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Embedded - System On Chip (SoC): The Heart of Modern Embedded Systems

Embedded - System On Chip (SoC) refers to an integrated circuit that consolidates all the essential components of a computer system into a single chip. This includes a microprocessor, memory, and other peripherals, all packed into one compact and efficient package. SoCs are designed to provide a complete computing solution, optimizing both space and power consumption, making them ideal for a wide range of embedded applications.

What are Embedded - System On Chip (SoC)?

System On Chip (SoC) integrates multiple functions of a computer or electronic system onto a single chip. Unlike traditional multi-chip solutions, SoCs combine a central

Details

Product Status	Active
Architecture	MCU, FPGA
Core Processor	ARM® Cortex®-M3
Flash Size	256KB
RAM Size	64KB
Peripherals	DDR, PCIe, SERDES
Connectivity	CANbus, Ethernet, I ² C, SPI, UART/USART, USB
Speed	166MHz
Primary Attributes	FPGA - 50K Logic Modules
Operating Temperature	-40°C ~ 100°C (TJ)
Package / Case	325-TFBGA, FCBGA
Supplier Device Package	325-FCBGA (11x11)
Purchase URL	https://www.e-xfl.com/product-detail/microchip-technology/m2s050ts-fcs325i

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2 IGLOO2 FPGA and SmartFusion2 SoC FPGA

Microsemi's mainstream SmartFusion[®]2 SoC and IGLOO[®]2 FPGA families integrate an industry standard 4-input lookup table-based (LUT) FPGA fabric with integrated math blocks, multiple embedded memory blocks, and high-performance SerDes communication interfaces on a single chip. Both families benefit from low-power flash technology and are the most secure and reliable FPGAs in the industry. These next generation devices offer up to 150K Logic Elements, up to 5 MBs of embedded RAM, up to 16 SerDes lanes, and up to four PCI Express Gen 2 endpoints, as well as integrated hard DDR3 memory controllers with error correction.

SmartFusion2 devices integrate an entire low-power, real-time microcontroller subsystem (MSS) with a rich set of industry-standard peripherals including Ethernet, USB, and CAN, while IGLOO2 devices integrate a high-performance memory subsystem with on-chip flash, 32 Kbyte embedded SRAM, and multiple DMA controllers.

2.1 Device Status

The following table shows the design security densities and development status of the IGLOO2 FPGA and SmartFusion2 SoC FPGA devices.

Table 1 • IGLOO2 and SmartFusion2 Design Security Densities

Design Security Device Densities	Status
005	Production
010, 010T	Production
025, 025T	Production
050, 050T	Production
060, 060T	Production
090, 090T	Production
150, 150T	Production

The following table shows the data security densities and development status of the IGLOO2 FPGA and SmartFusion2 SoC FPGA devices.

Table 2 • IGLOO2 and SmartFusion2 Data Security Densities

Data Security Device Densities	Status
005S	Production
010TS	Production
025TS	Production
050TS	Production
060TS	Production
090TS	Production
150TS	Production

Table 9 • Package Thermal Resistance of SmartFusion2 and IGLOO2 Devices (continued)

Device	Still Air	1.0 m/s	2.5 m/s	θ_{JB}	θ_{JC}	Unit
	θ_{JA}					
150						
FC1152	9.08	6.81	5.87	2.56	0.38	°C/W
FCS536	15.01	12.06	10.76	3.69	1.55	°C/W
FCV484	16.21	13.11	11.84	6.73	0.10	°C/W

2.3.1.2.1 Theta-JA

Junction-to-ambient thermal resistance (θ_{JA}) is determined under standard conditions specified by JEDEC (JESD-51), but it has little relevance in the actual performance of the product. It must be used with caution, but it is useful for comparing the thermal performance of one package with another.

The maximum power dissipation allowed is calculated using EQ4.

$$\text{Maximum power allowed} = \frac{T_{J(\text{MAX})} - T_{A(\text{MAX})}}{\theta_{JA}}$$

EQ 4

The absolute maximum junction temperature is 100 °C. EQ5 shows a sample calculation of the absolute maximum power dissipation allowed for the M2GL050T-FG896 package at commercial temperature and in still air, where:

$$\theta_{JA} = 14.7 \text{ °C/W (taken from Table 9, page 10).}$$

$$T_A = 85 \text{ °C}$$

$$\text{Maximum power allowed} = \frac{100 \text{ °C} - 85 \text{ °C}}{14.7 \text{ °C/W}} = 1.088 \text{ W}$$

EQ 5

The power consumption of a device can be calculated using the Microsemi SoC Products Group power calculator. The device's power consumption must be lower than the calculated maximum power dissipation by the package.

If the power consumption is higher than the device's maximum allowable power dissipation, a heat sink may be attached to the top of the case, or the airflow inside the system must be increased.

2.3.1.2.2 Theta-JB

Junction-to-board thermal resistance (θ_{JB}) measures the ability of the package to dissipate heat from the surface of the chip to the PCB. As defined by the JEDEC (JESD-51) standard, the thermal resistance from the junction to the board uses an isothermal ring cold plate zone concept. The ring cold plate is simply a means to generate an isothermal boundary condition at the perimeter. The cold plate is mounted on a JEDEC standard board with a minimum distance of 5.0 mm away from the package edge.

2.3.1.2.3 Theta-JC

Junction-to-case thermal resistance (θ_{JC}) measures the ability of a device to dissipate heat from the surface of the chip to the top or bottom surface of the package. It is applicable to packages used with external heat sinks. Constant temperature is applied to the surface, which acts as a boundary condition.

This only applies to situations where all or nearly all of the heat is dissipated through the surface in consideration.

2.3.1.3 ESD Performance

See *RT0001: Microsemi Corporation - SoC Products Reliability Report* for information about ESD.

Table 15 • Inrush Currents at Power up, $-40\text{ }^{\circ}\text{C} \leq T_J \leq 100\text{ }^{\circ}\text{C}$ – Typical Process

Power Supplies	Voltage (V)	005	010	025	050	060	090	150	Unit
V_{DD}	1.26	25	32	38	48	45	77	109	mA
V_{PP}	3.46	33	49	36	180	13	36	51	mA
V_{DDI}	2.62	134	141	161	187	93	272	388	mA
Number of banks		7	8	8	10	10	9	19	

2.3.3 Average Fabric Temperature and Voltage Derating Factors

The following table lists the average temperature and voltage derating factors for fabric timing delays normalized to $T_J = 85\text{ }^{\circ}\text{C}$, in worst-case $V_{DD} = 1.14\text{ V}$.

Table 16 • Average Junction Temperature and Voltage Derating Factors for Fabric Timing Delays

Array Voltage V_{DD} (V)	$-40\text{ }^{\circ}\text{C}$	$0\text{ }^{\circ}\text{C}$	$25\text{ }^{\circ}\text{C}$	$70\text{ }^{\circ}\text{C}$	$85\text{ }^{\circ}\text{C}$	$100\text{ }^{\circ}\text{C}$
1.14	0.83	0.89	0.92	0.98	1.00	1.02
1.2	0.75	0.80	0.83	0.89	0.91	0.93
1.26	0.69	0.73	0.76	0.81	0.83	0.85

Table 17 • Timing Model Parameters (continued)

Index	Symbol	Description	-1	Unit	For More Information
F	T_{DP}	Propagation delay of an OR gate	0.179	ns	See Table 223, page 76
G	T_{DP}	Propagation delay of an LVDS transmitter	2.136	ns	See Table 169, page 57
H	T_{DP}	Propagation delay of a three-input XOR Gate	0.241	ns	See Table 223, page 76
I	T_{DP}	Propagation delay of LVCMOS 2.5 V transmitter, drive strength of 16 mA on the MSIO bank	2.412	ns	See Table 46, page 27
J	T_{DP}	Propagation delay of a two-input NAND gate	0.179	ns	See Table 223, page 76
K	T_{DP}	Propagation delay of LVCMOS 2.5 V transmitter, drive strength of 8 mA on the MSIO bank	2.309	ns	See Table 46, page 27
L	T_{CLKQ}	Clock-to-Q of the data register	0.108	ns	See Table 224, page 77
	T_{SUD}	Setup time of the data register	0.254	ns	See Table 224, page 77
M	T_{DP}	Propagation delay of a two-input AND gate	0.179	ns	See Table 223, page 76
N	T_{OCLKQ}	Clock-to-Q of the output data register	0.263	ns	See Table 220, page 69
	T_{OSUD}	Setup time of the output data register	0.19	ns	See Table 220, page 69
O	T_{DP}	Propagation delay of SSTL2, Class I transmitter on the MSIO bank	2.055	ns	See Table 114, page 45
P	T_{DP}	Propagation delay of LVCMOS 1.5 V transmitter, drive strength of 12 mA, fast slew on the DDRIO bank	3.316	ns	See Table 70, page 34

Table 43 • LVCMOS 2.5 V AC Test Parameter Specifications

Parameter	Symbol	Typ	Unit
Measuring/trip point for data path	V_{TRIP}	1.2	V
Resistance for enable path (T_{ZH} , T_{ZL} , T_{HZ} , T_{LZ})	R_{ENT}	2K	$\Omega\sigma$
Capacitive loading for enable path (T_{ZH} , T_{ZL} , T_{HZ} , T_{LZ})	C_{ENT}	5	pF
Capacitive loading for data path (T_{DP})	C_{LOAD}	5	pF

Table 44 • LVCMOS 2.5 V Transmitter Drive Strength Specifications

Output Drive Selection			VOH (V)	VOL (V)	IOH (at VOH) mA	IOL (at VOL) mA
MSIO I/O Bank	MSIOD I/O Bank	DDRIO I/O Bank (With Software Default Fixed Code)	Min	Max		
2 mA	2 mA	2 mA	$V_{DDI} - 0.4$	0.4	2	2
4 mA	4 mA	4 mA	$V_{DDI} - 0.4$	0.4	4	4
6 mA	6 mA	6 mA	$V_{DDI} - 0.4$	0.4	6	6
8 mA	8 mA	8 mA	$V_{DDI} - 0.4$	0.4	8	8
12 mA	12 mA	12 mA	$V_{DDI} - 0.4$	0.4	12	12
16 mA		16 mA	$V_{DDI} - 0.4$	0.4	16	16

Note: For board design considerations, output slew rates extraction, detailed output buffer resistances, and I/V Curve, use the corresponding IBIS models located at:
www.microsemi.com/soc/download/ibis/default.aspx.

AC Switching Characteristics

Worst commercial-case conditions: $T_J = 85\text{ }^\circ\text{C}$, $V_{DD} = 1.14\text{ V}$, $V_{DDI} = 2.375\text{ V}$

Table 45 • LVCMOS 2.5 V Receiver Characteristics (Input Buffers)

	On-Die Termination (ODT)	T_{PY}		T_{PYS}		Unit
		-1	-Std	-1	-Std	
LVCMOS 2.5 V (for DDRIO I/O bank)	None	1.823	2.145	1.932	2.274	ns
LVCMOS 2.5 V (for MSIO I/O bank)	None	2.486	2.925	2.495	2.935	ns
LVCMOS 2.5 V (for MSIOD I/O bank)	None	2.29	2.694	2.305	2.712	ns

Table 46 • LVCMOS 2.5 V Transmitter Characteristics for DDRIO Bank (Output and Tristate Buffers)

Output Drive Selection	Slew Control	T_{DP}		T_{ZL}		T_{ZH}		T_{HZ}^1		T_{LZ}^1		Unit
		-1	-Std	-1	-Std	-1	-Std	-1	-Std	-1	-Std	
2 mA	Slow	3.657	4.302	3.393	3.991	3.675	4.323	3.894	4.582	3.552	4.18	ns
	Medium	3.374	3.97	3.139	3.693	3.396	3.995	3.635	4.277	3.253	3.828	ns
	Medium fast	3.239	3.811	3.036	3.572	3.261	3.836	3.519	4.141	3.128	3.681	ns
	Fast	3.224	3.793	3.029	3.563	3.246	3.818	3.512	4.132	3.119	3.67	ns

Table 46 • LVCMOS 2.5 V Transmitter Characteristics for DDRIO Bank (Output and Tristate Buffers)
(continued)

Output Drive Selection	Slew Control	T _{DP}		T _{ZL}		T _{ZH}		T _{HZ} ¹		T _{LZ} ¹		Unit
		-1	-Std	-1	-Std	-1	-Std	-1	-Std	-1	-Std	
4 mA	Slow	3.095	3.641	2.705	3.182	3.088	3.633	4.738	5.575	4.348	5.116	ns
	Medium	2.825	3.324	2.488	2.927	2.823	3.321	4.492	5.285	4.063	4.781	ns
	Medium fast	2.701	3.178	2.384	2.804	2.698	3.173	4.364	5.135	3.945	4.642	ns
	Fast	2.69	3.165	2.377	2.796	2.687	3.161	4.359	5.129	3.94	4.636	ns
6 mA	Slow	2.919	3.434	2.491	2.93	2.902	3.414	5.085	5.983	4.674	5.5	ns
	Medium	2.65	3.118	2.279	2.681	2.642	3.108	4.845	5.701	4.375	5.148	ns
	Medium fast	2.529	2.975	2.176	2.56	2.521	2.965	4.724	5.558	4.259	5.011	ns
	Fast	2.516	2.96	2.168	2.551	2.508	2.95	4.717	5.55	4.251	5.002	ns
8 mA	Slow	2.863	3.368	2.427	2.855	2.844	3.346	5.196	6.114	4.769	5.612	ns
	Medium	2.599	3.058	2.217	2.608	2.59	3.047	4.952	5.827	4.471	5.261	ns
	Medium fast	2.483	2.921	2.114	2.487	2.473	2.91	4.832	5.685	4.364	5.134	ns
	Fast	2.467	2.902	2.106	2.478	2.457	2.89	4.826	5.678	4.348	5.116	ns
12 mA	Slow	2.747	3.232	2.296	2.701	2.724	3.204	5.39	6.342	4.938	5.81	ns
	Medium	2.493	2.934	2.102	2.473	2.483	2.921	5.166	6.078	4.65	5.471	ns
	Medium fast	2.382	2.803	2.006	2.36	2.371	2.789	5.067	5.962	4.546	5.349	ns
	Fast	2.369	2.787	1.999	2.352	2.357	2.773	5.063	5.958	4.538	5.339	ns
16 mA	Slow	2.677	3.149	2.213	2.604	2.649	3.116	5.575	6.56	5.08	5.977	ns
	Medium	2.432	2.862	2.028	2.386	2.421	2.848	5.372	6.32	4.801	5.649	ns
	Medium fast	2.324	2.734	1.937	2.278	2.311	2.718	5.297	6.233	4.7	5.531	ns
	Fast	2.313	2.721	1.929	2.269	2.3	2.706	5.296	6.231	4.699	5.529	ns

1. Delay increases with drive strength are inherent to built-in slew control circuitry for simultaneous switching output (SSO) management.

Table 47 • LVCMOS 2.5 V Transmitter Characteristics for MSIO Bank (Output and Tristate Buffers)

Output Drive Selection	Slew Control	T _{DP}		T _{ZL}		T _{ZH}		T _{HZ} ¹		T _{LZ} ¹		Unit
		-1	-Std	-1	-Std	-1	-Std	-1	-Std	-1	-Std	
2 mA	Slow	3.48	4.095	3.855	4.534	3.785	4.453	2.12	2.494	3.45	4.059	ns
4 mA	Slow	2.583	3.039	3.042	3.579	3.138	3.691	4.143	4.874	4.687	5.513	ns
6 mA	Slow	2.392	2.815	2.669	3.139	2.82	3.317	4.909	5.775	5.083	5.98	ns
8 mA	Slow	2.309	2.717	2.565	3.017	2.74	3.223	5.812	6.837	5.523	6.497	ns
12 mA	Slow	2.333	2.745	2.437	2.867	2.626	3.089	6.131	7.213	5.712	6.72	ns
16 mA	Slow	2.412	2.838	2.335	2.747	2.533	2.979	6.54	7.694	6.007	7.067	ns

1. Delay increases with drive strength are inherent to built-in slew control circuitry for simultaneous switching output (SSO) management.

Table 82 • LVCMOS 1.2 V Receiver Characteristics for MSIOD I/O Bank (Input Buffers)

On-Die Termination (ODT)	T _{Py}		T _{Pys}		Unit
	-1	-Std	-1	-Std	
None	4.154	4.887	4.114	4.84	ns
50	6.918	8.139	6.806	8.008	ns
75	5.613	6.603	5.533	6.509	ns
150	4.716	5.549	4.657	5.479	ns

Table 83 • LVCMOS 1.2 V Transmitter Characteristics for DDRIO I/O Bank (Output and Tristate Buffers)

Output Drive Selection	Slew Control	T _{DP}		T _{ZL}		T _{ZH}		T _{HZ} ¹		T _{LZ} ¹		Unit
		-1	-Std	-1	-Std	-1	-Std	-1	-Std	-1	-Std	
2 mA	Slow	6.713	7.897	5.362	6.308	6.723	7.909	7.233	8.51	6.375	7.499	ns
	Medium	5.912	6.955	4.616	5.43	5.915	6.959	6.887	8.102	6.009	7.069	ns
	Medium fast	5.5	6.469	4.231	4.978	5.5	6.471	6.672	7.849	5.835	6.865	ns
	Fast	5.462	6.426	4.194	4.935	5.463	6.427	6.646	7.819	5.828	6.857	ns
4 mA	Slow	6.109	7.186	4.708	5.539	6.098	7.174	8.005	9.418	7.033	8.274	ns
	Medium	5.355	6.299	4.034	4.746	5.338	6.28	7.637	8.985	6.672	7.849	ns
	Medium fast	4.953	5.826	3.685	4.336	4.932	5.802	7.44	8.752	6.499	7.646	ns
	Fast	4.911	5.777	3.658	4.303	4.89	5.754	7.427	8.737	6.488	7.632	ns
6 mA	Slow	5.89	6.929	4.506	5.301	5.874	6.911	8.337	9.808	7.315	8.605	ns
	Medium	5.176	6.089	3.862	4.543	5.155	6.065	7.986	9.394	6.943	8.168	ns
	Medium fast	4.792	5.637	3.523	4.145	4.765	5.606	7.808	9.186	6.775	7.97	ns
	Fast	4.754	5.593	3.486	4.101	4.728	5.563	7.777	9.149	6.769	7.963	ns

1. Delay increases with drive strength are inherent to built-in slew control circuitry for simultaneous switching output (SSO) management.

Table 84 • LVCMOS 1.2 V Transmitter Characteristics for MSIO I/O Bank (Output and Tristate Buffers)

Output Drive Selection	Slew Control	T _{DP}		T _{ZL}		T _{ZH}		T _{HZ} ¹		T _{LZ} ¹		Unit
		-1	-Std	-1	-Std	-1	-Std	-1	-Std	-1	-Std	
2 mA	Slow	6.746	7.937	7.458	8.774	8.172	9.614	9.867	11.608	8.393	9.874	ns
4 mA	Slow	7.068	8.315	6.678	7.857	7.474	8.793	10.986	12.924	9.043	10.638	ns

1. Delay increases with drive strength are inherent to built-in slew control circuitry for simultaneous switching output (SSO) management.

AC Switching Characteristics

Worst commercial-case conditions: $T_J = 85\text{ }^\circ\text{C}$, $V_{DD} = 1.14\text{ V}$, $V_{DDI} = 2.375\text{ V}$.

Table 180 • B-LVDS AC Switching Characteristics for Receiver for MSIO I/O Bank (Input Buffers)

On-Die Termination (ODT)	T_{PY}		Unit
	-1	-Std	
None	2.738	3.221	ns
100	2.735	3.218	ns

Table 181 • B-LVDS AC Switching Characteristics for Receiver for MSIOD I/O Bank (Input Buffers)

On-Die Termination (ODT)	T_{PY}		Unit
	-1	-Std	
None	2.495	2.934	ns
100	2.495	2.935	ns

Table 182 • B-LVDS AC Switching Characteristics for Transmitter (for MSIO I/O Bank - Output and Tristate Buffers)

T_{DP}		T_{ZL}		T_{ZH}		T_{HZ}		T_{LZ}		Unit
-1	-Std	-1	-Std	-1	-Std	-1	-Std	-1	-Std	
2.258	2.656	2.343	2.756	2.329	2.74	2.12	2.494	2.123	2.497	ns

2.3.7.3 M-LVDS

M-LVDS specifications extend the existing LVDS standard to high-performance multipoint bus applications. Multidrop and multipoint bus configurations may contain any combination of drivers, receivers, and transceivers.

Minimum and Maximum Input and Output Levels

Table 183 • M-LVDS Recommended DC Operating Conditions

Parameter	Symbol	Min	Typ	Max	Unit
Supply voltage ¹	V_{DDI}	2.375	2.5	2.625	V

1. Only M-LVDS TYPE I is supported.

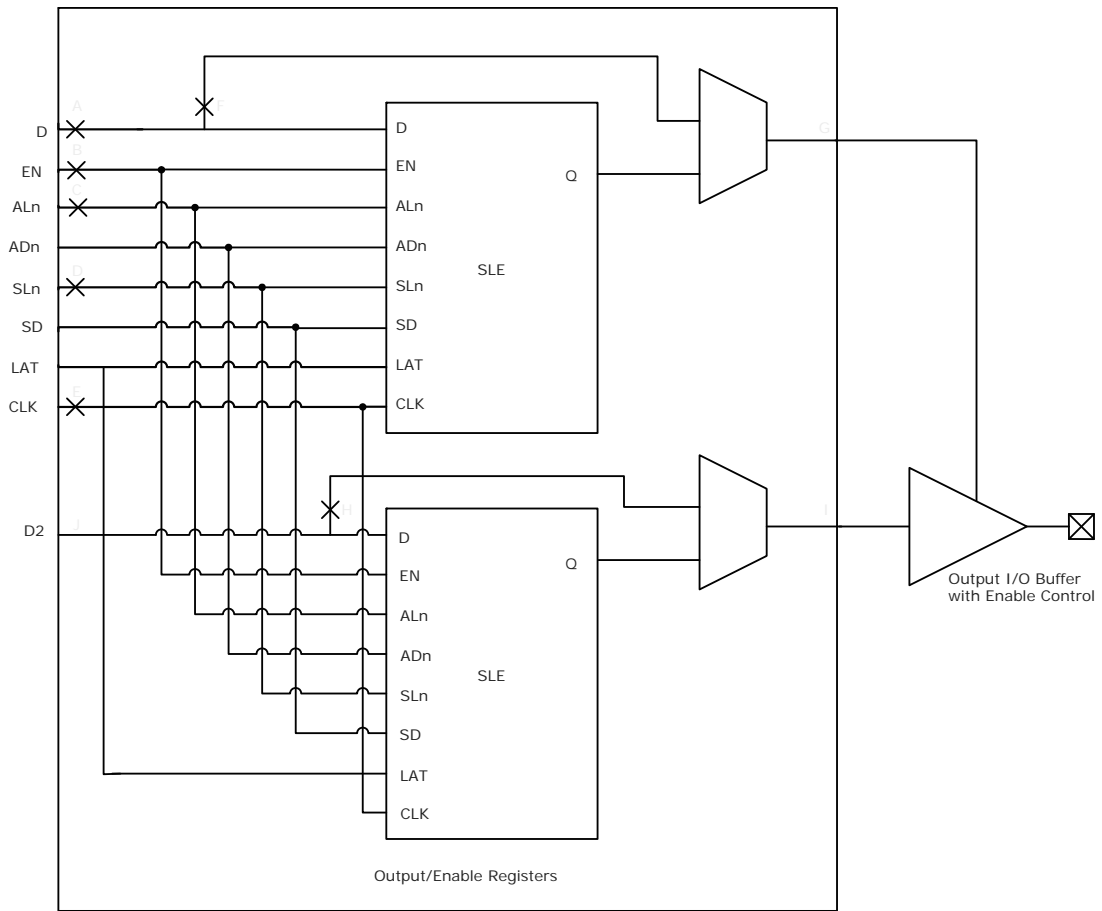
Table 184 • M-LVDS DC Input Voltage Specification

Parameter	Symbol	Min	Max	Unit
DC input voltage	V_I	0	2.925	V
Input current high ¹	I_{IH} (DC)			
Input current low ²	I_{IL} (DC)			

1. See Table 24, page 22.

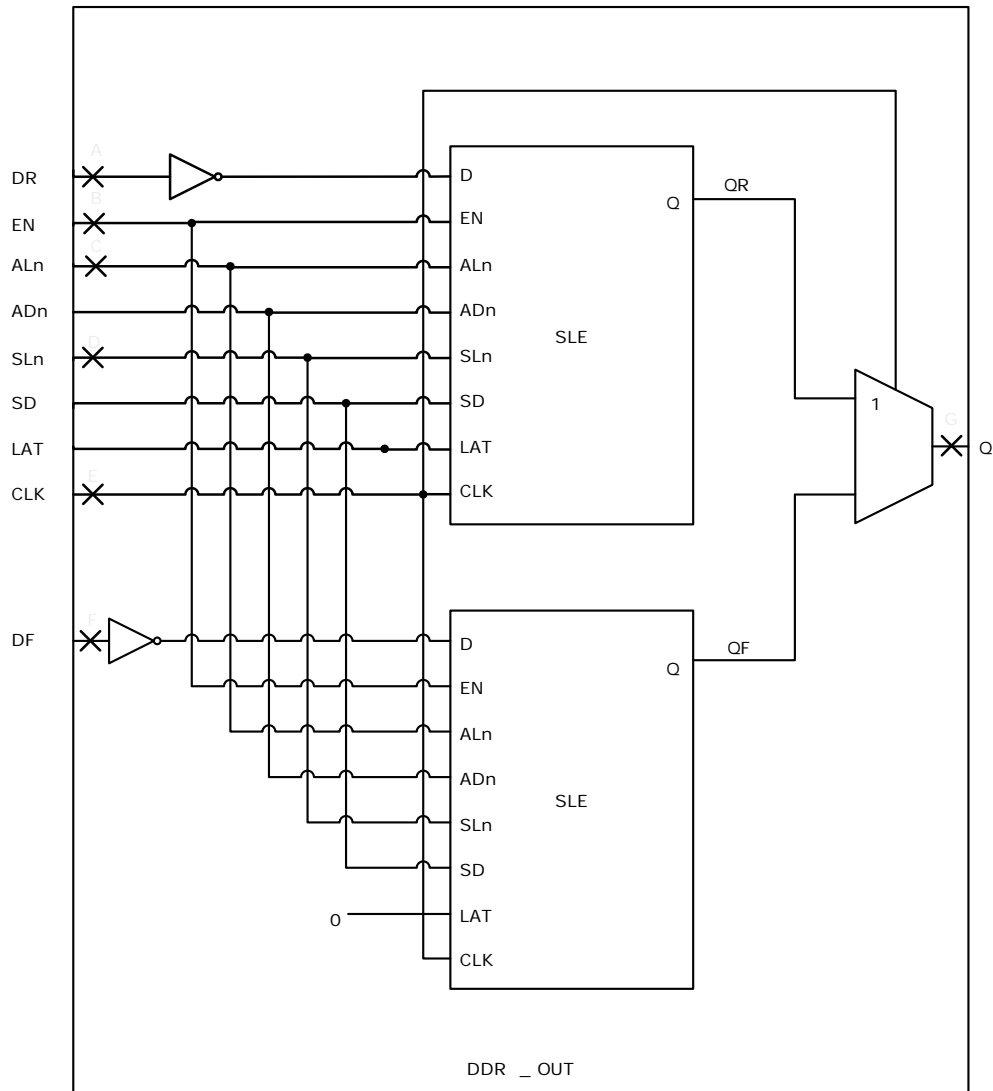
2.3.8.2 Output/Enable Register

Figure 8 • Timing Model for Output/Enable Register



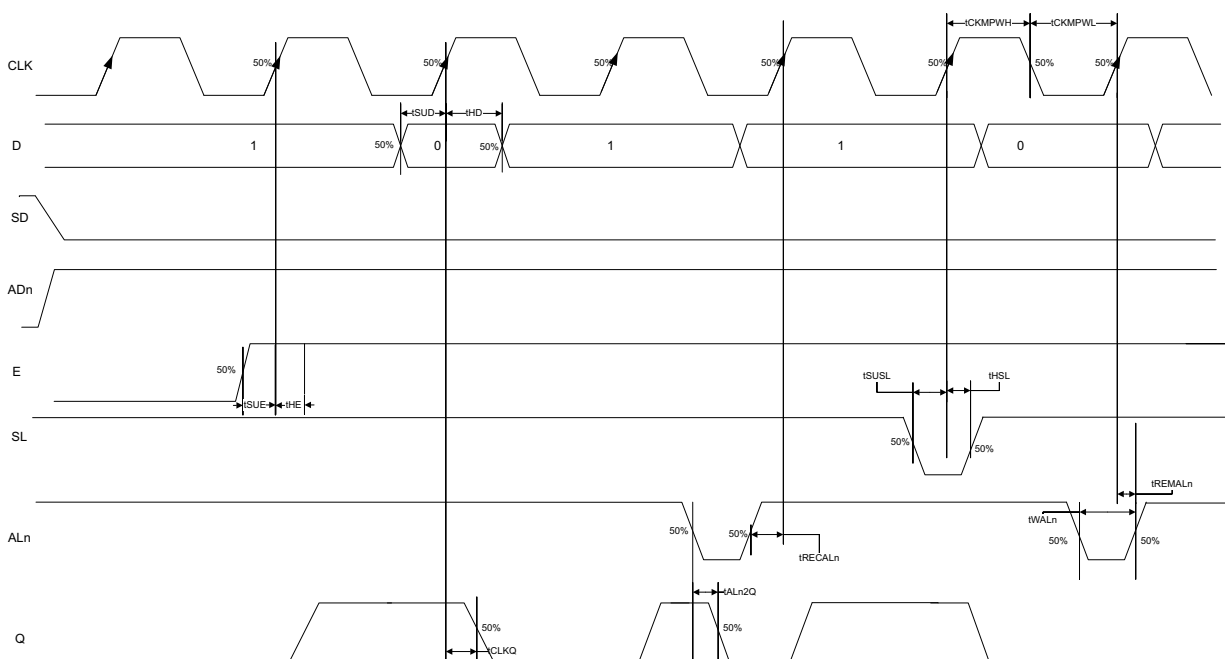
2.3.9.4 Output DDR Module

Figure 12 • Output DDR Module



The following figure shows a configuration with SD = 0 (synchronous clear) and ADn = 1 (asynchronous clear) for a flip-flop (LAT = 0).

Figure 16 • Sequential Module Timing Diagram



2.3.10.3.1 Timing Characteristics

The following table lists the register delays in worst commercial-case conditions when $T_J = 85^\circ\text{C}$, $V_{DD} = 1.14\text{ V}$.

Table 224 • Register Delays

Parameter	Symbol	-1	-Std	Unit
Clock-to-Q of the core register	T_{CLKQ}	0.108	0.127	ns
Data setup time for the core register	T_{SUD}	0.254	0.298	ns
Data hold time for the core register	T_{HD}	0	0	ns
Enable setup time for the core register	T_{SUE}	0.335	0.394	ns
Enable hold time for the core register	T_{HE}	0	0	ns
Synchronous load setup time for the core register	T_{SUSL}	0.335	0.394	ns
Synchronous load hold time for the core register	T_{HSL}	0	0	ns
Asynchronous Clear-to-Q of the core register (ADn = 1)	T_{ALN2Q}	0.473	0.556	ns
Asynchronous preset-to-Q of the core register (ADn = 0)		0.451	0.531	ns
Asynchronous load removal time for the core register	T_{RECALN}	0	0	ns
Asynchronous load recovery time for the core register	T_{RECALN}	0.353	0.415	ns
Asynchronous load minimum pulse width for the core register	T_{WALN}	0.266	0.313	ns
Clock minimum pulse width high for the core register	T_{CKMPWH}	0.065	0.077	ns
Clock minimum pulse width low for the core register	T_{CKMPWL}	0.139	0.164	ns

Table 232 • RAM1K18 – Dual-Port Mode for Depth × Width Configuration 2K × 9 (continued)

Parameter	Symbol	–1		–Std		Unit
		Min	Max	Min	Max	
Address setup time	T_{ADDRSU}	0.475		0.559		ns
Address hold time	T_{ADDRHD}	0.274		0.322		ns
Data setup time	T_{DSU}	0.336		0.395		ns
Data hold time	T_{DHD}	0.082		0.096		ns
Block select setup time	T_{BLKSU}	0.207		0.244		ns
Block select hold time	T_{BLKHD}	0.216		0.254		ns
Block select to out disable time (when pipelined register is disabled)	T_{BLK2Q}		1.529		1.799	ns
Block select minimum pulse width	T_{BLKMPW}	0.186		0.219		ns
Read enable setup time	T_{RDESU}	0.485		0.57		ns
Read enable hold time	T_{RDEHD}	0.071		0.083		ns
Pipelined read enable setup time (A_DOUT_EN, B_DOUT_EN)	$T_{RDPLESU}$	0.248		0.291		ns
Pipelined read enable hold time (A_DOUT_EN, B_DOUT_EN)	$T_{RDPLEHD}$	0.102		0.12		ns
Asynchronous reset to output propagation delay	T_{R2Q}		1.514		1.781	ns
Asynchronous reset removal time	T_{RSTREM}	0.506		0.595		ns
Asynchronous reset recovery time	T_{RSTREC}	0.004		0.005		ns
Asynchronous reset minimum pulse width	T_{RSTMPW}	0.301		0.354		ns
Pipelined register asynchronous reset removal time	$T_{PLRSTREM}$	–0.279		–0.328		ns
Pipelined register asynchronous reset recovery time	$T_{PLRSTREC}$	0.327		0.385		ns
Pipelined register asynchronous reset minimum pulse width	$T_{PLRSTMPW}$	0.282		0.332		ns
Synchronous reset setup time	T_{SRSTSU}	0.226		0.265		ns
Synchronous reset hold time	T_{SRSTHD}	0.036		0.043		ns
Write enable setup time	T_{WESU}	0.415		0.488		ns
Write enable hold time	T_{WEHD}	0.048		0.057		ns
Maximum frequency	F_{MAX}		400		340	MHz

The following table lists the RAM1K18 – dual-port mode for depth × width configuration 4K × 4 in worst commercial-case conditions when $T_J = 85\text{ }^\circ\text{C}$, $V_{DD} = 1.14\text{ V}$.

Table 233 • RAM1K18 – Dual-Port Mode for Depth × Width Configuration 4K × 4

Parameter	Symbol	–1		–Std		Unit
		Min	Max	Min	Max	
Clock period	T_{CY}	2.5		2.941		ns
Clock minimum pulse width high	$T_{CLKMPWH}$	1.125		1.323		ns
Clock minimum pulse width low	$T_{CLKMPWL}$	1.125		1.323		ns
Pipelined clock period	T_{PLCY}	2.5		2.941		ns
Pipelined clock minimum pulse width high	$T_{PLCLKMPWH}$	1.125		1.323		ns

The following table lists the RAM1K18 – dual-port mode for depth × width configuration 16K × 1 in worst commercial-case conditions when $T_J = 85\text{ }^\circ\text{C}$, $V_{DD} = 1.14\text{ V}$.

Table 235 • RAM1K18 – Dual-Port Mode for Depth × Width Configuration 16K × 1

Parameter	Symbol	–1		–Std		Unit
		Min	Max	Min	Max	
Clock period	T_{CY}	2.5		2.941		ns
Clock minimum pulse width high	$T_{CLKMPWH}$	1.125		1.323		ns
Clock minimum pulse width low	$T_{CLKMPWL}$	1.125		1.323		ns
Pipelined clock period	T_{PLCY}	2.5		2.941		ns
Pipelined clock minimum pulse width high	$T_{PLCLKMPWH}$	1.125		1.323		ns
Pipelined clock minimum pulse width low	$T_{PLCLKMPWL}$	1.125		1.323		ns
Read access time with pipeline register			0.32		0.377	ns
Read access time without pipeline register	T_{CLK2Q}		2.269		2.669	ns
Access time with feed-through write timing			1.51		1.777	ns
Address setup time	T_{ADDRSU}	0.626		0.737		ns
Address hold time	T_{ADDRHD}	0.274		0.322		ns
Data setup time	T_{DSU}	0.322		0.378		ns
Data hold time	T_{DHD}	0.082		0.096		ns
Block select setup time	T_{BLKSU}	0.207		0.244		ns
Block select hold time	T_{BLKHD}	0.216		0.254		ns
Block select to out disable time (when pipelined register is disabled)	T_{BLK2Q}		1.51		1.777	ns
Block select minimum pulse width	T_{BLKMPW}	0.186		0.219		ns
Read enable setup time	T_{RDESU}	0.53		0.624		ns
Read enable hold time	T_{RDEHD}	0.071		0.083		ns
Pipelined read enable setup time (A_DOUT_EN, B_DOUT_EN)	$T_{RDPLESU}$	0.248		0.291		ns
Pipelined read enable hold time (A_DOUT_EN, B_DOUT_EN)	$T_{RDPLEHD}$	0.102		0.12		ns
Asynchronous reset to output propagation delay	T_{R2Q}		1.547		1.82	ns
Asynchronous reset removal time	T_{RSTREM}	0.506		0.595		ns
Asynchronous reset recovery time	T_{RSTREC}	0.004		0.005		ns
Asynchronous reset minimum pulse width	T_{RSTMPW}	0.301		0.354		ns
Pipelined register asynchronous reset removal time	$T_{PLRSTREM}$	–0.279		–0.328		ns
Pipelined register asynchronous reset recovery time	$T_{PLRSTREC}$	0.327		0.385		ns
Pipelined register asynchronous reset minimum pulse width	$T_{PLRSTMPW}$	0.282		0.332		ns
Synchronous reset setup time	T_{SRSTSU}	0.226		0.265		ns
Synchronous reset hold time	T_{SRSTHD}	0.036		0.043		ns
Write enable setup time	T_{WESU}	0.454		0.534		ns
Write enable hold time	T_{WEHD}	0.048		0.057		ns
Maximum frequency	F_{MAX}		400		340	MHz

Table 239 • μ SRAM (RAM128x9) in 128 × 9 Mode (continued)

Parameter	Symbol	-1		-Std		Unit
		Min	Max	Min	Max	
Read asynchronous reset removal time (pipelined clock)		-0.023		-0.027		ns
Read asynchronous reset removal time (non-pipelined clock)	T_{RSTREM}	0.046		0.054		ns
Read asynchronous reset recovery time (pipelined clock)		0.507		0.597		ns
Read asynchronous reset recovery time (non-pipelined clock)	T_{RSTREC}	0.236		0.278		ns
Read asynchronous reset to output propagation delay (with pipelined register enabled)	T_{R2Q}		0.835		0.982	ns
Read synchronous reset setup time	T_{SRSTSU}	0.271		0.319		ns
Read synchronous reset hold time	T_{SRSTHD}	0.061		0.071		ns
Write clock period	T_{CCY}	4		4		ns
Write clock minimum pulse width high	$T_{CCLKMPWH}$	1.8		1.8		ns
Write clock minimum pulse width low	$T_{CCLKMPWL}$	1.8		1.8		ns
Write block setup time	T_{BLKCSU}	0.404		0.476		ns
Write block hold time	T_{BLKCHD}	0.007		0.008		ns
Write input data setup time	T_{DINCSU}	0.115		0.135		ns
Write input data hold time	T_{DINCHD}	0.15		0.177		ns
Write address setup time	$T_{ADDRCSU}$	0.088		0.104		ns
Write address hold time	$T_{ADDRCHD}$	0.128		0.15		ns
Write enable setup time	T_{WECSU}	0.397		0.467		ns
Write enable hold time	T_{WECHD}	-0.026		-0.03		ns
Maximum frequency	F_{MAX}		250		250	MHz

The following table lists the μ SRAM in 128 × 8 mode in worst commercial-case conditions when $T_J = 85^\circ\text{C}$, $V_{DD} = 1.14\text{ V}$.

Table 240 • μ SRAM (RAM128x8) in 128 × 8 Mode

Parameter	Symbol	-1		-Std		Unit
		Min	Max	Min	Max	
Read clock period	T_{CY}	4		4		ns
Read clock minimum pulse width high	$T_{CLKMPWH}$	1.8		1.8		ns
Read clock minimum pulse width low	$T_{CLKMPWL}$	1.8		1.8		ns
Read pipeline clock period	T_{PLCY}	4		4		ns
Read pipeline clock minimum pulse width high	$T_{PLCLKMPWH}$	1.8		1.8		ns
Read pipeline clock minimum pulse width low	$T_{PLCLKMPWL}$	1.8		1.8		ns
Read access time with pipeline register			0.266		0.313	ns
Read access time without pipeline register	T_{CLK2Q}		1.677		1.973	ns
Read address setup time in synchronous mode		0.301		0.354		ns
Read address setup time in asynchronous mode	T_{ADDRSU}	1.856		2.184		ns

Table 265 • Programming Times with 100 kHz, 25 MHz, and 12.5 MHz SPI Clock Rates (Fabric Only)

M2S/M2GL Device	Auto Programming			Unit
	100 kHz	25 MHz	12.5 MHz	
005	69	49	50	Sec
010	99	57	57	Sec
025	150	64	63	Sec
050	55 ¹	Not Supported	Not Supported	Sec
060	313	105	104	Sec
090	449	131	130	Sec
150	730	179	183	Sec

1. Auto programming in 050 device is done through SC_SPI, and SPI CLK is set to 6.25 MHz.

Table 266 • Programming Times with 100 kHz, 25 MHz, and 12.5 MHz SPI Clock Rates (eNVM Only)

M2S/M2GL Device	Auto Programming			Unit
	100 kHz	25 MHz	12.5 MHz	
005	63	70	71	Sec
010	108	109	109	Sec
025	109	107	108	Sec
050	107	Not Supported	Not Supported	Sec
060	100	108	108	Sec
090	176	184	184	Sec
150	183	183	183	Sec

Table 267 • Programming Times with 100 kHz, 25 MHz, and 12.5 MHz SPI Clock Rates (Fabric and eNVM)

M2S/M2GL Device	Auto Programming			Unit
	100 kHz	25 MHz	12.5 MHz	
005	109	89	88	Sec
010	183	135	135	Sec
025	251	142	143	Sec
050	134	Not Supported	Not Supported	Sec
060	390	183	180	Sec
090	604	283	282	Sec
150	889	331	332	Sec

Table 276 • Cryptographic Block Characteristics (continued)

Service	Conditions	Timing	Unit
SHA256	512 bits	540	kbps
	1024 bits	780	kbps
	2048 bits	950	kbps
	24 kbits	1140	kbps
HMAC	512 bytes	820	kbps
	1024 bytes	890	kbps
	2048 bytes	930	kbps
	24 kbytes	980	kbps
KeyTree		1.8	ms
Challenge-response	PUF = OFF	25	ms
	PUF = ON	7	ms
ECC point multiplication		590	ms
ECC point addition		8	ms

1. Using cypher block chaining (CBC) mode.

2.3.19 Crystal Oscillator

The following table describes the electrical characteristics of the crystal oscillator in the IGLOO2 FPGA and SmartFusion2 SoC FPGAs.

Table 277 • Electrical Characteristics of the Crystal Oscillator – High Gain Mode (20 MHz)

Parameter	Symbol	Min	Typ	Max	Unit	Condition
Operating frequency	FXTAL		20		MHz	
Accuracy	ACCXTAL			0.0047	%	005, 010, 025, 050, 060, and 090 devices
				0.0058	%	150 devices
Output duty cycle	CYCXTAL		49–51	47–53	%	
Output period jitter (peak to peak)	JITPERXTAL		200	300	ps	
Output cycle to cycle jitter (peak to peak)	JITCYCXTAL		200	300	ps	010, 025, 050, and 060 devices
			250	410	ps	150 devices
			250	550	ps	005 and 090 devices
Operating current	IDYNXTAL		1.5		mA	010, 050, and 060 devices
			1.65		mA	005, 025, 090, and 150 devices
Input logic level high	VIHXTAL	0.9 V _{PP}			V	
Input logic level low	VILXTAL			0.1 V _{PP}	V	

The following table lists the system controller characteristics in worst-case industrial conditions when $T_J = 100\text{ }^\circ\text{C}$, $V_{DD} = 1.14\text{ V}$.

Table 286 • System Controller SPI Characteristics for All Devices

Symbol	Description	Conditions	Min	Typ	Unit
sp1	SC_SPI_SCK minimum period		20		ns
sp2	SC_SPI_SCK minimum pulse width high		10		ns
sp3	SC_SPI_SCK minimum pulse width low		10		ns
sp4 ¹	SC_SPI_SCK, SC_SPI_SDO, SC_SPI_SS rise time (10%–90%) 1	I/O configuration: LVTTTL 3.3 V–20 mA AC loading: 35 pF Test conditions: Typical voltage, 25 °C		1.239	ns
sp5 ¹	SC_SPI_SCK, SC_SPI_SDO, SC_SPI_SS fall time (10%–90%) 1	I/O configuration: LVTTTL 3.3 V–20 mA AC loading: 35 pF Test conditions: Typical voltage, 25 °C		1.245	ns
sp6	Data from master (SC_SPI_SDO) setup time		160		ns
sp7	Data from master (SC_SPI_SDO) hold time		160		ns
sp8	SC_SPI_SDI setup time		20		ns
sp9	SC_SPI_SDI hold time		20		ns

- For specific Rise/Fall Times, board design considerations and detailed output buffer resistances, use the corresponding IBIS models located on the Microsemi SoC Products Group website: <http://www.microsemi.com/soc/download/ibis/default.aspx>. Use the supported I/O Configurations for the System Controller SPI in the following table.

Table 287 • Supported I/O Configurations for System Controller SPI (for MSIO Bank Only)

Voltage Supply	I/O Drive Configuration	Unit
3.3 V	20	mA
2.5 V	16	mA
1.8 V	12	mA
1.5 V	8	mA
1.2 V	4	mA

2.3.30 SerDes Electrical and Timing AC and DC Characteristics

PCIe is a high-speed, packet-based, point-to-point, low-pin-count, serial interconnect bus. The IGLOO2 and SmartFusion2 SoC FPGAs has up to four hard high-speed serial interface blocks. Each SerDes block contains a PCIe system block. The PCIe system is connected to the SerDes block.

The following table lists the transmitter parameters in worst-case industrial conditions when $T_J = 100\text{ }^\circ\text{C}$, $V_{DD} = 1.14\text{ V}$.

Table 296 • Transmitter Parameters

Symbol	Description	Min	Max	Unit
VTX-DIFF-PP	Differential swing (2.5 Gbps, 5.0 Gbps)	0.8	1.2	V
VTX-CM-AC-P	Output common mode voltage (2.5 Gbps)		20	mV
VTX-CM-AC-PP	Output common mode voltage (5.0 Gbps)		100	mV
VTX-RISE-FALL	Rise and fall time (20% to 80%, 2.5 Gbps)	0.125		UI
	Rise and fall time (20% to 80%, 5.0 Gbps)	0.15		UI
ZTX-DIFF-DC	Output impedance–differential	80	120	Ω
LTX-SKEW	Lane-to-lane TX skew within a SerDes block (2.5 Gbps)		500 ps + 2 UI	ps
	Lane-to-lane TX skew within a SerDes block (5.0 Gbps)		500 ps + 4 UI	ps
RLTX-DIFF	Return loss differential mode (2.5 Gbps)	–10		dB
	Return loss differential mode (5.0 Gbps) 0.05 GHz to 1.25 GHz	–10		dB
	1.25 GHz to 2.5 GHz	–8		dB
RLTX-CM	Return loss common mode (2.5 Gbps, 5.0 Gbps)	–6		dB
TX-LOCK-RST	Transmit PLL lock time from reset		10	μs
VTX-AMP	100 mV setting	90	150	mV
	400 mV setting	320	480	mV
	800 mV setting	660	940	mV
	1200 mV setting	950	1400	mV