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### **Embedded - System On Chip (SoC): The Heart of Modern Embedded Systems**

**Embedded - System On Chip (SoC)** refers to an integrated circuit that consolidates all the essential components of a computer system into a single chip. This includes a microprocessor, memory, and other peripherals, all packed into one compact and efficient package. SoCs are designed to provide a complete computing solution, optimizing both space and power consumption, making them ideal for a wide range of embedded applications.

### **What are Embedded - System On Chip (SoC)?**

**System On Chip (SoC)** integrates multiple functions of a computer or electronic system onto a single chip. Unlike traditional multi-chip solutions, SoCs combine a central

#### **Details**

Product Status	Active
Architecture	MCU, FPGA
Core Processor	ARM® Cortex®-M3
Flash Size	512KB
RAM Size	64KB
Peripherals	DDR, PCIe, SERDES
Connectivity	CANbus, Ethernet, I <sup>2</sup> C, SPI, UART/USART, USB
Speed	166MHz
Primary Attributes	FPGA - 90K Logic Modules
Operating Temperature	-40°C ~ 100°C (Tj)
Package / Case	484-BGA
Supplier Device Package	484-FPBGA (23x23)
Purchase URL	<a href="https://www.e-xfl.com/product-detail/microchip-technology/m2s090ts-fg484i">https://www.e-xfl.com/product-detail/microchip-technology/m2s090ts-fg484i</a>

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1. For flash programming and retention maximum limits, see Table 5, page 7. For recommended operating conditions, see Table 4, page 6.

**Table 4 • Recommended Operating Conditions**

Parameter	Symbol	Min	Typ	Max	Unit	Conditions
Operating junction temperature	$T_J$	0	25	85	°C	Commercial
		-40	25	100	°C	Industrial
Programming junction temperatures <sup>1</sup>	$T_J$	0	25	85	°C	Commercial
		-40	25	100	°C	Industrial
DC core supply voltage. Must always power this pin.	$V_{DD}$	1.14	1.2	1.26	V	
Power supply for charge pumps (for normal operation and programming) for the 005, 010, 025, 050, 060 devices	$V_{PP}$	2.375	2.5	2.625	V	2.5 V range
		3.15	3.3	3.45	V	3.3 V range
Power supply for charge pumps (for normal operation and programming) for the 090 and 150 devices	$V_{PP}$	3.15	3.3	3.45	V	3.3 V range
Analog power pad for MDDR PLL	MSS_MDDR_PLL_VDDA	2.375	2.5	2.625	V	2.5 V range
		3.15	3.3	3.45	V	3.3 V range
Analog power pad for MDDR PLL	HPMS_MDDR_PLL_VDDA	2.375	2.5	2.625	V	2.5 V range
		3.15	3.3	3.45	V	3.3 V range
Analog power pad for FDDR PLL	FDDR_PLL_VDDA	2.375	2.5	2.625	V	2.5 V range
		3.15	3.3	3.45	V	3.3 V range
Analog power pad for MDDR PLL	PLL0_PLL1_MSS_MDDR_V DDA	2.375	2.5	2.625	V	2.5 V range
		3.15	3.3	3.45	V	3.3 V range
Analog power pad for MDDR PLL	PLL0_PLL1_HPMS_MDDR_ VDDA	2.375	2.5	2.625	V	2.5 V range
		3.15	3.3	3.45	V	3.3 V range
Analog power pad for PLL0 to PLL5	CCC_XX[01]_PLL_VDDA	2.375	2.5	2.625	V	2.5 V range
		3.15	3.3	3.45	V	3.3 V range
High supply voltage for PLL SerDes[01]	SERDES_[01]_PLL_VDDA	2.375	2.5	2.625	V	2.5 V range
		3.15	3.3	3.45	V	3.3 V range
Analog power for SerDes[01] PLL Lane 0 to Lane 3. This is a 2.5 V SerDes internal PLL supply.	SERDES_[01]_L[0123]_VD DAPLL	2.375	2.5	2.625	V	
TX/RX analog I/O voltage. Low voltage power for the lanes of SerDesIF0. This is a 1.2 V SerDes PMA supply.	SERDES_[01]_L[0123]_VD DAIO	1.14	1.2	1.26	V	
PCIe/PCS power supply	SERDES_[01]_VDD	1.14	1.2	1.26	V	
1.2 V DC supply voltage	$V_{DDix}$	1.14	1.2	1.26	V	
1.5 V DC supply voltage	$V_{DDix}$	1.425	1.5	1.575	V	
1.8 V DC supply voltage	$V_{DDix}$	1.71	1.8	1.89	V	
2.5 V DC supply voltage	$V_{DDix}$	2.375	2.5	2.625	V	

**Table 9 • Package Thermal Resistance of SmartFusion2 and IGLOO2 Devices (continued)**

Device	Still Air	1.0 m/s	2.5 m/s	$\theta_{JB}$	$\theta_{JC}$	Unit
	$\theta_{JA}$					
<b>150</b>						
FC1152	9.08	6.81	5.87	2.56	0.38	°C/W
FCS536	15.01	12.06	10.76	3.69	1.55	°C/W
FCV484	16.21	13.11	11.84	6.73	0.10	°C/W

### 2.3.1.2.1 Theta-JA

Junction-to-ambient thermal resistance ( $\theta_{JA}$ ) is determined under standard conditions specified by JEDEC (JESD-51), but it has little relevance in the actual performance of the product. It must be used with caution, but it is useful for comparing the thermal performance of one package with another.

The maximum power dissipation allowed is calculated using EQ4.

$$\text{Maximum power allowed} = \frac{T_{J(\text{MAX})} - T_{A(\text{MAX})}}{\theta_{JA}}$$

EQ 4

The absolute maximum junction temperature is 100 °C. EQ5 shows a sample calculation of the absolute maximum power dissipation allowed for the M2GL050T-FG896 package at commercial temperature and in still air, where:

$$\theta_{JA} = 14.7 \text{ °C/W (taken from Table 9, page 10).}$$

$$T_A = 85 \text{ °C}$$

$$\text{Maximum power allowed} = \frac{100 \text{ °C} - 85 \text{ °C}}{14.7 \text{ °C/W}} = 1.088 \text{ W}$$

EQ 5

The power consumption of a device can be calculated using the Microsemi SoC Products Group power calculator. The device's power consumption must be lower than the calculated maximum power dissipation by the package.

If the power consumption is higher than the device's maximum allowable power dissipation, a heat sink may be attached to the top of the case, or the airflow inside the system must be increased.

### 2.3.1.2.2 Theta-JB

Junction-to-board thermal resistance ( $\theta_{JB}$ ) measures the ability of the package to dissipate heat from the surface of the chip to the PCB. As defined by the JEDEC (JESD-51) standard, the thermal resistance from the junction to the board uses an isothermal ring cold plate zone concept. The ring cold plate is simply a means to generate an isothermal boundary condition at the perimeter. The cold plate is mounted on a JEDEC standard board with a minimum distance of 5.0 mm away from the package edge.

### 2.3.1.2.3 Theta-JC

Junction-to-case thermal resistance ( $\theta_{JC}$ ) measures the ability of a device to dissipate heat from the surface of the chip to the top or bottom surface of the package. It is applicable to packages used with external heat sinks. Constant temperature is applied to the surface, which acts as a boundary condition.

This only applies to situations where all or nearly all of the heat is dissipated through the surface in consideration.

### 2.3.1.3 ESD Performance

See *RT0001: Microsemi Corporation - SoC Products Reliability Report* for information about ESD.

### 2.3.5.7 2.5 V LVCMOS

LVCMOS 2.5 V is a general standard for 2.5 V applications and is supported in IGLOO2 FPGA and SmartFusion2 SoC FPGAs that are in compliance with the JEDEC specification JESD8-5A.

#### Minimum and Maximum DC/AC Input and Output Levels Specification

**Table 38 • LVCMOS 2.5 V DC Recommended DC Operating Conditions**

Parameter	Symbol	Min	Typ	Max	Unit
Supply voltage	$V_{DDI}$	2.375	2.5	2.625	V

**Table 39 • LVCMOS 2.5 V DC Input Voltage Specification**

Parameter	Symbol	Min	Max	Unit
DC input logic high (for MSIOD and DDRIO I/O banks)	$V_{IH}$ (DC)	1.7	2.625	V
DC input logic high (for MSIO I/O bank)	$V_{IH}$ (DC)	1.7	3.45	V
DC input logic low	$V_{IL}$ (DC)	-0.3	0.7	V
Input current high <sup>1</sup>	$I_{IH}$ (DC)			
Input current low <sup>1</sup>	$I_{IL}$ (DC)			

1. See [Table 24](#), page 22.

**Table 40 • LVCMOS 2.5 V DC Output Voltage Specification**

Parameter	Symbol	Min	Max	Unit
DC output logic high	$V_{OH}$ <sup>1</sup>	$V_{DDI} - 0.4$	-	V
DC output logic low	$V_{OL}$ <sup>2</sup>		0.4	V

1. The VOH/VOL test points selected ensure compliance with LVCMOS 2.5 V JEDEC8-5A requirements.

**Table 41 • LVCMOS 2.5 V AC Minimum and Maximum Switching Speed**

Parameter	Symbol	Max	Unit	Conditions
Maximum data rate (for DDRIO I/O bank)	$D_{MAX}$	400	Mbps	AC loading: 17 pF load, maximum drive/slew
Maximum data rate (for MSIO I/O bank)	$D_{MAX}$	410	Mbps	AC loading: 17 pF load, maximum drive/slew
Maximum data rate (for MSIOD I/O bank)	$D_{MAX}$	420	Mbps	AC loading: 17 pF load, maximum drive/slew

**Table 42 • LVCMOS 2.5 V AC Calibrated Impedance Option**

Parameter	Symbol	Typ	Unit
Supported output driver calibrated impedance (for DDRIO I/O bank)	Rodt_cal	75, 60, 50, 33, 25, 20	$\Omega$

**Table 58 • LVCMOS 1.8 V Transmitter Characteristics for MSIO I/O Bank**

Output Drive Selection	Slew Control	$T_{DP}$		$T_{ZL}$		$T_{ZH}$		$T_{HZ}^1$		$T_{LZ}^1$		Unit
		-1	-Std	-1	-Std	-1	-Std	-1	-Std	-1	-Std	
2 mA	Slow	3.441	4.047	4.165	4.9	4.413	5.192	4.891	5.755	5.138	6.044	ns
4 mA	Slow	3.218	3.786	3.642	4.284	3.941	4.636	5.665	6.665	5.568	6.551	ns
6 mA	Slow	3.141	3.694	3.501	4.118	3.823	4.498	6.587	7.75	6.032	7.096	ns
8 mA	Slow	3.165	3.723	3.319	3.904	3.654	4.298	6.898	8.115	6.216	7.313	ns
10 mA	Slow	3.202	3.767	3.278	3.857	3.616	4.254	7.25	8.529	6.435	7.571	ns
12 mA	Slow	3.277	3.855	3.175	3.736	3.519	4.139	7.392	8.697	6.538	7.692	ns

1. Delay increases with drive strength are inherent to built-in slew control circuitry for simultaneous switching output (SSO) management.

**Table 59 • LVCMOS 1.8 V Transmitter Characteristics for MSIOD I/O Bank**

Output Drive Selection	Slew Control	$T_{DP}$		$T_{ZL}$		$T_{ZH}$		$T_{HZ}^1$		$T_{LZ}^1$		Unit
		-1	-Std	-1	-Std	-1	-Std	-1	-Std	-1	-Std	
2 mA	Slow	2.725	3.206	3.316	3.901	3.484	4.099	5.204	6.123	4.997	5.88	ns
4 mA	Slow	2.242	2.638	2.777	3.267	2.947	3.466	5.729	6.74	5.448	6.41	ns
6 mA	Slow	1.995	2.347	2.466	2.901	2.63	3.094	6.372	7.496	5.987	7.043	ns
8 mA	Slow	2.001	2.354	2.44	2.87	2.6	3.058	6.633	7.804	6.193	7.286	ns
10 mA	Slow	2.025	2.382	2.312	2.719	2.47	2.906	6.94	8.165	6.412	7.544	ns

1. Delay increases with drive strength are inherent to built-in slew control circuitry for simultaneous switching output (SSO) management.

### 2.3.5.9 1.5 V LVCMOS

LVCMOS 1.5 is a general standard for 1.5 V applications and is supported in IGLOO2 FPGAs and SmartFusion2 SoC FPGAs in compliance to the JEDEC specification JESD8-11A.

#### Minimum and Maximum DC/AC Input and Output Levels Specification

**Table 60 • LVCMOS 1.5 V DC Recommended Operating Conditions**

Parameter	Symbol	Min	Typ	Max	Unit
Supply voltage	$V_{DDI}$	1.425	1.5	1.575	V

**Table 61 • LVCMOS 1.5 V DC Input Voltage Specification**

Parameter	Symbol	Min	Max	Unit
DC input logic high for (MSIOD and DDRIO I/O banks)	$V_{IH}$ (DC)	$0.65 \times V_{DDI}$	1.575	V
DC input logic high (for MSIO I/O bank)	$V_{IH}$ (DC)	$0.65 \times V_{DDI}$	3.45	V
DC input logic low	$V_{IL}$ (DC)	-0.3	$0.35 \times V_{DDI}$	V
Input current high <sup>1</sup>	$I_{IH}$ (DC)			-
Input current low <sup>1</sup>	$I_{IL}$ (DC)			-

1. See Table 24, page 22.

### AC Switching Characteristics

Worst commercial-case conditions:  $T_J = 85\text{ }^\circ\text{C}$ ,  $V_{DD} = 1.14\text{ V}$ ,  $V_{DDI} = 2.375\text{ V}$ .

**Table 180 • B-LVDS AC Switching Characteristics for Receiver for MSIO I/O Bank (Input Buffers)**

On-Die Termination (ODT)	$T_{PY}$		Unit
	-1	-Std	
None	2.738	3.221	ns
100	2.735	3.218	ns

**Table 181 • B-LVDS AC Switching Characteristics for Receiver for MSIOD I/O Bank (Input Buffers)**

On-Die Termination (ODT)	$T_{PY}$		Unit
	-1	-Std	
None	2.495	2.934	ns
100	2.495	2.935	ns

**Table 182 • B-LVDS AC Switching Characteristics for Transmitter (for MSIO I/O Bank - Output and Tristate Buffers)**

$T_{DP}$		$T_{ZL}$		$T_{ZH}$		$T_{HZ}$		$T_{LZ}$		Unit
-1	-Std	-1	-Std	-1	-Std	-1	-Std	-1	-Std	
2.258	2.656	2.343	2.756	2.329	2.74	2.12	2.494	2.123	2.497	ns

#### 2.3.7.3 M-LVDS

M-LVDS specifications extend the existing LVDS standard to high-performance multipoint bus applications. Multidrop and multipoint bus configurations may contain any combination of drivers, receivers, and transceivers.

#### Minimum and Maximum Input and Output Levels

**Table 183 • M-LVDS Recommended DC Operating Conditions**

Parameter	Symbol	Min	Typ	Max	Unit
Supply voltage <sup>1</sup>	$V_{DDI}$	2.375	2.5	2.625	V

1. Only M-LVDS TYPE I is supported.

**Table 184 • M-LVDS DC Input Voltage Specification**

Parameter	Symbol	Min	Max	Unit
DC input voltage	$V_I$	0	2.925	V
Input current high <sup>1</sup>	$I_{IH}$ (DC)			
Input current low <sup>2</sup>	$I_{IL}$ (DC)			

1. See Table 24, page 22.



**Table 185 • M-LVDS DC Voltage Specification Output Voltage Specification (for MSIO I/O Bank Only)**

Parameter	Symbol	Min	Typ	Max	Unit
DC output logic high	$V_{OH}$	1.25	1.425	1.6	V
DC output logic low	$V_{OL}$	0.9	1.075	1.25	V

**Table 186 • M-LVDS Differential Voltage Specification**

Parameter	Symbol	Min	Max	Unit
Differential output voltage swing (for MSIO I/O bank only)	$V_{OD}$	300	650	mV
Output common mode voltage (for MSIO I/O bank only)	$V_{OCM}$	0.3	2.1	V
Input common mode voltage	$V_{ICM}$	0.3	1.2	V
Input differential voltage	$V_{ID}$	50	2400	mV

**Table 187 • M-LVDS Minimum and Maximum AC Switching Speed for MSIO I/O Bank**

Parameter	Symbol	Max	Unit	Conditions
Maximum data rate	$D_{MAX}$	500	Mbps	AC loading: 2 pF / 100 $\Omega$ differential load

**Table 188 • M-LVDS AC Impedance Specifications**

Parameter	Symbol	Typ	Unit
Termination resistance	$R_T$	50	$\Omega$

**Table 189 • M-LVDS AC Test Parameter Specifications**

Parameter	Symbol	Typ	Unit
Measuring/trip point for data path	$V_{TRIP}$	Cross point	V
Resistance for enable path ( $T_{ZH}$ , $T_{ZL}$ , $T_{HZ}$ , $T_{LZ}$ )	$R_{ENT}$	2K	$\Omega$
Capacitive loading for enable path ( $T_{ZH}$ , $T_{ZL}$ , $T_{HZ}$ , $T_{LZ}$ )	$C_{ENT}$	5	pF

**AC Switching Characteristics**

Worst commercial-case conditions:  $T_J = 85\text{ }^\circ\text{C}$ ,  $V_{DD} = 1.14\text{ V}$ ,  $V_{DDI} = 2.375\text{ V}$

**Table 190 • M-LVDS AC Switching Characteristics for Receiver (for MSIO I/O Bank - Input Buffers)**

On-Die Termination (ODT)	$T_{PY}$		Unit
	-1	-Std	
None	2.738	3.221	ns
100	2.735	3.218	ns

### AC Switching Characteristics

Worst commercial-case conditions:  $T_J = 85\text{ }^\circ\text{C}$ ,  $V_{DD} = 1.14\text{ V}$ ,  $V_{DDI} = 2.375\text{ V}$ .

**Table 210 • RSDS AC Switching Characteristics for Receiver (for MSIO I/O Bank - Input Buffers)**

On-Die Termination (ODT)	$T_{PY}$		Unit
	-1	-Std	
None	2.855	3.359	ns
100	2.85	3.353	ns

**Table 211 • RSDS AC Switching Characteristics for Receiver (for MSIOD I/O Bank - Input Buffers)**

On-Die Termination (ODT)	$T_{PY}$		Unit
	-1	-Std	
None	2.602	3.061	ns
100	2.597	3.055	ns

**Table 212 • RSDS AC Switching Characteristics for Transmitter (for MSIO I/O Bank - Output and Tristate Buffers)**

$T_{DP}$		$T_{ZL}$		$T_{ZH}$		$T_{HZ}$		$T_{LZ}$		Unit
-1	-Std	-1	-Std	-1	-Std	-1	-Std	-1	-Std	
2.097	2.467	2.303	2.709	2.291	2.695	1.961	2.307	1.947	2.29	ns

**Table 213 • RSDS AC Switching Characteristics for Transmitter (for MSIOD I/O Bank - Output and Tristate Buffers)**

	$T_{DP}$		$T_{ZL}$		$T_{ZH}$		$T_{HZ}$		$T_{LZ}$		Unit
	-1	-Std	-1	-Std	-1	-Std	-1	-Std	-1	-Std	
No pre-emphasis	1.614	1.899	1.559	1.834	1.55	1.823	1.59	1.87	1.575	1.852	ns
Min pre-emphasis	1.604	1.887	1.742	2.05	1.728	2.032	1.889	2.222	1.858	2.185	ns
Med pre-emphasis	1.521	1.79	1.753	2.062	1.737	2.043	1.9	2.235	1.868	2.197	ns
Max pre-emphasis	1.492	1.754	1.762	2.073	1.745	2.052	1.91	2.247	1.876	2.206	ns

#### 2.3.7.6 LVPECL

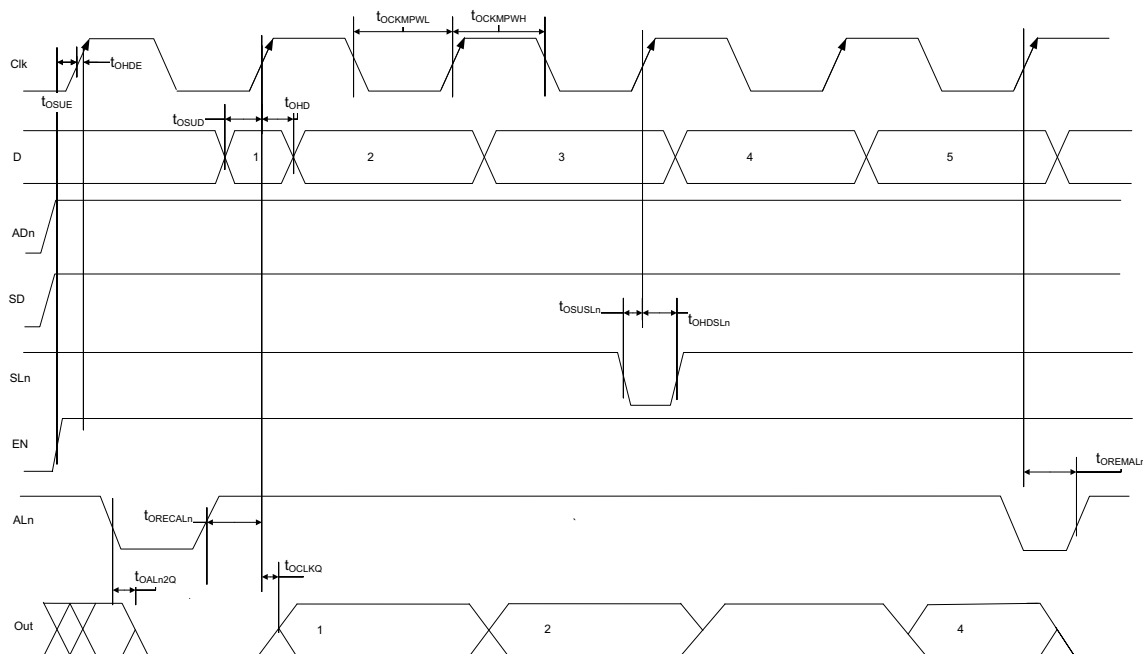
Low-Voltage Positive Emitter-Coupled Logic (LVPECL) is another differential I/O standard. It requires that one data bit be carried through two signal lines. Similar to LVDS, two pins are needed. It also requires external resistor termination. IGLOO2 and SmartFusion2 SoC FPGAs support only LVPECL receivers and do not support LVPECL transmitters.

#### Minimum and Maximum Input and Output Levels (Applicable to MSIO I/O Bank Only)

**Table 214 • LVPECL Recommended DC Operating Conditions**

Parameter	Symbol	Min	Typ	Max	Unit
Supply voltage	$V_{DDI}$	3.15	3.3	3.45	V

**Figure 9 • I/O Register Output Timing Diagram**



The following table lists the output/enable propagation delays in worst commercial-case conditions when  $T_J = 85\text{ }^\circ\text{C}$ ,  $V_{DD} = 1.14\text{ V}$ .

**Table 220 • Output/Enable Data Register Propagation Delays**

Parameter	Symbol	Measuring Nodes (from, to) <sup>1</sup>	-1		Unit
			-1	-Std	
Bypass delay of the output/enable register	$T_{OBYP}$	F, G or H, I	0.353	0.415	ns
Clock-to-Q of the output/enable register	$T_{OCLKQ}$	E, G or E, I	0.263	0.309	ns
Data setup time for the output/enable register	$T_{OSUD}$	A, E or J, E	0.19	0.223	ns
Data hold time for the output/enable register	$T_{OHD}$	A, E or J, E	0	0	ns
Enable setup time for the output/enable register	$T_{OSUE}$	B, E	0.419	0.493	ns
Enable hold time for the output/enable register	$T_{OHE}$	B, E	0	0	ns
Synchronous load setup time for the output/enable register	$T_{OSUSL}$	D, E	0.196	0.231	ns
Synchronous load hold time for the output/enable register	$T_{OHSL}$	D, E	0	0	ns
Asynchronous clear-to-q of the output/enable register (ADn = 1)	$T_{OALN2Q}$	C, G or C, I	0.505	0.594	ns
Asynchronous preset-to-q of the output/enable register (ADn = 0)		C, G or C, I	0.528	0.621	ns
Asynchronous load removal time for the output/enable register	$T_{OREMALN}$	C, E	0	0	ns
Asynchronous load recovery time for the output/enable register	$T_{ORECALN}$	C, E	0.034	0.04	ns
Asynchronous load minimum pulse width for the output/enable register	$T_{OWALN}$	C, C	0.304	0.357	ns
Clock minimum pulse width high for the output/enable register	$T_{OACKMPWH}$	E, E	0.075	0.088	ns
Clock minimum pulse width low for the output/enable register	$T_{OACKMPWL}$	E, E	0.159	0.187	ns

1. For the derating values at specific junction temperature and voltage supply levels, see Table 16, page 14 for derating values.

The following table lists the RAM1K18 – two-port mode for depth × width configuration 512 × 36 in worst commercial-case conditions when  $T_J = 85\text{ }^\circ\text{C}$ ,  $V_{DD} = 1.14\text{ V}$ .

**Table 236 • RAM1K18 – Two-Port Mode for Depth × Width Configuration 512 × 36**

Parameter	Symbol	–1		–Std		Unit
		Min	Max	Min	Max	
Clock period	$T_{CY}$	2.5		2.941		ns
Clock minimum pulse width high	$T_{CLKMPWH}$	1.125		1.323		ns
Clock minimum pulse width low	$T_{CLKMPWL}$	1.125		1.323		ns
Pipelined clock period	$T_{PLCY}$	2.5		2.941		ns
Pipelined clock minimum pulse width high	$T_{PLCLKMPWH}$	1.125		1.323		ns
Pipelined clock minimum pulse width low	$T_{PLCLKMPWL}$	1.125		1.323		ns
Read access time with pipeline register	$T_{CLK2Q}$		0.334		0.393	ns
Read access time without pipeline register			2.25		2.647	ns
Address setup time	$T_{ADDRSU}$	0.313		0.368		ns
Address hold time	$T_{ADDRHD}$	0.274		0.322		ns
Data setup time	$T_{DSU}$	0.337		0.396		ns
Data hold time	$T_{DHD}$	0.111		0.13		ns
Block select setup time	$T_{BLKSU}$	0.207		0.244		ns
Block select hold time	$T_{BLKHD}$	0.201		0.237		ns
Block select to out disable time (when pipelined register is disabled)	$T_{BLK2Q}$		2.25		2.647	ns
Block select minimum pulse width	$T_{BLKMPW}$	0.186		0.219		ns
Read enable setup time	$T_{RDESU}$	0.449		0.528		ns
Read enable hold time	$T_{RDEHD}$	0.167		0.197		ns
Pipelined read enable setup time (A_DOUT_EN, B_DOUT_EN)	$T_{RDPLESU}$	0.248		0.291		ns
Pipelined read enable hold time (A_DOUT_EN, B_DOUT_EN)	$T_{RDPLEHD}$	0.102		0.12		ns
Asynchronous reset to output propagation delay	$T_{R2Q}$		1.506		1.772	ns
Asynchronous reset removal time	$T_{RSTREM}$	0.506		0.595		ns
Asynchronous reset recovery time	$T_{RSTREC}$	0.004		0.005		ns
Asynchronous reset minimum pulse width	$T_{RSTMPW}$	0.301		0.354		ns
Pipelined register asynchronous reset removal time	$T_{PLRSTREM}$	–0.279		–0.328		ns
Pipelined register asynchronous reset recovery time	$T_{PLRSTREC}$	0.327		0.385		ns
Pipelined register asynchronous reset minimum pulse width	$T_{PLRSTMPW}$	0.282		0.332		ns
Synchronous reset setup time	$T_{SRSTSU}$	0.226		0.265		ns
Synchronous reset hold time	$T_{SRSTHD}$	0.036		0.043		ns
Write enable setup time	$T_{WESU}$	0.39		0.458		ns
Write enable hold time	$T_{WEHD}$	0.242		0.285		ns
Maximum frequency	$F_{MAX}$		400		340	MHz

### 2.3.12.2 FPGA Fabric Micro SRAM ( $\mu$ SRAM)

The following table lists the  $\mu$ SRAM in  $64 \times 18$  mode in worst commercial-case conditions when  $T_J = 85^\circ\text{C}$ ,  $V_{DD} = 1.14\text{ V}$ .

**Table 237 •  $\mu$ SRAM (RAM64x18) in  $64 \times 18$  Mode**

Parameter	Symbol	-1		-Std		Unit
		Min	Max	Min	Max	
Read clock period	$T_{CY}$	4		4		ns
Read clock minimum pulse width high	$T_{CLKMPWH}$	1.8		1.8		ns
Read clock minimum pulse width low	$T_{CLKMPWL}$	1.8		1.8		ns
Read pipeline clock period	$T_{PLCY}$	4		4		ns
Read pipeline clock minimum pulse width high	$T_{PLCLKMPWH}$	1.8		1.8		ns
Read pipeline clock minimum pulse width low	$T_{PLCLKMPWL}$	1.8		1.8		ns
Read access time with pipeline register	$T_{CLK2Q}$		0.266		0.313	ns
Read access time without pipeline register				1.677		1.973
Read address setup time in synchronous mode	$T_{ADDRSU}$	0.301		0.354		ns
Read address setup time in asynchronous mode			1.856		2.184	
Read address hold time in synchronous mode	$T_{ADDRHD}$	0.091		0.107		ns
Read address hold time in asynchronous mode			-0.778		-0.915	
Read enable setup time	$T_{RDENSU}$	0.278		0.327		ns
Read enable hold time	$T_{RDENHD}$	0.057		0.067		ns
Read block select setup time	$T_{BLKSU}$	1.839		2.163		ns
Read block select hold time	$T_{BLKHD}$	-0.65		-0.765		ns
Read block select to out disable time (when pipelined register is disabled)	$T_{BLK2Q}$		2.036		2.396	ns
Read asynchronous reset removal time (pipelined clock)	$T_{RSTREM}$	-0.023		-0.027		ns
Read asynchronous reset removal time (non-pipelined clock)			0.046		0.054	
Read asynchronous reset recovery time (pipelined clock)	$T_{RSTREC}$	0.507		0.597		ns
Read asynchronous reset recovery time (non-pipelined clock)			0.236		0.278	
Read asynchronous reset to output propagation delay (with pipelined register enabled)	$T_{R2Q}$		0.839		0.987	ns
Read synchronous reset setup time	$T_{SRSTSU}$	0.271		0.319		ns
Read synchronous reset hold time	$T_{SRSTHD}$	0.061		0.071		ns
Write clock period	$T_{CCY}$	4		4		ns
Write clock minimum pulse width high	$T_{CCLKMPWH}$	1.8		1.8		ns
Write clock minimum pulse width low	$T_{CCLKMPWL}$	1.8		1.8		ns
Write block setup time	$T_{BLKCSU}$	0.404		0.476		ns
Write block hold time	$T_{BLKCHD}$	0.007		0.008		ns
Write input data setup time	$T_{DINCSU}$	0.115		0.135		ns
Write input data hold time	$T_{DINCHD}$	0.15		0.177		ns

**Table 239 •  $\mu$ SRAM (RAM128x9) in 128 × 9 Mode (continued)**

Parameter	Symbol	-1		-Std		Unit
		Min	Max	Min	Max	
Read asynchronous reset removal time (pipelined clock)		-0.023		-0.027		ns
Read asynchronous reset removal time (non-pipelined clock)	$T_{RSTREM}$	0.046		0.054		ns
Read asynchronous reset recovery time (pipelined clock)		0.507		0.597		ns
Read asynchronous reset recovery time (non-pipelined clock)	$T_{RSTREC}$	0.236		0.278		ns
Read asynchronous reset to output propagation delay (with pipelined register enabled)	$T_{R2Q}$		0.835		0.982	ns
Read synchronous reset setup time	$T_{SRSTSU}$	0.271		0.319		ns
Read synchronous reset hold time	$T_{SRSTHD}$	0.061		0.071		ns
Write clock period	$T_{CCY}$	4		4		ns
Write clock minimum pulse width high	$T_{CCLKMPWH}$	1.8		1.8		ns
Write clock minimum pulse width low	$T_{CCLKMPWL}$	1.8		1.8		ns
Write block setup time	$T_{BLKCSU}$	0.404		0.476		ns
Write block hold time	$T_{BLKCHD}$	0.007		0.008		ns
Write input data setup time	$T_{DINCSU}$	0.115		0.135		ns
Write input data hold time	$T_{DINCHD}$	0.15		0.177		ns
Write address setup time	$T_{ADDRCSU}$	0.088		0.104		ns
Write address hold time	$T_{ADDRCHD}$	0.128		0.15		ns
Write enable setup time	$T_{WECSU}$	0.397		0.467		ns
Write enable hold time	$T_{WECHD}$	-0.026		-0.03		ns
Maximum frequency	$F_{MAX}$		250		250	MHz

The following table lists the  $\mu$ SRAM in 128 × 8 mode in worst commercial-case conditions when  $T_J = 85^\circ\text{C}$ ,  $V_{DD} = 1.14\text{ V}$ .

**Table 240 •  $\mu$ SRAM (RAM128x8) in 128 × 8 Mode**

Parameter	Symbol	-1		-Std		Unit
		Min	Max	Min	Max	
Read clock period	$T_{CY}$	4		4		ns
Read clock minimum pulse width high	$T_{CLKMPWH}$	1.8		1.8		ns
Read clock minimum pulse width low	$T_{CLKMPWL}$	1.8		1.8		ns
Read pipeline clock period	$T_{PLCY}$	4		4		ns
Read pipeline clock minimum pulse width high	$T_{PLCLKMPWH}$	1.8		1.8		ns
Read pipeline clock minimum pulse width low	$T_{PLCLKMPWL}$	1.8		1.8		ns
Read access time with pipeline register			0.266		0.313	ns
Read access time without pipeline register	$T_{CLK2Q}$		1.677		1.973	ns
Read address setup time in synchronous mode		0.301		0.354		ns
Read address setup time in asynchronous mode	$T_{ADDRSU}$	1.856		2.184		ns

**Table 251 • SmartFusion2 Cortex-M3 ISP Programming (eNVM Only) (continued)**

M2S/M2GL Device	Image size Bytes	Authenticate	Program	Verify	Unit
150	544496	10	158	15	Sec

**Table 252 • SmartFusion2 Cortex-M3 ISP Programming (Fabric and eNVM)**

M2S/M2GL Device	Image size Bytes	Authenticate	Program	Verify	Unit
005	439296	9	61	11	Sec
010	842688	15	107	21	Sec
025	1497408	26	121	35	Sec
050	2695168	43	141	55	Sec
060	2686464	48	143	60	Sec
090	4190208	75	244	91	Sec
150	6682768	117	296	141	Sec

**Table 253 • Programming Times with 100 kHz, 25 MHz, and 12.5 MHz SPI Clock Rates (Fabric Only)**

M2S/M2GL Device	Auto Programming	Auto Update	Programming Recovery	Unit
	100 kHz	25 MHz	12.5 MHz	
005	47	27	28	Sec
010	77	35	35	Sec
025	150	42	41	Sec
050	33 <sup>1</sup>	Not Supported	Not Supported	Sec
060	291	83	82	Sec
090	427	109	108	Sec
150	708	157	160	Sec

1. Auto Programming in 050 device is done through SC\_SPI, and SPI CLK is set to 6.25 MHz.

**Table 254 • Programming Times with 100 kHz, 25 MHz, and 12.5 MHz SPI Clock Rates (eNVM Only)**

M2S/M2GL Device	Auto Programming	Auto Update	Programming Recovery	Unit
	100 kHz	25 MHz	12.5 MHz	
005	41	48	49	Sec
010	86	87	87	Sec
025	87	85	86	Sec
050	85	Not Supported	Not Supported	Sec
060	78	86	86	Sec
090	154	162	162	Sec

**Table 254 • Programming Times with 100 kHz, 25 MHz, and 12.5 MHz SPI Clock Rates (eNVM Only) (continued)**

M2S/M2GL Device	Auto Programming	Auto Update	Programming Recovery	Unit
	100 kHz	25 MHz	12.5 MHz	
150	161	161	161	Sec

**Table 255 • Programming Times with 100 kHz, 25 MHz, and 12.5 MHz SPI Clock Rates (Fabric and eNVM)**

M2S/M2GL Device	Auto Programming	Auto Update	Programming Recovery	Unit
	100 kHz	25 MHz	12.5 MHz	
005	47	27	28	Sec
010	77	35	35	Sec
025	150	42	41	Sec
050	33 <sup>1</sup>	Not Supported	Not Supported	Sec
060	291	83	82	Sec
090	427	109	108	Sec
150	708	157	160	Sec
005	41	48	49	Sec
010	86	87	87	Sec
025	87	85	86	Sec
050	85	Not Supported	Not Supported	Sec
060	78	86	86	Sec
090	154	162	162	Sec
150	161	161	161	Sec
005	87	67	66	Sec
010	161	113	113	Sec
025	229	120	121	Sec
050	112	Not Supported	Not Supported	Sec
060	368	161	158	Sec
090	582	261	260	Sec
150	867	309	310	Sec

1. Auto Programming in 050 device is done through SC\_SPI, and SPI CLK is set to 6.25 MHz.



The following table lists the math blocks with input register used and output in bypass mode in worst commercial-case conditions when  $T_J = 85\text{ }^\circ\text{C}$ ,  $V_{DD} = 1.14\text{ V}$ .

**Table 270 • Math Block with Input Register Used and Output in Bypass Mode**

Parameter	Symbol	-1		-Std		Unit
		Min	Max	Min	Max	
Input register setup time	$T_{MISU}$	0.149		0.176		ns
Input register hold time	$T_{MIHD}$	0.185		0.218		ns
Synchronous reset/enable setup time	$T_{MSRSTENSU}$	0.08		0.094		ns
Synchronous reset/enable hold time	$T_{MSRSTENHD}$	-0.012		-0.014		ns
Asynchronous reset removal time	$T_{MARSTREM}$	-0.005		-0.005		ns
Asynchronous reset recovery time	$T_{MARSTREC}$	0.088		0.104		ns
Input register clock to output delay	$T_{MICQ}$		2.52		2.964	ns
CDIN to output delay	$T_{MCDIN2Q}$		1.951		2.295	ns

The following table lists the math blocks with input and output in bypass mode in worst commercial-case conditions when  $T_J = 85\text{ }^\circ\text{C}$ ,  $V_{DD} = 1.14\text{ V}$ .

**Table 271 • Math Block with Input and Output in Bypass Mode**

Parameter	Symbol	-1	-Std	Unit
		Max	Max	
Input to output delay	$T_{MIQ}$	2.568	3.022	ns
CDIN to output delay	$T_{MCDIN2Q}$	1.951	2.295	ns

### 2.3.15 Embedded NVM (eNVM) Characteristics

The following table lists the eNVM read performance in worst-case conditions when  $V_{DD} = 1.14\text{ V}$ ,  $V_{PPNVM} = V_{PP} = 2.375\text{ V}$ .

**Table 272 • eNVM Read Performance**

Symbol	Description	Operating Temperature Range						Unit
		-1	-Std	-1	-Std	-1	-Std	
$T_J$	Junction temperature range	-55 °C to 125 °C		-40 °C to 100 °C		0 °C to 85 °C		°C
$F_{MAXREAD}$	eNVM maximum read frequency	25	25	25	25	25	25	MHz

The following table lists the eNVM page programming in worst-case conditions when  $V_{DD} = 1.14\text{ V}$ ,  $V_{PPNVM} = V_{PP} = 2.375\text{ V}$ .

**Table 273 • eNVM Page Programming**

Symbol	Description	Operating Temperature Range						Unit
		-1	-Std	-1	-Std	-1	-Std	
$T_J$	Junction temperature range	-55 °C to 125 °C		-40 °C to 100 °C		0 °C to 85 °C		°C
$T_{PAGEPGM}$	eNVM page programming time	40	40	40	40	40	40	ms

## 2.3.16 SRAM PUF

For more details on static random-access memory (SRAM) physical unclonable functions (PUF) services, see [AC434: Using SRAM PUF System Service in SmartFusion2 Application Note](#).

The following table lists the SRAM PUF in worst-case industrial conditions when  $T_J = 100\text{ }^\circ\text{C}$ ,  $V_{DD} = 1.14\text{ V}$ .

**Table 274 • SRAM PUF**

Service	PUF Off		PUF On		Unit
	Typ	Max	Typ	Max	
Create activation code	709.1	746.4	754.4	762.5	ms
Delete activation code	1329.3	1399.3	1414.1	1429.3	ms
Create intrinsic keycode	656.6	691.1	698.5	706.0	ms
Create extrinsic keycode	656.6	691.1	698.5	706.0	ms
Get number of keys	1.3	1.4	1.4	1.4	ms
Export (Kc0, Kc1)	998.0	1050.5	1061.7	1073.1	ms
Export 2 keycodes	2020.2	2126.5	2149.2	2172.3	ms
Export 4 keycodes	3065.7	3227.0	3261.3	3296.4	ms
Export 8 keycodes	5101.0	5369.5	5426.6	5485.0	ms
Export 16 keycodes	9212.1	9697.0	9800.1	9905.5	ms
Import (Kc0, Kc1)	39.7	41.8	42.2	42.7	ms
Import 2 keycodes	50.1	52.7	53.3	53.9	ms
Import 4 keycodes	60.6	63.8	64.5	65.2	ms
Import 8 keycodes	80.9	85.1	86.1	87.0	ms
Import 16 keycodes	123.8	130.4	131.7	133.2	ms
Delete keycode	552.5	581.6	587.8	594.1	ms
Fetch key	31.4	33.0	33.4	33.7	ms
Fetch ecc key	20.0	21.1	21.3	21.5	ms
Get seed	2.0	2.1	2.2	2.2	ms

**Table 276 • Cryptographic Block Characteristics (continued)**

Service	Conditions	Timing	Unit
SHA256	512 bits	540	kbps
	1024 bits	780	kbps
	2048 bits	950	kbps
	24 kbits	1140	kbps
HMAC	512 bytes	820	kbps
	1024 bytes	890	kbps
	2048 bytes	930	kbps
	24 kbytes	980	kbps
KeyTree		1.8	ms
Challenge-response	PUF = OFF	25	ms
	PUF = ON	7	ms
ECC point multiplication		590	ms
ECC point addition		8	ms

1. Using cypher block chaining (CBC) mode.

### 2.3.19 Crystal Oscillator

The following table describes the electrical characteristics of the crystal oscillator in the IGLOO2 FPGA and SmartFusion2 SoC FPGAs.

**Table 277 • Electrical Characteristics of the Crystal Oscillator – High Gain Mode (20 MHz)**

Parameter	Symbol	Min	Typ	Max	Unit	Condition
Operating frequency	FXTAL		20		MHz	
Accuracy	ACCXTAL			0.0047	%	005, 010, 025, 050, 060, and 090 devices
				0.0058	%	150 devices
Output duty cycle	CYCXTAL		49–51	47–53	%	
Output period jitter (peak to peak)	JITPERXTAL		200	300	ps	
Output cycle to cycle jitter (peak to peak)	JITCYCXTAL		200	300	ps	010, 025, 050, and 060 devices
			250	410	ps	150 devices
			250	550	ps	005 and 090 devices
Operating current	IDYNXTAL		1.5		mA	010, 050, and 060 devices
			1.65		mA	005, 025, 090, and 150 devices
Input logic level high	VIHXTAL	0.9 V <sub>PP</sub>			V	
Input logic level low	VILXTAL			0.1 V <sub>PP</sub>	V	

**Table 305 • SPI Characteristics for All Devices (continued)**

Symbol	Description	Min	Typ	Max	Unit	Conditions
sp5	SPI_[0 1]_CLK, SPI_[0 1]_DO, SPI_[0 1]_SS fall time (10%–90%) <sup>1</sup>		2.906		ns	IO Configuration: LVCMOS 2.5 V-8 mA AC Loading: 35 pF Test Conditions: Typical Voltage, 25 °C
SPI master configuration (applicable for 005, 010, 025, and 050 devices)						
sp6m	SPI_[0 1]_DO setup time <sup>2</sup>	(SPI_x_CLK_period/2) – 8.0			ns	
sp7m	SPI_[0 1]_DO hold time <sup>2</sup>	(SPI_x_CLK_period/2) – 2.5			ns	
sp8m	SPI_[0 1]_DI setup time <sup>2</sup>	12			ns	
sp9m	SPI_[0 1]_DI hold time <sup>2</sup>	2.5			ns	
SPI slave configuration (applicable for 005, 010, 025, and 050 devices)						
sp6s	SPI_[0 1]_DO setup time <sup>2</sup>	(SPI_x_CLK_period/2) – 17.0			ns	
sp7s	SPI_[0 1]_DO hold time <sup>2</sup>	(SPI_x_CLK_period/2) + 3.0			ns	
sp8s	SPI_[0 1]_DI setup time <sup>2</sup>	2			ns	
sp9s	SPI_[0 1]_DI hold time <sup>2</sup>	7			ns	
SPI master configuration (applicable for 060, 090, and 150 devices)						
sp6m	SPI_[0 1]_DO setup time <sup>2</sup>	(SPI_x_CLK_period/2) – 7.0			ns	
sp7m	SPI_[0 1]_DO hold time <sup>2</sup>	(SPI_x_CLK_period/2) – 9.5			ns	
sp8m	SPI_[0 1]_DI setup time <sup>2</sup>	15			ns	
sp9m	SPI_[0 1]_DI hold time <sup>2</sup>	–2.5			ns	
SPI slave configuration (applicable for 060, 090, and 150 devices)						
sp6s	SPI_[0 1]_DO setup time <sup>2</sup>	(SPI_x_CLK_period/2) – 16.0			ns	
sp7s	SPI_[0 1]_DO hold time <sup>2</sup>	(SPI_x_CLK_period/2) – 3.5			ns	
sp8s	SPI_[0 1]_DI setup time <sup>2</sup>	3			ns	
sp9s	SPI_[0 1]_DI hold time <sup>2</sup>	2.5			ns	

1. For specific Rise/Fall Times board design considerations and detailed output buffer resistances, use the corresponding IBIS models located on the Microsemi SoC Products Group website: <http://www.microsemi.com/soc/download/ibis/default.aspx>.
2. For allowable pclk configurations, see Serial Peripheral Interface Controller section in the *UG0331: SmartFusion2 Microcontroller Subsystem User Guide*.

## 2.3.34 MMUART Characteristics

The following table lists the MMUART characteristics in worst-case industrial conditions when  $T_J = 100\text{ }^\circ\text{C}$ ,  $V_{DD} = 1.14\text{ V}$ .

**Table 308 • MMUART Characteristics**

Parameter	Description	-1	-Std	Unit
FMMUART_REF_CLK	Internally sourced MMUART reference clock frequency.	166	142	MHz
BAUDMMUARTTx	Maximum transmit baud rate	10.375	8.875	Mbps
BAUDMMUARTRx	Maximum receive baud rate	10.375	8.875	Mbps

## 2.3.35 IGLOO2 Specifications

### 2.3.35.1 HPMS Clock Frequency

The following table lists the maximum frequency for HPMS main clock in worst-case industrial conditions when  $T_J = 100\text{ }^\circ\text{C}$ ,  $V_{DD} = 1.14\text{ V}$ .

**Table 309 • Maximum Frequency for HPMS Main Clock**

Symbol	Description	-1	-Std	Unit
HPMS_CLK	Maximum frequency for the HPMS main clock	166	142	MHz

### 2.3.35.2 IGLOO2 Serial Peripheral Interface (SPI) Characteristics

This section describes the DC and switching of the SPI interface. Unless otherwise noted, all output characteristics given are for a 35 pF load on the pins and all sequential timing characteristics are related to SPI\_0\_CLK. For timing parameter definitions, see [Figure 23](#), page 131.

The following table lists the SPI characteristics in worst-case industrial conditions when  $T_J = 100\text{ }^\circ\text{C}$ ,  $V_{DD} = 1.14\text{ V}$ .

**Table 310 • SPI Characteristics for All Devices**

Symbol	Description	Min	Typ	Max	Unit	Conditions
SPIFMAX	Maximum operating frequency of SPI interface			20	MHz	
sp1	SPI_[0 1]_CLK minimum period					
	SPI_[0 1]_CLK = PCLK/2	12			ns	
	SPI_[0 1]_CLK = PCLK/4	24.1			ns	
	SPI_[0 1]_CLK = PCLK/8	48.2			ns	
	SPI_[0 1]_CLK = PCLK/16	0.1			$\mu\text{s}$	
	SPI_[0 1]_CLK = PCLK/32	0.19			$\mu\text{s}$	
	SPI_[0 1]_CLK = PCLK/64	0.39			$\mu\text{s}$	
SPI_[0 1]_CLK = PCLK/128	0.77			$\mu\text{s}$		