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What is "[Embedded - Microcontrollers](#)"?

"[Embedded - Microcontrollers](#)" refer to small, integrated circuits designed to perform specific tasks within larger systems. These microcontrollers are essentially compact computers on a single chip, containing a processor core, memory, and programmable input/output peripherals. They are called "embedded" because they are embedded within electronic devices to control various functions, rather than serving as standalone computers. Microcontrollers are crucial in modern electronics, providing the intelligence and control needed for a wide range of applications.

Applications of "[Embedded - Microcontrollers](#)"

Details

Product Status	Active
Core Processor	M8C
Core Size	8-Bit
Speed	12MHz
Connectivity	I ² C, SPI
Peripherals	LVD, POR, WDT
Number of I/O	28
Program Memory Size	8KB (8K x 8)
Program Memory Type	FLASH
EEPROM Size	-
RAM Size	512 x 8
Voltage - Supply (Vcc/Vdd)	2.4V ~ 5.25V
Data Converters	-
Oscillator Type	Internal
Operating Temperature	-40°C ~ 85°C (TA)
Mounting Type	Surface Mount
Package / Case	32-UFQFN Exposed Pad
Supplier Device Package	32-QFN (5x5)
Purchase URL	https://www.e-xfl.com/product-detail/infineon-technologies/cy8c20424-12lqxi

PSoC® Functional Overview

The PSoC family consists of many programmable system-on-chips with on-chip controller devices. These devices are designed to replace multiple traditional MCU based system components with one, low cost single chip programmable component. A PSoC device includes configurable analog and digital blocks, and programmable interconnect. This architecture enables the user to create customized peripheral configurations, to match the requirements of each individual application. Additionally, a fast CPU, flash program memory, SRAM data memory, and configurable I/O are included in a range of convenient pinouts.

The PSoC architecture for this device family is comprised of three main areas: core, system resources, and CapSense analog system. A common, versatile bus enables connection between I/O and the analog system. Each CY8C20x24 PSoC device includes a dedicated CapSense block that provides sensing and scanning control circuitry for capacitive sensing applications. Depending on the PSoC package, up to 28 GPIOs are also included. The GPIOs provide access to the MCU and analog mux.

PSoC Core

The PSoC core is a powerful engine that supports a rich instruction set. It encompasses SRAM for data storage, an interrupt controller, sleep and watchdog timers, and internal main oscillator (IMO) and internal low-speed oscillator (ILO). The CPU core, called the M8C, is a powerful processor with speeds up to 12 MHz. The M8C is a 2-MIPS, 8-bit Harvard-architecture microprocessor.

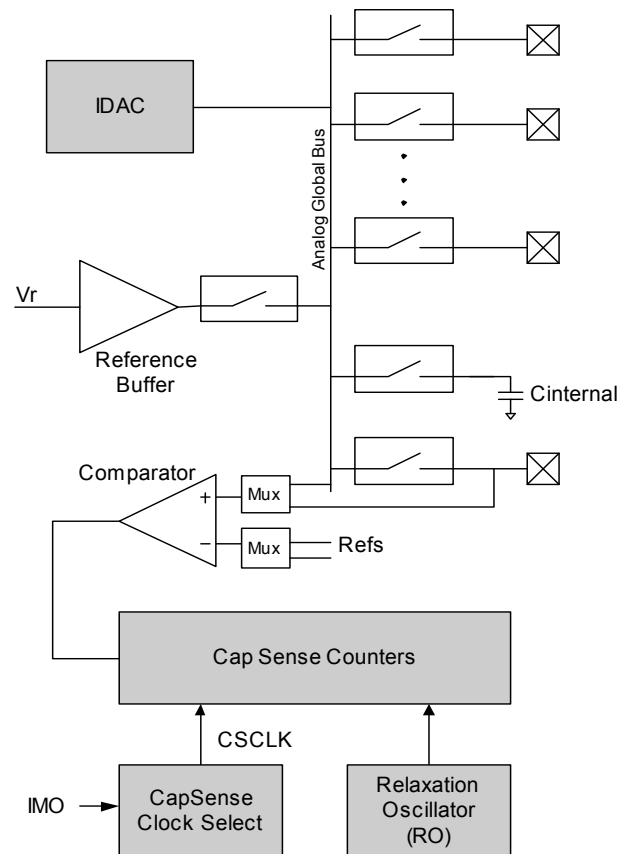
System resources provide additional capability, such as a configurable I²C slave or SPI master-slave communication interface and various system resets supported by the M8C.

The analog system is composed of the CapSense PSoC block and an internal 1.8-V analog reference. Together, they support capacitive sensing of up to 28 inputs.

CapSense Analog System

The analog system contains the capacitive sensing hardware. Several hardware algorithms are supported. This hardware performs capacitive sensing and scanning without requiring external components. Capacitive sensing is configurable on each GPIO pin. Scanning of enabled CapSense pins are completed quickly and easily across multiple ports.

Figure 1. Analog System Block Diagram



Analog Multiplexer System

The analog mux bus connects to every GPIO pin. Pins are connected to the bus individually or in any combination. The bus also connects to the analog system for analysis with the CapSense block comparator.

Switch control logic enables selected pins to precharge continuously under hardware control. This enables capacitive measurement for applications such as touch sensing. The analog multiplexer system in the CY8C20x24 device family is optimized for basic CapSense functionality. It supports sensing of CapSense buttons, proximity sensors, and a single slider. Other multiplexer applications include:

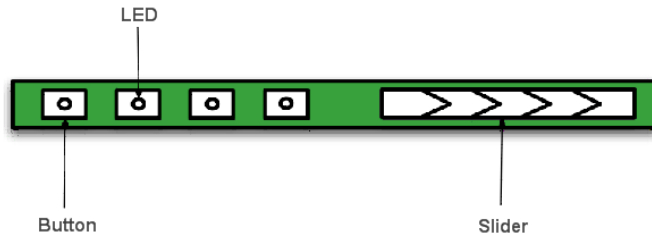
- Capacitive slider interface.
- Chip-wide mux that enables analog input from any I/O pin.
- Crosspoint connection between any I/O pin combinations.

When designing capacitive sensing applications, refer to the latest signal to noise signal level requirements application notes, which are found in <http://www.cypress.com> > Design Resources > Application Notes. In general, and unless otherwise noted in the relevant application notes, the minimum signal-to-noise ratio (SNR) requirement for CapSense applications is 5:1.

Typical Application

Figure 2 illustrates a typical application: CapSense multimedia keys for a notebook computer with a slider, four buttons, and four LEDs.

Figure 2. CapSense Multimedia Button-Board Application



Additional System Resources

System resources, some of which are previously listed, provide additional capability useful to complete systems. Additional resources include low voltage detection (LVD) and power on reset (POR). Brief statements describing the merits of each system resource follow.

- The I²C slave and SPI master-slave module provides 50, 100, or 400 kHz communication over two wires. SPI communication over three or four wires runs at speeds of 46.9 kHz to 3 MHz (lower for a slower system clock).
- LVD interrupts signal the application of falling voltage levels, while the advanced POR circuit eliminates the need for a system supervisor.
- An internal 1.8-V reference provides an absolute reference for capacitive sensing.
- The 5 V maximum input, 3 V fixed output, low dropout regulator (LDO) provides regulation for I/Os. A register controlled bypass mode enables the user to disable the LDO.

Getting Started

This datasheet is an overview of the PSoC integrated circuit and presents specific pin, register, and electrical specifications.

For in depth information, along with detailed programming details, see the PSoC® [Technical Reference Manual](#).

For up-to-date ordering, packaging, and electrical specification information, see the latest [PSoC device datasheets](#) on the web.

Application Notes

[Cypress application notes](#) are an excellent introduction to the wide variety of possible PSoC designs.

Development Kits

[PSoC Development Kits](#) are available online from and through a growing number of regional and global distributors, which include Arrow, Avnet, Digi-Key, Farnell, Future Electronics, and Newark.

Training

[Free PSoC technical training](#) (on demand, webinars, and workshops), which is available online via www.cypress.com, covers a wide variety of topics and skill levels to assist you in your designs.

CYPros Consultants

Certified PSoC consultants offer everything from technical assistance to completed PSoC designs. To contact or become a PSoC consultant go to the [CYPros Consultants](#) web site.

Solutions Library

Visit our growing [library of solution focused designs](#). Here you can find various application designs that include firmware and hardware design files that enable you to complete your designs quickly.

Technical Support

[Technical support](#) – including a searchable Knowledge Base articles and technical forums – is also available online. If you cannot find an answer to your question, call our Technical Support hotline at 1-800-541-4736.

Designing with PSoC Designer

The development process for the PSoC device differs from that of a traditional fixed-function microprocessor. The configurable analog and digital hardware blocks give the PSoC architecture a unique flexibility that pays dividends in managing specification change during development and lowering inventory costs. These configurable resources, called PSoC blocks, have the ability to implement a wide variety of user-selectable functions. The PSoC development process is:

1. Select [user modules](#).
2. Configure user modules.
3. Organize and connect.
4. Generate, verify, and debug.

Select User Modules

PSoC Designer provides a library of prebuilt, pretested hardware peripheral components called “user modules”. User modules make selecting and implementing peripheral devices, both analog and digital, simple.

Configure User Modules

Each user module that you select establishes the basic register settings that implement the selected function. They also provide parameters and properties that allow you to tailor their precise configuration to your particular application. For example, an EzI2Cs User Module configures the I²C block in PSoC. Using these parameters, you can establish the slave address and I²C speed. Configure the parameters and properties to correspond to your chosen application. Enter values directly or by selecting values from drop-down menus. All of the user modules are documented in datasheets that may be viewed directly in PSoC Designer or on the Cypress website. These [user module data sheets](#) explain the internal operation of the user module and provide performance specifications. Each datasheet describes the use of each user module parameter, and other information that you may need to successfully implement your design.

Organize and Connect

Build signal chains at the chip level by interconnecting user modules to each other and the I/O pins. Perform the selection, configuration, and routing so that you have complete control over all on-chip resources.

Generate, Verify, and Debug

When you are ready to test the hardware configuration or move on to developing code for the project, perform the “Generate Configuration Files” step. This causes PSoC Designer to generate source code that automatically configures the device to your specification and provides the software for the system. The generated code provides APIs with high-level functions to control and respond to hardware events at run time, and interrupt service routines that you can adapt as needed.

A complete code development environment allows you to develop and customize your applications in C, assembly language, or both.

The last step in the development process takes place inside PSoC Designer's Debugger (accessed by clicking the Connect icon). PSoC Designer downloads the HEX image to the ICE where it runs at full speed. PSoC Designer debugging capabilities rival those of systems costing many times more. In addition to traditional single-step, run-to-breakpoint, and watch-variable features, the debug interface provides a large trace buffer. It allows you to define complex breakpoint events that include monitoring address and data bus values, memory locations, and external signals

24-pin Part Pinout

Figure 4. CY8C20324 24-pin PSoC Device

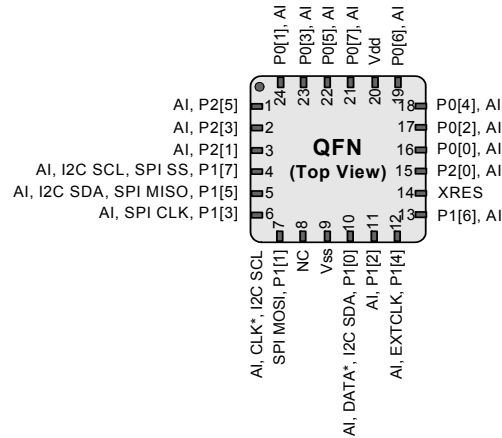


Table 2. 24-pin Part Pinout (QFN ^[2])

Pin No.	Digital	Analog	Name	Description
1	I/O	I	P2[5]	
2	I/O	I	P2[3]	
3	I/O	I	P2[1]	
4	I _{OH}	I	P1[7]	I ² C SCL, SPI SS
5	I _{OH}	I	P1[5]	I ² C SDA, SPI MISO
6	I _{OH}	I	P1[3]	SPI CLK
7	I _{OH}	I	P1[1]	CLK ^[3] , I ² C SCL, SPI MOSI
8			NC	No connection
9	Power		V _{SS}	Ground connection
10	I _{OH}	I	P1[0]	DATA ^[3] , I ² C SDA
11	I _{OH}	I	P1[2]	
12	I _{OH}	I	P1[4]	Optional external clock input (EXTCLK)
13	I _{OH}	I	P1[6]	
14	Input		XRES	Active high external reset with internal pull-down
15	I/O	I	P2[0]	
16	I/O	I	P0[0]	
17	I/O	I	P0[2]	
18	I/O	I	P0[4]	
19	I/O	I	P0[6]	
20	Power		V _{DD}	Supply voltage
21	I/O	I	P0[7]	
22	I/O	I	P0[5]	
23	I/O	I	P0[3]	Integrating input
24	I/O	I	P0[1]	Integrating input
CP	Power		V _{SS}	Center pad is connected to ground

A = Analog, I = Input, O = Output, OH = 5 mA High Output Drive

Notes

- The center pad on the QFN package is connected to ground (V_{SS}) for best mechanical, thermal, and electrical performance. If not connected to ground, it is electrically floated and not connected to any other signal.
- These are the ISSP pins, that are not high Z at POR (Power on reset). Refer the *PSoC Programmable System-on-Chip Technical Reference Manual* for details.

28-pin Part Pinout

Figure 5. CY8C20524 28-pin PSoC Device

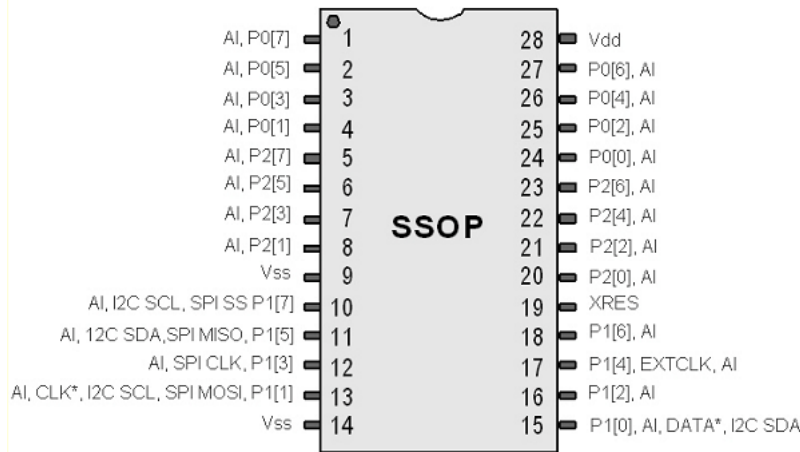


Table 3. 28-pin Part Pinout (SSOP)

Pin No.	Digital	Analog	Name	Description
1	I/O	I	P0[7]	
2	I/O	I	P0[5]	
3	I/O	I	P0[3]	Integrating input
4	I/O	I	P0[1]	Integrating input
5	I/O	I	P2[7]	
6	I/O	I	P2[5]	
7	I/O	I	P2[3]	
8	I/O	I	P2[1]	
9	Power		V _{SS}	Ground connection
10	I _{OH}	I	P1[7]	I ² C SCL, SPI SS
11	I _{OH}	I	P1[5]	I ² C SDA, SPI MISO
12	I _{OH}	I	P1[3]	SPI CLK
13	I _{OH}	I	P1[1]	CLK ^[4] , I ² C SCL, SPL MOSI
14	Power		V _{SS}	Ground connection
15	I _{OH}	I	P1[0]	Data ^[4] , I ² C SDA
16	I _{OH}	I	P1[2]	
17	I _{OH}	I	P1[4]	Optional external clock input (EXTCLK)
18	I _{OH}	I	P1[6]	
19	Input		XRES	Active high external reset with internal pull-down
20	I/O	I	P2[0]	
21	I/O	I	P2[2]	
22	I/O	I	P2[4]	
23	I/O	I	P2[6]	
24	I/O	I	P0[0]	
25	I/O	I	P0[2]	
26	I/O	I	P0[4]	
27	I/O	I	P0[6]	
28	Power		V _{DD}	Supply voltage

A = Analog, I = Input, O = Output, OH = 5 mA High Output Drive

Note

4. These are the ISSP pins, that are not high Z at POR (Power on reset). Refer the *PSoC Programmable System-on-Chip Technical Reference Manual* for details.

32-pin Part Pinout

Figure 6. CY8C20424 32-pin PSoC Device

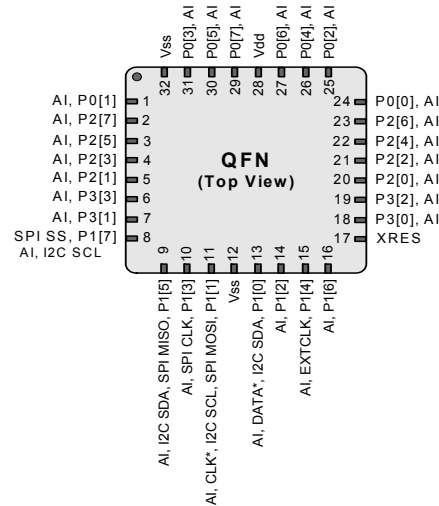


Table 4. 32-pin Part Pinout (QFN ^[5])

Pin No.	Digital	Analog	Name	Description
1	I/O	I	P0[1]	Integrating Input
2	I/O	I	P2[7]	
3	I/O	I	P2[5]	
4	I/O	I	P2[3]	
5	I/O	I	P2[1]	
6	I/O	I	P3[3]	
7	I/O	I	P3[1]	
8	I _{OH}	I	P1[7]	I ² C SCL, SPI SS
9	I _{OH}	I	P1[5]	I ² C SDA, SPI MISO
10	I _{OH}	I	P1[3]	SPI CLK
11	I _{OH}	I	P1[1]	CLK ^[6] , I ² C SCL, SPI MOSI
12	Power		V _{SS}	Ground connection
13	I _{OH}	I	P1[0]	DATA ^[6] , I ² C SDA
14	I _{OH}	I	P1[2]	
15	I _{OH}	I	P1[4]	Optional external clock input (EXTCLK)
16	I _{OH}	I	P1[6]	
17	Input		XRES	Active high external reset with internal pull-down

Notes

- The center pad on the QFN package is connected to ground (V_{SS}) for best mechanical, thermal, and electrical performance. If not connected to ground, it is electrically floated and not connected to any other signal.
- These are the ISSP pins, that are not high Z at POR (Power on reset). Refer the *PSoC Programmable System-on-Chip Technical Reference Manual* for details.

48-pin OCD Part Pinout

The 48-pin QFN part table and pin diagram is for the CY8C20024 On-Chip Debug (OCD) PSoC device. This part is only used for in-circuit debugging. **It is NOT available for production.**

Figure 7. CY8C20024 OCD PSoC Device

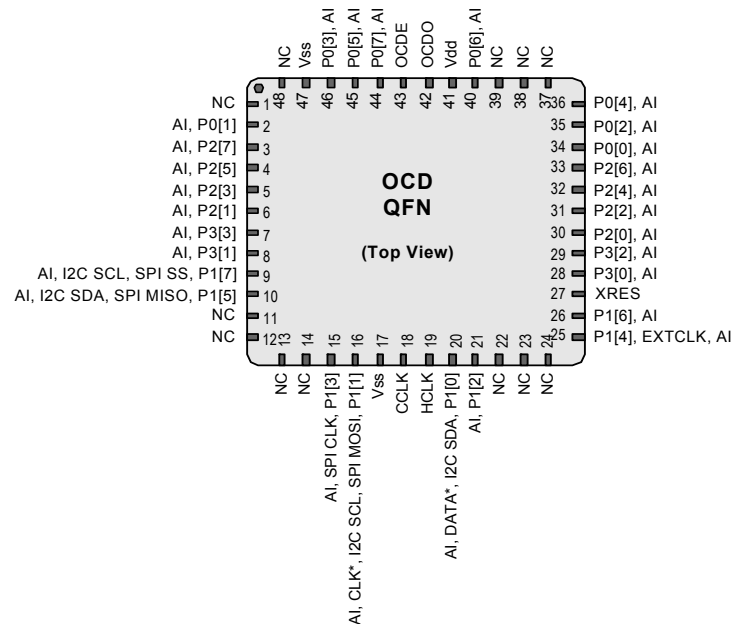


Table 5. 48-pin OCD Part Pinout (QFN^[7])

Pin No.	Digital	Analog	Name	Description
1			NC	No connection
2	I/O	I	P0[1]	Integrating Input
3	I/O	I	P2[7]	
4	I/O	I	P2[5]	
5	I/O	I	P2[3]	
6	I/O	I	P2[1]	
7	I/O	I	P3[3]	
8	I/O	I	P3[1]	
9	I _{OH}	I	P1[7]	I ² C SCL, SPI SS
10	I _{OH}	I	P1[5]	I ² C SDA, SPI MISO
11			NC	No connection
12			NC	No connection
13			NC	No connection
14			NC	No connection
15	I _{OH}	I	P1[3]	SPI CLK
16	I _{OH}	I	P1[1]	CLK ^[8] , I ² C SCL, SPI MOSI
17	Power		Vss	Ground connection
18			CCLK	OCD CPU clock output
19			HCLK	OCD high speed clock output
20	I _{OH}	I	P1[0]	DATA ^[8] , I ² C SDA

Notes

7. The center pad on the QFN package is connected to ground (V_{SS}) for best mechanical, thermal, and electrical performance. If not connected to ground, it is electrically floated and not connected to any other signal.

8. These are the ISSP pins, that are not high Z at POR (Power on reset). Refer the *PSoC Programmable System-on-Chip Technical Reference Manual* for details.

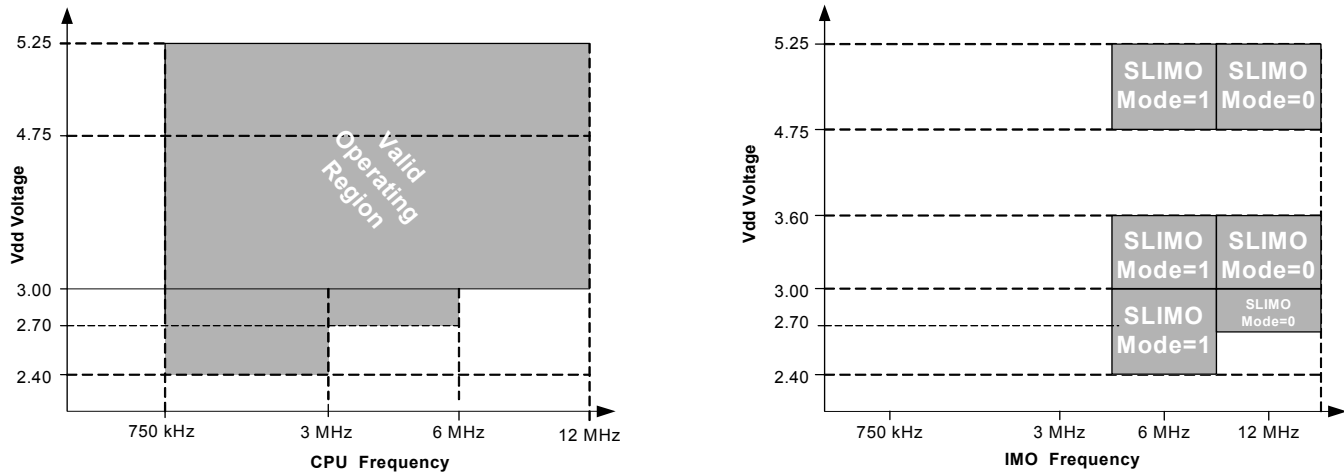
Electrical Specifications

This section presents the DC and AC electrical specifications of the CY8C20224, CY8C20324, CY8C20424, and CY8C20524 PSoC devices. For the latest electrical specifications, visit the web at <http://www.cypress.com/psoc>.

Specifications are valid for $-40^{\circ}\text{C} \leq T_A \leq 85^{\circ}\text{C}$ and $T_J \leq 100^{\circ}\text{C}$ as specified, except where noted.

Refer to [Table 16 on page 19](#) for the electrical specifications on the internal main oscillator (IMO) using SLIMO mode.

Figure 8. Voltage versus CPU Frequency and IMO Frequency Trim Options



Absolute Maximum Ratings

Table 6. Absolute Maximum Ratings

Symbol	Description	Min	Typ	Max	Units	Notes
T_{STG}	Storage temperature	-55	25	+100	$^{\circ}\text{C}$	Higher storage temperatures reduces data retention time. Recommended storage temperature is $+25^{\circ}\text{C} \pm 25^{\circ}\text{C}$. Extended duration storage temperatures above 65°C degrades reliability.
T_A	Ambient temperature with power applied	-40	—	+85	$^{\circ}\text{C}$	
V_{DD}	Supply voltage on V_{DD} relative to V_{SS}	-0.5	—	+6.0	V	
V_{IO}	DC input voltage	$V_{SS} - 0.5$	—	$V_{DD} + 0.5$	V	
V_{IOZ}	DC voltage applied to tri-state	$V_{SS} - 0.5$	—	$V_{DD} + 0.5$	V	
I_{MIO}	Maximum current into any port pin	-25	—	+50	mA	
ESD	Electrostatic discharge voltage	2000	—	—	V	Human Body Model ESD.
LU	Latch-up current	—	—	200	mA	

Operating Temperature

Table 7. Operating Temperature

Symbol	Description	Min	Typ	Max	Units	Notes
T_A	Ambient temperature	-40	—	+85	$^{\circ}\text{C}$	
T_J	Junction temperature	-40	—	+100	$^{\circ}\text{C}$	The temperature rise from ambient to junction is package specific. See Table 31 on page 30 . The user must limit the power consumption to comply with this requirement.

Table 17. 2.7 V AC Chip Level Specifications

Symbol	Description	Min	Typ	Max	Units	Notes
F _{CPU1A}	CPU frequency (2.7 V nominal)	0.75	–	3.25	MHz	2.4 V < V _{DD} < 3.0 V.
F _{CPU1B}	CPU frequency (2.7 V minimum)	0.75	–	6.3	MHz	2.7 V < V _{DD} < 3.0 V.
F _{32K1}	ILO frequency	8	32	96	kHz	
F _{32K_U}	ILO untrimmed frequency	5	–	–	kHz	After a reset and before the M8C starts to run, the ILO is not trimmed. See the System Resets section of the PSoC Technical Reference Manual for details on this timing.
F _{IMO12}	IMO stability for 12 MHz (Commercial temperature) ^[17]	11.0	12	12.9	MHz	Trimmed for 2.7 V operation using factory trim values. See Figure 8 on page 14 , SLIMO Mode = 0.
F _{IMO6}	IMO stability for 6 MHz (Commercial temperature)	5.5	6.0	6.5	MHz	Trimmed for 2.7 V operation using factory trim values. See Figure 8 on page 14 , SLIMO Mode = 1.
DC _{IMO}	Duty cycle of IMO	40	50	60	%	
DC _{ILO}	ILO duty cycle	20	50	80	%	
t _{RAMP}	Supply ramp time	0	–	–	μs	
t _{XRST}	External reset pulse width	10	–	–	μs	
t _{POWERUP}		–	16	100	ms	Power-up from 0 V. See the System Resets section of the PSoC Technical Reference Manual .
t _{jitter_IMO} ^[18]	12 MHz IMO cycle-to-cycle jitter (RMS)	–	500	900	ps	
	12 MHz IMO long term N cycle-to-cycle jitter (RMS)	–	800	1400	ps	N = 32
	12 MHz IMO period jitter (RMS)	–	300	500	ps	

Notes

17. 0 °C to 70 °C ambient, V_{DD} = 3.3 V.

18. Refer to Cypress Jitter Specifications application note, [Understanding Datasheet Jitter Specifications for Cypress Timing Products - AN5054](#) for more information.

AC GPIO Specifications

Table 18 and Table 19 list the guaranteed maximum and minimum specifications for the voltage and temperature ranges: 4.75 V to 5.25 V and $-40^{\circ}\text{C} \leq T_A \leq 85^{\circ}\text{C}$, 3.0 V to 3.6 V and $-40^{\circ}\text{C} \leq T_A \leq 85^{\circ}\text{C}$, or 2.4 V to 3.0 V and $-40^{\circ}\text{C} \leq T_A \leq 85^{\circ}\text{C}$ respectively. Typical parameters apply to 5 V, 3.3 V, or 2.7 V at 25 °C. These are for design guidance only.

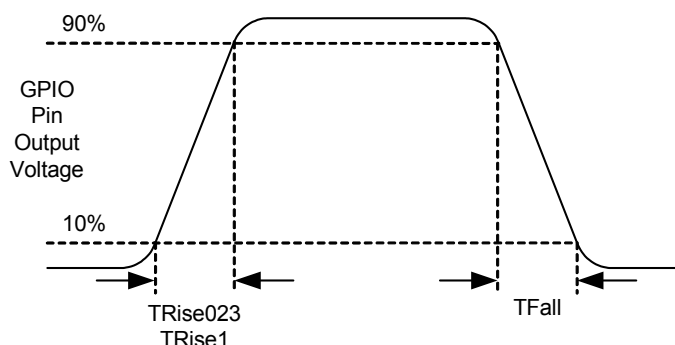
Table 18. 5 V and 3.3 V AC GPIO Specifications

Symbol	Description	Min	Typ	Max	Units	Notes
F_{GPIO}	GPIO operating frequency	0	—	6	MHz	Normal strong mode, Port 1.
t_{Rise023}	Rise time, strong mode, Load = 50 pF, ports 0, 2, 3	15	—	80	ns	$V_{\text{DD}} = 3.0 \text{ V to } 3.6 \text{ V and } 4.75 \text{ V to } 5.25 \text{ V, } 10\% \text{ to } 90\%$
t_{Rise1}	Rise time, strong mode, Load = 50 pF, port 1	10	—	50	ns	$V_{\text{DD}} = 3.0 \text{ V to } 3.6 \text{ V, } 10\% \text{ to } 90\%$
t_{Fall}	Fall time, strong mode, Load = 50 pF, all ports	10	—	50	ns	$V_{\text{DD}} = 3.0 \text{ V to } 3.6 \text{ V and } 4.75 \text{ V to } 5.25 \text{ V, } 10\% \text{ to } 90\%$

Table 19. 2.7 V AC GPIO Specifications

Symbol	Description	Min	Typ	Max	Units	Notes
F_{GPIO}	GPIO operating frequency	0	—	1.5	MHz	Normal Strong Mode, Port 1.
t_{Rise023}	Rise time, strong mode, Load = 50 pF, ports 0, 2, 3	15	—	100	ns	$V_{\text{DD}} = 2.4 \text{ V to } 3.0 \text{ V, } 10\% \text{ to } 90\%$
t_{Rise1}	Rise time, strong mode, Load = 50 pF, port 1	10	—	70	ns	$V_{\text{DD}} = 2.4 \text{ V to } 3.0 \text{ V, } 10\% \text{ to } 90\%$
t_{Fall}	Fall time, strong mode, Load = 50 pF, all ports	10	—	70	ns	$V_{\text{DD}} = 2.4 \text{ V to } 3.0 \text{ V, } 10\% \text{ to } 90\%$

Figure 9. GPIO Timing Diagram



AC Comparator Specifications

Table 20 lists the guaranteed maximum and minimum specifications for the voltage and temperature ranges: 4.75 V to 5.25 V and $-40^{\circ}\text{C} \leq T_A \leq 85^{\circ}\text{C}$, 3.0 V to 3.6 V and $-40^{\circ}\text{C} \leq T_A \leq 85^{\circ}\text{C}$, or 2.4 V to 3.0 V and $-40^{\circ}\text{C} \leq T_A \leq 85^{\circ}\text{C}$, respectively. Typical parameters apply to 5 V, 3.3 V, or 2.7 V at 25 °C. These are for design guidance only.

Table 20. AC Comparator Specifications

Symbol	Description	Min	Typ	Max	Units	Notes
t_{COMP}	Comparator response time, 50 mV overdrive	—	—	100 200	ns ns	$V_{\text{DD}} \geq 3.0 \text{ V}$ $2.4 \text{ V} < V_{\text{CC}} < 3.0 \text{ V}$

Table 24. 2.7 V AC External Clock Specifications (continued)

Symbol	Description	Min	Typ	Max	Units	Notes
F _{OSCEXT2B}	Frequency with CPU clock divide by 2 or greater (2.7 V minimum)	1.5	–	12.6	MHz	2.7 V < V _{DD} < 3.0 V. If the frequency of the external clock is greater than 3 MHz, the CPU clock divider is set to 2 or greater. In this case, the CPU clock divider ensures that the fifty percent duty cycle requirement is met.
–	High period with CPU clock divide by 1	160	–	5300	ns	
–	Low period with CPU clock divide by 1	160	–	–	ns	
–	Power-up IMO to switch	150	–	–	μs	

AC Programming Specifications

Table 25 lists the guaranteed maximum and minimum specifications for the voltage and temperature ranges: 4.75 V to 5.25 V and $-40^{\circ}\text{C} \leq T_A \leq 85^{\circ}\text{C}$, 3.0 V to 3.6 V and $-40^{\circ}\text{C} \leq T_A \leq 85^{\circ}\text{C}$, or 2.4 V to 3.0 V and $-40^{\circ}\text{C} \leq T_A \leq 85^{\circ}\text{C}$ respectively. Typical parameters apply to 5 V, 3.3 V, or 2.7 V at 25 °C. These are for design guidance only.

Table 25. AC Programming Specifications

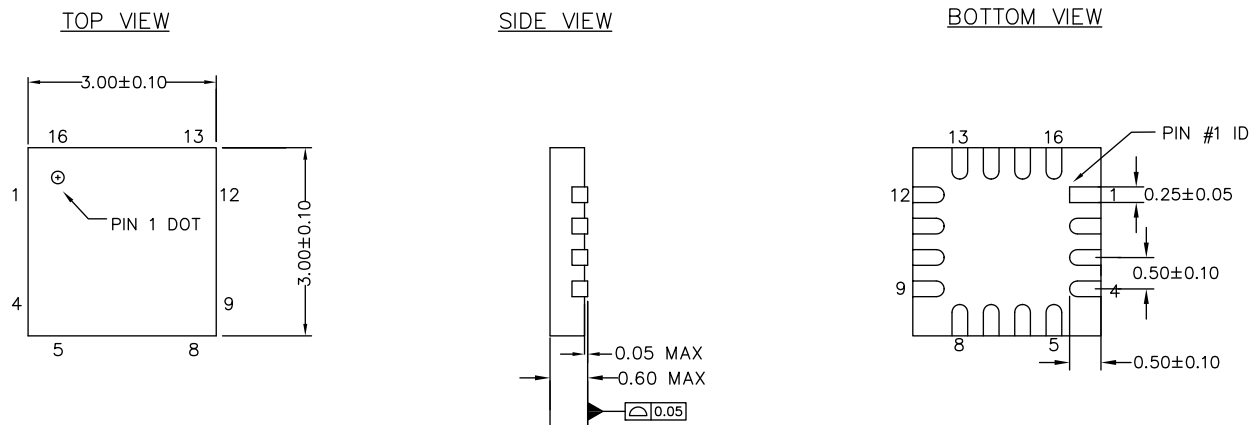
Symbol	Description	Min	Typ	Max	Units	Notes
t _{RSCLK}	Rise time of SCLK	1	–	20	ns	
t _{FSCLK}	Fall time of SCLK	1	–	20	ns	
t _{SSCLK}	Data set up time to falling edge of SCLK	40	–	–	ns	
t _{HSCLK}	Data hold time from falling edge of SCLK	40	–	–	ns	
F _{SCLK}	Frequency of SCLK	0	–	8	MHz	
t _{ERASEB}	Flash erase time (Block)	–	10	–	ms	
t _{WRITE}	Flash block write time	–	40	–	ms	
t _{DSCLK}	Data out delay from falling edge of SCLK	–	–	45	ns	3.6 < V _{DD}
t _{DSCLK3}	Data out delay from falling edge of SCLK	–	–	50	ns	3.0 ≤ V _{DD} ≤ 3.6
t _{DSCLK2}	Data out delay from falling edge of SCLK	–	–	70	ns	2.4 ≤ V _{DD} ≤ 3.0
t _{ERASEALL}	Flash erase time (Bulk)	–	20	–	ms	Erase all blocks and protection fields at once
t _{PROGRAM_HOT}	Flash block erase + Flash block write time	–	–	100	ms	0 °C ≤ T _j ≤ 100 °C
t _{PROGRAM_COLD}	Flash block erase + Flash block write time	–	–	200	ms	–40 °C ≤ T _j ≤ 0 °C

Packaging Dimensions

This section illustrates the packaging specifications for the CY8C20224, CY8C20324, CY8C20424, and CY8C20524 PSoC devices, along with the thermal impedances for each package.

Important Note Emulation tools may require a larger area on the target PCB than the chip's footprint. For a detailed description of the emulation tools' dimensions, refer to the document titled *PSoC Emulator Pod Dimensions* at <http://www.cypress.com/design/MR10161>.

Figure 11. 16-pin Chip On-Lead (3 × 3 × 0.6 mm) (Sawn) Package Outline, 001-09116



NOTES

1. REFERENCE JEDEC # MO-220
2. ALL DIMENSIONS ARE IN MILLIMETERS

001-09116 *J

Thermal Impedances

Table 31. Thermal Impedances Per Package

Package	Typical θ_{JA} ^[20]
16-pin COL	46 °C/W
24-pin QFN ^[21]	25 °C/W
28-pin SSOP	96 °C/W
32-pin QFN ^[21]	27 °C/W
48-pin QFN ^[21]	28 °C/W

Solder Reflow Specifications

Table 32 lists the minimum solder reflow peak temperature to achieve good solderability.

Table 32. Solder Reflow Specifications

Package	Maximum Peak Temperature	Time at Maximum Peak Temperature
16-pin COL	260 °C	30 s
24-pin QFN	260 °C	30 s
28-pin SSOP	260 °C	30 s
32-pin QFN	260 °C	30 s
48-pin QFN	260 °C	30 s

Notes

20. $T_J = T_A + \text{Power} \times \theta_{JA}$.

21. To achieve the thermal impedance specified for the QFN package, the center thermal pad is soldered to the PCB ground plane.

Development Tool Selection

Software

PSoC Designer

At the core of the PSoC development software suite is PSoC Designer. Utilized by thousands of PSoC developers, this robust software has been facilitating PSoC designs for over half a decade. PSoC Designer is available free of charge at <http://www.cypress.com>.

PSoC Programmer

Flexible enough to be used on the bench in development, yet suitable for factory programming, PSoC Programmer works either as a standalone programming application or it can operate directly from PSoC Designer. PSoC Programmer software is compatible with both PSoC ICE-Cube In-Circuit Emulator and PSoC MiniProg. PSoC Programmer is available free of charge at <http://www.cypress.com>.

Development Kits

All development kits are sold at the Cypress Online Store.

CY3215-DK Basic Development Kit

The **CY3215-DK** is for prototyping and development with PSoC Designer. This kit supports in-circuit emulation and the software interface enables users to run, halt, and single step the processor and view the content of specific memory locations. PSoC Designer supports the advance emulation features also. The kit includes:

- PSoC Designer Software CD
- ICE-Cube In-Circuit Emulator
- ICE Flex-Pod for CY8C29x66 Family
- Cat-5 Adapter
- Mini-Eval Programming Board
- 110 ~ 240 V Power Supply, Euro-Plug Adapter
- iMAGEcraft C Compiler (Registration required)
- ISSP Cable
- USB 2.0 Cable and Blue Cat-5 Cable
- Two CY8C29466-24PXI 28-PDIP Chip Samples

Evaluation Tools

All evaluation tools are sold at the Cypress Online Store.

CY3210-MiniProg1

The **CY3210-MiniProg1 kit** enables the user to program PSoC devices via the MiniProg1 programming unit. The MiniProg is a small, compact prototyping programmer that connects to the PC via a provided USB 2.0 cable. The kit includes:

- MiniProg Programming Unit
- MiniEval Socket Programming and Evaluation Board
- 28-pin CY8C29466-24PXI PDIP PSoC Device Sample
- 28-pin CY8C27443-24PXI PDIP PSoC Device Sample
- PSoC Designer Software CD
- Getting Started Guide
- USB 2.0 Cable

CY3210-PSoCEval1

The **CY3210-PSoCEval1 kit** features an evaluation board and the MiniProg1 programming unit. The evaluation board includes an LCD module, potentiometer, LEDs, and plenty of bread-boarding space to meet all of your evaluation needs. The kit includes:

- Evaluation Board with LCD Module
- MiniProg Programming Unit
- 28-pin CY8C29466-24PXI PDIP PSoC Device Sample (2)
- PSoC Designer Software CD
- Getting Started Guide
- USB 2.0 Cable

CY3214-PSoCEvalUSB

The **CY3214-PSoCEvalUSB evaluation kit** features a development board for the CY8C24794-24LFXI PSoC device. Special features of the board include both USB and capacitive sensing development and debugging support. This evaluation board also includes an LCD module, potentiometer, LEDs, an enunciator and plenty of bread boarding space to meet all of your evaluation needs. The kit includes:

- PSoCEvalUSB Board
- LCD Module
- MiniProg Programming Unit
- Mini USB Cable
- PSoC Designer and Example Projects CD
- Getting Started Guide
- Wire Pack

Glossary *(continued)*

block	<ol style="list-style-type: none"> 1. A functional unit that performs a single function, such as an oscillator. 2. A functional unit that may be configured to perform one of several functions, such as a digital PSoC block or an analog PSoC block.
buffer	<ol style="list-style-type: none"> 1. A storage area for data that is used to compensate for a speed difference, when transferring data from one device to another. Usually refers to an area reserved for I/O operations, into which data is read, or from which data is written. 2. A portion of memory set aside to store data, often before it is sent to an external device or as it is received from an external device. 3. An amplifier used to lower the output impedance of a system.
bus	<ol style="list-style-type: none"> 1. A named connection of nets. Bundling nets together in a bus makes it easier to route nets with similar routing patterns. 2. A set of signals performing a common function and carrying similar data. Typically represented using vector notation; for example, address[7:0]. 3. One or more conductors that serve as a common connection for a group of related devices.
clock	The device that generates a periodic signal with a fixed frequency and duty cycle. A clock is sometimes used to synchronize different logic blocks.
comparator	An electronic circuit that produces an output voltage or current whenever two input levels simultaneously satisfy predetermined amplitude requirements.
compiler	A program that translates a high level language, such as C, into machine language.
configuration space	In PSoC devices, the register space accessed when the XIO bit, in the CPU_F register, is set to '1'.
crystal oscillator	An oscillator in which the frequency is controlled by a piezoelectric crystal. Typically a piezoelectric crystal is less sensitive to ambient temperature than other circuit components.
cyclic redundancy check (CRC)	A calculation used to detect errors in data communications, typically performed using a linear feedback shift register. Similar calculations may be used for a variety of other purposes such as data compression.
data bus	A bi-directional set of signals used by a computer to convey information from a memory location to the central processing unit and vice versa. More generally, a set of signals used to convey data between digital functions.
debugger	A hardware and software system that allows you to analyze the operation of the system under development. A debugger usually allows the developer to step through the firmware one step at a time, set break points, and analyze memory.
dead band	A period of time when neither of two or more signals are in their active state or in transition.
digital blocks	The 8-bit logic blocks that can act as a counter, timer, serial receiver, serial transmitter, CRC generator, pseudo-random number generator, or SPI.
digital-to-analog (DAC)	A device that changes a digital signal to an analog signal of corresponding magnitude. The analog-to-digital (ADC) converter performs the reverse operation.
duty cycle	The relationship of a clock period high time to its low time, expressed as a percent.
emulator	Duplicates (provides an emulation of) the functions of one system with a different system, so that the second system appears to behave like the first system.

Glossary (continued)

External Reset (XRES)	An active high signal that is driven into the PSoC device. It causes all operation of the CPU and blocks to stop and return to a pre-defined state.
Flash	An electrically programmable and erasable, non-volatile technology that provides you the programmability and data storage of EPROMs, plus in-system erasability. Non-volatile means that the data is retained when power is OFF.
Flash block	The smallest amount of Flash ROM space that may be programmed at one time and the smallest amount of Flash space that may be protected. A Flash block holds 64 bytes.
frequency	The number of cycles or events per unit of time, for a periodic function.
gain	The ratio of output current, voltage, or power to input current, voltage, or power, respectively. Gain is usually expressed in dB.
I ² C	A two-wire serial computer bus by Philips Semiconductors (now NXP Semiconductors). I ² C is an Inter-Integrated Circuit. It is used to connect low-speed peripherals in an embedded system. The original system was created in the early 1980s as a battery control interface, but it was later used as a simple internal bus system for building control electronics. I ² C uses only two bi-directional pins, clock and data, both running at +5V and pulled high with resistors. The bus operates at 100 kbits/second in standard mode and 400 kbits/second in fast mode.
ICE	The in-circuit emulator that allows you to test the project in a hardware environment, while viewing the debugging device activity in a software environment (PSoC Designer).
input/output (I/O)	A device that introduces data into or extracts data from a system.
interrupt	A suspension of a process, such as the execution of a computer program, caused by an event external to that process, and performed in such a way that the process can be resumed.
interrupt service routine (ISR)	A block of code that normal code execution is diverted to when the M8C receives a hardware interrupt. Many interrupt sources may each exist with its own priority and individual ISR code block. Each ISR code block ends with the RETI instruction, returning the device to the point in the program where it left normal program execution.
jitter	<ol style="list-style-type: none"> 1. A misplacement of the timing of a transition from its ideal position. A typical form of corruption that occurs on serial data streams. 2. The abrupt and unwanted variations of one or more signal characteristics, such as the interval between successive pulses, the amplitude of successive cycles, or the frequency or phase of successive cycles.
low-voltage detect (LVD)	A circuit that senses V_{DD} and provides an interrupt to the system when V_{DD} falls lower than a selected threshold.
M8C	An 8-bit Harvard-architecture microprocessor. The microprocessor coordinates all activity inside a PSoC by interfacing to the Flash, SRAM, and register space.
master device	A device that controls the timing for data exchanges between two devices. Or when devices are cascaded in width, the master device is the one that controls the timing for data exchanges between the cascaded devices and an external interface. The controlled device is called the slave device .
microcontroller	An integrated circuit chip that is designed primarily for control systems and products. In addition to a CPU, a microcontroller typically includes memory, timing circuits, and I/O circuitry. The reason for this is to permit the realization of a controller with a minimal quantity of chips, thus achieving maximal possible miniaturization. This in turn, reduces the volume and the cost of the controller. The microcontroller is normally not used for general-purpose computation as is a microprocessor.
mixed-signal	The reference to a circuit containing both analog and digital techniques and components.

Glossary *(continued)*

modulator	A device that imposes a signal on a carrier.
noise	<ol style="list-style-type: none"> 1. A disturbance that affects a signal and that may distort the information carried by the signal. 2. The random variations of one or more characteristics of any entity such as voltage, current, or data.
oscillator	A circuit that may be crystal controlled and is used to generate a clock frequency.
parity	A technique for testing transmitting data. Typically, a binary digit is added to the data to make the sum of all the digits of the binary data either always even (even parity) or always odd (odd parity).
Phase-locked loop (PLL)	An electronic circuit that controls an oscillator so that it maintains a constant phase angle relative to a reference signal.
pinouts	The pin number assignment: the relation between the logical inputs and outputs of the PSoC device and their physical counterparts in the printed circuit board (PCB) package. Pinouts involve pin numbers as a link between schematic and PCB design (both being computer generated files) and may also involve pin names.
port	A group of pins, usually eight.
Power on reset (POR)	A circuit that forces the PSoC device to reset when the voltage is lower than a pre-set level. This is a type of hardware reset.
PSoC®	Cypress Semiconductor's PSoC® is a registered trademark and Programmable System-on-Chip™ is a trademark of Cypress.
PSoC Designer™	The software for Cypress' Programmable System-on-Chip technology.
pulse width modulator (PWM)	An output in the form of duty cycle which varies as a function of the applied measurand
RAM	An acronym for random access memory. A data-storage device from which data can be read out and new data can be written in.
register	A storage device with a specific capacity, such as a bit or byte.
reset	A means of bringing a system back to a know state. See hardware reset and software reset.
ROM	An acronym for read only memory. A data-storage device from which data can be read out, but new data cannot be written in.
serial	<ol style="list-style-type: none"> 1. Pertaining to a process in which all events occur one after the other. 2. Pertaining to the sequential or consecutive occurrence of two or more related activities in a single device or channel.
settling time	The time it takes for an output signal or value to stabilize after the input has changed from one value to another.
shift register	A memory storage device that sequentially shifts a word either left or right to output a stream of serial data.
slave device	A device that allows another device to control the timing for data exchanges between two devices. Or when devices are cascaded in width, the slave device is the one that allows another device to control the timing of data exchanges between the cascaded devices and an external interface. The controlling device is called the master device.

Document History Page

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Revision	ECN	Orig. of Change	Submission Date	Description of Change
**	1734104	YHW / AESA	See ECN	New parts and document (Revision **).
*A	2542938	RLRM / AESA	07/28/2008	Corrected Ordering Information format. Updated package diagram 001-13937 to Rev *B. Updated to new template.
*B	2610469	SNV / PYRS	11/20/08	Updated V _{OH5} , V _{OH7} , and V _{OH9} specifications.
*C	2634376	DRSW	01/12/09	Changed status from Preliminary to Final. Removed the part number CY3250-20234QFN from the 'CY8C20224-12LKXI' flex-pod kit Changed title from CapSense™ Multimedia PSoC® Mixed-Signal Array to CapSense™ Multimedia PSoC® Programmable System-on-Chip™ Added -12 to the CY8C20524 parts in the Ordering Information table Updated 'Development Tools' and 'Designing with PSoC Designer' sections on pages 4 and 5 Updated 'Development Tools Selection' section on page 30 Changed 16-Pin from QFN to COL
*D	2693024	DPT / PYRS	04/16/2009	Added devices CY8C20424-12LQXI and CY8C20424-12LQXIT in the Ordering Information table Added 32-Pin Sawn QFN package diagram
*E	2717566	DRSW / AESA	06/11/2009	Updated AC Chip-Level, and AC Programming Specifications as follows: Modified FIMO6 (page 19), TWRITE specifications (page 22) Added IOH & IOL (page 16), Flash endurance note (page 18), DCILO (page 19), F32K_U (page 19), TPOWERUP (page 19), TERASEALL (page 22), TPROGRAM_HOT (page 22), and TPROGRAM_COLD (page 22) specifications Added AC SPI Master and Slave Specifications
*F	2899195	CFW / ISW	03/26/2010	Updated Ordering Information. Updated Package Diagrams.
*G	3037121	CFW	09/24/2010	Updated title to read AC Comparator Specifications and also updated table caption to read "AC Comparator Specifications" in the same section. Minor edits. Updated to new template.
*H	3049675	BTK	10/06/2010	Removed AC analog mux bus specifications. Updated Development Tools and Designing with PSoC Designer sections.
*I	3072668	NJF	10/27/10	Added PSoC Device Characteristics table. Added DC I ² C Specifications table. Added F _{32K_U} max limit. Added Tjit_IMO specification, removed existing jitter specifications. Updated Units of Measure, Acronyms, Glossary, and References sections. Updated solder reflow specifications. No specific changed were made to I ² C Timing Diagram. Updated for clearer understanding. Updated to new template.
*J	3112469	ARVM	12/16/10	Updated Ordering Information : Updated part numbers.
*K	3182773	MATT	03/01/11	No technical updates. Completing Sunset Review.

Document History Page *(continued)*

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Revision	ECN	Orig. of Change	Submission Date	Description of Change
*L	3638597	BVI	06/06/2012	<p>Updated Getting Started: Updated description. Updated Application Notes: Updated description. Updated Development Kits: Updated description. Updated Training: Updated description. Updated CYPros Consultants: Updated description. Updated Solutions Library: Updated description. Updated Technical Support: Updated description. Updated AC SPI Specifications: Updated Table 28: Renamed “t_{OUT_HIGH}” as “t_{OUT_H}” in “Symbol” column. Updated Table 29: Removed t_{SCLK} parameter and its details. Added F_{SCLK} parameter and its details. Updated Packaging Dimensions: spec 001-09116 – Changed revision from *E to *F. spec 001-13937 – Changed revision from *C to *D. spec 51-85079 – Changed revision from *D to *E. spec 001-12919 – Changed revision from *B to *C. Updated Solder Reflow Specifications: Updated Table 32: Replaced “Time at Maximum Temperature” with “Time at Maximum Peak Temperature” in column heading and updated details in that column. Updated Development Tool Selection: Updated Software: Updated PSoC Designer: Updated description. Updated PSoC Designer: Updated description. Updated Reference Documents: Removed spec 001-17397 and spec 001-14503 from the list as these specs are obsolete.</p>
*M	4311264	VAIR	03/19/2014	<p>Updated Designing with PSoC Designer: Updated Configure User Modules: Updated description (Replaced references of PWM User Module with EzI2Cs User Module). Updated Packaging Dimensions: spec 001-09116 – Changed revision from *F to *J. spec 001-13937 – Changed revision from *D to *E. spec 001-48913 – Changed revision from *B to *D. spec 001-12919 – Changed revision from *C to *D.</p>
*N	5625819	DCHE	02/09/2017	<p>Updated Packaging Dimensions: spec 001-13937 – Changed revision from *E to *F. spec 51-85079 – Changed revision from *E to *F. Updated to new template. Completing Sunset Review.</p>

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