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#### What is "[Embedded - Microcontrollers](#)"?

"[Embedded - Microcontrollers](#)" refer to small, integrated circuits designed to perform specific tasks within larger systems. These microcontrollers are essentially compact computers on a single chip, containing a processor core, memory, and programmable input/output peripherals. They are called "embedded" because they are embedded within electronic devices to control various functions, rather than serving as standalone computers. Microcontrollers are crucial in modern electronics, providing the intelligence and control needed for a wide range of applications.

#### Applications of "[Embedded - Microcontrollers](#)"

##### Details

Product Status	Active
Core Processor	ARM® Cortex®-M4
Core Size	32-Bit Single-Core
Speed	180MHz
Connectivity	CANbus, EBI/EMI, Ethernet, I²C, IrDA, LINbus, SPI, UART/USART, USB OTG
Peripherals	Brown-out Detect/Reset, DMA, I²S, LCD, POR, PWM, WDT
Number of I/O	114
Program Memory Size	512KB (512K x 8)
Program Memory Type	FLASH
EEPROM Size	-
RAM Size	256K x 8
Voltage - Supply (Vcc/Vdd)	1.8V ~ 3.6V
Data Converters	A/D 24x12b; D/A 2x12b
Oscillator Type	Internal
Operating Temperature	-40°C ~ 85°C (TA)
Mounting Type	Surface Mount
Package / Case	144-LQFP
Supplier Device Package	144-LQFP (20x20)
Purchase URL	<a href="https://www.e-xfl.com/product-detail/stmicroelectronics/stm32f429zet6">https://www.e-xfl.com/product-detail/stmicroelectronics/stm32f429zet6</a>

**Table 1. Device summary**

Reference	Part number
STM32F427xx	STM32F427VG, STM32F427ZG, STM32F427IG, STM32F427AG, STM32F427VI, STM32F427ZI, STM32F427II, STM32F427AI
STM32F429xx	STM32F429VG, STM32F429ZG, STM32F429IG, STM32F429BG, STM32F429NG, STM32F429AG, STM32F429VI, STM32F429ZI, STM32F429II, STM32F429BI, STM32F429NI, STM32F429AI, STM32F429VE, STM32F429ZE, STM32F429IE, STM32F429BE, STM32F429NE

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Table 2. STM32F427xx and STM32F429xx features and peripheral counts (continued)

Peripherals	STM32F427 Vx	STM32F429Vx	STM32F427 Zx	STM32F429Zx	STM32F427 Ax	STM32F429 Ax	STM32F427 Ix	STM32F429Ix	STM32F429Bx	STM32F429Nx								
Communication interfaces	SPI / I <sup>2</sup> S	4/2 (full duplex) <sup>(2)</sup>					6/2 (full duplex) <sup>(2)</sup>											
	I <sup>2</sup> C						3											
	USART/ UART						4/4											
	USB OTG FS						Yes											
	USB OTG HS						Yes											
	CAN						2											
	SAI						1											
	SDIO						Yes											
Camera interface	Yes																	
LCD-TFT (STM32F429xx only)	No	Yes	No	Yes	No	Yes	No	Yes										
Chrom-ART Accelerator™	Yes																	
GPIOs	82		114		130		140		168									
12-bit ADC Number of channels	3																	
	16		24															
12-bit DAC Number of channels	Yes 2																	
	180 MHz																	
Maximum CPU frequency	1.8 to 3.6 V <sup>(3)</sup>																	
Operating voltage	Ambient temperatures: -40 to +85 °C / -40 to +105 °C																	
Operating temperatures	Junction temperature: -40 to + 125 °C																	
Packages	LQFP100		WLCSP143 LQFP144		UFBGA169		UFBGA176 LQFP176		LQFP208		TFBGA216							

- For the LQFP100 package, only FMC Bank1 or Bank2 are available. Bank1 can only support a multiplexed NOR/PSRAM memory using the NE1 Chip Select. Bank2 can only support a 16- or 8-bit NAND Flash memory using the NCE2 Chip Select. The interrupt line cannot be used since Port G is not available in this package. For UFBGA169 package, only SDRAM, NAND and multiplexed static memories are supported.
- The SPI2 and SPI3 interfaces give the flexibility to work in an exclusive way in either the SPI mode or the I2S audio mode.
- $V_{DD}/V_{DDA}$  minimum value of 1.7 V is obtained when the device operates in reduced temperature range, and with the use of an external power supply supervisor (refer to [Section 3.17.2: Internal reset OFF](#)).



## 2.1 Full compatibility throughout the family

The STM32F427xx and STM32F429xx devices are part of the STM32F4 family. They are fully pin-to-pin, software and feature compatible with the STM32F2xx devices, allowing the user to try different memory densities, peripherals, and performances (FPU, higher frequency) for a greater degree of freedom during the development cycle.

The STM32F427xx and STM32F429xx devices maintain a close compatibility with the whole STM32F10xx family. All functional pins are pin-to-pin compatible. The STM32F427xx and STM32F429xx, however, are not drop-in replacements for the STM32F10xx devices: the two families do not have the same power scheme, and so their power pins are different. Nonetheless, transition from the STM32F10xx to the STM32F42x family remains simple as only a few pins are impacted.

*Figure 1*, *Figure 2*, and *Figure 3*, give compatible board designs between the STM32F4xx, STM32F2xx, and STM32F10xx families.

**Figure 1. Compatible board design STM32F10xx/STM32F2xx/STM32F4xx for LQFP100 package**

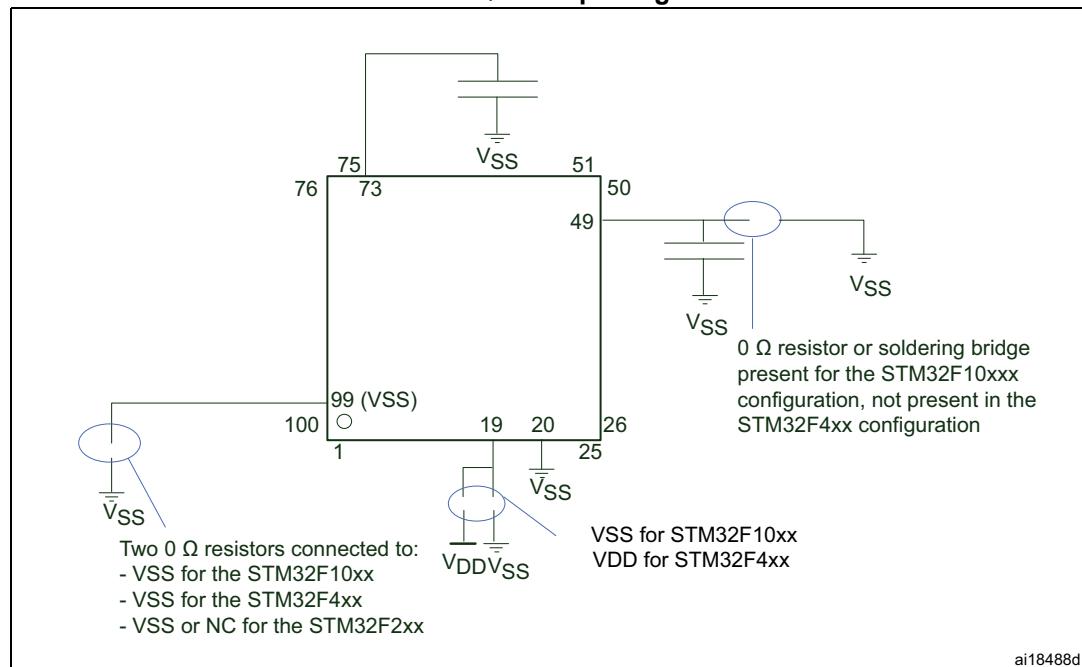
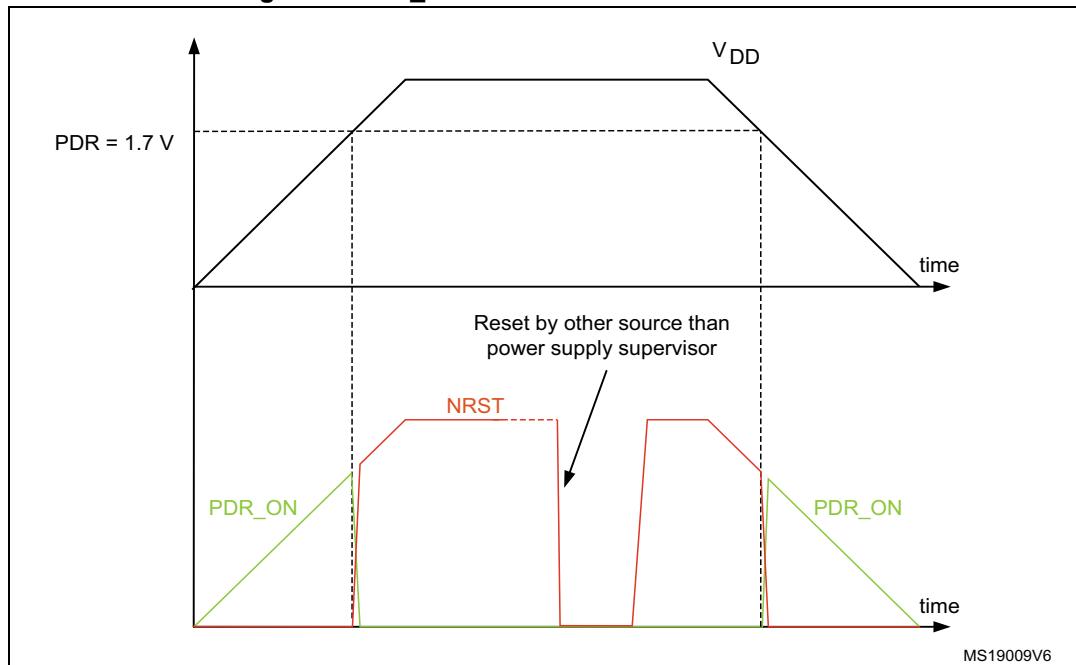


Figure 7. PDR\_ON control with internal reset OFF



### 3.18 Voltage regulator

The regulator has four operating modes:

- Regulator ON
  - Main regulator mode (MR)
  - Low power regulator (LPR)
  - Power-down
- Regulator OFF

#### 3.18.1 Regulator ON

On packages embedding the BYPASS\_REG pin, the regulator is enabled by holding BYPASS\_REG low. On all other packages, the regulator is always enabled.

There are three power modes configured by software when the regulator is ON:

- MR mode used in Run/sleep modes or in Stop modes
  - In Run/Sleep mode

The MR mode is used either in the normal mode (default mode) or the over-drive mode (enabled by software). Different voltages scaling are provided to reach the best compromise between maximum frequency and dynamic power consumption.

### 3.22.4 Independent watchdog

The independent watchdog is based on a 12-bit downcounter and 8-bit prescaler. It is clocked from an independent 32 kHz internal RC and as it operates independently from the main clock, it can operate in Stop and Standby modes. It can be used either as a watchdog to reset the device when a problem occurs, or as a free-running timer for application timeout management. It is hardware- or software-configurable through the option bytes.

### 3.22.5 Window watchdog

The window watchdog is based on a 7-bit downcounter that can be set as free-running. It can be used as a watchdog to reset the device when a problem occurs. It is clocked from the main clock. It has an early warning interrupt capability and the counter can be frozen in debug mode.

### 3.22.6 SysTick timer

This timer is dedicated to real-time operating systems, but could also be used as a standard downcounter. It features:

- A 24-bit downcounter
- Autoreload capability
- Maskable system interrupt generation when the counter reaches 0
- Programmable clock source.

## 3.23 Inter-integrated circuit interface (I<sup>2</sup>C)

Up to three I<sup>2</sup>C bus interfaces can operate in multimaster and slave modes. They can support the standard (up to 100 KHz), and fast (up to 400 KHz) modes. They support the 7/10-bit addressing mode and the 7-bit dual addressing mode (as slave). A hardware CRC generation/verification is embedded.

They can be served by DMA and they support SMBus 2.0/PMBus.

The devices also include programmable analog and digital noise filters (see [Table 7](#)).

**Table 7. Comparison of I<sup>2</sup>C analog and digital filters**

	Analog filter	Digital filter
Pulse width of suppressed spikes	≥ 50 ns	Programmable length from 1 to 15 I <sup>2</sup> C peripheral clocks

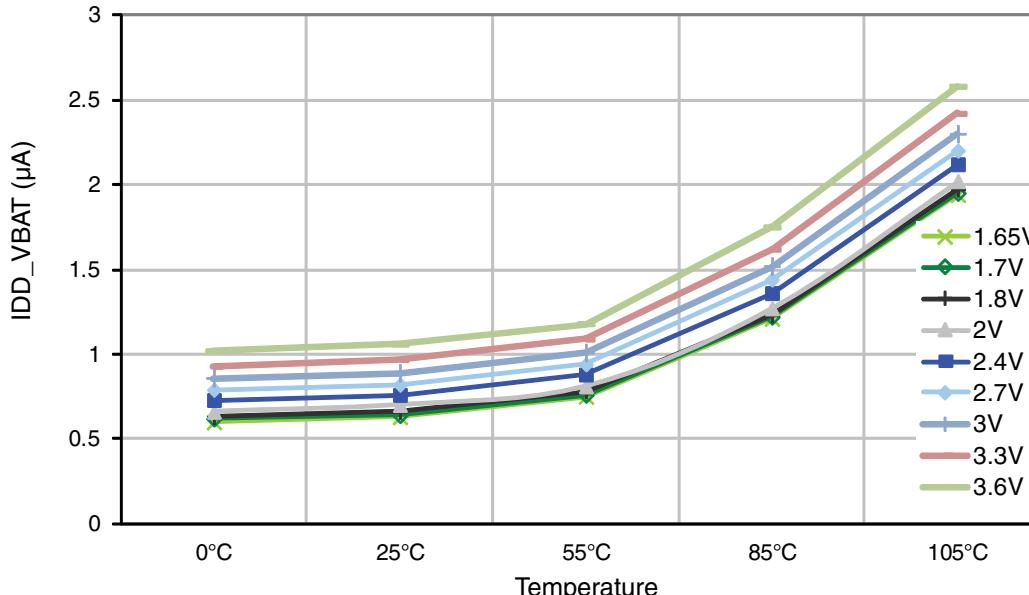
## 3.24 Universal synchronous/asynchronous receiver transmitters (USART)

The devices embed four universal synchronous/asynchronous receiver transmitters (USART1, USART2, USART3 and USART6) and four universal asynchronous receiver transmitters (UART4, UART5, UART7, and UART8).

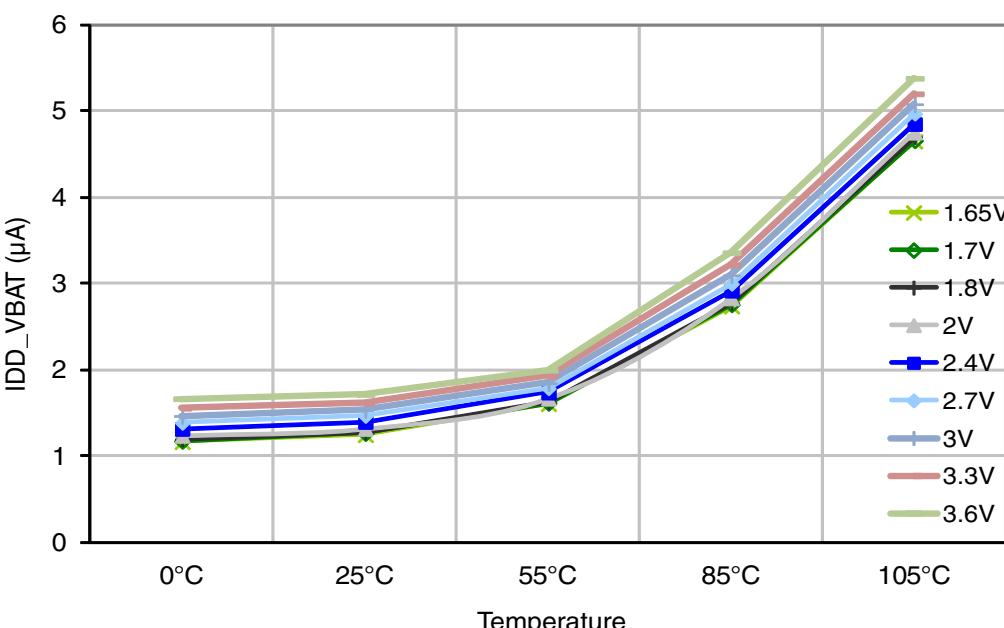
These six interfaces provide asynchronous communication, IrDA SIR ENDEC support, multiprocessor communication mode, single-wire half-duplex communication mode and have LIN Master/Slave capability. The USART1 and USART6 interfaces are able to

Table 10. STM32F427xx and STM32F429xx pin and ball definitions (continued)

Pin number									Pin name (function after reset) <sup>(1)</sup>	Pin type	I / O structure	Notes	Alternate functions	Additional functions
LQFP100	LQFP144	UFBGA169	UFBGA176	LQFP176	WL CSP143	LQFP208	TFBGA216							
35	46	N4	R5	56	N8	61	R5	PB0	I/O	FT	(5)	TIM1_CH2N, TIM3_CH3, TIM8_CH2N, LCD_R3, OTG_HS_ULPI_D1, ETH_MII_RXD2, EVENTOUT	ADC12_IN8	
36	47	K5	R4	57	K7	62	R4	PB1	I/O	FT	(5)	TIM1_CH3N, TIM3_CH4, TIM8_CH3N, LCD_R6, OTG_HS_ULPI_D2, ETH_MII_RXD3, EVENTOUT	ADC12_IN9	
37	48	L5	M6	58	L7	63	M5	PB2-BOOT1 (PB2)	I/O	FT	-	EVENTOUT	-	
-	-	-	-	-	-	64	G4	PI15	I/O	FT	-	LCD_R0, EVENTOUT	-	
-	-	-	-	-	-	65	R6	PJ0	I/O	FT	-	LCD_R1, EVENTOUT	-	
-	-	-	-	-	-	66	R7	PJ1	I/O	FT	-	LCD_R2, EVENTOUT	-	
-	-	-	-	-	-	67	P7	PJ2	I/O	FT	-	LCD_R3, EVENTOUT	-	
-	-	-	-	-	-	68	N8	PJ3	I/O	FT	-	LCD_R4, EVENTOUT	-	
-	-	-	-	-	-	69	M9	PJ4	I/O	FT	-	LCD_R5, EVENTOUT	-	
-	49	M5	R6	59	M7	70	P8	PF11	I/O	FT	-	SPI5_MOSI, FMC_SDNRAS, DCMI_D12, EVENTOUT	-	
-	50	N5	P6	60	N7	71	M6	PF12	I/O	FT	-	FMC_A6, EVENTOUT	-	
-	51	G9	M8	61	-	72	K7	V <sub>SS</sub>	S		-	-	-	
-	52	D10	N8	62	-	73	L8	V <sub>DD</sub>	S		-	-	-	
-	53	M6	N6	63	K6	74	N6	PF13	I/O	FT	-	FMC_A7, EVENTOUT	-	
-	54	K7	R7	64	L6	75	P6	PF14	I/O	FT	-	FMC_A8, EVENTOUT	-	
-	55	L7	P7	65	M6	76	M8	PF15	I/O	FT	-	FMC_A9, EVENTOUT	-	
-	56	N6	N7	66	N6	77	N7	PG0	I/O	FT	-	FMC_A10, EVENTOUT	-	
-	57	M7	M7	67	K5	78	M7	PG1	I/O	FT	-	FMC_A11, EVENTOUT	-	

**Figure 25. Typical  $V_{BAT}$  current consumption (LSE and RTC ON/backup RAM OFF)**

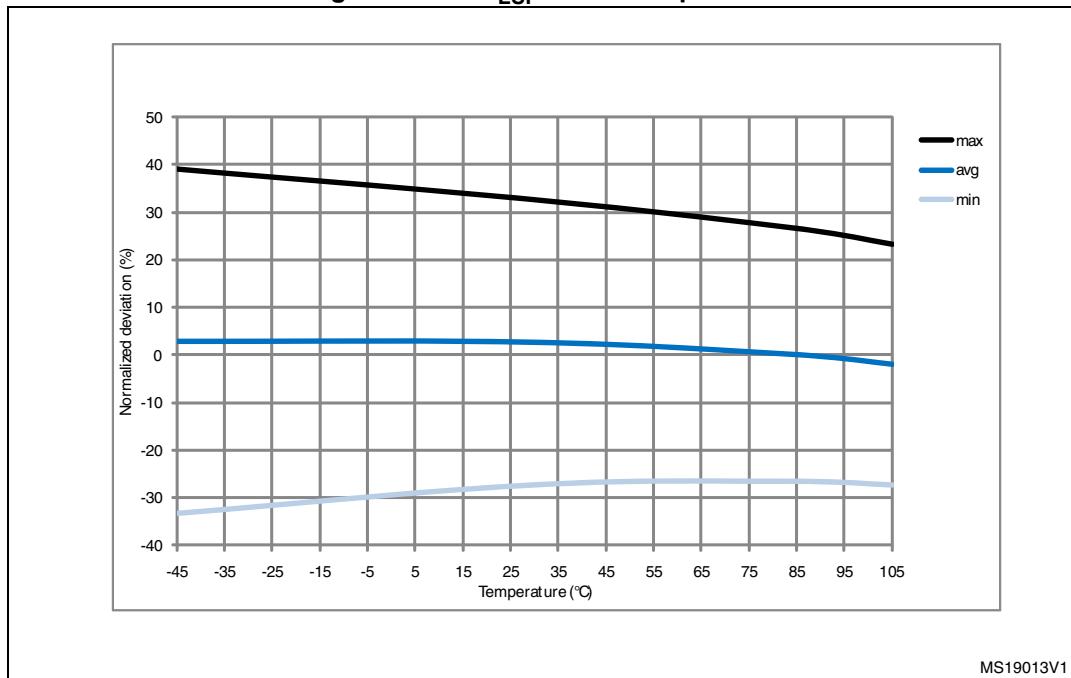
MS30490V1

**Figure 26. Typical  $V_{BAT}$  current consumption (LSE and RTC ON/backup RAM ON)**

MS30491V1

Table 35. Peripheral current consumption (continued)

Peripheral		$I_{DD(\text{Typ})}^{(1)}$			Unit
		Scale 1	Scale 2	Scale 3	
AHB2 (up to 180 MHz)	OTG_FS	25.67	26.67	23.58	$\mu\text{A}/\text{MHz}$
	DCMI	3.72	3.40	3.00	
	RNG	2.28	2.36	2.17	
AHB3 (up to 180 MHz)	FMC	21.39	19.79	17.50	$\mu\text{A}/\text{MHz}$
Bus matrix <sup>(2)</sup>		14.06	13.19	11.75	$\mu\text{A}/\text{MHz}$
APB1 (up to 45 MHz)	TIM2	17.56	16.42	14.47	$\mu\text{A}/\text{MHz}$
	TIM3	14.22	13.36	11.80	
	TIM4	14.89	13.64	12.13	
	TIM5	17.33	16.42	14.47	
	TIM6	2.89	2.53	2.47	
	TIM7	3.11	2.81	2.47	
	TIM12	7.33	6.97	6.13	
	TIM13	4.89	4.47	4.13	
	TIM14	5.56	5.31	4.80	
	PWR	11.11	10.31	9.13	
	USART2	4.22	3.92	3.47	
	USART3	4.44	4.19	3.80	
	UART4	4.00	3.92	3.47	
	UART5	4.00	3.92	3.47	
	UART7	4.00	3.92	3.47	
	UART8	3.78	3.92	3.47	
	I2C1	4.00	3.92	3.47	
	I2C2	4.00	3.92	3.47	
	I2C3	4.00	3.92	3.47	
	SPI2 <sup>(3)</sup>	3.11	3.08	2.80	
	SPI3 <sup>(3)</sup>	3.56	3.36	3.13	
	I2S2	2.89	2.81	2.47	
	I2S3	3.33	3.08	2.80	
	CAN1	6.89	6.42	5.80	
	CAN2	6.67	6.14	5.47	
	DAC <sup>(4)</sup>	2.89	2.25	2.13	
	WWDG	0.89	0.86	0.80	

Figure 32. ACC<sub>LSI</sub> versus temperature

MS19013V1

### 6.3.11 PLL characteristics

The parameters given in [Table 43](#) and [Table 44](#) are derived from tests performed under temperature and V<sub>DD</sub> supply voltage conditions summarized in [Table 17](#).

Table 43. Main PLL characteristics

Symbol	Parameter	Conditions	Min	Typ	Max	Unit
f <sub>PLL_IN</sub>	PLL input clock <sup>(1)</sup>		0.95 <sup>(2)</sup>	1	2.10	MHz
f <sub>PLL_OUT</sub>	PLL multiplier output clock		24	-	180	MHz
f <sub>PLL48_OUT</sub>	48 MHz PLL multiplier output clock		-	48	75	MHz
f <sub>VCO_OUT</sub>	PLL VCO output		100	-	432	MHz
t <sub>LOCK</sub>	PLL lock time	VCO freq = 100 MHz	75	-	200	μs
		VCO freq = 432 MHz	100	-	300	

**Table 44. PLLI2S (audio PLL) characteristics (continued)**

Symbol	Parameter	Conditions	Min	Typ	Max	Unit
$I_{DD(PLLI2S)}^{(4)}$	PLLI2S power consumption on $V_{DD}$	VCO freq = 100 MHz VCO freq = 432 MHz	0.15 0.45	-	0.40 0.75	mA
$I_{DDA(PLLI2S)}^{(4)}$	PLLI2S power consumption on $V_{DDA}$	VCO freq = 100 MHz VCO freq = 432 MHz	0.30 0.55	-	0.40 0.85	mA

1. Take care of using the appropriate division factor M to have the specified PLL input clock values.
2. Guaranteed by design.
3. Value given with main PLL running.
4. Guaranteed by characterization results.

**Table 45. PLLISAI (audio and LCD-TFT PLL) characteristics**

Symbol	Parameter	Conditions	Min	Typ	Max	Unit
$f_{PLLSAI\_IN}$	PLLSAI input clock <sup>(1)</sup>		0.95 <sup>(2)</sup>	1	2.10	MHz
$f_{PLLSAI\_OUT}$	PLLSAI multiplier output clock		-	-	216	MHz
$f_{VCO\_OUT}$	PLLSAI VCO output		100	-	432	MHz
$t_{LOCK}$	PLLSAI lock time	VCO freq = 100 MHz	75	-	200	$\mu s$
		VCO freq = 432 MHz	100	-	300	
Jitter <sup>(3)</sup>	Main SAI clock jitter	Cycle to cycle at 12.288 MHz on 48KHz period, N=432, R=5	RMS  peak to peak	-  -	90  $\pm 280$	-  ps
		Average frequency of 12.288 MHz N = 432, R = 5 on 1000 samples	-	90	-	ps
		FS clock jitter	Cycle to cycle at 48 KHz on 1000 samples	-	400	-
$I_{DD(PLLSAI)}^{(4)}$	PLLSAI power consumption on $V_{DD}$	VCO freq = 100 MHz VCO freq = 432 MHz	0.15 0.45	-	0.40 0.75	mA
$I_{DDA(PLLSAI)}^{(4)}$	PLLSAI power consumption on $V_{DDA}$	VCO freq = 100 MHz VCO freq = 432 MHz	0.30 0.55	-	0.40 0.85	mA

1. Take care of using the appropriate division factor M to have the specified PLL input clock values.
2. Guaranteed by design.
3. Value given with main PLL running.
4. Guaranteed by characterization results.

### 6.3.15 Absolute maximum ratings (electrical sensitivity)

Based on three different tests (ESD, LU) using specific measurement methods, the device is stressed in order to determine its performance in terms of electrical sensitivity.

#### Electrostatic discharge (ESD)

Electrostatic discharges (a positive then a negative pulse separated by 1 second) are applied to the pins of each sample according to each pin combination. The sample size depends on the number of supply pins in the device (3 parts  $\times$  (n+1) supply pins). This test conforms to the ANSI/ESDA/JEDEC JS-001 and ANSI/ESD S5.3.1 standards.

**Table 53. ESD absolute maximum ratings**

Symbol	Ratings	Conditions	Class	Maximum value <sup>(1)</sup>	Unit
$V_{ESD(HBM)}$	Electrostatic discharge voltage (human body model)	$T_A = +25^\circ\text{C}$ conforming to ANSI/ESDA/JEDEC JS-001	2	2000	V
$V_{ESD(CDM)}$	Electrostatic discharge voltage (charge device model)	$T_A = +25^\circ\text{C}$ conforming to ANSI/ESD S5.3.1, LQFP100/144/176, UFBGA169/176, TFBGA176 and WLCSP143 packages	C3	250	
		$T_A = +25^\circ\text{C}$ conforming to ANSI/ESD S5.3.1, LQFP208 package	C3	250	

1. Guaranteed by characterization results.

#### Static latchup

Two complementary static tests are required on six parts to assess the latchup performance:

- A supply overvoltage is applied to each power supply pin
- A current injection is applied to each input, output and configurable I/O pin

These tests are compliant with EIA/JESD 78A IC latchup standard.

**Table 54. Electrical sensitivities**

Symbol	Parameter	Conditions	Class
LU	Static latch-up class	$T_A = +105^\circ\text{C}$ conforming to JESD78A	II level A

### 6.3.18 NRST pin characteristics

The NRST pin input driver uses CMOS technology. It is connected to a permanent pull-up resistor,  $R_{PU}$  (see [Table 56: I/O static characteristics](#)).

Unless otherwise specified, the parameters given in [Table 59](#) are derived from tests performed under the ambient temperature and  $V_{DD}$  supply voltage conditions summarized in [Table 17](#).

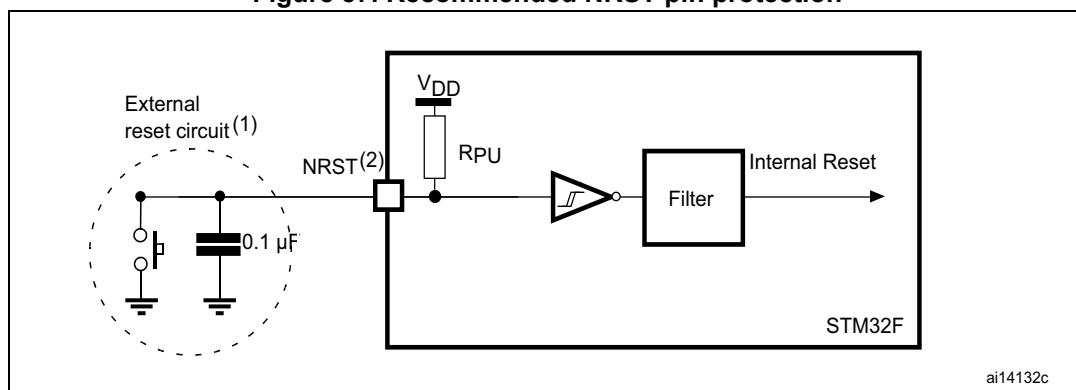
**Table 59. NRST pin characteristics**

Symbol	Parameter	Conditions	Min	Typ	Max	Unit
$R_{PU}$	Weak pull-up equivalent resistor <sup>(1)</sup>	$V_{IN} = V_{SS}$	30	40	50	kΩ
$V_{F(NRST)}^{(2)}$	NRST Input filtered pulse		-	-	100	ns
$V_{NF(NRST)}^{(2)}$	NRST Input not filtered pulse	$V_{DD} > 2.7$ V	300	-	-	ns
$T_{NRST\_OUT}$	Generated reset pulse duration	Internal Reset source	20	-	-	μs

1. The pull-up is designed with a true resistance in series with a switchable PMOS. This PMOS contribution to the series resistance must be minimum (~10% order).

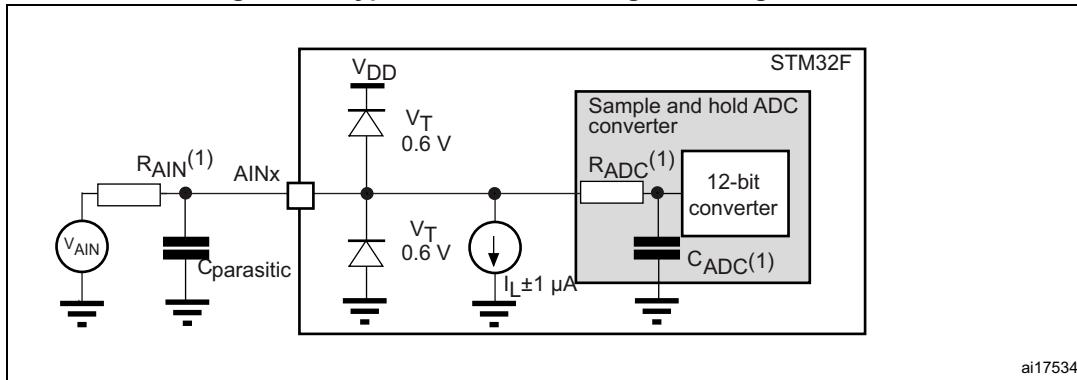
2. Guaranteed by design.

**Figure 37. Recommended NRST pin protection**



1. The reset network protects the device against parasitic resets.
2. The external capacitor must be placed as close as possible to the device.
3. The user must ensure that the level on the NRST pin can go below the  $V_{IL(NRST)}$  max level specified in [Table 59](#). Otherwise the reset is not taken into account by the device.

Figure 51. Typical connection diagram using the ADC



1. Refer to [Table 74](#) for the values of  $R_{AIN}$ ,  $R_{ADC}$  and  $C_{ADC}$ .
2.  $C_{parasitic}$  represents the capacitance of the PCB (dependent on soldering and PCB layout quality) plus the pad capacitance (roughly 5 pF). A high  $C_{parasitic}$  value downgrades conversion accuracy. To remedy this,  $f_{ADC}$  should be reduced.

**Table 90. Asynchronous multiplexed PSRAM/NOR read timings<sup>(1)(2)</sup>**

Symbol	Parameter	Min	Max	Unit
$t_{w(NE)}$	FMC_NE low time	$3T_{HCLK} - 1$	$3T_{HCLK} + 0.5$	ns
$t_{v(NOE\_NE)}$	FMC_NEx low to FMC_NOE low	$2T_{HCLK} - 0.5$	$2T_{HCLK}$	ns
$t_{w(NOE)}$	FMC_NOE low time	$T_{HCLK} - 1$	$T_{HCLK} + 1$	ns
$t_{h(NE\_NOE)}$	FMC_NOE high to FMC_NE high hold time	1	-	ns
$t_{v(A\_NE)}$	FMC_NEx low to FMC_A valid	-	2	ns
$t_{v(NADV\_NE)}$	FMC_NEx low to FMC_NADV low	0	2	ns
$t_{w(NADV)}$	FMC_NADV low time	$T_{HCLK} - 0.5$	$T_{HCLK} + 0.5$	ns
$t_{h(AD\_NADV)}$	FMC_AD(address) valid hold time after FMC_NADV high)	0	-	ns
$t_{h(A\_NOE)}$	Address hold time after FMC_NOE high	$T_{HCLK} - 0.5$	-	ns
$t_{h(BL\_NOE)}$	FMC_BL time after FMC_NOE high	0	-	ns
$t_{v(BL\_NE)}$	FMC_NEx low to FMC_BL valid	-	2	ns
$t_{su(Data\_NE)}$	Data to FMC_NEx high setup time	$T_{HCLK} + 1.5$	-	ns
$t_{su(Data\_NOE)}$	Data to FMC_NOE high setup time	$T_{HCLK} + 1$	-	ns
$t_{h(Data\_NE)}$	Data hold time after FMC_NEx high	0	-	ns
$t_{h(Data\_NOE)}$	Data hold time after FMC_NOE high	0	-	ns

1.  $C_L = 30 \text{ pF}$ .
2. Guaranteed by characterization results.

**Table 91. Asynchronous multiplexed PSRAM/NOR read-NWAIT timings<sup>(1)(2)</sup>**

Symbol	Parameter	Min	Max	Unit
$t_{w(NE)}$	FMC_NE low time	$8T_{HCLK} + 0.5$	$8T_{HCLK} + 2$	ns
$t_{w(NOE)}$	FMC_NWE low time	$5T_{HCLK} - 1$	$5T_{HCLK} + 1.5$	ns
$t_{su(NWAIT\_NE)}$	FMC_NWAIT valid before FMC_NEx high	$5T_{HCLK} + 1.5$	-	ns
$t_{h(NE\_NWAIT)}$	FMC_NEx hold time after FMC_NWAIT invalid	$4T_{HCLK} + 1$		ns

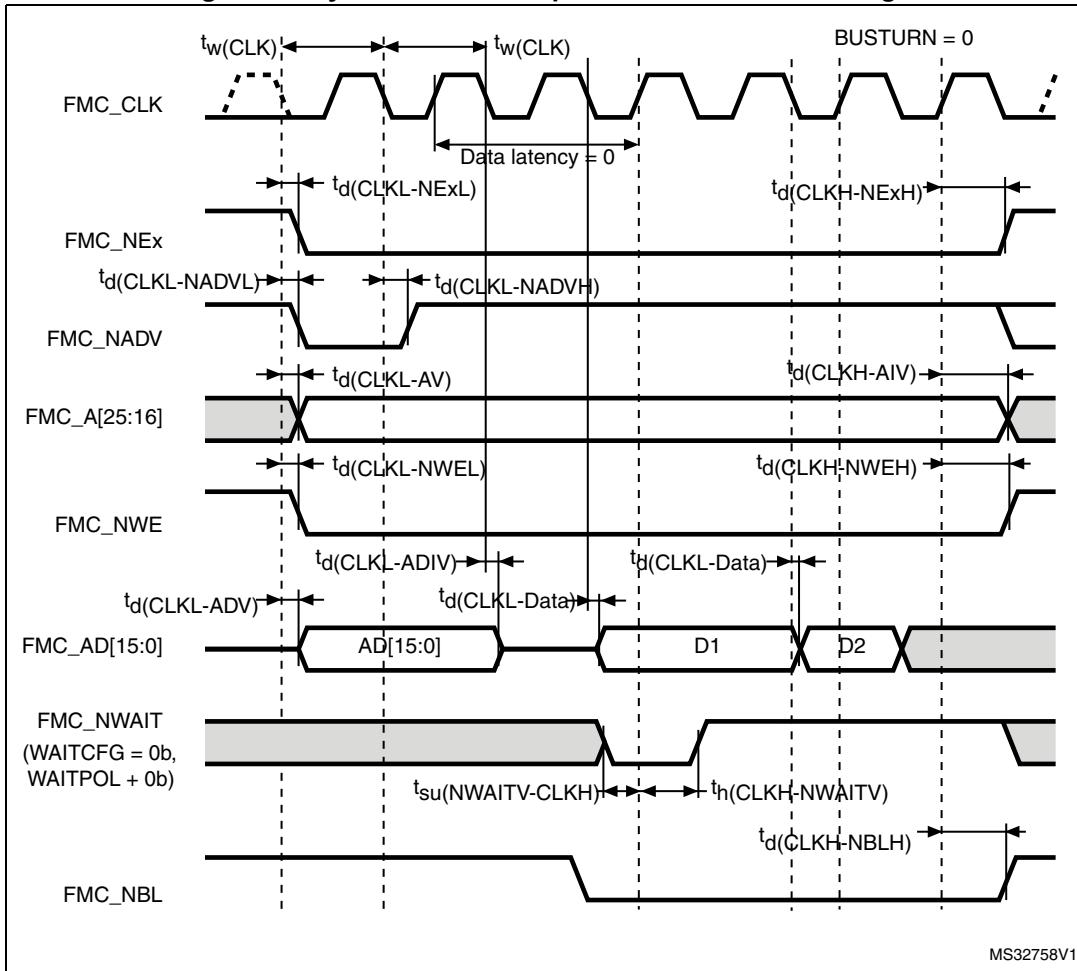
1.  $C_L = 30 \text{ pF}$ .
2. Guaranteed by characterization results.

**Table 94. Synchronous multiplexed NOR/PSRAM read timings<sup>(1)(2)</sup> (continued)**

Symbol	Parameter	Min	Max	Unit
$t_{su}(\text{ADV-CLKH})$	FMC_A/D[15:0] valid data before FMC_CLK high	5	-	ns
$t_h(\text{CLKH-ADV})$	FMC_A/D[15:0] valid data after FMC_CLK high	0	-	ns
$t_{su}(\text{NWAIT-CLKH})$	FMC_NWAIT valid before FMC_CLK high	4	-	ns
$t_h(\text{CLKH-NWAIT})$	FMC_NWAIT valid after FMC_CLK high	0	-	ns

1.  $C_L = 30 \text{ pF}$ .

2. Guaranteed by characterization results.

**Figure 60. Synchronous multiplexed PSRAM write timings**

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**Table 102. SDRAM read timings<sup>(1)(2)</sup>**

Symbol	Parameter	Min	Max	Unit
$t_w(\text{SDCLK})$	FMC_SDCLK period	$2T_{\text{HCLK}} - 0.5$	$2T_{\text{HCLK}} + 0.5$	ns
$t_{su}(\text{SDCLKH\_Data})$	Data input setup time	2	-	
$t_h(\text{SDCLKH\_Data})$	Data input hold time	0	-	
$t_d(\text{SDCLKL\_Add})$	Address valid time	-	1.5	
$t_d(\text{SDCLKL\_SDNE})$	Chip select valid time	-	0.5	
$t_h(\text{SDCLKL\_SDNE})$	Chip select hold time	0	-	
$t_d(\text{SDCLKL\_SDNRAS})$	SDNRAS valid time	-	0.5	
$t_h(\text{SDCLKL\_SDNRAS})$	SDNRAS hold time	0	-	
$t_d(\text{SDCLKL\_SDNCAS})$	SDNCAS valid time	-	0.5	
$t_h(\text{SDCLKL\_SDNCAS})$	SDNCAS hold time	0	-	

1. CL = 30 pF on data and address lines. CL=15pF on FMC\_SDCLK.

2. Guaranteed by characterization results.

**Table 103. LPDDR SDRAM read timings<sup>(1)(2)</sup>**

Symbol	Parameter	Min	Max	Unit
$t_w(\text{SDCLK})$	FMC_SDCLK period	$2T_{\text{HCLK}} - 0.5$	$2T_{\text{HCLK}} + 0.5$	ns
$t_{su}(\text{SDCLKH\_Data})$	Data input setup time	2.5	-	
$t_h(\text{SDCLKH\_Data})$	Data input hold time	0	-	
$t_d(\text{SDCLKL\_Add})$	Address valid time	-	1	
$t_d(\text{SDCLKL\_SDNE})$	Chip select valid time	-	1	
$t_h(\text{SDCLKL\_SDNE})$	Chip select hold time	1	-	
$t_d(\text{SDCLKL\_SDNRAS})$	SDNRAS valid time	-	1	
$t_h(\text{SDCLKL\_SDNRAS})$	SDNRAS hold time	1	-	
$t_d(\text{SDCLKL\_SDNCAS})$	SDNCAS valid time	-	1	
$t_h(\text{SDCLKL\_SDNCAS})$	SDNCAS hold time	1	-	

1. CL = 10 pF.

2. Guaranteed by characterization results.

**Table 120. TFBGA216 - 216 ball 13 × 13 mm 0.8 mm pitch thin fine pitch ball grid array package mechanical data (continued)**

Symbol	millimeters			inches <sup>(1)</sup>		
	Min	Typ	Max	Min	Typ	Max
eee	-	-	0.150	-	-	0.0059
fff	-	-	0.080	-	-	0.0031

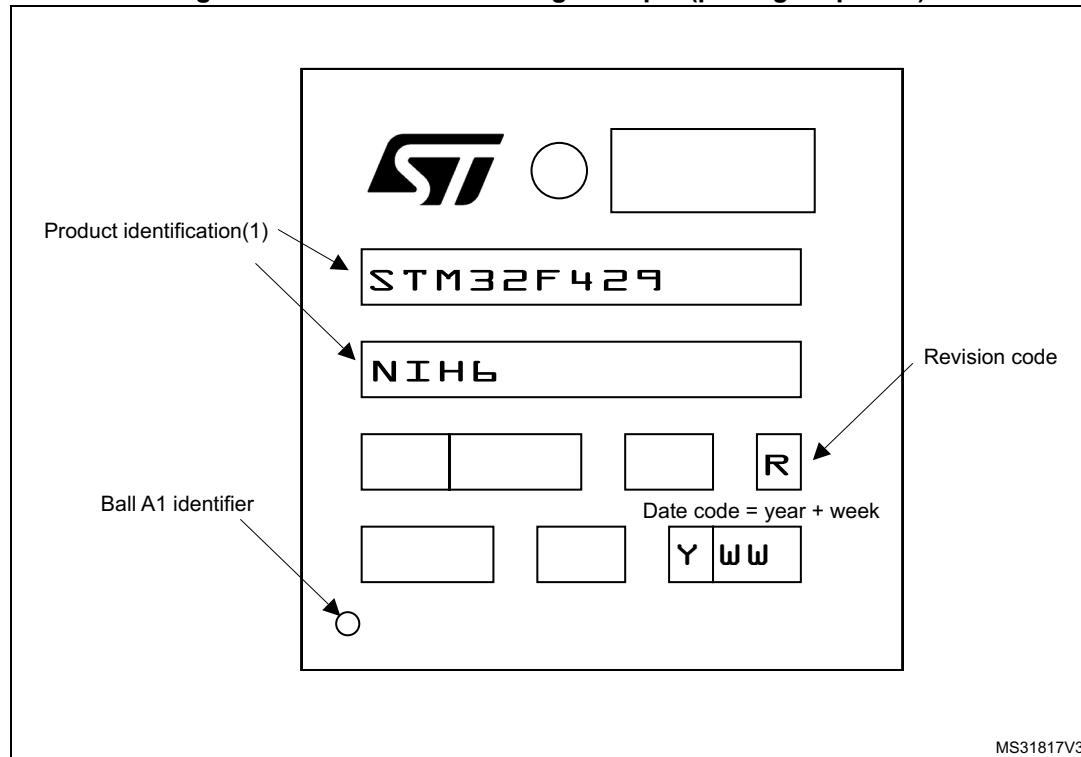
1. Values in inches are converted from mm and rounded to 4 decimal digits.

### Device marking for TFBGA176

The following figure gives an example of topside marking orientation versus ball A1 identifier location.

Other optional marking or inset/upset marks, which depends assembly location, are not indicated below.

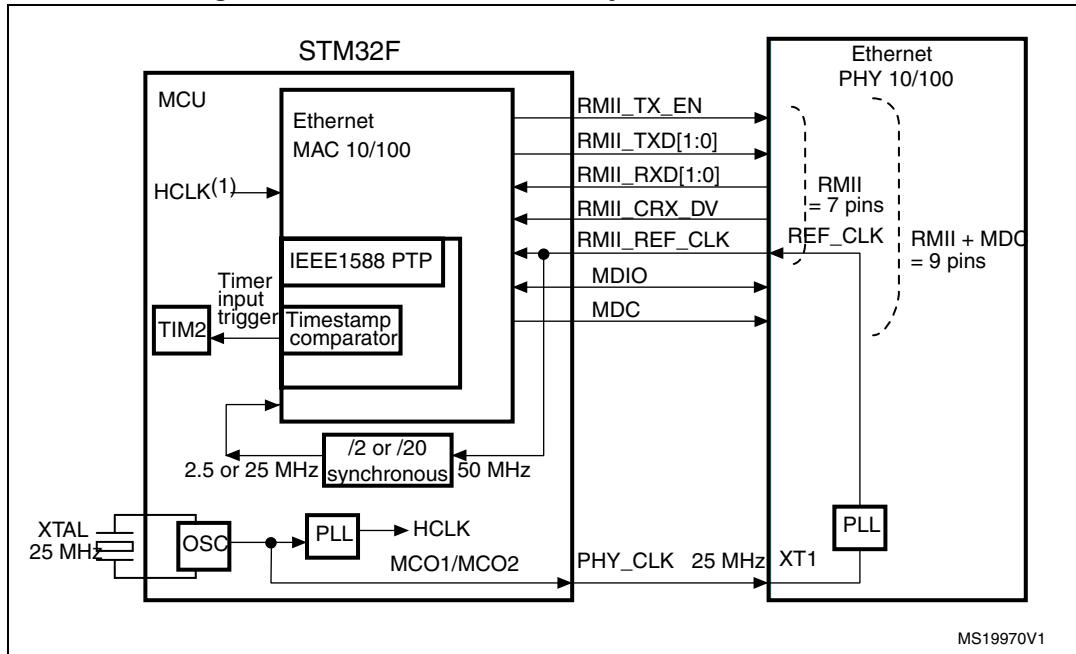
**Figure 102. TFBGA176 marking example (package top view)**



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1. Parts marked as "ES", "E" or accompanied by an Engineering Sample notification letter, are not yet qualified and therefore not yet ready to be used in production and any consequences deriving from such usage will not be at ST charge. In no event, ST will be liable for any customer usage of these engineering samples in production. ST Quality has to be contacted prior to any decision to use these Engineering Samples to run qualification activity.

Figure 109. RMII with a 25 MHz crystal and PHY with PLL



1.  $f_{HCLK}$  must be greater than 25 MHz.
2. The 25 MHz (PHY\_CLK) must be derived directly from the HSE oscillator, before the PLL block.

**Table 124. Document revision history**

Date	Revision	Changes
17-Sep-2015	6	<p>Updated notes related to the minimum and maximum values guaranteed by design, characterization or test in production.</p> <p>Updated <math>I_{DD\_STOP\_UDM}</math> in <a href="#">Table 27: Typical and maximum current consumptions in Stop mode</a>.</p> <p>Removed note related to tests in production in <a href="#">Table 24: Typical and maximum current consumption in Run mode</a>, code with data processing running from Flash memory (ART accelerator enabled except prefetch) or RAM and <a href="#">Table 26: Typical and maximum current consumption in Sleep mode</a>.</p> <p>Updated <a href="#">Table 41: HSI oscillator characteristics</a>. <a href="#">Figure 31</a> renamed <a href="#">ACCHSI accuracy versus temperature</a> and updated.</p> <p>Updated <a href="#">Figure 38: SPI timing diagram - slave mode and CPHA = 0</a>.</p> <p>Updated <a href="#">Section : Ethernet characteristics</a>.</p> <p>Updated <a href="#">Table 43: Main PLL characteristics</a>, <a href="#">Table 44: PLLI2S (audio PLL) characteristics</a> and <a href="#">Table 45: PLLISAI (audio and LCD-TFT PLL) characteristics</a>.</p> <p>Removed note 1 in <a href="#">Table 75: ADC static accuracy at fADC = 18 MHz</a>, <a href="#">Table 76: ADC static accuracy at fADC = 30 MHz</a> and <a href="#">Table 77: ADC static accuracy at fADC = 36 MHz</a>.</p> <p>Updated <math>t_d(SDCLKL\_Data)</math> and <math>t_h(SDCLKL\_Data)</math> in <a href="#">Table 104: SDRAM write timings</a>.</p> <p>Added <a href="#">Figure 96: UFBGA169 - 169-ball, 7 x 7 mm, 0.50 mm pitch, ultra fine pitch ball grid array recommended footprint</a> and <a href="#">Table 117: UFBGA169 recommended PCB design rules (0.5 mm pitch BGA)</a>.</p> <p>Added <a href="#">Figure 99: UFBGA176+25-ball, 10 x 10 mm, 0.65 mm pitch, ultra fine pitch ball grid array package recommended footprint</a> and <a href="#">Table 119: UFBGA176+25 recommended PCB design rules (0.65 mm pitch BGA)</a>.</p>
30-Nov-2015	7	<p>Updated <math> V_{SSX} - V_{SS} </math> in <a href="#">Table 14: Voltage characteristics</a> to add <math>V_{REF}</math>.</p> <p>Updated <math>t_d(TXEN)</math> and <math>t_d(TXD)</math> minimum value in <a href="#">Table 72: Dynamics characteristics: Ethernet MAC signals for RMII</a> and <a href="#">Table 73: Dynamics characteristics: Ethernet MAC signals for MII</a>.</p> <p>Added <math>V_{REF}</math> in <a href="#">Table 74: ADC characteristics</a>.</p> <p>Added A1 minimum and maximum values in <a href="#">Table 111: WLCSP143 - 143-ball, 4.521x 5.547 mm, 0.4 mm pitch wafer level chip scale package mechanical data</a>. Updated <a href="#">Figure 86: LQFP144-144-pin, 20 x 20 mm low-profile quad flat package outline</a>.</p> <p>Updated <a href="#">Figure 98: UFBGA176+25 - ball 10 x 10 mm, 0.65 mm pitch ultra thin fine pitch ball grid array package outline</a> and <a href="#">Table 118: UFBGA176+25 - ball, 10 x 10 mm, 0.65 mm pitch, ultra fine pitch ball grid array package mechanical data</a>. Updated <a href="#">Figure 101: TFBGA216 - 216 ball 13 x 13 mm 0.8 mm pitch thin fine pitch ball grid array package outline</a> and <a href="#">Table 120: TFBGA216 - 216 ball 13 x 13 mm 0.8 mm pitch thin fine pitch ball grid array package mechanical data</a>.</p>