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Applications of "<u>Embedded - Microcontrollers</u>"

Details	
Product Status	Active
Core Processor	PIC
Core Size	8-Bit
Speed	20MHz
Connectivity	-
Peripherals	Brown-out Detect/Reset, POR, PWM, WDT
Number of I/O	5
Program Memory Size	1.75KB (1K x 14)
Program Memory Type	FLASH
EEPROM Size	-
RAM Size	64 x 8
Voltage - Supply (Vcc/Vdd)	1.8V ~ 3.6V
Data Converters	A/D 4x10b
Oscillator Type	Internal
Operating Temperature	-40°C ~ 85°C (TA)
Mounting Type	Surface Mount
Package / Case	8-VDFN Exposed Pad
Supplier Device Package	8-DFN (3x3)
Purchase URL	https://www.e-xfl.com/product-detail/microchip-technology/pic12lf1501t-i-mf

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3.3.5 DEVICE MEMORY MAPS

The memory maps for Bank 0 through Bank 31 are shown in the tables in this section.

TABLE 3-3:	PIC12(L)F1501	MEMORY MAP
-------------------	---------------	------------

	BANK 0		BANK 1		BANK 2		BANK 3		BANK 4		BANK 5		BANK 6		BANK 7
000h		080h		100h		180h		200h		280h		300h		380h	
	Core Registers		Core Registers		Core Registers		Core Registers		Core Registers		Core Registers		Core Registers		Core Registers
	(Table 3-2)		(Table 3-2)		(Table 3-2)		(Table 3-2)		(Table 3-2)		(Table 3-2)		(Table 3-2)		(Table 3-2)
00Bh		08Bh		10Bh		18Bh		20Bh		28Bh		30Bh		38Bh	
00Ch	PORTA	08Ch	TRISA	10Ch	LATA	18Ch	ANSELA	20Ch	WPUA	28Ch	_	30Ch	_	38Ch	_
00Dh	_	08Dh	_	10Dh	_	18Dh	_	20Dh	_	28Dh	_	30Dh	_	38Dh	_
00Eh	_	08Eh	_	10Eh	_	18Eh	_	20Eh	_	28Eh	_	30Eh	_	38Eh	_
00Fh	_	08Fh	_	10Fh	_	18Fh	_	20Fh	_	28Fh	_	30Fh	_	38Fh	_
010h	_	090h	_	110h	_	190h	_	210h	_	290h	_	310h	_	390h	_
011h	PIR1	091h	PIE1	111h	CM1CON0	191h	PMADRL	211h	_	291h	_	311h	_	391h	IOCAP
012h	PIR2	092h	PIE2	112h	CM1CON1	192h	PMADRH	212h	_	292h	_	312h	_	392h	IOCAN
013h	PIR3	093h	PIE3	113h		193h	PMDATL	213h		293h	_	313h	_	393h	IOCAF
014h	TMR0	094h	OPTION REG	114h	 CMOUT	194h	PMDATH	214h		294h	_	314h		394h	_
015h 016h	TMR0 TMR1L	095h 096h	PCON PCON	115h 116h	BORCON	195h 196h	PMCON1 PMCON2	215h 216h	_	295h 296h		315h 316h		395h 396h	_
016H 017h	TMR1H	090h	WDTCON	117h	FVRCON	19011 197h	VREGCON	217h		297h		317h		397h	_
01711 018h	T1CON	098h	WB10011	118h	DACCON0	198h	—	218h		298h	_	318h	_	398h	_
019h	TIGCON	099h	OSCCON	119h	DACCON0 DACCON1	199h		219h		299h	_	319h	_	399h	_
019II 01Ah	TMR2	09Ah	OSCSTAT	11Ah	—	19Ah		21Ah		29Ah	_	31Ah	_	39Ah	_
-	PR2	09Bh	ADRESL	11Bh		19Bh		21Bh	_	29Bh	_	31Bh	_	39Bh	_
01Bh	T2CON	09Ch	ADRESH	11Ch		19Ch		21Ch		29Ch		31Ch		39Ch	_
01Ch	TZCON		_				_	-			_		_		
01Dh	_	09Dh	ADCON0	11Dh	APFCON	19Dh	_	21Dh	_	29Dh	_	31Dh	_	39Dh	
01Eh		09Eh	ADCON1	11Eh		19Eh		21Eh	_	29Eh	_	31Eh	_	39Eh	_
01Fh	_	09Fh 0A0h	ADCON2	11Fh		19Fh		21Fh	_	29Fh	_	31Fh		39Fh	_
020h	OI D	UAUII		120h		1A0h		220h		2A0h		320h		3A0h	
	General Purpose Register														
	48 Bytes		11.2		11.2		l lainealaneanta d		l ladan la anamta d		l la incula un cuta d				l la incole no cata d
04Fh	.0 2) 100		Unimplemented Read as '0'		Unimplemented Read as '0'		Unimplemented Read as '0'		Unimplemented Read as '0'		Unimplemented Read as '0'		Unimplemented Read as '0'		Unimplemented Read as '0'
050h			Neau as 0		ineau as 0		Neau as 0		Neau as 0		Neau as 0		ixeau as 0		ineau as 0
00011	Unimplemented														
	Read as '0'	0EFh		4051				0051		0==1		36Fh		3EFh	
06Fh 070h		0EFn 0F0h		16Fh 170h		1EFh 1F0h		26Fh 270h		2EFh 2F0h		370h		3F0h	
07011		01 011	Common RAM	17011	Common RAM	11 011	Common RAM	27011	Common RAM	21 011	Common RAM	37011	Common RAM	31 011	Common RAM
	Common RAM		(Accesses		(Accesses		(Accesses		(Accesses		(Accesses		(Accesses		(Accesses
07Fh		0FFh	70h – 7Fh)	17Fh	70h – 7Fh)	1FFh	70h – 7Fh)	27Fh	70h – 7Fh)	2FFh	70h – 7Fh)	37Fh	70h – 7Fh)	3FFh	70h – 7Fh)
UIFII		OFFII		17 [1]		ILLII		21 [1]		25511		SIFII		SEE	

Legend

= Unimplemented data memory locations, read as '0'

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Legend:

= Unimplemented data memory locations, read as '0'

TABL	_E 3-3: P	IC12(L)F1501 MEI	MOR	Y MAP (CON	TINU	ED)								
	BANK 8	_	BANK 9	_	BANK 10	_	BANK 11	_	BANK 12	_	BANK 13		BANK 14		BANK 15
400h	Core Registers (Table 3-2)	480h	Core Registers (Table 3-2)	500h	Core Registers (Table 3-2)	580h	Core Registers (Table 3-2)	600h	Core Registers (Table 3-2)	680h	Core Registers (Table 3-2)	700h	Core Registers (Table 3-2)	780h	Core Registers (Table 3-2)
40Bh	,	48Bh	, ,	50Bh	, i	58Bh	, , , ,	60Bh	, ,	68Bh	, ,	70Bh	, ,	78Bh	, , , ,
40Ch	_	48Ch	_	50Ch	_	58Ch	_	60Ch	_	68Ch	_	70Ch	_	78Ch	_
40Dh	_	48Dh	_	50Dh	_	58Dh	_	60Dh	_	68Dh	_	70Dh	_	78Dh	_
40Eh	_	48Eh	_	50Eh	_	58Eh	_	60Eh	_	68Eh	_	70Eh	_	78Eh	_
40Fh	_	48Fh	_	50Fh	_	58Fh	_	60Fh	_	68Fh	_	70Fh	_	78Fh	_
410h	_	490h	_	510h	_	590h	_	610h	_	690h	_	710h	_	790h	_
411h	_	491h	_	511h	_	591h	_	611h	PWM1DCL	691h	CWG1DBR	711h	_	791h	_
412h	ı	492h		512h		592h	_	612h	PWM1DCH	692h	CWG1DBF	712h		792h	_
413h	_	493h	_	513h	_	593h	_	613h	PWM1CON	693h	CWG1CON0	713h	_	793h	_
414h	ı	494h		514h		594h	_	614h	PWM2DCL	694h	CWG1CON1	714h		794h	_
415h		495h		515h		595h	_	615h	PWM2DCH	695h	CWG1CON2	715h		795h	_
416h	I	496h	I	516h	I	596h	_	616h	PWM2CON	696h		716h	I	796h	_
417h	_	497h	_	517h	_	597h	_	617h	PWM3DCL	697h	_	717h	_	797h	_
418h		498h	NCO1ACCL	518h		598h	_	618h	PWM3DCH	698h		718h		798h	_
419h		499h	NCO1ACCH	519h	_	599h	_	619h	PWM3CON	699h	_	719h	_	799h	_
41Ah	_	49Ah	NCO1ACCU	51Ah	_	59Ah	_	61Ah	PWM4DCL	69Ah	_	71Ah	_	79Ah	_
41Bh		49Bh	NCO1INCL	51Bh	_	59Bh	_	61Bh	PWM4DCH	69Bh	_	71Bh	_	79Bh	_
41Ch	_	49Ch	NCO1INCH	51Ch	_	59Ch	_	61Ch	PWM4CON	69Ch	_	71Ch	_	79Ch	_
41Dh	_	49Dh	_	51Dh	_	59Dh	_	61Dh	_	69Dh	_	71Dh		79Dh	_
41Eh	_	49Eh	NCO1CON	51Eh	_	59Eh	_	61Eh		69Eh	_	71Eh	_	79Eh	
41Fh	_	49Fh	NCO1CLK	51Fh	_	59Fh	_	61Fh	_	69Fh	_	71Fh	_	79Fh	_
420h		4A0h		520h		5A0h		620h		6A0h		720h		7A0h	
	Unimplemented Read as '0'		Unimplemented Read as '0'		Unimplemented Read as '0'		Unimplemented Read as '0'		Unimplemented Read as '0'		Unimplemented Read as '0'		Unimplemented Read as '0'		Unimplemented Read as '0'
46Fh		4EFh		56Fh		5EFh		66Fh		6EFh		76Fh		7EFh	
470h		4F0h		570h		5F0h		670h		6F0h		770h		7F0h	
	Common RAM		Common RAM		Common RAM		Common RAM		Common RAM		Common RAM		Common RAM		Common RAM
	(Accesses		(Accesses		(Accesses		(Accesses		(Accesses		(Accesses		(Accesses		(Accesses
47Fh	70h – 7Fh)	4FFh	70h – 7Fh)	57Fh	70h – 7Fh)	5FFh	70h – 7Fh)	67Fh	70h – 7Fh)	6FFh	70h – 7Fh)	77Fh	70h – 7Fh)	7FFh	70h – 7Fh)
4/1711		J 4FFII		37 FII		SEEII		0/11		OFFII		// [] /FFII	
	BANK 16		BANK 17		BANK 18		BANK 19		BANK 20		BANK 21		BANK 22		BANK 23
800h		880h		900h		980h		A00h		A80h		B00h		B80h	
	Core Registers (Table 3-2)		Core Registers (Table 3-2)		Core Registers (Table 3-2)		Core Registers (Table 3-2)		Core Registers (Table 3-2)		Core Registers (Table 3-2)		Core Registers (Table 3-2)		Core Registers (Table 3-2)
80Bh	,	88Bh	(,	90Bh	(/	98Bh	(,	A0Bh	(,	A8Bh	(,	B0Bh	(,	B8Bh	, , , , ,
80Ch		88Ch		90Ch		98Ch		A0Ch		A8Ch		B0Ch		B8Ch	
80CII	Unimplemented Read as '0'	OOCII	Unimplemented Read as '0'	90011	Unimplemented Read as '0'	90011	Unimplemented Read as '0'	AUCII	Unimplemented Read as '0'	Aocii	Unimplemented Read as '0'	BUCII	Unimplemented Read as '0'	Boon	Unimplemented Read as '0'
	incau as 0		incau as 0		incau as 0		incau as 0	l	incau as 0		ixeau as 0		ixeau as 0		
86Fh		8EFh		96Fh		9EFh		A6Fh		AEFh		B6Fh		BEFh	
870h	Common RAM (Accesses	8F0h	Common RAM (Accesses	970h	Common RAM (Accesses	9F0h	Common RAM (Accesses	A70h	Common RAM (Accesses	AF0h	Common RAM (Accesses	B70h	Common RAM (Accesses	BF0h	Common RAM (Accesses
87Fh	70h – 7Fh)	8FFh	70h – 7Fh)	97Fh	70h – 7Fh)	9FFh	70h – 7Fh)	A7Fh	70h – 7Fh)	AFFh	70h – 7Fh)	B7Fh	70h – 7Fh)	BFFh	70h – 7Fh)

4.3 Code Protection

Code protection allows the device to be protected from unauthorized access. Internal access to the program memory is unaffected by any code protection setting.

4.3.1 PROGRAM MEMORY PROTECTION

The entire program memory space is protected from external reads and writes by the \overline{CP} bit in Configuration Words. When $\overline{CP}=0$, external reads and writes of program memory are inhibited and a read will return all '0's. The CPU can continue to read program memory, regardless of the protection bit settings. Writing the program memory is dependent upon the write protection setting. See Section 4.4 "Write Protection" for more information.

4.4 Write Protection

Write protection allows the device to be protected from unintended self-writes. Applications, such as bootloader software, can be protected while allowing other regions of the program memory to be modified.

The WRT<1:0> bits in Configuration Words define the size of the program memory block that is protected.

4.5 User ID

Four memory locations (8000h-8003h) are designated as ID locations where the user can store checksum or other code identification numbers. These locations are readable and writable during normal execution. See Section 10.4 "User ID, Device ID and Configuration Word Access" for more information on accessing these memory locations. For more information on checksum calculation, see the "PIC12(L)F1501/PIC16(L)F150X Memory Programming Specification" (DS41573).

REGISTER 5-2: OSCSTAT: OSCILLATOR STATUS REGISTER

U-0	U-0	U-0	R-0/q	U-0	U-0	R-0/q	R-0/q
_	_	_	HFIOFR	_	-	LFIOFR	HFIOFS
bit 7							bit 0

Legend:

R = Readable bit W = Writable bit U = Unimplemented bit, read as '0'

u = Bit is unchanged x = Bit is unknown -n/n = Value at POR and BOR/Value at all other Resets

'1' = Bit is set '0' = Bit is cleared q = Conditional

bit 7-5 **Unimplemented:** Read as '0'

bit 4 HFIOFR: High-Frequency Internal Oscillator Ready bit

1 = HFINTOSC is ready
0 = HFINTOSC is not ready

bit 3-2 **Unimplemented:** Read as '0'

bit 1 LFIOFR: Low-Frequency Internal Oscillator Ready bit

1 = LFINTOSC is ready
0 = LFINTOSC is not ready

bit 0 HFIOFS: High-Frequency Internal Oscillator Stable bit

1 = HFINTOSC 16 MHz Oscillator is stable and is driving the INTOSC

0 = HFINTOSC 16 MHz is not stable, the Start-up Oscillator is driving INTOSC

TABLE 5-3: SUMMARY OF REGISTERS ASSOCIATED WITH CLOCK SOURCES

Name	Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0	Register on Page
OSCCON	_		IRCF	<3:0>		_	SCS	49	
OSCSTAT	_	_	_	HFIOFR	_	_	LFIOFR	HFIOFS	50

Legend: — = unimplemented location, read as '0'. Shaded cells are not used by clock sources.

TABLE 5-4: SUMMARY OF CONFIGURATION WORD WITH CLOCK SOURCES

Name	Bits	Bit -/7	Bit -/6	Bit 13/5	Bit 12/4	Bit 11/3	Bit 10/2	Bit 9/1	Bit 8/0	Register on Page
CONFICA	13:8	1	_		_	CLKOUTEN	BOREI	N<1:0>	-	20
CONFIG1	7:0	CP	MCLRE	PWRTE	WDTE	E<1:0>	_	FOSC	<1:0>	38

Legend: — = unimplemented location, read as '0'. Shaded cells are not used by clock sources.

REGISTER 7-5: PIR1: PERIPHERAL INTERRUPT REQUEST REGISTER 1

R/W-0/0	R/W-0/0	U-0	U-0	U-0	U-0	R/W-0/0	R/W-0/0
TMR1GIF	ADIF	_	_	_	_	TMR2IF	TMR1IF
bit 7							bit 0

Legend:

R = Readable bit W = Writable bit U = Unimplemented bit, read as '0'

u = Bit is unchanged x = Bit is unknown -n/n = Value at POR and BOR/Value at all other Resets

'1' = Bit is set '0' = Bit is cleared

bit 7 TMR1GIF: Timer1 Gate Interrupt Flag bit

1 = Interrupt is pending

0 = Interrupt is not pending

bit 6 ADIF: ADC Interrupt Flag bit

1 = Interrupt is pending0 = Interrupt is not pending

bit 5-2 **Unimplemented:** Read as '0'

bit 1 TMR2IF: Timer2 to PR2 Interrupt Flag bit

1 = Interrupt is pending0 = Interrupt is not pending

bit 0 TMR1IF: Timer1 Overflow Interrupt Flag bit

1 = Interrupt is pending0 = Interrupt is not pending

Note: Interrupt flag bits are set when an interrupt condition occurs, regardless of the state of

its corresponding enable bit or the Global Interrupt Enable bit, GIE of the INTCON register. User software should ensure the appropriate interrupt flag bits are clear prior

to enabling an interrupt.

10.2.2 FLASH MEMORY UNLOCK SEQUENCE

The unlock sequence is a mechanism that protects the Flash program memory from unintended self-write programming or erasing. The sequence must be executed and completed without interruption to successfully complete any of the following operations:

- · Row Erase
- · Load program memory write latches
- Write of program memory write latches to program memory
- Write of program memory write latches to User IDs

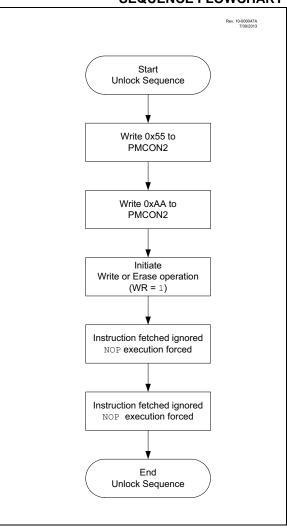
The unlock sequence consists of the following steps:

- 1. Write 55h to PMCON2
- 2. Write AAh to PMCON2
- 3. Set the WR bit in PMCON1
- 4. NOP instruction
- 5. NOP instruction

Once the WR bit is set, the processor will always force two \mathtt{NOP} instructions. When an Erase Row or Program Row operation is being performed, the processor will stall internal operations (typical 2 ms), until the operation is complete and then resume with the next instruction. When the operation is loading the program memory write latches, the processor will always force the two \mathtt{NOP} instructions and continue uninterrupted with the next instruction.

Since the unlock sequence must not be interrupted, global interrupts should be disabled prior to the unlock sequence and re-enabled after the unlock sequence is completed.

FIGURE 10-3: FLASH PROGRAM MEMORY UNLOCK SEQUENCE FLOWCHART



EXAMPLE 10-2: ERASING ONE ROW OF PROGRAM MEMORY

```
; This row erase routine assumes the following:
; 1. A valid address within the erase row is loaded in ADDRH:ADDRL
; 2. ADDRH and ADDRL are located in shared data memory 0x70 - 0x7F (common RAM)
       BCF
                  INTCON, GIE
                                 ; Disable ints so required sequences will execute properly
       BANKSEL
                  PMADRL
       MOVF
                  ADDRL,W
                                 ; Load lower 8 bits of erase address boundary
       MOVWF
                  PMADRL
       MOVF
                  ADDRH,W
                                 ; Load upper 6 bits of erase address boundary
       MOVWF
                  PMADRH
       BCF
                  PMCON1,CFGS
                                ; Not configuration space
                  PMCON1, FREE
                                 ; Specify an erase operation
       BSF
       BSF
                  PMCON1,WREN
                                 ; Enable writes
       MOVLW
                  55h
                                 ; Start of required sequence to initiate erase
       MOVWF
                  PMCON2
                                 ; Write 55h
       MOVLW
                  0AAh
       MOVWF
                  PMCON2
                                 ; Write AAh
       BSF
                  PMCON1,WR
                                ; Set WR bit to begin erase
       NOP
                                 ; NOP instructions are forced as processor starts
       NOP
                                 ; row erase of program memory.
                                 ; The processor stalls until the erase process is complete
                                  ; after erase processor continues with 3rd instruction
       BCF
                  PMCON1, WREN
                                 ; Disable writes
                  INTCON, GIE
                                 ; Enable interrupts
       BSF
```

15.2.6 ADC CONVERSION PROCEDURE

This is an example procedure for using the ADC to perform an Analog-to-Digital conversion:

- 1. Configure Port:
 - Disable pin output driver (Refer to the TRIS register)
 - Configure pin as analog (Refer to the ANSEL register)
 - Disable weak pull-ups either globally (Refer to the OPTION_REG register) or individually (Refer to the appropriate WPUx register).
- 2. Configure the ADC module:
 - · Select ADC conversion clock
 - · Configure voltage reference
 - · Select ADC input channel
 - · Turn on ADC module
- 3. Configure ADC interrupt (optional):
 - · Clear ADC interrupt flag
 - · Enable ADC interrupt
 - · Enable peripheral interrupt
 - Enable global interrupt⁽¹⁾
- 4. Wait the required acquisition time(2).
- 5. Start conversion by setting the GO/DONE bit.
- Wait for ADC conversion to complete by one of the following:
 - Polling the GO/DONE bit
 - Waiting for the ADC interrupt (interrupts enabled)
- Read ADC Result.
- Clear the ADC interrupt flag (required if interrupt is enabled).
 - **Note 1:** The global interrupt can be disabled if the user is attempting to wake-up from Sleep and resume in-line code execution.
 - 2: Refer to Section 15.4 "ADC Acquisition Requirements".

EXAMPLE 15-1: ADC CONVERSION

```
; This code block configures the ADC
;for polling, Vdd and Vss references, FRC
; oscillator and ANO input.
;Conversion start & polling for completion
; are included.
BANKSEL
         ADCON1
         B'11110000' ; Right justify, FRC
MOVLW
                      ;oscillator
MOVWF
         ADCON1
                      ; Vdd and Vss Vref+
BANKSEL
         TRISA
         TRISA,0
                     ;Set RAO to input
BSF
BANKSEL
         ANSEL
BSF
         ANSEL, 0
                     ;Set RAO to analog
BANKSEL
         WPUA
BCF
         WPUA,0
                      ;Disable weak
                      pull-up on RA0
BANKSEL
         ADCON0
         B'00000001' ;Select channel AN0
MOVLW
MOVWF
         ADCON0
                      ;Turn ADC On
         SampleTime ;Acquisiton delay
CALL
         ADCON0, ADGO ; Start conversion
BSF
BTFSC
         ADCON0, ADGO ; Is conversion done?
GOTO
                     ;No, test again
         $-1
BANKSEL
        ADRESH
MOVF
         ADRESH,W ;Read upper 2 bits
MOVWF
         RESULTHI ;store in GPR space
BANKSEL
         ADRESL
         ADRESL, W
                      ;Read lower 8 bits
MOVF
MOVWF
         RESULTLO
                      ;Store in GPR space
```

23.2 Fixed Duty Cycle (FDC) Mode

In Fixed Duty Cycle (FDC) mode, every time the accumulator overflows (NCO_overflow), the output is toggled. This provides a 50% duty cycle, provided that the increment value remains constant. For more information, see Figure 23-2.

The FDC mode is selected by clearing the NxPFM bit in the NCOxCON register.

23.3 Pulse Frequency (PF) Mode

In Pulse Frequency (PF) mode, every time the accumulator overflows (NCO_overflow), the output becomes active for one or more clock periods. Once the clock period expires, the output returns to an inactive state. This provides a pulsed output.

The output becomes active on the rising clock edge immediately following the overflow event. For more information, see Figure 23-2.

The value of the active and inactive states depends on the polarity bit, NxPOL in the NCOxCON register.

The PF mode is selected by setting the NxPFM bit in the NCOxCON register.

23.3.1 OUTPUT PULSE WIDTH CONTROL

When operating in PF mode, the active state of the output can vary in width by multiple clock periods. Various pulse widths are selected with the NxPWS<2:0> bits in the NCOxCLK register.

When the selected pulse width is greater than the accumulator overflow time frame, the output of the NCOx operation is indeterminate.

23.4 Output Polarity Control

The last stage in the NCOx module is the output polarity. The NxPOL bit in the NCOxCON register selects the output polarity. Changing the polarity while the interrupts are enabled will cause an interrupt for the resulting output transition.

The NCOx output can be used internally by source code or other peripherals. Accomplish this by reading the NxOUT (read-only) bit of the NCOxCON register.

The NCOx output signal is available to the following peripherals:

- CLC
- CWG

23.5 Interrupts

When the accumulator overflows (NCO_overflow), the NCOx Interrupt Flag bit, NCOxIF, of the PIRx register is set. To enable the interrupt event (NCO_interrupt), the following bits must be set:

- · NxEN bit of the NCOxCON register
- · NCOxIE bit of the PIEx register
- · PEIE bit of the INTCON register
- · GIE bit of the INTCON register

The interrupt must be cleared by software by clearing the NCOxIF bit in the Interrupt Service Routine.

23.6 Effects of a Reset

All of the NCOx registers are cleared to zero as the result of a Reset.

23.7 Operation In Sleep

The NCO module operates independently from the system clock and will continue to run during Sleep, provided that the clock source selected remains active

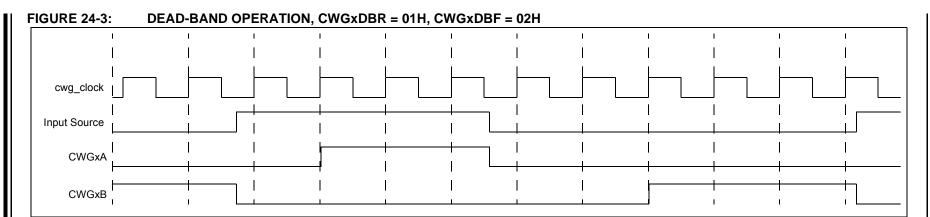
The HFINTOSC remains active during Sleep when the NCO module is enabled and the HFINTOSC is selected as the clock source, regardless of the system clock source selected.

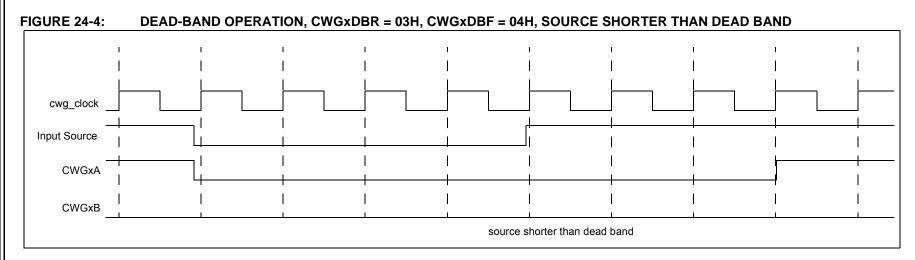
In other words, if the HFINTOSC is simultaneously selected as the system clock and the NCO clock source, when the NCO is enabled, the CPU will go idle during Sleep, but the NCO will continue to operate and the HFINTOSC will remain active.

This will have a direct effect on the Sleep mode current.

23.8 Alternate Pin Locations

This module incorporates I/O pins that can be moved to other locations with the use of the alternate pin function register, APFCON. To determine which pins can be moved and what their default locations are upon a Reset, see **Section 11.1 "Alternate Pin Function"** for more information.





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27.0 ELECTRICAL SPECIFICATIONS

27.1 Absolute Maximum Ratings^(†)

Ambient temperature under bias40°C to +125°C
Storage temperature65°C to +150°C
Voltage on pins with respect to Vss
on VDD pin
PIC12F15010.3V to +6.5V
PIC12LF15010.3V to +4.0V
on MCLR pin0.3V to +9.0V
on all other pins0.3V to (VDD + 0.3V)
Maximum current
on Vss pin ⁽¹⁾
-40°C ≤ TA ≤ +85°C
+85°C ≤ TA ≤ +125°C
+85°C ≤ TA ≤ +125°C
$+85^{\circ}\text{C} \leq \text{Ta} \leq +125^{\circ}\text{C}$ 85 mA on VDD pin ⁽¹⁾
$+85^{\circ}C \leq TA \leq +125^{\circ}C \qquad \qquad 85 \text{ mA}$ on VDD pin ⁽¹⁾ $-40^{\circ}C \leq TA \leq +85^{\circ}C \qquad \qquad 250 \text{ mA}$
$+85^{\circ}C \leq TA \leq +125^{\circ}C \\ \text{on VDD pin}^{(1)} \\ -40^{\circ}C \leq TA \leq +85^{\circ}C \\ +85^{\circ}C \leq TA \leq +125^{\circ}C \\ 85 \text{ mA}$
$+85^{\circ}C \leq TA \leq +125^{\circ}C \\ \text{on V}_{DD} \text{ pin}^{\text{(1)}} \\ -40^{\circ}C \leq TA \leq +85^{\circ}C \\ +85^{\circ}C \leq TA \leq +125^{\circ}C \\ \text{Sunk by any standard I/O pin} \\ 85 \text{ mA} \\ \text{Sunk by any standard I/O pin} \\ 85 \text{ mA}$

Note 1: Maximum current rating requires even load distribution across I/O pins. Maximum current rating may be limited by the device package power dissipation characterizations, see Table 27-6 to calculate device specifications.

† NOTICE: Stresses above those listed under "Absolute Maximum Ratings" may cause permanent damage to the device. This is a stress rating only and functional operation of the device at those or any other conditions above those indicated in the operation listings of this specification is not implied. Exposure above maximum rating conditions for extended periods may affect device reliability.

^{2:} Power dissipation is calculated as follows: PDIS = VDD x {IDD $- \Sigma$ IOH} + Σ {(VDD - VOH) x IOH} + Σ (VOI x IOL).

TABLE 27-2: SUPPLY CURRENT (IDD)^(1,2)

PIC12LF	1501	Stand	ard Opera	ating Con	ditions (u	ınless otl	herwise stated)
PIC12F1	501						
Param.	Device						Conditions
No.	Characteristics	Min.	Тур†	Max.	Units	V DD	Note
D013		_	30	65	μА	1.8	Fosc = 1 MHz,
		_	55	100	μΑ	3.0	External Clock (ECM), Medium Power mode
D013		_	65	110	μΑ	2.3	Fosc = 1 MHz,
		_	85	140	μА	3.0	External Clock (ECM), Medium Power mode
		—	115	190	μΑ	5.0	Medium Power mode
D014			115	190	μΑ	1.8	Fosc = 4 MHz,
		_	210	310	μΑ	3.0	External Clock (ECM), Medium Power mode
D014		_	180	270	μΑ	2.3	Fosc = 4 MHz,
		_	240	365	μΑ	3.0	External Clock (ECM),
		_	295	460	μΑ	5.0	Medium Power mode
D015		_	3.2	12	μΑ	1.8	Fosc = 31 kHz,
		_	5.4	20	μΑ	3.0	LFINTOSC, -40°C ≤ TA ≤ +85°C
D015		_	13	28	μΑ	2.3	Fosc = 31 kHz,
		_	15	30	μΑ	3.0	LFINTOSC,
		_	17	36	μΑ	5.0	-40°C ≤ TA ≤ +85°C
D016		_	215	360	μΑ	1.8	Fosc = 500 kHz,
		_	275	480	μΑ	3.0	HFINTOSC
D016		_	270	450	μΑ	2.3	Fosc = 500 kHz,
		_	300	500	μΑ	3.0	HFINTOSC
		_	350	620	μΑ	5.0	
D017*			410	660	μΑ	1.8	Fosc = 8 MHz,
		_	630	970	μΑ	3.0	HFINTOSC
D017*		_	530	750	μΑ	2.3	Fosc = 8 MHz,
		_	660	1100	μΑ	3.0	HFINTOSC
			730	1200	μΑ	5.0	
D018		_	600	940	μΑ	1.8	Fosc = 16 MHz,
			970	1400	μΑ	3.0	HFINTOSC
D018			780	1200	μΑ	2.3	Fosc = 16 MHz,
		_	1000	1550	μΑ	3.0	HFINTOSC
			1090	1700	μΑ	5.0	

- * These parameters are characterized but not tested.
- † Data in "Typ" column is at 3.0V, 25°C unless otherwise stated. These parameters are for design guidance only and are not tested.
- **Note 1:** The test conditions for all IDD measurements in active operation mode are: OSC1 = external square wave, from rail-to-rail; all I/O pins tri-stated, pulled to Vss; MCLR = VDD; WDT disabled.
 - 2: The supply current is mainly a function of the operating voltage and frequency. Other factors, such as I/O pin loading and switching rate, oscillator type, internal code execution pattern and temperature, also have an impact on the current consumption.

FIGURE 27-5: CLOCK TIMING

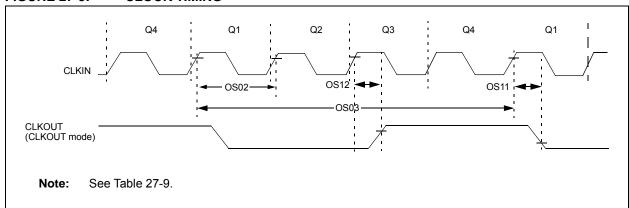


TABLE 27-7: CLOCK OSCILLATOR TIMING REQUIREMENTS

Standard Operating Conditions (unless otherwise stated)

Param.	Sym.	Characteristic	Min.	Тур†	Max.	Units	Conditions
	F000	Estamal CLKIN Francisco (1)	DC		0.5	N 41.1—	Estamal Clask (ECL)
OS01	Fosc	External CLKIN Frequency ⁽¹⁾	DC	_	0.5	MHz	External Clock (ECL)
			DC	_	4	MHz	External Clock (ECM)
			DC	_	20	MHz	External Clock (ECH)
OS02	Tosc	External CLKIN Period ⁽¹⁾	50	_	∞	ns	External Clock (EC)
OS03	TCY	Instruction Cycle Time ⁽¹⁾	200	Tcy	DC	ns	Tcy = 4/Fosc

- * These parameters are characterized but not tested.
- † Data in "Typ" column is at 3.0V, 25°C unless otherwise stated. These parameters are for design guidance only and are not tested.

Note 1: Instruction cycle period (TcY) equals four times the input oscillator time base period. All specified values are based on characterization data for that particular oscillator type under standard operating conditions with the device executing code. Exceeding these specified limits may result in an unstable oscillator operation and/or higher than expected current consumption. All devices are tested to operate at "min" values with an external clock applied to CLKIN pin. When an external clock input is used, the "max" cycle time limit is "DC" (no clock) for all devices.

FIGURE 28-35: Voh vs. Ioh OVER TEMPERATURE, VDD = 5.5V, PIC12F1501 ONLY

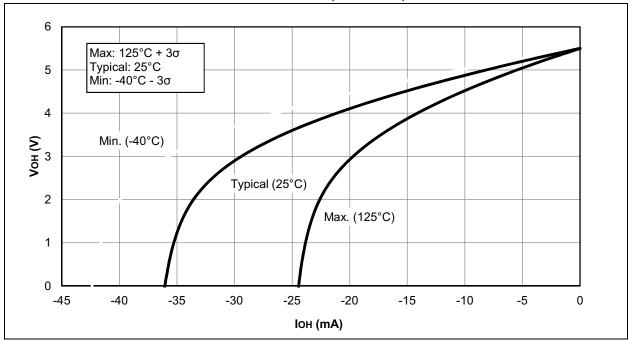


FIGURE 28-36: Vol vs. Iol OVER TEMPERATURE, VDD = 5.5V, PIC12F1501 ONLY

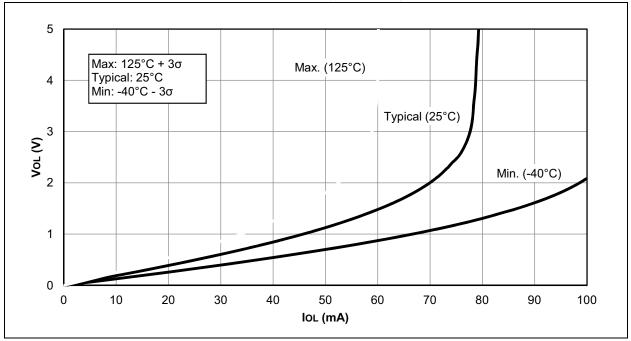


FIGURE 28-39: VOH VS. IOH OVER TEMPERATURE, VDD = 1.8V, PIC12LF1501 ONLY

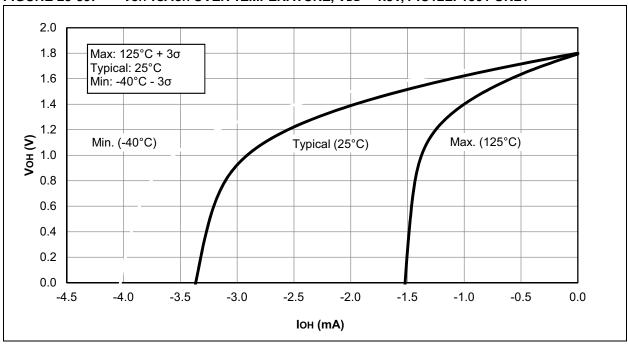


FIGURE 28-40: Vol vs. Iol OVER TEMPERATURE, VDD = 1.8V, PIC12LF1501 ONLY

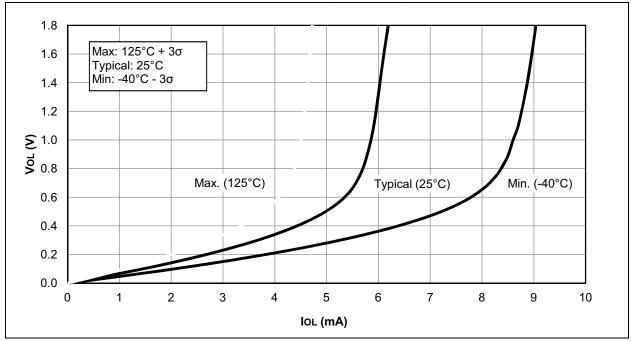


FIGURE 28-43: BROWN-OUT RESET VOLTAGE, BORV = 1, PIC12LF1501 ONLY

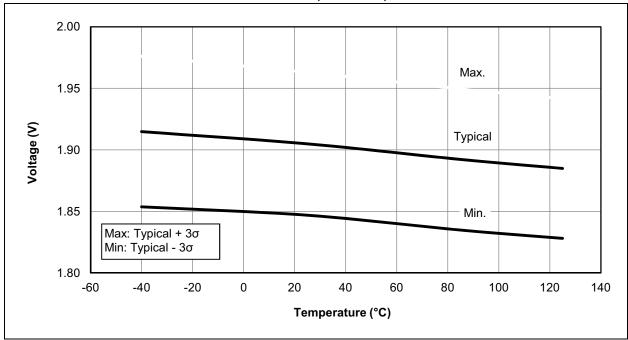
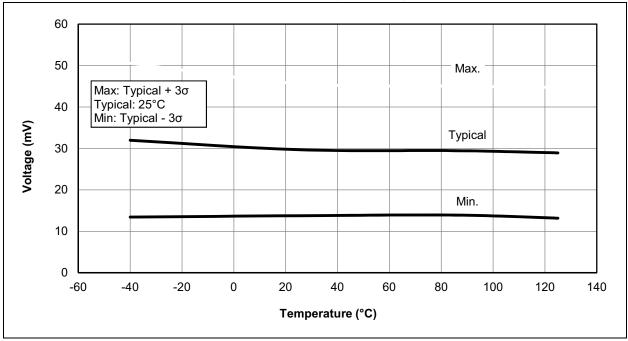
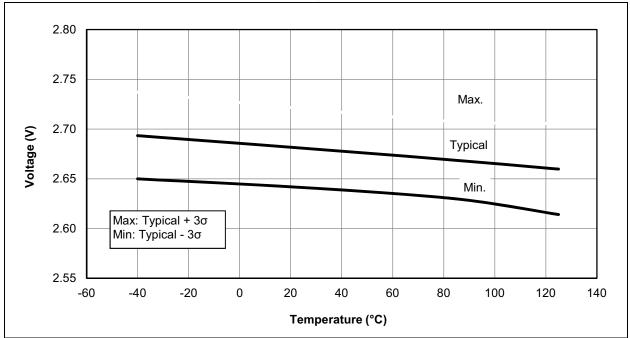


FIGURE 28-44: BROWN-OUT RESET HYSTERESIS, BORV = 1, PIC12LF1501 ONLY







29.11 Demonstration/Development Boards, Evaluation Kits, and Starter Kits

A wide variety of demonstration, development and evaluation boards for various PIC MCUs and dsPIC DSCs allows quick application development on fully functional systems. Most boards include prototyping areas for adding custom circuitry and provide application firmware and source code for examination and modification.

The boards support a variety of features, including LEDs, temperature sensors, switches, speakers, RS-232 interfaces, LCD displays, potentiometers and additional EEPROM memory.

The demonstration and development boards can be used in teaching environments, for prototyping custom circuits and for learning about various microcontroller applications.

In addition to the PICDEM™ and dsPICDEM™ demonstration/development board series of circuits, Microchip has a line of evaluation kits and demonstration software for analog filter design, KEELoQ® security ICs, CAN, IrDA®, PowerSmart battery management, SEEVAL® evaluation system, Sigma-Delta ADC, flow rate sensing, plus many more.

Also available are starter kits that contain everything needed to experience the specified device. This usually includes a single application and debug capability, all on one board.

Check the Microchip web page (www.microchip.com) for the complete list of demonstration, development and evaluation kits.

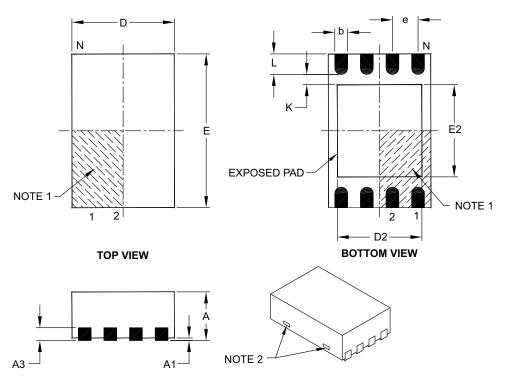
29.12 Third-Party Development Tools

Microchip also offers a great collection of tools from third-party vendors. These tools are carefully selected to offer good value and unique functionality.

- Device Programmers and Gang Programmers from companies, such as SoftLog and CCS
- Software Tools from companies, such as Gimpel and Trace Systems
- Protocol Analyzers from companies, such as Saleae and Total Phase
- Demonstration Boards from companies, such as MikroElektronika, Digilent[®] and Olimex
- Embedded Ethernet Solutions from companies, such as EZ Web Lynx, WIZnet and IPLogika[®]

8-Lead Plastic Dual Flat, No Lead Package (MC) - 2x3x0.9 mm Body [DFN]

Note: For the most current package drawings, please see the Microchip Packaging Specification located at http://www.microchip.com/packaging



	Units		MILLIMETERS		
Dimension Limits		MIN	NOM	MAX	
Number of Pins	N	8			
Pitch	е	0.50 BSC			
Overall Height	Α	0.80	0.90	1.00	
Standoff	A1	0.00	0.02	0.05	
Contact Thickness	А3	0.20 REF			
Overall Length	D	2.00 BSC			
Overall Width	Е	3.00 BSC			
Exposed Pad Length	D2	1.30	_	1.55	
Exposed Pad Width	E2	1.50	_	1.75	
Contact Width	b	0.20	0.25	0.30	
Contact Length	L	0.30	0.40	0.50	
Contact-to-Exposed Pad	K	0.20	_	_	

Notes:

- 1. Pin 1 visual index feature may vary, but must be located within the hatched area.
- 2. Package may have one or more exposed tie bars at ends.
- 3. Package is saw singulated.
- 4. Dimensioning and tolerancing per ASME Y14.5M.
 - BSC: Basic Dimension. Theoretically exact value shown without tolerances.
 - REF: Reference Dimension, usually without tolerance, for information purposes only.

Microchip Technology Drawing C04-123C