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"[Embedded - Microcontrollers](#)" refer to small, integrated circuits designed to perform specific tasks within larger systems. These microcontrollers are essentially compact computers on a single chip, containing a processor core, memory, and programmable input/output peripherals. They are called "embedded" because they are embedded within electronic devices to control various functions, rather than serving as standalone computers. Microcontrollers are crucial in modern electronics, providing the intelligence and control needed for a wide range of applications.

### Applications of "[Embedded - Microcontrollers](#)"

#### Details

Product Status	Active
Core Processor	PIC
Core Size	16-Bit
Speed	32MHz
Connectivity	I <sup>2</sup> C, IrDA, LINbus, SmartCard, SPI, UART/USART
Peripherals	AES, Brown-out Detect/Reset, DMA, I <sup>2</sup> S, HLVD, POR, PWM, WDT
Number of I/O	20
Program Memory Size	64KB (64K x 8)
Program Memory Type	FLASH
EEPROM Size	-
RAM Size	8K x 8
Voltage - Supply (Vcc/Vdd)	2V ~ 3.6V
Data Converters	A/D 9x10b/12b
Oscillator Type	Internal
Operating Temperature	-40°C ~ 125°C (TA)
Mounting Type	Surface Mount
Package / Case	28-SOIC (0.295", 7.50mm Width)
Supplier Device Package	28-SOIC
Purchase URL	<a href="https://www.e-xfl.com/product-detail/microchip-technology/pic24fj64gb202-e-so">https://www.e-xfl.com/product-detail/microchip-technology/pic24fj64gb202-e-so</a>

# PIC24FJ128GB204 FAMILY

**TABLE 1-3: PIC24FJ128GB204 FAMILY PINOUT DESCRIPTION (CONTINUED)**

Pin Function	Pin Number/Grid Locator			I/O	Input Buffer	Description
	28-Pin SPDIP/SOIC/SSOP	28-Pin QFN-S	44-Pin TQFP/QFN			
T1CK	18	15	1	I	ST	Timer1 Clock.
T2CK	26	23	15	I	ST	Timer2 Clock.
T3CK	26	23	15	I	ST	Timer3 Clock.
T4CK	6	3	23	I	ST	Timer4 Clock.
T5CK	6	3	23	I	ST	Timer5 Clock.
TCK	17	14	13	I	ST	JTAG Test Clock/Programming Clock Input.
TDI	16	13	35	I	ST	JTAG Test Data/Programming Data Input.
TDO	18	15	32	O	—	JTAG Test Data Output.
TMS	14	11	12	I	—	JTAG Test Mode Select Input.
USBID	14	11	41	I	ST	USB OTG ID (OTG mode only).
USBOEN	17	14	44	O	—	USB Output Enable Control (for external transceiver).
VBAT	19	16	6	P	—	Backup Battery (B+) Input (1.2V nominal).
VBUS	15	12	42	P	—	USB Voltage, Host mode (5V).
VCAP	20	17	7	P	—	External Filter Capacitor Connection.
VDD	13,28	25	28,40	P	—	Positive Supply for Peripheral Digital Logic and I/O Pins.
VDDCORE	20	17	7	—	—	Microcontroller Core Supply Voltage.
VREF+	2	27	19	I	ANA	A/D Reference Voltage Input (+).
VREF-	3	28	20	I	ANA	A/D Reference Voltage Input (-).
VSS	8,27	5,24	29,39	P	—	Ground Reference for Logic and I/O Pins.
VUSB3V3	23	20	10	P	—	USB Transceiver Power Input Voltage (3.3V nominal).

**Legend:** ST = Schmitt Trigger input

ANA = Analog input

I<sup>2</sup>C = ST with I<sup>2</sup>C™ or SMBus levels

TTL = TTL compatible input

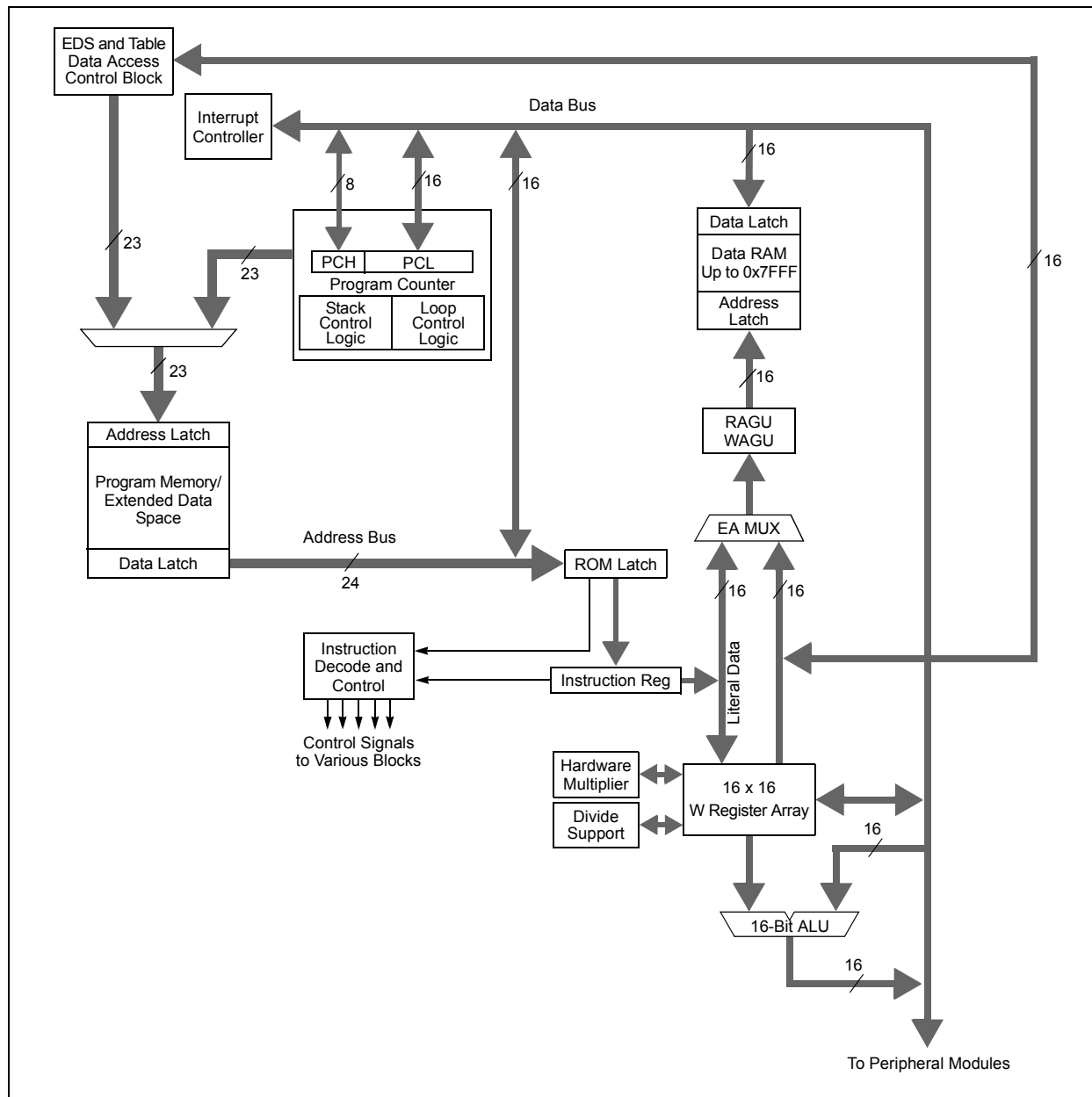
O = Output

I = Input

P = Power

# PIC24FJ128GB204 FAMILY

**FIGURE 3-1: PIC24F CPU CORE BLOCK DIAGRAM**



**TABLE 3-1: CPU CORE REGISTERS**

Register(s) Name	Description
W0 through W15	Working Register Array
PC	23-Bit Program Counter
SR	ALU STATUS Register
SPLIM	Stack Pointer Limit Value Register
TBLPAG	Table Memory Page Address Register
RCOUNT	REPEAT Loop Counter Register
CORCON	CPU Control Register
DISICNT	Disable Interrupt Count Register
DSRPAG	Data Space Read Page Register
DSWPAG	Data Space Write Page Register

# PIC24FJ128GB204 FAMILY

## REGISTER 7-1: RCON: RESET CONTROL REGISTER

R/W-0	R/W-0	U-0	R/W-0	U-0	R/W-0	R/W-0	R/W-0
TRAPR <sup>(1)</sup>	IOPUWR <sup>(1)</sup>	—	RETEN <sup>(2)</sup>	—	DPSLP <sup>(1)</sup>	CM <sup>(1)</sup>	VREGS <sup>(3)</sup>
bit 15						bit 8	

R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-1	R/W-1
EXTR <sup>(1)</sup>	SWR <sup>(1)</sup>	SWDTEN <sup>(4)</sup>	WDTO <sup>(1)</sup>	SLEEP <sup>(1)</sup>	IDLE <sup>(1)</sup>	BOR <sup>(1)</sup>	POR <sup>(1)</sup>
bit 7						bit 0	

### Legend:

R = Readable bit

W = Writable bit

U = Unimplemented bit, read as '0'

-n = Value at POR

'1' = Bit is set

'0' = Bit is cleared

x = Bit is unknown

- bit 15 **TRAPR:** Trap Reset Flag bit<sup>(1)</sup>  
 1 = A Trap Conflict Reset has occurred  
 0 = A Trap Conflict Reset has not occurred
- bit 14 **IOPUWR:** Illegal Opcode or Uninitialized W Access Reset Flag bit<sup>(1)</sup>  
 1 = An illegal opcode detection, an illegal address mode or Uninitialized W register is used as an Address Pointer and caused a Reset  
 0 = An illegal opcode or Uninitialized W register Reset has not occurred
- bit 13 **Unimplemented:** Read as '0'
- bit 12 **RETEN:** Retention Mode Enable bit<sup>(2)</sup>  
 1 = Retention mode is enabled while device is in Sleep modes (1.2V regulator supplies to the core)  
 0 = Retention mode is disabled; normal voltage levels are present
- bit 11 **Unimplemented:** Read as '0'
- bit 10 **DPSLP:** Deep Sleep Flag bit<sup>(1)</sup>  
 1 = Device has been in Deep Sleep mode  
 0 = Device has not been in Deep Sleep mode
- bit 9 **CM:** Configuration Word Mismatch Reset Flag bit<sup>(1)</sup>  
 1 = A Configuration Word Mismatch Reset has occurred  
 0 = A Configuration Word Mismatch Reset has not occurred
- bit 8 **VREGS:** Program Memory Power During Sleep bit<sup>(3)</sup>  
 1 = Program memory bias voltage remains powered during Sleep  
 0 = Program memory bias voltage is powered down during Sleep
- bit 7 **EXTR:** External Reset ( $\overline{\text{MCLR}}$ ) Pin bit<sup>(1)</sup>  
 1 = A Master Clear (pin) Reset has occurred  
 0 = A Master Clear (pin) Reset has not occurred
- bit 6 **SWR:** Software Reset (Instruction) Flag bit<sup>(1)</sup>  
 1 = A RESET instruction has been executed  
 0 = A RESET instruction has not been executed

**Note 1:** All of the Reset status bits may be set or cleared in software. Setting one of these bits in software does not cause a device Reset.

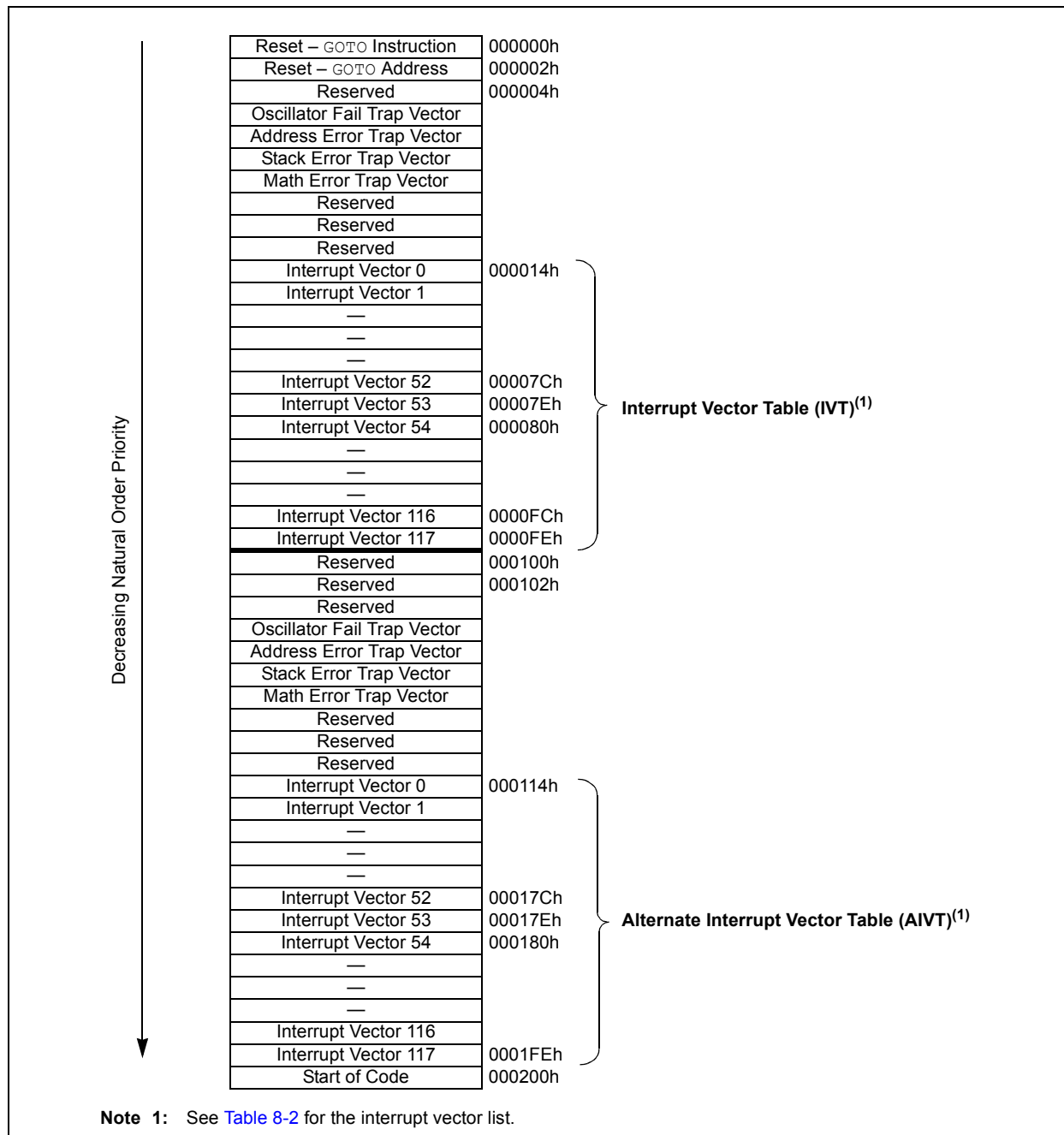
**2:** If the  $\overline{\text{LPCFG}}$  Configuration bit is '1' (unprogrammed), the retention regulator is disabled and the RETEN bit has no effect.

**3:** Re-enabling the regulator after it enters Standby mode will add a delay,  $T_{\text{VREG}}$ , when waking up from Sleep. Applications that do not use the voltage regulator should set this bit to prevent this delay from occurring.

**4:** If the FWDTEN Configuration bit is '1' (unprogrammed), the WDT is always enabled, regardless of the SWDTEN bit setting.

# PIC24FJ128GB204 FAMILY

**FIGURE 8-1: PIC24F INTERRUPT VECTOR TABLE**



**TABLE 8-1: TRAP VECTOR DETAILS**

Vector Number	IVT Address	AIVT Address	Trap Source
0	000004h	000104h	Reserved
1	000006h	000106h	Oscillator Failure
2	000008h	000108h	Address Error
3	00000Ah	00010Ah	Stack Error
4	00000Ch	00010Ch	Math Error
5	00000Eh	00010Eh	Reserved
6	000010h	000110h	Reserved
7	000012h	000112h	Reserved

# PIC24FJ128GB204 FAMILY

## REGISTER 8-43: IPC26: INTERRUPT PRIORITY CONTROL REGISTER 26

U-0	U-0	U-0	U-0	U-0	R/W-1	R/W-0	R/W-0
—	—	—	—	—	FSTIP<2:0>		
bit 15						bit 8	

U-0	U-0	U-0	U-0	U-0	U-0	U-0	U-0
—	—	—	—	—	—	—	—
bit 7						bit 0	

### Legend:

R = Readable bit

W = Writable bit

U = Unimplemented bit, read as '0'

-n = Value at POR

'1' = Bit is set

'0' = Bit is cleared

x = Bit is unknown

bit 15-11 **Unimplemented:** Read as '0'

bit 10-8 **FSTIP<2:0>:** FRC Self-Tune Interrupt Priority bits  
 111 = Interrupt is Priority 7 (highest priority interrupt)

•  
•  
•

001 = Interrupt is Priority 1

000 = Interrupt source is disabled

bit 7-0 **Unimplemented:** Read as '0'

## REGISTER 8-44: IPC29: INTERRUPT PRIORITY CONTROL REGISTER 29

U-0	U-0	U-0	U-0	U-0	U-0	U-0	U-0
—	—	—	—	—	—	—	—
bit 15						bit 8	

U-0	R/W-1	R/W-0	R/W-0	U-0	U-0	U-0	U-0
—	JTAGIP<2:0>			—	—	—	—
bit 7				bit 0			

### Legend:

R = Readable bit

W = Writable bit

U = Unimplemented bit, read as '0'

-n = Value at POR

'1' = Bit is set

'0' = Bit is cleared

x = Bit is unknown

bit 15-7 **Unimplemented:** Read as '0'

bit 6-4 **JTAGIP<2:0>:** JTAG Interrupt Priority bits  
 111 = Interrupt is Priority 7 (highest priority interrupt)

•  
•  
•

001 = Interrupt is Priority 1

000 = Interrupt source is disabled

bit 3-0 **Unimplemented:** Read as '0'

## 9.4 Clock Switching Operation

With few limitations, applications are free to switch between any of the four clock sources (POSC, SOSC, FRC and LPRC) under software control and at any time. To limit the possible side effects that could result from this flexibility, PIC24F devices have a safeguard lock built into the switching process.

**Note:** The Primary Oscillator mode has three different submodes (XT, HS and EC) which are determined by the POSCMDx Configuration bits. While an application can switch to and from Primary Oscillator mode in software, it cannot switch between the different primary submodes without reprogramming the device.

### 9.4.1 ENABLING CLOCK SWITCHING

To enable clock switching, the FCKSM1 Configuration bit in CW2 must be programmed to '0'. (For more information, refer to [Section 30.1 "Configuration Bits"](#).) If the FCKSM1 Configuration bit is unprogrammed ('1'), the clock switching function and Fail-Safe Clock Monitor function are disabled; this is the default setting.

The NOSCx control bits (OSCCON<10:8>) do not control the clock selection when clock switching is disabled. However, the COSC<2:0> bits (OSCCON<14:12>) will reflect the clock source selected by the FNOSCx Configuration bits.

The OSWEN control bit (OSCCON<0>) has no effect when clock switching is disabled; it is held at '0' at all times.

### 9.4.2 OSCILLATOR SWITCHING SEQUENCE

At a minimum, performing a clock switch requires this basic sequence:

1. If desired, read the COSC<2:0> bits (OSCCON<14:12>) to determine the current oscillator source.
2. Perform the unlock sequence to allow a write to the OSCCON register high byte.
3. Write the appropriate value to the NOSCx bits (OSCCON<10:8>) for the new oscillator source.
4. Perform the unlock sequence to allow a write to the OSCCON register low byte.
5. Set the OSWEN bit to initiate the oscillator switch.

Once the basic sequence is completed, the system clock hardware responds automatically as follows:

1. The clock switching hardware compares the COSCx bits with the new value of the NOSCx bits. If they are the same, then the clock switch is a redundant operation. In this case, the OSWEN bit is cleared automatically and the clock switch is aborted.
2. If a valid clock switch has been initiated, the LOCK (OSCCON<5>) and CF (OSCCON<3>) bits are cleared.
3. The new oscillator is turned on by the hardware if it is not currently running. If a crystal oscillator must be turned on, the hardware will wait until the OST expires. If the new source is using the PLL, then the hardware waits until a PLL lock is detected (LOCK = 1).
4. The hardware waits for 10 clock cycles from the new clock source and then performs the clock switch.
5. The hardware clears the OSWEN bit to indicate a successful clock transition. In addition, the NOSCx bits value is transferred to the COSCx bits.
6. The old clock source is turned off at this time, with the exception of LPRC (if WDT or FSCM is enabled) or SOSC (if SOSSEN remains set).

**Note 1:** The processor will continue to execute code throughout the clock switching sequence. Timing-sensitive code should not be executed during this time.

- 2:** Direct clock switches between any Primary Oscillator mode with PLL and FRCPLL mode are not permitted. This applies to clock switches in either direction. In these instances, the application must switch to FRC mode as a transitional clock source between the two PLL modes.

# PIC24FJ128GB204 FAMILY

## REGISTER 15-1: OCxCON1: OUTPUT COMPARE x CONTROL REGISTER 1 (CONTINUED)

- bit 4      **OCFLT0**: Output Compare x PWM Fault 0 (OCFA pin) Condition Status bit<sup>(2,4)</sup>  
1 = PWM Fault 0 has occurred  
0 = No PWM Fault 0 has occurred
- bit 3      **TRIGMODE**: Trigger Status Mode Select bit  
1 = TRIGSTAT (OCxCON2<6>) is cleared when OCxRS = OCxTMR or in software  
0 = TRIGSTAT is only cleared by software
- bit 2-0    **OCM<2:0>**: Output Compare x Mode Select bits<sup>(1)</sup>  
111 = Center-Aligned PWM mode on OCx<sup>(2)</sup>  
110 = Edge-Aligned PWM mode on OCx<sup>(2)</sup>  
101 = Double Compare Continuous Pulse mode: Initializes the OCx pin low; toggles the OCx state continuously on alternate matches of OCxR and OCxRS  
100 = Double Compare Single-Shot mode: Initializes the OCx pin low; toggles the OCx state on matches of OCxR and OCxRS for one cycle  
011 = Single Compare Continuous Pulse mode: Compare events continuously toggle the OCx pin  
010 = Single Compare Single-Shot mode: Initializes OCx pin high; compare event forces the OCx pin low  
001 = Single Compare Single-Shot mode: Initializes OCx pin low; compare event forces the OCx pin high  
000 = Output compare channel is disabled

**Note 1:** The OCx output must also be configured to an available RPn pin. For more information, see [Section 11.4 “Peripheral Pin Select \(PPS\)”](#).

**2:** The Fault input enable and Fault status bits are valid when OCM<2:0> = 111 or 110.

**3:** The Comparator 1 output controls the OC1-OC2 channels; Comparator 2 output controls the OC3-OC4 channels; Comparator 3 output controls the OC5-OC6 channels.

**4:** The OCFA/OCFB Fault input must also be configured to an available RPn/RPIn pin. For more information, see [Section 11.4 “Peripheral Pin Select \(PPS\)”](#).



# PIC24FJ128GB204 FAMILY

## REGISTER 16-2: SPIxCON1H: SPIx CONTROL REGISTER 1 HIGH

R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0
AUDEN <sup>(1)</sup>	SPISGNEXT	IGNROV	IGNTUR	AUDMONO <sup>(2)</sup>	URDTEN <sup>(3)</sup>	AUDMOD1 <sup>(4)</sup>	AUDMOD0 <sup>(4)</sup>
bit 15						bit 8	

R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0
FRMEN	FRMSYNC	FRMPOL	MSEN	FRMSYPW	FRMCNT2	FRMCNT1	FRMCNT0
bit 7						bit 0	

### Legend:

R = Readable bit

W = Writable bit

U = Unimplemented bit, read as '0'

-n = Value at POR

'1' = Bit is set

'0' = Bit is cleared

x = Bit is unknown

bit 15 **AUDEN:** Audio Codec Support Enable bit<sup>(1)</sup>

1 = Audio protocol is enabled; MSTEN controls the direction of both SCKx and Frame (a.k.a. LRC), and this module functions as if FRMEN = 1, FRMSYNC = MSTEN, FRMCNT<2:0> = 001 and SMP = 0, regardless of their actual values  
0 = Audio protocol is disabled

bit 14 **SPISGNEXT:** SPIx Sign-Extend RX FIFO Read Data Enable bit

1 = Data from RX FIFO is sign-extended  
0 = Data from RX FIFO is not sign-extended

bit 13 **IGNROV:** Ignore Receive Overflow bit

1 = A Receive Overflow (ROV) is NOT a critical error; during ROV, data in the FIFO is not overwritten by the receive data  
0 = A ROV is a critical error that stops SPI operation

bit 12 **IGNTUR:** Ignore Transmit Underrun bit

1 = A Transmit Underrun (TUR) is NOT a critical error and data indicated by URDTEN is transmitted until the SPIxTXB is not empty  
0 = A TUR is a critical error that stops SPI operation

bit 11 **AUDMONO:** Audio Data Format Transmit bit<sup>(2)</sup>

1 = Audio data is mono (i.e., each data word is transmitted on both left and right channels)  
0 = Audio data is stereo

bit 10 **URDTEN:** Transmit Underrun Data Enable bit<sup>(3)</sup>

1 = Transmits data out of SPIxURDTL/H registers during Transmit Underrun (TUR) conditions  
0 = Transmits the last received data during Transmit Underrun conditions

bit 9-8 **AUDMOD<1:0>:** Audio Protocol Mode Selection bits<sup>(4)</sup>

11 = PCM/DSP mode  
10 = Right Justified mode: This module functions as if SPIFE = 1, regardless of its actual value  
01 = Left Justified mode: This module functions as if SPIFE = 1, regardless of its actual value  
00 = I<sup>2</sup>S mode: This module functions as if SPIFE = 0, regardless of its actual value

bit 7 **FRMEN:** Framed SPIx Support bit

1 = Framed SPIx support is enabled ( $\overline{\text{SSx}}$  pin is used as the FSYNC input/output)  
0 = Framed SPIx support is disabled

**Note 1:** AUDEN can only be written when the SPIEN bit = 0.

**2:** AUDMONO can only be written when the SPIEN bit = 0 and is only valid for AUDEN = 1.

**3:** URDTEN is only valid when IGNTUR = 1.

**4:** AUDMOD<1:0> can only be written when the SPIEN bit = 0 and are only valid when AUDEN = 1. When NOT in PCM/DSP mode, this module functions as if FRMSYPW = 1, regardless of its actual value.

# PIC24FJ128GB204 FAMILY

## 18.2 Transmitting in 8-Bit Data Mode

1. Set up the UARTx:
  - a) Write appropriate values for data, parity and Stop bits.
  - b) Write appropriate baud rate value to the UxBRG register.
  - c) Set up transmit and receive interrupt enable and priority bits.
2. Enable the UARTx.
3. Set the UTXEN bit (causes a transmit interrupt, two cycles after being set).
4. Write a data byte to the lower byte of the UxTXREG word. The value will be immediately transferred to the Transmit Shift Register (TSR) and the serial bit stream will start shifting out with the next rising edge of the baud clock.
5. Alternatively, the data byte may be transferred while UTXEN = 0 and then, the user may set UTXEN. This will cause the serial bit stream to begin immediately because the baud clock will start from a cleared state.
6. A transmit interrupt will be generated as per interrupt control bits, UTXISEL<1:0>.

## 18.3 Transmitting in 9-Bit Data Mode

1. Set up the UARTx (as described in [Section 18.2 “Transmitting in 8-Bit Data Mode”](#)).
2. Enable the UARTx.
3. Set the UTXEN bit (causes a transmit interrupt).
4. Write UxTXREG as a 16-bit value only.
5. A word write to UxTXREG triggers the transfer of the 9-bit data to the TSR. The serial bit stream will start shifting out with the first rising edge of the baud clock.
6. A transmit interrupt will be generated as per the setting of control bits, UTXISEL<1:0>.

## 18.4 Break and Sync Transmit Sequence

The following sequence will send a message frame header, made up of a Break, followed by an auto-baud Sync byte.

1. Configure the UARTx for the desired mode.
2. Set UTXEN and UTXBRK to set up the Break character.
3. Load the UxTXREG with a dummy character to initiate transmission (value is ignored).
4. Write '55h' to UxTXREG; this loads the Sync character into the transmit FIFO.
5. After the Break has been sent, the UTXBRK bit is reset by hardware. The Sync character now transmits.

## 18.5 Receiving in 8-Bit or 9-Bit Data Mode

1. Set up the UARTx (as described in [Section 18.2 “Transmitting in 8-Bit Data Mode”](#)).
2. Enable the UARTx.
3. Set the URXEN bit (UxSTA<12>).
4. A receive interrupt will be generated when one or more data characters have been received as per interrupt control bits, URXISEL<1:0>.
5. Read the OERR bit to determine if an overrun error has occurred. The OERR bit must be reset in software.
6. Read UxRXREG.

The act of reading the UxRXREG character will move the next character to the top of the receive FIFO, including a new set of PERR and FERR values.

## 18.6 Operation of $\overline{\text{UxCTS}}$ and $\overline{\text{UxRTS}}$ Control Pins

UARTx Clear-to-Send ( $\overline{\text{UxCTS}}$ ) and Request-to-Send ( $\overline{\text{UxRTS}}$ ) are the two hardware controlled pins that are associated with the UARTx modules. These two pins allow the UARTx to operate in Simplex and Flow Control mode. They are implemented to control the transmission and reception between the Data Terminal Equipment (DTE). The UEN<1:0> bits in the UxMODE register configure these pins.

## 18.7 Infrared Support

The UARTx module provides two types of infrared UART support: one is the IrDA clock output to support an external IrDA encoder and decoder device (legacy module support), and the other is the full implementation of the IrDA encoder and decoder. Note that because the IrDA modes require a 16x baud clock, they will only work when the BRGH bit (UxMODE<3>) is '0'.

### 18.7.1 IrDA CLOCK OUTPUT FOR EXTERNAL IrDA SUPPORT

To support external IrDA encoder and decoder devices, the BCLKx pin (same as the  $\overline{\text{UxRTS}}$  pin) can be configured to generate the 16x baud clock. With UEN<1:0> = 11, the BCLKx pin will output the 16x baud clock if the UARTx module is enabled. It can be used to support the IrDA codec chip.

## REGISTER 18-1: UxMODE: UARTx MODE REGISTER (CONTINUED)

bit 7	<b>WAKE:</b> Wake-up on Start Bit Detect During Sleep Mode Enable bit 1 = UARTx will continue to sample the UxRX pin; interrupt is generated on the falling edge, bit is cleared in hardware on the following rising edge 0 = No wake-up is enabled
bit 6	<b>LPBACK:</b> UARTx Loopback Mode Select bit 1 = Enables Loopback mode 0 = Loopback mode is disabled
bit 5	<b>ABAUD:</b> Auto-Baud Enable bit 1 = Enables baud rate measurement on the next character – requires reception of a Sync field (55h); cleared in hardware upon completion 0 = Baud rate measurement is disabled or has completed
bit 4	<b>URXINV:</b> UARTx Receive Polarity Inversion bit 1 = UxRX Idle state is '0' 0 = UxRX Idle state is '1'
bit 3	<b>BRGH:</b> High Baud Rate Enable bit 1 = High-Speed mode (4 BRG clock cycles per bit) 0 = Standard Speed mode (16 BRG clock cycles per bit)
bit 2-1	<b>PDSEL&lt;1:0&gt;:</b> Parity and Data Selection bits 11 = 9-bit data, no parity 10 = 8-bit data, odd parity 01 = 8-bit data, even parity 00 = 8-bit data, no parity
bit 0	<b>STSEL:</b> Stop Bit Selection bit 1 = Two Stop bits 0 = One Stop bit

- Note 1:** If UARTEN = 1, the peripheral inputs and outputs must be configured to an available RPN/RPIn pin. For more information, see [Section 11.4 “Peripheral Pin Select \(PPS\)”](#).
- 2:** This feature is only available for 16x BRG mode (BRGH = 0).

# PIC24FJ128GB204 FAMILY

## REGISTER 18-2: UxSTA: UARTx STATUS AND CONTROL REGISTER

R/W-0	R/W-0	R/W-0	R/W-0	R/W-0, HC	R/W-0	R-0, HSC	R-1, HSC
UTXISEL1	UTXINV <sup>(1)</sup>	UTXISEL0	URXEN	UTXBRK	UTXEN <sup>(2)</sup>	UTXBF	TRMT
bit 15						bit 8	

R/W-0	R/W-0	R/W-0	R-1, HSC	R-0, HSC	R-0, HSC	R/C-0, HS	R-0, HSC
URXISEL1	URXISEL0	ADDEN	RIDLE	PERR	FERR	OERR	URXDA
bit 7							bit 0

<b>Legend:</b>	C = Clearable bit	HSC = Hardware Settable/Clearable bit
R = Readable bit	W = Writable bit	U = Unimplemented bit, read as '0'
-n = Value at POR	'1' = Bit is set	'0' = Bit is cleared
HS = Hardware Settable bit	HC = Hardware Clearable bit	x = Bit is unknown

- bit 15,13 **UTXISEL<1:0>**: UARTx Transmission Interrupt Mode Selection bits
- 11 = Reserved; do not use
  - 10 = Interrupt when a character is transferred to the Transmit Shift Register (TSR), and as a result, the transmit buffer becomes empty
  - 01 = Interrupt when the last character is shifted out of the Transmit Shift Register; all transmit operations are completed
  - 00 = Interrupt when a character is transferred to the Transmit Shift Register (this implies there is at least one character open in the transmit buffer)
- bit 14 **UTXINV**: IrDA<sup>®</sup> Encoder Transmit Polarity Inversion bit<sup>(1)</sup>
- IREN = 0:**
- 1 = UxTX is Idle ('0')
  - 0 = UxTX is Idle ('1')
- IREN = 1:**
- 1 = UxTX is Idle ('1')
  - 0 = UxTX is Idle ('0')
- bit 12 **URXEN**: UARTx Receive Enable bit
- 1 = Receive is enabled, UxRX pin is controlled by UARTx
  - 0 = Receive is disabled, UxRX pin is controlled by the port
- bit 11 **UTXBRK**: UARTx Transmit Break bit
- 1 = Sends Sync Break on next transmission – Start bit, followed by twelve '0' bits, followed by Stop bit; cleared by hardware upon completion
  - 0 = Sync Break transmission is disabled or has completed
- bit 10 **UTXEN**: UARTx Transmit Enable bit<sup>(2)</sup>
- 1 = Transmit is enabled, UxTX pin is controlled by UARTx
  - 0 = Transmit is disabled, any pending transmission is aborted and the buffer is reset; UxTX pin is controlled by the port
- bit 9 **UTXBF**: UARTx Transmit Buffer Full Status bit (read-only)
- 1 = Transmit buffer is full
  - 0 = Transmit buffer is not full, at least one more character can be written
- bit 8 **TRMT**: Transmit Shift Register Empty bit (read-only)
- 1 = Transmit Shift Register is empty and transmit buffer is empty (the last transmission has completed)
  - 0 = Transmit Shift Register is not empty, a transmission is in progress or queued

**Note 1:** The value of this bit only affects the transmit properties of the module when the IrDA<sup>®</sup> encoder is enabled (IREN = 1).

**2:** If UARTEN = 1, the peripheral inputs and outputs must be configured to an available RPN/RPIN pin. For more information, see [Section 11.4 “Peripheral Pin Select \(PPS\)”](#).

# PIC24FJ128GB204 FAMILY

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## 19.4.2 RECEIVING AN IN TOKEN IN DEVICE MODE

1. Attach to a USB host and enumerate as described in Chapter 9 of the *“USB 2.0 Specification”*.
2. Create a data buffer and populate it with the data to send to the host.
3. In the appropriate (Even or Odd) TX BD for the desired endpoint:
  - a) Set up the status register (BDnSTAT) with the correct data toggle (DATA0/1) value and the byte count of the data buffer.
  - b) Set up the address register (BDnADR) with the starting address of the data buffer.
  - c) Set the UOWN bit of the status register to ‘1’.
4. When the USB module receives an IN token, it automatically transmits the data in the buffer. Upon completion, the module updates the status register (BDnSTAT) and sets the Transfer Done Interrupt Flag, TRNIF (U1IR<3>).

## 19.4.3 RECEIVING AN OUT TOKEN IN DEVICE MODE

1. Attach to a USB host and enumerate as described in Chapter 9 of the *“USB 2.0 Specification”*.
2. Create a data buffer with the amount of data you are expecting from the host.
3. In the appropriate (Even or Odd) TX BD for the desired endpoint:
  - a) Set up the status register (BDnSTAT) with the correct data toggle (DATA0/1) value and the byte count of the data buffer.
  - b) Set up the address register (BDnADR) with the starting address of the data buffer.
  - c) Set the UOWN bit of the status register to ‘1’.
4. When the USB module receives an OUT token, it automatically receives the data sent by the host to the buffer. Upon completion, the module updates the status register (BDnSTAT) and sets the Transfer Done Interrupt Flag, TRNIF (U1IR<3>).

## 19.5 Host Mode Operation

The following sections describe how to perform common Host mode tasks. In Host mode, USB transfers are invoked explicitly by the host software. The host software is responsible for the Acknowledge portion of the transfer. Also, all transfers are performed using the USB Endpoint 0 Control register (U1EP0) and Buffer Descriptors.

### 19.5.1 ENABLE HOST MODE AND DISCOVER A CONNECTED DEVICE

1. Enable Host mode by setting the HOSTEN bit (U1CON<3>). This causes the Host mode control bits in other USB OTG registers to become available.
2. Enable the D+ and D- pull-down resistors by setting the DPPULDOWN and DMPULDOWN bits (U1OTGCON<5:4>). Disable the D+ and D-pull-up resistors by clearing the DPPULUP and DMPULUP bits (U1OTGCON<7:6>).
3. At this point, Start-of-Frame (SOF) generation begins with the SOF counter loaded with 12,000. Eliminate noise on the USB by clearing the SOFEN bit (U1CON<0>) to disable Start-of-Frame packet generation.
4. Enable the device attached interrupt by setting the ATTACHIE bit (U1IE<6>).
5. Wait for the device attached interrupt (U1IR<6> = 1). This is signaled by the USB device changing the state of D+ or D- from ‘0’ to ‘1’ (SE0 to J-state). After it occurs, wait 100 ms for the device power to stabilize.
6. Check the state of the JSTATE and SE0 bits in U1CON. If the JSTATE bit (U1CON<7>) is ‘0’, the connecting device is low speed. If the connecting device is low speed, set the LSPDEN and LSPD bits (U1ADDR<7> and U1EP0<7>, respectively) to enable low-speed operation.
7. Reset the USB device by setting the USBRST bit (U1CON<4>) for at least 50 ms, sending Reset signaling on the bus. After 50 ms, terminate the Reset by clearing USBRST.
8. In order to keep the connected device from going into suspend, enable the SOF packet generation by setting the SOFEN bit.
9. Wait 10 ms for the device to recover from Reset.
10. Perform enumeration as described by Chapter 9 of the *“USB 2.0 Specification”*.

# PIC24FJ128GB204 FAMILY

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## REGISTER 22-1: RCFGAL: RTCC CALIBRATION/CONFIGURATION REGISTER<sup>(1)</sup> (CONTINUED)

bit 7-0      **CAL<7:0>**: RTC Drift Calibration bits

01111111 = Maximum positive adjustment; adds 127 RTC clock pulses every 15 seconds

•

•

•

00000001 = Minimum positive adjustment; adds 1 RTC clock pulse every 15 seconds

00000000 = No adjustment

11111111 = Minimum negative adjustment; subtracts 1 RTC clock pulse every 15 seconds

•

•

•

10000000 = Maximum negative adjustment; subtracts 128 RTC clock pulses every 15 seconds

- Note 1:** The RCFGAL register is only affected by a POR.
- 2:** A write to the RTCEN bit is only allowed when RTCWREN = 1.
- 3:** This bit is read-only; it is cleared to '0' on a write to the lower half of the MINSEC register.

# PIC24FJ128GB204 FAMILY

## REGISTER 22-6: WKDYHR: WEEKDAY AND HOURS VALUE REGISTER<sup>(1)</sup>

U-0	U-0	U-0	U-0	U-0	R/W-x	R/W-x	R/W-x
—	—	—	—	—	WDAY2	WDAY1	WDAY0
bit 15							bit 8

U-0	U-0	R/W-x	R/W-x	R/W-x	R/W-x	R/W-x	R/W-x
—	—	HRTEN1	HRTEN0	HRONE3	HRONE2	HRONE1	HRONE0
bit 7							bit 0

### Legend:

R = Readable bit      W = Writable bit      U = Unimplemented bit, read as '0'  
 -n = Value at POR      '1' = Bit is set      '0' = Bit is cleared      x = Bit is unknown

- bit 15-11      **Unimplemented:** Read as '0'
- bit 10-8      **WDAY<2:0>:** Binary Coded Decimal Value of Weekday Digit bits  
Contains a value from 0 to 6.
- bit 7-6      **Unimplemented:** Read as '0'
- bit 5-4      **HRTEN<1:0>:** Binary Coded Decimal Value of Hour's Tens Digit bits  
Contains a value from 0 to 2.
- bit 3-0      **HRONE<3:0>:** Binary Coded Decimal Value of Hour's Ones Digit bits  
Contains a value from 0 to 9.

**Note 1:** A write to this register is only allowed when RTCWREN = 1.

## REGISTER 22-7: MINSEC: MINUTES AND SECONDS VALUE REGISTER

U-0	R/W-x	R/W-x	R/W-x	R/W-x	R/W-x	R/W-x	R/W-x
—	MINTEN2	MINTEN1	MINTEN0	MINONE3	MINONE2	MINONE1	MINONE0
bit 15							bit 8

U-0	R/W-x	R/W-x	R/W-x	R/W-x	R/W-x	R/W-x	R/W-x
—	SECTEN2	SECTEN1	SECTEN0	SECONE3	SECONE2	SECONE1	SECONE0
bit 7							bit 0

### Legend:

R = Readable bit      W = Writable bit      U = Unimplemented bit, read as '0'  
 -n = Value at POR      '1' = Bit is set      '0' = Bit is cleared      x = Bit is unknown

- bit 15      **Unimplemented:** Read as '0'
- bit 14-12      **MINTEN<2:0>:** Binary Coded Decimal Value of Minute's Tens Digit bits  
Contains a value from 0 to 5.
- bit 11-8      **MINONE<3:0>:** Binary Coded Decimal Value of Minute's Ones Digit bits  
Contains a value from 0 to 9.
- bit 7      **Unimplemented:** Read as '0'
- bit 6-4      **SECTEN<2:0>:** Binary Coded Decimal Value of Second's Tens Digit bits  
Contains a value from 0 to 5.
- bit 3-0      **SECONE<3:0>:** Binary Coded Decimal Value of Second's Ones Digit bits  
Contains a value from 0 to 9.

# PIC24FJ128GB204 FAMILY

## 23.0 CRYPTOGRAPHIC ENGINE

**Note:** This data sheet summarizes the features of the PIC24FJ128GB204 family of devices. It is not intended to be a comprehensive reference source. To complement the information in this data sheet, refer to the “dsPIC33/PIC24 Family Reference Manual”, “**Cryptographic Engine**” (DS70005133), which is available from the Microchip web site ([www.microchip.com](http://www.microchip.com)).

The Cryptographic Engine provides a new set of data security options. Using its own free-standing state machines, the engine can independently perform NIS standard encryption and decryption of data independently of the CPU. This eliminates the concerns of excessive CPU or program memory overhead that encryption and decryption would otherwise require, while enhancing the application's security.

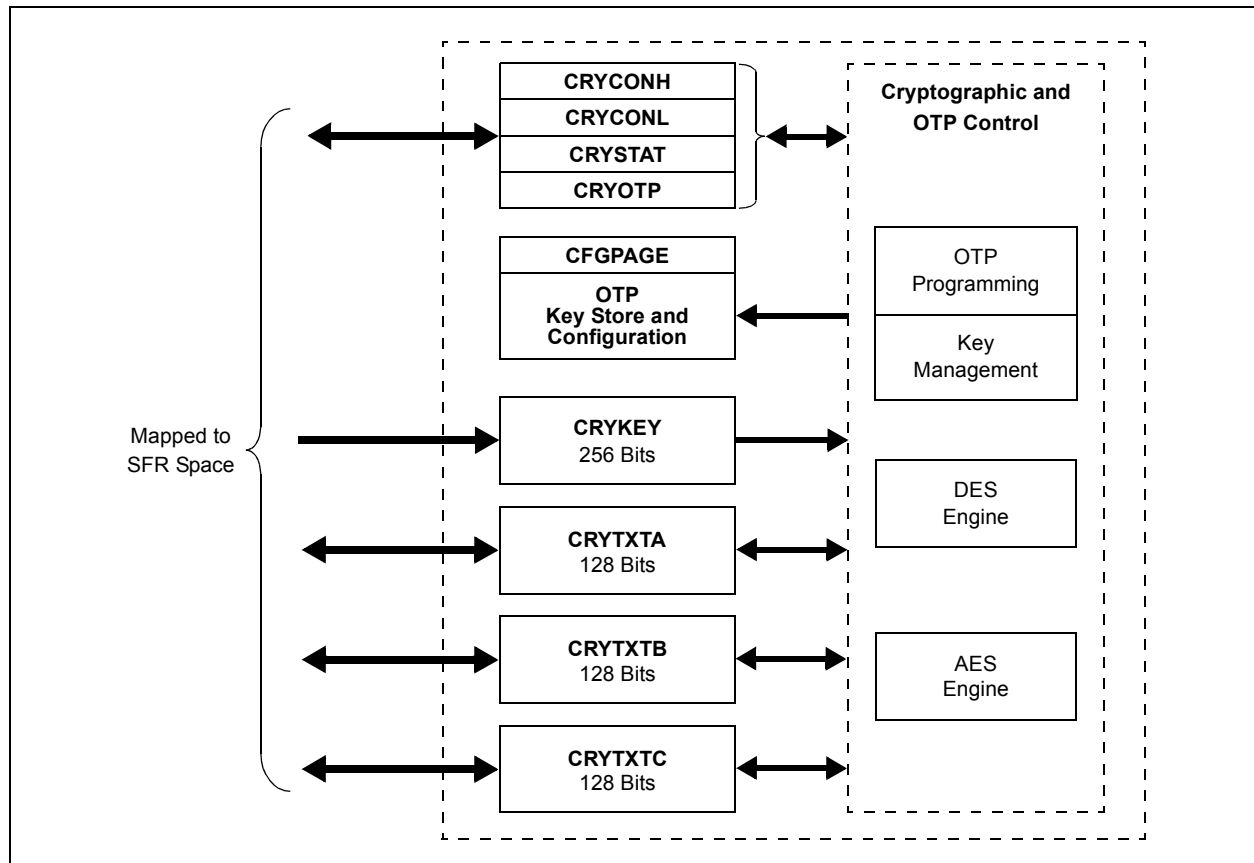
The primary features of the Cryptographic Engine are:

- Memory-mapped 128-bit and 256-bit memory spaces for encryption/decryption data
- Multiple options for key storage, selection and management

- Support for internal context saving
- Session key encryption and loading
- Half-duplex operation
- DES and Triple DES (3DES) encryption and decryption (64-bit block size):
  - Supports 64-bit keys and 2-key or 3-key Triple DES
- AES encryption and decryption (128-bit block size):
  - Supports key sizes of 128, 192 or 256 bits
- Supports ECB, CBC, CFB, OFB and CTR modes for both DES and AES standards
- Programmatically secure key storage:
  - 512-bit OTP array for key storage, not readable from other memory spaces
  - 32-bit Configuration Page
  - Simple in-module programming interface
  - Supports Key Encryption Key (KEK)
- Support for True and Pseudorandom Number Generation (PRNG), NIST SP800-90 compliant

A simplified block diagram of the Cryptographic Engine is shown in [Figure 23-1](#).

**FIGURE 23-1: CRYPTOGRAPHIC ENGINE BLOCK DIAGRAM**





# PIC24FJ128GB204 FAMILY

## 23.5.3 ENCRYPTING A SESSION KEY

**Note:** ECB and CBC modes are restricted to 128-bit session keys only.

1. If not already set, set the CRYON bit.
2. If not already programmed, program the SKEYEN bit to '1'.

**Note:** Setting SKEYEN permanently makes Key #1 available as a Key Encryption Key only. It cannot be used for other encryption or decryption operations after that.

3. Set OPMOD<3:0> to '1110'.
4. Configure the CPHRSEL, CPHRMOD<2:0> and KEYMOD<1:0> register bit fields as desired, set SKEYSEL to '0'.
5. Read the KEYFAIL status bit. If this bit is '1', an illegal configuration has been selected, and the encrypt operation will not be performed.
6. Write the software generated session key into the CRYKEY register or generate a random key into the CRYKEY register. It is only necessary to write the lowest  $n$  bits of CRYKEY for a key length of  $n$ , as all unused key bits are ignored.
7. Set the CRYGO bit. Poll the bit until it is cleared by hardware; alternatively, set the DONEIE bit (CRYCONL<11>) to generate an interrupt when the encryption is done.
8. Read the encrypted session key out of the appropriate CRYTXT register.
9. For total key lengths of more than 128 bits, set SKEYSEL to '1' and repeat Steps 6 and 7.
10. Set KEYSRC<3:0> to '0000' to use the session key to encrypt data.

## 23.5.4 RECEIVING A SESSION KEY

**Note:** ECB and CBC modes are restricted to 128-bit session keys only.

1. If not already set, set the CRYON bit.
2. If not already programmed, program the SKEYEN bit to '1'.

**Note:** Setting SKEYEN permanently makes Key #1 available as a Key Encryption Key only. It cannot be used for other encryption or decryption operations after that. It also permanently disables the ability of software to decrypt the session key into the CRYXTA register, thereby breaking programmatic security (i.e., software can read the unencrypted key).

3. Set OPMOD<3:0> to '1111'.
4. Configure the CPHRSEL, CPHRMOD<2:0> and KEYMOD<1:0> register bit fields as desired, set SKEYSEL to '0'.
5. Read the KEYFAIL status bit. If this bit is '1', an illegal configuration has been selected and the encrypt operation will NOT be performed.
6. Write the encrypted session key received into the appropriate CRYTXT register.
7. Set the CRYGO bit. Poll the bit until it is cleared by hardware; alternatively, set the DONEIE bit (CRYCONL<11>) to generate an interrupt when the process is done.
8. For total key lengths of more than 128 bits, set SKEYSEL to '1' and repeat Steps 6 and 7.
9. Set KEYSRC<3:0> to '0000' to use the newly generated session key to encrypt and decrypt data.

# PIC24FJ128GB204 FAMILY

**TABLE 23-1: DES/3DES KEY SOURCE SELECTION**

Mode of Operation	KEYMOD<1:0>	KEYSRC<3:0>	Session Key Source		OTP Array Address
			SKEYEN = 0	SKEYEN = 1	
64-Bit DES	00	0000 <sup>(1)</sup>	CRYKEY<63:0>		—
		0001	DES Key #1	Key Config Error <sup>(2)</sup>	<63:0>
		0010	DES Key #2		<127:64>
		0011	DES Key #3		<191:128>
		0100	DES Key #4		<255:192>
		0101	DES Key #5		<319:256>
		0110	DES Key #6		<383:320>
		0111	DES Key #7		<447:384>
		1111	Reserved <sup>(2)</sup>		—
		All Others	Key Config Error <sup>(2)</sup>		—
64-Bit 2-Key 3DES (Standard 2-Key E-D-E/D-E-D)	01	0000 <sup>(1)</sup>	CRYKEY<63:0> (1st/3rd) CRYKEY<127:64> (2nd)		—
		0001	DES Key #1 (1st/3rd) DES Key #2 (2nd)	Key Config Error <sup>(2)</sup>	<63:0> <127:64>
		0010	DES Key #3 (1st/3rd) DES Key #4 (2nd)		<191:128> <255:192>
		0011	DES Key #5 (1st/3rd) DES Key #6 (2nd)		<319:256> <383:320>
		0100	DES Key #7 (1st/3rd) DES Key #8 (2nd)		<447:384> <511:448>
		1111	Reserved <sup>(2)</sup>		—
		All Others	Key Config Error <sup>(2)</sup>		—
(Reserved)	10	xxxx	Key Config Error <sup>(2)</sup>		—
64-Bit 3-Key 3DES	11	0000 <sup>(1)</sup>	CRYKEY<63:0> (1st Iteration) CRYKEY<127:64> (2nd Iteration) CRYKEY<191:128> (3rd Iteration)		—
		0001	DES Key #1 (1st) DES Key #2 (2nd) DES Key #3 (3rd)	Key Config Error <sup>(2)</sup>	<63:0> <127:64> <191:128>
		0010	DES Key #4 (1st) DES Key #5 (2nd) DES Key #6 (3rd)		<255:192> <319:256> <383:320>
		1111	Reserved <sup>(2)</sup>		—
		All Others	Key Config Error <sup>(2)</sup>		—

**Note 1:** This configuration is considered a Key Configuration Error (KEYFAIL bit is set) if SWKYDIS is also set.

**2:** The KEYFAIL bit (CRYSTAT<1>) is set when these configurations are selected and remains set until a valid configuration is selected.

# PIC24FJ128GB204 FAMILY

## 24.0 32-BIT PROGRAMMABLE CYCLIC REDUNDANCY CHECK (CRC) GENERATOR

**Note:** This data sheet summarizes the features of this group of PIC24F devices. It is not intended to be a comprehensive reference source. For more information, refer to the “*dsPIC33/PIC24 Family Reference Manual*”, “**32-Bit Programmable Cyclic Redundancy Check (CRC)**” (DS30009729). The information in this data sheet supersedes the information in the FRM.

The 32-bit programmable CRC generator provides a hardware implemented method of quickly generating checksums for various networking and security applications. It offers the following features:

- User-programmable CRC polynomial equation, up to 32 bits
- Programmable shift direction (little or big-endian)
- Independent data and polynomial lengths
- Configurable interrupt output
- Data FIFO

Figure 24-1 displays a simplified block diagram of the CRC generator. A simple version of the CRC shift engine is displayed in Figure 24-2.

FIGURE 24-1: CRC MODULE BLOCK DIAGRAM

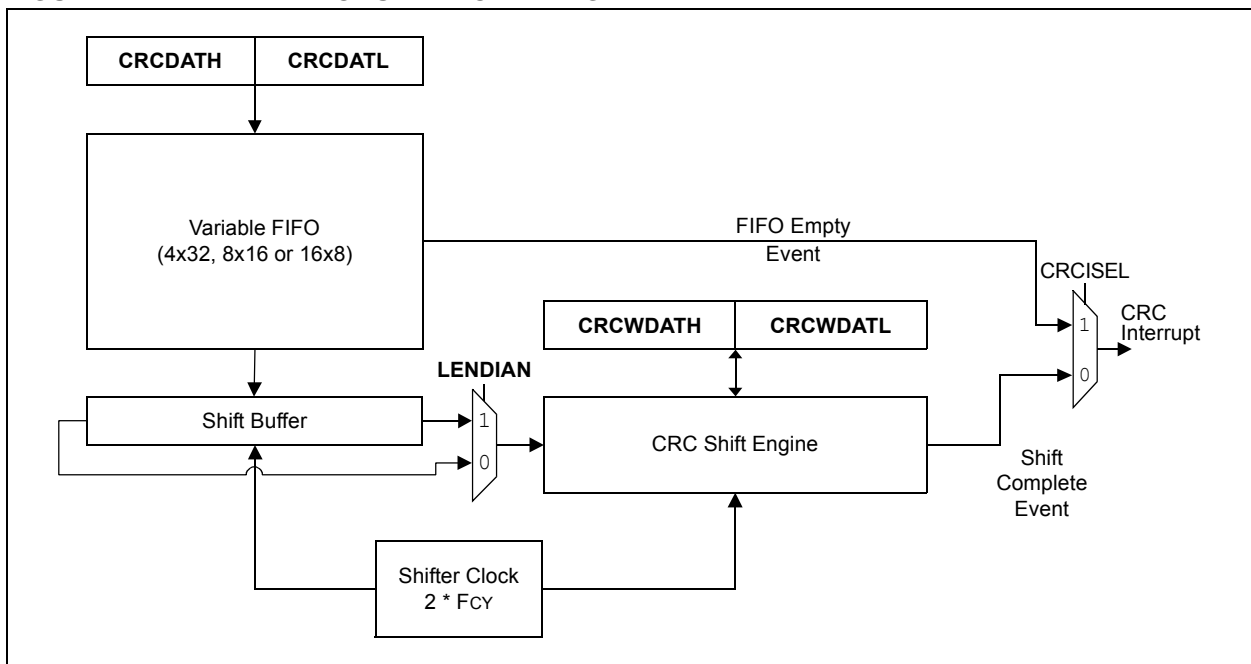
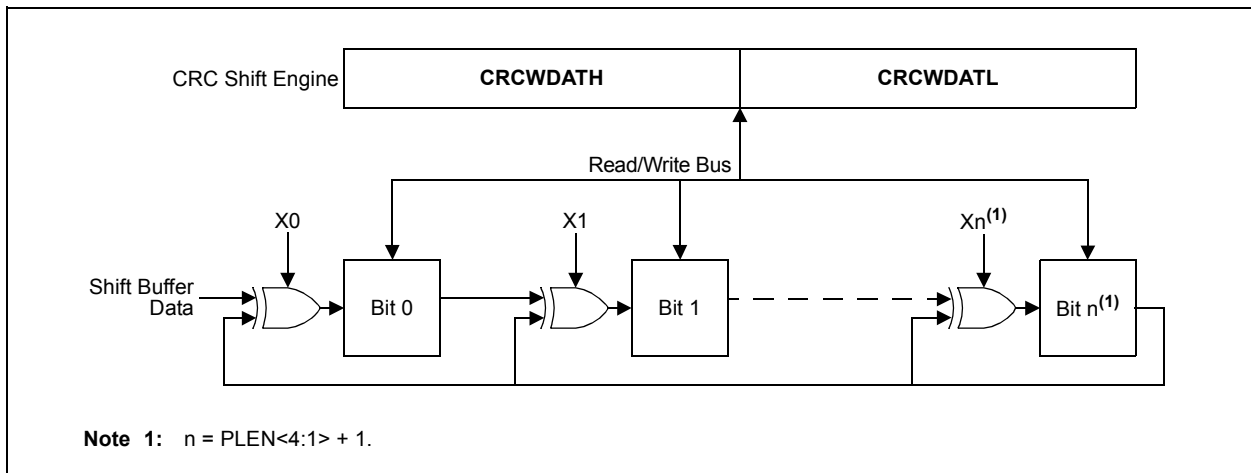


FIGURE 24-2: CRC SHIFT ENGINE DETAIL



# PIC24FJ128GB204 FAMILY

**TABLE 33-6: DC CHARACTERISTICS: POWER-DOWN CURRENT (IPD)**

DC CHARACTERISTICS			Standard Operating Conditions: 2.0V to 3.6V (unless otherwise stated)			
			Operating temperature    -40°C ≤ TA ≤ +85°C for Industrial -40°C ≤ TA ≤ +125°C for Extended			
Parameter No.	Typical <sup>(1)</sup>	Max	Units	Operating Temperature	VDD	Conditions
Power-Down Current (IPD) <sup>(5,6)</sup>						
DC60	2.9	17	μA	-40°C	2.0V	Sleep <sup>(2)</sup>
	4.3	17	μA	+25°C		
	8.3	27.5	μA	+60°C		
	20	27.5	μA	+85°C		
	—	79	μA	+125°C		
	2.9	18	μA	-40°C	3.3V	
	4.3	18	μA	+25°C		
	8.4	28	μA	+60°C		
	20.5	28	μA	+85°C		
	—	80	μA	+125°C		
DC61	0.07	—	μA	-40°C	2.0V	Low-Voltage Sleep <sup>(3)</sup>
	0.38	—	μA	+25°C		
	2.6	—	μA	+60°C		
	9.0	—	μA	+125°C		
	0.09	—	μA	-40°C	3.3V	
	0.42	—	μA	+25°C		
	2.75	—	μA	+60°C		
	9.0	—	μA	+125°C		
DC70	0.1	700	nA	-40°C	2.0V	Deep Sleep
	18	700	nA	+25°C		
	230	1700	nA	+60°C		
	1.8	3.0	μA	+85°C		
	—	24	μA	+125°C		
	5	900	nA	-40°C	3.3V	
	75	900	nA	+25°C		
	540	3450	nA	+60°C		
	1.5	6.0	μA	+85°C		
	—	48	μA	+125°C		
DC74	0.4	2.0	μA	-40°C to +125°C	0V	RTCC with VBAT mode (LPRC/SOSC) <sup>(4)</sup>

**Note 1:** Data in the Typical column is at 3.3V,  $+25^{\circ}\text{C}$  unless otherwise stated. Parameters are for design guidance only and are not tested.

**2:** The retention low-voltage regulator is disabled; RETEN (RCON<12>) = 0,  $\overline{\text{LPCFG}}$  (CW1<10>) = 1.

**3:** The retention low-voltage regulator is enabled; RETEN (RCON<12>) = 1,  $\overline{\text{LPCFG}}$  (CW1<10>) = 0.

**4:** The VBAT pin is connected to the battery and RTCC is running with  $V_{DD} = 0$ .

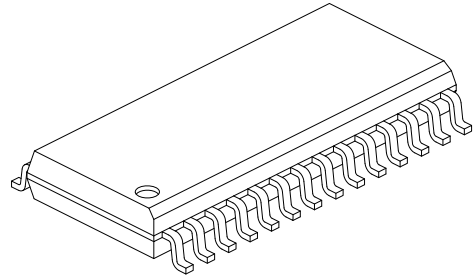
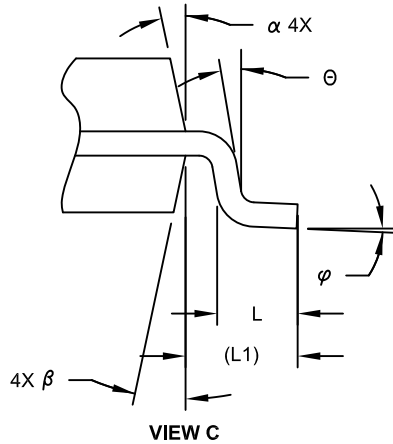
**5:** Base IPD is measured with all peripherals and clocks shut down. All I/Os are configured as inputs and pulled to Vss. WDT, etc., are all switched off.

**6:** These currents are measured on the device containing the most memory in this family.

# PIC24FJ128GB204 FAMILY

## 28-Lead Plastic Small Outline (SO) - Wide, 7.50 mm Body [SOIC]

**Note:** For the most current package drawings, please see the Microchip Packaging Specification located at <http://www.microchip.com/packaging>



Units		MILLIMETERS		
Dimension Limits		MIN	NOM	MAX
Number of Pins	N	28		
Pitch	e	1.27 BSC		
Overall Height	A	-	-	2.65
Molded Package Thickness	A2	2.05	-	-
Standoff §	A1	0.10	-	0.30
Overall Width	E	10.30 BSC		
Molded Package Width	E1	7.50 BSC		
Overall Length	D	17.90 BSC		
Chamfer (Optional)	h	0.25	-	0.75
Foot Length	L	0.40	-	1.27
Footprint	L1	1.40 REF		
Lead Angle	Θ	0°	-	-
Foot Angle	φ	0°	-	8°
Lead Thickness	c	0.18	-	0.33
Lead Width	b	0.31	-	0.51
Mold Draft Angle Top	α	5°	-	15°
Mold Draft Angle Bottom	β	5°	-	15°

### Notes:

- Pin 1 visual index feature may vary, but must be located within the hatched area.
- § Significant Characteristic
- Dimension D does not include mold flash, protrusions or gate burrs, which shall not exceed 0.15 mm per end. Dimension E1 does not include interlead flash or protrusion, which shall not exceed 0.25 mm per side.
- Dimensioning and tolerancing per ASME Y14.5M
  - BSC: Basic Dimension. Theoretically exact value shown without tolerances.
  - REF: Reference Dimension, usually without tolerance, for information purposes only.
- Datums A & B to be determined at Datum H.

Microchip Technology Drawing C04-052C Sheet 2 of 2