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### **Embedded - System On Chip (SoC): The Heart of Modern Embedded Systems**

**Embedded - System On Chip (SoC)** refers to an integrated circuit that consolidates all the essential components of a computer system into a single chip. This includes a microprocessor, memory, and other peripherals, all packed into one compact and efficient package. SoCs are designed to provide a complete computing solution, optimizing both space and power consumption, making them ideal for a wide range of embedded applications.

### **What are Embedded - System On Chip (SoC)?**

**System On Chip (SoC)** integrates multiple functions of a computer or electronic system onto a single chip. Unlike traditional multi-chip solutions, SoCs combine a central

#### **Details**

Product Status	Active
Architecture	MCU, FPGA
Core Processor	ARM® Cortex®-M3
Flash Size	512KB
RAM Size	64KB
Peripherals	DDR, PCIe, SERDES
Connectivity	CANbus, Ethernet, I <sup>2</sup> C, SPI, UART/USART, USB
Speed	166MHz
Primary Attributes	FPGA - 90K Logic Modules
Operating Temperature	-40°C ~ 100°C (Tj)
Package / Case	484-BGA
Supplier Device Package	484-FPBGA (23x23)
Purchase URL	<a href="https://www.e-xfl.com/product-detail/microchip-technology/m2s090t-fgg484i">https://www.e-xfl.com/product-detail/microchip-technology/m2s090t-fgg484i</a>

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**Table 9 • Package Thermal Resistance of SmartFusion2 and IGLOO2 Devices (continued)**

Device	Still Air	1.0 m/s	2.5 m/s	$\theta_{JB}$	$\theta_{JC}$	Unit
	$\theta_{JA}$					
<b>150</b>						
FC1152	9.08	6.81	5.87	2.56	0.38	°C/W
FCS536	15.01	12.06	10.76	3.69	1.55	°C/W
FCV484	16.21	13.11	11.84	6.73	0.10	°C/W

### 2.3.1.2.1 Theta-JA

Junction-to-ambient thermal resistance ( $\theta_{JA}$ ) is determined under standard conditions specified by JEDEC (JESD-51), but it has little relevance in the actual performance of the product. It must be used with caution, but it is useful for comparing the thermal performance of one package with another.

The maximum power dissipation allowed is calculated using EQ4.

$$\text{Maximum power allowed} = \frac{T_{J(\text{MAX})} - T_{A(\text{MAX})}}{\theta_{JA}}$$

EQ 4

The absolute maximum junction temperature is 100 °C. EQ5 shows a sample calculation of the absolute maximum power dissipation allowed for the M2GL050T-FG896 package at commercial temperature and in still air, where:

$$\theta_{JA} = 14.7 \text{ °C/W (taken from Table 9, page 10).}$$

$$T_A = 85 \text{ °C}$$

$$\text{Maximum power allowed} = \frac{100 \text{ °C} - 85 \text{ °C}}{14.7 \text{ °C/W}} = 1.088 \text{ W}$$

EQ 5

The power consumption of a device can be calculated using the Microsemi SoC Products Group power calculator. The device's power consumption must be lower than the calculated maximum power dissipation by the package.

If the power consumption is higher than the device's maximum allowable power dissipation, a heat sink may be attached to the top of the case, or the airflow inside the system must be increased.

### 2.3.1.2.2 Theta-JB

Junction-to-board thermal resistance ( $\theta_{JB}$ ) measures the ability of the package to dissipate heat from the surface of the chip to the PCB. As defined by the JEDEC (JESD-51) standard, the thermal resistance from the junction to the board uses an isothermal ring cold plate zone concept. The ring cold plate is simply a means to generate an isothermal boundary condition at the perimeter. The cold plate is mounted on a JEDEC standard board with a minimum distance of 5.0 mm away from the package edge.

### 2.3.1.2.3 Theta-JC

Junction-to-case thermal resistance ( $\theta_{JC}$ ) measures the ability of a device to dissipate heat from the surface of the chip to the top or bottom surface of the package. It is applicable to packages used with external heat sinks. Constant temperature is applied to the surface, which acts as a boundary condition.

This only applies to situations where all or nearly all of the heat is dissipated through the surface in consideration.

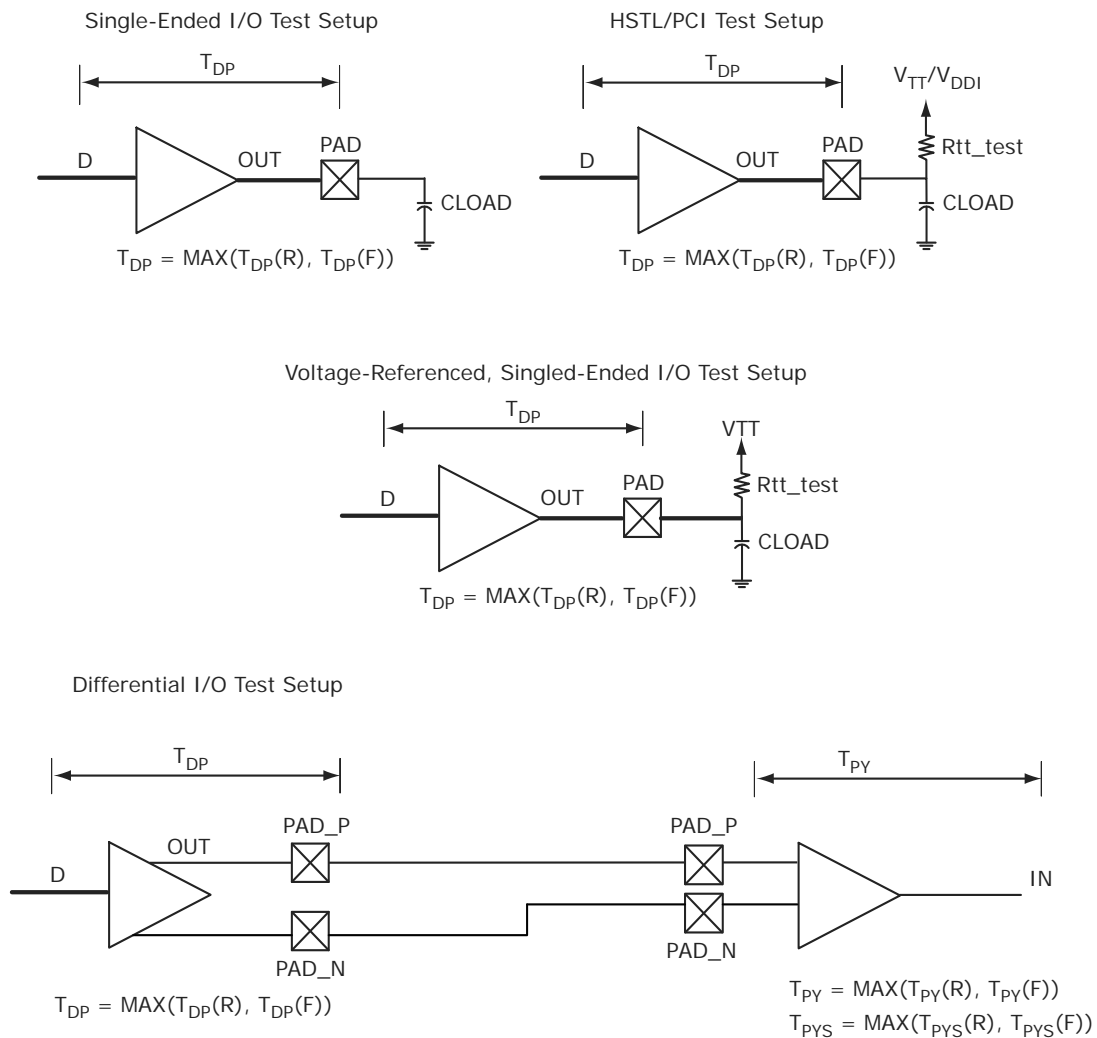
### 2.3.1.3 ESD Performance

See *RT0001: Microsemi Corporation - SoC Products Reliability Report* for information about ESD.

### 2.3.5.2 Output Buffer and AC Loading

The following figure shows the output buffer and AC loading.

**Figure 4 • Output Buffer AC Loading**



**Table 62 • LVCMOS 1.5 V DC Output Voltage Specification**

Parameter	Symbol	Min	Max	Unit
DC output logic high	VOH	$V_{DDI} \times 0.75$		V
DC output logic low	VOL		$V_{DDI} \times 0.25$	V

**Table 63 • LVCMOS 1.5 V AC Minimum and Maximum Switching Speed**

Parameter	Symbol	Max	Unit	Conditions
Maximum data rate (for DDRIO I/O bank)	$D_{MAX}$	235	Mbps	AC loading: 17 pF load, maximum drive/slew
Maximum data rate (for MSIO I/O bank)	$D_{MAX}$	160	Mbps	AC loading: 17 pF load, maximum drive/slew
Maximum data rate (for MSIOD I/O bank)	$D_{MAX}$	220	Mbps	AC loading: 17 pF load, maximum drive/slew

**Table 64 • LVCMOS 1.5 V AC Calibrated Impedance Option**

Parameter	Symbol	Typ	Unit
Supported output driver calibrated impedance (for DDRIO I/O bank)	RODT_CA L	75, 60, 50, 40	$\Omega$

**Table 65 • LVCMOS 1.5 V AC Test Parameter Specifications**

Parameter	Symbol	Typ	Unit
Measuring/trip point	$V_{TRIP}$	0.75	V
Resistance for enable path ( $T_{ZH}$ , $T_{ZL}$ , $T_{HZ}$ , $T_{LZ}$ )	$R_{ENT}$	2K	$\Omega$
Capacitive loading for enable path ( $T_{ZH}$ , $T_{ZL}$ , $T_{HZ}$ , $T_{LZ}$ )	$C_{ENT}$	5	pF
Capacitive loading for data path ( $T_{DP}$ )	$C_{LOAD}$	5	pF

**Table 66 • LVCMOS 1.5 V Transmitter Drive Strength Specifications**

Output Drive Selection			$V_{OH}$ (V)	$V_{OL}$ (V)	IOH (at $V_{OH}$ ) mA	IOL (at $V_{OL}$ ) mA
MSIO I/O Bank	MSIOD I/O Bank	DDRIO I/O Bank	Min	Max		
2 mA	2 mA	2 mA	$V_{DDI} \times 0.75$	$V_{DDI} \times 0.25$	2	2
4 mA	4 mA	4 mA	$V_{DDI} \times 0.75$	$V_{DDI} \times 0.25$	4	4
6 mA	6 mA	6 mA	$V_{DDI} \times 0.75$	$V_{DDI} \times 0.25$	6	6
8 mA		8 mA	$V_{DDI} \times 0.75$	$V_{DDI} \times 0.25$	8	8
		10 mA	$V_{DDI} \times 0.75$	$V_{DDI} \times 0.25$	10	10
		12 mA	$V_{DDI} \times 0.75$	$V_{DDI} \times 0.25$	12	12

**Note:** For a detailed I/V curve, use the corresponding IBIS models:  
[www.microsemi.com/soc/download/ibis/default.aspx](http://www.microsemi.com/soc/download/ibis/default.aspx).

**Table 70 • LVCMOS 1.5 V Transmitter Characteristics for DDRIO I/O Bank (Output and Tristate Buffers)**  
(continued)

Output Drive Selection	Slew Control	T <sub>DP</sub>		T <sub>ZL</sub>		T <sub>ZH</sub>		T <sub>HZ</sub> <sup>1</sup>		T <sub>LZ</sub> <sup>1</sup>		Unit
		-1	-Std	-1	-Std	-1	-Std	-1	-Std	-1	-Std	
6 mA	Slow	4.244	4.993	3.465	4.076	4.233	4.979	6.39	7.518	5.736	6.748	ns
	Medium	3.774	4.44	3.05	3.587	3.762	4.426	6.114	7.193	5.397	6.35	ns
	Medium fast	3.544	4.17	2.839	3.339	3.529	4.152	5.978	7.033	5.27	6.2	ns
	Fast	3.519	4.14	2.82	3.317	3.504	4.122	5.965	7.017	5.259	6.187	ns
8 mA	Slow	4.099	4.823	3.311	3.894	4.087	4.807	6.584	7.746	5.854	6.888	ns
	Medium	3.656	4.301	2.927	3.443	3.642	4.284	6.311	7.425	5.553	6.533	ns
	Medium fast	3.437	4.044	2.731	3.213	3.42	4.023	6.182	7.273	5.435	6.394	ns
	Fast	3.41	4.012	2.715	3.193	3.393	3.991	6.178	7.269	5.425	6.383	ns
10 mA	Slow	4.029	4.74	3.238	3.809	4.015	4.723	6.732	7.921	5.965	7.018	ns
	Medium	3.601	4.237	2.867	3.372	3.586	4.218	6.473	7.615	5.669	6.669	ns
	Medium fast	3.384	3.981	2.672	3.143	3.365	3.958	6.351	7.471	5.55	6.529	ns
	Fast	3.357	3.949	2.655	3.123	3.338	3.927	6.345	7.464	5.54	6.518	ns
12 mA	Slow	3.974	4.675	3.196	3.759	3.958	4.656	6.842	8.049	6.068	7.139	ns
	Medium	3.55	4.176	2.827	3.326	3.534	4.157	6.584	7.746	5.751	6.766	ns
	Medium fast	3.345	3.935	2.638	3.103	3.325	3.911	6.488	7.633	5.641	6.637	ns
	Fast	3.316	3.902	2.621	3.083	3.297	3.878	6.486	7.63	5.626	6.619	ns

1. Delay increases with drive strength are inherent to built-in slew control circuitry for simultaneous switching output (SSO) management.

**Table 71 • LVCMOS 1.5 V Transmitter Characteristics for MSIO I/O Bank (Output and Tristate Buffers)**

Output Drive Selection	Slew Control	T <sub>DP</sub>		T <sub>ZL</sub>		T <sub>ZH</sub>		T <sub>HZ</sub> <sup>1</sup>		T <sub>LZ</sub> <sup>1</sup>		Unit
		-1	-Std	-1	-Std	-1	-Std	-1	-Std	-1	-Std	
2 mA	Slow	4.423	5.203	5.397	6.35	5.686	6.69	5.609	6.599	5.561	6.542	ns
4 mA	Slow	4.05	4.765	4.503	5.298	4.92	5.788	7.358	8.657	6.525	7.677	ns
6 mA	Slow	4.081	4.801	4.259	5.012	4.699	5.528	7.659	9.011	6.709	7.893	ns
8 mA	Slow	4.234	4.98	4.068	4.786	4.521	5.319	8.218	9.668	7.05	8.294	ns

1. Delay increases with drive strength are inherent to built-in slew control circuitry for simultaneous switching output (SSO) management.

**Table 77 • LVCMOS 1.2 V AC Calibrated Impedance Option**

Parameter	Symbol	Typ	Unit
Supported output driver calibrated impedance (for DDRIO I/O bank)	RODT_CAL	75, 60, 50, 40	Ω

**Table 78 • LVCMOS 1.2 V AC Test Parameter Specifications**

Parameter	Symbol	Typ	Unit
Measuring/trip point	V <sub>TRIP</sub>	0.6	V
Resistance for enable path (T <sub>ZH</sub> , T <sub>ZL</sub> , T <sub>HZ</sub> , T <sub>LZ</sub> )	R <sub>ENT</sub>	2K	Ω
Capacitive loading for enable path (T <sub>ZH</sub> , T <sub>ZL</sub> , T <sub>HZ</sub> , T <sub>LZ</sub> )	C <sub>ENT</sub>	5	pF
Capacitive loading for data path (T <sub>DP</sub> )	C <sub>LOAD</sub>	5	pF

**Table 79 • LVCMOS 1.2 V Transmitter Drive Strength Specifications**

Output Drive Selection			V <sub>OH</sub> (V)	V <sub>OL</sub> (V)	IOH (at V <sub>OH</sub> )	IOL (at V <sub>OL</sub> )
MSIO I/O Bank	MSIOD I/O Bank	DDRIO I/O Bank	Min	Max	mA	mA
2 mA	2 mA	2 mA	V <sub>DDI</sub> × 0.75	V <sub>DDI</sub> × 0.25	2	2
4 mA	4 mA	4 mA	V <sub>DDI</sub> × 0.75	V <sub>DDI</sub> × 0.25	4	4
		6 mA	V <sub>DDI</sub> × 0.75	V <sub>DDI</sub> × 0.25	6	6

**Note:** For a detailed I/V curve, use the corresponding IBIS models:  
[www.microsemi.com/soc/download/ibis/default.aspx](http://www.microsemi.com/soc/download/ibis/default.aspx).

**AC Switching Characteristics**

Worst commercial-case conditions: T<sub>J</sub> = 85 °C, V<sub>DD</sub> = 1.14 V, V<sub>DDI</sub> = 1.14 V

**Table 80 • LVCMOS 1.2 V Receiver Characteristics for DDRIO I/O Bank with Fixed Code (Input Buffers)**

On-Die Termination (ODT)	T <sub>PY</sub>		T <sub>PYS</sub>		Unit
	-1	-Std	-1	-Std	
None	2.448	2.88	2.466	2.901	ns

**Table 81 • LVCMOS 1.2 V Receiver Characteristics for MSIO I/O Bank (Input Buffers)**

On-Die Termination ODT)	T <sub>PY</sub>		T <sub>PYS</sub>		Unit
	-1	-Std	-1	-Std	
None	4.714	5.545	4.675	5.5	ns
50	6.668	7.845	6.579	7.74	ns
75	5.832	6.862	5.76	6.777	ns
150	5.162	6.073	5.111	6.014	ns



**Table 131 • SSTL15 DC Output Voltage Specification (for DDRIO I/O Bank Only)**

Parameter	Symbol	Min	Max	Unit
<b>DDR3/SSTL15 Class I (DDR3 Reduced Drive)</b>				
DC output logic high	$V_{OH}$	$0.8 \times V_{DDI}$		V
DC output logic low	$V_{OL}$		$0.2 \times V_{DDI}$	V
Output minimum source DC current	$I_{OH}$ at $V_{OH}$	6.5		mA
Output minimum sink current	$I_{OL}$ at $V_{OL}$	-6.5		mA
<b>DDR3/SSTL15 Class II (DDR3 Full Drive)</b>				
DC output logic high	$V_{OH}$	$0.8 \times V_{DDI}$		V
DC output logic low	$V_{OL}$		$0.2 \times V_{DDI}$	V
Output minimum source DC current	$I_{OH}$ at $V_{OH}$	7.6		mA
Output minimum sink current	$I_{OL}$ at $V_{OL}$	-7.6		mA

**Table 132 • SSTL15 DC Differential Voltage Specification (for DDRIO I/O Bank Only)**

Parameter	Symbol	Min	Unit
DC input differential voltage	$V_{ID}$	0.2	V

**Note:** To meet JEDEC electrical compliance, use DDR3 full drive transmitter.

**Table 133 • SSTL15 AC SSTL15 Minimum and Maximum AC Switching Speed (for DDRIO I/O Bank Only)**

Parameter	Symbol	Min	Max	Unit
AC input differential voltage	$V_{DIFF}$ (AC)	0.3		V
AC differential cross point voltage	$V_x$ (AC)	$0.5 \times V_{DDI} - 0.150$	$0.5 \times V_{DDI} + 0.150$	V

**Table 134 • SSTL15 Minimum and Maximum AC Switching Speed (for DDRIO I/O Bank Only)**

Parameter	Symbol	Max	Unit	Conditions
Maximum data rate	$D_{MAX}$	667	Mbps	AC loading: per JEDEC specifications

**Table 135 • SSTL15 AC Calibrated Impedance Option (for DDRIO I/O Bank Only)**

Parameter	Symbol	Typ	Unit	Conditions
Supported output driver calibrated impedance	$R_{REF}$	34, 40	$\Omega$	Reference resistor = 240 $\Omega$
Effective impedance value (ODT)	$R_{TT}$	20, 30, 40, 60, 120	$\Omega$	Reference resistor = 240 $\Omega$

### 2.3.6.6 Low Power Double Data Rate (LPDDR)

LPDDR reduced and full drive low power double data rate standards are supported in IGLOO2 FPGA and SmartFusion2 SoC FPGA I/Os. This standard requires a differential amplifier input buffer and a push-pull output buffer.

#### Minimum and Maximum DC/AC Input and Output Levels Specification

**Table 139 • LPDDR DC Recommended DC Operating Conditions**

Parameter	Symbol	Min	Typ	Max
Supply voltage	$V_{DDI}$	1.71	1.8	1.89
Termination voltage	$V_{TT}$	0.838	0.900	0.964
Input reference voltage	$V_{REF}$	0.838	0.900	0.964

**Table 140 • LPDDR DC Input Voltage Specification**

Parameter	Symbol	Min	Max
DC input logic high	$V_{IH}$ (DC)	$0.7 \times V_{DDI}$	1.89
DC input logic low	$V_{IL}$ (DC)	-0.3	$0.3 \times V_{DDI}$
Input current high <sup>1</sup>	$I_{IH}$ (DC)		
Input current low <sup>1</sup>	$I_{IL}$ (DC)		

1. See Table 24, page 22.

**Table 141 • LPDDR DC Output Voltage Specification Reduced Drive**

Parameter	Symbol	Min	Max
DC output logic high	$V_{OH}$	$0.9 \times V_{DDI}$	
DC output logic low	$V_{OL}$		$0.1 \times V_{DDI}$
Output minimum source DC current	$I_{OH}$ at $V_{OH}$	0.1	
Output minimum sink current	$I_{OL}$ at $V_{OL}$	-0.1	

**Table 142 • LPDDR DC Output Voltage Specification Full Drive<sup>1</sup>**

Parameter	Symbol	Min	Max
DC output logic high	$V_{OH}$	$0.9 \times V_{DDI}$	
DC output logic low	$V_{OL}$		$0.1 \times V_{DDI}$
Output minimum source DC current	$I_{OH}$ at $V_{OH}$	0.1	
Output minimum sink current	$I_{OL}$ at $V_{OL}$	-0.1	

1. To meet JEDEC Electrical Compliance, use LPDDR Full Drive Transmitter.

**Table 143 • LPDDR DC Differential Voltage Specification**

Parameter	Symbol	Min
DC input differential voltage	$V_{ID}$ (DC)	$0.4 \times V_{DDI}$

### 2.3.7.2 B-LVDS

Bus LVDS (B-LVDS) specifications extend the existing LVDS standard to high-performance multipoint bus applications. Multidrop and multipoint bus configurations may contain any combination of drivers, receivers, and transceivers.

#### Minimum and Maximum DC/AC Input and Output Levels Specification

**Table 173 • B-LVDS Recommended DC Operating Conditions**

Parameter	Symbol	Min	Typ	Max	Unit
Supply voltage	$V_{DDI}$	2.375	2.5	2.625	V

**Table 174 • B-LVDS DC Input Voltage Specification**

Parameter	Symbol	Min	Max	Unit
DC input voltage	$V_I$	0	2.925	V
Input current high <sup>1</sup>	$I_{IH}$ (DC)			
Input current low <sup>1</sup>	$I_{IL}$ (DC)			

1. See Table 24, page 22.

**Table 175 • B-LVDS DC Output Voltage Specification (for MSIO I/O Bank Only)**

Parameter	Symbol	Min	Typ	Max	Unit
DC output logic high	$V_{OH}$	1.25	1.425	1.6	V
DC output logic low	$V_{OL}$	0.9	1.075	1.25	V

**Table 176 • B-LVDS DC Differential Voltage Specification**

Parameter	Symbol	Min	Max	Unit
Differential output voltage swing (for MSIO I/O bank only)	$V_{OD}$	65	460	mV
Output common mode voltage (for MSIO I/O bank only)	$V_{OCM}$	1.1	1.5	V
Input common mode voltage	$V_{ICM}$	0.05	2.4	V
Input differential voltage	$V_{ID}$	0.1	$V_{DDI}$	V

**Table 177 • B-LVDS Minimum and Maximum AC Switching Speed**

Parameter	Symbol	Max	Unit	Conditions
Maximum data rate (for MSIO I/O bank)	$D_{MAX}$	500	Mbps	AC loading: 2 pF / 100 $\Omega$ differential load

**Table 178 • B-LVDS AC Impedance Specifications**

Parameter	Symbol	Typ	Unit
Termination resistance	$R_T$	27	$\Omega$

**Table 179 • B-LVDS AC Test Parameter Specifications**

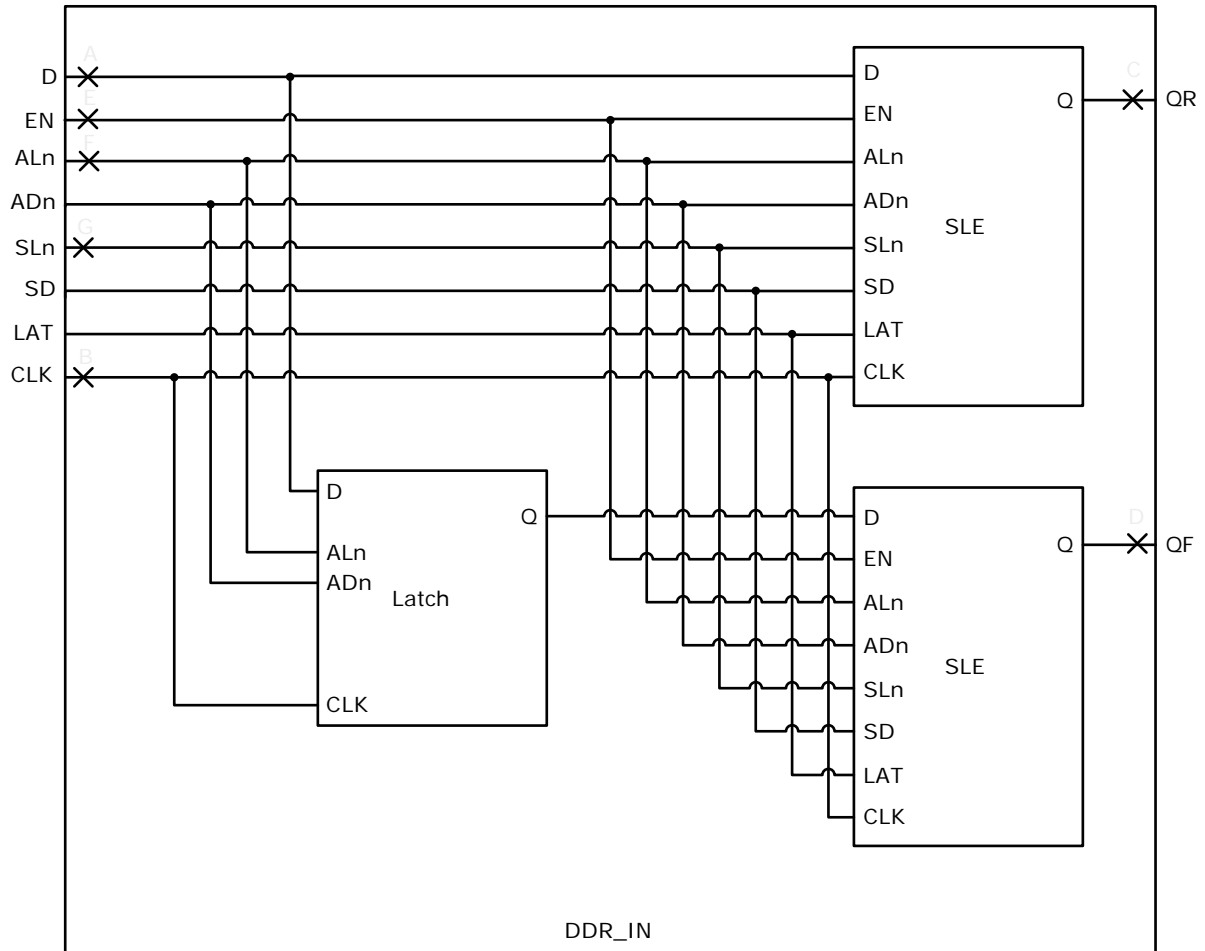
Parameter	Symbol	Typ	Unit
Measuring/trip point for data path	$V_{TRIP}$	Cross point	V
Resistance for enable path ( $T_{ZH}$ , $T_{ZL}$ , $T_{HZ}$ , $T_{LZ}$ )	$R_{ENT}$	2K	$\Omega$
Capacitive loading for enable path ( $T_{ZH}$ , $T_{ZL}$ , $T_{HZ}$ , $T_{LZ}$ )	$C_{ENT}$	5	pF

### 2.3.9 DDR Module Specification

This section describes input and output DDR module and timing specifications.

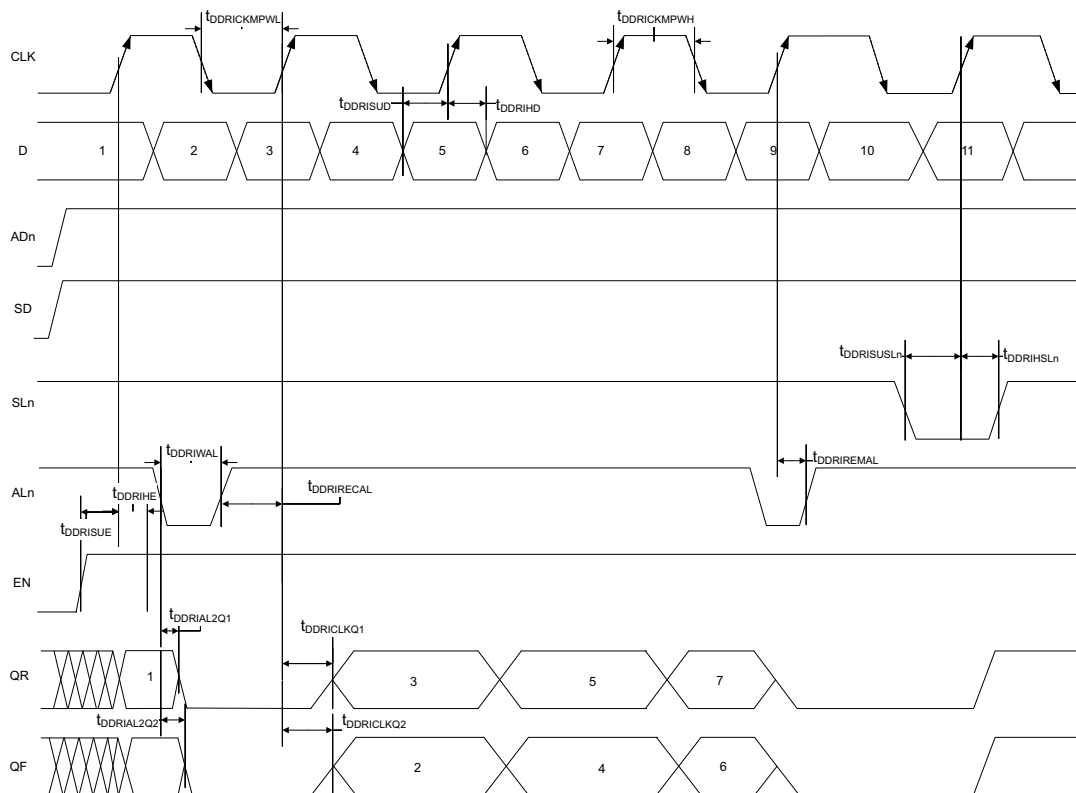
#### 2.3.9.1 Input DDR Module

Figure 10 • Input DDR Module



### 2.3.9.2 Input DDR Timing Diagram

Figure 11 • Input DDR Timing Diagram



### 2.3.9.3 Timing Characteristics

The following table lists the input DDR propagation delays in worst commercial-case conditions when  $T_J = 85\text{ }^\circ\text{C}$ ,  $V_{DD} = 1.14\text{ V}$ .

Table 221 • Input DDR Propagation Delays

Symbol	Description	Measuring Nodes (from, to)	-1	-Std	Unit
$T_{DDRICKLKQ1}$	Clock-to-Out Out_QR for input DDR	B, C	0.16	0.188	ns
$T_{DDRICKLKQ2}$	Clock-to-Out Out_QF for input DDR	B, D	0.166	0.195	ns
$T_{DDRISUD}$	Data setup for input DDR	A, B	0.357	0.421	ns
$T_{DDRIHD}$	Data hold for input DDR	A, B	0	0	ns
$T_{DDRISUE}$	Enable setup for input DDR	E, B	0.46	0.542	ns
$T_{DDRIHE}$	Enable hold for input DDR	E, B	0	0	ns
$T_{DDRISUSL}$	Synchronous load setup for input DDR	G, B	0.46	0.542	ns
$T_{DDRIHSL}$	Synchronous load hold for input DDR	G, B	0	0	ns
$T_{DDRIR2Q1}$	Asynchronous load-to-out QR for input DDR	F, C	0.587	0.69	ns
$T_{DDRIR2Q2}$	Asynchronous load-to-out QF for input DDR	F, D	0.541	0.636	ns
$T_{DDRIREMAL}$	Asynchronous load removal time for input DDR	F, B	0	0	ns
$T_{DDRIRECAL}$	Asynchronous load recovery time for input DDR	F, B	0.074	0.087	ns

### 2.3.10.2 Timing Characteristics

The following table lists the combinatorial cell propagation delays in worst commercial-case conditions when  $T_J = 85\text{ }^\circ\text{C}$ ,  $V_{DD} = 1.14\text{ V}$ .

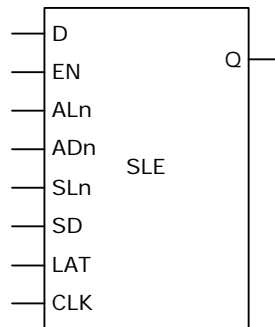
**Table 223 • Combinatorial Cell Propagation Delays**

Combinatorial Cell	Equation	Symbol	-1	-Std	Unit
INV	$Y = !A$	$T_{PD}$	0.1	0.118	ns
AND2	$Y = A \cdot B$	$T_{PD}$	0.164	0.193	ns
NAND2	$Y = !(A \cdot B)$	$T_{PD}$	0.147	0.173	ns
OR2	$Y = A + B$	$T_{PD}$	0.164	0.193	ns
NOR2	$Y = !(A + B)$	$T_{PD}$	0.147	0.173	ns
XOR2	$Y = A \oplus B$	$T_{PD}$	0.164	0.193	ns
XOR3	$Y = A \oplus B \oplus C$	$T_{PD}$	0.225	0.265	ns
AND3	$Y = A \cdot B \cdot C$	$T_{PD}$	0.209	0.246	ns
AND4	$Y = A \cdot B \cdot C \cdot D$	$T_{PD}$	0.287	0.338	ns

### 2.3.10.3 Sequential Module

IGLOO2 and SmartFusion2 SoC FPGAs offer a separate flip-flop which can be used independently from the LUT. The flip-flop can be configured as a register or a latch and has a data input and optional enable, synchronous load (clear or preset), and asynchronous load (clear or preset).

**Figure 15 • Sequential Module**



The following table lists the 010 device global resources in worst commercial-case conditions when  $T_J = 85\text{ }^\circ\text{C}$ ,  $V_{DD} = 1.14\text{ V}$ .

**Table 229 • 010 Device Global Resource**

Parameter	Symbol	-1		-Std		Unit
		Min	Max	Min	Max	
Input low delay for global clock	$T_{RCKL}$	0.626	0.669	0.627	0.668	ns
Input high delay for global clock	$T_{RCKH}$	1.112	1.182	1.308	1.393	ns
Maximum skew for global clock	$T_{RCKSW}$		0.07		0.085	ns

The following table lists the 005 device global resources in worst commercial-case conditions when  $T_J = 85\text{ }^\circ\text{C}$ ,  $V_{DD} = 1.14\text{ V}$ .

**Table 230 • 005 Device Global Resource**

Parameter	Symbol	-1		-Std		Unit
		Min	Max	Min	Max	
Input low delay for global clock	$T_{RCKL}$	0.625	0.66	0.628	0.66	ns
Input high delay for global clock	$T_{RCKH}$	1.126	1.187	1.325	1.397	ns
Maximum skew for global clock	$T_{RCKSW}$		0.061		0.072	ns

## 2.3.12 FPGA Fabric SRAM

See *UG0445: IGLOO2 FPGA and SmartFusion2 SoC FPGA Fabric User Guide* for more information.

### 2.3.12.1 FPGA Fabric Large SRAM (LSRAM)

The following table lists the RAM1K18 – dual-port mode for depth × width configuration 1K × 18 in worst commercial-case conditions when  $T_J = 85\text{ }^\circ\text{C}$ ,  $V_{DD} = 1.14\text{ V}$ .

**Table 231 • RAM1K18 – Dual-Port Mode for Depth × Width Configuration 1K × 18**

Parameter	Symbol	-1		-Std		Unit
		Min	Max	Min	Max	
Clock period	$T_{CY}$	2.5		2.941		ns
Clock minimum pulse width high	$T_{CLKMPWH}$	1.125		1.323		ns
Clock minimum pulse width low	$T_{CLKMPWL}$	1.125		1.323		ns
Pipelined clock period	$T_{PLCY}$	2.5		2.941		ns
Pipelined clock minimum pulse width high	$T_{PLCLKMPWH}$	1.125		1.323		ns
Pipelined clock minimum pulse width low	$T_{PLCLKMPWL}$	1.125		1.323		ns
Read access time with pipeline register				0.334	0.393	ns
Read access time without pipeline register	$T_{CLK2Q}$			2.273	2.674	ns
Access time with feed-through write timing				1.529	1.799	ns
Address setup time	$T_{ADDRSU}$	0.441		0.519		ns
Address hold time	$T_{ADDRHD}$	0.274		0.322		ns
Data setup time	$T_{DSU}$	0.341		0.401		ns
Data hold time	$T_{DHD}$	0.107		0.126		ns
Block select setup time	$T_{BLKSU}$	0.207		0.244		ns

**Table 232 • RAM1K18 – Dual-Port Mode for Depth × Width Configuration 2K × 9 (continued)**

Parameter	Symbol	–1		–Std		Unit
		Min	Max	Min	Max	
Address setup time	$T_{ADDRSU}$	0.475		0.559		ns
Address hold time	$T_{ADDRHD}$	0.274		0.322		ns
Data setup time	$T_{DSU}$	0.336		0.395		ns
Data hold time	$T_{DHD}$	0.082		0.096		ns
Block select setup time	$T_{BLKSU}$	0.207		0.244		ns
Block select hold time	$T_{BLKHD}$	0.216		0.254		ns
Block select to out disable time (when pipelined register is disabled)	$T_{BLK2Q}$		1.529		1.799	ns
Block select minimum pulse width	$T_{BLKMPW}$	0.186		0.219		ns
Read enable setup time	$T_{RDESU}$	0.485		0.57		ns
Read enable hold time	$T_{RDEHD}$	0.071		0.083		ns
Pipelined read enable setup time (A_DOUT_EN, B_DOUT_EN)	$T_{RDPLESU}$	0.248		0.291		ns
Pipelined read enable hold time (A_DOUT_EN, B_DOUT_EN)	$T_{RDPLEHD}$	0.102		0.12		ns
Asynchronous reset to output propagation delay	$T_{R2Q}$		1.514		1.781	ns
Asynchronous reset removal time	$T_{RSTREM}$	0.506		0.595		ns
Asynchronous reset recovery time	$T_{RSTREC}$	0.004		0.005		ns
Asynchronous reset minimum pulse width	$T_{RSTMPW}$	0.301		0.354		ns
Pipelined register asynchronous reset removal time	$T_{PLRSTREM}$	–0.279		–0.328		ns
Pipelined register asynchronous reset recovery time	$T_{PLRSTREC}$	0.327		0.385		ns
Pipelined register asynchronous reset minimum pulse width	$T_{PLRSTMPW}$	0.282		0.332		ns
Synchronous reset setup time	$T_{SRSTSU}$	0.226		0.265		ns
Synchronous reset hold time	$T_{SRSTHD}$	0.036		0.043		ns
Write enable setup time	$T_{WESU}$	0.415		0.488		ns
Write enable hold time	$T_{WEHD}$	0.048		0.057		ns
Maximum frequency	$F_{MAX}$		400		340	MHz

The following table lists the RAM1K18 – dual-port mode for depth × width configuration 4K × 4 in worst commercial-case conditions when  $T_J = 85\text{ }^\circ\text{C}$ ,  $V_{DD} = 1.14\text{ V}$ .

**Table 233 • RAM1K18 – Dual-Port Mode for Depth × Width Configuration 4K × 4**

Parameter	Symbol	–1		–Std		Unit
		Min	Max	Min	Max	
Clock period	$T_{CY}$	2.5		2.941		ns
Clock minimum pulse width high	$T_{CLKMPWH}$	1.125		1.323		ns
Clock minimum pulse width low	$T_{CLKMPWL}$	1.125		1.323		ns
Pipelined clock period	$T_{PLCY}$	2.5		2.941		ns
Pipelined clock minimum pulse width high	$T_{PLCLKMPWH}$	1.125		1.323		ns



The following table lists the math blocks with input register used and output in bypass mode in worst commercial-case conditions when  $T_J = 85\text{ }^\circ\text{C}$ ,  $V_{DD} = 1.14\text{ V}$ .

**Table 270 • Math Block with Input Register Used and Output in Bypass Mode**

Parameter	Symbol	-1		-Std		Unit
		Min	Max	Min	Max	
Input register setup time	$T_{MISU}$	0.149		0.176		ns
Input register hold time	$T_{MIHD}$	0.185		0.218		ns
Synchronous reset/enable setup time	$T_{MSRSTENSU}$	0.08		0.094		ns
Synchronous reset/enable hold time	$T_{MSRSTENHD}$	-0.012		-0.014		ns
Asynchronous reset removal time	$T_{MARSTREM}$	-0.005		-0.005		ns
Asynchronous reset recovery time	$T_{MARSTREC}$	0.088		0.104		ns
Input register clock to output delay	$T_{MICQ}$		2.52		2.964	ns
CDIN to output delay	$T_{MCDIN2Q}$		1.951		2.295	ns

The following table lists the math blocks with input and output in bypass mode in worst commercial-case conditions when  $T_J = 85\text{ }^\circ\text{C}$ ,  $V_{DD} = 1.14\text{ V}$ .

**Table 271 • Math Block with Input and Output in Bypass Mode**

Parameter	Symbol	-1		Unit
		Max	Max	
Input to output delay	$T_{MIQ}$	2.568	3.022	ns
CDIN to output delay	$T_{MCDIN2Q}$	1.951	2.295	ns

### 2.3.15 Embedded NVM (eNVM) Characteristics

The following table lists the eNVM read performance in worst-case conditions when  $V_{DD} = 1.14\text{ V}$ ,  $V_{PPNVM} = V_{PP} = 2.375\text{ V}$ .

**Table 272 • eNVM Read Performance**

Symbol	Description	Operating Temperature Range						Unit
		-1	-Std	-1	-Std	-1	-Std	
$T_J$	Junction temperature range	-55 °C to 125 °C		-40 °C to 100 °C		0 °C to 85 °C		°C
$F_{MAXREAD}$	eNVM maximum read frequency	25	25	25	25	25	25	MHz

The following table lists the eNVM page programming in worst-case conditions when  $V_{DD} = 1.14\text{ V}$ ,  $V_{PPNVM} = V_{PP} = 2.375\text{ V}$ .

**Table 273 • eNVM Page Programming**

Symbol	Description	Operating Temperature Range						Unit
		-1	-Std	-1	-Std	-1	-Std	
$T_J$	Junction temperature range	-55 °C to 125 °C		-40 °C to 100 °C		0 °C to 85 °C		°C
$T_{PAGEPGM}$	eNVM page programming time	40	40	40	40	40	40	ms

**Table 277 • Electrical Characteristics of the Crystal Oscillator – High Gain Mode (20 MHz) (continued)**

Parameter	Symbol	Min	Typ	Max	Unit	Condition
Startup time (with regard to stable oscillator output)	SUXTAL			0.8	ms	005, 010, 025, and 050 devices
				1.0	ms	090 and 150 devices

**Table 278 • Electrical Characteristics of the Crystal Oscillator – Medium Gain Mode (2 MHz)**

Parameter	Symbol	Min	Typ	Max	Unit	Condition
Operating frequency	FXTAL		2		MHz	
Accuracy	ACCXTAL			0.00105	%	050 devices
				0.003	%	005, 010, 025, 090, and 150 devices
				0.004	%	060 devices
Output duty cycle	CYCXTAL		49–51	47–53	%	
Output period jitter (peak to peak)	JITPERXTAL		1	5	ns	
Output cycle to cycle jitter (peak to peak)	JITCYCXTAL		1	5	ns	
Operating current	IDYNXTAL		0.3		mA	
Input logic level high	VIHXTAL	0.9 V <sub>PP</sub>			V	
Input logic level low	VILXTAL			0.1 V <sub>PP</sub>	V	
Startup time (with regard to stable oscillator output)	SUXTAL			4.5	ms	010 and 050 devices
				5	ms	005 and 025 devices
				7	ms	090 and 150 devices

**Table 279 • Electrical Characteristics of the Crystal Oscillator – Low Gain Mode (32 kHz)**

Parameter	Symbol	Min	Typ	Max	Unit	Condition
Operating frequency	FXTAL		32		kHz	
Accuracy	ACCXTAL			0.004	%	005, 010, 025, 050, 060, and 090 devices
				0.005	%	150 devices
Output duty cycle	CYCXTAL		49–51	47–53	%	
Output period jitter (peak to peak)	JITPERXTAL		150	300	ns	
Output cycle to cycle jitter (peak to peak)	JITCYCXTAL		150	300	ns	
Operating current	IDYNXTAL		0.044		mA	010 and 050 devices
			0.060		mA	005, 025, 060, 090, and 150 devices
Input logic level high	VIHXTAL	0.9 V <sub>PP</sub>			V	
Input logic level low	VILXTAL			0.1 V <sub>PP</sub>	V	
Startup time (with regard to stable oscillator output)	SUXTAL			115	ms	005, 025, 050, 090, and 150 devices
				126	ms	010 devices

## 2.3.21 Clock Conditioning Circuits (CCC)

The following table lists the CCC/PLL specifications in worst-case industrial conditions when  $T_J = 100\text{ }^\circ\text{C}$ ,  $V_{DD} = 1.14\text{ V}$ .

**Table 282 • IGLOO2 and SmartFusion2 SoC FPGAs CCC/PLL Specification**

Parameter	Min	Typ	Max	Unit	Conditions
Clock conditioning circuitry input frequency $F_{IN\_CCC}$	1		200	MHz	All CCC
	0.032		200	MHz	32 kHz capable CCC
Clock conditioning circuitry output frequency $F_{OUT\_CCC}^1$	0.078		400	MHz	
PLL VCO frequency <sup>2</sup>	500		1000	MHz	
Delay increments in programmable delay blocks		75	100	ps	
Number of programmable values in each programmable delay block			64		
Acquisition time		70	100	$\mu\text{s}$	$F_{IN} \geq 1\text{ MHz}$
		1	16	ms	$F_{IN} = 32\text{ kHz}$
Input duty cycle (reference clock)					Internal Feedback
	10		90	%	$1\text{ MHz} \leq F_{IN\_CCC} \leq 25\text{ MHz}$
	25		75	%	$25\text{ MHz} \leq F_{IN\_CCC} \leq 100\text{ MHz}$
	35		65	%	$100\text{ MHz} \leq F_{IN\_CCC} \leq 150\text{ MHz}$
	45		55	%	$150\text{ MHz} \leq F_{IN\_CCC} \leq 200\text{ MHz}$
					External Feedback (CCC, FPGA, Off-chip)
	25		75	%	$1\text{ MHz} \leq F_{IN\_CCC} \leq 25\text{ MHz}$
	35		65	%	$25\text{ MHz} \leq F_{IN\_CCC} \leq 35\text{ MHz}$
	45		55	%	$35\text{ MHz} \leq F_{IN\_CCC} \leq 50\text{ MHz}$
	Output duty cycle	48		52	%
48			52	%	005, 010, and 025 devices $F_{OUT} < 350\text{ MHz}$
46			54	%	005, 010, and 025 devices $350\text{ MHz} \leq F_{out} \leq 400\text{ MHz}$
48			52	%	060 and 090 devices $F_{OUT} \leq 100\text{ MHz}$
44			52	%	060 and 090 devices $100\text{ MHz} \leq F_{OUT} \leq 400\text{ MHz}$
48			52	%	150 devices $F_{OUT} \leq 120\text{ MHz}$
45			52	%	150 devices $120\text{ MHz} \leq F_{OUT} \leq 400\text{ MHz}$
<b>Spread Spectrum Characteristics</b>					
Modulation frequency range	25	35	50	k	
Modulation depth range	0		1.5	%	
Modulation depth control		0.5		%	

The following table lists the receiver pa in worst-case industrial conditions when  $T_J = 100\text{ }^\circ\text{C}$ ,  $V_{DD} = 1.14\text{ V}$ .

**Table 297 • Receiver Parameters**

Symbol	Description	Min	Typ	Max	Unit
VRX-IN-PP-CC	Differential input peak-to-peak sensitivity (2.5 Gbps)	0.238		1.2	V
	Differential input peak-to-peak sensitivity (2.5 Gbps, de-emphasized)	0.219		1.2	V
	Differential input peak-to-peak sensitivity (5.0 Gbps)	0.300		1.2	V
	Differential input peak-to-peak sensitivity (5.0 Gbps, de-emphasized)	0.300		1.2	V
VRX-CM-AC-P	Input common mode range (AC coupled)			150	mV
ZRX-DIFF-DC	Differential input termination	80	100	120	$\Omega$
REXT	External calibration resistor	1,188	1,200	1,212	$\Omega$
CDR-LOCK-RST	CDR relock time from reset			15	$\mu\text{s}$
RLRX-DIFF	Return loss differential mode (2.5 Gbps)	-10			dB
	Return loss differential mode (5.0 Gbps)				
	0.05 GHz to 1.25 GHz	-10			dB
	1.25 GHz to 2.5 GHz	-8			dB
RLRX-CM	Return loss common mode (2.5 Gbps, 5.0 Gbps)	-6			dB
RX-CID <sup>1</sup>	CID limit PCIe Gen1/2			200	UI
VRX-IDLE-DET-DIFF-PP	Signal detect limit	65		175	mV

1. AC-coupled, BER =  $e^{-12}$ , using synchronous clock.

**Table 298 • SerDes Protocol Compliance**

Protocol	Maximum Data Rate (Gbps)	-1	-Std
PCIe Gen 1	2.5	Yes	Yes
PCIe Gen 2	5.0	Yes	
XAUI	3.125	Yes	
Generic EPCS	3.2	Yes	
Generic EPCS	2.5	Yes	Yes

## 2.3.34 MMUART Characteristics

The following table lists the MMUART characteristics in worst-case industrial conditions when  $T_J = 100\text{ }^\circ\text{C}$ ,  $V_{DD} = 1.14\text{ V}$ .

**Table 308 • MMUART Characteristics**

Parameter	Description	-1	-Std	Unit
FMMUART_REF_CLK	Internally sourced MMUART reference clock frequency.	166	142	MHz
BAUDMMUARTTx	Maximum transmit baud rate	10.375	8.875	Mbps
BAUDMMUARTRx	Maximum receive baud rate	10.375	8.875	Mbps

## 2.3.35 IGLOO2 Specifications

### 2.3.35.1 HPMS Clock Frequency

The following table lists the maximum frequency for HPMS main clock in worst-case industrial conditions when  $T_J = 100\text{ }^\circ\text{C}$ ,  $V_{DD} = 1.14\text{ V}$ .

**Table 309 • Maximum Frequency for HPMS Main Clock**

Symbol	Description	-1	-Std	Unit
HPMS_CLK	Maximum frequency for the HPMS main clock	166	142	MHz

### 2.3.35.2 IGLOO2 Serial Peripheral Interface (SPI) Characteristics

This section describes the DC and switching of the SPI interface. Unless otherwise noted, all output characteristics given are for a 35 pF load on the pins and all sequential timing characteristics are related to SPI\_0\_CLK. For timing parameter definitions, see Figure 23, page 131.

The following table lists the SPI characteristics in worst-case industrial conditions when  $T_J = 100\text{ }^\circ\text{C}$ ,  $V_{DD} = 1.14\text{ V}$ .

**Table 310 • SPI Characteristics for All Devices**

Symbol	Description	Min	Typ	Max	Unit	Conditions
SPIFMAX	Maximum operating frequency of SPI interface			20	MHz	
sp1	SPI_[0 1]_CLK minimum period					
	SPI_[0 1]_CLK = PCLK/2	12			ns	
	SPI_[0 1]_CLK = PCLK/4	24.1			ns	
	SPI_[0 1]_CLK = PCLK/8	48.2			ns	
	SPI_[0 1]_CLK = PCLK/16	0.1			$\mu\text{s}$	
	SPI_[0 1]_CLK = PCLK/32	0.19			$\mu\text{s}$	
	SPI_[0 1]_CLK = PCLK/64	0.39			$\mu\text{s}$	
SPI_[0 1]_CLK = PCLK/128	0.77			$\mu\text{s}$		