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"[Embedded - Microcontrollers](#)" refer to small, integrated circuits designed to perform specific tasks within larger systems. These microcontrollers are essentially compact computers on a single chip, containing a processor core, memory, and programmable input/output peripherals. They are called "embedded" because they are embedded within electronic devices to control various functions, rather than serving as standalone computers. Microcontrollers are crucial in modern electronics, providing the intelligence and control needed for a wide range of applications.

### Applications of "[Embedded - Microcontrollers](#)"

#### Details

Product Status	Active
Core Processor	PIC
Core Size	8-Bit
Speed	20MHz
Connectivity	-
Peripherals	Brown-out Detect/Reset, POR, PWM, WDT
Number of I/O	5
Program Memory Size	1.75KB (1K x 14)
Program Memory Type	FLASH
EEPROM Size	-
RAM Size	64 x 8
Voltage - Supply (Vcc/Vdd)	2.3V ~ 5.5V
Data Converters	A/D 4x10b
Oscillator Type	Internal
Operating Temperature	-40°C ~ 85°C (TA)
Mounting Type	Surface Mount
Package / Case	8-SOIC (0.154", 3.90mm Width)
Supplier Device Package	8-SOIC
Purchase URL	<a href="https://www.e-xfl.com/product-detail/microchip-technology/pic12f1501-i-sn">https://www.e-xfl.com/product-detail/microchip-technology/pic12f1501-i-sn</a>

# PIC12(L)F1501

## 5.3 Clock Switching

The system clock source can be switched between external and internal clock sources via software using the System Clock Select (SCS) bits of the OSCCON register. The following clock sources can be selected using the SCS bits:

- Default system oscillator determined by FOSC bits in Configuration Words
- Internal Oscillator Block (INTOSC)

### 5.3.1 SYSTEM CLOCK SELECT (SCS) BITS

The System Clock Select (SCS) bits of the OSCCON register selects the system clock source that is used for the CPU and peripherals.

- When the SCS bits of the OSCCON register = 00, the system clock source is determined by value of the FOSC<1:0> bits in the Configuration Words.
- When the SCS bits of the OSCCON register = 01, the system clock source is the secondary oscillator.
- When the SCS bits of the OSCCON register = 1x, the system clock source is chosen by the internal oscillator frequency selected by the IRCF<3:0>

bits of the OSCCON register. After a Reset, the SCS bits of the OSCCON register are always cleared.

When switching between clock sources, a delay is required to allow the new clock to stabilize. These oscillator delays are shown in Table 5-2.

### 5.3.2 CLOCK SWITCHING BEFORE SLEEP

When clock switching from an old clock to a new clock is requested just prior to entering Sleep mode, it is necessary to confirm that the switch is complete before the *SLEEP* instruction is executed. Failure to do so may result in an incomplete switch and consequential loss of the system clock altogether. Clock switching is confirmed by monitoring the clock status bits in the OSCSTAT register. Switch confirmation can be accomplished by sensing that the ready bit for the new clock is set or the ready bit for the old clock is cleared. For example, when switching between the internal oscillator with the PLL and the internal oscillator without the PLL, monitor the PLLR bit. When PLLR is set, the switch to 32 MHz operation is complete. Conversely, when PLLR is cleared, the switch from 32 MHz operation to the selected internal clock is complete.

**TABLE 5-2: OSCILLATOR SWITCHING DELAYS**

Switch From	Switch To	Oscillator Delay
Any clock source	LFINTOSC	1 cycle of each clock source
	HFINTOSC	2 $\mu$ s (approx.)
	ECH, ECM, ECL	2 cycles

## 8.0 POWER-DOWN MODE (SLEEP)

The Power-down mode is entered by executing a `SLEEP` instruction.

Upon entering Sleep mode, the following conditions exist:

1. WDT will be cleared but keeps running, if enabled for operation during Sleep.
2.  $\overline{\text{PD}}$  bit of the STATUS register is cleared.
3.  $\overline{\text{TO}}$  bit of the STATUS register is set.
4. CPU clock is disabled.
5. 31 kHz LFINTOSC is unaffected and peripherals that operate from it may continue operation in Sleep.
6. Timer1 and peripherals that operate from Timer1 continue operation in Sleep when the Timer1 clock source selected is:
  - LFINTOSC
  - T1CKI
7. ADC is unaffected, if the dedicated FRC oscillator is selected.
8. I/O ports maintain the status they had before `SLEEP` was executed (driving high, low or high-impedance).
9. Resets other than WDT are not affected by Sleep mode.

Refer to individual chapters for more details on peripheral operation during Sleep.

To minimize current consumption, the following conditions should be considered:

- I/O pins should not be floating
- External circuitry sinking current from I/O pins
- Internal circuitry sourcing current from I/O pins
- Current draw from pins with internal weak pull-ups
- Modules using 31 kHz LFINTOSC
- CWG, NCO and CLC modules using HFINTOSC

I/O pins that are high-impedance inputs should be pulled to VDD or VSS externally to avoid switching currents caused by floating inputs.

Examples of internal circuitry that might be sourcing current include the FVR module. See **Section 13.0 “Fixed Voltage Reference (FVR)”** for more information on this module.

### 8.1 Wake-up from Sleep

The device can wake-up from Sleep through one of the following events:

1. External Reset input on  $\overline{\text{MCLR}}$  pin, if enabled
2. BOR Reset, if enabled
3. POR Reset
4. Watchdog Timer, if enabled
5. Any external interrupt
6. Interrupts by peripherals capable of running during Sleep (see individual peripheral for more information)

The first three events will cause a device Reset. The last three events are considered a continuation of program execution. To determine whether a device Reset or wake-up event occurred, refer to **Section 6.12 “Determining the Cause of a Reset”**.

When the `SLEEP` instruction is being executed, the next instruction ( $\text{PC} + 1$ ) is prefetched. For the device to wake-up through an interrupt event, the corresponding interrupt enable bit must be enabled. Wake-up will occur regardless of the state of the GIE bit. If the GIE bit is disabled, the device continues execution at the instruction after the `SLEEP` instruction. If the GIE bit is enabled, the device executes the instruction after the `SLEEP` instruction, the device will then call the Interrupt Service Routine. In cases where the execution of the instruction following `SLEEP` is not desirable, the user should have a `NOP` after the `SLEEP` instruction.

The WDT is cleared when the device wakes up from Sleep, regardless of the source of wake-up.

#### 8.1.1 WAKE-UP USING INTERRUPTS

When global interrupts are disabled (GIE cleared) and any interrupt source has both its interrupt enable bit and interrupt flag bit set, one of the following will occur:

- If the interrupt occurs **before** the execution of a `SLEEP` instruction
  - `SLEEP` instruction will execute as a `NOP`.
  - WDT and WDT prescaler will not be cleared
  - $\overline{\text{TO}}$  bit of the STATUS register will not be set
  - $\overline{\text{PD}}$  bit of the STATUS register will not be cleared.
- If the interrupt occurs **during or after** the execution of a `SLEEP` instruction
  - `SLEEP` instruction will be completely executed
  - Device will immediately wake-up from Sleep
  - WDT and WDT prescaler will be cleared
  - $\overline{\text{TO}}$  bit of the STATUS register will be set
  - $\overline{\text{PD}}$  bit of the STATUS register will be cleared

Even if the flag bits were checked before executing a `SLEEP` instruction, it may be possible for flag bits to become set before the `SLEEP` instruction completes. To determine whether a `SLEEP` instruction executed, test the  $\overline{\text{PD}}$  bit. If the  $\overline{\text{PD}}$  bit is set, the `SLEEP` instruction was executed as a `NOP`.

## 17.2.5 COMPARATOR OUTPUT POLARITY

Inverting the output of the comparator is functionally equivalent to swapping the comparator inputs. The polarity of the comparator output can be inverted by setting the CxPOL bit of the CMxCON0 register. Clearing the CxPOL bit results in a non-inverted output.

Table 17-2 shows the output state versus input conditions, including polarity control.

**TABLE 17-2: COMPARATOR OUTPUT STATE VS. INPUT CONDITIONS**

Input Condition	CxPOL	CxOUT
$CxVN > CxVP$	0	0
$CxVN < CxVP$	0	1
$CxVN > CxVP$	1	1
$CxVN < CxVP$	1	0

## 17.2.6 COMPARATOR SPEED/POWER SELECTION

The trade-off between speed or power can be optimized during program execution with the CxSP control bit. The default state for this bit is '1' which selects the Normal-Speed mode. Device power consumption can be optimized at the cost of slower comparator propagation delay by clearing the CxSP bit to '0'.

## 17.3 Analog Input Connection Considerations

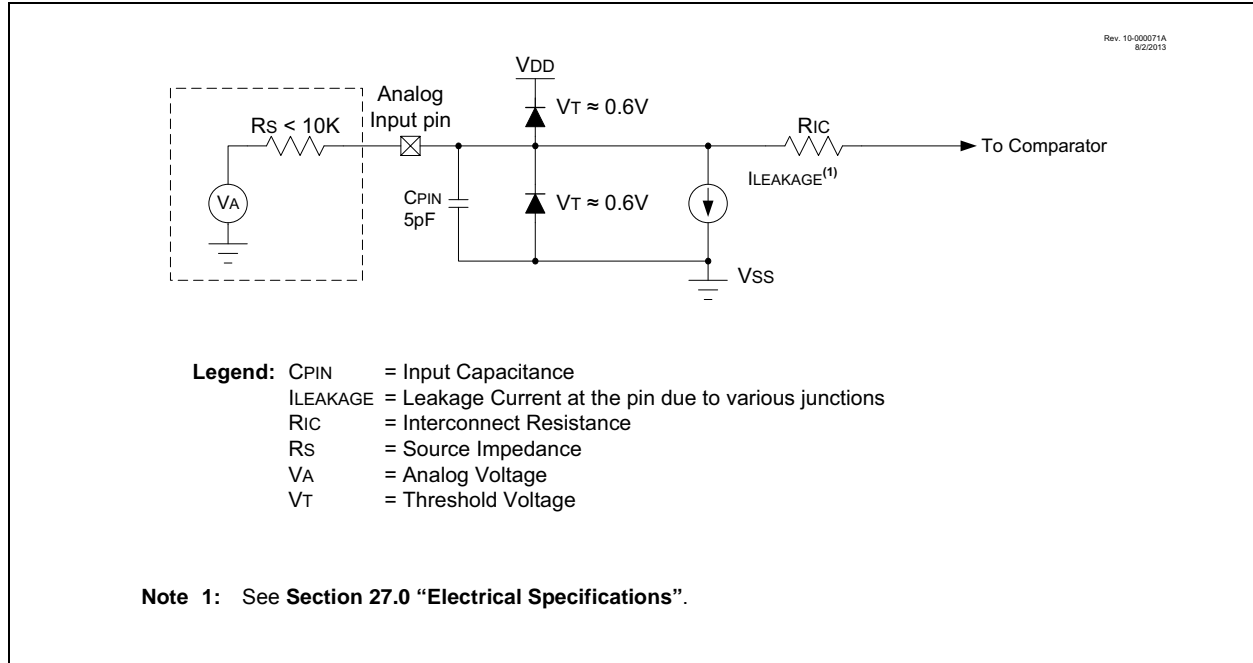
A simplified circuit for an analog input is shown in Figure 17-3. Since the analog input pins share their connection with a digital input, they have reverse biased ESD protection diodes to VDD and VSS. The analog input, therefore, must be between VSS and VDD. If the input voltage deviates from this range by more than 0.6V in either direction, one of the diodes is forward biased and a latch-up may occur.

A maximum source impedance of 10 kΩ is recommended for the analog sources. Also, any external component connected to an analog input pin, such as a capacitor or a Zener diode, should have very little leakage current to minimize inaccuracies introduced.

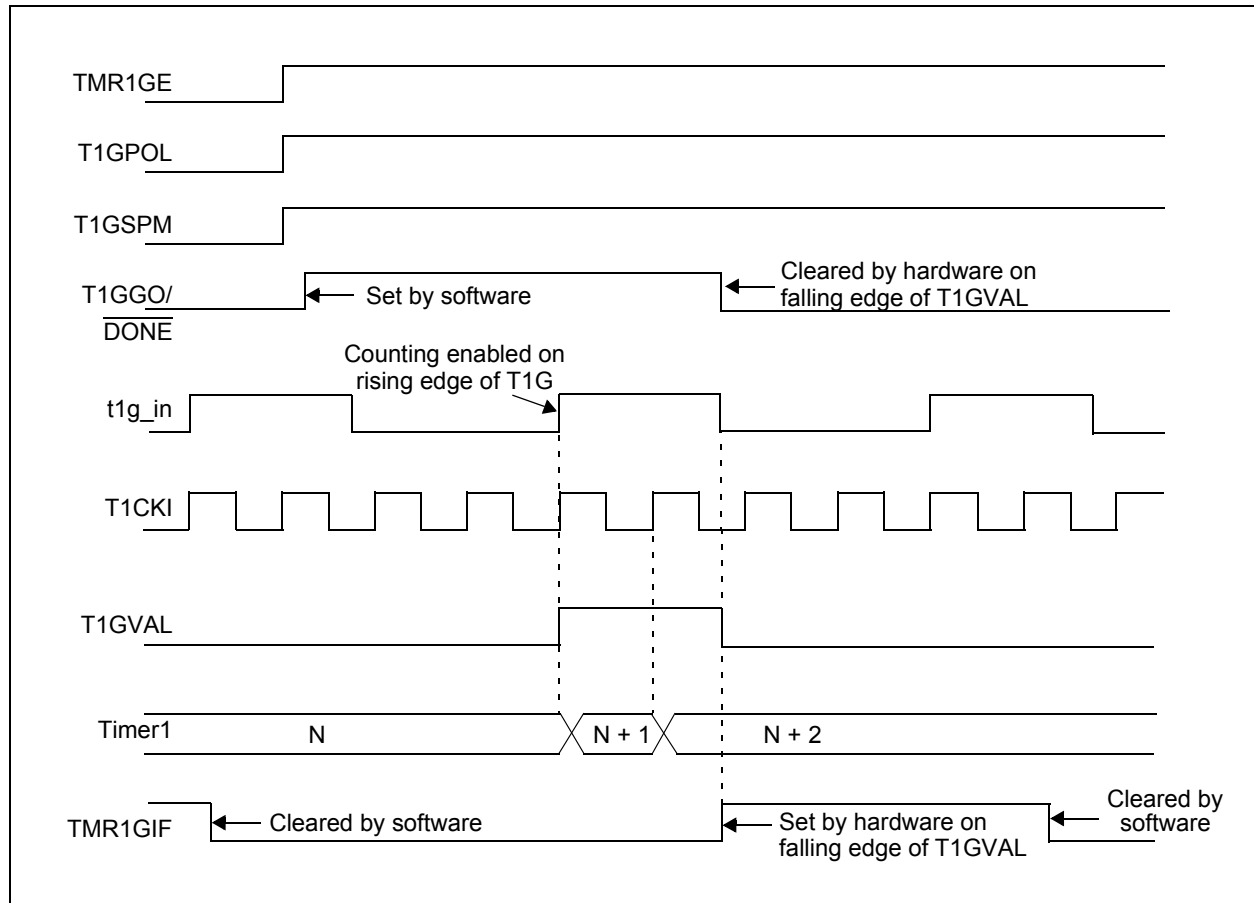
**Note 1:** When reading a PORT register, all pins configured as analog inputs will read as a '0'. Pins configured as digital inputs will convert as an analog input, according to the input specification.

**2:** Analog levels on any pin defined as a digital input, may cause the input buffer to consume more current than is specified.

**FIGURE 17-3: ANALOG INPUT MODEL**



**FIGURE 19-5: TIMER1 GATE SINGLE-PULSE MODE**



## 21.0 PULSE-WIDTH MODULATION (PWM) MODULE

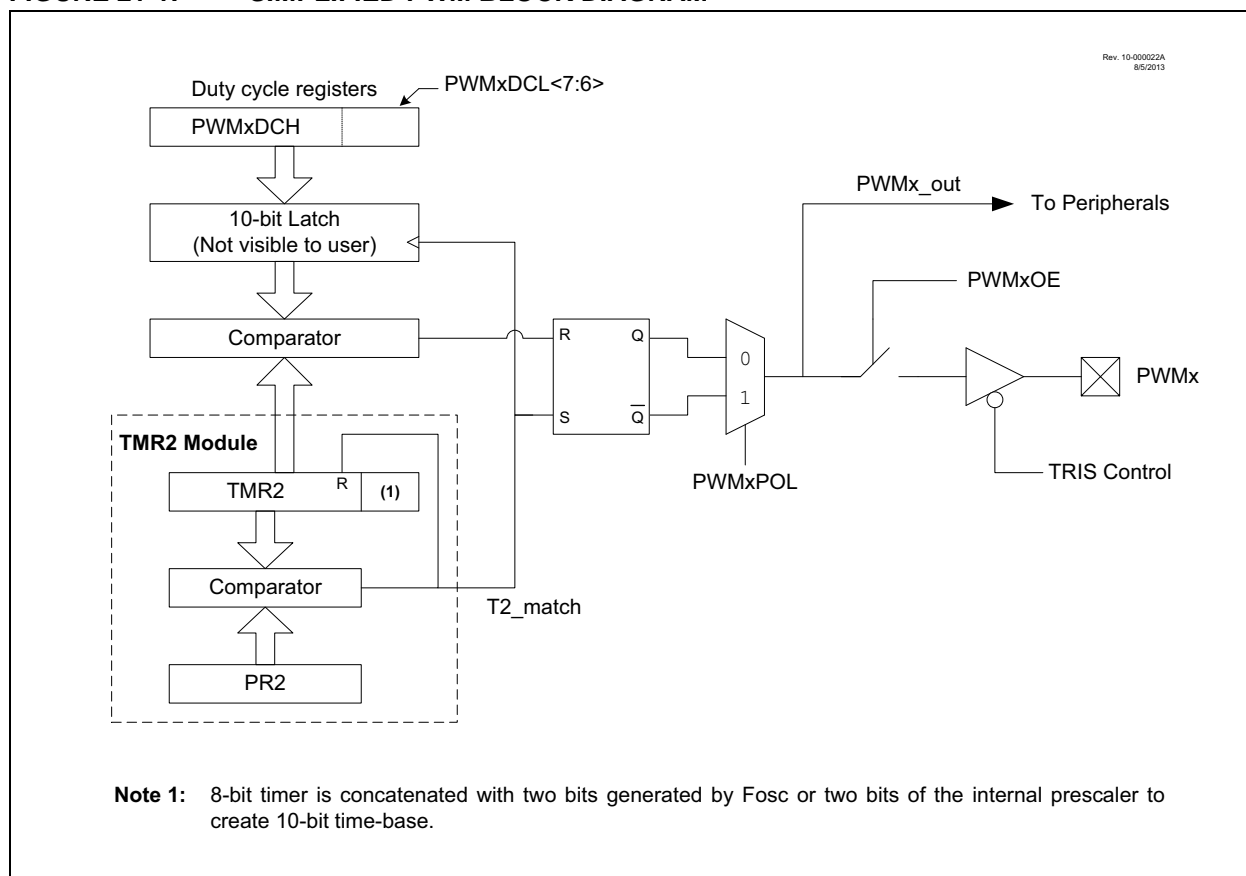
The PWM module generates a Pulse-Width Modulated signal determined by the duty cycle, period, and resolution that are configured by the following registers:

- PR2
- T2CON
- PWMxDCH
- PWMxDCL
- PWMxCON

Figure 21-1 shows a simplified block diagram of PWM operation.

For a step-by-step procedure on how to set up this module for PWM operation, refer to **Section 21.1.9 “Setup for PWM Operation using PWMx Pins”**.

**FIGURE 21-1: SIMPLIFIED PWM BLOCK DIAGRAM**



## 22.6 Register Definitions: CLC Control

**REGISTER 22-1: CLCxCON: CONFIGURABLE LOGIC CELL CONTROL REGISTER**

R/W-0/0		R/W-0/0		R-0/0		R/W-0/0		R/W-0/0		R/W-0/0		R/W-0/0		R/W-0/0		R/W-0/0	
LCxEN		LCxOE		LCxOUT		LCxINTP		LCxINTN		LCxMODE<2:0>							
bit 7																bit 0	

**Legend:**

R = Readable bit	W = Writable bit	U = Unimplemented bit, read as '0'
u = Bit is unchanged	x = Bit is unknown	-n/n = Value at POR and BOR/Value at all other Resets
'1' = Bit is set	'0' = Bit is cleared	

bit 7	<b>LCxEN:</b> Configurable Logic Cell Enable bit 1 = Configurable logic cell is enabled and mixing input signals 0 = Configurable logic cell is disabled and has logic zero output
bit 6	<b>LCxOE:</b> Configurable Logic Cell Output Enable bit 1 = Configurable logic cell port pin output enabled 0 = Configurable logic cell port pin output disabled
bit 5	<b>LCxOUT:</b> Configurable Logic Cell Data Output bit Read-only: logic cell output data, after LCxPOL; sampled from lcx_out wire.
bit 4	<b>LCxINTP:</b> Configurable Logic Cell Positive Edge Going Interrupt Enable bit 1 = CLCxIF will be set when a rising edge occurs on lcx_out 0 = CLCxIF will not be set
bit 3	<b>LCxINTN:</b> Configurable Logic Cell Negative Edge Going Interrupt Enable bit 1 = CLCxIF will be set when a falling edge occurs on lcx_out 0 = CLCxIF will not be set
bit 2-0	<b>LCxMODE&lt;2:0&gt;:</b> Configurable Logic Cell Functional Mode bits 111 = Cell is 1-input transparent latch with S and R 110 = Cell is J-K flip-flop with R 101 = Cell is 2-input D flip-flop with R 100 = Cell is 1-input D flip-flop with S and R 011 = Cell is S-R latch 010 = Cell is 4-input AND 001 = Cell is OR-XOR 000 = Cell is AND-OR

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## REGISTER 22-8: CLCxGLS3: GATE 4 LOGIC SELECT REGISTER

R/W-x/u	R/W-x/u	R/W-x/u	R/W-x/u	R/W-x/u	R/W-x/u	R/W-x/u	R/W-x/u
LCxG4D4T	LCxG4D4N	LCxG4D3T	LCxG4D3N	LCxG4D2T	LCxG4D2N	LCxG4D1T	LCxG4D1N
bit 7							bit 0

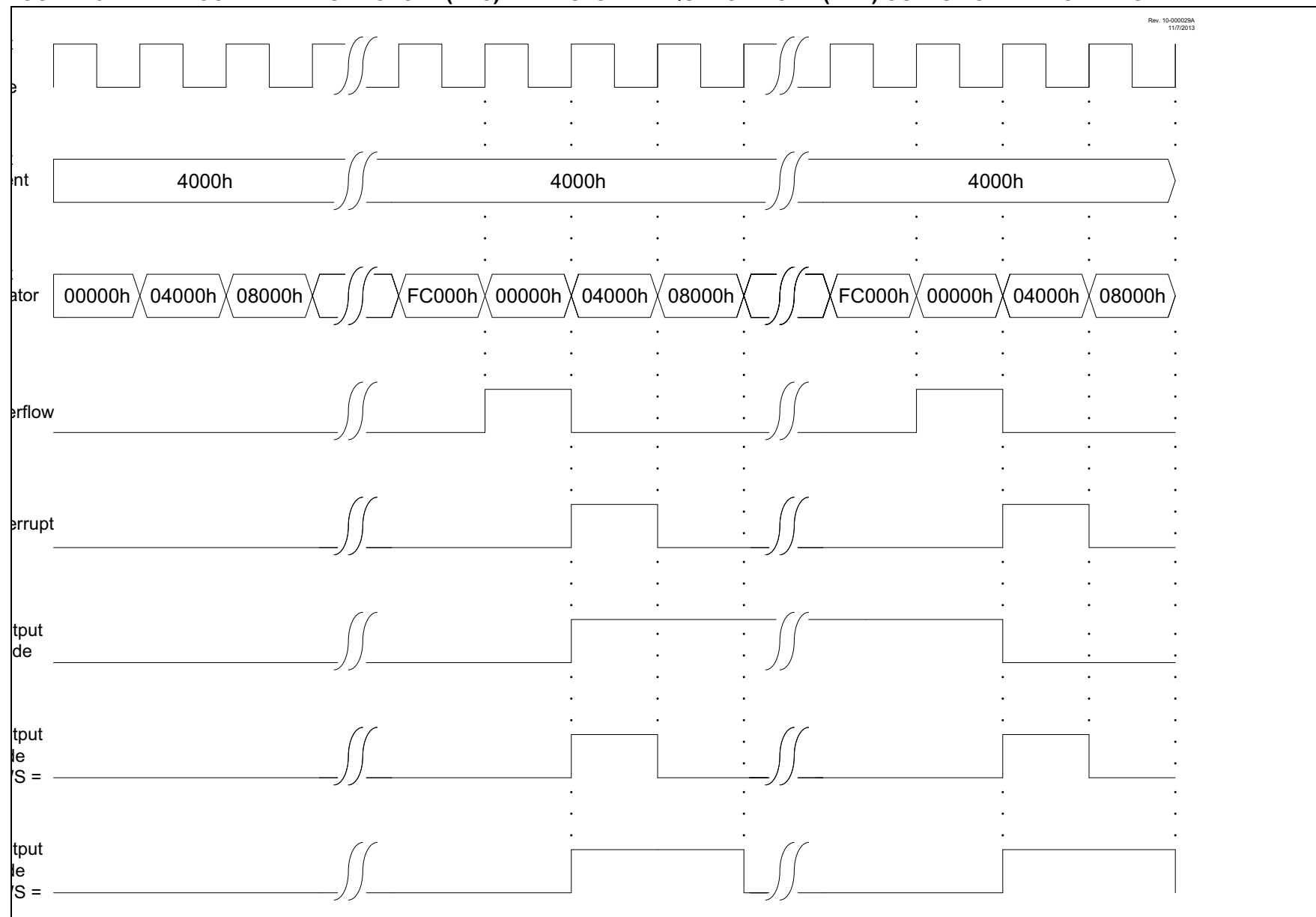
### Legend:

R = Readable bit	W = Writable bit	U = Unimplemented bit, read as '0'
u = Bit is unchanged	x = Bit is unknown	-n/n = Value at POR and BOR/Value at all other Resets
'1' = Bit is set	'0' = Bit is cleared	

bit 7	<b>LCxG4D4T:</b> Gate 4 Data 4 True (non-inverted) bit 1 = lcx4T is gated into lcxg4 0 = lcx4T is not gated into lcxg4
bit 6	<b>LCxG4D4N:</b> Gate 4 Data 4 Negated (inverted) bit 1 = lcx4N is gated into lcxg4 0 = lcx4N is not gated into lcxg4
bit 5	<b>LCxG4D3T:</b> Gate 4 Data 3 True (non-inverted) bit 1 = lcx3T is gated into lcxg4 0 = lcx3T is not gated into lcxg4
bit 4	<b>LCxG4D3N:</b> Gate 4 Data 3 Negated (inverted) bit 1 = lcx3N is gated into lcxg4 0 = lcx3N is not gated into lcxg4
bit 3	<b>LCxG4D2T:</b> Gate 4 Data 2 True (non-inverted) bit 1 = lcx2T is gated into lcxg4 0 = lcx2T is not gated into lcxg4
bit 2	<b>LCxG4D2N:</b> Gate 4 Data 2 Negated (inverted) bit 1 = lcx2N is gated into lcxg4 0 = lcx2N is not gated into lcxg4
bit 1	<b>LCxG4D1T:</b> Gate 4 Data 1 True (non-inverted) bit 1 = lcx1T is gated into lcxg4 0 = lcx1T is not gated into lcxg4
bit 0	<b>LCxG4D1N:</b> Gate 4 Data 1 Negated (inverted) bit 1 = lcx1N is gated into lcxg4 0 = lcx1N is not gated into lcxg4



**FIGURE 23-2: NCO – FIXED DUTY CYCLE (FDC) AND PULSE FREQUENCY MODE (PFM) OUTPUT OPERATION DIAGRAM**



## 23.9 Register Definitions: NCOx Control Registers

### REGISTER 23-1: NCOxCON: NCOx CONTROL REGISTER

R/W-0/0	R/W-0/0	R-0/0	R/W-0/0	U-0	U-0	U-0	R/W-0/0
NxEN	NxOE	NxOUT	NxPOL	—	—	—	NxPFM
bit 7							bit 0

#### Legend:

R = Readable bit	W = Writable bit	U = Unimplemented bit, read as '0'
u = Bit is unchanged	x = Bit is unknown	-n/n = Value at POR and BOR/Value at all other Resets
'1' = Bit is set	'0' = Bit is cleared	

bit 7	<b>NxEN:</b> NCOx Enable bit 1 = NCOx module is enabled 0 = NCOx module is disabled
bit 6	<b>NxOE:</b> NCOx Output Enable bit 1 = NCOx output pin is enabled 0 = NCOx output pin is disabled
bit 5	<b>NxOUT:</b> NCOx Output bit 1 = NCOx output is high 0 = NCOx output is low
bit 4	<b>NxPOL:</b> NCOx Polarity bit 1 = NCOx output signal is active low (inverted) 0 = NCOx output signal is active high (non-inverted)
bit 3-1	<b>Unimplemented:</b> Read as '0'
bit 0	<b>NxPFM:</b> NCOx Pulse Frequency Mode bit 1 = NCOx operates in Pulse Frequency mode 0 = NCOx operates in Fixed Duty Cycle mode

### REGISTER 23-2: NCOxCLK: NCOx INPUT CLOCK CONTROL REGISTER

R/W-0/0	R/W-0/0	R/W-0/0	U-0	U-0	U-0	R/W-0/0	R/W-0/0
NxPWS<2:0> <sup>(1, 2)</sup>			—	—	—	NxCKS<1:0>	
bit 7							bit 0

#### Legend:

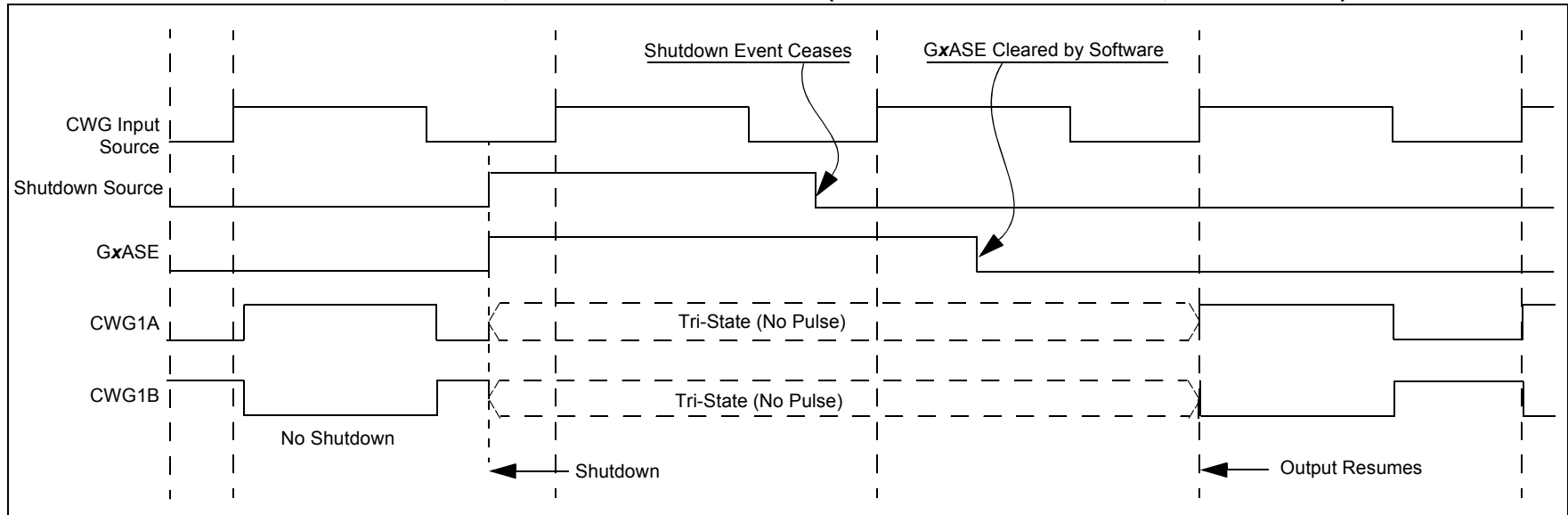
R = Readable bit	W = Writable bit	U = Unimplemented bit, read as '0'
u = Bit is unchanged	x = Bit is unknown	-n/n = Value at POR and BOR/Value at all other Resets
'1' = Bit is set	'0' = Bit is cleared	

bit 7-5	<b>NxPWS&lt;2:0&gt;:</b> NCOx Output Pulse Width Select bits <sup>(1, 2)</sup> 111 = 128 NCOx clock periods 110 = 64 NCOx clock periods 101 = 32 NCOx clock periods 100 = 16 NCOx clock periods 011 = 8 NCOx clock periods 010 = 4 NCOx clock periods 001 = 2 NCOx clock periods 000 = 1 NCOx clock periods
bit 4-2	<b>Unimplemented:</b> Read as '0'
bit 1-0	<b>NxCKS&lt;1:0&gt;:</b> NCOx Clock Source Select bits 11 = NCO1CLK pin 10 = LC1_out 01 = Fosc 00 = HFINTOSC (16 MHz)

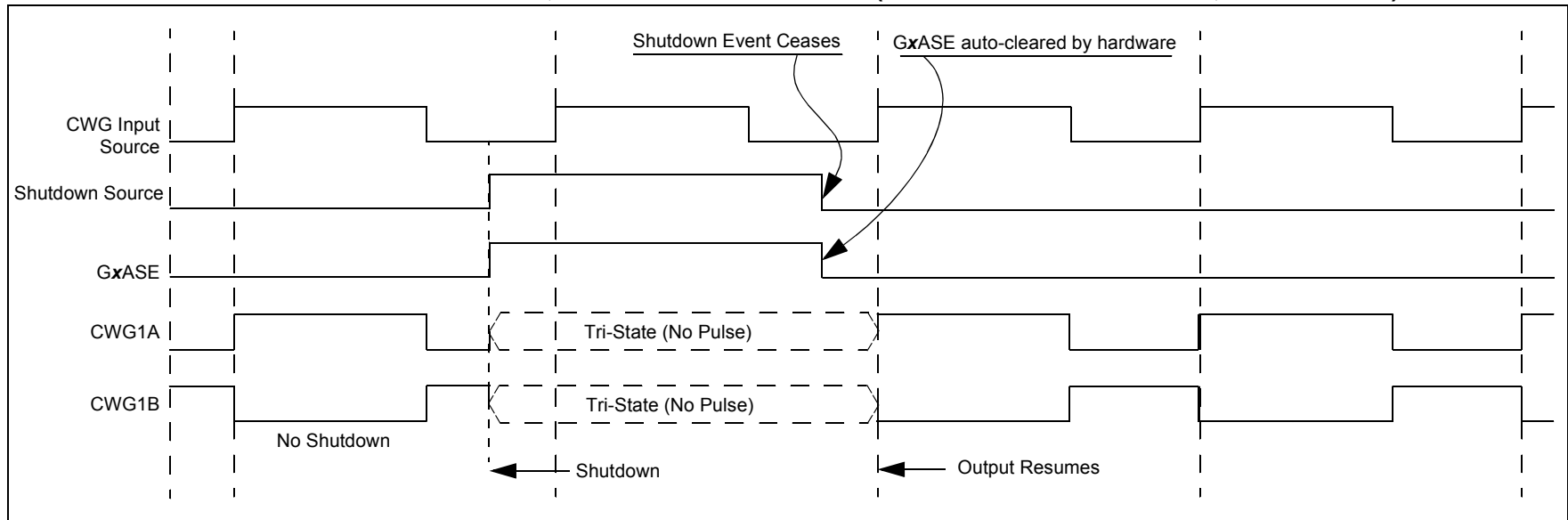
**Note 1:** NxPWS applies only when operating in Pulse Frequency mode.

**Note 2:** If NCOx pulse width is greater than NCO\_overflow period, operation is indeterminate.

**FIGURE 24-5: SHUTDOWN FUNCTIONALITY, AUTO-RESTART DISABLED (GxARSEN = 0, GxASDLA = 01, GxASDLB = 01)**



**FIGURE 24-6: SHUTDOWN FUNCTIONALITY, AUTO-RESTART ENABLED (GxARSEN = 1, GxASDLA = 01, GxASDLB = 01)**



**TABLE 24-2: SUMMARY OF REGISTERS ASSOCIATED WITH CWG**

Name	Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0	Register on Page
ANSELA	—	—	—	ANSA4	—	ANSA2	ANSA1	ANSA0	99
CWG1CON0	G1EN	G1OEB	G1OEA	G1POLB	G1POLA	—	—	G1CS0	187
CWG1CON1	G1ASDLB<1:0>		G1ASDLA<1:0>		—	—	G1IS<1:0>		188
CWG1CON2	G1ASE	G1ARSEN	—	—	—	G1ASDSC1	G1ASDSFLT	G1ASDSCLC2	189
CWG1DBF	—	—	CWG1DBF<5:0>						190
CWG1DBR	—	—	CWG1DBR<5:0>						190
TRISA	—	—	TRISA5	TRISA4	— <sup>(1)</sup>	TRISA2	TRISA1	TRISA0	98

**Legend:** x = unknown, u = unchanged, — = unimplemented locations read as '0'. Shaded cells are not used by CWG.

**Note 1:** Unimplemented, read as '1'.

## 26.0 INSTRUCTION SET SUMMARY

Each instruction is a 14-bit word containing the operation code (opcode) and all required operands. The opcodes are broken into three broad categories.

- Byte Oriented
- Bit Oriented
- Literal and Control

The literal and control category contains the most varied instruction word format.

Table 26-3 lists the instructions recognized by the MPASM™ assembler.

All instructions are executed within a single instruction cycle, with the following exceptions, which may take two or three cycles:

- Subroutine takes two cycles (CALL, CALLW)
- Returns from interrupts or subroutines take two cycles (RETURN, RETLW, RETFIE)
- Program branching takes two cycles (GOTO, BRA, BRW, BTFSS, BTFSC, DECFSZ, INCSFZ)
- One additional instruction cycle will be used when any instruction references an indirect file register and the file select register is pointing to program memory.

One instruction cycle consists of 4 oscillator cycles; for an oscillator frequency of 4 MHz, this gives a nominal instruction execution rate of 1 MHz.

All instruction examples use the format '0xhh' to represent a hexadecimal number, where 'h' signifies a hexadecimal digit.

## 26.1 Read-Modify-Write Operations

Any instruction that specifies a file register as part of the instruction performs a Read-Modify-Write (R-M-W) operation. The register is read, the data is modified, and the result is stored according to either the instruction, or the destination designator 'd'. A read operation is performed on a register even if the instruction writes to that register.

**TABLE 26-1: OPCODE FIELD DESCRIPTIONS**

Field	Description
f	Register file address (0x00 to 0x7F)
W	Working register (accumulator)
b	Bit address within an 8-bit file register
k	Literal field, constant data or label
x	Don't care location (= 0 or 1). The assembler will generate code with x = 0. It is the recommended form of use for compatibility with all Microchip software tools.
d	Destination select; d = 0: store result in W, d = 1: store result in file register f. Default is d = 1.
n	FSR or INDF number. (0-1)
mm	Pre-post increment-decrement mode selection

**TABLE 26-2: ABBREVIATION DESCRIPTIONS**

Field	Description
PC	Program Counter
$\overline{TO}$	Time-Out bit
C	Carry bit
DC	Digit Carry bit
Z	Zero bit
$\overline{PD}$	Power-Down bit

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## 26.2 Instruction Descriptions

### ADDFSR Add Literal to FSRn

**Syntax:** [ *label* ] ADDFSR FSRn, k

**Operands:**  $-32 \leq k \leq 31$   
 $n \in [0, 1]$

**Operation:**  $FSR(n) + k \rightarrow FSR(n)$

**Status Affected:** None

**Description:** The signed 6-bit literal 'k' is added to the contents of the FSRnH:FSRnL register pair.

FSRn is limited to the range 0000h - FFFFh. Moving beyond these bounds will cause the FSR to wrap-around.

### ANDLW AND literal with W

**Syntax:** [ *label* ] ANDLW k

**Operands:**  $0 \leq k \leq 255$

**Operation:**  $(W) .AND. (k) \rightarrow (W)$

**Status Affected:** Z

**Description:** The contents of W register are AND'ed with the 8-bit literal 'k'. The result is placed in the W register.

### ADDLW Add literal and W

**Syntax:** [ *label* ] ADDLW k

**Operands:**  $0 \leq k \leq 255$

**Operation:**  $(W) + k \rightarrow (W)$

**Status Affected:** C, DC, Z

**Description:** The contents of the W register are added to the 8-bit literal 'k' and the result is placed in the W register.

### ANDWF AND W with f

**Syntax:** [ *label* ] ANDWF f, d

**Operands:**  $0 \leq f \leq 127$   
 $d \in [0, 1]$

**Operation:**  $(W) .AND. (f) \rightarrow (\text{destination})$

**Status Affected:** Z

**Description:** AND the W register with register 'f'. If 'd' is '0', the result is stored in the W register. If 'd' is '1', the result is stored back in register 'f'.

### ADDWF Add W and f

**Syntax:** [ *label* ] ADDWF f, d

**Operands:**  $0 \leq f \leq 127$   
 $d \in [0, 1]$

**Operation:**  $(W) + (f) \rightarrow (\text{destination})$

**Status Affected:** C, DC, Z

**Description:** Add the contents of the W register with register 'f'. If 'd' is '0', the result is stored in the W register. If 'd' is '1', the result is stored back in register 'f'.

### ASRF Arithmetic Right Shift

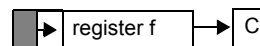
**Syntax:** [ *label* ] ASRF f {, d}

**Operands:**  $0 \leq f \leq 127$   
 $d \in [0, 1]$

**Operation:**  $(f < 7) \rightarrow \text{dest} < 7 >$   
 $(f < 7:1 >) \rightarrow \text{dest} < 6:0 >$ ,  
 $(f < 0 >) \rightarrow C$ ,

**Status Affected:** C, Z

**Description:** The contents of register 'f' are shifted one bit to the right through the Carry flag. The MSb remains unchanged. If 'd' is '0', the result is placed in W. If 'd' is '1', the result is stored back in register 'f'.



### ADDWFC ADD W and CARRY bit to f

**Syntax:** [ *label* ] ADDWFC f {, d}

**Operands:**  $0 \leq f \leq 127$   
 $d \in [0, 1]$

**Operation:**  $(W) + (f) + (C) \rightarrow \text{dest}$

**Status Affected:** C, DC, Z

**Description:** Add W, the Carry flag and data memory location 'f'. If 'd' is '0', the result is placed in W. If 'd' is '1', the result is placed in data memory location 'f'.

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## CALL Call Subroutine

Syntax: [ *label* ] CALL k

Operands:  $0 \leq k \leq 2047$

Operation: (PC) + 1 → TOS,  
k → PC<10:0>,  
(PCLATH<6:3>) → PC<14:11>

Status Affected: None

Description: Call Subroutine. First, return address (PC + 1) is pushed onto the stack. The 11-bit immediate address is loaded into PC bits <10:0>. The upper bits of the PC are loaded from PCLATH. CALL is a 2-cycle instruction.

## CLRWDTClear Watchdog Timer

Syntax: [ *label* ] CLRWDTClear Watchdog Timer

Operands: None

Operation: 00h → WDT  
0 → WDT prescaler,  
1 →  $\overline{TO}$   
1 →  $\overline{PD}$

Status Affected:  $\overline{TO}$ ,  $\overline{PD}$

Description: CLRWDTClear Watchdog Timer instruction resets the Watchdog Timer. It also resets the prescaler of the WDT. Status bits  $\overline{TO}$  and  $\overline{PD}$  are set.

## CALLW Subroutine Call With W

Syntax: [ *label* ] CALLW

Operands: None

Operation: (PC) + 1 → TOS,  
(W) → PC<7:0>,  
(PCLATH<6:0>) → PC<14:8>

Status Affected: None

Description: Subroutine call with W. First, the return address (PC + 1) is pushed onto the return stack. Then, the contents of W is loaded into PC<7:0>, and the contents of PCLATH into PC<14:8>. CALLW is a 2-cycle instruction.

## COMF Complement f

Syntax: [ *label* ] COMF f,d

Operands:  $0 \leq f \leq 127$   
d ∈ [0,1]

Operation: ( $\bar{f}$ ) → (destination)

Status Affected: Z

Description: The contents of register 'f' are complemented. If 'd' is '0', the result is stored in W. If 'd' is '1', the result is stored back in register 'f'.

## CLRF Clear f

Syntax: [ *label* ] CLRF f

Operands:  $0 \leq f \leq 127$

Operation: 00h → (f)  
1 → Z

Status Affected: Z

Description: The contents of register 'f' are cleared and the Z bit is set.

## DECF Decrement f

Syntax: [ *label* ] DECF f,d

Operands:  $0 \leq f \leq 127$   
d ∈ [0,1]

Operation: (f) - 1 → (destination)

Status Affected: Z

Description: Decrement register 'f'. If 'd' is '0', the result is stored in the W register. If 'd' is '1', the result is stored back in register 'f'.

## CLRWClear W

Syntax: [ *label* ] CLRW

Operands: None

Operation: 00h → (W)  
1 → Z

Status Affected: Z

Description: W register is cleared. Zero bit (Z) is set.

## MOVIW Move INDFn to W

Syntax: [ *label* ] MOVIW ++FSRn  
 [ *label* ] MOVIW --FSRn  
 [ *label* ] MOVIW FSRn++  
 [ *label* ] MOVIW FSRn--  
 [ *label* ] MOVIW k[FSRn]

Operands:  $n \in [0,1]$   
 $mm \in [00,01,10,11]$   
 $-32 \leq k \leq 31$

Operation: INDFn  $\rightarrow$  W  
 Effective address is determined by

- FSR + 1 (preincrement)
- FSR - 1 (predecrement)
- FSR + k (relative offset)

After the Move, the FSR value will be either:

- FSR + 1 (all increments)
- FSR - 1 (all decrements)
- Unchanged

Status Affected: Z

Mode	Syntax	mm
Preincrement	++FSRn	00
Predecrement	--FSRn	01
Postincrement	FSRn++	10
Postdecrement	FSRn--	11

Description: This instruction is used to move data between W and one of the indirect registers (INDFn). Before/after this move, the pointer (FSRn) is updated by pre/post incrementing/decrementing it.

**Note:** The INDFn registers are not physical registers. Any instruction that accesses an INDFn register actually accesses the register at the address specified by the FSRn.

FSRn is limited to the range 0000h - FFFFh. Incrementing/decrementing it beyond these bounds will cause it to wrap-around.

## MOVLB Move literal to BSR

Syntax: [ *label* ] MOVLB k

Operands:  $0 \leq k \leq 31$

Operation:  $k \rightarrow$  BSR

Status Affected: None

Description: The 5-bit literal 'k' is loaded into the Bank Select Register (BSR).

## MOVLP Move literal to PCLATH

Syntax: [ *label* ] MOVLP k

Operands:  $0 \leq k \leq 127$

Operation:  $k \rightarrow$  PCLATH

Status Affected: None

Description: The 7-bit literal 'k' is loaded into the PCLATH register.

## MOVLW Move literal to W

Syntax: [ *label* ] MOVLW k

Operands:  $0 \leq k \leq 255$

Operation:  $k \rightarrow$  (W)

Status Affected: None

Description: The 8-bit literal 'k' is loaded into W register. The "don't cares" will assemble as '0's.

Words: 1

Cycles: 1

Example: MOVLW 0x5A

After Instruction  
 W = 0x5A

## MOVWF Move W to f

Syntax: [ *label* ] MOVWF f

Operands:  $0 \leq f \leq 127$

Operation: (W)  $\rightarrow$  (f)

Status Affected: None

Description: Move data from W register to register 'f'.

Words: 1

Cycles: 1

Example: MOVWF OPTION\_REG

Before Instruction  
 OPTION\_REG = 0xFF  
 W = 0x4F

After Instruction  
 OPTION\_REG = 0x4F  
 W = 0x4F



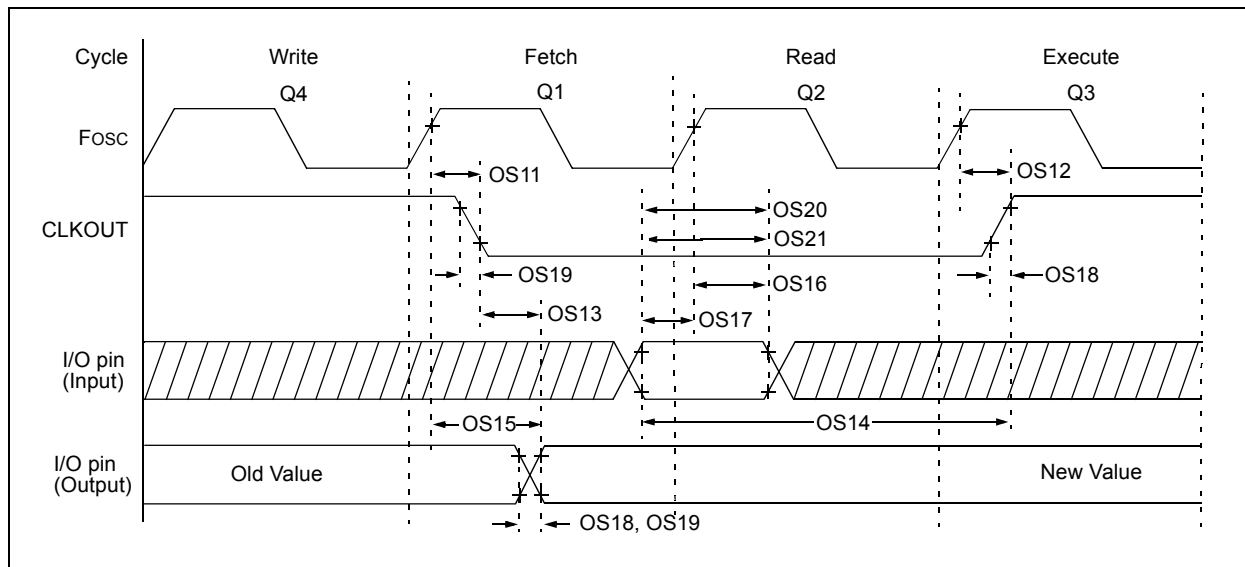
<b>SWAPF</b>	<b>Swap Nibbles in f</b>
Syntax:	[ <i>label</i> ] SWAPF f,d
Operands:	$0 \leq f \leq 127$ $d \in [0,1]$
Operation:	$(f<3:0>) \rightarrow (\text{destination}<7:4>)$ , $(f<7:4>) \rightarrow (\text{destination}<3:0>)$
Status Affected:	None
Description:	The upper and lower nibbles of register 'f' are exchanged. If 'd' is '0', the result is placed in the W register. If 'd' is '1', the result is placed in register 'f'.

<b>XORLW</b>	<b>Exclusive OR literal with W</b>
Syntax:	[ <i>label</i> ] XORLW k
Operands:	$0 \leq k \leq 255$
Operation:	$(W) .XOR. k \rightarrow (W)$
Status Affected:	Z
Description:	The contents of the W register are XOR'ed with the 8-bit literal 'k'. The result is placed in the W register.

<b>TRIS</b>	<b>Load TRIS Register with W</b>
Syntax:	[ <i>label</i> ] TRIS f
Operands:	$5 \leq f \leq 7$
Operation:	$(W) \rightarrow \text{TRIS register 'f'}$
Status Affected:	None
Description:	Move data from W register to TRIS register. When 'f' = 5, TRISA is loaded. When 'f' = 6, TRISB is loaded. When 'f' = 7, TRISC is loaded.

<b>XORWF</b>	<b>Exclusive OR W with f</b>
Syntax:	[ <i>label</i> ] XORWF f,d
Operands:	$0 \leq f \leq 127$ $d \in [0,1]$
Operation:	$(W) .XOR. (f) \rightarrow (\text{destination})$
Status Affected:	Z
Description:	Exclusive OR the contents of the W register with register 'f'. If 'd' is '0', the result is stored in the W register. If 'd' is '1', the result is stored back in register 'f'.

**FIGURE 27-7: CLKOUT AND I/O TIMING**



**TABLE 27-9: CLKOUT AND I/O TIMING PARAMETERS**

Standard Operating Conditions (unless otherwise stated)							
Param. No.	Sym.	Characteristic	Min.	Typ†	Max.	Units	Conditions
OS11	TosH2ckL	Fosc↑ to CLKOUT↓ <sup>(1)</sup>	—	—	70	ns	3.3V ≤ VDD ≤ 5.0V
OS12	TosH2ckH	Fosc↑ to CLKOUT↑ <sup>(1)</sup>	—	—	72	ns	3.3V ≤ VDD ≤ 5.0V
OS13	TckL2ioV	CLKOUT↓ to Port out valid <sup>(1)</sup>	—	—	20	ns	
OS14	TioV2ckH	Port input valid before CLKOUT↑ <sup>(1)</sup>	Tosc + 200 ns	—	—	ns	
OS15	TosH2ioV	Fosc↑ (Q1 cycle) to Port out valid	—	50	70*	ns	3.3V ≤ VDD ≤ 5.0V
OS16	TosH2ioI	Fosc↑ (Q2 cycle) to Port input invalid (I/O in setup time)	50	—	—	ns	3.3V ≤ VDD ≤ 5.0V
OS17	TioV2osH	Port input valid to Fosc↑ (Q2 cycle) (I/O in setup time)	20	—	—	ns	
OS18*	TioR	Port output rise time	—	40 15	72 32	ns	VDD = 1.8V 3.3V ≤ VDD ≤ 5.0V
OS19*	TioF	Port output fall time	—	28 15	55 30	ns	VDD = 1.8V 3.3V ≤ VDD ≤ 5.0V
OS20*	Tinp	INT pin input high or low time	25	—	—	ns	
OS21*	Tioc	Interrupt-on-change new input level time	25	—	—	ns	

\* These parameters are characterized but not tested.

† Data in "Typ" column is at 3.0V, 25°C unless otherwise stated.

**Note 1:** Measurements are taken in EXTRC mode where CLKOUT output is 4 x Tosc.

# PIC12(L)F1501

**TABLE 27-13: ANALOG-TO-DIGITAL CONVERTER (ADC) CHARACTERISTICS<sup>(1,2,3)</sup>**

Operating Conditions (unless otherwise stated) VDD = 3.0V, TA = 25°C							
Param. No.	Sym.	Characteristic	Min.	Typ†	Max.	Units	Conditions
AD01	NR	Resolution	—	—	10	bit	
AD02	EIL	Integral Error	—	±1	±1.7	LSb	VREF = 3.0V
AD03	EDL	Differential Error	—	±1	±1	LSb	No missing codes VREF = 3.0V
AD04	EOFF	Offset Error	—	±1	±2.5	LSb	VREF = 3.0V
AD05	EGN	Gain Error	—	±1	±2.0	LSb	VREF = 3.0V
AD06	VREF	Reference Voltage	1.8	—	VDD	V	VREF = (VRPOS - VRNEG) ( <b>Note 4</b> )
AD07	VAIN	Full-Scale Range	VSS	—	VREF	V	
AD08	ZAIN	Recommended Impedance of Analog Voltage Source	—	—	10	kΩ	Can go higher if external 0.01μF capacitor is present on input pin.

\* These parameters are characterized but not tested.

† Data in “Typ” column is at 3.0V, 25°C unless otherwise stated. These parameters are for design guidance only and are not tested.

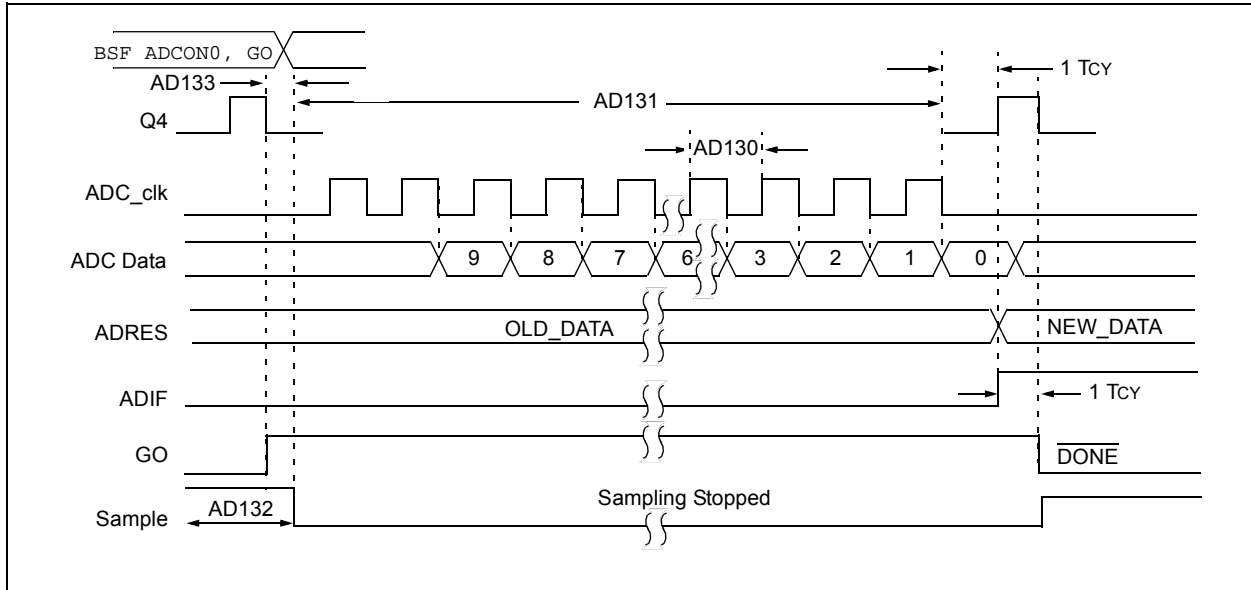
**Note 1:** Total Absolute Error includes integral, differential, offset and gain errors.

**2:** The ADC conversion result never decreases with an increase in the input voltage and has no missing codes.

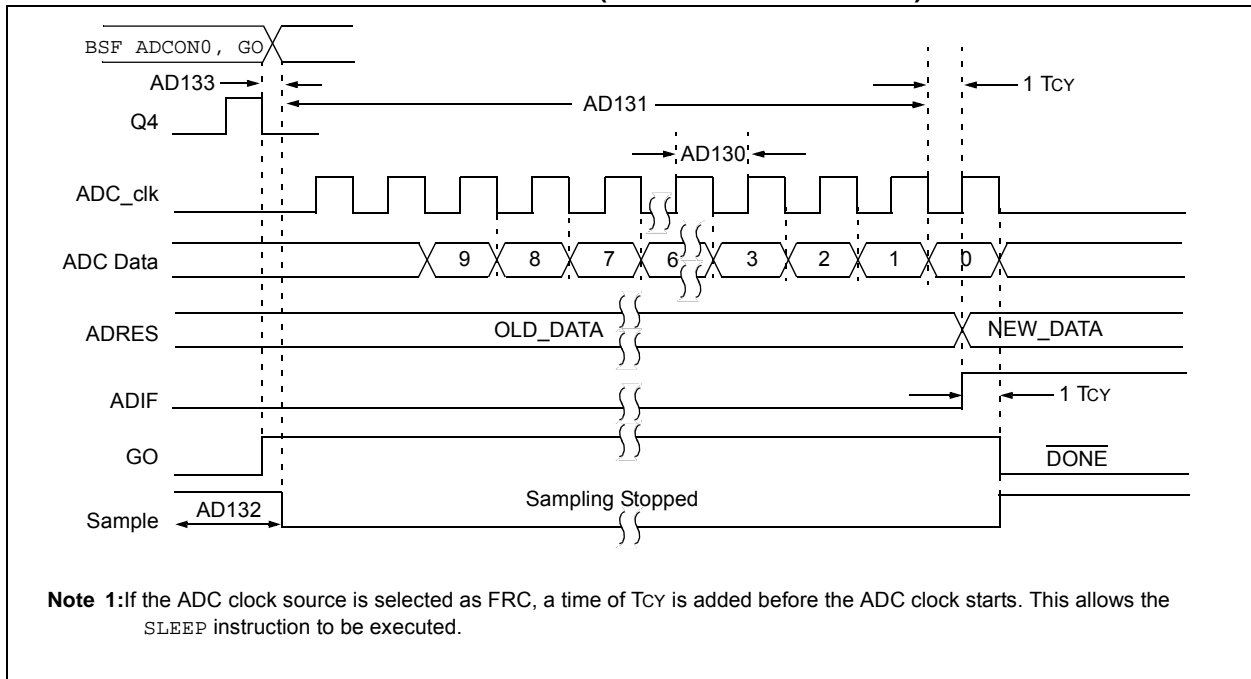
**3:** See **Section 28.0 “DC and AC Characteristics Graphs and Charts”** for operating characterization.

**4:** ADC VREF is selected by ADPREF<0> bit.

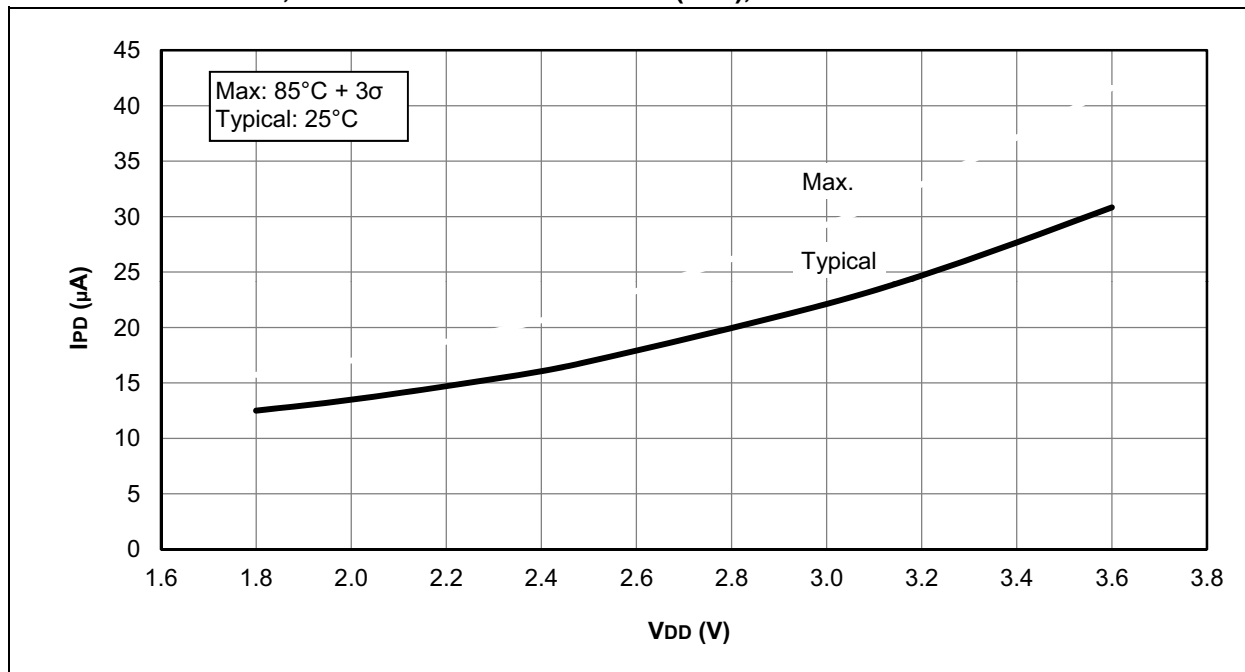
**FIGURE 27-12: ADC CONVERSION TIMING (ADC CLOCK Fosc-BASED)**



**FIGURE 27-13: ADC CONVERSION TIMING (ADC CLOCK FROM FRC)**



**FIGURE 28-25: I<sub>PD</sub>, FIXED VOLTAGE REFERENCE (FVR), PIC12LF1501 ONLY**



**FIGURE 28-26: I<sub>PD</sub>, FIXED VOLTAGE REFERENCE (FVR), PIC12F1501 ONLY**

