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Embedded - System On Chip (SoC): The Heart of Modern Embedded Systems

Embedded - System On Chip (SoC) refers to an integrated circuit that consolidates all the essential components of a computer system into a single chip. This includes a microprocessor, memory, and other peripherals, all packed into one compact and efficient package. SoCs are designed to provide a complete computing solution, optimizing both space and power consumption, making them ideal for a wide range of embedded applications.

What are Embedded - System On Chip (SoC)?

System On Chip (SoC) integrates multiple functions of a computer or electronic system onto a single chip. Unlike traditional multi-chip solutions, SoCs combine a central

Details

| | |
|-------------------------|---|
| Product Status | Active |
| Architecture | MCU, FPGA |
| Core Processor | ARM® Cortex®-M3 |
| Flash Size | 256KB |
| RAM Size | 64KB |
| Peripherals | DDR, PCIe, SERDES |
| Connectivity | CANbus, Ethernet, I ² C, SPI, UART/USART, USB |
| Speed | 166MHz |
| Primary Attributes | FPGA - 10K Logic Modules |
| Operating Temperature | -40°C ~ 100°C (TJ) |
| Package / Case | 256-LBGA |
| Supplier Device Package | 256-FPBGA (17x17) |
| Purchase URL | https://www.e-xfl.com/product-detail/microchip-technology/m2s010-1vfg256i |

Figure 1 • High Temperature Data Retention (HTR)**2.3.1.1 Overshoot/Undershoot Limits**

For AC signals, the input signal may undershoot during transitions to -1.0 V for no longer than 10% of the period. The current during the transition must not exceed 100 mA.

For AC signals, the input signal may overshoot during transitions to $V_{CC1} + 1.0$ V for no longer than 10% of the period. The current during the transition must not exceed 100 mA.

Note: The above specifications do not apply to the PCI standard. The IGLOO2 and SmartFusion2 PCI I/Os are compliant with the PCI standard including the PCI overshoot/undershoot specifications.

2.3.1.2 Thermal Characteristics

The temperature variable in the Microsemi SoC Products Group Designer software refers to the junction temperature, not the ambient, case, or board temperatures. This is an important distinction because dynamic and static power consumption causes the chip's junction temperature to be higher than the ambient, case, or board temperatures.

EQ1 through EQ3 give the relationship between thermal resistance, temperature gradient, and power.

$$\theta_{JA} = \frac{T_J - T_A}{P}$$

EQ 1

$$\theta_{JB} = \frac{T_J - T_B}{P}$$

EQ 2

$$\theta_{JC} = \frac{T_J - T_C}{P}$$

EQ 3

2.3.2 Power Consumption

The following sections describe the power consumptions of the devices.

2.3.2.1 Quiescent Supply Current

Table 10 • Quiescent Supply Current Characteristics

| Power Supplies/Blocks | Modes and Configurations | |
|---|--------------------------|--------------|
| | Non-Flash*Freeze | Flash*Freeze |
| FPGA Core | On | Off |
| V _{DD} /SERDES_[01]_VDD ¹ | On | On |
| V _{PP} /V _{PPNVM} | On | On |
| HPMS_MDDR_PLL_VDDA/FDDR_PLL_VDDA/ CCC_XX[01]_PLL_VDDA/PLL0_PLL1_HPMS_MDDR_VDD A | 0 V | 0 V |
| SERDES_[01]_PLL_VDDA ² | 0 V | 0 V |
| SERDES_[01]_L[0123]_VDDAPLL/VDD_2V5 ² | On | On |
| SERDES_[01]_L[0123]_VDDAIIO ² | On | On |
| V _{DDIx} ^{3, 4} | On | On |
| V _{REFx} | On | On |
| MSSDDR CLK | 32 kHz | 32 kHz |
| RAM | On | Sleep state |
| System controller | 50 MHz | 50 MHz |
| 50 MHz oscillator (enable/disable) | Enable | Disabled |
| 1 MHz oscillator (enable/disable) | Disabled | Disabled |
| Crystal oscillator (enable/disable) | Disabled | Disabled |

1. SERDES_[01]_VDD Power Supply is shorted to V_{DD}.
2. SerDes and DDR blocks to be unused.
3. V_{DDIx} has been set to ON for test conditions as described. Banks on the east side should always be powered with the appropriate V_{DDI} bank supplies. For details on bank power supplies, see "Recommendation for Unused Bank Supplies" table in the AC393: *SmartFusion2 and IGLOO2 Board Design Guidelines Application Note*.
4. No Differential (that is to say, LVDS) I/Os or ODT attributes to be used.

Table 11 • SmartFusion2 and IGLOO2 Quiescent Supply Current (V_{DD} = 1.2 V) – Typical Process

| Symbol | Modes | 005 | 010 | 025 | 050 | 060 | 090 | 150 | Unit | Conditions |
|--------|------------------|------|------|------|-------|-------|-------|-------|------|---|
| IDC1 | Non-Flash*Freeze | 6.2 | 6.9 | 8.9 | 13.1 | 15.3 | 15.4 | 27.5 | mA | Typical (T _J = 25 °C) |
| | | 24.0 | 28.4 | 40.6 | 67.8 | 80.6 | 81.4 | 144.7 | mA | Commercial (T _J = 85 °C) |
| | | 35.2 | 41.9 | 60.5 | 102.1 | 121.4 | 122.6 | 219.1 | mA | Industrial (T _J = 100 °C) |

Table 46 • LVCMOS 2.5 V Transmitter Characteristics for DDRIO Bank (Output and Tristate Buffers)
(continued)

| Output Drive Selection | Slew Control | T _{DP} | | T _{ZL} | | T _{ZH} | | T _{HZ} ¹ | | T _{LZ} ¹ | | Unit |
|------------------------|--------------|-----------------|-------|-----------------|-------|-----------------|-------|------------------------------|-------|------------------------------|-------|------|
| | | -1 | -Std | -1 | -Std | -1 | -Std | -1 | -Std | -1 | -Std | |
| 4 mA | Slow | 3.095 | 3.641 | 2.705 | 3.182 | 3.088 | 3.633 | 4.738 | 5.575 | 4.348 | 5.116 | ns |
| | Medium | 2.825 | 3.324 | 2.488 | 2.927 | 2.823 | 3.321 | 4.492 | 5.285 | 4.063 | 4.781 | ns |
| | Medium fast | 2.701 | 3.178 | 2.384 | 2.804 | 2.698 | 3.173 | 4.364 | 5.135 | 3.945 | 4.642 | ns |
| | Fast | 2.69 | 3.165 | 2.377 | 2.796 | 2.687 | 3.161 | 4.359 | 5.129 | 3.94 | 4.636 | ns |
| 6 mA | Slow | 2.919 | 3.434 | 2.491 | 2.93 | 2.902 | 3.414 | 5.085 | 5.983 | 4.674 | 5.5 | ns |
| | Medium | 2.65 | 3.118 | 2.279 | 2.681 | 2.642 | 3.108 | 4.845 | 5.701 | 4.375 | 5.148 | ns |
| | Medium fast | 2.529 | 2.975 | 2.176 | 2.56 | 2.521 | 2.965 | 4.724 | 5.558 | 4.259 | 5.011 | ns |
| | Fast | 2.516 | 2.96 | 2.168 | 2.551 | 2.508 | 2.95 | 4.717 | 5.55 | 4.251 | 5.002 | ns |
| 8 mA | Slow | 2.863 | 3.368 | 2.427 | 2.855 | 2.844 | 3.346 | 5.196 | 6.114 | 4.769 | 5.612 | ns |
| | Medium | 2.599 | 3.058 | 2.217 | 2.608 | 2.59 | 3.047 | 4.952 | 5.827 | 4.471 | 5.261 | ns |
| | Medium fast | 2.483 | 2.921 | 2.114 | 2.487 | 2.473 | 2.91 | 4.832 | 5.685 | 4.364 | 5.134 | ns |
| | Fast | 2.467 | 2.902 | 2.106 | 2.478 | 2.457 | 2.89 | 4.826 | 5.678 | 4.348 | 5.116 | ns |
| 12 mA | Slow | 2.747 | 3.232 | 2.296 | 2.701 | 2.724 | 3.204 | 5.39 | 6.342 | 4.938 | 5.81 | ns |
| | Medium | 2.493 | 2.934 | 2.102 | 2.473 | 2.483 | 2.921 | 5.166 | 6.078 | 4.65 | 5.471 | ns |
| | Medium fast | 2.382 | 2.803 | 2.006 | 2.36 | 2.371 | 2.789 | 5.067 | 5.962 | 4.546 | 5.349 | ns |
| | Fast | 2.369 | 2.787 | 1.999 | 2.352 | 2.357 | 2.773 | 5.063 | 5.958 | 4.538 | 5.339 | ns |
| 16 mA | Slow | 2.677 | 3.149 | 2.213 | 2.604 | 2.649 | 3.116 | 5.575 | 6.56 | 5.08 | 5.977 | ns |
| | Medium | 2.432 | 2.862 | 2.028 | 2.386 | 2.421 | 2.848 | 5.372 | 6.32 | 4.801 | 5.649 | ns |
| | Medium fast | 2.324 | 2.734 | 1.937 | 2.278 | 2.311 | 2.718 | 5.297 | 6.233 | 4.7 | 5.531 | ns |
| | Fast | 2.313 | 2.721 | 1.929 | 2.269 | 2.3 | 2.706 | 5.296 | 6.231 | 4.699 | 5.529 | ns |

1. Delay increases with drive strength are inherent to built-in slew control circuitry for simultaneous switching output (SSO) management.

Table 47 • LVCMOS 2.5 V Transmitter Characteristics for MSIO Bank (Output and Tristate Buffers)

| Output Drive Selection | Slew Control | T _{DP} | | T _{ZL} | | T _{ZH} | | T _{HZ} ¹ | | T _{LZ} ¹ | | Unit |
|------------------------|--------------|-----------------|-------|-----------------|-------|-----------------|-------|------------------------------|-------|------------------------------|-------|------|
| | | -1 | -Std | -1 | -Std | -1 | -Std | -1 | -Std | -1 | -Std | |
| 2 mA | Slow | 3.48 | 4.095 | 3.855 | 4.534 | 3.785 | 4.453 | 2.12 | 2.494 | 3.45 | 4.059 | ns |
| 4 mA | Slow | 2.583 | 3.039 | 3.042 | 3.579 | 3.138 | 3.691 | 4.143 | 4.874 | 4.687 | 5.513 | ns |
| 6 mA | Slow | 2.392 | 2.815 | 2.669 | 3.139 | 2.82 | 3.317 | 4.909 | 5.775 | 5.083 | 5.98 | ns |
| 8 mA | Slow | 2.309 | 2.717 | 2.565 | 3.017 | 2.74 | 3.223 | 5.812 | 6.837 | 5.523 | 6.497 | ns |
| 12 mA | Slow | 2.333 | 2.745 | 2.437 | 2.867 | 2.626 | 3.089 | 6.131 | 7.213 | 5.712 | 6.72 | ns |
| 16 mA | Slow | 2.412 | 2.838 | 2.335 | 2.747 | 2.533 | 2.979 | 6.54 | 7.694 | 6.007 | 7.067 | ns |

1. Delay increases with drive strength are inherent to built-in slew control circuitry for simultaneous switching output (SSO) management.

Table 57 • LVCMOS 1.8 V Transmitter Characteristics for DDRIO I/O Bank with Fixed Code (Output and Tristate Buffers)

| Output Drive Selection | Slew Control | T _{DP} | | T _{ZL} | | T _{ZH} | | T _{HZ} ¹ | | T _{LZ} ¹ | | Unit |
|------------------------|--------------|-----------------|-------|-----------------|-------|-----------------|-------|------------------------------|-------|------------------------------|-------|------|
| | | -1 | -Std | -1 | -Std | -1 | -Std | -1 | -Std | -1 | -Std | |
| 2 mA | Slow | 4.234 | 4.981 | 3.646 | 4.29 | 4.245 | 4.995 | 4.908 | 5.774 | 4.434 | 5.216 | ns |
| | Medium | 3.824 | 4.498 | 3.282 | 3.861 | 3.834 | 4.511 | 4.625 | 5.441 | 4.116 | 4.843 | ns |
| | Medium fast | 3.627 | 4.267 | 3.111 | 3.66 | 3.637 | 4.279 | 4.481 | 5.272 | 3.984 | 4.687 | ns |
| | Fast | 3.605 | 4.241 | 3.097 | 3.644 | 3.615 | 4.253 | 4.472 | 5.262 | 3.973 | 4.674 | ns |
| 4 mA | Slow | 3.923 | 4.615 | 3.314 | 3.9 | 3.918 | 4.61 | 5.403 | 6.356 | 4.894 | 5.757 | ns |
| | Medium | 3.518 | 4.138 | 2.961 | 3.484 | 3.515 | 4.135 | 5.121 | 6.025 | 4.561 | 5.366 | ns |
| | Medium fast | 3.321 | 3.907 | 2.783 | 3.275 | 3.317 | 3.903 | 4.966 | 5.843 | 4.426 | 5.206 | ns |
| | Fast | 3.301 | 3.883 | 2.77 | 3.259 | 3.296 | 3.878 | 4.957 | 5.831 | 4.417 | 5.196 | ns |
| 6 mA | Slow | 3.71 | 4.364 | 3.104 | 3.652 | 3.702 | 4.355 | 5.62 | 6.612 | 5.08 | 5.977 | ns |
| | Medium | 3.333 | 3.921 | 2.779 | 3.27 | 3.325 | 3.913 | 5.346 | 6.289 | 4.777 | 5.62 | ns |
| | Medium fast | 3.155 | 3.712 | 2.62 | 3.083 | 3.146 | 3.702 | 5.21 | 6.13 | 4.657 | 5.479 | ns |
| | Fast | 3.134 | 3.688 | 2.608 | 3.068 | 3.125 | 3.677 | 5.202 | 6.12 | 4.648 | 5.468 | ns |
| 8 mA | Slow | 3.619 | 4.258 | 3.007 | 3.538 | 3.607 | 4.244 | 5.815 | 6.841 | 5.249 | 6.175 | ns |
| | Medium | 3.246 | 3.819 | 2.686 | 3.16 | 3.236 | 3.807 | 5.542 | 6.52 | 4.936 | 5.807 | ns |
| | Medium fast | 3.066 | 3.607 | 2.525 | 2.971 | 3.054 | 3.593 | 5.405 | 6.359 | 4.811 | 5.66 | ns |
| | Fast | 3.046 | 3.584 | 2.513 | 2.957 | 3.034 | 3.57 | 5.401 | 6.353 | 4.803 | 5.651 | ns |
| 10 mA | Slow | 3.498 | 4.115 | 2.878 | 3.386 | 3.481 | 4.096 | 6.046 | 7.113 | 5.444 | 6.404 | ns |
| | Medium | 3.138 | 3.692 | 2.569 | 3.023 | 3.126 | 3.678 | 5.782 | 6.803 | 5.129 | 6.034 | ns |
| | Medium fast | 2.966 | 3.489 | 2.414 | 2.841 | 2.951 | 3.472 | 5.666 | 6.665 | 5.013 | 5.897 | ns |
| | Fast | 2.945 | 3.464 | 2.401 | 2.826 | 2.93 | 3.448 | 5.659 | 6.658 | 5.003 | 5.886 | ns |
| 12 mA | Slow | 3.417 | 4.02 | 2.807 | 3.303 | 3.401 | 4.002 | 6.083 | 7.156 | 5.464 | 6.428 | ns |
| | Medium | 3.076 | 3.618 | 2.519 | 2.964 | 3.063 | 3.604 | 5.828 | 6.856 | 5.176 | 6.089 | ns |
| | Medium fast | 2.913 | 3.427 | 2.376 | 2.795 | 2.898 | 3.41 | 5.725 | 6.736 | 5.072 | 5.966 | ns |
| | Fast | 2.894 | 3.405 | 2.362 | 2.78 | 2.879 | 3.388 | 5.715 | 6.724 | 5.064 | 5.957 | ns |
| 16 mA | Slow | 3.366 | 3.96 | 2.751 | 3.237 | 3.348 | 3.939 | 6.226 | 7.324 | 5.576 | 6.56 | ns |
| | Medium | 3.03 | 3.565 | 2.47 | 2.906 | 3.017 | 3.55 | 5.981 | 7.036 | 5.282 | 6.214 | ns |
| | Medium fast | 2.87 | 3.377 | 2.328 | 2.739 | 2.854 | 3.358 | 5.895 | 6.935 | 5.18 | 6.094 | ns |
| | Fast | 2.853 | 3.357 | 2.314 | 2.723 | 2.837 | 3.338 | 5.889 | 6.929 | 5.177 | 6.09 | ns |

1. Delay increases with drive strength are inherent to built-in slew control circuitry for simultaneous switching output (SSO) management.

Table 85 • LVCMOS 1.2 V Transmitter Characteristics for MSIOD I/O Bank (Output and Tristate Buffers)

| Output Drive Selection | Slew Control | T _{DP} | | T _{ZL} | | T _{ZH} | | T _{HZ} ¹ | | T _{LZ} ¹ | | Unit |
|------------------------|--------------|-----------------|-------|-----------------|-------|-----------------|-------|------------------------------|--------|------------------------------|-------|------|
| | | -1 | -Std | -1 | -Std | -1 | -Std | -1 | -Std | -1 | -Std | |
| 2 mA | Slow | 3.883 | 4.568 | 4.868 | 5.726 | 5.329 | 6.269 | 7.994 | 9.404 | 7.527 | 8.855 | ns |
| 4 mA | Slow | 3.774 | 4.44 | 4.188 | 4.926 | 4.613 | 5.426 | 8.972 | 10.555 | 8.315 | 9.782 | ns |

1. Delay increases with drive strength are inherent to built-in slew control circuitry for simultaneous switching output (SSO) management.

2.3.5.11 3.3 V PCI/PCIX

Peripheral Component Interface (PCI) for 3.3 V standards specify support for 33 MHz and 66 MHz PCI bus applications.

Minimum and Maximum DC/AC Input and Output Levels Specification (Applicable to MSIO Bank Only)

Table 86 • PCI/PCI-X DC Recommended Operating Conditions

| Parameter | Symbol | Min | Typ | Max | Unit |
|----------------|------------------|------|-----|------|------|
| Supply voltage | V _{DDI} | 3.15 | 3.3 | 3.45 | V |

Table 87 • PCI/PCI-X DC Input Voltage Specification

| Parameter | Symbol | Min | Max | Unit |
|---------------------------------|----------------------|-----|------|------|
| DC input voltage | V _I | 0 | 3.45 | V |
| Input current high ¹ | I _{IH} (DC) | | | |
| Input current low ¹ | I _{IL} (DC) | | | |

1. See Table 24, page 22.

Table 88 • PCI/PCI-X DC Output Voltage Specification

| Parameter | Symbol | Min | Typ | Max | Unit |
|----------------------|-----------------|-----|-----------------------|-----|------|
| DC output logic high | V _{OH} | | Per PCI specification | | V |
| DC output logic low | V _{OL} | | Per PCI specification | | V |

Table 89 • PCI/PCI-X Minimum and Maximum AC Switching Speed

| Parameter | Symbol | Max | Unit | Conditions |
|-----------------------------------|------------------|-----|------|--------------------------------------|
| Maximum data rate (MSIO I/O bank) | D _{MAX} | 630 | Mbps | AC Loading: per JEDEC specifications |

Table 90 • PCI/PCI-X AC Test Parameter Specifications

| Parameter | Symbol | Typ | Unit |
|---|----------------------|--------------------------|------|
| Measuring/trip point for data path (falling edge) | V _{TRIP} | 0.615 × V _{DDI} | V |
| Measuring/trip point for data path (rising edge) | V _{TRIP} | 0.285 × V _{DDI} | V |
| Resistance for data test path | R _{TT_TEST} | 25 | Ω |
| Resistance for enable path (T _{ZH} , T _{ZL} , T _{HZ} , T _{LZ}) | R _{ENT} | 2K | Ω |
| Capacitive loading for enable path (T _{ZH} , T _{ZL} , T _{HZ} , T _{LZ}) | C _{ENT} | 5 | pF |
| Capacitive loading for data path (T _{DP}) | C _{LOAD} | 10 | pF |

2.3.6.3 Stub-Series Terminated Logic 2.5 V (SSTL2)

SSTL2 Class I and Class II are supported in IGLOO2 and SmartFusion2 SoC FPGAs and also comply with reduced and full drive of double data rate (DDR) standards. IGLOO2 and SmartFusion2 SoC FPGA I/Os supports both standards for single-ended signaling and differential signaling for SSTL2. This standard requires a differential amplifier input buffer and a push-pull output buffer.

Minimum and Maximum DC/AC Input and Output Levels Specification

Table 103 • DDR1/SSTL2 DC Recommended Operating Conditions

| Parameter | Symbol | Min | Typ | Max | Unit |
|-------------------------|-----------|-------|-------|-------|------|
| Supply voltage | V_{DDI} | 2.375 | 2.5 | 2.625 | V |
| Termination voltage | V_{TT} | 1.164 | 1.250 | 1.339 | V |
| Input reference voltage | V_{REF} | 1.164 | 1.250 | 1.339 | V |

Table 104 • DDR1/SSTL2 DC Input Voltage Specification

| Parameter | Symbol | Min | Max | Unit |
|---------------------------------|---------------|------------------|------------------|------|
| DC input logic high | V_{IH} (DC) | $V_{REF} + 0.15$ | 2.625 | V |
| DC input logic low | V_{IL} (DC) | -0.3 | $V_{REF} - 0.15$ | V |
| Input current high ¹ | I_{IH} (DC) | | | |
| Input current low ¹ | I_{IL} (DC) | | | |

1. See Table 24, page 22.

Table 105 • DDR1/SSTL2 DC Output Voltage Specification

| Parameter | Symbol | Min | Max | Unit |
|---|----------------------|------------------|------------------|------|
| SSTL2 Class I (DDR Reduced Drive) | | | | |
| DC output logic high | V_{OH} | $V_{TT} + 0.608$ | | V |
| DC output logic low | V_{OL} | | $V_{TT} - 0.608$ | V |
| Output minimum source DC current | I_{OH} at V_{OH} | 8.1 | | mA |
| Output minimum sink current | I_{OL} at V_{OL} | -8.1 | | mA |
| SSTL2 Class II (DDR Full Drive) – Applicable to MSIO and DDRIO I/O Bank Only | | | | |
| DC output logic high | V_{OH} | $V_{TT} + 0.81$ | | V |
| DC output logic low | V_{OL} | | $V_{TT} - 0.81$ | V |
| Output minimum source DC current | I_{OH} at V_{OH} | 16.2 | | mA |
| Output minimum sink current | I_{OL} at V_{OL} | -16.2 | | mA |

Table 106 • DDR1/SSTL2 DC Differential Voltage Specification

| Parameter | Symbol | Min | Unit |
|-------------------------------|---------------|-----|------|
| DC input differential voltage | V_{ID} (DC) | 0.3 | V |

2.3.6.6 Low Power Double Data Rate (LPDDR)

LPDDR reduced and full drive low power double data rate standards are supported in IGLOO2 FPGA and SmartFusion2 SoC FPGA I/Os. This standard requires a differential amplifier input buffer and a push-pull output buffer.

Minimum and Maximum DC/AC Input and Output Levels Specification

Table 139 • LPDDR DC Recommended DC Operating Conditions

| Parameter | Symbol | Min | Typ | Max |
|-------------------------|-----------|-------|-------|-------|
| Supply voltage | V_{DDI} | 1.71 | 1.8 | 1.89 |
| Termination voltage | V_{TT} | 0.838 | 0.900 | 0.964 |
| Input reference voltage | V_{REF} | 0.838 | 0.900 | 0.964 |

Table 140 • LPDDR DC Input Voltage Specification

| Parameter | Symbol | Min | Max |
|---------------------------------|---------------|----------------------|----------------------|
| DC input logic high | V_{IH} (DC) | $0.7 \times V_{DDI}$ | 1.89 |
| DC input logic low | V_{IL} (DC) | -0.3 | $0.3 \times V_{DDI}$ |
| Input current high ¹ | I_{IH} (DC) | | |
| Input current low ¹ | I_{IL} (DC) | | |

1. See Table 24, page 22.

Table 141 • LPDDR DC Output Voltage Specification Reduced Drive

| Parameter | Symbol | Min | Max |
|----------------------------------|----------------------|----------------------|----------------------|
| DC output logic high | V_{OH} | $0.9 \times V_{DDI}$ | |
| DC output logic low | V_{OL} | | $0.1 \times V_{DDI}$ |
| Output minimum source DC current | I_{OH} at V_{OH} | 0.1 | |
| Output minimum sink current | I_{OL} at V_{OL} | -0.1 | |

Table 142 • LPDDR DC Output Voltage Specification Full Drive¹

| Parameter | Symbol | Min | Max |
|----------------------------------|----------------------|----------------------|----------------------|
| DC output logic high | V_{OH} | $0.9 \times V_{DDI}$ | |
| DC output logic low | V_{OL} | | $0.1 \times V_{DDI}$ |
| Output minimum source DC current | I_{OH} at V_{OH} | 0.1 | |
| Output minimum sink current | I_{OL} at V_{OL} | -0.1 | |

1. To meet JEDEC Electrical Compliance, use LPDDR Full Drive Transmitter.

Table 143 • LPDDR DC Differential Voltage Specification

| Parameter | Symbol | Min |
|-------------------------------|---------------|----------------------|
| DC input differential voltage | V_{ID} (DC) | $0.4 \times V_{DDI}$ |

Table 168 • LVDS25 Receiver Characteristics for MSIOD I/O Bank (Input Buffers)

| On-Die Termination (ODT) | T_{PY} | | Unit |
|--------------------------|----------|-------|------|
| | -1 | -Std | |
| None | 2.554 | 3.004 | ns |
| 100 | 2.549 | 2.999 | ns |

Table 169 • LVDS25 Transmitter Characteristics for MSIO I/O Bank (Output and Tristate Buffers)

| T_{DP} | | T_{ZL} | | T_{ZH} | | T_{HZ} | | T_{LZ} | | Unit |
|----------|-------|----------|-------|----------|-------|----------|------|----------|-------|------|
| -1 | -Std | -1 | -Std | -1 | -Std | -1 | -Std | -1 | -Std | |
| 2.136 | 2.513 | 2.416 | 2.842 | 2.402 | 2.825 | 2.423 | 2.85 | 2.409 | 2.833 | ns |

Table 170 • LVDS25 Transmitter Characteristics for MSIOD I/O Bank (Output and Tristate Buffers)

| | T_{DP} | | T_{ZL} | | T_{ZH} | | T_{HZ} | | T_{LZ} | | Unit |
|------------------|----------|-------|----------|-------|----------|-------|----------|-------|----------|-------|------|
| | -1 | -Std | -1 | -Std | -1 | -Std | -1 | -Std | -1 | -Std | |
| No pre-emphasis | 1.61 | 1.893 | 1.749 | 2.058 | 1.735 | 2.041 | 1.897 | 2.231 | 1.866 | 2.195 | ns |
| Min pre-emphasis | 1.527 | 1.796 | 1.757 | 2.067 | 1.744 | 2.052 | 1.905 | 2.241 | 1.876 | 2.207 | ns |
| Med pre-emphasis | 1.496 | 1.76 | 1.765 | 2.077 | 1.751 | 2.06 | 1.914 | 2.252 | 1.884 | 2.216 | ns |

LVDS33 AC Switching Characteristics

Table 171 • LVDS33 Receiver Characteristics for MSIO I/O Bank (Input Buffers)

| On Die Termination (ODT) | T_{PY} | | Unit |
|--------------------------|----------|-------|------|
| | -1 | -Std | |
| None | 2.572 | 3.025 | ns |
| 100 | 2.569 | 3.023 | ns |

Table 172 • LVDS33 Transmitter Characteristics for MSIO I/O Bank (Output and Tristate Buffers)

| T_{DP} | | T_{ZL} | | T_{ZH} | | T_{HZ} | | T_{LZ} | | Unit |
|----------|-------|----------|------|----------|-------|----------|-------|----------|-------|------|
| -1 | -Std | -1 | -Std | -1 | -Std | -1 | -Std | -1 | -Std | |
| 1.942 | 2.284 | 1.98 | 2.33 | 1.97 | 2.318 | 1.953 | 2.298 | 1.96 | 2.307 | ns |

Table 185 • M-LVDS DC Voltage Specification Output Voltage Specification (for MSIO I/O Bank Only)

| Parameter | Symbol | Min | Typ | Max | Unit |
|----------------------|----------|------|-------|------|------|
| DC output logic high | V_{OH} | 1.25 | 1.425 | 1.6 | V |
| DC output logic low | V_{OL} | 0.9 | 1.075 | 1.25 | V |

Table 186 • M-LVDS Differential Voltage Specification

| Parameter | Symbol | Min | Max | Unit |
|--|-----------|-----|------|------|
| Differential output voltage swing (for MSIO I/O bank only) | V_{OD} | 300 | 650 | mV |
| Output common mode voltage (for MSIO I/O bank only) | V_{OCM} | 0.3 | 2.1 | V |
| Input common mode voltage | V_{ICM} | 0.3 | 1.2 | V |
| Input differential voltage | V_{ID} | 50 | 2400 | mV |

Table 187 • M-LVDS Minimum and Maximum AC Switching Speed for MSIO I/O Bank

| Parameter | Symbol | Max | Unit | Conditions |
|-------------------|-----------|-----|------|---|
| Maximum data rate | D_{MAX} | 500 | Mbps | AC loading: 2 pF / 100 Ω differential load |

Table 188 • M-LVDS AC Impedance Specifications

| Parameter | Symbol | Typ | Unit |
|------------------------|--------|-----|----------|
| Termination resistance | R_T | 50 | Ω |

Table 189 • M-LVDS AC Test Parameter Specifications

| Parameter | Symbol | Typ | Unit |
|--|------------|-------------|----------|
| Measuring/trip point for data path | V_{TRIP} | Cross point | V |
| Resistance for enable path (T_{ZH} , T_{ZL} , T_{HZ} , T_{LZ}) | R_{ENT} | 2K | Ω |
| Capacitive loading for enable path (T_{ZH} , T_{ZL} , T_{HZ} , T_{LZ}) | C_{ENT} | 5 | pF |

AC Switching Characteristics

Worst commercial-case conditions: $T_J = 85\text{ }^\circ\text{C}$, $V_{DD} = 1.14\text{ V}$, $V_{DDI} = 2.375\text{ V}$

Table 190 • M-LVDS AC Switching Characteristics for Receiver (for MSIO I/O Bank - Input Buffers)

| On-Die Termination (ODT) | T_{PY} | | Unit |
|--------------------------|----------|-------|------|
| | -1 | -Std | |
| None | 2.738 | 3.221 | ns |
| 100 | 2.735 | 3.218 | ns |

Table 198 • Mini-LVDS AC Impedance Specifications

| Parameter | Symbol | Typ | Unit |
|------------------------|--------|-----|----------|
| Termination resistance | R_T | 100 | Ω |

Table 199 • Mini-LVDS AC Test Parameter Specifications

| Parameter | Symbol | Typ | Unit |
|--|------------|-------------|----------|
| Measuring/trip point for data path | V_{TRIP} | Cross point | V |
| Resistance for enable path (T_{ZH} , T_{ZL} , T_{HZ} , T_{LZ}) | R_{ENT} | 2K | Ω |
| Capacitive loading for enable path (T_{ZH} , T_{ZL} , T_{HZ} , T_{LZ}) | C_{ENT} | 5 | pF |

AC Switching Characteristics

Worst commercial-case conditions: $T_J = 85\text{ }^\circ\text{C}$, $V_{DD} = 1.14\text{ V}$, $V_{DDI} = 2.375\text{ V}$.

Table 200 • Mini-LVDS AC Switching Characteristics for Receiver (for MSIO I/O Bank - Input Buffers)

| On-Die Termination (ODT) | T_{PY} | | Unit |
|--------------------------|----------|-------|------|
| | -1 | -Std | |
| None | 2.855 | 3.359 | ns |
| 100 | 2.85 | 3.353 | ns |
| None | 2.602 | 3.061 | ns |
| 100 | 2.597 | 3.055 | ns |

Table 201 • Mini-LVDS AC Switching Characteristics for Transmitter for MSIO I/O Bank (Output and Tristate Buffers)

| T_{DP} | | T_{ZL} | | T_{ZH} | | T_{HZ} | | T_{LZ} | | Unit |
|----------|-------|----------|-------|----------|-------|----------|------|----------|-------|------|
| -1 | -Std | -1 | -Std | -1 | -Std | -1 | -Std | -1 | -Std | |
| 2.097 | 2.467 | 2.308 | 2.715 | 2.296 | 2.701 | 1.964 | 2.31 | 1.949 | 2.293 | ns |

Table 202 • Mini-LVDS AC Switching Characteristics for Transmitter (for MSIOD I/O Bank - Output and Tristate Buffers)

| | T_{DP} | | T_{ZL} | | T_{ZH} | | T_{HZ} | | T_{LZ} | | Unit |
|------------------|----------|-------|----------|-------|----------|-------|----------|-------|----------|-------|------|
| | -1 | -Std | -1 | -Std | -1 | -Std | -1 | -Std | -1 | -Std | |
| No pre-emphasis | 1.614 | 1.899 | 1.562 | 1.837 | 1.553 | 1.826 | 1.593 | 1.874 | 1.578 | 1.856 | ns |
| Min pre-emphasis | 1.604 | 1.887 | 1.745 | 2.053 | 1.731 | 2.036 | 1.892 | 2.225 | 1.861 | 2.189 | ns |
| Med pre-emphasis | 1.521 | 1.79 | 1.753 | 2.062 | 1.737 | 2.043 | 1.9 | 2.235 | 1.868 | 2.197 | ns |
| Max pre-emphasis | 1.492 | 1.754 | 1.762 | 2.073 | 1.745 | 2.052 | 1.91 | 2.247 | 1.876 | 2.206 | ns |

Table 215 • LVPECL DC Input Voltage Specification

| Parameter | Symbol | Min | Max | Unit |
|------------------|--------|-----|------|------|
| DC input voltage | V_I | 0 | 3.45 | V |

Table 216 • LVPECL DC Differential Voltage Specification

| Parameter | Symbol | Min | Typ | Max | Unit |
|----------------------------|-------------|-----|-----|-------|------|
| Input common mode voltage | V_{ICM} | 0.3 | | 2.8 | V |
| Input differential voltage | V_{IDIFF} | 100 | 300 | 1,000 | mV |

Table 217 • LVPECL Minimum and Maximum AC Switching Speeds

| Parameter | Symbol | Max | Unit |
|-------------------|-----------|-----|------|
| Maximum data rate | D_{MAX} | 900 | Mbps |

AC Switching Characteristics

Worst commercial-case conditions: $T_J = 85\text{ }^\circ\text{C}$, $V_{DD} = 1.14\text{ V}$, $V_{DDI} = 2.375\text{ V}$.

Table 218 • LVPECL Receiver Characteristics for MSIO I/O Bank

| On-Die Termination (ODT) | T_{PY} | | Unit |
|--------------------------|----------|-------|------|
| | -1 | -Std | |
| None | 2.572 | 3.025 | ns |
| 100 | 2.569 | 3.023 | ns |

2.3.8 I/O Register Specifications

This section describes input and output register specifications.

2.3.8.1 Input Register

Figure 6 • Timing Model for Input Register

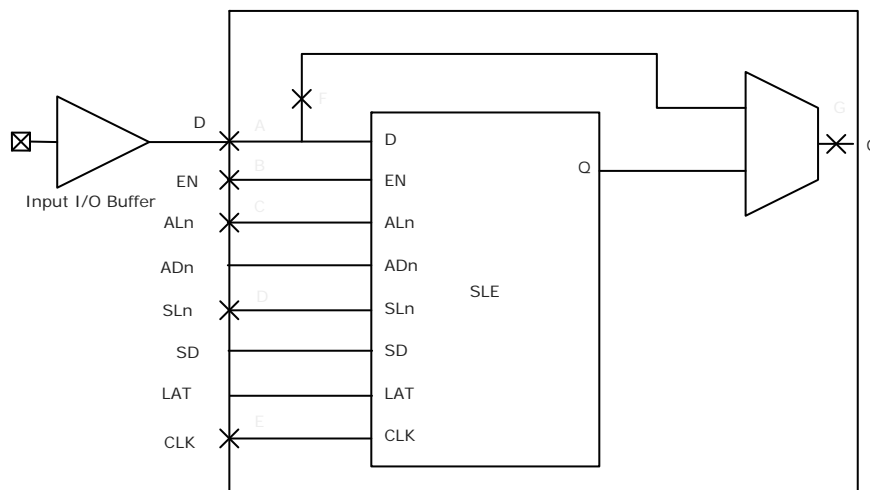


Table 232 • RAM1K18 – Dual-Port Mode for Depth × Width Configuration 2K × 9 (continued)

| Parameter | Symbol | –1 | | –Std | | Unit |
|--|-----------------------|--------|-------|--------|-------|------|
| | | Min | Max | Min | Max | |
| Address setup time | T _{ADDRSU} | 0.475 | | 0.559 | | ns |
| Address hold time | T _{ADDRHD} | 0.274 | | 0.322 | | ns |
| Data setup time | T _{DSU} | 0.336 | | 0.395 | | ns |
| Data hold time | T _{DHD} | 0.082 | | 0.096 | | ns |
| Block select setup time | T _{BLKSU} | 0.207 | | 0.244 | | ns |
| Block select hold time | T _{BLKHD} | 0.216 | | 0.254 | | ns |
| Block select to out disable time (when pipelined register is disabled) | T _{BLK2Q} | | 1.529 | | 1.799 | ns |
| Block select minimum pulse width | T _{BLKMPW} | 0.186 | | 0.219 | | ns |
| Read enable setup time | T _{RDESU} | 0.485 | | 0.57 | | ns |
| Read enable hold time | T _{RDEHD} | 0.071 | | 0.083 | | ns |
| Pipelined read enable setup time (A_DOUT_EN, B_DOUT_EN) | T _{RDPLESU} | 0.248 | | 0.291 | | ns |
| Pipelined read enable hold time (A_DOUT_EN, B_DOUT_EN) | T _{RDPLEHD} | 0.102 | | 0.12 | | ns |
| Asynchronous reset to output propagation delay | T _{R2Q} | | 1.514 | | 1.781 | ns |
| Asynchronous reset removal time | T _{RSTREM} | 0.506 | | 0.595 | | ns |
| Asynchronous reset recovery time | T _{RSTREC} | 0.004 | | 0.005 | | ns |
| Asynchronous reset minimum pulse width | T _{RSTMPW} | 0.301 | | 0.354 | | ns |
| Pipelined register asynchronous reset removal time | T _{PLRSTREM} | –0.279 | | –0.328 | | ns |
| Pipelined register asynchronous reset recovery time | T _{PLRSTREC} | 0.327 | | 0.385 | | ns |
| Pipelined register asynchronous reset minimum pulse width | T _{PLRSTMPW} | 0.282 | | 0.332 | | ns |
| Synchronous reset setup time | T _{SRSTSU} | 0.226 | | 0.265 | | ns |
| Synchronous reset hold time | T _{SRSTHD} | 0.036 | | 0.043 | | ns |
| Write enable setup time | T _{WESU} | 0.415 | | 0.488 | | ns |
| Write enable hold time | T _{WEHD} | 0.048 | | 0.057 | | ns |
| Maximum frequency | F _{MAX} | | 400 | | 340 | MHz |

The following table lists the RAM1K18 – dual-port mode for depth × width configuration 4K × 4 in worst commercial-case conditions when T_J = 85 °C, V_{DD} = 1.14 V.

Table 233 • RAM1K18 – Dual-Port Mode for Depth × Width Configuration 4K × 4

| Parameter | Symbol | –1 | | –Std | | Unit |
|--|------------------------|-------|-----|-------|-----|------|
| | | Min | Max | Min | Max | |
| Clock period | T _{CY} | 2.5 | | 2.941 | | ns |
| Clock minimum pulse width high | T _{CLKMPWH} | 1.125 | | 1.323 | | ns |
| Clock minimum pulse width low | T _{CLKMPWL} | 1.125 | | 1.323 | | ns |
| Pipelined clock period | T _{PLCY} | 2.5 | | 2.941 | | ns |
| Pipelined clock minimum pulse width high | T _{PLCLKMPWH} | 1.125 | | 1.323 | | ns |

Table 243 • μ SRAM (RAM1024x1) in 1024 x 1 Mode (continued)

| Parameter | Symbol | -1 | | -Std | | Unit |
|---|----------------|-------|------|-------|------|------|
| | | Min | Max | Min | Max | |
| Read asynchronous reset recovery time (pipelined clock) | T_{RSTREC} | 0.507 | | 0.597 | | ns |
| Read asynchronous reset recovery time (non-pipelined clock) | | 0.236 | | 0.278 | | ns |
| Read asynchronous reset to output propagation delay (with pipelined register enabled) | T_{R2Q} | | 0.83 | | 0.98 | ns |
| Read synchronous reset setup time | T_{SRSTSU} | 0.271 | | 0.319 | | ns |
| Read synchronous reset hold time | T_{SRSTHD} | 0.061 | | 0.071 | | ns |
| Write clock period | T_{CCY} | 4 | | 4 | | ns |
| Write clock minimum pulse width high | $T_{CCLKMPWH}$ | 1.8 | | 1.8 | | ns |
| Write clock minimum pulse width low | $T_{CCLKMPWL}$ | 1.8 | | 1.8 | | ns |
| Write block setup time | T_{BLKCSU} | 0.404 | | 0.476 | | ns |
| Write block hold time | T_{BLKCHD} | 0.007 | | 0.008 | | ns |
| Write input data setup time | T_{DINCSU} | 0.003 | | 0.004 | | ns |
| Write input data hold time | T_{DINCHD} | 0.137 | | 0.161 | | ns |
| Write address setup time | $T_{ADDRCSU}$ | 0.088 | | 0.104 | | ns |
| Write address hold time | $T_{ADDRCHD}$ | 0.247 | | 0.29 | | ns |
| Write enable setup time | T_{WECSU} | 0.397 | | 0.467 | | ns |
| Write enable hold time | T_{WECHD} | -0.03 | | -0.03 | | ns |
| Maximum frequency | F_{MAX} | | 250 | | 250 | MHz |

2.3.13 Programming Times

The following tables list the programming times in typical conditions when $T_J = 25\text{ }^\circ\text{C}$, $V_{DD} = 1.2\text{ V}$. External SPI flash part# AT25DF641-s3H is used during this measurement.

Table 244 • JTAG Programming (Fabric Only)

| M2S/M2GL | | | | |
|----------|------------------|---------|--------|------|
| Device | Image size Bytes | Program | Verify | Unit |
| 005 | 302672 | 22 | 10 | Sec |
| 010 | 568784 | 28 | 18 | Sec |
| 025 | 1223504 | 51 | 26 | Sec |
| 050 | 2424832 | 66 | 54 | Sec |
| 060 | 2418896 | 77 | 54 | Sec |
| 090 | 3645968 | 113 | 126 | Sec |
| 150 | 6139184 | 155 | 193 | Sec |

Table 265 • Programming Times with 100 kHz, 25 MHz, and 12.5 MHz SPI Clock Rates (Fabric Only)

| M2S/M2GL Device | Auto Programming | | | Unit |
|-----------------|------------------|---------------|---------------|------|
| | 100 kHz | 25 MHz | 12.5 MHz | |
| 005 | 69 | 49 | 50 | Sec |
| 010 | 99 | 57 | 57 | Sec |
| 025 | 150 | 64 | 63 | Sec |
| 050 | 55 ¹ | Not Supported | Not Supported | Sec |
| 060 | 313 | 105 | 104 | Sec |
| 090 | 449 | 131 | 130 | Sec |
| 150 | 730 | 179 | 183 | Sec |

1. Auto programming in 050 device is done through SC_SPI, and SPI CLK is set to 6.25 MHz.

Table 266 • Programming Times with 100 kHz, 25 MHz, and 12.5 MHz SPI Clock Rates (eNVM Only)

| M2S/M2GL Device | Auto Programming | | | Unit |
|-----------------|------------------|---------------|---------------|------|
| | 100 kHz | 25 MHz | 12.5 MHz | |
| 005 | 63 | 70 | 71 | Sec |
| 010 | 108 | 109 | 109 | Sec |
| 025 | 109 | 107 | 108 | Sec |
| 050 | 107 | Not Supported | Not Supported | Sec |
| 060 | 100 | 108 | 108 | Sec |
| 090 | 176 | 184 | 184 | Sec |
| 150 | 183 | 183 | 183 | Sec |

Table 267 • Programming Times with 100 kHz, 25 MHz, and 12.5 MHz SPI Clock Rates (Fabric and eNVM)

| M2S/M2GL Device | Auto Programming | | | Unit |
|-----------------|------------------|---------------|---------------|------|
| | 100 kHz | 25 MHz | 12.5 MHz | |
| 005 | 109 | 89 | 88 | Sec |
| 010 | 183 | 135 | 135 | Sec |
| 025 | 251 | 142 | 143 | Sec |
| 050 | 134 | Not Supported | Not Supported | Sec |
| 060 | 390 | 183 | 180 | Sec |
| 090 | 604 | 283 | 282 | Sec |
| 150 | 889 | 331 | 332 | Sec |

2.3.14 Math Block Timing Characteristics

The fundamental building block in any digital signal processing algorithm is the multiply-accumulate function. Each IGLOO2 and SmartFusion2 SoC math block supports 18×18 signed multiplication, dot product, and built-in addition, subtraction, and accumulation units to combine multiplication results efficiently. The following table lists the math blocks with all registers used in worst commercial-case conditions when $T_J = 85\text{ }^\circ\text{C}$, $V_{DD} = 1.14\text{ V}$.

Table 268 • Math Blocks with all Registers Used

| Parameter | Symbol | -1 | | -Std | | Unit |
|-------------------------------------|-----------------|--------|-------|--------|-------|------|
| | | Min | Max | Min | Max | |
| Input, control register setup time | T_{MISU} | 0.149 | | 0.176 | | ns |
| Input, control register hold time | T_{MIHD} | 1.68 | | 1.976 | | ns |
| CDIN input setup time | $T_{MOCDINSU}$ | 0.185 | | 0.218 | | ns |
| CDIN input hold time | $T_{MOCDINHHD}$ | 0.08 | | 0.094 | | ns |
| Synchronous reset/enable setup time | $T_{MSRSTENSU}$ | -0.419 | | -0.493 | | ns |
| Synchronous reset/enable hold time | $T_{MSRSTENHD}$ | 0.011 | | 0.013 | | ns |
| Asynchronous reset removal time | $T_{MARSTREM}$ | 0 | | 0 | | ns |
| Asynchronous reset recovery time | $T_{MARSTREC}$ | 0.088 | | 0.104 | | ns |
| Output register clock to out delay | T_{MOCQ} | | 0.232 | | 0.273 | ns |
| CLK minimum period | T_{MCLKMP} | 2.245 | | 2.641 | | ns |

The following table lists the math blocks with input bypassed and output registers used in worst commercial-case conditions when $T_J = 85\text{ }^\circ\text{C}$, $V_{DD} = 1.14\text{ V}$.

Table 269 • Math Block with Input Bypassed and Output Registers Used

| Parameter | Symbol | -1 | | -Std | | Unit |
|-------------------------------------|-----------------|--------|-------|--------|-------|------|
| | | Min | Max | Min | Max | |
| Output register setup time | T_{MOSU} | 2.294 | | 2.699 | | ns |
| Output register hold time | T_{MOHD} | 1.68 | | 1.976 | | ns |
| CDIN input setup time | $T_{MOCDINSU}$ | 0.115 | | 0.136 | | ns |
| CDIN input hold time | $T_{MOCDINHHD}$ | -0.444 | | -0.522 | | ns |
| Synchronous reset/enable setup time | $T_{MSRSTENSU}$ | -0.419 | | -0.493 | | ns |
| Synchronous reset/enable hold time | $T_{MSRSTENHD}$ | 0.011 | | 0.013 | | ns |
| Asynchronous reset removal time | $T_{MARSTREM}$ | 0 | | 0 | | ns |
| Asynchronous reset recovery time | $T_{MARSTREC}$ | 0.014 | | 0.017 | | ns |
| Output register clock to out delay | T_{MOCQ} | | 0.232 | | 0.273 | ns |
| CLK minimum period | T_{MCLKMP} | 2.179 | | 2.563 | | ns |

2.3.17 Non-Deterministic Random Bit Generator (NRBG) Characteristics

For more information about NRBG, see *AC407: Using NRBG Services in SmartFusion2 and IGLOO2 Devices Application Note*. The following table lists the NRBG in worst-case industrial conditions when $T_J = 100\text{ }^\circ\text{C}$, $V_{DD} = 1.14\text{ V}$.

Table 275 • Non-Deterministic Random Bit Generator (NRBG)

| Service | Timing | Unit | Conditions | |
|---|--|------|---------------------------|------------------|
| | | | Prediction Resistance | Additional Input |
| Instantiate | 85 | ms | OFF | X |
| Generate (after Instantiate) ¹ | 4.5 ms + (6.25 us/byte x No. of Bytes) | | OFF | 0 |
| | 6.0 ms + (6.25 us/byte x No. of Bytes) | | OFF | 64 |
| | 7.0 ms + (6.25 us/byte x No. of Bytes) | | OFF | 128 |
| Generate (after Instantiate) | 47 | ms | ON | X |
| Generate (subsequent) ¹ | 0.5 ms + (6.25 us/byte x No. of Bytes) | | OFF | 0 |
| | 2.0 ms + (6.25 us/byte x No. of Bytes) | | OFF | 64 |
| | 3.0 ms + (6.25 us/byte x No. of Bytes) | | OFF | 128 |
| Generate (subsequent) | 43 | ms | ON | X |
| Reseed | 40 | ms | | |
| Uninstantiate | 0.16 | ms | | |
| Reset | 0.10 | ms | | |
| Self test | 20 | ms | First time after power-up | |
| | 6 | ms | Subsequent | |

1. If PUF_OFF, generate will incur additional PUF delay time for consecutive service calls.

2.3.18 Cryptographic Block Characteristics

For more information about cryptographic block and associated services, see *AC410: Using AES System Services in SmartFusion2 and IGLOO2 Devices Application Note* and *AC432: Using SHA-256 System Services in SmartFusion2 and IGLOO2 Devices Application Note*.

The following table lists the cryptographic block characteristics in worst-case industrial conditions when $T_J = 100\text{ }^\circ\text{C}$, $V_{DD} = 1.14\text{ V}$.

Table 276 • Cryptographic Block Characteristics

| Service | Conditions | Timing | Unit |
|---|---|--------|------|
| Any service | First certificate check penalty at boot | 11.5 | ms |
| AES128/256 (encoding / decoding) ¹ | 100 blocks up to 64k blocks | 700 | kbps |

Table 277 • Electrical Characteristics of the Crystal Oscillator – High Gain Mode (20 MHz) (continued)

| Parameter | Symbol | Min | Typ | Max | Unit | Condition |
|--|--------|-----|-----|-----|------|--------------------------------|
| Startup time (with regard to stable oscillator output) | SUXTAL | | | 0.8 | ms | 005, 010, 025, and 050 devices |
| | | | | 1.0 | ms | 090 and 150 devices |

Table 278 • Electrical Characteristics of the Crystal Oscillator – Medium Gain Mode (2 MHz)

| Parameter | Symbol | Min | Typ | Max | Unit | Condition |
|--|------------|---------------------|-------|---------------------|------|-------------------------------------|
| Operating frequency | FXTAL | | 2 | | MHz | |
| Accuracy | ACCXTAL | | | 0.00105 | % | 050 devices |
| | | | | 0.003 | % | 005, 010, 025, 090, and 150 devices |
| | | | | 0.004 | % | 060 devices |
| Output duty cycle | CYCXTAL | | 49–51 | 47–53 | % | |
| Output period jitter (peak to peak) | JITPERXTAL | | 1 | 5 | ns | |
| Output cycle to cycle jitter (peak to peak) | JITCYCXTAL | | 1 | 5 | ns | |
| Operating current | IDYNXTAL | | 0.3 | | mA | |
| Input logic level high | VIHXTAL | 0.9 V _{PP} | | | V | |
| Input logic level low | VILXTAL | | | 0.1 V _{PP} | V | |
| Startup time (with regard to stable oscillator output) | SUXTAL | | | 4.5 | ms | 010 and 050 devices |
| | | | | 5 | ms | 005 and 025 devices |
| | | | | 7 | ms | 090 and 150 devices |

Table 279 • Electrical Characteristics of the Crystal Oscillator – Low Gain Mode (32 kHz)

| Parameter | Symbol | Min | Typ | Max | Unit | Condition |
|--|------------|---------------------|-------|---------------------|------|--|
| Operating frequency | FXTAL | | 32 | | kHz | |
| Accuracy | ACCXTAL | | | 0.004 | % | 005, 010, 025, 050, 060, and 090 devices |
| | | | | 0.005 | % | 150 devices |
| Output duty cycle | CYCXTAL | | 49–51 | 47–53 | % | |
| Output period jitter (peak to peak) | JITPERXTAL | | 150 | 300 | ns | |
| Output cycle to cycle jitter (peak to peak) | JITCYCXTAL | | 150 | 300 | ns | |
| Operating current | IDYNXTAL | | | 0.044 | mA | 010 and 050 devices |
| | | | | 0.060 | mA | 005, 025, 060, 090, and 150 devices |
| Input logic level high | VIHXTAL | 0.9 V _{PP} | | | V | |
| Input logic level low | VILXTAL | | | 0.1 V _{PP} | V | |
| Startup time (with regard to stable oscillator output) | SUXTAL | | | 115 | ms | 005, 025, 050, 090, and 150 devices |
| | | | | 126 | ms | 010 devices |

The following table lists the receiver pa in worst-case industrial conditions when $T_J = 100\text{ }^\circ\text{C}$, $V_{DD} = 1.14\text{ V}$.

Table 297 • Receiver Parameters

| Symbol | Description | Min | Typ | Max | Unit |
|----------------------|---|-------|-------|-------|---------------|
| VRX-IN-PP-CC | Differential input peak-to-peak sensitivity (2.5 Gbps) | 0.238 | | 1.2 | V |
| | Differential input peak-to-peak sensitivity (2.5 Gbps, de-emphasized) | 0.219 | | 1.2 | V |
| | Differential input peak-to-peak sensitivity (5.0 Gbps) | 0.300 | | 1.2 | V |
| | Differential input peak-to-peak sensitivity (5.0 Gbps, de-emphasized) | 0.300 | | 1.2 | V |
| VRX-CM-AC-P | Input common mode range (AC coupled) | | | 150 | mV |
| ZRX-DIFF-DC | Differential input termination | 80 | 100 | 120 | Ω |
| REXT | External calibration resistor | 1,188 | 1,200 | 1,212 | Ω |
| CDR-LOCK-RST | CDR relock time from reset | | | 15 | μs |
| RLRX-DIFF | Return loss differential mode (2.5 Gbps) | -10 | | | dB |
| | Return loss differential mode (5.0 Gbps) | | | | |
| | 0.05 GHz to 1.25 GHz | -10 | | | dB |
| | 1.25 GHz to 2.5 GHz | -8 | | | dB |
| RLRX-CM | Return loss common mode (2.5 Gbps, 5.0 Gbps) | -6 | | | dB |
| RX-CID ¹ | CID limit PCIe Gen1/2 | | | 200 | UI |
| VRX-IDLE-DET-DIFF-PP | Signal detect limit | 65 | | 175 | mV |

1. AC-coupled, BER = e^{-12} , using synchronous clock.

Table 298 • SerDes Protocol Compliance

| Protocol | Maximum Data Rate (Gbps) | -1 | -Std |
|--------------|--------------------------|-----|------|
| PCIe Gen 1 | 2.5 | Yes | Yes |
| PCIe Gen 2 | 5.0 | Yes | |
| XAUI | 3.125 | Yes | |
| Generic EPCS | 3.2 | Yes | |
| Generic EPCS | 2.5 | Yes | Yes |

2.3.31.2 SmartFusion2 Inter-Integrated Circuit (I²C) Characteristics

This section describes the DC and switching of the I²C interface. Unless otherwise noted, all output characteristics given are for a 100 pF load on the pins. For timing parameter definitions, see Figure 21, page 125.

The following table lists the I²C characteristics in worst-case industrial conditions when $T_J = 100\text{ }^\circ\text{C}$, $V_{DD} = 1.14\text{ V}$

Table 303 • I²C Characteristics

| Parameter | Symbol | Min | Typ | Max | Unit | Conditions |
|---|-----------------------|-----------------------|--------|--------|---------------|---|
| Input low voltage | V_{IL} | -0.3 | | 0.8 | V | See Single-Ended I/O Standards, page 24 for more information. I/O standard used for illustration: MSIO bank-LVTTL 8 mA low drive. |
| Input high voltage | V_{IH} | 2 | | 3.45 | V | See Single-Ended I/O Standards, page 24 for more information. I/O standard used for illustration: MSIO bank-LVTTL 8 mA low drive. |
| Hysteresis of schmitt triggered inputs for $V_{DDI} > 2\text{ V}$ | V_{HYS} | $0.05 \times V_{DDI}$ | | | V | See Table 28, page 23 for more information. |
| Input current high | I_{IL} | | | 10 | μA | See Single-Ended I/O Standards, page 24 for more information. |
| Input current low | I_{IH} | | | 10 | μA | See Single-Ended I/O Standards, page 24 for more information. |
| Input rise time | T_{ir} | | | 1000 | ns | Standard mode |
| | | | | 300 | ns | Fast mode |
| Input fall time | T_{if} | | | 300 | ns | Standard mode |
| | | | | 300 | ns | Fast mode |
| Maximum output voltage low (open drain) at 3 mA sink current for $V_{DDI} > 2\text{ V}$ | V_{OL} | | | 0.4 | V | See Single-Ended I/O Standards, page 24 for more information. I/O standard used for illustration: MSIO bank-LVTTL 8 mA low drive. |
| Pin capacitance | C_{in} | | | 10 | pF | $V_{IN} = 0$, $f = 1.0\text{ MHz}$ |
| Output fall time from V_{IHMin} to V_{ILMax}^1 | t_{OF}^1 | | 21.04 | | ns | V_{IHmin} to V_{ILMax} , $C_{LOAD} = 400\text{ pF}$ |
| | | | 5.556 | | ns | V_{IHmin} to V_{ILMax} , $C_{LOAD} = 100\text{ pF}$ |
| Output rise time from V_{ILMax} to V_{IHMin}^1 | t_{OR}^1 | | 19.887 | | ns | V_{ILMax} to V_{IHmin} , $C_{LOAD} = 400\text{ pF}$ |
| | | | 5.218 | | ns | V_{ILMax} to V_{IHmin} , $C_{LOAD} = 100\text{ pF}$ |
| Output buffer maximum pull-down resistance ^{2,3} | $R_{pull-up}^{2,3}$ | | | 50 | Ω | |
| Output buffer maximum pull-up resistance ^{2,4} | $R_{pull-down}^{2,4}$ | | | 131.25 | Ω | |

Table 303 • I2C Characteristics (continued)

| Parameter | Symbol | Min | Typ | Max | Unit | Conditions |
|--|------------|-----|-----|-----|------|---------------|
| Maximum data rate | D_{MAX} | | | 400 | Kbps | Fast mode |
| | | | | 100 | Kbps | Standard mode |
| Pulse width of spikes which must be suppressed by the input filter | T_{FILT} | | 50 | | ns | Fast mode |

1. These values are provided for MSIO Bank–LVTTTL 8 mA Low Drive at 25 °C, typical conditions. For board design considerations and detailed output buffer resistances, use the corresponding IBIS models located on the SoC Products Group website: <http://www.microsemi.com/soc/download/ibis/default.aspx>.
2. These maximum values are provided for information only. Minimum output buffer resistance values depend on V_{DDIX} , drive strength selection, temperature, and process. For board design considerations and detailed output buffer resistances, use the corresponding IBIS models located on the SoC Products Group website: <http://www.microsemi.com/soc/download/ibis/default.aspx>.
3. $R(PULL-DOWN-MAX) = (VOLspec)/IOLspec$.
4. $R(PULL-UP-MAX) = (VDDImax-VOHspec)/IOHspec$.

The following table lists the I²C switching characteristics in worst-case industrial conditions when $T_J = 100\text{ °C}$, $V_{DD} = 1.14\text{ V}$

Table 304 • I2C Switching Characteristics

| Parameter | Symbol | -1 | Std | Unit |
|--------------------------|--------------|-----|-----|-------------|
| | | Min | Min | |
| Low period of I2C_x_SCL | T_{LOW} | 1 | 1 | PCLK cycles |
| High period of I2C_x_SCL | T_{HIGH} | 1 | 1 | PCLK cycles |
| START hold time | $T_{HD;STA}$ | 1 | 1 | PCLK cycles |
| START setup time | $T_{SU;STA}$ | 1 | 1 | PCLK cycles |
| DATA hold time | $T_{HD;DAT}$ | 1 | 1 | PCLK cycles |
| DATA setup time | $T_{SU;DAT}$ | 1 | 1 | PCLK cycles |
| STOP setup time | $T_{SU;STO}$ | 1 | 1 | PCLK cycles |

Figure 21 • I²C Timing Parameter Definition

