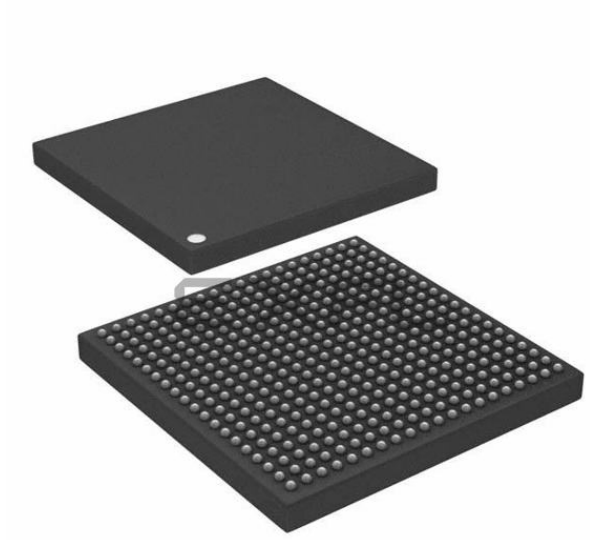

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Embedded - System On Chip (SoC) refers to an integrated circuit that consolidates all the essential components of a computer system into a single chip. This includes a microprocessor, memory, and other peripherals, all packed into one compact and efficient package. SoCs are designed to provide a complete computing solution, optimizing both space and power consumption, making them ideal for a wide range of embedded applications.

What are Embedded - System On Chip (SoC)?

System On Chip (SoC) integrates multiple functions of a computer or electronic system onto a single chip. Unlike traditional multi-chip solutions, SoCs combine a central

Details	
Product Status	Active
Architecture	MCU, FPGA
Core Processor	ARM® Cortex®-M3
Flash Size	256KB
RAM Size	64KB
Peripherals	DDR, PCIe, SERDES
Connectivity	CANbus, Ethernet, I²C, SPI, UART/USART, USB
Speed	166MHz
Primary Attributes	FPGA - 60K Logic Modules
Operating Temperature	0°C ~ 85°C (TJ)
Package / Case	400-LFBGA
Supplier Device Package	400-VFBGA (17x17)
Purchase URL	https://www.e-xfl.com/product-detail/microchip-technology/m2s060t-vf400

Figure 1 • **High Temperature Data Retention (HTR)**

2.3.1.1 Overshoot/Undershoot Limits

For AC signals, the input signal may undershoot during transitions to –1.0 V for no longer than 10% of the period. The current during the transition must not exceed 100 mA.

For AC signals, the input signal may overshoot during transitions to V_{CCI} + 1.0 V for no longer than 10% of the period. The current during the transition must not exceed 100 mA.

Note: The above specifications do not apply to the PCI standard. The IGLOO2 and SmartFusion2 PCI I/Os are compliant with the PCI standard including the PCI overshoot/undershoot specifications.

2.3.1.2 Thermal Characteristics

The temperature variable in the Microsemi SoC Products Group Designer software refers to the junction temperature, not the ambient, case, or board temperatures. This is an important distinction because dynamic and static power consumption causes the chip's junction temperature to be higher than the ambient, case, or board temperatures.

EQ1 through EQ3 give the relationship between thermal resistance, temperature gradient, and power.

$$\theta_{JA} = \frac{T_J - T_A}{P}$$

EQ 1

$$\theta_{JB} = \frac{T_J - T_B}{P}$$

EQ 2

$$\theta_{JC} = \frac{T_J - T_C}{P}$$

EQ 3

Table 17 • **Timing Model Parameters *(continued)***

Index	Symbol	Description	–1	Unit	For More Information
F	T_{DP}	Propagation delay of an OR gate	0.179	ns	See Table 223, page 76
G	T_{DP}	Propagation delay of an LVDS transmitter	2.136	ns	See Table 169, page 57
H	T_{DP}	Propagation delay of a three-input XOR Gate	0.241	ns	See Table 223, page 76
I	T_{DP}	Propagation delay of LVCMOS 2.5 V transmitter, drive strength of 16 mA on the MSIO bank	2.412	ns	See Table 46, page 27
J	T_{DP}	Propagation delay of a two-input NAND gate	0.179	ns	See Table 223, page 76
K	T_{DP}	Propagation delay of LVCMOS 2.5 V transmitter, drive strength of 8 mA on the MSIO bank	2.309	ns	See Table 46, page 27
L	T_{CLKQ}	Clock-to-Q of the data register	0.108	ns	See Table 224, page 77
	T_{SUD}	Setup time of the data register	0.254	ns	See Table 224, page 77
M	T_{DP}	Propagation delay of a two-input AND gate	0.179	ns	See Table 223, page 76
N	T_{OCLKQ}	Clock-to-Q of the output data register	0.263	ns	See Table 220, page 69
	T_{OSUD}	Setup time of the output data register	0.19	ns	See Table 220, page 69
O	T_{DP}	Propagation delay of SSTL2, Class I transmitter on the MSIO bank	2.055	ns	See Table 114, page 45
P	T_{DP}	Propagation delay of LVCMOS 1.5 V transmitter, drive strength of 12 mA, fast slew on the DDRIO bank	3.316	ns	See Table 70, page 34

Table 57 • **LVCMOS 1.8 V Transmitter Characteristics for DDRIO I/O Bank with Fixed Code (Output and Tristate Buffers)**

Output Drive Selection	Slew Control	T_{DP}		T_{ZL}		T_{ZH}		T_{HZ}[1]		T_{LZ}[1]		Unit
		–1	–Std	–1	–Std	–1	–Std	–1	–Std	–1	–Std	
2 mA	Slow	4.234	4.981	3.646	4.29	4.245	4.995	4.908	5.774	4.434	5.216	ns
	Medium	3.824	4.498	3.282	3.861	3.834	4.511	4.625	5.441	4.116	4.843	ns
	Medium fast	3.627	4.267	3.111	3.66	3.637	4.279	4.481	5.272	3.984	4.687	ns
	Fast	3.605	4.241	3.097	3.644	3.615	4.253	4.472	5.262	3.973	4.674	ns
4 mA	Slow	3.923	4.615	3.314	3.9	3.918	4.61	5.403	6.356	4.894	5.757	ns
	Medium	3.518	4.138	2.961	3.484	3.515	4.135	5.121	6.025	4.561	5.366	ns
	Medium fast	3.321	3.907	2.783	3.275	3.317	3.903	4.966	5.843	4.426	5.206	ns
	Fast	3.301	3.883	2.77	3.259	3.296	3.878	4.957	5.831	4.417	5.196	ns
6 mA	Slow	3.71	4.364	3.104	3.652	3.702	4.355	5.62	6.612	5.08	5.977	ns
	Medium	3.333	3.921	2.779	3.27	3.325	3.913	5.346	6.289	4.777	5.62	ns
	Medium fast	3.155	3.712	2.62	3.083	3.146	3.702	5.21	6.13	4.657	5.479	ns
	Fast	3.134	3.688	2.608	3.068	3.125	3.677	5.202	6.12	4.648	5.468	ns
8 mA	Slow	3.619	4.258	3.007	3.538	3.607	4.244	5.815	6.841	5.249	6.175	ns
	Medium	3.246	3.819	2.686	3.16	3.236	3.807	5.542	6.52	4.936	5.807	ns
	Medium fast	3.066	3.607	2.525	2.971	3.054	3.593	5.405	6.359	4.811	5.66	ns
	Fast	3.046	3.584	2.513	2.957	3.034	3.57	5.401	6.353	4.803	5.651	ns
10 mA	Slow	3.498	4.115	2.878	3.386	3.481	4.096	6.046	7.113	5.444	6.404	ns
	Medium	3.138	3.692	2.569	3.023	3.126	3.678	5.782	6.803	5.129	6.034	ns
	Medium fast	2.966	3.489	2.414	2.841	2.951	3.472	5.666	6.665	5.013	5.897	ns
	Fast	2.945	3.464	2.401	2.826	2.93	3.448	5.659	6.658	5.003	5.886	ns
12 mA	Slow	3.417	4.02	2.807	3.303	3.401	4.002	6.083	7.156	5.464	6.428	ns
	Medium	3.076	3.618	2.519	2.964	3.063	3.604	5.828	6.856	5.176	6.089	ns
	Medium fast	2.913	3.427	2.376	2.795	2.898	3.41	5.725	6.736	5.072	5.966	ns
	Fast	2.894	3.405	2.362	2.78	2.879	3.388	5.715	6.724	5.064	5.957	ns
16 mA	Slow	3.366	3.96	2.751	3.237	3.348	3.939	6.226	7.324	5.576	6.56	ns
	Medium	3.03	3.565	2.47	2.906	3.017	3.55	5.981	7.036	5.282	6.214	ns
	Medium fast	2.87	3.377	2.328	2.739	2.854	3.358	5.895	6.935	5.18	6.094	ns
	Fast	2.853	3.357	2.314	2.723	2.837	3.338	5.889	6.929	5.177	6.09	ns

1. Delay increases with drive strength are inherent to built-in slew control circuitry for simultaneous switching output (SSO) management.

Table 58 • **LVCMOS 1.8 V Transmitter Characteristics for MSIO I/O Bank**

Output Drive Selection	Slew Control	T_{DP}		T_{ZL}		T_{ZH}		T_{HZ}[1]		T_{LZ}[1]		Unit
		–1	–Std	–1	–Std	–1	–Std	–1	–Std	–1	–Std	
2 mA	Slow	3.441	4.047	4.165	4.9	4.413	5.192	4.891	5.755	5.138	6.044	ns
4 mA	Slow	3.218	3.786	3.642	4.284	3.941	4.636	5.665	6.665	5.568	6.551	ns
6 mA	Slow	3.141	3.694	3.501	4.118	3.823	4.498	6.587	7.75	6.032	7.096	ns
8 mA	Slow	3.165	3.723	3.319	3.904	3.654	4.298	6.898	8.115	6.216	7.313	ns
10 mA	Slow	3.202	3.767	3.278	3.857	3.616	4.254	7.25	8.529	6.435	7.571	ns
12 mA	Slow	3.277	3.855	3.175	3.736	3.519	4.139	7.392	8.697	6.538	7.692	ns

1. Delay increases with drive strength are inherent to built-in slew control circuitry for simultaneous switching output (SSO) management.

Table 59 • **LVCMOS 1.8 V Transmitter Characteristics for MSIOD I/O Bank**

Output Drive Selection	Slew Control	T_{DP}		T_{ZL}		T_{ZH}		T_{HZ}[1]		T_{LZ}[1]		Unit
		–1	–Std	–1	–Std	–1	–Std	–1	–Std	–1	–Std	
2 mA	Slow	2.725	3.206	3.316	3.901	3.484	4.099	5.204	6.123	4.997	5.88	ns
4 mA	Slow	2.242	2.638	2.777	3.267	2.947	3.466	5.729	6.74	5.448	6.41	ns
6 mA	Slow	1.995	2.347	2.466	2.901	2.63	3.094	6.372	7.496	5.987	7.043	ns
8 mA	Slow	2.001	2.354	2.44	2.87	2.6	3.058	6.633	7.804	6.193	7.286	ns
10 mA	Slow	2.025	2.382	2.312	2.719	2.47	2.906	6.94	8.165	6.412	7.544	ns

1. Delay increases with drive strength are inherent to built-in slew control circuitry for simultaneous switching output (SSO) management.

2.3.5.9 1.5 V LVCMOS

LVCMOS 1.5 is a general standard for 1.5 V applications and is supported in IGLOO2 FPGAs and SmartFusion2 SoC FPGAs in compliance to the JEDEC specification JESD8-11A.

Minimum and Maximum DC/AC Input and Output Levels Specification

Table 60 • **LVCMOS 1.5 V DC Recommended Operating Conditions**

Parameter	Symbol	Min	Typ	Max	Unit
Supply voltage	V_{DDI}	1.425	1.5	1.575	V

Table 61 • **LVCMOS 1.5 V DC Input Voltage Specification**

Parameter	Symbol	Min	Max	Unit
DC input logic high for (MSIOD and DDRIO I/O banks)	V_{IH} (DC)	0.65 × V_{DDI}	1.575	V
DC input logic high (for MSIO I/O bank)	V_{IH} (DC)	0.65 × V_{DDI}	3.45	V
DC input logic low	V_{IL} (DC)	–0.3	0.35 × V_{DDI}	V
Input current high[1]	I_{IH} (DC)			–
Input current low[1]	I_{IL} (DC			–

1. See Table 24, page 22.

Table 62 • **LVCMOS 1.5 V DC Output Voltage Specification**

Parameter	Symbol	Min	Max	Unit
DC output logic high	VOH	V_{DDI} × 0.75		V
DC output logic low	VOL		V_{DDI} × 0.25	V

Table 63 • **LVCMOS 1.5 V AC Minimum and Maximum Switching Speed**

Parameter	Symbol	Max	Unit	Conditions
Maximum data rate (for DDRIO I/O bank)	D_{MAX}	235	Mbps	AC loading: 17 pF load, maximum drive/slew
Maximum data rate (for MSIO I/O bank)	D_{MAX}	160	Mbps	AC loading: 17 pF load, maximum drive/slew
Maximum data rate (for MSIOD I/O bank)	D_{MAX}	220	Mbps	AC loading: 17 pF load, maximum drive/slew

Table 64 • **LVCMOS 1.5 V AC Calibrated Impedance Option**

Parameter	Symbol	Typ	Unit
Supported output driver calibrated impedance (for DDRIO I/O bank)	RODT_CAL	75, 60, 50, 40	Ω

Table 65 • **LVCMOS 1.5 V AC Test Parameter Specifications**

Parameter	Symbol	Typ	Unit
Measuring/trip point	V_{TRIP}	0.75	V
Resistance for enable path (T_{ZH}, T_{ZL}, T_{HZ}, T_{LZ})	R_{ENT}	2K	Ω
Capacitive loading for enable path (T_{ZH}, T_{ZL}, T_{HZ}, T_{LZ})	C_{ENT}	5	pF
Capacitive loading for data path (T_{DP})	C_{LOAD}	5	pF

Table 66 • **LVCMOS 1.5 V Transmitter Drive Strength Specifications**

Output Drive Selection			V_{OH} (V)	V_{OL} (V)	IOH (at V_{OH})	IOL (at V_{OL})
MSIO I/O Bank	MSIOD I/O Bank	DDRIO I/O Bank	Min	Max	mA	mA
2 mA	2 mA	2 mA	V_{DDI} × 0.75	V_{DDI} × 0.25	2	2
4 mA	4 mA	4 mA	V_{DDI} × 0.75	V_{DDI} × 0.25	4	4
6 mA	6 mA	6 mA	V_{DDI} × 0.75	V_{DDI} × 0.25	6	6
8 mA		8 mA	V_{DDI} × 0.75	V_{DDI} × 0.25	8	8
		10 mA	V_{DDI} × 0.75	V_{DDI} × 0.25	10	10
		12 mA	V_{DDI} × 0.75	V_{DDI} × 0.25	12	12

Note: For a detailed I/V curve, use the corresponding IBIS models: www.microsemi.com/soc/download/ibis/default.aspx.

Table 156 • **LPDDR-LVCMOS 1.8 V AC Test Parameter Specifications**

Parameter	Symbol	Typ	Unit
Measuring/trip point for data path	V_{TRIP}	0.9	V
Resistance for enable path (T_{ZH}, T_{ZL}, T_{HZ}, T_{LZ})	R_{ENT}	2K	Ω
Capacitive loading for enable path (T_{ZH}, T_{ZL}, T_{HZ}, T_{LZ})	C_{ENT}	5	pF
Capacitive loading for data path (T_{DP})	C_{LOAD}	5	pF

Table 157 • **LPDDR-LVCMOS 1.8 V Mode Transmitter Drive Strength Specification for DDRIO Bank**

Output Drive Selection	V_{OH} (V) Min	V_{OL} (V) Max	I_{OH} (at V_{OH}) mA	I_{OL} (at V_{OL}) mA
2 mA	V_{DDI} – 0.45	0.45	2	2
4 mA	V_{DDI} – 0.45	0.45	4	4
6 mA	V_{DDI} – 0.45	0.45	6	6
8 mA	V_{DDI} – 0.45	0.45	8	8
10 mA	V_{DDI} – 0.45	0.45	10	10
12 mA	V_{DDI} – 0.45	0.45	12	12
16 mA[1]	V_{DDI} – 0.45	0.45	16	16

1. 16 mA Drive Strengths, All Slews, meet LPDDR JEDEC electrical compliance.

Table 158 • **LPDDR-LVCMOS 1.8V AC Switching Characteristics for Receiver (for DDRIO I/O Bank with Fixed Code - Input Buffers)**

ODT (On Die Termination)	–1	–Std	–1	–Std	Unit
None	1.968	2.315	2.099	2.47	ns

Table 159 • **LPDDR-LVCMOS 1.8 V AC Switching Characteristics for Transmitter for DDRIO I/O Bank (Output and Tristate Buffers)**

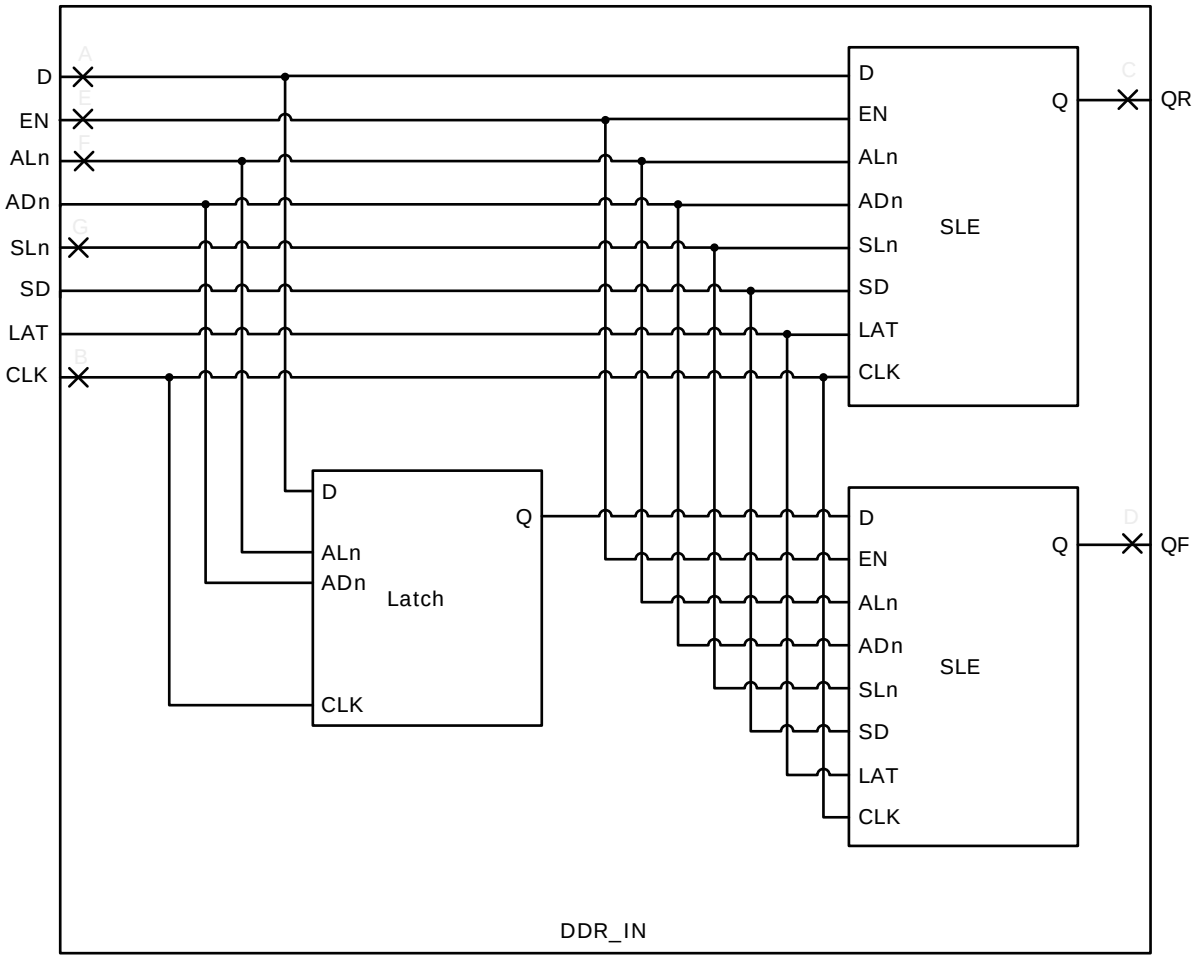
Output Drive Selection	Slew Control	T_{DP}		T_{ZL}		T_{ZH}		T_{HZ}[1]		T_{LZ}[1]		Unit
		–1	–Std	–1	–Std	–1	–Std	–1	–Std	–1	–Std	
2 mA	slow	4.234	4.981	3.646	4.29	4.245	4.995	4.908	5.774	4.434	5.216	ns
	medium	3.824	4.498	3.282	3.861	3.834	4.511	4.625	5.441	4.116	4.843	ns
	medium_fast	3.627	4.267	3.111	3.66	3.637	4.279	4.481	5.272	3.984	4.687	ns
	fast	3.605	4.241	3.097	3.644	3.615	4.253	4.472	5.262	3.973	4.674	ns
4 mA	slow	3.923	4.615	3.314	3.9	3.918	4.61	5.403	6.356	4.894	5.757	ns
	medium	3.518	4.138	2.961	3.484	3.515	4.135	5.121	6.025	4.561	5.366	ns
	medium_fast	3.321	3.907	2.783	3.275	3.317	3.903	4.966	5.843	4.426	5.206	ns
	fast	3.301	3.883	2.77	3.259	3.296	3.878	4.957	5.831	4.417	5.196	ns
6 mA	slow	3.71	4.364	3.104	3.652	3.702	4.355	5.62	6.612	5.08	5.977	ns
	medium	3.333	3.921	2.779	3.27	3.325	3.913	5.346	6.289	4.777	5.62	ns
	medium_fast	3.155	3.712	2.62	3.083	3.146	3.702	5.21	6.13	4.657	5.479	ns
	fast	3.134	3.688	2.608	3.068	3.125	3.677	5.202	6.12	4.648	5.468	ns
8 mA	slow	3.619	4.258	3.007	3.538	3.607	4.244	5.815	6.841	5.249	6.175	ns

2.3.9 DDR Module Specification

This section describes input and output DDR module and timing specifications.

2.3.9.1 Input DDR Module

Figure 10 • **Input DDR Module**



2.3.9.4 Output DDR Module

Figure 12 • Output DDR Module

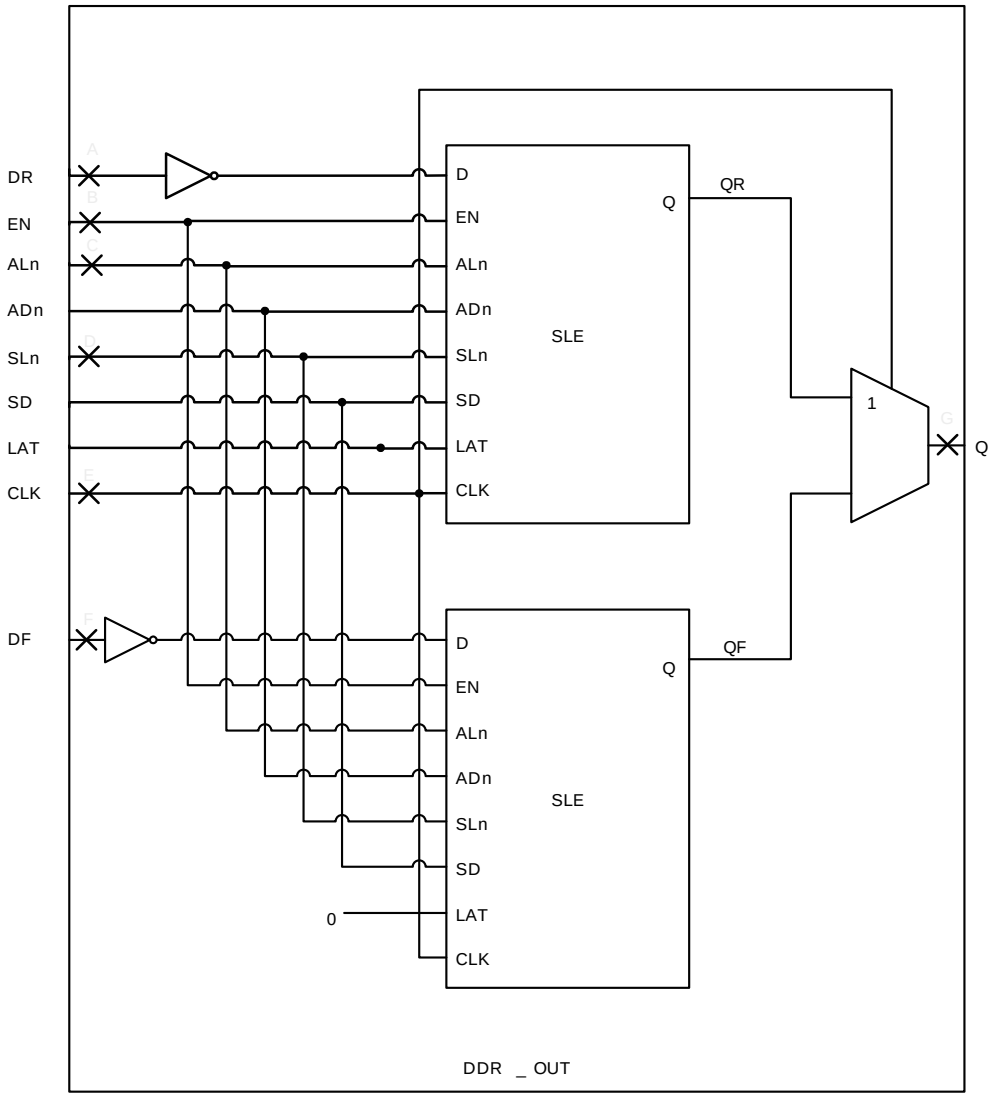
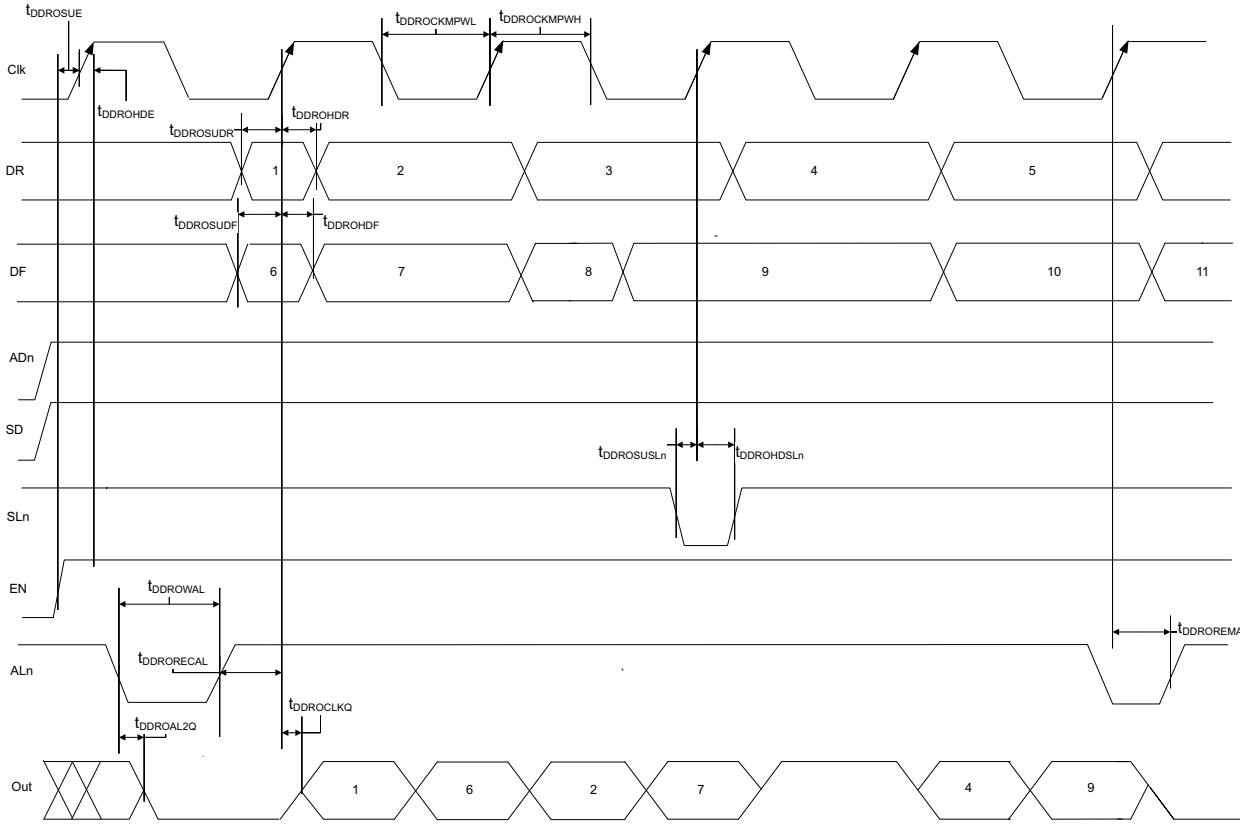


Figure 13 • **Output DDR Timing Diagram**



2.3.9.5 Timing Characteristics

The following table lists the output DDR propagation delays in worst commercial-case conditions when T_J = 85 °C, V_{DD} = 1.14 V.

Table 222 • **Output DDR Propagation Delays**

Symbol	Description	Measuring Nodes (from, to)	–1	–Std	Unit
$T_{DDROCLKQ}$	Clock-to-out of DDR for output DDR	E, G	0.263	0.309	ns
$T_{DDROSUDF}$	Data_F data setup for output DDR	F, E	0.143	0.168	ns
$T_{DDROSUDR}$	Data_R data setup for output DDR	A, E	0.19	0.223	ns
$T_{DDROHDF}$	Data_F data hold for output DDR	F, E	0	0	ns
$T_{DDROHDR}$	Data_R data hold for output DDR	A, E	0	0	ns
$T_{DDROSUE}$	Enable setup for input DDR	B, E	0.419	0.493	ns
T_{DDROHE}	Enable hold for input DDR	B, E	0	0	ns
$T_{DDROSUSLN}$	Synchronous load setup for input DDR	D, E	0.196	0.231	ns
$T_{DDROHSLN}$	Synchronous load hold for input DDR	D, E	0	0	ns
$T_{DDROAL2Q}$	Asynchronous load-to-out for output DDR	C, G	0.528	0.621	ns
$T_{DDROREMAL}$	Asynchronous load removal time for output DDR	C, E	0	0	ns
$T_{DDRORECAL}$	Asynchronous load recovery time for output DDR	C, E	0.034	0.04	ns

2.3.11 Global Resource Characteristics

The IGLOO2 and SmartFusion2 SoC FPGA devices offer a powerful, low skew global routing network which provides an effective clock distribution throughout the FPGA fabric. See *UG0445: IGLOO2 FPGA and SmartFusion2 SoC FPGA Fabric User Guide* for the positions of various global routing resources.

The following table lists the 150 device global resources in worst commercial-case conditions when T_J = 85 °C, V_{DD} = 1.14 V.

Table 225 • **150 Device Global Resource**

		–1		–Std		
Parameter	**Symbol**	**Min**	**Max**	**Min**	**Max**	**Unit**
Input low delay for global clock	T_{RCKL}	0.83	0.911	0.831	0.913	ns
Input high delay for global clock	T_{RCKH}	1.457	1.588	1.715	1.869	ns
Maximum skew for global clock	T_{RCKSW}		0.131		0.154	ns

The following table lists the 090 device global resources in worst commercial-case conditions when T_J = 85 °C, V_{DD} = 1.14 V.

Table 226 • **090 Device Global Resource**

		–1		–Std		
Parameter	**Symbol**	**Min**	**Max**	**Min**	**Max**	**Unit**
Input low delay for global clock	T_{RCKL}	0.835	0.888	0.833	0.886	ns
Input high delay for global clock	T_{RCKH}	1.405	1.489	1.654	1.752	ns
Maximum skew for global clock	T_{RCKSW}		0.084		0.098	ns

The following table lists the 050 device global resources in worst commercial-case conditions when T_J = 85 °C, V_{DD} = 1.14 V.

Table 227 • **050 Device Global Resource**

		–1		–Std		
Parameter	**Symbol**	**Min**	**Max**	**Min**	**Max**	**Unit**
Input low delay for global clock	T_{RCKL}	0.827	0.897	0.826	0.896	ns
Input high delay for global clock	T_{RCKH}	1.419	1.53	1.671	1.8	ns
Maximum skew for global clock	T_{RCKSW}		0.111		0.129	ns

The following table lists the 025 device global resources in worst commercial-case conditions when T_J = 85 °C, V_{DD} = 1.14 V.

Table 228 • **025 Device Global Resource**

		–1		–Std		
Parameter	**Symbol**	**Min**	**Max**	**Min**	**Max**	**Unit**
Input low delay for global clock	T_{RCKL}	0.747	0.799	0.745	0.797	ns
Input high delay for global clock	T_{RCKH}	1.294	1.378	1.522	1.621	ns
Maximum skew for global clock	T_{RCKSW}		0.084		0.099	ns

Table 241 • **µSRAM (RAM256x4) in 256 × 4 Mode *(continued)***

		–1		–Std		
Parameter	**Symbol**	**Min**	**Max**	**Min**	**Max**	**Unit**
Write address hold time	$T_{ADDRCHD}$	0.245		0.288		ns
Write enable setup time	T_{WECSU}	0.397		0.467		ns
Write enable hold time	T_{WECHD}	–0.03		–0.03		ns
Maximum frequency	F_{MAX}		250		250	MHz

The following table lists the µSRAM in 512 × 2 mode in worst commercial-case conditions when T_J = 85 °C, V_{DD} = 1.14 V.

Table 242 • **µSRAM (RAM512x2) in 512 × 2 Mode**

		–1		–Std		
Parameter	**Symbol**	**Min**	**Max**	**Min**	**Max**	**Unit**
Read clock period	T_{CY}	4		4		ns
Read clock minimum pulse width high	$T_{CLKMPWH}$	1.8		1.8		ns
Read clock minimum pulse width low	$T_{CLKMPWL}$	1.8		1.8		ns
Read pipeline clock period	T_{PLCY}	4		4		ns
Read pipeline clock minimum pulse width high	$T_{PLCLKMPWH}$	1.8		1.8		ns
Read pipeline clock minimum pulse width low	$T_{PLCLKMPWL}$	1.8		1.8		ns
Read access time with pipeline register	T_{CLK2Q}		0.27		0.31	ns
Read access time without pipeline register			1.76		2.08	ns
Read address setup time in synchronous mode	T_{ADDRSU}	0.301		0.354		ns
Read address setup time in asynchronous mode		1.96		2.306		ns
Read address hold time in synchronous mode	T_{ADDRHD}	0.137		0.161		ns
Read address hold time in asynchronous mode		–0.58		–0.68		ns
Read enable setup time	T_{RDENSU}	0.278		0.327		ns
Read enable hold time	T_{RDENHD}	0.057		0.067		ns
Read block select setup time	T_{BLKSU}	1.839		2.163		ns
Read block select hold time	T_{BLKHD}	–0.65		–0.77		ns
Read block select to out disable time (when pipelined register is disabled)	T_{BLK2Q}		2.14		2.52	ns
Read asynchronous reset removal time (pipelined clock)	T_{RSTREM}	–0.02		–0.03		ns
Read asynchronous reset removal time (non-pipelined clock)		0.046		0.054		ns
Read asynchronous reset recovery time (pipelined clock)	T_{RSTREC}	0.507		0.597		ns
Read asynchronous reset recovery time (non-pipelined clock)		0.236		0.278		ns
Read asynchronous reset to output propagation delay (with pipelined register enabled)	T_{R2Q}		0.83		0.98	ns
Read synchronous reset setup time	T_{SRSTSU}	0.271		0.319		ns
Read synchronous reset hold time	T_{SRSTHD}	0.061		0.071		ns

Table 245 • **JTAG Programming (eNVM Only)**

M2S/M2GL Device	Image size Bytes	Program	Verify	Unit
005	137536	39	4	Sec
010	274816	78	9	Sec
025	274816	78	9	Sec
050	278528	84	8	Sec
060	268480	76	8	Sec
090	544496	154	15	Sec
150	544496	155	15	Sec

Table 246 • **JTAG Programming (Fabric and eNVM)**

M2S/M2GL Device	Image size Bytes	Program	Verify	Unit
005	439296	59	11	Sec
010	842688	107	20	Sec
025	1497408	120	35	Sec
050	2695168	162	59	Sec
060	2686464	158	70	Sec
090	4190208	266	147	Sec
150	6682768	316	231	Sec

Table 247 • **2 Step IAP Programming (Fabric Only)**

M2S/M2GL Device	Image size Bytes	Authenticate	Program	Verify	Unit
005	302672	4	17	6	Sec
010	568784	7	23	12	Sec
025	1223504	14	33	23	Sec
050	2424832	29	52	40	Sec
060	2418896	39	61	50	Sec
090	3645968	60	84	73	Sec
150	6139184	100	132	120	Sec

Table 254 • Programming Times with 100 kHz, 25 MHz, and 12.5 MHz SPI Clock Rates (eNVM Only) *(continued)*

M2S/M2GL Device	Auto Programming 100 kHz	Auto Update 25 MHz	Programming Recovery 12.5 MHz	Unit
150	161	161	161	Sec

Table 255 • Programming Times with 100 kHz, 25 MHz, and 12.5 MHz SPI Clock Rates (Fabric and eNVM)

M2S/M2GL Device	Auto Programming 100 kHz	Auto Update 25 MHz	Programming Recovery 12.5 MHz	Unit
005	47	27	28	Sec
010	77	35	35	Sec
025	150	42	41	Sec
050	33[1]	Not Supported	Not Supported	Sec
060	291	83	82	Sec
090	427	109	108	Sec
150	708	157	160	Sec
005	41	48	49	Sec
010	86	87	87	Sec
025	87	85	86	Sec
050	85	Not Supported	Not Supported	Sec
060	78	86	86	Sec
090	154	162	162	Sec
150	161	161	161	Sec
005	87	67	66	Sec
010	161	113	113	Sec
025	229	120	121	Sec
050	112	Not Supported	Not Supported	Sec
060	368	161	158	Sec
090	582	261	260	Sec
150	867	309	310	Sec

1. Auto Programming in 050 device is done through SC_SPI, and SPI CLK is set to 6.25 MHz.

2.3.14 Math Block Timing Characteristics

The fundamental building block in any digital signal processing algorithm is the multiply-accumulate function. Each IGLOO2 and SmartFusion2 SoC math block supports 18×18 signed multiplication, dot product, and built-in addition, subtraction, and accumulation units to combine multiplication results efficiently. The following table lists the math blocks with all registers used in worst commercial-case conditions when T_J = 85 °C, V_{DD} = 1.14 V.

Table 268 • **Math Blocks with all Registers Used**

		–1		–Std		
Parameter	**Symbol**	**Min**	**Max**	**Min**	**Max**	**Unit**
Input, control register setup time	T_{MISU}	0.149		0.176		ns
Input, control register hold time	T_{MIHD}	1.68		1.976		ns
CDIN input setup time	$T_{MOCDINSU}$	0.185		0.218		ns
CDIN input hold time	$T_{MOCDINHD}$	0.08		0.094		ns
Synchronous reset/enable setup time	$T_{MSRSTENSU}$	–0.419		–0.493		ns
Synchronous reset/enable hold time	$T_{MSRSTENHD}$	0.011		0.013		ns
Asynchronous reset removal time	$T_{MARSTREM}$	0		0		ns
Asynchronous reset recovery time	$T_{MARSTREC}$	0.088		0.104		ns
Output register clock to out delay	T_{MOCQ}		0.232		0.273	ns
CLK minimum period	T_{MCLKMP}	2.245		2.641		ns

The following table lists the math blocks with input bypassed and output registers used in worst commercial-case conditions when T_J = 85 °C, V_{DD} = 1.14 V.

Table 269 • **Math Block with Input Bypassed and Output Registers Used**

		–1		–Std		
Parameter	**Symbol**	**Min**	**Max**	**Min**	**Max**	**Unit**
Output register setup time	T_{MOSU}	2.294		2.699		ns
Output register hold time	T_{MOHD}	1.68		1.976		ns
CDIN input setup time	$T_{MOCDINSU}$	0.115		0.136		ns
CDIN input hold time	$T_{MOCDINHD}$	–0.444		–0.522		ns
Synchronous reset/enable setup time	$T_{MSRSTENSU}$	–0.419		–0.493		ns
Synchronous reset/enable hold time	$T_{MSRSTENHD}$	0.011		0.013		ns
Asynchronous reset removal time	$T_{MARSTREM}$	0		0		ns
Asynchronous reset recovery time	$T_{MARSTREC}$	0.014		0.017		ns
Output register clock to out delay	T_{MOCQ}		0.232		0.273	ns
CLK minimum period	T_{MCLKMP}	2.179		2.563		ns

2.3.30 SerDes Electrical and Timing AC and DC Characteristics

PCIe is a high-speed, packet-based, point-to-point, low-pin-count, serial interconnect bus. The IGLOO2 and SmartFusion2 SoC FPGAs has up to four hard high-speed serial interface blocks. Each SerDes block contains a PCIe system block. The PCIe system is connected to the SerDes block.

The following table lists the transmitter parameters in worst-case industrial conditions when T_J = 100 °C, V_{DD} = 1.14 V.

Table 296 • **Transmitter Parameters**

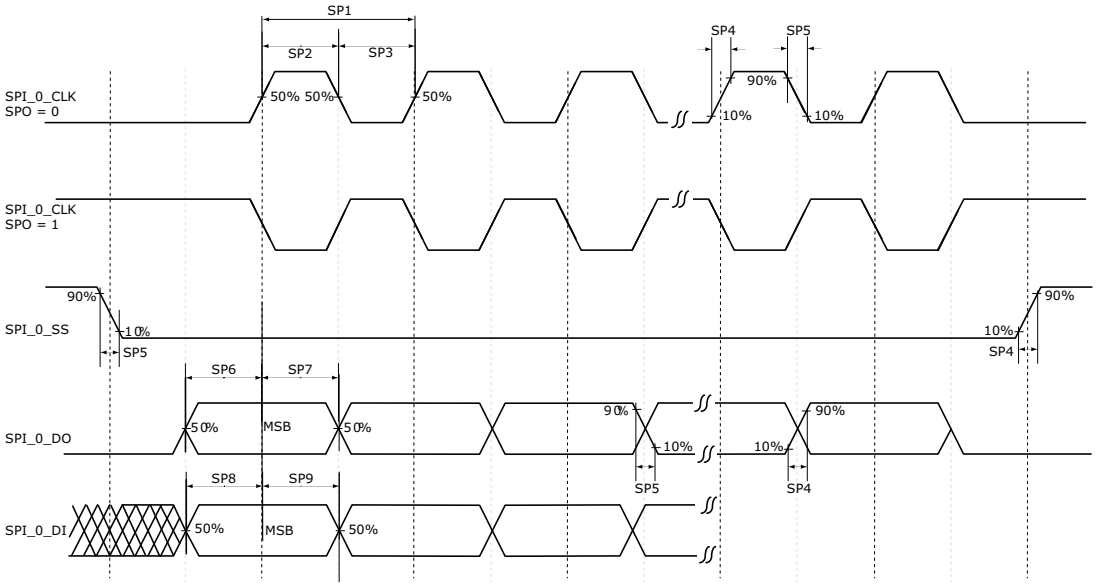
Symbol	Description	Min	Max	Unit
VTX-DIFF-PP	Differential swing (2.5 Gbps, 5.0 Gbps)	0.8	1.2	V
VTX-CM-AC-P	Output common mode voltage (2.5 Gbps)		20	mV
VTX-CM-AC-PP	Output common mode voltage (5.0 Gbps)		100	mV
VTX-RISE-FALL	Rise and fall time (20% to 80%, 2.5 Gbps)	0.125		UI
	Rise and fall time (20% to 80%, 5.0 Gbps)	0.15		UI
ZTX-DIFF-DC	Output impedance–differential	80	120	Ω
LTX-SKEW	Lane-to-lane TX skew within a SerDes block (2.5 Gbps)		500 ps + 2 UI	ps
	Lane-to-lane TX skew within a SerDes block (5.0 Gbps)		500 ps + 4 UI	ps
RLTX-DIFF	Return loss differential mode (2.5 Gbps)	–10		dB
	Return loss differential mode (5.0 Gbps) 0.05 GHz to 1.25 GHz	–10		dB
	1.25 GHz to 2.5 GHz	–8		dB
RLTX-CM	Return loss common mode (2.5 Gbps, 5.0 Gbps)	–6		dB
TX-LOCK-RST	Transmit PLL lock time from reset		10	µs
VTX-AMP	100 mV setting	90	150	mV
	400 mV setting	320	480	mV
	800 mV setting	660	940	mV
	1200 mV setting	950	1400	mV

Table 305 • **SPI Characteristics for All Devices *(continued)***

Symbol	Description	Min	Typ	Max	Unit	Conditions
sp5	SPI_[0|1]_CLK, SPI_[0|1]_DO, SPI_[0|1]_SS fall time (10%–90%)[1]		2.906		ns	IO Configuration: LVCMOS 2.5 V-8 mA AC Loading: 35 pF Test Conditions: Typical Voltage, 25 °C
SPI master configuration (applicable for 005, 010, 025, and 050 devices)						
sp6m	SPI_[0|1]_DO setup time[2]	(SPI_x_CLK_period/2) – 8.0			ns	
sp7m	SPI_[0|1]_DO hold time[2]	(SPI_x_CLK_period/2) – 2.5			ns	
sp8m	SPI_[0|1]_DI setup time[2]	12			ns	
sp9m	SPI_[0|1]_DI hold time[2]	2.5			ns	
SPI slave configuration (applicable for 005, 010, 025, and 050 devices)						
sp6s	SPI_[0|1]_DO setup time[2]	(SPI_x_CLK_period/2) – 17.0			ns	
sp7s	SPI_[0|1]_DO hold time[2]	(SPI_x_CLK_period/2) + 3.0			ns	
sp8s	SPI_[0|1]_DI setup time[2]	2			ns	
sp9s	SPI_[0|1]_DI hold time[2]	7			ns	
SPI master configuration (applicable for 060, 090, and 150 devices)						
sp6m	SPI_[0|1]_DO setup time[2]	(SPI_x_CLK_period/2) – 7.0			ns	
sp7m	SPI_[0|1]_DO hold time[2]	(SPI_x_CLK_period/2) – 9.5			ns	
sp8m	SPI_[0|1]_DI setup time[2]	15			ns	
sp9m	SPI_[0|1]_DI hold time[2]	–2.5			ns	
SPI slave configuration (applicable for 060, 090, and 150 devices)						
sp6s	SPI_[0|1]_DO setup time[2]	(SPI_x_CLK_period/2) – 16.0			ns	
sp7s	SPI_[0|1]_DO hold time[2]	(SPI_x_CLK_period/2) - 3.5			ns	
sp8s	SPI_[0|1]_DI setup time[2]	3			ns	
sp9s	SPI_[0|1]_DI hold time[2]	2.5			ns	

1. For specific Rise/Fall Times board design considerations and detailed output buffer resistances, use the corresponding IBIS models located on the Microsemi SoC Products Group website: http://www.microsemi.com/soc/download/ibis/default.aspx.
2. For allowable pclk configurations, see Serial Peripheral Interface Controller section in the *UG0331: SmartFusion2 Microcontroller Subsystem User Guide*.

Figure 22 • **SPI Timing for a Single Frame Transfer in Motorola Mode (SPH = 1)**



2.3.32 CAN Controller Characteristics

The following table lists the CAN controller characteristics in worst-case industrial conditions when T_J = 100 °C, V_{DD} = 1.14 V.

Table 306 • **CAN Controller Characteristics**

Parameter	Description	–1	–Std	Unit
FCANREFCLK[1]	Internally sourced CAN reference clock frequency	160	136	MHz
BAUDCANMAX	Maximum CAN performance baud rate	1	1	Mbps
BAUDCANMIN	Minimum CAN performance baud rate	0.05	0.05	Mbps

1. PCLK to CAN controller must be a multiple of 8 MHz.

2.3.33 USB Characteristics

The following table lists the USB characteristics in worst-case industrial conditions when T_J = 100 °C, V_{DD} = 1.14 V.

Table 307 • **USB Characteristics**

Parameter	Description	–1	–Std	Unit
FUSBREFCLK	Internally sourced USB reference clock frequency	166	142	MHz
TUSBCLK	USB clock period	16.66	16.66	ns
TUSBPD	Clock to USB data propagation delay	9.0	9.0	ns
TUSBSU	Setup time for USB data	6.0	6.0	ns
TUSBHD	Hold time for USB data	0	0	ns

2.3.34 MMUART Characteristics

The following table lists the MMUART characteristics in worst-case industrial conditions when T_J = 100 °C, V_{DD} = 1.14 V.

Table 308 • **MMUART Characteristics**

Parameter	Description	–1	–Std	Unit
FMMUART_REF_CLK	Internally sourced MMUART reference clock frequency.	166	142	MHz
BAUDMMUARTTx	Maximum transmit baud rate	10.375	8.875	Mbps
BAUDMMUARTRx	Maximum receive baud rate	10.375	8.875	Mbps

2.3.35 IGLOO2 Specifications

2.3.35.1 HPMS Clock Frequency

The following table lists the maximum frequency for HPMS main clock in worst-case industrial conditions when T_J = 100 °C, V_{DD} = 1.14 V.

Table 309 • **Maximum Frequency for HPMS Main Clock**

Symbol	Description	–1	–Std	Unit
HPMS_CLK	Maximum frequency for the HPMS main clock	166	142	MHz

2.3.35.2 IGLOO2 Serial Peripheral Interface (SPI) Characteristics

This section describes the DC and switching of the SPI interface. Unless otherwise noted, all output characteristics given are for a 35 pF load on the pins and all sequential timing characteristics are related to SPI_0_CLK. For timing parameter definitions, see Figure 23, page 131.

The following table lists the SPI characteristics in worst-case industrial conditions when T_J = 100 °C, V_{DD} = 1.14 V.

Table 310 • **SPI Characteristics for All Devices**

Symbol	Description	Min	Typ	Max	Unit	Conditions
SPIFMAX	Maximum operating frequency of SPI interface			20	MHz	
sp1	SPI_[0|1]_CLK minimum period					
	SPI_[0|1]_CLK = PCLK/2	12			ns	
	SPI_[0|1]_CLK = PCLK/4	24.1			ns	
	SPI_[0|1]_CLK = PCLK/8	48.2			ns	
	SPI_[0|1]_CLK = PCLK/16	0.1			µs	
	SPI_[0|1]_CLK = PCLK/32	0.19			µs	
	SPI_[0|1]_CLK = PCLK/64	0.39			µs	
	SPI_[0|1]_CLK = PCLK/128	0.77			µs	

Table 310 • **SPI Characteristics for All Devices *(continued)***

Symbol	Description	Min	Typ	Max	Unit	Conditions
sp2	SPI_[0|1]_CLK minimum pulse width high					
	SPI_[0|1]_CLK = PCLK/2	6			ns	
	SPI_[0|1]_CLK = PCLK/4	12.05			ns	
	SPI_[0|1]_CLK = PCLK/8	24.1			ns	
	SPI_[0|1]_CLK = PCLK/16	0.05			µs	
	SPI_[0|1]_CLK = PCLK/32	0.095			µs	
	SPI_[0|1]_CLK = PCLK/64	0.195			µs	
	SPI_[0|1]_CLK = PCLK/128	0.385			µs	
sp3	SPI_[0|1]_CLK minimum pulse width low					
	SPI_[0|1]_CLK = PCLK/2	6			ns	
	SPI_[0|1]_CLK = PCLK/4	12.05			ns	
	SPI_[0|1]_CLK = PCLK/8	24.1			ns	
	SPI_[0|1]_CLK = PCLK/16	0.05			µs	
	SPI_[0|1]_CLK = PCLK/32	0.095			µs	
	SPI_[0|1]_CLK = PCLK/64	0.195			µs	
	SPI_[0|1]_CLK = PCLK/128	0.385			µs	
sp4	SPI_[0|1]_CLK, SPI_[0|1]_DO, SPI_[0|1]_SS rise time (10%–90%)[1]		2.77		ns	I/O Configuration: LVCMOS 2.5 V - 8 mA AC loading: 35 pF test conditions: Typical voltage, 25 °C
sp5	SPI_[0|1]_CLK, SPI_[0|1]_DO, SPI_[0|1]_SS fall time (10%–90%)[1]		2.906		ns	I/O Configuration: LVCMOS 2.5 V - 8 mA AC loading: 35 pF test conditions: Typical voltage, 25 °C
SPI master configuration (applicable for 005, 010, 025, and 050 devices)						
sp6m	SPI_[0|1]_DO setup time[2]	(SPI_x_CLK_period/2) – 8.0			ns	
sp7m	SPI_[0|1]_DO hold time[2]	(SPI_x_CLK_period/2) – 2.5			ns	
sp8m	SPI_[0|1]_DI setup time[2]	12			ns	
sp9m	SPI_[0|1]_DI hold time[2]	2.5			ns	
SPI slave configuration (applicable for 005, 010, 025, and 050 devices)						
sp6s	SPI_[0|1]_DO setup time[2]	(SPI_x_CLK_period/2) – 17.0			ns	
sp7s	SPI_[0|1]_DO hold time[2]	(SPI_x_CLK_period/2) + 3.0			ns	
sp8s	SPI_[0|1]_DI setup time[2]	2			ns	
sp9s	SPI_[0|1]_DI hold time[2]	7			ns	