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Embedded - System On Chip (SoC): The Heart of Modern Embedded Systems

Embedded - System On Chip (SoC) refers to an integrated circuit that consolidates all the essential components of a computer system into a single chip. This includes a microprocessor, memory, and other peripherals, all packed into one compact and efficient package. SoCs are designed to provide a complete computing solution, optimizing both space and power consumption, making them ideal for a wide range of embedded applications.

What are Embedded - System On Chip (SoC)?

System On Chip (SoC) integrates multiple functions of a computer or electronic system onto a single chip. Unlike traditional multi-chip solutions, SoCs combine a central

Details

| | |
|-------------------------|---|
| Product Status | Active |
| Architecture | MCU, FPGA |
| Core Processor | ARM® Cortex®-M3 |
| Flash Size | 256KB |
| RAM Size | 64KB |
| Peripherals | DDR, PCIe, SERDES |
| Connectivity | CANbus, Ethernet, I ² C, SPI, UART/USART, USB |
| Speed | 166MHz |
| Primary Attributes | FPGA - 60K Logic Modules |
| Operating Temperature | -40°C ~ 100°C (Tj) |
| Package / Case | 325-TFBGA, FCBGA |
| Supplier Device Package | 325-FCBGA (11x11) |
| Purchase URL | https://www.e-xfl.com/product-detail/microchip-technology/m2s060-fcsg325i |

1.9 Revision 3.0

In revision 3.0 of this document, the Theta B/C columns and FCS325 package was updated. For more information, see Table 9, page 10 (SAR 62002).

1.10 Revision 2.0

The following is a summary of the changes in revision 2.0 of this document.

- Table 1, page 4 was updated (SAR 59056).
- Table 7, page 8 temperature and data retention information was updated SAR (61363).
- Storage Operating Table was updated and split into three tables – Table 5, page 7, Table 7, page 8 (SAR 58725).
- Updated Theta B/C columns and FCS325 package in Table 9, page 10 (SAR 62002).
- Added 090-FCS325 thermal resistance to Table 9, page 10 (SAR 59384).
- TQ144 package was added to Table 9, page 10 (SAR 57708).
- Added PLL jitter data for the VF400 package (SAR 53162).
- Added Additional Worst Case IDD to Table 11, page 12 and Table 12, page 13 (SAR 59077).
- Table 13, page 13, Table 14, page 13, and Table 15, page 14 were added to verify Inrush currents (SAR 56348).
- Table 18, page 19 and Table 21, page 20 – I/O speeds were replaced.
- Max speed was changed in Table 41, page 26 (SAR 57221) and in Table 52, page 29 (SAR 57113).
- Minimum and Maximum DC/AC Input and Output Levels Specification, page 29 and Table 49, page 29–Table 57, page 31 were added.
- Added Cload to Table 89, page 39 (SAR 56238).
- Removed "Rs" information in DDR Timing Measurement Table 123, page 47, Table 133, page 49, and Table 144, page 52.
- Updated drive programming for M/B-LVDS outputs (SAR 58154).
- Added an inverter bubble to DDR_IN latch in Figure 10, page 70 (SAR 61418).
- QF waveform in Figure 11, page 71 was updated (SAR 59816).
- uSRAM Write Clock minimum values were updated in Table 237, page 86–Table 243, page 93 (SAR 55236).
- Fixed typo in the 32 kHz Crystal (XTAL) oscillator accuracy data section (SAR 59669).
- The "On-Chip Oscillator" section was split, and the Embedded NVM (eNVM) Characteristics, page 104 was added. Table 277, page 107–Table 281, page 109 were revised.(SARs 57898 and 59669).
- PLL VCP Frequency and conditions were added to Table 282, page 110 (SAR 57416).
- Fixed typo for PLL jitter data in the 100-400 MHz range (SAR 60727).
- Updated FCCC information in Table 282, page 110 and Table 283, page 111 (SAR 60799).
- Device 025 specifications were added to Table 283, page 111 (SAR 51625).
- JTAG Table 284, page 112 was replaced (SAR 51188).
- Flash*Freeze Table 293, page 119 was replaced (SAR 57828).
- Added support for HCSL I/O Standard for SERDES reference clocks in Table 300, page 123 and Table 301, page 123 (SAR 50748).
- Tir and Tif parameters were added to Table 303, page 124 (SAR 52203).
- Speed grade consistency was fixed in tables throughout the datasheet (SAR 50722).
- Added jitter attenuation information (SAR 59405).

1.11 Revision 1.0

The following is a summary of the changes in revision 1.0 of this document.

- The IGLOO2 v2 and the SmartFusion2 v5 datasheets are combined into this single product family datasheet.

Table 34 • LVTTTL/LVCMOS 3.3 V AC Test Parameter Specifications (Applicable to MSIO I/O Bank Only)

| Parameter | Symbol | Typ | Unit |
|--|------------|-----|----------|
| Measuring/trip point for data path | V_{TRIP} | 1.4 | V |
| Resistance for enable path (T_{ZH} , T_{ZL} , T_{HZ} , T_{LZ}) | R_{ENT} | 2K | Ω |
| Capacitive loading for enable path (T_{ZH} , T_{ZL} , T_{HZ} , T_{LZ}) | C_{ENT} | 5 | pF |
| Capacitive loading for data path (T_{DP}) | C_{LOAD} | 5 | pF |

Table 35 • LVTTTL/LVCMOS 3.3 V Transmitter Drive Strength Specifications for MSIO I/O Bank

| Output Drive Selection | V_{OH} (V) | V_{OL} (V) | IOH (at V_{OH}) mA | IOL (at V_{OL}) mA |
|------------------------|-----------------|--------------|-----------------------|-----------------------|
| 2 mA | $V_{DDI} - 0.4$ | 0.4 | 2 | 2 |
| 4 mA | $V_{DDI} - 0.4$ | 0.4 | 4 | 4 |
| 8 mA | $V_{DDI} - 0.4$ | 0.4 | 8 | 8 |
| 12 mA | $V_{DDI} - 0.4$ | 0.4 | 12 | 12 |
| 16 mA | $V_{DDI} - 0.4$ | 0.4 | 16 | 16 |
| 20 mA | $V_{DDI} - 0.4$ | 0.4 | 20 | 20 |

Note: For a detailed I/V curve, use the corresponding IBIS models: www.microsemi.com/soc/download/ibis/default.aspx.

AC Switching Characteristics

Worst commercial-case conditions: $T_J = 85\text{ }^\circ\text{C}$, $V_{DD} = 1.14\text{ V}$, $V_{DDI} = 3.0\text{ V}$

Table 36 • LVTTTL/LVCMOS 3.3 V Receiver Characteristics for MSIO I/O Bank (Input Buffers)

| On-Die Termination (ODT) | T_{PY} | | T_{PYS} | | Unit |
|--------------------------|----------|-------|-----------|-------|------|
| | -1 | -Std | -1 | -Std | |
| None | 2.262 | 2.663 | 2.289 | 2.695 | ns |

Table 37 • LVTTTL/LVCMOS 3.3 V Transmitter Characteristics for MSIO I/O Bank (Output and Tristate Buffers)

| Output Drive Selection | Slew Control | T_{DP} | | T_{ZL} | | T_{ZH} | | T_{HZ}^1 | | T_{LZ}^1 | | Unit |
|------------------------|--------------|----------|-------|----------|-------|----------|-------|------------|-------|------------|-------|------|
| | | -1 | -Std | -1 | -Std | -1 | -Std | -1 | -Std | -1 | -Std | |
| 2 mA | Slow | 3.192 | 3.755 | 3.47 | 4.083 | 2.969 | 3.494 | 1.856 | 2.183 | 3.337 | 3.926 | ns |
| 4 mA | Slow | 2.331 | 2.742 | 2.673 | 3.145 | 2.526 | 2.973 | 3.034 | 3.569 | 4.451 | 5.236 | ns |
| 8 mA | Slow | 2.135 | 2.511 | 2.33 | 2.741 | 2.297 | 2.703 | 4.532 | 5.331 | 4.825 | 5.676 | ns |
| 12 mA | Slow | 2.052 | 2.414 | 2.107 | 2.479 | 2.162 | 2.544 | 5.75 | 6.764 | 5.445 | 6.406 | ns |
| 16 mA | Slow | 2.062 | 2.425 | 2.072 | 2.438 | 2.145 | 2.525 | 5.993 | 7.05 | 5.625 | 6.618 | ns |
| 20 mA | Slow | 2.148 | 2.527 | 1.999 | 2.353 | 2.088 | 2.458 | 6.262 | 7.367 | 5.876 | 6.913 | ns |

1. Delay increases with drive strength are inherent to built-in slew control circuitry for simultaneous switching output (SSO) management.

Table 48 • LVCMOS 2.5 V Transmitter Characteristics for MSIOD Bank (Output and Tristate Buffers)

| Output Drive Selection | Slew Control | T_{DP} | | T_{ZL} | | T_{ZH} | | T_{HZ}^1 | | T_{LZ}^1 | | Unit |
|------------------------|--------------|----------|-------|----------|-------|----------|-------|------------|-------|------------|-------|------|
| | | -1 | -Std | -1 | -Std | -1 | -Std | -1 | -Std | -1 | -Std | |
| 2 mA | Slow | 2.206 | 2.596 | 2.678 | 3.15 | 2.64 | 3.106 | 4.935 | 5.805 | 4.74 | 5.576 | ns |
| 4 mA | Slow | 1.835 | 2.159 | 2.242 | 2.637 | 2.256 | 2.654 | 5.413 | 6.368 | 5.15 | 6.059 | ns |
| 6 mA | Slow | 1.709 | 2.01 | 2.132 | 2.508 | 2.167 | 2.549 | 5.813 | 6.838 | 5.499 | 6.469 | ns |
| 8 mA | Slow | 1.63 | 1.918 | 1.958 | 2.303 | 2.012 | 2.367 | 6.226 | 7.324 | 5.816 | 6.842 | ns |
| 12 mA | Slow | 1.648 | 1.939 | 1.86 | 2.187 | 1.921 | 2.259 | 6.519 | 7.669 | 6.027 | 7.09 | ns |

1. Delay increases with drive strength are inherent to built-in slew control circuitry for simultaneous switching output (SSO) management.

2.3.5.8 1.8 V LVCMOS

LVCMOS 1.8 is a general standard for 1.8 V applications and is supported in IGLOO2 FPGAs and SmartFusion2 SoC FPGAs in compliance to the JEDEC specification JESD8-7A.

Minimum and Maximum DC/AC Input and Output Levels Specification

Table 49 • LVCMOS 1.8 V DC Recommended Operating Conditions

| Parameter | Symbol | Min | Typ | Max | Unit |
|---|-----------|-------|-----|------|------|
| LVCMOS 1.8 V DC Recommended Operating Conditions | | | | | |
| Supply voltage | V_{DDI} | 1.710 | 1.8 | 1.89 | V |

Table 50 • LVCMOS 1.8 V DC Input Voltage Specification

| Parameter | Symbol | Min | Max | Unit |
|---|---------------|-----------------------|-----------------------|------|
| DC input logic high (for MSIOD and DDRIO I/O banks) | V_{IH} (DC) | $0.65 \times V_{DDI}$ | 1.89 | V |
| DC input logic high (for MSIO I/O bank) | V_{IH} (DC) | $0.65 \times V_{DDI}$ | 3.45 | V |
| DC input logic low | V_{IL} (DC) | -0.3 | $0.35 \times V_{DDI}$ | V |
| Input current high ¹ | I_{IH} (DC) | | | - |
| Input current low ¹ | I_{IL} (DC) | | | - |

1. See Table 24, page 22.

Table 51 • LVCMOS 1.8 V DC Output Voltage Specification

| Parameter | Symbol | Min | Max | Unit |
|----------------------|----------|------------------|------|------|
| DC output logic high | V_{OH} | $V_{DDI} - 0.45$ | | V |
| DC output logic low | V_{OL} | | 0.45 | V |

Table 52 • LVCMOS 1.8 V Minimum and Maximum AC Switching Speed

| Parameter | Symbol | Max | Unit | Conditions |
|---|-----------|-----|------|--|
| Maximum data rate (for DDRIO I/O bank) ¹ | D_{MAX} | 400 | Mbps | AC loading: 17 pF load, maximum drive/slew |
| Maximum data rate (for MSIO I/O bank) | D_{MAX} | 295 | Mbps | AC loading: 17 pF load, maximum drive/slew |
| Maximum data rate (for MSIOD I/O bank) ¹ | D_{MAX} | 400 | Mbps | AC loading: 17 pF load, maximum drive/slew |

1. Maximum Data Rate applies for Drive Strength 8 mA and above, All Slews.

Table 57 • LVCMOS 1.8 V Transmitter Characteristics for DDRIO I/O Bank with Fixed Code (Output and Tristate Buffers)

| Output Drive Selection | Slew Control | T _{DP} | | T _{ZL} | | T _{ZH} | | T _{HZ} ¹ | | T _{LZ} ¹ | | Unit |
|------------------------|--------------|-----------------|-------|-----------------|-------|-----------------|-------|------------------------------|-------|------------------------------|-------|------|
| | | -1 | -Std | -1 | -Std | -1 | -Std | -1 | -Std | -1 | -Std | |
| 2 mA | Slow | 4.234 | 4.981 | 3.646 | 4.29 | 4.245 | 4.995 | 4.908 | 5.774 | 4.434 | 5.216 | ns |
| | Medium | 3.824 | 4.498 | 3.282 | 3.861 | 3.834 | 4.511 | 4.625 | 5.441 | 4.116 | 4.843 | ns |
| | Medium fast | 3.627 | 4.267 | 3.111 | 3.66 | 3.637 | 4.279 | 4.481 | 5.272 | 3.984 | 4.687 | ns |
| | Fast | 3.605 | 4.241 | 3.097 | 3.644 | 3.615 | 4.253 | 4.472 | 5.262 | 3.973 | 4.674 | ns |
| 4 mA | Slow | 3.923 | 4.615 | 3.314 | 3.9 | 3.918 | 4.61 | 5.403 | 6.356 | 4.894 | 5.757 | ns |
| | Medium | 3.518 | 4.138 | 2.961 | 3.484 | 3.515 | 4.135 | 5.121 | 6.025 | 4.561 | 5.366 | ns |
| | Medium fast | 3.321 | 3.907 | 2.783 | 3.275 | 3.317 | 3.903 | 4.966 | 5.843 | 4.426 | 5.206 | ns |
| | Fast | 3.301 | 3.883 | 2.77 | 3.259 | 3.296 | 3.878 | 4.957 | 5.831 | 4.417 | 5.196 | ns |
| 6 mA | Slow | 3.71 | 4.364 | 3.104 | 3.652 | 3.702 | 4.355 | 5.62 | 6.612 | 5.08 | 5.977 | ns |
| | Medium | 3.333 | 3.921 | 2.779 | 3.27 | 3.325 | 3.913 | 5.346 | 6.289 | 4.777 | 5.62 | ns |
| | Medium fast | 3.155 | 3.712 | 2.62 | 3.083 | 3.146 | 3.702 | 5.21 | 6.13 | 4.657 | 5.479 | ns |
| | Fast | 3.134 | 3.688 | 2.608 | 3.068 | 3.125 | 3.677 | 5.202 | 6.12 | 4.648 | 5.468 | ns |
| 8 mA | Slow | 3.619 | 4.258 | 3.007 | 3.538 | 3.607 | 4.244 | 5.815 | 6.841 | 5.249 | 6.175 | ns |
| | Medium | 3.246 | 3.819 | 2.686 | 3.16 | 3.236 | 3.807 | 5.542 | 6.52 | 4.936 | 5.807 | ns |
| | Medium fast | 3.066 | 3.607 | 2.525 | 2.971 | 3.054 | 3.593 | 5.405 | 6.359 | 4.811 | 5.66 | ns |
| | Fast | 3.046 | 3.584 | 2.513 | 2.957 | 3.034 | 3.57 | 5.401 | 6.353 | 4.803 | 5.651 | ns |
| 10 mA | Slow | 3.498 | 4.115 | 2.878 | 3.386 | 3.481 | 4.096 | 6.046 | 7.113 | 5.444 | 6.404 | ns |
| | Medium | 3.138 | 3.692 | 2.569 | 3.023 | 3.126 | 3.678 | 5.782 | 6.803 | 5.129 | 6.034 | ns |
| | Medium fast | 2.966 | 3.489 | 2.414 | 2.841 | 2.951 | 3.472 | 5.666 | 6.665 | 5.013 | 5.897 | ns |
| | Fast | 2.945 | 3.464 | 2.401 | 2.826 | 2.93 | 3.448 | 5.659 | 6.658 | 5.003 | 5.886 | ns |
| 12 mA | Slow | 3.417 | 4.02 | 2.807 | 3.303 | 3.401 | 4.002 | 6.083 | 7.156 | 5.464 | 6.428 | ns |
| | Medium | 3.076 | 3.618 | 2.519 | 2.964 | 3.063 | 3.604 | 5.828 | 6.856 | 5.176 | 6.089 | ns |
| | Medium fast | 2.913 | 3.427 | 2.376 | 2.795 | 2.898 | 3.41 | 5.725 | 6.736 | 5.072 | 5.966 | ns |
| | Fast | 2.894 | 3.405 | 2.362 | 2.78 | 2.879 | 3.388 | 5.715 | 6.724 | 5.064 | 5.957 | ns |
| 16 mA | Slow | 3.366 | 3.96 | 2.751 | 3.237 | 3.348 | 3.939 | 6.226 | 7.324 | 5.576 | 6.56 | ns |
| | Medium | 3.03 | 3.565 | 2.47 | 2.906 | 3.017 | 3.55 | 5.981 | 7.036 | 5.282 | 6.214 | ns |
| | Medium fast | 2.87 | 3.377 | 2.328 | 2.739 | 2.854 | 3.358 | 5.895 | 6.935 | 5.18 | 6.094 | ns |
| | Fast | 2.853 | 3.357 | 2.314 | 2.723 | 2.837 | 3.338 | 5.889 | 6.929 | 5.177 | 6.09 | ns |

1. Delay increases with drive strength are inherent to built-in slew control circuitry for simultaneous switching output (SSO) management.

AC Switching Characteristics

Worst commercial-case conditions: $T_J = 85\text{ }^\circ\text{C}$, $V_{DD} = 1.14\text{ V}$, $V_{DDI} = 3.0\text{ V}$

Table 91 • PCI/PCIX AC Switching Characteristics for Receiver for MSIO I/O Bank (Input Buffers)

| On-Die Termination (ODT) | T_{PY} | | T_{PYS} | | Unit |
|--------------------------|----------|-------|-----------|-------|------|
| | -1 | -Std | -1 | -Std | |
| None | 2.229 | 2.623 | 2.238 | 2.633 | ns |

Table 92 • PCI/PCIX AC switching Characteristics for Transmitter for MSIO I/O Bank (Output and Tristate Buffers)

| T_{DP} | | T_{ZL} | | T_{ZH} | | T_{HZ} | | T_{LZ} | | Unit |
|----------|-------|----------|-------|----------|-------|----------|-------|----------|-------|------|
| -1 | -Std | -1 | -Std | -1 | -Std | -1 | -Std | -1 | -Std | |
| 2.146 | 2.525 | 2.043 | 2.404 | 2.084 | 2.452 | 6.095 | 7.171 | 5.558 | 6.539 | ns |

2.3.6 Memory Interface and Voltage Referenced I/O Standards

This section describes High-Speed Transceiver Logic (HSTL) memory interface and voltage reference I/O standards.

2.3.6.1 High-Speed Transceiver Logic (HSTL)

The HSTL standard is a general purpose high-speed bus standard sponsored by IBM (EIA/JESD8-6). IGLOO2 FPGA and SmartFusion2 SoC FPGA devices support two classes of the 1.5 V HSTL. These differential versions of the standard require a differential amplifier input buffer and a push-pull output buffer.

Minimum and Maximum DC/AC Input and Output Levels Specification (Applicable to DDRIO Bank Only)

Table 93 • HSTL Recommended DC Operating Conditions

| Parameter | Symbol | Min | Typ | Max | Unit |
|-------------------------|-----------|-------|-------|-------|------|
| Supply voltage | V_{DDI} | 1.425 | 1.5 | 1.575 | V |
| Termination voltage | V_{TT} | 0.698 | 0.750 | 0.803 | V |
| Input reference voltage | V_{REF} | 0.698 | 0.750 | 0.803 | V |

Table 94 • HSTL DC Input Voltage Specification

| Parameter | Symbol | Min | Max | Unit |
|---------------------------------|---------------|-----------------|-----------------|------|
| DC input logic high | V_{IH} (DC) | $V_{REF} + 0.1$ | 1.575 | V |
| DC input logic low | V_{IL} (DC) | -0.3 | $V_{REF} - 0.1$ | V |
| Input current high ¹ | I_{IH} (DC) | | | |
| Input current low ¹ | I_{IL} (DC) | | | |

1. See Table 24, page 22.

Table 122 • SSTL18 DC Differential Voltage Specification

| Parameter | Symbol | Min | Unit |
|-------------------------------|---------------|-----|------|
| DC input differential voltage | V_{ID} (DC) | 0.3 | V |

Table 123 • SSTL18 AC Differential Voltage Specifications (Applicable to DDRIO Bank Only)

| Parameter | Symbol | Min | Max | Unit |
|-------------------------------------|-----------------|------------------------------|------------------------------|------|
| AC input differential voltage | V_{DIFF} (AC) | 0.5 | | V |
| AC differential cross point voltage | V_x (AC) | $0.5 \times V_{DDI} - 0.175$ | $0.5 \times V_{DDI} + 0.175$ | V |

Table 124 • SSTL18 Minimum and Maximum AC Switching Speed (Applicable to DDRIO Bank Only)

| Parameter | Symbol | Max | Unit | Conditions |
|--|-----------|-----|------|-------------------------------------|
| Maximum data rate (for DDRIO I/O bank) | D_{MAX} | 667 | Mbps | AC loading: per JEDEC specification |

Table 125 • SSTL18 AC Impedance Specifications (Applicable to DDRIO Bank Only)

| Parameter | Symbol | Typ | Unit | Conditions |
|---|-----------|-------------|----------|-----------------------------------|
| Supported output driver calibrated impedance (for DDRIO I/O bank) | R_{REF} | 20, 42 | Ω | Reference resistor = 150 Ω |
| Effective impedance value (ODT) | R_{TT} | 50, 75, 150 | Ω | Reference resistor = 150 Ω |

Table 126 • SSTL18 AC Test Parameter Specifications (Applicable to DDRIO Bank Only)

| Parameter | Symbol | Typ | Unit |
|--|----------------|-----|----------|
| Measuring/trip point for data path | V_{TRIP} | 0.9 | V |
| Resistance for enable path (T_{ZH} , T_{ZL} , T_{HZ} , T_{LZ}) | R_{ENT} | 2K | Ω |
| Capacitive loading for enable path (T_{ZH} , T_{ZL} , T_{HZ} , T_{LZ}) | C_{ENT} | 5 | pF |
| Reference resistance for data test path for SSTL18 Class I (T_{DP}) | R_{TT_TEST} | 50 | Ω |
| Reference resistance for data test path for SSTL18 Class II (T_{DP}) | R_{TT_TEST} | 25 | Ω |
| Capacitive loading for data path (T_{DP}) | C_{LOAD} | 5 | pF |

AC Switching Characteristics

Worst commercial-case conditions: $T_J = 85^\circ\text{C}$, $V_{DD} = 1.14\text{ V}$, $V_{DDI} = 1.71\text{ V}$

Table 127 • DDR2/SSTL18 Receiver Characteristics for DDRIO I/O Bank with Fixed Code

| | On-Die Termination (ODT) | T_{PY} | | Unit |
|---------------------|--------------------------|----------|-------|------|
| | | -1 | -Std | |
| Pseudo differential | None | 1.567 | 1.844 | ns |
| True differential | None | 1.588 | 1.869 | ns |

Table 131 • SSTL15 DC Output Voltage Specification (for DDRIO I/O Bank Only)

| Parameter | Symbol | Min | Max | Unit |
|---|----------------------|----------------------|----------------------|------|
| DDR3/SSTL15 Class I (DDR3 Reduced Drive) | | | | |
| DC output logic high | V_{OH} | $0.8 \times V_{DDI}$ | | V |
| DC output logic low | V_{OL} | | $0.2 \times V_{DDI}$ | V |
| Output minimum source DC current | I_{OH} at V_{OH} | 6.5 | | mA |
| Output minimum sink current | I_{OL} at V_{OL} | -6.5 | | mA |
| DDR3/SSTL15 Class II (DDR3 Full Drive) | | | | |
| DC output logic high | V_{OH} | $0.8 \times V_{DDI}$ | | V |
| DC output logic low | V_{OL} | | $0.2 \times V_{DDI}$ | V |
| Output minimum source DC current | I_{OH} at V_{OH} | 7.6 | | mA |
| Output minimum sink current | I_{OL} at V_{OL} | -7.6 | | mA |

Table 132 • SSTL15 DC Differential Voltage Specification (for DDRIO I/O Bank Only)

| Parameter | Symbol | Min | Unit |
|-------------------------------|----------|-----|------|
| DC input differential voltage | V_{ID} | 0.2 | V |

Note: To meet JEDEC electrical compliance, use DDR3 full drive transmitter.

Table 133 • SSTL15 AC SSTL15 Minimum and Maximum AC Switching Speed (for DDRIO I/O Bank Only)

| Parameter | Symbol | Min | Max | Unit |
|-------------------------------------|-----------------|------------------------------|------------------------------|------|
| AC input differential voltage | V_{DIFF} (AC) | 0.3 | | V |
| AC differential cross point voltage | V_x (AC) | $0.5 \times V_{DDI} - 0.150$ | $0.5 \times V_{DDI} + 0.150$ | V |

Table 134 • SSTL15 Minimum and Maximum AC Switching Speed (for DDRIO I/O Bank Only)

| Parameter | Symbol | Max | Unit | Conditions |
|-------------------|-----------|-----|------|--------------------------------------|
| Maximum data rate | D_{MAX} | 667 | Mbps | AC loading: per JEDEC specifications |

Table 135 • SSTL15 AC Calibrated Impedance Option (for DDRIO I/O Bank Only)

| Parameter | Symbol | Typ | Unit | Conditions |
|--|-----------|---------------------|----------|-----------------------------------|
| Supported output driver calibrated impedance | R_{REF} | 34, 40 | Ω | Reference resistor = 240 Ω |
| Effective impedance value (ODT) | R_{TT} | 20, 30, 40, 60, 120 | Ω | Reference resistor = 240 Ω |

2.3.6.6 Low Power Double Data Rate (LPDDR)

LPDDR reduced and full drive low power double data rate standards are supported in IGLOO2 FPGA and SmartFusion2 SoC FPGA I/Os. This standard requires a differential amplifier input buffer and a push-pull output buffer.

Minimum and Maximum DC/AC Input and Output Levels Specification

Table 139 • LPDDR DC Recommended DC Operating Conditions

| Parameter | Symbol | Min | Typ | Max |
|-------------------------|-----------|-------|-------|-------|
| Supply voltage | V_{DDI} | 1.71 | 1.8 | 1.89 |
| Termination voltage | V_{TT} | 0.838 | 0.900 | 0.964 |
| Input reference voltage | V_{REF} | 0.838 | 0.900 | 0.964 |

Table 140 • LPDDR DC Input Voltage Specification

| Parameter | Symbol | Min | Max |
|---------------------------------|---------------|----------------------|----------------------|
| DC input logic high | V_{IH} (DC) | $0.7 \times V_{DDI}$ | 1.89 |
| DC input logic low | V_{IL} (DC) | -0.3 | $0.3 \times V_{DDI}$ |
| Input current high ¹ | I_{IH} (DC) | | |
| Input current low ¹ | I_{IL} (DC) | | |

1. See Table 24, page 22.

Table 141 • LPDDR DC Output Voltage Specification Reduced Drive

| Parameter | Symbol | Min | Max |
|----------------------------------|----------------------|----------------------|----------------------|
| DC output logic high | V_{OH} | $0.9 \times V_{DDI}$ | |
| DC output logic low | V_{OL} | | $0.1 \times V_{DDI}$ |
| Output minimum source DC current | I_{OH} at V_{OH} | 0.1 | |
| Output minimum sink current | I_{OL} at V_{OL} | -0.1 | |

Table 142 • LPDDR DC Output Voltage Specification Full Drive¹

| Parameter | Symbol | Min | Max |
|----------------------------------|----------------------|----------------------|----------------------|
| DC output logic high | V_{OH} | $0.9 \times V_{DDI}$ | |
| DC output logic low | V_{OL} | | $0.1 \times V_{DDI}$ |
| Output minimum source DC current | I_{OH} at V_{OH} | 0.1 | |
| Output minimum sink current | I_{OL} at V_{OL} | -0.1 | |

1. To meet JEDEC Electrical Compliance, use LPDDR Full Drive Transmitter.

Table 143 • LPDDR DC Differential Voltage Specification

| Parameter | Symbol | Min |
|-------------------------------|---------------|----------------------|
| DC input differential voltage | V_{ID} (DC) | $0.4 \times V_{DDI}$ |

Table 162 • LVDS DC Output Voltage Specification

| Parameter | Symbol | Min | Typ | Max | Unit |
|----------------------|----------|------|-------|------|------|
| DC output logic high | V_{OH} | 1.25 | 1.425 | 1.6 | V |
| DC output logic low | V_{OL} | 0.9 | 1.075 | 1.25 | V |

Table 163 • LVDS DC Differential Voltage Specification

| Parameter | Symbol | Min | Typ | Max | Unit |
|-----------------------------------|-----------|-------|------|-------|------|
| Differential output voltage swing | V_{OD} | 250 | 350 | 450 | mV |
| Output common mode voltage | V_{OCM} | 1.125 | 1.25 | 1.375 | V |
| Input common mode voltage | V_{ICM} | 0.05 | 1.25 | 2.35 | V |
| Input differential voltage | V_{ID} | 100 | 350 | 600 | mV |

Table 164 • LVDS Minimum and Maximum AC Switching Speed

| Parameter | Symbol | Max | Unit | Conditions |
|--|-----------|-----|------|--|
| Maximum data rate (for MSIO I/O bank) | D_{MAX} | 535 | Mbps | AC loading: 12 pF / 100 Ω differential load |
| Maximum data rate (for MSIOD I/O bank) no pre-emphasis | D_{MAX} | 620 | Mbps | AC loading: 10 pF / 100 Ω differential load |
| | | 700 | Mbps | AC loading: 2 pF / 100 Ω differential load |

Table 165 • LVDS AC Impedance Specifications

| Parameter | Symbol | Typ | Max | Unit |
|------------------------|--------|-----|-----|----------|
| Termination resistance | R_T | 100 | | Ω |

Table 166 • LVDS AC Test Parameter Specifications

| Parameter | Symbol | Typ | Unit |
|--|------------|-------------|----------|
| Measuring/trip point for data path | V_{TRIP} | Cross point | V |
| Resistance for enable path (T_{ZH} , T_{ZL} , T_{HZ} , T_{LZ}) | R_{ENT} | 2K | Ω |
| Capacitive loading for enable path (T_{ZH} , T_{ZL} , T_{HZ} , T_{LZ}) | C_{ENT} | 5 | pF |

LVDS25 AC Switching Characteristics

 Worst commercial-case conditions: $T_J = 85^\circ\text{C}$, $V_{DD} = 1.14\text{ V}$, $V_{DDI} = 2.375\text{ V}$
Table 167 • LVDS25 Receiver Characteristics for MSIO I/O Bank (Input Buffers)

| On-Die Termination (ODT) | T_{PY} | | Unit |
|--------------------------|----------|-------|------|
| | -1 | -Std | |
| None | 2.774 | 3.263 | ns |
| 100 | 2.775 | 3.264 | ns |

Table 198 • Mini-LVDS AC Impedance Specifications

| Parameter | Symbol | Typ | Unit |
|------------------------|--------|-----|----------|
| Termination resistance | R_T | 100 | Ω |

Table 199 • Mini-LVDS AC Test Parameter Specifications

| Parameter | Symbol | Typ | Unit |
|--|------------|-------------|----------|
| Measuring/trip point for data path | V_{TRIP} | Cross point | V |
| Resistance for enable path (T_{ZH} , T_{ZL} , T_{HZ} , T_{LZ}) | R_{ENT} | 2K | Ω |
| Capacitive loading for enable path (T_{ZH} , T_{ZL} , T_{HZ} , T_{LZ}) | C_{ENT} | 5 | pF |

AC Switching Characteristics

Worst commercial-case conditions: $T_J = 85\text{ }^\circ\text{C}$, $V_{DD} = 1.14\text{ V}$, $V_{DDI} = 2.375\text{ V}$.

Table 200 • Mini-LVDS AC Switching Characteristics for Receiver (for MSIO I/O Bank - Input Buffers)

| On-Die Termination (ODT) | T_{PY} | | Unit |
|--------------------------|----------|-------|------|
| | -1 | -Std | |
| None | 2.855 | 3.359 | ns |
| 100 | 2.85 | 3.353 | ns |
| None | 2.602 | 3.061 | ns |
| 100 | 2.597 | 3.055 | ns |

Table 201 • Mini-LVDS AC Switching Characteristics for Transmitter for MSIO I/O Bank (Output and Tristate Buffers)

| T_{DP} | | T_{ZL} | | T_{ZH} | | T_{HZ} | | T_{LZ} | | Unit |
|----------|-------|----------|-------|----------|-------|----------|------|----------|-------|------|
| -1 | -Std | -1 | -Std | -1 | -Std | -1 | -Std | -1 | -Std | |
| 2.097 | 2.467 | 2.308 | 2.715 | 2.296 | 2.701 | 1.964 | 2.31 | 1.949 | 2.293 | ns |

Table 202 • Mini-LVDS AC Switching Characteristics for Transmitter (for MSIOD I/O Bank - Output and Tristate Buffers)

| | T_{DP} | | T_{ZL} | | T_{ZH} | | T_{HZ} | | T_{LZ} | | Unit |
|------------------|----------|-------|----------|-------|----------|-------|----------|-------|----------|-------|------|
| | -1 | -Std | -1 | -Std | -1 | -Std | -1 | -Std | -1 | -Std | |
| No pre-emphasis | 1.614 | 1.899 | 1.562 | 1.837 | 1.553 | 1.826 | 1.593 | 1.874 | 1.578 | 1.856 | ns |
| Min pre-emphasis | 1.604 | 1.887 | 1.745 | 2.053 | 1.731 | 2.036 | 1.892 | 2.225 | 1.861 | 2.189 | ns |
| Med pre-emphasis | 1.521 | 1.79 | 1.753 | 2.062 | 1.737 | 2.043 | 1.9 | 2.235 | 1.868 | 2.197 | ns |
| Max pre-emphasis | 1.492 | 1.754 | 1.762 | 2.073 | 1.745 | 2.052 | 1.91 | 2.247 | 1.876 | 2.206 | ns |

2.3.7.5 RSDS

Reduced Swing Differential Signaling (RSDS) is similar to an LVDS high-speed interface using differential signaling. RSDS has a similar implementation to LVDS devices and is only intended for point-to-point applications.

Minimum and Maximum Input and Output Levels

Table 203 • RSDS Recommended DC Operating Conditions

| Parameter | Symbol | Min | Typ | Max | Unit |
|----------------|-----------|-------|-----|-------|------|
| Supply voltage | V_{DDI} | 2.375 | 2.5 | 2.625 | V |

Table 204 • RSDS DC Input Voltage Specification

| Parameter | Symbol | Min | Max | Unit |
|------------------|--------|-----|-------|------|
| DC input voltage | V_I | 0 | 2.925 | V |

Table 205 • RSDS DC Output Voltage Specification

| Parameter | Symbol | Min | Typ | Max | Unit |
|----------------------|----------|------|-------|------|------|
| DC output logic high | V_{OH} | 1.25 | 1.425 | 1.6 | V |
| DC output logic low | V_{OL} | 0.9 | 1.075 | 1.25 | V |

Table 206 • RSDS Differential Voltage Specification

| Parameter | Symbol | Min | Max | Unit |
|-----------------------------------|-----------|-----|-----|------|
| Differential output voltage swing | V_{OD} | 100 | 600 | mV |
| Output common mode voltage | V_{OCM} | 0.5 | 1.5 | V |
| Input common mode voltage | V_{ICM} | 0.3 | 1.5 | V |
| Input differential voltage | V_{ID} | 100 | 600 | mV |

Table 207 • RSDS Minimum and Maximum AC Switching Speed

| Parameter | Symbol | Max | Unit | Conditions |
|--|-----------|-----|------|---|
| Maximum data rate (for MSIO I/O bank) | D_{MAX} | 520 | Mbps | AC loading: 2 pF / 100 Ω differential load |
| Maximum data rate (for MSIOD I/O bank) | D_{MAX} | 700 | Mbps | AC loading: 2 pF / 100 Ω differential load |

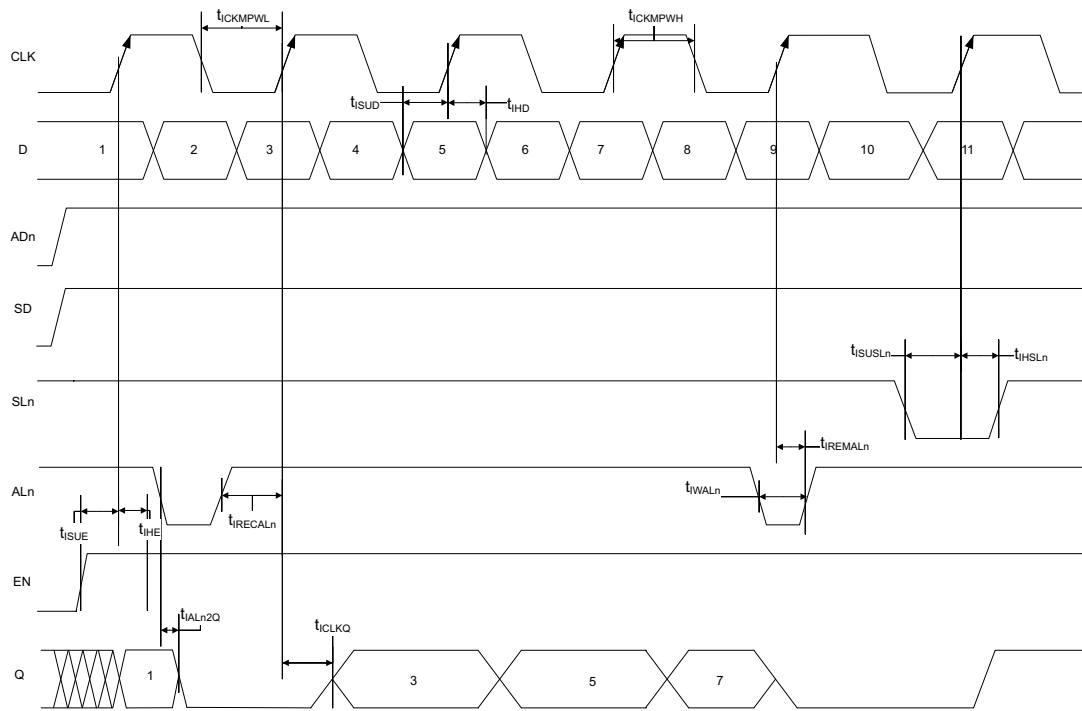
Table 208 • RSDS AC Impedance Specifications

| Parameter | Symbol | Typ | Unit |
|------------------------|--------|-----|----------|
| Termination resistance | R_T | 100 | Ω |

Table 209 • RSDS AC Test Parameter Specifications

| Parameter | Symbol | Typ | Unit |
|--|------------|-------------|----------|
| Measuring/trip point for data path | V_{TRIP} | Cross point | V |
| Resistance for enable path (T_{ZH} , T_{ZL} , T_{HZ} , T_{LZ}) | R_{ENT} | 2K | Ω |
| Capacitive loading for enable path (T_{ZH} , T_{ZL} , T_{HZ} , T_{LZ}) | C_{ENT} | 5 | pF |

Figure 7 • I/O Register Input Timing Diagram



2.3.10.2 Timing Characteristics

The following table lists the combinatorial cell propagation delays in worst commercial-case conditions when $T_J = 85\text{ }^\circ\text{C}$, $V_{DD} = 1.14\text{ V}$.

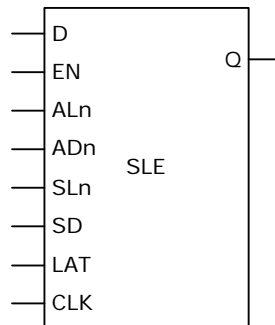
Table 223 • Combinatorial Cell Propagation Delays

| Combinatorial Cell | Equation | Symbol | -1 | -Std | Unit |
|--------------------|---------------------------------|----------|-------|-------|------|
| INV | $Y = !A$ | T_{PD} | 0.1 | 0.118 | ns |
| AND2 | $Y = A \cdot B$ | T_{PD} | 0.164 | 0.193 | ns |
| NAND2 | $Y = !(A \cdot B)$ | T_{PD} | 0.147 | 0.173 | ns |
| OR2 | $Y = A + B$ | T_{PD} | 0.164 | 0.193 | ns |
| NOR2 | $Y = !(A + B)$ | T_{PD} | 0.147 | 0.173 | ns |
| XOR2 | $Y = A \oplus B$ | T_{PD} | 0.164 | 0.193 | ns |
| XOR3 | $Y = A \oplus B \oplus C$ | T_{PD} | 0.225 | 0.265 | ns |
| AND3 | $Y = A \cdot B \cdot C$ | T_{PD} | 0.209 | 0.246 | ns |
| AND4 | $Y = A \cdot B \cdot C \cdot D$ | T_{PD} | 0.287 | 0.338 | ns |

2.3.10.3 Sequential Module

IGLOO2 and SmartFusion2 SoC FPGAs offer a separate flip-flop which can be used independently from the LUT. The flip-flop can be configured as a register or a latch and has a data input and optional enable, synchronous load (clear or preset), and asynchronous load (clear or preset).

Figure 15 • Sequential Module



The following table lists the RAM1K18 – dual-port mode for depth × width configuration 8K × 2 in worst commercial-case conditions when $T_J = 85\text{ }^\circ\text{C}$, $V_{DD} = 1.14\text{ V}$.

Table 234 • RAM1K18 – Dual-Port Mode for Depth × Width Configuration 8K × 2

| Parameter | Symbol | –1 | | –Std | | Unit |
|--|-----------------|--------|-----|--------|-------|------|
| | | Min | Max | Min | Max | |
| Clock period | T_{CY} | 2.5 | | 2.941 | | ns |
| Clock minimum pulse width high | $T_{CLKMPWH}$ | 1.125 | | 1.323 | | ns |
| Clock minimum pulse width low | $T_{CLKMPWL}$ | 1.125 | | 1.323 | | ns |
| Pipelined clock period | T_{PLCY} | 2.5 | | 2.941 | | ns |
| Pipelined clock minimum pulse width high | $T_{PLCLKMPWH}$ | 1.125 | | 1.323 | | ns |
| Pipelined clock minimum pulse width low | $T_{PLCLKMPWL}$ | 1.125 | | 1.323 | | ns |
| Read access time with pipeline register | | | | 0.32 | 0.377 | ns |
| Read access time without pipeline register | T_{CLK2Q} | | | 2.272 | 2.673 | ns |
| Access time with feed-through write timing | | | | 1.511 | 1.778 | ns |
| Address setup time | T_{ADDRSU} | 0.612 | | 0.72 | | ns |
| Address hold time | T_{ADDRHD} | 0.274 | | 0.322 | | ns |
| Data setup time | T_{DSU} | 0.33 | | 0.388 | | ns |
| Data hold time | T_{DHD} | 0.082 | | 0.096 | | ns |
| Block select setup time | T_{BLKSU} | 0.207 | | 0.244 | | ns |
| Block select hold time | T_{BLKHD} | 0.216 | | 0.254 | | ns |
| Block select to out disable time (when pipelined register is disabled) | T_{BLK2Q} | | | 1.511 | 1.778 | ns |
| Block select minimum pulse width | T_{BLKMPW} | 0.186 | | 0.219 | | ns |
| Read enable setup time | T_{RDESU} | 0.529 | | 0.622 | | ns |
| Read enable hold time | T_{RDEHD} | 0.071 | | 0.083 | | ns |
| Pipelined read enable setup time (A_DOUT_EN, B_DOUT_EN) | $T_{RDPLESU}$ | 0.248 | | 0.291 | | ns |
| Pipelined read enable hold time (A_DOUT_EN, B_DOUT_EN) | $T_{RDPLEHD}$ | 0.102 | | 0.12 | | ns |
| Asynchronous reset to output propagation delay | T_{R2Q} | | | 1.528 | 1.797 | ns |
| Asynchronous reset removal time | T_{RSTREM} | 0.506 | | 0.595 | | ns |
| Asynchronous reset recovery time | T_{RSTREC} | 0.004 | | 0.005 | | ns |
| Asynchronous reset minimum pulse width | T_{RSTMPW} | 0.301 | | 0.354 | | ns |
| Pipelined register asynchronous reset removal time | $T_{PLRSTREM}$ | –0.279 | | –0.328 | | ns |
| Pipelined register asynchronous reset recovery time | $T_{PLRSTREC}$ | 0.327 | | 0.385 | | ns |
| Pipelined register asynchronous reset minimum pulse width | $T_{PLRSTMPW}$ | 0.282 | | 0.332 | | ns |
| Synchronous reset setup time | T_{SRSTSU} | 0.226 | | 0.265 | | ns |
| Synchronous reset hold time | T_{SRSTHD} | 0.036 | | 0.043 | | ns |
| Write enable setup time | T_{WESU} | 0.488 | | 0.574 | | ns |
| Write enable hold time | T_{WEHD} | 0.048 | | 0.057 | | ns |
| Maximum frequency | F_{MAX} | | | 400 | 340 | MHz |

Table 245 • JTAG Programming (eNVM Only)

| M2S/M2GL | | | | |
|-----------------|-------------------------|----------------|---------------|-------------|
| Device | Image size Bytes | Program | Verify | Unit |
| 005 | 137536 | 39 | 4 | Sec |
| 010 | 274816 | 78 | 9 | Sec |
| 025 | 274816 | 78 | 9 | Sec |
| 050 | 278528 | 84 | 8 | Sec |
| 060 | 268480 | 76 | 8 | Sec |
| 090 | 544496 | 154 | 15 | Sec |
| 150 | 544496 | 155 | 15 | Sec |

Table 246 • JTAG Programming (Fabric and eNVM)

| M2S/M2GL | | | | |
|-----------------|-------------------------|----------------|---------------|-------------|
| Device | Image size Bytes | Program | Verify | Unit |
| 005 | 439296 | 59 | 11 | Sec |
| 010 | 842688 | 107 | 20 | Sec |
| 025 | 1497408 | 120 | 35 | Sec |
| 050 | 2695168 | 162 | 59 | Sec |
| 060 | 2686464 | 158 | 70 | Sec |
| 090 | 4190208 | 266 | 147 | Sec |
| 150 | 6682768 | 316 | 231 | Sec |

Table 247 • 2 Step IAP Programming (Fabric Only)

| M2S/M2GL | | | | | |
|-----------------|-------------------------|---------------------|----------------|---------------|-------------|
| Device | Image size Bytes | Authenticate | Program | Verify | Unit |
| 005 | 302672 | 4 | 17 | 6 | Sec |
| 010 | 568784 | 7 | 23 | 12 | Sec |
| 025 | 1223504 | 14 | 33 | 23 | Sec |
| 050 | 2424832 | 29 | 52 | 40 | Sec |
| 060 | 2418896 | 39 | 61 | 50 | Sec |
| 090 | 3645968 | 60 | 84 | 73 | Sec |
| 150 | 6139184 | 100 | 132 | 120 | Sec |

Table 254 • Programming Times with 100 kHz, 25 MHz, and 12.5 MHz SPI Clock Rates (eNVM Only) (continued)

| M2S/M2GL Device | Auto Programming | Auto Update | Programming Recovery | Unit |
|--------------------|---------------------|-------------|-------------------------|------|
| | 100 kHz | 25 MHz | 12.5 MHz | |
| 150 | 161 | 161 | 161 | Sec |

Table 255 • Programming Times with 100 kHz, 25 MHz, and 12.5 MHz SPI Clock Rates (Fabric and eNVM)

| M2S/M2GL Device | Auto Programming | Auto Update | Programming Recovery | Unit |
|--------------------|---------------------|---------------|-------------------------|------|
| | 100 kHz | 25 MHz | 12.5 MHz | |
| 005 | 47 | 27 | 28 | Sec |
| 010 | 77 | 35 | 35 | Sec |
| 025 | 150 | 42 | 41 | Sec |
| 050 | 33 ¹ | Not Supported | Not Supported | Sec |
| 060 | 291 | 83 | 82 | Sec |
| 090 | 427 | 109 | 108 | Sec |
| 150 | 708 | 157 | 160 | Sec |
| 005 | 41 | 48 | 49 | Sec |
| 010 | 86 | 87 | 87 | Sec |
| 025 | 87 | 85 | 86 | Sec |
| 050 | 85 | Not Supported | Not Supported | Sec |
| 060 | 78 | 86 | 86 | Sec |
| 090 | 154 | 162 | 162 | Sec |
| 150 | 161 | 161 | 161 | Sec |
| 005 | 87 | 67 | 66 | Sec |
| 010 | 161 | 113 | 113 | Sec |
| 025 | 229 | 120 | 121 | Sec |
| 050 | 112 | Not Supported | Not Supported | Sec |
| 060 | 368 | 161 | 158 | Sec |
| 090 | 582 | 261 | 260 | Sec |
| 150 | 867 | 309 | 310 | Sec |

1. Auto Programming in 050 device is done through SC_SPI, and SPI CLK is set to 6.25 MHz.

2.3.14 Math Block Timing Characteristics

The fundamental building block in any digital signal processing algorithm is the multiply-accumulate function. Each IGLOO2 and SmartFusion2 SoC math block supports 18×18 signed multiplication, dot product, and built-in addition, subtraction, and accumulation units to combine multiplication results efficiently. The following table lists the math blocks with all registers used in worst commercial-case conditions when $T_J = 85\text{ }^\circ\text{C}$, $V_{DD} = 1.14\text{ V}$.

Table 268 • Math Blocks with all Registers Used

| Parameter | Symbol | -1 | | -Std | | Unit |
|-------------------------------------|-----------------|--------|-------|--------|-------|------|
| | | Min | Max | Min | Max | |
| Input, control register setup time | T_{MISU} | 0.149 | | 0.176 | | ns |
| Input, control register hold time | T_{MIHD} | 1.68 | | 1.976 | | ns |
| CDIN input setup time | $T_{MOCDINSU}$ | 0.185 | | 0.218 | | ns |
| CDIN input hold time | $T_{MOCDINHHD}$ | 0.08 | | 0.094 | | ns |
| Synchronous reset/enable setup time | $T_{MSRSTENSU}$ | -0.419 | | -0.493 | | ns |
| Synchronous reset/enable hold time | $T_{MSRSTENHD}$ | 0.011 | | 0.013 | | ns |
| Asynchronous reset removal time | $T_{MARSTREM}$ | 0 | | 0 | | ns |
| Asynchronous reset recovery time | $T_{MARSTREC}$ | 0.088 | | 0.104 | | ns |
| Output register clock to out delay | T_{MOCQ} | | 0.232 | | 0.273 | ns |
| CLK minimum period | T_{MCLKMP} | 2.245 | | 2.641 | | ns |

The following table lists the math blocks with input bypassed and output registers used in worst commercial-case conditions when $T_J = 85\text{ }^\circ\text{C}$, $V_{DD} = 1.14\text{ V}$.

Table 269 • Math Block with Input Bypassed and Output Registers Used

| Parameter | Symbol | -1 | | -Std | | Unit |
|-------------------------------------|-----------------|--------|-------|--------|-------|------|
| | | Min | Max | Min | Max | |
| Output register setup time | T_{MOSU} | 2.294 | | 2.699 | | ns |
| Output register hold time | T_{MOHD} | 1.68 | | 1.976 | | ns |
| CDIN input setup time | $T_{MOCDINSU}$ | 0.115 | | 0.136 | | ns |
| CDIN input hold time | $T_{MOCDINHHD}$ | -0.444 | | -0.522 | | ns |
| Synchronous reset/enable setup time | $T_{MSRSTENSU}$ | -0.419 | | -0.493 | | ns |
| Synchronous reset/enable hold time | $T_{MSRSTENHD}$ | 0.011 | | 0.013 | | ns |
| Asynchronous reset removal time | $T_{MARSTREM}$ | 0 | | 0 | | ns |
| Asynchronous reset recovery time | $T_{MARSTREC}$ | 0.014 | | 0.017 | | ns |
| Output register clock to out delay | T_{MOCQ} | | 0.232 | | 0.273 | ns |
| CLK minimum period | T_{MCLKMP} | 2.179 | | 2.563 | | ns |

Table 277 • Electrical Characteristics of the Crystal Oscillator – High Gain Mode (20 MHz) (continued)

| Parameter | Symbol | Min | Typ | Max | Unit | Condition |
|--|--------|-----|-----|-----|------|--------------------------------|
| Startup time (with regard to stable oscillator output) | SUXTAL | | | 0.8 | ms | 005, 010, 025, and 050 devices |
| | | | | 1.0 | ms | 090 and 150 devices |

Table 278 • Electrical Characteristics of the Crystal Oscillator – Medium Gain Mode (2 MHz)

| Parameter | Symbol | Min | Typ | Max | Unit | Condition |
|--|------------|---------------------|-------|---------------------|------|-------------------------------------|
| Operating frequency | FXTAL | | 2 | | MHz | |
| Accuracy | ACCXTAL | | | 0.00105 | % | 050 devices |
| | | | | 0.003 | % | 005, 010, 025, 090, and 150 devices |
| | | | | 0.004 | % | 060 devices |
| Output duty cycle | CYCXTAL | | 49–51 | 47–53 | % | |
| Output period jitter (peak to peak) | JITPERXTAL | | 1 | 5 | ns | |
| Output cycle to cycle jitter (peak to peak) | JITCYCXTAL | | 1 | 5 | ns | |
| Operating current | IDYNXTAL | | 0.3 | | mA | |
| Input logic level high | VIHXTAL | 0.9 V _{PP} | | | V | |
| Input logic level low | VILXTAL | | | 0.1 V _{PP} | V | |
| Startup time (with regard to stable oscillator output) | SUXTAL | | | 4.5 | ms | 010 and 050 devices |
| | | | | 5 | ms | 005 and 025 devices |
| | | | | 7 | ms | 090 and 150 devices |

Table 279 • Electrical Characteristics of the Crystal Oscillator – Low Gain Mode (32 kHz)

| Parameter | Symbol | Min | Typ | Max | Unit | Condition |
|--|------------|---------------------|-------|---------------------|------|--|
| Operating frequency | FXTAL | | 32 | | kHz | |
| Accuracy | ACCXTAL | | | 0.004 | % | 005, 010, 025, 050, 060, and 090 devices |
| | | | | 0.005 | % | 150 devices |
| Output duty cycle | CYCXTAL | | 49–51 | 47–53 | % | |
| Output period jitter (peak to peak) | JITPERXTAL | | 150 | 300 | ns | |
| Output cycle to cycle jitter (peak to peak) | JITCYCXTAL | | 150 | 300 | ns | |
| Operating current | IDYNXTAL | | 0.044 | | mA | 010 and 050 devices |
| | | | 0.060 | | mA | 005, 025, 060, 090, and 150 devices |
| Input logic level high | VIHXTAL | 0.9 V _{PP} | | | V | |
| Input logic level low | VILXTAL | | | 0.1 V _{PP} | V | |
| Startup time (with regard to stable oscillator output) | SUXTAL | | | 115 | ms | 005, 025, 050, 090, and 150 devices |
| | | | | 126 | ms | 010 devices |

2.3.24 Power-up to Functional Times

The following table lists the SmartFusion2 power-up to functional times in worst-case industrial conditions when $T_J = 100\text{ }^\circ\text{C}$, $V_{DD} = 1.14\text{ V}$.

Table 288 • Power-up to Functional Times for SmartFusion2

| Symbol | From | To | Description | Maximum Power-up to Functional Time for SmartFusion2 (uS) | | | | | | |
|------------------|------------------|-------------------------|---|---|------|------|------|------|------|------|
| | | | | 005 | 010 | 025 | 050 | 060 | 090 | 150 |
| $T_{POR2OUT}$ | POWER_ON_RESET_N | Output available at I/O | Fabric to output | 647 | 500 | 531 | 483 | 474 | 524 | 647 |
| $T_{POR2MSSRST}$ | POWER_ON_RESET_N | MSS_RESE T_N_M2F | Fabric to MSS | 644 | 497 | 528 | 480 | 468 | 518 | 641 |
| $T_{MSSRST2OUT}$ | MSS_RESET_N_M2F | Output available at I/O | MSS to output | 3.6 | 3.6 | 3.6 | 3.4 | 4.9 | 4.8 | 4.8 |
| $T_{VDD2OUT}$ | V_{DD} | Output available at I/O | V_{DD} at its minimum threshold level to output | 3096 | 2975 | 3012 | 2959 | 2869 | 2992 | 3225 |
| $T_{VDD2POR}$ | V_{DD} | POWER_ON_RESET_N | V_{DD} at its minimum threshold level to fabric | 2476 | 2487 | 2496 | 2486 | 2406 | 2563 | 2602 |
| $T_{VDD2MSSRST}$ | V_{DD} | MSS_RESE T_N_M2F | V_{DD} at its minimum threshold level to MSS | 3093 | 2972 | 3008 | 2956 | 2864 | 2987 | 3220 |
| $T_{VDD2WPU}$ | DEVRST_N | DDRIO Inbuf weak pull | DEVRST_N to Inbuf weak pull | 2500 | 2487 | 2509 | 2475 | 2507 | 2519 | 2617 |
| | DEVRST_N | MSIO Inbuf weak pull | DEVRST_N to Inbuf weak pull | 2504 | 2491 | 2510 | 2478 | 2517 | 2525 | 2620 |
| | DEVRST_N | MSIOD Inbuf weak pull | DEVRST_N to Inbuf weak pull | 2479 | 2468 | 2493 | 2458 | 2486 | 2499 | 2595 |

Note: For more information about power-up times, see *UG0331: SmartFusion2 Microcontroller Subsystem User Guide*.

Table 305 • SPI Characteristics for All Devices (continued)

| Symbol | Description | Min | Typ | Max | Unit | Conditions |
|--|--|-----------------------------|-------|-----|------|--|
| sp5 | SPI_[0 1]_CLK, SPI_[0 1]_DO, SPI_[0 1]_SS fall time (10%–90%) ¹ | | 2.906 | | ns | IO Configuration: LVCMOS 2.5 V-8 mA AC Loading: 35 pF Test Conditions: Typical Voltage, 25 °C |
| SPI master configuration (applicable for 005, 010, 025, and 050 devices) | | | | | | |
| sp6m | SPI_[0 1]_DO setup time ² | (SPI_x_CLK_period/2) – 8.0 | | | ns | |
| sp7m | SPI_[0 1]_DO hold time ² | (SPI_x_CLK_period/2) – 2.5 | | | ns | |
| sp8m | SPI_[0 1]_DI setup time ² | 12 | | | ns | |
| sp9m | SPI_[0 1]_DI hold time ² | 2.5 | | | ns | |
| SPI slave configuration (applicable for 005, 010, 025, and 050 devices) | | | | | | |
| sp6s | SPI_[0 1]_DO setup time ² | (SPI_x_CLK_period/2) – 17.0 | | | ns | |
| sp7s | SPI_[0 1]_DO hold time ² | (SPI_x_CLK_period/2) + 3.0 | | | ns | |
| sp8s | SPI_[0 1]_DI setup time ² | 2 | | | ns | |
| sp9s | SPI_[0 1]_DI hold time ² | 7 | | | ns | |
| SPI master configuration (applicable for 060, 090, and 150 devices) | | | | | | |
| sp6m | SPI_[0 1]_DO setup time ² | (SPI_x_CLK_period/2) – 7.0 | | | ns | |
| sp7m | SPI_[0 1]_DO hold time ² | (SPI_x_CLK_period/2) – 9.5 | | | ns | |
| sp8m | SPI_[0 1]_DI setup time ² | 15 | | | ns | |
| sp9m | SPI_[0 1]_DI hold time ² | –2.5 | | | ns | |
| SPI slave configuration (applicable for 060, 090, and 150 devices) | | | | | | |
| sp6s | SPI_[0 1]_DO setup time ² | (SPI_x_CLK_period/2) – 16.0 | | | ns | |
| sp7s | SPI_[0 1]_DO hold time ² | (SPI_x_CLK_period/2) – 3.5 | | | ns | |
| sp8s | SPI_[0 1]_DI setup time ² | 3 | | | ns | |
| sp9s | SPI_[0 1]_DI hold time ² | 2.5 | | | ns | |

1. For specific Rise/Fall Times board design considerations and detailed output buffer resistances, use the corresponding IBIS models located on the Microsemi SoC Products Group website: <http://www.microsemi.com/soc/download/ibis/default.aspx>.
2. For allowable pclk configurations, see Serial Peripheral Interface Controller section in the *UG0331: SmartFusion2 Microcontroller Subsystem User Guide*.