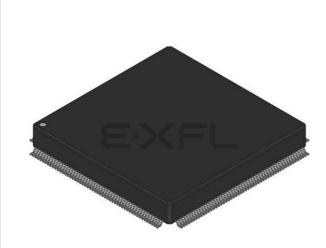
# E·XFI

# Altera - EPF10K100EQC208-2X Datasheet



Welcome to <u>E-XFL.COM</u>

#### Understanding Embedded - FPGAs (Field Programmable Gate Array)

Embedded - FPGAs, or Field Programmable Gate Arrays, are advanced integrated circuits that offer unparalleled flexibility and performance for digital systems. Unlike traditional fixed-function logic devices, FPGAs can be programmed and reprogrammed to execute a wide array of logical operations, enabling customized functionality tailored to specific applications. This reprogrammability allows developers to iterate designs quickly and implement complex functions without the need for custom hardware.

### **Applications of Embedded - FPGAs**

The versatility of Embedded - FPGAs makes them indispensable in numerous fields. In telecommunications.

D	e	t	a	i	l	s	
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Details	
Product Status	Active
Number of LABs/CLBs	624
Number of Logic Elements/Cells	-
Total RAM Bits	-
Number of I/O	147
Number of Gates	-
Voltage - Supply	2.375V ~ 2.625V
Mounting Type	Surface Mount
Operating Temperature	0°C ~ 70°C (TA)
Package / Case	208-BFQFP
Supplier Device Package	208-PQFP (28x28)
Purchase URL	https://www.e-xfl.com/pro/item?MUrl=&PartUrl=epf10k100eqc208-2x

Email: info@E-XFL.COM

Address: Room A, 16/F, Full Win Commercial Centre, 573 Nathan Road, Mongkok, Hong Kong

Table 5. FLEX 10KE Perform	nance					
Application	Resource	es Used		Performance		Units
	LEs	EABs	-1 Speed Grade	-2 Speed Grade	-3 Speed Grade	
16-bit loadable counter	16	0	285	250	200	MHz
16-bit accumulator	16	0	285	250	200	MHz
16-to-1 multiplexer (1)	10	0	3.5	4.9	7.0	ns
16-bit multiplier with 3-stage pipeline (2)	592	0	156	131	93	MHz
$256 \times 16$ RAM read cycle speed (2)	0	1	196	154	118	MHz
$256 \times 16$ RAM write cycle speed (2)	0	1	185	143	106	MHz

# Table 5. FLEX 10KE Performance

#### Notes:

(1) This application uses combinatorial inputs and outputs.

(2) This application uses registered inputs and outputs.

Table 6 shows FLEX 10KE performance for more complex designs. These designs are available as Altera MegaCore $^{\circ}$  functions.

Table 6. FLEX 10KE Performanc	e for Complex	Designs			
Application	LEs Used		Performance		Units
		-1 Speed Grade	-2 Speed Grade	-3 Speed Grade	
8-bit, 16-tap parallel finite impulse response (FIR) filter	597	192	156	116	MSPS
8-bit, 512-point fast Fourier	1,854	23.4	28.7	38.9	µs (1)
transform (FFT) function		113	92	68	MHz
a16450 universal asynchronous receiver/transmitter (UART)	342	36	28	20.5	MHz

#### Note:

(1) These values are for calculation time. Calculation time = number of clocks required /  $f_{max}$ . Number of clocks required = ceiling [log 2 (points)/2] × [points +14 + ceiling]

Similar to the FLEX 10KE architecture, embedded gate arrays are the fastest-growing segment of the gate array market. As with standard gate arrays, embedded gate arrays implement general logic in a conventional "sea-of-gates" architecture. Additionally, embedded gate arrays have dedicated die areas for implementing large, specialized functions. By embedding functions in silicon, embedded gate arrays reduce die area and increase speed when compared to standard gate arrays. While embedded megafunctions typically cannot be customized, FLEX 10KE devices are programmable, providing the designer with full control over embedded megafunctions and general logic, while facilitating iterative design changes during debugging.

Each FLEX 10KE device contains an embedded array and a logic array. The embedded array is used to implement a variety of memory functions or complex logic functions, such as digital signal processing (DSP), wide data-path manipulation, microcontroller applications, and datatransformation functions. The logic array performs the same function as the sea-of-gates in the gate array and is used to implement general logic such as counters, adders, state machines, and multiplexers. The combination of embedded and logic arrays provides the high performance and high density of embedded gate arrays, enabling designers to implement an entire system on a single device.

FLEX 10KE devices are configured at system power-up with data stored in an Altera serial configuration device or provided by a system controller. Altera offers the EPC1, EPC2, and EPC16 configuration devices, which configure FLEX 10KE devices via a serial data stream. Configuration data can also be downloaded from system RAM or via the Altera BitBlaster<sup>TM</sup>, ByteBlasterMV<sup>TM</sup>, or MasterBlaster download cables. After a FLEX 10KE device has been configured, it can be reconfigured in-circuit by resetting the device and loading new data. Because reconfiguration requires less than 85 ms, real-time changes can be made during system operation.

FLEX 10KE devices contain an interface that permits microprocessors to configure FLEX 10KE devices serially or in-parallel, and synchronously or asynchronously. The interface also enables microprocessors to treat a FLEX 10KE device as memory and configure it by writing to a virtual memory location, making it easy to reconfigure the device.

# Functional Description

Each FLEX 10KE device contains an enhanced embedded array to implement memory and specialized logic functions, and a logic array to implement general logic.

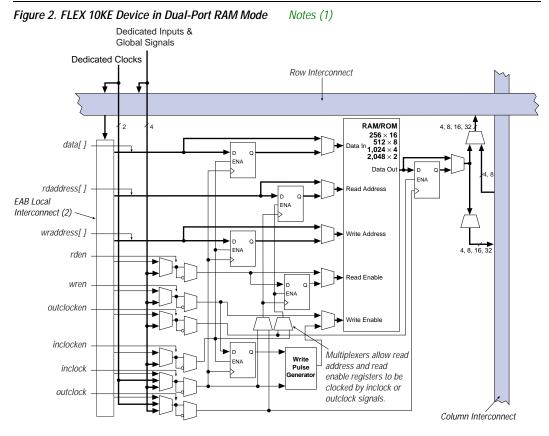
The embedded array consists of a series of EABs. When implementing memory functions, each EAB provides 4,096 bits, which can be used to create RAM, ROM, dual-port RAM, or first-in first-out (FIFO) functions. When implementing logic, each EAB can contribute 100 to 600 gates towards complex logic functions, such as multipliers, microcontrollers, state machines, and DSP functions. EABs can be used independently, or multiple EABs can be combined to implement larger functions.

The logic array consists of logic array blocks (LABs). Each LAB contains eight LEs and a local interconnect. An LE consists of a four-input look-up table (LUT), a programmable flipflop, and dedicated signal paths for carry and cascade functions. The eight LEs can be used to create medium-sized blocks of logic—such as 8-bit counters, address decoders, or state machines—or combined across LABs to create larger logic blocks. Each LAB represents about 96 usable gates of logic.

Signal interconnections within FLEX 10KE devices (as well as to and from device pins) are provided by the FastTrack Interconnect routing structure, which is a series of fast, continuous row and column channels that run the entire length and width of the device.

Each I/O pin is fed by an I/O element (IOE) located at the end of each row and column of the FastTrack Interconnect routing structure. Each IOE contains a bidirectional I/O buffer and a flipflop that can be used as either an output or input register to feed input, output, or bidirectional signals. When used with a dedicated clock pin, these registers provide exceptional performance. As inputs, they provide setup times as low as 0.9 ns and hold times of 0 ns. As outputs, these registers provide clock-to-output times as low as 3.0 ns. IOEs provide a variety of features, such as JTAG BST support, slew-rate control, tri-state buffers, and open-drain outputs. The EAB can also be used for bidirectional, dual-port memory applications where two ports read or write simultaneously. To implement this type of dual-port memory, two EABs are used to support two simultaneous read or writes.

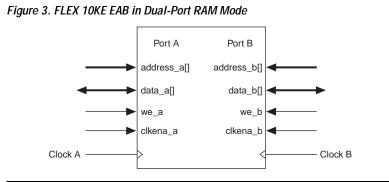
Alternatively, one clock and clock enable can be used to control the input registers of the EAB, while a different clock and clock enable control the output registers (see Figure 2).



#### Notes:

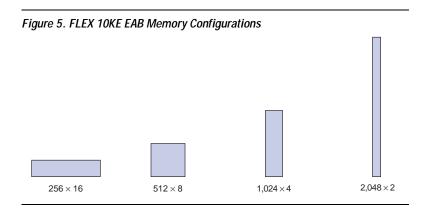
- (1) All registers can be asynchronously cleared by EAB local interconnect signals, global signals, or the chip-wide reset.
- (2) EPF10K30E and EPF10K50E devices have 88 EAB local interconnect channels; EPF10K100E, EPF10K130E, and EPF10K200E devices have 104 EAB local interconnect channels.

The EAB can also use Altera megafunctions to implement dual-port RAM applications where both ports can read or write, as shown in Figure 3.



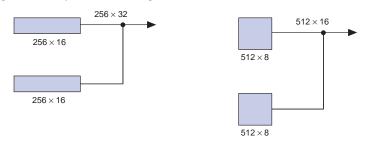
The FLEX 10KE EAB can be used in a single-port mode, which is useful for backward-compatibility with FLEX 10K designs (see Figure 4).

When used as RAM, each EAB can be configured in any of the following sizes:  $256 \times 16$ ,  $512 \times 8$ ,  $1,024 \times 4$ , or  $2,048 \times 2$  (see Figure 5).



Larger blocks of RAM are created by combining multiple EABs. For example, two  $256 \times 16$  RAM blocks can be combined to form a  $256 \times 32$  block; two  $512 \times 8$  RAM blocks can be combined to form a  $512 \times 16$  block (see Figure 6).





If necessary, all EABs in a device can be cascaded to form a single RAM block. EABs can be cascaded to form RAM blocks of up to 2,048 words without impacting timing. The Altera software automatically combines EABs to meet a designer's RAM specifications.

The programmable flipflop in the LE can be configured for D, T, JK, or SR operation. The clock, clear, and preset control signals on the flipflop can be driven by global signals, general-purpose I/O pins, or any internal logic. For combinatorial functions, the flipflop is bypassed and the output of the LUT drives the output of the LE.

The LE has two outputs that drive the interconnect: one drives the local interconnect and the other drives either the row or column FastTrack Interconnect routing structure. The two outputs can be controlled independently. For example, the LUT can drive one output while the register drives the other output. This feature, called register packing, can improve LE utilization because the register and the LUT can be used for unrelated functions.

The FLEX 10KE architecture provides two types of dedicated high-speed data paths that connect adjacent LEs without using local interconnect paths: carry chains and cascade chains. The carry chain supports high-speed counters and adders and the cascade chain implements wide-input functions with minimum delay. Carry and cascade chains connect all LEs in a LAB as well as all LABs in the same row. Intensive use of carry and cascade chains can reduce routing flexibility. Therefore, the use of these chains should be limited to speed-critical portions of a design.

# Carry Chain

The carry chain provides a very fast (as low as 0.2 ns) carry-forward function between LEs. The carry-in signal from a lower-order bit drives forward into the higher-order bit via the carry chain, and feeds into both the LUT and the next portion of the carry chain. This feature allows the FLEX 10KE architecture to implement high-speed counters, adders, and comparators of arbitrary width efficiently. Carry chain logic can be created automatically by the Altera Compiler during design processing, or manually by the designer during design entry. Parameterized functions such as LPM and DesignWare functions automatically take advantage of carry chains.

Carry chains longer than eight LEs are automatically implemented by linking LABs together. For enhanced fitting, a long carry chain skips alternate LABs in a row. A carry chain longer than one LAB skips either from even-numbered LAB to even-numbered LAB, or from oddnumbered LAB to odd-numbered LAB. For example, the last LE of the first LAB in a row carries to the first LE of the third LAB in the row. The carry chain does not cross the EAB at the middle of the row. For instance, in the EPF10K50E device, the carry chain stops at the eighteenth LAB and a new one begins at the nineteenth LAB.

# FastTrack Interconnect Routing Structure

In the FLEX 10KE architecture, connections between LEs, EABs, and device I/O pins are provided by the FastTrack Interconnect routing structure, which is a series of continuous horizontal and vertical routing channels that traverses the device. This global routing structure provides predictable performance, even in complex designs. In contrast, the segmented routing in FPGAs requires switch matrices to connect a variable number of routing paths, increasing the delays between logic resources and reducing performance.

The FastTrack Interconnect routing structure consists of row and column interconnect channels that span the entire device. Each row of LABs is served by a dedicated row interconnect. The row interconnect can drive I/O pins and feed other LABs in the row. The column interconnect routes signals between rows and can drive I/O pins.

Row channels drive into the LAB or EAB local interconnect. The row signal is buffered at every LAB or EAB to reduce the effect of fan-out on delay. A row channel can be driven by an LE or by one of three column channels. These four signals feed dual 4-to-1 multiplexers that connect to two specific row channels. These multiplexers, which are connected to each LE, allow column channels to drive row channels even when all eight LEs in a LAB drive the row interconnect.

Each column of LABs or EABs is served by a dedicated column interconnect. The column interconnect that serves the EABs has twice as many channels as other column interconnects. The column interconnect can then drive I/O pins or another row's interconnect to route the signals to other LABs or EABs in the device. A signal from the column interconnect, which can be either the output of a LE or an input from an I/O pin, must be routed to the row interconnect before it can enter a LAB or EAB. Each row channel that is driven by an IOE or EAB can drive one specific column channel.

Access to row and column channels can be switched between LEs in adjacent pairs of LABs. For example, a LE in one LAB can drive the row and column channels normally driven by a particular LE in the adjacent LAB in the same row, and vice versa. This flexibility enables routing resources to be used more efficiently (see Figure 13). Row-to-IOE Connections

When an IOE is used as an input signal, it can drive two separate row channels. The signal is accessible by all LEs within that row. When an IOE is used as an output, the signal is driven by a multiplexer that selects a signal from the row channels. Up to eight IOEs connect to each side of each row channel (see Figure 16).

# Figure 16. FLEX 10KE Row-to-IOE Connections The values for m and n are provided in Table 10.

m loe1

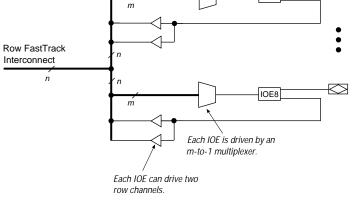


Table 10 lists the FLEX 10KE row-to-IOE interco	onnect resources.
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Table 10. FLEX 10K	Table 10. FLEX 10KE Row-to-IOE Interconnect Resources				
Device	Channels per Row (n)	Row Channels per Pin (m)			
EPF10K30E	216	27			
EPF10K50E	216	27			
EPF10K50S					
EPF10K100E	312	39			
EPF10K130E	312	39			
EPF10K200E	312	39			
EPF10K200S					

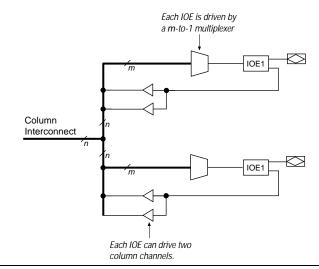
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Column-to-IOE Connections

When an IOE is used as an input, it can drive up to two separate column channels. When an IOE is used as an output, the signal is driven by a multiplexer that selects a signal from the column channels. Two IOEs connect to each side of the column channels. Each IOE can be driven by column channels via a multiplexer. The set of column channels is different for each IOE (see Figure 17).



The values for m and n are provided in Table 11.



### Table 11 lists the FLEX 10KE column-to-IOE interconnect resources.

Table 11. FLEX 10KE Column-to-IOE Interconnect Resources				
Device	Channels per Column (n)	Column Channels per Pin (m)		
EPF10K30E	24	16		
EPF10K50E EPF10K50S	24	16		
EPF10K100E	24	16		
EPF10K130E	32	24		
EPF10K200E EPF10K200S	48	40		

Table 17. 32-	Bit IDCOD	E for FLEX 10KE Devices	Note (1)				
Device		IDCODE (32 Bits)					
	Version (4 Bits)	Part Number (16 Bits)	Manufacturer's Identity (11 Bits)	<b>1 (1 Bit)</b> (2)			
EPF10K30E	0001	0001 0000 0011 0000	00001101110	1			
EPF10K50E EPF10K50S	0001	0001 0000 0101 0000	00001101110	1			
EPF10K100E	0010	0000 0001 0000 0000	00001101110	1			
EPF10K130E	0001	0000 0001 0011 0000	00001101110	1			
EPF10K200E EPF10K200S	0001	0000 0010 0000 0000	00001101110	1			

#### Notes:

(1) The most significant bit (MSB) is on the left.

(2) The least significant bit (LSB) for all JTAG IDCODEs is 1.

FLEX 10KE devices include weak pull-up resistors on the JTAG pins.



For more information, see the following documents:

- Application Note 39 (IEEE Std. 1149.1 (JTAG) Boundary-Scan Testing in Altera Devices)
- BitBlaster Serial Download Cable Data Sheet
- ByteBlasterMV Parallel Port Download Cable Data Sheet
- Jam Programming & Test Language Specification

Figure 20 shows the timing requirements for the JTAG signals.

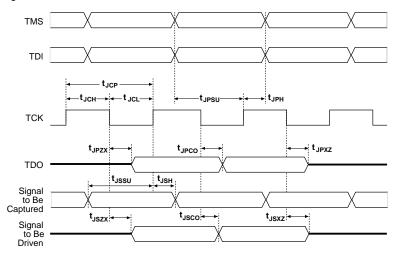


Figure 20. FLEX 10KE JTAG Waveforms

# Table 18 shows the timing parameters and values for FLEX 10KE devices.

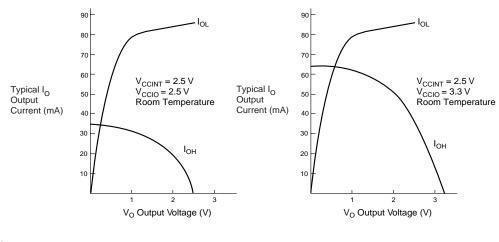
Sumbol	Parameter	Min	Max	Unit
Symbol	Parameter	IVIIII	IVIAX	Unit
t <sub>JCP</sub>	TCK clock period	100		ns
t <sub>JCH</sub>	TCK clock high time	50		ns
t <sub>JCL</sub>	TCK clock low time	50		ns
t <sub>JPSU</sub>	JTAG port setup time	20		ns
t <sub>JPH</sub>	JTAG port hold time	45		ns
t <sub>JPCO</sub>	JTAG port clock to output		25	ns
t <sub>JPZX</sub>	JTAG port high impedance to valid output		25	ns
t <sub>JPXZ</sub>	JTAG port valid output to high impedance		25	ns
t <sub>JSSU</sub>	Capture register setup time	20		ns
t <sub>JSH</sub>	Capture register hold time	45		ns
t <sub>JSCO</sub>	Update register clock to output		35	ns
t <sub>JSZX</sub>	Update register high impedance to valid output		35	ns
t <sub>JSXZ</sub>	Update register valid output to high impedance		35	ns

Table 20	0. 2.5-V EPF10K50E & EPF10K200	E Device Recommended	Operating Con	ditions	
Symbol	Parameter	Conditions	Min	Мах	Unit
V <sub>CCINT</sub>	Supply voltage for internal logic and input buffers	(3), (4)	2.30 (2.30)	2.70 (2.70)	V
V <sub>CCIO</sub>	Supply voltage for output buffers, 3.3-V operation	(3), (4)	3.00 (3.00)	3.60 (3.60)	V
	Supply voltage for output buffers, 2.5-V operation	(3), (4)	2.30 (2.30)	2.70 (2.70)	V
VI	Input voltage	(5)	-0.5	5.75	V
Vo	Output voltage		0	V <sub>CCIO</sub>	V
Τ <sub>A</sub>	Ambient temperature	For commercial use	0	70	°C
		For industrial use	-40	85	°C
TJ	Operating temperature	For commercial use	0	85	°C
		For industrial use	-40	100	°C
t <sub>R</sub>	Input rise time			40	ns
t <sub>F</sub>	Input fall time			40	ns

# *Table 21. 2.5-V EPF10K30E, EPF10K50S, EPF10K100E, EPF10K130E & EPF10K200S Device Recommended Operating Conditions*

Symbol	Parameter	Conditions	Min	Мах	Unit
V <sub>CCINT</sub>	Supply voltage for internal logic and input buffers	(3), (4)	2.375 (2.375)	2.625 (2.625)	V
V <sub>CCIO</sub>	Supply voltage for output buffers, 3.3-V operation	(3), (4)	3.00 (3.00)	3.60 (3.60)	V
	Supply voltage for output buffers, 2.5-V operation	(3), (4)	2.375 (2.375)	2.625 (2.625)	V
VI	Input voltage	(5)	-0.5	5.75	V
Vo	Output voltage		0	V <sub>CCIO</sub>	V
Τ <sub>A</sub>	Ambient temperature	For commercial use	0	70	°C
		For industrial use	-40	85	°C
TJ	Operating temperature	For commercial use	0	85	°C
		For industrial use	-40	100	°C
t <sub>R</sub>	Input rise time			40	ns
t <sub>F</sub>	Input fall time			40	ns





#### Figure 23. Output Drive Characteristics of FLEX 10KE Devices Note (1)

#### Note:

(1) These are transient (AC) currents.

# **Timing Model**

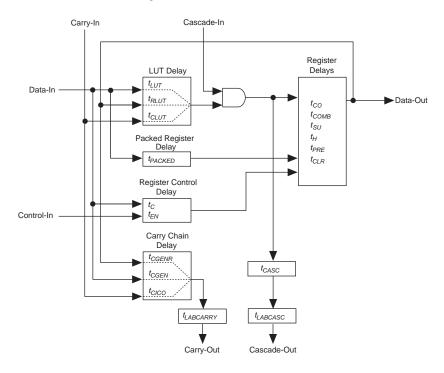
The continuous, high-performance FastTrack Interconnect routing resources ensure predictable performance and accurate simulation and timing analysis. This predictable performance contrasts with that of FPGAs, which use a segmented connection scheme and therefore have unpredictable performance.

Device performance can be estimated by following the signal path from a source, through the interconnect, to the destination. For example, the registered performance between two LEs on the same row can be calculated by adding the following parameters:

- LE register clock-to-output delay (*t*<sub>CO</sub>)
- Interconnect delay (t<sub>SAMEROW</sub>)
- **LE** look-up table delay  $(t_{LUT})$
- **LE** register setup time  $(t_{SU})$

The routing delay depends on the placement of the source and destination LEs. A more complex registered path may involve multiple combinatorial LEs between the source and destination LEs.

Figure 25. FLEX 10KE Device LE Timing Model



Figures 29 and 30 show the asynchronous and synchronous timing waveforms, respectively, or the EAB macroparameters in Tables 26 and 27.

EAB Asynchronous Read WE \_ a0 a2 Address a1 a3 – t<sub>EABAA</sub>t<sub>EABRCCOMB</sub> Data-Out d0 d3 d1 d2 **EAB Asynchronous Write** WE  $t_{EABWP}$ ► t<sub>EABWDH</sub> t<sub>EABWDSU</sub> × a din0 din1 Data-In t<sub>EABWASU</sub> t<sub>EABWAH</sub> t<sub>EABWCCOMB</sub> Address a0 a1 a2  $t_{EABDD}$ Data-Out din0 din1 dout2

#### Figure 29. EAB Asynchronous Timing Waveforms

Symbol	-1 Spee	d Grade	-2 Speed Grade		-3 Speed Grade		Unit
	Min	Max	Min	Max	Min	Max	
t <sub>CGENR</sub>		0.1		0.1		0.2	ns
t <sub>CASC</sub>		0.6		0.9		1.2	ns
t <sub>C</sub>		0.8		1.0		1.4	ns
t <sub>CO</sub>		0.6		0.8		1.1	ns
t <sub>COMB</sub>		0.4		0.5		0.7	ns
t <sub>SU</sub>	0.4		0.6		0.7		ns
t <sub>H</sub>	0.5		0.7		0.9		ns
t <sub>PRE</sub>		0.8		1.0		1.4	ns
t <sub>CLR</sub>		0.8		1.0		1.4	ns
t <sub>CH</sub>	1.5		2.0		2.5		ns
t <sub>CL</sub>	1.5		2.0		2.5		ns

Symbol	-1 Speed Grade		-2 Speed Grade		-3 Speed Grade		Unit
	Min	Мах	Min	Max	Min	Max	
t <sub>IOD</sub>		1.7		2.0		2.6	ns
t <sub>IOC</sub>		0.0		0.0		0.0	ns
t <sub>IOCO</sub>		1.4		1.6		2.1	ns
t <sub>IOCOMB</sub>		0.5		0.7		0.9	ns
t <sub>IOSU</sub>	0.8		1.0		1.3		ns
t <sub>IOH</sub>	0.7		0.9		1.2		ns
t <sub>IOCLR</sub>		0.5		0.7		0.9	ns
t <sub>OD1</sub>		3.0		4.2		5.6	ns
t <sub>OD2</sub>		3.0		4.2		5.6	ns
t <sub>OD3</sub>		4.0		5.5		7.3	ns
t <sub>XZ</sub>		3.5		4.6		6.1	ns
t <sub>ZX1</sub>		3.5		4.6		6.1	ns
t <sub>ZX2</sub>		3.5		4.6		6.1	ns
t <sub>ZX3</sub>		4.5		5.9		7.8	ns
t <sub>INREG</sub>		2.0		2.6		3.5	ns
t <sub>IOFD</sub>		0.5		0.8		1.2	ns
t <sub>INCOMB</sub>		0.5		0.8		1.2	ns

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Symbol	-1 Speed Grade		-2 Speed Grade		-3 Speed Grade		Unit
	Min	Max	Min	Max	Min	Max	
t <sub>DIN2IOE</sub>		2.8		3.5		4.4	ns
t <sub>DIN2LE</sub>		0.7		1.2		1.6	ns
t <sub>DIN2DATA</sub>		1.6		1.9		2.2	ns
t <sub>DCLK2IOE</sub>		1.6		2.1		2.7	ns
t <sub>DCLK2LE</sub>		0.7		1.2		1.6	ns
t <sub>SAMELAB</sub>		0.1		0.2		0.2	ns
t <sub>SAMEROW</sub>		1.9		3.4		5.1	ns
t <sub>SAMECOLUMN</sub>		0.9		2.6		4.4	ns
t <sub>DIFFROW</sub>		2.8		6.0		9.5	ns
t <sub>TWOROWS</sub>		4.7		9.4		14.6	ns
t <sub>LEPERIPH</sub>		3.1		4.7		6.9	ns
t <sub>LABCARRY</sub>		0.6		0.8		1.0	ns
t <sub>LABCASC</sub>		0.9		1.2		1.6	ns

Table 57. EPF10K130E External Timing Parameters Notes (1), (2)							
Symbol	-1 Speed Grade		-2 Speed Grade		-3 Speed Grade		Unit
	Min	Max	Min	Max	Min	Max	
t <sub>DRR</sub>		9.0		12.0		16.0	ns
t <sub>INSU</sub> (3)	1.9		2.1		3.0		ns
t <sub>INH</sub> (3)	0.0		0.0		0.0		ns
<b>t</b> оитсо (3)	2.0	5.0	2.0	7.0	2.0	9.2	ns
t <sub>INSU</sub> (4)	0.9		1.1		-		ns
t <sub>INH</sub> (4)	0.0		0.0		-		ns
<b>t</b> оитсо <i>(4)</i>	0.5	4.0	0.5	6.0	-	-	ns
t <sub>PCISU</sub>	3.0		6.2		-		ns
t <sub>PCIH</sub>	0.0		0.0		-		ns
t <sub>PCICO</sub>	2.0	6.0	2.0	6.9	-	-	ns

Symbol	-1 Speed Grade		-2 Speed Grade		-3 Speed Grade		Unit
	Min	Max	Min	Max	Min	Max	
t <sub>EABDATA1</sub>		1.7		2.4		3.2	ns
t <sub>EABDATA2</sub>		0.4		0.6		0.8	ns
t <sub>EABWE1</sub>		1.0		1.4		1.9	ns
t <sub>EABWE2</sub>		0.0		0.0		0.0	ns
t <sub>EABRE1</sub>		0.0		0.0		0.0	
t <sub>EABRE2</sub>		0.4		0.6		0.8	
t <sub>EABCLK</sub>		0.0		0.0		0.0	ns
t <sub>EABCO</sub>		0.8		1.1		1.5	ns
t <sub>EABBYPASS</sub>		0.0		0.0		0.0	ns
t <sub>EABSU</sub>	0.7		1.0		1.3		ns
t <sub>EABH</sub>	0.4		0.6		0.8		ns
t <sub>EABCLR</sub>	0.8		1.1		1.5		
t <sub>AA</sub>		2.0		2.8		3.8	ns
t <sub>WP</sub>	2.0		2.8		3.8		ns
t <sub>RP</sub>	1.0		1.4		1.9		
t <sub>WDSU</sub>	0.5		0.7		0.9		ns
t <sub>WDH</sub>	0.1		0.1		0.2		ns
t <sub>WASU</sub>	1.0		1.4		1.9		ns
t <sub>WAH</sub>	1.5		2.1		2.9		ns
t <sub>RASU</sub>	1.5		2.1		2.8		
t <sub>RAH</sub>	0.1		0.1		0.2		
t <sub>WO</sub>		2.1		2.9		4.0	ns
t <sub>DD</sub>		2.1		2.9		4.0	ns
t <sub>EABOUT</sub>		0.0		0.0		0.0	ns
t <sub>EABCH</sub>	1.5		2.0		2.5		ns
t <sub>EABCL</sub>	1.5		2.0		2.5	İ	ns

Additionally, the Altera software offers several features that help plan for future device migration by preventing the use of conflicting I/O pins.

Table 81. I/O Counts for FLEX 10KA & FLEX 10KE Devices						
FLEX 10	KA	FLEX 10KE				
Device	I/O Count	Device	I/O Count			
EPF10K30AF256	191	EPF10K30EF256	176			
EPF10K30AF484	246	EPF10K30EF484	220			
EPF10K50VB356	274	EPF10K50SB356	220			
EPF10K50VF484	291	EPF10K50EF484	254			
EPF10K50VF484	291	EPF10K50SF484	254			
EPF10K100AF484	369	EPF10K100EF484	338			

**Configuration Schemes** 

The configuration data for a FLEX 10KE device can be loaded with one of five configuration schemes (see Table 82), chosen on the basis of the target application. An EPC1, EPC2, or EPC16 configuration device, intelligent controller, or the JTAG port can be used to control the configuration of a FLEX 10KE device, allowing automatic configuration on system power-up.

Multiple FLEX 10KE devices can be configured in any of the five configuration schemes by connecting the configuration enable (nCE) and configuration enable output (nCEO) pins on each device. Additional FLEX 10K, FLEX 10KA, FLEX 10KE, and FLEX 6000 devices can be configured in the same serial chain.

Table 82. Data Sources for FLEX 10KE Configuration					
Configuration Scheme	Data Source				
Configuration device	EPC1, EPC2, or EPC16 configuration device				
Passive serial (PS)	BitBlaster, ByteBlasterMV, or MasterBlaster download cables, or serial data source				
Passive parallel asynchronous (PPA)	Parallel data source				
Passive parallel synchronous (PPS)	Parallel data source				
JTAG	BitBlaster or ByteBlasterMV download cables, or microprocessor with a Jam STAPL file or JBC file				