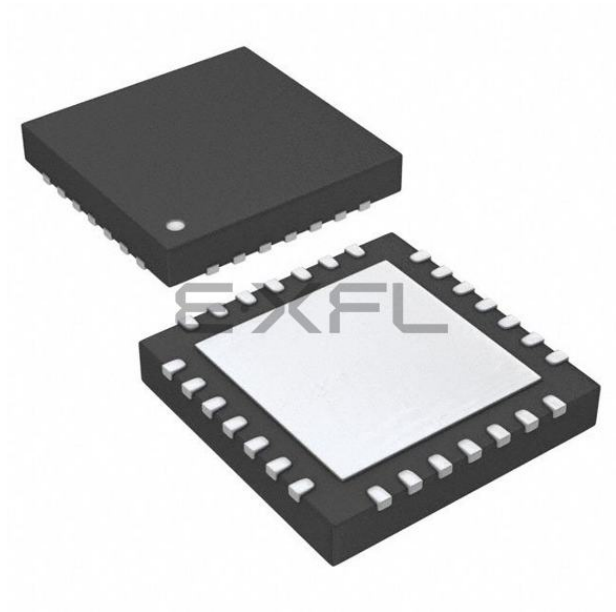
Microchip Technology - PIC24FJ128GA702-I/MV Datasheet



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Applications of "Embedded - Microcontrollers"

Details	
Product Status	Active
Core Processor	PIC
Core Size	16-Bit
Speed	32MHz
Connectivity	I²C, IrDA, LINbus, SPI, UART/USART
Peripherals	Brown-out Detect/Reset, DMA, I²S, LVD, POR, PWM, WDT
Number of I/O	22
Program Memory Size	128KB (43K x 24)
Program Memory Type	FLASH
EEPROM Size	-
RAM Size	16K x 8
Voltage - Supply (Vcc/Vdd)	2V ~ 3.6V
Data Converters	A/D 10x12b
Oscillator Type	Internal
Operating Temperature	-40°C ~ 85°C (TA)
Mounting Type	Surface Mount
Package / Case	28-UFQFN Exposed Pad
Supplier Device Package	28-UQFN (4x4)
Purchase URL	https://www.e-xfl.com/product-detail/microchip-technology/pic24fj128ga702-i-mv

TABLE 1-3: PIC24FJ256GA705 FAMILY PINOUT DESCRIPTIONS (CONTINUED)

Pin Function	Pin Number/Grid Locator				I/O	Input Buffer	Description
	28-Pin SOIC, SSOP, SPDIP	28-Pin QFN, UQFN	44-Pin TQFP	48-Pin QFN/TQFP			
IOCB0	4	1	21	23	I	ST	PORTB Interrupt-on-Change
IOCB1	5	2	22	24	I	ST	
IOCB2	6	3	23	25	I	ST	
IOCB3	7	4	24	26	I	ST	
IOCB4	11	8	33	36	I	ST	
IOCB5	14	11	41	45	I	ST	
IOCB6	15	12	42	46	I	ST	
IOCB7	16	13	43	47	I	ST	
IOCB8	17	14	44	48	I	ST	
IOCB9	18	15	1	1	I	ST	
IOCB10	21	18	8	9	I	ST	
IOCB11	22	19	9	10	I	ST	
IOCB12	23	20	10	11	I	ST	
IOCB13	24	21	11	12	I	ST	
IOCB14	25	22	14	15	I	ST	
IOCB15	26	23	15	16	I	ST	
IOCC1	—	—	26	28	I	ST	PORTC Interrupt-on-Change
IOCC2	—	—	27	29	I	ST	
IOCC3	—	—	36	39	I	ST	
IOCC4	—	—	37	40	I	ST	
IOCC5	—	—	38	41	I	ST	
IOCC6	—	—	2	2	I	ST	
IOCC7	—	—	3	3	I	ST	
IOCC8	—	—	4	4	I	ST	
IOCC9	—	—	5	5	I	ST	
$\overline{\text{MCLR}}$	1	26	18	19	I	ST	Master Clear (device Reset) Input. This line is brought low to cause a Reset.
OCM1A	16	13	43	47	O	DIG	MCCP1 Outputs
OCM1B	17	14	44	48	O	DIG	
OCM1C	21	18	8	9	O	DIG	
OCM1D	24	21	11	12	O	DIG	
OCM1E	14	11	41	45	O	DIG	
OCM1F	15	12	42	46	O	DIG	
OSCI	9	6	30	33	I	ANA/ST	Main Oscillator Input Connection
OSCO	10	7	31	34	O	ANA	Main Oscillator Output Connection

Legend: TTL = TTL input buffer
ANA = Analog level input/output
DIG = Digital input/output
ST = Schmitt Trigger input buffer
I^2C = I^2C/SMBus input buffer
XCVR = Dedicated Transceiver

2.4 Voltage Regulator Pin (VCAP)

Note: This section applies only to PIC24FJ devices with an on-chip voltage regulator.

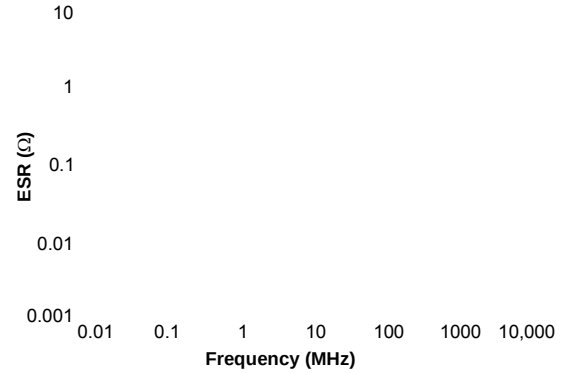
Refer to **Section 29.3 "On-Chip Voltage Regulator"** for details on connecting and using the on-chip regulator.

A low-ESR (< 5Ω) capacitor is required on the VCAP pin to stabilize the voltage regulator output voltage. The VCAP pin must not be connected to VDD and must use a capacitor of 10 µF connected to ground. The type can be ceramic or tantalum. Suitable examples of capacitors are shown in Table 2-1. Capacitors with equivalent specifications can be used.

Designers may use Figure 2-3 to evaluate the ESR equivalence of candidate devices.

The placement of this capacitor should be close to VCAP. It is recommended that the trace length not exceed 0.25 inch (6 mm). Refer to **Section 32.0 "Electrical Characteristics"** for additional information.

FIGURE 2-3: FREQUENCY vs. ESR PERFORMANCE FOR SUGGESTED VCAP



Note: Typical data measurement at +25°C, 0V DC bias.

TABLE 2-1: SUITABLE CAPACITOR EQUIVALENTS (0805 CASE SIZE)

Make	Part #	Nominal Capacitance	Base Tolerance	Rated Voltage
TDK	C2012X5R1E106K085AC	10 µF	±10%	25V
TDK	C2012X5R1C106K085AC	10 µF	±10%	16V
Kemet	C0805C106M4PACTU	10 µF	±10%	16V
Murata	GRM21BR61E106KA3L	10 µF	±10%	25V
Murata	GRM21BR61C106KE15	10 µF	±10%	16V

2.7 Configuration of Analog and Digital Pins During ICSP Operations

If an ICSP compliant emulator is selected as a debugger, it automatically initializes all of the A/D input pins (ANx) as “digital” pins. This is done by clearing all bits in the ANSx registers. Refer to **Section 11.2 “Configuring Analog Port Pins (ANSx)”** for more specific information.

The bits in these registers that correspond to the A/D pins that initialized the emulator must not be changed by the user application firmware; otherwise, communication errors will result between the debugger and the device.

If your application needs to use certain A/D pins as analog input pins during the debug session, the user application must modify the appropriate bits during initialization of the A/D module, as follows:

- Set the bits corresponding to the pin(s) to be configured as analog. Do not change any other bits, particularly those corresponding to the PGCx/PGDx pair, at any time.

When a Microchip debugger/emulator is used as a programmer, the user application firmware must correctly configure the ANSx registers. Automatic initialization of these registers is only done during debugger operation. Failure to correctly configure the register(s) will result in all A/D pins being recognized as analog input pins, resulting in the port value being read as a logic ‘0’, which may affect user application functionality.

2.8 Unused I/Os

Unused I/O pins should be configured as outputs and driven to a logic low state. Alternatively, connect a 1 kΩ to 10 kΩ resistor to V_{SS} on unused pins and drive the output to logic low.

4.2.5 EXTENDED DATA SPACE (EDS)

The Extended Data Space (EDS) allows PIC24F devices to address a much larger range of data than would otherwise be possible with a 16-bit address range. EDS includes any additional internal data memory not directly accessible by the lower 32-Kbyte data address space and any external memory through EPMP.

In addition, EDS also allows read access to the program memory space. This feature is called Program Space Visibility (PSV) and is discussed in detail in **Section 4.3.3 "Reading Data from Program Memory Using EDS"**.

Figure 4-3 displays the entire EDS space. The EDS is organized as pages, called EDS pages, with one page equal to the size of the EDS window (32 Kbytes). A particular EDS page is selected through the Data Space Read Page register (DSRPAG) or the Data Space Write Page register (DSWPAG). For PSV, only the DSRPAG register is used. The combination of the DSRPAG register value and the 16-bit wide data address forms a 24-bit Effective Address (EA).

The data addressing range of the PIC24FJ256GA705 family devices depends on the version of the Enhanced Parallel Master Port implemented on a particular device; this is, in turn, a function of device pin count. Table 4-12 lists the total memory accessible by each of the devices in this family. For more details on accessing external memory using EPMP, refer to the *"dsPIC33/PIC24 Family Reference Manual*", **"Enhanced Parallel Master Port (EPMP)"** (DS39730).

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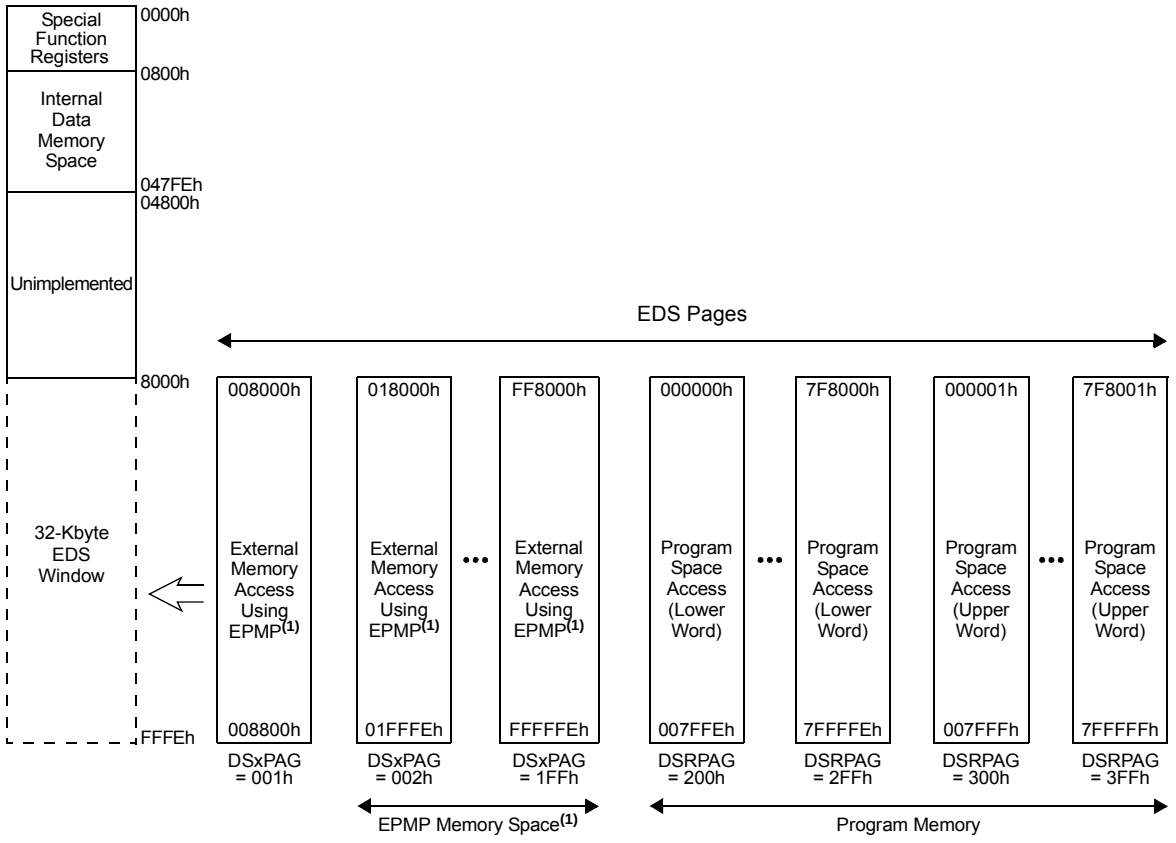
TABLE 4-12: TOTAL ACCESSIBLE DATA MEMORY

Family	Internal RAM	External RAM Access Using EPMP
PIC24FJXXXGA70X	16K	1K

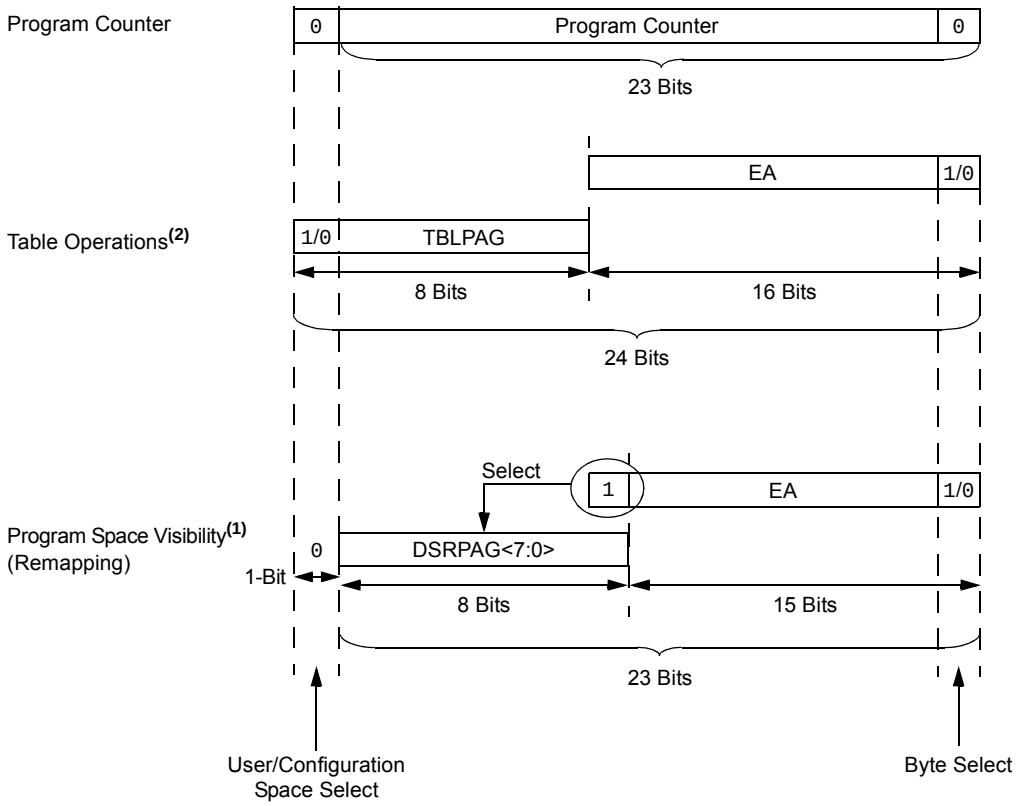
Note:	Accessing Page 0 in the EDS window will generate an address error trap as Page 0 is the base data memory (data locations, 0800h to 7FFFh, in the lower Data Space).

FIGURE 4-3: EXTENDED DATA SPACE



Note 1: The range of addressable memory available is dependent on the device pin count and EPMP implementation.

FIGURE 4-7: DATA ACCESS FROM PROGRAM SPACE ADDRESS GENERATION



Note 1: DSRPAG<8> acts as word select. DSRPAG<9> should always be '1' to map program memory to data memory.

2: The instructions, TBLRDH/TBLWTH/TBLRDL/TBLWTL, decide if the higher or lower word of program memory is accessed. TBLRDH/TBLWTH instructions access the higher word and TBLRDL/TBLWTL instructions access the lower word. Table Read operations are permitted in the configuration memory space.

TABLE 7-3: RESET DELAY TIMES FOR VARIOUS DEVICE RESETS

Reset Type	Clock Source	$\overline{\text{SYSRST}}$ Delay	System Clock Delay	Notes
POR	EC	TPOR + TSTARTUP + TRST	—	**1, 2, 3**
	ECPLL	TPOR + TSTARTUP + TRST	TLOCK	**1, 2, 3, 5**
	XT, HS, SOSC	TPOR + TSTARTUP + TRST	TOST	**1, 2, 3, 4**
	XTPLL, HSPLL	TPOR + TSTARTUP + TRST	TOST + TLOCK	**1, 2, 3, 4, 5**
	FRC, OSCFDIV	TPOR + TSTARTUP + TRST	TFRC	**1, 2, 3, 6, 7**
	FRCPLL	TPOR + TSTARTUP + TRST	TFRC + TLOCK	**1, 2, 3, 5, 6**
	LPRC	TPOR + TSTARTUP + TRST	TLPRC	**1, 2, 3, 6**
BOR	EC	TSTARTUP + TRST	—	**2, 3**
	ECPLL	TSTARTUP + TRST	TLOCK	**2, 3, 5**
	XT, HS, SOSC	TSTARTUP + TRST	TOST	**2, 3, 4**
	XTPLL, HSPLL	TSTARTUP + TRST	TOST + TLOCK	**2, 3, 4, 5**
	FRC, OSCFDIV	TSTARTUP + TRST	TFRC	**2, 3, 6, 7**
	FRCPLL	TSTARTUP + TRST	TFRC + TLOCK	**2, 3, 5, 6**
	LPRC	TSTARTUP + TRST	TLPRC	**2, 3, 6**
$\overline{\text{MCLR}}$	Any Clock	TRST	—	**3**
WDT	Any Clock	TRST	—	**3**
Software	Any clock	TRST	—	**3**
Illegal Opcode	Any Clock	TRST	—	**3**
Uninitialized W	Any Clock	TRST	—	**3**
Trap Conflict	Any Clock	TRST	—	**3**

Note 1: TPOR = Power-on Reset delay (10 μs nominal).

2: TSTARTUP = TVREG.

3: TRST = Internal State Reset Time (2 μs nominal).

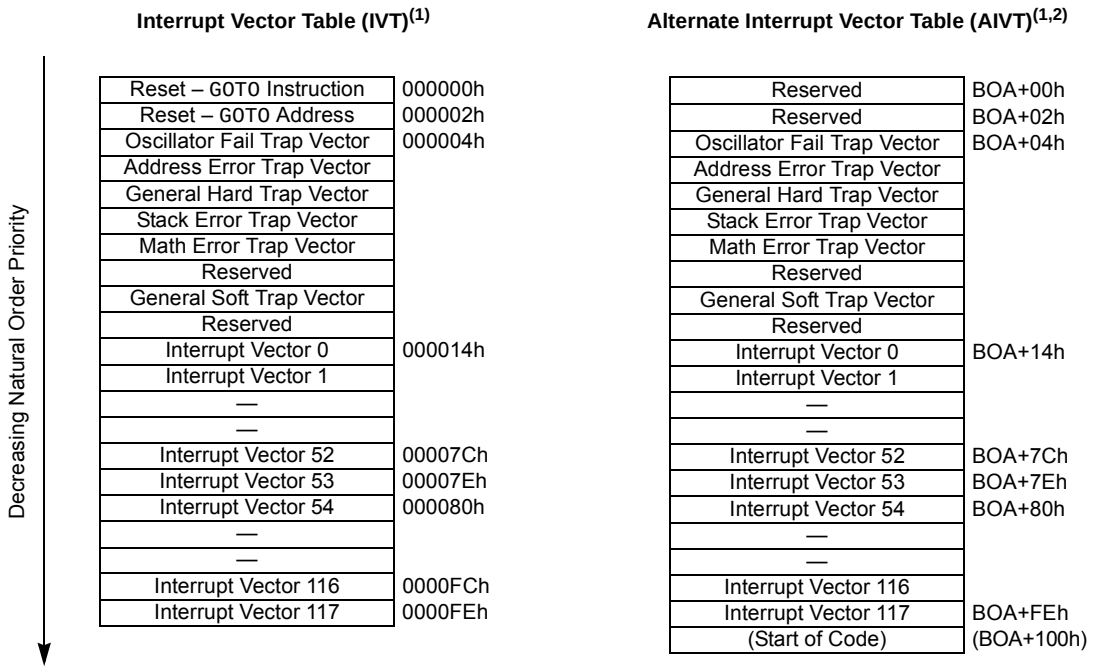
4: TOST = Oscillator Start-up Timer (OST). A 10-bit counter counts 1024 oscillator periods before releasing the oscillator clock to the system.

5: TLOCK = PLL Lock Time.

6: TFRC and TLPRC = RC Oscillator Start-up Times.

7: If Two-Speed Start-up is enabled, regardless of the Primary Oscillator selected, the device starts with FRC so the system clock delay is just TFRC, and in such cases, FRC start-up time is valid; it switches to the Primary Oscillator after its respective clock delay.

FIGURE 8-1: PIC24F INTERRUPT VECTOR TABLES



Legend: BOA: Base Offset Address for AIVT, which is the starting address of the last page of the Boot Segment. All addresses are in hexadecimal.

Note 1: See Table 8-2 for the interrupt vector list.

2: AIVT is only available when a Boot Segment is implemented.

TABLE 8-1: TRAP VECTOR DETAILS

Vector Number	IVT Address	AIVT Address	Trap Source
0	000004h	BOA+04h	Oscillator Failure
1	000006h	BOA+06h	Address Error
2	000008h	BOA+08h	General Hardware Error
3	00000Ah	BOA+0Ah	Stack Error
4	00000Ch	BOA+0Ch	Math Error
5	00000Eh	BOA+0Eh	Reserved
6	000010h	BOA+10h	General Software Error
7	000012h	BOA+12h	Reserved

Legend: BOA = Base Offset Address for AIVT segment, which is the starting address of the last page of the Boot Segment.

REGISTER 8-1: SR: ALU STATUS REGISTER(1)

U-0	U-0	U-0	U-0	U-0	U-0	U-0	R/W-0
—	—	—	—	—	—	—	DC
bit 15							bit 8

R/W-0(3)	R/W-0(3)	R/W-0(3)	R-0	R/W-0	R/W-0	R/W-0	R/W-0
IPL2(2)	IPL1(2)	IPL0(2)	RA	N	OV	Z	C
bit 7							bit 0

Legend:			
R = Readable bit	W = Writable bit	U = Unimplemented bit, read as '0'	
-n = Value at POR	'1'= Bit is set	'0' = Bit is cleared	x = Bit is unknown

bit 7-5 **IPL<2:0>:** CPU Interrupt Priority Level Status bits(2,3)
111 = CPU Interrupt Priority Level is 7 (15); user interrupts are disabled
110 = CPU Interrupt Priority Level is 6 (14)
101 = CPU Interrupt Priority Level is 5 (13)
100 = CPU Interrupt Priority Level is 4 (12)
011 = CPU Interrupt Priority Level is 3 (11)
010 = CPU Interrupt Priority Level is 2 (10)
001 = CPU Interrupt Priority Level is 1 (9)
000 = CPU Interrupt Priority Level is 0 (8)

Note 1: For complete register details, see Register 3-1.

2: The IPL<2:0> Status bits are concatenated with the IPL3 Status bit (CORCON<3>) to form the CPU Interrupt Priority Level (IPL). The value in parentheses indicates the IPL when IPL3 = 1. User interrupts are disabled when IPL3 = 1.

3: The IPL<2:0> Status bits are read-only when the NSTDIS bit (INTCON1<15>) = 1.

10.0 POWER-SAVING FEATURES

Note: This data sheet summarizes the features of this group of PIC24F devices. It is not intended to be a comprehensive reference source. For more information, refer to the *"dsPIC33/PIC24 Family Reference Manual"*, **"Power-Saving Features"** (DS39698), which is available from the Microchip web site (www.microchip.com). The information in this data sheet supersedes the information in the FRM.

The PIC24FJ256GA705 family of devices provides the ability to manage power consumption by selectively managing clocking to the CPU and the peripherals. In general, a lower clock frequency and a reduction in the number of circuits being clocked constitutes lower consumed power. All PIC24F devices manage power consumption in four different ways:

- Clock Frequency
- Instruction-Based Sleep and Idle modes
- Software Controlled Doze mode
- Selective Peripheral Control in Software

Combinations of these methods can be used to selectively tailor an application's power consumption, while still maintaining critical application features, such as timing-sensitive communications.

10.1 Clock Frequency and Clock Switching

PIC24F devices allow for a wide range of clock frequencies to be selected under application control. If the system clock configuration is not locked, users can choose low-power or high-precision oscillators by simply changing the NOSC<2:0> bits. The process of changing a system clock during operation, as well as limitations to the process, are discussed in more detail in **Section 9.0 "Oscillator Configuration"**.

10.2 Instruction-Based Power-Saving Modes

PIC24F devices have two special power-saving modes that are entered through the execution of a special PWRSAV instruction. Sleep mode stops clock operation and halts all code execution; Idle mode halts the CPU and code execution, but allows peripheral modules to continue operation. The assembly syntax of the PWRSAV instruction is shown in Example 10-1.

The MPLAB® XC16 C compiler offers "built-in" functions for the power-saving modes as follows:

```
Idle();    // places part in Idle
Sleep();   // places part in Sleep
```

Sleep and Idle modes can be exited as a result of an enabled interrupt, WDT time-out or a device Reset. When the device exits these modes, it is said to "wake-up".

Note: SLEEP_MODE and IDLE_MODE are constants defined in the assembler include file for the selected device.

10.2.1 SLEEP MODE

Sleep mode has these features:

- The system clock source is shut down. If an on-chip oscillator is used, it is turned off.
- The device current consumption will be reduced to a minimum provided that no I/O pin is sourcing current.
- The Fail-Safe Clock Monitor does not operate during Sleep mode since the system clock source is disabled.
- The LPRC clock will continue to run in Sleep mode if the WDT is enabled.
- The WDT, if enabled, is automatically cleared prior to entering Sleep mode.
- Some device features or peripherals may continue to operate in Sleep mode. This includes items, such as the Input Change Notification (ICN) on the I/O ports or peripherals that use an external clock input. Any peripheral that requires the system clock source for its operation will be disabled in Sleep mode.

The device will wake-up from Sleep mode on any of the these events:

- On any interrupt source that is individually enabled
- On any form of device Reset
- On a WDT time-out

On wake-up from Sleep, the processor will restart with the same clock source that was active when Sleep mode was entered.

EXAMPLE 10-1: PWRSAV INSTRUCTION SYNTAX

```
PWRSAV    #SLEEP_MODE            ; Put the device into SLEEP mode
PWRSAV    #IDLE_MODE             ; Put the device into IDLE mode
```

11.5.3.2 Output Mapping

In contrast to inputs, the outputs of the Peripheral Pin Select options are mapped on the basis of the pin. In this case, a control register associated with a particular pin dictates the peripheral output to be mapped. The RPORx registers are used to control output mapping. Each register contains two 6-bit fields, with each field being associated with one RPn pin (see Register 11-32 through Register 11-46). The value of the bit field corresponds to one of the peripherals and that peripheral's output is mapped to the pin (see Table 11-7).

Because of the mapping technique, the list of peripherals for output mapping also includes a null value of '000000'. This permits any given pin to remain disconnected from the output of any of the pin-selectable peripherals.

TABLE 11-7: SELECTABLE OUTPUT SOURCES (MAPS FUNCTION TO OUTPUT)

Output Function Number	Function	Output Name
0	None (Pin Disabled)	—
1	C1OUT	Comparator 1 Output
2	C2OUT	Comparator 2 Output
3	U1TX	UART1 Transmit
4	$\overline{\text{U1RTS}}$	UART1 Request-to-Send
5	U2TX	UART2 Transmit
6	$\overline{\text{U2RTS}}$	UART2 Request-to-Send
7	SDO1	SPI1 Data Output
8	SCK1OUT	SPI1 Clock Output
9	SS1OUT	SPI1 Slave Select Output
10	SDO2	SPI2 Data Output
11	SCK2OUT	SPI2 Clock Output
12	SS2OUT	SPI2 Slave Select Output
13	OC1	Output Compare 1
14	OC2	Output Compare 2
15	OC3	Output Compare 3
16	OCM2A	CCP2A Output Compare
17	OCM2B	CCP2B Output Compare
18	OCM3A	CCP3A Output Compare
19	OCM3B	CCP3B Output Compare
20	OCM4A	CCP4A Output Compare
21	OCM4B	CCP4B Output Compare
22	Reserved	—
23	SDO3	SPI3 Data Output
24	SCK3OUT	SPI3 Clock Output
25	SS3OUT	SPI3 Slave Select Output
26	C3OUT	Comparator 3 Output
27	PWRGT	RTCC Power Control
28	REFO	Reference Clock Output
29	CLC1OUT	CLC1 Output
30	CLC2OUT	CLC2 Output
31	RTCC	RTCC Clock Output

REGISTER 11-40: RPOR8: PERIPHERAL PIN SELECT OUTPUT REGISTER 8

U-0	U-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0
—	—	RP17R5	RP17R4	RP17R3	RP17R2	RP17R1	RP17R0
bit 15							bit 8

U-0	U-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0
—	—	RP16R5	RP16R4	RP16R3	RP16R2	RP16R1	RP16R0
bit 7							bit 0

Legend:			
R = Readable bit	W = Writable bit	U = Unimplemented bit, read as '0'	
-n = Value at POR	'1' = Bit is set	'0' = Bit is cleared	x = Bit is unknown

bit 15-14 **Unimplemented:** Read as '0'

bit 13-8 **RP17R<5:0>:** RP17 Output Pin Mapping bits
Peripheral Output Number n is assigned to pin, RP17 (see Table 11-7 for peripheral function numbers).

bit 7-6 **Unimplemented:** Read as '0'

bit 5-0 **RP16R<5:0>:** RP16 Output Pin Mapping bits
Peripheral Output Number n is assigned to pin, RP16 (see Table 11-7 for peripheral function numbers).

REGISTER 11-41: RPOR9: PERIPHERAL PIN SELECT OUTPUT REGISTER 9

U-0	U-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0
—	—	RP19R5	RP19R4	RP19R3	RP19R2	RP19R1	RP19R0
bit 15							bit 8

U-0	U-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0
—	—	RP18R5	RP18R4	RP18R3	RP18R2	RP18R1	RP18R0
bit 7							bit 0

Legend:			
R = Readable bit	W = Writable bit	U = Unimplemented bit, read as '0'	
-n = Value at POR	'1' = Bit is set	'0' = Bit is cleared	x = Bit is unknown

bit 15-14 **Unimplemented:** Read as '0'

bit 13-8 **RP19R<5:0>:** RP19 Output Pin Mapping bits
Peripheral Output Number n is assigned to pin, RP19 (see Table 11-7 for peripheral function numbers).

bit 7-6 **Unimplemented:** Read as '0'

bit 5-0 **RP18R<5:0>:** RP18 Output Pin Mapping bits
Peripheral Output Number n is assigned to pin, RP18 (see Table 11-7 for peripheral function numbers).

12.0 TIMER1

Note:	This data sheet summarizes the features of this group of PIC24F devices. It is not intended to be a comprehensive reference source. For more information, refer to the *"dsPIC33/PIC24 Family Reference Manual"*, **"Timers"** (DS39704), which is available from the Microchip web site (www.microchip.com). The information in this data sheet supersedes the information in the FRM.

The Timer1 module is a 16-bit timer, which can serve as the time counter for the Real-Time Clock (RTC) or operate as a free-running, interval timer/counter. Timer1 can operate in three modes:

- 16-Bit Timer
- 16-Bit Synchronous Counter
- 16-Bit Asynchronous Counter

Timer1 also supports these features:

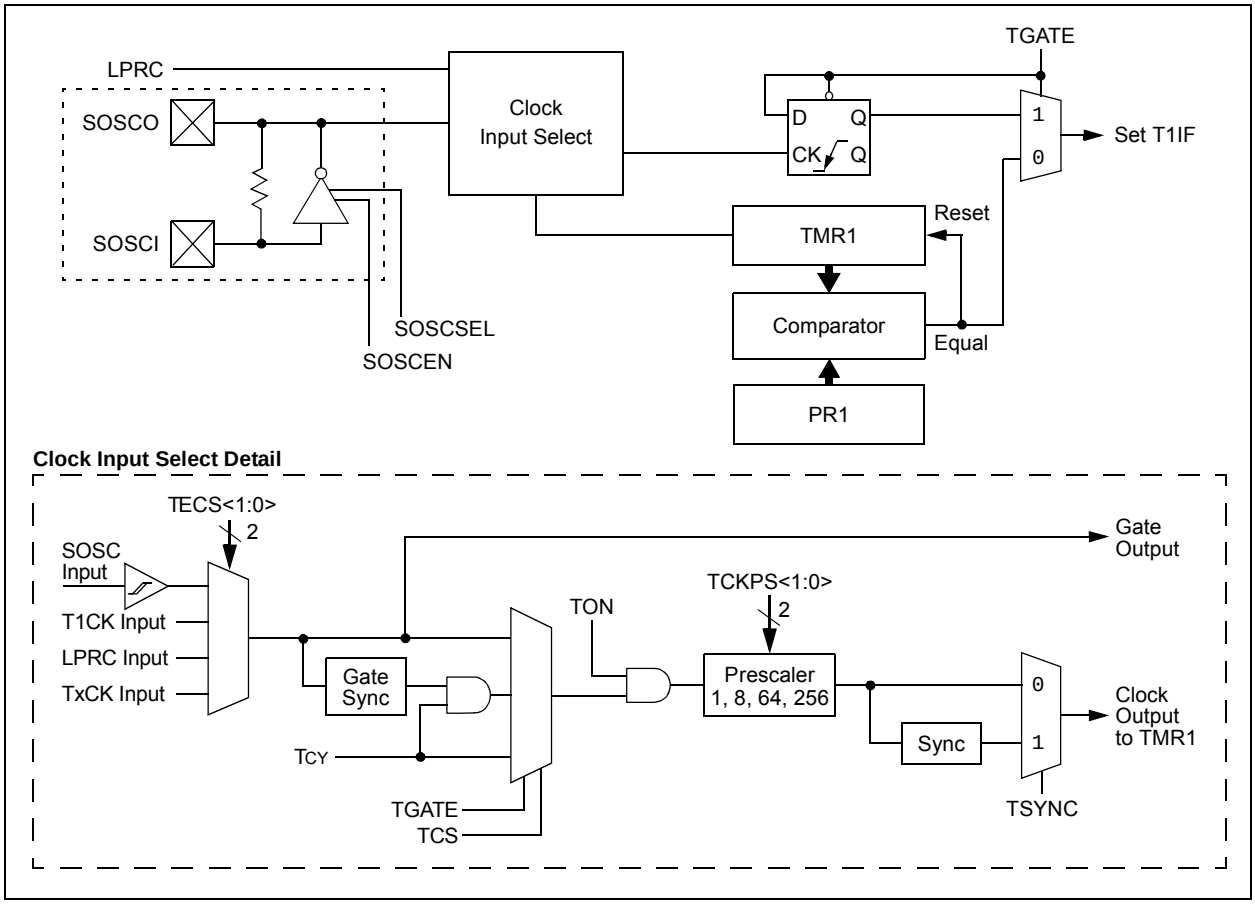
- Timer Gate Operation
- Selectable Prescaler Settings
- Timer Operation during CPU Idle and Sleep modes
- Interrupt on 16-Bit Period Register Match or Falling Edge of External Gate Signal

Figure 12-1 presents a block diagram of the 16-bit timer module.

To configure Timer1 for operation:

1. Set the TON bit (= 1).
2. Select the timer prescaler ratio using the TCKPS<1:0> bits.
3. Set the Clock and Gating modes using the TCS, TECS<1:0> and TGATE bits.
4. Set or clear the TSYNC bit to configure synchronous or asynchronous operation.
5. Load the timer period value into the PR1 register.
6. If interrupts are required, set the interrupt enable bit, T1IE. Use the priority bits, T1IP<2:0>, to set the interrupt priority.

FIGURE 12-1: 16-BIT TIMER1 MODULE BLOCK DIAGRAM



REGISTER 14-2: ICxCON2: INPUT CAPTURE x CONTROL REGISTER 2 (CONTINUED)

bit 4-0 **SYNCSEL<4:0>:** Synchronization/Trigger Source Selection bits

11111 = Not used
11110 = Not used
11101 = Not used
11100 = CTMU trigger(1)
11011 = A/D interrupt(1)
11010 = CMP3 trigger(1)
11001 = CMP2 trigger(1)
11000 = CMP1 trigger(1)
10111 = Not used
10110 = MCCP4 IC/OC interrupt
10101 = MCCP3 IC/OC interrupt
10100 = MCCP2 IC/OC interrupt
10011 = MCCP1 IC/OC interrupt
10010 = IC3 interrupt(2)
10001 = IC2 interrupt(2)
10000 = IC1 interrupt(2)
01111 = Not used
01110 = Not used
01101 = Timer3 match event
01100 = Timer2 match event
01011 = Timer1 match event
01010 = Not used
01001 = Not used
01000 = Not used
00111 = MCCP4 Sync/Trigger out
00110 = MCCP3 Sync/Trigger out
00101 = MCCP2 Sync/Trigger out
00100 = MCCP1 Sync/Trigger out
00011 = OC3 Sync/Trigger out
00010 = OC2 Sync/Trigger out
00001 = OC1 Sync/Trigger out
00000 = Off

Note 1: Use these inputs as Trigger sources only and never as Sync sources.
2: Never use an Input Capture x module as its own Trigger source by selecting this mode.

NOTES:

16.2 General Purpose Timer

Timer mode is selected when CCSEL = 0 and MOD<3:0> = 0000. The timer can function as a 32-bit timer or a dual 16-bit timer, depending on the setting of the T32 bit (Table 16-1).

TABLE 16-1: TIMER OPERATION MODE

T32 (CCPxCON1L<5>)	Operating Mode
0	Dual Timer Mode (16-bit)
1	Timer Mode (32-bit)

Dual 16-Bit Timer mode provides a simple timer function with two independent 16-bit timer/counters. The primary timer uses the CCPxTMRL and CCPxPRL registers. Only the primary timer can interact with other modules on the device. It generates the MCCPx Sync out signals for use by other MCCPx modules. It can also use the SYNC<4:0> bits signal generated by other modules.

The secondary timer uses the CCPxTMRH and CCPxPRH registers. It is intended to be used only as a periodic interrupt source for scheduling CPU events. It does not generate an output Sync/Trigger signal like the primary time base. In Dual Timer mode, the Timer Period High register, CCPxPRH, generates the MCCPx compare event (CCPxIF) used by many other modules on the device.

The 32-Bit Timer mode uses the CCPxTMRL and CCPxTMRH registers, together, as a single 32-bit timer. When CCPxTMRL overflows, CCPxTMRH increments by one. This mode provides a simple timer function when it is important to track long time periods. Note that the T32 bit (CCPxCON1L<5>) should be set before the CCPxTMRL or CCPxPRH registers are written to initialize the 32-bit timer.

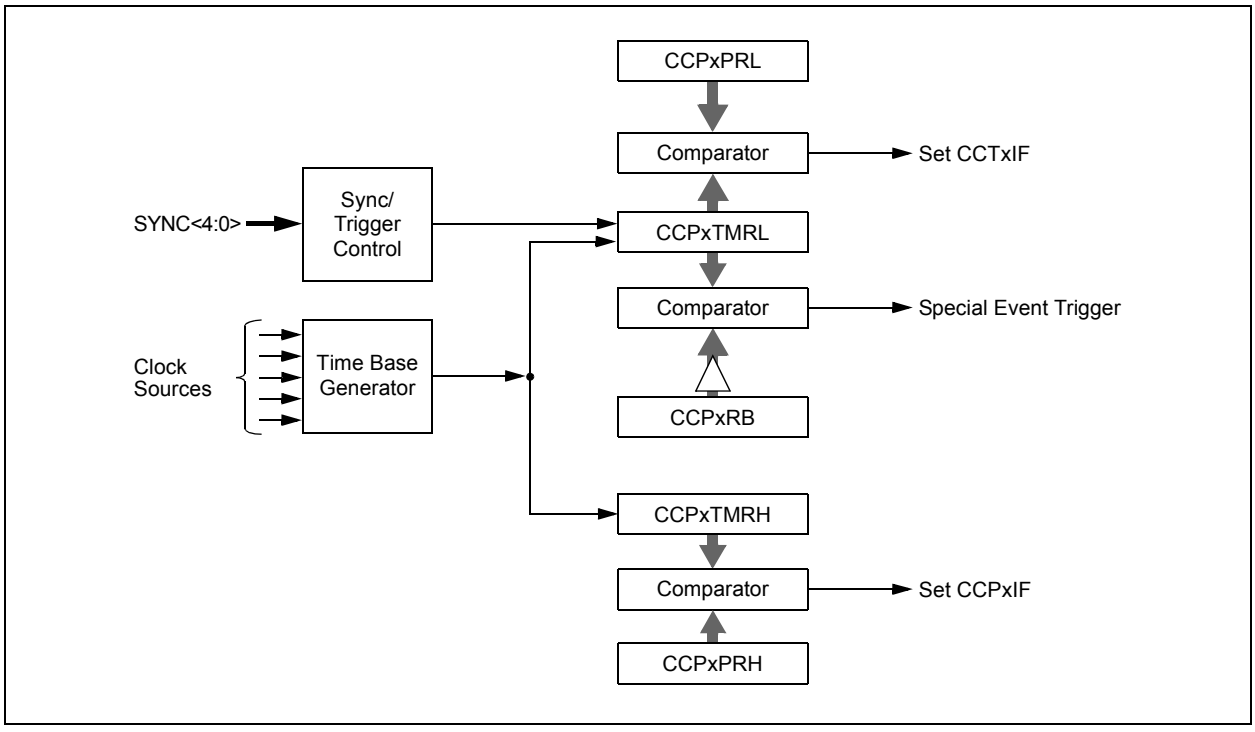
16.2.1 SYNC AND TRIGGER OPERATION

In both 16-bit and 32-bit modes, the timer can also function in either Synchronization (“Sync”) or Trigger mode operation. Both use the SYNC<4:0> bits (CCPxCON1H<4:0>) to determine the input signal source. The difference is how that signal affects the timer.

In Sync operation, the Timer Reset or clear occurs when the input selected by SYNC<4:0> is asserted. The timer immediately begins to count again from zero unless it is held for some other reason. Sync operation is used whenever the TRIGEN bit (CCPxCON1H<7>) is cleared. The SYNC<4:0> bits can have any value except ‘11111’.

In Trigger mode operation, the timer is held in Reset until the input selected by SYNC<4:0> is asserted; when it occurs, the timer starts counting. Trigger operation is used whenever the TRIGEN bit is set. In Trigger mode, the timer will continue running after a trigger event as long as the CCPTRIG bit (CCPxSTATL< 7>) is set. To clear CCPTRIG, the TRCLR bit (CCPxSTATL<5>) must be set to clear the trigger event, reset the timer and hold it at zero until another trigger event occurs. On PIC24FJ256GA705 family devices, Trigger mode operation can only be used when the system clock is the time base source (CLKSEL<2:0> = 000).

FIGURE 16-3: DUAL 16-BIT TIMER MODE



REGISTER 17-5: SPIxSTATH: SPIx STATUS REGISTER HIGH

U-0	U-0	R-0, HSC	R-0, HSC	R-0, HSC	R-0, HSC	R-0, HSC	R-0, HSC
—	—	RXELM5(3)	RXELM4(2)	RXELM3(1)	RXELM2	RXELM1	RXELM0
bit 15							bit 8

U-0	U-0	R-0, HSC	R-0, HSC	R-0, HSC	R-0, HSC	R-0, HSC	R-0, HSC
—	—	TXELM5(3)	TXELM4(2)	TXELM3(1)	TXELM2	TXELM1	TXELM0
bit 7							bit 0

Legend:	HSC = Hardware Settable/Clearable bit		
R = Readable bit	W = Writable bit	U = Unimplemented bit, read as '0'	
-n = Value at POR	'1' = Bit is set	'0' = Bit is cleared	x = Bit is unknown

bit 15-14 **Unimplemented:** Read as '0'

bit 13-8 **RXELM<5:0>:** Receive Buffer Element Count bits (valid in Enhanced Buffer mode)(1,2,3)

bit 7-6 **Unimplemented:** Read as '0'

bit 5-0 **TXELM<5:0>:** Transmit Buffer Element Count bits (valid in Enhanced Buffer mode)(1,2,3)

Note 1: RXELM3 and TXELM3 bits are only present when FIFODEPTH = 8 or higher.

2: RXELM4 and TXELM4 bits are only present when FIFODEPTH = 16 or higher.

3: RXELM5 and TXELM5 bits are only present when FIFODEPTH = 32.

TABLE 23-1: MODULE-SPECIFIC INPUT DATA SOURCES

Bit Field Value		Input Source	
		CLC1	CLC2
DS4<2:0>	011	SDI1	SDI2
	001	CLC2 Output	CLC1 Output
DS3<2:0>	100	U1RX	U2RX
	011	SDO1	SDO2
	001	CLC1 Output	CLC2 Output
DS2<2:0>	011	U1TX	U2TX
	001	CLC2 Output	CLC1 Output

REGISTER 23-4: CLCxGLSL: CLCx GATE LOGIC INPUT SELECT LOW REGISTER

R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0
G2D4T	G2D4N	G2D3T	G2D3N	G2D2T	G2D2N	G2D1T	G2D1N
bit 15							bit 8

R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0
G1D4T	G1D4N	G1D3T	G1D3N	G1D2T	G1D2N	G1D1T	G1D1N
bit 7							bit 0

Legend:			
R = Readable bit	W = Writable bit	U = Unimplemented bit, read as ‘0’	
-n = Value at POR	‘1’ = Bit is set	‘0’ = Bit is cleared	x = Bit is unknown

bit 15 **G2D4T:** Gate 2 Data Source 4 True Enable bit
1 = The Data Source 4 signal is enabled for Gate 2
0 = The Data Source 4 signal is disabled for Gate 2

bit 14 **G2D4N:** Gate 2 Data Source 4 Negated Enable bit
1 = The Data Source 4 inverted signal is enabled for Gate 2
0 = The Data Source 4 inverted signal is disabled for Gate 2

bit 13 **G2D3T:** Gate 2 Data Source 3 True Enable bit
1 = The Data Source 3 signal is enabled for Gate 2
0 = The Data Source 3 signal is disabled for Gate 2

bit 12 **G2D3N:** Gate 2 Data Source 3 Negated Enable bit
1 = The Data Source 3 inverted signal is enabled for Gate 2
0 = The Data Source 3 inverted signal is disabled for Gate 2

bit 11 **G2D2T:** Gate 2 Data Source 2 True Enable bit
1 = The Data Source 2 signal is enabled for Gate 2
0 = The Data Source 2 signal is disabled for Gate 2

bit 10 **G2D2N:** Gate 2 Data Source 2 Negated Enable bit
1 = The Data Source 2 inverted signal is enabled for Gate 2
0 = The Data Source 2 inverted signal is disabled for Gate 2

bit 9 **G2D1T:** Gate 2 Data Source 1 True Enable bit
1 = The Data Source 1 signal is enabled for Gate 2
0 = The Data Source 1 signal is disabled for Gate 2

24.3 Registers

The 12-bit A/D Converter is controlled through a total of 13 registers:

- AD1CON1 through AD1CON5 (Register 24-1 through Register 24-5)
- AD1CHS (Register 24-6)
- ANCFG (Register 24-7)
- AD1CHITL (Register 24-8)
- AD1CSSH and AD1CSSL (Register 24-9 and Register 24-10)
- AD1CTMENH and AD1CTMENL (Register 24-11 and Register 24-12)
- AD1DMBUF (not shown) – The 16-bit conversion buffer for Extended Buffer mode

TABLE 24-1: INDIRECT ADDRESS GENERATION IN PIA MODE

DMABL<2:0>	Buffer Size per Channel (words)	Generated Offset Address (lower 11 bits)	Available Input Channels	Allowable DMADSTn Addresses
000	1	000 00cc ccc0	32	xxxx xxxx xx00 0000
001	2	000 0ccc ccn0	32	xxxx xxxx x000 0000
010	4	000 cccc cnn0	32	xxxx xxxx 0000 0000
011	8	00c cccc nnn0	32	xxxx xxx0 0000 0000
100	16	0cc cccn nnn0	32	xxxx xx00 0000 0000
101	32	ccc ccnn nnn0	32	xxxx x000 0000 0000
110	64	ccc cnnn nnn0	16	xxxx x000 0000 0000
111	128	ccc nnnn nnn0	8	xxxx x000 0000 0000

Legend: ccc = Channel number (three to five bits), n = Base buffer address (zero to seven bits), x = User-definable range of DMADSTn for base address, 0 = Masked bits of DMADSTn for IA

REGISTER 28-1: HLVDCON: HIGH/LOW-VOLTAGE DETECT CONTROL REGISTER

R/W-0	U-0	R/W-0	U-0	R/W-0	HS, HC, R-0	HS, HC, R-0	HS, HC, R-0
HLVDEN	—	LSIDL	—	VDIR	BGVST	IRVST	LVDEVT(2)
bit 15							bit 8

U-0	U-0	U-0	U-0	R/W-0	R/W-0	R/W-0	R/W-0
—	—	—	—	HLVDL3	HLVDL2	HLVDL1	HLVDL0
bit 7							bit 0

Legend:	HS = Hardware Settable bit	HC = Hardware Clearable bit	
R = Readable bit	W = Writable bit	U = Unimplemented bit, read as '0'	
-n = Value at POR	'1' = Bit is set	'0' = Bit is cleared	x = Bit is unknown

bit 15 **HLVDEN:** High/Low-Voltage Detect Power Enable bit
1 = HLVD is enabled
0 = HLVD is disabled

bit 14 **Unimplemented:** Read as '0'

bit 13 **LSIDL:** HLVD Stop in Idle Mode bit
1 = Discontinues module operation when device enters Idle mode
0 = Continues module operation in Idle mode

bit 12 **Unimplemented:** Read as '0'

bit 11 **VDIR:** Voltage Change Direction Select bit
1 = Event occurs when voltage equals or exceeds trip point (HLVDL<3:0>)
0 = Event occurs when voltage equals or falls below trip point (HLVDL<3:0>)

bit 10 **BGVST:** Band Gap Voltage Stable Flag bit
1 = Indicates that the band gap voltage is stable
0 = Indicates that the band gap voltage is unstable

bit 9 **IRVST:** Internal Reference Voltage Stable Flag bit
1 = Internal reference voltage is stable; the High-Voltage Detect logic generates the interrupt flag at the specified voltage range
0 = Internal reference voltage is unstable; the High-Voltage Detect logic will not generate the interrupt flag at the specified voltage range and the HLVD interrupt should not be enabled

bit 8 **LVDEVT:** Low-Voltage Event Status bit(2)
1 = LVD event is true during current instruction cycle
0 = LVD event is not true during current instruction cycle

bit 7-4 **Unimplemented:** Read as '0'

bit 3-0 **HLVDL<3:0>:** High/Low-Voltage Detection Limit bits
1111 = External analog input is used (input comes from the HLVDIN pin)
1110 = Trip Point 1(1)
1101 = Trip Point 2(1)
1100 = Trip Point 3(1)
•
•
•
0100 = Trip Point 11(1)
00xx = Unused

Note 1: For the actual trip point, see **Section 32.0 "Electrical Characteristics"**.

2: The LVDIF flag cannot be cleared by software unless LVDEVT = 0. The voltage must be monitored so that the HLVD condition (as set by VDIR and HLVDL<3:0>) is not asserted.

REGISTER 29-2: FBSLIM CONFIGURATION REGISTER

U-1	U-1	U-1	U-1	U-1	U-1	U-1	U-1
—	—	—	—	—	—	—	—
bit 23							bit 16

U-1	U-1	U-1	R/PO-1	R/PO-1	R/PO-1	R/PO-1	R/PO-1
—	—	—	BSLIM<12:8>				
bit 15							bit 8

R/PO-1	R/PO-1	R/PO-1	R/PO-1	R/PO-1	R/PO-1	R/PO-1	R/PO-1
BSLIM<7:0>							
bit 7							bit 0

Legend:	PO = Program Once bit		
R = Readable bit	W = Writable bit	U = Unimplemented bit, read as ‘0’	
-n = Value at POR	‘1’ = Bit is set	‘0’ = Bit is cleared	x = Bit is unknown

bit 23-13 **Unimplemented:** Read as ‘1’

bit 12-0 **BSLIM<12:0>:** Active Boot Segment Code Flash Page Address Limit (Inverted) bits
This bit field contains the last active Boot Segment Page + 1 (i.e., first page address of GS). The value is stored as an inverted page address, such that programming additional ‘0’s can only increase the size of BS. If BSLIM<12:0> is set to all ‘1’s (unprogrammed default), the active Boot Segment size is zero.