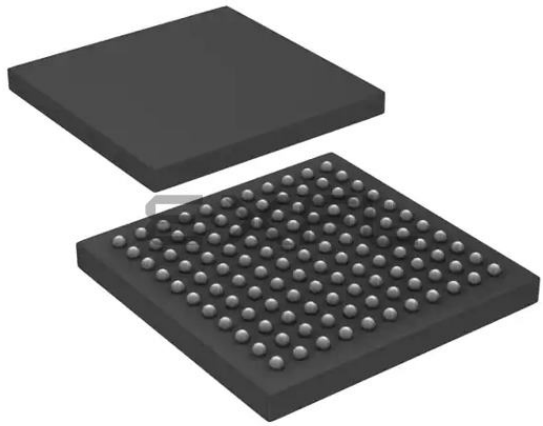
Microchip Technology - PIC24FJ256GA412-I/BG Datasheet



Welcome to E-XFL.COM

What is "Embedded - Microcontrollers"?

"Embedded - Microcontrollers" refer to small, integrated circuits designed to perform specific tasks within larger systems. These microcontrollers are essentially compact computers on a single chip, containing a processor core, memory, and programmable input/output peripherals. They are called "embedded" because they are embedded within electronic devices to control various functions, rather than serving as standalone computers. Microcontrollers are crucial in modern electronics, providing the intelligence and control needed for a wide range of applications.

Applications of "Embedded - Microcontrollers"

Details	
Product Status	Active
Core Processor	PIC
Core Size	16-Bit
Speed	32MHz
Connectivity	I²C, IrDA, LINbus, PMP/PSP, SPI, UART/USART
Peripherals	Brown-out Detect/Reset, DMA, LCD, LVD, POR, PWM, WDT
Number of I/O	102
Program Memory Size	256KB (85.5K x 24)
Program Memory Type	FLASH
EEPROM Size	-
RAM Size	16K x 8
Voltage - Supply (Vcc/Vdd)	2V ~ 3.6V
Data Converters	A/D 24x10/12b; D/A 1x10b
Oscillator Type	Internal
Operating Temperature	-40°C ~ 85°C (TA)
Mounting Type	Surface Mount
Package / Case	121-TFBGA
Supplier Device Package	121-TFBGA (10x10)
Purchase URL	https://www.e-xfl.com/product-detail/microchip-technology/pic24fj256ga412-i-bg

TO OUR VALUED CUSTOMERS

It is our intention to provide our valued customers with the best documentation possible to ensure successful use of your Microchip products. To this end, we will continue to improve our publications to better suit your needs. Our publications will be refined and enhanced as new volumes and updates are introduced.

If you have any questions or comments regarding this publication, please contact the Marketing Communications Department via E-mail at **docerrors@microchip.com**. We welcome your feedback.

Most Current Data Sheet

To obtain the most up-to-date version of this data sheet, please register at our Worldwide Web site at:

http://www.microchip.com

You can determine the version of a data sheet by examining its literature number found on the bottom outside corner of any page. The last character of the literature number is the version number, (e.g., DS30000000A is version A of document DS30000000).

Errata

An errata sheet, describing minor operational differences from the data sheet and recommended workarounds, may exist for current devices. As device/documentation issues become known to us, we will publish an errata sheet. The errata will specify the revision of silicon and revision of document to which it applies.

To determine if an errata sheet exists for a particular device, please check with one of the following:

- Microchip's Worldwide Web site; **http://www.microchip.com**
- Your local Microchip sales office (see last page)

When contacting a sales office, please specify which device, revision of silicon and data sheet (include literature number) you are using.

Customer Notification System

Register on our web site at **www.microchip.com** to receive the most current information on all of our products.

TABLE 1-2: DEVICE FEATURES FOR THE PIC24FJ256GA412/GB412 FAMILY: 100-PIN

Features	PIC24FJXXXGA/GB410					
	64GA	128GA	256GA	64GB	128GB	256GB
Operating Frequency	DC – 32 MHz					
Program Memory (bytes)	64K	128K	256K	64K	128K	256K
Program Memory (instructions)	22,016	44,032	88,064	22,016	44,032	88,064
Data Memory (bytes)	8K	16K		8K	16K	
Interrupt Sources (soft vectors/ NMI traps)	113 (107/6)					
I/O Ports	Ports A, B, C, D, E, F, G					
Total I/O Pins	85			84		
Remappable Pins	44 (32 I/Os, 12 input only)					
Timers:						
Total Number (16-bit)	19(1,2)					
32-Bit (from paired 16-bit timers)	9					
Input Capture w/Timer Channels	6(2)					
Output Compare/PWM Channels	6(2)					
Capture/Compare/PWM/Timer:						
Single Output (SCCP)	6(2)					
Multiple Output (MCCP)	1(2)					
Serial Communications:						
UART	6(2)					
SPI (3-wire/4-wire)	4(2)					
I^2C	3					
USB On-The-Go	No			Yes		
Cryptographic Engine	Yes					
Parallel Communications (EPMP/PSP)	Yes					
10/12-Bit Analog-to-Digital Converter (A/D) (input channels)	24					
Digital-to-Analog Converter (DAC)	1					
Analog Comparators	3					
CTMU Interface	Yes					
LCD Controller (available pixels)	512 (64 SEG x 8 COM)					
JTAG Boundary Scan	Yes					
Resets (and delays)	Core POR, VDD POR, VBAT POR, BOR, RESET Instruction, $\overline{MCLR}$, WDT, Illegal Opcode, REPEAT Instruction, Hardware Traps, Configuration Word Mismatch (OST, PLL Lock)					
Instruction Set	77 Base Instructions, Multiple Addressing Mode Variations					
Packages	100-Pin TQFP					

Note 1: Includes the Timer modes of the SCCP and MCCP modules.

2: Some instantiations of these modules are only available through remappable pins.

3.0 CPU

Note: This data sheet summarizes the features of this group of PIC24F devices. It is not intended to be a comprehensive reference source. For more information on the CPU, refer to the *"dsPIC33/PIC24 Family Reference Manual"*, **"CPU with Extended Data Space (EDS)"** (DS39732). The information in this data sheet supersedes the information in the FRM.

The PIC24F CPU has a 16-bit (data) modified Harvard architecture with an enhanced instruction set and a 24-bit instruction word with a variable length opcode field. The Program Counter (PC) is 23 bits wide and addresses up to 4M instructions of user program memory space. A single-cycle instruction prefetch mechanism is used to help maintain throughput and provides predictable execution. All instructions execute in a single cycle, with the exception of instructions that change the program flow, the double-word move (MOV.D) instruction and the table instructions. Overhead-free program loop constructs are supported using the REPEAT instructions, which are interruptible at any point.

PIC24F devices have sixteen, 16-bit Working registers in the programmer's model. Each of the Working registers can act as a data, address or address offset register. The 16th Working register (W15) operates as a Software Stack Pointer (SSP) for interrupts and calls.

The lower 32 Kbytes of the Data Space (DS) can be accessed linearly. The upper 32 Kbytes of the Data Space are referred to as Extended Data Space to which the extended data RAM, EPMP memory space or program memory can be mapped.

The Instruction Set Architecture (ISA) has been significantly enhanced beyond that of the PIC18, but maintains an acceptable level of backward compatibility. All PIC18 instructions and addressing modes are supported, either directly, or through simple macros. Many of the ISA enhancements have been driven by compiler efficiency needs.

The core supports Inherent (no operand), Relative, Literal and Memory Direct Addressing modes, along with three groups of addressing modes. All modes support Register Direct and various Register Indirect modes. Each group offers up to seven addressing modes. Instructions are associated with predefined addressing modes depending upon their functional requirements.

For most instructions, the core is capable of executing a data (or program data) memory read, a Working register (data) read, a data memory write and a program (instruction) memory read per instruction cycle. As a result, three parameter instructions can be supported, allowing trinary operations (that is, A + B = C) to be executed in a single cycle.

A high-speed, 17-bit x 17-bit multiplier has been included to significantly enhance the core arithmetic capability and throughput. The multiplier supports Signed, Unsigned and Mixed mode, 16-bit x 16-bit or 8-bit x 8-bit, integer multiplication. All multiply instructions execute in a single cycle.

The 16-bit ALU has been enhanced with integer divide assist hardware that supports an iterative non-restoring divide algorithm. It operates in conjunction with the REPEAT instruction looping mechanism and a selection of iterative divide instructions to support 32-bit (or 16-bit), divided by 16-bit, integer signed and unsigned division. All divide operations require 19 cycles to complete but are interruptible at any cycle boundary.

The PIC24F has a vectored exception scheme with up to 8 sources of non-maskable traps and up to 118 interrupt sources. Each interrupt source can be assigned to one of seven priority levels.

A block diagram of the CPU is shown in Figure 3-1.

3.1 Programmer's Model

The programmer's model for the PIC24F is shown in Figure 3-2. All registers in the programmer's model are memory-mapped and can be manipulated directly by instructions.

A description of each register is provided in Table 3-1. All registers associated with the programmer's model are memory-mapped.

REGISTER 8-30: IPC8: INTERRUPT PRIORITY CONTROL REGISTER 8

U-0	R/W-1	R/W-0	R/W-0	U-0	R/W-1	R/W-0	R/W-0
—	CRYROLLIP2	CRYROLLIP1	CRYROLLIP0	—	CRYFREEIP2	CRYFREEIP1	CRYFREEIP0
bit 15							bit 8

U-0	R/W-1	R/W-0	R/W-0	U-0	R/W-1	R/W-0	R/W-0
—	SPI2TXIP2	SPI2TXIP1	SPI2TXIP0	—	SPI2IP2	SPI2IP1	SPI2IP0
bit 7							bit 0

Legend:			
R = Readable bit	W = Writable bit	U = Unimplemented bit, read as '0'	
-n = Value at POR	'1' = Bit is set	'0' = Bit is cleared	x = Bit is unknown

bit 15 **Unimplemented:** Read as '0'

bit 14-12 **CRYROLLIP<2:0>:** Cryptographic Rollover Interrupt Priority bits
111 = Interrupt is Priority 7 (highest priority interrupt)
•
•
•
001 = Interrupt is Priority 1
000 = Interrupt source is disabled

bit 11 **Unimplemented:** Read as '0'

bit 10-8 **CRYFREEIP<2:0>:** Cryptographic Buffer Free Interrupt Priority bits
111 = Interrupt is Priority 7 (highest priority interrupt)
•
•
•
001 = Interrupt is Priority 1
000 = Interrupt source is disabled

bit 7 **Unimplemented:** Read as '0'

bit 6-4 **SPI2TXIP<2:0>:** SPI2 Transmit Interrupt Priority bits
111 = Interrupt is Priority 7 (highest priority interrupt)
•
•
•
001 = Interrupt is Priority 1
000 = Interrupt source is disabled

bit 3 **Unimplemented:** Read as '0'

bit 2-0 **SPI2IP<2:0>:** SPI2 General Interrupt Priority bits
111 = Interrupt is Priority 7 (highest priority interrupt)
•
•
•
001 = Interrupt is Priority 1
000 = Interrupt source is disabled

REGISTER 8-48: IPC26: INTERRUPT PRIORITY CONTROL REGISTER 26

U-0	U-0	U-0	U-0	U-0	R/W-1	R/W-0	R/W-0
—	—	—	—	—	FSTIP2	FSTIP1	FSTIP0
bit 15							bit 8

U-0	U-0	U-0	U-0	U-0	U-0	U-0	U-0
—	—	—	—	—	—	—	—
bit 7							bit 0

Legend:			
R = Readable bit	W = Writable bit	U = Unimplemented bit, read as '0'	
-n = Value at POR	'1' = Bit is set	'0' = Bit is cleared	x = Bit is unknown

bit 15-11 **Unimplemented:** Read as '0'

bit 10-8 **FSTIP<2:0>:** FRC Self-Tune Interrupt Priority bits
111 = Interrupt is Priority 7 (highest priority interrupt)
•
•
•
001 = Interrupt is Priority 1
000 = Interrupt source is disabled

bit 7-0 **Unimplemented:** Read as '0'

REGISTER 10-11: PMD8: PERIPHERAL MODULE DISABLE REGISTER 8

U-0	U-0	U-0	U-0	U-0	U-0	U-0	U-0
—	—	—	—	—	—	—	—
bit 15							bit 8

R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	U-0	R/W-0
U6MD	U5MD	CLC4MD	CLC3MD	CLC2MD	CLC1MD	—	CRYMD
bit 7							bit 0

Legend:			
R = Readable bit	W = Writable bit	U = Unimplemented bit, read as '0'	
-n = Value at POR	'1' = Bit is set	'0' = Bit is cleared	x = Bit is unknown

bit 15-8 **Unimplemented:** Read as '0'

bit 7 **U6MD:** UART6 Module Disable bit
1 = Module is disabled
0 = Module power and clock sources are enabled

bit 6 **U5MD:** UART5 Module Disable bit
1 = Module is disabled
0 = Module power and clock sources are enabled

bit 5 **CLC4MD:** CLC4 Module Disable bit
1 = Module is disabled
0 = Module power and clock sources are enabled

bit 4 **CLC3MD:** CLC3 Module Disable bit
1 = Module is disabled
0 = Module power and clock sources are enabled

bit 3 **CLC2MD:** CLC2 Module Disable bit
1 = Module is disabled
0 = Module power and clock sources are enabled

bit 2 **CLC1MD:** CLC1 Module Disable bit
1 = Module is disabled
0 = Module power and clock sources are enabled

bit 1 **Unimplemented:** Read as '0'

bit 0 **CRYMD:** Cryptographic Engine Disable bit
1 = Module is disabled
0 = Module power and clock sources are enabled

REGISTER 11-15: RPINR20: PERIPHERAL PIN SELECT INPUT REGISTER 20

U-0	U-0	R/W-1	R/W-1	R/W-1	R/W-1	R/W-1	R/W-1
—	—	SCK1R5	SCK1R4	SCK1R3	SCK1R2	SCK1R1	SCK1R0
bit 15							bit 8

U-0	U-0	R/W-1	R/W-1	R/W-1	R/W-1	R/W-1	R/W-1
—	—	SDI1R5	SDI1R4	SDI1R3	SDI1R2	SDI1R1	SDI1R0
bit 7							bit 0

Legend:			
R = Readable bit	W = Writable bit	U = Unimplemented bit, read as ‘0’	
-n = Value at POR	‘1’ = Bit is set	‘0’ = Bit is cleared	x = Bit is unknown

bit 15-14 **Unimplemented:** Read as ‘0’

bit 13-8 **SCK1R<5:0>:** Assign SPI1 Clock Input (SCK1IN) to Corresponding RPn or RPIn Pin bits

bit 7-6 **Unimplemented:** Read as ‘0’

bit 5-0 **SDI1R<5:0>:** Assign SPI1 Data Input (SDI1) to Corresponding RPn or RPIn Pin bits

REGISTER 11-16: RPINR21: PERIPHERAL PIN SELECT INPUT REGISTER 21

U-0	U-0	R/W-1	R/W-1	R/W-1	R/W-1	R/W-1	R/W-1
—	—	U3CTSR5	U3CTSR4	U3CTSR3	U3CTSR2	U3CTSR1	U3CTSR0
bit 15							bit 8

U-0	U-0	R/W-1	R/W-1	R/W-1	R/W-1	R/W-1	R/W-1
—	—	SS1R5	SS1R4	SS1R3	SS1R2	SS1R1	SS1R0
bit 7							bit 0

Legend:			
R = Readable bit	W = Writable bit	U = Unimplemented bit, read as ‘0’	
-n = Value at POR	‘1’ = Bit is set	‘0’ = Bit is cleared	x = Bit is unknown

bit 15-14 **Unimplemented:** Read as ‘0’

bit 13-8 **U3CTSR<5:0>:** Assign UART3 Clear-to-Send ($\overline{\text{U3CTS}}$) to Corresponding RPn or RPIn Pin bits

bit 7-6 **Unimplemented:** Read as ‘0’

bit 5-0 **SS1R<5:0>:** Assign SPI1 Slave Select Input (SS1IN) to Corresponding RPn or RPIn Pin bits

14.5 Auxiliary Output

The MCCPx and SCCPx modules have an auxiliary (secondary) output that provides other peripherals access to internal module signals. The auxiliary output is intended to connect to other MCCP or SCCP modules, or other digital peripherals, to provide these types of functions:

- Time Base Synchronization
- Peripheral Trigger and Clock Inputs
- Signal Gating

The type of output signal is selected using the AUXOUT<1:0> control bits (CCPxCON2H<4:3>). The type of output signal is also dependent on the module operating mode.

On the PIC24FJ256GA412/GB412 family of devices, only the CTMU discharge trigger has access to the auxiliary output signal.

TABLE 14-4: AUXILIARY OUTPUT

AUXOUT<1:0>	CCSEL	MOD<3:0>	Comments	Signal Description
00	x	xxxx	Auxiliary output disabled	No Output
01	0	0000	Time Base modes	Time Base Period Reset or Rollover
10				Special Event Trigger Output
11				No Output
01	0	0001 through 1111	Output Compare modes	Time Base Period Reset or Rollover
10				Output Compare Event Signal
11				Output Compare Signal
01	1	xxxx	Input Capture modes	Time Base Period Reset or Rollover
10				Reflects the Value of the ICDIS bit
11				Input Capture Event Signal

16.3.2 PWM DUTY CYCLE

The PWM duty cycle is specified by writing to the OCxRS and OCxR registers. The OCxRS and OCxR registers can be written to at any time, but the duty cycle value is not latched until a match between PRy and TMRy occurs (i.e., the period is complete). This provides a double buffer for the PWM duty cycle and is essential for glitchless PWM operation.

Some important boundary parameters of the PWM duty cycle include:

- If OCxR, OCxRS and PRy are all loaded with 0000h, the OCx pin will remain low (0% duty cycle).
- If OCxRS is greater than PRy, the pin will remain high (100% duty cycle).

See Example 16-1 for PWM mode timing details. Table 16-1 and Table 16-2 show example PWM frequencies and resolutions for a device operating at 4 MIPS and 10 MIPS, respectively.

EQUATION 16-2: CALCULATION FOR MAXIMUM PWM RESOLUTION(1)

$$\text{Maximum PWM Resolution (bits)} = \frac{\log_{10}\left(\frac{F_{CY}}{FPWM \bullet (\text{Timer Prescale Value})}\right)}{\log_{10}(2)} \text{ bits}$$

Note 1: Based on FCY = FOSC/2; Doze mode and PLL are disabled.

EXAMPLE 16-1: PWM PERIOD AND DUTY CYCLE CALCULATIONS(1)

1. Find the Timer Period register value for a desired PWM frequency of 52.08 kHz, where FOSC = 8 MHz with PLL (32 MHz device clock rate) and a Timer2 prescaler setting of 1:1.

   TCY = 2 * TOSC = 62.5 ns

   PWM Period = 1/PWM Frequency = 1/52.08 kHz = 19.2 ms

   PWM Period = (PR2 + 1) • TCY • (Timer2 Prescale Value)

   19.2 µs = (PR2 + 1) • 62.5 ns • 1

   PR2 = 306

2. Find the maximum resolution of the duty cycle that can be used with a 52.08 kHz frequency and a 32 MHz device clock rate:

   PWM Resolution = $\log_{10}(F_{CY}/F_{PWM})/\log_{10}2)$ bits

   = $(\log_{10}(16\text{ MHz}/52.08\text{ kHz})/\log_{10}2)$ bits

   = 8.3 bits

Note 1: Based on TCY = 2 * TOSC; Doze mode and PLL are disabled.

TABLE 16-1: EXAMPLE PWM FREQUENCIES AND RESOLUTIONS AT 4 MIPS (FCY = 4 MHz)(1)

PWM Frequency	7.6 Hz	61 Hz	122 Hz	977 Hz	3.9 kHz	31.3 kHz	125 kHz
Timer Prescaler Ratio	8	1	1	1	1	1	1
Period Register Value	FFFFh	FFFFh	7FFFh	0FFFh	03FFh	007Fh	001Fh
Resolution (bits)	16	16	15	12	10	7	5

Note 1: Based on FCY = FOSC/2; Doze mode and PLL are disabled.

TABLE 16-2: EXAMPLE PWM FREQUENCIES AND RESOLUTIONS AT 16 MIPS (FCY = 16 MHz)(1)

PWM Frequency	30.5 Hz	244 Hz	488 Hz	3.9 kHz	15.6 kHz	125 kHz	500 kHz
Timer Prescaler Ratio	8	1	1	1	1	1	1
Period Register Value	FFFFh	FFFFh	7FFFh	0FFFh	03FFh	007Fh	001Fh
Resolution (bits)	16	16	15	12	10	7	5

Note 1: Based on FCY = FOSC/2; Doze mode and PLL are disabled.

REGISTER 16-2: OCxCON2: OUTPUT COMPARE x CONTROL REGISTER 2 (CONTINUED)

bit 4-0 **SYNCSEL<4:0>:** Trigger/Synchronization Source Selection bits
11111 = This OC module(1)
11110 = OCTRIG1 external input
11101 = OCTRIG2 external input
11100 = CTMU(2)
11011 = A/D(2)
11010 = Comparator 3(2)
11001 = Comparator 2(2)
11000 = Comparator 1(2)
10111 = SCCP5 capture/compare
10110 = SCCP4 capture/compare
10101 = SCCP3 capture/compare
10100 = SCCP2 capture/compare
10011 = MCCP1 capture/compare
10010 = Input Capture 3(2)
10001 = Input Capture 2(2)
10000 = Input Capture 1(2)
01111 = SCCP7 capture/compare
01110 = SCCP6 capture/compare
01101 = Timer3
01100 = Timer2
01011 = Timer1
01010 = SCCP7 sync/trigger
01001 = SCCP6 sync/trigger
01000 = SCCP5 sync/trigger
00111 = SCCP4 sync/trigger
00110 = SCCP3 sync/trigger
00101 = SCCP2 sync/trigger
00100 = MCCP1 sync/trigger
00011 = Output Compare 5(1)
00010 = Output Compare 3(1)
00001 = Output Compare 1(1)
00000 = Not synchronized to any other module

Note 1: Never use an OCx module as its own trigger source, either by selecting this mode or another equivalent SYNCSELx setting.
2: Use these inputs as trigger sources only and never as sync sources.
3: The DCB<1:0> bits are double-buffered in PWM modes only (OCM<2:0> (OCxCON1<2:0>) = 111, 110).

REGISTER 17-1: SPIxCON1L: SPIx CONTROL REGISTER 1 LOW (CONTINUED)

bit 9 **SMP:** SPIx Data Input Sample Phase bit
Master Mode:
1 = Input data is sampled at the end of data output time
0 = Input data is sampled at the middle of data output time
Slave Mode:
Input data is always sampled at the middle of data output time, regardless of the SMP setting.

bit 8 **CKE:** SPIx Clock Edge Select bit(1)
1 = Transmit happens on transition from active clock state to Idle clock state
0 = Transmit happens on transition from Idle clock state to active clock state

bit 7 **SSEN:** Slave Select Enable bit (Slave mode)(2)
1 = $\overline{SSx}$ pin is used by the macro in Slave mode; $\overline{SSx}$ pin is used as the slave select input
0 = $\overline{SSx}$ pin is not used by the macro ($\overline{SSx}$ pin will be controlled by the port I/O)

bit 6 **CKP:** Clock Polarity Select bit
1 = Idle state for clock is a high level; active state is a low level
0 = Idle state for clock is a low level; active state is a high level

bit 5 **MSTEN:** Master Mode Enable bit
1 = Master mode
0 = Slave mode

bit 4 **DISSDI:** Disable SDIx Input Port bit
1 = SDIx pin is not used by the module; pin is controlled by port function
0 = SDIx pin is controlled by the module

bit 3 **DISSCK:** Disable SCKx Output Port bit
1 = SCKx pin is not used by the module; pin is controlled by port function
0 = SCKx pin is controlled by the module

bit 2 **MCLKEN:** Master Clock Enable bit(3)
1 = REFO is used by the BRG
0 = FOSC/2 is used by the BRG

bit 1 **SPIFE:** Frame Sync Pulse Edge Select bit
1 = Frame Sync pulse (Idle-to-active edge) coincides with the first bit clock
0 = Frame Sync pulse (Idle-to-active edge) precedes the first bit clock

bit 0 **ENHBUF:** Enhanced Buffer Enable bit
1 = Enhanced Buffer mode is enabled
0 = Enhanced Buffer mode is disabled

Note 1: When AUDEN (SPIxCON1H<15>) = 1, this module functions as if CKE = 0, regardless of its actual value.
2: When FRMEN = 1, SSEN is not used.
3: MCLKEN can only be written when the SPIEN bit = 0.
4: This channel is not meaningful for DSP/PCM mode as LRC follows FRMSYPW.

REGISTER 23-4: CLCxGLSL: CLCx GATE LOGIC INPUT SELECT LOW REGISTER (CONTINUED)

bit 8 **G2D1N:** Gate 2 Data Source 1 Negated Enable bit
1 = Data Source 1 inverted signal is enabled for Gate 2
0 = Data Source 1 inverted signal is disabled for Gate 2

bit 7 **G1D4T:** Gate 1 Data Source 4 True Enable bit
1 = Data Source 4 inverted signal is enabled for Gate 1
0 = Data Source 4 inverted signal is disabled for Gate 1

bit 6 **G1D4N:** Gate 1 Data Source 4 Negated Enable bit
1 = Data Source 4 inverted signal is enabled for Gate 1
0 = Data Source 4 inverted signal is disabled for Gate 1

bit 5 **G1D3T:** Gate 1 Data Source 3 True Enable bit
1 = Data Source 3 inverted signal is enabled for Gate 1
0 = Data Source 3 inverted signal is disabled for Gate 1

bit 4 **G1D3N:** Gate 1 Data Source 3 Negated Enable bit
1 = Data Source 3 inverted signal is enabled for Gate 1
0 = Data Source 3 inverted signal is disabled for Gate 1

bit 3 **G1D2T:** Gate 1 Data Source 2 True Enable bit
1 = Data Source 2 inverted signal is enabled for Gate 1
0 = Data Source 2 inverted signal is disabled for Gate 1

bit 2 **G1D2N:** Gate 1 Data Source 2 Negated Enable bit
1 = Data Source 2 inverted signal is enabled for Gate 1
0 = Data Source 2 inverted signal is disabled for Gate 1

bit 1 **G1D1T:** Gate 1 Data Source 1 True Enable bit
1 = Data Source 1 inverted signal is enabled for Gate 1
0 = Data Source 1 inverted signal is disabled for Gate 1

bit 0 **G1D1N:** Gate 1 Data Source 1 Negated Enable bit
1 = Data Source 1 inverted signal is enabled for Gate 1
0 = Data Source 1 inverted signal is disabled for Gate 1

TABLE 25-2: AES KEY MODE/SOURCE SELECTION

Mode of Operation	KEYMOD<1:0>	KEYSRC<3:0>	Key Source		OTP Address
			SKEYEN = 0	SKEYEN = 1	
128-Bit AES	00	0000(1)	CRYKEY<127:0>		—
		0001	AES Key #1	Key Config Error(2)	<127:0>
		0010	AES Key #2		<255:128>
		0011	AES Key #3		<383:256>
		0100	AES Key #4		<511:384>
		1001	AES Key #5 (RAM)		<127:0>
		1010	AES Key #6 (RAM)		<255:128>
		1011	AES Key #7 (RAM)		<383:256>
		1100	AES Key #8 (RAM)		<511:384>
		1111	Reserved(2)		—
		All Others	Key Config Error(2)		—
192-Bit AES	01	0000(1)	CRYKEY<191:0>		—
		0001	AES Key #1	Key Config Error(2)	<191:0>
		0010	AES Key #2		<383:192>
		1001	AES Key #3 (RAM)		<191:0>
		1010	AES Key #4 (RAM)		<383:192>
		1111	Reserved(2)		—
		All Others	Key Config Error(2)		—
256-Bit AES	10	0000(1)	CRYKEY<255:0>		—
		0001	AES Key #1	Key Config Error(2)	<255:0>
		0010	AES Key #2		<511:256>
		1001	AES Key #3 (RAM)		<255:0>
		1010	AES Key #4 (RAM)		<511:256>
		1111	Reserved(2)		—
		All Others	Key Config Error(2)		—
(Reserved)	11	xxxx	Key Config Error(2)		—

Note 1: This configuration is considered a key configuration error (KEYFAIL bit is set) if SWKYDIS is also set.

2: The KEYFAIL bit (CRYSTAT<1>) is set when these configurations are selected and remains set until a valid configuration is selected.

REGISTER 29-1: CMxCON: COMPARATOR x CONTROL REGISTERS (COMPARATORS 1 THROUGH 3)

R/W-0	R/W-0	R/W-0	U-0	U-0	U-0	R/W-0, HS	R-0, HSC
CON	COE	CPOL	—	—	—	CEVT	COUT
bit 15							bit 8

R/W-0	R/W-0	U-0	R/W-0	U-0	U-0	R/W-0	R/W-0
EVPOL1	EVPOL0	—	CREF	—	—	CCH1	CCH0
bit 7							bit 0

Legend:	HS = Hardware Settable bit	HSC = Hardware Settable/Clearable bit	
R = Readable bit	W = Writable bit	U = Unimplemented bit, read as '0'	
-n = Value at POR	'1' = Bit is set	'0' = Bit is cleared	x = Bit is unknown

bit 15 **CON:** Comparator Enable bit
1 = Comparator is enabled
0 = Comparator is disabled

bit 14 **COE:** Comparator Output Enable bit
1 = Comparator output is present on the CxOUT pin
0 = Comparator output is internal only

bit 13 **CPOL:** Comparator Output Polarity Select bit
1 = Comparator output is inverted
0 = Comparator output is not inverted

bit 12-10 **Unimplemented:** Read as '0'

bit 9 **CEVT:** Comparator Event bit
1 = Comparator event that is defined by EVPOL<1:0> has occurred; subsequent triggers and interrupts are disabled until the bit is cleared
0 = Comparator event has not occurred

bit 8 **COUT:** Comparator Output bit
When CPOL = 0:
1 = VIN+ > VIN-
0 = VIN+ < VIN-
When CPOL = 1:
1 = VIN+ < VIN-
0 = VIN+ > VIN-

bit 7-6 **EVPOL<1:0>:** Trigger/Event/Interrupt Polarity Select bits
11 = Trigger/event/interrupt is generated on any change of the comparator output (while CEVT = 0)
10 = Trigger/event/interrupt is generated on transition of the comparator output:
If CPOL = 0 (non-inverted polarity):
High-to-low transition only.
If CPOL = 1 (inverted polarity):
Low-to-high transition only.
01 = Trigger/event/interrupt is generated on transition of the comparator output:
If CPOL = 0 (non-inverted polarity):
Low-to-high transition only.
If CPOL = 1 (inverted polarity):
High-to-low transition only.
00 = Trigger/event/interrupt generation is disabled

bit 5 **Unimplemented:** Read as '0'

NOTES:

REGISTER 33-5: FOSC: OSCILLATOR CONFIGURATION WORD

U-1	U-1	U-1	U-1	U-1	U-1	U-1	U-1
—	—	—	—	—	—	—	—
bit 23							bit 16

U-1	U-1	U-1	U-1	U-1	U-1	U-1	U-1
—	—	—	—	—	—	—	—
bit 15							bit 8

R/PO-1	R/PO-1	R/PO-1	R/PO-1	R/PO-1	R/PO-1	R/PO-1	R/PO-1
FCKSM1	FCKSM0	IOL1WAY	PLLSS(1)	SOSCSEL	OSCIOFCN	POSCMOD1	POSCMOD0
bit 7							bit 0

Legend:	PO = Program Once bit		
R = Readable bit	W = Writable bit	U = Unimplemented bit, read as ‘0’	
-n = Value at POR	‘1’ = Bit is set	‘0’ = Bit is cleared	x = Bit is unknown

bit 23-8 **Unimplemented:** Read as ‘1’

bit 7-6 **FCKSM<1:0>:** Clock Switching and Fail-Safe Clock Monitor Configuration bits
1x = Clock switching and Fail-Safe Clock Monitor are disabled
01 = Clock switching is enabled, Fail-Safe Clock Monitor is disabled
00 = Clock switching is enabled, Fail-Safe Clock Monitor is enabled

bit 5 **IOL1WAY:** IOLOCK One-Way Set Enable bit
1 = The IOLOCK bit (OSCCON<6>) can be set once, provided the unlock sequence has been completed; once set, the Peripheral Pin Select registers cannot be written to a second time
0 = The IOLOCK bit can be set and cleared as needed, provided the unlock sequence has been completed

bit 4 **PLLSS:** PLL Block Secondary Selection Configuration bit(1)
1 = PLL is driven by the Primary Oscillator
0 = PLL is driven by the FRC Oscillator

bit 3 **SOSCSEL:** SOSC Selection bit
1 = SOSC circuit is selected
0 = Digital (SCLKI) mode(2)

bit 2 **OSCIOFCN:** OSCO Pin Configuration bit
If POSCMOD<1:0> = 11 or 00:
1 = OSCO/CLKO/RC15 functions as CLKO (FOSC/2)
0 = OSCO/CLKO/RC15 functions as port I/O (RC15)
If POSCMOD<1:0> = 10 or 01:
OSCIOFCN has no effect on OSCO/CLKO/RC15.

bit 1-0 **POSCMOD<1:0>:** Primary Oscillator Configuration bits
11 = Primary Oscillator mode is disabled
10 = HS Oscillator mode is selected (HS mode is used if crystal ≥ 10 MHz)
01 = XT Oscillator mode is selected (XT mode is used if crystal < 10 MHz)
00 = EC Oscillator mode is selected

Note 1: Used only when the PLL block is not being used as the system clock source.
2: Ensure that the SCLKI pin is made a digital input while using this configuration (see Table 11-1).

FIGURE 36-14: SPIx MODULE MASTER MODE TIMING CHARACTERISTICS (CKE = 1)

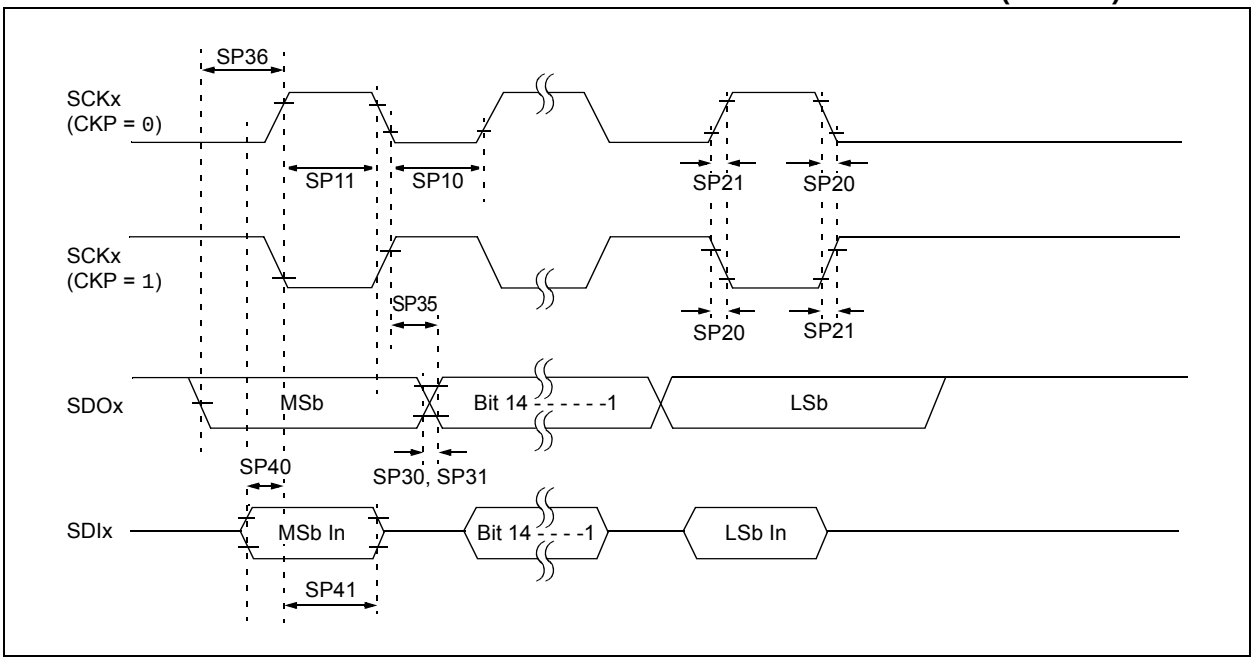


TABLE 36-35: SPIx MODULE MASTER MODE TIMING REQUIREMENTS (CKE = 1)

AC CHARACTERISTICS			Standard Operating Conditions: 2.0V to 3.6V (unless otherwise stated) Operating temperature -40°C ≤ TA ≤ +85°C for Industrial				
Param No.	**Symbol**	**Characteristic**	**Min**	**Typ(1)**	**Max**	**Units**	**Conditions**
SP10	TscL	SCKx Output Low Time(2)	TCY/2	—	—	ns	
SP11	TscH	SCKx Output High Time(2)	TCY/2	—	—	ns	
SP20	TscF	SCKx Output Fall Time(3)	—	10	25	ns	
SP21	TscR	SCKx Output Rise Time(3)	—	10	25	ns	
SP30	TdoF	SDOx Data Output Fall Time(3)	—	10	25	ns	
SP31	TdoR	SDOx Data Output Rise Time(3)	—	10	25	ns	
SP35	TscH2doV, TscL2doV	SDOx Data Output Valid After SCKx Edge	—	—	30	ns	
SP36	TdoV2sc, TdoV2scL	SDOx Data Output Setup to First SCKx Edge	30	—	—	ns	
SP40	TdiV2scH, TdiV2scL	Setup Time of SDIx Data Input to SCKx Edge	20	—	—	ns	
SP41	TscH2diL, TscL2diL	Hold Time of SDIx Data Input to SCKx Edge	20	—	—	ns	

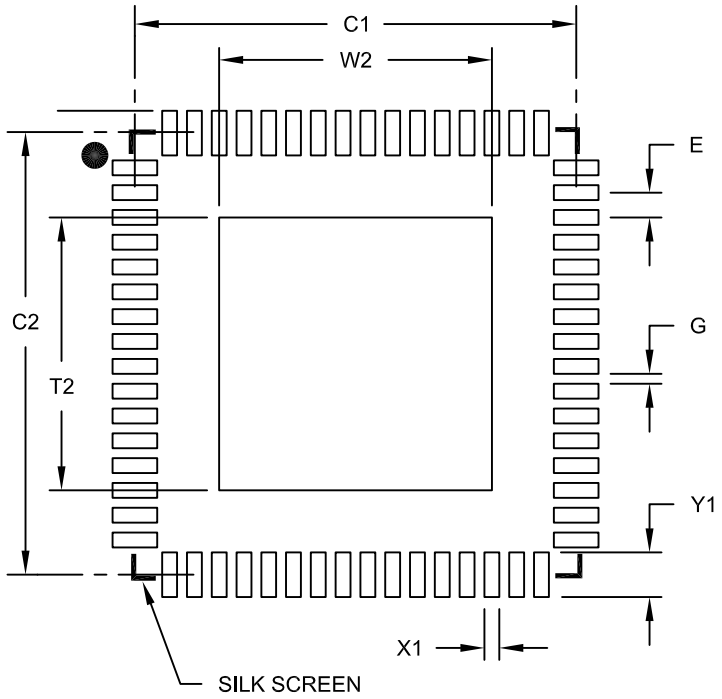
Note 1: Data in "Typ" column is at 3.3V, +25°C unless otherwise stated. Parameters are for design guidance only and are not tested.

2: The minimum clock period for SCKx is 100 ns. Therefore, the clock generated in Master mode must not violate this specification.

3: Assumes 50 pF load on all SPIx pins.

64-Lead Plastic Quad Flat, No Lead Package (MR) – 9x9x0.9 mm Body [QFN]
With 0.40 mm Contact Length and 5.40x5.40mm Exposed Pad

Note: For the most current package drawings, please see the Microchip Packaging Specification located at http://www.microchip.com/packaging



RECOMMENDED LAND PATTERN

Units		MILLIMETERS		
Dimension Limits		MIN	NOM	MAX
Contact Pitch	E		0.50 BSC	
Optional Center Pad Width	W2			5.50
Optional Center Pad Length	T2			5.50
Contact Pad Spacing	C1		8.90	
Contact Pad Spacing	C2		8.90	
Contact Pad Width (X64)	X1			0.30
Contact Pad Length (X64)	Y1			0.85
Distance Between Pads	G	0.20		

Notes:

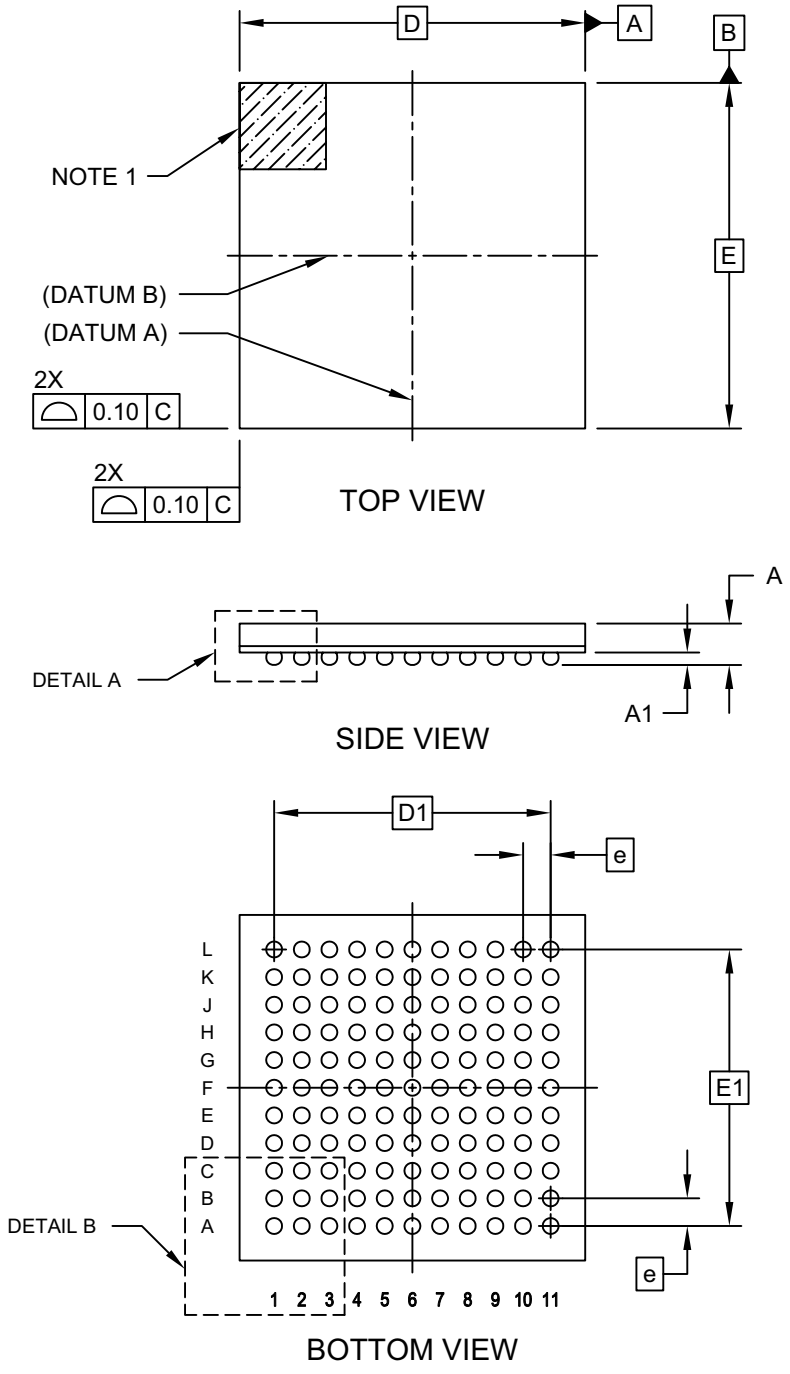
1. Dimensioning and tolerancing per ASME Y14.5M

BSC: Basic Dimension. Theoretically exact value shown without tolerances.

Microchip Technology Drawing No. C04-2154A

121-Ball Plastic Thin Profile Fine Pitch Ball Grid Array (BG) - 10x10x1.10 mm Body [TFBGA]

Note: For the most current package drawings, please see the Microchip Packaging Specification located at http://www.microchip.com/packaging



Microchip Technology Drawing C04-148 Rev F Sheet 1 of 2