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Embedded - System On Chip (SoC): The Heart of Modern Embedded Systems

Embedded - System On Chip (SoC) refers to an integrated circuit that consolidates all the essential components of a computer system into a single chip. This includes a microprocessor, memory, and other peripherals, all packed into one compact and efficient package. SoCs are designed to provide a complete computing solution, optimizing both space and power consumption, making them ideal for a wide range of embedded applications.

What are Embedded - System On Chip (SoC)?

System On Chip (SoC) integrates multiple functions of a computer or electronic system onto a single chip. Unlike traditional multi-chip solutions, SoCs combine a central

Details

Product Status	Active
Architecture	MCU, FPGA
Core Processor	ARM® Cortex®-M3
Flash Size	512KB
RAM Size	64KB
Peripherals	DDR, PCIe, SERDES
Connectivity	CANbus, Ethernet, I ² C, SPI, UART/USART, USB
Speed	166MHz
Primary Attributes	FPGA - 150K Logic Modules
Operating Temperature	0°C ~ 85°C (TJ)
Package / Case	536-LFBGA, CSPBGA
Supplier Device Package	536-CSPBGA (16x16)
Purchase URL	https://www.e-xfl.com/product-detail/microchip-technology/m2s150t-fcs536

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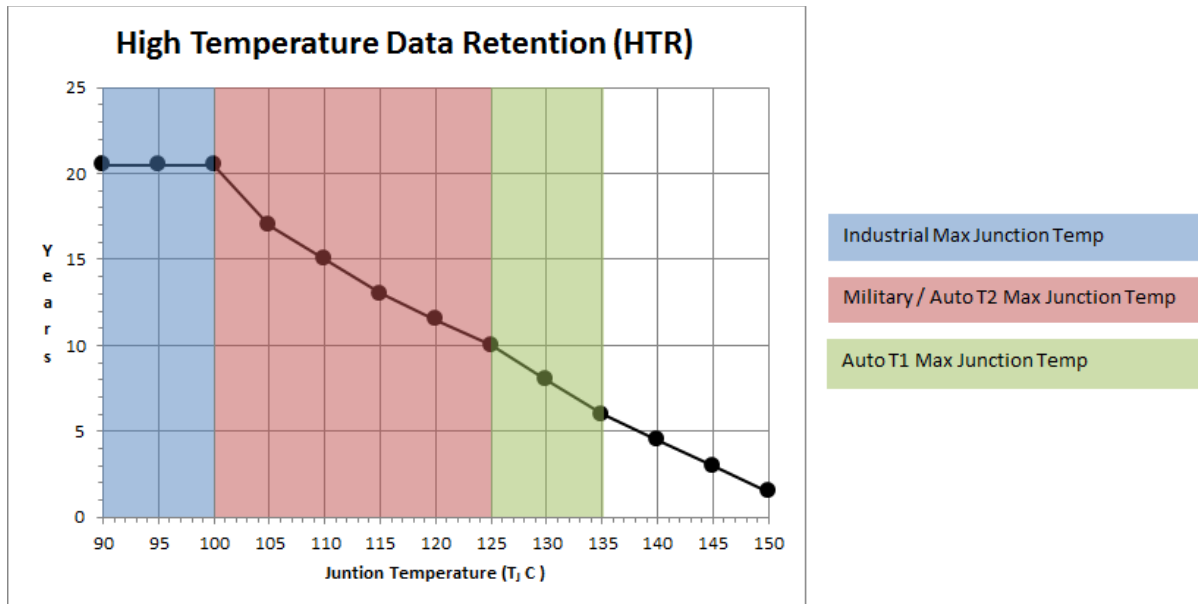
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Figure 1 • High Temperature Data Retention (HTR)



2.3.1.1 Overshoot/Undershoot Limits

For AC signals, the input signal may undershoot during transitions to -1.0 V for no longer than 10% of the period. The current during the transition must not exceed 100 mA.

For AC signals, the input signal may overshoot during transitions to $V_{CC1} + 1.0$ V for no longer than 10% of the period. The current during the transition must not exceed 100 mA.

Note: The above specifications do not apply to the PCI standard. The IGLOO2 and SmartFusion2 PCI I/Os are compliant with the PCI standard including the PCI overshoot/undershoot specifications.

2.3.1.2 Thermal Characteristics

The temperature variable in the Microsemi SoC Products Group Designer software refers to the junction temperature, not the ambient, case, or board temperatures. This is an important distinction because dynamic and static power consumption causes the chip's junction temperature to be higher than the ambient, case, or board temperatures.

EQ1 through EQ3 give the relationship between thermal resistance, temperature gradient, and power.

$$\theta_{JA} = \frac{T_J - T_A}{P}$$

EQ 1

$$\theta_{JB} = \frac{T_J - T_B}{P}$$

EQ 2

$$\theta_{JC} = \frac{T_J - T_C}{P}$$

EQ 3

Table 17 • Timing Model Parameters (continued)

Index	Symbol	Description	-1	Unit	For More Information
F	T_{DP}	Propagation delay of an OR gate	0.179	ns	See Table 223 , page 76
G	T_{DP}	Propagation delay of an LVDS transmitter	2.136	ns	See Table 169 , page 57
H	T_{DP}	Propagation delay of a three-input XOR Gate	0.241	ns	See Table 223 , page 76
I	T_{DP}	Propagation delay of LVCMOS 2.5 V transmitter, drive strength of 16 mA on the MSIO bank	2.412	ns	See Table 46 , page 27
J	T_{DP}	Propagation delay of a two-input NAND gate	0.179	ns	See Table 223 , page 76
K	T_{DP}	Propagation delay of LVCMOS 2.5 V transmitter, drive strength of 8 mA on the MSIO bank	2.309	ns	See Table 46 , page 27
L	T_{CLKQ}	Clock-to-Q of the data register	0.108	ns	See Table 224 , page 77
	T_{SUD}	Setup time of the data register	0.254	ns	See Table 224 , page 77
M	T_{DP}	Propagation delay of a two-input AND gate	0.179	ns	See Table 223 , page 76
N	T_{OCLKQ}	Clock-to-Q of the output data register	0.263	ns	See Table 220 , page 69
	T_{OSUD}	Setup time of the output data register	0.19	ns	See Table 220 , page 69
O	T_{DP}	Propagation delay of SSTL2, Class I transmitter on the MSIO bank	2.055	ns	See Table 114 , page 45
P	T_{DP}	Propagation delay of LVCMOS 1.5 V transmitter, drive strength of 12 mA, fast slew on the DDRIO bank	3.316	ns	See Table 70 , page 34

Table 43 • LVCMOS 2.5 V AC Test Parameter Specifications

Parameter	Symbol	Typ	Unit
Measuring/trip point for data path	V_{TRIP}	1.2	V
Resistance for enable path (T_{ZH} , T_{ZL} , T_{HZ} , T_{LZ})	R_{ENT}	2K	$\Omega\sigma$
Capacitive loading for enable path (T_{ZH} , T_{ZL} , T_{HZ} , T_{LZ})	C_{ENT}	5	pF
Capacitive loading for data path (T_{DP})	C_{LOAD}	5	pF

Table 44 • LVCMOS 2.5 V Transmitter Drive Strength Specifications

Output Drive Selection			VOH (V)	VOL (V)	IOH (at VOH) mA	IOL (at VOL) mA
MSIO I/O Bank	MSIOD I/O Bank	DDRIO I/O Bank (With Software Default Fixed Code)	Min	Max		
2 mA	2 mA	2 mA	$V_{DDI} - 0.4$	0.4	2	2
4 mA	4 mA	4 mA	$V_{DDI} - 0.4$	0.4	4	4
6 mA	6 mA	6 mA	$V_{DDI} - 0.4$	0.4	6	6
8 mA	8 mA	8 mA	$V_{DDI} - 0.4$	0.4	8	8
12 mA	12 mA	12 mA	$V_{DDI} - 0.4$	0.4	12	12
16 mA		16 mA	$V_{DDI} - 0.4$	0.4	16	16

Note: For board design considerations, output slew rates extraction, detailed output buffer resistances, and I/V Curve, use the corresponding IBIS models located at:
www.microsemi.com/soc/download/ibis/default.aspx.

AC Switching Characteristics

Worst commercial-case conditions: $T_J = 85\text{ }^\circ\text{C}$, $V_{DD} = 1.14\text{ V}$, $V_{DDI} = 2.375\text{ V}$

Table 45 • LVCMOS 2.5 V Receiver Characteristics (Input Buffers)

	On-Die Termination (ODT)	T_{PY}		T_{PYS}		Unit
		-1	-Std	-1	-Std	
LVCMOS 2.5 V (for DDRIO I/O bank)	None	1.823	2.145	1.932	2.274	ns
LVCMOS 2.5 V (for MSIO I/O bank)	None	2.486	2.925	2.495	2.935	ns
LVCMOS 2.5 V (for MSIOD I/O bank)	None	2.29	2.694	2.305	2.712	ns

Table 46 • LVCMOS 2.5 V Transmitter Characteristics for DDRIO Bank (Output and Tristate Buffers)

Output Drive Selection	Slew Control	T_{DP}		T_{ZL}		T_{ZH}		T_{HZ}^1		T_{LZ}^1		Unit
		-1	-Std	-1	-Std	-1	-Std	-1	-Std	-1	-Std	
2 mA	Slow	3.657	4.302	3.393	3.991	3.675	4.323	3.894	4.582	3.552	4.18	ns
	Medium	3.374	3.97	3.139	3.693	3.396	3.995	3.635	4.277	3.253	3.828	ns
	Medium fast	3.239	3.811	3.036	3.572	3.261	3.836	3.519	4.141	3.128	3.681	ns
	Fast	3.224	3.793	3.029	3.563	3.246	3.818	3.512	4.132	3.119	3.67	ns

Table 85 • LVCMOS 1.2 V Transmitter Characteristics for MSIOD I/O Bank (Output and Tristate Buffers)

Output Drive Selection	Slew Control	T _{DP}		T _{ZL}		T _{ZH}		T _{HZ} ¹		T _{LZ} ¹		Unit
		-1	-Std	-1	-Std	-1	-Std	-1	-Std	-1	-Std	
2 mA	Slow	3.883	4.568	4.868	5.726	5.329	6.269	7.994	9.404	7.527	8.855	ns
4 mA	Slow	3.774	4.44	4.188	4.926	4.613	5.426	8.972	10.555	8.315	9.782	ns

1. Delay increases with drive strength are inherent to built-in slew control circuitry for simultaneous switching output (SSO) management.

2.3.5.11 3.3 V PCI/PCIX

Peripheral Component Interface (PCI) for 3.3 V standards specify support for 33 MHz and 66 MHz PCI bus applications.

Minimum and Maximum DC/AC Input and Output Levels Specification (Applicable to MSIO Bank Only)

Table 86 • PCI/PCI-X DC Recommended Operating Conditions

Parameter	Symbol	Min	Typ	Max	Unit
Supply voltage	V _{DDI}	3.15	3.3	3.45	V

Table 87 • PCI/PCI-X DC Input Voltage Specification

Parameter	Symbol	Min	Max	Unit
DC input voltage	V _I	0	3.45	V
Input current high ¹	I _{IH} (DC)			
Input current low ¹	I _{IL} (DC)			

1. See Table 24, page 22.

Table 88 • PCI/PCI-X DC Output Voltage Specification

Parameter	Symbol	Min	Typ	Max	Unit
DC output logic high	V _{OH}		Per PCI specification		V
DC output logic low	V _{OL}		Per PCI specification		V

Table 89 • PCI/PCI-X Minimum and Maximum AC Switching Speed

Parameter	Symbol	Max	Unit	Conditions
Maximum data rate (MSIO I/O bank)	D _{MAX}	630	Mbps	AC Loading: per JEDEC specifications

Table 90 • PCI/PCI-X AC Test Parameter Specifications

Parameter	Symbol	Typ	Unit
Measuring/trip point for data path (falling edge)	V _{TRIP}	0.615 × V _{DDI}	V
Measuring/trip point for data path (rising edge)	V _{TRIP}	0.285 × V _{DDI}	V
Resistance for data test path	R _{TT_TEST}	25	Ω
Resistance for enable path (T _{ZH} , T _{ZL} , T _{HZ} , T _{LZ})	R _{ENT}	2K	Ω
Capacitive loading for enable path (T _{ZH} , T _{ZL} , T _{HZ} , T _{LZ})	C _{ENT}	5	pF
Capacitive loading for data path (T _{DP})	C _{LOAD}	10	pF

Table 100 • HSTL AC Test Parameter Specification

Parameter	Symbol	Typ	Unit
Measuring/trip point for data path	V_{TRIP}	0.75	V
Resistance for enable path (T_{ZH} , T_{ZL} , T_{HZ} , T_{LZ})	R_{ENT}	2K	Ω
Capacitive loading for enable path (T_{ZH} , T_{ZL} , T_{HZ} , T_{LZ})	C_{ENT}	5	pF
Reference resistance for data test path for HSTL15 Class I (T_{DP})	RTT_TEST	50	Ω
Reference resistance for data test path for HSTL15 Class II (T_{DP})	RTT_TEST	25	Ω
Capacitive loading for data path (T_{DP})	C_{LOAD}	5	pF

AC Switching Characteristics

Worst-case commercial conditions: $T_J = 85\text{ }^\circ\text{C}$, $V_{DD} = 1.14\text{ V}$, worst-case V_{DDI} .

Table 101 • HSTL Receiver Characteristics for DDRIO I/O Bank with Fixed Code (Input Buffers)

		T_{PY}		
		-1	-Std	Unit
Pseudo differential	None	1.605	1.888	ns
	47.8	1.614	1.898	ns
True differential	None	1.622	1.909	ns
	47.8	1.628	1.916	ns

Table 102 • HSTL Transmitter Characteristics for DDRIO I/O Bank (Output and Tristate Buffers)

	T_{DP}		T_{ZL}		T_{ZH}		T_{HZ}		T_{LZ}		Unit
	-1	-Std	-1	-Std	-1	-Std	-1	-Std	-1	-Std	
HSTL Class I											
Single-ended	2.6	3.059	2.514	2.958	2.514	2.958	2.431	2.86	2.431	2.86	ns
Differential	2.621	3.083	2.648	3.115	2.647	3.113	2.925	3.442	2.923	3.44	ns
HSTL Class II											
Single-ended	2.511	2.954	2.488	2.927	2.49	2.93	2.409	2.833	2.411	2.836	ns
Differential	2.528	2.974	2.552	3.003	2.551	3.001	2.897	3.409	2.896	3.408	ns

2.3.6.2 Stub-Series Terminated Logic

Stub-Series Terminated Logic (SSTL) for 2.5 V (SSTL2), 1.8 V (SSTL18), and 1.5 V (SSTL15) is supported in IGLOO2 and SmartFusion2 SoC FPGAs. SSTL2 is defined by JEDEC standard JESD8-9B and SSTL18 is defined by JEDEC standard JESD8-15. IGLOO2 SSTL I/O configurations are designed to meet double data rate standards DDR/2/3 for general purpose memory buses. Double data rate standards are designed to meet their JEDEC specifications as defined by JEDEC standard JESD79F for DDR, JEDEC standard JESD79-2F for DDR, JEDEC standard JESD79-3D for DDR3, and JEDEC standard JESD209A for LPDDR.

Table 144 • LPDDR AC Differential Voltage Specifications (for DDRIO I/O Bank Only)

Parameter	Symbol	Min	Max	Unit
AC input differential voltage	V_{DIFF}	$0.6 \times V_{DDI}$		V
AC differential cross point voltage	V_x	$0.4 \times V_{DDI}$	$0.6 \times V_{DDI}$	V

Table 145 • LPDDR AC Specifications (for DDRIO I/O Bank Only)

Parameter	Symbol	Max	Unit	Conditions
Maximum data rate	D_{MAX}	400	Mbps	AC loading: per JEDEC specifications

Table 146 • LPDDR AC Calibrated Impedance Option (for DDRIO I/O Bank Only)

Parameter	Symbol	Typ	Unit	Conditions
Supported output driver calibrated impedance	R_{REF}	20, 42	Ω	Reference resistor = 150 Ω
Effective impedance value (ODT)	R_{TT}	50, 70, 150	Ω	Reference resistor = 150 Ω

Table 147 • LPDDR AC Test Parameter Specifications (for DDRIO I/O Bank Only)

Parameter	Symbol	Typ	Unit
Measuring/trip point for data path	V_{TRIP}	0.9	V
Resistance for enable path (T_{ZH} , T_{ZL} , T_{HZ} , T_{LZ})	R_{ENT}	2K	Ω
Capacitive loading for enable path (T_{ZH} , T_{ZL} , T_{HZ} , T_{LZ})	C_{ENT}	5	pF
Reference resistance for data test path for LPDDR (T_{DP})	R_{TT_TEST}	50	Ω
Capacitive loading for data path (T_{DP})	C_{LOAD}	5	Ω

AC Switching Characteristics

Worst-case commercial conditions: $T_J = 85^\circ\text{C}$, $V_{DD} = 1.14\text{ V}$, worst-case V_{DDI} .

Table 148 • LPDDR Receiver Characteristics for DDRIO I/O Bank with Fixed Codes

	On-Die Termination (ODT)	T_{PY}		Unit
		-1	-Std	
Pseudo differential	None	1.568	1.845	ns
True differential	None	1.588	1.869	ns

Table 149 • LPDDR Reduced Drive for DDRIO I/O Bank (Output and Tristate Buffers)

	T_{DP}		T_{ENZL}		T_{ENZH}		T_{ENHZ}		T_{ENLZ}		Unit
	-1	-Std	-1	-Std	-1	-Std	-1	-Std	-1	-Std	
Single-ended	2.383	2.804	2.23	2.623	2.229	2.622	2.202	2.591	2.201	2.59	ns
Differential	2.396	2.819	2.764	3.252	2.764	3.252	2.255	2.653	2.255	2.653	ns

Table 162 • LVDS DC Output Voltage Specification

Parameter	Symbol	Min	Typ	Max	Unit
DC output logic high	V_{OH}	1.25	1.425	1.6	V
DC output logic low	V_{OL}	0.9	1.075	1.25	V

Table 163 • LVDS DC Differential Voltage Specification

Parameter	Symbol	Min	Typ	Max	Unit
Differential output voltage swing	V_{OD}	250	350	450	mV
Output common mode voltage	V_{OCM}	1.125	1.25	1.375	V
Input common mode voltage	V_{ICM}	0.05	1.25	2.35	V
Input differential voltage	V_{ID}	100	350	600	mV

Table 164 • LVDS Minimum and Maximum AC Switching Speed

Parameter	Symbol	Max	Unit	Conditions
Maximum data rate (for MSIO I/O bank)	D_{MAX}	535	Mbps	AC loading: 12 pF / 100 Ω differential load
Maximum data rate (for MSIOD I/O bank) no pre-emphasis	D_{MAX}	620	Mbps	AC loading: 10 pF / 100 Ω differential load
		700	Mbps	AC loading: 2 pF / 100 Ω differential load

Table 165 • LVDS AC Impedance Specifications

Parameter	Symbol	Typ	Max	Unit
Termination resistance	R_T	100		Ω

Table 166 • LVDS AC Test Parameter Specifications

Parameter	Symbol	Typ	Unit
Measuring/trip point for data path	V_{TRIP}	Cross point	V
Resistance for enable path (T_{ZH} , T_{ZL} , T_{HZ} , T_{LZ})	R_{ENT}	2K	Ω
Capacitive loading for enable path (T_{ZH} , T_{ZL} , T_{HZ} , T_{LZ})	C_{ENT}	5	pF

LVDS25 AC Switching Characteristics

Worst commercial-case conditions: $T_J = 85^\circ\text{C}$, $V_{DD} = 1.14\text{ V}$, $V_{DDI} = 2.375\text{ V}$

Table 167 • LVDS25 Receiver Characteristics for MSIO I/O Bank (Input Buffers)

On-Die Termination (ODT)	T_{PY}		Unit
	-1	-Std	
None	2.774	3.263	ns
100	2.775	3.264	ns

AC Switching Characteristics

Worst commercial-case conditions: $T_J = 85\text{ }^\circ\text{C}$, $V_{DD} = 1.14\text{ V}$, $V_{DDI} = 2.375\text{ V}$.

Table 210 • RSDS AC Switching Characteristics for Receiver (for MSIO I/O Bank - Input Buffers)

On-Die Termination (ODT)	T_{PY}		Unit
	-1	-Std	
None	2.855	3.359	ns
100	2.85	3.353	ns

Table 211 • RSDS AC Switching Characteristics for Receiver (for MSIOD I/O Bank - Input Buffers)

On-Die Termination (ODT)	T_{PY}		Unit
	-1	-Std	
None	2.602	3.061	ns
100	2.597	3.055	ns

Table 212 • RSDS AC Switching Characteristics for Transmitter (for MSIO I/O Bank - Output and Tristate Buffers)

T_{DP}		T_{ZL}		T_{ZH}		T_{HZ}		T_{LZ}		Unit
-1	-Std	-1	-Std	-1	-Std	-1	-Std	-1	-Std	
2.097	2.467	2.303	2.709	2.291	2.695	1.961	2.307	1.947	2.29	ns

Table 213 • RSDS AC Switching Characteristics for Transmitter (for MSIOD I/O Bank - Output and Tristate Buffers)

	T_{DP}		T_{ZL}		T_{ZH}		T_{HZ}		T_{LZ}		Unit
	-1	-Std	-1	-Std	-1	-Std	-1	-Std	-1	-Std	
No pre-emphasis	1.614	1.899	1.559	1.834	1.55	1.823	1.59	1.87	1.575	1.852	ns
Min pre-emphasis	1.604	1.887	1.742	2.05	1.728	2.032	1.889	2.222	1.858	2.185	ns
Med pre-emphasis	1.521	1.79	1.753	2.062	1.737	2.043	1.9	2.235	1.868	2.197	ns
Max pre-emphasis	1.492	1.754	1.762	2.073	1.745	2.052	1.91	2.247	1.876	2.206	ns

2.3.7.6 LVPECL

Low-Voltage Positive Emitter-Coupled Logic (LVPECL) is another differential I/O standard. It requires that one data bit be carried through two signal lines. Similar to LVDS, two pins are needed. It also requires external resistor termination. IGLOO2 and SmartFusion2 SoC FPGAs support only LVPECL receivers and do not support LVPECL transmitters.

Minimum and Maximum Input and Output Levels (Applicable to MSIO I/O Bank Only)

Table 214 • LVPECL Recommended DC Operating Conditions

Parameter	Symbol	Min	Typ	Max	Unit
Supply voltage	V_{DDI}	3.15	3.3	3.45	V

2.3.8.2 Output/Enable Register

Figure 8 • Timing Model for Output/Enable Register

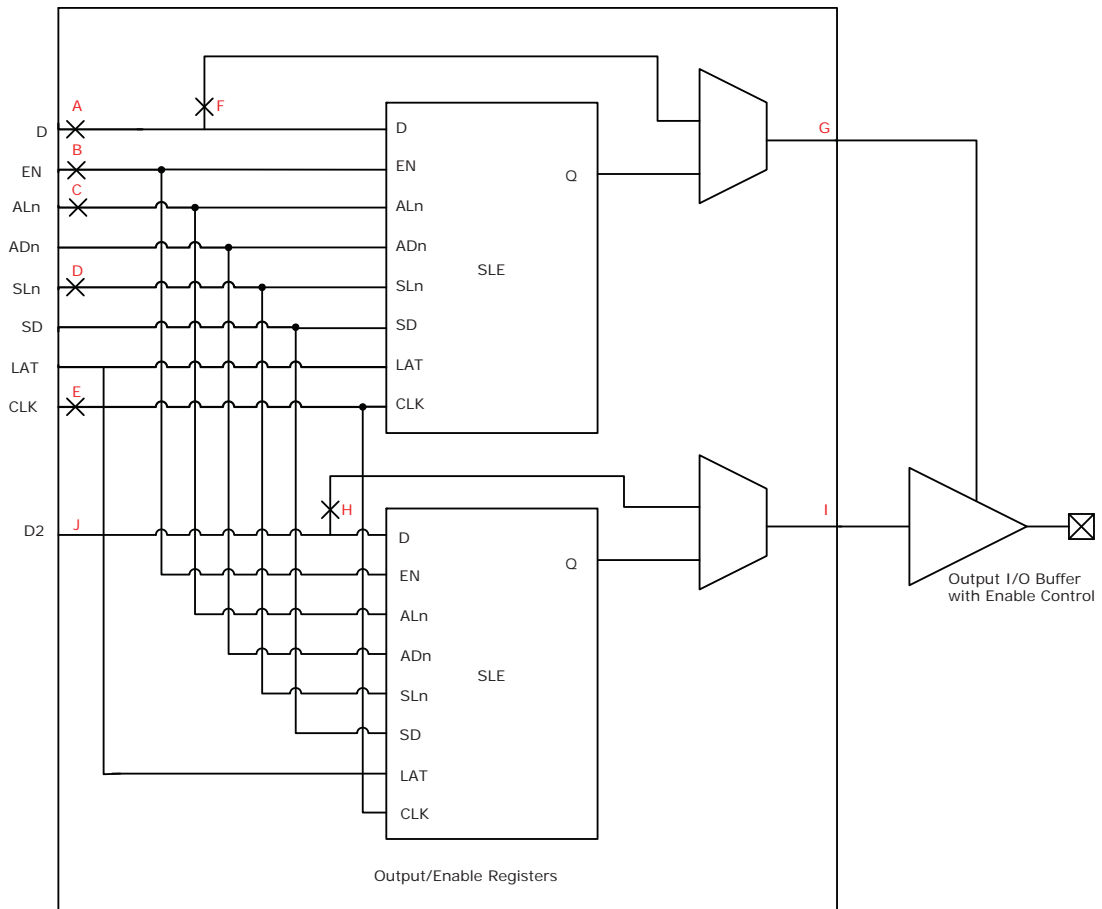


Table 232 • RAM1K18 – Dual-Port Mode for Depth × Width Configuration 2K × 9 (continued)

Parameter	Symbol	–1		–Std		Unit
		Min	Max	Min	Max	
Address setup time	T_{ADDRSU}	0.475		0.559		ns
Address hold time	T_{ADDRHD}	0.274		0.322		ns
Data setup time	T_{DSU}	0.336		0.395		ns
Data hold time	T_{DHD}	0.082		0.096		ns
Block select setup time	T_{BLKSU}	0.207		0.244		ns
Block select hold time	T_{BLKHD}	0.216		0.254		ns
Block select to out disable time (when pipelined register is disabled)	T_{BLK2Q}		1.529		1.799	ns
Block select minimum pulse width	T_{BLKMPW}	0.186		0.219		ns
Read enable setup time	T_{RDESU}	0.485		0.57		ns
Read enable hold time	T_{RDEHD}	0.071		0.083		ns
Pipelined read enable setup time (A_DOUT_EN, B_DOUT_EN)	$T_{RDPLESU}$	0.248		0.291		ns
Pipelined read enable hold time (A_DOUT_EN, B_DOUT_EN)	$T_{RDPLEHD}$	0.102		0.12		ns
Asynchronous reset to output propagation delay	T_{R2Q}		1.514		1.781	ns
Asynchronous reset removal time	T_{RSTREM}	0.506		0.595		ns
Asynchronous reset recovery time	T_{RSTREC}	0.004		0.005		ns
Asynchronous reset minimum pulse width	T_{RSTMPW}	0.301		0.354		ns
Pipelined register asynchronous reset removal time	$T_{PLRSTREM}$	–0.279		–0.328		ns
Pipelined register asynchronous reset recovery time	$T_{PLRSTREC}$	0.327		0.385		ns
Pipelined register asynchronous reset minimum pulse width	$T_{PLRSTMPW}$	0.282		0.332		ns
Synchronous reset setup time	T_{SRSTSU}	0.226		0.265		ns
Synchronous reset hold time	T_{SRSTHD}	0.036		0.043		ns
Write enable setup time	T_{WESU}	0.415		0.488		ns
Write enable hold time	T_{WEHD}	0.048		0.057		ns
Maximum frequency	F_{MAX}		400		340	MHz

The following table lists the RAM1K18 – dual-port mode for depth × width configuration 4K × 4 in worst commercial-case conditions when $T_J = 85\text{ }^\circ\text{C}$, $V_{DD} = 1.14\text{ V}$.

Table 233 • RAM1K18 – Dual-Port Mode for Depth × Width Configuration 4K × 4

Parameter	Symbol	–1		–Std		Unit
		Min	Max	Min	Max	
Clock period	T_{CY}	2.5		2.941		ns
Clock minimum pulse width high	$T_{CLKMPWH}$	1.125		1.323		ns
Clock minimum pulse width low	$T_{CLKMPWL}$	1.125		1.323		ns
Pipelined clock period	T_{PLCY}	2.5		2.941		ns
Pipelined clock minimum pulse width high	$T_{PLCLKMPWH}$	1.125		1.323		ns

Table 240 • μ SRAM (RAM128x8) in 128 x 8 Mode (continued)

Parameter	Symbol	-1		-Std		Unit
		Min	Max	Min	Max	
Read address hold time in synchronous mode	T_{ADDRHD}	0.091		0.107		ns
Read address hold time in asynchronous mode		-0.778		-0.915		ns
Read enable setup time	T_{RDENSU}	0.278		0.327		ns
Read enable hold time	T_{RDENHD}	0.057		0.067		ns
Read block select setup time	T_{BLKSU}	1.839		2.163		ns
Read block select hold time	T_{BLKHD}	-0.65		-0.765		ns
Read block select to out disable time (when pipelined register is disabled)	T_{BLK2Q}		2.036		2.396	ns
Read asynchronous reset removal time (pipelined clock)	T_{RSTREM}	-0.023		-0.027		ns
Read asynchronous reset removal time (non-pipelined clock)		0.046		0.054		ns
Read asynchronous reset recovery time (pipelined clock)	T_{RSTREC}	0.507		0.597		ns
Read asynchronous reset recovery time (non-pipelined clock)		0.236		0.278		ns
Read asynchronous reset to output propagation delay (with pipelined register enabled)	T_{R2Q}		0.835		0.982	ns
Read synchronous reset setup time	T_{SRSTSU}	0.271		0.319		ns
Read synchronous reset hold time	T_{SRSTHD}	0.061		0.071		ns
Write clock period	T_{CCY}	4		4		ns
Write clock minimum pulse width high	$T_{CCLKMPWH}$	1.8		1.8		ns
Write clock minimum pulse width low	$T_{CCLKMPWL}$	1.8		1.8		ns
Write block setup time	T_{BLKCSU}	0.404		0.476		ns
Write block hold time	T_{BLKCHD}	0.007		0.008		ns
Write input data setup time	T_{DINCSU}	0.115		0.135		ns
Write input data hold time	T_{DINCHD}	0.15		0.177		ns
Write address setup time	$T_{ADDRCSU}$	0.088		0.104		ns
Write address hold time	$T_{ADDRCHD}$	0.128		0.15		ns
Write enable setup time	T_{WECSU}	0.397		0.467		ns
Write enable hold time	T_{WECHD}	-0.026		-0.03		ns
Maximum frequency	F_{MAX}		250		250	MHz

2.3.14 Math Block Timing Characteristics

The fundamental building block in any digital signal processing algorithm is the multiply-accumulate function. Each IGLOO2 and SmartFusion2 SoC math block supports 18×18 signed multiplication, dot product, and built-in addition, subtraction, and accumulation units to combine multiplication results efficiently. The following table lists the math blocks with all registers used in worst commercial-case conditions when $T_J = 85\text{ }^\circ\text{C}$, $V_{DD} = 1.14\text{ V}$.

Table 268 • Math Blocks with all Registers Used

Parameter	Symbol	-1		-Std		Unit
		Min	Max	Min	Max	
Input, control register setup time	T_{MISU}	0.149		0.176		ns
Input, control register hold time	T_{MIHD}	1.68		1.976		ns
CDIN input setup time	$T_{MOCDINSU}$	0.185		0.218		ns
CDIN input hold time	$T_{MOCDINHHD}$	0.08		0.094		ns
Synchronous reset/enable setup time	$T_{MSRSTENSU}$	-0.419		-0.493		ns
Synchronous reset/enable hold time	$T_{MSRSTENHD}$	0.011		0.013		ns
Asynchronous reset removal time	$T_{MARSTREM}$	0		0		ns
Asynchronous reset recovery time	$T_{MARSTREC}$	0.088		0.104		ns
Output register clock to out delay	T_{MOCQ}		0.232		0.273	ns
CLK minimum period	T_{MCLKMP}	2.245		2.641		ns

The following table lists the math blocks with input bypassed and output registers used in worst commercial-case conditions when $T_J = 85\text{ }^\circ\text{C}$, $V_{DD} = 1.14\text{ V}$.

Table 269 • Math Block with Input Bypassed and Output Registers Used

Parameter	Symbol	-1		-Std		Unit
		Min	Max	Min	Max	
Output register setup time	T_{MOSU}	2.294		2.699		ns
Output register hold time	T_{MOHD}	1.68		1.976		ns
CDIN input setup time	$T_{MOCDINSU}$	0.115		0.136		ns
CDIN input hold time	$T_{MOCDINHHD}$	-0.444		-0.522		ns
Synchronous reset/enable setup time	$T_{MSRSTENSU}$	-0.419		-0.493		ns
Synchronous reset/enable hold time	$T_{MSRSTENHD}$	0.011		0.013		ns
Asynchronous reset removal time	$T_{MARSTREM}$	0		0		ns
Asynchronous reset recovery time	$T_{MARSTREC}$	0.014		0.017		ns
Output register clock to out delay	T_{MOCQ}		0.232		0.273	ns
CLK minimum period	T_{MCLKMP}	2.179		2.563		ns

Table 276 • Cryptographic Block Characteristics (continued)

Service	Conditions	Timing	Unit
SHA256	512 bits	540	kbps
	1024 bits	780	kbps
	2048 bits	950	kbps
	24 kbits	1140	kbps
HMAC	512 bytes	820	kbps
	1024 bytes	890	kbps
	2048 bytes	930	kbps
	24 kbytes	980	kbps
KeyTree		1.8	ms
Challenge-response	PUF = OFF	25	ms
	PUF = ON	7	ms
ECC point multiplication		590	ms
ECC point addition		8	ms

1. Using cypher block chaining (CBC) mode.

2.3.19 Crystal Oscillator

The following table describes the electrical characteristics of the crystal oscillator in the IGLOO2 FPGA and SmartFusion2 SoC FPGAs.

Table 277 • Electrical Characteristics of the Crystal Oscillator – High Gain Mode (20 MHz)

Parameter	Symbol	Min	Typ	Max	Unit	Condition
Operating frequency	FXTAL		20		MHz	
Accuracy	ACCXTAL			0.0047	%	005, 010, 025, 050, 060, and 090 devices
				0.0058	%	150 devices
Output duty cycle	CYCXTAL		49–51	47–53	%	
Output period jitter (peak to peak)	JITPERXTAL		200	300	ps	
Output cycle to cycle jitter (peak to peak)	JITCYCXTAL		200	300	ps	010, 025, 050, and 060 devices
			250	410	ps	150 devices
			250	550	ps	005 and 090 devices
Operating current	IDYNXTAL		1.5		mA	010, 050, and 060 devices
			1.65		mA	005, 025, 090, and 150 devices
Input logic level high	VIHXTAL	0.9 V _{PP}			V	
Input logic level low	VILXTAL			0.1 V _{PP}	V	

2.3.20 On-Chip Oscillator

The following tables describe the electrical characteristics of the available on-chip oscillators in the IGLOO2 FPGAs and SmartFusion2 SoC FPGAs.

Table 280 • Electrical Characteristics of the 50 MHz RC Oscillator

Parameter	Symbol	Typ	Max	Unit	Condition
Operating frequency	F50RC	50		MHz	
Accuracy	ACC50RC	1	4	%	050 devices
		1	5	%	005, 025, and 060 devices
		1	6.3	%	090 devices
		1	7.1	%	010 and 150 devices
Output duty cycle	CYC50RC	49–51	46.5–53.5	%	
Output jitter (peak to peak)	JIT50RC	Period Jitter			
		200	300	ps	005, 010, 050, and 060 devices
		200	400	ps	150 devices
		300	500	ps	025 and 090 devices
		Cycle-to-Cycle Jitter			
		200	300	ps	005 and 050 devices
		320	420	ps	010, 060, and 150 devices
		320	850	ps	025 and 090 devices
Operating current	IDYN50RC	6.5		mA	

Table 281 • Electrical Characteristics of the 1 MHz RC Oscillator

Parameter	Symbol	Typ	Max	Unit	Condition
Operating frequency	F1RC	1		MHz	
Accuracy	ACC1RC	1	3	%	005, 010, 025, and 050 devices
		1	4.5	%	060, and 150 devices
		1	5.6	%	090 devices
Output duty cycle	CYC1RC	49–51	46.5–53.5	%	005, 010, 025, 050, 090 and 150 devices
		49–51	46.0–54.0	%	060 devices
Output jitter (peak to peak)	JIT1RC	Period Jitter			
		10	20	ns	005, 010, 025, and 050 devices
		10	28	ns	060, 090 and 150 devices
		Cycle-to-Cycle Jitter			
		10	20	ns	005, 010, and 050 devices
		10	35	ns	025, 060, and 150 devices
		10	45	ns	090 devices
Operating current	IDYN1RC	0.1		mA	
Startup time	SU1RC	17		μs	050, 090, and 150 devices
		18		μs	005, 010, and 025 devices

2.3.30 SerDes Electrical and Timing AC and DC Characteristics

PCIe is a high-speed, packet-based, point-to-point, low-pin-count, serial interconnect bus. The IGLOO2 and SmartFusion2 SoC FPGAs has up to four hard high-speed serial interface blocks. Each SerDes block contains a PCIe system block. The PCIe system is connected to the SerDes block.

The following table lists the transmitter parameters in worst-case industrial conditions when $T_J = 100\text{ }^\circ\text{C}$, $V_{DD} = 1.14\text{ V}$.

Table 296 • Transmitter Parameters

Symbol	Description	Min	Max	Unit
VTX-DIFF-PP	Differential swing (2.5 Gbps, 5.0 Gbps)	0.8	1.2	V
VTX-CM-AC-P	Output common mode voltage (2.5 Gbps)		20	mV
VTX-CM-AC-PP	Output common mode voltage (5.0 Gbps)		100	mV
VTX-RISE-FALL	Rise and fall time (20% to 80%, 2.5 Gbps)	0.125		UI
	Rise and fall time (20% to 80%, 5.0 Gbps)	0.15		UI
ZTX-DIFF-DC	Output impedance–differential	80	120	Ω
LTX-SKEW	Lane-to-lane TX skew within a SerDes block (2.5 Gbps)		500 ps + 2 UI	ps
	Lane-to-lane TX skew within a SerDes block (5.0 Gbps)		500 ps + 4 UI	ps
RLTX-DIFF	Return loss differential mode (2.5 Gbps)	–10		dB
	Return loss differential mode (5.0 Gbps) 0.05 GHz to 1.25 GHz	–10		dB
	1.25 GHz to 2.5 GHz	–8		dB
RLTX-CM	Return loss common mode (2.5 Gbps, 5.0 Gbps)	–6		dB
TX-LOCK-RST	Transmit PLL lock time from reset		10	μs
VTX-AMP	100 mV setting	90	150	mV
	400 mV setting	320	480	mV
	800 mV setting	660	940	mV
	1200 mV setting	950	1400	mV

2.3.31.2 SmartFusion2 Inter-Integrated Circuit (I²C) Characteristics

This section describes the DC and switching of the I²C interface. Unless otherwise noted, all output characteristics given are for a 100 pF load on the pins. For timing parameter definitions, see [Figure 21](#), page 125.

The following table lists the I²C characteristics in worst-case industrial conditions when $T_J = 100\text{ }^\circ\text{C}$, $V_{DD} = 1.14\text{ V}$

Table 303 • I²C Characteristics

Parameter	Symbol	Min	Typ	Max	Unit	Conditions
Input low voltage	V_{IL}	-0.3		0.8	V	See Single-Ended I/O Standards , page 24 for more information. I/O standard used for illustration: MSIO bank-LVTTL 8 mA low drive.
Input high voltage	V_{IH}	2		3.45	V	See Single-Ended I/O Standards , page 24 for more information. I/O standard used for illustration: MSIO bank-LVTTL 8 mA low drive.
Hysteresis of schmitt triggered inputs for $V_{DDI} > 2\text{ V}$	V_{HYS}	$0.05 \times V_{DDI}$			V	See Table 28 , page 23 for more information.
Input current high	I_{IL}			10	μA	See Single-Ended I/O Standards , page 24 for more information.
Input current low	I_{IH}			10	μA	See Single-Ended I/O Standards , page 24 for more information.
Input rise time	T_{ir}			1000	ns	Standard mode
				300	ns	Fast mode
Input fall time	T_{if}			300	ns	Standard mode
				300	ns	Fast mode
Maximum output voltage low (open drain) at 3 mA sink current for $V_{DDI} > 2\text{ V}$	V_{OL}			0.4	V	See Single-Ended I/O Standards , page 24 for more information. I/O standard used for illustration: MSIO bank-LVTTL 8 mA low drive.
Pin capacitance	C_{in}			10	pF	$V_{IN} = 0$, $f = 1.0\text{ MHz}$
Output fall time from V_{IHMin} to V_{ILMax}^1	t_{OF}^1		21.04		ns	V_{IHmin} to V_{ILMax} , $C_{LOAD} = 400\text{ pF}$
			5.556		ns	V_{IHmin} to V_{ILMax} , $C_{LOAD} = 100\text{ pF}$
Output rise time from V_{ILMax} to V_{IHMin}^1	t_{OR}^1		19.887		ns	V_{ILMax} to V_{IHmin} , $C_{LOAD} = 400\text{ pF}$
			5.218		ns	V_{ILMax} to V_{IHmin} , $C_{LOAD} = 100\text{ pF}$
Output buffer maximum pull-down resistance ^{2, 3}	$R_{pull-up}^{2,3}$			50	Ω	
Output buffer maximum pull-up resistance ^{2, 4}	$R_{pull-down}^{2,4}$			131.25	Ω	

Table 310 • SPI Characteristics for All Devices (continued)

Symbol	Description	Min	Typ	Max	Unit	Conditions
SPI master configuration (applicable for 060, 090, and 150 devices)						
sp6m	SPI_[0 1]_DO setup time ²	(SPI_x_CLK_period/2) – 7.0			ns	
sp7m	SPI_[0 1]_DO hold time ²	(SPI_x_CLK_period/2) – 9.5			ns	
sp8m	SPI_[0 1]_DI setup time ²	15			ns	
sp9m	SPI_[0 1]_DI hold time ²	–2.5			ns	
SPI slave configuration (applicable for 060, 090, and 150 devices)						
sp6s	SPI_[0 1]_DO setup time ²	(SPI_x_CLK_period/2) – 16.0			ns	
sp7s	SPI_[0 1]_DO hold time ²	(SPI_x_CLK_period/2) – 3.5			ns	
sp8s	SPI_[0 1]_DI setup time ²	3			ns	
sp9s	SPI_[0 1]_DI hold time ²	2.5			ns	

1. For specific Rise/Fall Times board design considerations and detailed output buffer resistances, use the corresponding IBIS models located on the Microsemi SoC Products Group website: <http://www.microsemi.com/soc/download/ibis/default.aspx>.
2. For allowable pclk configurations, see the Serial Peripheral Interface Controller section in the *UG0331: SmartFusion2 Microcontroller Subsystem User Guide*.

Figure 23 • SPI Timing for a Single Frame Transfer in Motorola Mode (SPH = 1)

