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"Embedded - Microcontrollers" refer to small, integrated circuits designed to perform specific tasks within larger systems. These microcontrollers are essentially compact computers on a single chip, containing a processor core, memory, and programmable input/output peripherals. They are called "embedded" because they are embedded within electronic devices to control various functions, rather than serving as standalone computers. Microcontrollers are crucial in modern electronics, providing the intelligence and control needed for a wide range of applications.

Applications of "<u>Embedded -</u> <u>Microcontrollers</u>"

Details

Details	
Product Status	Active
Core Processor	R8C
Core Size	16-Bit
Speed	20MHz
Connectivity	I ² C, LINbus, SIO, SSU, UART/USART
Peripherals	POR, PWM, Voltage Detect, WDT
Number of I/O	55
Program Memory Size	128KB (128K x 8)
Program Memory Type	FLASH
EEPROM Size	-
RAM Size	7.5K x 8
Voltage - Supply (Vcc/Vdd)	2.2V ~ 5.5V
Data Converters	A/D 12x10b; D/A 2x8b
Oscillator Type	Internal
Operating Temperature	-20°C ~ 85°C (TA)
Mounting Type	Surface Mount
Package / Case	64-LQFP
Supplier Device Package	64-LQFP (14x14)
Purchase URL	https://www.e-xfl.com/product-detail/renesas-electronics-america/r5f212acsnfa-v2

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1.1.2 Specifications

Tables 1.1 and 1.2 outlines the Specifications for R8C/2A Group and Tables 1.3 and 1.4 outlines the Specifications for R8C/2B Group.

Item	Function	Specification
CPU	Central processing	R8C/Tiny series core
010	unit	Number of fundamental instructions: 89
	unit	Minimum instruction execution time:
		50 ns (f(XIN) = 20 MHz, VCC = 3.0 to 5.5 V)
		100 ns (f(XIN) = 10 MHz, VCC = 2.7 to 5.5 V)
		200 ns (f(XIN) = 5 MHz, VCC = 2.2 to 5.5 V)
		• Multiplier: 16 bits \times 16 bits \rightarrow 32 bits
		• Multiply-accumulate instruction: 16 bits \times 16 bits \times 16 bits \rightarrow 32 bits
		 Operation mode: Single-chip mode (address space: 1 Mbyte)
Momony	ROM, RAM	Refer to Table 1.5 Product List for R8C/2A Group.
Memory Dowor Supply	-	Power-on reset
Power Supply	Voltage detection	
Voltage	circuit	Voltage detection 2
Detection	Draggerennen ak la 1/O	a lanut anhu O nina
I/O Ports	Programmable I/O	Input-only: 2 pins ONOC I/O parts 55 coloritable pull up resister
	ports	CMOS I/O ports: 55, selectable pull-up resistor
		High current drive ports: 8
Clock	Clock generation	3 circuits: XIN clock oscillation circuit (with on-chip feedback resistor),
	circuits	On-chip oscillator (high-speed, low-speed)
		(high-speed on-chip oscillator has a frequency adjustment function),
		XCIN clock oscillation circuit (32 kHz)
		Oscillation stop detection: XIN clock oscillation stop detection function
		• Frequency divider circuit: Dividing selectable 1, 2, 4, 8, and 16
		Low power consumption modes:
		Standard operating mode (high-speed clock, low-speed clock, high-speed
		on-chip oscillator, low-speed on-chip oscillator), wait mode, stop mode
		Real-time clock (timer RE)
Interrupts		External: 5 sources, Internal: 23 sources, Software: 4 sources
		Priority levels: 7 levels
Watchdog Time		15 bits x 1 (with prescaler), reset start selectable
Timer	Timer RA	8 bits x 1 (with 8-bit prescaler) Timer mode (period timer), pulse output mode (output level inverted every
		period), event counter mode, pulse width measurement mode, pulse period
		measurement mode
	Timer RB	8 bits x 1 (with 8-bit prescaler)
		Timer mode (period timer), programmable waveform generation mode (PWM
		output), programmable one-shot generation mode, programmable wait one-
		shot generation mode
	Timer RC	16 bits x 1 (with 4 capture/compare registers)
	Timer RC	16 bits × 1 (with 4 capture/compare registers) Timer mode (input capture function, output compare function), PWM mode
		16 bits × 1 (with 4 capture/compare registers) Timer mode (input capture function, output compare function), PWM mode (output 3 pins), PWM2 mode (PWM output pin)
	Timer RC Timer RD	 16 bits × 1 (with 4 capture/compare registers) Timer mode (input capture function, output compare function), PWM mode (output 3 pins), PWM2 mode (PWM output pin) 16 bits × 2 (with 4 capture/compare registers)
		 16 bits × 1 (with 4 capture/compare registers) Timer mode (input capture function, output compare function), PWM mode (output 3 pins), PWM2 mode (PWM output pin) 16 bits × 2 (with 4 capture/compare registers) Timer mode (input capture function, output compare function), PWM mode
		 16 bits × 1 (with 4 capture/compare registers) Timer mode (input capture function, output compare function), PWM mode (output 3 pins), PWM2 mode (PWM output pin) 16 bits × 2 (with 4 capture/compare registers) Timer mode (input capture function, output compare function), PWM mode (output 6 pins), reset synchronous PWM mode (output three-phase
		 16 bits × 1 (with 4 capture/compare registers) Timer mode (input capture function, output compare function), PWM mode (output 3 pins), PWM2 mode (PWM output pin) 16 bits × 2 (with 4 capture/compare registers) Timer mode (input capture function, output compare function), PWM mode (output 6 pins), reset synchronous PWM mode (output three-phase waveforms (6 pins), sawtooth wave modulation), complementary PWM mode
		 16 bits × 1 (with 4 capture/compare registers) Timer mode (input capture function, output compare function), PWM mode (output 3 pins), PWM2 mode (PWM output pin) 16 bits × 2 (with 4 capture/compare registers) Timer mode (input capture function, output compare function), PWM mode (output 6 pins), reset synchronous PWM mode (output three-phase waveforms (6 pins), sawtooth wave modulation), complementary PWM mode (output three-phase waveforms (6 pins), triangular wave modulation), PWM3
	Timer RD	 16 bits × 1 (with 4 capture/compare registers) Timer mode (input capture function, output compare function), PWM mode (output 3 pins), PWM2 mode (PWM output pin) 16 bits × 2 (with 4 capture/compare registers) Timer mode (input capture function, output compare function), PWM mode (output 6 pins), reset synchronous PWM mode (output three-phase waveforms (6 pins), sawtooth wave modulation), complementary PWM mode (output three-phase waveforms (6 pins), triangular wave modulation), PWM3 mode (PWM output 2 pins with fixed period)
		 16 bits × 1 (with 4 capture/compare registers) Timer mode (input capture function, output compare function), PWM mode (output 3 pins), PWM2 mode (PWM output pin) 16 bits × 2 (with 4 capture/compare registers) Timer mode (input capture function, output compare function), PWM mode (output 6 pins), reset synchronous PWM mode (output three-phase waveforms (6 pins), sawtooth wave modulation), complementary PWM mode (output three-phase waveforms (6 pins), triangular wave modulation), PWM3 mode (PWM output 2 pins with fixed period) 8 bits × 1
	Timer RD	 16 bits × 1 (with 4 capture/compare registers) Timer mode (input capture function, output compare function), PWM mode (output 3 pins), PWM2 mode (PWM output pin) 16 bits × 2 (with 4 capture/compare registers) Timer mode (input capture function, output compare function), PWM mode (output 6 pins), reset synchronous PWM mode (output three-phase waveforms (6 pins), sawtooth wave modulation), complementary PWM mode (output three-phase waveforms (6 pins), triangular wave modulation), PWM3 mode (PWM output 2 pins with fixed period) 8 bits × 1 Real-time clock mode (count seconds, minutes, hours, days of week), output
	Timer RD	 16 bits × 1 (with 4 capture/compare registers) Timer mode (input capture function, output compare function), PWM mode (output 3 pins), PWM2 mode (PWM output pin) 16 bits × 2 (with 4 capture/compare registers) Timer mode (input capture function, output compare function), PWM mode (output 6 pins), reset synchronous PWM mode (output three-phase waveforms (6 pins), sawtooth wave modulation), complementary PWM mode (output three-phase waveforms (6 pins), triangular wave modulation), PWM3 mode (PWM output 2 pins with fixed period) 8 bits × 1

 Table 1.1
 Specifications for R8C/2A Group (1)

RENESAS

D	ROM Ca	apacity	RAM			
Part No.	Program ROM	Data flash	Capacity	Package Type	Remarks	
R5F212B7SNFP	48 Kbytes	1 Kbyte x 2	2.5 Kbytes	PLQP0064KB-A	N version	
R5F212B7SNFA	48 Kbytes	1 Kbyte x 2	2.5 Kbytes	PLQP0064GA-A		
R5F212B7SNLG	48 Kbytes	1 Kbyte x 2	2.5 Kbytes	PTLG0064JA-A		
R5F212B8SNFP	64 Kbytes	1 Kbyte x 2	3 Kbytes	PLQP0064KB-A		
R5F212B8SNFA	64 Kbytes	1 Kbyte x 2	3 Kbytes	PLQP0064GA-A		
R5F212B8SNLG	64 Kbytes	1 Kbyte x 2	3 Kbytes	PTLG0064JA-A		
R5F212BASNFP	96 Kbytes	1 Kbyte x 2	7 Kbytes	PLQP0064KB-A		
R5F212BASNFA	96 Kbytes	1 Kbyte x 2	7 Kbytes	PLQP0064GA-A		
R5F212BASNLG	96 Kbytes	1 Kbyte × 2	7 Kbytes	PTLG0064JA-A		
R5F212BCSNFP	128 Kbytes	1 Kbyte × 2	7.5 Kbytes	PLQP0064KB-A		
R5F212BCSNFA	128 Kbytes	1 Kbyte x 2	7.5 Kbytes	PLQP0064GA-A		
R5F212BCSNLG	128 Kbytes	1 Kbyte × 2	7.5 Kbytes	PTLG0064JA-A		
R5F212B7SDFP	48 Kbytes	1 Kbyte × 2	2.5 Kbytes	PLQP0064KB-A	D version	
R5F212B7SDFA	48 Kbytes	1 Kbyte × 2	2.5 Kbytes	PLQP0064GA-A		
R5F212B8SDFP	64 Kbytes	1 Kbyte × 2	3 Kbytes	PLQP0064KB-A		
R5F212B8SDFA	64 Kbytes	1 Kbyte × 2	3 Kbytes	PLQP0064GA-A		
R5F212BASDFP	96 Kbytes	1 Kbyte × 2	7 Kbytes	PLQP0064KB-A		
R5F212BASDFA	96 Kbytes	1 Kbyte × 2	7 Kbytes	PLQP0064GA-A		
R5F212BCSDFP	128 Kbytes	1 Kbyte × 2	7.5 Kbytes	PLQP0064KB-A		
R5F212BCSDFA	128 Kbytes	1 Kbyte × 2	7.5 Kbytes	PLQP0064GA-A		
R5F212B7SNXXXFP	48 Kbytes	1 Kbyte × 2	2.5 Kbytes	PLQP0064KB-A	N version	Factory
R5F212B7SNXXXFA	48 Kbytes	1 Kbyte × 2	2.5 Kbytes	PLQP0064GA-A		programming
R5F212B7SNXXXLG	48 Kbytes	1 Kbyte x 2	2.5 Kbytes	PTLG0064JA-A	_	product ⁽¹⁾
R5F212B8SNXXXFP	64 Kbytes	1 Kbyte × 2	3 Kbytes	PLQP0064KB-A		
R5F212B8SNXXXFA	64 Kbytes	1 Kbyte × 2	3 Kbytes	PLQP0064GA-A	_	
R5F212B8SNXXXLG	64 Kbytes	1 Kbyte x 2	3 Kbytes	PTLG0064JA-A	_	
R5F212BASNXXXFP	96 Kbytes	1 Kbyte x 2	7 Kbytes	PLQP0064KB-A	_	
R5F212BASNXXXFA	96 Kbytes	1 Kbyte x 2	7 Kbytes	PLQP0064GA-A		
R5F212BASNXXXLG	96 Kbytes	1 Kbyte x 2	7 Kbytes	PTLG0064JA-A		
R5F212BCSNXXXFP	128 Kbytes	1 Kbyte x 2	7.5 Kbytes	PLQP0064KB-A		
R5F212BCSNXXXFA	128 Kbytes	1 Kbyte x 2	7.5 Kbytes	PLQP0064GA-A		
R5F212BCSNXXXLG	128 Kbytes	1 Kbyte x 2	7.5 Kbytes	PTLG0064JA-A		
R5F212B7SDXXXFP	48 Kbytes	1 Kbyte x 2	2.5 Kbytes	PLQP0064KB-A	D version	
R5F212B7SDXXXFA	48 Kbytes	1 Kbyte x 2	2.5 Kbytes	PLQP0064GA-A		
R5F212B8SDXXXFP	64 Kbytes	1 Kbyte x 2	3 Kbytes	PLQP0064KB-A		
R5F212B8SDXXXFA	64 Kbytes	1 Kbyte x 2	3 Kbytes	PLQP0064GA-A		
R5F212BASDXXXFP	96 Kbytes	1 Kbyte x 2	7 Kbytes	PLQP0064KB-A		
R5F212BASDXXXFA	96 Kbytes	1 Kbyte x 2	7 Kbytes	PLQP0064GA-A		
R5F212BCSDXXXFP	128 Kbytes	1 Kbyte x 2	7.5 Kbytes	PLQP0064KB-A		
R5F212BCSDXXXFA	128 Kbytes	1 Kbyte x 2	7.5 Kbytes	PLQP0064GA-A		

Table 1.6 Product List for R8C/2B Group	Table 1.6	Product List for R8C/2B Group
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Current of Nov. 2007

NOTE:

1. The user ROM is programmed before shipment.

1.5 **Pin Functions**

Tables 1.9 and 1.10 list Pin Functions.

Table 1.9 Pin Functions (1)

Item	Pin Name	I/O Type	Description
Power supply input	VCC, VSS	-	Apply 2.2 V to 5.5 V to the VCC pin. Apply 0 V to the VSS pin
Analog power supply input	AVCC, AVSS	-	Power supply for the A/D converter. Connect a capacitor between AVCC and AVSS.
Reset input	RESET	I	Input "L" on this pin resets the MCU.
MODE	MODE	I	Connect this pin to VCC via a resistor.
XIN clock input	XIN	I	These pins are provided for XIN clock generation circuit I/O Connect a ceramic resonator or a crystal oscillator between
XIN clock output	XOUT	0	the XIN and XOUT pins ⁽¹⁾ . To use an external clock, input it to the XIN pin and leave the XOUT pin open.
XCIN clock input	XCIN	I	These pins are provided for XCIN clock generation circuit I/O Connect a crystal oscillator between the XCIN and XCOUT
XCIN clock output	XCOUT	0	pins ⁽¹⁾ . To use an external clock, input it to the XCIN pin and leave the XCOUT pin open.
INT interrupt input	INT0 to INT3	I	INT interrupt input pins. INT0 is timer RD input pin. INT1 is timer RA input pin.
Key input interrupt	KI0 to KI3	I	Key input interrupt input pins
Timer RA	TRAIO	I/O	Timer RA I/O pin
	TRAO	0	Timer RA output pin
Timer RB	TRBO	0	Timer RB output pin
Timer RC	TRCCLK	I	External clock input pin
-	TRCTRG	I	External trigger input pin
	TRCIOA, TRCIOB, TRCIOC, TRCIOD	I/O	Timer RC I/O pins
Timer RD	TRDIOA0, TRDIOA1, TRDIOB0, TRDIOB1, TRDIOC0, TRDIOC1, TRDIOD0, TRDIOD1	I/O	Timer RD I/O pins
	TRDCLK	I	External clock input pin
Timer RE	TREO	0	Divided clock output pin
Timer RF	TRFI	I	Timer RF input pin
	TRFO00 to TRFO02, TRFO10 to TRFO12	0	Timer RF output pins
Serial interface	CLK0, CLK1, CLK2	I/O	Transfer clock I/O pins
	RXD0, RXD1, RXD2	I	Serial data input pins
	TXD0, TXD1, TXD2	0	Serial data output pins
I ² C bus	SCL	I/O	Clock I/O pin
	SDA	I/O	Data I/O pin
SSU	SSI	I/O	Data I/O pin
	SCS	I/O	Chip-select signal I/O pin
	SSCK	I/O	Clock I/O pin
	SSO	I/O	Data I/O pin
Reference voltage input	VREF	I	Reference voltage input pin to A/D converter and D/A converter

I: Input NOTE:

1. Refer to the oscillator manufacturer for oscillation characteristics.



2.1 Data Registers (R0, R1, R2, and R3)

R0 is a 16-bit register for transfer, arithmetic, and logic operations. The same applies to R1 to R3. R0 can be split into high-order bits (R0H) and low-order bits (R0L) to be used separately as 8-bit data registers. R1H and R1L are analogous to R0H and R0L. R2 can be combined with R0 and used as a 32-bit data register (R2R0). R3R1 is analogous to R2R0.

2.2 Address Registers (A0 and A1)

A0 is a 16-bit register for address register indirect addressing and address register relative addressing. It is also used for transfer, arithmetic, and logic operations. A1 is analogous to A0. A1 can be combined with A0 and as a 32-bit address register (A1A0).

2.3 Frame Base Register (FB)

FB is a 16-bit register for FB relative addressing.

2.4 Interrupt Table Register (INTB)

INTB is a 20-bit register that indicates the start address of an interrupt vector table.

2.5 Program Counter (PC)

PC is 20 bits wide and indicates the address of the next instruction to be executed.

2.6 User Stack Pointer (USP) and Interrupt Stack Pointer (ISP)

The stack pointers (SP), USP, and ISP, are each 16 bits wide. The U flag of FLG is used to switch between USP and ISP.

2.7 Static Base Register (SB)

SB is a 16-bit register for SB relative addressing.

2.8 Flag Register (FLG)

FLG is an 11-bit register indicating the CPU state.

2.8.1 Carry Flag (C)

The C flag retains carry, borrow, or shift-out bits that have been generated by the arithmetic and logic unit.

2.8.2 Debug Flag (D)

The D flag is for debugging only. Set it to 0.

2.8.3 Zero Flag (Z)

The Z flag is set to 1 when an arithmetic operation results in 0; otherwise to 0.

2.8.4 Sign Flag (S)

The S flag is set to 1 when an arithmetic operation results in a negative value; otherwise to 0.

2.8.5 Register Bank Select Flag (B)

Register bank 0 is selected when the B flag is 0. Register bank 1 is selected when this flag is set to 1.

2.8.6 Overflow Flag (O)

The O flag is set to 1 when an operation results in an overflow; otherwise to 0.



2.8.7 Interrupt Enable Flag (I)

The I flag enables maskable interrupts.

Interrupt are disabled when the I flag is set to 0, and are enabled when the I flag is set to 1. The I flag is set to 0 when an interrupt request is acknowledged.

2.8.8 Stack Pointer Select Flag (U)

ISP is selected when the U flag is set to 0; USP is selected when the U flag is set to 1. The U flag is set to 0 when a hardware interrupt request is acknowledged or the INT instruction of software interrupt numbers 0 to 31 is executed.

2.8.9 Processor Interrupt Priority Level (IPL)

IPL is 3 bits wide and assigns processor interrupt priority levels from level 0 to level 7. If a requested interrupt has higher priority than IPL, the interrupt is enabled.

2.8.10 Reserved Bit

If necessary, set to 0. When read, the content is undefined.

Special Function Registers (SFRs) 4.

An SFR (special function register) is a control register for a peripheral function. Tables 4.1 to 4.12 list the special function registers.

Address	Register	Symbol	After reset
0000h			
0001h			
0002h			
0003h			
0004h	Processor Mode Register 0	PM0	00h
0005h	Processor Mode Register 1	PM1	00h
0006h	System Clock Control Register 0	CM0	01101000b
0007h	System Clock Control Register 1	CM1	0010000b
0008h	Module Operation Enable Register	MSTCR	00h
0009h			
000Ah	Protect Register	PRCR	00h
000Bh	· · · · · · · · · · · · · · · · · · ·		
000Ch	Oscillation Stop Detection Register	OCD	00000100b
000Dh	Watchdog Timer Reset Register	WDTR	XXh
000Eh	Watchdog Timer Start Register	WDTS	XXh
000Fh	Watchdog Timer Control Register	WDC	00X11111b
0010h	Address Match Interrupt Register 0	RMAD0	00h
0011h			00h
0012h	4		00h
0012h	Address Match Interrupt Enable Register	AIER	00h
0013h	Address Match Interrupt Register 1	RMAD1	00h
0015h		NW/ B1	00h
0016h	4		00h
0010h			0011
0017h			
0019h			
001Ah			
001An			
001Dh	Count Source Protection Mode Register	CSPR	00h
001011		CON	1000000b ⁽⁶⁾
001Dh			
001Eh			
001Fh			
0020h			
0021h			
0022h			
0023h	High-Speed On-Chip Oscillator Control Register 0	FRA0	00h
0024h	High-Speed On-Chip Oscillator Control Register 1	FRA1	When shipping
0025h	High-Speed On-Chip Oscillator Control Register 2	FRA2	00h
0026h			
0027h			
0028h	Clock Prescaler Reset Flag	CPSRF	00h
0029h	-		
002Ah			
002Bh	High-Speed On-Chip Oscillator Control Register 6	FRA6	When Shipping
002Ch	High-Speed On-Chip Oscillator Control Register 7	FRA7	When Shipping
0030h	Voltarra Datastian Danistan (2)		00001000b

Table 4.1 SFR Information (1)⁽¹⁾

0030h			
0031h	Voltage Detection Register 1 ⁽²⁾	VCA1	00001000b
0032h	Voltage Detection Register 2 ⁽²⁾	VCA2	00h ⁽³⁾
			0010000b ⁽⁴⁾
0033h			
0034h			
0035h			
0036h	Voltage Monitor 1 Circuit Control Register ⁽⁵⁾	VW1C	00001000b
0037h	Voltage Monitor 2 Circuit Control Register ⁽⁵⁾	VW2C	00h
0038h	Voltage Monitor 0 Circuit Control Register ⁽²⁾	VW0C	0000X000b ⁽³⁾
			0100X001b ⁽⁴⁾
0039h			
003Ah			

003Fh

X: Undefined

NOTES:

The blank regions are reserved. Do not access locations in these regions. 1.

2. Software reset, watchdog timer reset, voltage monitor 1 reset, or voltage monitor 2 reset do not affect this register. The LVD0ON bit in the OFS register is set to 1 and hardware reset.

3.

4. Power-on reset, voltage monitor 0 reset, or the LVD0ON bit in the OFS register is set to 0 and hardware reset.

Software reset, which dog time reset, voltage monitor 1 reset, or voltage monitor 2 reset do not affect b2 and b3. The CSPROINI bit in the OFS register is set to 0.

5. 6.



Address	Register	Symbol	After reset
0080h		e ye	
0081h			
0082h			
0083h			
0084h			
0085h			
0086h			
0087h			
0088h			
0089h			
008Ah			
008Bh			
008Ch			
008Dh			
008Eh			
008Fh			
0090h			
0091h			
0092h		1	1
0093h			1
0094h		1	1
0095h			1
0096h			
0097h		1	1
0098h		1	1
0099h			1
009Ah			1
009Bh			1
009Ch			1
009Dh			
009Eh			
009Fh			
00A0h	UART0 Transmit/Receive Mode Register	U0MR	00h
00A1h	UART0 Bit Rate Register	U0BRG	XXh
00A2h	UART0 Transmit Buffer Register	U0TB	XXh
00A3h			XXh
00A4h	UART0 Transmit/Receive Control Register 0	U0C0	00001000b
00A5h	UART0 Transmit/Receive Control Register 1	U0C1	00000010b
00A6h	UART0 Receive Buffer Register	UORB	XXh
00A7h			XXh
00A8h	UART1 Transmit/Receive Mode Register	U1MR	00h
00A9h	UART1 Bit Rate Register	U1BRG	XXh
00AAh	UART1 Transmit Buffer Register	U1TB	XXh
00ABh			XXh
00ACh	UART1 Transmit/Receive Control Register 0	U1C0	00001000b
00ADh	UART1 Transmit/Receive Control Register 1	U1C1	00000010b
00AEh	UART1 Receive Buffer Register	U1RB	XXh
00AFh			XXh
00B0h			
00B1h			
00B2h			
00B3h			
00B4h			
00B5h			
00B6h			
00B7h			
00B8h	SS Control Register H / IIC bus Control Register 1 ⁽²⁾	SSCRH / ICCR1	00h
00B9h	SS Control Register L / IIC bus Control Register 2 ⁽²⁾	SSCRL / ICCR2	01111101b
00BAh	SS Mode Register / IIC bus Mode Register ⁽²⁾	SSMR / ICMR	00011000b
00BBh	SS Enable Register / IIC bus Interrupt Enable Register ⁽²⁾	SSER / ICIER	00h
00BCh	SS Status Register / IIC bus Status Register ⁽²⁾	SSSR / ICSR	00h / 0000X000b
00BDh	SS Mode Register 2 / Slave Address Register ⁽²⁾	SSMR2 / SAR	00h
		SSIMR2 / SAR SSTDR / ICDRT	FFh
00BEh	SS Transmit Data Register / IIC bus Transmit Data Register ⁽²⁾		
00BFh	SS Receive Data Register / IIC bus Receive Data Register ⁽²⁾	SSRDR / ICDRR	FFh

SFR Information (3)⁽¹⁾ Table 4.3

X: Undefined
NOTES:

The blank regions are reserved. Do not access locations in these regions.
Selected by the IICSEL bit in the PMR register.



Address	Register	Symbol	After reset
00C0h		Cymbol	
00C1h			
00C2h			
00C3h			
00C4h			
00C5h			
00C6h			
00C7h			
00C7h			
00C8h			
00C9h			
00CAn 00CBh			
00CBn 00CCh			
00CCh 00CDh			
00CDh 00CEh			
00CEn 00CFh			
00CFN 00D0h			
00D1h			
00D2h			
00D3h			
00D4h			
00D5h			
00D6h			
00D7h	D/A Decision 0	DAO	006
00D8h	D/A Register 0	DA0	00h
00D9h		DA4	001
00DAh	D/A Register 1	DA1	00h
00DBh		D.4.0.01	
00DCh	D/A Control Register	DACON	00h
00DDh			
00DEh			
00DFh		20	
00E0h	Port PO Register	P0	XXh
00E1h	Port P1 Register	P1	XXh
00E2h	Port P0 Direction Register	PD0	00h
00E3h	Port P1 Direction Register	PD1	00h
00E4h	Port P2 Register	P2	XXh
00E5h	Port P3 Register	P3	XXh
00E6h	Port P2 Direction Register	PD2	00h
00E7h	Port P3 Direction Register	PD3	00h
00E8h	Port P4 Register	P4	XXh
00E9h	Port P5 Register	P5	XXh
00EAh	Port P4 Direction Register	PD4	00h
00EBh	Port P5 Direction Register	PD5	00h
00ECh	Port P6 Register	P6	XXh
00EDh			
00EEh	Port P6 Direction Register	PD6	00h
00EFh			
00F0h			
00F1h			
00F2h			
00F3h			
00F4h	Port P2 Drive Capacity Control Register	P2DRR	00h
00F5h	UART1 Function Select Register	U1SR	000000XXb
00F6h	-		
00F7h			
00F8h	Port Mode Register	PMR	00h
00F9h	External Input Enable Register	INTEN	00h
00FAh	INT Input Filter Select Register	INTF	00h
00FBh	Key Input Enable Register	KIEN	00h
00FCh	Pull-Up Control Register 0	PUR0	00h
00FDh	Pull-Up Control Register 1	PUR1	XX000000b
00FEh			
00FFh			
	1	1	1

SFR Information (4)⁽¹⁾ Table 4.4

X: Undefined NOTE: 1. The blank regions are reserved. Do not access locations in these regions.

Address	Register	Symbol	After reset
01C0h		e jinise.	7
01C1h			
01C2h			
01C3h			
01C4h			
01C5h			
01C6h			
01C6h			
01C7h			
01C8h			
01C9h			
01CAn			
01CBh			
01CCh			
01CDh			
01CEh			
01CFh			
01D0h			
01D1h			
01D2h			
01D3h			
01D4h			
01D5h			
01D6h			
01D7h			
01D8h			
01D9h			
01DAh			
01DBh			
01DCh			
01DDh			
01DEh			
01DFh			
01E0h			
01E1h			
01E2h			
01E3h			
01E4h			
01E5h			
01E6h			
01E7h			
01E8h			
01E9h			
01EAh			
01EBh			
01ECh			
01EDh			
01EEh			
01EFh			
01F0h			
01F1h			
01F2h			
01F3h			
01F4h			
01F411 01F5h			
01F5h			
01F6h			
01F7h 01F8h			
01F9h			
01FAh 01FBh			
01FCh			
01FDh 01FEh			
01FFh			

SFR Information (8)⁽¹⁾ Table 4.8

NOTE: 1. The blank regions are reserved. Do not access locations in these regions.

Address	Register	Symbol	After reset
0200h	Register	Symbol	Alter Teset
0200h			
02011 0202h			
020211 0203h			
0203h 0204h			
0204h 0205h			
02050			
0206h 0207h			
02070			
0208h			
0209h 020Ah			
020An 020Bh			
020Bh			
020Ch 020Dh			
020Dh 020Eh			
020EII			
020Fh			
0210h			
0211h			
0212h			
0213h			
0214h			
0215h 0216h			
0216h 0217h			
02170			
0218h 0219h			
02190			
021Ah			
021Bh 021Ch			
021Ch			
021Dh			
021Eh			
021Fh			
0220h			
0221h			
0222h			
0223h			
0224h			
0225h			
0226h			
0227h			
0228h			
0229h			
022Ah			
022Bh			
022Ch			
022Dh			
022Eh			
022Fh			
0230h			
0231h			
0232h			
0233h			
0234h			
0235h			
0236h			
0237h			
0238h			
0239h			
023Ah			
023Bh			
023Ch			
0000			I
023Dh			
023Dh 023Eh 023Fh			

SFR Information (9)⁽¹⁾ Table 4.9

NOTE: 1. The blank regions are reserved. Do not access locations in these regions.

Address	Register	Symbol	After reset
0240h		eyniser	7
0241h			
0242h			
0243h			
0244h			
0245h			
0246h			
0247h			
0248h			
0249h			
024Ah			
024Bh			
024Ch			
024Dh			
024Eh			
024Fh			
0250h			
0251h			
0252h 0253h			
0253h 0254h			
0254h 0255h			
0255h			
0257h			
0258h			
0259h			
025Ah			
025Bh			
025Ch			
025Dh			
025Eh			
025Fh			
0260h			
0261h			
0262h			
0263h			
0264h			
0265h			
0266h			
0267h 0268h			
0268h			
0269h			
026An			
026Ch			
026Dh			
026Eh			
026Fh			
0270h			
0271h			
0272h			
0273h			
0274h			
0275h			
0276h			
0277h			
0278h			
0279h			
027Ah			
027Bh			
027Ch			
027Dh			
027Eh			
027Fh			

SFR Information (10)⁽¹⁾ Table 4.10

NOTE: 1. The blank regions are reserved. Do not access locations in these regions.

Symbol	Parameter	Conditions		Unit		
Symbol	Falameter	Conditions	Min. Ty		Typ. Max.	
-	Program/erase endurance ⁽²⁾		10,000 ⁽³⁾	-	-	times
-	Byte program time (program/erase endurance ≤ 1,000 times)		-	50	400	μs
-	Byte program time (program/erase endurance > 1,000 times)		-	65	-	μS
-	Block erase time (program/erase endurance ≤ 1,000 times)		-	0.2	9	S
-	Block erase time (program/erase endurance > 1,000 times)		-	0.3	-	S
td(SR-SUS)	Time delay from suspend request until suspend		-	_	97+CPU clock × 6 cycles	μS
-	Interval from erase start/restart until following suspend request		650	-	-	μs
-	Interval from program start/restart until following suspend request		0	_	-	ns
-	Time from suspend until program/erase restart		-	-	3+CPU clock × 4 cycles	μs
-	Program, erase voltage		2.7	-	5.5	V
-	Read voltage		2.2	-	5.5	V
-	Program, erase temperature		-20 ⁽⁸⁾	-	85	°C
_	Data hold time ⁽⁹⁾	Ambient temperature = 55 °C	20	-	_	year

Table 5.6 Flash Memory (Data flash Block A, Block B) Electrical Characteristics⁽⁴⁾

NOTES:

1. Vcc = 2.7 to 5.5 V at Topr = -20 to 85°C (N version) / -40 to 85°C (D version), unless otherwise specified.

2. Definition of programming/erasure endurance

The programming and erasure endurance is defined on a per-block basis. If the programming and erasure endurance is n (n = 100 or 10,000), each block can be erased n times. For example, if 1,024 1-byte writes are performed to block A, a 1 Kbyte block, and then the block is erased, the programming/erasure endurance still stands at one.

However, the same address must not be programmed more than once per erase operation (overwriting prohibited).

3. Endurance to guarantee all electrical characteristics after program and erase. (1 to Min. value can be guaranteed).

- 4. Standard of block A and block B when program and erase endurance exceeds 1,000 times. Byte program time to 1,000 times is the same as that in program ROM.
- 5. In a system that executes multiple programming operations, the actual erasure count can be reduced by writing to sequential addresses in turn so that as much of the block as possible is used up before performing an erase operation. For example, when programming groups of 16 bytes, the effective number of rewrites can be minimized by programming up to 128 groups before erasing them all in one operation. It is also advisable to retain data on the erase count of each block and limit the number of erase operations to a certain number.

6. If an error occurs during block erase, attempt to execute the clear status register command, then execute the block erase command at least three times until the erase error does not occur.

7. Customers desiring program/erase failure rate information should contact their Renesas technical support representative.

8. -40°C for D version.

9. The data hold time includes time that the power supply is off or the clock is not supplied.

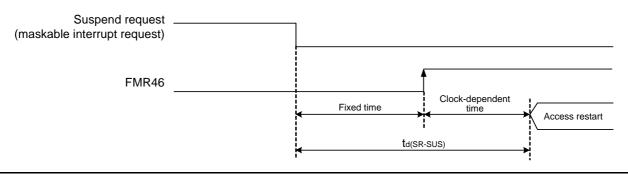


Figure 5.2 Time delay until Suspend

Table 5.7 Voltage Detection 0 Circuit Electrical Characteristics

Symbol	Parameter	Condition		Unit		
Symbol	Falanelei	Condition	Min.	Тур.	Max.	Unit
Vdet0	Voltage detection level		2.2	2.3	2.4	V
-	Voltage detection circuit self power consumption	VCA25 = 1, Vcc = 5.0 V	-	0.9	-	μΑ
td(E-A)	Waiting time until voltage detection circuit operation starts ⁽²⁾		-	-	300	μS
Vccmin	MCU operating voltage minimum value		2.2	-	-	V

NOTES:

1. The measurement condition is Vcc = 2.2 V to 5.5 V and Topr = -20 to 85°C (N version) / -40 to 85°C (D version).

2. Necessary time until the voltage detection circuit operates when setting to 1 again after setting the VCA25 bit in the VCA2 register to 0.

Table 5.8 Voltage Detection 1 Circuit Electrical Characteristics

Symbol	Parameter	Condition		Unit		
Symbol	Farameter	Condition		Тур.	Max.	Unit
Vdet1	Voltage detection level		2.70	2.85	3.00	V
-	Voltage monitor 1 interrupt request generation time ⁽²⁾		-	40	-	μS
-	Voltage detection circuit self power consumption	VCA26 = 1, Vcc = 5.0 V	_	0.6	-	μΑ
td(E-A)	Waiting time until voltage detection circuit operation starts ⁽³⁾		-	-	100	μS

NOTES:

1. The measurement condition is Vcc = 2.2 V to 5.5 V and Topr = -20 to 85°C (N version) / -40 to 85°C (D version).

2. Time until the voltage monitor 1 interrupt request is generated after the voltage passes Vdet1.

3. Necessary time until the voltage detection circuit operates when setting to 1 again after setting the VCA26 bit in the VCA2 register to 0.

Table 5.9 Voltage Detection 2 Circuit Electrical Characteristics

Symbol	Parameter	Condition		Unit		
Symbol	Farameter	Condition	Min.	Тур.	Max.	Unit
Vdet2	Voltage detection level		3.3	3.6	3.9	V
-	Voltage monitor 2 interrupt request generation time ⁽²⁾		-	40	-	μS
-	Voltage detection circuit self power consumption	VCA27 = 1, Vcc = 5.0 V	-	0.6	-	μA
td(E-A)	Waiting time until voltage detection circuit operation starts ⁽³⁾		-	-	100	μS

NOTES:

1. The measurement condition is Vcc = 2.2 V to 5.5 V and Topr = -20 to 85°C (N version) / -40 to 85°C (D version).

2. Time until the voltage monitor 2 interrupt request is generated after the voltage passes Vdet2.

3. Necessary time until the voltage detection circuit operates after setting to 1 again after setting the VCA27 bit in the VCA2 register to 0.

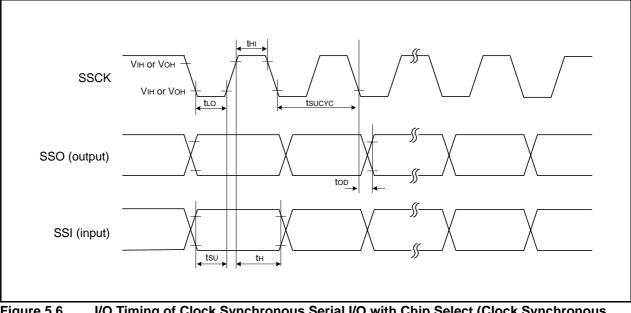


Figure 5.6 I/O Timing of Clock Synchronous Serial I/O with Chip Select (Clock Synchronous Communication Mode)

Table 5.17	Electrical Characteristics (2) [Vcc = 5 V]
	(Topr = -20 to 85° C (N version) / -40 to 85° C (D version), unless otherwise specified.)

Symbol	Parameter		Condition		Standard		Unit
lcc	Power supply current	High-speed clock mode	XIN = 20 MHz (square wave) High-speed on-chip oscillator off	Min.	Тур. 12	Max. 20	mA
	(Vcc = 3.3 to 5.5 V) Single-chip mode,	CIOCK MODE	Low-speed on-chip oscillator on = 125 kHz No division XIN = 16 MHz (square wave)		10	16	mA
	output pins are open, other pins		High-speed on-chip oscillator off Low-speed on-chip oscillator on = 125 kHz No division		10	10	
	are Vss		XIN = 10 MHz (square wave) High-speed on-chip oscillator off Low-speed on-chip oscillator on = 125 kHz No division	-	7	_	mA
			XIN = 20 MHz (square wave) High-speed on-chip oscillator off Low-speed on-chip oscillator on = 125 kHz Divide-by-8	-	5.5	-	mA
			XIN = 16 MHz (square wave) High-speed on-chip oscillator off Low-speed on-chip oscillator on = 125 kHz Divide-by-8	-	4.5	-	mA
			XIN = 10 MHz (square wave) High-speed on-chip oscillator off Low-speed on-chip oscillator on = 125 kHz Divide-by-8	-	3	-	mA
		High-speed on-chip oscillator mode	XIN clock off High-speed on-chip oscillator on fOCO = 10 MHz Low-speed on-chip oscillator on = 125 kHz No division	-	6	12	mA
			XIN clock off High-speed on-chip oscillator on fOCO = 10 MHz Low-speed on-chip oscillator on = 125 kHz Divide-by-8	-	2.5	_	mA
		Low-speed on-chip oscillator mode	XIN clock off High-speed on-chip oscillator off Low-speed on-chip oscillator on = 125 kHz Divide-by-8, FMR47 = 1	-	150	400	μA
		Low-speed clock mode	XIN clock off High-speed on-chip oscillator off Low-speed on-chip oscillator off XCIN clock oscillator on = 32 kHz FMR47 = 1	-	150	400	μA
			XIN clock off High-speed on-chip oscillator off Low-speed on-chip oscillator off XCIN clock oscillator on = 32 kHz Program operation on RAM Flash memory off, FMSTP = 1	-	35	_	μA
		Wait mode	XIN clock off High-speed on-chip oscillator off Low-speed on-chip oscillator on = 125 kHz While a WAIT instruction is executed Peripheral clock operation VCA27 = VCA26 = VCA25 = 0 VCA20 = 1	-	30	90	μA
			XIN clock off High-speed on-chip oscillator off Low-speed on-chip oscillator on = 125 kHz While a WAIT instruction is executed Peripheral clock off VCA27 = VCA26 = VCA25 = 0 VCA20 = 1	_	18	55	μΑ
			XIN clock off High-speed on-chip oscillator off Low-speed on-chip oscillator off XCIN clock oscillator on = 32 kHz (high drive) While a WAIT instruction is executed VCA27 = VCA26 = VCA25 = 0 VCA20 = 1	_	3.5	-	μA
			XIN clock off High-speed on-chip oscillator off Low-speed on-chip oscillator off XCIN clock oscillator on = 32 kHz (low drive) While a WAIT instruction is executed VCA27 = VCA26 = VCA25 = 0 VCA20 = 1	-	2.3	-	μA
		Stop mode	XIN clock off, Topr = 25°C High-speed on-chip oscillator off Low-speed on-chip oscillator off CM10 = 1 Peripheral clock off VCA27 = VCA26 = VCA25 = 0	-	0.7	3.0	μA
			XIN clock off, Topr = 85°C High-speed on-chip oscillator off Low-speed on-chip oscillator off CM10 = 1 Peripheral clock off	-	1.7	-	μA



Table 5.21Serial Interface

Sympol	Parameter		Standard		
Symbol	Parameter	Min.	Max.	Unit	
tc(CK)	CLKi input cycle time	200	-	ns	
tW(CKH)	CLKi input "H" width	100	-	ns	
tW(CKL)	CLKi input "L" width	100	-	ns	
td(C-Q)	TXDi output delay time	-	50	ns	
th(C-Q)	TXDi hold time	0	-	ns	
tsu(D-C)	RXDi input setup time	50	=	ns	
th(C-D)	RXDi input hold time	90	-	ns	

i = 0 to 2

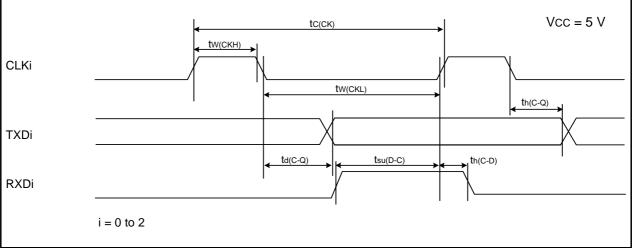


Figure 5.11 Serial Interface Timing Diagram when Vcc = 5 V

Table 5.22 External Interrupt INTi (i = 0, 2, 3) Input

Symbol	Parameter		Standard		
Symbol			Max.	Unit	
tw(INH)	INTO input "H" width	250(1)	-	ns	
tw(INL)	INTO input "L" width	I	ns		

NOTES:

1. When selecting the digital filter by the INTi input filter select bit, use an INTi input HIGH width of either (1/digital filter clock frequency × 3) or the minimum value of standard, whichever is greater.

2. When selecting the digital filter by the INTi input filter select bit, use an INTi input LOW width of either (1/digital filter clock frequency × 3) or the minimum value of standard, whichever is greater.

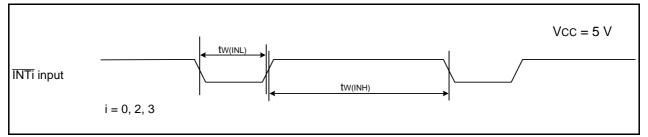


Figure 5.12 External Interrupt INTi Input Timing Diagram when Vcc = 5 V

Symbol	Parameter		Condition		Si	Unit		
Symbol	Pala	imeter	Condition		Min.	Тур.	Max.	Unit
Vон	Output "H" voltage	Except P2_0 to P2_7, XOUT	Iон = -1 mA		Vcc - 0.5	-	Vcc	V
		P2_0 to P2_7	Drive capacity HIGH	Іон = -2 mA	Vcc - 0.5	-	Vcc	V
			Drive capacity LOW	Іон = -1 mA	Vcc - 0.5	-	Vcc	V
		XOUT	Drive capacity HIGH	Іон = -0.1 mA	Vcc - 0.5	-	Vcc	V
			Drive capacity LOW	Іон = -50 μА	Vcc - 0.5	_	Vcc	V
Vol	Output "L" voltage	Except P2_0 to P2_7, XOUT	Iol = 1 mA	·	-	_	0.5	V
		P2_0 to P2_7	Drive capacity HIGH	IOL = 2 mA	-	-	0.5	V
			Drive capacity LOW	IoL = 1 mA	-	-	0.5	V
		XOUT	Drive capacity HIGH	IoL = 0.1 mA	-	-	0.5	V
			Drive capacity LOW	IoL = 50 μA	-	_	0.5	V
VT+-VT-	Hysteresis	INT0, INT1, INT2, INT3, KI0, KI1, KI2, KI3, TRAIO, TRFI, RXD0, RXD1, CLK0, CLK1, CLK2, SSI, SCL, SDA, SSO			0.05	0.3	_	V
		RESET			0.05	0.15	-	V
Ін	Input "H" current		VI = 2.2 V		-	-	4.0	μA
lı∟	Input "L" current		VI = 0 V		_	_	-4.0	μA
Rpullup	Pull-up resistance		VI = 0 V		100	200	600	kΩ
RfXIN	Feedback resistance	XIN				5	-	MΩ
Rfxcin	Feedback resistance	XCIN			-	35	-	MΩ
Vram	RAM hold voltage		During stop mod	e	1.8	-	-	V

 Table 5.30
 Electrical Characteristics (5) [Vcc = 2.2 V]

NOTE:

1. Vcc = 2.2 V at Topr = -20 to 85°C (N version) / -40 to 85°C (D version), f(XIN) = 5 MHz, unless otherwise specified.

Table 5.31Electrical Characteristics (6) [Vcc = 2.2 V]
(Topr = -20 to 85°C (N version) / -40 to 85°C (D version), unless otherwise specified.)

Symbol	Parameter	Condition		Standard			Unit
Symbol				Min.	Тур.	Max.	Unit
Icc	Power supply current (Vcc = 2.2 to 2.7 V) Single-chip mode, output pins are open,	High-speed clock mode	XIN = 5 MHz (square wave) High-speed on-chip oscillator off Low-speed on-chip oscillator on = 125 kHz No division	-	2.5	-	mA
	other pins are Vss		XIN = 5 MHz (square wave) High-speed on-chip oscillator off Low-speed on-chip oscillator on = 125 kHz Divide-by-8	_	1	_	mA
		High-speed on-chip oscillator	XIN clock off High-speed on-chip oscillator on fOCO = 5 MHz Low-speed on-chip oscillator on = 125 kHz No division	-	4	-	mA
		mode	XIN clock off High-speed on-chip oscillator on fOCO = 5 MHz Low-speed on-chip oscillator on = 125 kHz Divide-by-8	_	1.7	-	mA
		Low-speed on- chip oscillator mode	XIN clock off High-speed on-chip oscillator off Low-speed on-chip oscillator on = 125 kHz Divide-by-8, FMR47 = 1	_	110	300	μA
		Low-speed clock mode	XIN clock off High-speed on-chip oscillator off Low-speed on-chip oscillator off XCIN clock oscillator on = 32 kHz FMR47 = 1	-	125	350	μA
			XIN clock off High-speed on-chip oscillator off Low-speed on-chip oscillator off XCIN clock oscillator on = 32 kHz Program operation on RAM Flash memory off, FMSTP = 1	_	27	-	μA
		Wait mode	XIN clock off High-speed on-chip oscillator off Low-speed on-chip oscillator on = 125 kHz While a WAIT instruction is executed Peripheral clock operation VCA27 = VCA26 = VCA25 = 0 VCA20 = 1	_	20	60	μA
			XIN clock off High-speed on-chip oscillator off Low-speed on-chip oscillator on = 125 kHz While a WAIT instruction is executed Peripheral clock off VCA27 = VCA26 = VCA25 = 0 VCA20 = 1	_	12	40	μA
			XIN clock off High-speed on-chip oscillator off Low-speed on-chip oscillator off XCIN clock oscillator on = 32 kHz (high drive) While a WAIT instruction is executed VCA27 = VCA26 = VCA25 = 0 VCA20 = 1	_	2.8	_	μA
			XIN clock off High-speed on-chip oscillator off Low-speed on-chip oscillator off XCIN clock oscillator on = 32 kHz (low drive) While a WAIT instruction is executed VCA27 = VCA26 = VCA25 = 0 VCA20 = 1	_	1.9	-	μA
		Stop mode	XIN clock off, $T_{opr} = 25^{\circ}C$ High-speed on-chip oscillator off Low-speed on-chip oscillator off CM10 = 1 Peripheral clock off VCA27 = VCA26 = VCA25 = 0	-	0.6	3.0	μA
			XIN clock off, Topr = 85°C High-speed on-chip oscillator off Low-speed on-chip oscillator off CM10 = 1 Peripheral clock off VCA27 = VCA26 = VCA25 = 0	_	1.60	-	μA

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REVISION HISTORY

R8C/2A Group, R8C/2B Group Datasheet

Pov	Rev. Date -		Description
Nev.			Summary
2.00	Oct 17, 2007	33	Table 5.1; Pd: Rated Value "TBD" → "700" revised, "NOTE1" added
		59	Package Dimensions "PTLG0064JA-A (64F0G) package" added
2.10	Nov 26, 2007	2, 4	Table 1.1, Table 1.3 Clock: "Real-time clock (timer RE)" added
		6, 7	Table 1.5 and Figure 1.1 revised
		8, 9	Table 1.6 and Figure 1.2 revised
		20, 21	Figure 3.1 and Figure 3.2 revised
		22	Table 4.1 002Ch: High-Speed On-Chip Oscillator Control Register 7 added
		35	Table 5.2 NOTE2 revised
		41	Table 5.11 revised

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