}	2.62	134	141	161	187	93	272	388	mA
Number of banks		7	8	8	10	10	9	19	

2.3.3 Average Fabric Temperature and Voltage Derating Factors

The following table lists the average temperature and voltage derating factors for fabric timing delays normalized to $T_J = 85\text{ }^{\circ}\text{C}$, in worst-case $V_{DD} = 1.14\text{ V}$.

Table 16 • Average Junction Temperature and Voltage Derating Factors for Fabric Timing Delays

Array Voltage V_{DD} (V)	$-40\text{ }^{\circ}\text{C}$	$0\text{ }^{\circ}\text{C}$	$25\text{ }^{\circ}\text{C}$	$70\text{ }^{\circ}\text{C}$	$85\text{ }^{\circ}\text{C}$	$100\text{ }^{\circ}\text{C}$
1.14	0.83	0.89	0.92	0.98	1.00	1.02
1.2	0.75	0.80	0.83	0.89	0.91	0.93
1.26	0.69	0.73	0.76	0.81	0.83	0.85

2.3.5 User I/O Characteristics

There are three types of I/Os supported in the IGLOO2 FPGA and SmartFusion2 SoC FPGA families: MSIO, MSIOD, and DDRIO I/O banks. The I/O standards supported by the different I/O banks is described in the I/Os section of the *UG0445: IGLOO2 FPGA and SmartFusion2 SoC FPGA Fabric User Guide*.

2.3.5.1 Input Buffer and AC Loading

The following figure shows the input buffer and AC loading.

Figure 3 • Input Buffer AC Loading

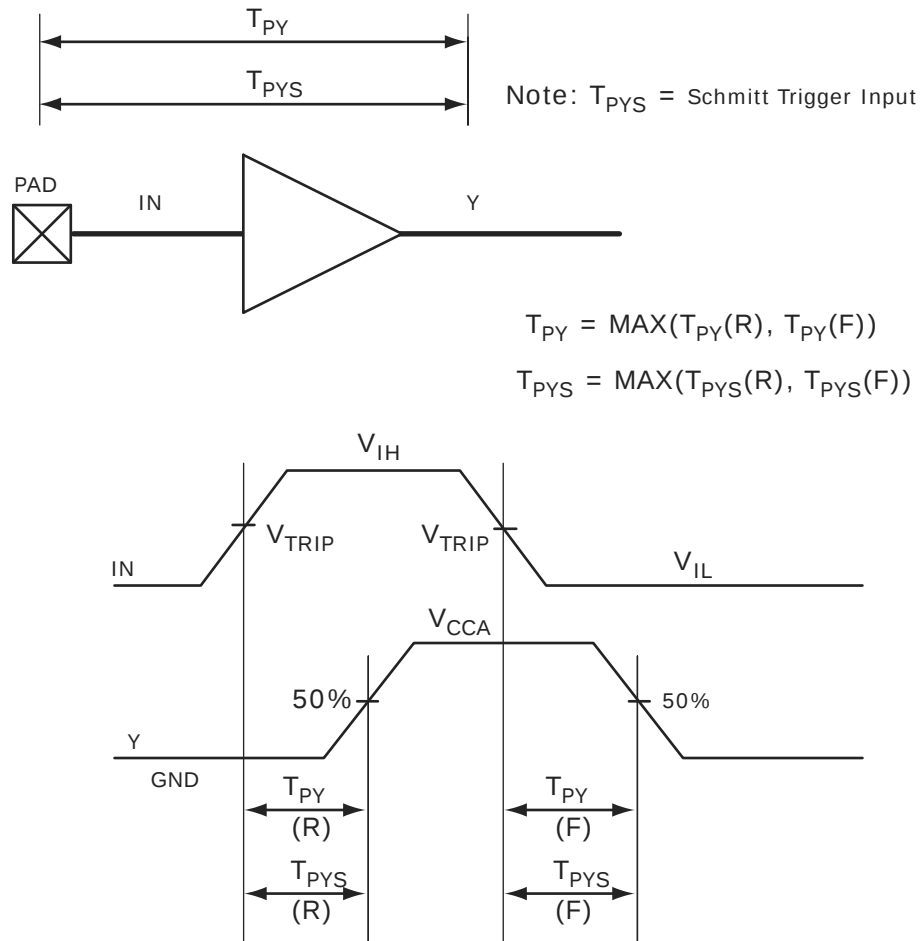


Table 22 • Maximum Frequency Summary Table for Voltage-Referenced I/O in Worst-Case Industrial Conditions

I/O	MSIO	MSIOD	DDRIO	Unit
LPDDR			200	MHz
HSTL1.5 V			200	MHz
SSTL 2.5 V	255	350	200	MHz
SSTL 1.8 V			334	MHz
SSTL 1.5 V			334	MHz

Table 23 • Maximum Frequency Summary Table for Differential I/O in Worst-Case Industrial Conditions

I/O	MSIO	MSIOD	Unit
LVPECL (input only)	450		MHz
LVDS 3.3 V	267.5		MHz
LVDS 2.5 V	267.5	350	MHz
RSDS	260	350	MHz
BLVDS	250		MHz
MLVDS	250		MHz
Mini-LVDS	260	350	MHz

Table 34 • LVTTTL/LVCMOS 3.3 V AC Test Parameter Specifications (Applicable to MSIO I/O Bank Only)

Parameter	Symbol	Typ	Unit
Measuring/trip point for data path	V_{TRIP}	1.4	V
Resistance for enable path (T_{ZH} , T_{ZL} , T_{HZ} , T_{LZ})	R_{ENT}	2K	Ω
Capacitive loading for enable path (T_{ZH} , T_{ZL} , T_{HZ} , T_{LZ})	C_{ENT}	5	pF
Capacitive loading for data path (T_{DP})	C_{LOAD}	5	pF

Table 35 • LVTTTL/LVCMOS 3.3 V Transmitter Drive Strength Specifications for MSIO I/O Bank

Output Drive Selection	V_{OH} (V)	V_{OL} (V)	IOH (at V_{OH}) mA	IOL (at V_{OL}) mA
2 mA	$V_{DDI} - 0.4$	0.4	2	2
4 mA	$V_{DDI} - 0.4$	0.4	4	4
8 mA	$V_{DDI} - 0.4$	0.4	8	8
12 mA	$V_{DDI} - 0.4$	0.4	12	12
16 mA	$V_{DDI} - 0.4$	0.4	16	16
20 mA	$V_{DDI} - 0.4$	0.4	20	20

Note: For a detailed I/V curve, use the corresponding IBIS models:
www.microsemi.com/soc/download/ibis/default.aspx.

AC Switching Characteristics

Worst commercial-case conditions: $T_J = 85^\circ\text{C}$, $V_{DD} = 1.14\text{ V}$, $V_{DDI} = 3.0\text{ V}$

Table 36 • LVTTTL/LVCMOS 3.3 V Receiver Characteristics for MSIO I/O Bank (Input Buffers)

On-Die Termination (ODT)	T_{PY}		T_{PYS}		Unit
	-1	-Std	-1	-Std	
None	2.262	2.663	2.289	2.695	ns

Table 37 • LVTTTL/LVCMOS 3.3 V Transmitter Characteristics for MSIO I/O Bank (Output and Tristate Buffers)

Output Drive Selection	Slew Control	T_{DP}		T_{ZL}		T_{ZH}		T_{HZ}^1		T_{LZ}^1		Unit
		-1	-Std	-1	-Std	-1	-Std	-1	-Std	-1	-Std	
2 mA	Slow	3.192	3.755	3.47	4.083	2.969	3.494	1.856	2.183	3.337	3.926	ns
4 mA	Slow	2.331	2.742	2.673	3.145	2.526	2.973	3.034	3.569	4.451	5.236	ns
8 mA	Slow	2.135	2.511	2.33	2.741	2.297	2.703	4.532	5.331	4.825	5.676	ns
12 mA	Slow	2.052	2.414	2.107	2.479	2.162	2.544	5.75	6.764	5.445	6.406	ns
16 mA	Slow	2.062	2.425	2.072	2.438	2.145	2.525	5.993	7.05	5.625	6.618	ns
20 mA	Slow	2.148	2.527	1.999	2.353	2.088	2.458	6.262	7.367	5.876	6.913	ns

- Delay increases with drive strength are inherent to built-in slew control circuitry for simultaneous switching output (SSO) management.

Table 118 • DDR1/SSTL2 Class II Transmitter Characteristics for MSIO I/O Bank (Output and Tristate Buffers)

	T_{DP}		T_{ZL}		T_{ZH}		T_{HZ}		T_{LZ}		Unit
	-1	-Std	-1	-Std	-1	-Std	-1	-Std	-1	-Std	
Single-ended	2.29	2.693	1.988	2.338	1.978	2.326	1.989	2.34	1.979	2.328	ns
Differential	2.418	2.846	2.304	2.711	2.297	2.702	2.131	2.506	2.124	2.499	ns

2.3.6.4 Stub-Series Terminated Logic 1.8 V (SSTL18)

SSTL18 Class I and Class II are supported in IGLOO2 and SmartFusion2 SoC FPGAs, and also comply with the reduced and full drive double data rate (DDR2) standard. IGLOO2 and SmartFusion2 SoC FPGA I/Os support both standards for single-ended signaling and differential signaling for SSTL18. This standard requires a differential amplifier input buffer and a push-pull output buffer.

Minimum and Maximum DC/AC Input and Output Levels Specification**Table 119 • SSTL18 DC Recommended DC Operating Conditions**

Parameter	Symbol	Min	Typ	Max	Unit
Supply voltage	V_{DDI}	1.71	1.8	1.89	V
Termination voltage	V_{TT}	0.838	0.900	0.964	V
Input reference voltage	V_{REF}	0.838	0.900	0.964	V

Table 120 • SSTL18 DC Input Voltage Specification

Parameter	Symbol	Min	Max	Unit
DC input logic high	V_{IH} (DC)	$V_{REF} + 0.125$	1.89	V
DC input logic low	V_{IL} (DC)	-0.3	$V_{REF} - 0.125$	V
Input current high ¹	I_{IH} (DC)			
Input current low ¹	I_{IL} (DC)			

1. See Table 24, page 22.

Table 121 • SSTL18 DC Output Voltage Specification

Parameter	Symbol	Min	Max	Unit
SSTL18 Class I (DDR2 Reduced Drive)				
DC output logic high	V_{OH}	$V_{TT} + 0.603$		V
DC output logic low	V_{OL}		$V_{TT} - 0.603$	V
Output minimum source DC current (DDRIO I/O bank only)	I_{OH} at V_{OH}	6.5		mA
Output minimum sink current (DDRIO I/O bank only)	I_{OL} at V_{OL}	-6.5		mA
SSTL18 Class II (DDR2 Full Drive)¹				
DC output logic high	V_{OH}	$V_{TT} + 0.603$		V
DC output logic low	V_{OL}		$V_{TT} - 0.603$	V
Output minimum source DC current (DDRIO I/O bank only)	I_{OH} at V_{OH}	13.4		mA
Output minimum sink current (DDRIO I/O bank only)	I_{OL} at V_{OL}	-13.4		mA

1. To meet JEDEC Electrical Compliance, use DDR2 Full Drive Transmitter.

Table 215 • LVPECL DC Input Voltage Specification

Parameter	Symbol	Min	Max	Unit
DC input voltage	V_I	0	3.45	V

Table 216 • LVPECL DC Differential Voltage Specification

Parameter	Symbol	Min	Typ	Max	Unit
Input common mode voltage	V_{ICM}	0.3		2.8	V
Input differential voltage	V_{IDIFF}	100	300	1,000	mV

Table 217 • LVPECL Minimum and Maximum AC Switching Speeds

Parameter	Symbol	Max	Unit
Maximum data rate	D_{MAX}	900	Mbps

AC Switching Characteristics

Worst commercial-case conditions: $T_J = 85\text{ }^{\circ}\text{C}$, $V_{DD} = 1.14\text{ V}$, $V_{DDI} = 2.375\text{ V}$.

Table 218 • LVPECL Receiver Characteristics for MSIO I/O Bank

On-Die Termination (ODT)	T_{PY}		Unit
	-1	-Std	
None	2.572	3.025	ns
100	2.569	3.023	ns

2.3.8 I/O Register Specifications

This section describes input and output register specifications.

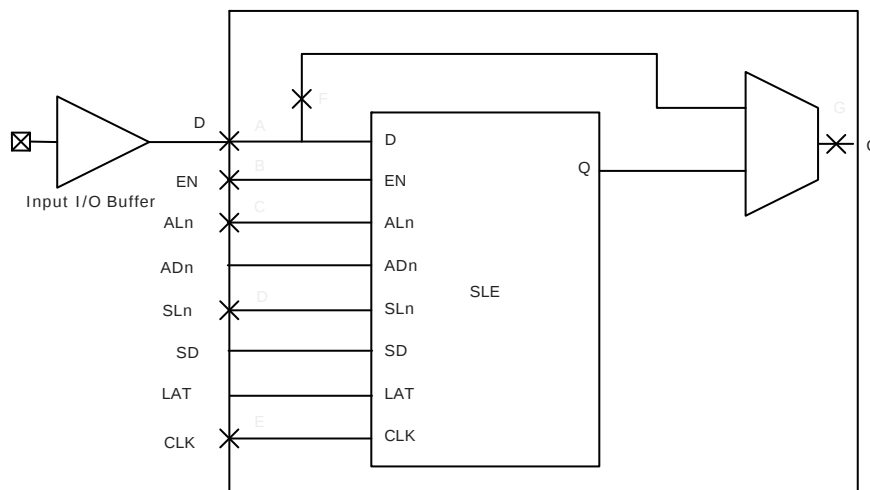
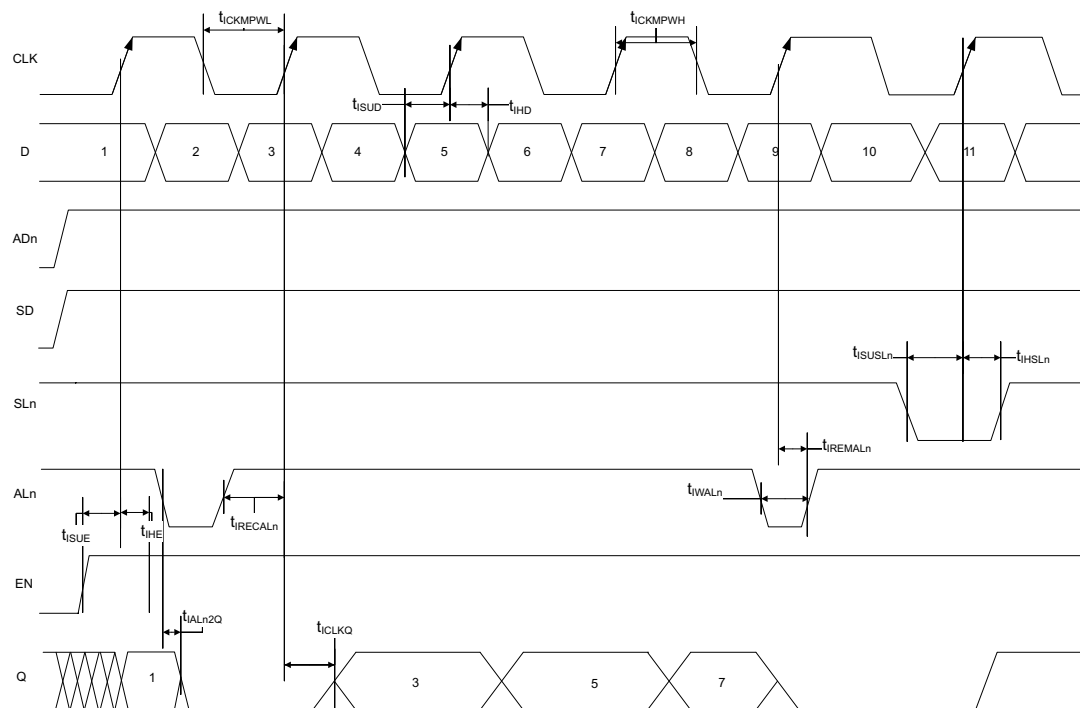
2.3.8.1 Input Register**Figure 6 • Timing Model for Input Register**

Figure 7 • I/O Register Input Timing Diagram



2.3.11 Global Resource Characteristics

The IGLOO2 and SmartFusion2 SoC FPGA devices offer a powerful, low skew global routing network which provides an effective clock distribution throughout the FPGA fabric. See *UG0445: IGLOO2 FPGA and SmartFusion2 SoC FPGA Fabric User Guide* for the positions of various global routing resources.

The following table lists the 150 device global resources in worst commercial-case conditions when $T_J = 85^\circ\text{C}$, $V_{DD} = 1.14\text{ V}$.

Table 225 • 150 Device Global Resource

Parameter	Symbol	-1		-Std		Unit
		Min	Max	Min	Max	
Input low delay for global clock	T_{RCKL}	0.83	0.911	0.831	0.913	ns
Input high delay for global clock	T_{RCKH}	1.457	1.588	1.715	1.869	ns
Maximum skew for global clock	T_{RCKSW}		0.131		0.154	ns

The following table lists the 090 device global resources in worst commercial-case conditions when $T_J = 85^\circ\text{C}$, $V_{DD} = 1.14\text{ V}$.

Table 226 • 090 Device Global Resource

Parameter	Symbol	-1		-Std		Unit
		Min	Max	Min	Max	
Input low delay for global clock	T_{RCKL}	0.835	0.888	0.833	0.886	ns
Input high delay for global clock	T_{RCKH}	1.405	1.489	1.654	1.752	ns
Maximum skew for global clock	T_{RCKSW}		0.084		0.098	ns

The following table lists the 050 device global resources in worst commercial-case conditions when $T_J = 85^\circ\text{C}$, $V_{DD} = 1.14\text{ V}$.

Table 227 • 050 Device Global Resource

Parameter	Symbol	-1		-Std		Unit
		Min	Max	Min	Max	
Input low delay for global clock	T_{RCKL}	0.827	0.897	0.826	0.896	ns
Input high delay for global clock	T_{RCKH}	1.419	1.53	1.671	1.8	ns
Maximum skew for global clock	T_{RCKSW}		0.111		0.129	ns

The following table lists the 025 device global resources in worst commercial-case conditions when $T_J = 85^\circ\text{C}$, $V_{DD} = 1.14\text{ V}$.

Table 228 • 025 Device Global Resource

Parameter	Symbol	-1		-Std		Unit
		Min	Max	Min	Max	
Input low delay for global clock	T_{RCKL}	0.747	0.799	0.745	0.797	ns
Input high delay for global clock	T_{RCKH}	1.294	1.378	1.522	1.621	ns
Maximum skew for global clock	T_{RCKSW}		0.084		0.099	ns

Table 231 • RAM1K18 – Dual-Port Mode for Depth × Width Configuration 1K × 18 (continued)

Parameter	Symbol	–1		–Std		Unit
		Min	Max	Min	Max	
Block select hold time	T _{BLKHD}	0.216		0.254		ns
Block select to out disable time (when pipelined register is disabled)	T _{BLK2Q}		1.529		1.799	ns
Block select minimum pulse width	T _{BLKMPW}	0.186		0.219		ns
Read enable setup time	T _{RDESU}	0.449		0.528		ns
Read enable hold time	T _{RDEHD}	0.167		0.197		ns
Pipelined read enable setup time (A_DOUT_EN, B_DOUT_EN)	T _{RDPLESU}	0.248		0.291		ns
Pipelined read enable hold time (A_DOUT_EN, B_DOUT_EN)	T _{RDPLEHD}	0.102		0.12		ns
Asynchronous reset to output propagation delay	T _{R2Q}	–	1.506	–	1.772	ns
Asynchronous reset removal time	T _{RSTREM}	0.506		0.595		ns
Asynchronous reset recovery time	T _{RSTREC}	0.004		0.005		ns
Asynchronous reset minimum pulse width	T _{RSTMPW}	0.301		0.354		ns
Pipelined register asynchronous reset removal time	T _{PLRSTREM}	–0.279		–0.328		ns
Pipelined register asynchronous reset recovery time	T _{PLRSTREC}	0.327		0.385		ns
Pipelined register asynchronous reset minimum pulse width	T _{PLRSTMPW}	0.282		0.332		ns
Synchronous reset setup time	T _{SRSTSU}	0.226		0.265		ns
Synchronous reset hold time	T _{SRSTHD}	0.036		0.043		ns
Write enable setup time	T _{WESU}	0.39		0.458		ns
Write enable hold time	T _{WEHD}	0.242		0.285		ns
Maximum frequency	F _{MAX}		400		340	MHz

The following table lists the RAM1K18 – dual-port mode for depth × width configuration 2K × 9 in worst commercial-case conditions when T_J = 85 °C, V_{DD} = 1.14 V.

Table 232 • RAM1K18 – Dual-Port Mode for Depth × Width Configuration 2K × 9

Parameter	Symbol	–1		–Std		Unit
		Min	Max	Min	Max	
Clock period	T _{CY}	2.5		2.941		ns
Clock minimum pulse width high	T _{CLKMPWH}	1.125		1.323		ns
Clock minimum pulse width low	T _{CLKMPWL}	1.125		1.323		ns
Pipelined clock period	T _{PLCY}	2.5		2.941		ns
Pipelined clock minimum pulse width high	T _{PLCLKMPWH}	1.125		1.323		ns
Pipelined clock minimum pulse width low	T _{PLCLKMPWL}	1.125		1.323		ns
Read access time with pipeline register			0.334		0.393	ns
Read access time without pipeline register	T _{CLK2Q}		2.273		2.674	ns
Access time with feed-through write timing			1.529		1.799	ns

The following table lists the RAM1K18 – dual-port mode for depth × width configuration 8K × 2 in worst commercial-case conditions when $T_J = 85^\circ\text{C}$, $V_{DD} = 1.14\text{ V}$.

Table 234 • RAM1K18 – Dual-Port Mode for Depth × Width Configuration 8K × 2

Parameter	Symbol	–1		–Std		Unit
		Min	Max	Min	Max	
Clock period	T_{CY}	2.5		2.941		ns
Clock minimum pulse width high	$T_{CLKMPWH}$	1.125		1.323		ns
Clock minimum pulse width low	$T_{CLKMPWL}$	1.125		1.323		ns
Pipelined clock period	T_{PLCY}	2.5		2.941		ns
Pipelined clock minimum pulse width high	$T_{PLCLKMPWH}$	1.125		1.323		ns
Pipelined clock minimum pulse width low	$T_{PLCLKMPWL}$	1.125		1.323		ns
Read access time with pipeline register			0.32		0.377	ns
Read access time without pipeline register	T_{CLK2Q}		2.272		2.673	ns
Access time with feed-through write timing			1.511		1.778	ns
Address setup time	T_{ADDRSU}	0.612		0.72		ns
Address hold time	T_{ADDRHD}	0.274		0.322		ns
Data setup time	T_{DSU}	0.33		0.388		ns
Data hold time	T_{DHD}	0.082		0.096		ns
Block select setup time	T_{BLKSU}	0.207		0.244		ns
Block select hold time	T_{BLKHD}	0.216		0.254		ns
Block select to out disable time (when pipelined register is disabled)	T_{BLK2Q}		1.511		1.778	ns
Block select minimum pulse width	T_{BLKMPW}	0.186		0.219		ns
Read enable setup time	T_{RDESU}	0.529		0.622		ns
Read enable hold time	T_{RDEHD}	0.071		0.083		ns
Pipelined read enable setup time (A_DOUT_EN, B_DOUT_EN)	$T_{RDPLESU}$	0.248		0.291		ns
Pipelined read enable hold time (A_DOUT_EN, B_DOUT_EN)	$T_{RDPLEHD}$	0.102		0.12		ns
Asynchronous reset to output propagation delay	T_{R2Q}		1.528		1.797	ns
Asynchronous reset removal time	T_{RSTREM}	0.506		0.595		ns
Asynchronous reset recovery time	T_{RSTREC}	0.004		0.005		ns
Asynchronous reset minimum pulse width	T_{RSTMPW}	0.301		0.354		ns
Pipelined register asynchronous reset removal time	$T_{PLRSTREM}$	–0.279		–0.328		ns
Pipelined register asynchronous reset recovery time	$T_{PLRSTREC}$	0.327		0.385		ns
Pipelined register asynchronous reset minimum pulse width	$T_{PLRSTMPW}$	0.282		0.332		ns
Synchronous reset setup time	T_{SRSTSU}	0.226		0.265		ns
Synchronous reset hold time	T_{SRSTHD}	0.036		0.043		ns
Write enable setup time	T_{WESU}	0.488		0.574		ns
Write enable hold time	T_{WEHD}	0.048		0.057		ns
Maximum frequency	F_{MAX}		400		340	MHz

The following table lists the RAM1K18 – dual-port mode for depth × width configuration 16K × 1 in worst commercial-case conditions when $T_J = 85^\circ\text{C}$, $V_{DD} = 1.14\text{ V}$.

Table 235 • RAM1K18 – Dual-Port Mode for Depth × Width Configuration 16K × 1

Parameter	Symbol	–1		–Std		Unit
		Min	Max	Min	Max	
Clock period	T_{CY}	2.5		2.941		ns
Clock minimum pulse width high	$T_{CLKMPWH}$	1.125		1.323		ns
Clock minimum pulse width low	$T_{CLKMPWL}$	1.125		1.323		ns
Pipelined clock period	T_{PLCY}	2.5		2.941		ns
Pipelined clock minimum pulse width high	$T_{PLCLKMPWH}$	1.125		1.323		ns
Pipelined clock minimum pulse width low	$T_{PLCLKMPWL}$	1.125		1.323		ns
Read access time with pipeline register			0.32		0.377	ns
Read access time without pipeline register	T_{CLK2Q}		2.269		2.669	ns
Access time with feed-through write timing			1.51		1.777	ns
Address setup time	T_{ADDRSU}	0.626		0.737		ns
Address hold time	T_{ADDRHD}	0.274		0.322		ns
Data setup time	T_{DSU}	0.322		0.378		ns
Data hold time	T_{DHD}	0.082		0.096		ns
Block select setup time	T_{BLKSU}	0.207		0.244		ns
Block select hold time	T_{BLKHD}	0.216		0.254		ns
Block select to out disable time (when pipelined register is disabled)	T_{BLK2Q}		1.51		1.777	ns
Block select minimum pulse width	T_{BLKMPW}	0.186		0.219		ns
Read enable setup time	T_{RDESU}	0.53		0.624		ns
Read enable hold time	T_{RDEHD}	0.071		0.083		ns
Pipelined read enable setup time (A_DOUT_EN, B_DOUT_EN)	$T_{RDPLESU}$	0.248		0.291		ns
Pipelined read enable hold time (A_DOUT_EN, B_DOUT_EN)	$T_{RDPLEHD}$	0.102		0.12		ns
Asynchronous reset to output propagation delay	T_{R2Q}		1.547		1.82	ns
Asynchronous reset removal time	T_{RSTREM}	0.506		0.595		ns
Asynchronous reset recovery time	T_{RSTREC}	0.004		0.005		ns
Asynchronous reset minimum pulse width	T_{RSTMPW}	0.301		0.354		ns
Pipelined register asynchronous reset removal time	$T_{PLRSTREM}$	–0.279		–0.328		ns
Pipelined register asynchronous reset recovery time	$T_{PLRSTREC}$	0.327		0.385		ns
Pipelined register asynchronous reset minimum pulse width	$T_{PLRSTMPW}$	0.282		0.332		ns
Synchronous reset setup time	T_{SRSTSU}	0.226		0.265		ns
Synchronous reset hold time	T_{SRSTHD}	0.036		0.043		ns
Write enable setup time	T_{WESU}	0.454		0.534		ns
Write enable hold time	T_{WEHD}	0.048		0.057		ns
Maximum frequency	F_{MAX}		400		340	MHz

The following table lists the programming times in worst-case conditions when $T_J = 100\text{ }^{\circ}\text{C}$, $V_{DD} = 1.14\text{ V}$. External SPI flash part# AT25DF641-s3H is used during this measurement.

Table 256 • JTAG Programming (Fabric Only)

M2S/M2GL Device	Image size Bytes	Program	Verify	Unit
005	302672	44	10	Sec
010	568784	50	18	Sec
025	1223504	73	26	Sec
050	2424832	88	54	Sec
060	2418896	99	54	Sec
090	3645968	135	126	Sec
150	6139184	177	193	Sec

Table 257 • JTAG Programming (eNVM Only)

M2S/M2GL Device	Image size	Program	Verify	Unit
	Bytes			
005	137536	61	4	Sec
010	274816	100	9	Sec
025	274816	100	9	Sec
050	2,78,528	106	8	Sec
060	268480	98	8	Sec
090	544496	176	15	Sec
150	544496	177	15	Sec

Table 258 • JTAG Programming (Fabric and eNVM)

M2S/M2GL Device	Image size		Program	Verify	Unit
	Bytes				
005	439296	71	11	Sec	
010	842688	129	20	Sec	
025	1497408	142	35	Sec	
050	2695168	184	59	Sec	
060	2686464	180	70	Sec	
090	4190208	288	147	Sec	
150	6682768	338	231	Sec	

Table 276 • Cryptographic Block Characteristics (continued)

Service	Conditions	Timing	Unit
SHA256	512 bits	540	kbps
	1024 bits	780	kbps
	2048 bits	950	kbps
	24 kbits	1140	kbps
HMAC	512 bytes	820	kbps
	1024 bytes	890	kbps
	2048 bytes	930	kbps
	24 kbytes	980	kbps
KeyTree		1.8	ms
Challenge-response	PUF = OFF	25	ms
	PUF = ON	7	ms
ECC point multiplication		590	ms
ECC point addition		8	ms

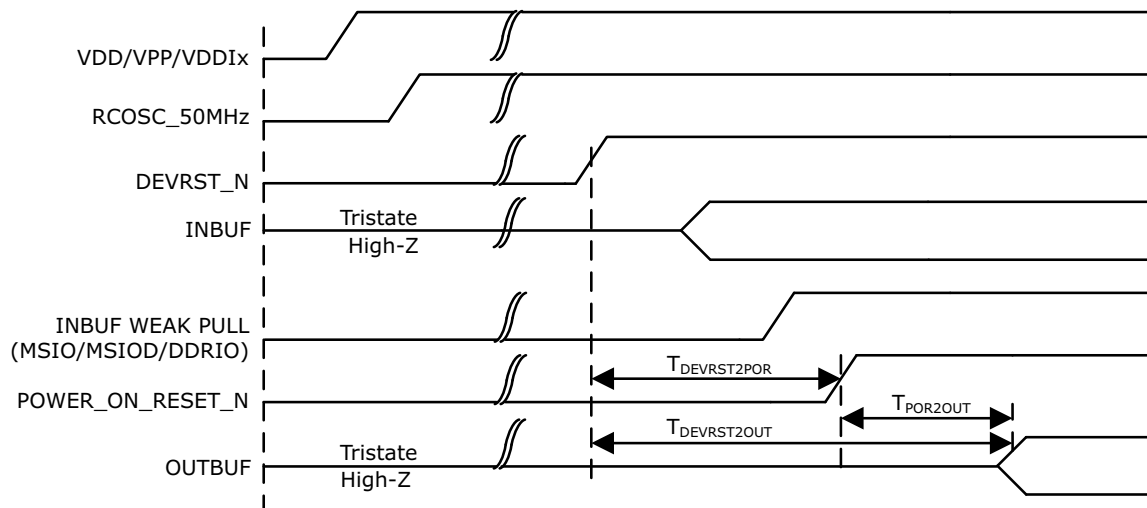
1. Using cypher block chaining (CBC) mode.

2.3.19 Crystal Oscillator

The following table describes the electrical characteristics of the crystal oscillator in the IGLOO2 FPGA and SmartFusion2 SoC FPGAs.

Table 277 • Electrical Characteristics of the Crystal Oscillator – High Gain Mode (20 MHz)

Parameter	Symbol	Min	Typ	Max	Unit	Condition
Operating frequency	FXTAL		20		MHz	
Accuracy	ACCXTAL			0.0047	%	005, 010, 025, 050, 060, and 090 devices
				0.0058	%	150 devices
Output duty cycle	CYCXTAL		49–51	47–53	%	
Output period jitter (peak to peak)	JITPERXTAL		200	300	ps	
Output cycle to cycle jitter (peak to peak)	JITCYCXTAL		200	300	ps	010, 025, 050, and 060 devices
			250	410	ps	150 devices
			250	550	ps	005 and 090 devices
Operating current	IDYNXTAL		1.5		mA	010, 050, and 060 devices
			1.65		mA	005, 025, 090, and 150 devices
Input logic level high	VIHXTAL	0.9 V _{PP}			V	
Input logic level low	VILXTAL			0.1 V _{PP}	V	

Figure 20 • DEVRST_N to Functional Timing Diagram for IGLOO2

2.3.27 Flash*Freeze Timing Characteristics

The following table lists the Flash*Freeze entry and exit times in worst-case industrial conditions when $T_J = 100\text{ }^{\circ}\text{C}$, $V_{DD} = 1.14\text{ V}$.

Table 293 • Flash*Freeze Entry and Exit Times

Parameter	Symbol	Entry/Exit Timing FCLK = 100MHz		Entry/Exit Timing FCLK = 3 MHz		Unit	Conditions
		005, 010, 025, 060, 090, and 150	050	All Devices			
Entry time	TFF_ENTRY	160	150	320		μs	eNVM and MSS/HPMS PLL = ON
		215	200	430		μs	eNVM and MSS/HPMS PLL= OFF
Exit time with respect to the MSS PLL Lock	TFF_EXIT	100	100	140		μs	eNVM and MSS/HPMS PLL = ON during F*F
		136	120	190		μs	eNVM = ON and MSS/HPMS PLL = OFF during F*F and MSS/HPMS PLL turned back on at exit
		200	200	285		μs	eNVM and MSS/HPMS PLL = OFF during F*F and both are turned back on at exit
		200	200	285		μs	eNVM = OFF and MSS/HPMS PLL = ON during F*F and eNVM turned back on at exit

2.3.31.3 Serial Peripheral Interface (SPI) Characteristics

This section describes the DC and switching of the SPI interface. Unless otherwise noted, all output characteristics given are for a 35 pF load on the pins and all sequential timing characteristics are related to SPI_x_CLK. For timing parameter definitions, see Figure 22, page 128.

The following table lists the SPI characteristics in worst-case industrial conditions when $T_J = 100\text{ }^{\circ}\text{C}$, $V_{DD} = 1.14\text{ V}$

Table 305 • SPI Characteristics for All Devices

Symbol	Description	Min	Typ	Max	Unit	Conditions
SPIFMAX	Maximum operating frequency of SPI interface			20	MHz	
sp1	SPI_[0 1]_CLK minimum period					
	SPI_[0 1]_CLK = PCLK/2	12			ns	
	SPI_[0 1]_CLK = PCLK/4	24.1			ns	
	SPI_[0 1]_CLK = PCLK/8	48.2			ns	
	SPI_[0 1]_CLK = PCLK/16	0.1			μs	
	SPI_[0 1]_CLK = PCLK/32	0.19			μs	
	SPI_[0 1]_CLK = PCLK/64	0.39			μs	
	SPI_[0 1]_CLK = PCLK/128	0.77			μs	
sp2	SPI_[0 1]_CLK minimum pulse width high					
	SPI_[0 1]_CLK = PCLK/2	6			ns	
	SPI_[0 1]_CLK = PCLK/4	12.05			ns	
	SPI_[0 1]_CLK = PCLK/8	24.1			ns	
	SPI_[0 1]_CLK = PCLK/16	0.05			μs	
	SPI_[0 1]_CLK = PCLK/32	0.095			μs	
	SPI_[0 1]_CLK = PCLK/64	0.195			μs	
	SPI_[0 1]_CLK = PCLK/128	0.385			μs	
sp3	SPI_[0 1]_CLK minimum pulse width low					
	SPI_[0 1]_CLK = PCLK/2	6			ns	
	SPI_[0 1]_CLK = PCLK/4	12.05			ns	
	SPI_[0 1]_CLK = PCLK/8	24.1			ns	
	SPI_[0 1]_CLK = PCLK/16	0.05			μs	
	SPI_[0 1]_CLK = PCLK/32	0.095			μs	
	SPI_[0 1]_CLK = PCLK/64	0.195			μs	
	SPI_[0 1]_CLK = PCLK/128	0.385			μs	
sp4	SPI_[0 1]_CLK, SPI_[0 1]_DO, SPI_[0 1]_SS rise time (10%–90%) ¹		2.77		ns	I/O Configuration: LVCMOS 2.5 V– 8 mA AC loading: 35 pF Test conditions: Typical voltage, 25 °C

2.3.34 MMUART Characteristics

The following table lists the MMUART characteristics in worst-case industrial conditions when $T_J = 100\text{ }^{\circ}\text{C}$, $V_{DD} = 1.14\text{ V}$.

Table 308 • MMUART Characteristics

Parameter	Description	–1	–Std	Unit
FMMUART_REF_CLK	Internally sourced MMUART reference clock frequency.	166	142	MHz
BAUDMMUARTTx	Maximum transmit baud rate	10.375	8.875	Mbps
BAUDMMUARTRx	Maximum receive baud rate	10.375	8.875	Mbps

2.3.35 IGLOO2 Specifications

2.3.35.1 HPMS Clock Frequency

The following table lists the maximum frequency for HPMS main clock in worst-case industrial conditions when $T_J = 100\text{ }^{\circ}\text{C}$, $V_{DD} = 1.14\text{ V}$.

Table 309 • Maximum Frequency for HPMS Main Clock

Symbol	Description	–1	–Std	Unit
HPMS_CLK	Maximum frequency for the HPMS main clock	166	142	MHz

2.3.35.2 IGLOO2 Serial Peripheral Interface (SPI) Characteristics

This section describes the DC and switching of the SPI interface. Unless otherwise noted, all output characteristics given are for a 35 pF load on the pins and all sequential timing characteristics are related to SPI_0_CLK. For timing parameter definitions, see Figure 23, page 131.

The following table lists the SPI characteristics in worst-case industrial conditions when $T_J = 100\text{ }^{\circ}\text{C}$, $V_{DD} = 1.14\text{ V}$.

Table 310 • SPI Characteristics for All Devices

Symbol	Description	Min	Typ	Max	Unit	Conditions
SPIFMAX	Maximum operating frequency of SPI interface			20	MHz	
sp1	SPI_[0 1]_CLK minimum period					
	SPI_[0 1]_CLK = PCLK/2	12			ns	
	SPI_[0 1]_CLK = PCLK/4	24.1			ns	
	SPI_[0 1]_CLK = PCLK/8	48.2			ns	
	SPI_[0 1]_CLK = PCLK/16	0.1			μs	
	SPI_[0 1]_CLK = PCLK/32	0.19			μs	
	SPI_[0 1]_CLK = PCLK/64	0.39			μs	
	SPI_[0 1]_CLK = PCLK/128	0.77			μs	

Table 310 • SPI Characteristics for All Devices (continued)

Symbol	Description	Min	Typ	Max	Unit	Conditions
SPI master configuration (applicable for 060, 090, and 150 devices)						
sp6m	SPI_[0 1]_DO setup time ²	$(\text{SPI_x_CLK_period}/2) - 7.0$			ns	
sp7m	SPI_[0 1]_DO hold time ²	$(\text{SPI_x_CLK_period}/2) - 9.5$			ns	
sp8m	SPI_[0 1]_DI setup time ²	15			ns	
sp9m	SPI_[0 1]_DI hold time ²	-2.5			ns	
SPI slave configuration (applicable for 060, 090, and 150 devices)						
sp6s	SPI_[0 1]_DO setup time ²	$(\text{SPI_x_CLK_period}/2) - 16.0$			ns	
sp7s	SPI_[0 1]_DO hold time ²	$(\text{SPI_x_CLK_period}/2) - 3.5$			ns	
sp8s	SPI_[0 1]_DI setup time ²	3			ns	
sp9s	SPI_[0 1]_DI hold time ²	2.5			ns	

1. For specific Rise/Fall Times board design considerations and detailed output buffer resistances, use the corresponding IBIS models located on the Microsemi SoC Products Group website: <http://www.microsemi.com/soc/download/ibis/default.aspx>.
2. For allowable pclk configurations, see the Serial Peripheral Interface Controller section in the *UG0331: SmartFusion2 Microcontroller Subsystem User Guide*.

Figure 23 • SPI Timing for a Single Frame Transfer in Motorola Mode (SPH = 1)