NXP USA Inc. - XPC8260CVVIHBC Datasheet

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Understanding Embedded - Microprocessors

Embedded microprocessors are specialized computing chips designed to perform specific tasks within an embedded system. Unlike general-purpose microprocessors found in personal computers, embedded microprocessors are tailored for dedicated functions within larger systems, offering optimized performance, efficiency, and reliability. These microprocessors are integral to the operation of countless electronic devices, providing the computational power necessary for controlling processes, handling data, and managing communications.

Applications of Embedded - Microprocessors

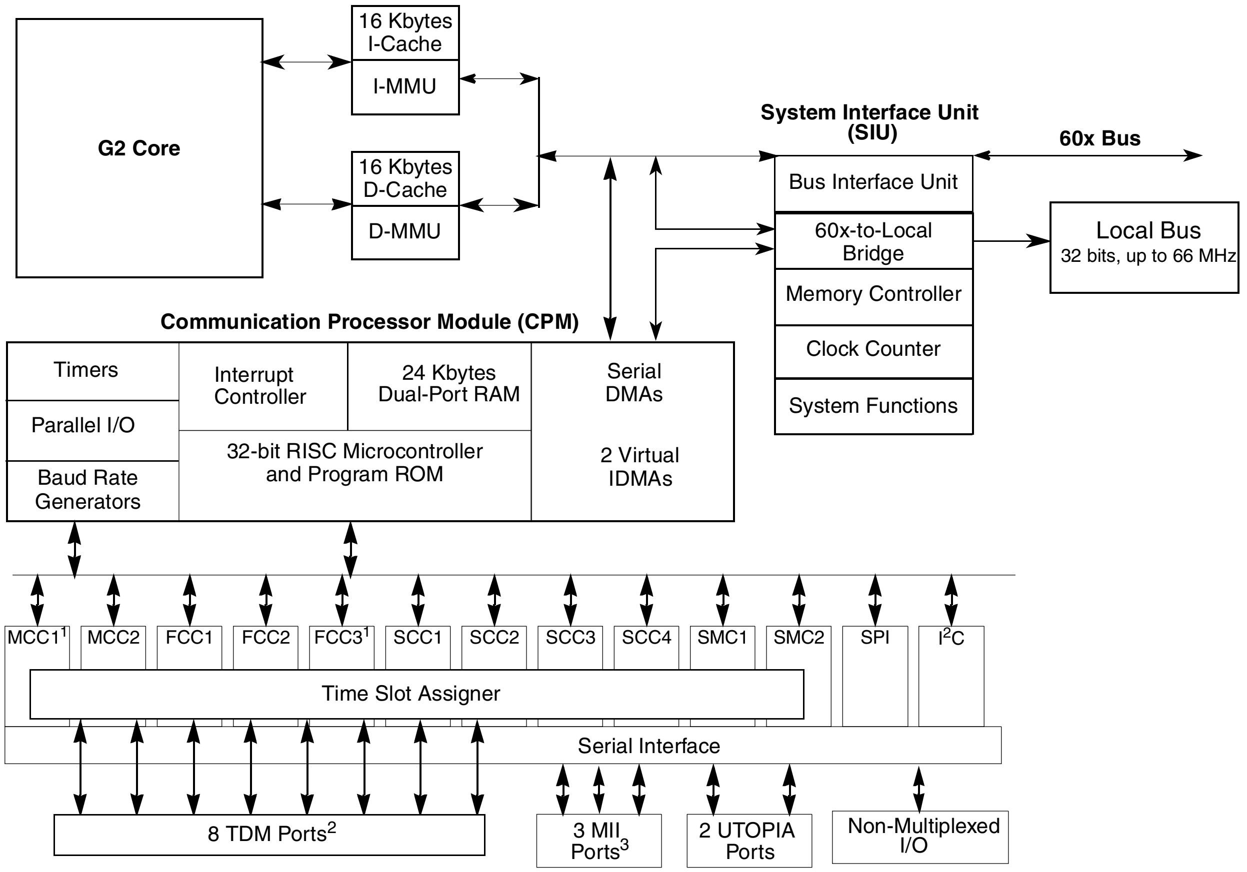
Embedded microprocessors are utilized across a broad spectrum of applications, making them indispensable in

Details	
Product Status	Obsolete
Core Processor	PowerPC G2
Number of Cores/Bus Width	1 Core, 32-Bit
Speed	200MHz
Co-Processors/DSP	Communications; RISC CPM
RAM Controllers	DRAM, SDRAM
Graphics Acceleration	No
Display & Interface Controllers	-
Ethernet	10/100Mbps (3)
SATA	-
USB	-
Voltage - I/O	3.3V
Operating Temperature	-40°C ~ 105°C (TA)
Security Features	-
Package / Case	480-LBGA Exposed Pad
Supplier Device Package	480-TBGA (37.5x37.5)
Purchase URL	https://www.e-xfl.com/product-detail/nxp-semiconductors/xpc8260cvvihbc

Email: info@E-XFL.COM

Address: Room A, 16/F, Full Win Commercial Centre, 573 Nathan Road, Mongkok, Hong Kong

Figure 1 shows the block diagram for the MPC8260.



Notes:
[1] Not on MPC8255
[2] 4 on the MPC8255
[3] 2 on the MPC8255

Figure 1. MPC8260 Block Diagram

1 Features

The major features of the MPC8260 are as follows:

- Dual-issue integer core
  - — A core version of the EC603e microprocessor
  - — System core microprocessor supporting frequencies of 133–200 MHz (150–200 MHz for the MPC8255)
  - — Separate 16-Kbyte data and instruction caches:
    - – Four-way set associative
    - – Physically addressed
    - – LRU replacement algorithm
  - — PowerPC architecture-compliant memory management unit (MMU)

  - Common on-chip processor (COP) test interface
  - High-performance (4.4–5.1 SPEC95 benchmark at 200 MHz; 280 Dhrystones MIPS at 200 MHz)
  - Supports bus snooping for data cache coherency
  - Floating-point unit (FPU)
- Separate power supply for internal logic and for I/O
- Separate PLLs for G2 core and for the CPM
  - G2 core and CPM can run at different frequencies for power/performance optimization
  - Internal core/bus clock multiplier that provides 1.5:1, 2:1, 2.5:1, 3:1, 3.5:1, 4:1, 5:1, 6:1 ratios
  - Internal CPM/bus clock multiplier that provides 2:1, 2.5:1, 3:1, 3.5:1, 4:1, 5:1, 6:1 ratios
- 64-bit data and 32-bit address 60x bus
  - Bus supports multiple master designs
  - Supports single- and four-beat burst transfers
  - 64-, 32-, 16-, and 8-bit port sizes controlled by on-chip memory controller
  - Supports data parity or ECC and address parity
- 32-bit data and 18-bit address local bus
  - Single-master bus, supports external slaves
  - Eight-beat burst transfers
  - 32-, 16-, and 8-bit port sizes controlled by on-chip memory controller
- System interface unit (SIU)
  - Clock synthesizer
  - Reset controller
  - Real-time clock (RTC) register
  - Periodic interrupt timer
  - Hardware bus monitor and software watchdog timer
  - IEEE Std 1149.1™ JTAG test access port
- Twelve-bank memory controller
  - Glueless interface to SRAM, page mode SDRAM, DRAM, EPROM, Flash and other user-definable peripherals
  - Byte write enables and selectable parity generation
  - 32-bit address decodes with programmable bank size
  - Three user programmable machines, general-purpose chip-select machine, and page-mode pipeline SDRAM machine
  - Byte selects for 64 bus width (60x) and byte selects for 32 bus width (local)
  - Dedicated interface logic for SDRAM
- CPU core can be disabled and the device can be used in slave mode to an external core
- Communications processor module (CPM)

- Embedded 32-bit communications processor (CP) uses a RISC architecture for flexible support for communications protocols
- Interfaces to G2 core through on-chip 24-Kbyte dual-port RAM and DMA controller
- Serial DMA channels for receive and transmit on all serial channels
- Parallel I/O registers with open-drain and interrupt capability
- Virtual DMA functionality executing memory-to-memory and memory-to-I/O transfers
- Three fast communications controllers (two on the MPC8255) supporting the following protocols:
  - 10/100-Mbit Ethernet/IEEE Std 802.3™ CDMA/CS interface through media independent interface (MII)
  - ATM—Full-duplex SAR protocols at 155 Mbps, through UTOPIA interface, AAL5, AAL1, AAL0 protocols, TM 4.0 CBR, VBR, UBR, ABR traffic types, up to 16 K external connections
  - Transparent
  - HDLC—Up to T3 rates (clear channel)
- Two multichannel controllers (MCCs) (only MCC2 on the MPC8255)
  - Each MCC handles 128 serial, full-duplex, 64-Kbps data channels. Each MCC can be split into four subgroups of 32 channels each.
  - Almost any combination of subgroups can be multiplexed to single or multiple TDM interfaces up to four TDM interfaces per MCC
- Four serial communications controllers (SCCs) identical to those on the MPC860, supporting the digital portions of the following protocols:
  - Ethernet/IEEE 802.3 CDMA/CS
  - HDLC/SDLC and HDLC bus
  - Universal asynchronous receiver transmitter (UART)
  - Synchronous UART
  - Binary synchronous (BISYNC) communications
  - Transparent
- Two serial management controllers (SMCs), identical to those of the MPC860
  - Provide management for BRI devices as general circuit interface (GCI) controllers in time-division-multiplexed (TDM) channels
  - Transparent
  - UART (low-speed operation)
- One serial peripheral interface identical to the MPC860 SPI
- One inter-integrated circuit (I^2C) controller (identical to the MPC860 I^2C controller)
  - Microwire compatible
  - Multiple-master, single-master, and slave modes

Table 3. DC Electrical Characteristics[1] (continued)

Characteristic	Symbol	Min	Max	Unit
I_{OL} = 5.3mA $\overline{\text{CS}}$[0-9] $\overline{\text{CS}}$(10)/$\overline{\text{BCTL1}}$ $\overline{\text{CS}}$(11)/AP(0) BADDR[27–28] ALE $\overline{\text{BCTL0}}$ $\overline{\text{PWE}}$(0:7)/$\overline{\text{PSDDQM}}$(0:7)/$\overline{\text{PBS}}$(0:7) PSDA10/PGPL0 $\overline{\text{PSDWE}}$/PGPL1 POE/PSDRAS/PGPL2 PSDCAS/PGPL3 PGTA/PUPMWAIT/PGPL4/PPBS PSDAMUX/PGPL5 LWE[0–3]LSDDQM[0:3]/LBS[0–3] LSDA10/LGPL0 LSDWE/LGPL1 LOE/LSDRAS/LGPL2 LSDCAS/LGPL3 LGTA/LUPMWAIT/LGPL4/$\overline{\text{LPBS}}$ LSDAMUX[3]/LGPL5 $\overline{\text{LWR}}$ MODCK1/AP(1)/TC(0)/BNKSEL(0) MODCK2/AP(2)/TC(1)/BNKSEL(1) MODCK3/AP(3)/TC(2)/BNKSEL(2) I_{OL} = 3.2mA L_A14 L_A15/$\overline{\text{SMI}}$ L_A16 L_A17/CKSTP_OUT L_A18 L_A19 L_A20 L_A21 L_A22 L_A23 L_A24 L_A25 L_A26 L_A27 L_A28/$\overline{\text{CORE\_SRESET}}$ L_A29 L_A30 L_A31 LCL_D(0-31) LCL_DP(0-3) PA[0–31] PB[4–31] PC[0–31] PD[4–31] TDO	V_{OL}	—	0.4	V

[1] The default configuration of the CPM pins (PA[0–31], PB[4–31], PC[0–31], PD[4–31]) is input. To prevent excessive DC current, it is recommended to either pull unused pins to GND or VDDH, or to configure them as outputs.

[2] The leakage current is measured for nominal VDD, VCCSYN, and VDD.

2.4 AC Electrical Characteristics

The following sections include illustrations and tables of clock diagrams, signals, and CPM outputs and inputs for the 66 MHz MPC8260 device. Note that AC timings are based on a 50-p*f* load. Typical output buffer impedances are shown in Table 6.

Table 6. Output Buffer Impedances[1]

Output Buffers	Typical Impedance (Ω)
60x bus	40
Local bus	40
Memory controller	40
Parallel I/O	46

Note:

[1] These are typical values at 65° C. The impedance may vary by ±25% with process and temperature.

Table 7 lists CPM output characteristics.

Table 7. AC Characteristics for CPM Outputs[1]

Spec Number		Characteristic	Max Delay (ns)	Min Delay (ns)
Max	Min		66 MHz	66 MHz
sp36a	sp37a	FCC outputs—internal clock (NMSI)	6	1
sp36b	sp37b	FCC outputs—external clock (NMSI)	14	2
sp40	sp41	TDM outputs/SI	25	5
sp38a	sp39a	SCC/SMC/SPI/I2C outputs—internal clock (NMSI)	19	1
sp38b	sp39b	Ex_SCC/SMC/SPI/I2C outputs—external clock (NMSI)	19	2
sp42	sp43	PIO/TIMER/IDMA outputs	14	1

Note:

[1] Output specifications are measured from the 50% level of the rising edge of CLKIN to the 50% level of the signal. Timings are measured at the pin.

Table 8 lists CPM input characteristics.

NOTE: Rise/Fall Time on CPM Input Pins

It is recommended that the rise/fall time on CPM input pins should not exceed 5 ns. This should be enforced especially on clock signals. Rise time refers to signal transitions from 10% to 90% of VCC; fall time refers to transitions from 90% to 10% of VCC.

Table 8. AC Characteristics for CPM Inputs[1]

Spec Number		Characteristic	Setup (ns)	Hold (ns)
Setup	Hold		66 MHz	66 MHz
sp16a	sp17a	FCC inputs—internal clock (NMSI)	10	0
sp16b	sp17b	FCC inputs—external clock (NMSI)	3	3
sp20	sp21	TDM inputs/SI	15	12
sp18a	sp19a	SCC/SMC/SPI/I2C inputs—internal clock (NMSI)	20	0
sp18b	sp19b	SCC/SMC/SPI/I2C inputs—external clock (NMSI)	5	5
sp22	sp23	PIO/TIMER/IDMA inputs	10	3

Note:

[1] Input specifications are measured from the 50% level of the signal to the 50% level of the rising edge of CLKIN. Timings are measured at the pin.

Note that although the specifications generally reference the rising edge of the clock, the following AC timing diagrams also apply when the falling edge is the active edge.

Figure 3 shows the FCC external clock.

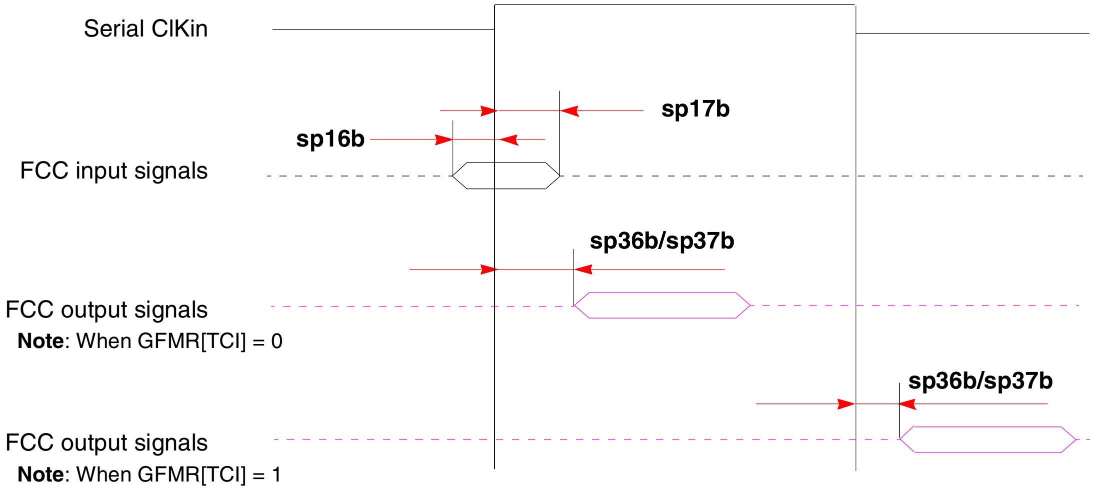


Figure 3. FCC External Clock Diagram

Figure 4 shows the FCC internal clock.

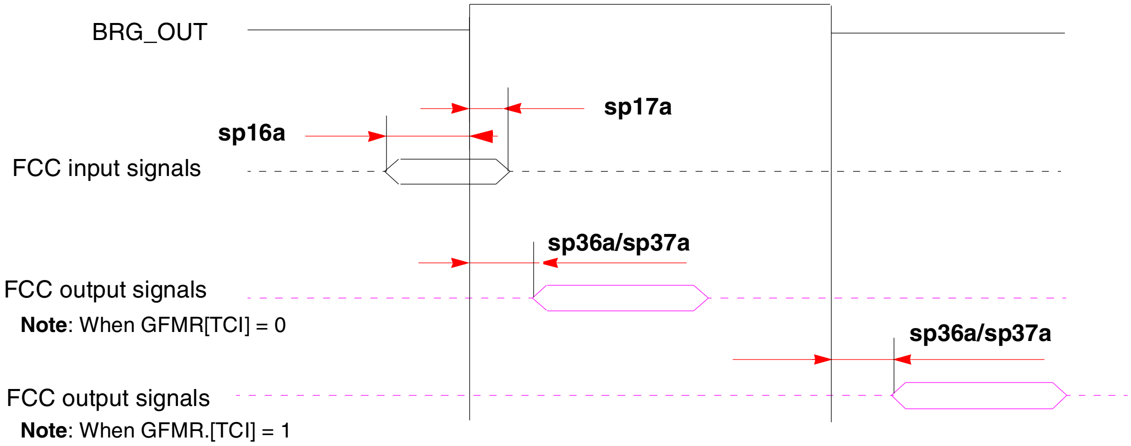
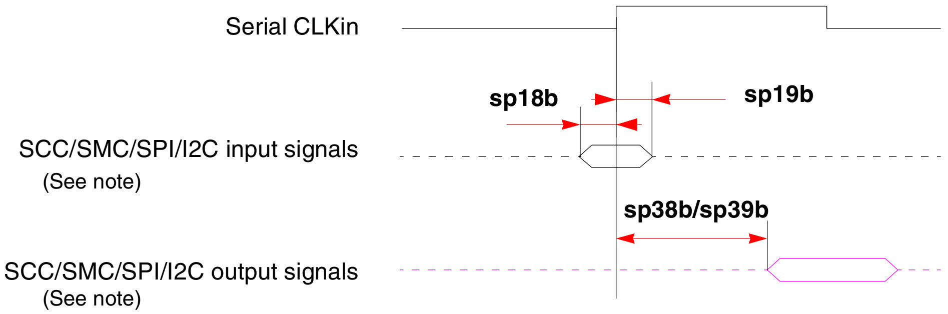


Figure 4. FCC Internal Clock Diagram

Figure 5 shows the SCC/SMC/SPI/I^{2}C external clock.

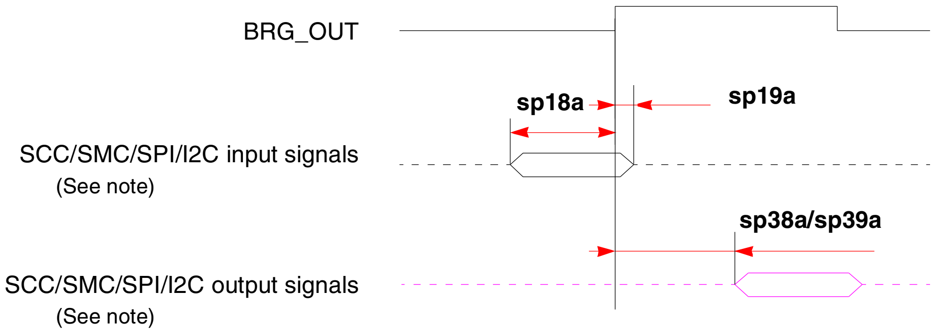


Note: There are four possible timing conditions for SCC and SPI:

1. Input sampled on the rising edge and output driven on the rising edge (shown).
2. Input sampled on the rising edge and output driven on the falling edge.
3. Input sampled on the falling edge and output driven on the falling edge.
4. Input sampled on the falling edge and output driven on the rising edge.

Figure 5. SCC/SMC/SPI/I^{2}C External Clock Diagram

Figure 6 shows the SCC/SMC/SPI/I^{2}C internal clock.

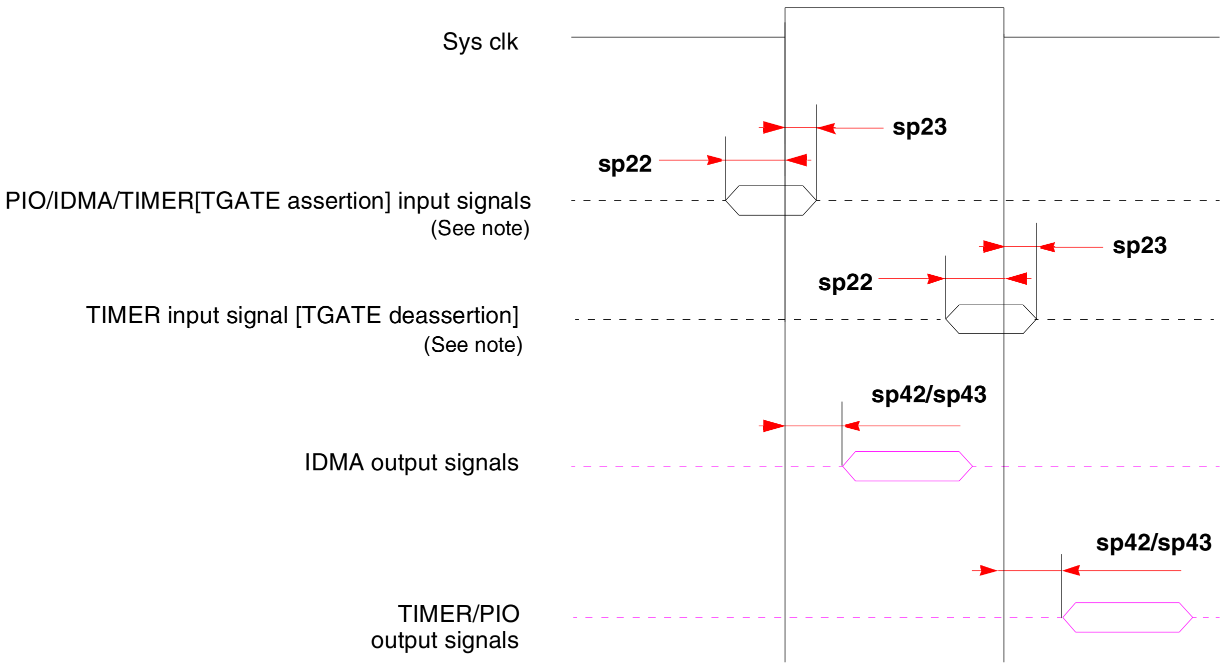


Note: There are four possible timing conditions for SCC and SPI:

1. Input sampled on the rising edge and output driven on the rising edge (shown).
2. Input sampled on the rising edge and output driven on the falling edge.
3. Input sampled on the falling edge and output driven on the falling edge.
4. Input sampled on the falling edge and output driven on the rising edge.

Figure 6. SCC/SMC/SPI/I^{2}C Internal Clock Diagram

Figure 7 shows PIO, timer, and DMA signals.



Note: TGATE is asserted on the rising edge of the clock; it is deasserted on the falling edge.

Figure 7. PIO, Timer, and DMA Signal Diagram

Table 9 lists SIU input characteristics.

Table 9. AC Characteristics for SIU Inputs[1]

Spec Number		Characteristic	Setup (ns)	Hold (ns)
Setup	Hold		66 MHz	66 MHz
sp11	sp10	$\overline{\text{AACK}}$/$\overline{\text{ARTRY}}$/$\overline{\text{TA}}$/$\overline{\text{TS}}$/$\overline{\text{TEA}}$/$\overline{\text{DBG}}$/$\overline{\text{BG}}$/$\overline{\text{BR}}$	6	1
sp12	sp10	Data bus in normal mode	5	1
sp13	sp10	Data bus in ECC and PARITY modes	8	1
sp14	sp10	DP pins	8	1
sp14	sp10	All other pins	5	1

Note:

[1] Input specifications are measured from the 50% level of the signal to the 50% level of the rising edge of CLKIN. Timings are measured at the pin.

Table 10 lists SIU output characteristics.

Table 10. AC Characteristics for SIU Outputs[1]

Spec Number		Characteristic	Max Delay (ns)	Min Delay (ns)
Max	Min		66 MHz	66 MHz
sp31	sp30	$\overline{\text{PSDVAL}}$/$\overline{\text{TEA}}$/$\overline{\text{TA}}$	10	0.5
sp32	sp30	ADD/ADD_atr./BADDR/CI/GBL/WT	8	0.5
sp33a	sp30	Data bus	8	0.5
sp33b	sp30	DP	12	0.5
sp34	sp30	memc signals/ALE	6	0.5
sp35	sp30	all other signals	7.5	0.5

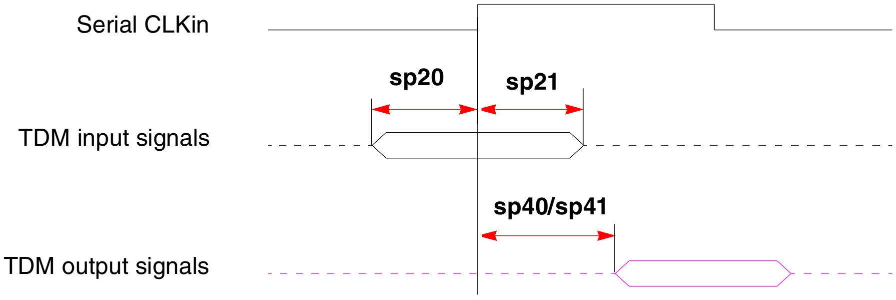
Note:

[1] Output specifications are measured from the 50% level of the rising edge of CLKIN to the 50% level of the signal. Timings are measured at the pin.

NOTE

Activating data pipelining (setting BR*x*[DR] in the memory controller) improves the AC timing. When data pipelining is activated, sp12 can be used for data bus setup even when ECC or PARITY are used. Also, sp33a can be used as the AC specification for DP signals.

Figure 8 shows TDM input and output signals.



Note: There are four possible TDM timing conditions:

1. Input sampled on the rising edge and output driven on the rising edge (shown).
2. Input sampled on the rising edge and output driven on the falling edge.
3. Input sampled on the falling edge and output driven on the falling edge.
4. Input sampled on the falling edge and output driven on the rising edge.

Figure 8. TDM Signal Diagram

Table 13. Clock Configuration Modes[1] (continued)

MODCK_H–MODCK[1–3]	Input Clock Frequency[2,3,4]	CPM Multiplication Factor[2, 5]	CPM Frequency[2]	Core Multiplication Factor[2, 6]	Core Frequency[2]
0001_101	**33 MHz**	**3**	**100 MHz**	4	**133 MHz**
0001_110	**33 MHz**	**3**	**100 MHz**	5	**166 MHz**
0001_111	33 MHz	3	100 MHz	6	200 MHz
0010_000	33 MHz	3	100 MHz	7	233 MHz
0010_001	33 MHz	3	100 MHz	8	266 MHz
0010_010	**33 MHz**	**4**	**133 MHz**	**4**	**133 MHz**
0010_011	**33 MHz**	**4**	**133 MHz**	**5**	**166 MHz**
0010_100	33 MHz	4	133 MHz	6	200 MHz
0010_101	33 MHz	4	133 MHz	7	233 MHz
0010_110	33 MHz	4	133 MHz	8	266 MHz
0010_111	33 MHz	5	166 MHz	4	133 MHz
0011_000	33 MHz	5	166 MHz	5	166 MHz
0011_001	33 MHz	5	166 MHz	6	200 MHz
0011_010	33 MHz	5	166 MHz	7	233 MHz
0011_011	33 MHz	5	166 MHz	8	266 MHz
0011_100	33 MHz	6	200 MHz	4	133 MHz
0011_101	33 MHz	6	200 MHz	5	166 MHz
0011_110	33 MHz	6	200 MHz	6	200 MHz
0011_111	33 MHz	6	200 MHz	7	233 MHz
0100_000	33 MHz	6	200 MHz	8	266 MHz
0100_001	Reserved				
0100_010					
0100_011					
0100_100					
0100_101					
0100_110					

[1] Because of speed dependencies, not all of the possible configurations in Table 13 are applicable.

[2] The user should choose the input clock frequency and the multiplication factors such that the frequency of the CPU ranges between 133–200 and the CPM ranges between 50–166 MHz.

[3] Input clock frequency is given only for the purpose of reference. User should set MODCK_H–MODCK_L so that the resulting configuration does not exceed the frequency rating of the user's part.

[4] 60x and local bus frequency. Identical to CLKIN.

[5] CPM multiplication factor = CPM clock/bus clock

[6] CPU multiplication factor = Core PLL multiplication factor

4 Pinout

This section provides the pin assignments and pinout list for the MPC8260.

4.1 Pin Assignments

Figure 13 shows the pinout of the MPC8260 480 TBGA package as viewed from the top surface.

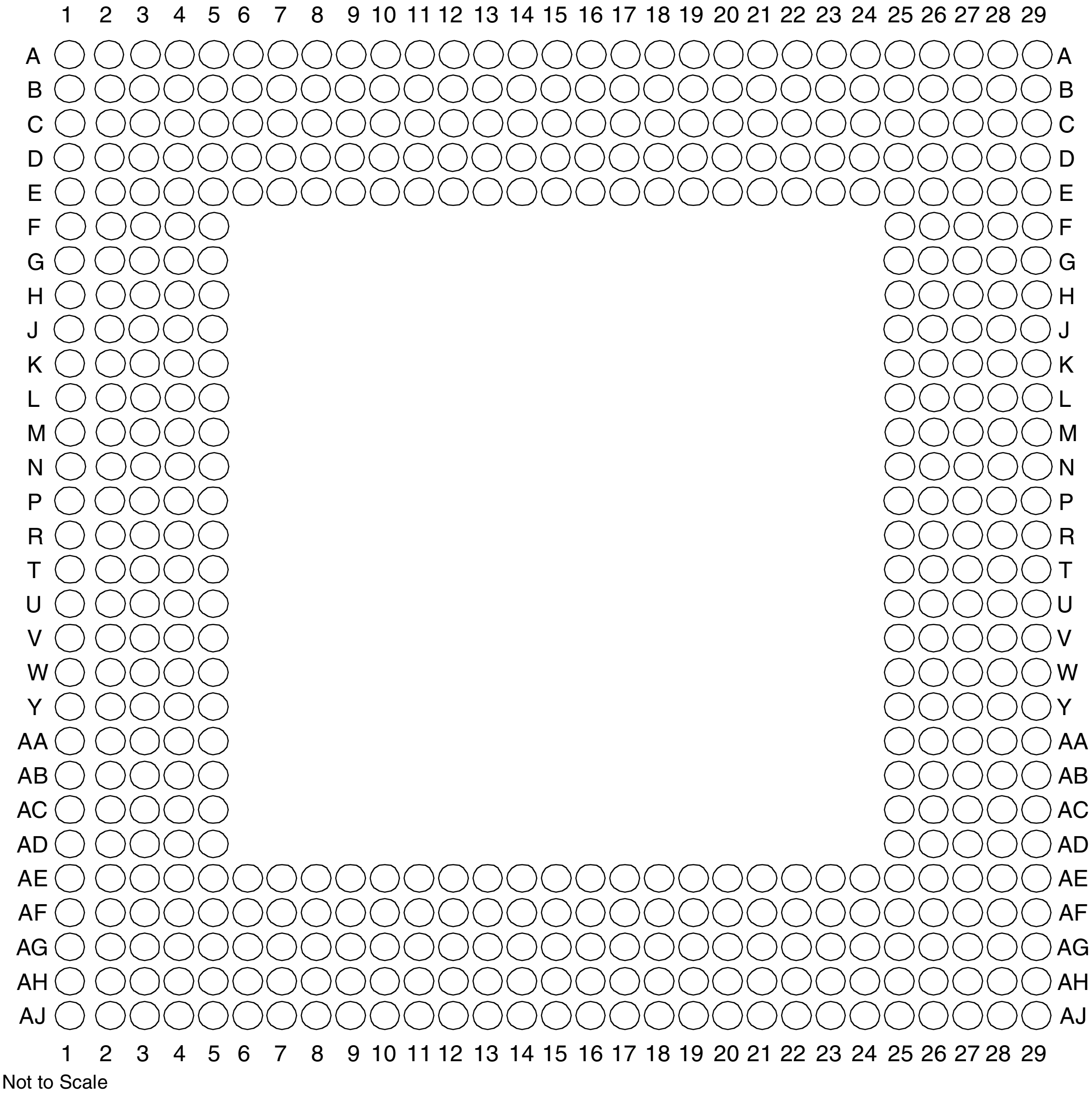


Figure 13. Pinout of the 480 TBGA Package as Viewed from the Top Surface

Figure 14 shows the side profile of the TBGA package to indicate the direction of the top surface view.

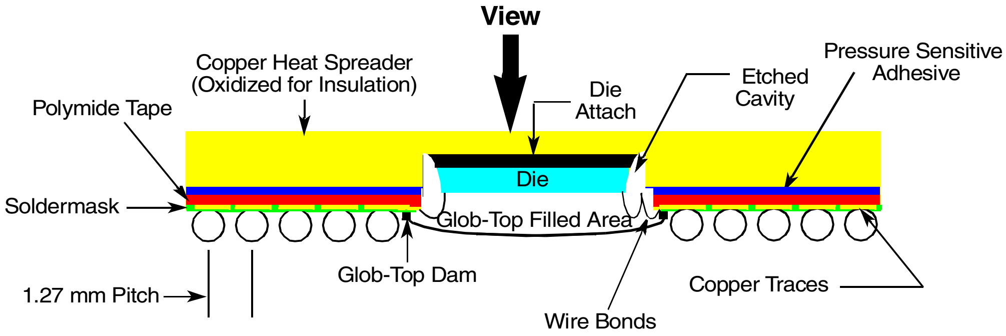


Figure 14. Side View of the TBGA Package

Table 14 shows the pinout list of the MPC8260. Table 15 defines conventions and acronyms used in Table 14.

Table 14. Pinout List

Pin Name	Ball
$\overline{\text{BR}}$	W5
$\overline{\text{BG}}$	F4
$\overline{\text{ABB}}$/$\overline{\text{IRQ2}}$	E2
$\overline{\text{TS}}$	E3
A0	G1
A1	H5
A2	H2
A3	H1
A4	J5
A5	J4
A6	J3
A7	J2
A8	J1
A9	K4
A10	K3
A11	K2
A12	K1
A13	L5
A14	L4
A15	L3
A16	L2
A17	L1

Table 14. Pinout List (continued)

Pin Name	Ball
D42	A14
D43	B12
D44	A10
D45	D8
D46	B6
D47	C4
D48	C18
D49	E16
D50	B14
D51	C12
D52	B10
D53	A7
D54	C6
D55	D5
D56	B18
D57	B16
D58	E14
D59	D12
D60	C10
D61	E8
D62	D6
D63	C2
DP0/RSRV/EXT_BR2	B22
IRQ1/DP1/EXT_BG2	A22
IRQ2/DP2/TLBISYNC/EXT_DBG2	E21
IRQ3/DP3/CKSTP_OUT/EXT_BR3	D21
IRQ4/DP4/CORE_SRESET/EXT_BG3	C21
IRQ5/DP5/TBEN/EXT_DBG3	B21
IRQ6/DP6/CSE0	A21
IRQ7/DP7/CSE1	E20
PSDVAL	V3
TA	C22
TEA	V5
GBL/IRQ1	W1
CI/BADDR29/IRQ2	U2

Table 14. Pinout List (continued)

Pin Name	Ball
$\overline{\mathrm{LWE0}}$/$\overline{\mathrm{LSDDQM0}}$/$\overline{\mathrm{LBS0}}$	H28
$\overline{\mathrm{LWE1}}$/$\overline{\mathrm{LSDDQM1}}$/$\overline{\mathrm{LBS1}}$	H27
$\overline{\mathrm{LWE2}}$/$\overline{\mathrm{LSDDQM2}}$/$\overline{\mathrm{LBS2}}$	H26
$\overline{\mathrm{LWE3}}$/$\overline{\mathrm{LSDDQM3}}$/$\overline{\mathrm{LBS3}}$	G29
LSDA10/LGPL0	D27
$\overline{\mathrm{LSDWE}}$/LGPL1	C28
$\overline{\mathrm{LOE}}$/$\overline{\mathrm{LSDRAS}}$/LGPL2	E26
$\overline{\mathrm{LSDCAS}}$/LGPL3	D25
$\overline{\mathrm{LGTA}}$/LUPMWAIT/LGPL4/$\overline{\mathrm{LPBS}}$	C26
LGPL5/LSDAMUX[1]	B27
$\overline{\mathrm{LWR}}$	D28
L_A14	N27
L_A15/$\overline{\mathrm{SMI}}$	T29
L_A16	R27
L_A17/$\overline{\mathrm{CKSTP\_OUT}}$	R26
L_A18	R29
L_A19	R28
L_A20	W29
L_A21	P28
L_A22	N26
L_A23	AA27
L_A24	P29
L_A25	AA26
L_A26	N25
L_A27	AA25
L_A28/$\overline{\mathrm{CORE\_SRESET}}$	AB29
L_A29	AB28
L_A30	P25
L_A31	AB27
LCL_D0	H29
LCL_D1	J29
LCL_D2	J28
LCL_D3	J27
LCL_D4	J26
LCL_D5	J25

Table 14. Pinout List (continued)

Pin Name	Ball
LCL_D6	K25
LCL_D7	L29
LCL_D8	L27
LCL_D9	L26
LCL_D10	L25
LCL_D11	M29
LCL_D12	M28
LCL_D13	M27
LCL_D14	M26
LCL_D15	N29
LCL_D16	T25
LCL_D17	U27
LCL_D18	U26
LCL_D19	U25
LCL_D20	V29
LCL_D21	V28
LCL_D22	V27
LCL_D23	V26
LCL_D24	W27
LCL_D25	W26
LCL_D26	W25
LCL_D27	Y29
LCL_D28	Y28
LCL_D29	Y25
LCL_D30	AA29
LCL_D31	AA28
LCL_DP0	L28
LCL_DP1	N28
LCL_DP2	T28
LCL_DP3	W28
$\overline{\text{IRQ0}}/\overline{\text{NMI\_OUT}}$	T1
$\overline{\text{IRQ7}}/\overline{\text{INT\_OUT}}/\overline{\text{APE}}$	D1
$\overline{\text{TRST}}$	AH3
TCK	AG5
TMS	AJ3

Table 14. Pinout List (continued)

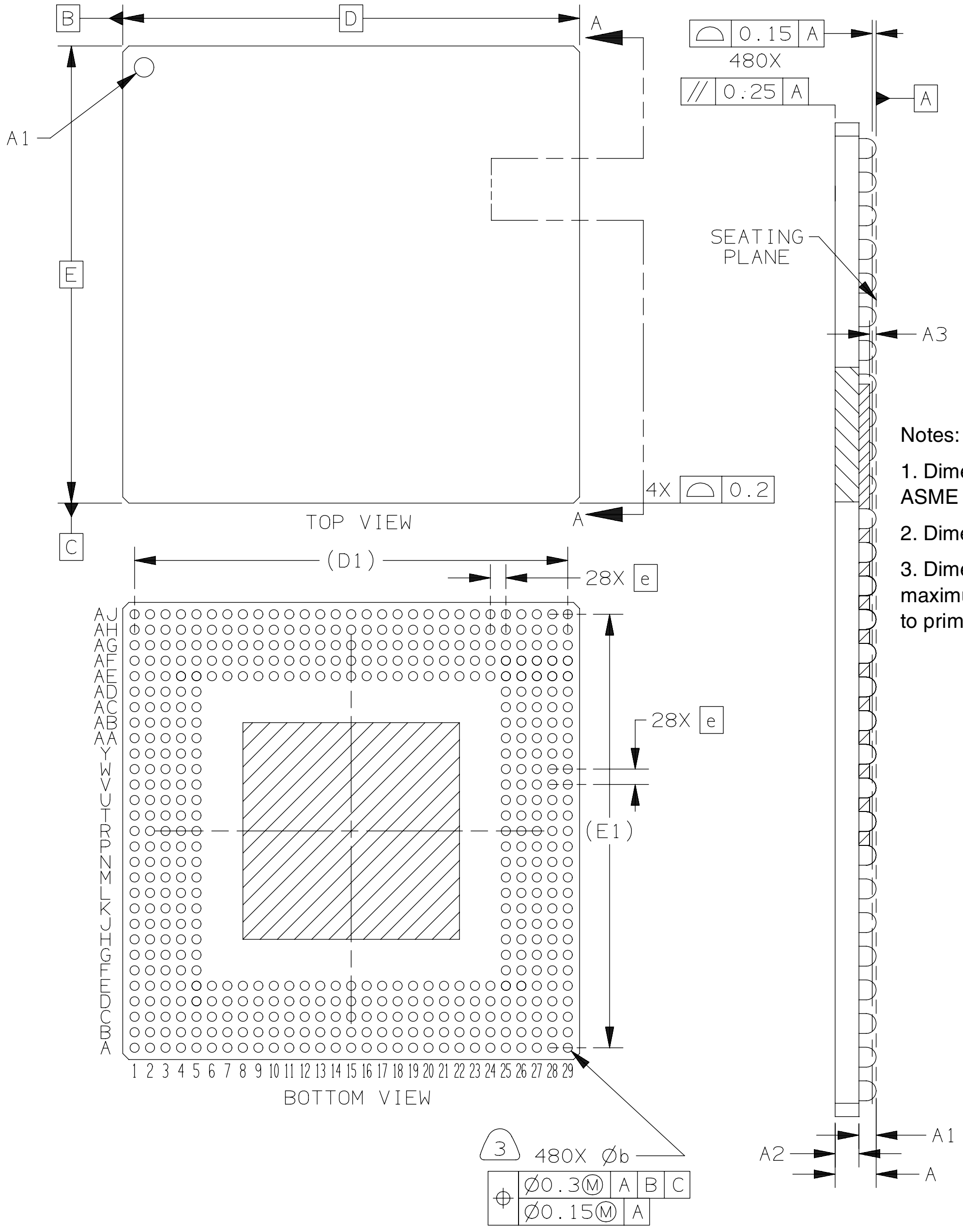
Pin Name	Ball
PA22/FCC1_UT8_TXD3/FCC1_UT16_TXD11	AF12[2]
PA23/FCC1_UT8_TXD2/FCC1_UT16_TXD10	AG11[2]
PA24/FCC1_UT8_TXD1/FCC1_UT16_TXD9/MSNUM1	AH9[2]
PA25/FCC1_UT8_TXD0/FCC1_UT16_TXD8/MSNUM0	AJ8[2]
PA26/FCC1_UTM_RXCLAV/FCC1_UTS_RXCLAV/FCC1_MII_RX_ER	AH7[2]
PA27/FCC1_UT_RXSOC/FCC1_MII_RX_DV	AF7[2]
PA28/FCC1_UTM_RXENB/FCC1_UTS_RXENB/FCC1_MII_TX_EN	AD5[2]
PA29/FCC1_UT_TXSOC/FCC1_MII_TX_ER	AF1[2]
PA30/FCC1_UTM_TXCLAV/FCC1_UTS_TXCLAV/FCC1_MII_CRS/FCC1_RTS	AD3[2]
PA31/FCC1_UTM_TXENB/FCC1_UTS_TXENB/FCC1_MII_COL	AB5[2]
PB4/FCC3_TXD3/FCC2_UT8_RXD0/L1RSYNCA2/FCC3_RTS	AD28[2]
PB5/FCC3_TXD2/FCC2_UT8_RXD1/L1TSYNCA2/L1GNTA2	AD26[2]
PB6/FCC3_TXD1/FCC2_UT8_RXD2/L1RXDA2/L1RXD0A2	AD25[2]
PB7/FCC3_TXD0/FCC3_TXD/FCC2_UT8_RXD3/L1TXDA2/L1TXD0A2	AE26[2]
PB8/FCC2_UT8_TXD3/FCC3_RXD0/FCC3_RXD/TXD3/L1RSYNCD1	AH27[2]
PB9/FCC2_UT8_TXD2/FCC3_RXD1/L1TXD2A2/L1TSYNCD1/L1GNTD1	AG24[2]
PB10/FCC2_UT8_TXD1/FCC3_RXD2/L1RXDD1	AH24[2]
PB11/FCC3_RXD3/FCC2_UT8_TXD0/L1TXDD1	AJ24[2]
PB12/FCC3_MII_CRS/L1CLKOB1/L1RSYNCC1/TXD2	AG22[2]
PB13/FCC3_MII_COL/L1RQB1/L1TSYNCC1/L1GNTC1/L1TXD1A2	AH21[2]
PB14/FCC3_MII_TX_EN/RXD3/L1RXDC1	AG20[2]
PB15/FCC3_MII_TX_ER/RXD2/L1TXDC1	AF19[2]
PB16/FCC3_MII_RX_ER/L1CLKOA1/CLK18	AJ18[2]
PB17/FCC3_MII_RX_DV/L1RQA1/CLK17	AJ17[2]
PB18/FCC2_UT8_RXD4/FCC2_RXD3/L1CLKOD2/L1RXD2A2	AE14[2]
PB19/FCC2_UT8_RXD5/FCC2_RXD2/L1RQD2/L1RXD3A2	AF13[2]
PB20/FCC2_UT8_RXD6/FCC2_RXD1/L1RSYNCD2/L1TXD1A1	AG12[2]
PB21/FCC2_UT8_RXD7/FCC2_RXD0/FCC2_RXD/L1TSYNCD2/L1GNTD2/ L1TXD2A1	AH11[2]
PB22/FCC2_UT8_TXD7/FCC2_TXD0/FCC2_TXD/L1RXD1A1/L1RXDD2	AH16[2]
PB23/FCC2_UT8_TXD6/FCC2_TXD1/L1RXD2A1/L1TXDD2	AE15[2]
PB24/FCC2_UT8_TXD5/FCC2_TXD2/L1RXD3A1/L1RSYNCC2	AJ9[2]
PB25/FCC2_UT8_TXD4/FCC2_TXD3/L1TSYNCC2/L1GNTC2/L1TXD3A1	AE9[2]
PB26/FCC2_MII_CRS/FCC2_UT8_TXD1/L1RXDC2	AJ7[2]
PB27/FCC2_MII_COL/FCC2_UT8_TXD0/L1TXDC2	AH6[2]

Table 14. Pinout List (continued)

Pin Name	Ball
PB28/FCC2_MII_RX_ER/$\overline{\text{FCC2\_RTS}}$/L1TSYNCB2/L1GNTB2/TXD1	AE3[2]
PB29/FCC2_UTM_RXCLAV/FCC2_UTS_RXCLAV/L1RSYNCB2/ FCC2_MII_TX_EN	AE2[2]
PB30/FCC2_MII_RX_DV/FCC2_UT_TXSOC/L1RXDB2	AC5[2]
PB31/FCC2_MII_TX_ER/FCC2_UT_RXSOC/L1TXDB2	AC4[2]
PC0/DREQ1/BRGO7/$\overline{\text{SMSYN2}}$/L1CLKOA2	AB26[2]
PC1/DREQ2/BRGO6/$\overline{\text{L1RQA2}}$	AD29[2]
PC2/$\overline{\text{FCC3\_CD}}$/FCC2_UT8_TXD3/$\overline{\text{DONE2}}$	AE29[2]
PC3/$\overline{\text{FCC3\_CTS}}$/FCC2_UT8_TXD2/$\overline{\text{DACK2}}$/$\overline{\text{CTS4}}$	AE27[2]
PC4/$\overline{\text{FCC2\_UTM\_RXENB}}$/$\overline{\text{FCC2\_UTS\_RXENB}}$/SI2_L1ST4/$\overline{\text{FCC2\_CD}}$	AF27[2]
PC5/FCC2_UTM_TXCLAV/FCC2_UTS_TXCLAV/SI2_L1ST3/$\overline{\text{FCC2\_CTS}}$	AF24[2]
PC6/$\overline{\text{FCC1\_CD}}$/L1CLKOC1/FCC1_UTM_RXADDR2/FCC1_UTS_RXADDR2/ FCC1_UTM_RXCLAV1	AJ26[2]
PC7/$\overline{\text{FCC1\_CTS}}$/$\overline{\text{L1RQC1}}$/FCC1_UTM_TXADDR2/FCC1_UTS_TXADDR2/ FCC1_UTM_TXCLAV1	AJ25[2]
PC8/$\overline{\text{CD4}}$/RENA4/FCC1_UT16_TXD0/SI2_L1ST2/$\overline{\text{CTS3}}$	AF22[2]
PC9/$\overline{\text{CTS4}}$/CLSN4/FCC1_UT16_TXD1/SI2_L1ST1/L1TSYNCA2/L1GNTA2	AE21[2]
PC10/$\overline{\text{CD3}}$/RENA3/FCC1_UT16_TXD2/SI1_L1ST4/FCC2_UT8_RXD3	AF20[2]
PC11/$\overline{\text{CTS3}}$/CLSN3/L1CLKOD1/L1TXD3A2/FCC2_UT8_RXD2	AE19[2]
PC12/$\overline{\text{CD2}}$/RENA2/SI1_L1ST3/FCC1_UTM_RXADDR1/FCC1_UTS_RXADDR1	AE18[2]
PC13/$\overline{\text{CTS2}}$/CLSN2/$\overline{\text{L1RQD1}}$/FCC1_UTM_TXADDR1/FCC1_UTS_TXADDR1	AH18[2]
PC14/$\overline{\text{CD1}}$/RENA1/FCC1_UTM_RXADDR0/FCC1_UTS_RXADDR0	AH17[2]
PC15/$\overline{\text{CTS1}}$/CLSN1/SMTXD2/FCC1_UTM_TXADDR0/FCC1_UTS_TXADDR0	AG16[2]
PC16/CLK16/TIN4	AF15[2]
PC17/CLK15/TIN3/BRGO8	AJ15[2]
PC18/CLK14/$\overline{\text{TGATE2}}$	AH14[2]
PC19/CLK13/BRGO7/SPICLK	AG13[2]
PC20/CLK12/$\overline{\text{TGATE1}}$	AH12[2]
PC21/CLK11/BRGO6	AJ11[2]
PC22/CLK10/$\overline{\text{DONE1}}$	AG10[2]
PC23/CLK9/BRGO5/$\overline{\text{DACK1}}$	AE10[2]
PC24/FCC2_UT8_TXD3/CLK8/$\overline{\text{TOUT4}}$	AF9[2]
PC25/FCC2_UT8_TXD2/CLK7/BRGO4	AE8[2]
PC26/CLK6/$\overline{\text{TOUT3}}$/TMCLK	AJ6[2]
PC27/FCC3_TXD/FCC3_TXD0/CLK5/BRGO3	AG2[2]
PC28/CLK4/TIN1/$\overline{\text{TOUT2}}$/$\overline{\text{CTS2}}$/CLSN2	AF3[2]

5.2 Mechanical Dimensions

Figure 15 provides the mechanical dimensions and bottom surface nomenclature of the 480 TBGA package.



Notes:

1. Dimensions and Tolerancing per ASME Y14.5M-1994.
2. Dimensions in millimeters.
3. Dimension b is measured at the maximum solder ball diameter, parallel to primary data A.

Dim	Millimeters	
	Min	Max
A	1.45	1.65
A1	0.60	0.70
A2	0.85	0.95
A3	0.25	—
b	0.65	0.85
D	37.50 BSC	
D1	35.56 REF	
e	1.27 BSC	
E	37.50 BSC	
E1	35.56 REF	

Figure 15. Mechanical Dimensions and Bottom Surface Nomenclature