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What is "Embedded - Microcontrollers"?

"Embedded - Microcontrollers" refer to small, integrated circuits designed to perform specific tasks within larger systems. These microcontrollers are essentially compact computers on a single chip, containing a processor core, memory, and programmable input/output peripherals. They are called "embedded" because they are embedded within electronic devices to control various functions, rather than serving as standalone computers. Microcontrollers are crucial in modern electronics, providing the intelligence and control needed for a wide range of applications.

Applications of "<u>Embedded - Microcontrollers</u>"

Details	
Product Status	Active
Core Processor	PIC
Core Size	16-Bit
Speed	32MHz
Connectivity	I <sup>2</sup> C, IrDA, LINbus, SmartCard, SPI, UART/USART
Peripherals	AES, Brown-out Detect/Reset, DMA, I <sup>2</sup> S, HLVD, POR, PWM, WDT
Number of I/O	20
Program Memory Size	64KB (64K x 8)
Program Memory Type	FLASH
EEPROM Size	-
RAM Size	8K x 8
Voltage - Supply (Vcc/Vdd)	2V ~ 3.6V
Data Converters	A/D 9x10b/12b
Oscillator Type	Internal
Operating Temperature	-40°C ~ 85°C (TA)
Mounting Type	Surface Mount
Package / Case	28-VQFN Exposed Pad
Supplier Device Package	28-QFN-S (6x6)
Purchase URL	https://www.e-xfl.com/product-detail/microchip-technology/pic24fj64gb202t-i-mm

FIGURE 3-2: PROGRAMMER'S MODEL 0 W0 (WREG) **Divider Working Registers** W1 W2 Multiplier Registers W3 W4 W5 W6 W7 Working/Address Registers W8 W9 W10 W11 W12 W13 Frame Pointer W14 W15 Stack Pointer Stack Pointer Limit Value Register SPLIM 0 РС 0 **Program Counter** Table Memory Page Address Register **TBLPAG** DSRPAG Data Space Read Page Register DSWPAG Data Space Write Page Register 15 REPEAT Loop Counter RCOUNT Register SRH SRL 0 15 RA N OV Z ALU STATUS Register (SR) CPU Control Register (CORCON) DISICNT Disable Interrupt Count Register Registers or bits are shadowed for PUSH.S and POP.S instructions.

#### REGISTER 8-6: IFS1: INTERRUPT FLAG STATUS REGISTER 1

R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0
U2TXIF	U2RXIF	INT2IF	T5IF	T4IF	OC4IF	OC3IF	DMA2IF
bit 15							bit 8

U-0	U-0	U-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0
_	_	_	INT1IF	CNIF	CMIF	MI2C1IF	SI2C1IF
bit 7							bit 0

Legend:

R = Readable bit W = Writable bit U = Unimplemented bit, read as '0'

-n = Value at POR '1' = Bit is set '0' = Bit is cleared x = Bit is unknown

bit 15 **U2TXIF:** UART2 Transmitter Interrupt Flag Status bit

1 = Interrupt request has occurred

0 = Interrupt request has not occurred

bit 14 **U2RXIF:** UART2 Receiver Interrupt Flag Status bit

1 = Interrupt request has occurred

0 = Interrupt request has not occurred

bit 13 INT2IF: External Interrupt 2 Flag Status bit

1 = Interrupt request has occurred

0 = Interrupt request has not occurred

bit 12 **T5IF:** Timer5 Interrupt Flag Status bit

1 = Interrupt request has occurred

0 = Interrupt request has not occurred

bit 11 **T4IF:** Timer4 Interrupt Flag Status bit

1 = Interrupt request has occurred

0 = Interrupt request has not occurred

bit 10 OC4IF: Output Compare Channel 4 Interrupt Flag Status bit

1 = Interrupt request has occurred

0 = Interrupt request has not occurred

bit 9 OC3IF: Output Compare Channel 3 Interrupt Flag Status bit

1 = Interrupt request has occurred

0 = Interrupt request has not occurred

bit 8 DMA2IF: DMA Channel 2 Interrupt Flag Status bit

1 = Interrupt request has occurred

0 = Interrupt request has not occurred

bit 7-5 **Unimplemented:** Read as '0'

bit 4 INT1IF: External Interrupt 1 Flag Status bit

1 = Interrupt request has occurred

0 = Interrupt request has not occurred

bit 3 CNIF: Input Change Notification Interrupt Flag Status bit

1 = Interrupt request has occurred

0 = Interrupt request has not occurred

## REGISTER 8-14: IEC1: INTERRUPT ENABLE CONTROL REGISTER 1 (CONTINUED)

bit 1 MI2C1IE: Master I2C1 Event Interrupt Enable bit

1 = Interrupt request is enabled0 = Interrupt request is not enabled

bit 0 SI2C1IE: Slave I2C1 Event Interrupt Enable bit

1 = Interrupt request is enabled0 = Interrupt request is not enabled

**Note 1:** If an external interrupt is enabled, the interrupt input must also be configured to an available RPn or RPIn pin. For more information, see **Section 11.4 "Peripheral Pin Select (PPS)"**.

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	8GB2U4	8GBZU4 FAMIL	8GBZU4 FAIVIILY	8GBZU4 FAMILY

## 11.4.3.1 Input Mapping

The inputs of the Peripheral Pin Select options are mapped on the basis of the peripheral; that is, a control register associated with a peripheral dictates the pin it will be mapped to. The RPINRx registers are used to configure peripheral input mapping (see Register 11-4 through Register 11-22).

Each register contains two sets of 6-bit fields, with each set associated with one of the pin-selectable peripherals. Programming a given peripheral's bit field with an appropriate 6-bit value maps the RPn/RPIn pin with that value to that peripheral. For any given device, the valid range of values for any of the bit fields corresponds to the maximum number of Peripheral Pin Selections supported by the device.

TABLE 11-3: SELECTABLE INPUT SOURCES (MAPS INPUT TO FUNCTION)(1)

Input Name	Function Name	Register	Function Mapping Bits
DSM Modulation Input	MDMIN	RPINR30	MDMIR<5:0>
DSM Carrier 1 Input	MDCIN1	RPINR31	MDC1R<5:0>
DSM Carrier 2 Input	MDCIN2	RPINR31	MDC2R<5:0>
External Interrupt 1	INT1	RPINR0	INT1R<5:0>
External Interrupt 2	INT2	RPINR1	INT2R<5:0>
External Interrupt 3	INT3	RPINR1	INT3R<5:0>
External Interrupt 4	INT4	RPINR2	INT4R<5:0>
Input Capture 1	IC1	RPINR7	IC1R<5:0>
Input Capture 2	IC2	RPINR7	IC2R<5:0>
Input Capture 3	IC3	RPINR8	IC3R<5:0>
Input Capture 4	IC4	RPINR8	IC4R<5:0>
Input Capture 5	IC5	RPINR9	IC5R<5:0>
Input Capture 6	IC6	RPINR9	IC6R<5:0>
Output Compare Fault A	OCFA	RPINR11	OCFAR<5:0>
Output Compare Fault B	OCFB	RPINR11	OCFBR<5:0>
Output Compare Trigger 1	OCTRIG1	RPINR0	OCTRIG1R<5:0>
Output Compare Trigger 2	OCTRIG2	RPINR2	OCTRIG2R<5:0>
SPI1 Clock Input	SCK1IN	RPINR20	SCK1R<5:0>
SPI1 Data Input	SDI1	RPINR20	SDI1R<5:0>
SPI1 Slave Select Input	SS1IN	RPINR21	SS1R<5:0>
SPI2 Clock Input	SCK2IN	RPINR22	SCK2R<5:0>
SPI2 Data Input	SDI2	RPINR22	SDI2R<5:0>
SPI2 Slave Select Input	SS2IN	RPINR23	SS2R<5:0>
SPI3 Clock Input	SCK3IN	RPINR28	SCK3R<5:0>
SPI3 Data Input	SDI3	RPINR28	SDI3R<5:0>
SPI3 Slave Select Input	SS3IN	RPINR29	SS3R<5:0>
Generic Timer External Clock	TMRCK	RPINR23	TMRCKR<5:0>
UART1 Clear-to-Send	U1CTS	RPINR18	U1CTSR<5:0>
UART1 Receive	U1RX	RPINR18	U1RXR<5:0>
UART2 Clear-to-Send	U2CTS	RPINR19	U2CTSR<5:0>
UART2 Receive	U2RX	RPINR19	U2RXR<5:0>
UART3 Clear-to-Send	U3CTS	RPINR21	U3CTSR<5:0>
UART3 Receive	U3RX	RPINR17	U3RXR<5:0>
UART4 Clear-to-Send	U4CTS	RPINR27	U4CTSR<5:0>
UART4 Receive	U4RX	RPINR27	U4RXR<5:0>

Note 1: Unless otherwise noted, all inputs use the Schmitt Trigger (ST) input buffers.

## REGISTER 13-1: TxCON: TIMER2 AND TIMER4 CONTROL REGISTER<sup>(1)</sup>

R/W-0	U-0	R/W-0	U-0	U-0	U-0	R/W-0	R/W-0
TON	_	TSIDL	_	_	_	TECS1 <sup>(2)</sup>	TECS0 <sup>(2)</sup>
bit 15							bit 8

U-0	R/W-0	R/W-0	R/W-0	R/W-0	U-0	R/W-0	U-0
_	TGATE	TCKPS1	TCKPS0	T32 <sup>(3)</sup>	_	TCS <sup>(2)</sup>	_
bit 7							bit 0

Legend:

R = Readable bit W = Writable bit U = Unimplemented bit, read as '0'

-n = Value at POR '1' = Bit is set '0' = Bit is cleared x = Bit is unknown

bit 15 **TON:** Timerx On bit

When TxCON<3> = 1:

1 = Starts 32-bit Timerx/y

0 = Stops 32-bit Timerx/y

When TxCON<3> = 0:

1 = Starts 16-bit Timerx

0 = Stops 16-bit Timerx

bit 14 Unimplemented: Read as '0'

bit 13 TSIDL: Timerx Stop in Idle Mode bit

1 = Discontinues module operation when device enters Idle mode

0 = Continues module operation in Idle mode

bit 12-10 Unimplemented: Read as '0'

bit 9-8 **TECS<1:0>:** Timerx Extended Clock Source Select bits (selected when TCS = 1)(2)

When TCS = 1:

11 = Generic Timer (TMRCK) external input

10 = LPRC Oscillator

01 = TxCK external clock input

00 = SOSC

When TCS = 0

These bits are ignored; Timerx is clocked from the internal system clock (Fosc/2).

bit 7 Unimplemented: Read as '0'

bit 6 TGATE: Timerx Gated Time Accumulation Enable bit

When TCS = 1:

This bit is ignored.

When TCS = 0:

1 = Gated time accumulation is enabled

0 = Gated time accumulation is disabled

bit 5-4 TCKPS<1:0>: Timerx Input Clock Prescale Select bits

11 = 1:256

10 = 1:64

01 = 1:8

00 = 1:1

- **Note 1:** Changing the value of TxCON while the timer is running (TON = 1) causes the timer prescale counter to reset and is not recommended.
  - 2: If TCS = 1 and TECS<1:0> = x1, the selected external timer input (TMRCK or TxCK) must be configured to an available RPn/RPIn pin. For more information, see Section 11.4 "Peripheral Pin Select (PPS)".
  - 3: In T4CON, the T45 bit is implemented instead of T32 to select 32-bit mode. In 32-bit mode, the T3CON or T5CON control bits do not affect 32-bit timer operation.

## REGISTER 13-2: TyCON: TIMER3 AND TIMER5 CONTROL REGISTER<sup>(1)</sup>

R/W-0	U-0	R/W-0	U-0	U-0	U-0	R/W-0	R/W-0
TON <sup>(2)</sup>	_	TSIDL <sup>(2)</sup>	_	_	_	TECS1 <sup>(2,3)</sup>	TECS0 <sup>(2,3)</sup>
bit 15							bit 8

U-0	R/W-0	R/W-0	R/W-0	U-0	U-0	R/W-0	U-0
_	TGATE <sup>(2)</sup>	TCKPS1 <sup>(2)</sup>	TCKPS0 <sup>(2)</sup>	_	_	TCS <sup>(2,3)</sup>	
bit 7							bit 0

Legend:

R = Readable bit W = Writable bit U = Unimplemented bit, read as '0'

-n = Value at POR '1' = Bit is set '0' = Bit is cleared x = Bit is unknown

bit 15 **TON:** Timery On bit<sup>(2)</sup>

1 = Starts 16-bit Timery

0 = Stops 16-bit Timery

bit 14 Unimplemented: Read as '0'

bit 13 **TSIDL:** Timery Stop in Idle Mode bit<sup>(2)</sup>

1 = Discontinues module operation when device enters Idle mode

0 = Continues module operation in Idle mode

bit 12-10 Unimplemented: Read as '0'

bit 9-8 **TECS<1:0>:** Timery Extended Clock Source Select bits (selected when TCS = 1)(2,3)

11 = Generic Timer (TMRCK) external input

10 = LPRC Oscillator

01 = TxCK external clock input

00 = SOSC

bit 7 **Unimplemented:** Read as '0'

bit 6 **TGATE:** Timery Gated Time Accumulation Enable bit<sup>(2)</sup>

When TCS = 1: This bit is ignored. When TCS = 0:

1 = Gated time accumulation is enabled0 = Gated time accumulation is disabled

bit 5-4 TCKPS<1:0>: Timery Input Clock Prescale Select bits(2)

11 = 1:256

10 = 1:64

01 = 1:8

00 = 1:1

bit 3-2 **Unimplemented:** Read as '0'

bit 1 TCS: Timery Clock Source Select bit<sup>(2,3)</sup>

1 = External clock from pin, TyCK (on the rising edge)

0 = Internal clock (Fosc/2)

bit 0 **Unimplemented:** Read as '0'

**Note 1:** Changing the value of TyCON while the timer is running (TON = 1) causes the timer prescale counter to reset and is not recommended.

- 2: When 32-bit operation is enabled (T2CON<3> or T4CON<3> = 1), these bits have no effect on Timery operation; all timer functions are set through T2CON and T4CON.
- 3: If TCS = 1 and TECS<1:0> = x1, the selected external timer input (TyCK) must be configured to an available RPn/RPIn pin. For more information, see Section 11.4 "Peripheral Pin Select (PPS)".

#### REGISTER 18-2: UXSTA: UARTX STATUS AND CONTROL REGISTER (CONTINUED)

- bit 7-6 URXISEL<1:0>: UARTx Receive Interrupt Mode Selection bits
  - 11 = Interrupt is set on an RSR transfer, making the receive buffer full (i.e., has 4 data characters)
  - 10 = Interrupt is set on an RSR transfer, making the receive buffer 3/4 full (i.e., has 3 data characters)
  - 0x = Interrupt is set when any character is received and transferred from the RSR to the receive buffer; receive buffer has one or more characters
- bit 5 **ADDEN:** Address Character Detect bit (bit 8 of received data = 1)
  - 1 = Address Detect mode is enabled (if 9-bit mode is not selected, this does not take effect)
  - 0 = Address Detect mode is disabled
- bit 4 RIDLE: Receiver Idle bit (read-only)
  - 1 = Receiver is Idle
  - 0 = Receiver is active
- bit 3 PERR: Parity Error Status bit (read-only)
  - 1 = Parity error has been detected for the current character (the character at the top of the receive FIFO)
  - 0 = Parity error has not been detected
- bit 2 **FERR:** Framing Error Status bit (read-only)
  - 1 = Framing error has been detected for the current character (the character at the top of the receive FIFO)
  - 0 = Framing error has not been detected
- bit 1 **OERR:** Receive Buffer Overrun Error Status bit (clear/read-only)
  - 1 = Receive buffer has overflowed
  - 0 = Receive buffer has not overflowed (clearing a previously set OERR bit (1  $\rightarrow$  0 transition); will reset the receive buffer and the RSR to the empty state)
- bit 0 **URXDA:** UARTX Receive Buffer Data Available bit (read-only)
  - 1 = Receive buffer has data, at least one more character can be read
  - 0 = Receive buffer is empty
- **Note 1:** The value of this bit only affects the transmit properties of the module when the IrDA® encoder is enabled (IREN = 1).
  - 2: If UARTEN = 1, the peripheral inputs and outputs must be configured to an available RPn/RPIn pin. For more information, see Section 11.4 "Peripheral Pin Select (PPS)".

# 19.0 UNIVERSAL SERIAL BUS WITH ON-THE-GO SUPPORT (USB OTG)

Note:

This data sheet summarizes the features of this group of PIC24F devices. It is not intended to be a comprehensive reference source. For more information, refer to the "dsPIC33/PIC24 Family Reference Manual", "USB On-The-Go (OTG)" (DS39721). The information in this data sheet supersedes the information in the FRM.

PIC24FJ128GB204 family devices contain a full-speed and low-speed compatible, On-The-Go (OTG) USB Serial Interface Engine (SIE). The OTG capability allows the device to act either as a USB peripheral device or as a USB embedded host with limited host capabilities. The OTG capability allows the device to dynamically switch from device to host operation using OTG's Host Negotiation Protocol (HNP).

For more details on OTG operation, refer to the "On-The-Go Supplement" to the "USB 2.0 Specification", published by the USB-IF. For more details on USB operation, refer to the "Universal Serial Bus Specification", v2.0.

The USB OTG module offers these features:

- USB functionality in Device and Host modes, and OTG capabilities for application-controlled mode switching
- Software-selectable module speeds of full speed (12 Mbps) or low speed (1.5 Mbps, available in Host mode only)
- Support for all four USB transfer types: control, interrupt, bulk and isochronous
- Sixteen bidirectional endpoints for a total of 32 unique endpoints
- DMA interface for data RAM access
- Queues up to sixteen unique endpoint transfers without servicing
- · Integrated, on-chip USB transceiver
- Integrated VBUS generation with on-chip comparators and boost generation
- Configurations for on-chip bus pull-up and pull-down resistors

A simplified block diagram of the USB OTG module is shown in Figure 19-1.

The USB OTG module can function as a USB peripheral device or as a USB host, and may dynamically switch between Device and Host modes under software control. In either mode, the same data paths and Buffer Descriptors (BDs) are used for the transmission and reception of data.

In discussing USB operation, this section will use a controller-centric nomenclature for describing the direction of the data transfer between the microcontroller and the USB. RX (Receive) will be used to describe transfers that move data from the USB to the microcontroller and TX (Transmit) will be used to describe transfers that move data from the microcontroller to the USB. Table 19-1 shows the relationship between data direction in this nomenclature and the USB tokens exchanged.

TABLE 19-1: CONTROLLER-CENTRIC
DATA DIRECTION FOR USB
HOST OR TARGET

USB Mode	Direc	ction			
USB Widde	RX TX				
Device	OUT or SETUP	IN			
Host	IN	OUT or SETUP			

This chapter presents the most basic operations needed to implement USB OTG functionality in an application. A complete and detailed discussion of the USB protocol and its OTG supplement are beyond the scope of this data sheet. It is assumed that the user already has a basic understanding of USB architecture and the latest version of the protocol.

Not all steps for proper USB operation (such as device enumeration) are presented here. It is recommended that application developers use an appropriate device driver to implement all of the necessary features. Microchip provides a number of application-specific resources, such as USB firmware and driver support. Refer to <a href="https://www.microchip.com/usb">www.microchip.com/usb</a> for the latest firmware and driver support.

# 19.7.1 USB OTG MODULE CONTROL REGISTERS

#### REGISTER 19-3: U10TGSTAT: USB OTG STATUS REGISTER (HOST MODE ONLY)

U-0	U-0	U-0	U-0	U-0	U-0	U-0	U-0
_	_	_	_	_	_	_	_
bit 15		_	_		_		bit 8

R-0, HSC	U-0	R-0, HSC	U-0	R-0, HSC	R-0, HSC	U-0	R-0, HSC
ID	_	LSTATE	_	SESVD	SESEND	_	VBUSVD
bit 7							bit 0

**Legend:** U = Unimplemented bit, read as '0'

R = Readable bit W = Writable bit HSC = Hardware Settable/Clearable bit

-n = Value at POR '1' = Bit is set '0' = Bit is cleared x = Bit is unknown

bit 15-8 **Unimplemented:** Read as '0'

bit 7 ID: ID Pin State Indicator bit

1 = No plug is attached or a Type B cable has been plugged into the USB receptacle

0 = A Type A plug has been plugged into the USB receptacle

bit 6 **Unimplemented:** Read as '0'

bit 5 LSTATE: Line State Stable Indicator bit

1 = The USB line state (as defined by SE0 and JSTATE) has been stable for the previous 1 ms

0 = The USB line state has not been stable for the previous 1 ms

bit 4 Unimplemented: Read as '0'

bit 3 SESVD: Session Valid Indicator bit

1 = The VBUS voltage is above VA\_SESS\_VLD (as defined in the "USB 2.0 Specification") on the A or

B-device

0 = The VBUS voltage is below VA\_SESS\_VLD on the A or B-device

bit 2 SESEND: B Session End Indicator bit

1 = The VBUS voltage is below VB\_SESS\_END (as defined in the "USB 2.0 Specification") on the B-device

0 = The VBUS voltage is above VB SESS END on the B-device

bit 1 **Unimplemented:** Read as '0'

bit 0 **VBUSVD:** A VBUS Valid Indicator bit

1 = The VBUS voltage is above VA\_VBUS\_VLD (as defined in the "USB 2.0 Specification") on the A-device

0 = The VBUS voltage is below VA VBUS VLD on the A-device

#### REGISTER 19-20: U1EIE: USB ERROR INTERRUPT ENABLE REGISTER

U-0	U-0	U-0	U-0	U-0	U-0	U-0	U-0
_	_	_	_	_	_	_	_
bit 15							bit 8

R/W-0	U-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0
BTSEE	_	DMAEE	BTOEE	DFN8EE	CRC16EE	CRC5EE	PIDEE
						EOFEE	
bit 7							bit 0

Legend:

R = Readable bit W = Writable bit U = Unimplemented bit, read as '0'

-n = Value at POR '1' = Bit is set '0' = Bit is cleared x = Bit is unknown

bit 15-8 Unimplemented: Read as '0'

bit 7 BTSEE: Bit Stuff Error Interrupt Enable bit

1 = Interrupt is enabled0 = Interrupt is disabled

bit 6 **Unimplemented:** Read as '0'

bit 5 DMAEE: DMA Error Interrupt Enable bit

1 = Interrupt is enabled0 = Interrupt is disabled

bit 4 BTOEE: Bus Turnaround Time-out Error Interrupt Enable bit

1 = Interrupt is enabled0 = Interrupt is disabled

bit 3 **DFN8EE**: Data Field Size Error Interrupt Enable bit

1 = Interrupt is enabled0 = Interrupt is disabled

bit 2 CRC16EE: CRC16 Failure Interrupt Enable bit

1 = Interrupt is enabled0 = Interrupt is disabled

bit 1 For Device Mode:

CRC5EE: CRC5 Host Error Interrupt Enable bit

1 = Interrupt is enabled0 = Interrupt is disabled

For Host Mode:

**EOFEE:** End-of-Frame Error interrupt Enable bit

1 = Interrupt is enabled0 = Interrupt is disabled

bit 0 PIDEE: PID Check Failure Interrupt Enable bit

1 = Interrupt is enabled0 = Interrupt is disabled

#### REGISTER 21-9: PADCFG1: PAD CONFIGURATION CONTROL REGISTER

U-0	U-0	U-0	U-0	U-0	U-0	U-0	U-0
_	_	_	_	_	_	_	_
bit 15							bit 8

U-0	U-0	U-0	U-0	U-0	U-0	U-0	R/W-0
_	_	_	_	_	_	_	PMPTTL
bit 7							bit 0

Legend:

R = Readable bit W = Writable bit U = Unimplemented bit, read as '0'

-n = Value at POR '1' = Bit is set '0' = Bit is cleared x = Bit is unknown

bit 15-1 Unimplemented: Read as '0'

bit 0 PMPTTL: EPMP Module TTL Input Buffer Select bit

1 = EPMP module inputs (PMDx, PMCS1) use TTL input buffers

0 = EPMP module inputs use Schmitt Trigger input buffers

# REGISTER 26-1: CMxCON: COMPARATOR x CONTROL REGISTERS (COMPARATORS 1 THROUGH 3)

R/W-0	R/W-0	R/W-0	U-0	U-0	U-0	R/W-0, HS	R-0, HSC
CON	COE	CPOL	_	_	_	CEVT	COUT
bit 15							bit 8

R/W-0	R/W-0	U-0	R/W-0	U-0	U-0	R/W-0	R/W-0
EVPOL1 <sup>(1)</sup>	EVPOL0 <sup>(1)</sup>	_	CREF	_	_	CCH1	CCH0
bit 7							bit 0

Legend:	HS = Hardware Settable bit	HSC = Hardware Settable/Clearable bit		
R = Readable bit	W = Writable bit	U = Unimplemented bit, read as '0'		
-n = Value at POR	'1' = Bit is set	'0' = Bit is cleared	x = Bit is unknown	

bit 15 CON: Comparator Enable bit

1 = Comparator is enabled

0 = Comparator is disabled

bit 14 **COE:** Comparator Output Enable bit

1 = Comparator output is present on the CxOUT pin

0 = Comparator output is internal only

bit 13 **CPOL:** Comparator Output Polarity Select bit

1 = Comparator output is inverted

0 = Comparator output is not inverted

bit 12-10 Unimplemented: Read as '0'

bit 9 **CEVT:** Comparator Event bit

1 = Comparator event that is defined by the EVPOL<1:0> bits has occurred; subsequent triggers and interrupts are disabled until the bit is cleared

0 = Comparator event has not occurred

bit 8 **COUT:** Comparator Output bit

When CPOL = 0:

1 = VIN+ > VIN-

0 = VIN+ < VIN-

When CPOL = 1:

1 = VIN+ < VIN-

0 = VIN+ > VIN-

bit 7-6 **EVPOL<1:0>:** Trigger/Event/Interrupt Polarity Select bits<sup>(1)</sup>

11 = Trigger/event/interrupt is generated on any change of the comparator output (while CEVT = 0)

10 = Trigger/event/interrupt is generated on the high-to-low transition of the comparator output

01 = Trigger/event/interrupt is generated on the low-to-high transition of the comparator output

00 = Trigger/event/interrupt generation is disabled

bit 5 **Unimplemented:** Read as '0'

bit 4 CREF: Comparator Reference Select bit (non-inverting input)

 $\ensuremath{\mathtt{1}}$  = Non-inverting input connects to the internal CVREF voltage

0 = Non-inverting input connects to the CxINA pin

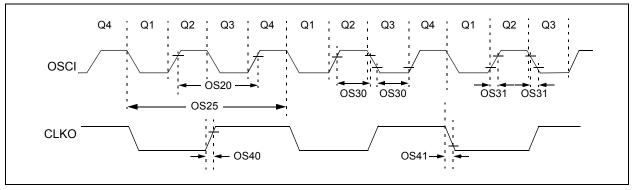
bit 3-2 **Unimplemented:** Read as '0'

**Note 1:** If the EVPOL<1:0> bits are set to a value other than '00', the first interrupt generated will occur on any transition of COUT. Subsequent interrupts will occur based on the EVPOLx bits setting.

## TABLE 32-2: INSTRUCTION SET OVERVIEW (CONTINUED)

Assembly Mnemonic		Assembly Syntax	Description	# of Words	# of Cycles	Status Flags Affected
TBLRDH	TBLRDH	Ws,Wd	Read Prog<23:16> to Wd<7:0>	1	2	None
TBLRDL	TBLRDL	Ws, Wd	Read Prog<15:0> to Wd	1	2	None
TBLWTH	TBLWTH	Ws, Wd	Write Ws<7:0> to Prog<23:16>	1	2	None
TBLWTL	TBLWTL	Ws, Wd	Write Ws to Prog<15:0>	1	2	None
ULNK	ULNK		Unlink Frame Pointer	1	1	None
XOR	XOR	f	f = f .XOR. WREG	1	1	N, Z
	XOR	f,WREG	WREG = f .XOR. WREG	1	1	N, Z
	XOR	#lit10,Wn	Wd = lit10 .XOR. Wd	1	1	N, Z
	XOR	Wb, Ws, Wd	Wd = Wb .XOR. Ws	1	1	N, Z
	XOR	Wb,#lit5,Wd	Wd = Wb .XOR. lit5	1	1	N, Z
ZE	ZE	Ws, Wnd	Wnd = Zero-Extend Ws	1	1	C, Z, N

FIGURE 33-3: EXTERNAL CLOCK TIMING

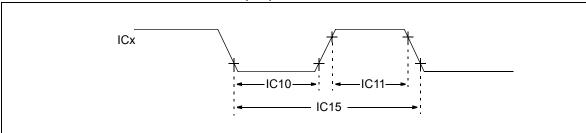


**TABLE 33-20: EXTERNAL CLOCK TIMING REQUIREMENTS** 

40.011	A D A OTE	DIOTION	Standard Operating Conditions: 2.0V to 3.6V (unless otherwise stated)						
AC CH	ARACTE	RISTICS	Operating ten	nperature		$-40^{\circ}$ C $\leq$ TA $\leq$ +85 $^{\circ}$ C for Industrial $-40^{\circ}$ C $\leq$ TA $\leq$ +125 $^{\circ}$ C for Extended			
Param No.	Symbol	Characteristic	Min	Typ <sup>(1)</sup>	Max	Units	Conditions		
OS10	Fosc	External CLKI Frequency (External clocks allowed only in EC mode)	DC 4		32 48	MHz MHz	EC ECPLL (Note 2)		
		Oscillator Frequency	3.5 4 10 12 31		10 8 32 32 33	MHz MHz MHz MHz kHz	XT XTPLL HS HSPLL SOSC		
OS20	Tosc	Tosc = 1/Fosc	_		_	_	See Parameter OS10 for Fosc value		
OS25	Tcy	Instruction Cycle Time <sup>(3)</sup>	62.5	_	DC	ns			
OS30	TosL, TosH	External Clock in (OSCI) High or Low Time	0.45 x Tosc		_	ns	EC		
OS31	TosR, TosF	External Clock in (OSCI) Rise or Fall Time	_	_	20	ns	EC		
OS40	TckR	CLKO Rise Time <sup>(4)</sup>	_	6	10	ns			
OS41	TckF	CLKO Fall Time(4)	_	6	10	ns			

- **Note 1:** Data in the "Typ" column is at 3.3V, +25°C unless otherwise stated. Parameters are for design guidance only and are not tested.
  - 2: Represents input to the system clock prescaler. PLL dividers and postscalers must still be configured so that the system clock frequency does not exceed the maximum frequency shown in Figure 33-1.
  - 3: Instruction cycle period (TcY) equals two times the input oscillator time base period. All specified values are based on characterization data for that particular oscillator type, under standard operating conditions, with the device executing code. Exceeding these specified limits may result in an unstable oscillator operation and/or higher than expected current consumption. All devices are tested to operate at "Min." values with an external clock applied to the OSCI/CLKI pin. When an external clock input is used, the "Max." cycle time limit is "DC" (no clock) for all devices.
  - **4:** Measurements are taken in EC mode. The CLKO signal is measured on the OSCO pin. CLKO is low for the Q1-Q2 period (1/2 TcY) and high for the Q3-Q4 period (1/2 TcY).

#### FIGURE 33-6: INPUT CAPTURE x (ICx) TIMING CHARACTERISTICS



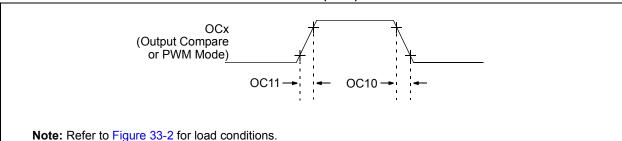
Note: Refer to Figure 33-2 for load conditions.

#### TABLE 33-29: INPUT CAPTURE x TIMING REQUIREMENTS

AC CHAPACTERISTICS			Standard Operating Conditions: 2.0V to 3.6V (unless otherwise stated) Operating temperature $-40^{\circ}\text{C} \le \text{TA} \le +85^{\circ}\text{C}$ for Industrial $-40^{\circ}\text{C} \le \text{TA} \le +125^{\circ}\text{C}$ for Extended				
Param No.	Symbol	Characteristic <sup>(1)</sup>		Min	Max	Units	Conditions
IC10	TccL	ICx Input Low Time	No Prescaler	0.5 Tcy + 20		ns	
			With Prescaler	10	_	ns	
IC11	TccH	ICx Input High	No Prescaler	0.5 Tcy + 20	_	ns	
	Time		With Prescaler	10		ns	
IC15	TccP	ICx Input Period		(Tcy + 40)/N	_	ns	N = Prescale Value (1, 4, 16)

**Note 1:** These parameters are characterized but not tested in manufacturing.

## FIGURE 33-7: OUTPUT COMPARE x MODULE (OCx) TIMING CHARACTERISTICS



## TABLE 33-30: OUTPUT COMPARE x MODULE TIMING REQUIREMENTS

AC CHARACTERISTICS			Standard Operating Conditions: 2.0V to 3.6V (unless otherwise stated) Operating temperature $-40^{\circ}\text{C} \le \text{TA} \le +85^{\circ}\text{C}$ for Industrial $-40^{\circ}\text{C} \le \text{TA} \le +125^{\circ}\text{C}$ for Extended					
Param No.	Symbol	Characteristic <sup>(1)</sup>	Min	Тур	Max	Units	Conditions	
OC10	TccF	OCx Output Fall Time		_	_	ns	See Parameter DO32	
OC11	TccR	OCx Output Rise Time	ns See Parameter DO31					

**Note 1:** These parameters are characterized but not tested in manufacturing.

FIGURE 33-13: I<sup>2</sup>C™ BUS START/STOP BITS TIMING CHARACTERISTICS (MASTER MODE)

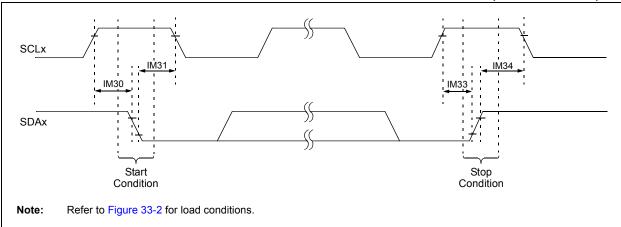


TABLE 33-36: I<sup>2</sup>C™ BUS START/STOP BIT TIMING REQUIREMENTS (MASTER MODE)

AC CHARACTERISTICS				Standard Operating Conditions: 2.0V to 3.6V (unless otherwise stated) Operating temperature $-40^{\circ}C \le TA \le +85^{\circ}C$ for Industrial $-40^{\circ}C \le TA \le +125^{\circ}C$ for Extended					
Param No. Characteristic			Min <sup>(1)</sup>	Max	Units	Conditions			
IM30	Tsu:sta	Start Condition	100 kHz mode	Tcy (BRG + 1)	_	μS	Only relevant for		
		Setup Time	400 kHz mode	Tcy (BRG + 1)	_	μS	Repeated Start		
			1 MHz mode <sup>(2)</sup>	Tcy (BRG + 1)	_	μS	condition		
IM31	THD:STA	Start Condition	100 kHz mode	Tcy (BRG + 1)	_	μS	After this period, the		
		Hold Time	400 kHz mode	Tcy (BRG + 1)	_	μS	first clock pulse is		
			1 MHz mode <sup>(2)</sup>	Tcy (BRG + 1)	_	μS	generated		
IM33	Tsu:sto	Stop Condition	100 kHz mode	Tcy (BRG + 1)	_	μS			
		Setup Time	400 kHz mode	Tcy (BRG + 1)	_	μS			
			1 MHz mode <sup>(2)</sup>	Tcy (BRG + 1)	_	μS			
IM34	THD:STO	Stop Condition	100 kHz mode	Tcy (BRG + 1)	_	ns			
		Hold Time	400 kHz mode	Tcy (BRG + 1)	_	ns			
			1 MHz mode <sup>(2)</sup>	Tcy (BRG + 1)	_	ns			

Note 1: BRG is the value of the I<sup>2</sup>C Baud Rate Generator. Refer to Section 17.2 "Setting Baud Rate When Operating as a Bus Master" for details.

2: Maximum Pin Capacitance = 10 pF for all I<sup>2</sup>C pins (for 1 MHz mode only).

FIGURE 33-16: I<sup>2</sup>C™ BUS DATA TIMING CHARACTERISTICS (SLAVE MODE)

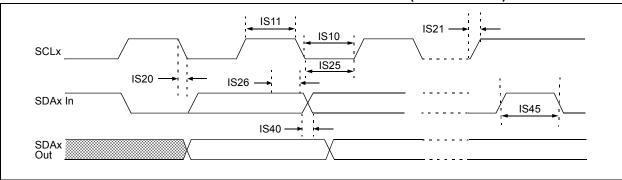


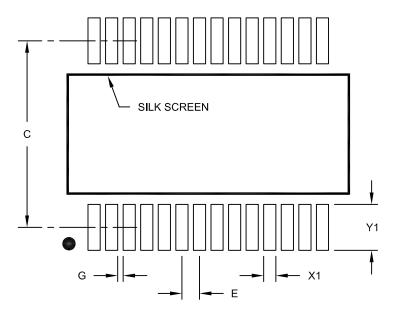
TABLE 33-39: I<sup>2</sup>C™ BUS DATA TIMING REQUIREMENTS (SLAVE MODE)

AC CHARACTERISTICS				Standard Operating Conditions: 2.0V to 3.6V (unless otherwise stated) Operating temperature $-40^{\circ}\text{C} \le \text{Ta} \le +85^{\circ}\text{C}$ for Industrial $-40^{\circ}\text{C} \le \text{Ta} \le +125^{\circ}\text{C}$ for Extended				
Param No.	Symbol	Characteristic		Min	Max	Units	Conditions	
IS10	TLO:SCL	Clock Low Time	100 kHz mode	4.7	_	μS	Device must operate at a minimum of 1.5 MHz	
			400 kHz mode	1.3	_	μS	Device must operate at a minimum of 10 MHz	
			1 MHz mode <sup>(1)</sup>	0.5	_	μS		
IS11	THI:SCL	Clock High Time	100 kHz mode	4.0	_	μS	Device must operate at a minimum of 1.5 MHz	
			400 kHz mode	0.6	_	μS	Device must operate at a minimum of 10 MHz	
			1 MHz mode <sup>(1)</sup>	0.5	_	μS		
IS20	TF:SCL	SDAx and SCLx Fall Time	100 kHz mode	_	300	ns	CB is specified to be from 10 to 400 pF	
			400 kHz mode	20 + 0.1 CB	300	ns		
			1 MHz mode <sup>(1)</sup>	_	100	ns		
IS21	TR:SCL	SDAx and SCLx Rise Time	100 kHz mode	_	1000	ns	CB is specified to be from 10 to 400 pF	
			400 kHz mode	20 + 0.1 CB	300	ns		
			1 MHz mode <sup>(1)</sup>	_	300	ns		
IS25	Tsu:dat	Data Input Setup Time	100 kHz mode	250	_	ns		
			400 kHz mode	100	_	ns		
			1 MHz mode <sup>(1)</sup>	100		ns		
IS26	THD:DAT	Data Input Hold Time	100 kHz mode	0		ns		
			400 kHz mode	0	0.9	μS		
			1 MHz mode <sup>(1)</sup>	0	0.3	μS		
IS40	TAA:SCL	Clock	100 kHz mode	0	3500	ns		
			400 kHz mode	0	1000	ns		
			1 MHz mode <sup>(1)</sup>	0	350	ns		
IS45	TBF:SDA	Bus Free Time	100 kHz mode	4.7	_	μS	Time the bus must be free before a new transmission can start	
			400 kHz mode	1.3	_	μS		
			1 MHz mode <sup>(1)</sup>	0.5	_	μS		
IS50	Св	Bus Capacitive Lo	ading	_	400	pF		

**Note 1:** Maximum Pin Capacitance = 10 pF for all I<sup>2</sup>C pins (for 1 MHz mode only).

## 28-Lead Plastic Shrink Small Outline (SS) - 5.30 mm Body [SSOP]

**Note:** For the most current package drawings, please see the Microchip Packaging Specification located at http://www.microchip.com/packaging



**RECOMMENDED LAND PATTERN** 

	MILLIMETERS					
Dimension	MIN	NOM	MAX			
Contact Pitch	Е		0.65 BSC			
Contact Pad Spacing	С		7.20			
Contact Pad Width (X28)	X1			0.45		
Contact Pad Length (X28)	Y1			1.75		
Distance Between Pads	G	0.20				

#### Notes:

1. Dimensioning and tolerancing per ASME Y14.5M

BSC: Basic Dimension. Theoretically exact value shown without tolerances.

Microchip Technology Drawing No. C04-2073A

## APPENDIX A: REVISION HISTORY

#### Revision A (May 2013)

Original data sheet for the PIC24FJ128GB204 family of devices.

#### Revision B (May 2014)

This revision incorporates the following updates:

- · Sections:
  - Inserted new bulleted list in "Cryptographic Engine"
  - Updated a unit in "Analog Features"
  - Updated note in Section 16.0 "Serial Peripheral Interface (SPI)", Section 17.0 "Inter-Integrated Circuit™ (I²C™)", Section 18.0 "Universal Asynchronous Receiver Transmitter (UART)", Section 23.0 "Cryptographic Engine" and Section 27.0 "Comparator Voltage Reference"
  - Updated Section 17.3 "Slave Address Masking"
  - Updated Section 23.0 "Cryptographic Engine"
  - Inserted new Section 23.5.6 "Generating a Random Number"
  - Updated Section 30.3.1 "Windowed Operation"
  - Updated packaging information in Section 34.0 "Packaging Information"
- · Registers:
  - Updated Register 8-45, Register 16-1, Register 16-4, Register 17-1, Register 18-1, Register 20-1, Register 23-1 and Register 23-5
  - Updated the title of Register 18-2 and Register 18-4
  - Updated bit 10 register description in Register 23-5
- · Tables:
  - Updated Table 1-3, Table 4-5, Table 4-9, Table 4-10, Table 4-11, Table 4-12, Table 4-13, Table 4-14, Table 4-29, Table 33-1, Table 33-3, Table 33-4, Table 33-5, Table 33-6, Table 33-7, Table 33-8, Table 33-10, Table 33-12, Table 33-13, Table 33-14, Table 33-15, Table 33-16, Table 33-21
  - Added Table 33-26 through Table 33-39
- · Figures:
  - Added Figure 9-1, Figure 33-5, Figure 33-6,
     Figure 33-7, Figure 33-8, Figure 33-9,
     Figure 33-10, Figure 33-11 and Figure 33-12.
- · Examples:
  - Example 22-1

## Revision C (March 2015)

This revision incorporates the following updates:

- · Registers:
  - Register 26-1
- · Tables:
  - Table 33-4, Table 33-5, Table 33-6 and Table 33-21
- Package marking examples and package diagrams in Section 34.0 "Packaging Information" were updated