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"[Embedded - Microcontrollers](#)" refer to small, integrated circuits designed to perform specific tasks within larger systems. These microcontrollers are essentially compact computers on a single chip, containing a processor core, memory, and programmable input/output peripherals. They are called "embedded" because they are embedded within electronic devices to control various functions, rather than serving as standalone computers. Microcontrollers are crucial in modern electronics, providing the intelligence and control needed for a wide range of applications.

### Applications of "[Embedded - Microcontrollers](#)"

Details	
Product Status	Active
Core Processor	PIC
Core Size	16-Bit
Speed	32MHz
Connectivity	I <sup>2</sup> C, IrDA, LINbus, SPI, UART/USART
Peripherals	Brown-out Detect/Reset, DMA, I <sup>2</sup> S, LVD, POR, PWM, WDT
Number of I/O	22
Program Memory Size	128KB (43K x 24)
Program Memory Type	FLASH
EEPROM Size	-
RAM Size	16K x 8
Voltage - Supply (Vcc/Vdd)	2V ~ 3.6V
Data Converters	A/D 10x12b
Oscillator Type	Internal
Operating Temperature	-40°C ~ 85°C (TA)
Mounting Type	Surface Mount
Package / Case	28-VQFN Exposed Pad
Supplier Device Package	28-QFN (6x6)
Purchase URL	<a href="https://www.e-xfl.com/product-detail/microchip-technology/pic24fj128ga702t-i-ml">https://www.e-xfl.com/product-detail/microchip-technology/pic24fj128ga702t-i-ml</a>

# PIC24FJ256GA705 FAMILY

**TABLE 4-9: SFR MAP: 0500h BLOCK**

File Name	Address	All Resets	File Name	Address	All Resets
<b>DMA (CONTINUED)</b>			<b>DMA (CONTINUED)</b>		
DMAINT5	0500	0000	DMADST5	0504	0000
DMASRC5	0502	0000	DMACNT5	0506	0001

**Legend:** x = undefined. Reset values are shown in hexadecimal.

**TABLE 4-10: SFR MAP: 0600h BLOCK**

File Name	Address	All Resets	File Name	Address	All Resets
<b>I/O</b>			<b>PORTB (CONTINUED)</b>		
PADCON	065E	0000	ANSB	067E	FFFF
IOCSTAT	0660	0000	IOCPB	0680	0000
<b>PORTA</b>			IOCNB	0682	0000
TRISA	0662	FFFF	IOCFB	0684	0000
PORTA	0664	0000	IOCPUB	0686	0000
LATA	0666	0000	IOCPDB	0688	0000
ODCA	0668	0000	<b>PORTC</b>		
ANSA	066A	FFFF	TRISC	068A	FFFF
IOCPA	066C	0000	PORTC	068C	0000
IOCNA	066E	0000	LATC	068E	0000
IOCFA	0670	0000	ODCC	0690	0000
IOCPUA	0672	0000	ANSC	0692	FFFF
IOCPDA	0674	0000	IOCPD	0694	0000
<b>PORTB</b>			IOCNC	0696	0000
TRISB	0676	FFFF	IOCFD	0698	0000
PORTB	0678	0000	IOCPUC	069A	0000
LATB	067A	0000	IOCPDC	069C	0000
ODCB	067C	0000			

**Legend:** x = undefined. Reset values are shown in hexadecimal.

# PIC24FJ256GA705 FAMILY

## 7.1 Special Function Register Reset States

Most of the Special Function Registers (SFRs) associated with the PIC24F CPU and peripherals are reset to a particular value at a device Reset. The SFRs are grouped by their peripheral or CPU function and their Reset values are specified in each section of this manual.

The Reset value for each SFR does not depend on the type of Reset, with the exception of four registers. The Reset value for the Reset Control register, RCON, will depend on the type of device Reset. The Reset value for the Oscillator Control register, OSCCON, will depend on the type of Reset and the programmed values of the FNOSC<2:0> bits in the FOSCSEL Flash Configuration Word (see Table 7-2). The RCFGAL and NVMCON registers are only affected by a POR.

## 7.2 Device Reset Times

The Reset times for various types of device Reset are summarized in Table 7-3. Note that the Master Reset Signal,  $\overline{\text{SYSRST}}$ , is released after the POR delay time expires.

The time at which the device actually begins to execute code will also depend on the system oscillator delays, which include the Oscillator Start-up Timer (OST) and the PLL lock time. The OST and PLL lock times occur in parallel with the applicable  $\overline{\text{SYSRST}}$  delay times.

The Fail-Safe Clock Monitor (FSCM) delay determines the time at which the FSCM begins to monitor the system clock source after the  $\overline{\text{SYSRST}}$  signal is released.

## 7.3 Brown-out Reset (BOR)

PIC24FJ256GA705 family devices implement a BOR circuit that provides the user with several configuration and power-saving options. The BOR is controlled by the BOREN<1:0> (FPOR<1:0>) Configuration bits.

When BOR is enabled, any drop of  $V_{DD}$  below the BOR threshold results in a device BOR. Threshold levels are described in **Section 32.1 “DC Characteristics”**.

## 7.4 Clock Source Selection at Reset

If clock switching is enabled, the system clock source at device Reset is chosen, as shown in Table 7-2. If clock switching is disabled, the system clock source is always selected according to the Oscillator Configuration bits. For more information, refer to the “*dsPIC33/PIC24 Family Reference Manual*”, “**Oscillator**” (DS39700).

**TABLE 7-2: OSCILLATOR SELECTION vs. TYPE OF RESET (CLOCK SWITCHING ENABLED)**

Reset Type	Clock Source Determinant
POR	FNOSC<2:0> Configuration bits
BOR	(FOSCSEL<2:0>)
$\overline{\text{MCLR}}$	COSC<2:0> Control bits (OSCCON<14:12>)
WDTO	
SWR	

# PIC24FJ256GA705 FAMILY

## REGISTER 8-2: CORCON: CPU CORE CONTROL REGISTER<sup>(1)</sup>

U-0	U-0	U-0	U-0	U-0	U-0	U-0	U-0
—	—	—	—	—	—	—	—
bit 15							bit 8

U-0	U-0	U-0	U-0	R/C-0	R/W-1	U-0	U-0
—	—	—	—	IPL3 <sup>(2)</sup>	PSV	—	—
bit 7							bit 0

<b>Legend:</b>	C = Clearable bit		
R = Readable bit	W = Writable bit	U = Unimplemented bit, read as '0'	
-n = Value at POR	'1' = Bit is set	'0' = Bit is cleared	x = Bit is unknown

- bit 15-4      **Unimplemented:** Read as '0'
- bit 3        **IPL3:** CPU Interrupt Priority Level Status bit<sup>(2)</sup>  
               1 = CPU Interrupt Priority Level is greater than 7  
               0 = CPU Interrupt Priority Level is 7 or less
- bit 2        **PSV:** Not used as part of the interrupt module
- bit 1-0     **Unimplemented:** Read as '0'

- Note 1:** For complete register details, see Register 3-2.
- 2:** The IPL<2:0> Status bits are concatenated with the IPL3 Status bit (CORCON<3>) to form the CPU Interrupt Priority Level (IPL). The value in parentheses indicates the IPL when IPL3 = 1. User interrupts are disabled when IPL3 = 1.

# PIC24FJ256GA705 FAMILY

## REGISTER 10-1: PMD1: PERIPHERAL MODULE DISABLE REGISTER 1

U-0	U-0	R/W-0	R/W-0	R/W-0	U-0	U-0	U-0
—	—	T3MD	T2MD	T1MD	—	—	—
bit 15						bit 8	

R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	U-0	U-0	R/W-0
I2C1MD	U2MD	U1MD	SPI2MD	SPI1MD	—	—	ADC1MD
bit 7						bit 0	

### Legend:

R = Readable bit	W = Writable bit	U = Unimplemented bit, read as '0'
-n = Value at POR	'1' = Bit is set	'0' = Bit is cleared
		x = Bit is unknown

- bit 15-14    **Unimplemented:** Read as '0'
- bit 13      **T3MD:** Timer3 Module Disable bit  
1 = Module is disabled  
0 = Module power and clock sources are enabled
- bit 12      **T2MD:** Timer2 Module Disable bit  
1 = Module is disabled  
0 = Module power and clock sources are enabled
- bit 11      **T1MD:** Timer1 Module Disable bit  
1 = Module is disabled  
0 = Module power and clock sources are enabled
- bit 10-8    **Unimplemented:** Read as '0'
- bit 7        **I2C1MD:** I2C1 Module Disable bit  
1 = Module is disabled  
0 = Module power and clock sources are enabled
- bit 6        **U2MD:** UART2 Module Disable bit  
1 = Module is disabled  
0 = Module power and clock sources are enabled
- bit 5        **U1MD:** UART1 Module Disable bit  
1 = Module is disabled  
0 = Module power and clock sources are enabled
- bit 4        **SPI2MD:** SPI2 Module Disable bit  
1 = Module is disabled  
0 = Module power and clock sources are enabled
- bit 3        **SPI1MD:** SPI1 Module Disable bit  
1 = Module is disabled  
0 = Module power and clock sources are enabled
- bit 2-1     **Unimplemented:** Read as '0'
- bit 0        **ADC1MD:** A/D Converter Module Disable bit  
1 = Module is disabled  
0 = Module power and clock sources are enabled

# PIC24FJ256GA705 FAMILY

## REGISTER 10-3: PMD3: PERIPHERAL MODULE DISABLE REGISTER 3

U-0	U-0	U-0	U-0	U-0	R/W-0	R/W-0	R/W-0
—	—	—	—	—	CMPMD	RTCCMD	PMPMD
bit 15						bit 8	

R/W-0	U-0	U-0	U-0	U-0	U-0	R/W-0	U-0
CRCMD	—	—	—	—	—	I2C2MD	—
bit 7						bit 0	

### Legend:

R = Readable bit                      W = Writable bit                      U = Unimplemented bit, read as '0'  
 -n = Value at POR                      '1' = Bit is set                      '0' = Bit is cleared                      x = Bit is unknown

- bit 15-11    **Unimplemented:** Read as '0'
- bit 10      **CMPMD:** Triple Comparator Module Disable bit  
                  1 = Module is disabled  
                  0 = Module power and clock sources are enabled
- bit 9        **RTCCMD:** RTCC Module Disable bit  
                  1 = Module is disabled  
                  0 = Module power and clock sources are enabled
- bit 8        **PMPMD:** Enhanced Parallel Master Port Disable bit  
                  1 = Module is disabled  
                  0 = Module power and clock sources are enabled
- bit 7        **CRCMD:** CRC Module Disable bit  
                  1 = Module is disabled  
                  0 = Module power and clock sources are enabled
- bit 6-2     **Unimplemented:** Read as '0'
- bit 1        **I2C2MD:** I2C2 Module Disable bit  
                  1 = Module is disabled  
                  0 = Module power and clock sources are enabled
- bit 0        **Unimplemented:** Read as '0'

## 11.5.6 PERIPHERAL PIN SELECT REGISTERS

The PIC24FJ256GA705 family of devices implements a total of 34 registers for remappable peripheral configuration:

- Input Remappable Peripheral Registers (19)
- Output Remappable Peripheral Registers (15)

**Note:** Input and Output register values can only be changed if IOLOCK (OSCCON<6>) = 0. See **Section 11.5.4.1 “Control Register Lock”** for a specific command sequence.

### REGISTER 11-13: RPINR0: PERIPHERAL PIN SELECT INPUT REGISTER 0

U-0	U-0	R/W-1	R/W-1	R/W-1	R/W-1	R/W-1	R/W-1
—	—	INT1R5	INT1R4	INT1R3	INT1R2	INT1R1	INT1R0
bit 15							bit 8

U-0	U-0	R/W-1	R/W-1	R/W-1	R/W-1	R/W-1	R/W-1
—	—	OCTRIG1R5	OCTRIG1R4	OCTRIG1R3	OCTRIG1R2	OCTRIG1R1	OCTRIG1R0
bit 7							bit 0

**Legend:**

R = Readable bit                      W = Writable bit                      U = Unimplemented bit, read as '0'  
 -n = Value at POR                      '1' = Bit is set                      '0' = Bit is cleared                      x = Bit is unknown

- bit 15-14     **Unimplemented:** Read as '0'
- bit 13-8     **INT1R<5:0>:** Assign External Interrupt 1 (INT1) to Corresponding RPN or RPN Pin bits
- bit 7-6       **Unimplemented:** Read as '0'
- bit 5-0       **OCTRIG1R<5:0>:** Assign Output Compare Trigger 1 to Corresponding RPN or RPN Pin bits

### REGISTER 11-14: RPINR1: PERIPHERAL PIN SELECT INPUT REGISTER 1

U-0	U-0	R/W-1	R/W-1	R/W-1	R/W-1	R/W-1	R/W-1
—	—	INT3R5	INT3R4	INT3R3	INT3R2	INT3R1	INT3R0
bit 15							bit 8

U-0	U-0	R/W-1	R/W-1	R/W-1	R/W-1	R/W-1	R/W-1
—	—	INT2R5	INT2R4	INT2R3	INT2R2	INT2R1	INT2R0
bit 7							bit 0

**Legend:**

R = Readable bit                      W = Writable bit                      U = Unimplemented bit, read as '0'  
 -n = Value at POR                      '1' = Bit is set                      '0' = Bit is cleared                      x = Bit is unknown

- bit 15-14     **Unimplemented:** Read as '0'
- bit 13-8     **INT3R<5:0>:** Assign External Interrupt 3 (INT3) to Corresponding RPN or RPN Pin bits
- bit 7-6       **Unimplemented:** Read as '0'
- bit 5-0       **INT2R<5:0>:** Assign External Interrupt 2 (INT2) to Corresponding RPN or RPN Pin bits

# PIC24FJ256GA705 FAMILY

## REGISTER 11-27: RPINR22: PERIPHERAL PIN SELECT INPUT REGISTER 22

U-0	U-0	R/W-1	R/W-1	R/W-1	R/W-1	R/W-1	R/W-1
—	—	SCK2R5	SCK2R4	SCK2R3	SCK2R2	SCK2R1	SCK2R0
bit 15							bit 8

U-0	U-0	R/W-1	R/W-1	R/W-1	R/W-1	R/W-1	R/W-1
—	—	SDI2R5	SDI2R4	SDI2R3	SDI2R2	SDI2R1	SDI2R0
bit 7							bit 0

### Legend:

R = Readable bit                      W = Writable bit                      U = Unimplemented bit, read as '0'  
 -n = Value at POR                      '1' = Bit is set                      '0' = Bit is cleared                      x = Bit is unknown

- bit 15-14      **Unimplemented:** Read as '0'
- bit 13-8      **SCK2R<5:0>:** Assign SPI2 Clock Input (SCK2IN) to Corresponding RPn or RPIIn Pin bits
- bit 7-6      **Unimplemented:** Read as '0'
- bit 5-0      **SDI2R<5:0>:** Assign SPI2 Data Input (SDI2) to Corresponding RPn or RPIIn Pin bits

## REGISTER 11-28: RPINR23: PERIPHERAL PIN SELECT INPUT REGISTER 23

U-0	U-0	R/W-1	R/W-1	R/W-1	R/W-1	R/W-1	R/W-1
—	—	TXCKR5	TXCKR4	TXCKR3	TXCKR2	TXCKR1	TXCKR0
bit 15							bit 8

U-0	U-0	R/W-1	R/W-1	R/W-1	R/W-1	R/W-1	R/W-1
—	—	SS2R5	SS2R4	SS2R3	SS2R2	SS2R1	SS2R0
bit 7							bit 0

### Legend:

R = Readable bit                      W = Writable bit                      U = Unimplemented bit, read as '0'  
 -n = Value at POR                      '1' = Bit is set                      '0' = Bit is cleared                      x = Bit is unknown

- bit 15-14      **Unimplemented:** Read as '0'
- bit 13-8      **TXCKR<5:0>:** Assign General Timer External Input (TxCK) to Corresponding RPn or RPIIn Pin bits
- bit 7-6      **Unimplemented:** Read as '0'
- bit 5-0      **SS2R<5:0>:** Assign SPI2 Slave Select Input (SS2IN) to Corresponding RPn or RPIIn Pin bits



## 13.0 TIMER2/3

**Note:** This data sheet summarizes the features of this group of PIC24F devices. It is not intended to be a comprehensive reference source. For more information, refer to the “*dsPIC33/PIC24 Family Reference Manual*”, “**Timers**” (DS39704), which is available from the Microchip web site ([www.microchip.com](http://www.microchip.com)). The information in this data sheet supersedes the information in the FRM.

The Timer2/3 module is a 32-bit timer, which can also be configured as independent, 16-bit timers with selectable operating modes.

As a 32-bit timer, Timer2/3 can operate in three modes:

- Two Independent 16-Bit Timers with All 16-Bit Operating modes (except Asynchronous Counter mode)
- Single 32-Bit Timer
- Single 32-Bit Synchronous Counter

They also support these features:

- Timer Gate Operation
- Selectable Prescaler Settings
- Timer Operation during Idle and Sleep modes
- Interrupt on a 32-Bit Period Register Match
- A/D Event Trigger (on Timer2/3 in 32-bit mode and Timer3 in 16-bit mode)

Individually, all of the 16-bit timers can function as synchronous timers or counters. They also offer the features listed above, except for the A/D event trigger. This trigger is implemented only on Timer2/3 in 32-bit mode and Timer3 in 16-bit mode. The operating modes and enabled features are determined by setting the appropriate bit(s) in the T2CON and T3CON registers. T2CON is shown in generic form in Register 13-1; T3CON is shown in Register 13-2.

For 32-bit timer/counter operation, Timer2 is the least significant word; Timer3 is the most significant word of the 32-bit timer.

**Note:** For 32-bit operation, T3CON control bits are ignored. Only T2CON control bits are used for setup and control. Timer2 clock and gate inputs are utilized for the 32-bit timer modules, but an interrupt is generated with the Timer3 interrupt flags.

To configure Timer2/3 for 32-bit operation:

1. Set the T32 bit (T2CON<3> = 1).
2. Select the prescaler ratio for Timer2 using the TCKPS<1:0> bits.
3. Set the Clock and Gating modes using the TCS and TGATE bits. If TCS is set to an external clock, RPINRx (TyCK) must be configured to an available RPn/RPIn pin. For more information, see **Section 11.5 “Peripheral Pin Select (PPS)”**.
4. Load the timer period value. PR3 will contain the most significant word (msw) of the value, while PR2 contains the least significant word (lsw).
5. If interrupts are required, set the interrupt enable bit, T3IE. Use the priority bits, T3IP<2:0>, to set the interrupt priority. Note that while Timer2 controls the timer, the interrupt appears as a Timer3 interrupt.
6. Set the TON bit (= 1).

The timer value, at any point, is stored in the register pair, TMR<3:2>. TMR3 always contains the most significant word of the count, while TMR2 contains the least significant word.

To configure any of the timers for individual 16-bit operation:

1. Clear the T32 bit (T2CON<3>).
2. Select the timer prescaler ratio using the TCKPS<1:0> bits.
3. Set the Clock and Gating modes using the TCS and TGATE bits. See **Section 11.5 “Peripheral Pin Select (PPS)”** for more information.
4. Load the timer period value into the PRx register.
5. If interrupts are required, set the interrupt enable bit, TxIE. Use the priority bits, TxIP<2:0>, to set the interrupt priority.
6. Set the TON (TxCON<15> = 1) bit.

## REGISTER 14-2: ICxCON2: INPUT CAPTURE x CONTROL REGISTER 2 (CONTINUED)

bit 4-0      **SYNCSEL<4:0>**: Synchronization/Trigger Source Selection bits

11111 = Not used  
11110 = Not used  
11101 = Not used  
11100 = CTMU trigger<sup>(1)</sup>  
11011 = A/D interrupt<sup>(1)</sup>  
11010 = CMP3 trigger<sup>(1)</sup>  
11001 = CMP2 trigger<sup>(1)</sup>  
11000 = CMP1 trigger<sup>(1)</sup>  
10111 = Not used  
10110 = MCCP4 IC/OC interrupt  
10101 = MCCP3 IC/OC interrupt  
10100 = MCCP2 IC/OC interrupt  
10011 = MCCP1 IC/OC interrupt  
10010 = IC3 interrupt<sup>(2)</sup>  
10001 = IC2 interrupt<sup>(2)</sup>  
10000 = IC1 interrupt<sup>(2)</sup>  
01111 = Not used  
01110 = Not used  
01101 = Timer3 match event  
01100 = Timer2 match event  
01011 = Timer1 match event  
01010 = Not used  
01001 = Not used  
01000 = Not used  
00111 = MCCP4 Sync/Trigger out  
00110 = MCCP3 Sync/Trigger out  
00101 = MCCP2 Sync/Trigger out  
00100 = MCCP1 Sync/Trigger out  
00011 = OC3 Sync/Trigger out  
00010 = OC2 Sync/Trigger out  
00001 = OC1 Sync/Trigger out  
00000 = Off

**Note 1:** Use these inputs as Trigger sources only and never as Sync sources.

**2:** Never use an Input Capture x module as its own Trigger source by selecting this mode.

## REGISTER 15-1: OCxCON1: OUTPUT COMPARE x CONTROL REGISTER 1 (CONTINUED)

- bit 3        **TRIGMODE**: Trigger Status Mode Select bit  
1 = TRIGSTAT (OCxCON2<6>) is cleared when OCxRS = OCxTMR or in software  
0 = TRIGSTAT is only cleared by software
- bit 2-0      **OCM<2:0>**: Output Compare x Mode Select bits<sup>(1)</sup>  
111 = Center-Aligned PWM mode on OCx<sup>(2)</sup>  
110 = Edge-Aligned PWM mode on OCx<sup>(2)</sup>  
101 = Double Compare Continuous Pulse mode: Initializes the OCx pin low; toggles the OCx state continuously on alternate matches of OCxR and OCxRS  
100 = Double Compare Single-Shot mode: Initializes the OCx pin low; toggles the OCx state on matches of OCxR and OCxRS for one cycle  
011 = Single Compare Continuous Pulse mode: Compare events continuously toggle the OCx pin  
010 = Single Compare Single-Shot mode: Initializes OCx pin high; compare event forces the OCx pin low  
001 = Single Compare Single-Shot mode: Initializes OCx pin low; compare event forces the OCx pin high  
000 = Output compare channel is disabled

- Note 1:** The OCx output must also be configured to an available RPN pin. For more information, see **Section 11.5 “Peripheral Pin Select (PPS)”**.
- 2:** The Fault input enable and Fault status bits are valid when OCM<2:0> = 111 or 110.
- 3:** The Comparator 1 output controls the OC1-OC3 channels.
- 4:** The OCFA/OCFB Fault input must also be configured to an available RPN/RPN pin. For more information, see **Section 11.5 “Peripheral Pin Select (PPS)”**.

## REGISTER 16-1: CCPxCON1L: CCPx CONTROL 1 LOW REGISTERS (CONTINUED)

bit 3-0      **MOD<3:0>**: CCPx Mode Select bits

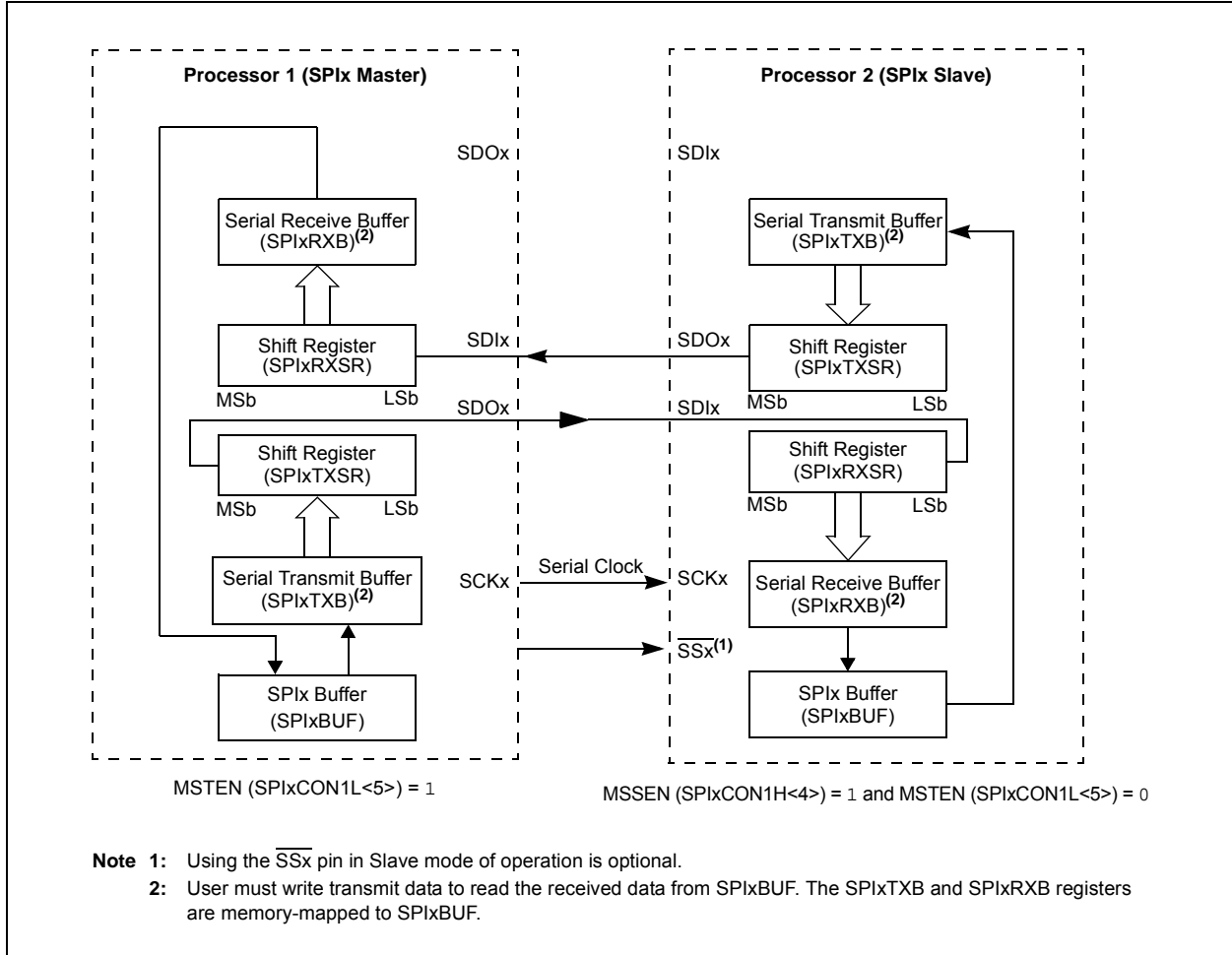
For CCSEL = 1 (Input Capture modes):

- 1xxx = Reserved
- 011x = Reserved
- 0101 = Capture every 16th rising edge
- 0100 = Capture every 4th rising edge
- 0011 = Capture every rising and falling edge
- 0010 = Capture every falling edge
- 0001 = Capture every rising edge
- 0000 = Capture every rising and falling edge (Edge Detect mode)

For CCSEL = 0 (Output Compare/Timer modes):

- 1111 = External Input mode: Pulse generator is disabled, source is selected by ICS<2:0>
- 1110 = Reserved
- 110x = Reserved
- 10xx = Reserved
- 0111 = Variable Frequency Pulse mode
- 0110 = Center-Aligned Pulse Compare mode, buffered
- 0101 = Dual Edge Compare mode, buffered
- 0100 = Dual Edge Compare mode
- 0011 = 16-Bit/32-Bit Single Edge mode, toggles output on compare match
- 0010 = 16-Bit/32-Bit Single Edge mode, drives output low on compare match
- 0001 = 16-Bit/32-Bit Single Edge mode, drives output high on compare match
- 0000 = 16-Bit/32-Bit Timer mode, output functions are disabled

**FIGURE 17-2: SPIx MASTER/SLAVE CONNECTION (STANDARD MODE)**



## 18.2 Setting Baud Rate When Operating as a Bus Master

To compute the Baud Rate Generator reload value, use Equation 18-1.

### EQUATION 18-1: COMPUTING BAUD RATE RELOAD VALUE<sup>(1,2,3)</sup>

$$F_{SCL} = \frac{F_{CY}}{(I2CxBRG + 2) * 2}$$

or:

$$I2CxBRG = \left[ \frac{F_{CY}}{(F_{SCL} * 2)} - 2 \right]$$

**Note 1:** Based on  $F_{CY} = F_{OSC}/2$ ; Doze mode and PLL are disabled.

**2:** These clock rate values are for guidance only. The actual clock rate can be affected by various system-level parameters. The actual clock rate should be measured in its intended application.

**3:** BRG values of 0 and 1 are forbidden.

## 18.3 Slave Address Masking

The I2CxMSK register (Register 18-4) designates address bit positions as “don’t care” for both 7-Bit and 10-Bit Addressing modes. Setting a particular bit location (= 1) in the I2CxMSK register causes the slave module to respond, whether the corresponding address bit value is a ‘0’ or a ‘1’. For example, when I2CxMSK is set to ‘0010000000’, the slave module will detect both addresses, ‘0000000000’ and ‘0010000000’.

To enable address masking, the Intelligent Peripheral Management Interface (IPMI) must be disabled by clearing the STRICT bit (I2CxCONL<11>).

**Note:** As a result of changes in the I<sup>2</sup>C protocol, the addresses in Table 18-2 are reserved and will not be Acknowledged in Slave mode. This includes any address mask settings that include any of these addresses.

**TABLE 18-1: I2Cx CLOCK RATES<sup>(1,2)</sup>**

Required System F <sub>SCL</sub>	F <sub>CY</sub>	I2CxBRG Value		Actual F <sub>SCL</sub>
		(Decimal)	(Hexadecimal)	
100 kHz	16 MHz	78	4E	100 kHz
100 kHz	8 MHz	38	26	100 kHz
100 kHz	4 MHz	18	12	100 kHz
400 kHz	16 MHz	18	12	400 kHz
400 kHz	8 MHz	8	8	400 kHz
400 kHz	4 MHz	3	3	400 kHz
1 MHz	16 MHz	6	6	1.000 MHz
1 MHz	8 MHz	2	2	1.000 MHz

**Note 1:** Based on  $F_{CY} = F_{OSC}/2$ ; Doze mode and PLL are disabled.

**2:** These clock rate values are for guidance only. The actual clock rate can be affected by various system-level parameters. The actual clock rate should be measured in its intended application.

**TABLE 18-2: I2Cx RESERVED ADDRESSES<sup>(1)</sup>**

Slave Address	R/W Bit	Description
0000 000	0	General Call Address <sup>(2)</sup>
0000 000	1	Start Byte
0000 001	x	Cbus Address
0000 01x	x	Reserved
0000 1xx	x	HS Mode Master Code
1111 0xx	x	10-Bit Slave Upper Byte <sup>(3)</sup>
1111 1xx	x	Reserved

**Note 1:** The address bits listed here will never cause an address match independent of address mask settings.

**2:** This address will be Acknowledged only if GCEN = 1.

**3:** A match on this address can only occur on the upper byte in 10-Bit Addressing mode.

# PIC24FJ256GA705 FAMILY

## REGISTER 18-1: I2CxCONL: I2Cx CONTROL REGISTER LOW

R/W-0	U-0	HC, R/W-0	R/W-1	R/W-0	R/W-0	R/W-0	R/W-0
I2CEN	—	I2CSIDL	SCLREL <sup>(1)</sup>	STRICT	A10M	DISSLW	SMEN
bit 15							bit 8

R/W-0	R/W-0	R/W-0	HC, R/W-0	HC, R/W-0	HC, R/W-0	HC, R/W-0	HC, R/W-0
GCEN	STREN	ACKDT	ACKEN	RCEN	PEN	RSEN	SEN
bit 7							bit 0

<b>Legend:</b>	HC = Hardware Clearable bit		
R = Readable bit	W = Writable bit	U = Unimplemented bit, read as '0'	
-n = Value at POR	'1' = Bit is set	'0' = Bit is cleared	x = Bit is unknown

- bit 15      **I2CEN:** I2Cx Enable bit (writable from software only)  
 1 = Enables the I2Cx module and configures the SDAx and SCLx pins as serial port pins  
 0 = Disables the I2Cx module; all I<sup>2</sup>C pins are controlled by port functions
- bit 14      **Unimplemented:** Read as '0'
- bit 13      **I2CSIDL:** I2Cx Stop in Idle Mode bit  
 1 = Discontinues module operation when device enters Idle mode  
 0 = Continues module operation in Idle mode
- bit 12      **SCLREL:** SCLx Release Control bit (I<sup>2</sup>C Slave mode only)<sup>(1)</sup>  
 Module resets and (I2CEN = 0) sets SCLREL = 1.  
If STREN = 0:<sup>(2)</sup>  
 1 = Releases clock  
 0 = Forces clock low (clock stretch)  
If STREN = 1:  
 1 = Releases clock  
 0 = Holds clock low (clock stretch); user may program this bit to '0', clock stretch at next SCLx low
- bit 11      **STRICT:** I2Cx Strict Reserved Address Rule Enable bit  
 1 = Strict reserved addressing is enforced (for reserved addresses, refer to Table 18-2)  
     In Slave Mode: The device doesn't respond to reserved address space and addresses falling in that category are NACKed.  
     In Master Mode: The device is allowed to generate addresses with reserved address space.  
 0 = Reserved addressing would be Acknowledged  
     In Slave Mode: The device will respond to an address falling in the reserved address space. When there is a match with any of the reserved addresses, the device will generate an ACK.  
     In Master Mode: Reserved.
- bit 10      **A10M:** 10-Bit Slave Address Flag bit  
 1 = I2CxADD is a 10-bit slave address  
 0 = I2CxADD is a 7-bit slave address
- bit 9        **DISSLW:** Slew Rate Control Disable bit  
 1 = Slew rate control is disabled for Standard Speed mode (100 kHz, also disabled for 1 MHz mode)  
 0 = Slew rate control is enabled for High-Speed mode (400 kHz)

**Note 1:** Automatically cleared to '0' at the beginning of slave transmission; automatically cleared to '0' at the end of slave reception. The user software must provide a delay between writing to the transmit buffer and setting the SCLREL bit. This delay must be greater than the minimum setup time for slave transmissions, as specified in **Section 32.0 "Electrical Characteristics"**.

**2:** Automatically cleared to '0' at the beginning of slave transmission.

# PIC24FJ256GA705 FAMILY

## REGISTER 20-1: PMCON1: EPMP CONTROL REGISTER 1

R/W-0	U-0	R/W-0	R/W-0	R/W-0	U-0	R/W-0	R/W-0
PMPEN	—	PSIDL	ADRMUX1	ADRMUX0	—	MODE1	MODE0
bit 15							bit 8

R/W-0	R/W-0	R/W-0	R/W-0	U-0	R/W-0	R/W-0	R/W-0
CSF1	CSF0	ALP	ALMODE	—	BUSKEEP	IRQM1	IRQM0
bit 7							bit 0

### Legend:

R = Readable bit                      W = Writable bit                      U = Unimplemented bit, read as '0'  
 -n = Value at POR                      '1' = Bit is set                      '0' = Bit is cleared                      x = Bit is unknown

- bit 15            **PMPEN:** Parallel Master Port Enable bit  
                   1 = EPMP is enabled  
                   0 = EPMP is disabled
- bit 14            **Unimplemented:** Read as '0'
- bit 13            **PSIDL:** Parallel Master Port Stop in Idle Mode bit  
                   1 = Discontinues module operation when device enters Idle mode  
                   0 = Continues module operation in Idle mode
- bit 12-11        **ADRMUX<1:0>:** Address/Data Multiplexing Selection bits  
                   11 = Lower address bits are multiplexed with data bits using 3 address phases  
                   10 = Lower address bits are multiplexed with data bits using 2 address phases  
                   01 = Lower address bits are multiplexed with data bits using 1 address phase  
                   00 = Address and data appear on separate pins
- bit 10            **Unimplemented:** Read as '0'
- bit 9-8          **MODE<1:0>:** Parallel Port Mode Select bits  
                   11 = Master mode  
                   10 = Enhanced PSP; pins used are PMRD, PMWR, PMCS, PMD<7:0> and PMA<1:0>  
                   01 = Buffered PSP; pins used are PMRD, PMWR, PMCS and PMD<7:0>  
                   00 = Legacy Parallel Slave Port; pins used are PMRD, PMWR, PMCS and PMD<7:0>
- bit 7-6          **CSF<1:0>:** Chip Select Function bits  
                   11 = Reserved  
                   10 = PMA14 is used for Chip Select 1  
                   01 = Reserved  
                   00 = PMCS2 is used for Chip Select 2, PMCS1 is used for Chip Select 1
- bit 5            **ALP:** Address Latch Polarity bit  
                   1 = Active-high (PMALL, PMALH and PMALU)  
                   0 = Active-low (PMALL, PMALH and PMALU)
- bit 4            **ALMODE:** Address Latch Strobe Mode bit  
                   1 = Enables "smart" address strobes (each address phase is only present if the current access would cause a different address in the latch than the previous address)  
                   0 = Disables "smart" address strobes
- bit 3            **Unimplemented:** Read as '0'
- bit 2            **BUSKEEP:** Bus Keeper bit  
                   1 = Data bus keeps its last value when not actively being driven  
                   0 = Data bus is in a high-impedance state when not actively being driven
- bit 1-0         **IRQM<1:0>:** Interrupt Request Mode bits  
                   11 = Interrupt is generated when Read Buffer 3 is read or Write Buffer 3 is written (Buffered PSP mode), or on a read or write operation when PMA<1:0> = 11 (Addressable PSP mode only)  
                   10 = Reserved  
                   01 = Interrupt is generated at the end of a read/write cycle  
                   00 = No interrupt is generated



# PIC24FJ256GA705 FAMILY

## REGISTER 21-16: TSATIMEH: RTCC TIMESTAMP A TIME REGISTER (HIGH)<sup>(1)</sup>

U-0	U-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0
—	—	HRTEN1	HRTEN0	HRONE3	HRONE2	HRONE1	HRONE0
bit 15							bit 8

U-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0
—	MINTEN2	MINTEN1	MINTEN0	MINONE3	MINONE2	MINONE1	MINONE0
bit 7							bit 0

### Legend:

R = Readable bit

W = Writable bit

U = Unimplemented bit, read as '0'

-n = Value at POR

'1' = Bit is set

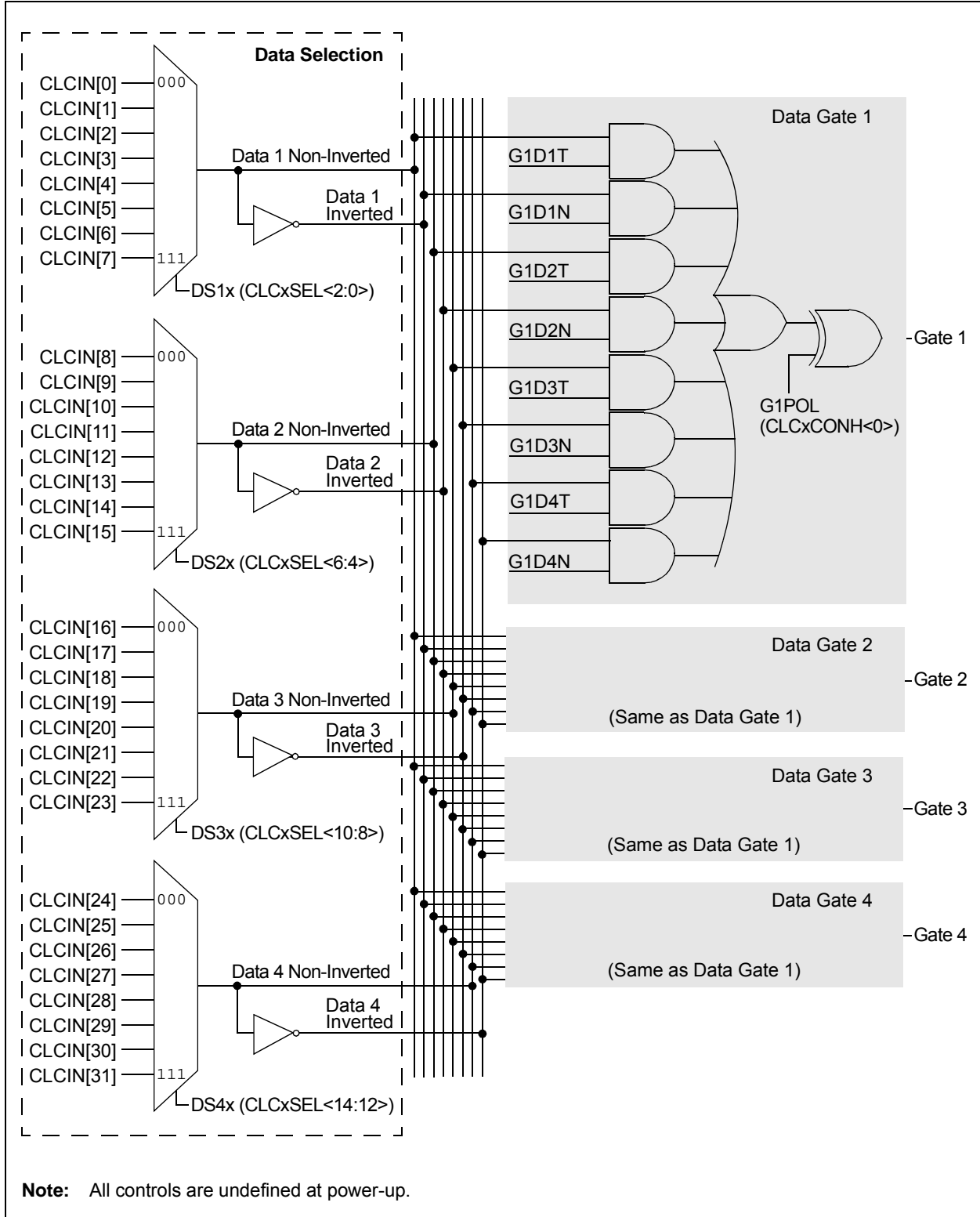
'0' = Bit is cleared

x = Bit is unknown

- bit 15-14     **Unimplemented:** Read as '0'
- bit 13-12     **HRTEN<1:0>:** Binary Coded Decimal Value of Hours '10' Digit bits  
Contains a value from 0 to 2.
- bit 11-8      **HRONE<3:0>:** Binary Coded Decimal Value of Hours '1' Digit bits  
Contains a value from 0 to 9.
- bit 7          **Unimplemented:** Read as '0'
- bit 6-4       **MINTEN<2:0>:** Binary Coded Decimal Value of Minutes '10' Digit bits  
Contains a value from 0 to 5.
- bit 3-0       **MINONE<3:0>:** Binary Coded Decimal Value of Minutes '1' Digit bits  
Contains a value from 0 to 9.

**Note 1:** If TSAEN = 0, bits<15:0> can be used for persistence storage throughout a non-Power-on Reset ( $\overline{\text{MCLR}}$ , WDT, etc.).

**FIGURE 23-3: CLCx INPUT SOURCE SELECTION DIAGRAM**



# PIC24FJ256GA705 FAMILY

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## 30.2 MPLAB XC Compilers

The MPLAB XC Compilers are complete ANSI C compilers for all of Microchip's 8, 16, and 32-bit MCU and DSC devices. These compilers provide powerful integration capabilities, superior code optimization and ease of use. MPLAB XC Compilers run on Windows, Linux or MAC OS X.

For easy source level debugging, the compilers provide debug information that is optimized to the MPLAB X IDE.

The free MPLAB XC Compiler editions support all devices and commands, with no time or memory restrictions, and offer sufficient code optimization for most applications.

MPLAB XC Compilers include an assembler, linker and utilities. The assembler generates relocatable object files that can then be archived or linked with other relocatable object files and archives to create an executable file. MPLAB XC Compiler uses the assembler to produce its object file. Notable features of the assembler include:

- Support for the entire device instruction set
- Support for fixed-point and floating-point data
- Command-line interface
- Rich directive set
- Flexible macro language
- MPLAB X IDE compatibility

## 30.3 MPASM Assembler

The MPASM Assembler is a full-featured, universal macro assembler for PIC10/12/16/18 MCUs.

The MPASM Assembler generates relocatable object files for the MPLINK Object Linker, Intel® standard HEX files, MAP files to detail memory usage and symbol reference, absolute LST files that contain source lines and generated machine code, and COFF files for debugging.

The MPASM Assembler features include:

- Integration into MPLAB X IDE projects
- User-defined macros to streamline assembly code
- Conditional assembly for multipurpose source files
- Directives that allow complete control over the assembly process

## 30.4 MPLINK Object Linker/ MPLIB Object Librarian

The MPLINK Object Linker combines relocatable objects created by the MPASM Assembler. It can link relocatable objects from precompiled libraries, using directives from a linker script.

The MPLIB Object Librarian manages the creation and modification of library files of precompiled code. When a routine from a library is called from a source file, only the modules that contain that routine will be linked in with the application. This allows large libraries to be used efficiently in many different applications.

The object linker/library features include:

- Efficient linking of single libraries instead of many smaller files
- Enhanced code maintainability by grouping related modules together
- Flexible creation of libraries with easy module listing, replacement, deletion and extraction

## 30.5 MPLAB Assembler, Linker and Librarian for Various Device Families

MPLAB Assembler produces relocatable machine code from symbolic assembly language for PIC24, PIC32 and dsPIC DSC devices. MPLAB XC Compiler uses the assembler to produce its object file. The assembler generates relocatable object files that can then be archived or linked with other relocatable object files and archives to create an executable file. Notable features of the assembler include:

- Support for the entire device instruction set
- Support for fixed-point and floating-point data
- Command-line interface
- Rich directive set
- Flexible macro language
- MPLAB X IDE compatibility

## 30.6 MPLAB X SIM Software Simulator

The MPLAB X SIM Software Simulator allows code development in a PC-hosted environment by simulating the PIC MCUs and dsPIC DSCs on an instruction level. On any given instruction, the data areas can be examined or modified and stimuli can be applied from a comprehensive stimulus controller. Registers can be logged to files for further run-time analysis. The trace buffer and logic analyzer display extend the power of the simulator to record and track program execution, actions on I/O, most peripherals and internal registers.

The MPLAB X SIM Software Simulator fully supports symbolic debugging using the MPLAB XC Compilers, and the MPASM and MPLAB Assemblers. The software simulator offers the flexibility to develop and debug code outside of the hardware laboratory environment, making it an excellent, economical software development tool.

## 30.7 MPLAB REAL ICE In-Circuit Emulator System

The MPLAB REAL ICE In-Circuit Emulator System is Microchip's next generation high-speed emulator for Microchip Flash DSC and MCU devices. It debugs and programs all 8, 16 and 32-bit MCU, and DSC devices with the easy-to-use, powerful graphical user interface of the MPLAB X IDE.

The emulator is connected to the design engineer's PC using a high-speed USB 2.0 interface and is connected to the target with either a connector compatible with in-circuit debugger systems (RJ-11) or with the new high-speed, noise tolerant, Low-Voltage Differential Signal (LVDS) interconnection (CAT5).

The emulator is field upgradable through future firmware downloads in MPLAB X IDE. MPLAB REAL ICE offers significant advantages over competitive emulators including full-speed emulation, run-time variable watches, trace analysis, complex breakpoints, logic probes, a ruggedized probe interface and long (up to three meters) interconnection cables.

## 30.8 MPLAB ICD 3 In-Circuit Debugger System

The MPLAB ICD 3 In-Circuit Debugger System is Microchip's most cost-effective, high-speed hardware debugger/programmer for Microchip Flash DSC and MCU devices. It debugs and programs PIC Flash microcontrollers and dsPIC DSCs with the powerful, yet easy-to-use graphical user interface of the MPLAB IDE.

The MPLAB ICD 3 In-Circuit Debugger probe is connected to the design engineer's PC using a high-speed USB 2.0 interface and is connected to the target with a connector compatible with the MPLAB ICD 2 or MPLAB REAL ICE systems (RJ-11). MPLAB ICD 3 supports all MPLAB ICD 2 headers.

## 30.9 PICkit 3 In-Circuit Debugger/Programmer

The MPLAB PICkit 3 allows debugging and programming of PIC and dsPIC Flash microcontrollers at a most affordable price point using the powerful graphical user interface of the MPLAB IDE. The MPLAB PICkit 3 is connected to the design engineer's PC using a full-speed USB interface and can be connected to the target via a Microchip debug (RJ-11) connector (compatible with MPLAB ICD 3 and MPLAB REAL ICE). The connector uses two device I/O pins and the Reset line to implement in-circuit debugging and In-Circuit Serial Programming™ (ICSP™).

## 30.10 MPLAB PM3 Device Programmer

The MPLAB PM3 Device Programmer is a universal, CE compliant device programmer with programmable voltage verification at VDDMIN and VDDMAX for maximum reliability. It features a large LCD display (128 x 64) for menus and error messages, and a modular, detachable socket assembly to support various package types. The ICSP cable assembly is included as a standard item. In Stand-Alone mode, the MPLAB PM3 Device Programmer can read, verify and program PIC devices without a PC connection. It can also set code protection in this mode. The MPLAB PM3 connects to the host PC via an RS-232 or USB cable. The MPLAB PM3 has high-speed communications and optimized algorithms for quick programming of large memory devices, and incorporates an MMC card for file storage and data applications.

# PIC24FJ256GA705 FAMILY

**TABLE 31-2: INSTRUCTION SET OVERVIEW (CONTINUED)**

Assembly Mnemonic	Assembly Syntax	Description	# of Words	# of Cycles	Status Flags Affected
PWRSVAV	PWRSVAV #lit1	Go into Sleep or Idle mode	1	1	WDTO, Sleep
RCALL	RCALL Expr	Relative Call	1	2	None
	RCALL Wn	Computed Call	1	2	None
REPEAT	REPEAT #lit14	Repeat Next Instruction lit14 + 1 times	1	1	None
	REPEAT Wn	Repeat Next Instruction (Wn) + 1 times	1	1	None
RESET	RESET	Software Device Reset	1	1	None
RETFIE	RETFIE	Return from Interrupt	1	3 (2)	None
RETLW	RETLW #lit10, Wn	Return with Literal in Wn	1	3 (2)	None
RETURN	RETURN	Return from Subroutine	1	3 (2)	None
RLC	RLC f	f = Rotate Left through Carry f	1	1	C, N, Z
	RLC f, WREG	WREG = Rotate Left through Carry f	1	1	C, N, Z
	RLC Ws, Wd	Wd = Rotate Left through Carry Ws	1	1	C, N, Z
RLNC	RLNC f	f = Rotate Left (No Carry) f	1	1	N, Z
	RLNC f, WREG	WREG = Rotate Left (No Carry) f	1	1	N, Z
	RLNC Ws, Wd	Wd = Rotate Left (No Carry) Ws	1	1	N, Z
RRC	RRC f	f = Rotate Right through Carry f	1	1	C, N, Z
	RRC f, WREG	WREG = Rotate Right through Carry f	1	1	C, N, Z
	RRC Ws, Wd	Wd = Rotate Right through Carry Ws	1	1	C, N, Z
RRNC	RRNC f	f = Rotate Right (No Carry) f	1	1	N, Z
	RRNC f, WREG	WREG = Rotate Right (No Carry) f	1	1	N, Z
	RRNC Ws, Wd	Wd = Rotate Right (No Carry) Ws	1	1	N, Z
SE	SE Ws, Wnd	Wnd = Sign-Extended Ws	1	1	C, N, Z
SETM	SETM f	f = FFFFh	1	1	None
	SETM WREG	WREG = FFFFh	1	1	None
	SETM Ws	Ws = FFFFh	1	1	None
SL	SL f	f = Left Shift f	1	1	C, N, OV, Z
	SL f, WREG	WREG = Left Shift f	1	1	C, N, OV, Z
	SL Ws, Wd	Wd = Left Shift Ws	1	1	C, N, OV, Z
	SL Wb, Wns, Wnd	Wnd = Left Shift Wb by Wns	1	1	N, Z
	SL Wb, #lit5, Wnd	Wnd = Left Shift Wb by lit5	1	1	N, Z
SUB	SUB f	f = f - WREG	1	1	C, DC, N, OV, Z
	SUB f, WREG	WREG = f - WREG	1	1	C, DC, N, OV, Z
	SUB #lit10, Wn	Wn = Wn - lit10	1	1	C, DC, N, OV, Z
	SUB Wb, Ws, Wd	Wd = Wb - Ws	1	1	C, DC, N, OV, Z
	SUB Wb, #lit5, Wd	Wd = Wb - lit5	1	1	C, DC, N, OV, Z
SUBB	SUBB f	f = f - WREG - ( $\overline{C}$ )	1	1	C, DC, N, OV, Z
	SUBB f, WREG	WREG = f - WREG - ( $\overline{C}$ )	1	1	C, DC, N, OV, Z
	SUBB #lit10, Wn	Wn = Wn - lit10 - ( $\overline{C}$ )	1	1	C, DC, N, OV, Z
	SUBB Wb, Ws, Wd	Wd = Wb - Ws - ( $\overline{C}$ )	1	1	C, DC, N, OV, Z
	SUBB Wb, #lit5, Wd	Wd = Wb - lit5 - ( $\overline{C}$ )	1	1	C, DC, N, OV, Z
SUBR	SUBR f	f = WREG - f	1	1	C, DC, N, OV, Z
	SUBR f, WREG	WREG = WREG - f	1	1	C, DC, N, OV, Z
	SUBR Wb, Ws, Wd	Wd = Ws - Wb	1	1	C, DC, N, OV, Z
	SUBR Wb, #lit5, Wd	Wd = lit5 - Wb	1	1	C, DC, N, OV, Z
SUBBR	SUBBR f	f = WREG - f - ( $\overline{C}$ )	1	1	C, DC, N, OV, Z
	SUBBR f, WREG	WREG = WREG - f - ( $\overline{C}$ )	1	1	C, DC, N, OV, Z
	SUBBR Wb, Ws, Wd	Wd = Ws - Wb - ( $\overline{C}$ )	1	1	C, DC, N, OV, Z
	SUBBR Wb, #lit5, Wd	Wd = lit5 - Wb - ( $\overline{C}$ )	1	1	C, DC, N, OV, Z
SWAP	SWAP.b Wn	Wn = Nibble Swap Wn	1	1	None
	SWAP Wn	Wn = Byte Swap Wn	1	1	None