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### Understanding [Embedded - FPGAs \(Field Programmable Gate Array\)](#)

Embedded - FPGAs, or Field Programmable Gate Arrays, are advanced integrated circuits that offer unparalleled flexibility and performance for digital systems. Unlike traditional fixed-function logic devices, FPGAs can be programmed and reprogrammed to execute a wide array of logical operations, enabling customized functionality tailored to specific applications. This reprogrammability allows developers to iterate designs quickly and implement complex functions without the need for custom hardware.

### Applications of Embedded - FPGAs

The versatility of Embedded - FPGAs makes them indispensable in numerous fields. In telecommunications.

#### Details

Product Status	Obsolete
Number of LABs/CLBs	216
Number of Logic Elements/Cells	1728
Total RAM Bits	24576
Number of I/O	147
Number of Gates	119000
Voltage - Supply	2.375V ~ 2.625V
Mounting Type	Surface Mount
Operating Temperature	0°C ~ 70°C (TA)
Package / Case	208-BFQFP
Supplier Device Package	208-PQFP (28x28)
Purchase URL	<a href="https://www.e-xfl.com/product-detail/intel/epf10k30eqc208-1n">https://www.e-xfl.com/product-detail/intel/epf10k30eqc208-1n</a>

Table 2. FLEX 10KE Device Features

Feature	EPF10K100E (2)	EPF10K130E	EPF10K200E EPF10K200S
Typical gates (1)	100,000	130,000	200,000
Maximum system gates	257,000	342,000	513,000
Logic elements (LEs)	4,992	6,656	9,984
EABs	12	16	24
Total RAM bits	49,152	65,536	98,304
Maximum user I/O pins	338	413	470

**Note to tables:**

- (1) The embedded IEEE Std. 1149.1 JTAG circuitry adds up to 31,250 gates in addition to the listed typical or maximum system gates.
- (2) New EPF10K100B designs should use EPF10K100E devices.

## ...and More Features

- Fabricated on an advanced process and operate with a 2.5-V internal supply voltage
- In-circuit reconfigurability (ICR) via external configuration devices, intelligent controller, or JTAG port
- ClockLock™ and ClockBoost™ options for reduced clock delay/skew and clock multiplication
- Built-in low-skew clock distribution trees
- 100% functional testing of all devices; test vectors or scan chains are not required
- Pull-up on I/O pins before and during configuration
- Flexible interconnect
  - FastTrack® Interconnect continuous routing structure for fast, predictable interconnect delays
  - Dedicated carry chain that implements arithmetic functions such as fast adders, counters, and comparators (automatically used by software tools and megafunctions)
  - Dedicated cascade chain that implements high-speed, high-fan-in logic functions (automatically used by software tools and megafunctions)
  - Tri-state emulation that implements internal tri-state buses
  - Up to six global clock signals and four global clear signals
- Powerful I/O pins
  - Individual tri-state output enable control for each pin
  - Open-drain option on each I/O pin
  - Programmable output slew-rate control to reduce switching noise
  - Clamp to V<sub>CCIO</sub> user-selectable on a pin-by-pin basis
  - Supports hot-socketing

**Table 5. FLEX 10KE Performance**

Application	Resources Used		Performance			Units
	LEs	EABs	-1 Speed Grade	-2 Speed Grade	-3 Speed Grade	
16-bit loadable counter	16	0	285	250	200	MHz
16-bit accumulator	16	0	285	250	200	MHz
16-to-1 multiplexer (1)	10	0	3.5	4.9	7.0	ns
16-bit multiplier with 3-stage pipeline (2)	592	0	156	131	93	MHz
256 × 16 RAM read cycle speed (2)	0	1	196	154	118	MHz
256 × 16 RAM write cycle speed (2)	0	1	185	143	106	MHz

**Notes:**

- (1) This application uses combinatorial inputs and outputs.  
 (2) This application uses registered inputs and outputs.

Table 6 shows FLEX 10KE performance for more complex designs. These designs are available as Altera MegaCore® functions.

**Table 6. FLEX 10KE Performance for Complex Designs**

Application	LEs Used	Performance			Units
		-1 Speed Grade	-2 Speed Grade	-3 Speed Grade	
8-bit, 16-tap parallel finite impulse response (FIR) filter	597	192	156	116	MSPS
8-bit, 512-point fast Fourier transform (FFT) function	1,854	23.4	28.7	38.9	μs (1)
		113	92	68	MHz
a16450 universal asynchronous receiver/transmitter (UART)	342	36	28	20.5	MHz

**Note:**

- (1) These values are for calculation time. Calculation time = number of clocks required /  $f_{\max}$ . Number of clocks required = ceiling  $[\log_2 (\text{points})/2] \times [\text{points} + 14 + \text{ceiling}]$



For more information on FLEX device configuration, see the following documents:

- [\*Configuration Devices for APEX & FLEX Devices Data Sheet\*](#)
- [\*BitBlaster Serial Download Cable Data Sheet\*](#)
- [\*ByteBlasterMV Parallel Port Download Cable Data Sheet\*](#)
- [\*MasterBlaster Download Cable Data Sheet\*](#)
- [\*Application Note 116 \(Configuring APEX 20K, FLEX 10K, & FLEX 6000 Devices\)\*](#)

FLEX 10KE devices are supported by the Altera development systems, which are integrated packages that offer schematic, text (including AHDL), and waveform design entry, compilation and logic synthesis, full simulation and worst-case timing analysis, and device configuration. The Altera software provides EDIF 2 0 0 and 3 0 0, LPM, VHDL, Verilog HDL, and other interfaces for additional design entry and simulation support from other industry-standard PC- and UNIX workstation-based EDA tools.

The Altera software works easily with common gate array EDA tools for synthesis and simulation. For example, the Altera software can generate Verilog HDL files for simulation with tools such as Cadence Verilog-XL. Additionally, the Altera software contains EDA libraries that use device-specific features such as carry chains, which are used for fast counter and arithmetic functions. For instance, the Synopsys Design Compiler library supplied with the Altera development system includes DesignWare functions that are optimized for the FLEX 10KE architecture.

The Altera development system runs on Windows-based PCs and Sun SPARCstation, and HP 9000 Series 700/800.



See the [\*MAX+PLUS II Programmable Logic Development System & Software Data Sheet\*](#) and the [\*Quartus Programmable Logic Development System & Software Data Sheet\*](#) for more information.

## Functional Description

Each FLEX 10KE device contains an enhanced embedded array to implement memory and specialized logic functions, and a logic array to implement general logic.

The embedded array consists of a series of EABs. When implementing memory functions, each EAB provides 4,096 bits, which can be used to create RAM, ROM, dual-port RAM, or first-in first-out (FIFO) functions. When implementing logic, each EAB can contribute 100 to 600 gates towards complex logic functions, such as multipliers, microcontrollers, state machines, and DSP functions. EABs can be used independently, or multiple EABs can be combined to implement larger functions.

The logic array consists of logic array blocks (LABs). Each LAB contains eight LEs and a local interconnect. An LE consists of a four-input look-up table (LUT), a programmable flipflop, and dedicated signal paths for carry and cascade functions. The eight LEs can be used to create medium-sized blocks of logic—such as 8-bit counters, address decoders, or state machines—or combined across LABs to create larger logic blocks. Each LAB represents about 96 usable gates of logic.

Signal interconnections within FLEX 10KE devices (as well as to and from device pins) are provided by the FastTrack Interconnect routing structure, which is a series of fast, continuous row and column channels that run the entire length and width of the device.

Each I/O pin is fed by an I/O element (IOE) located at the end of each row and column of the FastTrack Interconnect routing structure. Each IOE contains a bidirectional I/O buffer and a flipflop that can be used as either an output or input register to feed input, output, or bidirectional signals. When used with a dedicated clock pin, these registers provide exceptional performance. As inputs, they provide setup times as low as 0.9 ns and hold times of 0 ns. As outputs, these registers provide clock-to-output times as low as 3.0 ns. IOEs provide a variety of features, such as JTAG BST support, slew-rate control, tri-state buffers, and open-drain outputs.

## Embedded Array Block

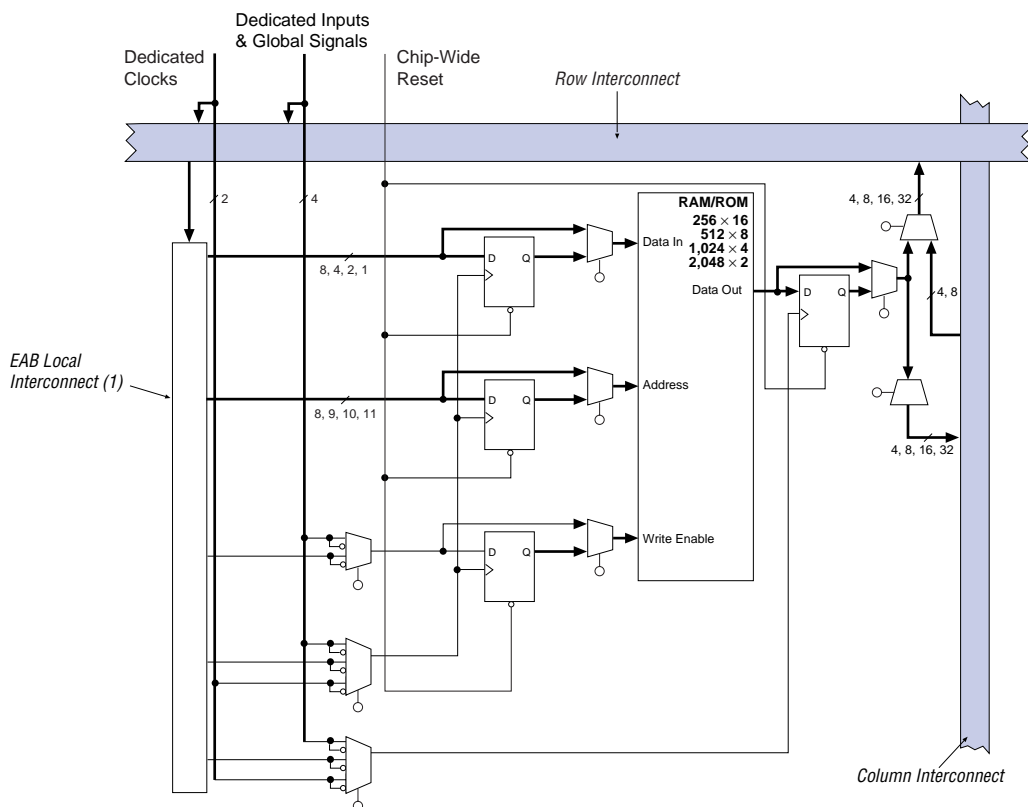
The EAB is a flexible block of RAM, with registers on the input and output ports, that is used to implement common gate array megafunctions. Because it is large and flexible, the EAB is suitable for functions such as multipliers, vector scalars, and error correction circuits. These functions can be combined in applications such as digital filters and microcontrollers.

Logic functions are implemented by programming the EAB with a read-only pattern during configuration, thereby creating a large LUT. With LUTs, combinatorial functions are implemented by looking up the results, rather than by computing them. This implementation of combinatorial functions can be faster than using algorithms implemented in general logic, a performance advantage that is further enhanced by the fast access times of EABs. The large capacity of EABs enables designers to implement complex functions in one logic level without the routing delays associated with linked LEs or field-programmable gate array (FPGA) RAM blocks. For example, a single EAB can implement any function with 8 inputs and 16 outputs. Parameterized functions such as LPM functions can take advantage of the EAB automatically.

The FLEX 10KE EAB provides advantages over FPGAs, which implement on-board RAM as arrays of small, distributed RAM blocks. These small FPGA RAM blocks must be connected together to make RAM blocks of manageable size. The RAM blocks are connected together using multiplexers implemented with more logic blocks. These extra multiplexers cause extra delay, which slows down the RAM block. FPGA RAM blocks are also prone to routing problems because small blocks of RAM must be connected together to make larger blocks. In contrast, EABs can be used to implement large, dedicated blocks of RAM that eliminate these timing and routing concerns.

The FLEX 10KE enhanced EAB adds dual-port capability to the existing EAB structure. The dual-port structure is ideal for FIFO buffers with one or two clocks. The FLEX 10KE EAB can also support up to 16-bit-wide RAM blocks and is backward-compatible with any design containing FLEX 10K EABs. The FLEX 10KE EAB can act in dual-port or single-port mode. When in dual-port mode, separate clocks may be used for EAB read and write sections, which allows the EAB to be written and read at different rates. It also has separate synchronous clock enable signals for the EAB read and write sections, which allow independent control of these sections.

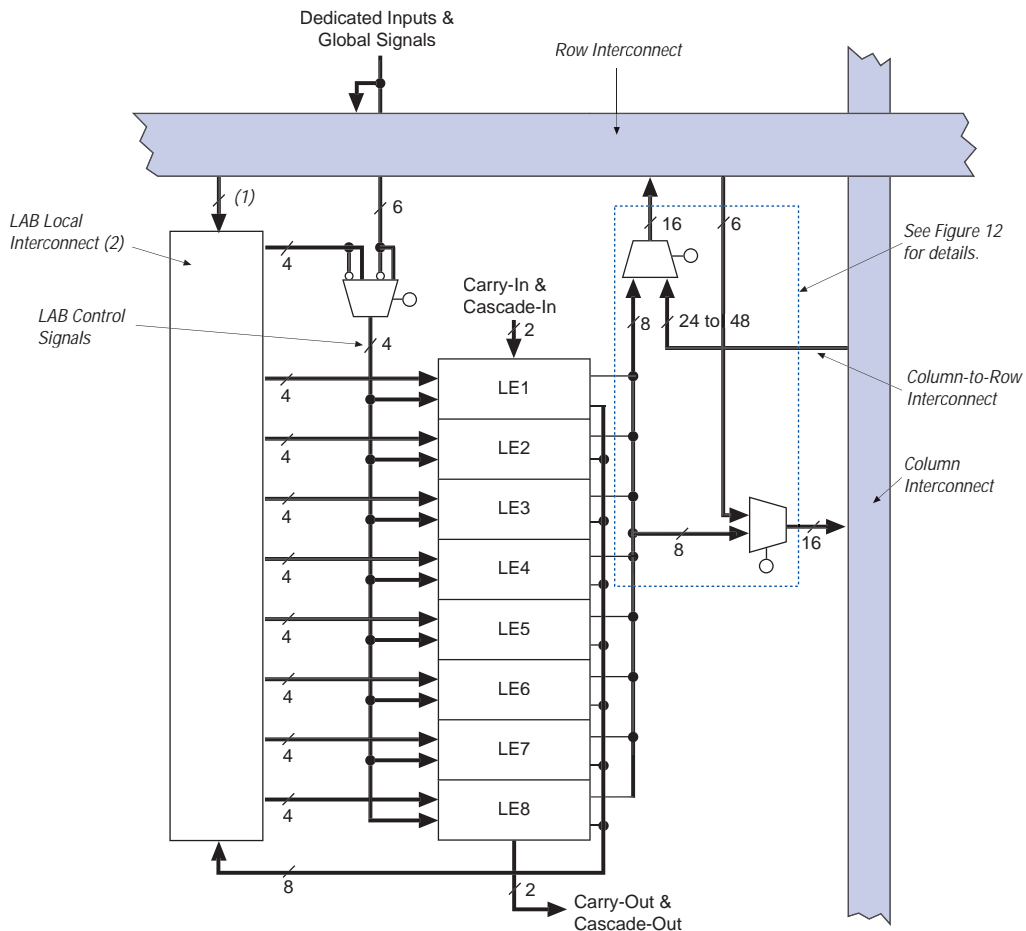
Figure 4. FLEX 10KE Device in Single-Port RAM Mode

**Note:**

- (1) EPF10K30E, EPF10K50E, and EPF10K50S devices have 88 EAB local interconnect channels; EPF10K100E, EPF10K130E, EPF10K200E, and EPF10K200S devices have 104 EAB local interconnect channels.

EABs can be used to implement synchronous RAM, which is easier to use than asynchronous RAM. A circuit using asynchronous RAM must generate the RAM write enable signal, while ensuring that its data and address signals meet setup and hold time specifications relative to the write enable signal. In contrast, the EAB's synchronous RAM generates its own write enable signal and is self-timed with respect to the input or write clock. A circuit using the EAB's self-timed RAM must only meet the setup and hold time specifications of the global clock.

Figure 7. FLEX 10KE LAB

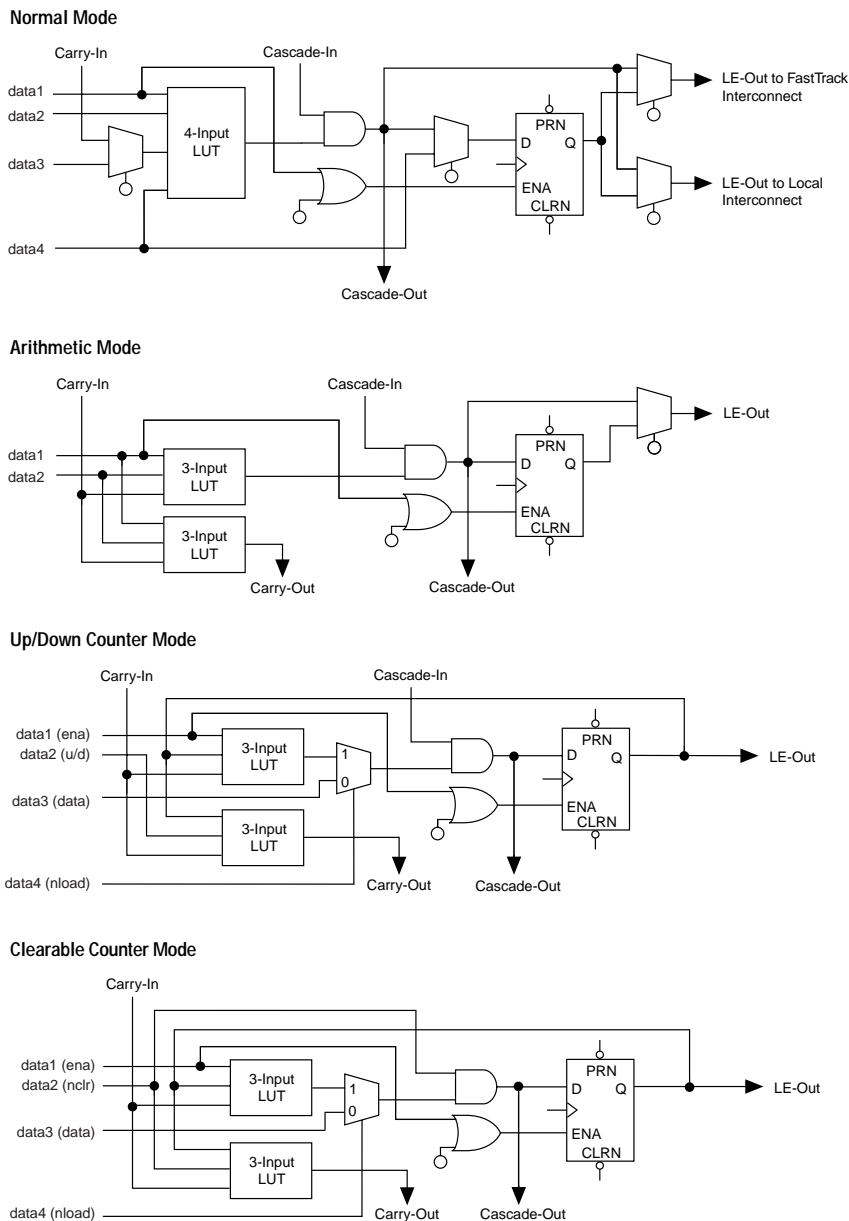


**Notes:**

- (1) EPF10K30E, EPF10K50E, and EPF10K50S devices have 22 inputs to the LAB local interconnect channel from the row; EPF10K100E, EPF10K130E, EPF10K200E, and EPF10K200S devices have 26.
- (2) EPF10K30E, EPF10K50E, and EPF10K50S devices have 30 LAB local interconnect channels; EPF10K100E, EPF10K130E, EPF10K200E, and EPF10K200S devices have 34.

Figure 11 shows the LE operating modes.

*Figure 11. FLEX 10KE LE Operating Modes*



## SameFrame Pin-Outs

FLEX 10KE devices support the SameFrame pin-out feature for FineLine BGA packages. The SameFrame pin-out feature is the arrangement of balls on FineLine BGA packages such that the lower-ball-count packages form a subset of the higher-ball-count packages. SameFrame pin-outs provide the flexibility to migrate not only from device to device within the same package, but also from one package to another. A given printed circuit board (PCB) layout can support multiple device density/package combinations. For example, a single board layout can support a range of devices from an EPF10K30E device in a 256-pin FineLine BGA package to an EPF10K200S device in a 672-pin FineLine BGA package.

The Altera software provides support to design PCBs with SameFrame pin-out devices. Devices can be defined for present and future use. The Altera software generates pin-outs describing how to lay out a board to take advantage of this migration (see [Figure 18](#)).

*Figure 18. SameFrame Pin-Out Example*

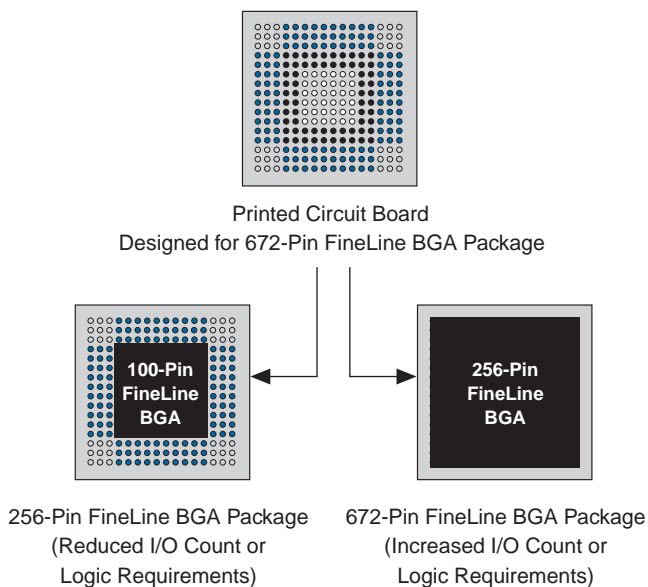


Figure 20 shows the timing requirements for the JTAG signals.

Figure 20. FLEX 10KE JTAG Waveforms

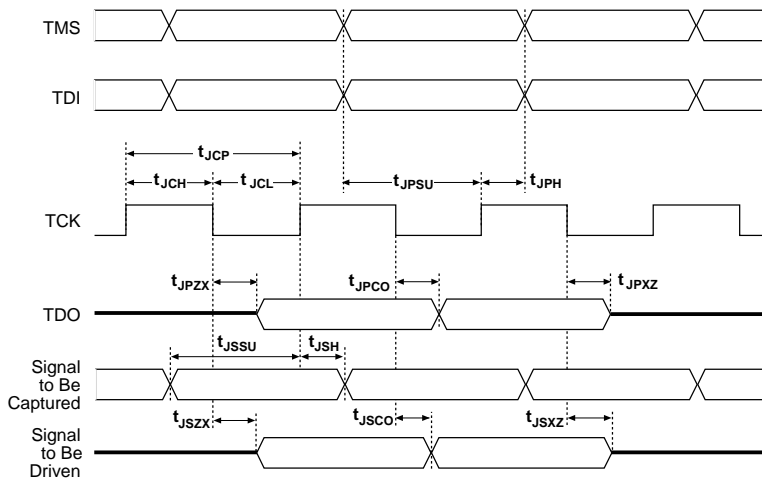


Table 18 shows the timing parameters and values for FLEX 10KE devices.

Table 18. FLEX 10KE JTAG Timing Parameters & Values

Symbol	Parameter	Min	Max	Unit
$t_{JCP}$	TCK clock period	100		ns
$t_{JCH}$	TCK clock high time	50		ns
$t_{JCL}$	TCK clock low time	50		ns
$t_{JPSU}$	JTAG port setup time	20		ns
$t_{JPH}$	JTAG port hold time	45		ns
$t_{JPCO}$	JTAG port clock to output		25	ns
$t_{JPZX}$	JTAG port high impedance to valid output		25	ns
$t_{JPXZ}$	JTAG port valid output to high impedance		25	ns
$t_{JSSU}$	Capture register setup time	20		ns
$t_{JSH}$	Capture register hold time	45		ns
$t_{JSCO}$	Update register clock to output		35	ns
$t_{JSZX}$	Update register high impedance to valid output		35	ns
$t_{JSXZ}$	Update register valid output to high impedance		35	ns

Table 31. EPF10K30E Device LE Timing Microparameters (Part 2 of 2) *Note (1)*

Symbol	-1 Speed Grade		-2 Speed Grade		-3 Speed Grade		Unit
	Min	Max	Min	Max	Min	Max	
$t_{CGENR}$		0.1		0.1		0.2	ns
$t_{CASC}$		0.6		0.8		1.0	ns
$t_C$		0.0		0.0		0.0	ns
$t_{CO}$		0.3		0.4		0.5	ns
$t_{COMB}$		0.4		0.4		0.6	ns
$t_{SU}$	0.4		0.6		0.6		ns
$t_H$	0.7		1.0		1.3		ns
$t_{PRE}$		0.8		0.9		1.2	ns
$t_{CLR}$		0.8		0.9		1.2	ns
$t_{CH}$	2.0		2.5		2.5		ns
$t_{CL}$	2.0		2.5		2.5		ns

Table 32. EPF10K30E Device IOE Timing Microparameters *Note (1)*

Symbol	-1 Speed Grade		-2 Speed Grade		-3 Speed Grade		Unit
	Min	Max	Min	Max	Min	Max	
$t_{IOD}$		2.4		2.8		3.8	ns
$t_{IOC}$		0.3		0.4		0.5	ns
$t_{IOCO}$		1.0		1.1		1.6	ns
$t_{IOCOMB}$		0.0		0.0		0.0	ns
$t_{IOSU}$	1.2		1.4		1.9		ns
$t_{IOH}$	0.3		0.4		0.5		ns
$t_{IOCLR}$		1.0		1.1		1.6	ns
$t_{OD1}$		1.9		2.3		3.0	ns
$t_{OD2}$		1.4		1.8		2.5	ns
$t_{OD3}$		4.4		5.2		7.0	ns
$t_{XZ}$		2.7		3.1		4.3	ns
$t_{ZX1}$		2.7		3.1		4.3	ns
$t_{ZX2}$		2.2		2.6		3.8	ns
$t_{ZX3}$		5.2		6.0		8.3	ns
$t_{INREG}$		3.4		4.1		5.5	ns
$t_{IOFD}$		0.8		1.3		2.4	ns
$t_{INCOMB}$		0.8		1.3		2.4	ns

Table 37. EPF10K30E External Bidirectional Timing Parameters *Notes (1), (2)*

Symbol	-1 Speed Grade		-2 Speed Grade		-3 Speed Grade		Unit
	Min	Max	Min	Max	Min	Max	
$t_{\text{INSUBIDIR}}$ (3)	2.8		3.9		5.2		ns
$t_{\text{INHBIDIR}}$ (3)	0.0		0.0		0.0		ns
$t_{\text{INSUBIDIR}}$ (4)	3.8		4.9		—		ns
$t_{\text{INHBIDIR}}$ (4)	0.0		0.0		—		ns
$t_{\text{OUTCOBIDIR}}$ (3)	2.0	4.9	2.0	5.9	2.0	7.6	ns
$t_{\text{XZBIDIR}}$ (3)		6.1		7.5		9.7	ns
$t_{\text{ZXBIDIR}}$ (3)		6.1		7.5		9.7	ns
$t_{\text{OUTCOBIDIR}}$ (4)	0.5	3.9	0.5	4.9	—	—	ns
$t_{\text{XZBIDIR}}$ (4)		5.1		6.5		—	ns
$t_{\text{ZXBIDIR}}$ (4)		5.1		6.5		—	ns

**Notes to tables:**

- (1) All timing parameters are described in Tables 24 through 30 in this data sheet.
- (2) These parameters are specified by characterization.
- (3) This parameter is measured without the use of the ClockLock or ClockBoost circuits.
- (4) This parameter is measured with the use of the ClockLock or ClockBoost circuits.

Tables 38 through 44 show EPF10K50E device internal and external timing parameters.

Table 38. EPF10K50E Device LE Timing Microparameters (Part 1 of 2) *Note (1)*

Symbol	-1 Speed Grade		-2 Speed Grade		-3 Speed Grade		Unit
	Min	Max	Min	Max	Min	Max	
$t_{\text{LUT}}$		0.6		0.9		1.3	ns
$t_{\text{CLUT}}$		0.5		0.6		0.8	ns
$t_{\text{RLUT}}$		0.7		0.8		1.1	ns
$t_{\text{PACKED}}$		0.4		0.5		0.6	ns
$t_{\text{EN}}$		0.6		0.7		0.9	ns
$t_{\text{CICO}}$		0.2		0.2		0.3	ns
$t_{\text{CGEN}}$		0.5		0.5		0.8	ns
$t_{\text{CGENR}}$		0.2		0.2		0.3	ns
$t_{\text{CASC}}$		0.8		1.0		1.4	ns
$t_{\text{C}}$		0.5		0.6		0.8	ns
$t_{\text{CO}}$		0.7		0.7		0.9	ns
$t_{\text{COMB}}$		0.5		0.6		0.8	ns
$t_{\text{SU}}$	0.7		0.7		0.8		ns

Table 38. EPF10K50E Device LE Timing Microparameters (Part 2 of 2) *Note (1)*

Symbol	-1 Speed Grade		-2 Speed Grade		-3 Speed Grade		Unit
	Min	Max	Min	Max	Min	Max	
$t_H$	0.9		1.0		1.4		ns
$t_{PRE}$		0.5		0.6		0.8	ns
$t_{CLR}$		0.5		0.6		0.8	ns
$t_{CH}$	2.0		2.5		3.0		ns
$t_{CL}$	2.0		2.5		3.0		ns

Table 39. EPF10K50E Device IOE Timing Microparameters *Note (1)*

Symbol	-1 Speed Grade		-2 Speed Grade		-3 Speed Grade		Unit
	Min	Max	Min	Max	Min	Max	
$t_{IOD}$		2.2		2.4		3.3	ns
$t_{IOC}$		0.3		0.3		0.5	ns
$t_{IOCO}$		1.0		1.0		1.4	ns
$t_{IOCOMB}$		0.0		0.0		0.2	ns
$t_{IOSU}$	1.0		1.2		1.7		ns
$t_{IOH}$	0.3		0.3		0.5		ns
$t_{IOCLR}$		0.9		1.0		1.4	ns
$t_{OD1}$		0.8		0.9		1.2	ns
$t_{OD2}$		0.3		0.4		0.7	ns
$t_{OD3}$		3.0		3.5		3.5	ns
$t_{XZ}$		1.4		1.7		2.3	ns
$t_{ZX1}$		1.4		1.7		2.3	ns
$t_{ZX2}$		0.9		1.2		1.8	ns
$t_{ZX3}$		3.6		4.3		4.6	ns
$t_{INREG}$		4.9		5.8		7.8	ns
$t_{IOFD}$		2.8		3.3		4.5	ns
$t_{INCOMB}$		2.8		3.3		4.5	ns

Table 48. EPF10K100E Device EAB Internal Timing Macroparameters (Part 2 of 2) *Note (1)*

Symbol	-1 Speed Grade		-2 Speed Grade		-3 Speed Grade		Unit
	Min	Max	Min	Max	Min	Max	
$t_{EABWCOMB}$	5.9		7.7		10.3		ns
$t_{EABWCREG}$	5.4		7.0		9.4		ns
$t_{EABDD}$		3.4		4.5		5.9	ns
$t_{EABDATACO}$		0.5		0.7		0.8	ns
$t_{EABDATASU}$	0.8		1.0		1.4		ns
$t_{EABDATAH}$	0.1		0.1		0.2		ns
$t_{EABWESU}$	1.1		1.4		1.9		ns
$t_{EABWEH}$	0.0		0.0		0.0		ns
$t_{EABWDSU}$	1.0		1.3		1.7		ns
$t_{EABWDH}$	0.2		0.2		0.3		ns
$t_{EABWASU}$	4.1		5.2		6.8		ns
$t_{EABWAH}$	0.0		0.0		0.0		ns
$t_{EABWO}$		3.4		4.5		5.9	ns

Table 49. EPF10K100E Device Interconnect Timing Microparameters *Note (1)*

Symbol	-1 Speed Grade		-2 Speed Grade		-3 Speed Grade		Unit
	Min	Max	Min	Max	Min	Max	
$t_{DIN2IOE}$		3.1		3.6		4.4	ns
$t_{DIN2LE}$		0.3		0.4		0.5	ns
$t_{DIN2DATA}$		1.6		1.8		2.0	ns
$t_{DCLK2IOE}$		0.8		1.1		1.4	ns
$t_{DCLK2LE}$		0.3		0.4		0.5	ns
$t_{SAMELAB}$		0.1		0.1		0.2	ns
$t_{SAMEROW}$		1.5		2.5		3.4	ns
$t_{SAMECOLUMN}$		0.4		1.0		1.6	ns
$t_{DIFFROW}$		1.9		3.5		5.0	ns
$t_{TROWROWS}$		3.4		6.0		8.4	ns
$t_{LEPERIPH}$		4.3		5.4		6.5	ns
$t_{LABCARRY}$		0.5		0.7		0.9	ns
$t_{LABCASC}$		0.8		1.0		1.4	ns

Tables 52 through 58 show EPF10K130E device internal and external timing parameters.

**Table 52. EPF10K130E Device LE Timing Microparameters** *Note (1)*

Symbol	-1 Speed Grade		-2 Speed Grade		-3 Speed Grade		Unit
	Min	Max	Min	Max	Min	Max	
$t_{LUT}$		0.6		0.9		1.3	ns
$t_{CLUT}$		0.6		0.8		1.0	ns
$t_{RLUT}$		0.7		0.9		0.2	ns
$t_{PACKED}$		0.3		0.5		0.6	ns
$t_{EN}$		0.2		0.3		0.4	ns
$t_{CICO}$		0.1		0.1		0.2	ns
$t_{CGEN}$		0.4		0.6		0.8	ns
$t_{CGENR}$		0.1		0.1		0.2	ns
$t_{CASC}$		0.6		0.9		1.2	ns
$t_C$		0.3		0.5		0.6	ns
$t_{CO}$		0.5		0.7		0.8	ns
$t_{COMB}$		0.3		0.5		0.6	ns
$t_{SU}$	0.5		0.7		0.8		ns
$t_H$	0.6		0.7		1.0		ns
$t_{PRE}$		0.9		1.2		1.6	ns
$t_{CLR}$		0.9		1.2		1.6	ns
$t_{CH}$	1.5		1.5		2.5		ns
$t_{CL}$	1.5		1.5		2.5		ns

**Table 53. EPF10K130E Device IOE Timing Microparameters** *Note (1)*

Symbol	-1 Speed Grade		-2 Speed Grade		-3 Speed Grade		Unit
	Min	Max	Min	Max	Min	Max	
$t_{IOD}$		1.3		1.5		2.0	ns
$t_{IOC}$		0.0		0.0		0.0	ns
$t_{IOCO}$		0.6		0.8		1.0	ns
$t_{IOCOMB}$		0.6		0.8		1.0	ns
$t_{IOSU}$	1.0		1.2		1.6		ns
$t_{IOH}$	0.9		0.9		1.4		ns
$t_{IOCLR}$		0.6		0.8		1.0	ns
$t_{OD1}$		2.8		4.1		5.5	ns
$t_{OD2}$		2.8		4.1		5.5	ns

Table 56. EPF10K130E Device Interconnect Timing Microparameters *Note (1)*

Symbol	-1 Speed Grade		-2 Speed Grade		-3 Speed Grade		Unit
	Min	Max	Min	Max	Min	Max	
$t_{DIN2IOE}$		2.8		3.5		4.4	ns
$t_{DIN2LE}$		0.7		1.2		1.6	ns
$t_{DIN2DATA}$		1.6		1.9		2.2	ns
$t_{DCLK2IOE}$		1.6		2.1		2.7	ns
$t_{DCLK2LE}$		0.7		1.2		1.6	ns
$t_{SAMELAB}$		0.1		0.2		0.2	ns
$t_{SAMEROW}$		1.9		3.4		5.1	ns
$t_{SAMECOLUMN}$		0.9		2.6		4.4	ns
$t_{DIFFROW}$		2.8		6.0		9.5	ns
$t_{TWOROWS}$		4.7		9.4		14.6	ns
$t_{LEPERIPH}$		3.1		4.7		6.9	ns
$t_{LABCARRY}$		0.6		0.8		1.0	ns
$t_{LABCASC}$		0.9		1.2		1.6	ns

Table 57. EPF10K130E External Timing Parameters *Notes (1), (2)*

Symbol	-1 Speed Grade		-2 Speed Grade		-3 Speed Grade		Unit
	Min	Max	Min	Max	Min	Max	
$t_{DRR}$		9.0		12.0		16.0	ns
$t_{INSU}$ (3)	1.9		2.1		3.0		ns
$t_{INH}$ (3)	0.0		0.0		0.0		ns
$t_{OUTCO}$ (3)	2.0	5.0	2.0	7.0	2.0	9.2	ns
$t_{INSU}$ (4)	0.9		1.1		—		ns
$t_{INH}$ (4)	0.0		0.0		—		ns
$t_{OUTCO}$ (4)	0.5	4.0	0.5	6.0	—	—	ns
$t_{PCISU}$	3.0		6.2		—		ns
$t_{PCIH}$	0.0		0.0		—		ns
$t_{PCICO}$	2.0	6.0	2.0	6.9	—	—	ns

Table 66. EPF10K50S Device LE Timing Microparameters (Part 2 of 2) *Note (1)*

Symbol	-1 Speed Grade		-2 Speed Grade		-3 Speed Grade		Unit
	Min	Max	Min	Max	Min	Max	
$t_{CGENR}$		0.1		0.1		0.1	ns
$t_{CASC}$		0.5		0.8		1.0	ns
$t_C$		0.5		0.6		0.8	ns
$t_{CO}$		0.6		0.6		0.7	ns
$t_{COMB}$		0.3		0.4		0.5	ns
$t_{SU}$	0.5		0.6		0.7		ns
$t_H$	0.5		0.6		0.8		ns
$t_{PRE}$		0.4		0.5		0.7	ns
$t_{CLR}$		0.8		1.0		1.2	ns
$t_{CH}$	2.0		2.5		3.0		ns
$t_{CL}$	2.0		2.5		3.0		ns

Table 67. EPF10K50S Device IOE Timing Microparameters *Note (1)*

Symbol	-1 Speed Grade		-2 Speed Grade		-3 Speed Grade		Unit
	Min	Max	Min	Max	Min	Max	
$t_{IOD}$		1.3		1.3		1.9	ns
$t_{IOC}$		0.3		0.4		0.4	ns
$t_{IOCO}$		1.7		2.1		2.6	ns
$t_{IOCOMB}$		0.5		0.6		0.8	ns
$t_{IOSU}$	0.8		1.0		1.3		ns
$t_{IOH}$	0.4		0.5		0.6		ns
$t_{IOCLR}$		0.2		0.2		0.4	ns
$t_{OD1}$		1.2		1.2		1.9	ns
$t_{OD2}$		0.7		0.8		1.7	ns
$t_{OD3}$		2.7		3.0		4.3	ns
$t_{XZ}$		4.7		5.7		7.5	ns
$t_{ZX1}$		4.7		5.7		7.5	ns
$t_{ZX2}$		4.2		5.3		7.3	ns
$t_{ZX3}$		6.2		7.5		9.9	ns
$t_{INREG}$		3.5		4.2		5.6	ns
$t_{IOFD}$		1.1		1.3		1.8	ns
$t_{INCOMB}$		1.1		1.3		1.8	ns

Table 68. EPF10K50S Device EAB Internal Microparameters *Note (1)*

Symbol	-1 Speed Grade		-2 Speed Grade		-3 Speed Grade		Unit
	Min	Max	Min	Max	Min	Max	
$t_{EABDATA1}$		1.7		2.4		3.2	ns
$t_{EABDATA2}$		0.4		0.6		0.8	ns
$t_{EABWE1}$		1.0		1.4		1.9	ns
$t_{EABWE2}$		0.0		0.0		0.0	ns
$t_{EABRE1}$		0.0		0.0		0.0	
$t_{EABRE2}$		0.4		0.6		0.8	
$t_{EABCLK}$		0.0		0.0		0.0	ns
$t_{EABCO}$		0.8		1.1		1.5	ns
$t_{EABYPASS}$		0.0		0.0		0.0	ns
$t_{EABSU}$	0.7		1.0		1.3		ns
$t_{EABH}$	0.4		0.6		0.8		ns
$t_{EABCLR}$	0.8		1.1		1.5		
$t_{AA}$		2.0		2.8		3.8	ns
$t_{WP}$	2.0		2.8		3.8		ns
$t_{RP}$	1.0		1.4		1.9		
$t_{WDSU}$	0.5		0.7		0.9		ns
$t_{WDH}$	0.1		0.1		0.2		ns
$t_{WASU}$	1.0		1.4		1.9		ns
$t_{WAH}$	1.5		2.1		2.9		ns
$t_{RASU}$	1.5		2.1		2.8		
$t_{RAH}$	0.1		0.1		0.2		
$t_{WO}$		2.1		2.9		4.0	ns
$t_{DD}$		2.1		2.9		4.0	ns
$t_{EABOUT}$		0.0		0.0		0.0	ns
$t_{EABCH}$	1.5		2.0		2.5		ns
$t_{EABCL}$	1.5		2.0		2.5		ns

Table 73. EPF10K200S Device Internal & External Timing Parameters

Note (1)

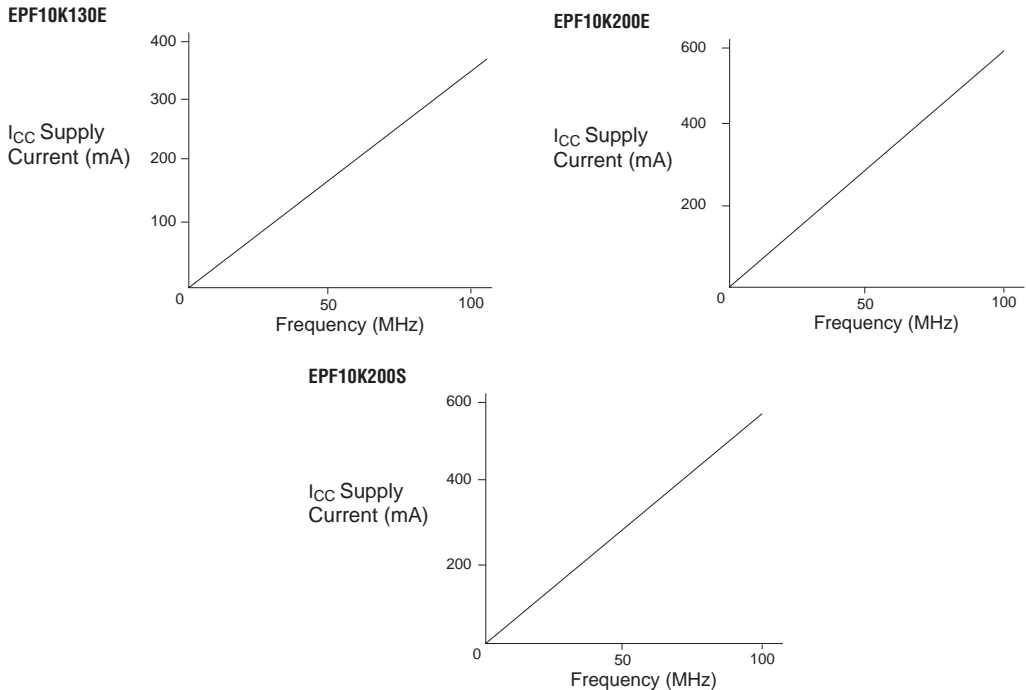
Symbol	-1 Speed Grade		-2 Speed Grade		-3 Speed Grade		Unit
	Min	Max	Min	Max	Min	Max	
$t_{LUT}$		0.7		0.8		1.2	ns
$t_{CLUT}$		0.4		0.5		0.6	ns
$t_{RLUT}$		0.5		0.7		0.9	ns
$t_{PACKED}$		0.4		0.5		0.7	ns
$t_{EN}$		0.6		0.5		0.6	ns
$t_{CICO}$		0.1		0.2		0.3	ns
$t_{CGEN}$		0.3		0.4		0.6	ns
$t_{CGENR}$		0.1		0.2		0.3	ns
$t_{CASC}$		0.7		0.8		1.2	ns
$t_C$		0.5		0.6		0.8	ns
$t_{CO}$		0.5		0.6		0.8	ns
$t_{COMB}$		0.3		0.6		0.8	ns
$t_{SU}$	0.4		0.6		0.7		ns
$t_H$	1.0		1.1		1.5		ns
$t_{PRE}$		0.4		0.6		0.8	ns
$t_{CLR}$		0.5		0.6		0.8	ns
$t_{CH}$	2.0		2.5		3.0		ns
$t_{CL}$	2.0		2.5		3.0		ns

Table 74. EPF10K200S Device IOE Timing Microparameters (Part 1 of 2)

Note (1)

Symbol	-1 Speed Grade		-2 Speed Grade		-3 Speed Grade		Unit
	Min	Max	Min	Max	Min	Max	
$t_{IOD}$		1.8		1.9		2.6	ns
$t_{IOC}$		0.3		0.3		0.5	ns
$t_{IOCO}$		1.7		1.9		2.6	ns
$t_{IOCOMB}$		0.5		0.6		0.8	ns
$t_{IOSU}$	0.8		0.9		1.2		ns
$t_{IOH}$	0.4		0.8		1.1		ns
$t_{IOCLR}$		0.2		0.2		0.3	ns
$t_{OD1}$		1.3		0.7		0.9	ns
$t_{OD2}$		0.8		0.2		0.4	ns
$t_{OD3}$		2.9		3.0		3.9	ns
$t_{XZ}$		5.0		5.3		7.1	ns
$t_{ZX1}$		5.0		5.3		7.1	ns

Figure 31. FLEX 10KE  $I_{CCACTIVE}$  vs. Operating Frequency (Part 2 of 2)



## Configuration & Operation

The FLEX 10KE architecture supports several configuration schemes. This section summarizes the device operating modes and available device configuration schemes.

### Operating Modes

The FLEX 10KE architecture uses SRAM configuration elements that require configuration data to be loaded every time the circuit powers up. The process of physically loading the SRAM data into the device is called *configuration*. Before configuration, as  $V_{CC}$  rises, the device initiates a Power-On Reset (POR). This POR event clears the device and prepares it for configuration. The FLEX 10KE POR time does not exceed 50  $\mu$ s.

When configuring with a configuration device, refer to the respective configuration device data sheet for POR timing information.