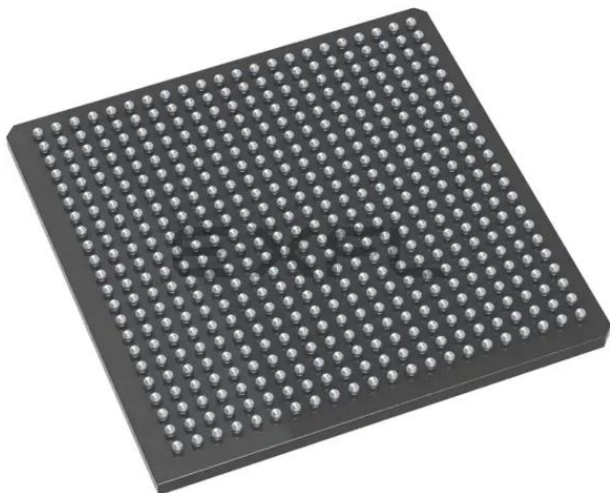




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Embedded - System On Chip (SoC): The Heart of Modern Embedded Systems

Embedded - System On Chip (SoC) refers to an integrated circuit that consolidates all the essential components of a computer system into a single chip. This includes a microprocessor, memory, and other peripherals, all packed into one compact and efficient package. SoCs are designed to provide a complete computing solution, optimizing both space and power consumption, making them ideal for a wide range of embedded applications.

What are Embedded - System On Chip (SoC)?

System On Chip (SoC) integrates multiple functions of a computer or electronic system onto a single chip. Unlike traditional multi-chip solutions, SoCs combine a central

Details

Product Status	Active
Architecture	MCU, FPGA
Core Processor	ARM® Cortex®-M3
Flash Size	512KB
RAM Size	64KB
Peripherals	DDR, PCIe, SERDES
Connectivity	CANbus, Ethernet, I ² C, SPI, UART/USART, USB
Speed	166MHz
Primary Attributes	FPGA - 90K Logic Modules
Operating Temperature	-40°C ~ 100°C (TJ)
Package / Case	484-BGA
Supplier Device Package	484-FPBGA (23x23)
Purchase URL	https://www.e-xfl.com/product-detail/microchip-technology/m2s090-fgg484i

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2.2 References

The following documents are recommended references:

- *PB0121: IGLOO2 Product Brief*
- *DS0124: IGLOO2 Pin Descriptions*
- *PB0115: SmartFusion2 SoC FPGA Product Brief*
- *DS0115: SmartFusion2 Pin Descriptions*

All product documentation for IGLOO2 and SmartFusion2 is available at:

<http://www.microsemi.com/products/fpga-soc/fpga/igloo2-fpga>

<http://www.microsemi.com/products/fpga-soc/soc-fpga/smartfusion2#overview>

2.3 Electrical Specifications

2.3.1 Operating Conditions

The following table lists the stress limits. Stress applied above the specified limit may cause permanent damage to the device. Exposure to absolute maximum rating conditions for extended periods may affect device reliability.

Absolute maximum ratings are stress ratings only; functional operation of the device at these or any other conditions beyond those listed under the recommended operating conditions specified in the following table are not implied.

Table 3 • Absolute Maximum Ratings

Parameter	Symbol	Min	Max	Unit
DC core supply voltage. Must always power this pin.	V _{DD}	−0.3	1.32	V
Power supply for charge pumps (for normal operation and programming). Must always power this pin.	V _{PP}	−0.3	3.63	V
Analog power pad for MDDR PLL	MSS_MDDR_PLL_VDDA	−0.3	3.63	V
Analog power pad for MDDR PLL	HPMS_MDDR_PLL_VDDA	−0.3	3.63	V
Analog power pad for FDDR PLL	FDDR_PLL_VDDA	−0.3	3.63	V
Analog power pad for MDDR PLL	PLL0_PLL1_MSS_MDDR_VDDA	−0.3	3.63	V
Analog power pad for MDDR PLL	PLL0_PLL1_HPMS_MDDR_VDDA	−0.3	3.63	V
Analog power pad for PLL0–5	CCC_XX[01]_PLL_VDDA	−0.3	3.63	V
High supply voltage for PLL SerDes[01]	SERDES_[01]_PLL_VDDA	−0.3	3.63	V
Analog power for SerDes[01] PLL lane0 to lane3. This is a 2.5 V SerDes internal PLL supply.	SERDES_[01]_L[0123]_VDDAPLL	−0.3	2.75	V
TX/RX analog I/O voltage. Low voltage power for the lanes of SerDesIF0. This is a 1.2 V SerDes PMA supply.	SERDES_[01]_L[0123]_VDDAIO	−0.3	1.32	V
PCIe/PCS power supply	SERDES_[01]_VDD	−0.3	1.32	V
DC FPGA I/O buffer supply voltage for MSIO I/O bank	V _{DDI_x}	−0.3	3.63	V
DC FPGA I/O buffer supply voltage for MSIOD/DDRIO I/O banks	V _{DDI_x}	−0.3	2.75	V
I/O Input voltage for MSIO I/O bank	V _I	−0.3	3.63	V
I/O Input voltage for MSIOD/DDRIO I/O bank	V _I	−0.3	2.75	V
Analog sense circuit supply of embedded nonvolatile memory (eNVM). Must be shorted to V _{PP} .	V _{PPNVM}	−0.3	3.63	V
Storage temperature ¹	T _{STG}	−65	150	°C
Junction temperature	T _J	−55	135	°C

Table 4 • Recommended Operating Conditions (continued)

Parameter	Symbol	Min	Typ	Max	Unit	Conditions
3.3 V DC supply voltage	V_{DDIX}	3.15	3.3	3.45	V	
LVDS differential I/O	V_{DDIX}	2.375	2.5	3.45	V	
B-LVDS, M-LVDS, Mini-LVDS, RSDS differential I/O	V_{DDIX}	2.375	2.5	2.625	V	
LVPECL differential I/O	V_{DDIX}	3.15	3.3	3.45	V	
Reference voltage supply for FDDR (Bank0) and MDDR (Bank5)	V_{REFX}	$0.49 \times V_{DDIX}$	$0.5 \times V_{DDIX}$	$0.51 \times V_{DDIX}$	V	
Analog sense circuit supply of embedded nonvolatile memory (eNVM). Must be shorted to V_{PP} .	V_{PPNVM}	2.375	2.5	2.625	V	2.5 V range
		3.15	3.3	3.45	V	3.3 V range

1. Programming at Industrial temperature range is available only with $V_{PP} = 3.3$ V.

Note: Power supply ramps must all be strictly monotonic, without plateaus.

Table 5 • FPGA Operating Limits

Product Grade	Element	Programming Temperature	Operating Temperature	Programming Cycles	Digest Temperature	Digest Cycles	Retention (Biased/Unbiased)
Commercial	FPGA	Min $T_J = 0$ °C Max $T_J = 85$ °C	Min $T_J = 0$ °C Max $T_J = 85$ °C	500	Min $T_J = 0$ °C Max $T_J = 85$ °C	2000	20 years
Industrial ¹	FPGA	Min $T_J = -40$ °C Max $T_J = 100$ °C	Min $T_J = -40$ °C Max $T_J = 100$ °C	500	Min $T_J = -40$ °C Max $T_J = 100$ °C	2000	20 years

1. Programming at Industrial temperature range is available only with $V_{PP} = 3.3$ V.

Note: The retention specification is defined as the total number of programing and digest cycles. For example, 20 years of retention after 500 programming cycles.

Note: The digest cycle specification is 2000 digest cycles for every program cycle with a maximum of 500 programming cycles.

Note: If your product qualification requires accelerated programming cycles, see *Microsemi SoC Products Quality and Reliability Report* about recommended methodologies.

The following table lists the embedded operating flash limits.

Table 6 • Embedded Operating Flash Limits

Product Grade	Element	Programming Temperature	Maximum Operating Temperature	Programming Cycles	Retention (Biased/Unbiased)
Commercial	Embedded flash	Min $T_J = 0\text{ }^{\circ}\text{C}$ Max $T_J = 85\text{ }^{\circ}\text{C}$	Min $T_J = 0\text{ }^{\circ}\text{C}$ Max $T_J = 85\text{ }^{\circ}\text{C}$	< 1000 cycles per page, up to two million cycles per eNVM array	20 years
			Min $T_J = 0\text{ }^{\circ}\text{C}$ Max $T_J = 85\text{ }^{\circ}\text{C}$	< 10000 cycles per page, up to 20 million cycles per eNVM array	10 years
Industrial	Embedded flash	Min $T_J = -40\text{ }^{\circ}\text{C}$ Max $T_J = 100\text{ }^{\circ}\text{C}$	Min $T_J = -40\text{ }^{\circ}\text{C}$ Max $T_J = 100\text{ }^{\circ}\text{C}$	< 1000 cycles per page, up to two million cycles per eNVM array	20 years
			Min $T_J = -40\text{ }^{\circ}\text{C}$ Max $T_J = 100\text{ }^{\circ}\text{C}$	< 10000 cycles per page, up to 20 million cycles per eNVM array	10 years

Note: If your product qualification requires accelerated programming cycles, see *Microsemi SoC Products Quality and Reliability Report* about recommended methodologies.

Table 7 • Device Storage Temperature and Retention

Product Grade	Storage Temperature (Tstg)	Retention
Commercial	Min $T_J = 0\text{ }^{\circ}\text{C}$ Max $T_J = 85\text{ }^{\circ}\text{C}$	20 years
Industrial	Min $T_J = -40\text{ }^{\circ}\text{C}$ Max $T_J = 100\text{ }^{\circ}\text{C}$	20 years

Table 8 • High Temperature Data Retention (HTR) Lifetime

T_J (C)	HTR Lifetime ¹ (yrs)
90	20.5
95	20.5
100	20.5
105	17.0
110	15.0
115	13.0
120	11.5
125	10.0
130	8.0
135	6.0
140	4.5
145	3.0
150	1.5

1. HTR Lifetime is the period during which a verify failure is not expected due to flash leakage.

2.3.2 Power Consumption

The following sections describe the power consumptions of the devices.

2.3.2.1 Quiescent Supply Current

Table 10 • Quiescent Supply Current Characteristics

Power Supplies/Blocks	Modes and Configurations	
	Non-Flash*Freeze	Flash*Freeze
FPGA Core	On	Off
V _{DD} /SERDES_[01]_VDD ¹	On	On
V _{PP} /V _{PPNVM}	On	On
HPMS_MDDR_PLL_VDDA/FDDR_PLL_VDDA/ CCC_XX[01]_PLL_VDDA/PLL0_PLL1_HPMS_MDDR_VDD A	0 V	0 V
SERDES_[01]_PLL_VDDA ²	0 V	0 V
SERDES_[01]_L[0123]_VDDAPLL/VDD_2V5 ²	On	On
SERDES_[01]_L[0123]_VDDAIIO ²	On	On
V _{DDI_x} ^{3, 4}	On	On
V _{REFx}	On	On
MSSDDR CLK	32 kHz	32 kHz
RAM	On	Sleep state
System controller	50 MHz	50 MHz
50 MHz oscillator (enable/disable)	Enable	Disabled
1 MHz oscillator (enable/disable)	Disabled	Disabled
Crystal oscillator (enable/disable)	Disabled	Disabled

1. SERDES_[01]_VDD Power Supply is shorted to V_{DD}.
2. SerDes and DDR blocks to be unused.
3. V_{DDI_x} has been set to ON for test conditions as described. Banks on the east side should always be powered with the appropriate V_{DDI} bank supplies. For details on bank power supplies, see "Recommendation for Unused Bank Supplies" table in the AC393: *SmartFusion2 and IGLOO2 Board Design Guidelines Application Note*.
4. No Differential (that is to say, LVDS) I/Os or ODT attributes to be used.

Table 11 • SmartFusion2 and IGLOO2 Quiescent Supply Current (V_{DD} = 1.2 V) – Typical Process

Symbol	Modes	005	010	025	050	060	090	150	Unit	Conditions
IDC1	Non-Flash*Freeze	6.2	6.9	8.9	13.1	15.3	15.4	27.5	mA	Typical (T _J = 25 °C)
		24.0	28.4	40.6	67.8	80.6	81.4	144.7	mA	Commercial (T _J = 85 °C)
		35.2	41.9	60.5	102.1	121.4	122.6	219.1	mA	Industrial (T _J = 100 °C)

Table 82 • LVCMOS 1.2 V Receiver Characteristics for MSIOD I/O Bank (Input Buffers)

On-Die Termination (ODT)	T_{PY}		T_{PYS}		Unit
	-1	-Std	-1	-Std	
None	4.154	4.887	4.114	4.84	ns
50	6.918	8.139	6.806	8.008	ns
75	5.613	6.603	5.533	6.509	ns
150	4.716	5.549	4.657	5.479	ns

Table 83 • LVCMOS 1.2 V Transmitter Characteristics for DDRIO I/O Bank (Output and Tristate Buffers)

Output Drive Selection	Slew Control	T_{DP}		T_{ZL}		T_{ZH}		T_{HZ}^1		T_{LZ}^1		Unit
		-1	-Std	-1	-Std	-1	-Std	-1	-Std	-1	-Std	
2 mA	Slow	6.713	7.897	5.362	6.308	6.723	7.909	7.233	8.51	6.375	7.499	ns
	Medium	5.912	6.955	4.616	5.43	5.915	6.959	6.887	8.102	6.009	7.069	ns
	Medium fast	5.5	6.469	4.231	4.978	5.5	6.471	6.672	7.849	5.835	6.865	ns
	Fast	5.462	6.426	4.194	4.935	5.463	6.427	6.646	7.819	5.828	6.857	ns
4 mA	Slow	6.109	7.186	4.708	5.539	6.098	7.174	8.005	9.418	7.033	8.274	ns
	Medium	5.355	6.299	4.034	4.746	5.338	6.28	7.637	8.985	6.672	7.849	ns
	Medium fast	4.953	5.826	3.685	4.336	4.932	5.802	7.44	8.752	6.499	7.646	ns
	Fast	4.911	5.777	3.658	4.303	4.89	5.754	7.427	8.737	6.488	7.632	ns
6 mA	Slow	5.89	6.929	4.506	5.301	5.874	6.911	8.337	9.808	7.315	8.605	ns
	Medium	5.176	6.089	3.862	4.543	5.155	6.065	7.986	9.394	6.943	8.168	ns
	Medium fast	4.792	5.637	3.523	4.145	4.765	5.606	7.808	9.186	6.775	7.97	ns
	Fast	4.754	5.593	3.486	4.101	4.728	5.563	7.777	9.149	6.769	7.963	ns

1. Delay increases with drive strength are inherent to built-in slew control circuitry for simultaneous switching output (SSO) management.

Table 84 • LVCMOS 1.2 V Transmitter Characteristics for MSIO I/O Bank (Output and Tristate Buffers)

Output Drive Selection	Slew Control	T_{DP}		T_{ZL}		T_{ZH}		T_{HZ}^1		T_{LZ}^1		Unit
		-1	-Std	-1	-Std	-1	-Std	-1	-Std	-1	-Std	
2 mA	Slow	6.746	7.937	7.458	8.774	8.172	9.614	9.867	11.608	8.393	9.874	ns
4 mA	Slow	7.068	8.315	6.678	7.857	7.474	8.793	10.986	12.924	9.043	10.638	ns

1. Delay increases with drive strength are inherent to built-in slew control circuitry for simultaneous switching output (SSO) management.

Table 144 • LPDDR AC Differential Voltage Specifications (for DDRIO I/O Bank Only)

Parameter	Symbol	Min	Max	Unit
AC input differential voltage	V_{DIFF}	$0.6 \times V_{DDI}$		V
AC differential cross point voltage	V_x	$0.4 \times V_{DDI}$	$0.6 \times V_{DDI}$	V

Table 145 • LPDDR AC Specifications (for DDRIO I/O Bank Only)

Parameter	Symbol	Max	Unit	Conditions
Maximum data rate	D_{MAX}	400	Mbps	AC loading: per JEDEC specifications

Table 146 • LPDDR AC Calibrated Impedance Option (for DDRIO I/O Bank Only)

Parameter	Symbol	Typ	Unit	Conditions
Supported output driver calibrated impedance	R_{REF}	20, 42	Ω	Reference resistor = 150 Ω
Effective impedance value (ODT)	R_{TT}	50, 70, 150	Ω	Reference resistor = 150 Ω

Table 147 • LPDDR AC Test Parameter Specifications (for DDRIO I/O Bank Only)

Parameter	Symbol	Typ	Unit
Measuring/trip point for data path	V_{TRIP}	0.9	V
Resistance for enable path (T_{ZH} , T_{ZL} , T_{HZ} , T_{LZ})	R_{ENT}	2K	Ω
Capacitive loading for enable path (T_{ZH} , T_{ZL} , T_{HZ} , T_{LZ})	C_{ENT}	5	pF
Reference resistance for data test path for LPDDR (T_{DP})	R_{TT_TEST}	50	Ω
Capacitive loading for data path (T_{DP})	C_{LOAD}	5	Ω

AC Switching Characteristics

Worst-case commercial conditions: $T_J = 85^\circ\text{C}$, $V_{DD} = 1.14\text{ V}$, worst-case V_{DDI} .

Table 148 • LPDDR Receiver Characteristics for DDRIO I/O Bank with Fixed Codes

		T_{PY}		Unit
On-Die Termination (ODT)		-1	-Std	
Pseudo differential	None	1.568	1.845	ns
True differential	None	1.588	1.869	ns

Table 149 • LPDDR Reduced Drive for DDRIO I/O Bank (Output and Tristate Buffers)

	T_{DP}		T_{ENZL}		T_{ENZH}		T_{ENHZ}		T_{ENLZ}		Unit
	-1	-Std	-1	-Std	-1	-Std	-1	-Std	-1	-Std	
Single-ended	2.383	2.804	2.23	2.623	2.229	2.622	2.202	2.591	2.201	2.59	ns
Differential	2.396	2.819	2.764	3.252	2.764	3.252	2.255	2.653	2.255	2.653	ns

AC Switching Characteristics

Worst commercial-case conditions: $T_J = 85\text{ }^{\circ}\text{C}$, $V_{DD} = 1.14\text{ V}$, $V_{DDI} = 2.375\text{ V}$.

Table 210 • RSDS AC Switching Characteristics for Receiver (for MSIO I/O Bank - Input Buffers)

On-Die Termination (ODT)	T_{PY}		Unit
	-1	-Std	
None	2.855	3.359	ns
100	2.85	3.353	ns

Table 211 • RSDS AC Switching Characteristics for Receiver (for MSIOD I/O Bank - Input Buffers)

On-Die Termination (ODT)	T_{PY}		Unit
	-1	-Std	
None	2.602	3.061	ns
100	2.597	3.055	ns

Table 212 • RSDS AC Switching Characteristics for Transmitter (for MSIO I/O Bank - Output and Tristate Buffers)

T_{DP}		T_{ZL}		T_{ZH}		T_{HZ}		T_{LZ}		Unit
-1	-Std	-1	-Std	-1	-Std	-1	-Std	-1	-Std	
2.097	2.467	2.303	2.709	2.291	2.695	1.961	2.307	1.947	2.29	ns

Table 213 • RSDS AC Switching Characteristics for Transmitter (for MSIOD I/O Bank - Output and Tristate Buffers)

	T_{DP}		T_{ZL}		T_{ZH}		T_{HZ}		T_{LZ}		Unit
	-1	-Std	-1	-Std	-1	-Std	-1	-Std	-1	-Std	
No pre-emphasis	1.614	1.899	1.559	1.834	1.55	1.823	1.59	1.87	1.575	1.852	ns
Min pre-emphasis	1.604	1.887	1.742	2.05	1.728	2.032	1.889	2.222	1.858	2.185	ns
Med pre-emphasis	1.521	1.79	1.753	2.062	1.737	2.043	1.9	2.235	1.868	2.197	ns
Max pre-emphasis	1.492	1.754	1.762	2.073	1.745	2.052	1.91	2.247	1.876	2.206	ns

2.3.7.6 LVPECL

Low-Voltage Positive Emitter-Coupled Logic (LVPECL) is another differential I/O standard. It requires that one data bit be carried through two signal lines. Similar to LVDS, two pins are needed. It also requires external resistor termination. IGLOO2 and SmartFusion2 SoC FPGAs support only LVPECL receivers and do not support LVPECL transmitters.

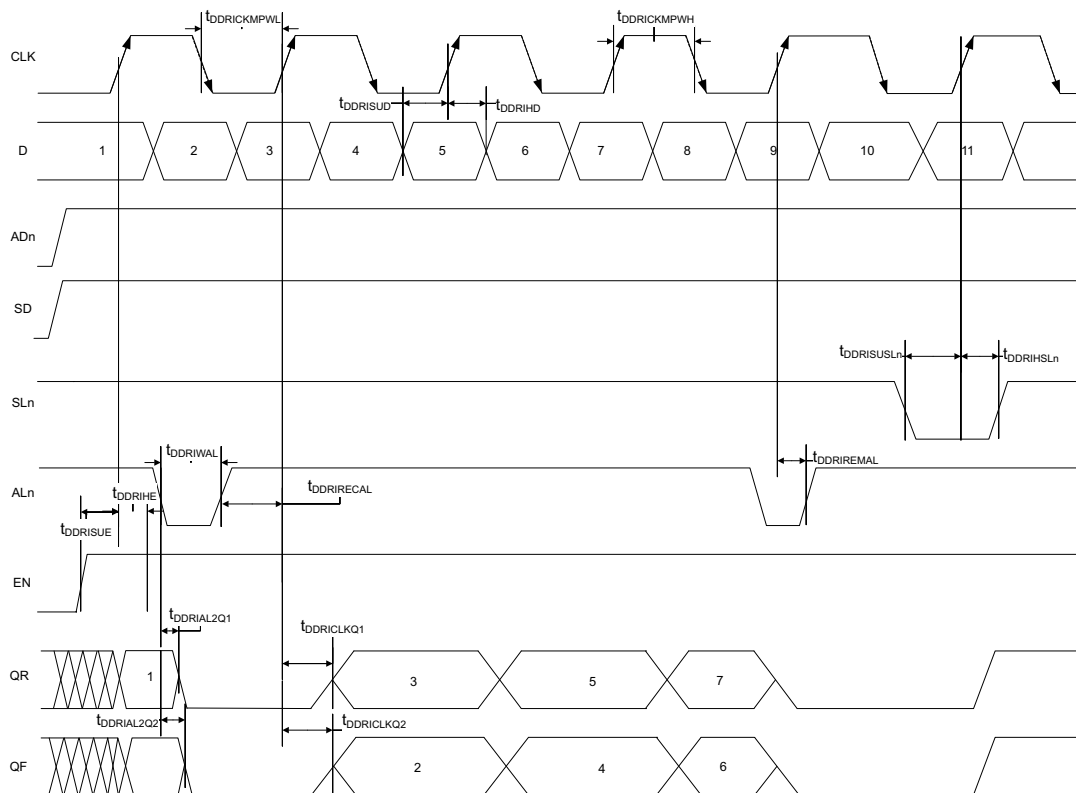
Minimum and Maximum Input and Output Levels (Applicable to MSIO I/O Bank Only)

Table 214 • LVPECL Recommended DC Operating Conditions

Parameter	Symbol	Min	Typ	Max	Unit
Supply voltage	V_{DDI}	3.15	3.3	3.45	V

2.3.9.2 Input DDR Timing Diagram

Figure 11 • Input DDR Timing Diagram



2.3.9.3 Timing Characteristics

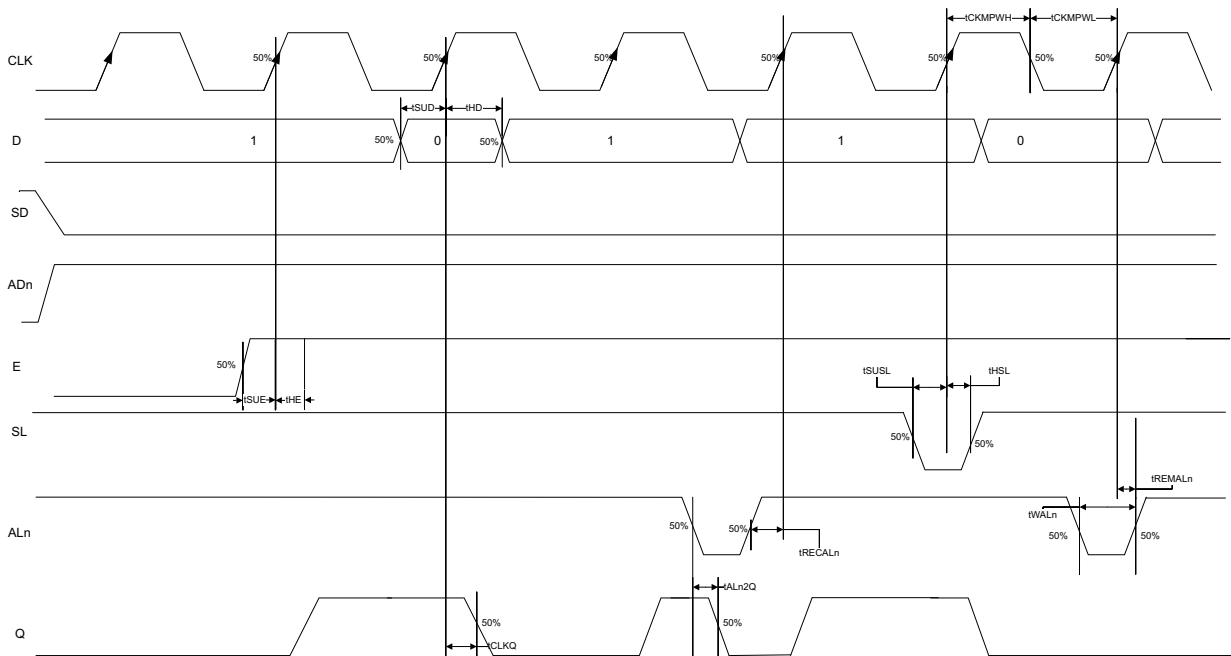
The following table lists the input DDR propagation delays in worst commercial-case conditions when $T_J = 85^\circ\text{C}$, $V_{DD} = 1.14\text{ V}$.

Table 221 • Input DDR Propagation Delays

Symbol	Description	Measuring Nodes (from, to)	–1	–Std	Unit
T _{DDRICKQ1}	Clock-to-Out Out_QR for input DDR	B, C	0.16	0.188	ns
T _{DDRICKQ2}	Clock-to-Out Out_QF for input DDR	B, D	0.166	0.195	ns
T _{DDRISUD}	Data setup for input DDR	A, B	0.357	0.421	ns
T _{DDRIHD}	Data hold for input DDR	A, B	0	0	ns
T _{DDRISUE}	Enable setup for input DDR	E, B	0.46	0.542	ns
T _{DDRIHE}	Enable hold for input DDR	E, B	0	0	ns
T _{DDRISUSLN}	Synchronous load setup for input DDR	G, B	0.46	0.542	ns
T _{DDRIHSLN}	Synchronous load hold for input DDR	G, B	0	0	ns
T _{DDRIAL2Q1}	Asynchronous load-to-out QR for input DDR	F, C	0.587	0.69	ns
T _{DDRIAL2Q2}	Asynchronous load-to-out QF for input DDR	F, D	0.541	0.636	ns
T _{DDRIREMA}	Asynchronous load removal time for input DDR	F, B	0	0	ns
T _{DDRIRECA}	Asynchronous load recovery time for input DDR	F, B	0.074	0.087	ns

The following figure shows a configuration with SD = 0 (synchronous clear) and ADn = 1 (asynchronous clear) for a flip-flop (LAT = 0).

Figure 16 • Sequential Module Timing Diagram



2.3.10.3.1 Timing Characteristics

The following table lists the register delays in worst commercial-case conditions when $T_J = 85^\circ\text{C}$, $V_{DD} = 1.14\text{ V}$.

Table 224 • Register Delays

Parameter	Symbol	-1	-Std	Unit
Clock-to-Q of the core register	T_{CLKQ}	0.108	0.127	ns
Data setup time for the core register	T_{SUD}	0.254	0.298	ns
Data hold time for the core register	T_{HD}	0	0	ns
Enable setup time for the core register	T_{SUE}	0.335	0.394	ns
Enable hold time for the core register	T_{HE}	0	0	ns
Synchronous load setup time for the core register	T_{SUSL}	0.335	0.394	ns
Synchronous load hold time for the core register	T_{HSL}	0	0	ns
Asynchronous Clear-to-Q of the core register (ADn = 1)	T_{ALN2Q}	0.473	0.556	ns
Asynchronous preset-to-Q of the core register (ADn = 0)		0.451	0.531	ns
Asynchronous load removal time for the core register	T_{RECALN}	0	0	ns
Asynchronous load recovery time for the core register	T_{RECALN}	0.353	0.415	ns
Asynchronous load minimum pulse width for the core register	T_{WALN}	0.266	0.313	ns
Clock minimum pulse width high for the core register	T_{CKMPWH}	0.065	0.077	ns
Clock minimum pulse width low for the core register	T_{CKMPWL}	0.139	0.164	ns

The following table lists the 010 device global resources in worst commercial-case conditions when $T_J = 85^\circ\text{C}$, $V_{DD} = 1.14\text{ V}$.

Table 229 • 010 Device Global Resource

Parameter	Symbol	-1		-Std		Unit
		Min	Max	Min	Max	
Input low delay for global clock	T_{RCKL}	0.626	0.669	0.627	0.668	ns
Input high delay for global clock	T_{RCKH}	1.112	1.182	1.308	1.393	ns
Maximum skew for global clock	T_{RCKSW}		0.07		0.085	ns

The following table lists the 005 device global resources in worst commercial-case conditions when $T_J = 85^\circ\text{C}$, $V_{DD} = 1.14\text{ V}$.

Table 230 • 005 Device Global Resource

Parameter	Symbol	-1		-Std		Unit
		Min	Max	Min	Max	
Input low delay for global clock	T_{RCKL}	0.625	0.66	0.628	0.66	ns
Input high delay for global clock	T_{RCKH}	1.126	1.187	1.325	1.397	ns
Maximum skew for global clock	T_{RCKSW}		0.061		0.072	ns

2.3.12 FPGA Fabric SRAM

See *UG0445: IGLOO2 FPGA and SmartFusion2 SoC FPGA Fabric User Guide* for more information.

2.3.12.1 FPGA Fabric Large SRAM (LSRAM)

The following table lists the RAM1K18 – dual-port mode for depth × width configuration 1K × 18 in worst commercial-case conditions when $T_J = 85^\circ\text{C}$, $V_{DD} = 1.14\text{ V}$.

Table 231 • RAM1K18 – Dual-Port Mode for Depth × Width Configuration 1K × 18

Parameter	Symbol	-1		-Std		Unit
		Min	Max	Min	Max	
Clock period	T_{CY}	2.5		2.941		ns
Clock minimum pulse width high	$T_{CLKMPWH}$	1.125		1.323		ns
Clock minimum pulse width low	$T_{CLKMPWL}$	1.125		1.323		ns
Pipelined clock period	T_{PLCY}	2.5		2.941		ns
Pipelined clock minimum pulse width high	$T_{PLCLKMPWH}$	1.125		1.323		ns
Pipelined clock minimum pulse width low	$T_{PLCLKMPWL}$	1.125		1.323		ns
Read access time with pipeline register			0.334		0.393	ns
Read access time without pipeline register	T_{CLK2Q}		2.273		2.674	ns
Access time with feed-through write timing			1.529		1.799	ns
Address setup time	T_{ADDRSU}	0.441		0.519		ns
Address hold time	T_{ADDRHD}	0.274		0.322		ns
Data setup time	T_{DSU}	0.341		0.401		ns
Data hold time	T_{DHD}	0.107		0.126		ns
Block select setup time	T_{BLKSU}	0.207		0.244		ns

Table 231 • RAM1K18 – Dual-Port Mode for Depth × Width Configuration 1K × 18 (continued)

Parameter	Symbol	–1		–Std		Unit
		Min	Max	Min	Max	
Block select hold time	T _{BLKHD}	0.216		0.254		ns
Block select to out disable time (when pipelined register is disabled)	T _{BLK2Q}		1.529		1.799	ns
Block select minimum pulse width	T _{BLKMPW}	0.186		0.219		ns
Read enable setup time	T _{RDESU}	0.449		0.528		ns
Read enable hold time	T _{RDEHD}	0.167		0.197		ns
Pipelined read enable setup time (A_DOUT_EN, B_DOUT_EN)	T _{RDPLESU}	0.248		0.291		ns
Pipelined read enable hold time (A_DOUT_EN, B_DOUT_EN)	T _{RDPLEHD}	0.102		0.12		ns
Asynchronous reset to output propagation delay	T _{R2Q}	–	1.506	–	1.772	ns
Asynchronous reset removal time	T _{RSTREM}	0.506		0.595		ns
Asynchronous reset recovery time	T _{RSTREC}	0.004		0.005		ns
Asynchronous reset minimum pulse width	T _{RSTMPW}	0.301		0.354		ns
Pipelined register asynchronous reset removal time	T _{PLRSTREM}	–0.279		–0.328		ns
Pipelined register asynchronous reset recovery time	T _{PLRSTREC}	0.327		0.385		ns
Pipelined register asynchronous reset minimum pulse width	T _{PLRSTMPW}	0.282		0.332		ns
Synchronous reset setup time	T _{SRSTSU}	0.226		0.265		ns
Synchronous reset hold time	T _{SRSTHD}	0.036		0.043		ns
Write enable setup time	T _{WESU}	0.39		0.458		ns
Write enable hold time	T _{WEHD}	0.242		0.285		ns
Maximum frequency	F _{MAX}		400		340	MHz

The following table lists the RAM1K18 – dual-port mode for depth × width configuration 2K × 9 in worst commercial-case conditions when T_J = 85 °C, V_{DD} = 1.14 V.

Table 232 • RAM1K18 – Dual-Port Mode for Depth × Width Configuration 2K × 9

Parameter	Symbol	–1		–Std		Unit
		Min	Max	Min	Max	
Clock period	T _{CY}	2.5		2.941		ns
Clock minimum pulse width high	T _{CLKMPWH}	1.125		1.323		ns
Clock minimum pulse width low	T _{CLKMPWL}	1.125		1.323		ns
Pipelined clock period	T _{PLCY}	2.5		2.941		ns
Pipelined clock minimum pulse width high	T _{PLCLKMPWH}	1.125		1.323		ns
Pipelined clock minimum pulse width low	T _{PLCLKMPWL}	1.125		1.323		ns
Read access time with pipeline register			0.334		0.393	ns
Read access time without pipeline register	T _{CLK2Q}		2.273		2.674	ns
Access time with feed-through write timing			1.529		1.799	ns

The following table lists the RAM1K18 – two-port mode for depth × width configuration 512 × 36 in worst commercial-case conditions when $T_J = 85\text{ }^{\circ}\text{C}$, $V_{DD} = 1.14\text{ V}$.

Table 236 • RAM1K18 – Two-Port Mode for Depth × Width Configuration 512 × 36

Parameter	Symbol	–1		–Std		Unit
		Min	Max	Min	Max	
Clock period	T_{CY}	2.5		2.941		ns
Clock minimum pulse width high	$T_{CLKMPWH}$	1.125		1.323		ns
Clock minimum pulse width low	$T_{CLKMPWL}$	1.125		1.323		ns
Pipelined clock period	T_{PLCY}	2.5		2.941		ns
Pipelined clock minimum pulse width high	$T_{PLCLKMPWH}$	1.125		1.323		ns
Pipelined clock minimum pulse width low	$T_{PLCLKMPWL}$	1.125		1.323		ns
Read access time with pipeline register	T_{CLK2Q}		0.334		0.393	ns
Read access time without pipeline register			2.25		2.647	ns
Address setup time	T_{ADDRSU}	0.313		0.368		ns
Address hold time	T_{ADDRHD}	0.274		0.322		ns
Data setup time	T_{DSU}	0.337		0.396		ns
Data hold time	T_{DHD}	0.111		0.13		ns
Block select setup time	T_{BLKSU}	0.207		0.244		ns
Block select hold time	T_{BLKHD}	0.201		0.237		ns
Block select to out disable time (when pipelined register is disabled)	T_{BLK2Q}		2.25		2.647	ns
Block select minimum pulse width	T_{BLKMPW}	0.186		0.219		ns
Read enable setup time	T_{RDESU}	0.449		0.528		ns
Read enable hold time	T_{RDEHD}	0.167		0.197		ns
Pipelined read enable setup time (A_DOUT_EN, B_DOUT_EN)	$T_{RDPLESU}$	0.248		0.291		ns
Pipelined read enable hold time (A_DOUT_EN, B_DOUT_EN)	$T_{RDPLEHD}$	0.102		0.12		ns
Asynchronous reset to output propagation delay	T_{R2Q}		1.506		1.772	ns
Asynchronous reset removal time	T_{RSTREM}	0.506		0.595		ns
Asynchronous reset recovery time	T_{RSTREC}	0.004		0.005		ns
Asynchronous reset minimum pulse width	T_{RSTMPW}	0.301		0.354		ns
Pipelined register asynchronous reset removal time	$T_{PLRSTREM}$	–0.279		–0.328		ns
Pipelined register asynchronous reset recovery time	$T_{PLRSTREC}$	0.327		0.385		ns
Pipelined register asynchronous reset minimum pulse width	$T_{PLRSTMPW}$	0.282		0.332		ns
Synchronous reset setup time	T_{SRSTSU}	0.226		0.265		ns
Synchronous reset hold time	T_{SRSTHD}	0.036		0.043		ns
Write enable setup time	T_{WESU}	0.39		0.458		ns
Write enable hold time	T_{WEHD}	0.242		0.285		ns
Maximum frequency	F_{MAX}		400		340	MHz

The following table lists the math blocks with input register used and output in bypass mode in worst commercial-case conditions when $T_J = 85\text{ }^{\circ}\text{C}$, $V_{DD} = 1.14\text{ V}$.

Table 270 • Math Block with Input Register Used and Output in Bypass Mode

Parameter	Symbol	-1		-Std		Unit
		Min	Max	Min	Max	
Input register setup time	T_{MISU}	0.149		0.176		ns
Input register hold time	T_{MIHD}	0.185		0.218		ns
Synchronous reset/enable setup time	$T_{MSRSTENSU}$	0.08		0.094		ns
Synchronous reset/enable hold time	$T_{MSRSTENHD}$	-0.012		-0.014		ns
Asynchronous reset removal time	$T_{MARSTREM}$	-0.005		-0.005		ns
Asynchronous reset recovery time	$T_{MARSTREC}$	0.088		0.104		ns
Input register clock to output delay	T_{MICQ}		2.52		2.964	ns
CDIN to output delay	$T_{MCDIN2Q}$		1.951		2.295	ns

The following table lists the math blocks with input and output in bypass mode in worst commercial-case conditions when $T_J = 85\text{ }^{\circ}\text{C}$, $V_{DD} = 1.14\text{ V}$.

Table 271 • Math Block with Input and Output in Bypass Mode

Parameter	Symbol	-1	-Std	Unit
		Max	Max	
Input to output delay	T_{MIQ}	2.568	3.022	ns
CDIN to output delay	$T_{MCDIN2Q}$	1.951	2.295	ns

2.3.15 Embedded NVM (eNVM) Characteristics

The following table lists the eNVM read performance in worst-case conditions when $V_{DD} = 1.14\text{ V}$, $V_{PPNVM} = V_{PP} = 2.375\text{ V}$.

Table 272 • eNVM Read Performance

Symbol	Description	Operating Temperature Range						Unit
		-1	-Std	-1	-Std	-1	-Std	
T_J	Junction temperature range	-55 °C to 125 °C		-40 °C to 100 °C		0 °C to 85 °C		°C
$F_{MAXREAD}$	eNVM maximum read frequency	25	25	25	25	25	25	MHz

The following table lists the eNVM page programming in worst-case conditions when $V_{DD} = 1.14\text{ V}$, $V_{PPNVM} = V_{PP} = 2.375\text{ V}$.

Table 273 • eNVM Page Programming

Symbol	Description	Operating Temperature Range						Unit
		-1	-Std	-1	-Std	-1	-Std	
T_J	Junction temperature range	-55 °C to 125 °C		-40 °C to 100 °C		0 °C to 85 °C		°C
$T_{PAGEPGM}$	eNVM page programming time	40	40	40	40	40	40	ms

2.3.20 On-Chip Oscillator

The following tables describe the electrical characteristics of the available on-chip oscillators in the IGLOO2 FPGAs and SmartFusion2 SoC FPGAs.

Table 280 • Electrical Characteristics of the 50 MHz RC Oscillator

Parameter	Symbol	Typ	Max	Unit	Condition
Operating frequency	F50RC	50		MHz	
Accuracy	ACC50RC	1	4	%	050 devices
		1	5	%	005, 025, and 060 devices
		1	6.3	%	090 devices
		1	7.1	%	010 and 150 devices
Output duty cycle	CYC50RC	49–51	46.5–53.5	%	
Output jitter (peak to peak)	JIT50RC				Period Jitter
		200	300	ps	005, 010, 050, and 060 devices
		200	400	ps	150 devices
		300	500	ps	025 and 090 devices
					Cycle-to-Cycle Jitter
		200	300	ps	005 and 050 devices
		320	420	ps	010, 060, and 150 devices
		320	850	ps	025 and 090 devices
Operating current	IDYN50RC	6.5		mA	

Table 281 • Electrical Characteristics of the 1 MHz RC Oscillator

Parameter	Symbol	Typ	Max	Unit	Condition
Operating frequency	F1RC	1		MHz	
Accuracy	ACC1RC	1	3	%	005, 010, 025, and 050 devices
		1	4.5	%	060, and 150 devices
		1	5.6	%	090 devices
Output duty cycle	CYC1RC	49–51	46.5–53.5	%	005, 010, 025, 050, 090 and 150 devices
		49–51	46.0–54.0	%	060 devices
Output jitter (peak to peak)	JIT1RC				Period Jitter
		10	20	ns	005, 010, 025, and 050 devices
		10	28	ns	060, 090 and 150 devices
					Cycle-to-Cycle Jitter
		10	20	ns	005, 010, and 050 devices
		10	35	ns	025, 060, and 150 devices
		10	45	ns	090 devices
Operating current	IDYN1RC	0.1		mA	
Startup time	SU1RC		17	μs	050, 090, and 150 devices
			18	μs	005, 010, and 025 devices

1. The minimum output clock frequency is limited by the PLL. For more information, see *UG0449: SmartFusion2 and IGLOO2 Clocking Resources User Guide*.
2. The PLL is used in conjunction with the Clock Conditioning Circuitry. Performance is limited by the CCC output frequency.

The following table lists the CCC/PLL jitter specifications in worst-case industrial conditions when $T_J = 100\text{ }^{\circ}\text{C}$, $V_{DD} = 1.14\text{ V}$.

Table 283 • IGLOO2 and SmartFusion2 SoC FPGAs CCC/PLL Jitter Specifications

CCC Output Maximum Peak-to-Peak Period Jitter F _{OUT_CCC}						
Parameter		Conditions/Package Combinations				Unit
10 FG484, 050 FG896/FG484/FCS325 Packages ¹	SSO = 0	0 < SSO <= 2	SSO <= 4	SSO <= 8	SSO <= 16	
20 MHz to 100 MHz	Max(110, ± 1% x (1/F _{OUT_CCC}))	Max(150, ± 1% x (1/F _{OUT_CCC}))				ps
100 MHz to 400 MHz	Max(120, ± 1% x (1/F _{OUT_CCC}))	Max(150, ± 1% x (1/F _{OUT_CCC}))			Max(170, ± 1% x (1/F _{OUT_CCC}))	ps
025 FG484/FCS325 Package ¹	0 < SSO <=16					
20 MHz to 74 MHz	± 1% x (1/F _{OUT_CCC}))					ps
74 MHz to 400 MHz	210					ps
005 FG484 Package ¹	0 < SSO <=16					
20 MHz to 53 MHz	± 1% x (1/F _{OUT_CCC}))					ps
53 MHz to 400 MHz	270					ps
090 FG676 and FC325 Package ¹	0 < SSO <=16					
20 MHz to 100 MHz	± 1% x (1/F _{OUT_CCC}))					ps
100 MHz to 400 MHz	150					ps
060 FG676 Package ¹	0 < SSO <=16					
20 MHz to 100 MHz	± 1% x (1/F _{OUT_CCC})					ps
100 MHz to 400 MHz	150					
150 FC1152 Package ¹	0 < SSO <=16					
20 MHz to 100 MHz	± 1% x (1/F _{OUT_CCC}))					ps
100 MHz to 400 MHz	120					ps

1. SSO data is based on LVCMOS 2.5 V MSIO and/or MSIOD bank I/Os.

The following table lists the receiver pa in worst-case industrial conditions when $T_J = 100\text{ }^{\circ}\text{C}$, $V_{DD} = 1.14\text{ V}$.

Table 297 • Receiver Parameters

Symbol	Description	Min	Typ	Max	Unit
VRX-IN-PP-CC	Differential input peak-to-peak sensitivity (2.5 Gbps)	0.238		1.2	V
	Differential input peak-to-peak sensitivity (2.5 Gbps, de-emphasized)	0.219		1.2	V
	Differential input peak-to-peak sensitivity (5.0 Gbps)	0.300		1.2	V
	Differential input peak-to-peak sensitivity (5.0 Gbps, de-emphasized)	0.300		1.2	V
VRX-CM-AC-P	Input common mode range (AC coupled)			150	mV
ZRX-DIFF-DC	Differential input termination	80	100	120	Ω
REXT	External calibration resistor	1,188	1,200	1,212	Ω
CDR-LOCK-RST	CDR relock time from reset			15	μs
RLRX-DIFF	Return loss differential mode (2.5 Gbps)	-10			dB
	Return loss differential mode (5.0 Gbps)				
	0.05 GHz to 1.25 GHz	-10			dB
	1.25 GHz to 2.5 GHz	-8			dB
RLRX-CM	Return loss common mode (2.5 Gbps, 5.0 Gbps)	-6			dB
RX-CID ¹	CID limit PCIe Gen1/2			200	UI
VRX-IDLE-DET-DIFF-PP	Signal detect limit	65		175	mV

1. AC-coupled, BER = e^{-12} , using synchronous clock.

Table 298 • SerDes Protocol Compliance

Protocol	Maximum Data Rate (Gbps)	-1	-Std
PCIe Gen 1	2.5	Yes	Yes
PCIe Gen 2	5.0	Yes	
XAUI	3.125	Yes	
Generic EPCS	3.2	Yes	
Generic EPCS	2.5	Yes	Yes

Table 303 • I2C Characteristics (continued)

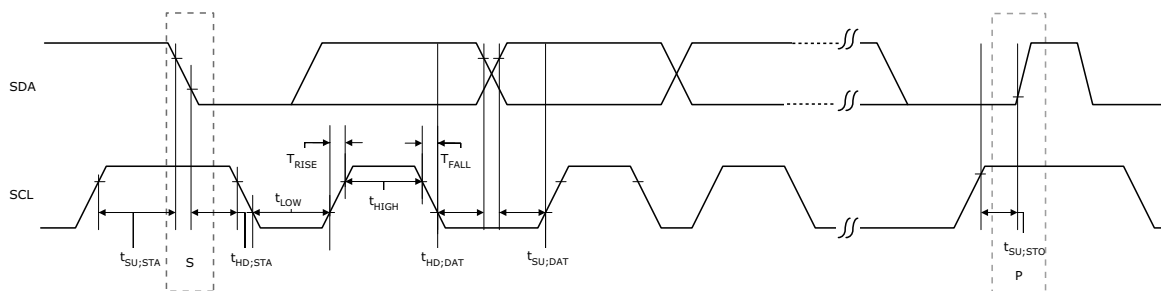
Parameter	Symbol	Min	Typ	Max	Unit	Conditions
Maximum data rate	D_{MAX}			400	Kbps	Fast mode
				100	Kbps	Standard mode
Pulse width of spikes which must be suppressed by the input filter	T_{FILT}		50		ns	Fast mode

1. These values are provided for MSIO Bank–LVTTL 8 mA Low Drive at 25 °C, typical conditions. For board design considerations and detailed output buffer resistances, use the corresponding IBIS models located on the SoC Products Group website: <http://www.microsemi.com/soc/download/ibis/default.aspx>.
2. These maximum values are provided for information only. Minimum output buffer resistance values depend on V_{DDIX} , drive strength selection, temperature, and process. For board design considerations and detailed output buffer resistances, use the corresponding IBIS models located on the SoC Products Group website: <http://www.microsemi.com/soc/download/ibis/default.aspx>.
3. $R(PULL-DOWN-MAX) = (VOL_{spec})/IOL_{spec}$.
4. $R(PULL-UP-MAX) = (VDDImax - VOH_{spec})/IOH_{spec}$.

The following table lists the I²C switching characteristics in worst-case industrial conditions when $T_J = 100\text{ °C}$, $V_{DD} = 1.14\text{ V}$

Table 304 • I2C Switching Characteristics

Parameter	Symbol	–1	Std	Unit
		Min	Min	
Low period of I2C_x_SCL	T_{LOW}	1	1	PCLK cycles
High period of I2C_x_SCL	T_{HIGH}	1	1	PCLK cycles
START hold time	$T_{HD;STA}$	1	1	PCLK cycles
START setup time	$T_{SU;STA}$	1	1	PCLK cycles
DATA hold time	$T_{HD;DAT}$	1	1	PCLK cycles
DATA setup time	$T_{SU;DAT}$	1	1	PCLK cycles
STOP setup time	$T_{SU;STO}$	1	1	PCLK cycles

Figure 21 • I²C Timing Parameter Definition

2.3.31.3 Serial Peripheral Interface (SPI) Characteristics

This section describes the DC and switching of the SPI interface. Unless otherwise noted, all output characteristics given are for a 35 pF load on the pins and all sequential timing characteristics are related to SPI_x_CLK. For timing parameter definitions, see Figure 22, page 128.

The following table lists the SPI characteristics in worst-case industrial conditions when $T_J = 100\text{ }^{\circ}\text{C}$, $V_{DD} = 1.14\text{ V}$

Table 305 • SPI Characteristics for All Devices

Symbol	Description	Min	Typ	Max	Unit	Conditions
SPIFMAX	Maximum operating frequency of SPI interface			20	MHz	
sp1	SPI_[0 1]_CLK minimum period					
	SPI_[0 1]_CLK = PCLK/2	12			ns	
	SPI_[0 1]_CLK = PCLK/4	24.1			ns	
	SPI_[0 1]_CLK = PCLK/8	48.2			ns	
	SPI_[0 1]_CLK = PCLK/16	0.1			μs	
	SPI_[0 1]_CLK = PCLK/32	0.19			μs	
	SPI_[0 1]_CLK = PCLK/64	0.39			μs	
	SPI_[0 1]_CLK = PCLK/128	0.77			μs	
sp2	SPI_[0 1]_CLK minimum pulse width high					
	SPI_[0 1]_CLK = PCLK/2	6			ns	
	SPI_[0 1]_CLK = PCLK/4	12.05			ns	
	SPI_[0 1]_CLK = PCLK/8	24.1			ns	
	SPI_[0 1]_CLK = PCLK/16	0.05			μs	
	SPI_[0 1]_CLK = PCLK/32	0.095			μs	
	SPI_[0 1]_CLK = PCLK/64	0.195			μs	
	SPI_[0 1]_CLK = PCLK/128	0.385			μs	
sp3	SPI_[0 1]_CLK minimum pulse width low					
	SPI_[0 1]_CLK = PCLK/2	6			ns	
	SPI_[0 1]_CLK = PCLK/4	12.05			ns	
	SPI_[0 1]_CLK = PCLK/8	24.1			ns	
	SPI_[0 1]_CLK = PCLK/16	0.05			μs	
	SPI_[0 1]_CLK = PCLK/32	0.095			μs	
	SPI_[0 1]_CLK = PCLK/64	0.195			μs	
	SPI_[0 1]_CLK = PCLK/128	0.385			μs	
sp4	SPI_[0 1]_CLK, SPI_[0 1]_DO, SPI_[0 1]_SS rise time (10%–90%) ¹		2.77		ns	I/O Configuration: LVCMOS 2.5 V– 8 mA AC loading: 35 pF Test conditions: Typical voltage, 25 °C

Table 305 • SPI Characteristics for All Devices (continued)

Symbol	Description	Min	Typ	Max	Unit	Conditions
sp5	SPI_[0 1]_CLK, SPI_[0 1]_DO, SPI_[0 1]_SS fall time (10%– 90%) ¹		2.906		ns	IO Configuration: LVCMOS 2.5 V-8 mA AC Loading: 35 pF Test Conditions: Typical Voltage, 25 °C
SPI master configuration (applicable for 005, 010, 025, and 050 devices)						
sp6m	SPI_[0 1]_DO setup time ²	(SPI_x_CLK_period/2) – 8.0			ns	
sp7m	SPI_[0 1]_DO hold time ²	(SPI_x_CLK_period/2) – 2.5			ns	
sp8m	SPI_[0 1]_DI setup time ²	12			ns	
sp9m	SPI_[0 1]_DI hold time ²	2.5			ns	
SPI slave configuration (applicable for 005, 010, 025, and 050 devices)						
sp6s	SPI_[0 1]_DO setup time ²	(SPI_x_CLK_period/2) – 17.0			ns	
sp7s	SPI_[0 1]_DO hold time ²	(SPI_x_CLK_period/2) + 3.0			ns	
sp8s	SPI_[0 1]_DI setup time ²	2			ns	
sp9s	SPI_[0 1]_DI hold time ²	7			ns	
SPI master configuration (applicable for 060, 090, and 150 devices)						
sp6m	SPI_[0 1]_DO setup time ²	(SPI_x_CLK_period/2) – 7.0			ns	
sp7m	SPI_[0 1]_DO hold time ²	(SPI_x_CLK_period/2) – 9.5			ns	
sp8m	SPI_[0 1]_DI setup time ²	15			ns	
sp9m	SPI_[0 1]_DI hold time ²	–2.5			ns	
SPI slave configuration (applicable for 060, 090, and 150 devices)						
sp6s	SPI_[0 1]_DO setup time ²	(SPI_x_CLK_period/2) – 16.0			ns	
sp7s	SPI_[0 1]_DO hold time ²	(SPI_x_CLK_period/2) – 3.5			ns	
sp8s	SPI_[0 1]_DI setup time ²	3			ns	
sp9s	SPI_[0 1]_DI hold time ²	2.5			ns	

1. For specific Rise/Fall Times board design considerations and detailed output buffer resistances, use the corresponding IBIS models located on the Microsemi SoC Products Group website: <http://www.microsemi.com/soc/download/ibis/default.aspx>.
2. For allowable pclk configurations, see Serial Peripheral Interface Controller section in the *UG0331: SmartFusion2 Microcontroller Subsystem User Guide*.