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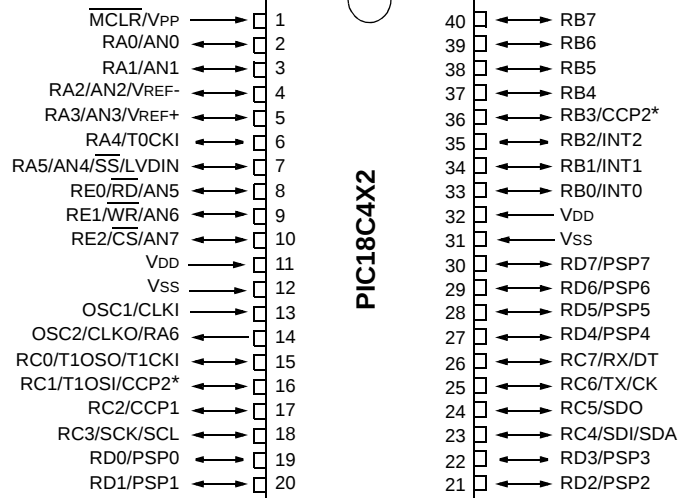
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Details

Product Status	Active
Core Processor	PIC
Core Size	8-Bit
Speed	40MHz
Connectivity	I ² C, SPI, UART/USART
Peripherals	Brown-out Detect/Reset, LVD, POR, PWM, WDT
Number of I/O	22
Program Memory Size	32KB (16K x 16)
Program Memory Type	OTP
EEPROM Size	-
RAM Size	1.5K x 8
Voltage - Supply (Vcc/Vdd)	4.2V ~ 5.5V
Data Converters	A/D 5x10b
Oscillator Type	External
Operating Temperature	-40°C ~ 85°C (TA)
Mounting Type	Surface Mount
Package / Case	28-SOIC (0.295", 7.50mm Width)
Supplier Device Package	28-SOIC
Purchase URL	https://www.e-xfl.com/product-detail/microchip-technology/pic18c252-i-so

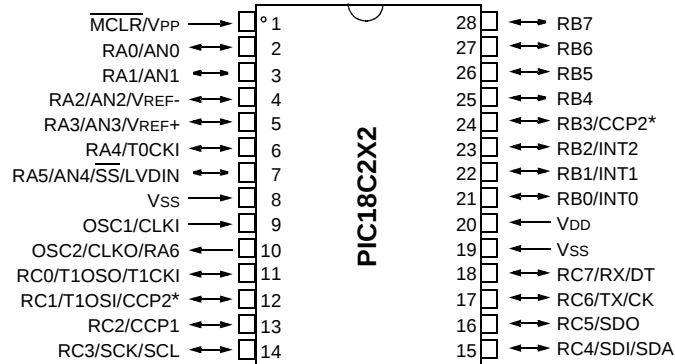
Pin Diagrams (Cont.'d)

DIP, JW



Note: Pin compatible with 40-pin PIC16C7X devices.

DIP, SOIC, JW



* RB3 is the alternate pin for the CCP2 pin multiplexing.

Note: Pin compatible with 28-pin PIC16C7X devices.

TABLE 4-1: SPECIAL FUNCTION REGISTER MAP

FFFh	TOSU	FDFh	INDF2 ⁽³⁾	FBFh	CCPR1H	F9Fh	IPR1
FFEh	TOSH	FDEh	POSTINC2 ⁽³⁾	FBEh	CCPR1L	F9Eh	PIR1
FFDh	TOSL	FDDh	POSTDEC2 ⁽³⁾	FBDh	CCP1CON	F9Dh	PIE1
FFCh	STKPTR	FDCh	PREINC2 ⁽³⁾	FBCh	CCPR2H	F9Ch	—
FFBh	PCLATU	FDBh	PLUSW2 ⁽³⁾	FBBh	CCPR2L	F9Bh	—
FFAh	PCLATH	FDAh	FSR2H	FBAh	CCP2CON	F9Ah	—
FF9h	PCL	FD9h	FSR2L	FB9h	—	F99h	—
FF8h	TBLPTRU	FD8h	STATUS	FB8h	—	F98h	—
FF7h	TBLPTRH	FD7h	TMR0H	FB7h	—	F97h	—
FF6h	TBLPTRL	FD6h	TMR0L	FB6h	—	F96h	TRISE ⁽²⁾
FF5h	TABLAT	FD5h	T0CON	FB5h	—	F95h	TRISD ⁽²⁾
FF4h	PRODH	FD4h	—	FB4h	—	F94h	TRISC
FF3h	PRODL	FD3h	OSCCON	FB3h	TMR3H	F93h	TRISB
FF2h	INTCON	FD2h	LVDCON	FB2h	TMR3L	F92h	TRISA
FF1h	INTCON2	FD1h	WDTCON	FB1h	T3CON	F91h	—
FF0h	INTCON3	FD0h	RCON	FB0h	—	F90h	—
FEFh	INDF0 ⁽³⁾	FCFh	TMR1H	FAFh	SPBRG	F8Fh	—
FEeh	POSTINC0 ⁽³⁾	FCEh	TMR1L	FAeh	RCREG	F8Eh	—
FEDh	POSTDEC0 ⁽³⁾	FCDh	T1CON	FADh	TXREG	F8Dh	LATE ⁽²⁾
FECh	PREINC0 ⁽³⁾	FCCh	TMR2	FACH	TXSTA	F8Ch	LATD ⁽²⁾
FEBh	PLUSW0 ⁽³⁾	FCBh	PR2	FABh	RCSTA	F8Bh	LATC
FEAh	FSR0H	FCAh	T2CON	FAAh	—	F8Ah	LATB
FE9h	FSR0L	FC9h	SSPBUF	FA9h	—	F89h	LATA
FE8h	WREG	FC8h	SSPADDD	FA8h	—	F88h	—
FE7h	INDF1 ⁽³⁾	FC7h	SSPSTAT	FA7h	—	F87h	—
FE6h	POSTINC1 ⁽³⁾	FC6h	SSPCON1	FA6h	—	F86h	—
FE5h	POSTDEC1 ⁽³⁾	FC5h	SSPCON2	FA5h	—	F85h	—
FE4h	PREINC1 ⁽³⁾	FC4h	ADRESH	FA4h	—	F84h	PORTE ⁽²⁾
FE3h	PLUSW1 ⁽³⁾	FC3h	ADRESL	FA3h	—	F83h	PORTD ⁽²⁾
FE2h	FSR1H	FC2h	ADCON0	FA2h	IPR2	F82h	PORTC
FE1h	FSR1L	FC1h	ADCON1	FA1h	PIR2	F81h	PORTB
FE0h	BSR	FC0h	—	FA0h	PIE2	F80h	PORTA

- Note 1:** Unimplemented registers are read as '0'.
Note 2: This register is not available on PIC18C2X2 devices.
Note 3: This is not a physical register.

5.1.2 TABLAT - TABLE LATCH REGISTER

The Table Latch (TABLAT) is an 8-bit register mapped into the SFR space. The Table Latch is used to hold 8-bit data during data transfers between program memory and data memory.

5.1.3 TBLPTR - TABLE POINTER REGISTER

The Table Pointer (TBLPTR) addresses a byte within the program memory. The TBLPTR is comprised of three SFR registers (Table Pointer Upper Byte, High Byte and Low Byte). These three registers (TBLPTRU:TBLPTRH:TBLPTRL) join to form a 22-bit wide pointer. The lower 21-bits allow the device to address up to 2 Mbytes of program memory space. The 22nd bit allows access to the Device ID, the User ID and the Configuration bits.

The Table Pointer, TBLPTR, is used by the TBLRD and TBLWT instructions. These instructions can update the TBLPTR in one of four ways, based on the table operation. These operations are shown in Table 5-1. These operations on the TBLPTR only affect the lower 21-bits.

TABLE 5-1: TABLE POINTER OPERATIONS WITH TBLRD AND TBLWT INSTRUCTIONS

Example	Operation on Table Pointer
TBLRD* TBLWT*	TBLPTR is not modified
TBLRD*+ TBLWT*+	TBLPTR is incremented after the read/write
TBLRD*- TBLWT*-	TBLPTR is decremented after the read/write
TBLRD+* TBLWT+*	TBLPTR is incremented before the read/write

5.2 Internal Program Memory Read/ Writes

5.2.1 TABLE READ OVERVIEW (TBLRD)

The TBLRD instructions are used to read data from program memory to data memory.

TBLPTR points to a byte address in program space. Executing TBLRD places the byte pointed to into TABLAT. In addition, TBLPTR can be modified automatically for the next Table Read operation.

Table Reads from program memory are performed one byte at a time. The instruction will load TABLAT with the one byte from program memory pointed to by TBLPTR.

5.2.2 INTERNAL PROGRAM MEMORY WRITE BLOCK SIZE

The internal program memory of PIC18CXXX devices is written in blocks. For PIC18CXX2 devices, the write block size is 2 bytes. Consequently, Table Write operations to internal program memory are performed in pairs, one byte at a time.

When a Table Write occurs to an even program memory address ($TBLPTR<0> = 0$), the contents of TABLAT are transferred to an internal holding register. This is performed as a short write and the program memory block is not actually programmed at this time. The holding register is not accessible by the user.

When a Table Write occurs to an odd program memory address ($TBLPTR<0> = 1$), a long write is started. During the long write, the contents of TABLAT are written to the high byte of the program memory block and the contents of the holding register are transferred to the low byte of the program memory block.

Figure 5-3 shows the holding register and the program memory write blocks.

If a single byte is to be programmed, the low (even) byte of the destination program word should be read using TBLRD*, modified or changed, if required, and written back to the same address using TBLWT*+. The high (odd) byte should be read using TBLRD*, modified or changed if required, and written back to the same address using TBLWT. A write to the odd address will cause a long write to begin. This process ensures that existing data in either byte will not be changed unless desired.

7.6 INT0 Interrupt

External interrupts on the RB0/INT0, RB1/INT1 and RB2/INT2 pins are edge triggered: either rising, if the corresponding INTEDGx bit is set in the INTCON2 register, or falling, if the INTEDGx bit is clear. When a valid edge appears on the RBx/INTx pin, the corresponding flag bit INTxF is set. This interrupt can be disabled by clearing the corresponding enable bit INTxE. Flag bit INTxF must be cleared in software in the Interrupt Service Routine before re-enabling the interrupt. All external interrupts (INT0, INT1 and INT2) can wake-up the processor from SLEEP, if bit INTxE was set prior to going into SLEEP. If the global interrupt enable bit GIE set, the processor will branch to the interrupt vector following wake-up.

Interrupt priority for INT1 and INT2 is determined by the value contained in the interrupt priority bits, INT1IP (INTCON3<6>) and INT2IP (INTCON3<7>). There is no priority bit associated with INT0. It is always a high priority interrupt source.

7.7 TMR0 Interrupt

In 8-bit mode (which is the default), an overflow (FFh → 00h) in the TMR0 register will set flag bit TMR0IF. In 16-bit mode, an overflow (FFFFh → 0000h) in the TMR0H:TMR0L registers will set flag bit TMR0IF. The interrupt can be enabled/disabled by setting/clearing enable bit T0IE (INTCON<5>). Interrupt priority for Timer0 is determined by the value contained in the interrupt priority bit TMR0IP (INTCON2<2>). See Section 8.0 for further details on the Timer0 module.

7.8 PORTB Interrupt-on-Change

An input change on PORTB<7:4> sets flag bit RBIF (INTCON<0>). The interrupt can be enabled/disabled by setting/clearing enable bit, RBIE (INTCON<3>). Interrupt priority for PORTB Interrupt-on-change is determined by the value contained in the interrupt priority bit, RBIP (INTCON2<0>).

7.9 Context Saving During Interrupts

During an interrupt, the return PC value is saved on the stack. Additionally, the WREG, STATUS and BSR registers are saved on the fast return stack. If a fast return from interrupt is not used (see Section 4.3), the user may need to save the WREG, STATUS and BSR registers in software. Depending on the user's application, other registers may also need to be saved. Example 7-1 saves and restores the WREG, STATUS and BSR registers during an Interrupt Service Routine.

EXAMPLE 7-1: SAVING STATUS, WREG AND BSR REGISTERS IN RAM

```
MOVWF  W_TEMP          ; W_TEMP is in virtual bank
MOVFF  STATUS, STATUS_TEMP ; STATUS_TEMP located anywhere
MOVFF  BSR, BSR_TEMP    ; BSR located anywhere
;
; USER ISR CODE
;
MOVFF  BSR_TEMP, BSR    ; Restore BSR
MOVF   W_TEMP, W        ; Restore WREG
MOVFF  STATUS_TEMP, STATUS ; Restore STATUS
```

PIC18CXX2

FIGURE 8-2: BLOCK DIAGRAM OF RA4/T0CKI PIN

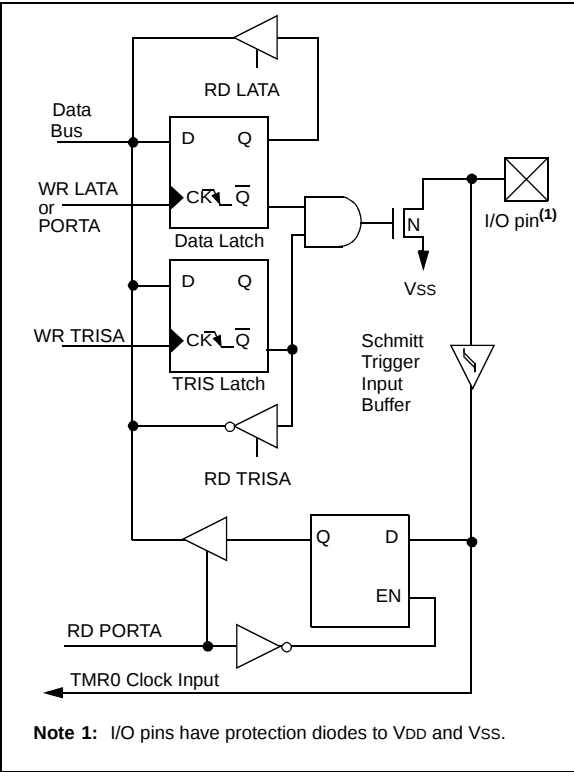
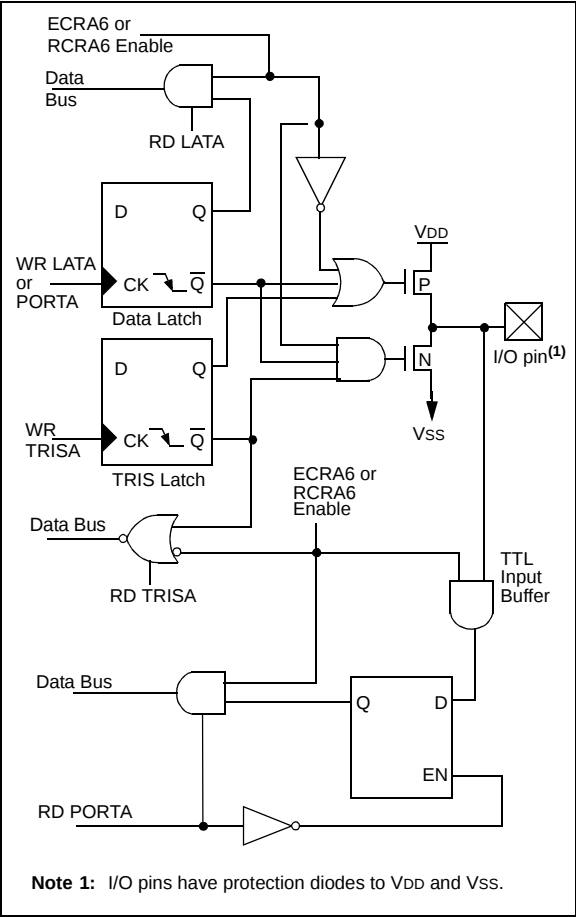


FIGURE 8-3: BLOCK DIAGRAM OF RA6



PIC18CXX2

REGISTER 8-1: TRISE REGISTER

R-0	R-0	R/W-0	R/W-0	U-0	R/W-1	R/W-1	R/W-1
IBF	OBF	IBOV	PSPMODE	—	TRISE2	TRISE1	TRISE0

bit 7

bit 0

- bit 7 **IBF:** Input Buffer Full Status bit
 1 = A word has been received and waiting to be read by the CPU
 0 = No word has been received
- bit 6 **OBF:** Output Buffer Full Status bit
 1 = The output buffer still holds a previously written word
 0 = The output buffer has been read
- bit 5 **IBOV:** Input Buffer Overflow Detect bit (in Microprocessor mode)
 1 = A write occurred when a previously input word has not been read
 (must be cleared in software)
 0 = No overflow occurred
- bit 4 **PSPMODE:** Parallel Slave Port Mode Select bit
 1 = Parallel Slave Port mode
 0 = General purpose I/O mode
- bit 3 **Unimplemented:** Read as '0'
- bit 2 **TRISE2:** RE2 Direction Control bit
 1 = Input
 0 = Output
- bit 1 **TRISE1:** RE1 Direction Control bit
 1 = Input
 0 = Output
- bit 0 **TRISE0:** RE0 Direction Control bit
 1 = Input
 0 = Output

Legend:

R = Readable bit	W = Writable bit	U = Unimplemented bit, read as '0'
- n = Value at POR	'1' = Bit is set	'0' = Bit is cleared x = Bit is unknown

PIC18CXX2

NOTES:

PIC18CXX2

10.1 Timer1 Operation

Timer1 can operate in one of these modes:

- As a timer
- As a synchronous counter
- As an asynchronous counter

The operating mode is determined by the clock select bit, TMR1CS (T1CON<1>).

When TMR1CS = 0, Timer1 increments every instruction cycle. When TMR1CS = 1, Timer1 increments on every rising edge of the external clock input or the Timer1 oscillator, if enabled.

When the Timer1 oscillator is enabled (T1OSCEN is set), the RC1/T1OSI and RC0/T1OSO/T1CKI pins become inputs. That is, the TRISC<1:0> value is ignored.

Timer1 also has an internal "RESET input". This RESET can be generated by the CCP module (Section 13.0).

FIGURE 10-1: TIMER1 BLOCK DIAGRAM

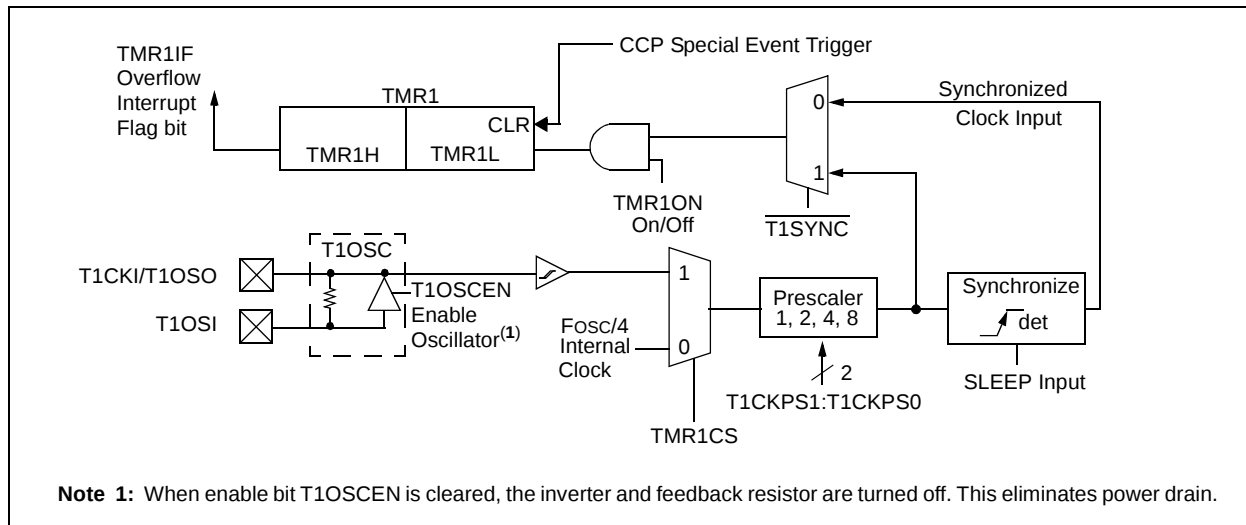
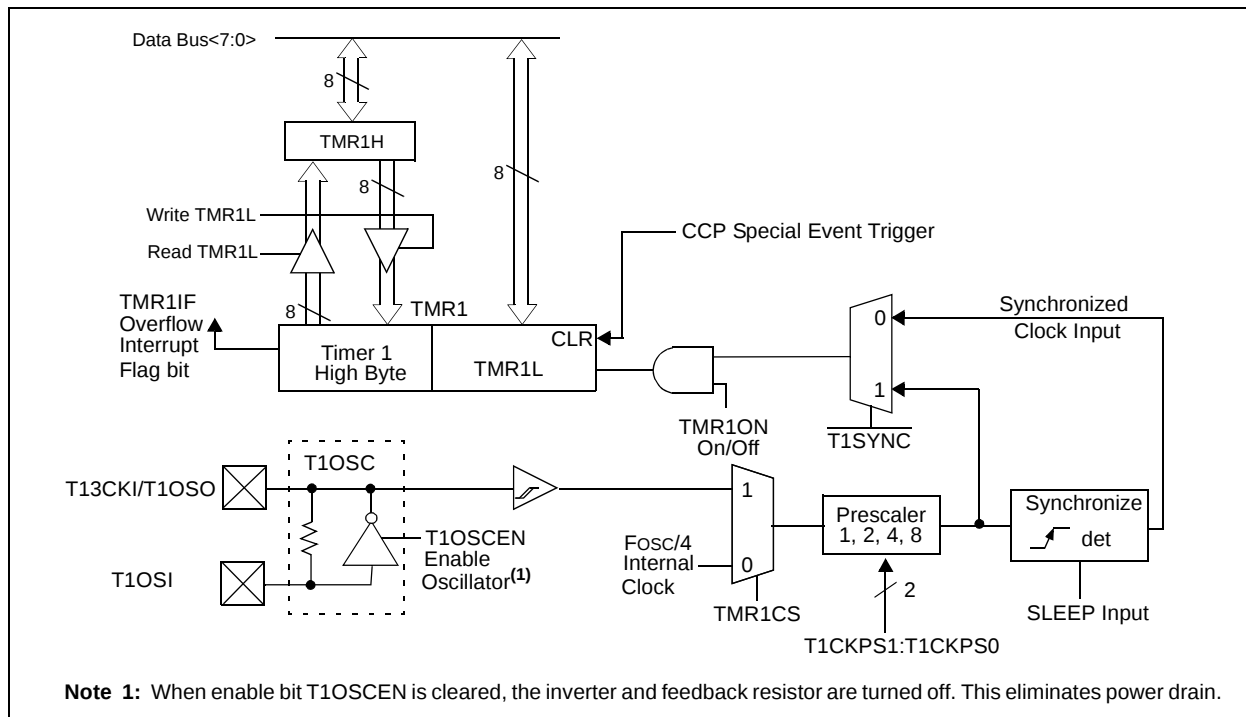


FIGURE 10-2: TIMER1 BLOCK DIAGRAM: 16-BIT READ/WRITE MODE



14.4.4.1 I²C Master Mode Operation

The master device generates all of the serial clock pulses and the START and STOP conditions. A transfer is ended with a STOP condition or with a Repeated START condition. Since the Repeated START condition is also the beginning of the next serial transfer, the I²C bus will not be released.

In Master Transmitter mode, serial data is output through SDA, while SCL outputs the serial clock. The first byte transmitted contains the slave address of the receiving device (7 bits) and the Read/Write (R/W) bit. In this case, the R/W bit will be logic '0'. Serial data is transmitted 8 bits at a time. After each byte is transmitted, an Acknowledge bit is received. START and STOP conditions are output to indicate the beginning and the end of a serial transfer.

In Master Receive mode, the first byte transmitted contains the slave address of the transmitting device (7 bits) and the R/W bit. In this case, the R/W bit will be logic '1'. Thus, the first byte transmitted is a 7-bit slave address followed by a '1' to indicate receive bit. Serial data is received via SDA, while SCL outputs the serial clock. Serial data is received 8 bits at a time. After each byte is received, an Acknowledge bit is transmitted. START and STOP conditions indicate the beginning and end of transmission.

The baud rate generator used for the SPI mode operation is now used to set the SCL clock frequency for either 100 kHz, 400 kHz, or 1 MHz I²C operation. The baud rate generator reload value is contained in the lower 7 bits of the SSPADD register. The baud rate generator will automatically begin counting on a write to the SSPBUF. Once the given operation is complete, (i.e., transmission of the last data bit is followed by ACK), the internal clock will automatically stop counting and the SCL pin will remain in its last state.

A typical transmit sequence would go as follows:

- a) The user generates a START condition by setting the START enable bit, SEN (SSPCON2<0>).
- b) SSPIF is set. The MSSP module will wait the required start time before any other operation takes place.
- c) The user loads the SSPBUF with the address to transmit.
- d) Address is shifted out the SDA pin until all 8 bits are transmitted.
- e) The MSSP module shifts in the ACK bit from the slave device and writes its value into the SSPCON2 register (SSPCON2<6>).
- f) The MSSP module generates an interrupt at the end of the ninth clock cycle by setting the SSPIF bit.
- g) The user loads the SSPBUF with eight bits of data.
- h) Data is shifted out the SDA pin until all 8 bits are transmitted.
- i) The MSSP module shifts in the ACK bit from the slave device and writes its value into the SSPCON2 register (SSPCON2<6>).
- j) The MSSP module generates an interrupt at the end of the ninth clock cycle by setting the SSPIF bit.
- k) The user generates a STOP condition by setting the STOP enable bit, PEN (SSPCON2<2>).
- l) Interrupt is generated once the STOP condition is complete.

14.4.5 BAUD RATE GENERATOR

In I²C Master mode, the reload value for the BRG is located in the lower 7 bits of the SSPADD register (Figure 14-14). When the BRG is loaded with this value, the BRG counts down to 0 and stops until another reload has taken place. The BRG count is dec-

rementated twice per instruction cycle (T_{cy}) on the Q2 and Q4 clocks. In I²C Master mode, the BRG is reloaded automatically. If Clock Arbitration is taking place, for instance, the BRG will be reloaded when the SCL pin is sampled high (Figure 14-15).

FIGURE 14-14: BAUD RATE GENERATOR BLOCK DIAGRAM

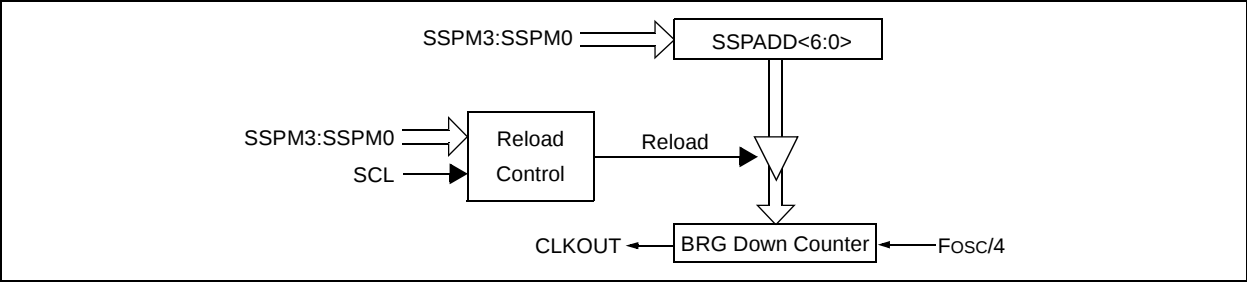


FIGURE 14-15: BAUD RATE GENERATOR TIMING WITH CLOCK ARBITRATION

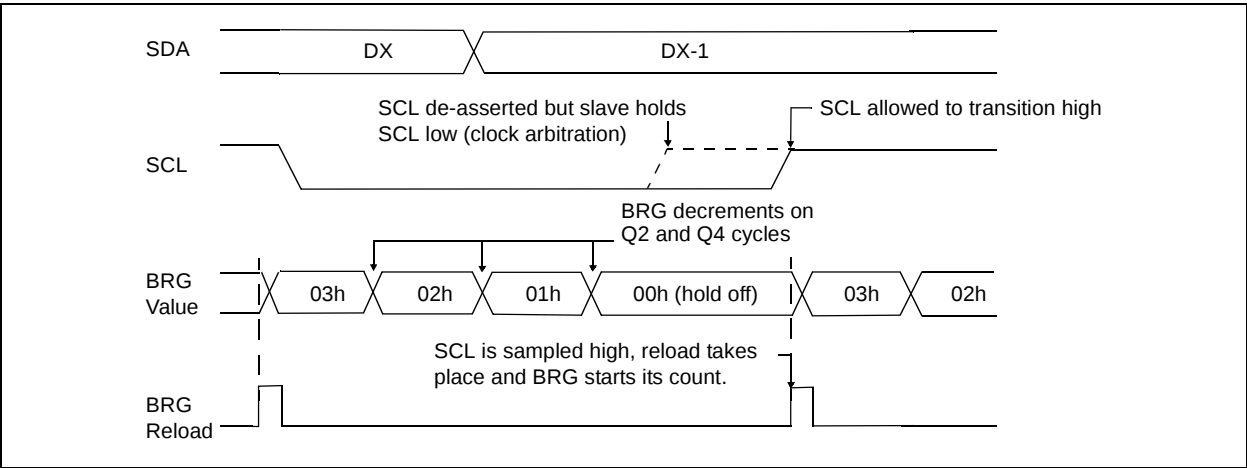
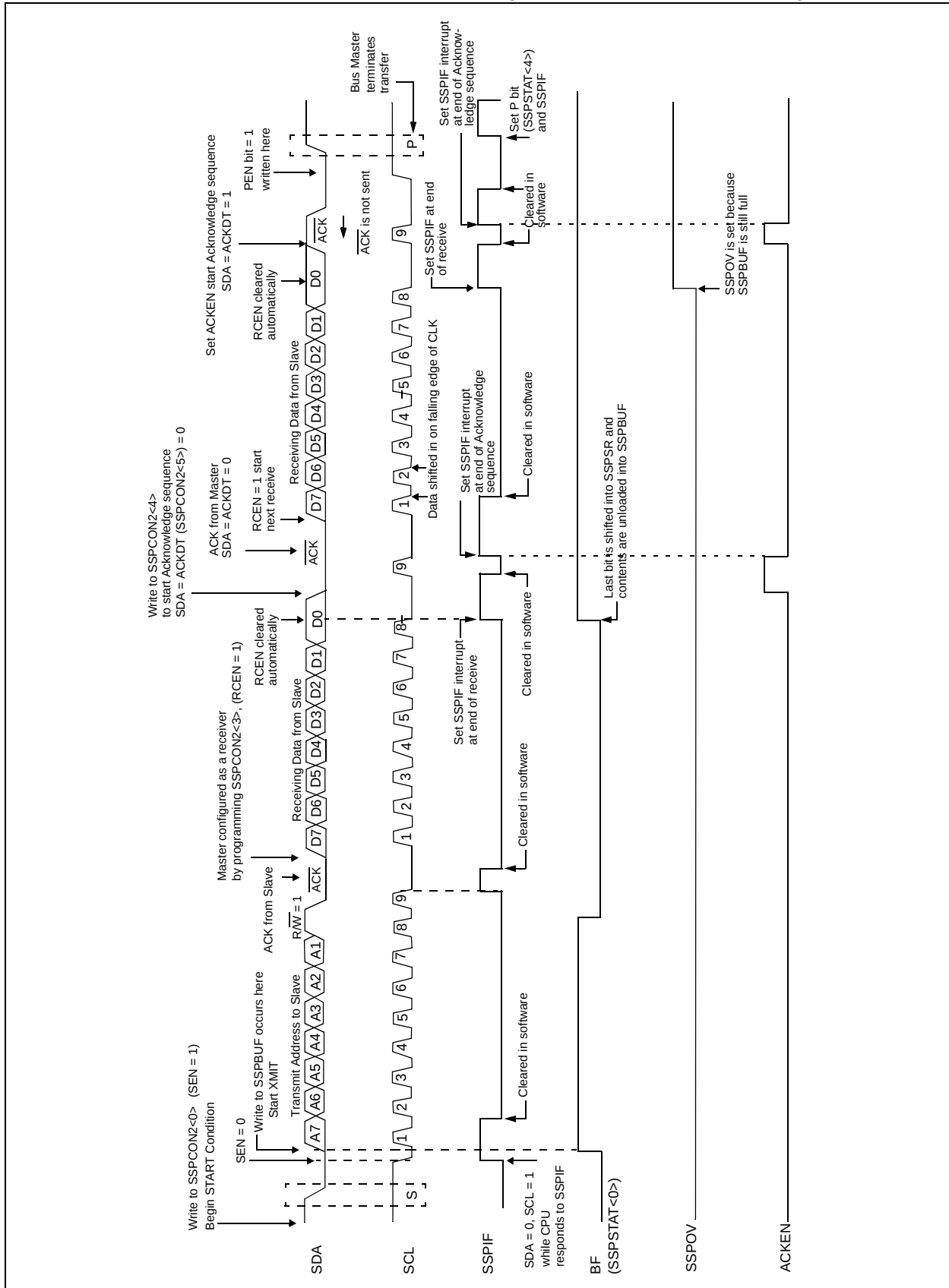


FIGURE 14-19: I²C MASTER MODE WAVEFORM (RECEPTION, 7-BIT ADDRESS)



PIC18CXX2

FIGURE 14-25: BUS COLLISION DURING START CONDITION (SCL = 0)

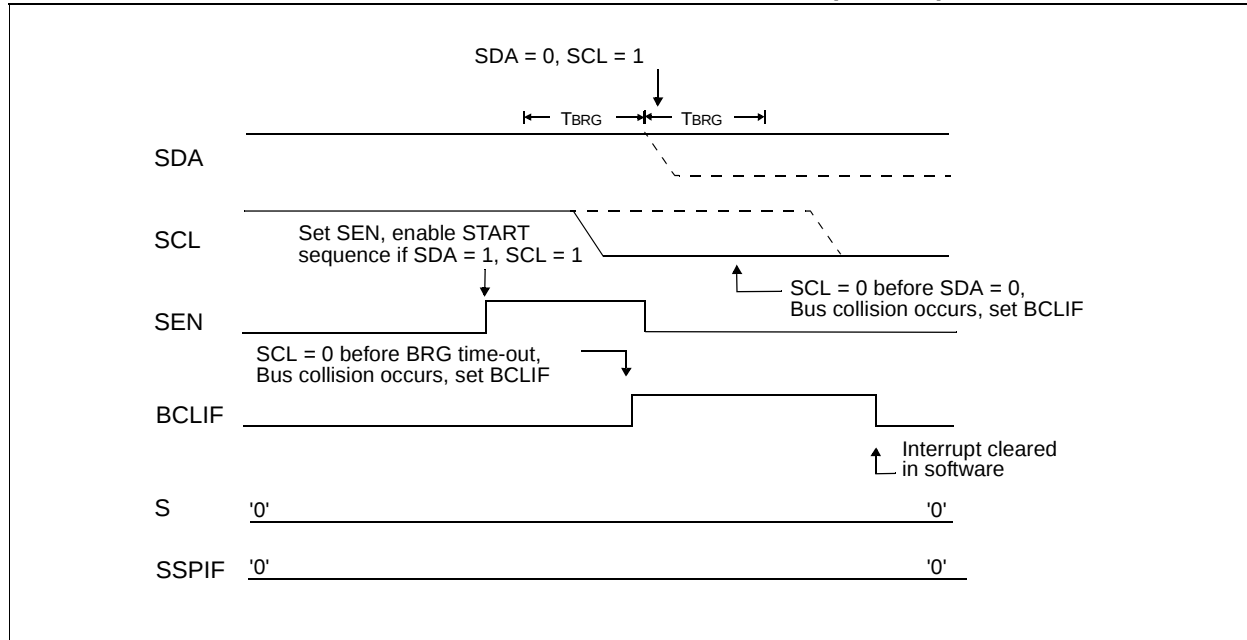
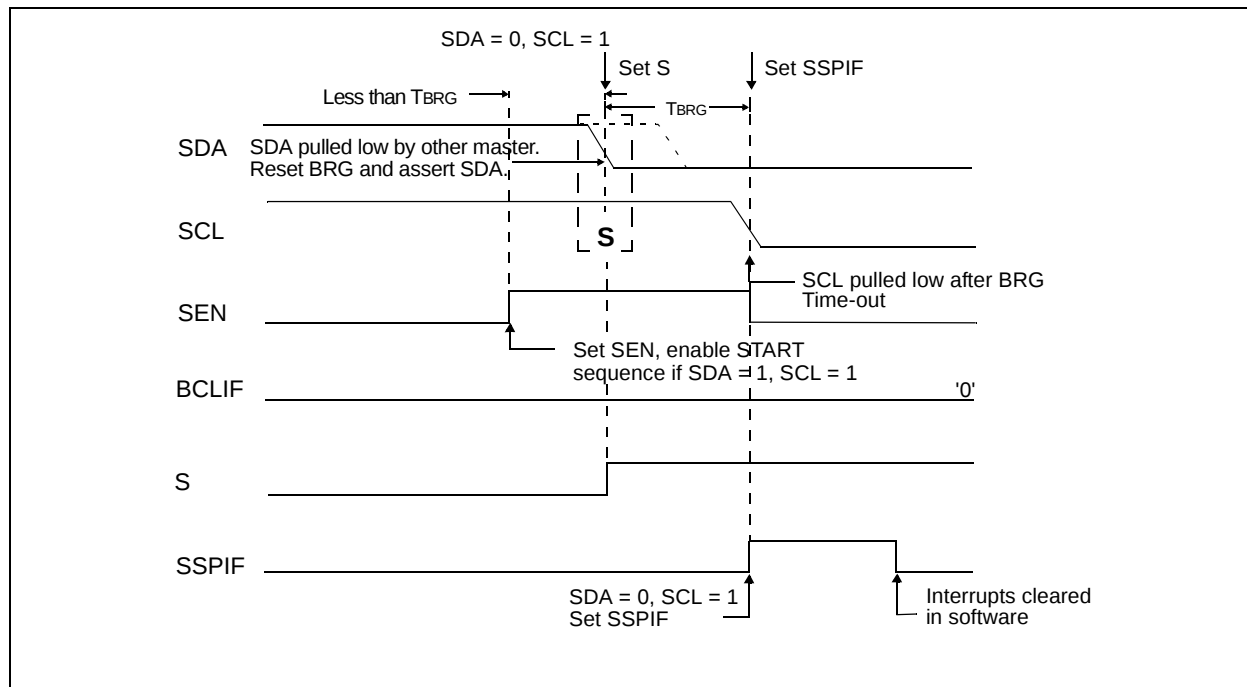


FIGURE 14-26: BRG RESET DUE TO SDA ARBITRATION DURING START CONDITION



15.1 USART Baud Rate Generator (BRG)

The BRG supports both the Asynchronous and Synchronous modes of the USART. It is a dedicated 8-bit baud rate generator. The SPBRG register controls the period of a free running 8-bit timer. In Asynchronous mode, bit BRGH (TXSTA<2>) also controls the baud rate. In Synchronous mode, bit BRGH is ignored. Table 15-1 shows the formula for computation of the baud rate for different USART modes, which only apply in Master mode (internal clock).

Given the desired baud rate and Fosc, the nearest integer value for the SPBRG register can be calculated using the formula in Table 15-1. From this, the error in baud rate can be determined.

Example 15-1 shows the calculation of the baud rate error for the following conditions:

- Fosc = 16 MHz
- Desired Baud Rate = 9600
- BRGH = 0
- SYNC = 0

It may be advantageous to use the high baud rate (BRGH = 1), even for slower baud clocks. This is because the $F_{osc}/(16(X+1))$ equation can reduce the baud rate error in some cases.

Writing a new value to the SPBRG register causes the BRG timer to be reset (or cleared). This ensures the BRG does not wait for a timer overflow before outputting the new baud rate.

15.1.1 SAMPLING

The data on the RC7/RX/DT pin is sampled three times by a majority detect circuit to determine if a high or a low level is present at the RX pin.

EXAMPLE 15-1: CALCULATING BAUD RATE ERROR

Desired Baud Rate	=	$F_{osc} / (64 (X + 1))$
Solving for X:		
X	=	$(F_{osc} / \text{Desired Baud rate}) / 64 - 1$
X	=	$((16000000 / 9600) / 64) - 1$
X	=	$[25.042] = 25$
Calculated Baud Rate	=	$16000000 / (64 (25 + 1))$
	=	9615
Error	=	$\frac{(\text{Calculated Baud Rate} - \text{Desired Baud Rate})}{\text{Desired Baud Rate}}$
	=	$(9615 - 9600) / 9600$
	=	0.16%

TABLE 15-1: BAUD RATE FORMULA

SYNC	BRGH = 0 (Low Speed)	BRGH = 1 (High Speed)
0	(Asynchronous) Baud Rate = $F_{osc}/(64(X+1))$	Baud Rate = $F_{osc}/(16(X+1))$
1	(Synchronous) Baud Rate = $F_{osc}/(4(X+1))$	NA

Legend: X = value in SPBRG (0 to 255)

TABLE 15-2: REGISTERS ASSOCIATED WITH BAUD RATE GENERATOR

Name	Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0	Value on POR, BOR	Value on all other RESETS
TXSTA	CSRC	TX9	TXEN	SYNC	—	BRGH	TRMT	TX9D	0000 -010	0000 -010
RCSTA	SPEN	RX9	SREN	CREN	ADDEN	FERR	OERR	RX9D	0000 -00x	0000 -00x
SPBRG	Baud Rate Generator Register								0000 0000	0000 0000

Legend: x = unknown, - = unimplemented, read as '0'. Shaded cells are not used by the BRG.

BNC Branch if Not Carry

Syntax: [label] BNC n

Operands: $-128 \leq n \leq 127$

Operation: if carry bit is '0'
(PC) + 2 + 2n → PC

Status Affected: None

Encoding:

1110	0011	nnnn	nnnn
------	------	------	------

Description: If the Carry bit is '0', then the program will branch.
The 2's complement number '2n' is added to the PC. Since the PC will have incremented to fetch the next instruction, the new address will be PC+2+2n. This instruction is then a two-cycle instruction.

Words: 1

Cycles: 1(2)

Q Cycle Activity:

If Jump:

Q1	Q2	Q3	Q4
Decode	Read literal 'n'	Process Data	Write to PC
No operation	No operation	No operation	No operation

If No Jump:

Q1	Q2	Q3	Q4
Decode	Read literal 'n'	Process Data	No operation

Example: HERE BNC Jump

Before Instruction

PC = address (HERE)

After Instruction

If Carry = 0;
PC = address (Jump)
If Carry = 1;
PC = address (HERE+2)

BNN Branch if Not Negative

Syntax: [label] BNN n

Operands: $-128 \leq n \leq 127$

Operation: if negative bit is '0'
(PC) + 2 + 2n → PC

Status Affected: None

Encoding:

1110	0111	nnnn	nnnn
------	------	------	------

Description: If the Negative bit is '0', then the program will branch.
The 2's complement number '2n' is added to the PC. Since the PC will have incremented to fetch the next instruction, the new address will be PC+2+2n. This instruction is then a two-cycle instruction.

Words: 1

Cycles: 1(2)

Q Cycle Activity:

If Jump:

Q1	Q2	Q3	Q4
Decode	Read literal 'n'	Process Data	Write to PC
No operation	No operation	No operation	No operation

If No Jump:

Q1	Q2	Q3	Q4
Decode	Read literal 'n'	Process Data	No operation

Example: HERE BNN Jump

Before Instruction

PC = address (HERE)

After Instruction

If Negative = 0;
PC = address (Jump)
If Negative = 1;
PC = address (HERE+2)

PIC18CXX2

MULLW Multiply Literal with WREG

Syntax: [*label*] MULLW *k*

Operands: $0 \leq k \leq 255$

Operation: $(WREG) \times k \rightarrow PRODH:PRODL$

Status Affected: None

Encoding:

0000	1101	kkkk	kkkk
------	------	------	------

Description: An unsigned multiplication is carried out between the contents of WREG and the 8-bit literal 'k'. The 16-bit result is placed in PRODH:PRODL register pair. PRODH contains the high byte. WREG is unchanged. None of the status flags are affected. Note that neither overflow, nor carry is possible in this operation. A zero result is possible but not detected.

Words: 1

Cycles: 1

Q Cycle Activity:

Q1	Q2	Q3	Q4
Decode	Read literal 'k'	Process Data	Write registers PRODH: PRODL

Example: MULLW 0xC4

Before Instruction

WREG	=	0xE2
PRODH	=	?
PRODL	=	?

After Instruction

WREG	=	0xE2
PRODH	=	0xAD
PRODL	=	0x08

MULWF Multiply WREG with f

Syntax: [*label*] MULWF *f* [,a]

Operands: $0 \leq f \leq 255$

$a \in [0,1]$

Operation: $(WREG) \times (f) \rightarrow PRODH:PRODL$

Status Affected: None

Encoding:

0000	001a	ffff	ffff
------	------	------	------

Description: An unsigned multiplication is carried out between the contents of WREG and the register file location 'f'. The 16-bit result is stored in the PRODH:PRODL register pair. PRODH contains the high byte.

Both WREG and 'f' are unchanged.

None of the status flags are affected.

Note that neither overflow, nor carry is possible in this operation. A zero result is possible but not detected. If 'a' is 0, the Access Bank will be selected, overriding the BSR value. If 'a'=1, then the bank will be selected as per the BSR value (default).

Words: 1

Cycles: 1

Q Cycle Activity:

Q1	Q2	Q3	Q4
Decode	Read register 'f'	Process Data	Write registers PRODH: PRODL

Example: MULWF REG, 1

Before Instruction

WREG	=	0xC4
REG	=	0xB5
PRODH	=	?
PRODL	=	?

After Instruction

WREG	=	0xC4
REG	=	0xB5
PRODH	=	0x8A
PRODL	=	0x94

RRNCF		Rotate Right f (no carry)								
Syntax:	[<i>label</i>] RRNCF f [,d [,a]]									
Operands:	0 ≤ f ≤ 255 d ∈ [0,1] a ∈ [0,1]									
Operation:	(f<n>) → dest<n-1>, (f<0>) → dest<7>									
Status Affected:	N,Z									
Encoding:	<table border="1"><tr><td>0100</td><td>00da</td><td>ffff</td><td>ffff</td></tr></table>						0100	00da	ffff	ffff
0100	00da	ffff	ffff							
Description:	The contents of register 'f' are rotated one bit to the right. If 'd' is 0, the result is placed in WREG. If 'd' is 1, the result is placed back in register 'f' (default). If 'a' is 0, the Access Bank will be selected, overriding the BSR value. If 'a' is 1, then the bank will be selected as per the BSR value (default). 									

Words: 1

Cycles: 1

Q Cycle Activity:

Q1	Q2	Q3	Q4
Decode	Read register 'f'	Process Data	Write to destination

Example 1: RRNCF REG, 1, 0

Before Instruction

REG = 1101 0111

After Instruction

REG = 1110 1011

Example 2: RRNCF REG, 0, 0

Before Instruction

WREG = ?

REG = 1101 0111

After Instruction

WREG = 1110 1011

REG = 1101 0111

SETF		Set f						
Syntax:	[label] SETF f [,a]							
Operands:	0 ≤ f ≤ 255 a ∈ [0,1]							
Operation:	FFh → f							
Status Affected:	None							
Encoding:	<table border="1"><tr><td>0110</td><td>100a</td><td>ffff</td><td>ffff</td></tr></table>				0110	100a	ffff	ffff
0110	100a	ffff	ffff					
Description:	The contents of the specified register are set to FFh. If 'a' is 0, the Access Bank will be selected, overriding the BSR value. If 'a' is 1, then the bank will be selected as per the BSR value (default).							
Words:	1							
Cycles:	1							
Q Cycle Activity:								
Q1		Q2		Q3		Q4		
Decode		Read register 'f'		Process Data		Write register 'f'		

Example: SETF REG, 1

Before Instruction

REG = 0x5A

After Instruction

REG = 0xFF

FIGURE 21-9: TIMER0 AND TIMER1 EXTERNAL CLOCK TIMINGS

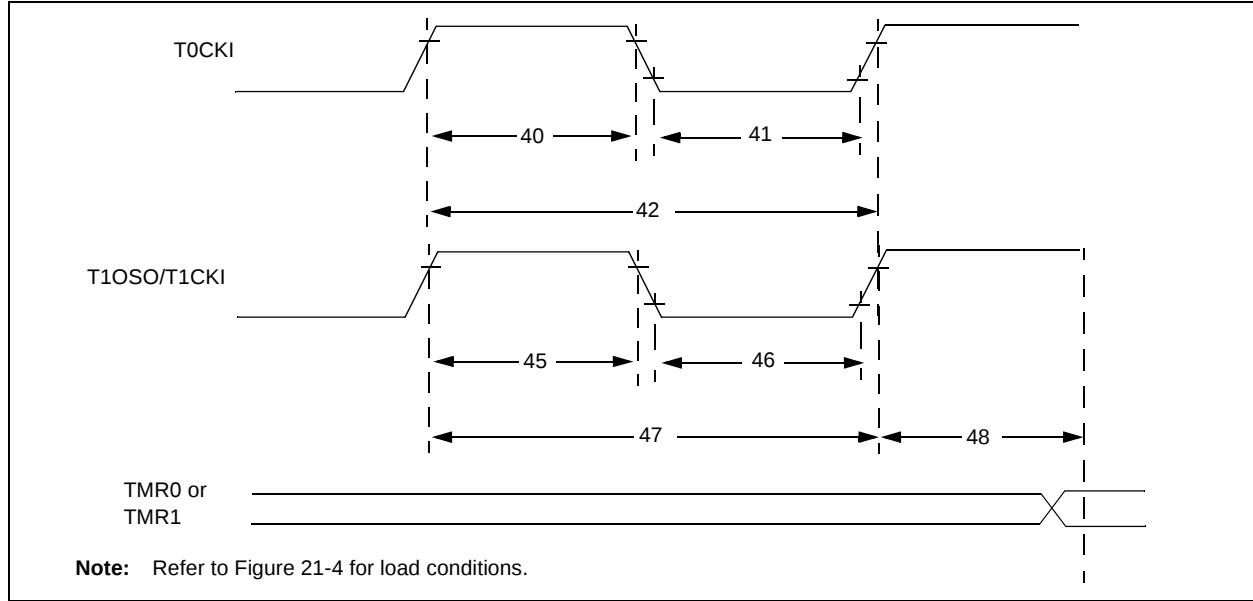
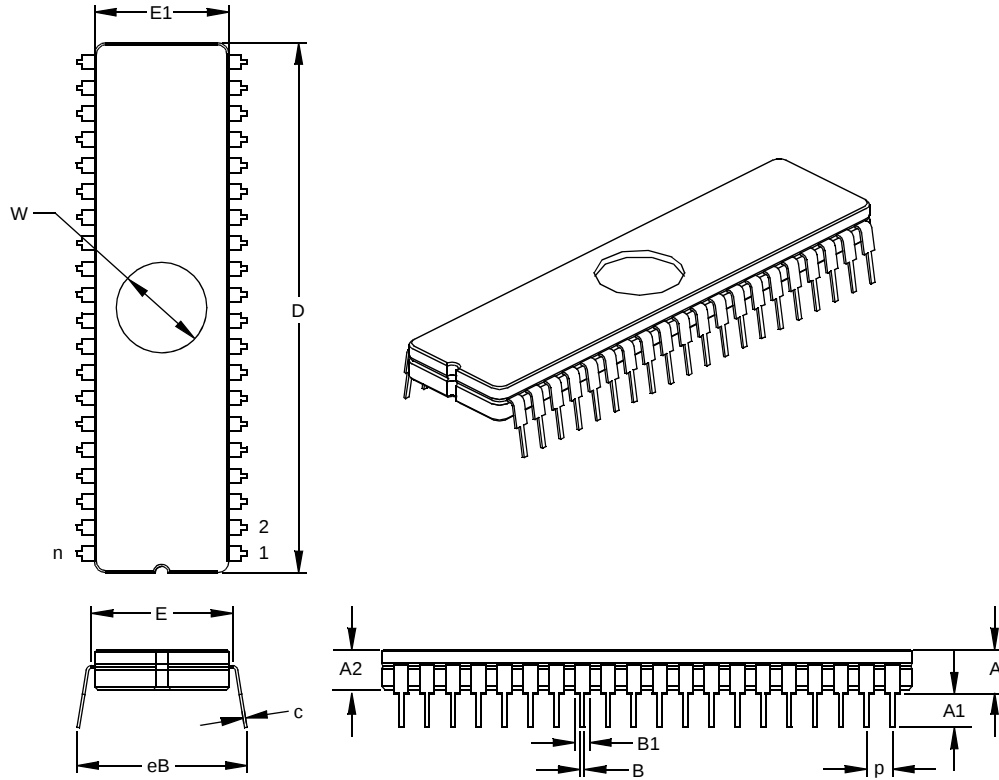


TABLE 21-8: TIMER0 AND TIMER1 EXTERNAL CLOCK REQUIREMENTS

Param No.	Symbol	Characteristic		Min	Max	Units	Conditions
40	Tt0H	T0CKI High Pulse Width	No Prescaler	$0.5T_{CY} + 20$	—	ns	
			With Prescaler	10	—	ns	
41	Tt0L	T0CKI Low Pulse Width	No Prescaler	$0.5T_{CY} + 20$	—	ns	
			With Prescaler	10	—	ns	
42	Tt0P	T0CKI Period	No Prescaler	$T_{CY} + 10$	—	ns	
			With Prescaler	Greater of: $20 \text{ ns or } \frac{T_{CY} + 40}{N}$	—	ns	
45	Tt1H	T1CKI High Time	Synchronous, no prescaler	$0.5T_{CY} + 20$	—	ns	
			Synchronous, with prescaler	PIC18CXXX	10	—	ns
				PIC18LCXXX	25	—	ns
			Asynchronous	PIC18CXXX	30	—	ns
				PIC18LCXXX	40	—	ns
46	Tt1L	T1CKI Low Time	Synchronous, no prescaler	$0.5T_{CY} + 20$	—	ns	
			Synchronous, with prescaler	PIC18CXXX	15	—	ns
				PIC18LCXXX	30	—	ns
			Asynchronous	PIC18CXXX	30	—	ns
				PIC18LCXXX	40	—	ns
47	Tt1P	T1CKI input period	Synchronous	Greater of: $20 \text{ ns or } \frac{T_{CY} + 40}{N}$	—	ns	N = prescale value (1, 2, 4, 8)
			Asynchronous	60	—	ns	
	Ft1	T1CKI oscillator input frequency range		DC	50	kHz	
48	Tcke2tmr1	Delay from external T1CKI clock edge to timer increment		$2T_{osc}$	$7T_{osc}$	—	

40-Lead Ceramic Dual In-line with Window (JW) – 600 mil (CERDIP)

Note: For the most current package drawings, please see the Microchip Packaging Specification located at <http://www.microchip.com/packages>



Units		INCHES*			MILLIMETERS		
Dimension Limits		MIN	NOM	MAX	MIN	NOM	MAX
Number of Pins	n		40			40	
Pitch	p		.100			2.54	
Top to Seating Plane	A	.185	.205	.225	4.70	5.21	5.72
Ceramic Package Height	A2	.155	.160	.165	3.94	4.06	4.19
Standoff	A1	.030	.045	.060	0.76	1.14	1.52
Shoulder to Shoulder Width	E	.595	.600	.625	15.11	15.24	15.88
Ceramic Pkg. Width	E1	.514	.520	.526	13.06	13.21	13.36
Overall Length	D	2.040	2.050	2.060	51.82	52.07	52.32
Tip to Seating Plane	L	.135	.140	.145	3.43	3.56	3.68
Lead Thickness	c	.008	.011	.014	0.20	0.28	0.36
Upper Lead Width	B1	.050	.053	.055	1.27	1.33	1.40
Lower Lead Width	B	.016	.020	.023	0.41	0.51	0.58
Overall Row Spacing §	eB	.610	.660	.710	15.49	16.76	18.03
Window Diameter	W	.340	.350	.360	8.64	8.89	9.14

* Controlling Parameter

§ Significant Characteristic

JEDEC Equivalent: MO-103

Drawing No. C04-014

PIC18CXX2

Code Examples

16 x 16 Signed Multiply Routine	62
16 x 16 Unsigned Multiply Routine	62
8 x 8 Signed Multiply Routine	61
8 x 8 Unsigned Multiply Routine	61
Changing Between Capture Prescalers	109
Fast Register Stack	39
Initializing PORTA	77
Initializing PORTB	80
Initializing PORTC	83
Initializing PORTD	85
Initializing PORTE	87
Loading the SSPBUF Register	122
Saving STATUS, WREG and BSR Registers in RAM	75
Code Protection	179, 186
COMF	204
Compare (CCP Module)	110
Associated Registers	111
Block Diagram	110
CCP Pin Configuration	110
CCPR1H:CCPR1L Registers	110
Software Interrupt	110
Special Event Trigger	99, 105, 110, 171
Timer1 Mode Selection	110
Configuration Bits	179
Context Saving During Interrupts	75
Example Code	75
Conversion Considerations	288
CPFSEQ	204
CPFSGT	205
CPFSLT	205

D

Data Memory	42
General Purpose Registers	42
Special Function Registers	42
DAW	206
DC Characteristics	237, 240
DECf	206
DECFSNZ	207
DECFSZ	207
Device Differences	287
Direct Addressing	51

E

Electrical Characteristics	235
Errata	5

F

Firmware Instructions	187
-----------------------------	-----

G

General Call Address Sequence	133
General Call Address Support	133
GOTO	208

I

I/O Ports	77
I ² C (SSP Module)	128
ACK Pulse	128, 129
Addressing	129
Block Diagram	128
Read/Write Bit Information (R/W Bit)	129
Reception	129
Serial Clock (RC3/SCK/SCL)	129
Slave Mode	128
Timing Diagram, Data	257
Timing Diagram, START/STOP Bits	256
Transmission	129
I ² C Master Mode Reception	139
I ² C Master Mode Repeated START Condition	138
I ² C Module	
Acknowledge Sequence Timing	142
Baud Rate Generator	
Block Diagram	
Baud Rate Generator	136
BRG Reset Due to SDA Collision	146
BRG Timing	136
Bus Collision	
Acknowledge	144
Repeated START Condition	147
Repeated START Condition Timing	
(Case 1)	147
Repeated START Condition Timing	
(Case 2)	147
START Condition	145
START Condition Timing	145, 146
STOP Condition	148
STOP Condition Timing (Case 1)	148
STOP Condition Timing (Case 2)	148
Transmit Timing	144
Bus Collision Timing	144
Clock Arbitration	143
Clock Arbitration Timing (Master Transmit)	143
General Call Address Support	133
Master Mode 7-bit Reception Timing	141
Master Mode Operation	135
Master Mode START Condition	137
Master Mode Transmission	139
Master Mode Transmit Sequence	135
Multi-Master Mode	144
Repeat START Condition Timing	138
STOP Condition Receive or Transmit Timing	143
STOP Condition Timing	142
Waveforms for 7-bit Reception	130
Waveforms for 7-bit Transmission	130
ICEPIC In-Circuit Emulator	230
ID Locations	179, 186
INCF	208
INCFSZ	209
In-Circuit Serial Programming (ICSP)	179, 186
Indirect Addressing	51
FSR Register	50
INFSNZ	209
Instruction Cycle	39
Instruction Flow/Pipelining	40
Instruction Format	189

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