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Embedded - System On Chip (SoC): The Heart of Modern Embedded Systems

Embedded - System On Chip (SoC) refers to an integrated circuit that consolidates all the essential components of a computer system into a single chip. This includes a microprocessor, memory, and other peripherals, all packed into one compact and efficient package. SoCs are designed to provide a complete computing solution, optimizing both space and power consumption, making them ideal for a wide range of embedded applications.

What are Embedded - System On Chip (SoC)?

System On Chip (SoC) integrates multiple functions of a computer or electronic system onto a single chip. Unlike traditional multi-chip solutions, SoCs combine a central

Details

Product Status	Active
Architecture	MCU, FPGA
Core Processor	ARM® Cortex®-M3
Flash Size	256KB
RAM Size	64KB
Peripherals	DDR, PCIe, SERDES
Connectivity	CANbus, Ethernet, I ² C, SPI, UART/USART, USB
Speed	166MHz
Primary Attributes	FPGA - 60K Logic Modules
Operating Temperature	-40°C ~ 100°C (TJ)
Package / Case	676-BGA
Supplier Device Package	676-FBGA (27x27)
Purchase URL	https://www.e-xfl.com/product-detail/microchip-technology/m2s060ts-1fgg676i

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Table 9 • Package Thermal Resistance of SmartFusion2 and IGLOO2 Devices (continued)

Device	Still Air	1.0 m/s	2.5 m/s	θ_{JB}	θ_{JC}	Unit
	θ_{JA}					
150						
FC1152	9.08	6.81	5.87	2.56	0.38	°C/W
FCS536	15.01	12.06	10.76	3.69	1.55	°C/W
FCV484	16.21	13.11	11.84	6.73	0.10	°C/W

2.3.1.2.1 Theta-JA

Junction-to-ambient thermal resistance (θ_{JA}) is determined under standard conditions specified by JEDEC (JESD-51), but it has little relevance in the actual performance of the product. It must be used with caution, but it is useful for comparing the thermal performance of one package with another.

The maximum power dissipation allowed is calculated using EQ4.

$$\text{Maximum power allowed} = \frac{T_{J(\text{MAX})} - T_{A(\text{MAX})}}{\theta_{JA}}$$

EQ 4

The absolute maximum junction temperature is 100 °C. EQ5 shows a sample calculation of the absolute maximum power dissipation allowed for the M2GL050T-FG896 package at commercial temperature and in still air, where:

$$\theta_{JA} = 14.7 \text{ °C/W (taken from Table 9, page 10).}$$

$$T_A = 85 \text{ °C}$$

$$\text{Maximum power allowed} = \frac{100 \text{ °C} - 85 \text{ °C}}{14.7 \text{ °C/W}} = 1.088 \text{ W}$$

EQ 5

The power consumption of a device can be calculated using the Microsemi SoC Products Group power calculator. The device's power consumption must be lower than the calculated maximum power dissipation by the package.

If the power consumption is higher than the device's maximum allowable power dissipation, a heat sink may be attached to the top of the case, or the airflow inside the system must be increased.

2.3.1.2.2 Theta-JB

Junction-to-board thermal resistance (θ_{JB}) measures the ability of the package to dissipate heat from the surface of the chip to the PCB. As defined by the JEDEC (JESD-51) standard, the thermal resistance from the junction to the board uses an isothermal ring cold plate zone concept. The ring cold plate is simply a means to generate an isothermal boundary condition at the perimeter. The cold plate is mounted on a JEDEC standard board with a minimum distance of 5.0 mm away from the package edge.

2.3.1.2.3 Theta-JC

Junction-to-case thermal resistance (θ_{JC}) measures the ability of a device to dissipate heat from the surface of the chip to the top or bottom surface of the package. It is applicable to packages used with external heat sinks. Constant temperature is applied to the surface, which acts as a boundary condition.

This only applies to situations where all or nearly all of the heat is dissipated through the surface in consideration.

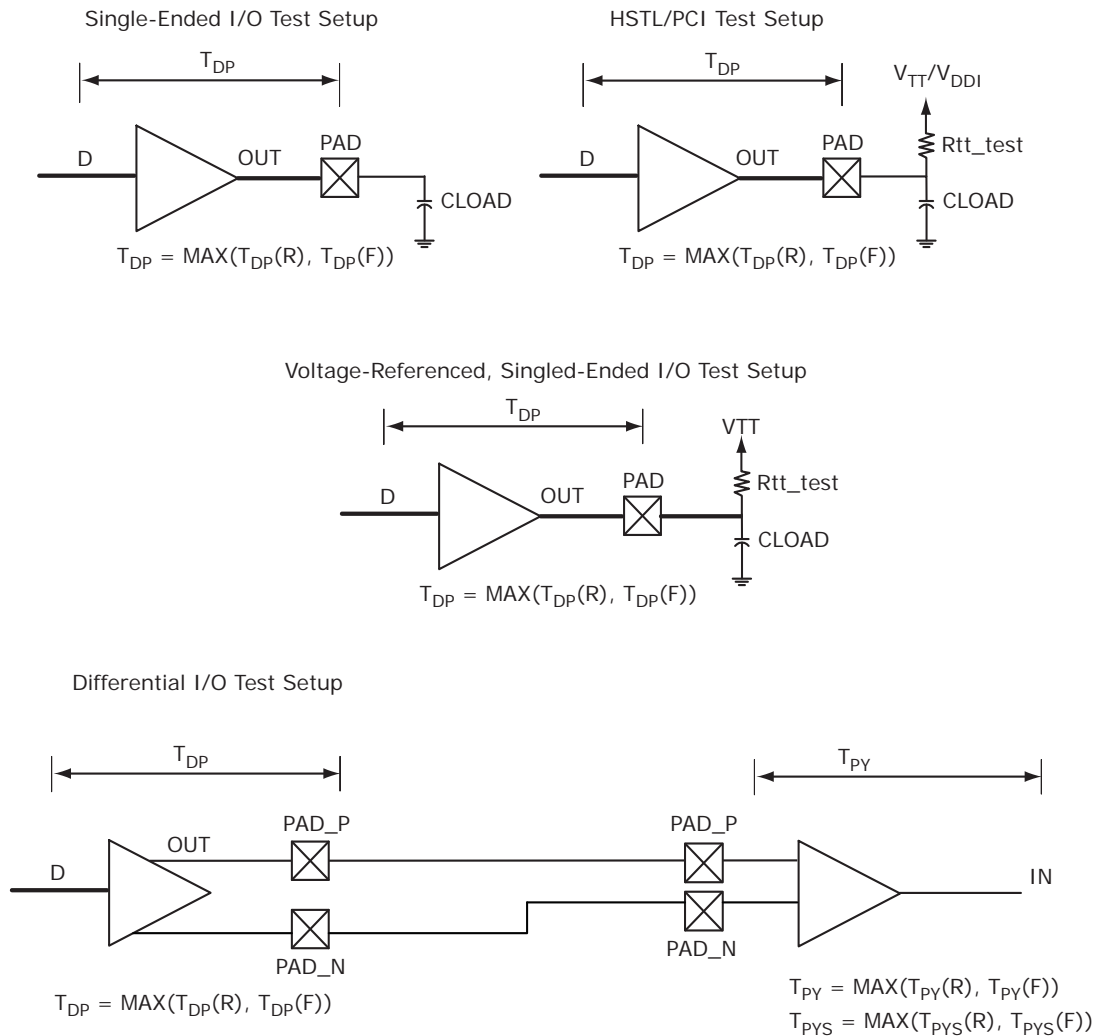
2.3.1.3 ESD Performance

See *RT0001: Microsemi Corporation - SoC Products Reliability Report* for information about ESD.

2.3.5.2 Output Buffer and AC Loading

The following figure shows the output buffer and AC loading.

Figure 4 • Output Buffer AC Loading



2.3.5.5 Detailed I/O Characteristics

Table 24 • Input Capacitance, Leakage Current, and Ramp Time

Symbol	Description	Maximum	Unit	Conditions
C_{IN}	Input capacitance	10	pF	
I_{IL} (dc)	Input current low (Applicable to HSTL/SSTL inputs only)	400	μ A	$V_{DDI} = 2.5$ V
		500	μ A	$V_{DDI} = 1.8$ V
		600	μ A	$V_{DDI} = 1.5$ V ¹
	Input current low (Applicable to all other digital inputs)	10	μ A	
I_{IH} (dc)	Input current high (Applicable to HSTL/SSTL inputs only)	400	μ A	$V_{DDI} = 2.5$ V
		500	μ A	$V_{DDI} = 1.8$ V
		600	μ A	$V_{DDI} = 1.5$ V ¹
	Input current high (Applicable to all other digital inputs)	10	μ A	
T_{RAMPIN} ²	Input ramp time (Applicable to all digital inputs)	50	ns	

1. Applicable when I/O pair is programmed with an HSTL/SSTL I/O type on IOP and an un-terminated I/O type (LVCMOS, for example) on ION pad.
2. Voltage ramp must be monotonic.

The following table lists the minimum and maximum I/O weak pull-up/pull-down resistance values of DDRIO I/O bank at V_{OH}/V_{OL} Level.

Table 25 • I/O Weak Pull-up/Pull-down Resistances for DDRIO I/O Bank

V_{DDI} Domain	R(WEAK PULL-UP) at V_{OH} (Ω)		R(WEAK PULL-DOWN) at V_{OL} (Ω)	
	Min	Max	Min	Max
2.5 V ^{1, 2}	10K	17.8K	9.98K	18K
1.8 V ^{1, 2}	10.3K	19.1K	10.3K	19.5K
1.5 V ^{1, 2}	10.6K	20.2K	10.6K	21.1K
1.2 V ^{1, 2}	11.1K	22.7K	11.2K	24.6K

1. $R(\text{WEAK PULL-DOWN}) = (V_{OLspec})/I(\text{WEAK PULL-DOWN MAX})$.
2. $R(\text{WEAK PULL-UP}) = (V_{DDImax} - V_{OHspec})/I(\text{WEAK PULL-UP MIN})$.

Table 53 • LVCMOS 1.8 V AC Calibrated Impedance Option

Parameter	Symbol	Typ	Unit
Supported output driver calibrated impedance (for DDRIO I/O bank)	Rodt_cal	75, 60, 50, 33, 25, 20	Ω

Table 54 • LVCMOS 1.8 V AC Test Parameter Specifications

Parameter	Symbol	Typ	Unit
Measuring/trip point for data path	V _{TRIP}	0.9	V
Resistance for enable path (T _{ZH} , T _{ZL} , T _{HZ} , T _{LZ})	R _{ENT}	2k	Ω
Capacitive loading for enable path (T _{ZH} , T _{ZL} , T _{HZ} , T _{LZ})	C _{ENT}	5	pF
Capacitive loading for data path (T _{DP})	C _{LOAD}	5	pF

Table 55 • LVCMOS 1.8 V Transmitter Drive Strength Specifications

Output Drive Selection			V _{OH} (V)	V _{OL} (V)	IOH (at V _{OH})	IOL (at V _{OL})
MSIO I/O Bank	MSIOD I/O Bank	DDRIO I/O Bank	Min	Max	mA	mA
2 mA	2 mA	2 mA	V _{DDI} - 0.45	0.45	2	2
4 mA	4 mA	4 mA	V _{DDI} - 0.45	0.45	4	4
6 mA	6 mA	6 mA	V _{DDI} - 0.45	0.45	6	6
8 mA	8 mA	8 mA	V _{DDI} - 0.45	0.45	8	8
10 mA	10 mA	10 mA	V _{DDI} - 0.45	0.45	10	10
12 mA		12 mA	V _{DDI} - 0.45	0.45	12	12
		16 mA ¹	V _{DDI} - 0.45	0.45	16	16

1. 16 mA drive strengths, all slews, meets LPDDR JEDEC electrical compliance.

AC Switching Characteristics

Worst commercial-case conditions: T_J = 85 °C, V_{DD} = 1.14 V, V_{DDI} = 1.71 V

Table 56 • LVCMOS 1.8 V Receiver Characteristics (Input Buffers)

	On-Die Termination (ODT)	T _{py}		T _{pys}		Unit
		-1	-Std	-1	-Std	
LVCMOS 1.8 V (for DDRIO I/O bank with Fixed Codes)	None	1.968	2.315	2.099	2.47	ns
	None	2.898	3.411	2.883	3.393	ns
	50	3.05	3.59	3.044	3.583	ns
	75	2.999	3.53	2.987	3.516	ns
LVCMOS 1.8 V (for MSIO I/O bank)	150	2.947	3.469	2.933	3.452	ns
	None	2.611	3.071	2.598	3.057	ns
	50	2.775	3.264	2.775	3.265	ns
LVCMOS 1.8 V (for MSIOD I/O bank)	75	2.72	3.2	2.712	3.19	ns
	150	2.666	3.137	2.655	3.123	ns

Table 131 • SSTL15 DC Output Voltage Specification (for DDRIO I/O Bank Only)

Parameter	Symbol	Min	Max	Unit
DDR3/SSTL15 Class I (DDR3 Reduced Drive)				
DC output logic high	V_{OH}	$0.8 \times V_{DDI}$		V
DC output logic low	V_{OL}		$0.2 \times V_{DDI}$	V
Output minimum source DC current	I_{OH} at V_{OH}	6.5		mA
Output minimum sink current	I_{OL} at V_{OL}	-6.5		mA
DDR3/SSTL15 Class II (DDR3 Full Drive)				
DC output logic high	V_{OH}	$0.8 \times V_{DDI}$		V
DC output logic low	V_{OL}		$0.2 \times V_{DDI}$	V
Output minimum source DC current	I_{OH} at V_{OH}	7.6		mA
Output minimum sink current	I_{OL} at V_{OL}	-7.6		mA

Table 132 • SSTL15 DC Differential Voltage Specification (for DDRIO I/O Bank Only)

Parameter	Symbol	Min	Unit
DC input differential voltage	V_{ID}	0.2	V

Note: To meet JEDEC electrical compliance, use DDR3 full drive transmitter.

Table 133 • SSTL15 AC SSTL15 Minimum and Maximum AC Switching Speed (for DDRIO I/O Bank Only)

Parameter	Symbol	Min	Max	Unit
AC input differential voltage	V_{DIFF} (AC)	0.3		V
AC differential cross point voltage	V_x (AC)	$0.5 \times V_{DDI} - 0.150$	$0.5 \times V_{DDI} + 0.150$	V

Table 134 • SSTL15 Minimum and Maximum AC Switching Speed (for DDRIO I/O Bank Only)

Parameter	Symbol	Max	Unit	Conditions
Maximum data rate	D_{MAX}	667	Mbps	AC loading: per JEDEC specifications

Table 135 • SSTL15 AC Calibrated Impedance Option (for DDRIO I/O Bank Only)

Parameter	Symbol	Typ	Unit	Conditions
Supported output driver calibrated impedance	R_{REF}	34, 40	Ω	Reference resistor = 240 Ω
Effective impedance value (ODT)	R_{TT}	20, 30, 40, 60, 120	Ω	Reference resistor = 240 Ω

Table 150 • LPDDR Full Drive for DDRIO I/O Bank (Output and Tristate Buffers)

	T_{DP}		T_{ENZL}		T_{ENZH}		T_{ENHZ}		T_{ENLZ}		Unit
	-1	-Std	-1	-Std	-1	-Std	-1	-Std	-1	-Std	
Single-ended	2.281	2.683	2.196	2.584	2.195	2.583	2.171	2.555	2.17	2.554	ns
Differential	2.298	2.703	2.288	2.692	2.288	2.692	2.593	3.051	2.593	3.051	ns

Minimum and Maximum DC/AC Input and Output Levels Specification using LPDDR-LVCMOS 1.8 V Mode

Table 151 • LPDDR-LVCMOS 1.8 V Mode Recommended DC Operating Conditions

Parameter	Symbol	Min	Typ	Max	Unit
Supply voltage	V_{DDI}	1.710	1.8	1.89	V

Table 152 • LPDDR-LVCMOS 1.8 V Mode DC Input Voltage Specification

Parameter	Symbol	Min	Max	Unit
DC input logic high (for MSIOD and DDRIO I/O banks)	$V_{IH} (DC)$	$0.65 \times V_{DDI}$	1.89	V
DC input logic high (for MSIO I/O bank)	$V_{IH} (DC)$	$0.65 \times V_{DDI}$	3.45	V
DC input logic low	$V_{IL} (DC)$	-0.3	$0.35 \times V_{DDI}$	V
Input current high ¹	$I_{IH} (DC)$			
Input current low ¹	$I_{IL} (DC)$			

1. See Table 24, page 22.

Table 153 • LPDDR-LVCMOS 1.8 V Mode DC Output Voltage Specification

Parameter	Symbol	Min	Max	Unit
DC output logic high	V_{OH}	$V_{DDI} - 0.45$		V
DC output logic low	V_{OL}		0.45	V

Table 154 • LPDDR-LVCMOS 1.8 V Minimum and Maximum AC Switching Speeds

Parameter	Symbol	Max	Unit	Conditions
Maximum data rate (for DDRIO I/O bank)	D_{MAX}	400	Mbps	AC loading: 17pf load, 8 ma drive and above/all slew

Table 155 • LPDDR-LVCMOS 1.8 V Calibrated Impedance Option

Parameter	Symbol	Typ	Unit
Supported output driver calibrated impedance (for DDRIO I/O bank)	RODT_CAL	75, 60, 50, 33, 25, 20	Ω

Table 159 • LPDDR-LVCMOS 1.8 V AC Switching Characteristics for Transmitter for DDRIO I/O Bank (Output and Tristate Buffers) (continued)

	medium	3.246	3.819	2.686	3.16	3.236	3.807	5.542	6.52	4.936	5.807	ns
	medium_fast	3.066	3.607	2.525	2.971	3.054	3.593	5.405	6.359	4.811	5.66	ns
	fast	3.046	3.584	2.513	2.957	3.034	3.57	5.401	6.353	4.803	5.651	ns
10 mA	slow	3.498	4.115	2.878	3.386	3.481	4.096	6.046	7.113	5.444	6.404	ns
	medium	3.138	3.692	2.569	3.023	3.126	3.678	5.782	6.803	5.129	6.034	ns
	medium_fast	2.966	3.489	2.414	2.841	2.951	3.472	5.666	6.665	5.013	5.897	ns
	fast	2.945	3.464	2.401	2.826	2.93	3.448	5.659	6.658	5.003	5.886	ns
12 mA	slow	3.417	4.02	2.807	3.303	3.401	4.002	6.083	7.156	5.464	6.428	ns
	medium	3.076	3.618	2.519	2.964	3.063	3.604	5.828	6.856	5.176	6.089	ns
	medium_fast	2.913	3.427	2.376	2.795	2.898	3.41	5.725	6.736	5.072	5.966	ns
	fast	2.894	3.405	2.362	2.78	2.879	3.388	5.715	6.724	5.064	5.957	ns
16 mA	slow	3.366	3.96	2.751	3.237	3.348	3.939	6.226	7.324	5.576	6.56	ns
	medium	3.03	3.565	2.47	2.906	3.017	3.55	5.981	7.036	5.282	6.214	ns
	medium_fast	2.87	3.377	2.328	2.739	2.854	3.358	5.895	6.935	5.18	6.094	ns
	fast	2.853	3.357	2.314	2.723	2.837	3.338	5.889	6.929	5.177	6.09	ns

1. Delay increases with drive strength are inherent to built-in slew control circuitry for simultaneous switching output (SSO management).

2.3.7 Differential I/O Standards

Configuration of the I/O modules as a differential pair is handled by Microsemi SoC Products Group Libero software when the user instantiates a differential I/O macro in the design. Differential I/Os can also be used in conjunction with the embedded Input register (InReg), Output register (OutReg), Enable register (EnReg), and Double Data Rate registers (DDR).

2.3.7.1 LVDS

Low-Voltage Differential Signaling (ANSI/TIA/EIA-644) is a high-speed, differential I/O standard.

Minimum and Maximum Input and Output Levels

Table 160 • LVDS Recommended DC Operating Conditions

Parameter	Symbol	Min	Typ	Max	Unit	Conditions
Supply voltage	V_{DDI}	2.375	2.5	2.625	V	2.5 V range
Supply voltage	V_{DDI}	3.15	3.3	3.45	V	3.3 V range

Table 161 • LVDS DC Input Voltage Specification

Parameter	Symbol	Min	Max	Unit	Conditions
DC Input voltage	V_I	0	2.925	V	2.5 V range
DC input voltage	V_I	0	3.45	V	3.3 V range
Input current high ¹	I_{IH} (DC)				
Input current low ¹	I_{IL} (DC)				

1. See Table 24, page 22.

AC Switching Characteristics

Worst commercial-case conditions: $T_J = 85\text{ }^\circ\text{C}$, $V_{DD} = 1.14\text{ V}$, $V_{DDI} = 2.375\text{ V}$.

Table 180 • B-LVDS AC Switching Characteristics for Receiver for MSIO I/O Bank (Input Buffers)

On-Die Termination (ODT)	T_{PY}		Unit
	-1	-Std	
None	2.738	3.221	ns
100	2.735	3.218	ns

Table 181 • B-LVDS AC Switching Characteristics for Receiver for MSIOD I/O Bank (Input Buffers)

On-Die Termination (ODT)	T_{PY}		Unit
	-1	-Std	
None	2.495	2.934	ns
100	2.495	2.935	ns

Table 182 • B-LVDS AC Switching Characteristics for Transmitter (for MSIO I/O Bank - Output and Tristate Buffers)

T_{DP}		T_{ZL}		T_{ZH}		T_{HZ}		T_{LZ}		Unit
-1	-Std	-1	-Std	-1	-Std	-1	-Std	-1	-Std	
2.258	2.656	2.343	2.756	2.329	2.74	2.12	2.494	2.123	2.497	ns

2.3.7.3 M-LVDS

M-LVDS specifications extend the existing LVDS standard to high-performance multipoint bus applications. Multidrop and multipoint bus configurations may contain any combination of drivers, receivers, and transceivers.

Minimum and Maximum Input and Output Levels

Table 183 • M-LVDS Recommended DC Operating Conditions

Parameter	Symbol	Min	Typ	Max	Unit
Supply voltage ¹	V_{DDI}	2.375	2.5	2.625	V

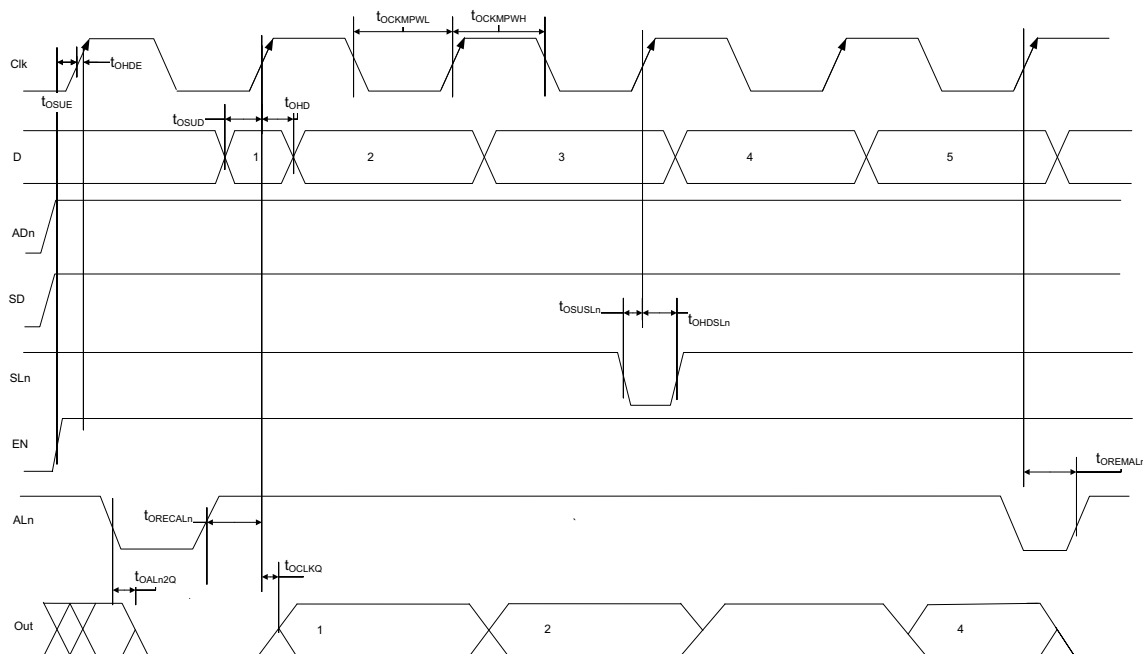
1. Only M-LVDS TYPE I is supported.

Table 184 • M-LVDS DC Input Voltage Specification

Parameter	Symbol	Min	Max	Unit
DC input voltage	V_I	0	2.925	V
Input current high ¹	I_{IH} (DC)			
Input current low ²	I_{IL} (DC)			

1. See Table 24, page 22.

Figure 9 • I/O Register Output Timing Diagram



The following table lists the output/enable propagation delays in worst commercial-case conditions when $T_J = 85\text{ }^\circ\text{C}$, $V_{DD} = 1.14\text{ V}$.

Table 220 • Output/Enable Data Register Propagation Delays

Parameter	Symbol	Measuring Nodes (from, to) ¹	-1		Unit
			-1	-Std	
Bypass delay of the output/enable register	T_{OBYP}	F, G or H, I	0.353	0.415	ns
Clock-to-Q of the output/enable register	T_{OCLKQ}	E, G or E, I	0.263	0.309	ns
Data setup time for the output/enable register	T_{OSUD}	A, E or J, E	0.19	0.223	ns
Data hold time for the output/enable register	T_{OHD}	A, E or J, E	0	0	ns
Enable setup time for the output/enable register	T_{OSUE}	B, E	0.419	0.493	ns
Enable hold time for the output/enable register	T_{OHE}	B, E	0	0	ns
Synchronous load setup time for the output/enable register	T_{OSUSL}	D, E	0.196	0.231	ns
Synchronous load hold time for the output/enable register	T_{OHSL}	D, E	0	0	ns
Asynchronous clear-to-q of the output/enable register (ADn = 1)	T_{OALN2Q}	C, G or C, I	0.505	0.594	ns
Asynchronous preset-to-q of the output/enable register (ADn = 0)		C, G or C, I	0.528	0.621	ns
Asynchronous load removal time for the output/enable register	$T_{OREMALN}$	C, E	0	0	ns
Asynchronous load recovery time for the output/enable register	$T_{ORECALN}$	C, E	0.034	0.04	ns
Asynchronous load minimum pulse width for the output/enable register	T_{OWALN}	C, C	0.304	0.357	ns
Clock minimum pulse width high for the output/enable register	$T_{OACKMPWH}$	E, E	0.075	0.088	ns
Clock minimum pulse width low for the output/enable register	$T_{OACKMPWL}$	E, E	0.159	0.187	ns

1. For the derating values at specific junction temperature and voltage supply levels, see Table 16, page 14 for derating values.

2.3.11 Global Resource Characteristics

The IGLOO2 and SmartFusion2 SoC FPGA devices offer a powerful, low skew global routing network which provides an effective clock distribution throughout the FPGA fabric. See [UG0445: IGLOO2 FPGA and SmartFusion2 SoC FPGA Fabric User Guide](#) for the positions of various global routing resources.

The following table lists the 150 device global resources in worst commercial-case conditions when $T_J = 85\text{ }^\circ\text{C}$, $V_{DD} = 1.14\text{ V}$.

Table 225 • 150 Device Global Resource

Parameter	Symbol	-1		-Std		Unit
		Min	Max	Min	Max	
Input low delay for global clock	T_{RCKL}	0.83	0.911	0.831	0.913	ns
Input high delay for global clock	T_{RCKH}	1.457	1.588	1.715	1.869	ns
Maximum skew for global clock	T_{RCKSW}		0.131		0.154	ns

The following table lists the 090 device global resources in worst commercial-case conditions when $T_J = 85\text{ }^\circ\text{C}$, $V_{DD} = 1.14\text{ V}$.

Table 226 • 090 Device Global Resource

Parameter	Symbol	-1		-Std		Unit
		Min	Max	Min	Max	
Input low delay for global clock	T_{RCKL}	0.835	0.888	0.833	0.886	ns
Input high delay for global clock	T_{RCKH}	1.405	1.489	1.654	1.752	ns
Maximum skew for global clock	T_{RCKSW}		0.084		0.098	ns

The following table lists the 050 device global resources in worst commercial-case conditions when $T_J = 85\text{ }^\circ\text{C}$, $V_{DD} = 1.14\text{ V}$.

Table 227 • 050 Device Global Resource

Parameter	Symbol	-1		-Std		Unit
		Min	Max	Min	Max	
Input low delay for global clock	T_{RCKL}	0.827	0.897	0.826	0.896	ns
Input high delay for global clock	T_{RCKH}	1.419	1.53	1.671	1.8	ns
Maximum skew for global clock	T_{RCKSW}		0.111		0.129	ns

The following table lists the 025 device global resources in worst commercial-case conditions when $T_J = 85\text{ }^\circ\text{C}$, $V_{DD} = 1.14\text{ V}$.

Table 228 • 025 Device Global Resource

Parameter	Symbol	-1		-Std		Unit
		Min	Max	Min	Max	
Input low delay for global clock	T_{RCKL}	0.747	0.799	0.745	0.797	ns
Input high delay for global clock	T_{RCKH}	1.294	1.378	1.522	1.621	ns
Maximum skew for global clock	T_{RCKSW}		0.084		0.099	ns

Table 232 • RAM1K18 – Dual-Port Mode for Depth × Width Configuration 2K × 9 (continued)

Parameter	Symbol	–1		–Std		Unit
		Min	Max	Min	Max	
Address setup time	T_{ADDRSU}	0.475		0.559		ns
Address hold time	T_{ADDRHD}	0.274		0.322		ns
Data setup time	T_{DSU}	0.336		0.395		ns
Data hold time	T_{DHD}	0.082		0.096		ns
Block select setup time	T_{BLKSU}	0.207		0.244		ns
Block select hold time	T_{BLKHD}	0.216		0.254		ns
Block select to out disable time (when pipelined register is disabled)	T_{BLK2Q}		1.529		1.799	ns
Block select minimum pulse width	T_{BLKMPW}	0.186		0.219		ns
Read enable setup time	T_{RDESU}	0.485		0.57		ns
Read enable hold time	T_{RDEHD}	0.071		0.083		ns
Pipelined read enable setup time (A_DOUT_EN, B_DOUT_EN)	$T_{RDPLESU}$	0.248		0.291		ns
Pipelined read enable hold time (A_DOUT_EN, B_DOUT_EN)	$T_{RDPLEHD}$	0.102		0.12		ns
Asynchronous reset to output propagation delay	T_{R2Q}		1.514		1.781	ns
Asynchronous reset removal time	T_{RSTREM}	0.506		0.595		ns
Asynchronous reset recovery time	T_{RSTREC}	0.004		0.005		ns
Asynchronous reset minimum pulse width	T_{RSTMPW}	0.301		0.354		ns
Pipelined register asynchronous reset removal time	$T_{PLRSTREM}$	–0.279		–0.328		ns
Pipelined register asynchronous reset recovery time	$T_{PLRSTREC}$	0.327		0.385		ns
Pipelined register asynchronous reset minimum pulse width	$T_{PLRSTMPW}$	0.282		0.332		ns
Synchronous reset setup time	T_{SRSTSU}	0.226		0.265		ns
Synchronous reset hold time	T_{SRSTHD}	0.036		0.043		ns
Write enable setup time	T_{WESU}	0.415		0.488		ns
Write enable hold time	T_{WEHD}	0.048		0.057		ns
Maximum frequency	F_{MAX}		400		340	MHz

The following table lists the RAM1K18 – dual-port mode for depth × width configuration 4K × 4 in worst commercial-case conditions when $T_J = 85\text{ }^\circ\text{C}$, $V_{DD} = 1.14\text{ V}$.

Table 233 • RAM1K18 – Dual-Port Mode for Depth × Width Configuration 4K × 4

Parameter	Symbol	–1		–Std		Unit
		Min	Max	Min	Max	
Clock period	T_{CY}	2.5		2.941		ns
Clock minimum pulse width high	$T_{CLKMPWH}$	1.125		1.323		ns
Clock minimum pulse width low	$T_{CLKMPWL}$	1.125		1.323		ns
Pipelined clock period	T_{PLCY}	2.5		2.941		ns
Pipelined clock minimum pulse width high	$T_{PLCLKMPWH}$	1.125		1.323		ns

The following table lists the RAM1K18 – dual-port mode for depth × width configuration 8K × 2 in worst commercial-case conditions when $T_J = 85\text{ }^\circ\text{C}$, $V_{DD} = 1.14\text{ V}$.

Table 234 • RAM1K18 – Dual-Port Mode for Depth × Width Configuration 8K × 2

Parameter	Symbol	–1		–Std		Unit
		Min	Max	Min	Max	
Clock period	T_{CY}	2.5		2.941		ns
Clock minimum pulse width high	$T_{CLKMPWH}$	1.125		1.323		ns
Clock minimum pulse width low	$T_{CLKMPWL}$	1.125		1.323		ns
Pipelined clock period	T_{PLCY}	2.5		2.941		ns
Pipelined clock minimum pulse width high	$T_{PLCLKMPWH}$	1.125		1.323		ns
Pipelined clock minimum pulse width low	$T_{PLCLKMPWL}$	1.125		1.323		ns
Read access time with pipeline register				0.32	0.377	ns
Read access time without pipeline register	T_{CLK2Q}			2.272	2.673	ns
Access time with feed-through write timing				1.511	1.778	ns
Address setup time	T_{ADDRSU}	0.612		0.72		ns
Address hold time	T_{ADDRHD}	0.274		0.322		ns
Data setup time	T_{DSU}	0.33		0.388		ns
Data hold time	T_{DHD}	0.082		0.096		ns
Block select setup time	T_{BLKSU}	0.207		0.244		ns
Block select hold time	T_{BLKHD}	0.216		0.254		ns
Block select to out disable time (when pipelined register is disabled)	T_{BLK2Q}			1.511	1.778	ns
Block select minimum pulse width	T_{BLKMPW}	0.186		0.219		ns
Read enable setup time	T_{RDESU}	0.529		0.622		ns
Read enable hold time	T_{RDEHD}	0.071		0.083		ns
Pipelined read enable setup time (A_DOUT_EN, B_DOUT_EN)	$T_{RDPLESU}$	0.248		0.291		ns
Pipelined read enable hold time (A_DOUT_EN, B_DOUT_EN)	$T_{RDPLEHD}$	0.102		0.12		ns
Asynchronous reset to output propagation delay	T_{R2Q}			1.528	1.797	ns
Asynchronous reset removal time	T_{RSTREM}	0.506		0.595		ns
Asynchronous reset recovery time	T_{RSTREC}	0.004		0.005		ns
Asynchronous reset minimum pulse width	T_{RSTMPW}	0.301		0.354		ns
Pipelined register asynchronous reset removal time	$T_{PLRSTREM}$	–0.279		–0.328		ns
Pipelined register asynchronous reset recovery time	$T_{PLRSTREC}$	0.327		0.385		ns
Pipelined register asynchronous reset minimum pulse width	$T_{PLRSTMPW}$	0.282		0.332		ns
Synchronous reset setup time	T_{SRSTSU}	0.226		0.265		ns
Synchronous reset hold time	T_{SRSTHD}	0.036		0.043		ns
Write enable setup time	T_{WESU}	0.488		0.574		ns
Write enable hold time	T_{WEHD}	0.048		0.057		ns
Maximum frequency	F_{MAX}			400	340	MHz

Table 259 • 2 Step IAP Programming (Fabric Only)

M2S/M2GL Device	Image size		Authenticate	Program	Verify	Unit
	Bytes					
005	302672	4	39	6	Sec	
010	568784	7	45	12	Sec	
025	1223504	14	55	23	Sec	
050	2424832	29	74	40	Sec	
060	2418896	39	83	50	Sec	
090	3645968	60	106	73	Sec	
150	6139184	100	154	120	Sec	

Table 260 • 2 Step IAP Programming (eNVM Only)

M2S/M2GL Device	Image size		Authenticate	Program	Verify	Unit
	Bytes					
005	137536	2	59	5	Sec	
010	274816	4	98	11	Sec	
025	274816	4	100	10	Sec	
050	2,78,528	3	107	9	Sec	
060	268480	5	98	22	Sec	
090	544496	10	174	43	Sec	
150	544496	10	175	44	Sec	

Table 261 • 2 Step IAP Programming (Fabric and eNVM)

M2S/M2GL Device	Image size		Authenticate	Program	Verify	Unit
	Bytes					
005	439296	6	78	11	Sec	
010	842688	11	122	21	Sec	
025	1497408	19	135	32	Sec	
050	2695168	32	158	48	Sec	
060	2686464	43	159	70	Sec	
090	4190208	68	258	115	Sec	
150	6682768	109	308	162	Sec	

Table 276 • Cryptographic Block Characteristics (continued)

Service	Conditions	Timing	Unit
SHA256	512 bits	540	kbps
	1024 bits	780	kbps
	2048 bits	950	kbps
	24 kbits	1140	kbps
HMAC	512 bytes	820	kbps
	1024 bytes	890	kbps
	2048 bytes	930	kbps
	24 kbytes	980	kbps
KeyTree		1.8	ms
Challenge-response	PUF = OFF	25	ms
	PUF = ON	7	ms
ECC point multiplication		590	ms
ECC point addition		8	ms

1. Using cypher block chaining (CBC) mode.

2.3.19 Crystal Oscillator

The following table describes the electrical characteristics of the crystal oscillator in the IGLOO2 FPGA and SmartFusion2 SoC FPGAs.

Table 277 • Electrical Characteristics of the Crystal Oscillator – High Gain Mode (20 MHz)

Parameter	Symbol	Min	Typ	Max	Unit	Condition
Operating frequency	FXTAL		20		MHz	
Accuracy	ACCXTAL			0.0047	%	005, 010, 025, 050, 060, and 090 devices
				0.0058	%	150 devices
Output duty cycle	CYCXTAL		49–51	47–53	%	
Output period jitter (peak to peak)	JITPERXTAL		200	300	ps	
Output cycle to cycle jitter (peak to peak)	JITCYCXTAL		200	300	ps	010, 025, 050, and 060 devices
			250	410	ps	150 devices
			250	550	ps	005 and 090 devices
Operating current	IDYNXTAL		1.5		mA	010, 050, and 060 devices
			1.65		mA	005, 025, 090, and 150 devices
Input logic level high	VIHXTAL	0.9 V _{PP}			V	
Input logic level low	VILXTAL			0.1 V _{PP}	V	

Table 277 • Electrical Characteristics of the Crystal Oscillator – High Gain Mode (20 MHz) (continued)

Parameter	Symbol	Min	Typ	Max	Unit	Condition
Startup time (with regard to stable oscillator output)	SUXTAL			0.8	ms	005, 010, 025, and 050 devices
				1.0	ms	090 and 150 devices

Table 278 • Electrical Characteristics of the Crystal Oscillator – Medium Gain Mode (2 MHz)

Parameter	Symbol	Min	Typ	Max	Unit	Condition
Operating frequency	FXTAL		2		MHz	
Accuracy	ACCXTAL			0.00105	%	050 devices
				0.003	%	005, 010, 025, 090, and 150 devices
				0.004	%	060 devices
Output duty cycle	CYCXTAL		49–51	47–53	%	
Output period jitter (peak to peak)	JITPERXTAL		1	5	ns	
Output cycle to cycle jitter (peak to peak)	JITCYCXTAL		1	5	ns	
Operating current	IDYNXTAL		0.3		mA	
Input logic level high	VIHXTAL	0.9 V _{PP}			V	
Input logic level low	VILXTAL			0.1 V _{PP}	V	
Startup time (with regard to stable oscillator output)	SUXTAL			4.5	ms	010 and 050 devices
				5	ms	005 and 025 devices
				7	ms	090 and 150 devices

Table 279 • Electrical Characteristics of the Crystal Oscillator – Low Gain Mode (32 kHz)

Parameter	Symbol	Min	Typ	Max	Unit	Condition
Operating frequency	FXTAL		32		kHz	
Accuracy	ACCXTAL			0.004	%	005, 010, 025, 050, 060, and 090 devices
				0.005	%	150 devices
Output duty cycle	CYCXTAL		49–51	47–53	%	
Output period jitter (peak to peak)	JITPERXTAL		150	300	ns	
Output cycle to cycle jitter (peak to peak)	JITCYCXTAL		150	300	ns	
Operating current	IDYNXTAL		0.044		mA	010 and 050 devices
			0.060		mA	005, 025, 060, 090, and 150 devices
Input logic level high	VIHXTAL	0.9 V _{PP}			V	
Input logic level low	VILXTAL			0.1 V _{PP}	V	
Startup time (with regard to stable oscillator output)	SUXTAL			115	ms	005, 025, 050, 090, and 150 devices
				126	ms	010 devices

The following table lists the IGLOO2 DEVRST_N to functional times in worst-case industrial conditions when $T_J = 100\text{ }^\circ\text{C}$, $V_{DD} = 1.14\text{ V}$.

Table 292 • DEVRST_N to Functional Times for IGLOO2

Symbol	From	To	Description	Maximum Power-up to Functional Time for IGLOO2 (uS)						
				005	010	025	050	060	090	150
$T_{POR2OUT}$	POWER_ON_RESET_N	Output available at I/O	Fabric to output	114	116	113	113	115	115	114
$T_{DEVRST2OUT}$	DEVRST_N	Output available at I/O	V_{DD} at its minimum threshold level to output	314	353	314	307	343	341	341
$T_{DEVRST2POR}$	DEVRST_N	POWER_ON_RESET_N	V_{DD} at its minimum threshold level to fabric	200	238	201	195	230	229	227
$T_{DEVRST2WPU}$	DEVRST_N	DDRIO Inbuf weak pull	DEVRST_N to Inbuf weak pull	208	202	197	193	216	215	215
	DEVRST_N	MSIO Inbuf weak pull	DEVRST_N to Inbuf weak pull	208	202	197	193	216	215	215
	DEVRST_N	MSIOD Inbuf weak pull	DEVRST_N to Inbuf weak pull	208	202	197	193	216	215	215

2.3.30 SerDes Electrical and Timing AC and DC Characteristics

PCIe is a high-speed, packet-based, point-to-point, low-pin-count, serial interconnect bus. The IGLOO2 and SmartFusion2 SoC FPGAs has up to four hard high-speed serial interface blocks. Each SerDes block contains a PCIe system block. The PCIe system is connected to the SerDes block.

The following table lists the transmitter parameters in worst-case industrial conditions when $T_J = 100\text{ }^\circ\text{C}$, $V_{DD} = 1.14\text{ V}$.

Table 296 • Transmitter Parameters

Symbol	Description	Min	Max	Unit
VTX-DIFF-PP	Differential swing (2.5 Gbps, 5.0 Gbps)	0.8	1.2	V
VTX-CM-AC-P	Output common mode voltage (2.5 Gbps)		20	mV
VTX-CM-AC-PP	Output common mode voltage (5.0 Gbps)		100	mV
VTX-RISE-FALL	Rise and fall time (20% to 80%, 2.5 Gbps)	0.125		UI
	Rise and fall time (20% to 80%, 5.0 Gbps)	0.15		UI
ZTX-DIFF-DC	Output impedance–differential	80	120	Ω
LTX-SKEW	Lane-to-lane TX skew within a SerDes block (2.5 Gbps)		500 ps + 2 UI	ps
	Lane-to-lane TX skew within a SerDes block (5.0 Gbps)		500 ps + 4 UI	ps
RLTX-DIFF	Return loss differential mode (2.5 Gbps)	–10		dB
	Return loss differential mode (5.0 Gbps) 0.05 GHz to 1.25 GHz	–10		dB
	1.25 GHz to 2.5 GHz	–8		dB
RLTX-CM	Return loss common mode (2.5 Gbps, 5.0 Gbps)	–6		dB
TX-LOCK-RST	Transmit PLL lock time from reset		10	μs
VTX-AMP	100 mV setting	90	150	mV
	400 mV setting	320	480	mV
	800 mV setting	660	940	mV
	1200 mV setting	950	1400	mV

Table 303 • I2C Characteristics (continued)

Parameter	Symbol	Min	Typ	Max	Unit	Conditions
Maximum data rate	D_{MAX}			400	Kbps	Fast mode
				100	Kbps	Standard mode
Pulse width of spikes which must be suppressed by the input filter	T_{FILT}		50		ns	Fast mode

1. These values are provided for MSIO Bank–LVTTTL 8 mA Low Drive at 25 °C, typical conditions. For board design considerations and detailed output buffer resistances, use the corresponding IBIS models located on the SoC Products Group website: <http://www.microsemi.com/soc/download/ibis/default.aspx>.
2. These maximum values are provided for information only. Minimum output buffer resistance values depend on V_{DDIX} , drive strength selection, temperature, and process. For board design considerations and detailed output buffer resistances, use the corresponding IBIS models located on the SoC Products Group website: <http://www.microsemi.com/soc/download/ibis/default.aspx>.
3. $R(PULL-DOWN-MAX) = (VOLspec)/IOLspec$.
4. $R(PULL-UP-MAX) = (VDDImax-VOHspec)/IOHspec$.

The following table lists the I²C switching characteristics in worst-case industrial conditions when $T_J = 100\text{ °C}$, $V_{DD} = 1.14\text{ V}$

Table 304 • I2C Switching Characteristics

Parameter	Symbol	-1		Unit
		Min	Min	
Low period of I2C_x_SCL	T_{LOW}	1	1	PCLK cycles
High period of I2C_x_SCL	T_{HIGH}	1	1	PCLK cycles
START hold time	$T_{HD;STA}$	1	1	PCLK cycles
START setup time	$T_{SU;STA}$	1	1	PCLK cycles
DATA hold time	$T_{HD;DAT}$	1	1	PCLK cycles
DATA setup time	$T_{SU;DAT}$	1	1	PCLK cycles
STOP setup time	$T_{SU;STO}$	1	1	PCLK cycles

Figure 21 • I²C Timing Parameter Definition

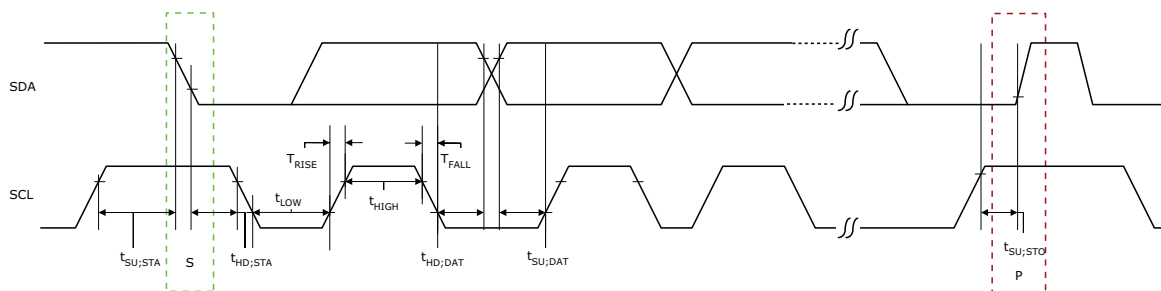


Table 310 • SPI Characteristics for All Devices (continued)

Symbol	Description	Min	Typ	Max	Unit	Conditions
sp2	SPI_[0 1]_CLK minimum pulse width high					
	SPI_[0 1]_CLK = PCLK/2	6			ns	
	SPI_[0 1]_CLK = PCLK/4	12.05			ns	
	SPI_[0 1]_CLK = PCLK/8	24.1			ns	
	SPI_[0 1]_CLK = PCLK/16	0.05			µs	
	SPI_[0 1]_CLK = PCLK/32	0.095			µs	
	SPI_[0 1]_CLK = PCLK/64	0.195			µs	
	SPI_[0 1]_CLK = PCLK/128	0.385			µs	
sp3	SPI_[0 1]_CLK minimum pulse width low					
	SPI_[0 1]_CLK = PCLK/2	6			ns	
	SPI_[0 1]_CLK = PCLK/4	12.05			ns	
	SPI_[0 1]_CLK = PCLK/8	24.1			ns	
	SPI_[0 1]_CLK = PCLK/16	0.05			µs	
	SPI_[0 1]_CLK = PCLK/32	0.095			µs	
	SPI_[0 1]_CLK = PCLK/64	0.195			µs	
	SPI_[0 1]_CLK = PCLK/128	0.385			µs	
sp4	SPI_[0 1]_CLK, SPI_[0 1]_DO, SPI_[0 1]_SS rise time (10%–90%) ¹		2.77		ns	I/O Configuration: LVCMOS 2.5 V - 8 mA AC loading: 35 pF test conditions: Typical voltage, 25 °C
sp5	SPI_[0 1]_CLK, SPI_[0 1]_DO, SPI_[0 1]_SS fall time (10%–90%) ¹		2.906		ns	I/O Configuration: LVCMOS 2.5 V - 8 mA AC loading: 35 pF test conditions: Typical voltage, 25 °C
SPI master configuration (applicable for 005, 010, 025, and 050 devices)						
sp6m	SPI_[0 1]_DO setup time ²	(SPI_x_CLK_period/2) – 8.0			ns	
sp7m	SPI_[0 1]_DO hold time ²	(SPI_x_CLK_period/2) – 2.5			ns	
sp8m	SPI_[0 1]_DI setup time ²	12			ns	
sp9m	SPI_[0 1]_DI hold time ²	2.5			ns	
SPI slave configuration (applicable for 005, 010, 025, and 050 devices)						
sp6s	SPI_[0 1]_DO setup time ²	(SPI_x_CLK_period/2) – 17.0			ns	
sp7s	SPI_[0 1]_DO hold time ²	(SPI_x_CLK_period/2) + 3.0			ns	
sp8s	SPI_[0 1]_DI setup time ²	2			ns	
sp9s	SPI_[0 1]_DI hold time ²	7			ns	