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Embedded - System On Chip (SoC): The Heart of Modern Embedded Systems

Embedded - System On Chip (SoC) refers to an integrated circuit that consolidates all the essential components of a computer system into a single chip. This includes a microprocessor, memory, and other peripherals, all packed into one compact and efficient package. SoCs are designed to provide a complete computing solution, optimizing both space and power consumption, making them ideal for a wide range of embedded applications.

What are Embedded - System On Chip (SoC)?

System On Chip (SoC) integrates multiple functions of a computer or electronic system onto a single chip. Unlike traditional multi-chip solutions, SoCs combine a central

Details

Product Status	Active
Architecture	MCU, FPGA
Core Processor	ARM® Cortex®-M3
Flash Size	256KB
RAM Size	64KB
Peripherals	DDR, PCIe, SERDES
Connectivity	CANbus, Ethernet, I ² C, SPI, UART/USART, USB
Speed	166MHz
Primary Attributes	FPGA - 60K Logic Modules
Operating Temperature	-40°C ~ 100°C (TJ)
Package / Case	676-BGA
Supplier Device Package	676-FBGA (27x27)
Purchase URL	https://www.e-xfl.com/product-detail/microchip-technology/m2s060ts-fg676i

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Table 9 • Package Thermal Resistance of SmartFusion2 and IGLOO2 Devices (continued)

Device	Still Air	1.0 m/s	2.5 m/s	χ_{JB}	χ_{JC}	Unit
	χ_{JA}					
150						
FC1152	9.08	6.81	5.87	2.56	0.38	°C/W
FCS536	15.01	12.06	10.76	3.69	1.55	°C/W
FCV484	16.21	13.11	11.84	6.73	0.10	°C/W

2.3.1.2.1 Theta-JA

Junction-to-ambient thermal resistance (χ_{JA}) is determined under standard conditions specified by JEDEC (JESD-51), but it has little relevance in the actual performance of the product. It must be used with caution, but it is useful for comparing the thermal performance of one package with another.

The maximum power dissipation allowed is calculated using EQ4.

$$\text{Maximum power allowed} = \frac{T_{J(\text{MAX})} - T_{A(\text{MAX})}}{\chi_{JA}}$$

EQ4

The absolute maximum junction temperature is 100 °C. EQ5 shows a sample calculation of the absolute maximum power dissipation allowed for the M2GL050T-FG896 package at commercial temperature and in still air, where:

$$\chi_{JA} = 14.7 \text{ °C/W (taken from Table 9, page 10).}$$

$$T_A = 85 \text{ °C}$$

$$\text{Maximum power allowed} = \frac{100 \text{ °C} - 85 \text{ °C}}{14.7 \text{ °C/W}} = 1.088 \text{ W}$$

EQ5

The power consumption of a device can be calculated using the Microsemi SoC Products Group power calculator. The device's power consumption must be lower than the calculated maximum power dissipation by the package.

If the power consumption is higher than the device's maximum allowable power dissipation, a heat sink may be attached to the top of the case, or the airflow inside the system must be increased.

2.3.1.2.2 Theta-JB

Junction-to-board thermal resistance (χ_{JB}) measures the ability of the package to dissipate heat from the surface of the chip to the PCB. As defined by the JEDEC (JESD-51) standard, the thermal resistance from the junction to the board uses an isothermal ring cold plate zone concept. The ring cold plate is simply a means to generate an isothermal boundary condition at the perimeter. The cold plate is mounted on a JEDEC standard board with a minimum distance of 5.0 mm away from the package edge.

2.3.1.2.3 Theta-JC

Junction-to-case thermal resistance (χ_{JC}) measures the ability of a device to dissipate heat from the surface of the chip to the top or bottom surface of the package. It is applicable to packages used with external heat sinks. Constant temperature is applied to the surface, which acts as a boundary condition.

This only applies to situations where all or nearly all of the heat is dissipated through the surface in consideration.

2.3.1.3 ESD Performance

See [R001: MIP](#)

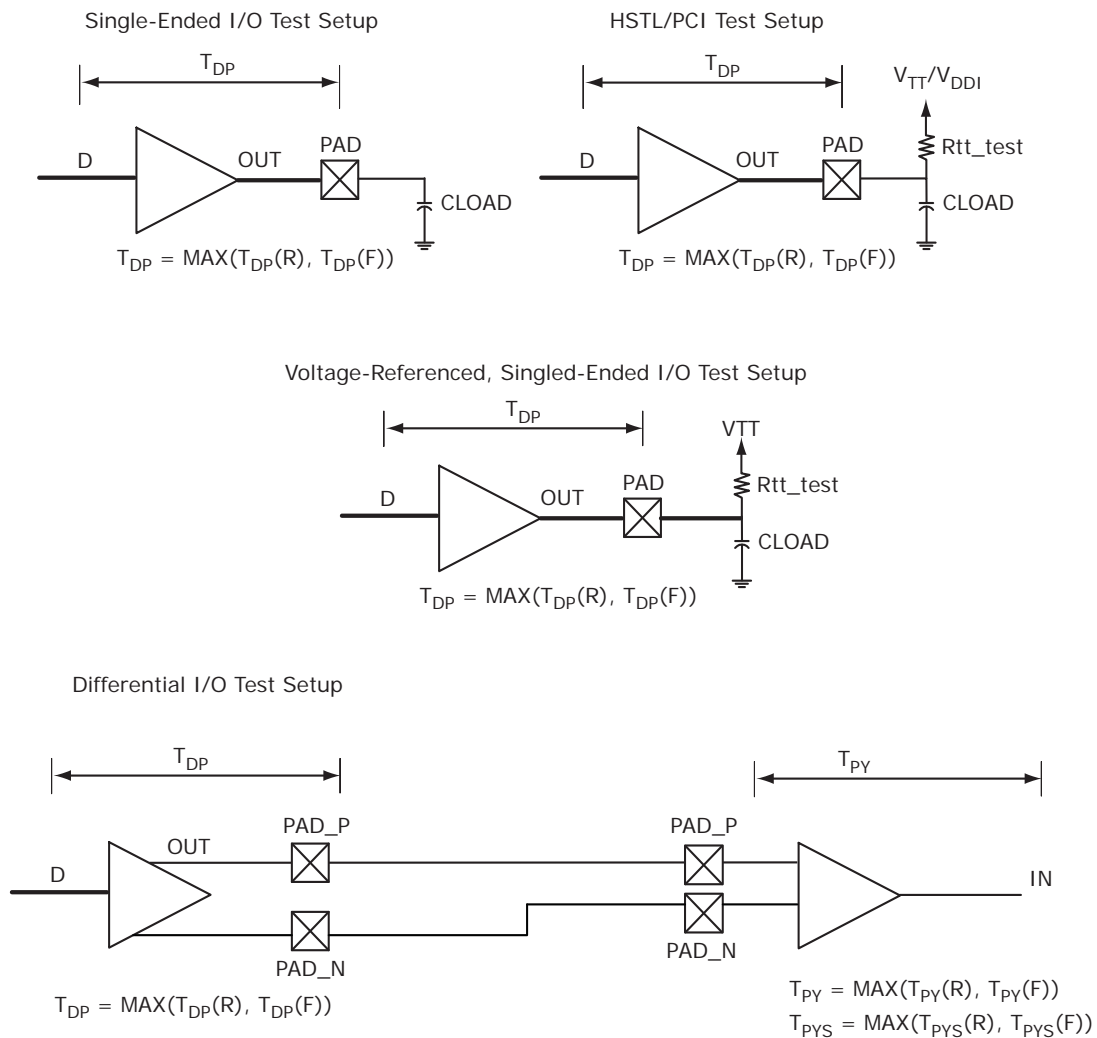


for information about ESD.

2.3.5.2 Output Buffer and AC Loading

The following figure shows the output buffer and AC loading.

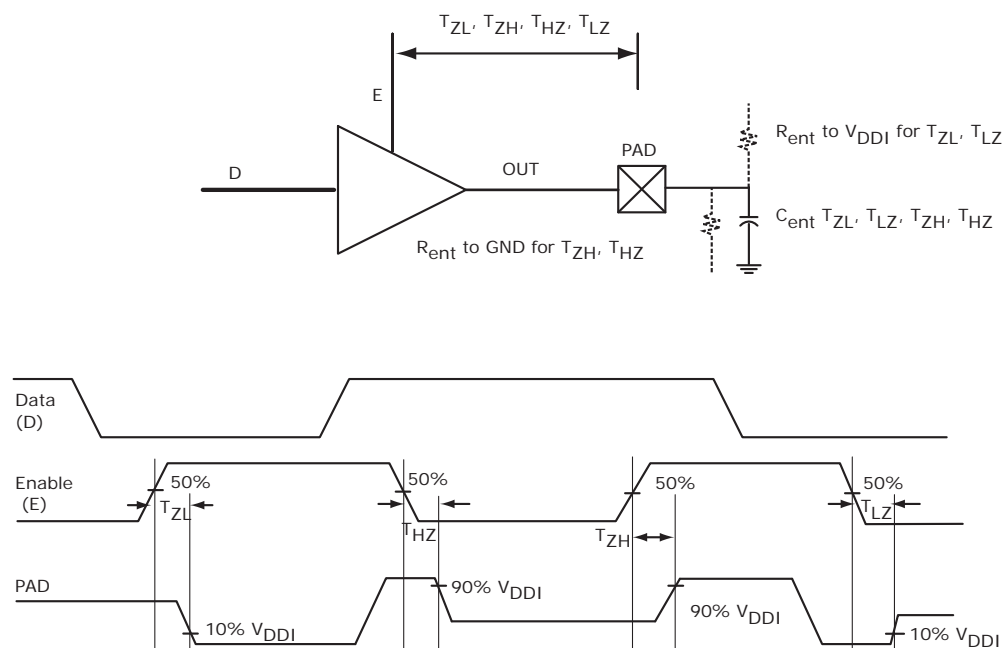
Figure 4 • Output Buffer AC Loading



2.3.5.3 Tristate Buffer and AC Loading

The tristate path for enable path loadings is described in the respective specifications. The following figure shows the methodology of characterization illustrated by the enable path test point.

Figure 5 • Tristate Buffer for Enable Path Test Point



2.3.5.4 I/O Speeds

This section describes the maximum data rate summary of I/O in worst-case industrial conditions. See the individual I/O standards for operating conditions.

Table 18 • Maximum Data Rate Summary Table for Single-Ended I/O in Worst-Case Industrial Conditions

I/O	MSIO	MSIOD	DDRIO	Unit
PCI 3.3 V	630			Mbps
LVTTL 3.3 V	600			Mbps
LVC MOS 3.3 V	600			Mbps
LVC MOS 2.5 V	410	420	400	Mbps
LVC MOS 1.8 V	295	400	400	Mbps
LVC MOS 1.5 V	160	220	235	Mbps
LVC MOS 1.2 V	120	160	200	Mbps
LPDDR-LVC MOS 1.8 V mode			400	Mbps

2.3.5.7 2.5 V LVCMOS

LVCMOS 2.5 V is a general standard for 2.5 V applications and is supported in IGLOO2 FPGA and SmartFusion2 SoC FPGAs that are in compliance with the JEDEC specification JESD8-5A.

Minimum and Maximum DC/AC Input and Output Levels Specification

Table 38 • LVCMOS 2.5 V DC Recommended DC Operating Conditions

Parameter	Symbol	Min	Typ	Max	Unit
Supply voltage	V_{DDI}	2.375	2.5	2.625	V

Table 39 • LVCMOS 2.5 V DC Input Voltage Specification

Parameter	Symbol	Min	Max	Unit
DC input logic high (for MSIOD and DDRIO I/O banks)	V_{IH} (DC)	1.7	2.625	V
DC input logic high (for MSIO I/O bank)	V_{IH} (DC)	1.7	3.45	V
DC input logic low	V_{IL} (DC)	-0.3	0.7	V
Input current high ¹	I_{IH} (DC)			
Input current low ¹	I_{IL} (DC)			

1. See Table 24, page 22.

Table 40 • LVCMOS 2.5 V DC Output Voltage Specification

Parameter	Symbol	Min	Max	Unit
DC output logic high	V_{OH} ¹	$V_{DDI} - 0.4$	-	V
DC output logic low	V_{OL} ²		0.4	V

1. The VOH/VOL test points selected ensure compliance with LVCMOS 2.5 V JEDEC8-5A requirements.

Table 41 • LVCMOS 2.5 V AC Minimum and Maximum Switching Speed

Parameter	Symbol	Max	Unit	Conditions
Maximum data rate (for DDRIO I/O bank)	D_{MAX}	400	Mbps	AC loading: 17 pF load, maximum drive/slew
Maximum data rate (for MSIO I/O bank)	D_{MAX}	410	Mbps	AC loading: 17 pF load, maximum drive/slew
Maximum data rate (for MSIOD I/O bank)	D_{MAX}	420	Mbps	AC loading: 17 pF load, maximum drive/slew

Table 42 • LVCMOS 2.5 V AC Calibrated Impedance Option

Parameter	Symbol	Typ	Unit
Supported output driver calibrated impedance (for DDRIO I/O bank)	Rodt_cal	75, 60, 50, 33, 25, 20	T

Table 57 • **LVC MOS 1.8 V Transmitter Characteristics for DDRIO I/O Bank with Fixed Code (Output and Tristate Buffers)**

Output Drive Selection	Slew Control	T _{DP}		T _{ZL}		T _{ZH}		T _{HZ} ¹		T _{LZ} ¹		Unit
		-1	-Std	-1	-Std	-1	-Std	-1	-Std	-1	-Std	
2 mA	Slow	4.234	4.981	3.646	4.29	4.245	4.995	4.908	5.774	4.434	5.216	ns
	Medium	3.824	4.498	3.282	3.861	3.834	4.511	4.625	5.441	4.116	4.843	ns
	Medium fast	3.627	4.267	3.111	3.66	3.637	4.279	4.481	5.272	3.984	4.687	ns
	Fast	3.605	4.241	3.097	3.644	3.615	4.253	4.472	5.262	3.973	4.674	ns
4 mA	Slow	3.923	4.615	3.314	3.9	3.918	4.61	5.403	6.356	4.894	5.757	ns
	Medium	3.518	4.138	2.961	3.484	3.515	4.135	5.121	6.025	4.561	5.366	ns
	Medium fast	3.321	3.907	2.783	3.275	3.317	3.903	4.966	5.843	4.426	5.206	ns
	Fast	3.301	3.883	2.77	3.259	3.296	3.878	4.957	5.831	4.417	5.196	ns
6 mA	Slow	3.71	4.364	3.104	3.652	3.702	4.355	5.62	6.612	5.08	5.977	ns
	Medium	3.333	3.921	2.779	3.27	3.325	3.913	5.346	6.289	4.777	5.62	ns
	Medium fast	3.155	3.712	2.62	3.083	3.146	3.702	5.21	6.13	4.657	5.479	ns
	Fast	3.134	3.688	2.608	3.068	3.125	3.677	5.202	6.12	4.648	5.468	ns
8 mA	Slow	3.619	4.258	3.007	3.538	3.607	4.244	5.815	6.841	5.249	6.175	ns
	Medium	3.246	3.819	2.686	3.16	3.236	3.807	5.542	6.52	4.936	5.807	ns
	Medium fast	3.066	3.607	2.525	2.971	3.054	3.593	5.405	6.359	4.811	5.66	ns
	Fast	3.046	3.584	2.513	2.957	3.034	3.57	5.401	6.353	4.803	5.651	ns
10 mA	Slow	3.498	4.115	2.878	3.386	3.481	4.096	6.046	7.113	5.444	6.404	ns
	Medium	3.138	3.692	2.569	3.023	3.126	3.678	5.782	6.803	5.129	6.034	ns
	Medium fast	2.966	3.489	2.414	2.841	2.951	3.472	5.666	6.665	5.013	5.897	ns
	Fast	2.945	3.464	2.401	2.826	2.93	3.448	5.659	6.658	5.003	5.886	ns
12 mA	Slow	3.417	4.02	2.807	3.303	3.401	4.002	6.083	7.156	5.464	6.428	ns
	Medium	3.076	3.618	2.519	2.964	3.063	3.604	5.828	6.856	5.176	6.089	ns
	Medium fast	2.913	3.427	2.376	2.795	2.898	3.41	5.725	6.736	5.072	5.966	ns
	Fast	2.894	3.405	2.362	2.78	2.879	3.388	5.715	6.724	5.064	5.957	ns
16 mA	Slow	3.366	3.96	2.751	3.237	3.348	3.939	6.226	7.324	5.576	6.56	ns
	Medium	3.03	3.565	2.47	2.906	3.017	3.55	5.981	7.036	5.282	6.214	ns
	Medium fast	2.87	3.377	2.328	2.739	2.854	3.358	5.895	6.935	5.18	6.094	ns
	Fast	2.853	3.357	2.314	2.723	2.837	3.338	5.889	6.929	5.177	6.09	ns

1. Delay increases with drive strength are inherent to built-in slew control circuitry for simultaneous switching output (SSO) management.

Table 144 • LPDDR AC Differential Voltage Specifications (for DDRIO I/O Bank Only)

Parameter	Symbol	Min	Max	Unit
AC input differential voltage	V_{DIFF}	$0.6 \times V_{DDI}$		V
AC differential cross point voltage	V_x	$0.4 \times V_{DDI}$	$0.6 \times V_{DDI}$	V

Table 145 • LPDDR AC Specifications (for DDRIO I/O Bank Only)

Parameter	Symbol	Max	Unit	Conditions
Maximum data rate	D_{MAX}	400	Mbps	AC loading: per JEDEC specifications

Table 146 • LPDDR AC Calibrated Impedance Option (for DDRIO I/O Bank Only)

Parameter	Symbol	Typ	Unit	Conditions
Supported output driver calibrated impedance	R_{REF}	20, 42	T	Reference resistor = 150 T
Effective impedance value (ODT)	R_{TT}	50, 70, 150	T	Reference resistor = 150 T

Table 147 • LPDDR AC Test Parameter Specifications (for DDRIO I/O Bank Only)

Parameter	Symbol	Typ	Unit
Measuring/trip point for data path	V_{TRIP}	0.9	V
Resistance for enable path (T_{ZH} , T_{ZL} , T_{HZ} , T_{LZ})	R_{ENT}	2K	T
Capacitive loading for enable path (T_{ZH} , T_{ZL} , T_{HZ} , T_{LZ})	C_{ENT}	5	pF
Reference resistance for data test path for LPDDR (T_{DP})	R_{TT_TEST}	50	T
Capacitive loading for data path (T_{DP})	C_{LOAD}	5	T

AC Switching Characteristics

Worst-case commercial conditions: $T_J = 85^\circ\text{C}$, $V_{DD} = 1.14\text{ V}$, worst-case V_{DDI} .

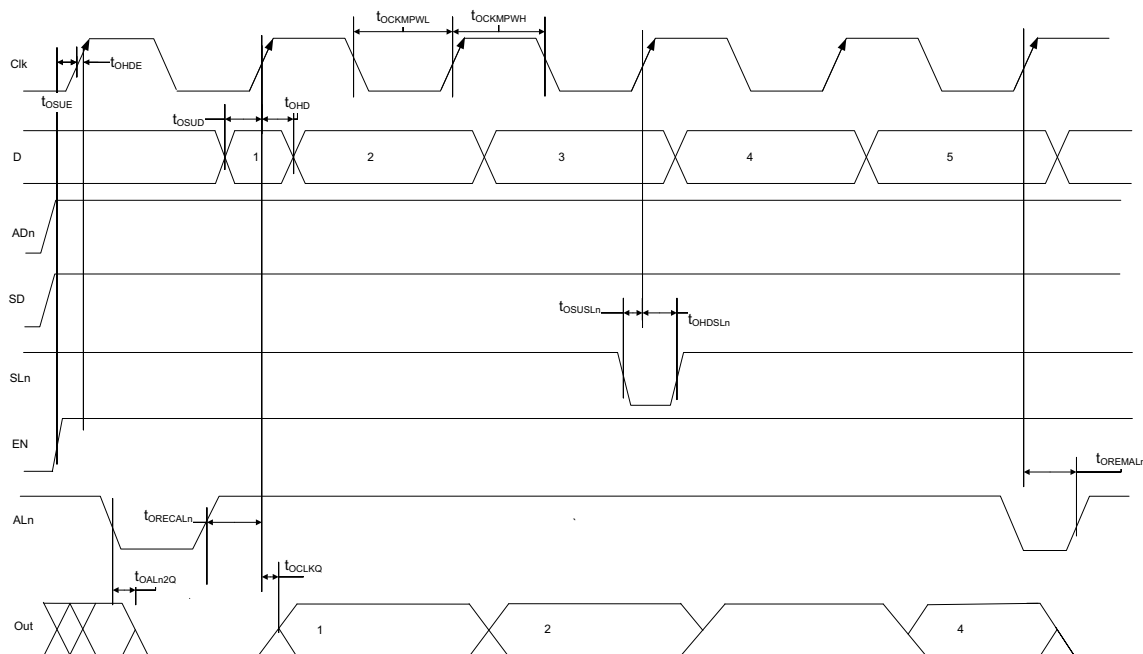
Table 148 • LPDDR Receiver Characteristics for DDRIO I/O Bank with Fixed Codes

	On-Die Termination (ODT)	T_{PY}		Unit
		-1	-Std	
Pseudo differential	None	1.568	1.845	ns
True differential	None	1.588	1.869	ns

Table 149 • LPDDR Reduced Drive for DDRIO I/O Bank (Output and Tristate Buffers)

	T_{DP}		T_{ENZL}		T_{ENZH}		T_{ENHZ}		T_{ENLZ}		Unit
	-1	-Std	-1	-Std	-1	-Std	-1	-Std	-1	-Std	
Single-ended	2.383	2.804	2.23	2.623	2.229	2.622	2.202	2.591	2.201	2.59	ns
Differential	2.396	2.819	2.764	3.252	2.764	3.252	2.255	2.653	2.255	2.653	ns

Figure 9 • I/O Register Output Timing Diagram



The following table lists the output/enable propagation delays in worst commercial-case conditions when $T_J = 85\text{ }^\circ\text{C}$, $V_{DD} = 1.14\text{ V}$.

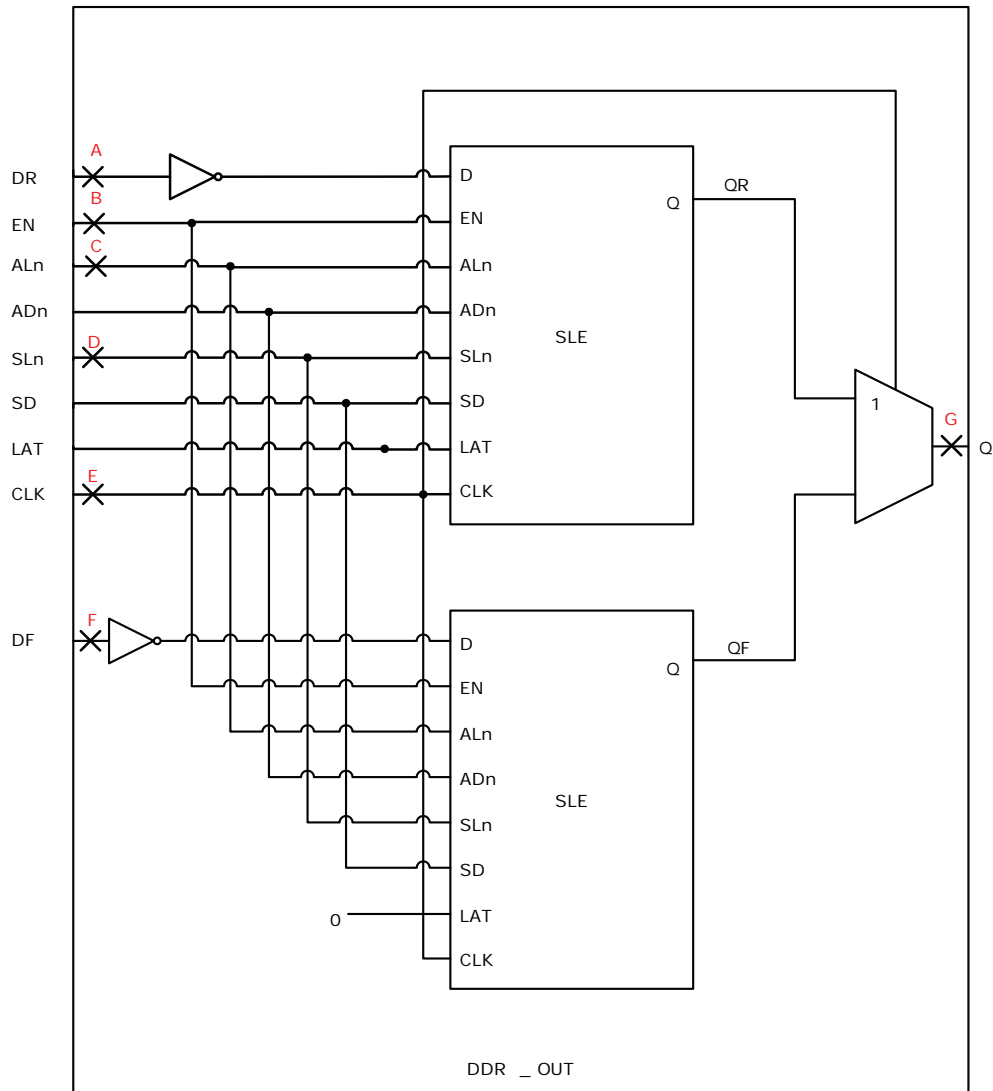
Table 220 • Output/Enable Data Register Propagation Delays

Parameter	Symbol	Measuring Nodes (from, to) ¹	-1		Unit
			-1	-Std	
Bypass delay of the output/enable register	T_{OBYP}	F, G or H, I	0.353	0.415	ns
Clock-to-Q of the output/enable register	T_{OCLKQ}	E, G or E, I	0.263	0.309	ns
Data setup time for the output/enable register	T_{OSUD}	A, E or J, E	0.19	0.223	ns
Data hold time for the output/enable register	T_{OHD}	A, E or J, E	0	0	ns
Enable setup time for the output/enable register	T_{OSUE}	B, E	0.419	0.493	ns
Enable hold time for the output/enable register	T_{OHE}	B, E	0	0	ns
Synchronous load setup time for the output/enable register	T_{OSUSL}	D, E	0.196	0.231	ns
Synchronous load hold time for the output/enable register	T_{OHSL}	D, E	0	0	ns
Asynchronous clear-to-q of the output/enable register (ADn = 1)	T_{OALN2Q}	C, G or C, I	0.505	0.594	ns
Asynchronous preset-to-q of the output/enable register (ADn = 0)		C, G or C, I	0.528	0.621	ns
Asynchronous load removal time for the output/enable register	$T_{OREMALN}$	C, E	0	0	ns
Asynchronous load recovery time for the output/enable register	$T_{ORECALN}$	C, E	0.034	0.04	ns
Asynchronous load minimum pulse width for the output/enable register	T_{OWALN}	C, C	0.304	0.357	ns
Clock minimum pulse width high for the output/enable register	$T_{OACKMPWH}$	E, E	0.075	0.088	ns
Clock minimum pulse width low for the output/enable register	$T_{OACKMPWL}$	E, E	0.159	0.187	ns

1. For the derating values at specific junction temperature and voltage supply levels, see Table 16, page 14 for derating values.

2.3.9.4 Output DDR Module

Figure 12 • Output DDR Module



2.3.10.2 Timing Characteristics

The following table lists the combinatorial cell propagation delays in worst commercial-case conditions when $T_J = 85\text{ }^\circ\text{C}$, $V_{DD} = 1.14\text{ V}$.

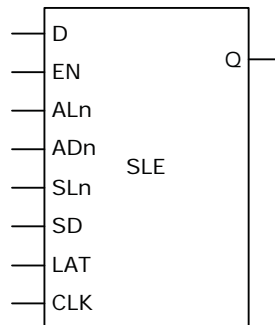
Table 223 • **Combinatorial Cell Propagation Delays**

Combinatorial Cell	Equation	Symbol	-1	-Std	Unit
INV	$Y = !A$	T_{PD}	0.1	0.118	ns
AND2	$Y = A \cdot B$	T_{PD}	0.164	0.193	ns
NAND2	$Y = !(A \cdot B)$	T_{PD}	0.147	0.173	ns
OR2	$Y = A + B$	T_{PD}	0.164	0.193	ns
NOR2	$Y = !(A + B)$	T_{PD}	0.147	0.173	ns
XOR2	$Y = A \oplus B$	T_{PD}	0.164	0.193	ns
XOR3	$Y = A \oplus B \oplus C$	T_{PD}	0.225	0.265	ns
AND3	$Y = A \cdot B \cdot C$	T_{PD}	0.209	0.246	ns
AND4	$Y = A \cdot B \cdot C \cdot D$	T_{PD}	0.287	0.338	ns

2.3.10.3 Sequential Module

IGLOO2 and SmartFusion2 SoC FPGAs offer a separate flip-flop which can be used independently from the LUT. The flip-flop can be configured as a register or a latch and has a data input and optional enable, synchronous load (clear or preset), and asynchronous load (clear or preset).

Figure 15 • **Sequential Module**



The following table lists the 010 device global resources in worst commercial-case conditions when $T_J = 85\text{ }^\circ\text{C}$, $V_{DD} = 1.14\text{ V}$.

Table 229 • 010 Device Global Resource

Parameter	Symbol	-1		-Std		Unit
		Min	Max	Min	Max	
Input low delay for global clock	T_{RCKL}	0.626	0.669	0.627	0.668	ns
Input high delay for global clock	T_{RCKH}	1.112	1.182	1.308	1.393	ns
Maximum skew for global clock	T_{RCKSW}		0.07		0.085	ns

The following table lists the 005 device global resources in worst commercial-case conditions when $T_J = 85\text{ }^\circ\text{C}$, $V_{DD} = 1.14\text{ V}$.

Table 230 • 005 Device Global Resource

Parameter	Symbol	-1		-Std		Unit
		Min	Max	Min	Max	
Input low delay for global clock	T_{RCKL}	0.625	0.66	0.628	0.66	ns
Input high delay for global clock	T_{RCKH}	1.126	1.187	1.325	1.397	ns
Maximum skew for global clock	T_{RCKSW}		0.061		0.072	ns

2.3.12 FPGA Fabric SRAM

See [G0445: IGDFBA](#)

[FBA F100](#)

for more information.

2.3.12.1 FPGA Fabric Large SRAM (LSRAM)

The following table lists the RAM1K18 – dual-port mode for depth × width configuration 1K × 18 in worst commercial-case conditions when $T_J = 85\text{ }^\circ\text{C}$, $V_{DD} = 1.14\text{ V}$.

Table 231 • RAM1K18 – Dual-Port Mode for Depth × Width Configuration 1K × 18

Parameter	Symbol	-1		-Std		Unit
		Min	Max	Min	Max	
Clock period	T_{CY}	2.5		2.941		ns
Clock minimum pulse width high	$T_{CLKMPWH}$	1.125		1.323		ns
Clock minimum pulse width low	$T_{CLKMPWL}$	1.125		1.323		ns
Pipelined clock period	T_{PLCY}	2.5		2.941		ns
Pipelined clock minimum pulse width high	$T_{PLCLKMPWH}$	1.125		1.323		ns
Pipelined clock minimum pulse width low	$T_{PLCLKMPWL}$	1.125		1.323		ns
Read access time with pipeline register				0.334	0.393	ns
Read access time without pipeline register	T_{CLK2Q}			2.273	2.674	ns
Access time with feed-through write timing				1.529	1.799	ns
Address setup time	T_{ADDRSU}	0.441		0.519		ns
Address hold time	T_{ADDRHD}	0.274		0.322		ns
Data setup time	T_{DSU}	0.341		0.401		ns
Data hold time	T_{DHD}	0.107		0.126		ns
Block select setup time	T_{BLKSU}	0.207		0.244		ns

Table 232 • RAM1K18 – Dual-Port Mode for Depth × Width Configuration 2K × 9 (continued)

Parameter	Symbol	–1		–Std		Unit
		Min	Max	Min	Max	
Address setup time	T_{ADDRSU}	0.475		0.559		ns
Address hold time	T_{ADDRHD}	0.274		0.322		ns
Data setup time	T_{DSU}	0.336		0.395		ns
Data hold time	T_{DHD}	0.082		0.096		ns
Block select setup time	T_{BLKSU}	0.207		0.244		ns
Block select hold time	T_{BLKHD}	0.216		0.254		ns
Block select to out disable time (when pipelined register is disabled)	T_{BLK2Q}		1.529		1.799	ns
Block select minimum pulse width	T_{BLKMPW}	0.186		0.219		ns
Read enable setup time	T_{RDESU}	0.485		0.57		ns
Read enable hold time	T_{RDEHD}	0.071		0.083		ns
Pipelined read enable setup time (A_DOUT_EN, B_DOUT_EN)	$T_{RDPLESU}$	0.248		0.291		ns
Pipelined read enable hold time (A_DOUT_EN, B_DOUT_EN)	$T_{RDPLEHD}$	0.102		0.12		ns
Asynchronous reset to output propagation delay	T_{R2Q}		1.514		1.781	ns
Asynchronous reset removal time	T_{RSTREM}	0.506		0.595		ns
Asynchronous reset recovery time	T_{RSTREC}	0.004		0.005		ns
Asynchronous reset minimum pulse width	T_{RSTMPW}	0.301		0.354		ns
Pipelined register asynchronous reset removal time	$T_{PLRSTREM}$	–0.279		–0.328		ns
Pipelined register asynchronous reset recovery time	$T_{PLRSTREC}$	0.327		0.385		ns
Pipelined register asynchronous reset minimum pulse width	$T_{PLRSTMPW}$	0.282		0.332		ns
Synchronous reset setup time	T_{SRSTSU}	0.226		0.265		ns
Synchronous reset hold time	T_{SRSTHD}	0.036		0.043		ns
Write enable setup time	T_{WESU}	0.415		0.488		ns
Write enable hold time	T_{WEHD}	0.048		0.057		ns
Maximum frequency	F_{MAX}		400		340	MHz

The following table lists the RAM1K18 – dual-port mode for depth × width configuration 4K × 4 in worst commercial-case conditions when $T_J = 85\text{ }^\circ\text{C}$, $V_{DD} = 1.14\text{ V}$.

Table 233 • RAM1K18 – Dual-Port Mode for Depth × Width Configuration 4K × 4

Parameter	Symbol	–1		–Std		Unit
		Min	Max	Min	Max	
Clock period	T_{CY}	2.5		2.941		ns
Clock minimum pulse width high	$T_{CLKMPWH}$	1.125		1.323		ns
Clock minimum pulse width low	$T_{CLKMPWL}$	1.125		1.323		ns
Pipelined clock period	T_{PLCY}	2.5		2.941		ns
Pipelined clock minimum pulse width high	$T_{PLCLKMPWH}$	1.125		1.323		ns

Table 237 • μ SRAM (RAM64x18) in 64 × 18 Mode (continued)

Parameter	Symbol	-1		-Std		Unit
		Min	Max	Min	Max	
Write address setup time	$T_{ADDRCSU}$	0.088		0.104		ns
Write address hold time	$T_{ADDRCHD}$	0.128		0.15		ns
Write enable setup time	T_{WECSU}	0.397		0.467		ns
Write enable hold time	T_{WECHD}	-0.026		-0.03		ns
Maximum frequency	F_{MAX}		250		250	MHz

The following table lists the μ SRAM in 64 × 16 mode in worst commercial-case conditions when $T_J = 85^\circ\text{C}$, $V_{DD} = 1.14\text{ V}$.

Table 238 • μ SRAM (RAM64x16) in 64 × 16 Mode

Parameter	Symbol	-1		-Std		Unit
		Min	Max	Min	Max	
Read clock period	T_{CY}	4		4		ns
Read clock minimum pulse width high	$T_{CLKMPWH}$	1.8		1.8		ns
Read clock minimum pulse width low	$T_{CLKMPWL}$	1.8		1.8		ns
Read pipeline clock period	T_{PLCY}	4		4		ns
Read pipeline clock minimum pulse width high	$T_{PLCLKMPWH}$	1.8		1.8		ns
Read pipeline clock minimum pulse width low	$T_{PLCLKMPWL}$	1.8		1.8		ns
Read access time with pipeline register	T_{CLK2Q}		0.266		0.313	ns
Read access time without pipeline register				1.677		1.973
Read address setup time in synchronous mode	T_{ADDRSU}	0.301		0.354		ns
Read address setup time in asynchronous mode			1.856		2.184	
Read address hold time in synchronous mode	T_{ADDRHD}	0.091		0.107		ns
Read address hold time in asynchronous mode			-0.778		-0.915	
Read enable setup time	T_{RDENSU}	0.278		0.327		ns
Read enable hold time	T_{RDENHD}	0.057		0.067		ns
Read block select setup time	T_{BLKSU}	1.839		2.163		ns
Read block select hold time	T_{BLKHD}	-0.65		-0.765		ns
Read block select to out disable time (when pipelined register is disabled)	T_{BLK2Q}		2.036		2.396	ns
Read asynchronous reset removal time (pipelined clock)	T_{RSTREM}	-0.023		-0.027		ns
Read asynchronous reset removal time (non-pipelined clock)			0.046		0.054	
Read asynchronous reset recovery time (pipelined clock)	T_{RSTREC}	0.507		0.597		ns
Read asynchronous reset recovery time (non-pipelined clock)			0.236		0.278	
Read asynchronous reset to output propagation delay (with pipelined register enabled)	T_{R2Q}		0.835		0.983	ns
Read synchronous reset setup time	T_{SRSTSU}	0.271		0.319		ns

Table 240 • μ SRAM (RAM128x8) in 128 x 8 Mode (continued)

Parameter	Symbol	-1		-Std		Unit
		Min	Max	Min	Max	
Read address hold time in synchronous mode	T _{ADDRHD}	0.091		0.107		ns
Read address hold time in asynchronous mode		-0.778		-0.915		ns
Read enable setup time	T _{RDENSU}	0.278		0.327		ns
Read enable hold time	T _{RDENHD}	0.057		0.067		ns
Read block select setup time	T _{BLKSU}	1.839		2.163		ns
Read block select hold time	T _{BLKHD}	-0.65		-0.765		ns
Read block select to out disable time (when pipelined register is disabled)	T _{BLK2Q}		2.036		2.396	ns
Read asynchronous reset removal time (pipelined clock)	T _{RSTREM}	-0.023		-0.027		ns
Read asynchronous reset removal time (non-pipelined clock)		0.046		0.054		ns
Read asynchronous reset recovery time (pipelined clock)	T _{RSTREC}	0.507		0.597		ns
Read asynchronous reset recovery time (non-pipelined clock)		0.236		0.278		ns
Read asynchronous reset to output propagation delay (with pipelined register enabled)	T _{R2Q}		0.835		0.982	ns
Read synchronous reset setup time	T _{SRSTSU}	0.271		0.319		ns
Read synchronous reset hold time	T _{SRSTHD}	0.061		0.071		ns
Write clock period	T _{CCY}	4		4		ns
Write clock minimum pulse width high	T _{CCLKMPWH}	1.8		1.8		ns
Write clock minimum pulse width low	T _{CCLKMPWL}	1.8		1.8		ns
Write block setup time	T _{BLKCSU}	0.404		0.476		ns
Write block hold time	T _{BLKCHD}	0.007		0.008		ns
Write input data setup time	T _{DINCSU}	0.115		0.135		ns
Write input data hold time	T _{DINCHD}	0.15		0.177		ns
Write address setup time	T _{ADDRCSU}	0.088		0.104		ns
Write address hold time	T _{ADDRCHD}	0.128		0.15		ns
Write enable setup time	T _{WECSU}	0.397		0.467		ns
Write enable hold time	T _{WECHD}	-0.026		-0.03		ns
Maximum frequency	F _{MAX}		250		250	MHz

The following table lists the μ SRAM in 256×4 mode in worst commercial-case conditions when $T_J = 85^\circ\text{C}$, $V_{DD} = 1.14\text{ V}$.

Table 241 • μ SRAM (RAM256x4) in 256×4 Mode

Parameter	Symbol	-1		-Std		Unit
		Min	Max	Min	Max	
Read clock period	T_{CY}	4		4		ns
Read clock minimum pulse width high	$T_{CLKMPWH}$	1.8		1.8		ns
Read clock minimum pulse width low	$T_{CLKMPWL}$	1.8		1.8		ns
Read pipeline clock period	T_{PLCY}	4		4		ns
Read pipeline clock minimum pulse width high	$T_{PLCLKMPWH}$	1.8		1.8		ns
Read pipeline clock minimum pulse width low	$T_{PLCLKMPWL}$	1.8		1.8		ns
Read access time with pipeline register	T_{CLK2Q}		0.27		0.31	ns
Read access time without pipeline register				1.75		2.06
Read address setup time in synchronous mode	T_{ADDRSU}	0.301		0.354		ns
Read address setup time in asynchronous mode			1.931		2.272	
Read address hold time in synchronous mode	T_{ADDRHD}	0.121		0.142		ns
Read address hold time in asynchronous mode			-0.65		-0.76	
Read enable setup time	T_{RDENSU}	0.278		0.327		ns
Read enable hold time	T_{RDENHD}	0.057		0.067		ns
Read block select setup time	T_{BLKSU}	1.839		2.163		ns
Read block select hold time	T_{BLKHD}	-0.65		-0.77		ns
Read block select to out disable time (when pipelined register is disabled)	T_{BLK2Q}		2.09		2.46	ns
Read asynchronous reset removal time (pipelined clock)	T_{RSTREM}	-0.02		-0.03		ns
Read asynchronous reset removal time (non-pipelined clock)			0.046		0.054	
Read asynchronous reset recovery time (pipelined clock)	T_{RSTREC}	0.507		0.597		ns
Read asynchronous reset recovery time (non-pipelined clock)			0.236		0.278	
Read asynchronous reset to output propagation delay (with pipelined register enabled)	T_{R2Q}		0.83		0.98	ns
Read synchronous reset setup time	T_{SRSTSU}	0.271		0.319		ns
Read synchronous reset hold time	T_{SRSTHD}	0.061		0.071		ns
Write clock period	T_{CCY}	4		4		ns
Write clock minimum pulse width high	$T_{CCLKMPWH}$	1.8		1.8		ns
Write clock minimum pulse width low	$T_{CCLKMPWL}$	1.8		1.8		ns
Write block setup time	T_{BLKCSU}	0.404		0.476		ns
Write block hold time	T_{BLKCHD}	0.007		0.008		ns
Write input data setup time	T_{DINCSU}	0.101		0.118		ns
Write input data hold time	T_{DINCHD}	0.137		0.161		ns
Write address setup time	$T_{ADDRCSU}$	0.088		0.104		ns

Table 248 • 2 Step IAP Programming (eNVM Only)

M2S/M2GL					
Device	Image size Bytes	Authenticate	Program	Verify	Unit
005	137536	2	37	5	Sec
010	274816	4	76	11	Sec
025	274816	4	78	10	Sec
050	278528	3	85	9	Sec
060	268480	5	76	22	Sec
090	544496	10	152	43	Sec
150	544496	10	153	44	Sec

Table 249 • 2 Step IAP Programming (Fabric and eNVM)

M2S/M2GL					
Device	Image size Bytes	Authenticate	Program	Verify	Unit
005	439296	6	56	11	Sec
010	842688	11	100	21	Sec
025	1497408	19	113	32	Sec
050	2695168	32	136	48	Sec
060	2686464	43	137	70	Sec
090	4190208	68	236	115	Sec
150	6682768	109	286	162	Sec

Table 250 • SmartFusion2 Cortex-M3 ISP Programming (Fabric Only)

M2S/M2GL Device	Image size Bytes	Authenticate	Program	Verify	Unit
005	302672	6	19	8	Sec
010	568784	10	26	14	Sec
025	1223504	21	39	29	Sec
050	2424832	39	60	50	Sec
060	2418896	44	65	54	Sec
090	3645968	66	90	79	Sec
150	6139184	108	140	128	Sec

Table 251 • SmartFusion2 Cortex-M3 ISP Programming (eNVM Only)

M2S/M2GL Device	Image size Bytes	Authenticate	Program	Verify	Unit
005	137536	3	42	4	Sec
010	274816	4	82	7	Sec
025	274816	4	82	8	Sec
050	278528	4	80	8	Sec
060	268480	6	80	8	Sec
090	544496	10	157	15	Sec

Table 251 • SmartFusion2 Cortex-M3 ISP Programming (eNVM Only) (continued)

M2S/M2GL Device	Image size Bytes	Authenticate	Program	Verify	Unit
150	544496	10	158	15	Sec

Table 252 • SmartFusion2 Cortex-M3 ISP Programming (Fabric and eNVM)

M2S/M2GL Device	Image size Bytes	Authenticate	Program	Verify	Unit
005	439296	9	61	11	Sec
010	842688	15	107	21	Sec
025	1497408	26	121	35	Sec
050	2695168	43	141	55	Sec
060	2686464	48	143	60	Sec
090	4190208	75	244	91	Sec
150	6682768	117	296	141	Sec

Table 253 • Programming Times with 100 kHz, 25 MHz, and 12.5 MHz SPI Clock Rates (Fabric Only)

M2S/M2GL Device	Auto Programming	Auto Update	Programming Recovery	Unit
	100 kHz	25 MHz	12.5 MHz	
005	47	27	28	Sec
010	77	35	35	Sec
025	150	42	41	Sec
050	33 ¹	Not Supported	Not Supported	Sec
060	291	83	82	Sec
090	427	109	108	Sec
150	708	157	160	Sec

1. Auto Programming in 050 device is done through SC_SPI, and SPI CLK is set to 6.25 MHz.

Table 254 • Programming Times with 100 kHz, 25 MHz, and 12.5 MHz SPI Clock Rates (eNVM Only)

M2S/M2GL Device	Auto Programming	Auto Update	Programming Recovery	Unit
	100 kHz	25 MHz	12.5 MHz	
005	41	48	49	Sec
010	86	87	87	Sec
025	87	85	86	Sec
050	85	Not Supported	Not Supported	Sec
060	78	86	86	Sec
090	154	162	162	Sec

The following table lists the system controller characteristics in worst-case industrial conditions when $T_J = 100\text{ }^\circ\text{C}$, $V_{DD} = 1.14\text{ V}$.

Table 286 • **System Controller SPI Characteristics for All Devices**

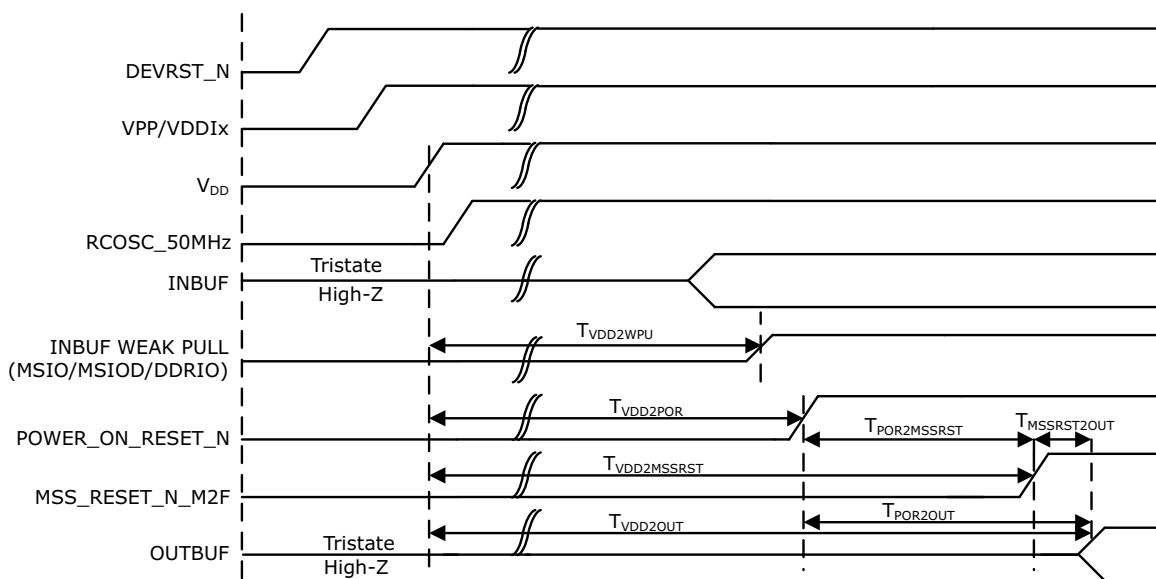
Symbol	Description	Conditions	Min	Typ	Unit
sp1	SC_SPI_SCK minimum period		20		ns
sp2	SC_SPI_SCK minimum pulse width high		10		ns
sp3	SC_SPI_SCK minimum pulse width low		10		ns
sp4 ¹	SC_SPI_SCK, SC_SPI_SDO, SC_SPI_SS rise time (10%–90%) 1	I/O configuration: LVTTTL 3.3 V–20 mA AC loading: 35 pF Test conditions: Typical voltage, 25 °C		1.239	ns
sp5 ¹	SC_SPI_SCK, SC_SPI_SDO, SC_SPI_SS fall time (10%–90%) 1	I/O configuration: LVTTTL 3.3 V–20 mA AC loading: 35 pF Test conditions: Typical voltage, 25 °C		1.245	ns
sp6	Data from master (SC_SPI_SDO) setup time		160		ns
sp7	Data from master (SC_SPI_SDO) hold time		160		ns
sp8	SC_SPI_SDI setup time		20		ns
sp9	SC_SPI_SDI hold time		20		ns

- For specific Rise/Fall Times, board design considerations and detailed output buffer resistances, use the corresponding IBIS models located on the Microsemi SoC Products Group website: <http://www.microsemi.com/soc/download/ibis/default.aspx>. Use the supported I/O Configurations for the System Controller SPI in the following table.

Table 287 • **Supported I/O Configurations for System Controller SPI (for MSIO Bank Only)**

Voltage Supply	I/O Drive Configuration	Unit
3.3 V	20	mA
2.5 V	16	mA
1.8 V	12	mA
1.5 V	8	mA
1.2 V	4	mA

Figure 17 • Power-up to Functional Timing Diagram for SmartFusion2



The following table lists the IGLOO2 power-up to functional times in worst-case industrial conditions when $T_J = 100\text{ }^\circ\text{C}$, $V_{DD} = 1.14\text{ V}$.

Table 289 • Power-up to Functional Times for IGLOO2

Symbol	From	To	Description	Maximum Power-up to Functional Time for IGLOO2 (uS)						
				005	010	025	050	060	090	150
$T_{POR2OUT}$	POWER_ON_RESET_N	Output available at I/O	Fabric to output	114	114	114	113	114	114	114
$T_{VDD2OUT}$	V_{DD}	Output available at I/O	V_{DD} at its minimum threshold level to output	2587	2600	2607	2558	2591	2600	2699
$T_{VDD2POR}$	V_{DD}	POWER_ON_RESET_N	V_{DD} at its minimum threshold level to fabric	2474	2486	2493	2445	2477	2486	2585
$T_{VDD2WPU}$	DEVRST_N	DDRIO Inbuf weak pull	DEVRST_N to Inbuf weak pull	2500	2487	2509	2475	2507	2519	2617
	DEVRST_N	MSIO Inbuf weak pull	DEVRST_N to Inbuf weak pull	2504	2491	2510	2478	2517	2525	2620
	DEVRST_N	MSIOD Inbuf weak pull	DEVRST_N to Inbuf weak pull	2479	2468	2493	2458	2486	2499	2595

Note: For more information about power-up times, see [G0448: IGDFBA H01](#)

2.3.34 MMUART Characteristics

The following table lists the MMUART characteristics in worst-case industrial conditions when $T_J = 100\text{ }^\circ\text{C}$, $V_{DD} = 1.14\text{ V}$.

Table 308 • MMUART Characteristics

Parameter	Description	-1	-Std	Unit
FMMUART_REF_CLK	Internally sourced MMUART reference clock frequency.	166	142	MHz
BAUDMMUARTTx	Maximum transmit baud rate	10.375	8.875	Mbps
BAUDMMUARTRx	Maximum receive baud rate	10.375	8.875	Mbps

2.3.35 IGLOO2 Specifications

2.3.35.1 HPMS Clock Frequency

The following table lists the maximum frequency for HPMS main clock in worst-case industrial conditions when $T_J = 100\text{ }^\circ\text{C}$, $V_{DD} = 1.14\text{ V}$.

Table 309 • Maximum Frequency for HPMS Main Clock

Symbol	Description	-1	-Std	Unit
HPMS_CLK	Maximum frequency for the HPMS main clock	166	142	MHz

2.3.35.2 IGLOO2 Serial Peripheral Interface (SPI) Characteristics

This section describes the DC and switching of the SPI interface. Unless otherwise noted, all output characteristics given are for a 35 pF load on the pins and all sequential timing characteristics are related to SPI_0_CLK. For timing parameter definitions, see [Figure 23](#), page 131.

The following table lists the SPI characteristics in worst-case industrial conditions when $T_J = 100\text{ }^\circ\text{C}$, $V_{DD} = 1.14\text{ V}$.

Table 310 • SPI Characteristics for All Devices

Symbol	Description	Min	Typ	Max	Unit	Conditions
SPIFMAX	Maximum operating frequency of SPI interface			20	MHz	
sp1	SPI_[0 1]_CLK minimum period					
	SPI_[0 1]_CLK = PCLK/2	12			ns	
	SPI_[0 1]_CLK = PCLK/4	24.1			ns	
	SPI_[0 1]_CLK = PCLK/8	48.2			ns	
	SPI_[0 1]_CLK = PCLK/16	0.1			μs	
	SPI_[0 1]_CLK = PCLK/32	0.19			μs	
	SPI_[0 1]_CLK = PCLK/64	0.39			μs	
SPI_[0 1]_CLK = PCLK/128	0.77			μs		