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"[Embedded - Microcontrollers](#)" refer to small, integrated circuits designed to perform specific tasks within larger systems. These microcontrollers are essentially compact computers on a single chip, containing a processor core, memory, and programmable input/output peripherals. They are called "embedded" because they are embedded within electronic devices to control various functions, rather than serving as standalone computers. Microcontrollers are crucial in modern electronics, providing the intelligence and control needed for a wide range of applications.

Applications of "[Embedded - Microcontrollers](#)"

Details

Product Status	Active
Core Processor	ARM® Cortex®-M4
Core Size	32-Bit Single-Core
Speed	180MHz
Connectivity	CANbus, EBI/EMI, Ethernet, I²C, IrDA, SD, SPI, UART/USART, USB, USB OTG
Peripherals	DMA, I²S, LVD, POR, PWM, WDT
Number of I/O	116
Program Memory Size	2MB (2M x 8)
Program Memory Type	FLASH
EEPROM Size	-
RAM Size	256K x 8
Voltage - Supply (Vcc/Vdd)	1.71V ~ 3.6V
Data Converters	A/D 2x16b; D/A 2x12b
Oscillator Type	Internal
Operating Temperature	-40°C ~ 85°C (TA)
Mounting Type	Surface Mount
Package / Case	169-UFBGA, WLCSP
Supplier Device Package	169-WLCSP (5.5x5.63)
Purchase URL	https://www.e-xfl.com/product-detail/nxp-semiconductors/mk65fn2m0cac18r

Kinetis K65 Sub-Family

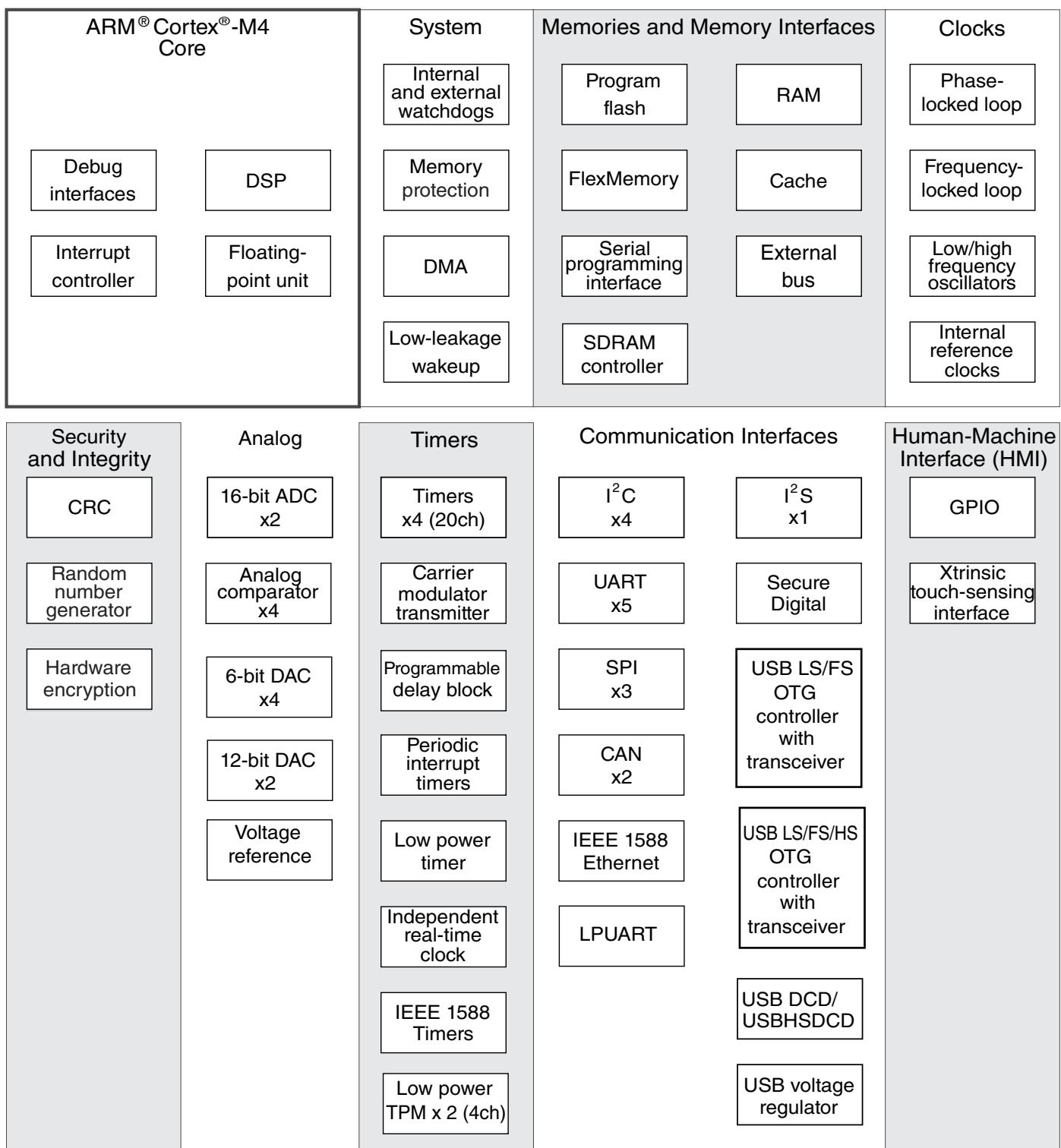


Figure 1. K65 Block Diagram

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Symbol	Description	Min.	Max.	Unit
V_{DD}	Digital supply voltage	-0.3	3.8	V
I_{DD}	Digital supply current	—	300	mA
V_{DIO}	Digital ¹ input voltage, including RESET_b	-0.3	$V_{DD} + 0.3$	V
V_{AIO}	Analog ¹ input voltage, including EXTAL32 and XTAL32	-0.3	$V_{DD} + 0.3$	V
I_D	Maximum current single pin limit (digital output pins)	-25	25	mA
V_{DDA}	Analog supply voltage	$V_{DD} - 0.3$	$V_{DD} + 0.3$	V
V_{USB0_DP}	USB0_DP input voltage	-0.3	3.63	V
V_{USB1_DP}	USB1_DP input voltage	-0.3	3.63	V
V_{USB0_DM}	USB0_DM input voltage	-0.3	3.63	V
V_{USB1_DM}	USB1_DM input voltage	-0.3	3.63	V
V_{USB1_VBUS}	USB1_VBUS detect voltage	-0.3	6.0	V
$V_{REG_IN0},$ V_{REG_IN1}	USB regulator input	-0.3	6.0	V
V_{BAT}	RTC battery supply voltage	-0.3	3.8	V

1. Digital pins have a general purpose I/O port assigned (e.g. PTA0). Analog pins do not have an associated general purpose I/O port.

2 General

2.1 AC electrical characteristics

Unless otherwise specified, propagation delays are measured from the 50% to the 50% point, and rise and fall times are measured at the 20% and 80% points, as shown in the following figure.

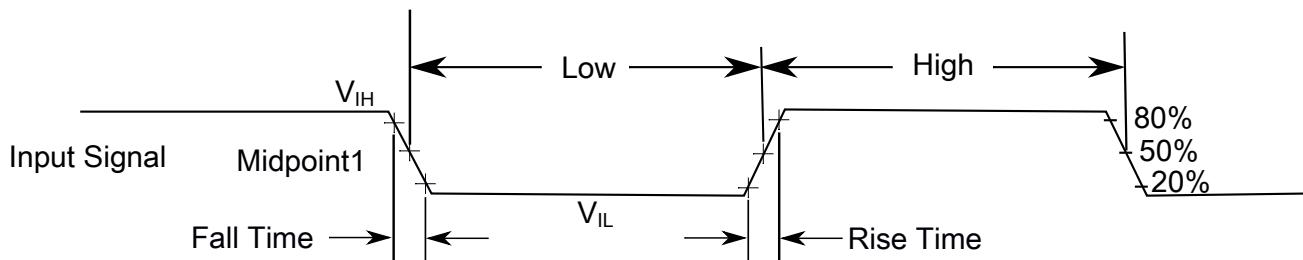


Figure 2. Input signal measurement reference

All digital I/O switching characteristics assume:

1. output pins

- have $C_L = 30\text{pF}$ loads,
 - are slew rate disabled, and
 - are normal drive strength
2. input pins
- have their passive filter disabled (PORTx_PCRn[PFE]=0)

2.2 Nonswitching electrical specifications

2.2.1 Voltage and current operating requirements

Table 1. Voltage and current operating requirements

Symbol	Description	Min.	Max.	Unit	Notes
V_{DD}	Supply voltage	1.71	3.6	V	
V_{DDA}	Analog supply voltage	1.71	3.6	V	
$V_{DD} - V_{DDA}$	V_{DD} -to- V_{DDA} differential voltage	-0.1	0.1	V	
$V_{SS} - V_{SSA}$	V_{SS} -to- V_{SSA} differential voltage	-0.1	0.1	V	
V_{BAT}	RTC battery supply voltage	1.71	3.6	V	
V_{IH}	Input high voltage				
	• $2.7\text{ V} \leq V_{DD} \leq 3.6\text{ V}$	$0.7 \times V_{DD}$	—	V	
	• $1.71\text{ V} \leq V_{DD} \leq 2.7\text{ V}$	$0.75 \times V_{DD}$	—	V	
V_{IL}	Input low voltage				
	• $2.7\text{ V} \leq V_{DD} \leq 3.6\text{ V}$	—	$0.35 \times V_{DD}$	V	
	• $1.71\text{ V} \leq V_{DD} \leq 2.7\text{ V}$	—	$0.3 \times V_{DD}$	V	
V_{HYS}	Input hysteresis	$0.06 \times V_{DD}$	—	V	
I_{ICDIO}	Digital ¹ input pin negative DC injection current — single pin	-5	—	mA	²
	• $V_{IN} < V_{SS}-0.3\text{V}$				
I_{ICAIO}	Analog ¹ input pin DC injection current — single pin			mA	²
	• $V_{IN} < V_{SS}-0.3\text{V}$ (Negative current injection)	-5	—		
I_{ICcont}	Contiguous pin DC injection current —regional limit, includes sum of negative injection currents of 16 contiguous pin			mA	
	• Negative current injection	-25	—		
V_{ODPU}	Pseudo Open drain pullup voltage level	V_{DD}	V_{DD}	V	³
V_{RAM}	V_{DD} voltage required to retain RAM	1.2	—	V	
V_{RFVBAT}	V_{BAT} voltage required to retain the VBAT register file	V_{POR_VBAT}	—	V	

Table 7. Power consumption operating behaviors (continued)

Symbol	Description	Min.	Typ.	Max.	Unit	Notes
I _{DD_WAIT}	Wait mode reduced frequency current at 3.0 V — all peripheral clocks enabled	—	35	62.81	mA	9
I _{DD_VLPR}	Very-low-power run mode current at 3.0 V — all peripheral clocks disabled	—	1.1	9.56	mA	10
I _{DD_VLPR}	Very-low-power run mode current at 3.0 V — all peripheral clocks enabled	—	2	9.88	mA	11
I _{DD_VLPRC_O}	Very-low-power run mode current in compute operation - 4 MHz core / 1 MHz flash / bus clock disabled, LPTMR running with 4 MHz internal reference clock • at 3.0 V	—	986	9.47	μA	12
I _{DD_VLPW}	Very-low-power wait mode current at 3.0 V — all peripheral clocks disabled	—	0.690	9.25	mA	13
I _{DD_VLPW}	Very-low-power wait mode current at 3.0 V — all peripheral clocks enabled	—	1.5	10.00	mA	
I _{DD_STOP}	Stop mode current at 3.0 V • @ -40 to 25°C • @ 70°C • @ 85°C	— — —	0.791 3.8 6.8	2.39 6.91 11.44	mA mA mA	
I _{DD_VLPS}	Very-low-power stop mode current at 3.0 V • @ -40 to 25°C • @ 70°C • @ 85°C	— — —	202 1400 2700	353.77 2464.54 4642.45	μA μA μA	
I _{DD_LLSS3}	Low leakage stop mode current at 3.0 V • @ -40 to 25°C • @ 70°C • @ 85°C	— — —	9.0 76.3 169.1	16.5 88.63 181.46	μA μA μA	
I _{DD_LLSS2}	Low leakage stop mode current at 3.0 V • @ -40 to 25°C • @ 70°C • @ 85°C	— — —	5.7 41.3 92.4	9.7 55.80 120.01	μA μA μA	
I _{DD_VLLS3}	Very low-leakage stop mode 3 current at 3.0 V • @ -40 to 25°C • @ 70°C • @ 85°C	— — —	5.5 46.3 104	7.31 58.33 196.02	μA μA μA	
I _{DD_VLLS2}	Very low-leakage stop mode 2 current at 3.0 V • @ -40 to 25°C • @ 70°C • @ 85°C	— — —	2.7 13.1 29.6	3.24 18.72 37.49	μA μA μA	

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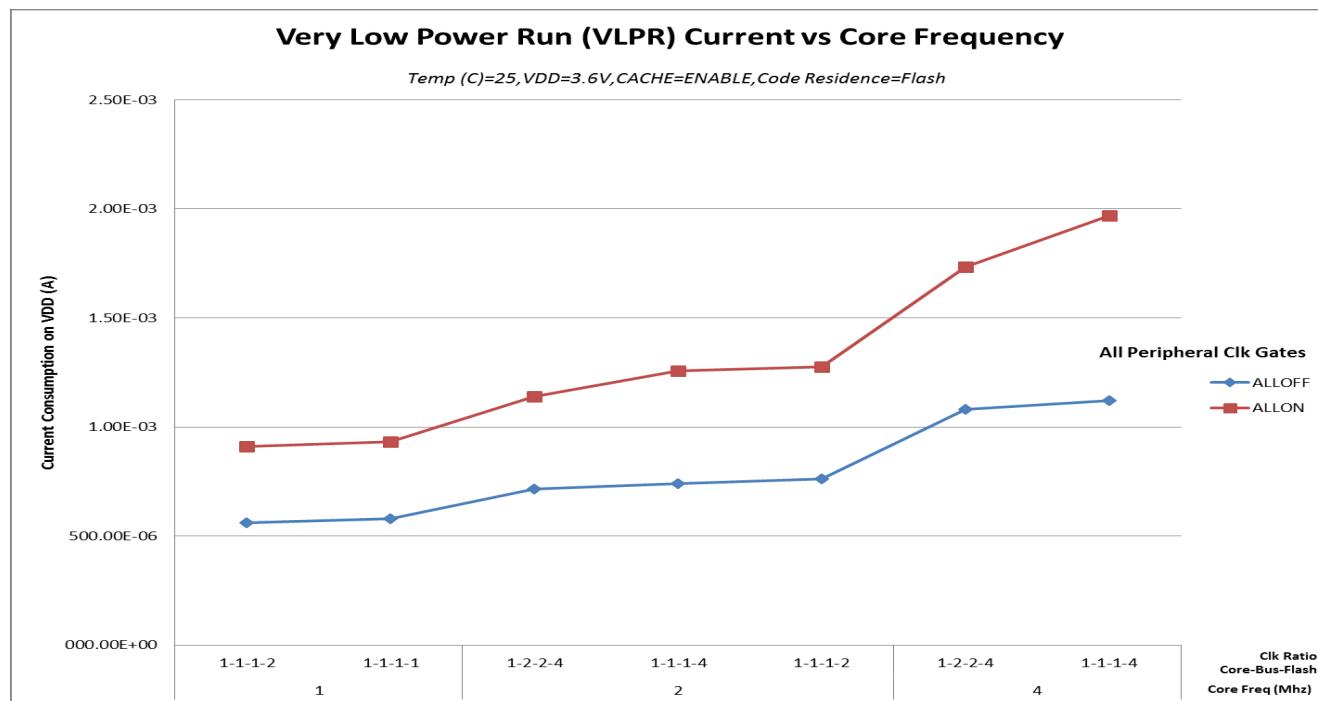


Figure 4. VLPR mode supply current vs. core frequency

2.2.6 EMC radiated emissions operating behaviors

Table 8. EMC radiated emissions operating behaviors

Symbol	Description	Frequency band (MHz)	Typ.	Unit	Notes
V _{RE1}	Radiated emissions voltage, band 1	0.15–50	23	dB μ V	1, 2
V _{RE2}	Radiated emissions voltage, band 2	50–150	27	dB μ V	
V _{RE3}	Radiated emissions voltage, band 3	150–500	28	dB μ V	
V _{RE4}	Radiated emissions voltage, band 4	500–1000	14	dB μ V	
V _{RE_IEC}	IEC level	0.15–1000	K	—	2, 3

- Determined according to IEC Standard 61967-1, *Integrated Circuits - Measurement of Electromagnetic Emissions, 150 kHz to 1 GHz Part 1: General Conditions and Definitions* and IEC Standard 61967-2, *Integrated Circuits - Measurement of Electromagnetic Emissions, 150 kHz to 1 GHz Part 2: Measurement of Radiated Emissions – TEM Cell and Wideband TEM Cell Method*. Measurements were made while the microcontroller was running basic application code.

Table 10. Device clock specifications (continued)

Symbol	Description	Min.	Max.	Unit	Notes
f_{BUS}	Bus clock	—	60	MHz	
FB_CLK	FlexBus clock	—	60	MHz	
f_{FLASH}	Flash clock	—	28	MHz	
f_{LPTMR}	LPTMR clock	—	25	MHz	
VLPR mode ¹					
f_{SYS}	System and core clock	—	4	MHz	
f_{BUS}	Bus clock	—	4	MHz	
FB_CLK	FlexBus clock	—	4	MHz	
f_{FLASH}	Flash clock	—	1	MHz	
f_{ERCLK}	External reference clock	—	16	MHz	
f_{LPTMR_pin}	LPTMR clock	—	25	MHz	
$f_{FlexCAN_ERCLK}$	FlexCAN external reference clock	—	8	MHz	
f_{I2S_MCLK}	I2S master clock	—	12.5	MHz	
f_{I2S_BCLK}	I2S bit clock	—	4	MHz	

1. The frequency limitations in VLPR mode here override any frequency specification listed in the timing specification for any other module.

2.3.2 General switching specifications

These general purpose specifications apply to all signals configured for GPIO, UART, CAN, CMT, IEEE 1588 timer, timers, and I²C signals.

Table 11. General switching specifications

Symbol	Description	Min.	Max.	Unit	Notes
	GPIO pin interrupt pulse width (digital glitch filter disabled) — Synchronous path	1.5	—	Bus clock cycles	1, 2
	GPIO pin interrupt pulse width (digital glitch filter disabled, analog filter enabled) — Asynchronous path	100	—	ns	3
	GPIO pin interrupt pulse width (digital glitch filter disabled, analog filter disabled) — Asynchronous path	50	—	ns	3
	External reset pulse width (digital glitch filter disabled)	100	—	ns	3
	Mode select (EZP_CS) hold time after reset deassertion	2	—	Bus clock cycles	
	Port rise and fall time (high drive strength) • Slew enabled	—	25	ns	4
		—	15	ns	

Table continues on the next page...

3.1.2 JTAG electricals

Table 14. JTAG limited voltage range electricals

Symbol	Description	Min.	Max.	Unit
	Operating voltage	2.7	3.6	V
J1	TCLK frequency of operation <ul style="list-style-type: none"> • Boundary Scan • JTAG and CJTAG • Serial Wire Debug 	0	10	MHz
		0	25	
		0	50	
J2	TCLK cycle period	1/J1	—	ns
J3	TCLK clock pulse width <ul style="list-style-type: none"> • Boundary Scan • JTAG and CJTAG • Serial Wire Debug 	50	—	ns
		20	—	ns
		10	—	ns
J4	TCLK rise and fall times	—	3	ns
J5	Boundary scan input data setup time to TCLK rise	20	—	ns
J6	Boundary scan input data hold time after TCLK rise	2.0	—	ns
J7	TCLK low to boundary scan output data valid	—	28	ns
J8	TCLK low to boundary scan output high-Z	—	25	ns
J9	TMS, TDI input data setup time to TCLK rise	8	—	ns
J10	TMS, TDI input data hold time after TCLK rise	1	—	ns
J11	TCLK low to TDO data valid	—	19	ns
J12	TCLK low to TDO high-Z	—	17	ns
J13	TRST assert time	100	—	ns
J14	TRST setup time (negation) to TCLK high	8	—	ns

Table 15. JTAG full voltage range electricals

Symbol	Description	Min.	Max.	Unit
	Operating voltage	1.71	3.6	V
J1	TCLK frequency of operation <ul style="list-style-type: none"> • Boundary Scan • JTAG and CJTAG • Serial Wire Debug 	0	10	MHz
		0	20	
		0	40	
J2	TCLK cycle period	1/J1	—	ns
J3	TCLK clock pulse width <ul style="list-style-type: none"> • Boundary Scan 	50	—	ns

Table continues on the next page...

Table 16. MCG specifications (continued)

Symbol	Description	Min.	Typ.	Max.	Unit	Notes
f_{loc_low}	Loss of external clock minimum frequency — RANGE = 00 ext clk freq: above $(3/5)f_{int}$ never reset ext clk freq: between $(2/5)f_{int}$ and $(3/5)f_{int}$ maybe reset (phase dependency) ext clk freq: below $(2/5)f_{int}$ always reset	$(3/5) \times f_{ints_t}$	—	—	kHz	
f_{loc_high}	Loss of external clock minimum frequency — RANGE = 01, 10, or 11 ext clk freq: above $(16/5)f_{int}$ never reset ext clk freq: between $(15/5)f_{int}$ and $(16/5)f_{int}$ maybe reset (phase dependency) ext clk freq: below $(15/5)f_{int}$ always reset	$(16/5) \times f_{ints_t}$	—	—	kHz	
FLL						
f_{fll_ref}	FLL reference frequency range	31.25	—	39.0625	kHz	
f_{dco_ut}	DCO output frequency range — untrimmed	Low range (DRS=00, DMX32=0) $640 \times f_{ints_ut}$	16.0	23.04	26.66	MHz 2
		Mid range (DRS=01, DMX32=0) $1280 \times f_{ints_ut}$	32.0	46.08	53.32	
		Mid-high range (DRS=10, DMX32=0) $1920 \times f_{ints_ut}$	48.0	69.12	79.99	
		High range (DRS=11, DMX32=0) $2560 \times f_{ints_ut}$	64.0	92.16	106.65	
		Low range (DRS=00, DMX32=1) $732 \times f_{ints_ut}$	18.3	26.35	30.50	
		Mid range (DRS=01, DMX32=1) $1464 \times f_{ints_ut}$	36.6	52.70	60.99	
		Mid-high range (DRS=10, DMX32=1) $2197 \times f_{ints_ut}$	54.93	79.09	91.53	
		High range (DRS=11, DMX32=1) $2929 \times f_{ints_ut}$	73.23	105.44	122.02	

Table continues on the next page...

Table 17. IRC48M specifications (continued)

Symbol	Description	Min.	Typ.	Max.	Unit	Notes
	<ul style="list-style-type: none"> Regulator enable (USB_CLK_RECOVER_IRC_EN[REG_EN]=1) 					
Δf_{irc48m_cl}	Closed loop total deviation of IRC48M frequency over voltage and temperature	—	—	± 0.1	%f _{host}	2
J _{cyc_irc48m}	Period Jitter (RMS)	—	35	150	ps	
t _{irc48mst}	Startup time	—	2	3	μs	3

- The maximum value represents characterized results equivalent to mean plus or minus three times the standard deviation (mean ± 3 sigma)
- Closed loop operation of the IRC48M is only feasible for USB device operation; it is not usable for USB host operation. It is enabled by configuring for USB Device, selecting IRC48M as USB clock source, and enabling the clock recover function (USB_CLK_RECOVER_IRC_CTRL[CLOCK_RECOVER_EN]=1, USB_CLK_RECOVER_IRC_EN[IRC_EN]=1).
- IRC48M startup time is defined as the time between clock enablement and clock availability for system use. Enable the clock by one of the following settings:
 - USB_CLK_RECOVER_IRC_EN[IRC_EN]=1, or
 - MCG_C7[OSCSEL]=10, or
 - SIM_SOPT2[PLLFLSEL]=11

3.3.3 Oscillator electrical specifications

3.3.3.1 Oscillator DC electrical specifications

Table 18. Oscillator DC electrical specifications

Symbol	Description	Min.	Typ.	Max.	Unit	Notes
V _{DD}	Supply voltage	1.71	—	3.6	V	
I _{DDOSC}	Supply current — low-power mode (HGO=0)					
	<ul style="list-style-type: none"> 32 kHz 4 MHz 8 MHz (RANGE=01) 16 MHz 24 MHz 32 MHz 	—	600	—	nA	1
		—	200	—	μA	
		—	300	—	μA	
		—	950	—	μA	
		—	1.2	—	mA	
		—	1.5	—	mA	
I _{DDOSC}	Supply current — high gain mode (HGO=1)					1
	<ul style="list-style-type: none"> 32 kHz 4 MHz 8 MHz (RANGE=01) 16 MHz 	—	7.5	—	μA	
		—	500	—	μA	
		—	650	—	μA	
		—	2.5	—	mA	

Table continues on the next page...

Table 23. Flash command timing specifications (continued)

Symbol	Description	Min.	Typ.	Max.	Unit	Notes
$t_{setram128k}$	• 128 KB EEPROM backup	—	2.4	3.1	ms	
$t_{setram256k}$	• 256 KB EEPROM backup	—	4.5	5.5	ms	
$t_{eewr8b32k}$	Byte-write to FlexRAM execution time: • 32 KB EEPROM backup	—	385	1700	μs	
$t_{eewr8b64k}$	• 64 KB EEPROM backup	—	475	2000	μs	
$t_{eewr8b128k}$	• 128 KB EEPROM backup	—	650	2350	μs	
$t_{eewr8b256k}$	• 256 KB EEPROM backup	—	1000	3250	μs	
$t_{eewr16b32k}$	16-bit write to FlexRAM execution time: • 32 KB EEPROM backup	—	385	1700	μs	
$t_{eewr16b64k}$	• 64 KB EEPROM backup	—	475	2000	μs	
$t_{eewr16b128k}$	• 128 KB EEPROM backup	—	650	2350	μs	
$t_{eewr16b256k}$	• 256 KB EEPROM backup	—	1000	3250	μs	
$t_{eewr32bers}$	32-bit write to erased FlexRAM location execution time	—	360	550	μs	
$t_{eewr32b32k}$	32-bit write to FlexRAM execution time: • 32 KB EEPROM backup	—	630	2000	μs	
$t_{eewr32b64k}$	• 64 KB EEPROM backup	—	810	2250	μs	
$t_{eewr32b128k}$	• 128 KB EEPROM backup	—	1200	2650	μs	
$t_{eewr32b256k}$	• 256 KB EEPROM backup	—	1900	3500	μs	

- Assumes 25MHz or greater flash clock frequency.
- Maximum times for erase parameters based on expectations at cycling end-of-life.

3.4.1.3 Flash high voltage current behaviors

Table 24. Flash high voltage current behaviors

Symbol	Description	Min.	Typ.	Max.	Unit
I_{DD_PGM}	Average current adder during high voltage flash programming operation	—	3.5	7.5	mA
I_{DD_ERS}	Average current adder during high voltage flash erase operation	—	1.5	4.0	mA

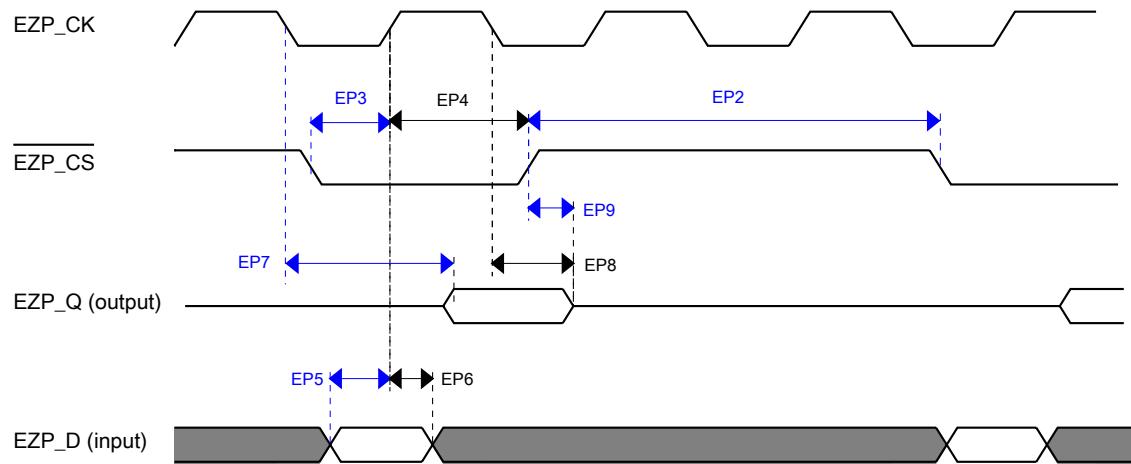


Figure 12. EzPort Timing Diagram

3.4.3 Flexbus switching specifications

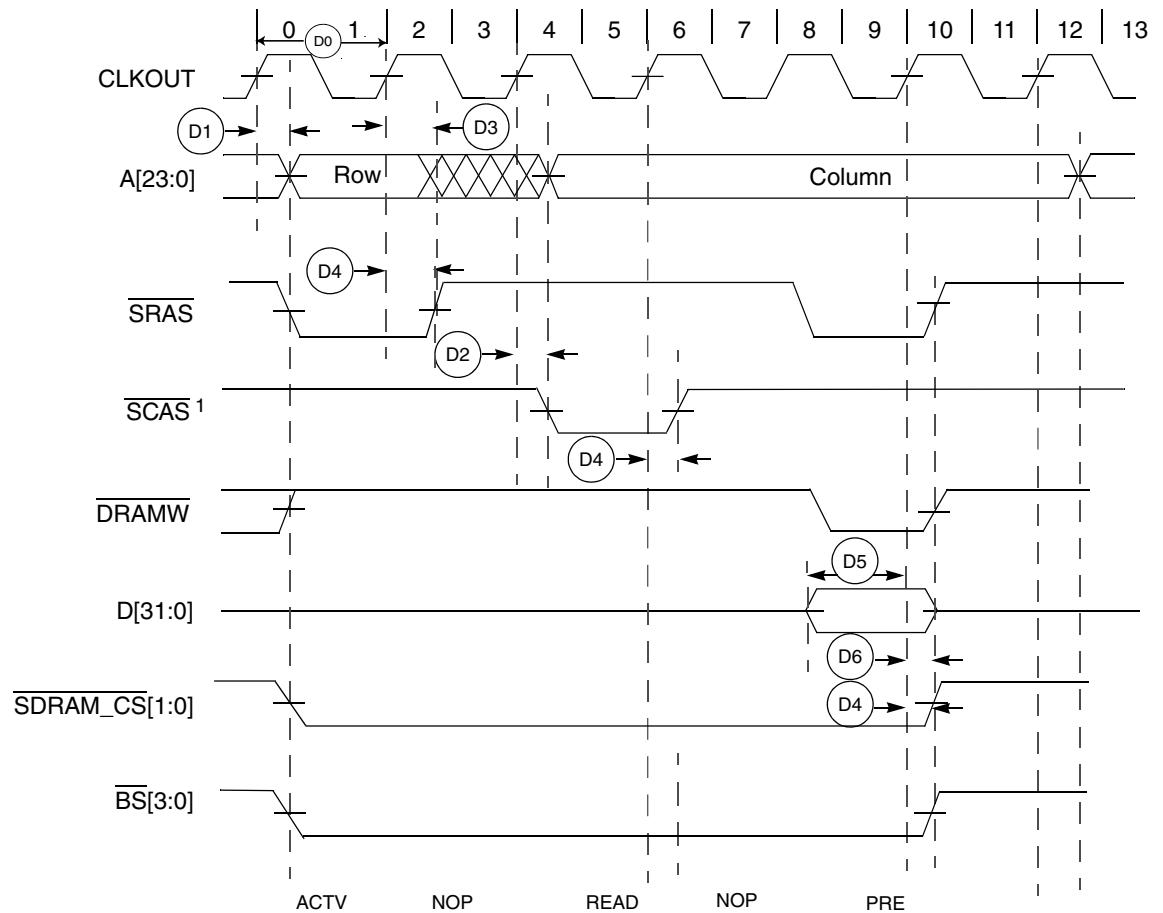
All processor bus timings are synchronous; input setup/hold and output delay are given in respect to the rising edge of a reference clock, FB_CLK. The FB_CLK frequency may be the same as the internal system bus frequency or an integer divider of that frequency.

The following timing numbers indicate when data is latched or driven onto the external bus, relative to the Flexbus output clock (FB_CLK). All other timing relationships can be derived from these values.

Table 27. Flexbus limited voltage range switching specifications

Num	Description	Min.	Max.	Unit	Notes
	Operating voltage	2.7	3.6	V	
	Frequency of operation	—	FB_CLK	MHz	
FB1	Clock period	1/FB_CLK	—	ns	
FB2	Address, data, and control output valid	—	11.8	ns	
FB3	Address, data, and control output hold	1.0	—	ns	1
FB4	Data and FB_TA input setup	11.9	—	ns	
FB5	Data and FB_TA input hold	0.0	—	ns	2

1. Specification is valid for all FB_AD[31:0], FB_BE/BWE_n, FB_CS_n, FB_OE, FB_R/W, FB_TBST, FB_TSIZ[1:0], FB_ALE, and FB_TS.



¹DACR[CASL] = 2

Figure 15. SDRAM read timing diagram

Table 29. SDRAM Timing (Full voltage range)

NUM	Characteristic ¹	Symbol	Min	Max	Unit
	Operating voltage	1.71	3.6	V	
	Frequency of operation	—	CLKOUT	MHz	
D0	Clock period	1/CLKOUT	—	ns	²
D1	CLKOUT high to SDRAM address valid	t _{CHDAV}	-	11.2	ns
D2	CLKOUT high to SDRAM control valid	t _{CHDCV}		11.1	ns
D3	CLKOUT high to SDRAM address invalid	t _{CHDAI}	1.0	-	ns
D4	CLKOUT high to SDRAM control invalid	t _{CHDCI}	1.0	-	ns
D5	SDRAM data valid to CLKOUT high	t _{DDVCH}	12.0	-	ns
D6	CLKOUT high to SDRAM data invalid	t _{CHDDI}	1.0	-	ns
D7 ³	CLKOUT high to SDRAM data valid	t _{CHDDVW}	-	12.0	ns
D8 ³	CLKOUT high to SDRAM data invalid	t _{CHDDIW}	1.0	-	ns

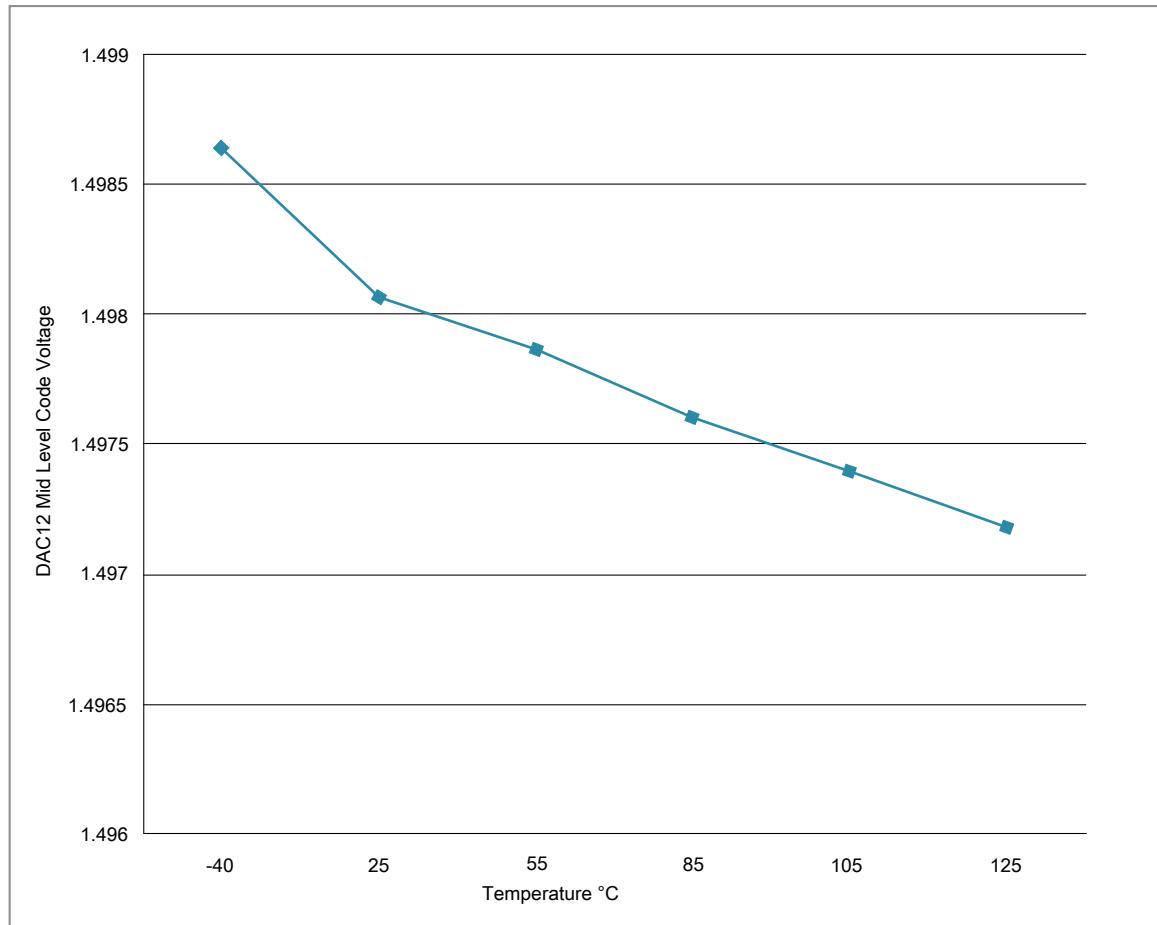
1. All timing specifications are based on taking into account, a 25pF load on the SDRAM output pins.

2. CLKOUT is same as FB_CLK, maximum frequency can be 60 MHz

Table 32. 16-bit ADC characteristics ($V_{REFH} = V_{DDA}$, $V_{REFL} = V_{SSA}$) (continued)

Symbol	Description	Conditions ¹	Min.	Typ. ²	Max.	Unit	Notes
INL	Integral non-linearity	<ul style="list-style-type: none"> • 12-bit modes • <12-bit modes 	—	±1.0 ±0.5	-2.7 to +1.9 -0.7 to +0.5	LSB ⁴	5
E _{FS}	Full-scale error	<ul style="list-style-type: none"> • 12-bit modes • <12-bit modes 	—	-4 -1.4	-5.4 -1.8	LSB ⁴	$V_{ADIN} = V_{DDA}$ ⁵
E _Q	Quantization error	<ul style="list-style-type: none"> • 16-bit modes • ≤13-bit modes 	—	-1 to 0 —	— ±0.5	LSB ⁴	
ENOB	Effective number of bits	16-bit differential mode <ul style="list-style-type: none"> • Avg = 32 • Avg = 4 16-bit single-ended mode <ul style="list-style-type: none"> • Avg = 32 • Avg = 4 	12.8 11.9 12.2 11.4	14.5 13.8 13.9 13.1	— — — —	bits bits bits bits	6
SINAD	Signal-to-noise plus distortion	See ENOB		6.02 × ENOB + 1.76		dB	
THD	Total harmonic distortion	16-bit differential mode <ul style="list-style-type: none"> • Avg = 32 16-bit single-ended mode <ul style="list-style-type: none"> • Avg = 32 	— —	-94 -85	— —	dB dB	7
SFDR	Spurious free dynamic range	16-bit differential mode <ul style="list-style-type: none"> • Avg = 32 16-bit single-ended mode <ul style="list-style-type: none"> • Avg = 32 	82 78	95 90	— —	dB dB	7
E _{IL}	Input leakage error			$I_{In} \times R_{AS}$		mV	I_{In} = leakage current (refer to the MCU's voltage and current operating ratings)
	Temp sensor slope	Across the full temperature range of the device	1.55	1.62	1.69	mV/°C	8
V _{TEMP25}	Temp sensor voltage	25 °C	706	716	726	mV	8

1. All accuracy numbers assume the ADC is calibrated with $V_{REFH} = V_{DDA}$
2. Typical values assume $V_{DDA} = 3.0$ V, Temp = 25 °C, $f_{ADCK} = 2.0$ MHz unless otherwise stated. Typical values are for reference only and are not tested in production.

**Figure 23. Offset at half scale vs. temperature**

3.6.4 Voltage reference electrical specifications

Table 36. VREF full-range operating requirements

Symbol	Description	Min.	Max.	Unit	Notes
V_{DDA}	Supply voltage		3.6	V	
T_A	Temperature	Operating temperature range of the device		°C	
C_L	Output load capacitance	100		nF	1, 2

1. C_L must be connected to VREF_OUT if the VREF_OUT functionality is being used for either an internal or external reference.
2. The load capacitance should not exceed +/-25% of the nominal specified C_L value over the operating temperature range of the device.

3.8.4 USB DCD electrical specifications

Table 43. USB DCD electrical specifications

Symbol	Description	Min.	Typ.	Max.	Unit
V_{DP_SRC} , V_{DM_SRC}	USB_DP and USB_DM source voltages (up to 250 μ A)	0.5	—	0.7	V
V_{LGC}	Threshold voltage for logic high	0.8	—	2.0	V
I_{DP_SRC}	USB_DP source current	7	10	13	μ A
I_{DM_SINK} , I_{DP_SINK}	USB_DM and USB_DP sink currents	50	100	150	μ A
R_{DM_DWN}	D-pulldown resistance for data pin contact detect	14.25	—	24.8	k Ω
V_{DAT_REF}	Data detect voltage	0.25	0.33	0.4	V

3.8.5 CAN switching specifications

See [General switching specifications](#).

3.8.6 DSPI switching specifications (limited voltage range)

The DMA Serial Peripheral Interface (DSPI) provides a synchronous serial bus with master and slave operations. Many of the transfer attributes are programmable. The tables below provide DSPI timing characteristics for classic SPI timing modes. Refer to the DSPI chapter of the Reference Manual for information on the modified transfer formats used for communicating with slower peripheral devices.

Table 44. Master mode DSPI timing (limited voltage range)

Num	Description	Min.	Max.	Unit	Notes
	Operating voltage	2.7	3.6	V	
	Frequency of operation	—	30	MHz	
DS1	DSPI_SCK output cycle time	$2 \times t_{BUS}$	—	ns	
DS2	DSPI_SCK output high/low time	$(t_{SCK}/2) - 2$	$(t_{SCK}/2) + 2$	ns	
DS3	DSPI_PCSn valid to DSPI_SCK delay	$(t_{BUS} \times 2) - 2$	—	ns	1
DS4	DSPI_SCK to DSPI_PCSn invalid delay	$(t_{BUS} \times 2) - 2$	—	ns	2
DS5	DSPI_SCK to DSPI_SOUT valid	—	15.0	ns	
DS6	DSPI_SCK to DSPI_SOUT invalid	1.0	—	ns	

Table continues on the next page...

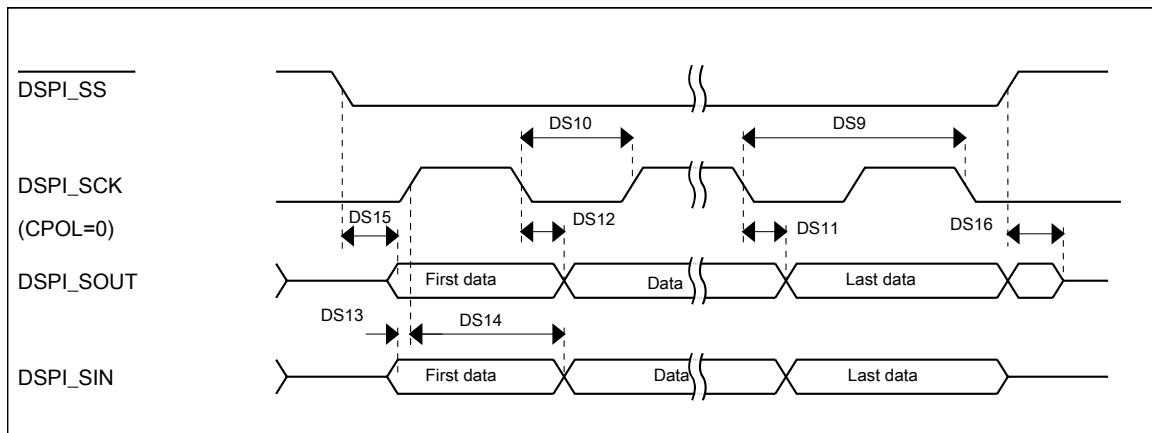


Figure 27. DSPI classic SPI timing — slave mode

3.8.7 DSPI switching specifications (full voltage range)

The DMA Serial Peripheral Interface (DSPI) provides a synchronous serial bus with master and slave operations. Many of the transfer attributes are programmable. The tables below provides DSPI timing characteristics for classic SPI timing modes. Refer to the DSPI chapter of the Reference Manual for information on the modified transfer formats used for communicating with slower peripheral devices.

Table 46. Master mode DSPI timing (full voltage range)

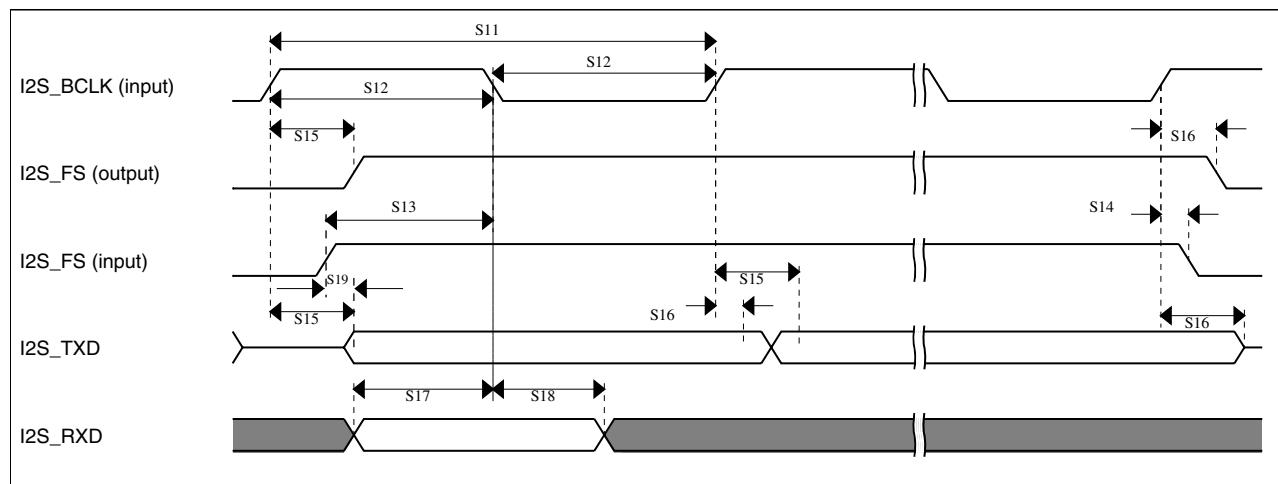
Num	Description	Min.	Max.	Unit	Notes
	Operating voltage	1.71	3.6	V	1
	Frequency of operation	—	15	MHz	
DS1	DSPI_SCK output cycle time	$4 \times t_{BUS}$	—	ns	
DS2	DSPI_SCK output high/low time	$(t_{SCK}/2) - 4$	$(t_{SCK}/2) + 4$	ns	
DS3	DSPI_PCSn valid to DSPI_SCK delay	$(t_{BUS} \times 2) - 4$	—	ns	2
DS4	DSPI_SCK to DSPI_PCSn invalid delay	$(t_{BUS} \times 2) - 4$	—	ns	3
DS5	DSPI_SCK to DSPI_SOUT valid	—	15	ns	
DS6	DSPI_SCK to DSPI_SOUT invalid	1.0	—	ns	
DS7	DSPI_SIN to DSPI_SCK input setup	15.8	—	ns	
DS8	DSPI_SCK to DSPI_SIN input hold	0	—	ns	

1. The DSPI module can operate across the entire operating voltage for the processor, but to run across the full voltage range the maximum frequency of operation is reduced.
2. The delay is programmable in SPIx_CTARn[PSSCK] and SPIx_CTARn[CSSCK].
3. The delay is programmable in SPIx_CTARn[PASC] and SPIx_CTARn[ASC].

Table 51. I²S slave mode timing (limited voltage range) (continued)

Num	Description	Min.	Max.	Unit
S13	I ² S_FS input setup before I ² S_BCLK	4.5	—	ns
S14	I ² S_FS input hold after I ² S_BCLK	2	—	ns
S15	I ² S_BCLK to I ² S_TXD/I ² S_FS output valid	—	20	ns
S16	I ² S_BCLK to I ² S_TXD/I ² S_FS output invalid	0	—	ns
S17	I ² S_RXD setup before I ² S_BCLK	4.5	—	ns
S18	I ² S_RXD hold after I ² S_BCLK	2	—	ns
S19	I ² S_TX_FS input assertion to I ² S_TXD output valid ¹		25	ns

1. Applies to first bit in each frame and only if the TCR4[FSE] bit is clear

**Figure 32. I²S timing — slave modes**

3.8.12.1 Normal Run, Wait and Stop mode performance over the full operating voltage range

This section provides the operating performance over the full operating voltage for the device in Normal Run, Wait and Stop modes.

Table 52. I²S/SAI master mode timing

Num.	Characteristic	Min.	Max.	Unit
	Operating voltage	1.71	3.6	V
S1	I ² S_MCLK cycle time	40	—	ns
S2	I ² S_MCLK (as an input) pulse width high/low	45%	55%	MCLK period
S3	I ² S_TX_BCLK/I ² S_RX_BCLK cycle time (output)	80	—	ns
S4	I ² S_TX_BCLK/I ² S_RX_BCLK pulse width high/low	45%	55%	BCLK period

Table continues on the next page...

Pinout

169 WLC SP	Pin Name	Default	ALT0	ALT1	ALT2	ALT3	ALT4	ALT5	ALT6	ALT7	EzPort
M3	VDD	VDD	VDD								
M2	VSS	VSS	VSS								
N1	PTA18	EXTAL0	EXTAL0	PTA18		FTM0_FLT2	FTM_CLKIN0			TPM_CLKIN0	
N2	PTA19	XTAL0	XTAL0	PTA19		FTM1_FLT0	FTM_CLKIN1		LPTMR0_ ALT1	TPM_CLKIN1	
M1	RESET_b	RESET_b	RESET_b								
K3	PTA24	CMP3_IN4	CMP3_IN4	PTA24				MII0_TXD2	FB_A15/ SDRAM_D15	FB_A29	
J4	PTA25	CMP3_IN5	CMP3_IN5	PTA25				MII0_TXCLK	FB_A14/ SDRAM_D14	FB_A28	
J3	PTA26	DISABLED		PTA26				MII0_TXD3	FB_A13/ SDRAM_D13	FB_A27	
L2	PTA27	DISABLED		PTA27				MII0_CRS	FB_A12/ SDRAM_D12	FB_A26	
L1	PTA28	DISABLED		PTA28				MII0_TXER		FB_A25	
K2	PTA29	DISABLED		PTA29				MII0_COL		FB_A24	
K1	PTA30	DISABLED		PTA30	CANO_TX				FB_A11/ SDRAM_D11		
H5	PTA31	DISABLED		PTA31	CANO_RX				FB_A10/ SDRAM_D10		
H4	PTB0/ LLWU_P5	ADC0_SE8/ ADC1_SE8/ TSI0_CH0	ADC0_SE8/ ADC1_SE8/ TSI0_CH0	PTB0/ LLWU_P5	I2CO_SCL	FTM1_CH0	RMI0_MDIO/ MII0_MDIO	SDRAM_CAS_b	FTM1_QD_ PHA/ TPM1_CH0		
J2	PTB1	ADC0_SE9/ ADC1_SE9/ TSI0_CH6	ADC0_SE9/ ADC1_SE9/ TSI0_CH6	PTB1	I2CO_SDA	FTM1_CH1	RMI0_MDC/ MII0_MDC	SDRAM_RAS_b	FTM1_QD_ PHB/ TPM1_CH1		
J1	PTB2	ADC0_SE12/ TSI0_CH7	ADC0_SE12/ TSI0_CH7	PTB2	I2CO_SCL	UART0_RTS_b	ENET0_1588_TMR0	SDRAM_WE	FTM0_FLT3		
H3	PTB3	ADC0_SE13/ TSI0_CH8	ADC0_SE13/ TSI0_CH8	PTB3	I2CO_SDA	UART0_CTS_b/ UART0_COL_b	ENET0_1588_TMR1	SDRAM_CS0_b	FTM0_FLT0		
G7	VSS	VSS	VSS								
G6	VDD	VDD	VDD								
H2	PTB4	ADC1_SE10	ADC1_SE10	PTB4				ENET0_1588_TMR2	SDRAM_CS1_b	FTM1_FLT0	
H1	PTB5	ADC1_SE11	ADC1_SE11	PTB5				ENET0_1588_TMR3		FTM2_FLT0	
G5	PTB6	ADC1_SE12	ADC1_SE12	PTB6					FB_AD23/ SDRAM_D23		
G4	PTB7	ADC1_SE13	ADC1_SE13	PTB7					FB_AD22/ SDRAM_D22		
G3	PTB8	DISABLED		PTB8			UART3_RTS_b		FB_AD21/ SDRAM_D21		

5.2 Recommended connection for unused analog and digital pins

Table 57 shows the recommended connections for analog interface pins if those analog interfaces are not used in the customer's application

Table 57. Recommended connection for unused analog interfaces

Pin Type	K65	Short recommendation	Detailed recommendation
Analog/non GPIO	ADCx/CMPx	Float	Analog input - Float
Analog/non GPIO	VREF_OUT	Float	Analog output - Float
Analog/non GPIO	DAC0_OUT, DAC1_OUT	Float	Analog output - Float
Analog/non GPIO	RTC_WAKEUP_B	Float	Analog output - Float
Analog/non GPIO	XTAL32	Float	Analog output - Float
Analog/non GPIO	EXTAL32	Float	Analog input - Float
GPIO/Analog	PTA18/EXTAL0	Float	Analog input - Float
GPIO/Analog	PTA19/XTAL0	Float	Analog output - Float
GPIO/Analog	PTx/ADCx	Float	Float (default is analog input)
GPIO/Analog	PTx/CMPx	Float	Float (default is analog input)
GPIO/Analog	PTx/TSIOx	Float	Float (default is analog input)
GPIO/Digital	PTA0/JTAG_TCLK	Float	Float (default is JTAG with pulldown)
GPIO/Digital	PTA1/JTAG_TDI	Float	Float (default is JTAG with pullup)
GPIO/Digital	PTA2/JTAG_TDO	Float	Float (default is JTAG with pullup)
GPIO/Digital	PTA3/JTAG_TMS	Float	Float (default is JTAG with pullup)
GPIO/Digital	PTA4/NMI_b	10kΩ pullup or disable and float	Pull high or disable in PCR & FOPT and float
GPIO/Digital	PTx	Float	Float (default is disabled)
USB	USB0_DP	Float	Float
USB	USB0_DM	Float	Float
USB	VREG_OUT	Tie to input and ground through 10kΩ	Tie to input and ground through 10kΩ
USB	VREG_IN0	Tie to output and ground through 10kΩ	Tie to output and ground through 10kΩ
USB	VREG_IN1	Tie to output and ground through 10kΩ	Tie to output and ground through 10kΩ
USB	USB1_VSS	Always connect to VSS	Always connect to VSS
USB	USB1_DP	Float	Float
USB	USB1_DM	Float	Float

Table continues on the next page...