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### **Embedded - System On Chip (SoC): The Heart of Modern Embedded Systems**

**Embedded - System On Chip (SoC)** refers to an integrated circuit that consolidates all the essential components of a computer system into a single chip. This includes a microprocessor, memory, and other peripherals, all packed into one compact and efficient package. SoCs are designed to provide a complete computing solution, optimizing both space and power consumption, making them ideal for a wide range of embedded applications.

#### **What are Embedded - System On Chip (SoC)?**

**System On Chip (SoC)** integrates multiple functions of a computer or electronic system onto a single chip. Unlike traditional multi-chip solutions, SoCs combine a central

#### **Details**

Product Status	Active
Architecture	MCU, FPGA
Core Processor	ARM® Cortex®-M3
Flash Size	256KB
RAM Size	64KB
Peripherals	DDR, PCIe, SERDES
Connectivity	CANbus, Ethernet, I²C, SPI, UART/USART, USB
Speed	166MHz
Primary Attributes	FPGA - 50K Logic Modules
Operating Temperature	-40°C ~ 100°C (TJ)
Package / Case	325-TFBGA, FCBGA
Supplier Device Package	325-FCBGA (11x11)
Purchase URL	<a href="https://www.e-xfl.com/product-detail/microchip-technology/m2s050-1fcsg325i">https://www.e-xfl.com/product-detail/microchip-technology/m2s050-1fcsg325i</a>

- For flash programming and retention maximum limits, see Table 5, page 7. For recommended operating conditions, see Table 4, page 6.

**Table 4 • Recommended Operating Conditions**

<b>Parameter</b>	<b>Symbol</b>	<b>Min</b>	<b>Typ</b>	<b>Max</b>	<b>Unit</b>	<b>Conditions</b>
Operating junction temperature	$T_J$	0	25	85	°C	Commercial
		-40	25	100	°C	Industrial
Programming junction temperatures <sup>1</sup>	$T_J$	0	25	85	°C	Commercial
		-40	25	100	°C	Industrial
DC core supply voltage. Must always power this pin.	$V_{DD}$	1.14	1.2	1.26	V	
Power supply for charge pumps (for normal operation and programming) for the 005, 010, 025, 050, 060 devices	$V_{PP}$	2.375	2.5	2.625	V	2.5 V range
		3.15	3.3	3.45	V	3.3 V range
Power supply for charge pumps (for normal operation and programming) for the 090 and 150 devices	$V_{PP}$	3.15	3.3	3.45	V	3.3 V range
Analog power pad for MDDR PLL	MSS_MDDR_PLL_VDDA	2.375	2.5	2.625	V	2.5 V range
		3.15	3.3	3.45	V	3.3 V range
Analog power pad for MDDR PLL	HPMS_MDDR_PLL_VDDA	2.375	2.5	2.625	V	2.5 V range
		3.15	3.3	3.45	V	3.3 V range
Analog power pad for FDDR PLL	FDDR_PLL_VDDA	2.375	2.5	2.625	V	2.5 V range
		3.15	3.3	3.45	V	3.3 V range
Analog power pad for MDDR PLL	PLL0_PLL1_MSS_MDDR_V DDA	2.375	2.5	2.625	V	2.5 V range
		3.15	3.3	3.45	V	3.3 V range
Analog power pad for MDDR PLL	PLL0_PLL1_HPMS_MDDR_ VDDA	2.375	2.5	2.625	V	2.5 V range
		3.15	3.3	3.45	V	3.3 V range
Analog power pad for PLL0 to PLL5	CCC_XX[01]_PLL_VDDA	2.375	2.5	2.625	V	2.5 V range
		3.15	3.3	3.45	V	3.3 V range
High supply voltage for PLL SerDes[01]	SERDES_[01]_PLL_VDDA	2.375	2.5	2.625	V	2.5 V range
		3.15	3.3	3.45	V	3.3 V range
Analog power for SerDes[01] PLL Lane 0 to Lane 3. This is a 2.5 V SerDes internal PLL supply.	SERDES_[01]_L[0123]_VD DAPLL	2.375	2.5	2.625	V	
TX/RX analog I/O voltage. Low voltage power for the lanes of SerDesIF0. This is a 1.2 V SerDes PMA supply.	SERDES_[01]_L[0123]_VD DAIO	1.14	1.2	1.26	V	
PCIe/PCS power supply	SERDES_[01]_VDD	1.14	1.2	1.26	V	
1.2 V DC supply voltage	$V_{DD1x}$	1.14	1.2	1.26	V	
1.5 V DC supply voltage	$V_{DD1x}$	1.425	1.5	1.575	V	
1.8 V DC supply voltage	$V_{DD1x}$	1.71	1.8	1.89	V	
2.5 V DC supply voltage	$V_{DD1x}$	2.375	2.5	2.625	V	

**Figure 1 • High Temperature Data Retention (HTR)**

### 2.3.1.1 Overshoot/Undershoot Limits

For AC signals, the input signal may undershoot during transitions to  $-1.0\text{ V}$  for no longer than 10% of the period. The current during the transition must not exceed 100 mA.

For AC signals, the input signal may overshoot during transitions to  $V_{CC1} + 1.0\text{ V}$  for no longer than 10% of the period. The current during the transition must not exceed 100 mA.

**Note:** The above specifications do not apply to the PCI standard. The IGLOO2 and SmartFusion2 PCI I/Os are compliant with the PCI standard including the PCI overshoot/undershoot specifications.

### 2.3.1.2 Thermal Characteristics

The temperature variable in the Microsemi SoC Products Group Designer software refers to the junction temperature, not the ambient, case, or board temperatures. This is an important distinction because dynamic and static power consumption causes the chip's junction temperature to be higher than the ambient, case, or board temperatures.

EQ1 through EQ3 give the relationship between thermal resistance, temperature gradient, and power.

$$\theta_{JA} = \frac{T_J - T_A}{P} \quad EQ\ 1$$

$$\theta_{JB} = \frac{T_J - T_B}{P} \quad EQ\ 2$$

$$\theta_{JC} = \frac{T_J - T_C}{P} \quad EQ\ 3$$

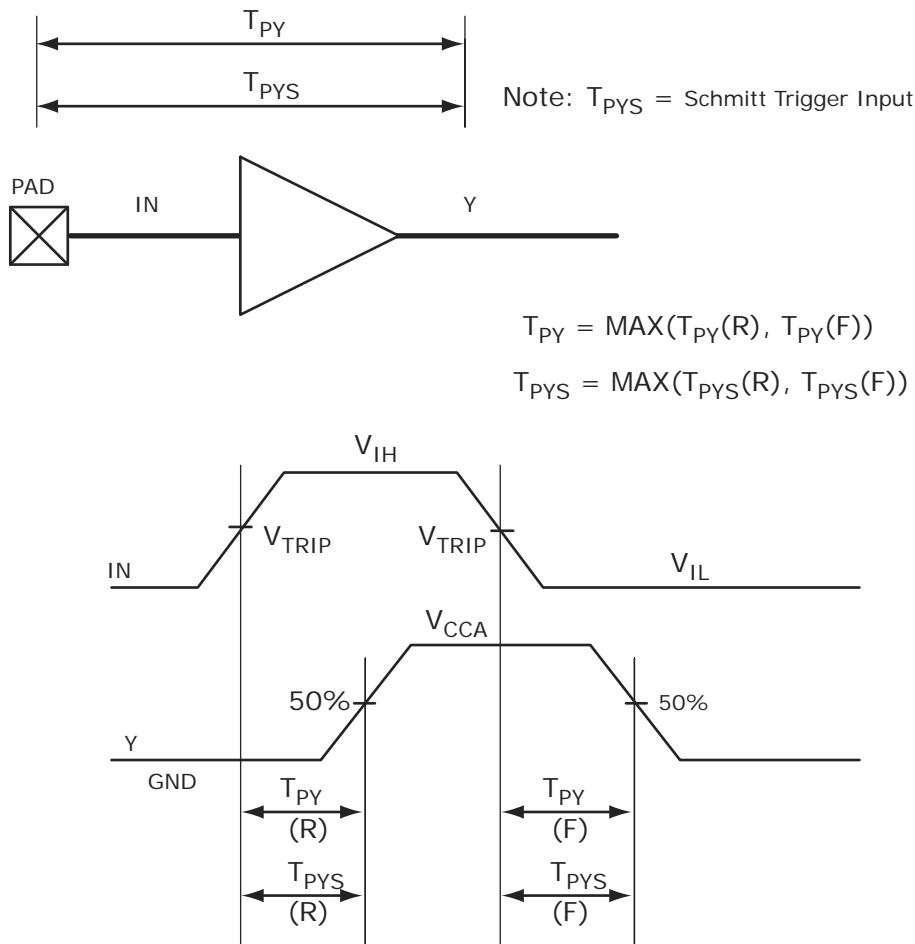
## 2.3.5 User I/O Characteristics

There are three types of I/Os supported in the IGLOO2 FPGA and SmartFusion2 SoC FPGA families: MSIO, MSIOD, and DDRIO I/O banks. The I/O standards supported by the different I/O banks is described in the I/Os section of the *UG0445: IGLOO2 FPGA and SmartFusion2 SoC FPGA Fabric User Guide*.

### 2.3.5.1 Input Buffer and AC Loading

The following figure shows the input buffer and AC loading.

**Figure 3 • Input Buffer AC Loading**



**Table 43 • LVC MOS 2.5 V AC Test Parameter Specifications**

Parameter	Symbol	Typ	Unit
Measuring/trip point for data path	V <sub>TRIP</sub>	1.2	V
Resistance for enable path (T <sub>ZH</sub> , T <sub>ZL</sub> , T <sub>HZ</sub> , T <sub>LZ</sub> )	R <sub>ENT</sub>	2K	Ωσ
Capacitive loading for enable path (T <sub>ZH</sub> , T <sub>ZL</sub> , T <sub>HZ</sub> , T <sub>LZ</sub> )	C <sub>ENT</sub>	5	pF
Capacitive loading for data path (T <sub>DP</sub> )	C <sub>LOAD</sub>	5	pF

**Table 44 • LVC MOS 2.5 V Transmitter Drive Strength Specifications**

Output Drive Selection			V <sub>OH</sub> (V)	V <sub>OL</sub> (V)	IOH (at V <sub>OH</sub> ) mA	I <sub>OL</sub> (at V <sub>OL</sub> ) mA
MSIO I/O Bank	MSIOD I/O Bank	DDRIO I/O Bank (With Software Default Fixed Code)	Min	Max		
2 mA	2 mA	2 mA	V <sub>DDI</sub> – 0.4	0.4	2	2
4 mA	4 mA	4 mA	V <sub>DDI</sub> – 0.4	0.4	4	4
6 mA	6 mA	6 mA	V <sub>DDI</sub> – 0.4	0.4	6	6
8 mA	8 mA	8 mA	V <sub>DDI</sub> – 0.4	0.4	8	8
12 mA	12 mA	12 mA	V <sub>DDI</sub> – 0.4	0.4	12	12
16 mA		16 mA	V <sub>DDI</sub> – 0.4	0.4	16	16

**Note:** For board design considerations, output slew rates extraction, detailed output buffer resistances, and I/V Curve, use the corresponding IBIS models located at:  
[www.microsemi.com/soc/download/ibis/default.aspx](http://www.microsemi.com/soc/download/ibis/default.aspx).

#### AC Switching Characteristics

Worst commercial-case conditions: T<sub>J</sub> = 85 °C, V<sub>DD</sub> = 1.14 V, V<sub>DDI</sub> = 2.375 V

**Table 45 • LVC MOS 2.5 V Receiver Characteristics (Input Buffers)**

	On-Die Termination (ODT)	T <sub>PY</sub>				T <sub>PYS</sub>		Unit
		-1	-Std	-1	-Std			
LVC MOS 2.5 V (for DDRIO I/O bank)	None	1.823	2.145	1.932	2.274	ns		
LVC MOS 2.5 V (for MSIO I/O bank)	None	2.486	2.925	2.495	2.935	ns		
LVC MOS 2.5 V (for MSIOD I/O bank)	None	2.29	2.694	2.305	2.712	ns		

**Table 46 • LVC MOS 2.5 V Transmitter Characteristics for DDRIO Bank (Output and Tristate Buffers)**

Output Drive Selection	Slew Control	T <sub>DP</sub>		T <sub>ZL</sub>		T <sub>ZH</sub>		T <sub>HZ</sub> <sup>1</sup>		T <sub>LZ</sub> <sup>1</sup>		Unit
		-1	-Std	-1	-Std	-1	-Std	-1	-Std	-1	-Std	
2 mA	Slow	3.657	4.302	3.393	3.991	3.675	4.323	3.894	4.582	3.552	4.18	ns
	Medium	3.374	3.97	3.139	3.693	3.396	3.995	3.635	4.277	3.253	3.828	ns
	Medium fast	3.239	3.811	3.036	3.572	3.261	3.836	3.519	4.141	3.128	3.681	ns
	Fast	3.224	3.793	3.029	3.563	3.246	3.818	3.512	4.132	3.119	3.67	ns

**Table 58 • LVC MOS 1.8 V Transmitter Characteristics for MSIO I/O Bank**

Output Drive Selection	Slew Control	T <sub>DP</sub>		T <sub>ZL</sub>		T <sub>ZH</sub>		T <sub>HZ</sub> <sup>1</sup>		T <sub>LZ</sub> <sup>1</sup>		Unit
		-1	-Std	-1	-Std	-1	-Std	-1	-Std	-1	-Std	
2 mA	Slow	3.441	4.047	4.165	4.9	4.413	5.192	4.891	5.755	5.138	6.044	ns
4 mA	Slow	3.218	3.786	3.642	4.284	3.941	4.636	5.665	6.665	5.568	6.551	ns
6 mA	Slow	3.141	3.694	3.501	4.118	3.823	4.498	6.587	7.75	6.032	7.096	ns
8 mA	Slow	3.165	3.723	3.319	3.904	3.654	4.298	6.898	8.115	6.216	7.313	ns
10 mA	Slow	3.202	3.767	3.278	3.857	3.616	4.254	7.25	8.529	6.435	7.571	ns
12 mA	Slow	3.277	3.855	3.175	3.736	3.519	4.139	7.392	8.697	6.538	7.692	ns

1. Delay increases with drive strength are inherent to built-in slew control circuitry for simultaneous switching output (SSO) management.

**Table 59 • LVC MOS 1.8 V Transmitter Characteristics for MSIOD I/O Bank**

Output Drive Selection	Slew Control	T <sub>DP</sub>		T <sub>ZL</sub>		T <sub>ZH</sub>		T <sub>HZ</sub> <sup>1</sup>		T <sub>LZ</sub> <sup>1</sup>		Unit
		-1	-Std	-1	-Std	-1	-Std	-1	-Std	-1	-Std	
2 mA	Slow	2.725	3.206	3.316	3.901	3.484	4.099	5.204	6.123	4.997	5.88	ns
4 mA	Slow	2.242	2.638	2.777	3.267	2.947	3.466	5.729	6.74	5.448	6.41	ns
6 mA	Slow	1.995	2.347	2.466	2.901	2.63	3.094	6.372	7.496	5.987	7.043	ns
8 mA	Slow	2.001	2.354	2.44	2.87	2.6	3.058	6.633	7.804	6.193	7.286	ns
10 mA	Slow	2.025	2.382	2.312	2.719	2.47	2.906	6.94	8.165	6.412	7.544	ns

1. Delay increases with drive strength are inherent to built-in slew control circuitry for simultaneous switching output (SSO) management.

### 2.3.5.9 1.5 V LVC MOS

LVC MOS 1.5 is a general standard for 1.5 V applications and is supported in IGLOO2 FPGAs and SmartFusion2 SoC FPGAs in compliance to the JEDEC specification JESD8-11A.

#### Minimum and Maximum DC/AC Input and Output Levels Specification

**Table 60 • LVC MOS 1.5 V DC Recommended Operating Conditions**

Parameter	Symbol	Min	Typ	Max	Unit
Supply voltage	V <sub>DDI</sub>	1.425	1.5	1.575	V

**Table 61 • LVC MOS 1.5 V DC Input Voltage Specification**

Parameter	Symbol	Min	Max	Unit
DC input logic high for (MSIOD and DDRIO I/O banks)	V <sub>IH</sub> (DC)	0.65 × V <sub>DDI</sub>	1.575	V
DC input logic high (for MSIO I/O bank)	V <sub>IH</sub> (DC)	0.65 × V <sub>DDI</sub>	3.45	V
DC input logic low	V <sub>IL</sub> (DC)	-0.3	0.35 × V <sub>DDI</sub>	V
Input current high <sup>1</sup>	I <sub>IH</sub> (DC)			-
Input current low <sup>1</sup>	I <sub>IL</sub> (DC)			-

1. See Table 24, page 22.

### AC Switching Characteristics

Worst commercial-case conditions:  $T_J = 85^\circ\text{C}$ ,  $V_{DD} = 1.14\text{ V}$ ,  $V_{DDI} = 3.0\text{ V}$

**Table 91 • PCI/PCIX AC Switching Characteristics for Receiver for MSIO I/O Bank (Input Buffers)**

On-Die Termination (ODT)	$T_{PY}$		$T_{PYS}$			Unit
	-1	-Std	-1	-Std		
None	2.229	2.623	2.238	2.633	ns	

**Table 92 • PCI/PCIX AC switching Characteristics for Transmitter for MSIO I/O Bank (Output and Tristate Buffers)**

$T_{DP}$	$T_{ZL}$	$T_{ZH}$	$T_{HZ}$	$T_{LZ}$		
-1	-Std	-1	-Std	-1	-Std	Unit
2.146	2.525	2.043	2.404	2.084	2.452	6.095 7.171 5.558 6.539 ns

### 2.3.6 Memory Interface and Voltage Referenced I/O Standards

This section describes High-Speed Transceiver Logic (HSTL) memory interface and voltage reference I/O standards.

#### 2.3.6.1 High-Speed Transceiver Logic (HSTL)

The HSTL standard is a general purpose high-speed bus standard sponsored by IBM (EIA/JESD8-6). IGLOO2 FPGA and SmartFusion2 SoC FPGA devices support two classes of the 1.5 V HSTL. These differential versions of the standard require a differential amplifier input buffer and a push-pull output buffer.

**Minimum and Maximum DC/AC Input and Output Levels Specification (Applicable to DDRIO Bank Only)**

**Table 93 • HSTL Recommended DC Operating Conditions**

Parameter	Symbol	Min	Typ	Max	Unit
Supply voltage	$V_{DDI}$	1.425	1.5	1.575	V
Termination voltage	$V_{TT}$	0.698	0.750	0.803	V
Input reference voltage	$V_{REF}$	0.698	0.750	0.803	V

**Table 94 • HSTL DC Input Voltage Specification**

Parameter	Symbol	Min	Max	Unit
DC input logic high	$V_{IH}$ (DC)	$V_{REF} + 0.1$	1.575	V
DC input logic low	$V_{IL}$ (DC)	-0.3	$V_{REF} - 0.1$	V
Input current high <sup>1</sup>	$I_{IH}$ (DC)			
Input current low <sup>1</sup>	$I_{IL}$ (DC)			

1. See Table 24, page 22.

**Table 131 • SSTL15 DC Output Voltage Specification (for DDRIO I/O Bank Only)**

Parameter	Symbol	Min	Max	Unit
<b>DDR3/SSTL15 Class I (DDR3 Reduced Drive)</b>				
DC output logic high	$V_{OH}$	$0.8 \times V_{DDI}$		V
DC output logic low	$V_{OL}$		$0.2 \times V_{DDI}$	V
Output minimum source DC current	$I_{OH}$ at $V_{OH}$	6.5		mA
Output minimum sink current	$I_{OL}$ at $V_{OL}$	-6.5		mA
<b>DDR3/SSTL15 Class II (DDR3 Full Drive)</b>				
DC output logic high	$V_{OH}$	$0.8 \times V_{DDI}$		V
DC output logic low	$V_{OL}$		$0.2 \times V_{DDI}$	V
Output minimum source DC current	$I_{OH}$ at $V_{OH}$	7.6		mA
Output minimum sink current	$I_{OL}$ at $V_{OL}$	-7.6		mA

**Table 132 • SSTL15 DC Differential Voltage Specification (for DDRIO I/O Bank Only)**

Parameter	Symbol	Min	Unit
DC input differential voltage	$V_{ID}$	0.2	V

**Note:** To meet JEDEC electrical compliance, use DDR3 full drive transmitter.

**Table 133 • SSTL15 AC SSTL15 Minimum and Maximum AC Switching Speed (for DDRIO I/O Bank Only)**

Parameter	Symbol	Min	Max	Unit
AC input differential voltage	$V_{DIFF}$ (AC)	0.3		V
AC differential cross point voltage	$V_x$ (AC)	$0.5 \times V_{DDI} - 0.150$	$0.5 \times V_{DDI} + 0.150$	V

**Table 134 • SSTL15 Minimum and Maximum AC Switching Speed (for DDRIO I/O Bank Only)**

Parameter	Symbol	Max	Unit	Conditions
Maximum data rate	$D_{MAX}$	667	Mbps	AC loading: per JEDEC specifications

**Table 135 • SSTL15 AC Calibrated Impedance Option (for DDRIO I/O Bank Only)**

Parameter	Symbol	Typ	Unit	Conditions
Supported output driver calibrated impedance	$R_{REF}$	34, 40	$\Omega$	Reference resistor = 240 $\Omega$
Effective impedance value (ODT)	$R_{TT}$	20, 30, 40, 60, 120	$\Omega$	Reference resistor = 240 $\Omega$

### 2.3.7.2 B-LVDS

Bus LVDS (B-LVDS) specifications extend the existing LVDS standard to high-performance multipoint bus applications. Multidrop and multipoint bus configurations may contain any combination of drivers, receivers, and transceivers.

#### Minimum and Maximum DC/AC Input and Output Levels Specification

**Table 173 • B-LVDS Recommended DC Operating Conditions**

Parameter	Symbol	Min	Typ	Max	Unit
Supply voltage	$V_{DDI}$	2.375	2.5	2.625	V

**Table 174 • B-LVDS DC Input Voltage Specification**

Parameter	Symbol	Min	Max	Unit
DC input voltage	$V_I$	0	2.925	V
Input current high <sup>1</sup>	$I_{IH}$ (DC)			
Input current low <sup>1</sup>	$I_{IL}$ (DC)			

1. See Table 24, page 22.

**Table 175 • B-LVDS DC Output Voltage Specification (for MSIO I/O Bank Only)**

Parameter	Symbol	Min	Typ	Max	Unit
DC output logic high	$V_{OH}$	1.25	1.425	1.6	V
DC output logic low	$V_{OL}$	0.9	1.075	1.25	V

**Table 176 • B-LVDS DC Differential Voltage Specification**

Parameter	Symbol	Min	Max	Unit
Differential output voltage swing (for MSIO I/O bank only)	$V_{OD}$	65	460	mV
Output common mode voltage (for MSIO I/O bank only)	$V_{OCM}$	1.1	1.5	V
Input common mode voltage	$V_{ICM}$	0.05	2.4	V
Input differential voltage	$V_{ID}$	0.1	$V_{DDI}$	V

**Table 177 • B-LVDS Minimum and Maximum AC Switching Speed**

Parameter	Symbol	Max	Unit	Conditions
Maximum data rate (for MSIO I/O bank)	$D_{MAX}$	500	Mbps	AC loading: 2 pF / 100 Ω differential load

**Table 178 • B-LVDS AC Impedance Specifications**

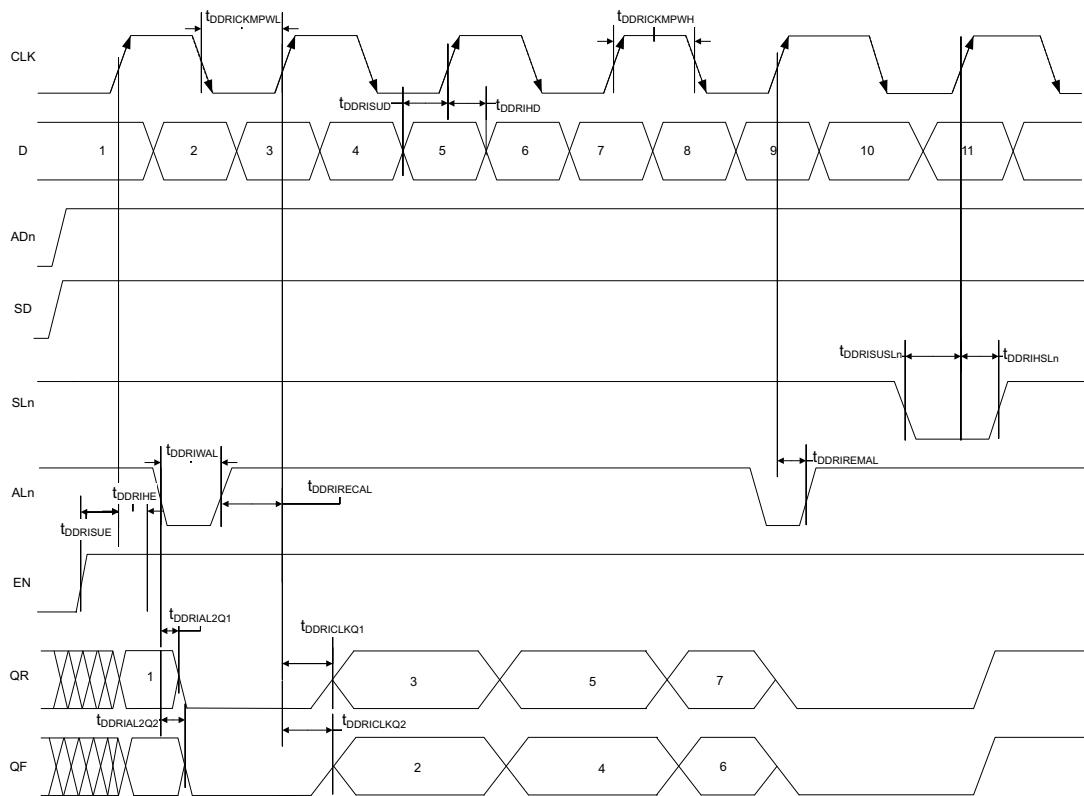
Parameter	Symbol	Typ	Unit
Termination resistance	$R_T$	27	Ω

**Table 179 • B-LVDS AC Test Parameter Specifications**

Parameter	Symbol	Typ	Unit
Measuring/trip point for data path	$V_{TRIP}$	Cross point	V
Resistance for enable path ( $T_{ZH}$ , $T_{ZL}$ , $T_{HZ}$ , $T_{LZ}$ )	$R_{ENT}$	2K	Ω
Capacitive loading for enable path ( $T_{ZH}$ , $T_{ZL}$ , $T_{HZ}$ , $T_{LZ}$ )	$C_{ENT}$	5	pF

### 2.3.9.2 Input DDR Timing Diagram

Figure 11 • Input DDR Timing Diagram

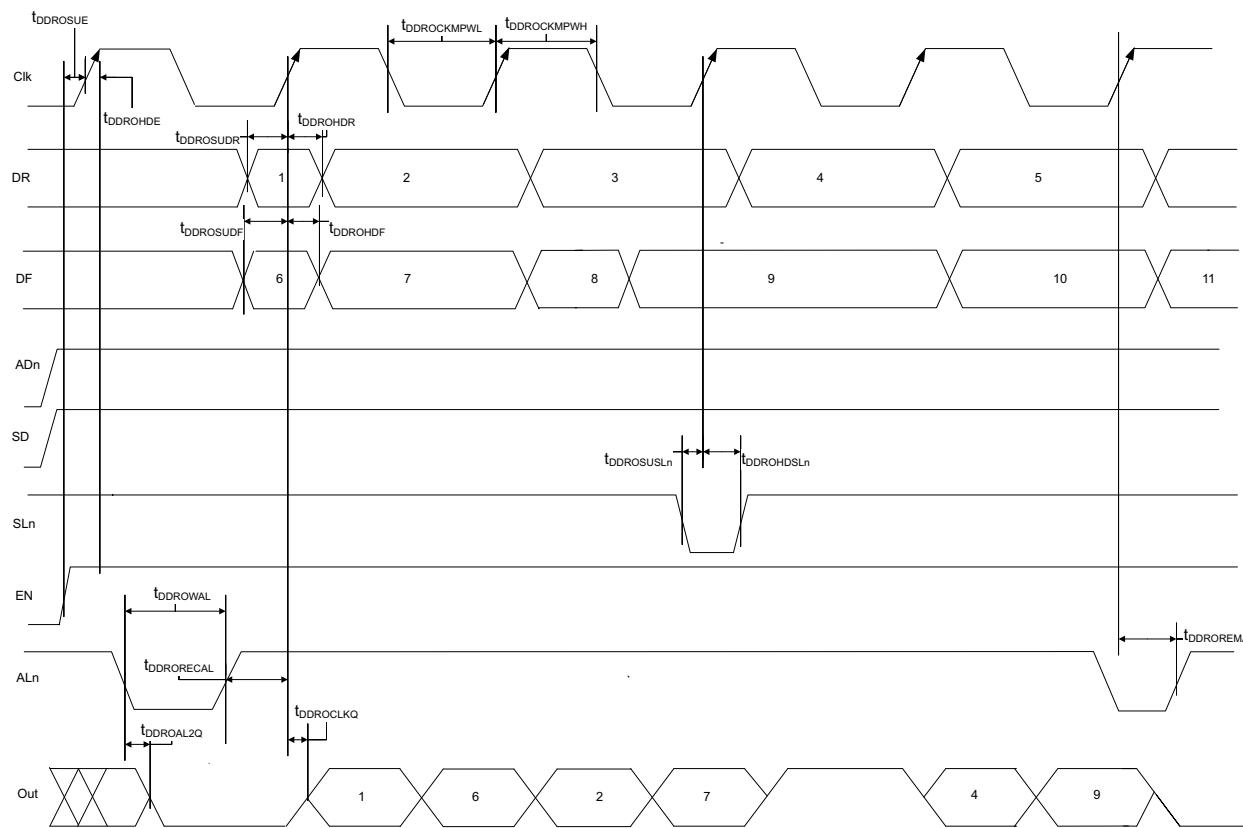


### 2.3.9.3 Timing Characteristics

The following table lists the input DDR propagation delays in worst commercial-case conditions when  $T_J = 85^\circ\text{C}$ ,  $V_{DD} = 1.14\text{ V}$ .

Table 221 • Input DDR Propagation Delays

Symbol	Description	Measuring Nodes (from, to)	-1	-Std	Unit
$T_{DDRICKQ1}$	Clock-to-Out Out_QR for input DDR	B, C	0.16	0.188	ns
$T_{DDRICKQ2}$	Clock-to-Out Out_QF for input DDR	B, D	0.166	0.195	ns
$T_{DDRISUD}$	Data setup for input DDR	A, B	0.357	0.421	ns
$T_{DDRIHD}$	Data hold for input DDR	A, B	0	0	ns
$T_{DDRISE}$	Enable setup for input DDR	E, B	0.46	0.542	ns
$T_{DDRIHE}$	Enable hold for input DDR	E, B	0	0	ns
$T_{DDRISULN}$	Synchronous load setup for input DDR	G, B	0.46	0.542	ns
$T_{DDRIHSLN}$	Synchronous load hold for input DDR	G, B	0	0	ns
$T_{DDRIAL2Q1}$	Asynchronous load-to-out QR for input DDR	F, C	0.587	0.69	ns
$T_{DDRIAL2Q2}$	Asynchronous load-to-out QF for input DDR	F, D	0.541	0.636	ns
$T_{DDRIREMAL}$	Asynchronous load removal time for input DDR	F, B	0	0	ns
$T_{DDRIRECAL}$	Asynchronous load recovery time for input DDR	F, B	0.074	0.087	ns

**Figure 13 • Output DDR Timing Diagram****2.3.9.5 Timing Characteristics**

The following table lists the output DDR propagation delays in worst commercial-case conditions when  $T_J = 85^\circ\text{C}$ ,  $V_{DD} = 1.14\text{ V}$ .

**Table 222 • Output DDR Propagation Delays**

Symbol	Description	Measuring Nodes (from, to)	-1	-Std	Unit
$T_{DDROCLKQ}$	Clock-to-out of DDR for output DDR	E, G	0.263	0.309	ns
$T_{DDROSUDF}$	Data_F data setup for output DDR	F, E	0.143	0.168	ns
$T_{DDROSUDR}$	Data_R data setup for output DDR	A, E	0.19	0.223	ns
$T_{DDROHDF}$	Data_F data hold for output DDR	F, E	0	0	ns
$T_{DDROHDR}$	Data_R data hold for output DDR	A, E	0	0	ns
$T_{DDROSUE}$	Enable setup for input DDR	B, E	0.419	0.493	ns
$T_{DDROHE}$	Enable hold for input DDR	B, E	0	0	ns
$T_{DDROSUSLN}$	Synchronous load setup for input DDR	D, E	0.196	0.231	ns
$T_{DDROHSLN}$	Synchronous load hold for input DDR	D, E	0	0	ns
$T_{DDROAL2Q}$	Asynchronous load-to-out for output DDR	C, G	0.528	0.621	ns
$T_{DDROREMAL}$	Asynchronous load removal time for output DDR	C, E	0	0	ns
$T_{DDRORECAL}$	Asynchronous load recovery time for output DDR	C, E	0.034	0.04	ns

### 2.3.11 Global Resource Characteristics

The IGLOO2 and SmartFusion2 SoC FPGA devices offer a powerful, low skew global routing network which provides an effective clock distribution throughout the FPGA fabric. See *UG0445: IGLOO2 FPGA and SmartFusion2 SoC FPGA Fabric User Guide* for the positions of various global routing resources.

The following table lists the 150 device global resources in worst commercial-case conditions when  $T_J = 85^\circ\text{C}$ ,  $V_{DD} = 1.14\text{ V}$ .

**Table 225 • 150 Device Global Resource**

<b>Parameter</b>	<b>Symbol</b>	<b>-1</b>		<b>-Std</b>		<b>Unit</b>
		<b>Min</b>	<b>Max</b>	<b>Min</b>	<b>Max</b>	
Input low delay for global clock	$T_{RCKL}$	0.83	0.911	0.831	0.913	ns
Input high delay for global clock	$T_{RCKH}$	1.457	1.588	1.715	1.869	ns
Maximum skew for global clock	$T_{RCKSW}$		0.131		0.154	ns

The following table lists the 090 device global resources in worst commercial-case conditions when  $T_J = 85^\circ\text{C}$ ,  $V_{DD} = 1.14\text{ V}$ .

**Table 226 • 090 Device Global Resource**

<b>Parameter</b>	<b>Symbol</b>	<b>-1</b>		<b>-Std</b>		<b>Unit</b>
		<b>Min</b>	<b>Max</b>	<b>Min</b>	<b>Max</b>	
Input low delay for global clock	$T_{RCKL}$	0.835	0.888	0.833	0.886	ns
Input high delay for global clock	$T_{RCKH}$	1.405	1.489	1.654	1.752	ns
Maximum skew for global clock	$T_{RCKSW}$		0.084		0.098	ns

The following table lists the 050 device global resources in worst commercial-case conditions when  $T_J = 85^\circ\text{C}$ ,  $V_{DD} = 1.14\text{ V}$ .

**Table 227 • 050 Device Global Resource**

<b>Parameter</b>	<b>Symbol</b>	<b>-1</b>		<b>-Std</b>		<b>Unit</b>
		<b>Min</b>	<b>Max</b>	<b>Min</b>	<b>Max</b>	
Input low delay for global clock	$T_{RCKL}$	0.827	0.897	0.826	0.896	ns
Input high delay for global clock	$T_{RCKH}$	1.419	1.53	1.671	1.8	ns
Maximum skew for global clock	$T_{RCKSW}$		0.111		0.129	ns

The following table lists the 025 device global resources in worst commercial-case conditions when  $T_J = 85^\circ\text{C}$ ,  $V_{DD} = 1.14\text{ V}$ .

**Table 228 • 025 Device Global Resource**

<b>Parameter</b>	<b>Symbol</b>	<b>-1</b>		<b>-Std</b>		<b>Unit</b>
		<b>Min</b>	<b>Max</b>	<b>Min</b>	<b>Max</b>	
Input low delay for global clock	$T_{RCKL}$	0.747	0.799	0.745	0.797	ns
Input high delay for global clock	$T_{RCKH}$	1.294	1.378	1.522	1.621	ns
Maximum skew for global clock	$T_{RCKSW}$		0.084		0.099	ns

The following table lists the µSRAM in  $256 \times 4$  mode in worst commercial-case conditions when  $T_J = 85^\circ\text{C}$ ,  $V_{DD} = 1.14\text{ V}$ .

**Table 241 • µSRAM (RAM256x4) in  $256 \times 4$  Mode**

<b>Parameter</b>	<b>Symbol</b>	<b>-1</b>		<b>-Std</b>		<b>Unit</b>
		<b>Min</b>	<b>Max</b>	<b>Min</b>	<b>Max</b>	
Read clock period	$T_{CY}$	4	4			ns
Read clock minimum pulse width high	$T_{CLKMPWH}$	1.8	1.8			ns
Read clock minimum pulse width low	$T_{CLKMPWL}$	1.8	1.8			ns
Read pipeline clock period	$T_{PLCY}$	4	4			ns
Read pipeline clock minimum pulse width high	$T_{PLCLKMPWH}$	1.8	1.8			ns
Read pipeline clock minimum pulse width low	$T_{PLCLKMPWL}$	1.8	1.8			ns
Read access time with pipeline register	$T_{CLK2Q}$		0.27		0.31	ns
Read access time without pipeline register			1.75		2.06	ns
Read address setup time in synchronous mode	$T_{ADDRSU}$	0.301	0.354			ns
Read address setup time in asynchronous mode		1.931	2.272			ns
Read address hold time in synchronous mode	$T_{ADDRHD}$	0.121	0.142			ns
Read address hold time in asynchronous mode		-0.65	-0.76			ns
Read enable setup time	$T_{RDENSU}$	0.278	0.327			ns
Read enable hold time	$T_{RDENHD}$	0.057	0.067			ns
Read block select setup time	$T_{BLKSU}$	1.839	2.163			ns
Read block select hold time	$T_{BLKHD}$	-0.65	-0.77			ns
Read block select to out disable time (when pipelined register is disabled)	$T_{BLK2Q}$		2.09		2.46	ns
Read asynchronous reset removal time (pipelined clock)	$T_{RSTREM}$	-0.02	-0.03			ns
Read asynchronous reset removal time (non-pipelined clock)		0.046	0.054			ns
Read asynchronous reset recovery time (pipelined clock)	$T_{RSTREC}$	0.507	0.597			ns
Read asynchronous reset recovery time (non-pipelined clock)		0.236	0.278			ns
Read asynchronous reset to output propagation delay (with pipelined register enabled)	$T_{R2Q}$		0.83		0.98	ns
Read synchronous reset setup time	$T_{SRSTSU}$	0.271	0.319			ns
Read synchronous reset hold time	$T_{SRSTHD}$	0.061	0.071			ns
Write clock period	$T_{CCY}$	4	4			ns
Write clock minimum pulse width high	$T_{CCLKMPWH}$	1.8	1.8			ns
Write clock minimum pulse width low	$T_{CCLKMPWL}$	1.8	1.8			ns
Write block setup time	$T_{BLKCSU}$	0.404	0.476			ns
Write block hold time	$T_{BLKCHD}$	0.007	0.008			ns
Write input data setup time	$T_{DINCSU}$	0.101	0.118			ns
Write input data hold time	$T_{DINCHD}$	0.137	0.161			ns
Write address setup time	$T_{ADDRCSU}$	0.088	0.104			ns

**Table 259 • 2 Step IAP Programming (Fabric Only)**

<b>M2S/M2GL Device</b>	<b>Image size Bytes</b>	<b>Authenticate</b>	<b>Program</b>	<b>Verify</b>	<b>Unit</b>
005	302672	4	39	6	Sec
010	568784	7	45	12	Sec
025	1223504	14	55	23	Sec
050	2424832	29	74	40	Sec
060	2418896	39	83	50	Sec
090	3645968	60	106	73	Sec
150	6139184	100	154	120	Sec

**Table 260 • 2 Step IAP Programming (eNVM Only)**

<b>M2S/M2GL Device</b>	<b>Image size Bytes</b>	<b>Authenticate</b>	<b>Program</b>	<b>Verify</b>	<b>Unit</b>
005	137536	2	59	5	Sec
010	274816	4	98	11	Sec
025	274816	4	100	10	Sec
050	2,78,528	3	107	9	Sec
060	268480	5	98	22	Sec
090	544496	10	174	43	Sec
150	544496	10	175	44	Sec

**Table 261 • 2 Step IAP Programming (Fabric and eNVM)**

<b>M2S/M2GL Device</b>	<b>Image size Bytes</b>	<b>Authenticate</b>	<b>Program</b>	<b>Verify</b>	<b>Unit</b>
005	439296	6	78	11	Sec
010	842688	11	122	21	Sec
025	1497408	19	135	32	Sec
050	2695168	32	158	48	Sec
060	2686464	43	159	70	Sec
090	4190208	68	258	115	Sec
150	6682768	109	308	162	Sec

**Table 276 • Cryptographic Block Characteristics (continued)**

<b>Service</b>	<b>Conditions</b>	<b>Timing</b>	<b>Unit</b>
SHA256	512 bits	540	kbytes
	1024 bits	780	kbytes
	2048 bits	950	kbytes
	24 kbytes	1140	kbytes
HMAC	512 bytes	820	kbytes
	1024 bytes	890	kbytes
	2048 bytes	930	kbytes
	24 kbytes	980	kbytes
KeyTree		1.8	ms
Challenge-response	PUF = OFF	25	ms
	PUF = ON	7	ms
ECC point multiplication		590	ms
ECC point addition		8	ms

1. Using cypher block chaining (CBC) mode.

### 2.3.19 Crystal Oscillator

The following table describes the electrical characteristics of the crystal oscillator in the IGLOO2 FPGA and SmartFusion2 SoC FPGAs.

**Table 277 • Electrical Characteristics of the Crystal Oscillator – High Gain Mode (20 MHz)**

<b>Parameter</b>	<b>Symbol</b>	<b>Min</b>	<b>Typ</b>	<b>Max</b>	<b>Unit</b>	<b>Condition</b>
Operating frequency	FXTAL		20		MHz	
Accuracy	ACCXTAL		0.0047	0.0058	%	005, 010, 025, 050, 060, and 090 devices
					%	150 devices
Output duty cycle	CYCXTAL	49–51	47–53		%	
Output period jitter (peak to peak)	JITPERXTAL	200	300		ps	
Output cycle to cycle jitter (peak to peak)	JITCYCXTAL	200	300	410	ps	010, 025, 050, and 060 devices
					ps	150 devices
					ps	005 and 090 devices
Operating current	IDYNXTAL	1.5		550	mA	010, 050, and 060 devices
					mA	005, 025, 090, and 150 devices
Input logic level high	VIHXTAL	0.9 V <sub>PP</sub>			V	
Input logic level low	VILXTAL		0.1 V <sub>PP</sub>		V	

**Table 277 • Electrical Characteristics of the Crystal Oscillator – High Gain Mode (20 MHz) (continued)**

Parameter	Symbol	Min	Typ	Max	Unit	Condition
Startup time (with regard to stable oscillator output)	SUXTAL		0.8	ms	005, 010, 025, and 050 devices	005, 010, 025, and 050 devices
						090 and 150 devices

**Table 278 • Electrical Characteristics of the Crystal Oscillator – Medium Gain Mode (2 MHz)**

Parameter	Symbol	Min	Typ	Max	Unit	Condition
Operating frequency	FXTAL		2		MHz	
Accuracy	ACCXTAL			0.00105	%	050 devices
				0.003	%	005, 010, 025, 090, and 150 devices
				0.004	%	060 devices
Output duty cycle	CYCXTAL	49–51	47–53		%	
Output period jitter (peak to peak)	JITPERXTAL	1	5	ns		
Output cycle to cycle jitter (peak to peak)	JITCYCXTAL		1	5	ns	
Operating current	IDYNXTAL		0.3		mA	
Input logic level high	VIHXTAL	0.9 V <sub>PP</sub>			V	
Input logic level low	VILXTAL			0.1 V <sub>PP</sub>	V	
Startup time (with regard to stable oscillator output)	SUXTAL			4.5	ms	010 and 050 devices
				5	ms	005 and 025 devices
				7	ms	090 and 150 devices

**Table 279 • Electrical Characteristics of the Crystal Oscillator – Low Gain Mode (32 kHz)**

Parameter	Symbol	Min	Typ	Max	Unit	Condition
Operating frequency	FXTAL		32		kHz	
Accuracy	ACCXTAL			0.004	%	005, 010, 025, 050, 060, and 090 devices
				0.005	%	150 devices
Output duty cycle	CYCXTAL	49–51	47–53		%	
Output period jitter (peak to peak)	JITPERXTAL	150	300	ns		
Output cycle to cycle jitter (peak to peak)	JITCYCXTAL	150	300	ns		
Operating current	IDYNXTAL			0.044	mA	010 and 050 devices
				0.060	mA	005, 025, 060, 090, and 150 devices
Input logic level high	VIHXTAL	0.9 V <sub>PP</sub>			V	
Input logic level low	VILXTAL			0.1 V <sub>PP</sub>	V	
Startup time (with regard to stable oscillator output)	SUXTAL			115	ms	005, 025, 050, 090, and 150 devices
				126	ms	010 devices

### 2.3.20 On-Chip Oscillator

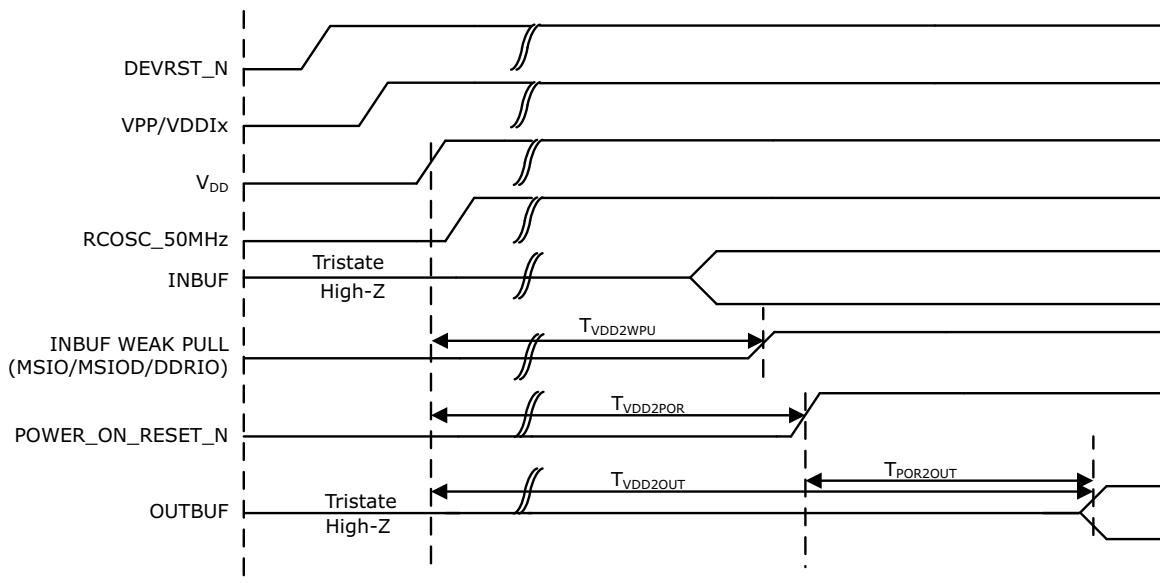
The following tables describe the electrical characteristics of the available on-chip oscillators in the IGLOO2 FPGAs and SmartFusion2 SoC FPGAs.

**Table 280 • Electrical Characteristics of the 50 MHz RC Oscillator**

Parameter	Symbol	Typ	Max	Unit	Condition
Operating frequency	F50RC	50		MHz	
Accuracy	ACC50RC	1	4	%	050 devices
		1	5	%	005, 025, and 060 devices
		1	6.3	%	090 devices
		1	7.1	%	010 and 150 devices
Output duty cycle	CYC50RC	49–51	46.5–53.5	%	
Output jitter (peak to peak)	JIT50RC				Period Jitter
		200	300	ps	005, 010, 050, and 060 devices
		200	400	ps	150 devices
		300	500	ps	025 and 090 devices
					Cycle-to-Cycle Jitter
		200	300	ps	005 and 050 devices
		320	420	ps	010, 060, and 150 devices
		320	850	ps	025 and 090 devices
Operating current	IDYN50RC	6.5		mA	

**Table 281 • Electrical Characteristics of the 1 MHz RC Oscillator**

Parameter	Symbol	Typ	Max	Unit	Condition
Operating frequency	F1RC	1		MHz	
Accuracy	ACC1RC	1	3	%	005, 010, 025, and 050 devices
		1	4.5	%	060, and 150 devices
		1	5.6	%	090 devices
Output duty cycle	CYC1RC	49–51	46.5–53.5	%	005, 010, 025, 050, 090 and 150 devices
		49–51	46.0–54.0	%	060 devices
Output jitter (peak to peak)	JIT1RC				Period Jitter
		10	20	ns	005, 010, 025, and 050 devices
		10	28	ns	060, 090 and 150 devices
					Cycle-to-Cycle Jitter
		10	20	ns	005, 010, and 050 devices
		10	35	ns	025, 060, and 150 devices
		10	45	ns	090 devices
Operating current	IDYN1RC	0.1		mA	
Startup time	SU1RC	17	$\mu$ s		050, 090, and 150 devices
		18	$\mu$ s		005, 010, and 025 devices

**Figure 18 • Power-up to Functional Timing Diagram for IGLOO2**

### 2.3.25 DEVRST\_N Characteristics

**Table 290 • DEVRST\_N Characteristics for All Devices**

Parameter	Symbol	Max	Unit
DEVRST_N ramp rate	$T_{RAMPDEVRSTN}$	1	us
DEVRST_N cycling rate	$F_{MAXPDEVRSTN}$	100	kHz

### 2.3.26 DEVRST\_N to Functional Times

The following table lists the SmartFusion2 DEVRST\_N to functional times in worst-case industrial conditions when  $T_J = 100^\circ\text{C}$ ,  $V_{DD} = 1.14\text{ V}$ .

**Table 291 • DEVRST\_N to Functional Times for SmartFusion2**

Symbol	From	To	Description	Maximum Power-up to Functional Time for SmartFusion2 (uS)						
				005	010	025	050	060	090	150
$T_{POR2OUT}$	POWER_ON_RESET_N	Output available at I/O	Fabric to output	518	501	527	521	422	419	694
$T_{POR2MSSRST}$	POWER_ON_RESET_N	MSS_RESET_N_M2F	Fabric to MSS	515	497	524	518	417	414	689
$T_{MSSRST2OUT}$	MSS_RESET_N_M2F	Output available at I/O	MSS to output	3.5	3.5	3.5	3.3	4.8	4.8	4.8
$T_{DEVRST2OUT}$	DEVRST_N	Output available at I/O	$V_{DD}$ at its minimum threshold level to output	706	768	715	691	641	635	871

### 2.3.30 SerDes Electrical and Timing AC and DC Characteristics

PCIe is a high-speed, packet-based, point-to-point, low-pin-count, serial interconnect bus. The IGLOO2 and SmartFusion2 SoC FPGAs has up to four hard high-speed serial interface blocks. Each SerDes block contains a PCIe system block. The PCIe system is connected to the SerDes block.

The following table lists the transmitter parameters in worst-case industrial conditions when  $T_J = 100\text{ }^{\circ}\text{C}$ ,  $V_{DD} = 1.14\text{ V}$ .

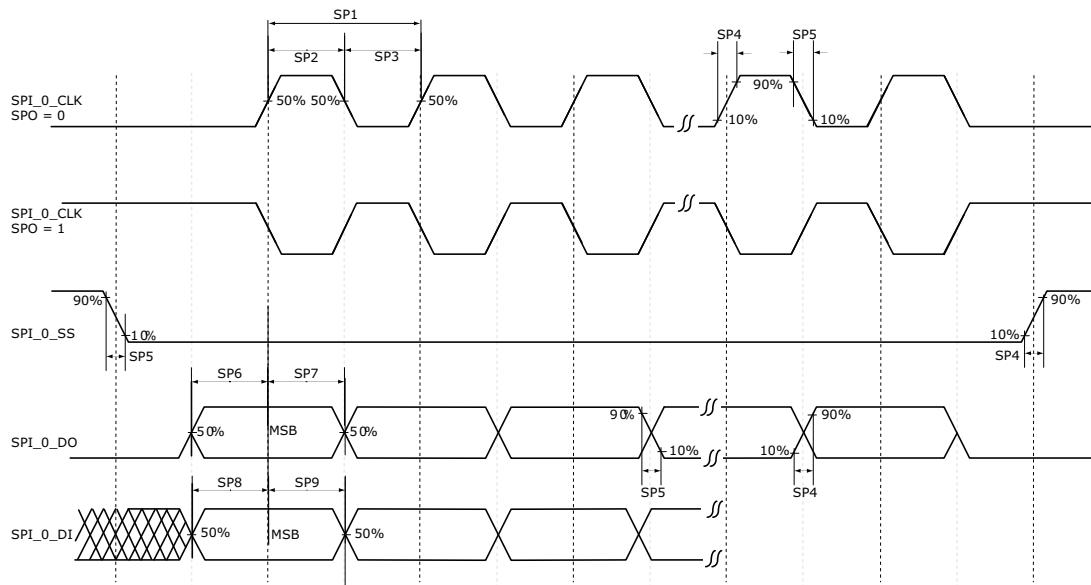
**Table 296 • Transmitter Parameters**

Symbol	Description	Min	Max	Unit
VTX-DIFF-PP	Differential swing (2.5 Gbps, 5.0 Gbps)	0.8	1.2	V
VTX-CM-AC-P	Output common mode voltage (2.5 Gbps)	20		mV
VTX-CM-AC-PP	Output common mode voltage (5.0 Gbps)	100		mV
VTX-RISE-FALL	Rise and fall time (20% to 80%, 2.5 Gbps)	0.125		UI
	Rise and fall time (20% to 80%, 5.0 Gbps)	0.15		UI
ZTX-DIFF-DC	Output impedance–differential	80	120	$\Omega$
LTX-SKEW	Lane-to-lane TX skew within a SerDes block (2.5 Gbps)	500 ps + 2 UI		ps
	Lane-to-lane TX skew within a SerDes block (5.0 Gbps)	500 ps + 4 UI		ps
RLTX-DIFF	Return loss differential mode (2.5 Gbps)	-10		dB
	Return loss differential mode (5.0 Gbps)	-10		dB
	0.05 GHz to 1.25 GHz	-10		dB
	1.25 GHz to 2.5 GHz	-8		dB
RLTX-CM	Return loss common mode (2.5 Gbps, 5.0 Gbps)	-6		dB
TX-LOCK-RST	Transmit PLL lock time from reset	10		$\mu\text{s}$
VTX-AMP	100 mV setting	90	150	mV
	400 mV setting	320	480	mV
	800 mV setting	660	940	mV
	1200 mV setting	950	1400	mV

**Table 305 • SPI Characteristics for All Devices (continued)**

<b>Symbol</b>	<b>Description</b>	<b>Min</b>	<b>Typ</b>	<b>Max</b>	<b>Unit</b>	<b>Conditions</b>
sp5	SPI_[0 1]_CLK, SPI_[0 1]_DO, SPI_[0 1]_SS fall time (10%– 90%) <sup>1</sup>		2.906	ns		IO Configuration: LVC MOS 2.5 V-8 mA AC Loading: 35 pF Test Conditions: Typical Voltage, 25 °C
SPI master configuration (applicable for 005, 010, 025, and 050 devices)						
sp6m	SPI_[0 1]_DO setup time <sup>2</sup>	(SPI_x_CLK_period/2) – 8.0		ns		
sp7m	SPI_[0 1]_DO hold time <sup>2</sup>	(SPI_x_CLK_period/2) – 2.5		ns		
sp8m	SPI_[0 1]_DI setup time <sup>2</sup>	12		ns		
sp9m	SPI_[0 1]_DI hold time <sup>2</sup>	2.5		ns		
SPI slave configuration (applicable for 005, 010, 025, and 050 devices)						
sp6s	SPI_[0 1]_DO setup time <sup>2</sup>	(SPI_x_CLK_period/2) – 17.0		ns		
sp7s	SPI_[0 1]_DO hold time <sup>2</sup>	(SPI_x_CLK_period/2) + 3.0		ns		
sp8s	SPI_[0 1]_DI setup time <sup>2</sup>	2		ns		
sp9s	SPI_[0 1]_DI hold time <sup>2</sup>	7		ns		
SPI master configuration (applicable for 060, 090, and 150 devices)						
sp6m	SPI_[0 1]_DO setup time <sup>2</sup>	(SPI_x_CLK_period/2) – 7.0		ns		
sp7m	SPI_[0 1]_DO hold time <sup>2</sup>	(SPI_x_CLK_period/2) – 9.5		ns		
sp8m	SPI_[0 1]_DI setup time <sup>2</sup>	15		ns		
sp9m	SPI_[0 1]_DI hold time <sup>2</sup>	-2.5		ns		
SPI slave configuration (applicable for 060, 090, and 150 devices)						
sp6s	SPI_[0 1]_DO setup time <sup>2</sup>	(SPI_x_CLK_period/2) – 16.0		ns		
sp7s	SPI_[0 1]_DO hold time <sup>2</sup>	(SPI_x_CLK_period/2) - 3.5		ns		
sp8s	SPI_[0 1]_DI setup time <sup>2</sup>	3		ns		
sp9s	SPI_[0 1]_DI hold time <sup>2</sup>	2.5		ns		

1. For specific Rise/Fall Times board design considerations and detailed output buffer resistances, use the corresponding IBIS models located on the Microsemi SoC Products Group website: <http://www.microsemi.com/soc/download/ibis/default.aspx>.
2. For allowable pclk configurations, see Serial Peripheral Interface Controller section in the *UG0331: SmartFusion2 Microcontroller Subsystem User Guide*.

**Figure 22 • SPI Timing for a Single Frame Transfer in Motorola Mode (SPH = 1)**

### 2.3.32 CAN Controller Characteristics

The following table lists the CAN controller characteristics in worst-case industrial conditions when  $T_J = 100^\circ\text{C}$ ,  $V_{DD} = 1.14\text{ V}$ .

**Table 306 • CAN Controller Characteristics**

Parameter	Description	-1	-Std	Unit
FCANREFCLK <sup>1</sup>	Internally sourced CAN reference clock frequency	160	136	MHz
BAUDCANMAX	Maximum CAN performance baud rate	1	1	Mbps
BAUDCANMIN	Minimum CAN performance baud rate	0.05	0.05	Mbps

1. PCLK to CAN controller must be a multiple of 8 MHz.

### 2.3.33 USB Characteristics

The following table lists the USB characteristics in worst-case industrial conditions when  $T_J = 100^\circ\text{C}$ ,  $V_{DD} = 1.14\text{ V}$ .

**Table 307 • USB Characteristics**

Parameter	Description	-1	-Std	Unit
FUSBREFCLK	Internally sourced USB reference clock frequency	166	142	MHz
TUSBCLK	USB clock period	16.66	16.66	ns
TUSBPD	Clock to USB data propagation delay	9.0	9.0	ns
TUSBSU	Setup time for USB data	6.0	6.0	ns
TUSBHD	Hold time for USB data	0	0	ns