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## What is "[Embedded - Microcontrollers](#)"?

"[Embedded - Microcontrollers](#)" refer to small, integrated circuits designed to perform specific tasks within larger systems. These microcontrollers are essentially compact computers on a single chip, containing a processor core, memory, and programmable input/output peripherals. They are called "embedded" because they are embedded within electronic devices to control various functions, rather than serving as standalone computers. Microcontrollers are crucial in modern electronics, providing the intelligence and control needed for a wide range of applications.

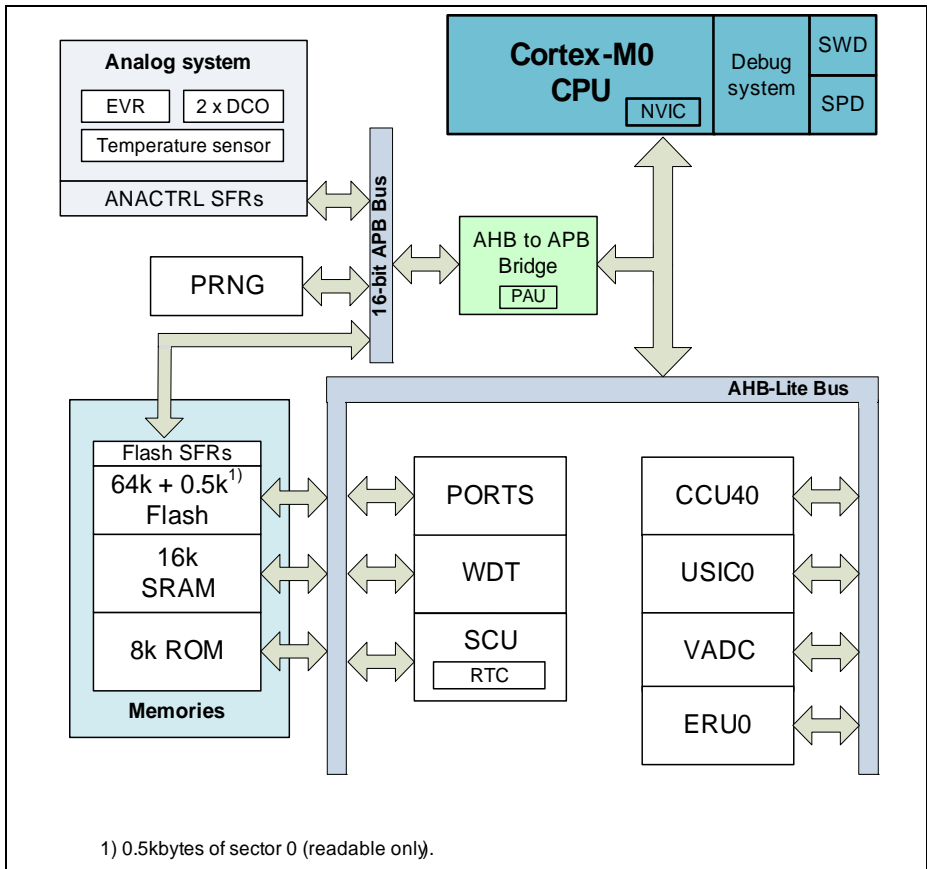
## Applications of "[Embedded - Microcontrollers](#)"

### Details

Product Status	Active
Core Processor	ARM® Cortex®-M0
Core Size	32-Bit Single-Core
Speed	32MHz
Connectivity	I <sup>2</sup> C, LINbus, SPI, UART/USART
Peripherals	Brown-out Detect/Reset, I <sup>2</sup> S, POR, PWM, WDT
Number of I/O	18
Program Memory Size	32KB (32K x 8)
Program Memory Type	FLASH
EEPROM Size	-
RAM Size	16K x 8
Voltage - Supply (Vcc/Vdd)	1.8V ~ 5.5V
Data Converters	A/D 8x12b
Oscillator Type	Internal
Operating Temperature	-40°C ~ 85°C (TA)
Mounting Type	Surface Mount
Package / Case	24-VQFN Exposed Pad
Supplier Device Package	PG-VQFN-24-19
Purchase URL	<a href="https://www.e-xfl.com/product-detail/infineon-technologies/xmc1100q024f0032abxuma1">https://www.e-xfl.com/product-detail/infineon-technologies/xmc1100q024f0032abxuma1</a>

## 1 Summary of Features

The XMC1100 devices are members of the XMC1000 family of microcontrollers based on the ARM Cortex-M0 processor core. The XMC1100 series devices are designed for general purpose applications.



**Figure 1 System Block Diagram**

### CPU Subsystem

- CPU Core
  - High Performance 32-bit ARM Cortex-M0 CPU
  - Most of 16-bit Thumb instruction set
  - Subset of 32-bit Thumb2 instruction set

**Summary of Features**

- <Z> the package variant
  - T: TSSOP
  - Q: VQFN
- <PPP> package pin count
- <T> the temperature range:
  - F: -40°C to 85°C
  - X: -40°C to 105°C
- <FFFF> the Flash memory size.

For ordering codes for the XMC1100 please contact your sales representative or local distributor.

This document describes several derivatives of the XMC1100 series, some descriptions may not apply to a specific product. Please see [Table 1](#).

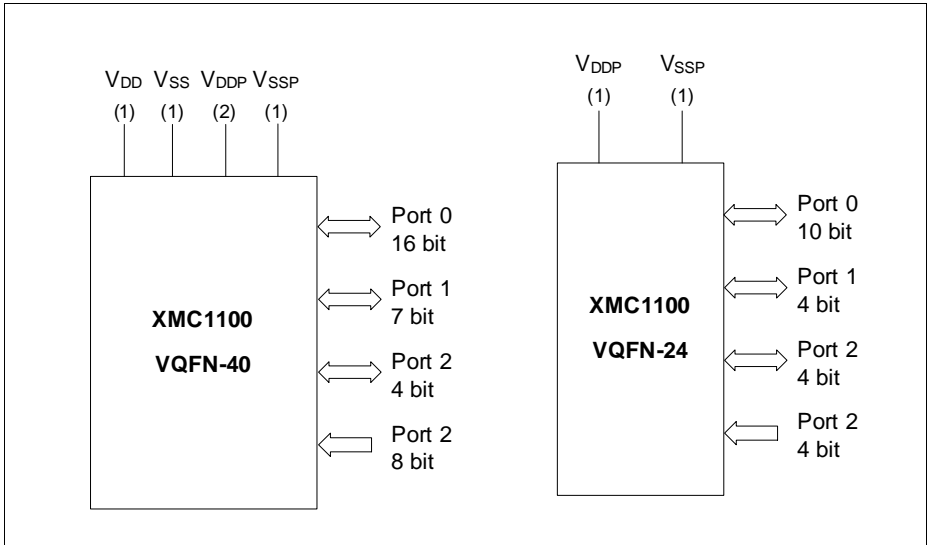
For simplicity the term **XMC1100** is used for all derivatives throughout this document.

## 1.2 Device Types

These device types are available and can be ordered through Infineon's direct and/or distribution channels.

**Table 1 Synopsis of XMC1100 Device Types**

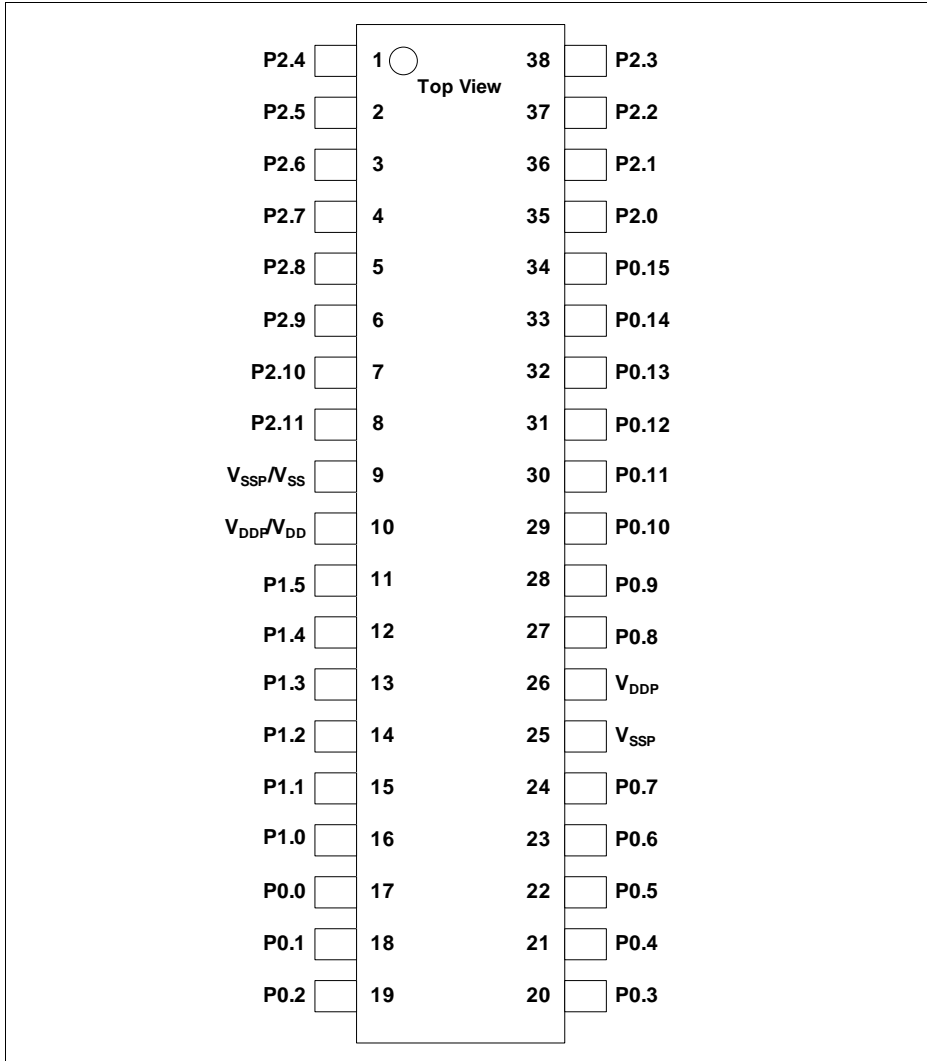
Derivative	Package	Flash Kbytes	SRAM Kbytes
XMC1100-T016F0008	PG-TSSOP-16-8	8	16
XMC1100-T016F0016	PG-TSSOP-16-8	16	16
XMC1100-T016F0032	PG-TSSOP-16-8	32	16
XMC1100-T016F0064	PG-TSSOP-16-8	64	16
XMC1100-T016X0064	PG-TSSOP-16-8	64	16
XMC1100-T038F0016	PG-TSSOP-38-9	16	16
XMC1100-T038F0032	PG-TSSOP-38-9	32	16
XMC1100-T038F0064	PG-TSSOP-38-9	64	16
XMC1100-T038X0064	PG-TSSOP-38-9	64	16
XMC1100-Q024F0008	PG-VQFN-24-19	8	16
XMC1100-Q024F0016	PG-VQFN-24-19	16	16
XMC1100-Q024F0032	PG-VQFN-24-19	32	16
XMC1100-Q024F0064	PG-VQFN-24-19	64	16
XMC1100-Q040F0016	PG-VQFN-40-13	16	16



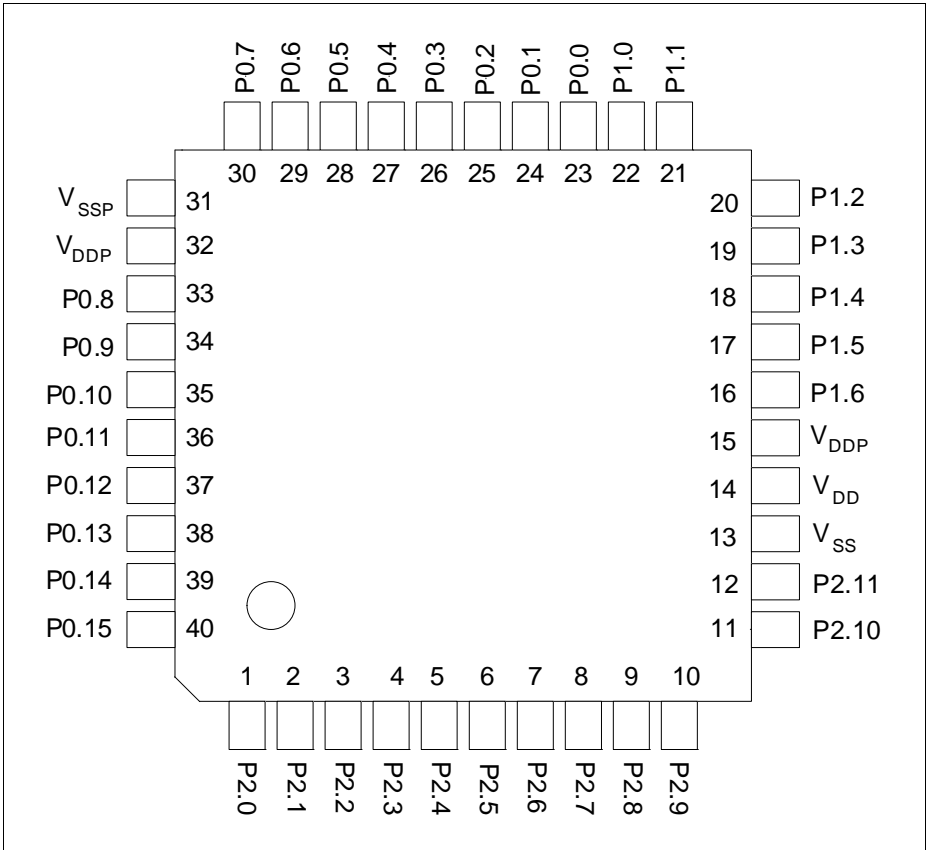
**Figure 3 XMC1100 Logic Symbol for VQFN-24 and VQFN-40**

## 2.2 Pin Configuration and Definition

The following figures summarize all pins, showing their locations on the different packages.



**Figure 4** XMC1100 PG-TSSOP-38 Pin Configuration (top view)



**Figure 7** XMC1100 PG-VQFN-40 Pin Configuration (top view)

## 2.2.1 Package Pin Summary

The following general building block is used to describe each pin:

**Table 5 Package Pin Mapping Description**

Function	Package A	Package B	...	Pad Type
Px.y	N	N		Pad Class

The table is sorted by the “Function” column, starting with the regular Port pins (Px.y), followed by the supply pins.

The following columns, titled with the supported package variants, lists the package pin number to which the respective function is mapped in that package.

The “Pad Type” indicates the employed pad type:

- STD\_INOUT (standard bi-directional pads)
- STD\_INOUT/AN (standard bi-directional pads with analog input)
- High Current (high current bi-directional pads)
- STD\_IN/AN (standard input pads with analog input)
- Power (power supply)

Details about the pad properties are defined in the Electrical Parameters.

**Table 6 Package Pin Mapping**

Function	VQFN 40	TSSOP 38	VQFN 24	TSSOP 16	Pad Type	Notes
P0.0	23	17	15	7	STD_INOUT	
P0.1	24	18	-	-	STD_INOUT	
P0.2	25	19	-	-	STD_INOUT	
P0.3	26	20	-	-	STD_INOUT	
P0.4	27	21	-	-	STD_INOUT	
P0.5	28	22	16	8	STD_INOUT	
P0.6	29	23	17	9	STD_INOUT	
P0.7	30	24	18	10	STD_INOUT	
P0.8	33	27	19	11	STD_INOUT	
P0.9	34	28	20	12	STD_INOUT	
P0.10	35	29	-	-	STD_INOUT	
P0.11	36	30	-	-	STD_INOUT	
P0.12	37	31	21	-	STD_INOUT	

**Table 6 Package Pin Mapping**

Function	VQFN 40	TSSOP 38	VQFN 24	TSSOP 16	Pad Type	Notes
VDDP	15	10	10	6	Power	I/O port supply
VSSP	31	25	-	-	Power	I/O port ground
VDDP	32	26	-	-	Power	I/O port supply
VSSP	Exp. Pad	-	Exp. Pad	-	Power	<b>Exposed Die Pad</b> The exposed die pad is connected internally to VSSP. For proper operation, it is mandatory to connect the exposed pad to the board ground. For thermal aspects, please refer to the Package and Reliability chapter.



### 3.1.3 Operating Conditions

The following operating conditions must not be exceeded in order to ensure correct operation and reliability of the XMC1100. All parameters specified in the following tables refer to these operating conditions, unless noted otherwise.

**Table 10 Operating Conditions Parameters**

Parameter	Symbol	Values			Unit	Note / Test Condition
		Min.	Typ.	Max.		
Ambient Temperature	$T_A$ SR	-40	–	85	°C	Temp. Range F
		-40	–	105	°C	Temp. Range X
Digital supply voltage <sup>1)</sup>	$V_{DDP}$ SR	1.8	–	5.5	V	
MCLK Frequency	$f_{MCLK}$ CC	–	–	33.2	MHz	CPU clock
PCLK Frequency	$f_{PCLK}$ CC	–	–	66.4	MHz	Peripherals clock

1) See also the Supply Monitoring thresholds, [Chapter 3.3.3](#).

**Table 11 Input/Output Characteristics (Operating Conditions apply) (cont'd)**

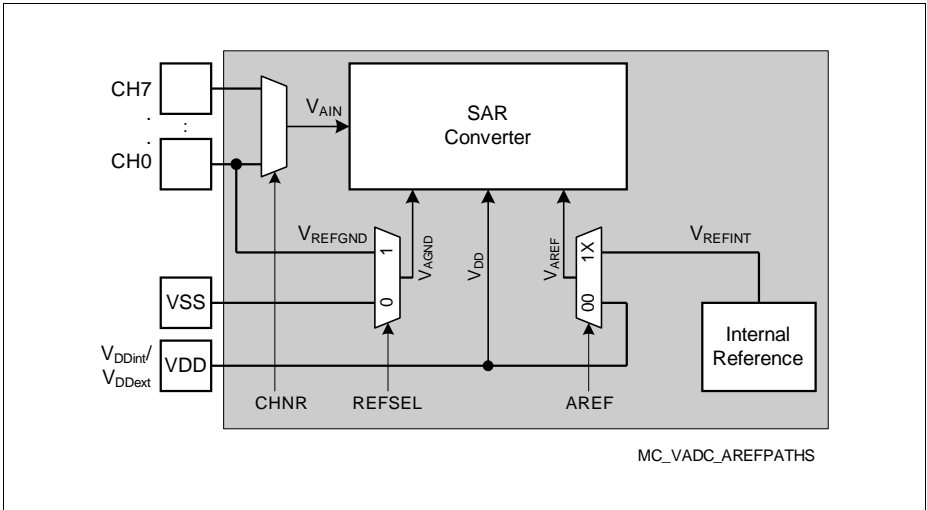
Parameter	Symbol		Limit Values		Unit	Test Conditions
			Min.	Max.		
Maximum current into $V_{DDP}$ (TSSOP28/16, VQFN24)	$I_{MVDD1}$	SR	–	130	mA	<sup>3)</sup>
Maximum current into $V_{DDP}$ (TSSOP38, VQFN40)	$I_{MVDD2}$	SR	–	260	mA	<sup>3)</sup>
Maximum current out of $V_{SS}$ (TSSOP28/16, VQFN24)	$I_{MVSS1}$	SR	–	130	mA	<sup>3)</sup>
Maximum current out of $V_{SS}$ (TSSOP38, VQFN40)	$I_{MVSS2}$	SR	–	260	mA	<sup>3)</sup>

- 1) Not subject to production test, verified by design/characterization. Hysteresis is implemented to avoid meta stable states and switching due to internal ground bounce. It cannot be guaranteed that it suppresses switching due to external system noise.
- 2) An additional error current ( $I_{INL}$ ) will flow if an overload current flows through an adjacent pin.
- 3) Not subject to production test, verified by design/characterization.
- 4) Not subject to production test, verified by design/characterization. However, for applications with strict low power-down current requirements, it is mandatory that no active voltage source is supplied at any GPIO pin when  $V_{DDP}$  is powered off.

**Table 12 ADC Characteristics (Operating Conditions apply) (cont'd)**

Parameter	Symbol	Values			Unit	Note / Test Condition
		Min.	Typ.	Max.		
Maximum sample rate in 8-bit mode <sup>3)</sup>	$f_{C8}$ CC	–	–	$f_{ADC} / 38.5$	–	1 sample pending
		–	–	$f_{ADC} / 54.5$	–	2 samples pending
DNL error	$EA_{DNL}$ CC	–	±2.0	–	LSB 12	
INL error	$EA_{INL}$ CC	–	±4.0	–	LSB 12	
Gain error with external reference	$EA_{GAIN}$ CC	–	±0.5	–	%	SHSCFG.AREF = 00 <sub>B</sub> (calibrated)
Gain error with internal reference	$EA_{GAIN}$ CC	–	±3.6	–	%	SHSCFG.AREF = 1X <sub>B</sub> (calibrated), -40°C - 105°C
		–	±2.0	–	%	SHSCFG.AREF = 1X <sub>B</sub> (calibrated), 0°C - 85°C
Offset error	$EA_{OFF}$ CC	–	±6.0	–	LSB 12	Calibrated

- 1) Not subject to production test, verified by design/characterization.
- 2) No pending samples assumed, excluding sampling time and calibration.
- 3) Includes synchronization and calibration (average of gain and offset calibration).



**Figure 8 ADC Voltage Supply**

### 3.2.3 Temperature Sensor Characteristics

**Table 13 Temperature Sensor Characteristics<sup>1)</sup>**

Parameter	Symbol	Values			Unit	Note / Test Condition
		Min.	Typ.	Max.		
Measurement time	$t_M$ CC	–	–	10	ms	
Temperature sensor range	$T_{SR}$ SR	-40	–	115	°C	
Sensor Accuracy <sup>2)</sup>	$T_{TSAL}$ CC	–	+/-20	–	°C	$T_J = -40\text{ °C}$ (calibrated)
		–	+/-12	–	°C	$T_J = -25\text{ °C}$ (calibrated)
		-5	–	5	°C	$T_J = 0\text{ °C}$
		-2	–	2	°C	$T_J = 25\text{ °C}$ (calibrated)
		-4	–	4	°C	$T_J = 70\text{ °C}$
		-2	–	2	°C	$T_J = 115\text{ °C}$ (calibrated)

1) Not subject to production test, verified by design/characterization.

2) The temperature sensor accuracy is independent of the supply voltage.

### 3.2.5 Flash Memory Parameters

*Note: These parameters are not subject to production test, but verified by design and/or characterization.*

**Table 16 Flash Memory Parameters**

Parameter	Symbol	Values			Unit	Note / Test Condition
		Min.	Typ.	Max.		
Erase Time per page	$t_{ERASE}$ CC	6.8	7.1	7.6	ms	
Program time per block	$t_{PSE}$ CC	102	152	204	$\mu$ s	
Wake-Up time	$t_{WU}$ CC	–	32.2	–	$\mu$ s	
Read time per word	$t_a$ CC	–	50	–	ns	
Data Retention Time	$t_{RET}$ CC	10	–	–	years	Max. 100 erase / program cycles
Flash Wait States <sup>1)</sup>	$N_{WSFLASH}$ CC	0	0.5	–		$f_{MCLK} = 8$ MHz
		0	1.4	–		$f_{MCLK} = 16$ MHz
		1	1.9	–		$f_{MCLK} = 32$ MHz
Erase Cycles per page	$N_{ECC}$ CC	–	–	$5 \cdot 10^4$	cycles	
Total Erase Cycles	$N_{TECC}$ CC	–	–	$2 \cdot 10^6$	cycles	

1) Flash wait states are automatically inserted by the Flash module during memory read when needed. Typical values are calculated from the execution of the Dhystone benchmark program.

### 3.3.3 Power-Up and Supply Threshold Characteristics

**Table 18** provides the characteristics of the supply threshold in XMC1100.

**Table 18 Power-Up and Supply Threshold Parameters (Operating Conditions apply) <sup>1)</sup>**

Parameter	Symbol	Values			Unit	Note / Test Condition
		Min.	Typ.	Max.		
$V_{DDP}$ ramp-up time	$t_{RAMPUP}$ SR	$V_{DDP}/S_{VDDPrise}$	–	$10^7$	$\mu s$	
$V_{DDP}$ slew rate	$S_{VDDPOP}$ SR	0	–	0.1	$V/\mu s$	Slope during normal operation
	$S_{VDDP10}$ SR	0	–	10	$V/\mu s$	Slope during fast transient within +/- 10% of $V_{DDP}$
	$S_{VDDPrise}$ SR	0	–	10	$V/\mu s$	Slope during power-on or restart after brownout event
	$S_{VDDPfall}$ <sup>2)</sup> SR	0	–	0.25	$V/\mu s$	Slope during supply falling out of the +/- 10% limits <sup>3)</sup>
$V_{DDP}$ prewarning voltage	$V_{DDPPW}$ CC	2.1	2.25	2.4	V	ANAVDEL.VDEL_SELECT = 00 <sub>B</sub>
		2.85	3	3.15	V	ANAVDEL.VDEL_SELECT = 01 <sub>B</sub>
		4.2	4.4	4.6	V	ANAVDEL.VDEL_SELECT = 10 <sub>B</sub>
$V_{DDP}$ brownout reset voltage	$V_{DDPBO}$ CC	1.55	1.62	1.75	V	calibrated, before user code starts running
Start-up time from power-on reset	$t_{SSW}$ SR	–	320	–	$\mu s$	Time to the first user code instruction <sup>4)</sup>

1) Not all parameters are 100% tested, but are verified by design/characterisation.

2) A capacitor of at least 100 nF has to be added between  $V_{DDP}$  and  $V_{SSP}$  to fulfill the requirement as stated for this parameter.

### 3.3.4 On-Chip Oscillator Characteristics

**Table 19** provides the characteristics of the 64 MHz clock output from the digital controlled oscillator, DCO1 in XMC1100.

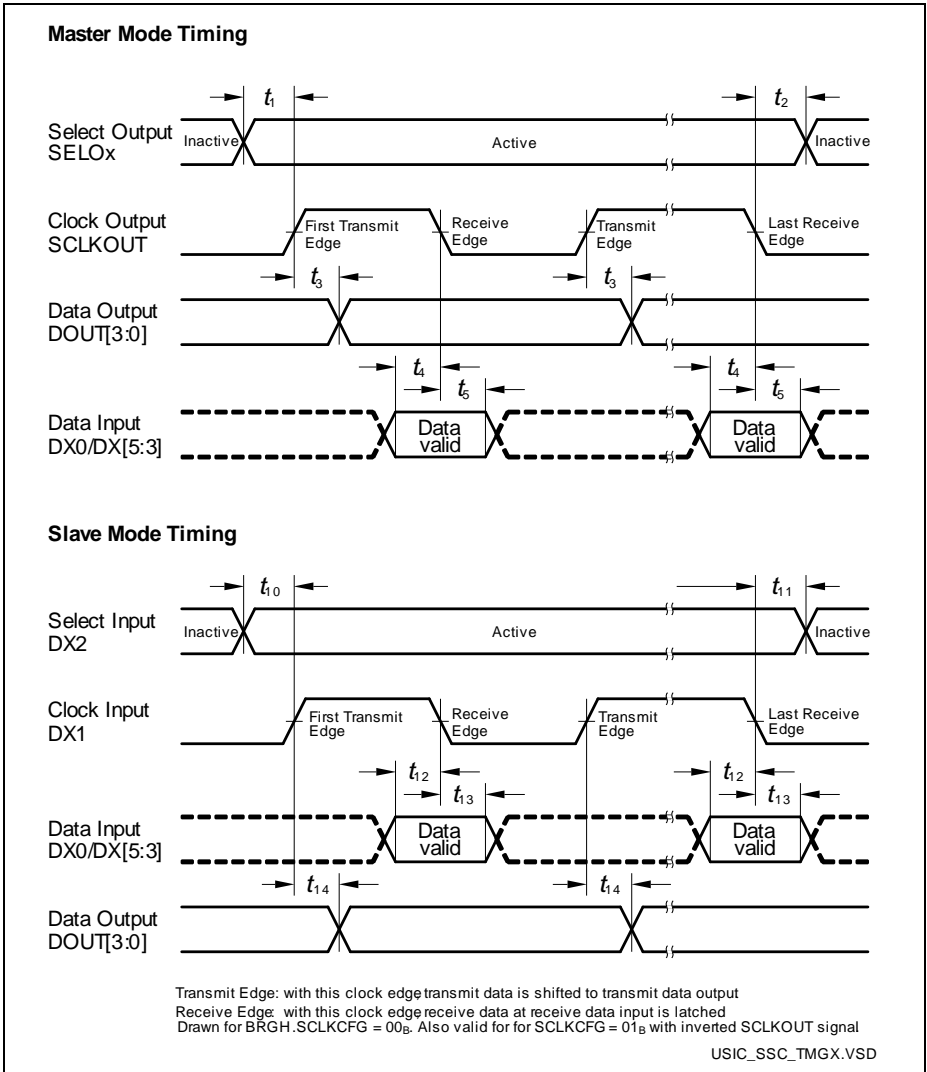
**Table 19 64 MHz DCO1 Characteristics (Operating Conditions apply)**

Parameter	Symbol		Limit Values			Unit	Test Conditions
			Min.	Typ.	Max.		
Nominal frequency	$f_{\text{NOM}}$	CC	63.5	64	64.5	MHz	under nominal conditions <sup>1)</sup> after trimming
Accuracy	$\Delta f_{\text{LT}}$	CC	-1.7	–	3.4	%	with respect to $f_{\text{NOM}}(\text{typ})$ , over temperature (0 °C to 85 °C) <sup>2)</sup>
			-3.9	–	4.0	%	with respect to $f_{\text{NOM}}(\text{typ})$ , over temperature (-40 °C to 105 °C) <sup>2)</sup>
Accuracy with calibration based on temperature sensor	$\Delta f_{\text{LTT}}$	CC	-1.3	–	1.25	%	with respect to $f_{\text{NOM}}(\text{typ})$ , over temperature ( $T_A = 0$ °C to 105 °C) <sup>2)</sup>
			-2.6	–	1.25	%	with respect to $f_{\text{NOM}}(\text{typ})$ , over temperature ( $T_A = -40$ °C to 105 °C) <sup>2)</sup>

1) The deviation is relative to the factory trimmed frequency at nominal  $V_{\text{DDC}}$  and  $T_A = +25$  °C.

2) Not subject to production test, verified by design/characterisation.





**Figure 15 USIC - SSC Master/Slave Mode Timing**

*Note: This timing diagram shows a standard configuration, for which the slave select signal is low-active, and the serial clock signal is not shifted and not inverted.*

### 3.3.7.2 Inter-IC (IIC) Interface Timing

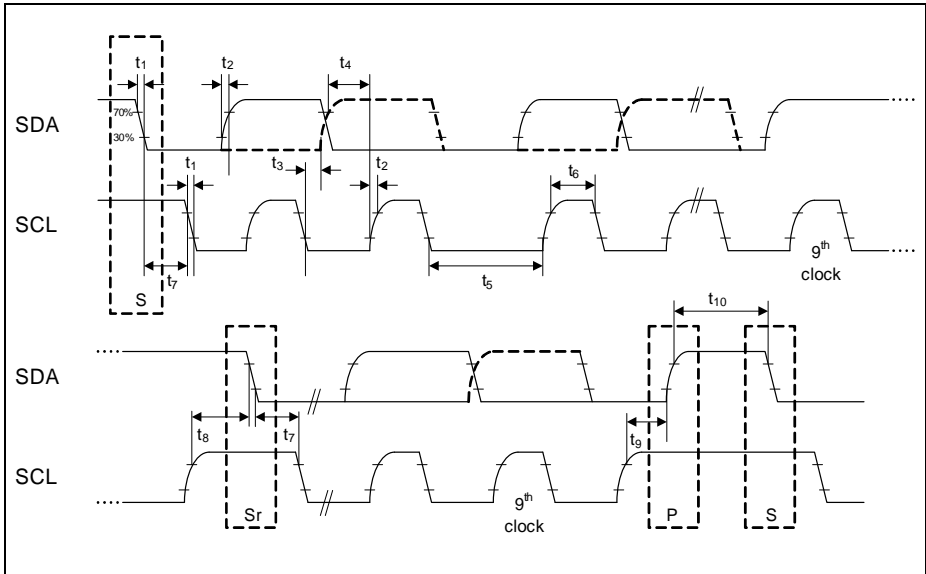
The following parameters are applicable for a USIC channel operated in IIC mode.

*Note: Operating Conditions apply.*

**Table 25 USIC IIC Standard Mode Timing<sup>1)</sup>**

Parameter	Symbol	Values			Unit	Note / Test Condition
		Min.	Typ.	Max.		
Fall time of both SDA and SCL	$t_1$ CC/SR	-	-	300	ns	
Rise time of both SDA and SCL	$t_2$ CC/SR	-	-	1000	ns	
Data hold time	$t_3$ CC/SR	0	-	-	µs	
Data set-up time	$t_4$ CC/SR	250	-	-	ns	
LOW period of SCL clock	$t_5$ CC/SR	4.7	-	-	µs	
HIGH period of SCL clock	$t_6$ CC/SR	4.0	-	-	µs	
Hold time for (repeated) START condition	$t_7$ CC/SR	4.0	-	-	µs	
Set-up time for repeated START condition	$t_8$ CC/SR	4.7	-	-	µs	
Set-up time for STOP condition	$t_9$ CC/SR	4.0	-	-	µs	
Bus free time between a STOP and START condition	$t_{10}$ CC/SR	4.7	-	-	µs	
Capacitive load for each bus line	$C_b$ SR	-	-	400	pF	

1) Due to the wired-AND configuration of an IIC bus system, the port drivers of the SCL and SDA signal lines need to operate in open-drain mode. The high level on these lines must be held by an external pull-up device, approximately 10 kOhm for operation at 100 kbit/s, approximately 2 kOhm for operation at 400 kbit/s.



**Figure 16 USIC IIC Stand and Fast Mode Timing**

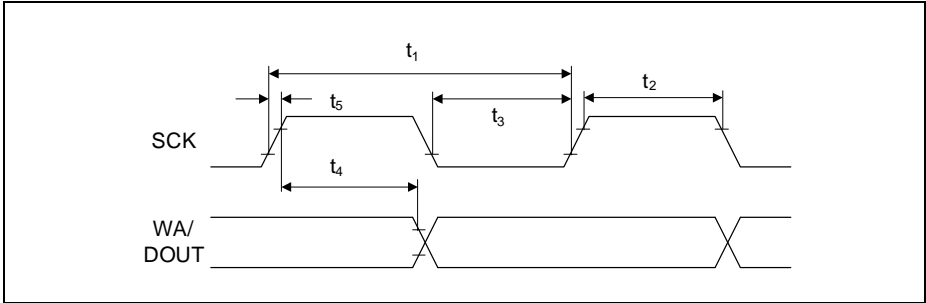
### 3.3.7.3 Inter-IC Sound (IIS) Interface Timing

The following parameters are applicable for a USIC channel operated in IIS mode.

*Note: Operating Conditions apply.*

**Table 27 USIC IIS Master Transmitter Timing**

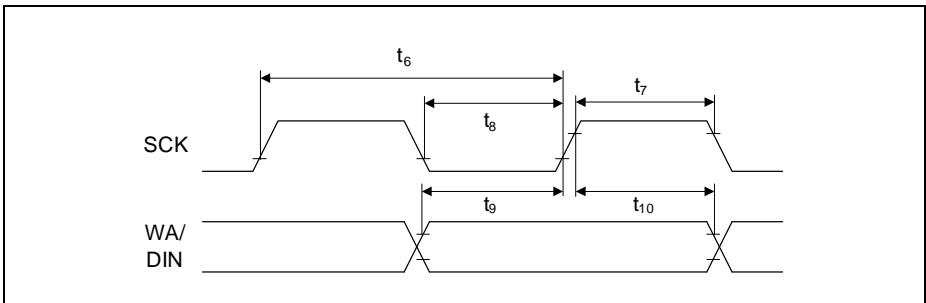
Parameter	Symbol	Values			Unit	Note / Test Condition
		Min.	Typ.	Max.		
Clock period	$t_1$ CC	$2/f_{MCLK}$	-	-	ns	$V_{DDP} \geq 3 V$
		$4/f_{MCLK}$	-	-	ns	$V_{DDP} < 3 V$
Clock HIGH	$t_2$ CC	$0.35 \times t_{1min}$	-	-	ns	
Clock Low	$t_3$ CC	$0.35 \times t_{1min}$	-	-	ns	
Hold time	$t_4$ CC	0	-	-	ns	
Clock rise time	$t_5$ CC	-	-	$0.15 \times t_{1min}$	ns	



**Figure 17 USIC IIS Master Transmitter Timing**

**Table 28 USIC IIS Slave Receiver Timing**

Parameter	Symbol	Values			Unit	Note / Test Condition
		Min.	Typ.	Max.		
Clock period	$t_6$ SR	$4/f_{MCLK}$	-	-	ns	
Clock HIGH	$t_7$ SR	$0.35 \times t_{6min}$	-	-	ns	
Clock Low	$t_8$ SR	$0.35 \times t_{6min}$	-	-	ns	
Set-up time	$t_9$ SR	$0.2 \times t_{6min}$	-	-	ns	
Hold time	$t_{10}$ SR	10	-	-	ns	



**Figure 18 USIC IIS Slave Receiver Timing**

