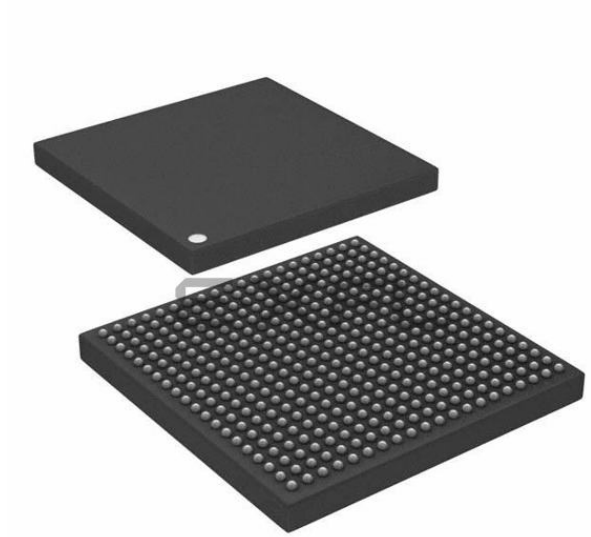

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Embedded - System On Chip (SoC): The Heart of Modern Embedded Systems

Embedded - System On Chip (SoC) refers to an integrated circuit that consolidates all the essential components of a computer system into a single chip. This includes a microprocessor, memory, and other peripherals, all packed into one compact and efficient package. SoCs are designed to provide a complete computing solution, optimizing both space and power consumption, making them ideal for a wide range of embedded applications.

What are Embedded - System On Chip (SoC)?

System On Chip (SoC) integrates multiple functions of a computer or electronic system onto a single chip. Unlike traditional multi-chip solutions, SoCs combine a central

Details	
Product Status	Active
Architecture	MCU, FPGA
Core Processor	ARM® Cortex®-M3
Flash Size	256KB
RAM Size	64KB
Peripherals	DDR, PCIe, SERDES
Connectivity	CANbus, Ethernet, I²C, SPI, UART/USART, USB
Speed	166MHz
Primary Attributes	FPGA - 25K Logic Modules
Operating Temperature	0°C ~ 85°C (TJ)
Package / Case	400-LFBGA
Supplier Device Package	400-VFBGA (17x17)
Purchase URL	https://www.e-xfl.com/product-detail/microchip-technology/m2s025t-vfg400

Tables

1 Revision History

The revision history describes the changes that were implemented in the document. The changes are listed by revision, starting with the most current publication.

1.1 Revision 11.0

The following is a summary of the changes in revision 11.0 of this document.

- Updated Table 24, page 22 with minimum and maximum values for input current low and high (SAR 73114 and 80314).
- Added Non-Deterministic Random Bit Generator (NRBG) Characteristics, page 106 (SAR 73114 and 79517).
- Added 060 device in Table 282, page 110 (SAR 79860).
- Added DEVRST_N to Functional Times, page 116 (SAR 73114).
- Added Cryptographic Block Characteristics, page 106 (SAR 73114 and 79516).
- Update Table 296, page 121 with VTX-AMP details (SAR 81756).
- Update note in Table 297, page 122 (SAR 74570 and 80677).
- Update Table 298, page 122 with generic EPCS details (SAR 75307).
- Added Table 308, page 129 (SAR 50424).

1.2 Revision 10.0

The following is a summary of the changes in revision 10.0 of this document.

- The Surge Current on VDD during DEVRST_B Assertion and Surge Current on VDD during Digest Check using System Services tables were deleted and added reference to *AC393: Board Design Guidelines for SmartFusion2 SoC and IGLOO2 FPGAs Application Note*. (SAR 76865 and 76623).
- Added 060 device in Table 4, page 6 (SAR 76383).
- Updated Table 24, page 22 for ramp time input (SAR 72103).
- Added 060 device details in Table 284, page 112 (SAR 74927).
- Updated Table 290, page 116 for name change (SAR 74925).
- Updated Table 283, page 111 for 060 FG676 Package details (SAR 78849).
- Updated Table 305, page 126 for SmartFusion2 and Table 310, page 129 for IGLOO2 for SPI timing and Fmax (SAR 56645, 75331).
- Updated Table 293, page 119 for Flash*Freeze entry and exit times (SAR 75329, 75330).
- Updated Table 297, page 122 for RX-CID information (SAR 78271).
- Added Table 8, page 8 and Figure 1, page 9 (SAR 78932).
- Updated Table 223, page 76 for timing characteristics and Table 224, page 77(SAR 75998).
- Added SRAM PUF, page 105 (SAR 64406).
- Added a footnote on digest cycle in Table 5, page 7 (SAR 79812).

1.3 Revision 9.0

The following is a summary of the changes in revision 9.0 of this document.

- Added a note in Table 5, page 7 (SAR 71506).
- Added a note in Table 6, page 8 (SAR 74616).
- Added a note in Figure 3, page 17 (SAR 71506).
- Updated Quiescent Supply Current for 060 in Table 11, page 12 and Table 12, page 13 (SAR 74483).
- Updated programming currents for 060 in Table 13, page 13, Table 14, page 13, and Table 15, page 14.
- Added DEVRST_B assertion tables (SAR 74708).
- Updated I/O speeds for LVDS 3.3 V in Table 18, page 19 and Table 21, page 20 (SAR 69829).
- Updated Table 24, page 22 (SAR 69418).
- Updated Table 25, page 22, Table 26, page 23, Table 27, page 23 (SAR 74570).
- Updated all AC/DC table to link to the Input Capacitance, Leakage Current, and Ramp Time, page 22 for reference (SAR 69418).

Figure 1 • **High Temperature Data Retention (HTR)**

2.3.1.1 Overshoot/Undershoot Limits

For AC signals, the input signal may undershoot during transitions to –1.0 V for no longer than 10% of the period. The current during the transition must not exceed 100 mA.

For AC signals, the input signal may overshoot during transitions to V_{CCI} + 1.0 V for no longer than 10% of the period. The current during the transition must not exceed 100 mA.

Note: The above specifications do not apply to the PCI standard. The IGLOO2 and SmartFusion2 PCI I/Os are compliant with the PCI standard including the PCI overshoot/undershoot specifications.

2.3.1.2 Thermal Characteristics

The temperature variable in the Microsemi SoC Products Group Designer software refers to the junction temperature, not the ambient, case, or board temperatures. This is an important distinction because dynamic and static power consumption causes the chip's junction temperature to be higher than the ambient, case, or board temperatures.

EQ1 through EQ3 give the relationship between thermal resistance, temperature gradient, and power.

$$\theta_{JA} = \frac{T_J - T_A}{P}$$

EQ 1

$$\theta_{JB} = \frac{T_J - T_B}{P}$$

EQ 2

$$\theta_{JC} = \frac{T_J - T_C}{P}$$

EQ 3

2.3.5.2 Output Buffer and AC Loading

The following figure shows the output buffer and AC loading.

Figure 4 • **Output Buffer AC Loading**

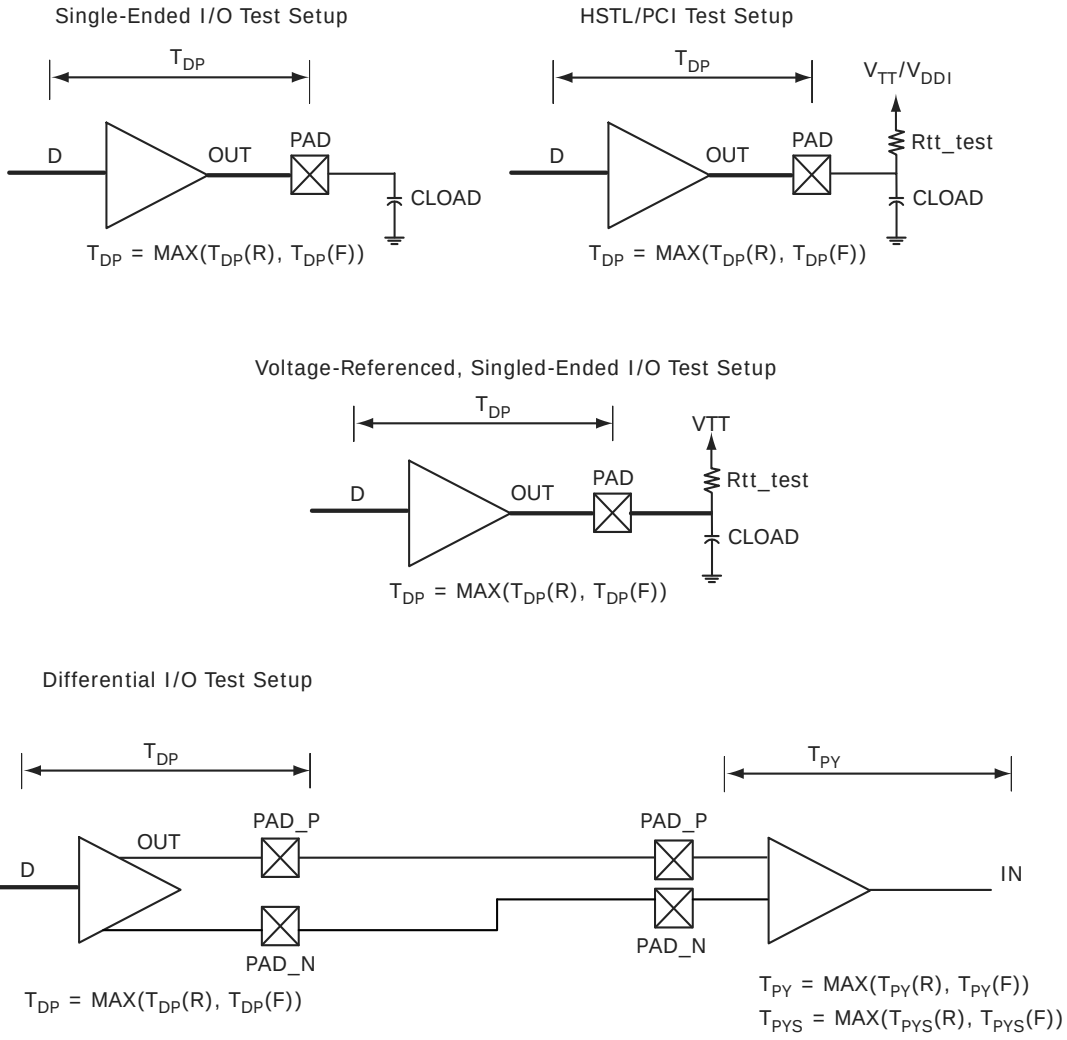


Table 70 • **LVCMOS 1.5 V Transmitter Characteristics for DDRIO I/O Bank (Output and Tristate Buffers) *(continued)***

Output Drive Selection	Slew Control	T_{DP}		T_{ZL}		T_{ZH}		T_{HZ}[1]		T_{LZ}[1]		
		–1	–Std	–1	–Std	–1	–Std	–1	–Std	–1	–Std	Unit
6 mA	Slow	4.244	4.993	3.465	4.076	4.233	4.979	6.39	7.518	5.736	6.748	ns
	Medium	3.774	4.44	3.05	3.587	3.762	4.426	6.114	7.193	5.397	6.35	ns
	Medium fast	3.544	4.17	2.839	3.339	3.529	4.152	5.978	7.033	5.27	6.2	ns
	Fast	3.519	4.14	2.82	3.317	3.504	4.122	5.965	7.017	5.259	6.187	ns
8 mA	Slow	4.099	4.823	3.311	3.894	4.087	4.807	6.584	7.746	5.854	6.888	ns
	Medium	3.656	4.301	2.927	3.443	3.642	4.284	6.311	7.425	5.553	6.533	ns
	Medium fast	3.437	4.044	2.731	3.213	3.42	4.023	6.182	7.273	5.435	6.394	ns
	Fast	3.41	4.012	2.715	3.193	3.393	3.991	6.178	7.269	5.425	6.383	ns
10 mA	Slow	4.029	4.74	3.238	3.809	4.015	4.723	6.732	7.921	5.965	7.018	ns
	Medium	3.601	4.237	2.867	3.372	3.586	4.218	6.473	7.615	5.669	6.669	ns
	Medium fast	3.384	3.981	2.672	3.143	3.365	3.958	6.351	7.471	5.55	6.529	ns
	Fast	3.357	3.949	2.655	3.123	3.338	3.927	6.345	7.464	5.54	6.518	ns
12 mA	Slow	3.974	4.675	3.196	3.759	3.958	4.656	6.842	8.049	6.068	7.139	ns
	Medium	3.55	4.176	2.827	3.326	3.534	4.157	6.584	7.746	5.751	6.766	ns
	Medium fast	3.345	3.935	2.638	3.103	3.325	3.911	6.488	7.633	5.641	6.637	ns
	Fast	3.316	3.902	2.621	3.083	3.297	3.878	6.486	7.63	5.626	6.619	ns

1. Delay increases with drive strength are inherent to built-in slew control circuitry for simultaneous switching output (SSO) management.

Table 71 • **LVCMOS 1.5 V Transmitter Characteristics for MSIO I/O Bank (Output and Tristate Buffers)**

Output Drive Selection	Slew Control	T_{DP}		T_{ZL}		T_{ZH}		T_{HZ}[1]		T_{LZ}[1]		
		–1	–Std	–1	–Std	–1	–Std	–1	–Std	–1	–Std	Unit
2 mA	Slow	4.423	5.203	5.397	6.35	5.686	6.69	5.609	6.599	5.561	6.542	ns
4 mA	Slow	4.05	4.765	4.503	5.298	4.92	5.788	7.358	8.657	6.525	7.677	ns
6 mA	Slow	4.081	4.801	4.259	5.012	4.699	5.528	7.659	9.011	6.709	7.893	ns
8 mA	Slow	4.234	4.98	4.068	4.786	4.521	5.319	8.218	9.668	7.05	8.294	ns

1. Delay increases with drive strength are inherent to built-in slew control circuitry for simultaneous switching output (SSO) management.

AC Switching Characteristics

Worst commercial-case conditions: T_J = 85 °C, V_{DD} = 1.14 V, V_{DDI} = 3.0 V

Table 91 • **PCI/PCIX AC Switching Characteristics for Receiver for MSIO I/O Bank (Input Buffers)**

	T_{PY}		T_{PYS}		
On-Die Termination (ODT)	**–1**	**–Std**	**–1**	**–Std**	**Unit**
None	2.229	2.623	2.238	2.633	ns

Table 92 • **PCI/PCIX AC switching Characteristics for Transmitter for MSIO I/O Bank (Output and Tristate Buffers)**

T_{DP}		T_{ZL}		T_{ZH}		T_{HZ}		T_{LZ}		
–1	**–Std**	**–1**	**–Std**	**–1**	**–Std**	**–1**	**–Std**	**–1**	**–Std**	**Unit**
2.146	2.525	2.043	2.404	2.084	2.452	6.095	7.171	5.558	6.539	ns

2.3.6 Memory Interface and Voltage Referenced I/O Standards

This section describes High-Speed Transceiver Logic (HSTL) memory interface and voltage reference I/O standards.

2.3.6.1 High-Speed Transceiver Logic (HSTL)

The HSTL standard is a general purpose high-speed bus standard sponsored by IBM (EIA/JESD8-6). IGLOO2 FPGA and SmartFusion2 SoC FPGA devices support two classes of the 1.5 V HSTL. These differential versions of the standard require a differential amplifier input buffer and a push-pull output buffer.

Minimum and Maximum DC/AC Input and Output Levels Specification (Applicable to DDRIO Bank Only)

Table 93 • **HSTL Recommended DC Operating Conditions**

Parameter	**Symbol**	**Min**	**Typ**	**Max**	**Unit**
Supply voltage	V_{DDI}	1.425	1.5	1.575	V
Termination voltage	V_{TT}	0.698	0.750	0.803	V
Input reference voltage	V_{REF}	0.698	0.750	0.803	V

Table 94 • **HSTL DC Input Voltage Specification**

Parameter	**Symbol**	**Min**	**Max**	**Unit**
DC input logic high	V_{IH} (DC)	V_{REF} + 0.1	1.575	V
DC input logic low	V_{IL} (DC)	–0.3	V_{REF} – 0.1	V
Input current high[1]	I_{IH} (DC)			
Input current low[1]	I_{IL} (DC)			

1. See Table 24, page 22.

Table 118 • **DDR1/SSTL2 Class II Transmitter Characteristics for MSIO I/O Bank (Output and Tristate Buffers)**

	T_{DP}		T_{ZL}		T_{ZH}		T_{HZ}		T_{LZ}		
	–1	**–Std**	**–1**	**–Std**	**–1**	**–Std**	**–1**	**–Std**	**–1**	**–Std**	**Unit**
Single-ended	2.29	2.693	1.988	2.338	1.978	2.326	1.989	2.34	1.979	2.328	ns
Differential	2.418	2.846	2.304	2.711	2.297	2.702	2.131	2.506	2.124	2.499	ns

2.3.6.4 Stub-Series Terminated Logic 1.8 V (SSTL18)

SSTL18 Class I and Class II are supported in IGLOO2 and SmartFusion2 SoC FPGAs, and also comply with the reduced and full drive double date rate (DDR2) standard. IGLOO2 and SmartFusion2 SoC FPGA I/Os support both standards for single-ended signaling and differential signaling for SSTL18. This standard requires a differential amplifier input buffer and a push-pull output buffer.

Minimum and Maximum DC/AC Input and Output Levels Specification

Table 119 • **SSTL18 DC Recommended DC Operating Conditions**

Parameter	Symbol	Min	Typ	Max	Unit
Supply voltage	V_{DDI}	1.71	1.8	1.89	V
Termination voltage	V_{TT}	0.838	0.900	0.964	V
Input reference voltage	V_{REF}	0.838	0.900	0.964	V

Table 120 • **SSTL18 DC Input Voltage Specification**

Parameter	Symbol	Min	Max	Unit
DC input logic high	V_{IH} (DC)	V_{REF} + 0.125	1.89	V
DC input logic low	V_{IL} (DC)	–0.3	V_{REF} – 0.125	V
Input current high[1]	I_{IH} (DC)			
Input current low[1]	I_{IL} (DC)			

1. See Table 24, page 22.

Table 121 • **SSTL18 DC Output Voltage Specification**

Parameter	Symbol	Min	Max	Unit
SSTL18 Class I (DDR2 Reduced Drive)				
DC output logic high	V_{OH}	V_{TT} + 0.603		V
DC output logic low	V_{OL}		V_{TT}– 0.603	V
Output minimum source DC current (DDRIO I/O bank only)	I_{OH} at V_{OH}	6.5		mA
Output minimum sink current (DDRIO I/O bank only)	I_{OL} at V_{OL}	–6.5		mA
SSTL18 Class II (DDR2 Full Drive)[1]				
DC output logic high	V_{OH}	V_{TT} + 0.603		V
DC output logic low	V_{OL}		V_{TT}– 0.603	V
Output minimum source DC current (DDRIO I/O bank only)	I_{OH} at V_{OH}	13.4		mA
Output minimum sink current (DDRIO I/O bank only)	I_{OL} at V_{OL}	–13.4		mA

1. To meet JEDEC Electrical Compliance, use DDR2 Full Drive Transmitter.

2.3.7.5 RSDS

Reduced Swing Differential Signaling (RSDS) is similar to an LVDS high-speed interface using differential signaling. RSDS has a similar implementation to LVDS devices and is only intended for point-to-point applications.

Minimum and Maximum Input and Output Levels

Table 203 • **RSDS Recommended DC Operating Conditions**

Parameter	Symbol	Min	Typ	Max	Unit
Supply voltage	V_{DDI}	2.375	2.5	2.625	V

Table 204 • **RSDS DC Input Voltage Specification**

Parameter	Symbol	Min	Max	Unit
DC input voltage	V_I	0	2.925	V

Table 205 • **RSDS DC Output Voltage Specification**

Parameter	Symbol	Min	Typ	Max	Unit
DC output logic high	V_{OH}	1.25	1.425	1.6	V
DC output logic low	V_{OL}	0.9	1.075	1.25	V

Table 206 • **RSDS Differential Voltage Specification**

Parameter	Symbol	Min	Max	Unit
Differential output voltage swing	V_{OD}	100	600	mV
Output common mode voltage	V_{OCM}	0.5	1.5	V
Input common mode voltage	V_{ICM}	0.3	1.5	V
Input differential voltage	V_{ID}	100	600	mV

Table 207 • **RSDS Minimum and Maximum AC Switching Speed**

Parameter	Symbol	Max	Unit	Conditions
Maximum data rate (for MSIO I/O bank)	D_{MAX}	520	Mbps	AC loading: 2 pF / 100 Ω differential load
Maximum data rate (for MSIOD I/O bank)	D_{MAX}	700	Mbps	AC loading: 2 pF / 100 Ω differential load

Table 208 • **RSDS AC Impedance Specifications**

Parameter	Symbol	Typ	Unit
Termination resistance	RT	100	Ω

Table 209 • **RSDS AC Test Parameter Specifications**

Parameter	Symbol	Typ	Unit
Measuring/trip point for data path	V_{TRIP}	Cross point	V
Resistance for enable path (T_{ZH}, T_{ZL}, T_{HZ}, T_{LZ})	R_{ENT}	2K	Ω
Capacitive loading for enable path (T_{ZH}, T_{ZL}, T_{HZ}, T_{LZ})	C_{ENT}	5	pF

The following table lists the 010 device global resources in worst commercial-case conditions when T_J = 85 °C, V_{DD} = 1.14 V.

Table 229 • **010 Device Global Resource**

		–1		–Std		
Parameter	**Symbol**	**Min**	**Max**	**Min**	**Max**	**Unit**
Input low delay for global clock	T_{RCKL}	0.626	0.669	0.627	0.668	ns
Input high delay for global clock	T_{RCKH}	1.112	1.182	1.308	1.393	ns
Maximum skew for global clock	T_{RCKSW}		0.07		0.085	ns

The following table lists the 005 device global resources in worst commercial-case conditions when T_J = 85 °C, V_{DD} = 1.14 V.

Table 230 • **005 Device Global Resource**

		–1		–Std		
Parameter	**Symbol**	**Min**	**Max**	**Min**	**Max**	**Unit**
Input low delay for global clock	T_{RCKL}	0.625	0.66	0.628	0.66	ns
Input high delay for global clock	T_{RCKH}	1.126	1.187	1.325	1.397	ns
Maximum skew for global clock	T_{RCKSW}		0.061		0.072	ns

2.3.12 FPGA Fabric SRAM

See *UG0445: IGLOO2 FPGA and SmartFusion2 SoC FPGA Fabric User Guide* for more information.

2.3.12.1 FPGA Fabric Large SRAM (LSRAM)

The following table lists the RAM1K18 – dual-port mode for depth × width configuration 1K × 18 in worst commercial-case conditions when T_J = 85 °C, V_{DD} = 1.14 V.

Table 231 • **RAM1K18 – Dual-Port Mode for Depth × Width Configuration 1K × 18**

		–1		–Std		
Parameter	**Symbol**	**Min**	**Max**	**Min**	**Max**	**Unit**
Clock period	T_{CY}	2.5		2.941		ns
Clock minimum pulse width high	$T_{CLKMPWH}$	1.125		1.323		ns
Clock minimum pulse width low	$T_{CLKMPWL}$	1.125		1.323		ns
Pipelined clock period	T_{PLCY}	2.5		2.941		ns
Pipelined clock minimum pulse width high	$T_{PLCLKMPWH}$	1.125		1.323		ns
Pipelined clock minimum pulse width low	$T_{PLCLKMPWL}$	1.125		1.323		ns
Read access time with pipeline register	T_{CLK2Q}		0.334		0.393	ns
Read access time without pipeline register			2.273		2.674	ns
Access time with feed-through write timing			1.529		1.799	ns
Address setup time	T_{ADDRSU}	0.441		0.519		ns
Address hold time	T_{ADDRHD}	0.274		0.322		ns
Data setup time	T_{DSU}	0.341		0.401		ns
Data hold time	T_{DHD}	0.107		0.126		ns
Block select setup time	T_{BLKSU}	0.207		0.244		ns

The following table lists the programming times in worst-case conditions when T_J = 100 °C, V_{DD} = 1.14 V. External SPI flash part# AT25DF641-s3H is used during this measurement.

Table 256 • **JTAG Programming (Fabric Only)**

M2S/M2GL Device	Image size Bytes	Program	Verify	Unit
005	302672	44	10	Sec
010	568784	50	18	Sec
025	1223504	73	26	Sec
050	2424832	88	54	Sec
060	2418896	99	54	Sec
090	3645968	135	126	Sec
150	6139184	177	193	Sec

Table 257 • **JTAG Programming (eNVM Only)**

M2S/M2GL Device	Image size Bytes	Program	Verify	Unit
005	137536	61	4	Sec
010	274816	100	9	Sec
025	274816	100	9	Sec
050	2,78,528	106	8	Sec
060	268480	98	8	Sec
090	544496	176	15	Sec
150	544496	177	15	Sec

Table 258 • **JTAG Programming (Fabric and eNVM)**

M2S/M2GL Device	Image size Bytes	Program	Verify	Unit
005	439296	71	11	Sec
010	842688	129	20	Sec
025	1497408	142	35	Sec
050	2695168	184	59	Sec
060	2686464	180	70	Sec
090	4190208	288	147	Sec
150	6682768	338	231	Sec

Table 259 • **2 Step IAP Programming (Fabric Only)**

M2S/M2GL Device	Image size Bytes	Authenticate	Program	Verify	Unit
005	302672	4	39	6	Sec
010	568784	7	45	12	Sec
025	1223504	14	55	23	Sec
050	2424832	29	74	40	Sec
060	2418896	39	83	50	Sec
090	3645968	60	106	73	Sec
150	6139184	100	154	120	Sec

Table 260 • **2 Step IAP Programming (eNVM Only)**

M2S/M2GL Device	Image size Bytes	Authenticate	Program	Verify	Unit
005	137536	2	59	5	Sec
010	274816	4	98	11	Sec
025	274816	4	100	10	Sec
050	2,78,528	3	107	9	Sec
060	268480	5	98	22	Sec
090	544496	10	174	43	Sec
150	544496	10	175	44	Sec

Table 261 • **2 Step IAP Programming (Fabric and eNVM)**

M2S/M2GL Device	Image size Bytes	Authenticate	Program	Verify	Unit
005	439296	6	78	11	Sec
010	842688	11	122	21	Sec
025	1497408	19	135	32	Sec
050	2695168	32	158	48	Sec
060	2686464	43	159	70	Sec
090	4190208	68	258	115	Sec
150	6682768	109	308	162	Sec

2.3.14 Math Block Timing Characteristics

The fundamental building block in any digital signal processing algorithm is the multiply-accumulate function. Each IGLOO2 and SmartFusion2 SoC math block supports 18×18 signed multiplication, dot product, and built-in addition, subtraction, and accumulation units to combine multiplication results efficiently. The following table lists the math blocks with all registers used in worst commercial-case conditions when T_J = 85 °C, V_{DD} = 1.14 V.

Table 268 • **Math Blocks with all Registers Used**

		–1		–Std		
Parameter	**Symbol**	**Min**	**Max**	**Min**	**Max**	**Unit**
Input, control register setup time	T_{MISU}	0.149		0.176		ns
Input, control register hold time	T_{MIHD}	1.68		1.976		ns
CDIN input setup time	$T_{MOCDINSU}$	0.185		0.218		ns
CDIN input hold time	$T_{MOCDINHD}$	0.08		0.094		ns
Synchronous reset/enable setup time	$T_{MSRSTENSU}$	–0.419		–0.493		ns
Synchronous reset/enable hold time	$T_{MSRSTENHD}$	0.011		0.013		ns
Asynchronous reset removal time	$T_{MARSTREM}$	0		0		ns
Asynchronous reset recovery time	$T_{MARSTREC}$	0.088		0.104		ns
Output register clock to out delay	T_{MOCQ}		0.232		0.273	ns
CLK minimum period	T_{MCLKMP}	2.245		2.641		ns

The following table lists the math blocks with input bypassed and output registers used in worst commercial-case conditions when T_J = 85 °C, V_{DD} = 1.14 V.

Table 269 • **Math Block with Input Bypassed and Output Registers Used**

		–1		–Std		
Parameter	**Symbol**	**Min**	**Max**	**Min**	**Max**	**Unit**
Output register setup time	T_{MOSU}	2.294		2.699		ns
Output register hold time	T_{MOHD}	1.68		1.976		ns
CDIN input setup time	$T_{MOCDINSU}$	0.115		0.136		ns
CDIN input hold time	$T_{MOCDINHD}$	–0.444		–0.522		ns
Synchronous reset/enable setup time	$T_{MSRSTENSU}$	–0.419		–0.493		ns
Synchronous reset/enable hold time	$T_{MSRSTENHD}$	0.011		0.013		ns
Asynchronous reset removal time	$T_{MARSTREM}$	0		0		ns
Asynchronous reset recovery time	$T_{MARSTREC}$	0.014		0.017		ns
Output register clock to out delay	T_{MOCQ}		0.232		0.273	ns
CLK minimum period	T_{MCLKMP}	2.179		2.563		ns

Table 277 • **Electrical Characteristics of the Crystal Oscillator – High Gain Mode (20 MHz)** ***(continued)***

Parameter	Symbol	Min	Typ	Max	Unit	Condition
Startup time (with regard to stable oscillator output)	SUXTAL			0.8	ms	005, 010, 025, and 050 devices
				1.0	ms	090 and 150 devices

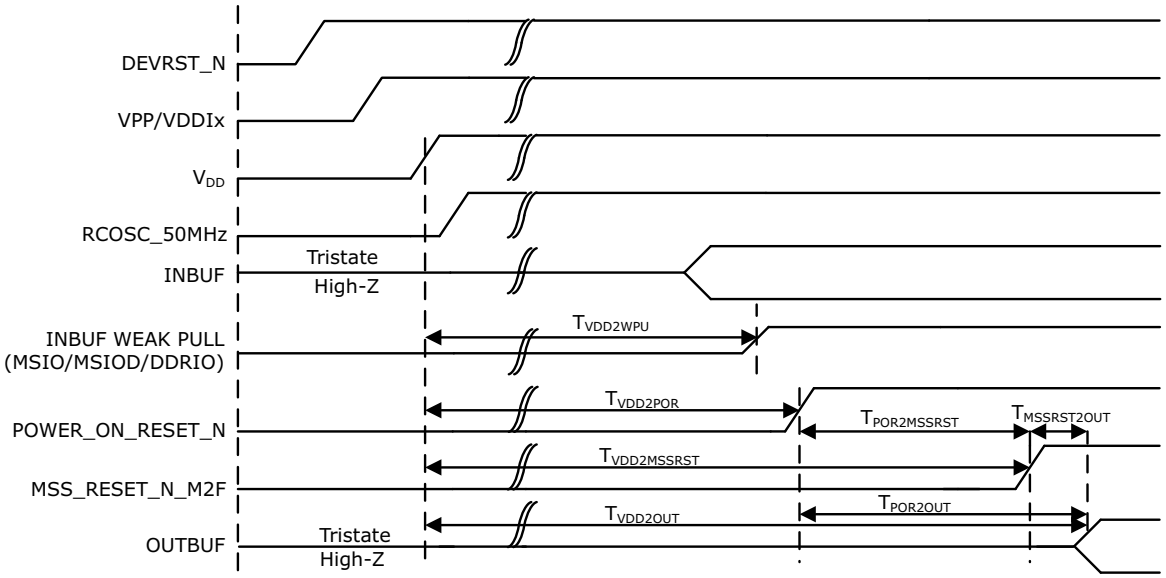
Table 278 • **Electrical Characteristics of the Crystal Oscillator – Medium Gain Mode (2 MHz)**

Parameter	Symbol	Min	Typ	Max	Unit	Condition
Operating frequency	FXTAL		2		MHz	
Accuracy	ACCXTAL			0.00105	%	050 devices
				0.003	%	005, 010, 025, 090, and 150 devices
				0.004	%	060 devices
Output duty cycle	CYCXTAL		49–51	47–53	%	
Output period jitter (peak to peak)	JITPERXTAL		1	5	ns	
Output cycle to cycle jitter (peak to peak)	JITCYCXTAL		1	5	ns	
Operating current	IDYNXTAL		0.3		mA	
Input logic level high	VIHXTAL	0.9 V_{PP}			V	
Input logic level low	VILXTAL			0.1 V_{PP}	V	
Startup time (with regard to stable oscillator output)	SUXTAL			4.5	ms	010 and 050 devices
				5	ms	005 and 025 devices
				7	ms	090 and 150 devices

Table 279 • **Electrical Characteristics of the Crystal Oscillator – Low Gain Mode (32 kHz)**

Parameter	Symbol	Min	Typ	Max	Unit	Condition
Operating frequency	FXTAL		32		kHz	
Accuracy	ACCXTAL			0.004	%	005, 010, 025, 050, 060, and 090 devices
				0.005	%	150 devices
Output duty cycle	CYCXTAL		49–51	47–53	%	
Output period jitter (peak to peak)	JITPERXTAL		150	300	ns	
Output cycle to cycle jitter (peak to peak)	JITCYCXTAL		150	300	ns	
Operating current	IDYNXTAL		0.044		mA	010 and 050 devices
			0.060		mA	005, 025, 060, 090, and 150 devices
Input logic level high	VIHXTAL	0.9 V_{PP}			V	
Input logic level low	VILXTAL			0.1 V_{PP}	V	
Startup time (with regard to stable oscillator output)	SUXTAL			115	ms	005, 025, 050, 090, and 150 devices
				126	ms	010 devices

Figure 17 • **Power-up to Functional Timing Diagram for SmartFusion2**



The following table lists the IGLOO2 power-up to functional times in worst-case industrial conditions when T_J = 100 °C, V_{DD} = 1.14 V.

Table 289 • **Power-up to Functional Times for IGLOO2**

				Maximum Power-up to Functional Time for IGLOO2 (uS)						
Symbol	**From**	**To**	**Description**	**005**	**010**	**025**	**050**	**060**	**090**	**150**
$T_{POR2OUT}$	POWER_ON_RESET_N	Output available at I/O	Fabric to output	114	114	114	113	114	114	114
$T_{VDD2OUT}$	V_{DD}	Output available at I/O	V_{DD} at its minimum threshold level to output	2587	2600	2607	2558	2591	2600	2699
$T_{VDD2POR}$	V_{DD}	POWER_ON_RESET_N	V_{DD} at its minimum threshold level to fabric	2474	2486	2493	2445	2477	2486	2585
$T_{VDD2WPU}$	DEVRST_N	DDRIO Inbuf weak pull	DEVRST_N to Inbuf weak pull	2500	2487	2509	2475	2507	2519	2617
	DEVRST_N	MSIO Inbuf weak pull	DEVRST_N to Inbuf weak pull	2504	2491	2510	2478	2517	2525	2620
	DEVRST_N	MSIOD Inbuf weak pull	DEVRST_N to Inbuf weak pull	2479	2468	2493	2458	2486	2499	2595

Note: For more information about power-up times, see *UG0448: IGLOO2 FPGA High Performance Memory Subsystem User Guide*.

Table 291 • **DEVRST_N to Functional Times for SmartFusion2 *(continued)***

				Maximum Power-up to Functional Time for SmartFusion2 (uS)						
Symbol	**From**	**To**	**Description**	**005**	**010**	**025**	**050**	**060**	**090**	**150**
$T_{DEVRST2POR}$	DEVRST_N	POWER_ON_RESET_N	V_{DD} at its minimum threshold level to fabric	233	289	216	213	237	234	219
$T_{DEVRST2MSSRST}$	DEVRST_N	MSS_RESET_N_M2F	V_{DD} at its minimum threshold level to MSS	702	765	712	688	636	630	866
$T_{DEVRST2WPU}$	DEVRST_N	DDRIO Inbuf weak pull	DEVRST_N to Inbuf weak pull	208	202	197	193	216	215	215
	DEVRST_N	MSIO Inbuf weak pull	DEVRST_N to Inbuf weak pull	208	202	197	193	216	215	215
	DEVRST_N	MSIOD Inbuf weak pull	DEVRST_N to Inbuf weak pull	208	202	197	193	216	215	215

Figure 19 • **DEVRST_N to Functional Timing Diagram for SmartFusion2**

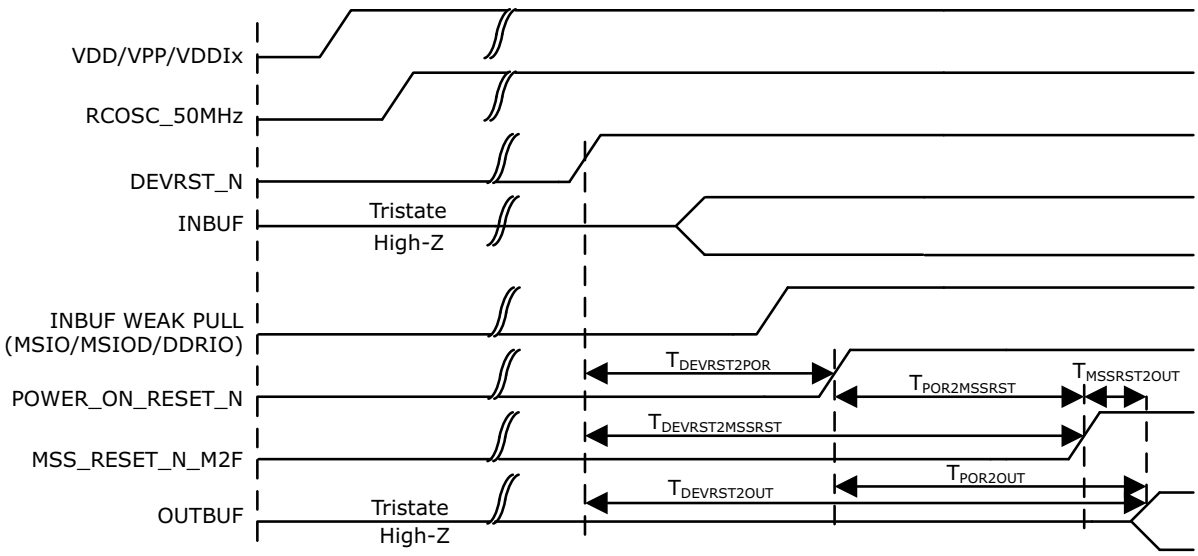
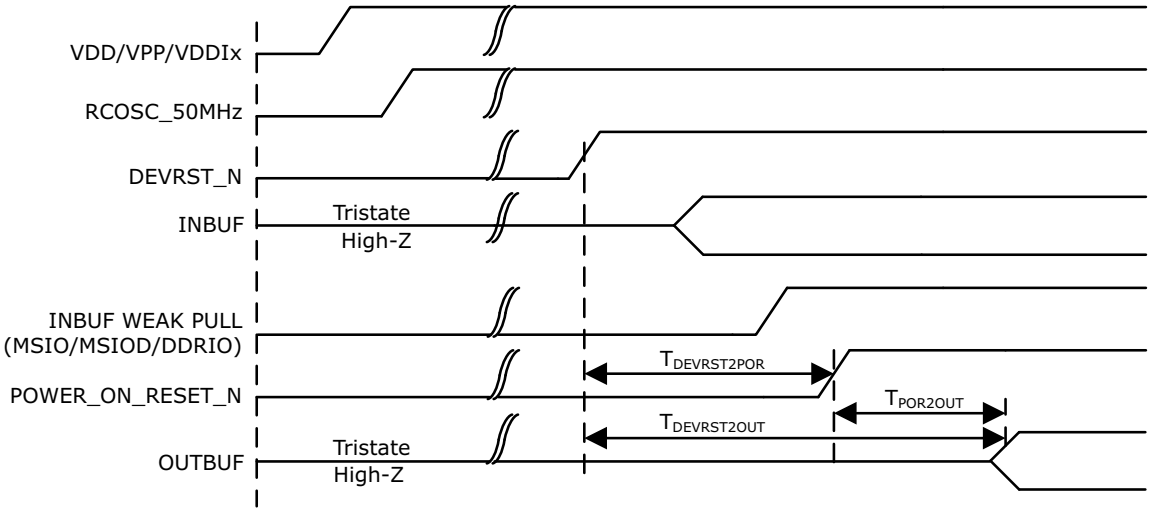


Figure 20 • **DEVRST_N to Functional Timing Diagram for IGLOO2**



2.3.27 Flash*Freeze Timing Characteristics

The following table lists the Flash*Freeze entry and exit times in worst-case industrial conditions when T_J = 100 °C, V_{DD} = 1.14 V.

Table 293 • **Flash*Freeze Entry and Exit Times**

		Entry/Exit Timing FCLK = 100MHz		Entry/Exit Timing FCLK = 3 MHz		
Parameter	**Symbol**	**005, 010, 025, 060, 090, and 150**	**050**	**All Devices**	**Unit**	**Conditions**
Entry time	TFF_ENTRY	160	150	320	µs	eNVM and MSS/HPMS PLL = ON
		215	200	430	µs	eNVM and MSS/HPMS PLL= OFF
Exit time with respect to the MSS PLL Lock	TFF_EXIT	100	100	140	µs	eNVM and MSS/HPMS PLL = ON during F*F
		136	120	190	µs	eNVM = ON and MSS/HPMS PLL = OFF during F*F and MSS/HPMS PLL turned back on at exit
		200	200	285	µs	eNVM and MSS/HPMS PLL = OFF during F*F and both are turned back on at exit
		200	200	285	µs	eNVM = OFF and MSS/HPMS PLL = ON during F*F and eNVM turned back on at exit

2.3.30 SerDes Electrical and Timing AC and DC Characteristics

PCIe is a high-speed, packet-based, point-to-point, low-pin-count, serial interconnect bus. The IGLOO2 and SmartFusion2 SoC FPGAs has up to four hard high-speed serial interface blocks. Each SerDes block contains a PCIe system block. The PCIe system is connected to the SerDes block.

The following table lists the transmitter parameters in worst-case industrial conditions when T_J = 100 °C, V_{DD} = 1.14 V.

Table 296 • **Transmitter Parameters**

Symbol	Description	Min	Max	Unit
VTX-DIFF-PP	Differential swing (2.5 Gbps, 5.0 Gbps)	0.8	1.2	V
VTX-CM-AC-P	Output common mode voltage (2.5 Gbps)		20	mV
VTX-CM-AC-PP	Output common mode voltage (5.0 Gbps)		100	mV
VTX-RISE-FALL	Rise and fall time (20% to 80%, 2.5 Gbps)	0.125		UI
	Rise and fall time (20% to 80%, 5.0 Gbps)	0.15		UI
ZTX-DIFF-DC	Output impedance–differential	80	120	Ω
LTX-SKEW	Lane-to-lane TX skew within a SerDes block (2.5 Gbps)		500 ps + 2 UI	ps
	Lane-to-lane TX skew within a SerDes block (5.0 Gbps)		500 ps + 4 UI	ps
RLTX-DIFF	Return loss differential mode (2.5 Gbps)	–10		dB
	Return loss differential mode (5.0 Gbps) 0.05 GHz to 1.25 GHz	–10		dB
	1.25 GHz to 2.5 GHz	–8		dB
RLTX-CM	Return loss common mode (2.5 Gbps, 5.0 Gbps)	–6		dB
TX-LOCK-RST	Transmit PLL lock time from reset		10	µs
VTX-AMP	100 mV setting	90	150	mV
	400 mV setting	320	480	mV
	800 mV setting	660	940	mV
	1200 mV setting	950	1400	mV

Table 305 • **SPI Characteristics for All Devices *(continued)***

Symbol	Description	Min	Typ	Max	Unit	Conditions
sp5	SPI_[0|1]_CLK, SPI_[0|1]_DO, SPI_[0|1]_SS fall time (10%–90%)[1]		2.906		ns	IO Configuration: LVCMOS 2.5 V-8 mA AC Loading: 35 pF Test Conditions: Typical Voltage, 25 °C
SPI master configuration (applicable for 005, 010, 025, and 050 devices)						
sp6m	SPI_[0|1]_DO setup time[2]	(SPI_x_CLK_period/2) – 8.0			ns	
sp7m	SPI_[0|1]_DO hold time[2]	(SPI_x_CLK_period/2) – 2.5			ns	
sp8m	SPI_[0|1]_DI setup time[2]	12			ns	
sp9m	SPI_[0|1]_DI hold time[2]	2.5			ns	
SPI slave configuration (applicable for 005, 010, 025, and 050 devices)						
sp6s	SPI_[0|1]_DO setup time[2]	(SPI_x_CLK_period/2) – 17.0			ns	
sp7s	SPI_[0|1]_DO hold time[2]	(SPI_x_CLK_period/2) + 3.0			ns	
sp8s	SPI_[0|1]_DI setup time[2]	2			ns	
sp9s	SPI_[0|1]_DI hold time[2]	7			ns	
SPI master configuration (applicable for 060, 090, and 150 devices)						
sp6m	SPI_[0|1]_DO setup time[2]	(SPI_x_CLK_period/2) – 7.0			ns	
sp7m	SPI_[0|1]_DO hold time[2]	(SPI_x_CLK_period/2) – 9.5			ns	
sp8m	SPI_[0|1]_DI setup time[2]	15			ns	
sp9m	SPI_[0|1]_DI hold time[2]	–2.5			ns	
SPI slave configuration (applicable for 060, 090, and 150 devices)						
sp6s	SPI_[0|1]_DO setup time[2]	(SPI_x_CLK_period/2) – 16.0			ns	
sp7s	SPI_[0|1]_DO hold time[2]	(SPI_x_CLK_period/2) - 3.5			ns	
sp8s	SPI_[0|1]_DI setup time[2]	3			ns	
sp9s	SPI_[0|1]_DI hold time[2]	2.5			ns	

1. For specific Rise/Fall Times board design considerations and detailed output buffer resistances, use the corresponding IBIS models located on the Microsemi SoC Products Group website: http://www.microsemi.com/soc/download/ibis/default.aspx.
2. For allowable pclk configurations, see Serial Peripheral Interface Controller section in the *UG0331: SmartFusion2 Microcontroller Subsystem User Guide*.

Table 310 • **SPI Characteristics for All Devices *(continued)***

Symbol	Description	Min	Typ	Max	Unit	Conditions
SPI master configuration (applicable for 060, 090, and 150 devices)						
sp6m	SPI_[0|1]_DO setup time[2]	(SPI_x_CLK_period/2) – 7.0			ns	
sp7m	SPI_[0|1]_DO hold time[2]	(SPI_x_CLK_period/2) – 9.5			ns	
sp8m	SPI_[0|1]_DI setup time[2]	15			ns	
sp9m	SPI_[0|1]_DI hold time[2]	–2.5			ns	
SPI slave configuration (applicable for 060, 090, and 150 devices)						
sp6s	SPI_[0|1]_DO setup time[2]	(SPI_x_CLK_period/2) – 16.0			ns	
sp7s	SPI_[0|1]_DO hold time[2]	(SPI_x_CLK_period/2) - 3.5			ns	
sp8s	SPI_[0|1]_DI setup time[2]	3			ns	
sp9s	SPI_[0|1]_DI hold time[2]	2.5			ns	

1. For specific Rise/Fall Times board design considerations and detailed output buffer resistances, use the corresponding IBIS models located on the Microsemi SoC Products Group website: http://www.microsemi.com/soc/download/ibis/default.aspx.
2. For allowable pclk configurations, see the Serial Peripheral Interface Controller section in the *UG0331: SmartFusion2 Microcontroller Subsystem User Guide*.

Figure 23 • **SPI Timing for a Single Frame Transfer in Motorola Mode (SPH = 1)**