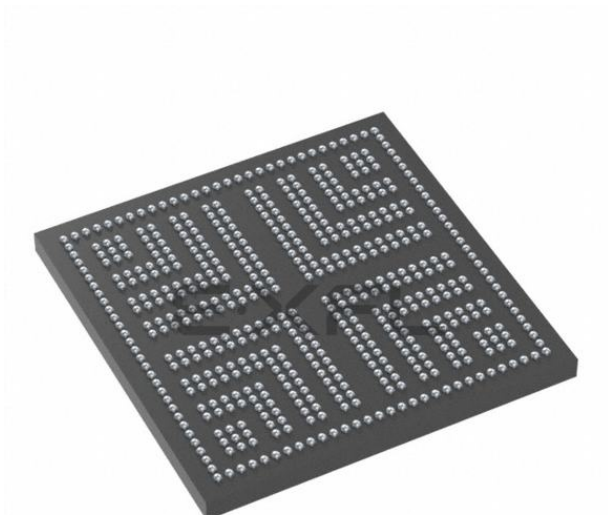




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[Embedded - System On Chip \(SoC\)](#) refers to an integrated circuit that consolidates all the essential components of a computer system into a single chip. This includes a microprocessor, memory, and other peripherals, all packed into one compact and efficient package. SoCs are designed to provide a complete computing solution, optimizing both space and power consumption, making them ideal for a wide range of embedded applications.

What are [Embedded - System On Chip \(SoC\)](#)?

System On Chip (SoC) integrates multiple functions of a computer or electronic system onto a single chip. Unlike traditional multi-chip solutions, SoCs combine a central

Details

Product Status	Active
Architecture	MCU, FPGA
Core Processor	ARM® Cortex®-M3
Flash Size	512KB
RAM Size	64KB
Peripherals	DDR, PCIe, SERDES
Connectivity	CANbus, Ethernet, I ² C, SPI, UART/USART, USB
Speed	166MHz
Primary Attributes	FPGA - 150K Logic Modules
Operating Temperature	0°C ~ 85°C (TJ)
Package / Case	536-LFBGA, CSPBGA
Supplier Device Package	536-CSPBGA (16x16)
Purchase URL	https://www.e-xfl.com/product-detail/microchip-technology/m2s150ts-1fcsg536



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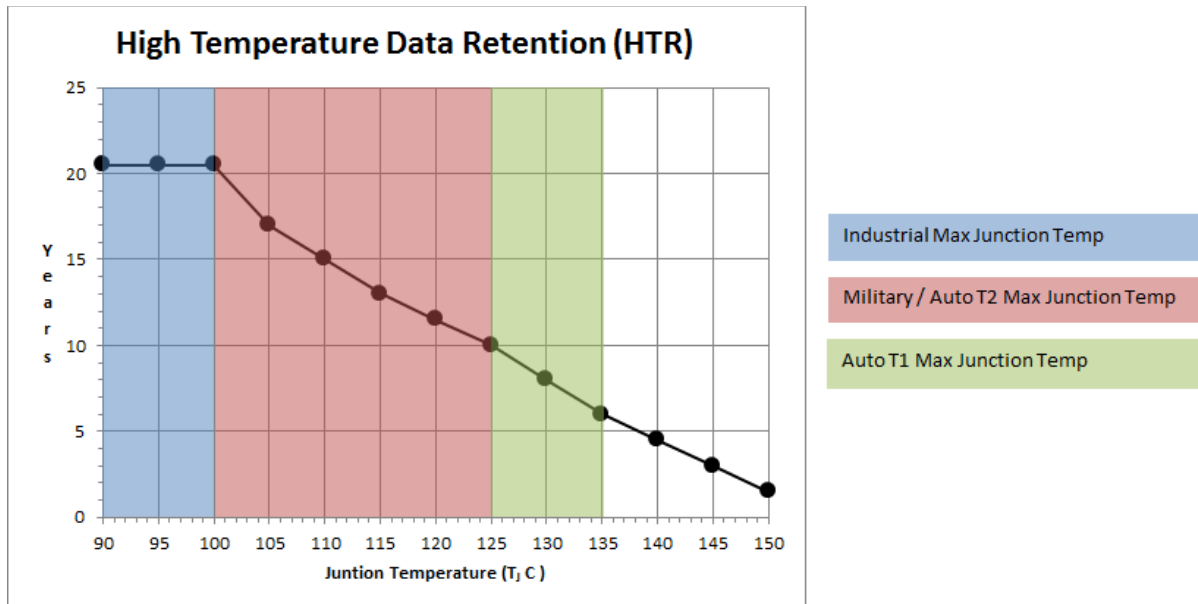
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Microsemi Corporation (Nasdaq: MSCC) offers a comprehensive portfolio of semiconductor and system solutions for aerospace & defense, communications, data center and industrial markets. Products include high-performance and radiation-hardened analog mixed-signal integrated circuits, FPGAs, SoCs and ASICs; power management products; timing and synchronization devices and precise time solutions, setting the world's standard for time; voice processing devices; RF solutions; discrete components; enterprise storage and communication solutions, security technologies and scalable anti-tamper products; Ethernet solutions; Power-over-Ethernet ICs and midspans; as well as custom design capabilities and services. Microsemi is headquartered in Aliso Viejo, California, and has approximately 4,800 employees globally. Learn more at www.microsemi.com.

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Figure 1 • High Temperature Data Retention (HTR)

2.3.1.1 Overshoot/Undershoot Limits

For AC signals, the input signal may undershoot during transitions to -1.0 V for no longer than 10% of the period. The current during the transition must not exceed 100 mA.

For AC signals, the input signal may overshoot during transitions to $V_{CCI} + 1.0$ V for no longer than 10% of the period. The current during the transition must not exceed 100 mA.

Note: The above specifications do not apply to the PCI standard. The IGLOO2 and SmartFusion2 PCI I/Os are compliant with the PCI standard including the PCI overshoot/undershoot specifications.

2.3.1.2 Thermal Characteristics

The temperature variable in the Microsemi SoC Products Group Designer software refers to the junction temperature, not the ambient, case, or board temperatures. This is an important distinction because dynamic and static power consumption causes the chip's junction temperature to be higher than the ambient, case, or board temperatures.

EQ1 through EQ3 give the relationship between thermal resistance, temperature gradient, and power.

$$\theta_{JA} = \frac{T_J - T_A}{P} \quad \text{EQ 1}$$

$$\theta_{JB} = \frac{T_J - T_B}{P} \quad \text{EQ 2}$$

$$\theta_{JC} = \frac{T_J - T_C}{P} \quad \text{EQ 3}$$

Table 9 • Package Thermal Resistance of SmartFusion2 and IGLOO2 Devices (continued)

	Still Air	1.0 m/s	2.5 m/s			
Device	θ_{JA}			θ_{JB}	θ_{JC}	Unit
150						
FC1152	9.08	6.81	5.87	2.56	0.38	°C/W
FCS536	15.01	12.06	10.76	3.69	1.55	°C/W
FCV484	16.21	13.11	11.84	6.73	0.10	°C/W

2.3.1.2.1 Theta-JA

Junction-to-ambient thermal resistance (θ_{JA}) is determined under standard conditions specified by JEDEC (JESD-51), but it has little relevance in the actual performance of the product. It must be used with caution, but it is useful for comparing the thermal performance of one package with another.

The maximum power dissipation allowed is calculated using EQ4.

$$\text{Maximum power allowed} = \frac{T_{J(\text{MAX})} - T_{A(\text{MAX})}}{\theta_{JA}}$$

EQ 4

The absolute maximum junction temperature is 100 °C. EQ5 shows a sample calculation of the absolute maximum power dissipation allowed for the M2GL050T-FG896 package at commercial temperature and in still air, where:

$$\begin{aligned}\theta_{JA} &= 14.7 \text{ °C/W (taken from Table 9, page 10).} \\ T_A &= 85 \text{ °C}\end{aligned}$$

$$\text{Maximum power allowed} = \frac{100 \text{ °C} - 85 \text{ °C}}{14.7 \text{ °C/W}} = 1.088 \text{ W}$$

EQ 5

The power consumption of a device can be calculated using the Microsemi SoC Products Group power calculator. The device's power consumption must be lower than the calculated maximum power dissipation by the package.

If the power consumption is higher than the device's maximum allowable power dissipation, a heat sink may be attached to the top of the case, or the airflow inside the system must be increased.

2.3.1.2.2 Theta-JB

Junction-to-board thermal resistance (θ_{JB}) measures the ability of the package to dissipate heat from the surface of the chip to the PCB. As defined by the JEDEC (JESD-51) standard, the thermal resistance from the junction to the board uses an isothermal ring cold plate zone concept. The ring cold plate is simply a means to generate an isothermal boundary condition at the perimeter. The cold plate is mounted on a JEDEC standard board with a minimum distance of 5.0 mm away from the package edge.

2.3.1.2.3 Theta-JC

Junction-to-case thermal resistance (θ_{JC}) measures the ability of a device to dissipate heat from the surface of the chip to the top or bottom surface of the package. It is applicable to packages used with external heat sinks. Constant temperature is applied to the surface, which acts as a boundary condition.

This only applies to situations where all or nearly all of the heat is dissipated through the surface in consideration.

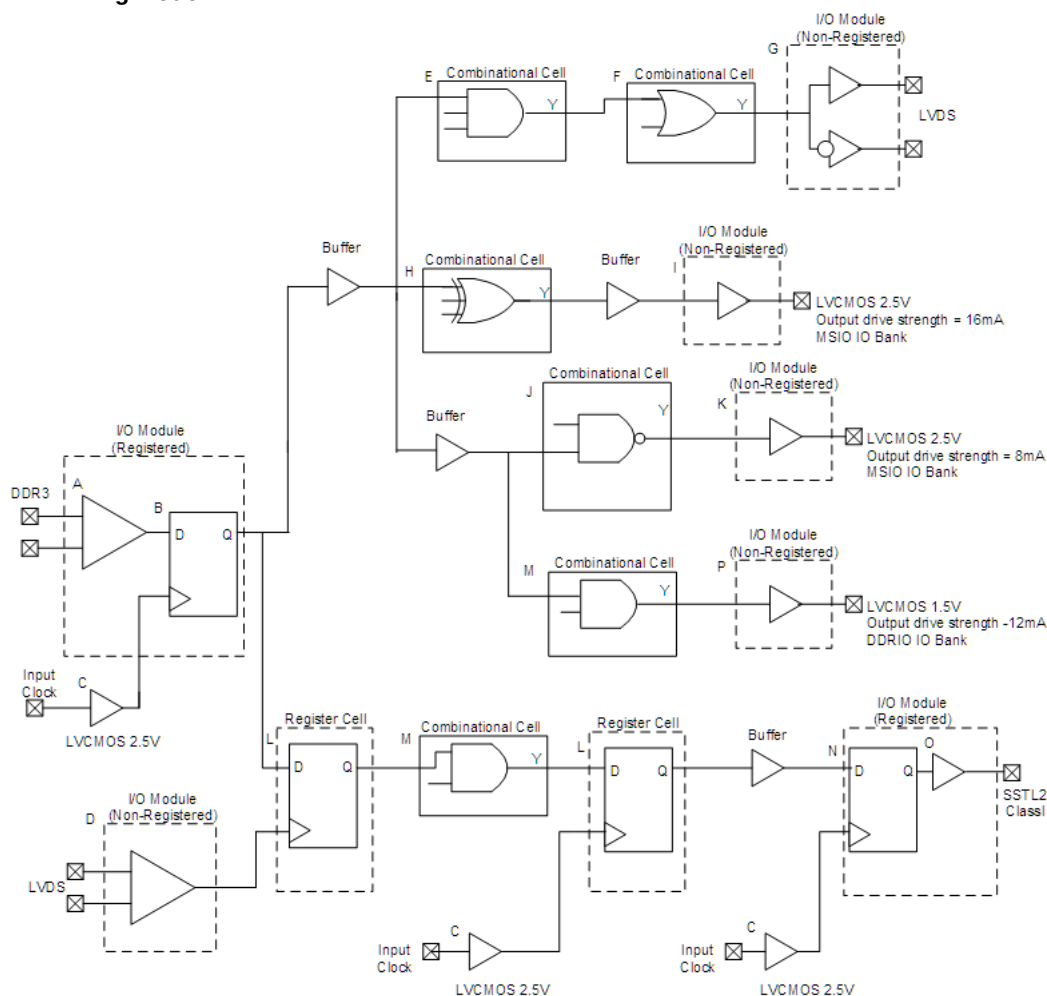
2.3.1.3 ESD Performance

See *RT0001: Microsemi Corporation - SoC Products Reliability Report* for information about ESD.

2.3.4 Timing Model

This section describes timing model and timing parameters.

Figure 2 • Timing Model



The following table lists the timing model parameters in worst commercial-case conditions when $T_J = 85^\circ\text{C}$, $V_{DD} = 1.14\text{ V}$.

Table 17 • Timing Model Parameters

Index	Symbol	Description	-1	Unit	For More Information
A	T_{PY}	Propagation delay of DDR3 receiver	1.605	ns	See Table 137 , page 50
B	T_{ICLKQ}	Clock-to-Q of the input data register	0.16	ns	See Table 221 , page 71
	T_{ISUD}	Setup time of the input data register	0.357	ns	See Table 221 , page 71
C	T_{RCKH}	Input high delay for global clock	1.53	ns	See Table 227 , page 78
	T_{RCKL}	Input low delay for global clock	0.897	ns	See Table 227 , page 78
D	T_{PY}	Input propagation delay of LVDS receiver	2.774	ns	See Table 167 , page 56
E	T_{DP}	Propagation delay of a three-input AND gate	0.198	ns	See Table 223 , page 76

Table 43 • LVCMOS 2.5 V AC Test Parameter Specifications

Parameter	Symbol	Typ	Unit
Measuring/trip point for data path	V_{TRIP}	1.2	V
Resistance for enable path (T_{ZH} , T_{ZL} , T_{HZ} , T_{LZ})	R_{ENT}	2K	$\Omega\sigma$
Capacitive loading for enable path (T_{ZH} , T_{ZL} , T_{HZ} , T_{LZ})	C_{ENT}	5	pF
Capacitive loading for data path (T_{DP})	C_{LOAD}	5	pF

Table 44 • LVCMOS 2.5 V Transmitter Drive Strength Specifications

Output Drive Selection			VOH (V)	VOL (V)	IOH (at VOH) mA	IOL (at VOL) mA
MSIO I/O Bank	MSIOD I/O Bank	DDRIO I/O Bank (With Software Default Fixed Code)	Min	Max		
2 mA	2 mA	2 mA	$V_{DDI} - 0.4$	0.4	2	2
4 mA	4 mA	4 mA	$V_{DDI} - 0.4$	0.4	4	4
6 mA	6 mA	6 mA	$V_{DDI} - 0.4$	0.4	6	6
8 mA	8 mA	8 mA	$V_{DDI} - 0.4$	0.4	8	8
12 mA	12 mA	12 mA	$V_{DDI} - 0.4$	0.4	12	12
16 mA		16 mA	$V_{DDI} - 0.4$	0.4	16	16

Note: For board design considerations, output slew rates extraction, detailed output buffer resistances, and I/V Curve, use the corresponding IBIS models located at:
www.microsemi.com/soc/download/ibis/default.aspx.

AC Switching Characteristics

Worst commercial-case conditions: $T_J = 85^\circ\text{C}$, $V_{DD} = 1.14\text{ V}$, $V_{DDI} = 2.375\text{ V}$

Table 45 • LVCMOS 2.5 V Receiver Characteristics (Input Buffers)

	On-Die Termination (ODT)	T_{PY}		T_{PYS}		Unit
		-1	-Std	-1	-Std	
LVCMOS 2.5 V (for DDRIO I/O bank)	None	1.823	2.145	1.932	2.274	ns
LVCMOS 2.5 V (for MSIO I/O bank)	None	2.486	2.925	2.495	2.935	ns
LVCMOS 2.5 V (for MSIOD I/O bank)	None	2.29	2.694	2.305	2.712	ns

Table 46 • LVCMOS 2.5 V Transmitter Characteristics for DDRIO Bank (Output and Tristate Buffers)

Output Drive Selection	Slew Control	T_{DP}		T_{ZL}		T_{ZH}		T_{HZ}^1		T_{LZ}^1		Unit
		-1	-Std	-1	-Std	-1	-Std	-1	-Std	-1	-Std	
2 mA	Slow	3.657	4.302	3.393	3.991	3.675	4.323	3.894	4.582	3.552	4.18	ns
	Medium	3.374	3.97	3.139	3.693	3.396	3.995	3.635	4.277	3.253	3.828	ns
	Medium fast	3.239	3.811	3.036	3.572	3.261	3.836	3.519	4.141	3.128	3.681	ns
	Fast	3.224	3.793	3.029	3.563	3.246	3.818	3.512	4.132	3.119	3.67	ns

Table 62 • LVCMOS 1.5 V DC Output Voltage Specification

Parameter	Symbol	Min	Max	Unit
DC output logic high	VOH	$V_{DDI} \times 0.75$		V
DC output logic low	VOL		$V_{DDI} \times 0.25$	V

Table 63 • LVCMOS 1.5 V AC Minimum and Maximum Switching Speed

Parameter	Symbol	Max	Unit	Conditions
Maximum data rate (for DDRIO I/O bank)	D _{MAX}	235	Mbps	AC loading: 17 pF load, maximum drive/slew
Maximum data rate (for MSIO I/O bank)	D _{MAX}	160	Mbps	AC loading: 17 pF load, maximum drive/slew
Maximum data rate (for MSIOD I/O bank)	D _{MAX}	220	Mbps	AC loading: 17 pF load, maximum drive/slew

Table 64 • LVCMOS 1.5 V AC Calibrated Impedance Option

Parameter	Symbol	Typ	Unit
Supported output driver calibrated impedance (for DDRIO I/O bank)	RODT_CA L	75, 60, 50, 40	Ω

Table 65 • LVCMOS 1.5 V AC Test Parameter Specifications

Parameter	Symbol	Typ	Unit
Measuring/trip point	V _{TRIP}	0.75	V
Resistance for enable path (T _{ZH} , T _{ZL} , T _{HZ} , T _{LZ})	R _{ENT}	2K	Ω
Capacitive loading for enable path (T _{ZH} , T _{ZL} , T _{HZ} , T _{LZ})	C _{ENT}	5	pF
Capacitive loading for data path (T _{DP})	C _{LOAD}	5	pF

Table 66 • LVCMOS 1.5 V Transmitter Drive Strength Specifications

Output Drive Selection			V _{OH} (V)	V _{OL} (V)	IOH (at V _{OH}) mA	IOL (at V _{OL}) mA
MSIO I/O Bank	MSIOD I/O Bank	DDRIO I/O Bank	Min	Max		
2 mA	2 mA	2 mA	$V_{DDI} \times 0.75$	$V_{DDI} \times 0.25$	2	2
4 mA	4 mA	4 mA	$V_{DDI} \times 0.75$	$V_{DDI} \times 0.25$	4	4
6 mA	6 mA	6 mA	$V_{DDI} \times 0.75$	$V_{DDI} \times 0.25$	6	6
8 mA		8 mA	$V_{DDI} \times 0.75$	$V_{DDI} \times 0.25$	8	8
		10 mA	$V_{DDI} \times 0.75$	$V_{DDI} \times 0.25$	10	10
		12 mA	$V_{DDI} \times 0.75$	$V_{DDI} \times 0.25$	12	12

Note: For a detailed I/V curve, use the corresponding IBIS models:

www.microsemi.com/soc/download/ibis/default.aspx.

Table 85 • LVCMOS 1.2 V Transmitter Characteristics for MSIOD I/O Bank (Output and Tristate Buffers)

Output Drive Selection	Slew Control	T _{DP}		T _{ZL}		T _{ZH}		T _{HZ} ¹		T _{LZ} ¹		Unit
		-1	-Std	-1	-Std	-1	-Std	-1	-Std	-1	-Std	
2 mA	Slow	3.883	4.568	4.868	5.726	5.329	6.269	7.994	9.404	7.527	8.855	ns
4 mA	Slow	3.774	4.44	4.188	4.926	4.613	5.426	8.972	10.555	8.315	9.782	ns

1. Delay increases with drive strength are inherent to built-in slew control circuitry for simultaneous switching output (SSO) management.

2.3.5.11 3.3 V PCI/PCIX

Peripheral Component Interface (PCI) for 3.3 V standards specify support for 33 MHz and 66 MHz PCI bus applications.

Minimum and Maximum DC/AC Input and Output Levels Specification (Applicable to MSIO Bank Only)

Table 86 • PCI/PCI-X DC Recommended Operating Conditions

Parameter	Symbol	Min	Typ	Max	Unit
Supply voltage	V _{DDI}	3.15	3.3	3.45	V

Table 87 • PCI/PCI-X DC Input Voltage Specification

Parameter	Symbol	Min	Max	Unit
DC input voltage	V _I	0	3.45	V
Input current high ¹	I _{IH} (DC)			
Input current low ¹	I _{IL} (DC)			

1. See Table 24, page 22.

Table 88 • PCI/PCI-X DC Output Voltage Specification

Parameter	Symbol	Min	Typ	Max	Unit
DC output logic high	V _{OH}		Per PCI specification		V
DC output logic low	V _{OL}		Per PCI specification		V

Table 89 • PCI/PCI-X Minimum and Maximum AC Switching Speed

Parameter	Symbol	Max	Unit	Conditions
Maximum data rate (MSIO I/O bank)	D _{MAX}	630	Mbps	AC Loading: per JEDEC specifications

Table 90 • PCI/PCI-X AC Test Parameter Specifications

Parameter	Symbol	Typ	Unit
Measuring/trip point for data path (falling edge)	V _{TRIP}	0.615 × V _{DDI}	V
Measuring/trip point for data path (rising edge)	V _{TRIP}	0.285 × V _{DDI}	V
Resistance for data test path	RTT_TEST	25	Ω
Resistance for enable path (T _{ZH} , T _{ZL} , T _{HZ} , T _{LZ})	R _{ENT}	2K	Ω
Capacitive loading for enable path (T _{ZH} , T _{ZL} , T _{HZ} , T _{LZ})	C _{ENT}	5	pF
Capacitive loading for data path (T _{DP})	C _{LOAD}	10	pF

Table 118 • DDR1/SSTL2 Class II Transmitter Characteristics for MSIO I/O Bank (Output and Tristate Buffers)

	T_{DP}		T_{ZL}		T_{ZH}		T_{HZ}		T_{LZ}		Unit
	-1	-Std	-1	-Std	-1	-Std	-1	-Std	-1	-Std	
Single-ended	2.29	2.693	1.988	2.338	1.978	2.326	1.989	2.34	1.979	2.328	ns
Differential	2.418	2.846	2.304	2.711	2.297	2.702	2.131	2.506	2.124	2.499	ns

2.3.6.4 Stub-Series Terminated Logic 1.8 V (SSTL18)

SSTL18 Class I and Class II are supported in IGLOO2 and SmartFusion2 SoC FPGAs, and also comply with the reduced and full drive double data rate (DDR2) standard. IGLOO2 and SmartFusion2 SoC FPGA I/Os support both standards for single-ended signaling and differential signaling for SSTL18. This standard requires a differential amplifier input buffer and a push-pull output buffer.

Minimum and Maximum DC/AC Input and Output Levels Specification**Table 119 • SSTL18 DC Recommended DC Operating Conditions**

Parameter	Symbol	Min	Typ	Max	Unit
Supply voltage	V_{DDI}	1.71	1.8	1.89	V
Termination voltage	V_{TT}	0.838	0.900	0.964	V
Input reference voltage	V_{REF}	0.838	0.900	0.964	V

Table 120 • SSTL18 DC Input Voltage Specification

Parameter	Symbol	Min	Max	Unit
DC input logic high	V_{IH} (DC)	$V_{REF} + 0.125$	1.89	V
DC input logic low	V_{IL} (DC)	-0.3	$V_{REF} - 0.125$	V
Input current high ¹	I_{IH} (DC)			
Input current low ¹	I_{IL} (DC)			

1. See Table 24, page 22.

Table 121 • SSTL18 DC Output Voltage Specification

Parameter	Symbol	Min	Max	Unit
SSTL18 Class I (DDR2 Reduced Drive)				
DC output logic high	V_{OH}	$V_{TT} + 0.603$		V
DC output logic low	V_{OL}		$V_{TT} - 0.603$	V
Output minimum source DC current (DDRIO I/O bank only)	I_{OH} at V_{OH}	6.5		mA
Output minimum sink current (DDRIO I/O bank only)	I_{OL} at V_{OL}	-6.5		mA
SSTL18 Class II (DDR2 Full Drive)¹				
DC output logic high	V_{OH}	$V_{TT} + 0.603$		V
DC output logic low	V_{OL}		$V_{TT} - 0.603$	V
Output minimum source DC current (DDRIO I/O bank only)	I_{OH} at V_{OH}	13.4		mA
Output minimum sink current (DDRIO I/O bank only)	I_{OL} at V_{OL}	-13.4		mA

1. To meet JEDEC Electrical Compliance, use DDR2 Full Drive Transmitter.

Table 185 • M-LVDS DC Voltage Specification Output Voltage Specification (for MSIO I/O Bank Only)

Parameter	Symbol	Min	Typ	Max	Unit
DC output logic high	V_{OH}	1.25	1.425	1.6	V
DC output logic low	V_{OL}	0.9	1.075	1.25	V

Table 186 • M-LVDS Differential Voltage Specification

Parameter	Symbol	Min	Max	Unit
Differential output voltage swing (for MSIO I/O bank only)	V_{OD}	300	650	mV
Output common mode voltage (for MSIO I/O bank only)	V_{OCM}	0.3	2.1	V
Input common mode voltage	V_{ICM}	0.3	1.2	V
Input differential voltage	V_{ID}	50	2400	mV

Table 187 • M-LVDS Minimum and Maximum AC Switching Speed for MSIO I/O Bank

Parameter	Symbol	Max	Unit	Conditions
Maximum data rate	D_{MAX}	500	Mbps	AC loading: 2 pF / 100 Ω differential load

Table 188 • M-LVDS AC Impedance Specifications

Parameter	Symbol	Typ	Unit
Termination resistance	R_T	50	Ω

Table 189 • M-LVDS AC Test Parameter Specifications

Parameter	Symbol	Typ	Unit
Measuring/trip point for data path	V_{TRIP}	Cross point	V
Resistance for enable path (T_{ZH} , T_{ZL} , T_{HZ} , T_{LZ})	R_{ENT}	2K	Ω
Capacitive loading for enable path (T_{ZH} , T_{ZL} , T_{HZ} , T_{LZ})	C_{ENT}	5	pF

AC Switching Characteristics

Worst commercial-case conditions: $T_J = 85^\circ\text{C}$, $V_{DD} = 1.14\text{ V}$, $V_{DDI} = 2.375\text{ V}$

Table 190 • M-LVDS AC Switching Characteristics for Receiver (for MSIO I/O Bank - Input Buffers)

On-Die Termination (ODT)	T_{PY}		Unit
	-1	-Std	
None	2.738	3.221	ns
100	2.735	3.218	ns

2.3.7.5 RSDS

Reduced Swing Differential Signaling (RSDS) is similar to an LVDS high-speed interface using differential signaling. RSDS has a similar implementation to LVDS devices and is only intended for point-to-point applications.

Minimum and Maximum Input and Output Levels

Table 203 • RSDS Recommended DC Operating Conditions

Parameter	Symbol	Min	Typ	Max	Unit
Supply voltage	V_{DDI}	2.375	2.5	2.625	V

Table 204 • RSDS DC Input Voltage Specification

Parameter	Symbol	Min	Max	Unit
DC input voltage	V_I	0	2.925	V

Table 205 • RSDS DC Output Voltage Specification

Parameter	Symbol	Min	Typ	Max	Unit
DC output logic high	V_{OH}	1.25	1.425	1.6	V
DC output logic low	V_{OL}	0.9	1.075	1.25	V

Table 206 • RSDS Differential Voltage Specification

Parameter	Symbol	Min	Max	Unit
Differential output voltage swing	V_{OD}	100	600	mV
Output common mode voltage	V_{OCM}	0.5	1.5	V
Input common mode voltage	V_{ICM}	0.3	1.5	V
Input differential voltage	V_{ID}	100	600	mV

Table 207 • RSDS Minimum and Maximum AC Switching Speed

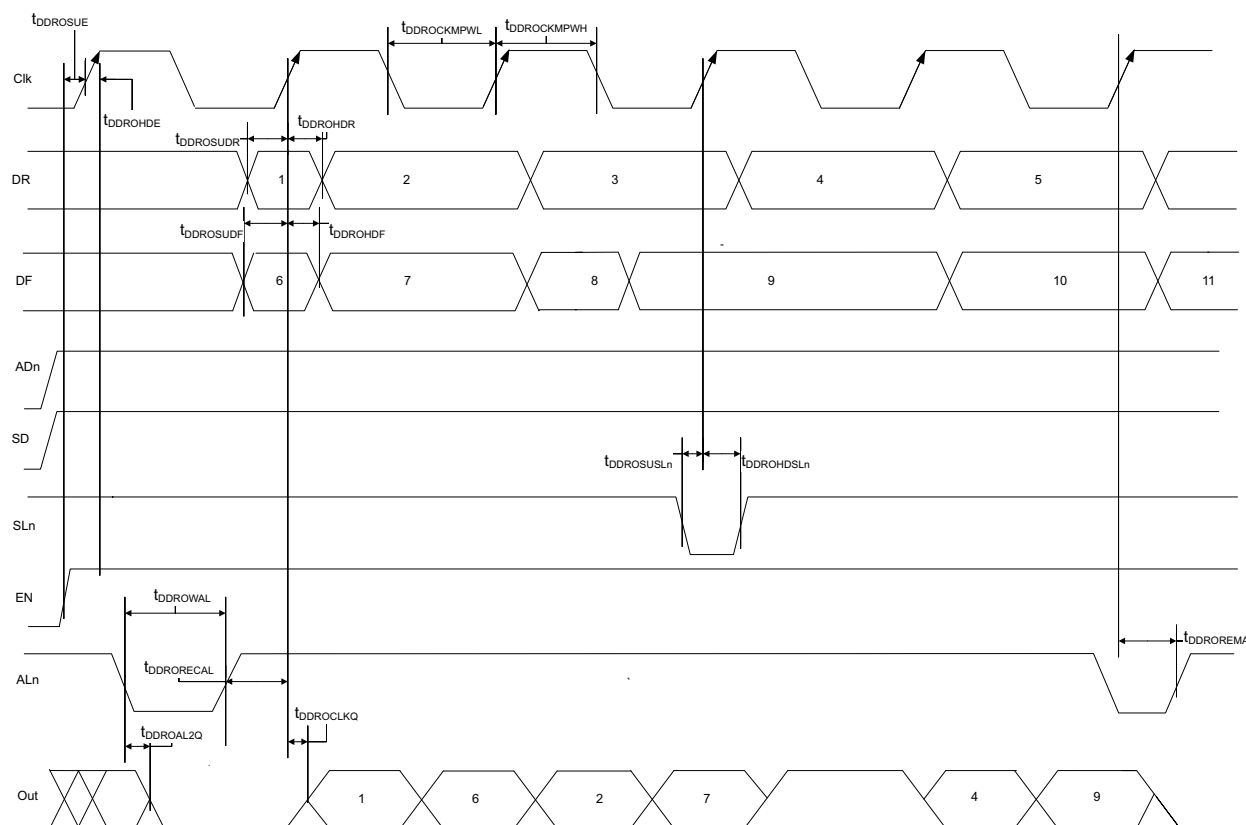
Parameter	Symbol	Max	Unit	Conditions
Maximum data rate (for MSIO I/O bank)	D_{MAX}	520	Mbps	AC loading: 2 pF / 100 Ω differential load
Maximum data rate (for MSIOD I/O bank)	D_{MAX}	700	Mbps	AC loading: 2 pF / 100 Ω differential load

Table 208 • RSDS AC Impedance Specifications

Parameter	Symbol	Typ	Unit
Termination resistance	R_T	100	Ω

Table 209 • RSDS AC Test Parameter Specifications

Parameter	Symbol	Typ	Unit
Measuring/trip point for data path	V_{TRIP}	Cross point	V
Resistance for enable path (T_{ZH} , T_{ZL} , T_{HZ} , T_{LZ})	R_{ENT}	2K	Ω
Capacitive loading for enable path (T_{ZH} , T_{ZL} , T_{HZ} , T_{LZ})	C_{ENT}	5	pF

Figure 13 • Output DDR Timing Diagram**2.3.9.5 Timing Characteristics**

The following table lists the output DDR propagation delays in worst commercial-case conditions when $T_J = 85^\circ\text{C}$, $V_{DD} = 1.14\text{ V}$.

Table 222 • Output DDR Propagation Delays

Symbol	Description	Measuring Nodes (from, to)	-1	-Std	Unit
$T_{DDROCLKQ}$	Clock-to-out of DDR for output DDR	E, G	0.263	0.309	ns
$T_{DDROSUDF}$	Data_F data setup for output DDR	F, E	0.143	0.168	ns
$T_{DDROSUDR}$	Data_R data setup for output DDR	A, E	0.19	0.223	ns
$T_{DDROHDF}$	Data_F data hold for output DDR	F, E	0	0	ns
$T_{DDROHDR}$	Data_R data hold for output DDR	A, E	0	0	ns
$T_{DDROSUE}$	Enable setup for input DDR	B, E	0.419	0.493	ns
T_{DDROHE}	Enable hold for input DDR	B, E	0	0	ns
$T_{DDROSUSLn}$	Synchronous load setup for input DDR	D, E	0.196	0.231	ns
$T_{DDROHSLn}$	Synchronous load hold for input DDR	D, E	0	0	ns
$T_{DDROAL2Q}$	Asynchronous load-to-out for output DDR	C, G	0.528	0.621	ns
$T_{DDRORECAL}$	Asynchronous load removal time for output DDR	C, E	0	0	ns
$T_{DDRORECAL}$	Asynchronous load recovery time for output DDR	C, E	0.034	0.04	ns

2.3.11 Global Resource Characteristics

The IGLOO2 and SmartFusion2 SoC FPGA devices offer a powerful, low skew global routing network which provides an effective clock distribution throughout the FPGA fabric. See [UG0445: IGLOO2 FPGA and SmartFusion2 SoC FPGA Fabric User Guide](#) for the positions of various global routing resources.

The following table lists the 150 device global resources in worst commercial-case conditions when $T_J = 85^\circ\text{C}$, $V_{DD} = 1.14\text{ V}$.

Table 225 • 150 Device Global Resource

Parameter	Symbol	–1		–Std		Unit
		Min	Max	Min	Max	
Input low delay for global clock	T_{RCKL}	0.83	0.911	0.831	0.913	ns
Input high delay for global clock	T_{RCKH}	1.457	1.588	1.715	1.869	ns
Maximum skew for global clock	T_{RCKSW}		0.131		0.154	ns

The following table lists the 090 device global resources in worst commercial-case conditions when $T_J = 85^\circ\text{C}$, $V_{DD} = 1.14\text{ V}$.

Table 226 • 090 Device Global Resource

Parameter	Symbol	–1		–Std		Unit
		Min	Max	Min	Max	
Input low delay for global clock	T_{RCKL}	0.835	0.888	0.833	0.886	ns
Input high delay for global clock	T_{RCKH}	1.405	1.489	1.654	1.752	ns
Maximum skew for global clock	T_{RCKSW}		0.084		0.098	ns

The following table lists the 050 device global resources in worst commercial-case conditions when $T_J = 85^\circ\text{C}$, $V_{DD} = 1.14\text{ V}$.

Table 227 • 050 Device Global Resource

Parameter	Symbol	–1		–Std		Unit
		Min	Max	Min	Max	
Input low delay for global clock	T_{RCKL}	0.827	0.897	0.826	0.896	ns
Input high delay for global clock	T_{RCKH}	1.419	1.53	1.671	1.8	ns
Maximum skew for global clock	T_{RCKSW}		0.111		0.129	ns

The following table lists the 025 device global resources in worst commercial-case conditions when $T_J = 85^\circ\text{C}$, $V_{DD} = 1.14\text{ V}$.

Table 228 • 025 Device Global Resource

Parameter	Symbol	–1		–Std		Unit
		Min	Max	Min	Max	
Input low delay for global clock	T_{RCKL}	0.747	0.799	0.745	0.797	ns
Input high delay for global clock	T_{RCKH}	1.294	1.378	1.522	1.621	ns
Maximum skew for global clock	T_{RCKSW}		0.084		0.099	ns

Table 238 • μ SRAM (RAM64x16) in 64 × 16 Mode (continued)

Parameter	Symbol	–1		–Std		Unit
		Min	Max	Min	Max	
Read synchronous reset hold time	T_{SRSTHD}	0.061		0.071		ns
Write clock period	T_{CCY}	4		4		ns
Write clock minimum pulse width high	$T_{CCLKMPWH}$	1.8		1.8		ns
Write clock minimum pulse width low	$T_{CCLKMPWL}$	1.8		1.8		ns
Write block setup time	T_{BLKCSU}	0.404		0.476		ns
Write block hold time	T_{BLKCHD}	0.007		0.008		ns
Write input data setup time	T_{DINCSU}	0.115		0.135		ns
Write input data hold time	T_{DINCHD}	0.15		0.177		ns
Write address setup time	$T_{ADDRCSU}$	0.088		0.104		ns
Write address hold time	$T_{ADDRCHD}$	0.128		0.15		ns
Write enable setup time	T_{WECSU}	0.397		0.467		ns
Write enable hold time	T_{WECHD}	–0.026		–0.03		ns
Maximum frequency	F_{MAX}		250		250	MHz

The following table lists the μ SRAM in 128 × 9 mode in worst commercial-case conditions when $T_J = 85^\circ\text{C}$, $V_{DD} = 1.14\text{ V}$.

Table 239 • μ SRAM (RAM128x9) in 128 × 9 Mode

Parameter	Symbol	–1		–Std		Unit
		Min	Max	Min	Max	
Read clock period	T_{CY}	4		4		ns
Read clock minimum pulse width high	$T_{CLKMPWH}$	1.8		1.8		ns
Read clock minimum pulse width low	$T_{CLKMPWL}$	1.8		1.8		ns
Read pipeline clock period	T_{PLCY}	4		4		ns
Read pipeline clock minimum pulse width high	$T_{PLCLKMPWH}$	1.8		1.8		ns
Read pipeline clock minimum pulse width low	$T_{PLCLKMPWL}$	1.8		1.8		ns
Read access time with pipeline register	T_{CLK2Q}		0.266		0.313	ns
Read access time without pipeline register			1.677		1.973	ns
Read address setup time in synchronous mode	T_{ADDRSU}	0.301		0.354		ns
Read address setup time in asynchronous mode		1.856		2.184		ns
Read address hold time in synchronous mode	T_{ADDRHD}	0.091		0.107		ns
Read address hold time in asynchronous mode		–0.778		–0.915		ns
Read enable setup time	T_{RDENSU}	0.278		0.327		ns
Read enable hold time	T_{RDENHD}	0.057		0.067		ns
Read block select setup time	T_{BLKSU}	1.839		2.163		ns
Read block select hold time	T_{BLKHD}	–0.65		–0.765		ns
Read block select to out disable time (when pipelined register is disabled)	T_{BLK2Q}		2.036		2.396	ns

Table 240 • μ SRAM (RAM128x8) in 128 × 8 Mode (continued)

Parameter	Symbol	–1		–Std		Unit
		Min	Max	Min	Max	
Read address hold time in synchronous mode	T_{ADDRHD}	0.091		0.107		ns
Read address hold time in asynchronous mode		–0.778		–0.915		ns
Read enable setup time	T_{RDENSU}	0.278		0.327		ns
Read enable hold time	T_{RDENHD}	0.057		0.067		ns
Read block select setup time	T_{BLKSU}	1.839		2.163		ns
Read block select hold time	T_{BLKHD}	–0.65		–0.765		ns
Read block select to out disable time (when pipelined register is disabled)	T_{BLK2Q}		2.036		2.396	ns
Read asynchronous reset removal time (pipelined clock)	T_{RSTREM}	–0.023		–0.027		ns
Read asynchronous reset removal time (non-pipelined clock)		0.046		0.054		ns
Read asynchronous reset recovery time (pipelined clock)	T_{RSTREC}	0.507		0.597		ns
Read asynchronous reset recovery time (non-pipelined clock)		0.236		0.278		ns
Read asynchronous reset to output propagation delay (with pipelined register enabled)	T_{R2Q}		0.835		0.982	ns
Read synchronous reset setup time	T_{SRSTSU}	0.271		0.319		ns
Read synchronous reset hold time	T_{SRSTHD}	0.061		0.071		ns
Write clock period	T_{CCY}	4		4		ns
Write clock minimum pulse width high	$T_{CCLKMPWH}$	1.8		1.8		ns
Write clock minimum pulse width low	$T_{CCLKMPWL}$	1.8		1.8		ns
Write block setup time	T_{BLKCSU}	0.404		0.476		ns
Write block hold time	T_{BLKCHD}	0.007		0.008		ns
Write input data setup time	T_{DINCSU}	0.115		0.135		ns
Write input data hold time	T_{DINCHD}	0.15		0.177		ns
Write address setup time	$T_{ADDRCSU}$	0.088		0.104		ns
Write address hold time	$T_{ADDRCHD}$	0.128		0.15		ns
Write enable setup time	T_{WECSU}	0.397		0.467		ns
Write enable hold time	T_{WECHD}	–0.026		–0.03		ns
Maximum frequency	F_{MAX}		250		250	MHz

The following table lists the μ SRAM in 256×4 mode in worst commercial-case conditions when $T_J = 85^\circ\text{C}$, $V_{DD} = 1.14\text{ V}$.

Table 241 • μ SRAM (RAM256x4) in 256×4 Mode

Parameter	Symbol	-1		-Std		Unit
		Min	Max	Min	Max	
Read clock period	T_{CY}	4		4		ns
Read clock minimum pulse width high	$T_{CLKMPWH}$	1.8		1.8		ns
Read clock minimum pulse width low	$T_{CLKMPWL}$	1.8		1.8		ns
Read pipeline clock period	T_{PLCY}	4		4		ns
Read pipeline clock minimum pulse width high	$T_{PLCLKMPWH}$	1.8		1.8		ns
Read pipeline clock minimum pulse width low	$T_{PLCLKMPWL}$	1.8		1.8		ns
Read access time with pipeline register	T_{CLK2Q}		0.27		0.31	ns
Read access time without pipeline register			1.75		2.06	ns
Read address setup time in synchronous mode	T_{ADDRSU}	0.301		0.354		ns
Read address setup time in asynchronous mode		1.931		2.272		ns
Read address hold time in synchronous mode	T_{ADDRHD}	0.121		0.142		ns
Read address hold time in asynchronous mode		-0.65		-0.76		ns
Read enable setup time	T_{RDENSU}	0.278		0.327		ns
Read enable hold time	T_{RDENHD}	0.057		0.067		ns
Read block select setup time	T_{BLKSU}	1.839		2.163		ns
Read block select hold time	T_{BLKHD}	-0.65		-0.77		ns
Read block select to out disable time (when pipelined register is disabled)	T_{BLK2Q}		2.09		2.46	ns
Read asynchronous reset removal time (pipelined clock)	T_{RSTREM}	-0.02		-0.03		ns
Read asynchronous reset removal time (non-pipelined clock)		0.046		0.054		ns
Read asynchronous reset recovery time (pipelined clock)	T_{RSTREC}	0.507		0.597		ns
Read asynchronous reset recovery time (non-pipelined clock)		0.236		0.278		ns
Read asynchronous reset to output propagation delay (with pipelined register enabled)	T_{R2Q}		0.83		0.98	ns
Read synchronous reset setup time	T_{SRSTSU}	0.271		0.319		ns
Read synchronous reset hold time	T_{SRSTHD}	0.061		0.071		ns
Write clock period	T_{CCY}	4		4		ns
Write clock minimum pulse width high	$T_{CCLKMPWH}$	1.8		1.8		ns
Write clock minimum pulse width low	$T_{CCLKMPWL}$	1.8		1.8		ns
Write block setup time	T_{BLKCSU}	0.404		0.476		ns
Write block hold time	T_{BLKCHD}	0.007		0.008		ns
Write input data setup time	T_{DINCSU}	0.101		0.118		ns
Write input data hold time	T_{DINCHD}	0.137		0.161		ns
Write address setup time	$T_{ADDRCSU}$	0.088		0.104		ns

Table 242 • μ SRAM (RAM512x2) in 512 × 2 Mode (continued)

Parameter	Symbol	–1		–Std		Unit
		Min	Max	Min	Max	
Write clock period	T_{CCY}	4		4		ns
Write clock minimum pulse width high	$T_{CCLKMPWH}$	1.8		1.8		ns
Write clock minimum pulse width low	$T_{CCLKMPWL}$	1.8		1.8		ns
Write block setup time	T_{BLKCSU}	0.404		0.476		ns
Write block hold time	T_{BLKCHD}	0.007		0.008		ns
Write input data setup time	T_{DINCSU}	0.101		0.118		ns
Write input data hold time	T_{DINCHD}	0.137		0.161		ns
Write address setup time	$T_{ADDRCSU}$	0.088		0.104		ns
Write address hold time	$T_{ADDRCHD}$	0.247		0.29		ns
Write enable setup time	T_{WECSU}	0.397		0.467		ns
Write enable hold time	T_{WECHD}	–0.03		–0.03		ns
Maximum frequency	F_{MAX}		250		250	MHz

The following table lists the μ SRAM in 1024 × 1 mode in worst commercial-case conditions when $T_J = 85^\circ\text{C}$, $V_{DD} = 1.14\text{ V}$.

Table 243 • μ SRAM (RAM1024x1) in 1024 × 1 Mode

Parameter	Symbol	–1		–Std		Unit
		Min	Max	Min	Max	
Read clock period	T_{CY}	4		4		ns
Read clock minimum pulse width high	$T_{CLKMPWH}$	1.8		1.8		ns
Read clock minimum pulse width low	$T_{CLKMPWL}$	1.8		1.8		ns
Read pipeline clock period	T_{PLCY}	4		4		ns
Read pipeline clock minimum pulse width high	$T_{PLCLKMPWH}$	1.8		1.8		ns
Read pipeline clock minimum pulse width low	$T_{PLCLKMPWL}$	1.8		1.8		ns
Read access time with pipeline register	T_{CLK2Q}		0.27		0.31	ns
Read access time without pipeline register			1.78		2.1	ns
Read address setup time in synchronous mode	T_{ADDRSU}	0.301		0.354		ns
Read address setup time in asynchronous mode		1.978		2.327		ns
Read address hold time in synchronous mode	T_{ADDRHD}	0.137		0.161		ns
Read address hold time in asynchronous mode		–0.6		–0.71		ns
Read enable setup time	T_{RDENSU}	0.278		0.327		ns
Read enable hold time	T_{RDENHD}	0.057		0.067		ns
Read block select setup time	T_{BLKSU}	1.839		2.163		ns
Read block select hold time	T_{BLKHD}	–0.65		–0.77		ns
Read block select to out disable time (when pipelined register is disabled)	T_{BLK2Q}		2.16		2.54	ns
Read asynchronous reset removal time (pipelined clock)	T_{RSTREM}	–0.02		–0.03		ns
Read asynchronous reset removal time (non-pipelined clock)		0.046		0.054		ns

2.3.14 Math Block Timing Characteristics

The fundamental building block in any digital signal processing algorithm is the multiply-accumulate function. Each IGLOO2 and SmartFusion2 SoC math block supports 18×18 signed multiplication, dot product, and built-in addition, subtraction, and accumulation units to combine multiplication results efficiently. The following table lists the math blocks with all registers used in worst commercial-case conditions when $T_J = 85^\circ\text{C}$, $V_{DD} = 1.14\text{ V}$.

Table 268 • Math Blocks with all Registers Used

Parameter	Symbol	–1		–Std		Unit
		Min	Max	Min	Max	
Input, control register setup time	T_{MISU}	0.149		0.176		ns
Input, control register hold time	T_{MIHD}	1.68		1.976		ns
CDIN input setup time	$T_{MOCDINSU}$	0.185		0.218		ns
CDIN input hold time	$T_{MOCDINHHD}$	0.08		0.094		ns
Synchronous reset/enable setup time	$T_{MSRSTENSU}$	–0.419		–0.493		ns
Synchronous reset/enable hold time	$T_{MSRSTENHD}$	0.011		0.013		ns
Asynchronous reset removal time	$T_{MARSTREM}$	0		0		ns
Asynchronous reset recovery time	$T_{MARSTREC}$	0.088		0.104		ns
Output register clock to out delay	T_{MOCQ}		0.232		0.273	ns
CLK minimum period	T_{MCLKMP}	2.245		2.641		ns

The following table lists the math blocks with input bypassed and output registers used in worst commercial-case conditions when $T_J = 85^\circ\text{C}$, $V_{DD} = 1.14\text{ V}$.

Table 269 • Math Block with Input Bypassed and Output Registers Used

Parameter	Symbol	–1		–Std		Unit
		Min	Max	Min	Max	
Output register setup time	T_{MOSU}	2.294		2.699		ns
Output register hold time	T_{MOHD}	1.68		1.976		ns
CDIN input setup time	$T_{MOCDINSU}$	0.115		0.136		ns
CDIN input hold time	$T_{MOCDINHHD}$	–0.444		–0.522		ns
Synchronous reset/enable setup time	$T_{MSRSTENSU}$	–0.419		–0.493		ns
Synchronous reset/enable hold time	$T_{MSRSTENHD}$	0.011		0.013		ns
Asynchronous reset removal time	$T_{MARSTREM}$	0		0		ns
Asynchronous reset recovery time	$T_{MARSTREC}$	0.014		0.017		ns
Output register clock to out delay	T_{MOCQ}		0.232		0.273	ns
CLK minimum period	T_{MCLKMP}	2.179		2.563		ns

2.3.22 JTAG

Table 284 • JTAG 1532 for 005, 010, 025, and 050 Devices

Parameter	Symbol	005		010		025		050		Unit
		-1	-Std	-1	-Std	-1	-Std	-1	-Std	
Clock to Q (data out)	T_{TCK2Q}	7.47	8.79	7.73	9.09	7.75	9.12	7.89	9.28	ns
Reset to Q (data out)	T_{RSTB2Q}	7.65	9	6.43	7.56	6.13	7.21	7.40	8.70	ns
Test data input setup time	T_{DISU}	-1.05	-0.89	-0.69	-0.59	-0.67	-0.57	-0.30	-0.25	ns
Test data input hold time	T_{DIHD}	2.38	2.8	2.38	2.8	2.42	2.85	2.09	2.45	ns
Test mode select setup time	T_{TMSSU}	-0.73	-0.62	-1.03	-1.21	-1.1	-0.94	0.28	0.33	ns
Test mode select hold time	T_{TMDHD}	1.36	1.6	1.43	1.68	1.93	2.27	0.16	0.19	ns
ResetB removal time	$T_{TRSTREM}$	-0.77	-0.65	-1.08	-0.92	-1.33	-1.13	-0.45	-0.38	ns
ResetB recovery time	$T_{TRSTREC}$	-0.76	-0.65	-1.07	-0.91	-1.34	-1.14	-0.45	-0.38	ns
TCK maximum frequency	F_{TCKMAX}	25	21.25	25	21.25	25	21.25	25.00	21.25	MHz

Table 285 • JTAG 1532 for 060, 090, and 150 Devices

Parameter	Symbol	060		090		150		Unit
		-1	-Std	-1	-Std	-1	-Std	
Clock to Q (data out)	T_{TCK2Q}	8.38	9.86	8.96	10.54	8.66	10.19	ns
Reset to Q (data out)	T_{RSTB2Q}	8.54	10.04	7.75	9.12	8.79	10.34	ns
Test data input setup time	T_{DISU}	-1.18	-1	-1.31	-1.11	-0.96	-0.82	ns
Test data input hold time	T_{DIHD}	2.52	2.97	2.68	3.15	2.57	3.02	ns
Test mode select setup time	T_{TMSSU}	-0.97	-0.83	-1.02	-0.87	-0.53	-0.45	ns
Test mode select hold time	T_{TMDHD}	1.7	2	1.67	1.96	1.02	1.2	ns
ResetB removal time	$T_{TRSTREM}$	-1.21	-1.03	-0.76	-0.65	-1.03	-0.88	ns
ResetB recovery time	$T_{TRSTREC}$	-1.21	-1.03	-0.77	-0.65	-1.03	-0.88	ns
TCK maximum frequency	F_{TCKMAX}	25	21.25	25	21.25	25	21.25	MHz

2.3.23 System Controller SPI Characteristics